THE EFFECT OF BODY ORIENTATION ON EMG PATTERNS IN CYCLING

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In human powered vehicles, manipulation of body orientation often results in changes in cycling **performance**. These changes in performance may be attributed to alterations in: (1) the aerodynamic properties of the cyclist and vehicle; (2) contribution of the lower limb weight to pedal force production; and/or (3) body configuration (joint angle changes affecting the interactions between the muscle length and moment arm length of the muscle groups involved in cycling). In a previous investigation examining cycling performance in a semi-prone, upright, and semi-recumbent position (the trunk relative to the ground at an angle of **60**, **90**, and 120 degrees, respectively), it had been concluded that an optimal cycling body orientation exists which maximizes power production (Too. 1991). Because the body configuration (hip, knee, and ankle angle) had been controlled for in that investigation, it had been speculated that differences in power production were attributed to changes in lower limb weight contribution to the total force on the pedals. It is believed that these differences would be reflected by changes in the muscle activity patterns. Therefore, it was the purpose of this investigation to determine whether cycling performance differences with different body orientations are attributed to changes in EMG patterns, as determined by one or more of these: (1) the sequence of activity by the different muscles; (2) the duration of the muscle activity; and (3) the pedal position each muscle was active and inactive during a complete pedal cycle.

METHODOLOGY

Seventeen male recreational cyclists (age 20-36 yrs) were tested in three different body orientation (60.90, 120 degrees), as defined by the angle of the cyclist's trunk relative to the ground (Figure 1). To accomplish this. a variable position seating apparatus was constructed and interfaced with a cycle ergometer, allowing for manipulations with 3 degrees of freedom. This included (1) changes in seat tube angle; (2) changes in seat backrest angles; and (3) changes in seat to pedal distance. A reference cycling position (90 degree orientation) was defined. This consisted of (I) a 75 degree angle formed by the seat tube and a vertical line (Hull & Gonzalez. 1990; Too, 1990. in press); (2) a backrest perpendicular to the ground; and (3) a seat-to-pedal distance of approximately 100% (to within 3/4 of an inch or 1.905 cm) of the total leg length as

measured **from** the greater **trochanter** of the femur of the right leg to the ground. To obtain the 60 and 120 degree body orientation, the entire cycling apparatus was rotated 30 degrees forward and backward from the 90 degree orientation. respectively (**see** Figure 1).

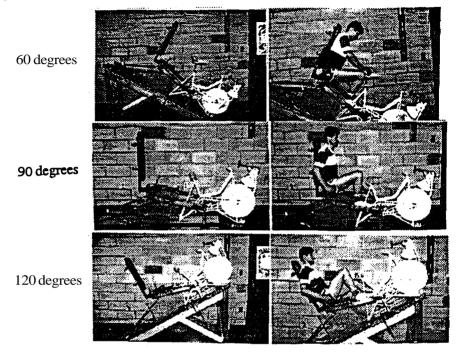


Figure 1. Body Orientations

All subjects were tested in each of the three body orientations according to a randomly determined sequence. Each subject was strapped to the seating apparatus at the trunk and hip with pedal **toe-clips** worn. The minimum and maximum hip, **kree**, and ankle angles were recorded at the 90 degree orientation for one complete pedal revolution and then controlled for in **the other** orientations (with adjustments made in the seat-to-pedal distance). A Monark Cycleergometer was used with a **resistance of** 65 gm/kg of the subject's body mass (3.82 joules/pedal rev/kg BM) and a pedalling frequency of **60 rpm** (asdictated by a metronome). There was a minimum of 5 minutes rest between lest conditions, and the ergometer was **re-calibrated** each time during this period.

For each body orientation condition, **EMG** activity of six muscles of the lower right limb was examined. **The** muscles were the (1) gastrocnemius (lateral head); (2) biceps femoris (long head); (3) gluteus maximus; (4) tibialis anterior; (5) vastus medialis; and (6) rectus femoris. **EMG** activity was recorded from surface electrodes

placed 3 cm apart over the belly of each muscle. Electrode placement was determined as described by Delagi and Perotto (1981). Electrode grounds were placed at the tibial condyles and iliac crest. Prior to electrode placement, the skin at the appropriate sites ups shaven, abraded with emery cloth to remove the dead skin layer, and cleaned with alcohol. Silver/silver chloride pregelled self-adhering disposable electrodes with a diameter of 4 cm were used in this investigation. The electrode resistance was always less than 10,000 ohms as determined by a Simpson 260 senes 8 volt-ohm-milliammeter. The electrode wires were taped to the skin with surgical uppe to minimize wire movement and to prevent accidental electrode removal. An elastic wrapplaced around the thigh and leg was used to secure the electrode cables and leads.

A four channel Beckman Dynograph Recorder (model R511A) was used to process the EMG signals. Because six muscles user examined, only three channels used at one time. After data were acquired in one body orientation, the electrodes user detached and re-applied to the remaining three muscles. In each body orientation, data user acquired from the same three channels and their corresponding muscles.

The Beckman recorder and a micro-switch, on-line with a Macpacq data acquisition system having an analog-to-digital converter interfaced to a Macintosh SE microcomputer, use used to record EMG activity and pedal position, respectively. A computer program, Pacqmanager, use used to collect the data of each channel at 200 samples/second. A micro-switch mounted on the bicycle ergometer chain guard use used to monitor pedal revolutions and record the position of the right crank uben the pedal crossed the top of it's revolution in the reference cycling position (90 degree orientation).

Prior to data collection in the experimental conditions, baseline EMG activity of the muscles at rest unane recorded, as well as during maximal isometric contractions. Maximal isometric contractions unane obtained with the use of a Cybex isokinetic dynanometer. In the different body orientations, EMG activity was obtained over a 10 second interval, after the proper resistance was applied, and the subject was pedalling at the prescribed cadence.

For a complete pedal cycle in each body onentation, a waveform data analysis program (Acqknowledge) by Biopac Systems Inc, was used to determine: (1) the sequence of activity by the different muscles; (2) the duration of activity; and (3) the pedal position each muscle was active and inactive. Repeated measures ANOVA uses used to determine whether there users significant differences in EMG activity sequence, duration, and pedal position with changes in body orientation.

RESULTS AND DISCUSSION

Observations of Figure 2 and 3 would indicate that the sequence of EMG activity patterns is very similar in all three orientations. This would suggest that differences in peak power production unbern cycling in different orientations, as reported in a previous

investigation (TCC, 1991), is not attributed to changes in the sequence of activation or timing of the various muscles with changes in body orientation. Comparing across cycling orientation for each muscle, the duration of EMG activity and the position of activity during one pedal cycle also appear to be very similar (see Table 1). Repeated measures ANOVAs confirm these similarities because no significant differences (p > .05) were found in (1) duration of EMG activity in real time or as a percentage of the pedal cycle; (2) position in the pedal cycle that the muscles were active; or (3) position in the pedal cycle that the muscles were active; or interactions.

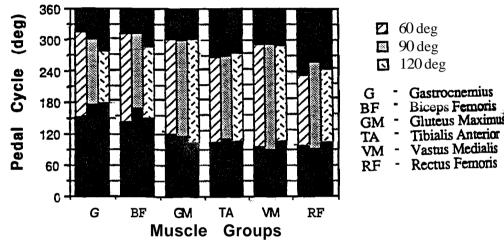
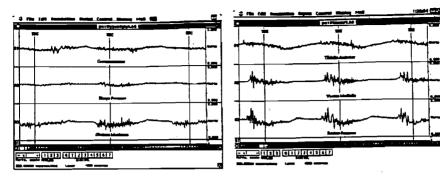


Figure 2. Muscle time diagram.

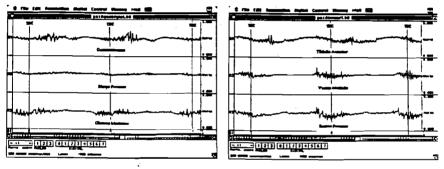
A sample of the raw EMG signal of the six muscles in the **60**, **90**, and **120** degree body orientation for subject **10** is displayed in Figure 3. Observations of Figure 3 would suggest that all muscles are active at the top **dead** center (TDC) position, regardless of cycling orientation. Activity of the **vastus medialis at** the TDC position is consistent with the results reported by **Despires (1974). Faria** and Cavanagh **(1978). Gregor**, Green, and **Garhammer (1981). Houtz** and **Fischer (1959).** and Jorge and Hull **(1984, 1986).** However, activity of the gluteus **maximus** at the TDC position is only similar to that reported by **Faria** and Cavanagh **(1978).** while no activity was reported for the **gas**trocnemius at the TDC position in the other investigations. For the remaining muscles, activity at the TDC was consistent with that reported in some investigations, but equivocal to those reported in others. These differences may be attributed to varying seat to pedal distances in different investigations and to the body configuration (hip and seat tube angle of **75** degrees) used in this investigation.

Speculations as to why no significant differences were found may include (1) differences in task specificity and test protocol; and (2) potential differences in quanti-

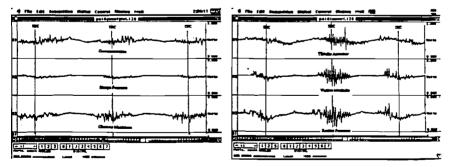


12

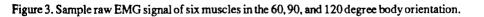
60 degree body orientation



90 degree body orientation







tative EMG values and analyses, as opposed to qualitative ones. The power test described by Too (1991) was the **Wingate** Anaerobic Cycling Test where a load of 85 **gm/kg** of the subject's body mass were used (5.0 **joules/pedal rev/kg** BM) and a 30 second time interval given to accomplish the maximal **number** of pedal revolution possible. In this investigation, the use of 65 **gm/kg** of the subject's body **mass** and the use of a predetermined pedalling frequency may have deviated from the protocol specified by Too (1991) sufficiently to result in non-significant differences between conditions. It is possible that higher loads with unconstrained pedal cadences in a maximal all-out effort may result in significantly different EMG patterns. It is also possible that differences in power production with changing body orientations are not attributed to differences in qualitative EMG patterns. **as** examined in this investigation, butrathertodifferences in qualitativeones. These quantitativedifferences may include differences in: (1) integrated EMG values; (2) percentage of maximal isometric contraction; and (3) peak to peak values with various body orientations.

Muscles	Body	Duration	Pedal Cycle	Location of Pedal Cycle	
Examined	Orientation	Active (sec)	Active (%)	ON (deg)	OFF (deg)
	(deg)				
		Mean (SD)	Mean(SD)	Mean(SD)	Mean(SD)
	60	0.64 (0.17)	55.5 (153)	314 (25.7)	154 (57.1)
Gastrocnemius	90	0.74 (0.18)	63.9 (13.9)	300 (38.4)	175 (523)
	120	0.69 (0.17)	60.4 (15.1)	277 (98.7)	180 (54.9)
	60	0.62 (0.18)	53.8 (15.9)	308 (18.1)	141 (595)
Biceps Femoris	90	0.73 (0.22)	63.1 (18.4)	310 (18.8)	171 (70.1)
*	120	0.64 (0.21)	58.0 (21.2)	283 (78.0)	147 (57.4)
	60	0.58 (0.08)	50.7 (6.7)	298 (15.0)	121 (29.0)
Gluteus Maximus	90	057 (0.14)	50.1 (11.7)	294 (18.6)	116 (495)
	120	051 (0.08)	45.3 (7.8)	298 (15.1)	102 (28.7)
	60	0.64 (0.16)	56.6 (14.8)	262 (46.6)	105 (25.4)
Tibialis Anterior	90	0.58 (0.16)	50.7 (15.0)	266 (71.3)	110 (39.1)
	120	0.63 (0.14)	54.8 (13.4)	270(375)	108 (30.2)
	60	054 (0.08)	46.9 (5.7)	287 (17.1)	95 (17.6)
Vastus Medialis	90	0.53 (0.12)	46.0 (12.0)	286 (35.5)	90 (12.0)
	120	0.55 (0.09)	48.1 (8.1)	283 (32.6)	108 (41.7)
	60	0.73 (0.19)	64.5 (14.2)	226 (45.6)	98 (13.0)
Rectus Femoris	90	0.63 (0.15)	56.1 (15.7)	250 (48.5)	92 (21.1)
	120	0.67 (0.17)	59.4 (16.7)	237 (54.7)	103 (45.4)

Table 1.	EMG A	Activity with	Changes in	Body Or	rientation over	one Pedal Cycle

CONCLUSIONS

Based on the results of this investigation, it was concluded that differences in anaerobic cycling performance with changes in body orientation were not attributed to differences in qualitative EMG patterns, as defined by the (1) sequence of activity by the different muscles examined; (2) duration of EMG activity in real time; (3) duration of EMG activity as a percentage of the pedal cycle; (4) position in the pedal cycle that the muscles were inactive. To further address this issue requires examination of the EMG data quantitatively.

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