

SPLINE APPROXIMATION FOR SYSTEM OF TWO THIRD ORDER ORDINARY DIFFERENTIAL EQUATIONS, II

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DESCRIPTION OF THE METHOD

Consider the system of nonlinear ordinary differential equations:

$$(1) \quad y''' = f_1(x, y, z), \quad y(x_0) = y_0, \quad y'(x_0) = y'_0, \quad y''(x_0) = y''_0,$$

$$(2) \quad z''' = f_2(x, y, z), \quad z(x_0) = z_0, \quad z'(x_0) = z'_0, \quad z''(x_0) = z''_0$$

where $f_1, f_2 \in C^r([0,1] \times \mathbb{R}^2)$.

Let Δ be the partition

$$\Delta : 0 = x_0 < x_1 < \dots < x_k < x_{k+1} < \dots < x_n = 1$$

where $x_{k+1} - x_k = h < 1$ and $k = 0(1)n - 1$.

Let L_1 and L_2 be the Lipschitz constants satisfied by the functions $f_1^{(q)}$ and $f_2^{(q)}$ respectively, i.e.,

$$(3) \quad \left| f_1^{(q)}(x, y_1, z_1) - f_1^{(q)}(x, y_2, z_2) \right| \leq L_1 \{ |y_1 - y_2| + |z_1 - z_2| \}$$

and

$$(4) \quad \left| f_2^{(q)}(x, y_1, z_1) - f_2^{(q)}(x, y_2, z_2) \right| \leq L_2 \{ |y_1 - y_2| + |z_1 - z_2| \}$$

for all (x, y_1, z_1) and (x, y_2, z_2) in the domain of definition of f_1 and f_2 and all $q = 0(1)r$.

The functions $f_1^{(q)}$ and $f_2^{(q)}$, $q = 1(1)r$ are functions of x, y and z only and they are given from the following algorithm:

set

$$f_1^{(0)} = f_1(x, y, z), \quad f_2^{(0)} = f_2(x, y, z)$$

and if $f_1^{(q-1)}$ and $f_2^{(q-1)}$ are defined, then

$$f_1^{(q)} = \frac{\partial f_1^{(q-1)}}{\partial x} + \frac{\partial f_1^{(q-1)}}{\partial y} y' + \frac{\partial f_1^{(q-1)}}{\partial z} z'$$

and

$$f_2^{(q)} = \frac{\partial f_2^{(q-1)}}{\partial x} + \frac{\partial f_2^{(q-1)}}{\partial y} y' + \frac{\partial f_2^{(q-1)}}{\partial z} z'$$

Then, we define the spline functions approximating $y(x)$ and $z(x)$ by $S_\Delta(x)$ and $\bar{S}_\Delta(x)$ where

$$S_\Delta(x) \equiv S_k(x) = S_{k-1}(x_k) + S'_{k-1}(x_k)(x - x_k) + S''_{k-1}(x_k) \frac{(x - x_k)^2}{2!} + \sum_{j=0}^r f_1^{(j)}[(x_k, s_{k-1}(x_k), \bar{s}_{k-1}(x_k))] \frac{(x - x_k)^{j+3}}{(j+3)!}$$

and

$$\bar{S}_\Delta(x) \equiv \bar{S}_k(x) = \bar{S}_{k-1}(x_k) + \bar{S}'_{k-1}(x_k)(x - x_k) + \bar{S}''_{k-1}(x_k) \frac{(x - x_k)^2}{2!} + \sum_{j=0}^r f_2^{(j)}[(x_k, s_{k-1}(x_k), \bar{s}_{k-1}(x_k))] \frac{(x - x_k)^{j+3}}{(j+3)!}$$

where $x_{k-1} \leq x \leq x_k$, $k = 0(1)n - 1$, $s_{-1}(x_0) = y_0$, $s'_{-1}(x_0) = y'_0$, $s''_{-1}(x_0) = y''_0$, $\bar{s}_{-1}(x_0) = z_0$, $\bar{s}'_{-1}(x_0) = z'_0$ and $\bar{s}''_{-1}(x_0) = z''_0$.

By construction it is clear that $s_\Delta(x), \bar{s}_\Delta(x) \in C^2[0, 1]$.

ERROR ESTIMATIONS AND CONVERGENCE

For all $x \in [x_k, x_{k+1}]$, $k = 0(1)n - 1$, the exact solutions of (1) and (2) can be written, by Taylor's expansion, in the following forms:

$$y(x) = \sum_{j=0}^{r+2} \frac{y_k^{(j)}}{j!} (x - x_k)^j + \frac{y^{(r+3)}(\xi_k)}{(r+3)!} (x - x_k)^{r+3}$$

and

$$z(x) = \sum_{j=0}^{r+2} \frac{z_k^{(j)}}{j!} (x - x_k)^j + \frac{z^{(r+3)}(\eta_k)}{(r+3)!} (x - x_k)^{r+3}$$

where $\xi_k, \eta_k \in (x_k, x_{k+1})$, $k = 0(1)n - 1$.

The following notation will be used along the discussion of the convergence of those spine approximants:

$$\begin{aligned} e(x) &= |y(x) - S_\Delta(x)|, \\ e_k &= |y_k - S_\Delta(x_k)|, \\ \bar{e}(x) &= |z(x) - \bar{S}_\Delta(x)|, \\ \bar{e}_k &= |z_k - \bar{S}_\Delta(x_k)|, \\ f_{1,k}^{(j)} &= f_1^{(j)}[x_k, s_{k-1}(x_k), \bar{s}_{k-1}(x_k)] \end{aligned}$$

and

$$f_{2,k}^{(j)} = f_2^{(j)}[x_k, s_{k-1}(x_k), \bar{s}_{k-1}(x_k)]$$

where $j = 0(1)r$ and $k = 0(1)n - 1$.

Along this work, we will deal with the general subinterval

$$I_k = [x_k, x_{k+1}], \quad k = 0(1)n - 1.$$

Now, we are going to estimate $|y_k - S_k(x)|$.

Using (5), (7) the Lipschitz condition (3) and the notation (9), we get:

$$\begin{aligned} |y(x) - S_k(x)| &\leq |y_k - S_{k-1}(x_k)| + |y'_k - S'_{k-1}(x_k)| |x - x_k| + \\ &+ |y''_k - S''_{k-1}(x_k)| \frac{|x - x_k|^2}{2!} + \sum_{j=0}^{r-1} |y_k^{(j+3)} - f_{1,k}^{(j)}| \frac{|x - x_k|^{j+3}}{(j+3)!} + \\ &+ |y^{(r+3)}(\xi_k) - f_{1,k}^{(r)}| \frac{|x - x_k|^{r+3}}{(r+3)!} \leq \end{aligned}$$

$$\begin{aligned} &\leq e_k + h e'_k + \frac{h^2}{2!} e''_k + \sum_{j=0}^{r-1} |y_k^{(j+3)} - f_{1,k}^{(j)}| \frac{h^{j+3}}{(j+3)!} + \\ &+ |y^{(r+3)}(\xi_k) - f_{1,k}^{(r)}| \frac{h^{r+3}}{(r+3)!} \end{aligned}$$

Now, let

$$U = |y_k^{(j+3)} - f_{1,k}^{(j)}|$$

then using the Lipschitz condition (3), we get:

$$(11) \quad U \leq L_1(e_k + \bar{e}_k)$$

Also let

$$v = |y^{(r+3)}(\xi_k) - f_{1,k}^{(r)}|$$

then, using (3), we get:

$$(12) \quad v \leq |y^{(r+3)}(\xi_k) - y_k^{(r+3)}| + |f_1^{(r)}(x_k, y_k, z_k) - f_{1,k}^{(r)}| \leq \omega(y^{(r+3)}, h) + L_1(e_k + \bar{e}_k)$$

where $\omega(y^{(r+3)}, h)$ is the modulus of continuity of the function $y^{(r+3)}$.

From (10-12) and noting that

$$(13) \quad \sum_{j=0}^{r-1} \frac{h^{j+3}}{(j+3)!} < h^2(e-1) < h^2e$$

we can see that:

$$(14) \quad e(x) \leq (1+c_0h^2)e_k + c_0h^2\bar{e}_k + he'_k + \frac{h^2}{2!}e''_k + \frac{h^{r+3}}{(r+3)!}\omega(y^{(r+3)}, h)$$

where $C_0 = L_1\left(e + \frac{1}{(r+3)!}\right)$ is a constant independent of h .

Similarly, using (6), (8), the Lipschitz condition (4) and the notation (9), we can see that:

$$(15) \quad \bar{e}(x) \leq C_1h^2e_k + (1+C_1h^2)\bar{e}_k + h\bar{e}'_k + \frac{h^2}{2!}\bar{e}''_k + \frac{h^{r+3}}{(r+3)!}\omega(z^{(r+3)}, h)$$

Where $C_1 = L_2\left(e + \frac{1}{(r+3)!}\right)$, is a constant independent of h and $\omega(z^{(r+3)}, h)$ is the modulus of continuity of the function $z^{(r+3)}$.

We are going to estimate $|y'(x) - S'_\Delta(x)|$. For this purpose we use equations (5), (7), the Lipschitz condition (3), the notation (9) and the inequalities (11), (12) and (13) and we get:

$$(16) \quad e'(x) \leq C_2he_k + C_2h\bar{e}_k + e'_k + he''_k + \frac{h^{r+2}}{(r+2)!}\omega(y^{(r+3)}, h)$$

where $C_2 = L_1\left(e + \frac{1}{(r+2)!}\right)$, is a constant independent of h .

Similarly, we estimate $|z'(x) - \bar{s}'_\Delta(x)|$. Thus using (6), (8), the Lipschitz condition (4), the notation (9), it can be easily shown that:

$$(17) \quad \bar{e}'(x) \leq C_3he_k + C_3h\bar{e}_k + \bar{e}'_k + h\bar{e}''_k + \frac{h^{r+2}}{(r+2)!}\omega(z^{(r+3)}, h)$$

where $C_3 = L_2\left(e + \frac{1}{(r+2)!}\right)$, is a constant independent of h .

We now estimate $|y''(x) - S''_k(x)|$ and $|z''(x) - \bar{s}''_k(x)|$. Thus, using equations (5-8), the Lipschitz conditions (3-4) and the notation (9), we get:

$$(18) \quad e''(x) \leq C_4he_k + C_4h\bar{e}_k + e''_k + \frac{h^{r+1}}{(r+1)!}\omega(y^{(r+3)}, h)$$

and

$$(19) \quad \bar{e}''(x) \leq C_5he_k + C_5h\bar{e}_k + \bar{e}''_k + \frac{h^{r+1}}{(r+1)!}\omega(z^{(r+3)}, h)$$

where $C_4 = L_1\left(e + \frac{1}{(r+1)!}\right)$ and $C_5 = L_2\left(e + \frac{1}{(r+1)!}\right)$ are constants independent of h .

To complete the convergence proof, we use the matrix inequality which is given in the following definition:

DEFINITION 1. Let $A = [a_{ij}]$, $B = [b_{ij}]$ be two matrices of the same order, then we say that $A \leq B$ iff

- (i) both a_{ij} and b_{ij} are nonnegative,
- (ii) $a_{ij} \leq b_{ij}$ for all i, j .

According to this definition, and if we use the matrix notation:

$$E(x) = [e(x) \quad \bar{e}(x) \quad e'(x) \quad \bar{e}'(x) \quad e''(x) \quad \bar{e}''(x)]^T$$

and

$$E_k = (e_k \quad \bar{e}_k \quad e'_k \quad \bar{e}'_k \quad e''_k \quad \bar{e}''_k)^T$$

then, we can write the estimations (14-19) in the following form:

$$(20) \quad E(x) \leq (I + hA)E_k + h^{r+1}\omega(h)B$$

$$\text{where } A = \begin{bmatrix} C_0 & C_0 & 1 & 0 & \frac{1}{2!} & 0 \\ C_1 & C_1 & 0 & 1 & 0 & \frac{1}{2!} \\ C_2 & C_2 & 0 & 0 & 1 & 0 \\ C_3 & C_3 & 0 & 0 & 0 & 1 \\ C_4 & C_4 & 0 & 0 & 0 & 0 \\ C_5 & C_5 & 0 & 0 & 0 & 0 \end{bmatrix}, \quad B = \begin{bmatrix} \frac{1}{(r+3)!} \\ \frac{1}{(r+3)!} \\ \frac{1}{(r+2)!} \\ \frac{1}{(r+2)!} \\ \frac{1}{(r+1)!} \\ \frac{1}{(r+1)!} \end{bmatrix},$$

I is the identity matrix of order 6 and

$$\omega(h) = \max\{\omega(y^{(r+3)}, h), \omega(z^{(r+3)}, h)\}.$$

Then, we give the following definition of the matrix norm.

DEFINITION 2. Let $T = [t_{ij}]$ be an $m \times n$ matrix, then we define

$$\|T\| = \max_i \sum_{j=1}^n |t_{ij}|.$$

According to this definition, we get:

$$(21) \quad \|E(x)\| = \max\{e(x), \bar{e}(x), e'(x), \bar{e}'(x), e''(x), \bar{e}''(x)\}.$$

Since (20) is valid for all $x \in [x_k, x_{k+1}]$, $k = 0(1)n-1$, then the following inequalities hold true:

$$\begin{aligned} \|E(x)\| &\leq (1 + h\|A\|)\|E_k\| + h^{r+1}\omega(h)\|B\| \\ (1 + h\|A\|)\|E_k\| &\leq (1 + h\|A\|)^2\|E_{k-1}\| + h^{r+1}\omega(h)\|B\|(1 + h\|A\|) \\ (1 + h\|A\|)^2\|E_{k-1}\| &\leq (1 + h\|A\|)^3\|E_{k-2}\| + h^{r+1}\omega(h)\|B\|(1 + h\|A\|)^2 \\ &\dots \dots \dots \\ (1 + h\|A\|)^k\|E_1\| &\leq (1 + h\|A\|)^{k+1}\|E_0\| + h^{r+1}\omega(h)\|B\|(1 + h\|A\|)^k \end{aligned}$$

Adding L.H.S. and R.H.S. of these inequalities and noting that $\|E_0\| = 0$, we get:

$$\|E(x)\| < C_6 h^r \omega(h)$$

Where $C_6 = \frac{\|B\|}{\|A\|} (e^{\|A\|} - 1)$, is a constant independent of h .

Then applying (21), we get:

$$(22) \quad \begin{aligned} e(x) &\leq C_6 h^r \omega(h) = O(h^{r+\alpha}), \\ \bar{e}(x) &\leq C_6 h^r \omega(h) = O(h^{r+\alpha}), \\ e'(x) &\leq C_6 h^r \omega(h) = O(h^{r+\alpha}), \\ \bar{e}'(x) &\leq C_6 h^r \omega(h) = O(h^{r+\alpha}), \\ e''(x) &\leq C_6 h^r \omega(h) = O(h^{r+\alpha}) \end{aligned}$$

and

$$\bar{e}''(x) \leq C_6 h^r \omega(h) = O(h^{r+\alpha})$$

Now, we estimate $|y^{(q)}(x) - s_k^{(q)}(x)|$ where $q = 3(1)r + 2$.

Using (3), (5), (7), (9), (11), (12), and (22), we get:

$$(23) \quad \begin{aligned} |y^{(q)}(x) - s_k^{(q)}(x)| &= \sum_{j=q-3}^{r-1} |y_k^{(j+3)} - f_{1,k}^{(j)}| \frac{|x - x_k|^{j+3-q}}{(j+3-q)!} + \\ &+ |y^{(r+3)}(\xi_k) - f_{1,k}^{(r)}| \frac{|x - x_k|^{r+3-q}}{(r+3-q)!} \leq \\ &\leq C_7 h^{r+3-q} \omega(h) = O(h^{\alpha+r+3-q}) \end{aligned}$$

where C_7 is a constant independent of h .

For the case $q = r + 3$, we use (5), (7), (12) and (22) we get:

$$\begin{aligned} |y^{(r+3)}(x) - s_k^{(r+3)}(x)| &= |y^{(r+3)}(\xi) - f_{1,k}^{(r)}| \leq \\ &\leq C_8 \omega(h) = O(h^\alpha) \end{aligned}$$

where $C_8 = 1 + 2L_1 C_6$, is a constant independent of h .

In a similar manner, using (4), (6), (8), (9) and (22), it can be shown that:

$$\left| z^{(q)}(x) - \bar{s}_k^{(q)}(x) \right| \leq C_9 h^{r+3-q} \omega(h) = O(h^{\alpha+r+3-q})$$

and

$$\left| z^{(r+3)}(x) - \bar{s}_k^{(r+3)}(x) \right| \leq C_{10} \omega(h) = O(h^\alpha)$$

where $q = 3(1)r+2$ and C_9, C_{10} are constants independent of h .

Thus, we have proved the following theorem:

THEOREM. Let $S_\Delta(x)$ and $\bar{S}_\Delta(x)$ be the approximate solutions to problem (1)–(2) given by equations (5)–(6), and let $f_1, f_2 \in C^r([0,1] \times \mathbb{R}^2)$.

Then for all $x \in [x_k, x_{k+1}]$, $k = 0(1)n-1$, we have:

$$\left| y^{(i)}(x) - s_k^{(i)}(x) \right| \leq Ch^r \omega(h), \quad i = 0(1)2,$$

$$\left| z^{(i)}(x) - \bar{s}_k^{(i)}(x) \right| \leq Ch^r \omega(h), \quad i = 0(1)2,$$

$$\left| y^{(i)}(x) - s_k^{(i)}(x) \right| \leq kh^{r+3-j} \omega(h)$$

and

$$\left| z^{(i)}(x) - \bar{s}_k^{(i)}(x) \right| \leq k^* h^{r+3-j} \omega(h)$$

where $j = 3(1)r+3$, c, k and k^* are constants independent of h .

NUMERICAL EXAMPLE

Consider the following system of differential equations:

$$y''' = y - z + 2x + e^{-x}, \quad y(0) = 1, y'(0) = 0, y''(0) = 1,$$

$$z''' = y - z + 2x + e^x, \quad z(0) = 1, z'(0) = 0, z''(0) = 1.$$

The method is tested using this example in the interval $[0, 1]$ with step size $h = 0.1$ where $r = 0$.

The analytical solution is:

$$y(x) = e^x - x,$$

$$z(x) = e^{-x} + x.$$

The tabulated results, appearing in the following table, are evaluated at the point $x = 0.25$.

Table

	analytical value	numerical value	absolute error
y	1.03403	1.03392	1.05417E-04
z	1.028800783	1.028698843	1.0194007E-04
y'	0.2840254167	0.28258275	0.0014426667
z'	0.2211992169	0.2199325875	0.001266629424
y''	1.284025417	1.27159	0.012435417
z''	0.7788007831	0.7685835	0.0102172831
y'''	1.284025417	1.22140	0.06262541668
z'''	-0.7788007831	-0.81873	0.0399292169

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