1	Microstructurally related model for predicting
2	behaviour of unsaturated soils with double porosity in
3	triaxial space
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11	ABSTRACT
12	Microstructure can have an important impact on the hydraulic and mechanical
13	behaviour of unsaturated soil and so it is necessary for it to be considered in constitutive
14	models to enable accurate predictions of soil behaviour. This paper focuses on
15	constitutive modelling of soils exhibiting a dual-porosity structure. Based on the
16	assumption that macro and micropores contained in the double porosity structure have
17	different influences on the mechanical and hydraulic behaviour, the effective degree of
18	saturation was selected as a microstructural index. This microstructural index was
19	implemented within a Bishop's effective stress based approach and the Glasgow
20	Coupled Model and the Modified Camclay Model were adopted as the basic framework
21	for the development of a constitutive model. Typical samples of low-expansive, non-
22	expansive and collapsible soils with dual porosity were selected to validate the model's

23 performance, with the model found to perform well when compared with experimental

24 data in terms of isotropic compression, triaxial shear and wetting tests.

Key words: unsaturated soils; coupled constitutive model; effective degree of saturation;
 microstructure

27 INTRODUCTION

28 Recently, there has been growing interest in how the microstructure affects the 29 hydraulic and mechanical behaviour of unsaturated soils (Cai et al. 2014, 2020b; a; Cuisinier et al. 2011; Jia et al. 2020; Low et al. 2008; Manahiloh et al. 2016; 30 31 Ranaivomanana et al. 2017; Romero and Simms 2008; Sánchez et al. 2016; Sergeyev 32 et al. 1980; Tian-er and Lin 2010; Trzciński and Wójcik 2019). The microstructure can 33 be classified as having single or double porosity (Alazaiza et al. 2017; Bagherieh et al. 2009; Russell 2010) according to features of pore size distribution (PSD). The PSD for 34 35 double porosity manifests significant bimodality, which is related to the presence of both macro and micropores (Casini et al. 2012; Lewandowska et al. 2004; Musso et al. 36 37 2014; Ngien et al. 2012). According to Li et al (2019), the macropores are mainly 38 deformed during loading while the micropores are less affected; however, during drying 39 and wetting process, the micropores will exhibit significant changes and be 40 accompanied by reversible volumetric deformation.

A review of the literature (Cai et al. 2018; Li et al. 2013, 2019; Mašín 2013; Mašín
et al. 2005) suggests that there are two ways to consider the effects of double porosity
on the hydraulic and mechanical behaviour of unsaturated soils. The first way is

44 adopting a specific microstructural index to represent the main features of double porosity. For example, the effective degree of saturation can be adopted as this index 45 considers the different impacts of water within macropores and micropores, which 46 47 provides an indirect way to take features of double porosity into consideration. 48 Adopting this approach, Cai et al. (2018) established a hydro-mechanical coupled 49 constitutive model based on the Glasgow Coupled Model that was validated against 50 isotropic compression tests of double-porosity soils. Li et al. (2019) also used the 51 effective degree of saturation to establish a model for unsaturated soils with double 52 porosity. Their model used average effective stress, deviator stress and modified suction as the main stress variables. However, the model established by Cai et al (2018) is 53 54 limited to isotropic loading and so cannot consider shear response. Also whilst the 55 model established by Li et al. (2019) can consider shear response it adopts average 56 effective stress as one of the main stress variables and so cannot consider how the three 57 principal stresses will change respectively in a triaxial space, such as during shear at a 58 constant net mean stress. A second way is to establish mutually independent models for 59 the loading behaviour of macropores and micropores. For example, Mašin (2013) used different constitutive models for the behaviour of macropores and micropores and 60 satisfactorily reproduced macro-mechanical properties by establishing a corresponding 61 62 coupling relationship. However, this model has a complex form and requires determination of numerous material parameters, which limits its practical application. 63 64 This paper introduces a microstructurally based constitutive model for unsaturated 65 soils with double porosity. The key contribution is that the model adopts effective degree of saturation as the microstructural index and uses the Glasgow Coupled Model 66 67 as the basic framework to acquire a concise constitutive relationship, which needs only nine physically meaningful parameters. The generalized tensor and Modified Camclay 68 69 Model (Roscoe and Burland 1968) were adopted to extend the model to a three-70 dimensional space where both isotropic compression and shear loading can be 71 simulated. The model is validated through experimental results of low-expansive 72 Speswhite kaolin (Sivakumar 1993), low-plastic clay (Almahbobi 2018) and non-73 expansive Jossigny silt (Cui and Delage 1996) in terms of wetting, saturated and 74 unsaturated, isotropic compression and shear tests.

75

CONSTITUTIVE MODEL

The effective degree of saturation was adopted to consider the effects of double 76 77 porosity on the mechanical and hydraulic behaviour of unsaturated soils. The model was established based on the framework of the Glasgow Coupled Model (GCM) 78 79 (Wheeler et al. 2003). The GCM is an important constitutive model which considers 80 the impact of degree of saturation on effective stress and behaviour of unsaturated soils. 81 Unlike other models which adopt a single loading-collapse yield curve in the net mean 82 stress-suction plane to study the elasto-plastic mechanism during suction decrease or 83 mechanical loading, the GCM utilises yield curves in the effective stress-modified 84 suction plane (see Fig. 1). These yield curves are: the loading-collapse line (LC), which 85 serves as the boundary between elastic volumetric change and plastic volumetric 86 change when the effective stress increases or decrease; the suction-decrease line (SD), which acts as the boundary between elastic and plastic changes of degree of saturation 87 88 when suction decreases; and the suction-increase line (SI) which is defined to represent 89 the position where plastic change of degree of saturation will occur during suction 90 increase. According to Lloret-Cabot et al. (2013), the generalized stress tensor was 91 adopted to study both mechanical and hydraulic in a unified framework and Modified 92 Camclay Model (Roscoe and Burland 1968) was adopted to extend the model to a three-93 dimensional space to study the shear behaviour of soils.

94 Effective Degree of Saturation

95 According to Alonso et al. (2010), pores within double-porosity soils can be grouped into two categories: macropores partially filled with freely available water (the 96 main source of suction) and micropores filled with bound water. Correspondingly, 97 degree of saturation Sr can also be separated into two components: macroscopic degree 98 of saturation S_r^M , which contributes to the mechanical behaviour of soils, and 99 microscopic degree of saturation S_r^m , which is considered constant and independent of 100 applied suction and load ($S_{\rm r}=S_{\rm r}^{\rm m}+S_{\rm r}^{\rm M}$). Subsequently the effective degree of 101 102 saturation can be defined as:

103
$$S_{\rm e} = \frac{S_{\rm r} - S_{\rm r}^{\rm m}}{1 - S_{\rm r}^{\rm m}}$$
(1)

with this definition, effective degree of saturation is a microstructurally based variable,
which considers the feature of double porosity and establishes a link between this

structure and the hydro-mechanical behaviour of soils. The effective degree of saturation can be represented by the residual degree of saturation because it is related to water stored within small occluded pores or intercrystalline pore space, where physico-chemical bonds hold the water to the solid and are not strongly related to applied suction or mechanical load, resulting in a very limited impact on effective stress (Alonso et al. 2010).

112 Stress Variables

According to Houlsby's theory (Houlsby 1997), the increment of work input *dW*per unit volume of unsaturated soil can be written as:

115
$$dW = [\sigma_{ij} - (S_r u_w + (1 - S_r) u_a \delta_{ij})] d\varepsilon_{ij} - (u_a - u_w) n dS_r$$
(2)

116 where σ_{ij} is the stress tensor, $d\varepsilon_{ij}$ is the strain increment tensor, δ_{ij} is the Kronecker 117 delta, u_w is the water pressure, u_a is the air pressure, S_r is the degree of saturation and 118 *n* is the porosity.

Incorporating the Bishop's effective stress (Bishop 1959) and the effective degree of saturation S_e into (2), the expression of the Bishop's stress tensor σ_{ij}^* and the modified suction s^* can be derived as:

122
$$\sigma_{ij}^{*} = \sigma_{ij} - (S_{e}u_{w} + (1 - S_{e})u_{a})\delta_{ij}$$
(3)

123 $s^* = (u_a - u_w)n$ (4)

124 Correspondingly, the stress and strain increment vectors have been adopted as 125 follows:

126
$$\mathbf{d\sigma}^* = (d\sigma_{xx}^*, d\sigma_{yy}^*, d\sigma_{zz}^*, d\sigma_{yz}^*, d\sigma_{yz}^*, d\sigma_{xz}^*)^T$$
(5)

127
$$\mathbf{d}\boldsymbol{\varepsilon} = (d\varepsilon_{xx}, d\varepsilon_{yy}, d\varepsilon_{zz}, d\varepsilon_{yz}, d\varepsilon_{yz}, d\varepsilon_{xz})^T$$
(6)

Following the approach of Lloret-Cabot et al. (2013) and taking the modified suction s^* and effective degree of saturation S_e as generalized stress and strain invariants, then the generalized stress and strain increment vectors can be written as:

131
$$\mathbf{d\sigma}^* = (d\sigma_{xx}^*, d\sigma_{yy}^*, d\sigma_{zz}^*, d\sigma_{yz}^*, d\sigma_{xz}^*, d\sigma_{xz}^*, ds^*)^T$$
(7)

132
$$\tilde{\mathbf{d\varepsilon}} = (d\varepsilon_{xx}, d\varepsilon_{yy}, d\varepsilon_{zz}, d\varepsilon_{xy}, d\varepsilon_{yz}, d\varepsilon_{zz}, -dS_{e})^{T}$$
(8)

For a hydro-mechanical coupled model, the increment of stress is the collective output of the force, suction and effective degree of saturation. According to (3) and (4), the formulas for the increments of generalized stress can be defined as:

136
$$d\sigma_{ij}^* = d(\sigma_{ij} - u_a \delta_{ij}) + (sdS_e + S_e ds)\delta_{ij}$$
(9)

$$ds^* = nds - \frac{sd\varepsilon_v}{v}$$
(10)

138 where $s=u_a - u_w$ is the suction, v is the specific volume and $d\varepsilon_v$ is the increment of 139 volumetric strain.

140 Yield Surfaces

Three yield surfaces, including the loading-collapse surface (LC), suction increase surface (SI) and suction decrease surface (SD) were adopted based on Lloret-Cabot et al., (2013), as seen in **Fig. 1**, in the $q: p^*: s^*$ stress space (where q is the deviatoric stress, p^* is the mean Bishop's stress). The Modified CamClay Model (MCC), with a unique M (assuming that a unique Critical State Line in the $q: p^*$ plane exists), was adopted as the reference model for the saturated condition. Then the algebraic expressions of the 147 three yield surfaces are given as follows:

148
$$F_{\rm LC} = q^2 - M^2 p^* (p_0^* - p^*) = 0$$
(11)

149
$$F_{\rm SI} = s^* - s_{\rm I}^* = 0$$
 (12)

150
$$F_{\rm SD} = s_{\rm D}^* - s^* = 0$$
 (13)

151 where p_0^* is the Bishop's pre-consolidation pressure which defines the position of F_{LC} ,

152 $s_{\rm I}^*$ and $s_{\rm D}^*$ are the modified suctions that locate $F_{\rm SI}$ and $F_{\rm SD}$, respectively.

153 Coupling between Yield Surfaces

Yielding on either of the three surfaces will lead to the movement of the other two surfaces. The plastic mechanisms and couplings of yield surfaces are defined as follows: 1) yielding on the LC yield surface (F_{s1}) will bring about plastic volumetric strain with no irreversible change of the effective degree of saturation S_e , which in turn triggers upward movements of the SI and SD surfaces. This coupling is established, with a coupling parameter k_2 , by:

160
$$\frac{ds_{\rm I}^*}{s_{\rm I}^*} = \frac{ds_{\rm D}^*}{s_{\rm D}^*} = k_2 \frac{dp_0^*}{p_0^*}$$
(14)

161 2) yielding on the SI/SD yield surfaces (F_{SI}/F_{SD}) will lead to a plastic reduction of 162 S_e but no change of plastic volumetric strain, which in turn induces upward/downward 163 movement of the SD/SI surfaces and outward/inward movement of the LC surface. 164 This coupling is established, with a coupling parameter k_1 , by:

165
$$\frac{dp_0^*}{p_0^*} = k_1 \frac{ds_1^*}{s_1^*} = k_1 \frac{ds_D^*}{s_D^*}$$
(15)

166 Flow Rules

Flow rules define the orientation of the generalized plastic strain increments during yielding. This paper assumes associated flow rules and adopts the generalized expression presented by Lloret Cabot et al., (2013):

170
$$d\tilde{\varepsilon}_{j}^{p} = d\lambda_{l}^{j} \frac{\partial F_{l}}{\partial \sigma}^{*} \quad \text{with} \quad l = \text{LC}, \beta; j = \text{LC}, \beta, \text{LC} + \beta; \beta = \text{SI} \quad \text{or} \quad \text{SD} \quad (16)$$

171 where $d\lambda_l^{j}$ is the plastic multiplier with *j* related to the plastic mechanism which is 172 active (e.g. when yield on LC yield surface is activated *j* is LC and for yield on SI or 173 SD *j* is LC is β) and *l* is associated with plastic changes of effective degrees of 174 saturation (when *l* is β) or volumetric strains (when *l* is LC).

175 Hardening Laws

176 The generalized hardening laws determining the relationships between increments 177 of plastic volumetric strain $d\varepsilon_v^p$, increments of the plastic effective degree of saturation 178 dS_e^p , and increments of the hardening variables dp_o^* , ds_1^* , ds_D^* are as follows:

179
$$dp_o^* = p_0^* \left[\frac{v d\varepsilon_v^p}{\lambda - \kappa} - \frac{k_1 dS_e^p}{\lambda_s - \kappa_s} \right]$$
(17)

180
$$ds_{\rm I/D}^* = s_{\rm I/D}^* \left[-\frac{dS_{\rm e}^{\rm p}}{\lambda_{\rm s} - \kappa_{\rm s}} + k_2 \frac{\nu d\varepsilon_{\rm v}^{\rm p}}{\lambda - \kappa} \right]$$
(18)

181 Generalized Stress-Strain Relationship

182 Current knowledge on the elasto-plastic mechanisms of unsaturated soils indicates
183 that the generalized strains can be separated into elastic and plastic components (Lloret-

184 Cabot et al. 2013), so the increment of total generalized strains can be expressed as:

185
$$d\tilde{\boldsymbol{\varepsilon}} = d\tilde{\boldsymbol{\varepsilon}}^{\text{e}} + d\tilde{\boldsymbol{\varepsilon}}_{j}^{\text{p}}$$
 with $j = \text{LC}, \beta, \text{LC} + \beta; \beta = \text{SI}$ or SD (19)

186 where j is as defined in equation (16).

187 When only one elastic mechanism is activated, the generalized stress-strain188 relationship can be expressed as:

189

$$d\mathbf{\sigma} = \mathbf{D}_{\rm e}^* d\mathbf{\hat{\epsilon}} \tag{20}$$

190 where \mathbf{D}_{e}^{*} is the generalized elastic matrix written in terms of the elastic bulk modulus 191 *K*, the slope of the scanning curve in the water retention plane κ_{s} and the Poisson's 192 ratio μ . Full details of \mathbf{D}_{e}^{*} and \mathbf{D}_{ep}^{*} , the generalized elasto-plastic matrix, are presented 193 in Appendix A.

194 There are nine parameters required in this microstructurally related constitutive model, namely λ , κ , k_1 , k_2 , M, μ , λ_s , κ_s and S_{res} . λ and κ are the slopes of 195 196 normal consolidation line for saturated soil and slope of rebound curve, and they are 197 related to the volumetric deformation during loading. k_1 and k_2 reflect the coupled movement between yield surfaces. To determine k_1 and k_2 , two sets of data where both 198 199 plastic volumetric strain and plastic change of degree of saturation are witnessed during loading (the parameters can be determined by using this data to solve equation (17) and 200 equation (18)). M is a parameter that represents the relationship between deviator 201 202 stress and effective stress under critical state and can be acquired by considering standard triaxial test data. μ is Poisson's ratio. λ_{s} , κ_{s} and S_{res} are the slopes of the 203 main drying/wetting curve, the slope of scanning curve and residual degree of saturation, 204

respectively. The residual degree of saturation can be gained by drawing two tangents
at the start point and end point of the residual phase in a soil-water characteristic curve
and taking the degree of saturation at the intersection as the residual degree of saturation
(Eyo et al. 2022).

209 MODEL VALIDATION

210 To test the applicability of the proposed model, reported behaviour of a series of 211 statically compacted samples of soils with double porosity (Speswhite kaolin, lowplastic clay and Jossigny silt) are considered. Speswhite kaolin is a low-expansive clay 212 213 with dominant mineral as kaolinite and 75% clay fraction, which has a higher rate of 214 consolidation compared with other clay soils (Sivakumar 1993). The low-plastic soil 215 is a mixture of 40% Leighton Buzzard sand, 40% M400 silt and 20% Speswhite kaolin 216 (Almahbobi, 2018). The soil showed significant collapsibility, in that it had a 16.2% 217 vertical strain in a single oedometer test where the specimens were compacted at water content of 10% and dry unit weight of 14kN/m³, and applied vertical pressure was 218 219 increased to 50kPa. The plasticity index is 8%. According to the Unified Soil 220 Classification System (USCS), the soil can be classified as low-plastic clay. Jossigny silt originates from the eastern region of Paris and typically shows little swelling on 221 222 wetting. The soil is composed of illite, kaolinite and interstratified illite-smectite. The liquid limit and plastic limit are 37% and 19%, respectively (Cui and Delage 1996). 223 224 Experimental data in terms of wetting, isotropic compression and shear response of

these soils are used to validate the model's performance.

226 Speswhite Kaolin

227 Isotropic compression

228 Suction-controlled triaxial tests reported by Sivakumar (1993) on compacted 229 samples of Speswhite kaolin and conducted under both isotropic compression and shear have been considered. For isotropic loading, Path 1 was carried out by compressing the 230 initial sample (mean net stress $\overline{p} = 50$ kPa) to $\overline{p} = 250$ kPa at a constant suction of 300kPa; 231 Path 2 was carried out by wetting the initial sample (mean net stress $\overline{p} = 50$ kPa) to 232 s=100kPa and then compressing it to p=200kPa at a constant suction of 100kPa (see 233 234 Fig. 2). Model parameters and initial states given by Lloret-Cabot et al. (2013) are 235 shown in **Table 1**.

For both isotropic loading paths, the increasing net mean stress \overline{p} resulted in 236 overall compression and a decrease in void ratio. As noted by Lloret-Cabot et al. (2013), 237 238 the initial stress state lay on the SD yield surface for both paths. This meant that as the 239 modified suction reduced, yielding invariably occurred on the SD yield surface, which brought about a coupled inward movement of the LC yield surface and downward 240 241 movement of SI yield surface. Before yielding on the SD surface there was no 242 significant change in the void ratio or degree of saturation mainly because the modified 243 suction did not decrease rapidly. In path 1, when the mean effective stress reached about 244 275kPa, the sample yielded on both the LC and SD yield surface. This yielding induced considerable amounts of plastic volumetric strain resulting in a significant decrease in 245 246 void ratio (see Fig. 3 (b)). Since the yielding on the LC yield surface results in a coupled upward movement of the SD yield surface, this also generated a significant increase in
degree of saturation (see Fig. 3 (c)). Fig. 3 also presents a similar pattern of behaviour
for Path 2. Overall, it can also be seen that the proposed model is able to reproduce
well the isotropic loading behaviour of the Speswhite kaolin sample.

251 Shear loading

252 The loading of Speswhite kaolin samples included shear tests at constant confining stress and constant mean net stress. Both tests were carried out while suction remained 253 254 unchanged. Before conducting the shear test at constant confining stress the sample was compressed from initial conditions of $\overline{p} = 50$ kPa and s = 300kPa to $\overline{p} = 150$ kPa. The 255 axial stress σ_1 was then increased until reaching failure ($\sigma_2 = \sigma_3 = 150$ kPa , 256 s = 300kPa). For shear tests at constant net mean stress, the loading path included 257 wetting the initial sample (\overline{p} =50kPa and s=300kPa) to s=100kPa and then compressing 258 it to \overline{p} =200kPa before shearing it until failure. The model parameters and initial states 259 260 are again as presented in Table 1.

Fig. 4 shows the simulated and experimental results of shear tests at constant confining stress and net mean stress. The constant confining stress path yielded on both the LC and SD yield surface due to the previous isotropic compression where the net mean stress was increased to 150kPa. Yielding on the LC yield surface brought about significant plastic volumetric deformation and a decrease of void ratio (see Fig. 4 (b)). Meanwhile, the coupled upward movement of the SD yield surface resulted in a significant increase in degree of saturation (see Fig. 4 (c)). As shown in Fig. 4, the simulated stress path is consistent with the experimental path, however the developed axial strain ε_a is larger compared with the observed behaviour. This over prediction of axial strain whilst a soil tends towards critical state is a previously reported phenomenon which is attributed to the deficiency of the Modified Camclay Model (Lloret-Cabot et al. 2013). Generally, it can be observed that the proposed model can satisfactorily reproduce the development of void ratio and degree of saturation during shear.

For the shear test at constant net mean stress, the yielding also occurred on the LC and SD yield surfaces and generated a large amount of plastic change of void ratio and degree of saturation (see **Fig. 4** (e) and (f)). Although the proposed model overestimates the axial strain at critical state (see **Fig. 4** (d)), it can generally represent the mechanical and hydraulic behaviour of the Speswhite kaolin sample.

280 Low-Plastic Clay

281 The soil samples were prepared by adding quantities of distilled water to dry 282 mixtures with a target initial water content of 10%. Then the soil-water mixtures were 283 compacted in a mould until an axial pressure equivalent to 998kPa was reached. The 284 final dry unit weight of the soil samples was 15kN/m³. The measured initial void ratio, 285 degree of saturation and suction were 0.732, 36.2% and 563kPa, respectively, and for the tests considered here the sample was first isotropically loaded under a confining 286 stress of 20kPa. Model parameters and initial states are estimated from calibrating 287 experimental data of wetting, isotropic compression and shear tests provided by 288

Almahbobi (2018). λ , κ , k_1 and k_2 are from isotropic compression tests. M is attained from shear tests and μ is assumed to be 0.3. λ_s , κ_s and S_{res} are obtained from the reported soil-water characteristic curve. Model parameters and initial states are shown in **Table 2**.

293 Wetting

294 The sample was initially wetted to a suction equivalent to 500kPa (at constant 295 confining stress of 20kPa) and compressed to net mean stress equivalent to 100kPa (at 296 constant suction of 500kPa), the suction of the sample was then decreased in a stepwise 297 manner to 5kPa. Experimentally observed behaviour showed the void ratio 298 monotonically decreasing during wetting, along with a decrease in effective stress. This 299 behaviour is consistent with the highly collapsible nature of the soil (Almahbobi 2018). 300 Degree of saturation increased significantly with suction decrease and was close to 301 saturation at the final suction of 5kPa. The proposed model simulated yielding on both 302 the LC and SD yield surfaces throughout the wetting stress path (the initial stress state 303 was located at the corner intersection of both) leading to a prediction of a significant 304 decrease in void ratio and increase of degree of saturation. The modelled behaviour is consistent with the experimental behaviour, with the model successfully reproducing 305 306 the collapsibility and saturation increase observed during wetting (see Fig. 5).

307 Isotropic compression

308 For saturated compression, the initial samples were wetted to saturation at a 309 confining stress of 20kPa and then compressed to target net mean stresses of 100, 250 and 400kPa, respectively.

311 Table 3 compares experimentally reported and proposed model calculated void 312 ratio and water content at the end of compression. Both the void ratio and water content 313 decreased during compression due to the volumetric compression and water discharge 314 induced by the increasing net mean stress. The differences between model results and 315 experimental results are small with relative differences always less than 10% and below 316 5% for some data. It can be seen that the model performs well when predicting the void 317 ratio and water content in a saturated compression test (see Table 3). 318 For unsaturated compression, the initial samples were wetted to a suction equivalent to 300kPa at the confining stress of 20kPa and then compressed to target net mean 319 stresses of 100, 250 and 400kPa. Experimental and model results are again shown in 320 321 Table 3 and it can be seen that the model matches the experimental behaviour well (relative differences are around 1% for void ratio and less than 10% for degree of 322 323 saturation), demonstrating the effectiveness of the model in reproducing hydro-324 mechanical behaviour in unsaturated compression (see Table 3).

325 Shear loading

After the compression stage described above each of the saturated and unsaturated samples were sheared at a constant confining stress equivalent to the net mean stress at the end of compression. The experimentally measured void ratio and water content at the start of the shear loading stage were used in the proposed model.

330 In the saturated shear tests the deviatoric stress was observed to increase with

331 increase in axial strain and reached a peak at an axial strain of 25%. The samples with higher confining stress had a higher peak of deviatoric stress. The peaks of deviatoric 332 333 stress were 172, 436 and 660kPa, respectively, for the samples with confining stress 334 equivalent to 100, 250 and 400kPa. The volumetric strain also increased and the sample 335 with larger confining stress generated more significant volumetric deformation. In the 336 model, the stress path remained yielding on both LC and SD yield surfaces and so 337 volumetric strain developed further during shear. The modelled deviatoric stresses were 338 consistent with the experimental results (see Fig. 6(a)). The model also performs well 339 in terms of void ratios (see Fig. 6 (b)). Similar conclusions can also be drawn from the 340 unsaturated shear tests with the model demonstrating satisfactory performance (see Fig. 341 6 (c), (d)). For Fig. 6 (d), the model satisfactorily reproduced the change of void ratio 342 when the confining stress is 400kPa. However, whilst the model correctly captures the 343 overall trends of decreasing volume during shear, it overpredicts the magnitude of 344 changes in void ratio when the confining stresses are 100kPa and 250kPa.

345 Jossigny Silt

Cui and Delage (Cui and Delage 1996) studied the yielding and plastic behaviour of unsaturated compacted samples of the Jossigny silt through isotropic compression and shear tests. According to the experimental results reported by Cui and Delage (1996), λ , κ , k_1 and k_2 are based on the isotropic compression tests. *M* is attained from shear tests and μ is assumed to be 0.3. λ_s and κ_s are obtained from the reported soil-water characteristic curve. The model parameters and initial states are presented in 352 **Table 4**. The microscopic degree of saturation S_{res} was estimated by Alonso et al 353 (2010).

The samples were firstly wetted to target suctions (200, 400, 800 and 1500kPa) and then compressed to target net mean stresses (50, 100, 200, 400 and 600kPa) before they were sheared at constant cell pressures (50, 100, 200, 400 and 600kPa). The shear stage terminated when the critical state was reached.

358 Isotropic compression

Table 5 presents the comparison between model results and experimental results for isotropic compression at both a constant suction equivalent to 200kPa and at a constant net mean stress equivalent to 200kPa. It can be concluded that the model performs well in isotropic compression with the simulated development of void ratio and degree of saturation satisfactorily consistent with the experimental results.

364 Shear

Shear tests were conducted after the target suctions and net mean stresses were reached in the compression tests mentioned above. Shear tests continued until the critical state was reached. **Fig. 7** presents the deviatoric stress/void ratio-axial strain relationship in shear tests at constant suction equivalent to 200kPa and **Table 6** shows the comparison on degree of saturation between model results and experimental results when critical states are reached.

In general, the model can reproduce the changing trend of deviatoric stress withrespect to the axial strain despite the model tending to overestimate the axial strain at a

373 specific deviatoric stress (see Fig. 7 (a)). The model also performs well in predicting the trends in degree of saturation (see Table 6) during shear but does overpredict the 374 375 magnitude of the change of void ratio, as shown in Fig. 7 (b). It is noted that as the 376 wetting and compression steps, undertaken before shearing commenced, are also 377 included in the simulation there is different in the predicted and measured void ratios 378 at zero axial strain. It can also be noticed in Fig. 7 (a) that there are discontinuities of 379 the gradient for shear tests at cell pressure equivalent to 50 and 200kPa because the 380 stress paths for these tests reached the LC yield surface during shearing. The stress path 381 for the shear test at cell pressure equivalent to 600kPa had reached the LC yield surface 382 during the isotropic compression stage so there is no discontinuity observed on the 383 curve.

For shear tests at constant cell pressure equivalent to 200kPa, **Fig. 7** (c), (d) present the deviatoric stress/void ratio-axial strain relationship and **Table 6** shows the comparison on degree of saturation between model results and experimental results at the end of shear tests. It is clear that the model performs well under different suctions by satisfactorily reproducing the trends of behaviour but does exhibit a tendency to overpredict the magnitude of changes in void ratio.

390 CONCLUSIONS

A hydro-mechanical coupled constitutive model for unsaturated soils with double
porosity is proposed in this paper, based on the framework of Glasgow Coupled Model.
Since the Glasgow Coupled Model does not consider microstructure, the model

394 established in this paper adopts effective degree of saturation as a microstructural index and introduces this index into Bishop's effective stress to establish the Bishop's 395 396 effective stress formula that can consider the characteristics of the double porosity. The 397 model also adopted the Modified Camclay Model in the average effective stress-398 deviatoric stress plane. The expressions of the model were derived by combining the 399 generalized stress-strain tensor, associated flow law, hardening law and consistency 400 conditions. The novelty of the established model lies in the combination of effective degree of saturation, Glasgow Coupled Model and Modified Camclay Model to provide 401 402 a convenient and straightforward way to model the behaviour of double-porosity soils 403 utilising only nine physically meaningful parameters.

The model has been validated against experimentally observed behaviour of 404 405 double-porosity samples, such as the compacted samples of Speswhite kaolin (low-406 expansive), low-plastic clay (highly collapsible) and Jossigny silt (non-expansive). The 407 validation results show that the model is able to predict with reasonable accuracy the hydro-mechanical coupled characteristics of unsaturated soils with double porosity, 408 409 whether the soil is collapsible or non-expansive. In terms of isotropic compression and wetting behaviour, the model satisfactorily reproduces both the mechanical behaviour 410 411 (the variation of the modified suction and the void ratio) and hydraulic behaviour (the 412 variation of degree of saturation). The model also performs well in terms of shear 413 response. The model results are generally consistent with the experimental results in terms of void ratio and degree of saturation, but the model, to some extent, overpredicts 414

the axial strain at specific deviatoric stress. This feature is not unexpected as the Modified Camclay Model usually overestimates the axial strain developed during shear on the path to reach critical state. Overall, it is demonstrated that the inclusion of effective degree of saturation in such model is beneficial to consider the effect of microstructure, especially double porosity, on the behaviour of unsaturated soils and the proposed model is reliable in predicting the hydro-mechanical coupled behaviour of collapsible and non-expansive soils with double porosity.

422

423 APPENDIX A

424 The full expression for \mathbf{D}_{e}^{*} is given as follows:

425
$$\mathbf{D}_{e}^{*} = \begin{pmatrix} E_{11} & E_{12} & E_{13} & 0 & 0 & 0 & 0 \\ E_{21} & E_{22} & E_{23} & 0 & 0 & 0 & 0 \\ E_{31} & E_{32} & E_{33} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & E_{44} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & E_{55} & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & E_{66} & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & E_{77} \end{pmatrix} = \begin{pmatrix} \mathbf{D}_{e \ 6 \times 6} & 0 \\ 0 & \gamma_{e \ 1 \times 1} \end{pmatrix}$$
(21)

426
$$E_{11} = E_{22} = E_{33} = K + \frac{4}{3G} = \left(\frac{v}{\kappa}\right)p^* + \frac{4}{3G}$$
(22)

427
$$E_{44} = E_{55} = E_{66} = G = \frac{3K(1-2\mu)}{2(1+\mu)}$$
(23)

428
$$E_{12} = E_{23} = E_{13} = K - \frac{2}{3G}$$
(24)

429
$$E_{77} = \gamma_{\rm e} = \left(\frac{1}{\kappa_{\rm s}}\right) s^* \tag{25}$$

430 where K is the bulk modulus and G is the shear modulus.

431 When a plastic mechanism is active, the generalized stress-strain relationship can

432 be also assumed as follows:

433
$$d\boldsymbol{\sigma}^* = \mathbf{D}_e^* d\tilde{\boldsymbol{\varepsilon}}^e = \mathbf{D}_{ep}^* d\tilde{\boldsymbol{\varepsilon}}$$
(26)

 \boldsymbol{D}_{ep}^{*} is the generalized elasto-plastic matrix, depending on the specific plastic 434 mechanism(s) active during loading. \boldsymbol{D}_{ep}^{*} is unknown hitherto, but the expression of it 435 436 can be obtained by the following approach.

Considering the general case that two plastic mechanisms are active, the expression 437

(26) can be written as 438

439
$$d\boldsymbol{\sigma}^{*} = \mathbf{D}_{\mathbf{e}}^{*} d\tilde{\boldsymbol{\varepsilon}}^{\mathbf{e}} = \mathbf{D}_{\mathbf{e}}^{*} \left(d\tilde{\boldsymbol{\varepsilon}} - d\tilde{\boldsymbol{\varepsilon}}_{\mathrm{LC}+\beta}^{\mathrm{p}} \right)$$
(27)

440 Then considering the flow rule (16),

441
$$d\tilde{\varepsilon}_{LC+\beta}^{p} = d\lambda_{LC}^{LC+\beta} \frac{\partial F_{LC}}{\partial \sigma} + d\lambda_{\beta}^{LC+\beta} \frac{\partial F_{\beta}}{\partial \sigma}^{*}$$
(28)

442 To keep the end of the stress path invariably attached on yield surfaces after yielding, the consistency condition on $F_{\rm LC}$ and F_{β} should be considered: 443

444
$$dF_{\rm LC} = \left(\frac{\partial F_{\rm LC}}{\partial \boldsymbol{\sigma}^*}\right)^T d\boldsymbol{\sigma}^* + \frac{\partial F_{\rm LC}}{\partial p_0^*} dp_0^* = 0 \tag{29}$$

445
$$dF_{\beta} = \left(\frac{\partial F_{\beta}}{\partial s^{*}}\right)^{T} ds^{*} + \frac{\partial F_{\beta}}{\partial s^{*}_{\beta}} ds^{*}_{\beta} = 0$$
(30)

Incorporating (29), (30) and hardening laws (17) and (18), the following 446 447 expressions can be obtained:

448

450

$$452 \qquad \left(\frac{\partial F_{\rm LC}}{\partial \mathbf{\sigma}^*}\right)^T \mathbf{D}_{\rm e} \left(d\mathbf{\varepsilon} - d\,\chi_{\rm LC}^{\rm LC+\beta}\,\frac{\partial F_{\rm LC}}{\partial \mathbf{\sigma}^*}\right) + \frac{\partial F_{\rm LC}}{\partial p_o^*}\,p_o^* \left[\nu \frac{m^T d\,\lambda_{\rm LC}^{\rm LC+\beta}\,\frac{\partial F_{\rm LC}}{\partial \mathbf{\sigma}^*}}{\lambda - \kappa} - \frac{k_{\rm I} d\,\lambda_{\beta}^{\rm LC+\beta}\,\frac{\partial F_{\beta}}{\partial s^*}}{\lambda_{\rm s} - \kappa_{\rm s}}\right] = 0 \tag{32}$$

453 Then the plastic multiplies can be derived as:

454
$$d\lambda_{\rm LC}^{\rm LC+\beta} = \frac{\mathbf{a}_{\rm LC+\beta}^T d\mathbf{\varepsilon} + b_{\rm LC+\beta} dS_{\rm e}}{h_{\rm LC+\beta}}$$
(33)

455
$$d\lambda_{\beta}^{\mathrm{LC}+\beta} = \frac{\mathbf{c}_{\mathrm{LC}+\beta}^{T} d\mathbf{\varepsilon} + d_{\mathrm{LC}+\beta} dS_{\mathrm{e}}}{h_{\mathrm{LC}+\beta}}$$
(34)

456 where

457
$$\mathbf{a}_{\mathrm{LC}+\beta}^{T} = \left(\frac{\partial F_{\mathrm{LC}}}{\partial \boldsymbol{\sigma}^{*}}\right)^{T} \mathbf{D}_{e} \left(\frac{\partial F_{\beta}}{\partial s^{*}} \gamma_{e} \frac{\partial F_{\beta}}{\partial s^{*}} - \frac{\partial F_{\beta}}{\partial s^{*}_{\beta}} s_{\beta}^{*} \frac{1}{\lambda_{s} - \kappa_{s}} \frac{\partial F_{\beta}}{\partial s^{*}}\right)$$
(35)

458
$$b_{\mathrm{LC}+\beta} = -k_1 \frac{\partial F_{\beta}}{\partial s^*} \gamma_e \frac{\partial F_{\mathrm{LC}}}{\partial p_0^*} \frac{p_0^*}{\lambda_s - \kappa_s} \frac{\partial F_{\beta}}{\partial s^*}$$
(36)

459
$$\mathbf{c}_{\mathrm{LC}+\beta}^{T} = k_{2} \left(\frac{\partial F_{\mathrm{LC}}}{\partial \mathbf{\sigma}^{*}}\right)^{T} \mathbf{D}_{\mathbf{e}} \frac{\partial F_{\beta}}{\partial s_{\beta}^{*}} v \frac{s_{\beta}^{*}}{\lambda - \kappa} m^{T} \frac{\partial F_{\mathrm{LC}}}{\partial \mathbf{\sigma}^{*}}$$
(37)

460
$$d_{\mathrm{LC}+\beta} = \frac{\partial F_{\beta}}{\partial s^{*}} \gamma_{\mathrm{e}} \left(-\left(\frac{\partial F_{\mathrm{LC}}}{\partial \boldsymbol{\sigma}^{*}}\right)^{T} \mathbf{D}_{\mathrm{e}} \frac{\partial F_{\mathrm{LC}}}{\partial \boldsymbol{\sigma}^{*}} + \frac{\partial F_{\mathrm{LC}}}{\partial p_{0}^{*}} \frac{v}{\lambda - \kappa} m^{T} \frac{\partial F_{\mathrm{LC}}}{\partial \boldsymbol{\sigma}^{*}} \right)$$
(38)

$$h_{_{\mathrm{LC}+\beta}} = \left[-\left(\frac{\partial F_{\mathrm{LC}}}{\partial \sigma^*}\right)^T \mathbf{D}_{\mathbf{e}} \frac{\partial F_{\mathrm{LC}}}{\partial \sigma^*} + \frac{\partial F_{\mathrm{LC}}}{\partial p_0^*} \frac{\nu}{\lambda - \kappa} p_0^* m^T \frac{\partial F_{\mathrm{LC}}}{\partial \sigma^*} \right]$$

$$+ \left[-\frac{\partial F_{\beta}}{\partial s^*} \gamma_{\mathbf{e}} \frac{\partial F_{\beta}}{\partial s^*} + \frac{\partial F_{\beta}}{\partial s_{\beta}^*} s_{\beta}^* \frac{1}{\lambda_{\mathrm{s}} - \kappa_{\mathrm{s}}} \frac{\partial F_{\beta}}{\partial s^*} \right]$$

$$-k_1 k_2 \frac{\partial F_{\beta}}{\partial s_{\beta}^*} p_0^* \frac{\nu}{\lambda - \kappa} s_{\beta}^* \frac{1}{\lambda_{\mathrm{s}} - \kappa_{\mathrm{s}}} \frac{\partial F_{\mathrm{LC}}}{\partial p_0^*} m^T \frac{\partial F_{\mathrm{LC}}}{\partial \sigma^*} \frac{\partial F_{\beta}}{\partial s^*}$$

$$(39)$$

462 Substituting these two plastic multipliers (33) and (34) into (26) and after some

463 algebra, the generalized elasto-plastic matrix can be obtained as follows:

464
$$\mathbf{D}_{ep}^{*} = \begin{pmatrix} \mathbf{A}_{\mathbf{LC}+\beta} & \mathbf{B}_{\mathbf{LC}+\beta} \\ \left(\mathbf{C}_{\mathbf{LC}+\beta}\right)^{T} & D_{\mathbf{LC}+\beta} \end{pmatrix}$$
(40)

465 where

466
$$\mathbf{A}_{\mathbf{LC}+\beta} = \mathbf{D}_{\mathbf{e}} \left(\mathbf{I}_{6\times6} - \frac{\mathbf{a}_{\mathbf{LC}+\beta}^{T}}{h_{\mathbf{LC}+\beta}} \frac{\partial F_{\mathbf{LC}}}{\partial \mathbf{\sigma}^{*}} \right)$$
(41)

467
$$\mathbf{B}_{\mathbf{LC}+\beta} = \mathbf{D}_{\mathbf{e}} \left(\frac{\partial F_{\mathbf{LC}}}{\partial \boldsymbol{\sigma}^*} \frac{b_{\mathbf{LC}+\beta}}{h_{\mathbf{LC}+\beta}} \right)$$
(42)

468
$$\left(\mathbf{C}_{\mathbf{LC}+\beta}\right)^{T} = -\gamma_{e} \left(\frac{\partial F_{\beta}}{\partial s^{*}} \frac{\mathbf{c}^{T}_{\mathbf{LC}+\beta}}{h_{\mathbf{LC}+\beta}}\right)$$
(43)

469
$$D_{\mathrm{LC}+\beta} = \gamma_{\mathrm{e}} \left(1 + \frac{\partial F_{\beta}}{\partial s^{*}} \frac{d_{\mathrm{LC}+\beta}}{h_{\mathrm{LC}+\beta}} \right)$$
(44)

470 DATA AVAILABILITY STATEMENT

471 All data, models, or code that support the findings of this study are available from472 the corresponding author upon reasonable request.

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- 596
- 597

Table 1. Model parameters and initial states for Speswhite kaolin (Lloret-Cabot et al. 598

599

2013)

Parameters		Initial states	
λ	0.124	\overline{p}/kPa	50.00
K	0.006	s/kPa	300.00
$\lambda_{ m s}$	0.098	е	1.208
Ks	0.0076	$S_{ m r}$	60.1%
k_1	0.662	$S_{\rm r}^{\rm m}$	5.0%
k_2	0.803	p_0^* / kPa	273.00
M	0.71	$S_{\rm D}^*/{\rm kPa}$	164.00
μ	0.3	$S_{\rm I}^*/{\rm kPa}$	/

Table 2. Model parameters and initial states for the mixture

Parameters		Initial states	
λ	0.07	\overline{p}/kPa	20.00
K	0.008	s/kPa	563.00
$\lambda_{ m s}$	0.12	е	0.732
K _s	0.02	$S_{ m r}$	36.2%
k_{1}	0.6	$S_{\rm r}^{\rm m}$	10.0%
k_2	0.3	p_0^* / kPa	250.00
M	1.076	$S_{\rm D}^*/{\rm kPa}$	237.94
μ	0.3	$S_{\rm I}^*/{\rm kPa}$	/

601 **Table 3.** Void ratios and water contents/degrees of saturation at the end of saturated

and unsaturated compression P_{net} (kPa) e (model) w (model) e (experiment) w (experiment) 100 0.579 0.529 21.87% 19.90% 250 0.490 0.476 18.49% 17.90% Saturated 400 0.439 0.438 16.58% 16.50% S_r (model) Sr (experiment) 100 0.713 0.702 43.8% 40.7% Unsaturated 250 46.2% 42.2% 0.665 0.661 400 0.632 0.626 47.8% 43.6%

602

Table 4. Model parameters and initial states for the Jossigny silt samples

Parameters		Initial states	
λ	0.091	\overline{p}/kPa	25.00
K	0.013	s/kPa	200.00
$\lambda_{ m s}$	0.131	е	0.629
κ_{s}	0.008	$S_{ m r}$	76.4%
k_1	0.65	S ^m _r	56.0%
k_{2}	0.66	p_0^* / kPa	374.60
M	1.02	$S_{\rm D}^*/{\rm kPa}$	77.23
μ	0.3	$S_{\rm I}^*/{\rm kPa}$	103.84

604

Table 5. Results for the compression at constant suction/net mean stress

s (kPa)	p _{net} (kPa)	e (model)	e (experiment)	Sr (model)	S _r (experiment)
200	600	0.502	0.569	82.0%	84.0%
200	200	0.617	0.599	76.5%	77.0%
200	50	0.626	0.621	76.4%	77.0%
400	200	0.545	0.577	75.1%	74.0%
800	200	0.570	0.599	70.1%	70.0%

605

Table 6. Results of degree of saturation in the critical state

s /kPa	σ_3 /kPa	$S_{\rm r}$ (model)	$S_{\rm r}$ (experiment)
200	600	94.3%	98.0%
200	200	85.7%	79.0%
200	50	79.2%	79.0%
400	200	76.3%	77.0%
800	200	70.1%	70.0%



608 Fig. 1. Yield surfaces of the 3D generalized model (after Lloret-Cabot et al., 2013)



Fig. 2. Isotropic loading paths conducted by Sivakumar (Sivakumar, 1993)



Fig. 3. Comparison between model results and experimental results on Speswhite 612 kaolin (Sivakumar, 1993) for Path 1 and Path 2: (a/d) $p^* - s^*$; (b/e) $p^* - e$; (c/f)

$$b^* - S_r$$



617 **Fig. 4.** Comparison between model results and experimental results (Sivakumar 1993) 618 for shear at constant confining stress and net mean stress: (a/d) $\varepsilon_a - q$; (b/e) $\varepsilon_a - e$;

619 (c/f)
$$q - S$$









clay: (a) s - e; (b) $s - S_{r}$





624 Fig. 6. Comparison between model results and experimental results (Almahbobi

2018) for saturated and unsaturated shear: (a/c) q; (b/d) e



Fig. 7. Comparison between model results and experimental results on Jossigny silt
(Cui and Delage 1996) for shear at constant suction or cell pressure: (a/c) q; (b/d) e