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Pile-Supported Wharves Subjected to Inertial Loads and Lateral Ground Deformations. II: Guidelines for Equivalent Static Analysis

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31 **INTRODUCTION**

32 Pile-supported wharves must be designed to accommodate superstructure inertial loads
33 imposed at the pile head and kinematic loads imposed on the piles from the lateral ground
34 deformations when subjected to earthquake motions. Lateral ground deformations may be caused
35 by inertial slope movement, and/or by lateral spreading from liquefaction or cyclic softening of
36 foundation soils in sloping ground adjacent to the structure and in the backland areas. However,
37 there is no consensus in existing guidelines for pile design on how to combine inertial loads and
38 kinematic demands from lateral ground deformations.

39 The damage to pile-supported bridges and wharves due to liquefaction-induced lateral
40 spreading has been documented in a number of case histories, e.g., 1964 Niigata earthquake
41 (Hamada et al. 1986), 1989 Loma Prieta earthquake (Donahue et al. 2005), 1995 Kobe earthquake
42 (Tokimatsu and Asaka 1998), 2010 Haiti earthquake (Rathje et al. 2010), 2010 El Mayor-Cucapah
43 earthquake (Turner et al. 2016), and 2016 Kaikoura earthquake (Cubrinovski et al. 2017). In most
44 of these studies, the lateral spreading displacements exceeding 1 m were reported as the likely
45 cause of damage. While some studies back-calculated the likely combination of superstructure
46 inertia and lateral spreading demands (e.g., Turner et al. 2016), the exact interaction of inertia and
47 lateral spreading loads could not be directly calculated in these case histories due to the lack of
48 strong motion instrumentation on the superstructure and the soil, and lack of data necessary to
49 establish the pattern of soil deformations with depth. The paucity of well-instrumented sites at
50 ports subjected to damaging earthquakes has necessitated the use of numerical and physical models
51 to evaluate the phasing and relative impact of inertial and kinematic loads in piles. The robust data
52 set from five centrifuge tests on pile-supported wharves performed by McCullough et al. (2007)
53 has been thoroughly re-evaluated and used in this study to address previously unexamined aspects

54 of dynamic soil-pile interaction. These models included instrumented superstructure deck and piles
55 and embedded sensors within the soil profile. These tests provided a unique opportunity to back-
56 calculate the inertial and kinematic loads combination factors for equivalent static analysis.

57 Different design guidelines provide varying recommendations on how to combine
58 superstructure inertial and kinematic ground deformation loads to estimate the lateral demands on
59 piles. MCEER/ATC (2003) states that for most earthquakes the peak inertia is likely to occur early
60 in the ground motion while the maximum lateral spreading load will develop near the end of
61 motion. Consequently, it recommended designing piles for independent effects of inertia and
62 lateral spreading.

63 Boulanger and coworkers performed a series of 14 centrifuge tests on piles in liquefiable
64 soils (Boulanger et al. 1999; Brandenberg et al. 2007). They recommended combining the full
65 residual lateral spreading load with 65% to 85% of the peak inertial load, in contrast to the
66 recommendations put forth in MCEER/ATC (Boulanger et al. 2007; Ashford et al. 2011).

67 Researchers at Rensselaer Polytechnic Institute (RPI) have performed many centrifuge
68 tests on piles in liquefiable soils. Abdoun and Dobry (2002) showed that while the bending
69 moments at depths shallower than 2 or 3 m are affected by superstructure inertia, this effect
70 disappeared for bending moments at deeper depths for 0.6-m-diameter piles. They also reported a
71 post-peak reduction in the lateral spreading force despite the increase in ground displacement
72 (Dobry et al. 2003; Abdoun et al. 2003). Olson et al. (2017) performed another series of four
73 centrifuge tests at RPI to investigate the magnitude of lateral spreading force on large-diameter
74 foundations. The latter tests focused on the kinematic effects, and the effects of inertia were not
75 considered.

76 Tokimatsu et al. (2005) performed large-scale 1-g shake table tests in Japan's NIED facility
77 to study phasing of inertia and liquefaction-induced lateral spreading. They concluded that the
78 inertial and lateral spreading loads were in-phase for structures having a natural period shorter than
79 the natural period of the ground ($T_{\text{structure}} < T_{\text{ground}}$), and the two loads were out-of-phase for
80 $T_{\text{structure}} > T_{\text{ground}}$.

81 Cubrinovski et al. (2014) developed a design guideline for liquefaction and lateral
82 spreading effects on highway bridges in New Zealand. They separated the development of
83 kinematic loading due to soil displacements into a cyclic phase and a spreading phase. While they
84 recommended a combination of the inertial load with kinematic loads for the transient, cyclic
85 phase, they stated that the combination of the two loads may or may not be considered for the
86 spreading phase at the discretion of the engineer.

87 The design guidelines provided in commonly used codes for wharves and piers are
88 summarized in Table 1. ASCE 61-14 (ASCE 2014) requires that simultaneous application of
89 inertial and kinematic loads be considered, taking into account the phasing and the locations where
90 the loads are applied. The commentary in Section C4.7 of ASCE 61-14 and the Port of Long Beach
91 Wharf Design Criteria (POLB 2015) suggest that the locations of maximum bending moments
92 from inertia and lateral ground deformations are spaced far enough apart that the two loads do not
93 need to be superimposed. They also suggest that the maximum bending moments from the two
94 loads tend to occur at different times; therefore, they recommend that the loads be treated as
95 uncoupled for typical marginal container wharves. On the other hand, Port of Anchorage
96 Modernization Program Seismic Design Manual (POA 2017) recommends combining the peak
97 inertial loading from earthquake ground motions with 100% of peak kinematic loads from lateral

98 ground displacements. This design manual allows for smaller combination factors (no less than
99 25%) if justified using peer-reviewed 2-D nonlinear numerical analysis.

100 The design recommendations for pile-supported highway bridges also vary significantly as
101 summarized in Table 1. The transportation agencies in California and Oregon require combining
102 100% lateral spreading with 50% inertia (Caltrans 2012; ODOT 2014); Caltrans later retracted this
103 recommendation in favor of higher performance criteria (Caltrans 2016). Washington State DOT
104 recommends 100% lateral spreading + 25% inertia (WSDOT 2021), while AASHTO (2014)
105 recommends designing piles for the simultaneous effects of inertia and lateral spreading only for
106 large magnitude earthquakes ($M > 8$).

107 The varying recommendations provided by highway and maritime transportation agencies
108 highlight the site- and project-specific assumptions that are made to combine inertial and kinematic
109 demands on piles. It is recognized that there is limited research and validation of these
110 assumptions, and most design codes indicate that these assumptions should be evaluated on a
111 project-specific basis.

112 This paper summarizes the development of a practice-oriented equivalent static analysis
113 (ESA) procedure using p-y models for the design of pile-supported wharves subjected to lateral
114 ground deformations during earthquake loading. The accuracy of the ESA procedures in estimating
115 pile demands is evaluated against the results of five centrifuge tests on pile-supported wharves.
116 The piles in these centrifuge tests were subjected to the combined effects of wharf deck inertial
117 loads and ground deformations. The experiments included soil properties ranging from
118 nonliquefiable to fully liquefied cases, providing a wide range of conditions against which the ESA
119 method could be evaluated. Additionally, these tests included the system-level response of the
120 wharf deck and all rigidly-connected piles, as opposed to single piles, as had been used in most of

121 the centrifuge-based investigations previously cited. This is important because the restraining
122 effects of the superstructure affect how inertial and kinematic loads interact, as reported by Turner
123 et al. (2016). The following section of this paper provides an overview of the five centrifuge tests
124 that were used in this study. The paper is then followed by two sections where peak inertial and
125 peak kinematic demands are estimated and compared with centrifuge measurements. Next, load
126 factors to combine peak inertial and peak kinematic loads are presented. Concluding remarks are
127 provided based on a comparison of the demands estimated from ESA to those measured in the
128 centrifuge tests. A design example is provided to summarize the implementation of the
129 recommended procedure in design.

130 **CENTRIFUGE TESTS**

131 Details for the centrifuge tests can be found in a series of data reports in McCullough et al.
132 (2000), Schlechter et al. (2000a, b), and Boland et al. (2001a, b). The pile, superstructure, and soil
133 properties and the applied input motions are provided in the companion paper (Souri et al. 2022).
134 The methods of re-evaluation and re-interpretation of the carefully curated data set are also
135 addressed in the companion paper. All tests included a wharf deck supported by 21 piles configured
136 in a 7-by-3 setup. The piles consisted of aluminum pipe piles with outer diameters ranging from
137 0.38 m to 0.64 m (in prototype scale). The centrifuge scale factor was 40.1 for all tests.

138 Fig. 1 shows the cross sections of the five centrifuge models. The subsurface conditions in
139 model NJM01 included a multi-lift rock dike, a loose sand layer that liquefied during shaking and
140 resulted in lateral spreading, a dense sand layer above the water table, and a dense sand layer at
141 the pile tips. A relatively soft Bay Mud layer was included in model NJM02, while a cement-deep-
142 soil-mixing (CDSM) unit was incorporated into model SMS01. Model SMS02 featured a single,
143 monolithic rock dike supported by a dense layer of sand. In model JCB01, the rock dikes were

144 replaced with a thin layer of rock simulating an armour, wave protection layer. The failure surfaces
145 in each model, indicated in Fig. 1 with red dashed lines, were determined based on the soil
146 displacement profiles interpreted from accelerometer data. In general, the observed zone of shear
147 failure in the liquefied sand in the vicinity of piles can be characterized as broad, diffuse shear
148 failure combined with a localized shear plane at the interface of weak and resistant layers (such as
149 liquefied sand and upper rockfill). Localized shear planes were also developed above the Bay Mud
150 layer in NJM02 and below the CDSM unit in SMS01, which contributed to the large pile bending
151 moments that developed at depth in these two models. The overall objective of the current study
152 was to develop guidelines for combining inertial and kinematic demands in ESA and to evaluate
153 their accuracy in estimating the large bending moments that were observed in the centrifuge tests.

154 **ESTIMATING PEAK KINEMATIC DEMANDS**

155 The estimation of kinematic demands on piles is routinely made in practice using slope
156 deformations computed using simplified Newmark sliding block analysis (Newmark 1965) and
157 application of the approximated free-field soil deformation pattern to p-y springs connected to the
158 piles. The use of more complex and detailed two- or three-dimensional dynamic analysis that
159 incorporates coupled soil–structure interaction is also common, and often compared with the
160 results of the practical initial analysis. In the subsequent analysis completed in this investigation,
161 the soil displacements were computed using the Newmark method and were applied to the end
162 nodes of p-y springs using beam on nonlinear Winkler foundation (BNWF) approach. One
163 pertinent question in this method of analysis is whether the permanent, residual soil displacement
164 (at the end of shaking) or the peak transient soil displacement (which occurs during shaking)
165 should be used in design to evaluate the kinematic pile demands. ASCE 61-14 (Section 4.7.2)
166 specifically requires that the permanent portion of the lateral ground deformations be used to

167 estimate the kinematic demands on piles. However, it has been shown in Sourì et al. (2019) that
168 the peak transient bending moments at both the pile head and at depth are often greater than the
169 residual bending moments at the end of shaking; this result was attributed, partly, to the difference
170 between the peak transient soil displacement and the permanent soil displacement. The following
171 section provides practical guidelines for design by comparing the estimated soil displacements
172 against the measurements obtained from the centrifuge tests.

173 **Estimating Soil Displacements at the Ground Surface**

174 *Estimation of Soil Displacements using the Newmark Sliding Block Method*

175 Permanent ground displacements were estimated using the Newmark sliding block method
176 (hereafter referred to as *Newmark analysis*). The yield accelerations for each test were determined
177 by using pseudo-static limit equilibrium analysis and were assumed to be constant during the
178 motion in the Newmark analysis. The beneficial resistance of the piles against the laterally moving
179 ground (i.e., the pile pinning effects) were considered by including the piles as reinforcement
180 elements in the limit equilibrium analysis. Thus, the soil displacements calculated here are pile-
181 restrained displacements and not free-field displacements. The residual strength for liquefied soils
182 in the limit equilibrium analysis was determined using correlations and were consistent with the
183 weighted approach proposed by Kramer (2008). If liquefaction was not triggered, an equivalent
184 friction angle was calculated proportional to the pore water pressure ratio using the relationship by
185 Ebeling and Morrison (1992). Full details for these analyses are provided in McCullough et al.
186 (2001). The yield accelerations used in the Newmark sliding block analysis are reported in
187 Supplemental Appendix B. Newmark analyses are typically performed in practical applications
188 using accelerations that are obtained from site response modeling; however, in this study, the

189 recorded accelerations from centrifuge tests were used as input for the Newmark analysis. Thus,
190 uncertainties in ground motion estimation associated with site response analysis are minimized.

191 *Comparison between the Soil Displacements from Centrifuge Tests and Newmark Analysis*

192 The accuracy of the Newmark method in estimating soil displacements was evaluated by
193 comparing the results of the Newmark analysis to the measured displacements obtained from the
194 centrifuge tests. Fig. 2 shows a comparison of median Newmark displacements for all
195 accelerometers within the failure mass against the permanent displacement (end of shaking) and
196 peak transient displacement measured at the ground surface in the centrifuge tests. The vertical
197 bars show the Newmark median + 1σ and Newmark median - 1σ values. The Newmark
198 displacements include the pile-pinning effects. The centrifuge displacements were calculated by
199 combining high-frequency and low-frequency components of displacements using data from the
200 linear variable differential transformer (LVDT) and accelerometers that were installed in the
201 vicinity of the piles; therefore, the displacements shown in Fig. 2 can be considered pile-restrained.
202 All displacements are adjusted to be relative to the base of the model. This figure suggests that the
203 permanent (end of shaking) displacements from the centrifuge tests are better estimated using the
204 median Newmark displacements; however, this analytical approach tended to overestimate the
205 observed displacements by roughly 10%, on average. This figure also suggests that the peak
206 transient displacements from the centrifuge tests are better estimated using the median + 1σ
207 displacements from the Newmark analysis, and in this case the simplified sliding block model
208 tends to underestimate the peak displacement by roughly 10%. For comparison, the peak transient
209 displacements from the centrifuge tests are underestimated by median Newmark displacements by
210 approximately 50%. The measured peak transient displacements were found to be between 1.2 and
211 7.5 times larger than the permanent displacements in most cases (with the larger ratios

212 corresponding to nonliquefied soil profiles). The median + 1σ displacements from Newmark were,
213 on average, 1.8 times larger than the median Newmark displacements.

214 The difference between the permanent displacement and peak transient displacement
215 should be considered in conjunction with the distribution of soil displacements with depth in the
216 pseudo-static analysis. While Fig. 2 illustrates that the median Newmark displacements
217 underestimated the peak transient soil displacements, it will be shown that the distinct transitions
218 in the idealized soil displacement profiles resulted in overestimation of the predicted pile bending
219 moments such that the combination of median Newmark displacements and an idealized soil
220 displacement profile resulted in satisfactory estimates of the peak pile bending moments.

221 **Estimating Soil Displacements with Depth**

222 *Idealized Soil Displacement Profile with Depth*

223 Cubrinovski et al. (2014) showed that the lateral displacement index (LDI) approach
224 (Zhang et al. 2004; Idriss and Boulanger 2008) can be used to estimate the shape of soil
225 displacement profile with depth. They found that the ground surface displacements computed from
226 the LDI approach were two to three times larger than the measured free-field displacements in the
227 case histories pertaining to damaged bridges during the 2010-2011 Canterbury, New Zealand
228 earthquakes. Therefore, they used the measured displacements at the ground surface and
229 distributed it with depth based on the shape of the displacement profile from the LDI approach.
230 The LDI approach includes integrating the maximum shear strains in all soil layers to develop the
231 soil displacement profile. Armstrong et al. (2014) used a similar approach where they used the
232 LDI approach to estimate the displacement profile with depth and then scaled it down to match the
233 ground surface displacement estimated from the Newmark method. Using the LDI approach for
234 the five sets of centrifuge models resulted in approximately linear deformations with depth within

235 the loose sand layer and negligible deformations in the rockfill and dense sand layers. Therefore,
236 the idealized soil displacement profiles in this study were simply assumed to vary linearly with
237 depth within the loose sand units and remain constant within the rockfill and the dense sands units.
238 The idealized soil displacements profiles are referred to as “design” soil displacements hereafter.

239 ***Soil Displacement Profiles Obtained from Centrifuge Tests***

240 To evaluate the accuracy of the design soil displacement profiles, it was necessary to develop the
241 soil displacement profiles in each of the centrifuge tests. The horizontal soil displacements at a
242 given depth below the ground surface were calculated by combining the high-frequency and low-
243 frequency components of the displacements. Following the procedure explained by Wilson (1998),
244 the high-frequency component of soil displacements was calculated by double integration of the
245 recorded accelerations from the embedded accelerometers and were filtered by applying a high-
246 pass Butterworth filter with a corner frequency of 0.25 Hz. The low-frequency component of soil
247 displacements at a given depth were calculated by applying a low-pass Butterworth filter with the
248 same corner frequency to the recorded LVDT displacement at the ground surface and then
249 distributing it with depth based on an assumed profile. This profile was developed using the shape
250 of the maximum transient displacements with depth obtained from the accelerometer data as a
251 guide. No permanent soil displacement was considered below the shear failure plane. The pattern
252 of the permanent accumulated soil displacements with depth generally agreed with the
253 measurements on the dissected model, which were made after the tests were completed. The
254 baseline analysis that is described later in the paper provides a measure of accuracy of the
255 interpreted soil displacements from centrifuge tests by comparing the computed and measured
256 bending moments in piles.

257 **Comparison Between Centrifuge and Design Soil Displacement Profiles**

258 A comparison of soil displacement profiles from centrifuge tests and design is shown in
259 Fig. 3 for Event 11 of model NJM01. The soil displacements were interpreted at the pile locations
260 to be applied to the end nodes of p-y springs. The design soil displacements were estimated using
261 the mean Newmark displacements, and the centrifuge soil displacements correspond to the peak
262 transient displacement during motion (which occurred at time $t = 21.6$ sec). It can be observed from
263 this figure that for piles in rows 1, 2 and 3, where the kinematic effects are large, the peak transient soil
264 displacements are underestimated by the mean Newmark displacements by approximately 33% (i.e. the
265 ratio of estimated displacements at the top of the slope from Newmark to interpreted displacements from
266 centrifuge was 0.67). While the design soil displacement profile follows the general trends observed
267 in the centrifuge tests, it lacks the smooth curvature of the displacements at the boundary of rockfill
268 and loose sand and the localized curvature within the loose sand from the centrifuge test.

269 The same trend for soil displacements interpreted from centrifuge tests and estimated in
270 design for model NJM01 was consistently observed in other centrifuge tests. In the results for all
271 five tests shown in Fig. 4, the peak transient soil displacements from the centrifuge tests were generally
272 underestimated when evaluated using the mean Newmark values (the ratio of estimated displacements at
273 top of the slope from Newmark to interpreted displacements from centrifuge ranged from 0.13 to 1.21).
274 This is important considering that mean Newmark displacements are typically recommended by design
275 guidelines to evaluate the permanent (not peak transient) lateral ground deformations and the associated
276 kinematic demands (e.g., ASCE 61-14). However, we found that the distinct transitions in the idealized soil
277 displacement profiles at layer boundaries above and below the loose sand layer over-predict the pile bending
278 moments. These two effects have an approximately equal and opposite influence on the estimated bending
279 moments, such that the combination of idealized soil displacement profiles and mean Newmark
280 displacements provided reasonable estimations of computed peak transient pile bending moments. This is
281 shown in Fig. 5 for Pile 1 in NJM01-Event 11 as an example. Fig. 5a shows two different soil displacement
282 profiles: (a) interpreted from centrifuge exhibiting a ground surface displacement of 0.13 m and smooth

283 transitions at layer boundaries, and (b) estimated from Newmark exhibiting a ground surface displacement
284 of 0.09 m and an idealized “design” distribution of displacements with depth with distinct transitions at
285 layer boundaries. Fig. 5b shows the bending moments along the pile calculated by exerting the two soil
286 displacement profiles to the end nodes of p-y springs in a pseudo static analysis (details for the developed
287 p-y models are provided later in this paper). This figure shows that the maximum deep bending moment at
288 the boundary between liquefied sand and the lower dense sand is fairly similar between the two approaches
289 (1116 kN-m in the case of using centrifuge displacements and 1101 kN-m in the case of using design soil
290 displacements). For comparison, the measured peak bending moments from centrifuge are also plotted in
291 this figure. The reasonable agreement between the measured bending moments and the estimated bending
292 moments by applying interpreted soil displacements from centrifuge confirms that the assumptions made
293 in interpreting soil displacement profiles with depth by combining the high- and low-frequency components
294 of embedded accelerometer data and LVDT at the ground surface were reasonable. The discrepancy
295 between the curvature of the estimated and interpreted soil displacement profiles at layer
296 boundaries was also reported in other studies involving centrifuge tests and numerical analyses
297 (e.g., Brandenberg et al. 2007; McGann et al. 2011; Armstrong et al. 2014). Caltrans (2012)
298 recommends tapering the p-y spring properties over a transitional zone that extends one to two pile
299 diameters from the interface between the liquefied and nonliquefied layers; this approach was
300 adopted in this study.

301 **Lateral Soil Reactions on Piles at the Time of Maximum Bending Moment**

302 The lateral soil reactions back-calculated from the centrifuge tests showed that the
303 nonliquefied rockfill does not apply a uniformly bayward (i.e., downslope) pressure. Rather, the
304 direction of the transient lateral soil reaction changes throughout the rockfill. The cross sections
305 of two tests where the pile instrumentation was dense enough to accurately compute the soil
306 reactions are shown in Fig. 6. The soil reactions were computed by fitting a spline curve to the

307 bending moments and a double differentiation with depth (Souri et al. 2020). The profiles show
308 the lateral soil reactions that occur at the time of maximum bending moments. The soil reactions
309 plotted in this figure are all based on experimental results. In Piles 1 and 2 of NJM01 and in Piles
310 2 and 5 of SMS01, where a thick nonliquefiable crust (rockfill) was present, the top portion of the
311 crust was resisting the inertial load, as indicated by positive (landward) soil reactions. The inertial
312 force at the pile head was bayward. In these models, the effect of inertia was resisted by the
313 resisting lateral soil pressure from the nonliquefied crust, and it did not contribute to the bending
314 moments that developed at depth (~20 m below the pile head in NJM01 and ~22 m below the pile
315 head in SMS01). It is important to note that in both tests the rockfill moved almost uniformly over
316 the liquefied soils. This observation is further analyzed in Fig. 7 for Pile 1 in NJM01 Event 11, as
317 an example. The soil and pile displacement profiles are plotted at the time of maximum bending
318 moment (Fig. 7a) showing that the pile has moved more than the soil in the top half portion of the
319 rockfill resulting in a positive (landward) soil reaction (Figs. 7b and 7c). Conversely, the soil has
320 moved more than the pile in the bottom half portion of the rockfill resulting in a negative (bayward)
321 soil reaction. The inertial force at the pile head was bayward as indicated by the slope of the
322 bending moments at the pile head (Fig. 7d). Figure 7b and 7c show the same data but at different
323 scales. The ultimate soil reactions (p_u) were calculated based on commonly used p-y relationships
324 for sand proposed by American Petroleum Institute (API 1993) and are plotted in this figure as a
325 reference (details and input parameters for API model are provided in Supplemental Appendix A).
326 This comparison shows that the soil reactions are significantly smaller than the full passive
327 pressure. This is expected for relatively flexible piles used in this study as the piles closely follow
328 the soil deformations. This conclusion is likely to be different for relatively stiff piles such as large
329 diameter shafts as the soil deformations could be much larger than the pile deformations to the

330 extent that full passive pressure may develop throughout the nonliquefied crust. This finding is
331 consistent with those in Boulanger et al. (2007), which showed that with relatively flexible piles,
332 the nonliquefiable crust load can, in fact, apply a resisting upslope reaction while the inertia is
333 downslope.

334 The observations made regarding models NJM01 and SMS01 suggest that it is overly
335 conservative to estimate the kinematic demands by applying a bayward limiting pressure
336 throughout the entire rockfill. Thus, for the piles analyzed in this study, it was more appropriate to
337 apply kinematic demands by imposing the estimated soil displacements (including pile-pinning
338 effects) to the end nodes of the p-y springs.

339 **DEVELOPING P-Y MODELS FOR EQUIVALENT STATIC ANALYSIS**

340 Nonlinear beam on Winkler foundation models (i.e. p-y models) were developed for
341 equivalent static analysis. The p-y models were created in *LPILE* v. 2019 (Ensoft 2016) and were
342 calibrated using four static lateral load pile tests that were performed for SMS02 and JCB01. A
343 summary of these calibrations is provided in the Supplemental Appendix A. More details on
344 calibrations of *LPILE* models are provided in Souri et al. (2020). A baseline analysis was
345 performed to measure the accuracy of assumptions in developing p-y spring properties, p-
346 multipliers, and soil displacement profiles.

347 **Soil Properties**

348 The moduli of the subgrade reaction for sand were modified from the API
349 recommendations to match the results of the four static lateral load tests. The rockfill was modeled
350 by incorporating a pseudo-cohesion of 15 kPa to account for additional resistance caused by the
351 interlocking and movement of rock particles near the ground surface, and stress-dependent strength
352 at very low confining stress thus simply modeled as a ϕ' - c' soil as applied in calibration studies

353 from field load tests in rockfill (e.g. McCullough and Dickenson 2004; Dickenson et al. 2016). No
354 modifications were made to the p-y springs in regard to the ground slope as the p-y models
355 reasonably captured the pushover curves and pile demands from the four static lateral load tests as
356 described in Sourì et al. (2020).

357 **Pile Properties**

358 The wharf deck in the centrifuge tests was supported by three rows of seven piles (for a
359 total of 21 piles) with diameters ranging from 0.38 m to 0.64 m. Considering the rigidity of the
360 wharf deck, all piles were assumed to have zero rotation at the pile head. The piles remained elastic
361 in the centrifuge tests and were modeled as elastic in the *LPILE* models. While the piles in the
362 centrifuge tests were hollow aluminum pipes, their stiffness properties in prototype scale
363 represented those of prestressed concrete piles.

364 **P-multipliers**

365 The p-y springs were modified using p-multipliers (P_m) proportional to the pore water
366 pressure ratio R_u generated during the ground motion: $P_m = 1.2 - 1.1 * R_u$ for $R_u > 0.2$ and $P_m =$
367 1.0 for $R_u \leq 0.2$, as the effect of liquefaction is assumed to be negligible when R_u is below 0.2.
368 These practice-oriented relationships account for the first-order softening effect of liquefaction
369 and generally agree with the nonlinear relationship proposed by Liu and Dobry (1995). For details
370 on the development of the proposed R_u -proportional p-multipliers for liquefiable soils and their
371 effectiveness in predicting peak pile demands, see Sourì et al. (2020). In this study, the R_u values
372 recorded in the vicinity of piles were used. In practice, these values can be estimated from
373 simplified correlations with the factor of safety against liquefaction.

374 **Baseline Analysis – Accuracy of Modeling Assumptions**

375 There are several sources of uncertainty in performing equivalent static analysis including
376 (a) numerical modeling approach (e.g., p-y spring properties, pile properties, and boundary
377 conditions), (b) estimating kinematic demands from soil displacements, (c) estimating inertial
378 demands associated with superstructure mass, and (d) combining inertial and kinematic demands
379 in equivalent static analysis. The baseline analysis described in this section provides a measure of
380 accuracy of the assumptions that were made during the numerical modeling approach (item a) and
381 in estimating the soil displacement profiles (item b). The accuracy of assumptions made in
382 estimating inertial demands and the combination of inertial and kinematic demands are assessed
383 later in this paper.

384 The baseline analyses consist of applying the interpreted soil displacements from
385 centrifuge (“centrifuge” displacements shown in Fig. 4) to the end nodes of p-y springs in the
386 calibrated *LPILE* models. The inertial loads at top of the piles were directly calculated from
387 centrifuge tests by differentiating the bending moments at top of the piles for cases where at least
388 two strain gauges were installed between the top of the pile and the ground surface. It is worth
389 noting that equivalent static analysis inherently suffers from simplifying a dynamic response
390 including soil-pile-structure interaction and liquefaction-induced softening of soils to a static
391 analysis. The accuracy of these assumptions and simplifications are assessed in this section by
392 comparing the measured and computed bending moments.

393 Fig. 8 shows the computed and measured bending moments for NJM01-Event 11 as an
394 example. The measured bending moments correspond to the peak values during motion measured
395 at time $t = 21.6$ sec. While the time of maximum bending moment was found to generally vary
396 with pile row and depth, in NJM01-Event 11 specifically, the maximum bending moment in all
397 instrumented piles occurred at approximately the same time (i.e. $t = 21.6$ sec). The locations of

398 large bending moments are color-coded: bending moments above grade are shown in red, and
399 those below grade are shown in blue, noting that deep bending moments below grade are
400 specifically affected by the shape and magnitude of exerted soil displacement profiles. Close
401 agreement is observed between the measured and estimated bending moments, which justifies the
402 assumptions that were made in developing the p-y models and the interpreted soil displacement
403 profiles from centrifuge. The maximum bending moments along the piles are compared for all five
404 tests and two shaking events for each test in Fig. 9. This figure shows the accuracy in measuring
405 the bending moments in piles subjected to liquefaction and lateral spreading loads using the
406 calibrated *LPILE* models in equivalent static analysis. The bending moments below grade are
407 plotted in blue and those above grade (i.e. at pile head) are plotted in red. On average, the estimated
408 bending moments using *LPILE* are 5% larger than the measured bending moments while the
409 majority of the data points are bounded within the 1:2 and 2:1 lines (with the exception of two data
410 points with very small bending moments).

411 **ESTIMATING PEAK INERTIAL DEMANDS**

412 Equivalent non-linear static analysis (ESA) was used to estimate the peak inertial demands
413 associated with the dynamic response of the deck mass. The ESA procedure included developing
414 p-y models for a single row of piles, developing a lateral force-displacement relationship (pushover
415 curve) for the entire pile group, calculating the equivalent stiffness and natural period of the wharf,
416 and estimating the peak inertial force using the acceleration response spectra at the ground surface.
417 The ESA was performed for both liquefied and nonliquefied conditions. The estimated inertial
418 demands were then compared against the measured demands from the centrifuge tests to evaluate
419 the accuracy of the ESA procedures. It is worth noting that there are other important variables in
420 performing ESA that were not evaluated in this study, such as the uncertainties associated with the

421 p-y spring properties in the design as recommended by ASCE 61-14 (ASCE 2014), the effect of
422 pile head fixity on the lateral stiffness of the pile group, and the uncertainties associated with site
423 response analysis. These are complex, project-specific issues, which warrants additional
424 investigation of the sensitivity of the load combinations to these uncertainties.

425 **Pile Group Force–Displacement Relationships**

426 Force–displacement relationships (i.e., pushover curves) were developed for the entire pile
427 group for each centrifuge test under the two conditions shown in Fig. 10. In the nonliquefied
428 condition (Case A), regular p-y springs were used with no soil displacements. For the liquefied
429 condition (Case B), soil displacements were imposed to the end nodes of the p-y springs, and the
430 p-y curves for the liquefiable soils were softened using p-multipliers. The mean Newmark soil
431 displacements were distributed with depth using an idealized profile, as this combination
432 reasonably predicted the peak bending moments in the centrifuge tests. The idealized soil
433 displacements used in Case A analyses are the ones labeled as “Design” in Fig. 4. To develop
434 pushover curves using *LPILE* models, displacements were imposed incrementally at the top of
435 individual piles while maintaining zero rotation at the pile head to simulate the rigid connection
436 between the piles and the wharf deck. The total shear force for the pile group was calculated by
437 summing the pile head shear forces of all seven piles in one row multiplied by three rows in the
438 transverse direction. No group reduction factor was considered based on AASHTO (2014), since
439 the pile spacing was greater than six times the pile diameter. Some studies have shown that the
440 sequence of applying inertial and kinematic demands can affect the estimated demands on piles
441 (e.g. Chang 2007). However, this topic was not investigated in this study; thus, the full soil
442 displacement was applied in *LPILE*, and the pile head displacements were incrementally increased
443 to reach 1 m.

444 The pushover curves are shown in Fig. 11 for all five sets of centrifuge test models. The
445 pushover curves for the liquefied condition are different for each shaking because the soil
446 displacements are different. For plotting purposes, the pushover curves in Fig. 11 are only shown
447 for one event in each centrifuge test. The pushover curves for liquefied conditions exhibit a non-
448 zero displacement at zero shear force due to the application of soil displacements. They also show
449 a softer response as compared to pushover curves for the nonliquefied condition due to softened
450 p-y springs in the liquefied soils and the application of soil displacements. The soil displacements
451 had a more pronounced effect on the pushover curves for liquefied conditions in the cases analyzed
452 in this study due to the fact that flexible piles follow the ground deformations more closely. The
453 variations in p-multipliers had a minor effect on the pushover curves for liquefied conditions, likely
454 because the majority of the piles (except for those in JCB01) were not embedded in liquefied soils.

455 The equivalent natural period of the soil-wharf system was computed for both conditions
456 in each test using the initial stiffness of the pushover curves and the total wharf mass including the
457 deck and the piles (the deck mass constitutes 74% of the total wharf mass). The effect of initial
458 versus secant stiffness on the equivalent natural period was insignificant. Fig. 12 shows the
459 equivalent natural period of the wharf calculated based on the pushover curves for liquefied and
460 nonliquefied conditions. The wharf natural periods ranged from 0.5 sec to 1 sec in the nonliquefied
461 condition but were elongated to values between 0.8 sec and 1.1 sec in the liquefied condition (an
462 average increase of 25%).

463 **Estimate of Peak Inertia using Equivalent Static Analysis**

464 Equivalent static analyses (ESAs) were performed for liquefied and nonliquefied conditions in
465 order to estimate peak superstructure inertial demands. The pushover curves (Cases A or B) were
466 used to estimate the lateral stiffness and natural period of the wharf system. The acceleration

467 response spectra (ARS) at the ground surface were then used to extract the spectral acceleration at
468 the corresponding natural period of the wharf. The peak inertial load at the wharf deck was
469 estimated by multiplying the spectral acceleration and the wharf mass.

470 The ESA for nonliquefied conditions included pushover curves (Case A in Fig. 11)
471 combined with the ARS in the lower rock dike, which were representative of a nonliquefied site
472 response. While there were no liquefied soils underlying the lower rock dike, the liquefaction of
473 soils in the backland may have affected the recorded accelerations in the lower rock dike; however,
474 this effect is believed to be minimal. The use of nonliquefied ARS is consistent with procedures
475 proposed by Caltrans (2012), where the peak inertial loads are estimated in the absence of
476 liquefaction and then reduced by 50% to account for the effects of liquefaction on site response
477 and the asynchronous timing of peak inertial and peak kinematic demands.

478 The ESA for liquefied conditions included a pushover curve (Case B in Fig. 11) combined
479 with an ARS in the backland representative of the accelerations in the liquefied ground. This
480 approach is sometimes used in practice when the effect of liquefaction is already included in the
481 design spectra. It should be noted that the peak inertial demand estimated using this approach will
482 only need to be multiplied by a potential reduction factor due to asynchronous timing of peak
483 inertial and peak kinematic loads. There is considerable damping associated with soil-pile-fluid
484 interaction that should be accounted for in estimating inertial demands. This complex behavior
485 was approximated in the ESA analyses by developing the ARS for 14% damping ratio (as opposed
486 to the typical 5% damping ratio). The equivalent damping ratio of 14% was calculated based on a
487 dashpot coefficient of $c = 4 \cdot B \cdot \rho \cdot V_s$ proposed by Wang et al. (1998), where B is the pile diameter
488 and ρ and V_s are the density and shear wave velocity in the rockfill. The damping ratio of 14%
489 provided a reasonable estimate of the peak acceleration at the wharf deck as explained in the next

490 section. For comparison, using 5% damping ratio overestimated the wharf accelerations by a factor
491 of 1.5. Other studies based on centrifuge tests have also shown the importance of accounting for
492 additional damping along the piles to capture the radiation damping and the interaction between
493 soil, structure and fluid and modeled this damping using dashpots along the piles in dynamic
494 analysis (e.g. Shafieezadeh et al. 2012, Brandenberg et al. 2013).

495 Fig. 13 shows how spectral accelerations were extracted using the ESA approaches
496 described above, using the first event in NJM01 as an example. The natural period of the wharf
497 changed slightly from 0.94 sec in nonliquefied conditions to 0.95 sec in liquefied conditions. The
498 spectral accelerations were calculated from accelerations time histories recorded in the centrifuge
499 test. A black line shows the spectra in the backland that are representative of liquefied conditions;
500 three lines in different shades of blue show the spectra for three different accelerometers in the
501 lower rock dike that are representative of nonliquefied conditions. The base spectra are also shown
502 for comparison purposes. The nonliquefied spectra in the lower rock dike confirm that the lower
503 rock dike moves fairly rigidly and that the extracted spectral acceleration is not sensitive to the
504 location of the selected accelerometer. The spectral acceleration at the natural period of the
505 structure increased from 0.2 g in the nonliquefied condition to 0.24 g in the liquefied condition.

506 **Comparison Between Peak Inertial Demands from Centrifuge Tests and ESA**

507 The accuracy of the ESA methods in estimating inertial demands was evaluated by
508 comparing the estimated peak deck acceleration and peak pile head shear forces with those
509 measured in the centrifuge tests. Fig. 14 shows that ESA for both liquefied and nonliquefied
510 conditions reasonably estimated peak deck accelerations (slightly overestimated by a factor of 1.1.)

511 The pile head shear in ESA was calculated by distributing the peak deck inertial force (i.e.,
512 spectral acceleration multiplied by the wharf mass) between individual piles in the pile group based

513 on their relative lateral stiffness. The pile head shear forces in centrifuge tests were calculated
514 using the measured bending moments from the top two strain gauges in each pile (for piles with
515 two strain gauges located above the ground surface). Fig. 15 shows that the nonliquefied ESA
516 underestimates the measured pile head shear forces by a factor of 0.9, and the liquefied ESA
517 overestimates the measured pile head shear forces by a factor of 1.2. This indicates that the pile
518 head shear forces were, on average, estimated reasonably well. This comparison confirms that no
519 significant bias was introduced in estimating inertial demands that would affect the load
520 combination factors that are proposed next.

521 Overall, Figs. 14 and 15 show no significant difference between the inertial forces at pile
522 head estimated using ESA for liquefied or nonliquefied conditions. In the subsequent analyses, the
523 liquefied ESA was used to evaluate the accuracy of design methods in estimating pile bending
524 moments. However, it should be noted that performing the ESA for liquefied conditions requires
525 estimation of soil displacement profiles, which includes significant uncertainty and could greatly
526 affect the results for flexible piles. In addition, performing ESA for liquefied conditions requires
527 estimating the response spectra in liquefied soils using effective-stress site response analysis,
528 which also include significant uncertainty. Thus, it is sometimes desirable for design purposes to
529 perform ESA for nonliquefied conditions and the results of this study show that the pile head
530 inertial loads can be reasonably captured using ESA for nonliquefied conditions.

531 **COMBINING PEAK INERTIAL AND PEAK KINEMATIC DEMANDS IN DESIGN**

532 **Load Combinations**

533 As the peak inertial and peak kinematic demands do not always occur during the same
534 cycle, Boulanger et al. (2007) recommends combining the peak kinematic demand with a fraction
535 of the peak inertial demand, defined as parameter C_{cc} , which ranged from 0.65 to 0.85 in their

536 investigation. The proposed values in Boulanger et al (2007) were developed primarily for bridge
537 structures with an embedded pile cap and an elevated superstructure. The *Ccc* parameters in this
538 study were calculated for pile-supported wharf structures where the pile cap is rigidly fixed to the
539 superstructure. The back-calculated *Ccc* parameters from the centrifuge tests are described in detail
540 in the companion paper (Souri et al. 202X). The data from this study suggests that *Ccc* decreases
541 as the depth to the maximum pile moment increases, which can be attributed to the finding that the
542 bending moments at the pile head are heavily influenced by, and correlated with, the deck inertia,
543 resulting in *Ccc* values closer to 1. In contrast, the bending moments that develop at depth are less
544 correlated with deck inertia as they are more influenced by kinematic demands and thus will have
545 smaller *Ccc* values.

546 There is also a noticeable dependence between the *Ccc* values and different soil profiles,
547 as discussed in the companion paper. The *Ccc* values calculated for the first three tests (NJM01,
548 NJM02, and SMS01) range from 0.3 to 0.6, while the *Ccc* values calculated for the last two tests
549 (JCB01 and SMS02) range from 0.9 to 1.0. In the first three tests, the kinematic demands are driven
550 by a large overlying nonliquefiable rockfill. The time-dependent mobilization of slope deformation
551 and corresponding application of kinematic loads on piles associated with this soil profile and
552 configuration resulted in a lower likelihood for the peak kinematic loads to coincide with peak
553 inertial loads. In contrast, the kinematic loads in the last two tests are relatively small and mobilized
554 earlier in the motion. The kinematic loads in JCB01 were driven by a thin layer of rock face
555 underlain by a loose sand layer that liquefied early in the motion and the soil profile in SMS02 did
556 not include a liquefiable layer. The peak kinematic loads in the last two tests were more likely to
557 coincide with peak inertia which resulted in larger *Ccc* values. The difference between the

558 calculated *Ccc* values among different soil profiles highlights the site-specific nature of inertial
559 and kinematic interaction and the subsequent load combination factors.

560 For the sake of comparison of the tests performed in this study, a *Ccc* value of 85% was
561 used based on the median + 1σ values among all five tests. This multiplier resulted in a better
562 match between the recorded and estimated bending moments in all five tests on average, as
563 presented in the next section. However, it is acknowledged that the scatter in data can be reduced
564 if different inertial load factors are used based on different soil profiles; for example, lower
565 combination factors may be used for soil profiles that resemble those in NJM01, NJM02 and
566 SMS1. Table 2 shows the back-calculated load combinations for different soil profiles. These load
567 combinations were calculated for the soil profile, pile properties, and ground motion considered in
568 the five centrifuge tests in this paper, therefore they are applicable for conditions that are similar
569 to those modeled.

570 It will be shown in the next section that two uncoupled load combinations were adequate
571 to estimate the bending moments that develop at, and near, the pile head (Case A) and at deep
572 locations (Case C, where depth $>10D$) in these tests. However, the bending moments at shallow
573 depths ($<10D$) could only be accurately estimated when the two loads were combined (Case B).
574 Therefore, the inertial multipliers in Table 2 were selected primarily based on the *Ccc* values that
575 were back-calculated for bending moments at shallow locations. Fig. 16 shows a schematic
576 diagram of the ESA load combinations in the p-y analysis. The back-calculated inertial multipliers
577 in Table 2 were used in decoupled, ESA analysis where peak inertial and peak kinematic demands
578 were estimated separately. As suggested in POA (2017) more refined multipliers may be used if
579 nonlinear dynamic analysis is adopted in design.

580 **Comparison of Estimated and Measured Maximum Bending Moments**

581 Equivalent static analyses were performed in *LPILE* using the three load combinations
582 listed in Table 2 and an inertial multiplier of 85% as an average for all tests. The estimated bending
583 moments from the ESA were compared to the measured bending moments in the centrifuge tests.
584 Fig. 17 shows the measured and estimated bending moments for NJM01 Event 11, as an example.
585 The bending moments were compared for key strain gauges where large moments were exhibited
586 during the motion. The large measured bending moments are classified into three categories based
587 on their location: bending moments that develop at the pile head (highlighted in blue in Fig. 17),
588 bending moments that develop shallower than 10D (highlighted in red), and bending moments that
589 develop deeper than 10D (highlighted in green). It was observed that the location of large recorded
590 bending moments varied for different pile rows. In Piles #1, #2 and #3, large bending moments
591 were recorded at the pile head as well as above and below the loose liquefiable layer. This was
592 expected, as the failure shear plane passed through the liquefied layer, imposing significant
593 curvature (and moment) in the piles. In Piles #4, #6, and #7, which did not pass through the loose
594 liquefiable layer, large bending moments were recorded at the pile head and at shallow depths
595 (depths <10D).

596 The estimated bending moments from ESA using the three load combinations are also
597 shown in Fig. 17. As an example, for Pile #1, it is observed that applying inertia only (indicated
598 by a green line) accurately estimates the measured bending moment at the pile head, while applying
599 kinematics only (indicated by a red line) accurately estimates the measured bending moment at
600 depth. The effects of inertia attenuate within 5 to 6 m from the ground surface (approximately 8 to
601 10 pile diameters). Fig. 17 also shows that while the p-y analysis may not always accurately capture
602 the location of maximum moments, it is capable of capturing the magnitude of the maximum
603 moment with reasonable accuracy (note the location of the estimated and measured deep bending

604 moments in Pile #1). This analysis was performed for two main shaking events for each of the five
605 tests, producing a total of 10 different experimental results that are used to evaluate the accuracy
606 of the proposed load combinations in estimating the pile bending moments. Similar plots for the
607 other tests are provided in the Supplemental Appendix C.

608 Plots of the peak bending moments measured in the centrifuge tests and those estimated in the ESA
609 are provided in Fig. 18 for all five tests and two shaking events for each test. In this figure, the dashed lines
610 indicate the mean residual between the estimated and measured values (i.e. residual =
611 $\ln(\text{estimated}/\text{measured})$) providing a measure of accuracy for each ESA load combination. At the pile head
612 (Fig. 18a), it can be seen that applying inertia only (Case A) adequately estimated the bending moments
613 (overestimated by +1% on average) while the combined case (Case B) slightly underestimated the bending
614 moments (-9%) and applying kinematics only (Case C) significantly underestimated the bending moments
615 (-95%). This is expected, as pile head bending moments are primarily affected by wharf inertia; thus, it was
616 necessary to apply full inertial load to estimate the demands at this location. For shallow locations (depth
617 $<10D$) shown in Fig. 18b, a combination of the two loads (Case B) estimated the bending moments with a
618 reasonable accuracy (overestimated by +11%) while applying inertia only (Case A) underestimated the
619 bending moments (-33%) and applying kinematic only (Case C) noticeably underestimated the bending
620 moments (-72%). Note that some shallow bending moments were significantly underestimated using load
621 cases A and C, which makes them inadequate for design. For deep locations with (depth $>10D$) shown in
622 Fig. 18c, it is clear that applying kinematics only (Case C) overestimated the bending moments (+34%),
623 which is associated with uncertainties in estimating the soil displacement profile. Combining inertia and
624 kinematics (Case B) did not improve the accuracy in estimating deep bending moments (overestimate by
625 37%) and applying inertia only (Case A) significantly underestimated the bending moments (-95%). Note
626 that the soil displacements in Case C were estimated using Newmark mean values, which were shown to
627 reasonably estimate the permanent soil displacements but underestimate the peak transient soil
628 displacements (Fig. 2). However, this underestimation was compensated by the overestimation of pile

629 curvatures using idealized soil displacement profiles with distinct transitions at layer boundaries. As a
630 sensitivity analysis, combining kinematic demands and full (100%) inertia overestimated the bending
631 moments at pile head by +7%, overestimated the shallow bending moments (depth <10D) by +24%, and
632 overestimated the deep bending moments (depth > 10D) by 37%, on average. While the results presented
633 in Figures 18a to 18c were discussed in the preceding section in terms of average trends between estimated
634 and measured bending moments, there is a noticeably large scatter in the estimated values. This scatter is
635 associated with the inherent limitations in equivalent static analysis where a dynamic, nonlinear response
636 is simplified to a pseudo-static application of loads, as well as the modeling assumptions that were
637 made in these analyses such as the use of a constant inertial multiplier (C_{cc}) of 85% for all tests.
638 This scatter can be reduced by refining the inertial multiplier for each test based on the soil profile
639 and the inertial multipliers reported in Table 2 as guidance. Alternatively, nonlinear dynamic
640 analysis can be performed to refine the combination of inertial and kinematic loads as suggested
641 by POA (2017).

642 **DESIGN EXAMPLE**

643 A design example is presented here to summarize the implementation of the recommended
644 procedure for estimating and combining the inertial and kinematic loads in design. The soil profile
645 and pile properties in Test NJM02 is used in this example. The wharf structure in this example is
646 supported on 21 piles in a 7-by-3 configuration as shown in Figure 1. The pile demands are
647 estimated using the following steps:

648 **Step 1: Estimate kinematic demands:**

649 In this example the lateral soil displacements are estimated using the Newmark sliding
650 block method. The yield acceleration is estimated as 0.053 g using pseudo-static limit
651 equilibrium analysis and is assumed to be constant during the acceleration time histories.

652 The recorded accelerations from the centrifuge test are used as input for the Newmark
653 analysis; however, in a design project the accelerations are typically obtained from 1D or
654 2D site response analysis. The mean Newmark displacement at the ground surface is
655 estimated as 0.07 m and is assumed to be distributed linearly with depth in the loose
656 liquefiable layer and to remain constant within the nonliquefiable layers (rockfill and dense
657 sand). The idealized estimated soil profiles along the piles are shown in Figure 3.

658 **Step 2: Estimate peak inertial demands:**

659 The peak inertial loads are estimated in a pseudo-static analysis as described by the
660 following steps.

- 661 • Pushover curves are developed in *LPILE* for the entire pile group under the two
662 conditions shown in Figure 10. In the liquefied condition the estimated soil
663 displacements from the previous step is applied to the end nodes of p-y springs and the
664 p-y springs in the liquefiable layer were softened using p-multipliers. The initial lateral
665 stiffness of the wharf-foundation system is estimated as 42,710 kN/m and 42,080 kN/m
666 in nonliquefied and liquefied conditions, respectively (Figure 11). Using the wharf
667 mass of 971.3 Mg, the equivalent natural period is calculated as 0.94 sec and 0.95 sec
668 in nonliquefied and liquefied conditions, respectively. In the following steps in this
669 example, the liquefied condition is used to estimate the peak inertial load.
- 670 • The spectral accelerations at the ground surface are calculated from recorded
671 acceleration time histories in the centrifuge test; however, the spectral accelerations are
672 typically developed in design applications based on site-specific site response analysis.
673 The spectral acceleration at the ground surface in the liquefied condition is estimated
674 as $PSA = 0.24$ g at the structural period of 0.95 sec as shown in Figure 13.

675 • The total inertial load from the structure mass is calculated as the product of the wharf
676 mass and *PSA* as $971.3 \text{ Mg} * 0.24 * 9.81 \text{ ms}^{-2} = 2287 \text{ kN}$. Pile head shear loads are
677 estimated for each pile by distributing the total deck inertial load between the 21
678 individual piles in the pile group based on their relative lateral stiffness obtained from
679 the pushover analysis.

680 **Step 3: Combine peak inertial and peak kinematic loads to estimate pile demands:**

681 The estimated soil displacement profile and the pile head shear load (multiplied by an inertial
682 load factor, *Ccc*) are imposed in *LPILE* based on the three load combinations shown in Figure 16
683 and the pile bending moments are estimated accordingly (Figure 17). Table 2 provides some
684 guidance on selecting the inertial load factor (*Ccc*) based on different soil profiles. In this
685 example, a *Ccc* value of 0.85 is used based on the median + 1σ values among all five tests. The
686 comparison of estimated and recorded bending moments in this study showed that applying pile
687 head shear only (Case A) accurately predicts the magnitude of measured bending moments at the
688 pile head, while applying soil displacement only (Case C) accurately estimates the magnitude of
689 recorded bending moments at locations deeper than 10 times pile diameter. Pile bending
690 moments at shallower locations are better estimated when the two loads are combined (Case B).

691 **CONCLUDING REMARKS**

692 The combination of inertial and kinematic demands in pile foundations subjected to
693 liquefaction-induced lateral spreading was investigated using the experimental data from five
694 centrifuge tests on pile-supported wharves in conjunction with a practice-oriented equivalent static
695 analysis using *LPILE*. The peak kinematic demands were estimated from displacement profiles
696 established with the Newmark sliding block method using recorded acceleration time histories in
697 centrifuge tests. The peak inertial demands were estimated using the natural period of the wharf–

698 foundation system and the spectral acceleration at the ground surface. The analysis was performed
699 for three loading cases: soil displacement only, peak inertia only, and soil displacement combined
700 with 85% of peak inertia. The bending moments estimated from ESA were compared to the peak
701 bending moments measured in the centrifuge tests. The comparison provided a systematic way to
702 evaluate the accuracy of the load combinations in estimating bending moment demands and
703 highlighted circumstances under which each load combination controls the pile design. The
704 primary conclusions of the analyses are summarized as follows.

- 705 • Reasonable estimates of bending moments at the pile head were made by applying only the
706 peak inertial load, while bending moments at deep locations ($>10D$) were overestimated by
707 34% by applying only the kinematic demands.
- 708 • Bending moments at shallow locations ($<10D$) were reasonably estimated (overestimated by
709 11%) by combining kinematic demands with 85% of peak deck inertial load.
- 710 • Median soil displacements calculated using the Newmark sliding block method were well
711 correlated with permanent, residual displacements from the centrifuge tests, but
712 underestimated the peak transient displacements. Newmark median + 1σ values were better
713 correlated with the peak transient displacements from the centrifuge tests.
- 714 • There is considerable uncertainty in predicting the pattern of soil displacement with depth, and
715 this significantly affects the estimated bending moments in the equivalent static analysis of
716 flexible piles. The idealized profile of soil displacements in multi-layered soils based on the
717 maximum shear strain potential in each layer (i.e. LDI approach) resulted in distinct transitions.
718 In the cases that were analyzed in this study, the overestimation of bending moments due to
719 distinct transitions in idealized soil displacement profiles appeared to cancel out the
720 underestimation of peak transient soil displacements using the Newmark mean values. A more

721 rigorous analysis may include smoothening the transition over one to two pile diameters, as
722 recommended by Caltrans (2012) and McGann et al. (2011), combined with the use of peak
723 transient displacements.

724 • The peak deck accelerations and the peak shear forces at pile head were reasonably estimated
725 by ESA methods using pushover analyses for both liquefied and nonliquefied conditions.

726 • The analyses in this study suggest that higher damping ratios ($> 5\%$) may be warranted in
727 estimating deck accelerations to approximate the combined influence of radiation damping,
728 nonlinear soil behavior and inelastic pile performance consistent with the cyclically-induced
729 permanent deformations.

730 • The portion of the peak inertia that was acting at the deck during the critical cycle (C_{cc}) ranged
731 from 0.2 to 1.0 and appeared to be generally correlated with soil profile and the dynamic
732 response of each soil unit. The five tests were subdivided into two general categories: Profile
733 B1 is characterized as configurations that include deep-seated liquefaction underlying
734 significant nonliquefiable crust (i.e. rockfill). Profile B2 is characterized as configurations that
735 include generally smaller kinematic demands associated with either nonliquefiable profiles or
736 weak/softened soils closer to the ground surface, and thin nonliquefiable crust (i.e. sliver
737 rockfill). Inertial multipliers (C_{cc}) of 0.3 to 0.6 were back-calculated for soil profiles that
738 resemble Profile B1 and C_{cc} values of 0.9 to 1.0 were back-calculated for soil profiles that
739 resemble Profile B2.

740 • The wide range of C_{cc} values observed in this research highlights the need for sensitivity
741 analysis when performing ESA, and the benefit of performing coupled nonlinear dynamic
742 analysis that capture complex soil-pile-structure interaction for varying soil profiles.

743 • The load combination factors were used in this study in decoupled analysis using the p-y spring
744 approach and are not necessarily appropriate for use with the simplified equivalent fluid
745 pressure for lateral spreading load.

746 These conclusions are applicable only for relatively flexible piles with small diameters (up to about
747 0.7 m). The interaction of inertial and kinematic loads could be different for pile shafts with larger
748 diameters. Incorporating uncertainties in design (e.g. uncertainties associated with estimating
749 ground motions) may introduce bias in estimating inertial demands that could affect how the
750 inertial and kinematic demands are combined. The sensitivity of the proposed load combinations
751 to these uncertainties is an important issue that needs to be evaluated in future studies.

752 **DATA AVAILABILITY STATEMENT**

753 Some or all data, models, or code generated or used during the study are available at the
754 Center of Geotechnical Modeling at the University of California at Davis
755 (<https://cgm.engr.ucdavis.edu>) in accordance with granting agency data retention policies.

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764 **SUPPLEMENTAL DATA**

765 Supplemental Appendix A provides details on the calibration of the *LPILE* models using
766 four quasi-static lateral load tests. Supplemental Appendix B provides input parameters used in
767 the Newmark sliding block analyses. Supplemental Appendix C shows the comparison between
768 measured and estimated bending moments for all five centrifuge tests (NJM01, NJM02, SMS01,
769 SMS02 and JCB01). The supplemental appendices are available online in the ASCE Library
770 (www.ascelibrary.org).

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928 **LIST OF TABLES**

- 929 Table 1. Design guidelines on combination of inertial and kinematic demands on piles
930 Table 2. Back-calculated load combinations to combine inertial load and kinematic load from
931 lateral ground deformations for the centrifuge tests in this study
932

933 **LIST OF FIGURES**

- 934 Figure 1. Cross sections and plan view of five centrifuge tests on pile-supported wharves.
935 Figure 2. Comparison of estimated and measured ground surface soil displacements.
936 Figure 3. Comparison of soil displacements at pile locations estimated in design (mean Newmark)
937 and interpreted from centrifuge test results (peak transient) for NJM01 Event 11.
938 Figure 4. Comparison of soil displacement profiles at the pile locations interpreted from centrifuge
939 tests (peak transient) and estimated in design (mean Newmark).
940 Figure 5. (a) Comparison of soil displacement profiles interpreted from
941 centrifuge tests (peak transient) and estimated in design (mean Newmark) for Pile #1 in NJM01.
942 (b) comparison of estimated bending moments from LPILE and measured bending moments from
943 centrifuge
944 Figure 6: Soil reaction profiles at the time of maximum bending moment in NJM01 and SMS01.
945 Figure 7. (a) Displacement, (b) soil reaction at small scale, (c) soil reaction at large scale, and (d)
946 bending moment profiles at the time of maximum bending moment for Pile 1 in NJM01 Event 11.
947 Figure 8. Comparison of recorded maximum bending moments for all instrumented piles in
948 NJM01 Event 11 with estimated values from the baseline analysis in *LPILE*
949 Figure 9. Comparison of maximum bending moments recorded from centrifuge and predicted from
950 *LPILE* baseline analyses (soil displacements and pile head shear extracted from centrifuge) for all
951 five centrifuge tests
952 Figure 10. Schematic of (a) nonliquefied and (b) liquefied pushover analyses.
953 Figure 11. Pile group force-displacement relationships (pushover curves) for nonliquefied and
954 liquefied conditions.
955 Figure 12. Comparison of estimated natural period in liquefied condition against nonliquefied
956 condition from pushover analyses.
957 Figure 13. Spectral accelerations for liquefied and nonliquefied conditions for NJM01 Event 11.
958 Figure 14. Comparison of estimated spectral acceleration from design method to peak wharf
959 acceleration measured in the centrifuge tests.
960 Figure 15. Comparison of estimated shear force from pushover analysis to the peak shear force at
961 the pile head calculated from the centrifuge test results.
962 Figure 16. Schematic of proposed ESA load combinations for piles subjected to ground
963 deformations: (a) inertia only, (b) combined inertia and kinematic, and (c) kinematic only
964 Figure 17. Comparison of measured and estimated bending moments for NJM01 Event 11.
965 Figure 18. Peak bending moments measured in the centrifuge tests and estimated from ESA
966 analyses in LPILE at (a) pile head, (b) locations shallower than 10D, and (c) locations deeper
967 than 10D.

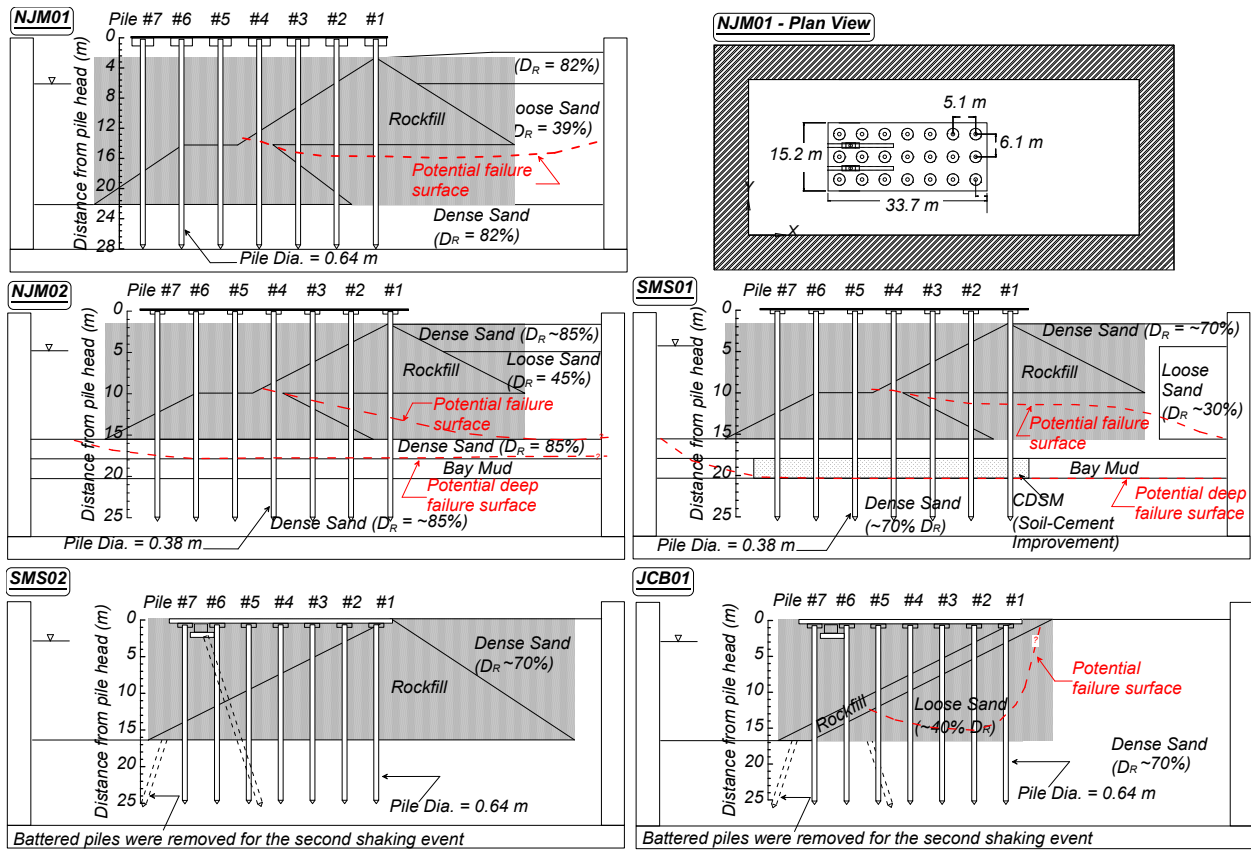
Table 1. Design guidelines on combination of inertial and kinematic demands on piles

Design Code	Recommendation
ASCE 61-14 (2014) Section C4.7 and Port of Long Beach Wharf Design Criteria (POLB 2015)	Locations of maximum bending moment from inertial and lateral ground deformation are spaced far enough apart that the two loads do not need to be superimposed. Maximum bending moments occur at different times. The two loads should be treated uncoupled for marginal wharves.
Port of Anchorage Modernization Program Seismic Design Manual (POA 2017)	Combine peak inertial loading from earthquake ground motion with 100% peak kinematic demands from lateral ground displacements. Smaller factors are allowed if peer-reviewed 2-D nonlinear numerical analysis is used (no less than 25%).
AASHTO (2014)	Design the piles for the simultaneous effects of inertial and lateral spreading loads only for large magnitude earthquakes ($M > 8$).
MCEER/ATC (2003)	For most earthquakes, peak inertia is likely to occur early in the ground motion. Design piles for independent effects of inertia and lateral spreading. For large magnitude and long-duration earthquakes the two loads may interact.
PEER (2011)	100% kinematic + (65% to 85%) inertial (multiplied by 0.35 to 1.4 to account for the effects of liquefaction on peak inertial load)
Caltrans (2012) and ODOT (2014)	100% kinematic + 50% inertial
WSDOT (2021)	100% kinematic + 25% inertial

971 **Table 2.** Back-calculated load combinations to combine inertial load and kinematic load from
 972 lateral ground deformations for the centrifuge tests in this study

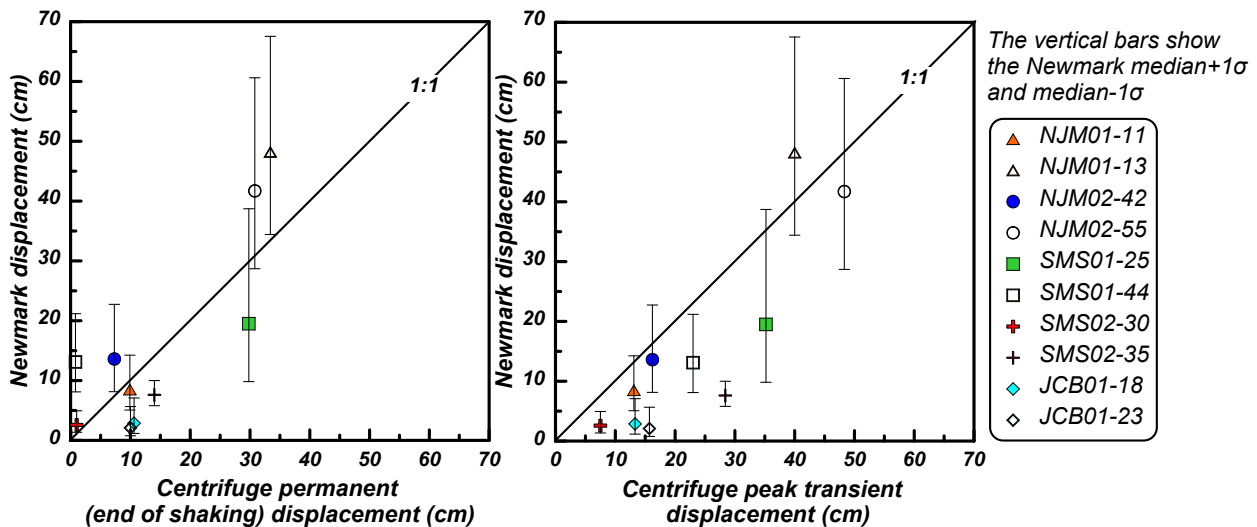
(Case) Load combination	Portion of permanent soil displacements applied at end nodes of p-y springs ¹	Portion of peak deck inertial force applied at deck ²	Applicability
(A) Inertia only	NA	100%	Adequate to estimate bending moments at pile head.
(B1) Combined kinematic and inertial demands- Profile B1 ³	100%	0.3 to 0.6 ⁵	Suitable to estimate bending moments below grade down to depth of 10D.
(B2) Combined kinematic and inertial demands- Profile B2 ⁴	100%	0.9 to 1.0 ⁵	Suitable to estimate bending moments below grade down to depth of 10D.
(C) Kinematic only	100%	NA	Adequate to estimate pile bending moments deeper than 10D.

- 973 1. Soil displacement profiles in this study were estimated using the mean Newmark values distributed with depth
 974 using an idealized profile based on the lateral displacement index approach (Zhang et al. 2004; Idriss and Boulanger
 975 2008)
- 976 2. Peak deck inertial forces were estimated in this study using ESA performed for liquefied conditions. If ESA is
 977 performed for nonliquefied conditions, an additional multiplier may be needed (*Cliq* per Boulanger et al. 2007) to
 978 account for the effects of liquefaction on the wharf peak inertial demands.
- 979 3. Profile B1 represents typical cross sections in tests NJM02, NJM02, and SMS01 which can be characterized as
 980 configurations that include deep-seated liquefaction underlying significant nonliquefiable crust (i.e. rockfill).
- 981 4. Profile B2 represent the cross sections in two tests that can be characterized as configurations that include generally
 982 smaller kinematic demands/loads associated with either nonliquefiable profile (test SMS02) or weak/softened soils
 983 closer to the ground surface, and thin nonliquefiable crust (test JCB01).
- 984 5. These ranges provide an initial baseline for preliminary analysis subject to refinement on a project-specific basis.
 985 The load combination factors presented here are appropriate for decoupled analysis using the p-y spring approach
 986 and are not necessarily appropriate for use with the simplified equivalent fluid pressure for lateral spreading load.
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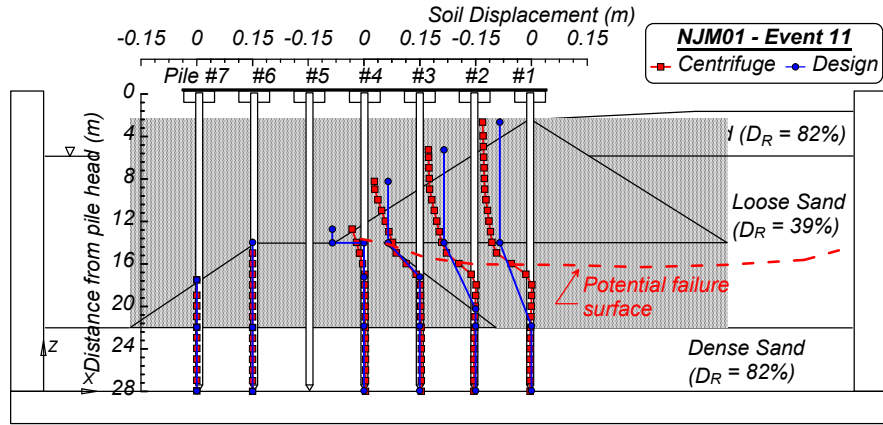
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Fig. 1. Cross sections and plan view of five centrifuge tests on pile-supported wharves.

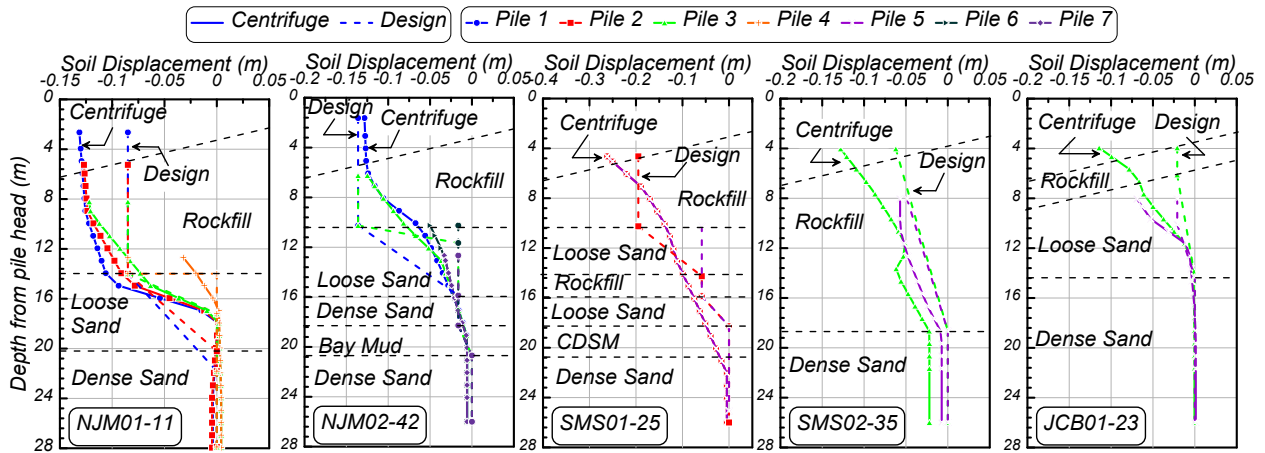


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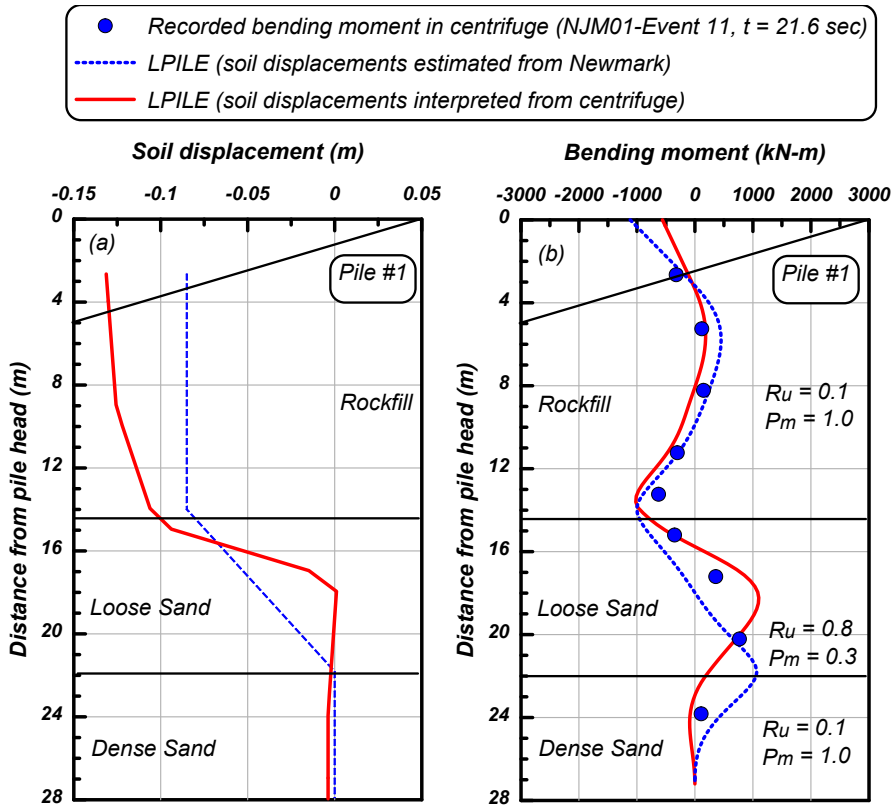
Fig. 2. Comparison of estimated and measured ground surface soil displacements.



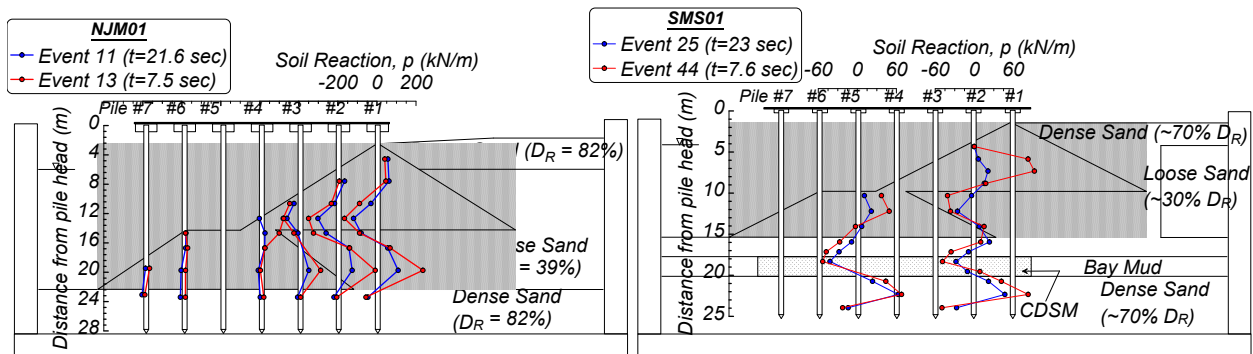
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 996 **Fig. 3.** Comparison of soil displacements at pile locations estimated in design (mean Newmark)
 997 and interpreted from centrifuge test results (peak transient) for NJM01 Event 11.
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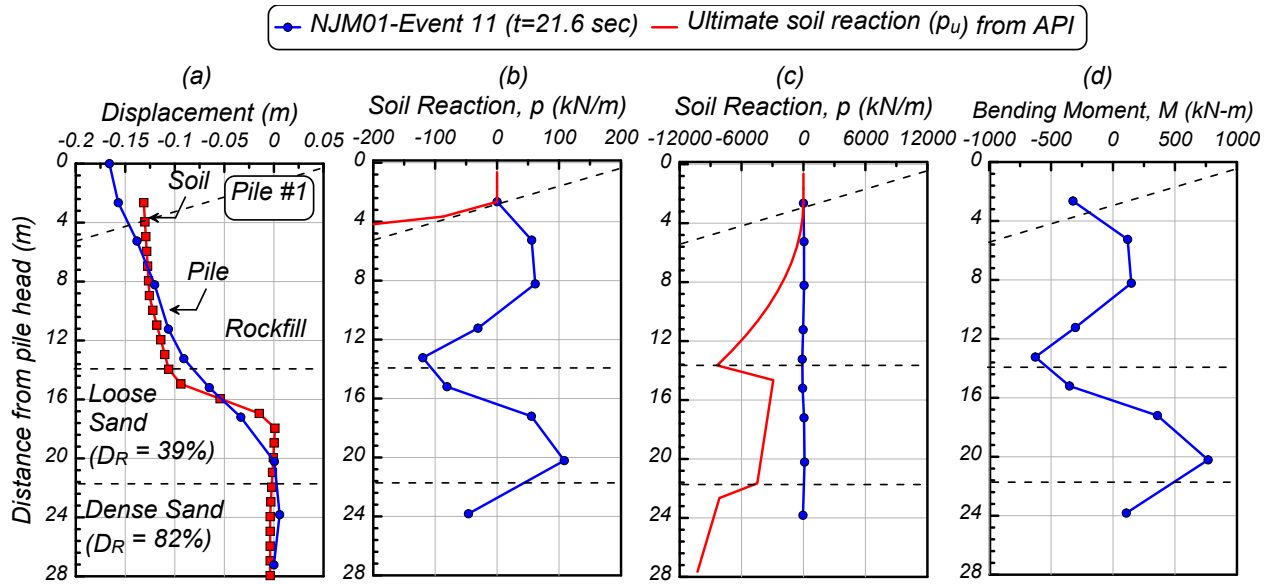
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 1000 **Fig. 4.** Comparison of soil displacement profiles at the pile locations interpreted from
 1001 centrifuge tests (peak transient) and estimated in design (mean Newmark).
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1003
 1004 **Fig. 5.** (a) Comparison of soil displacement profiles interpreted from
 1005 centrifuge test (peak transient) and estimated in design (mean Newmark) for Pile #1 in NJM01.
 1006 (b) comparison of estimated bending moments from LPILE and measured bending moments
 1007 from centrifuge



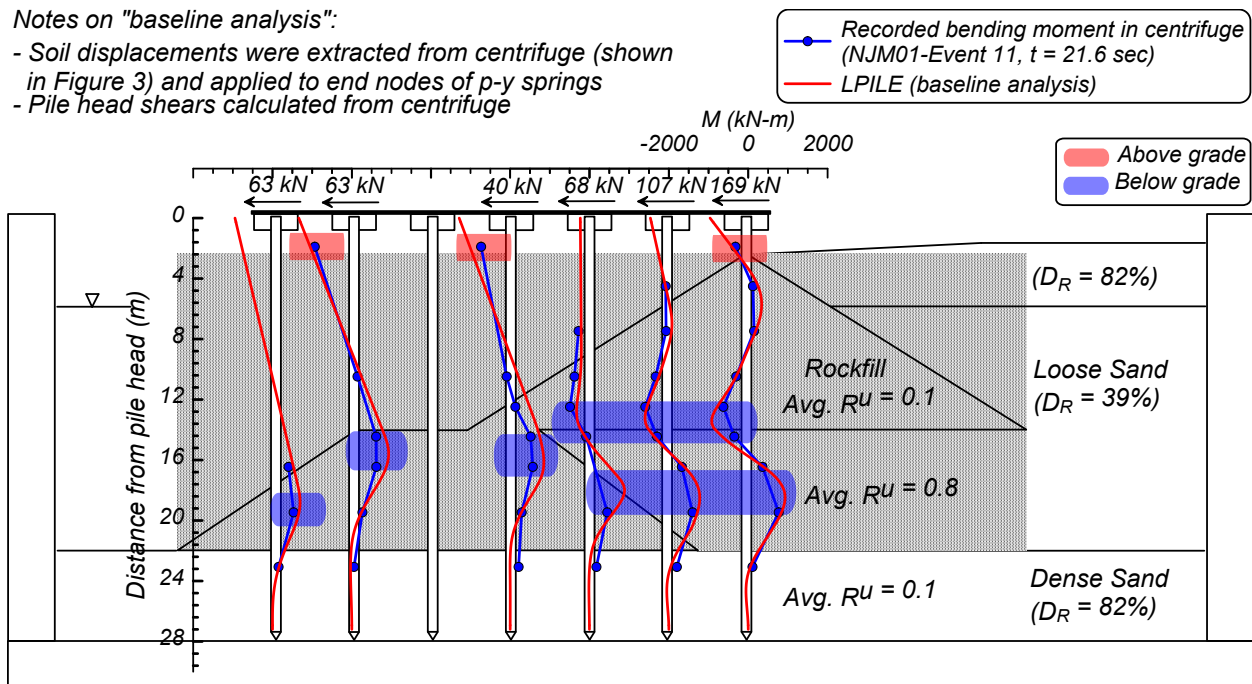
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 1009 **Fig. 6.** Soil reaction profiles at the time of maximum bending moment in NJM01 and SMS01.
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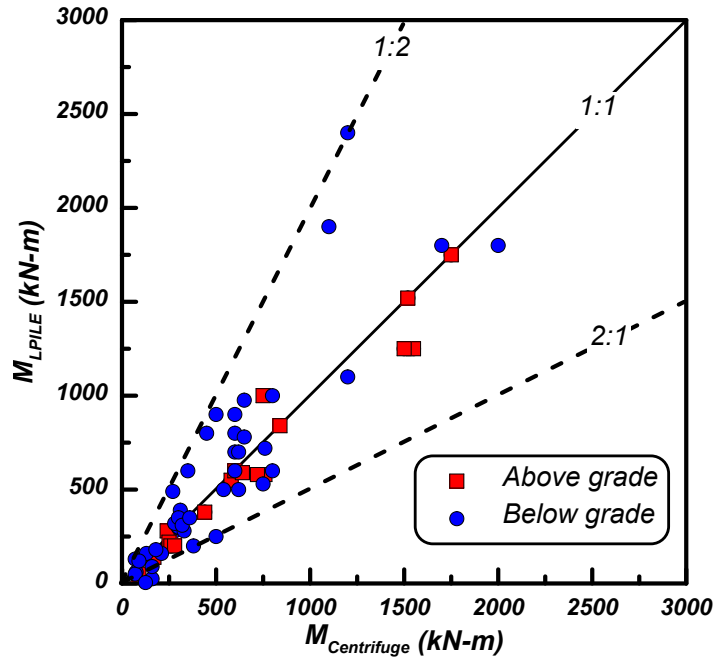
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 1012 **Fig. 7.** (a) Displacement, (b) soil reaction at small scale, (c) soil reaction at large scale, and (d)
 1013 bending moment profiles at the time of maximum bending moment for Pile 1 in NJM01 Event
 1014 11.
 1015

Notes on "baseline analysis":

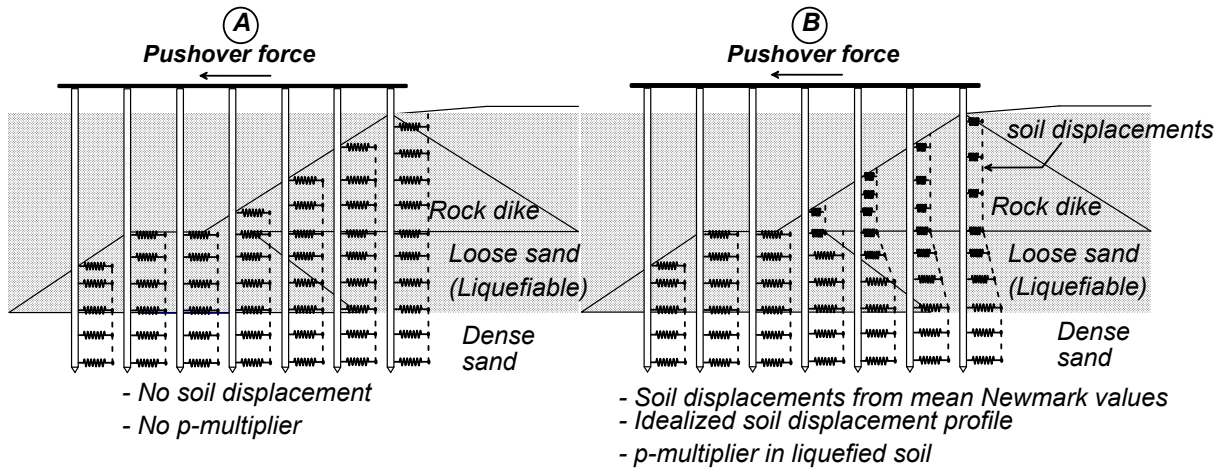
- Soil displacements were extracted from centrifuge (shown in Figure 3) and applied to end nodes of p-y springs
- Pile head shears calculated from centrifuge



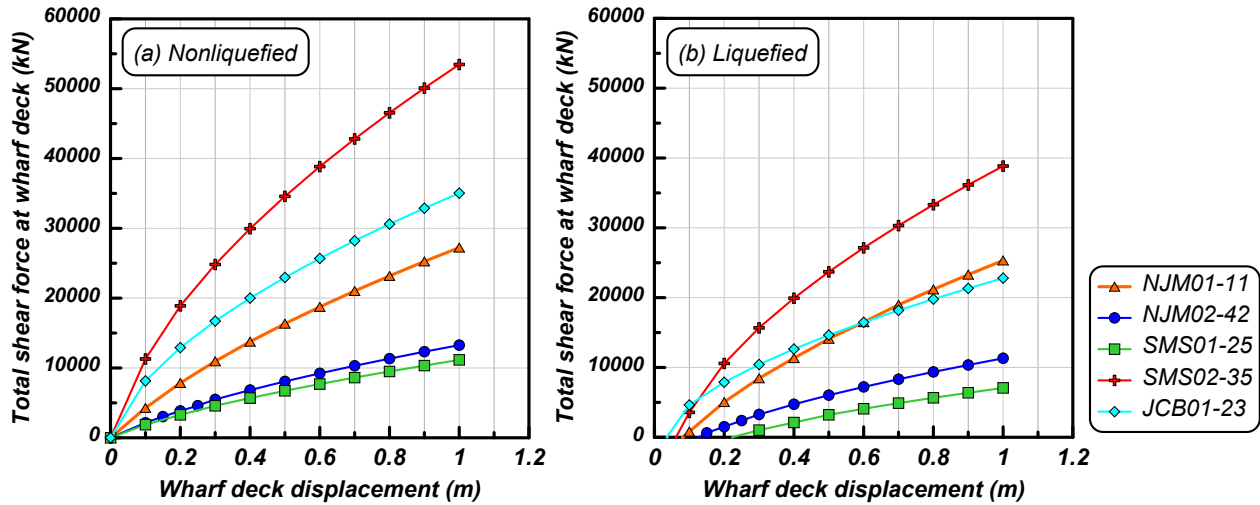
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 1017 **Fig. 8.** Comparison of recorded maximum bending moments for all instrumented piles in NJM01
 1018 Event 11 with estimated values from the baseline analysis in *LPILE*
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 1022 **Fig. 9.** Comparison of maximum bending moments recorded from centrifuge and predicted from
 1023 *LPILE* baseline analyses (soil displacements and pile head shear extracted from centrifuge) for
 1024 all five centrifuge tests
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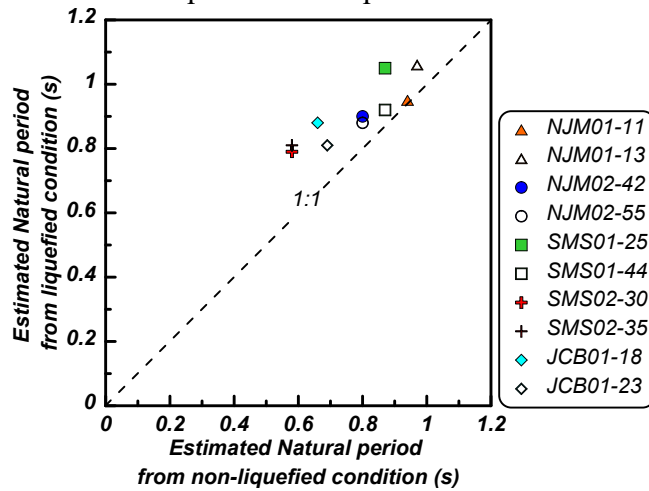


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 1027 **Fig. 10.** Schematic of (a) nonliquefied and (b) liquefied pushover analyses.



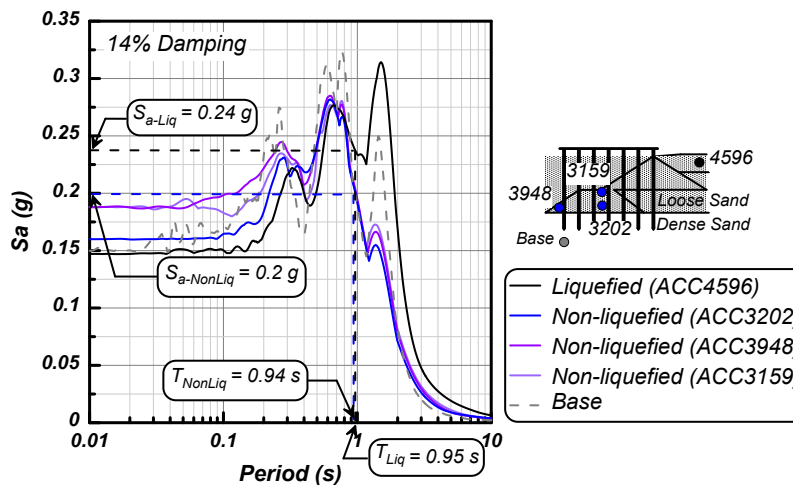
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Fig. 11. Pile group force–displacement relationships (pushover curves) for nonliquefied and liquefied conditions.



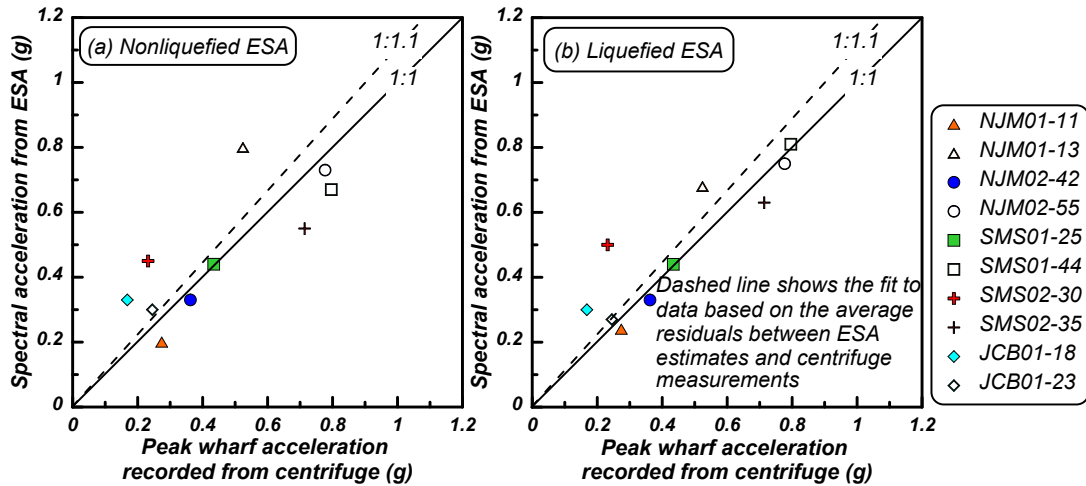
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Fig. 12. Comparison of estimated natural period in liquefied condition against nonliquefied condition from pushover analyses.



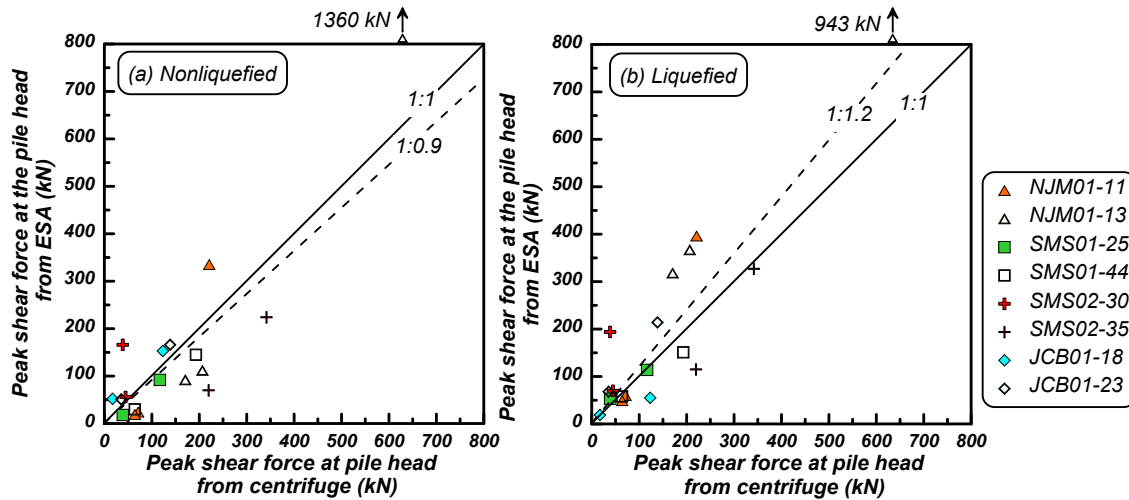
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Fig. 13. Spectral accelerations for liquefied and nonliquefied conditions for NJM01 Event 11.



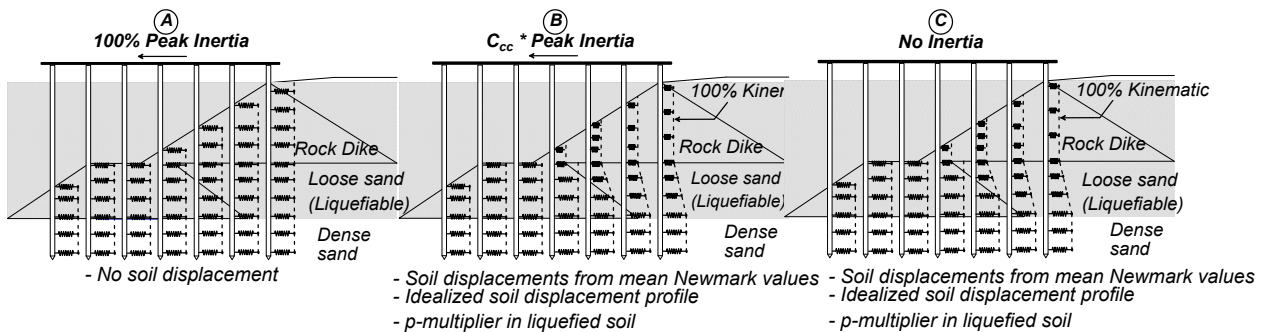
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Fig. 14. Comparison of estimated spectral acceleration from design method to peak wharf acceleration measured in the centrifuge tests.



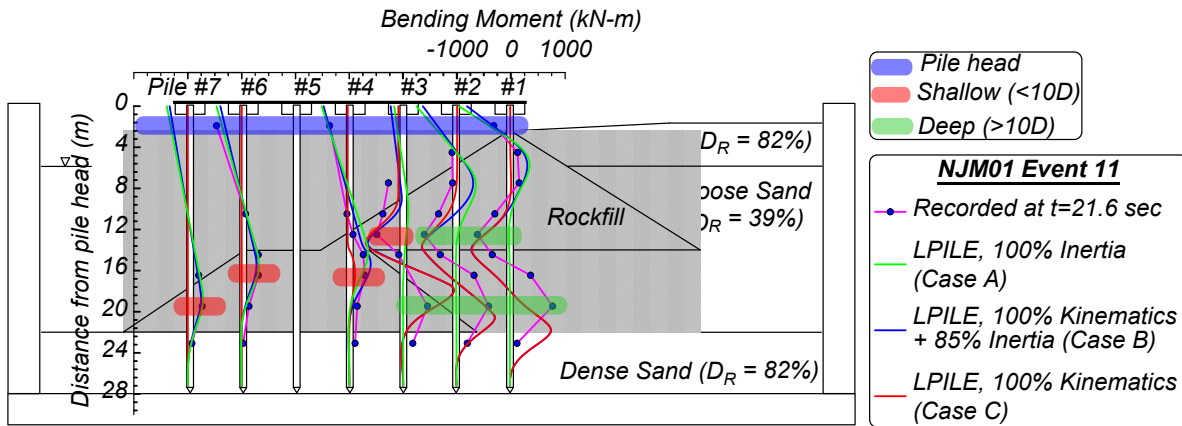
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Fig. 15. Comparison of estimated shear force from pushover analysis to the peak shear force at the pile head calculated from the centrifuge test results.



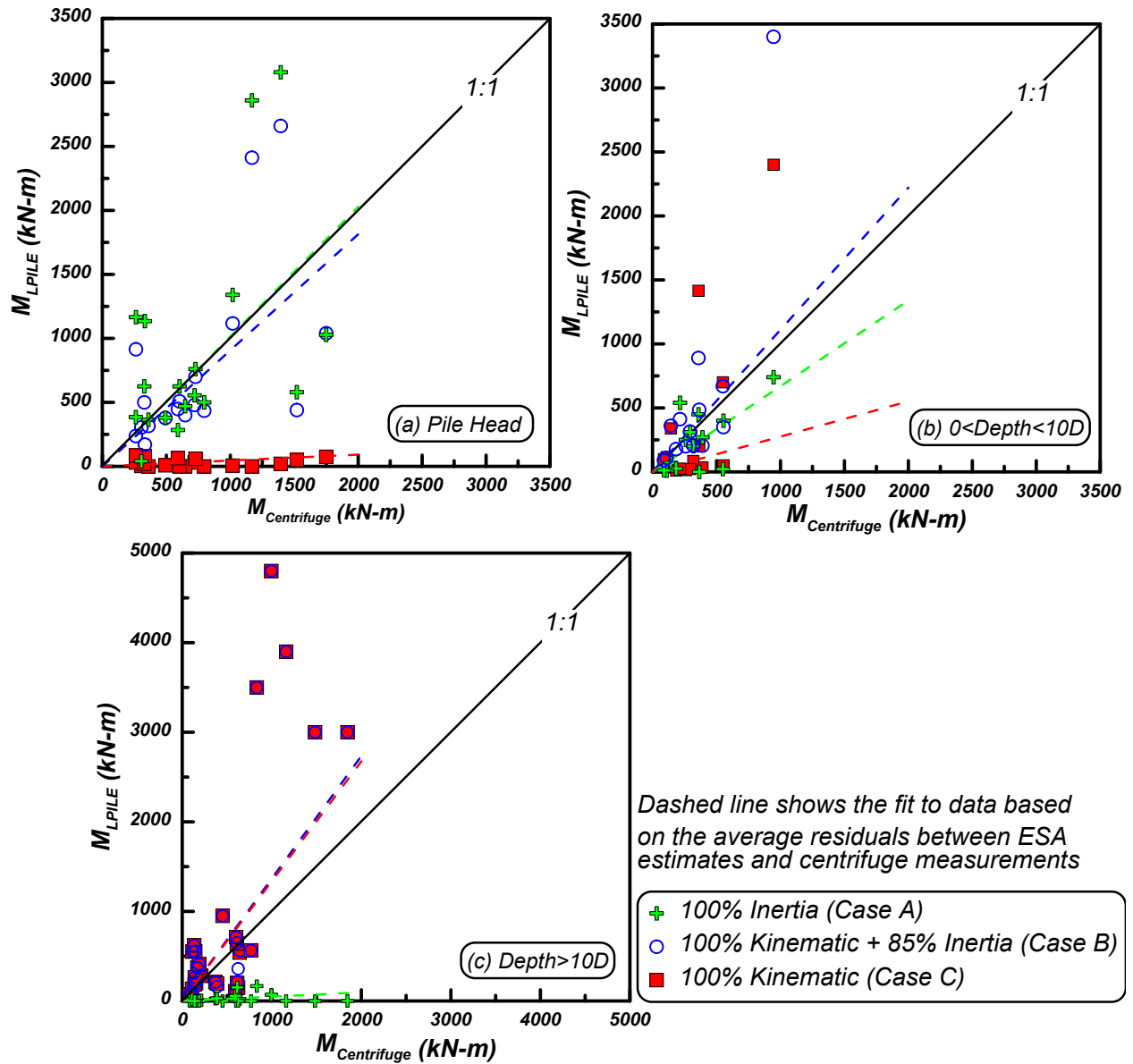
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Fig. 16. Schematic of proposed ESA load combinations for piles subjected to ground deformations: (a) inertia only, (b) combined inertia and kinematic, and (c) kinematic only.



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Fig. 17. Comparison of measured and estimated bending moments for NJM01 Event 11.



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Fig. 18. Peak bending moments measured in centrifuge tests and estimated from ESA analyses in *LPILE* at (a) the pile head, (b) locations shallower than $10D$, and (c) locations deeper than $10D$.