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1	Research in Context
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3	TITLE: Why Should We Investigate the Morphological Disparity of Plant Clades?
4	
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ABSTRACT

2 Background

Disparity refers to the morphological variation in a sample of taxa, and is distinct from 3 4 diversity or taxonomic richness. Diversity and disparity are fundamentally decoupled; many groups attain high levels of disparity early in their evolution, while diversity is still 5 comparatively low. Diversity may subsequently increase even in the face of static or 6 declining disparity by increasingly fine subdivision of morphological 'design' space 7 (morphospace). Many animal clades reached high levels of disparity early in their evolution, 8 9 but here have been few comparable studies of plant clades, despite their profound ecological evolutionary importance. We offer a prospective and some preliminary 10 and macroevolutonary analyses. 11

12 Methods

13 Classical morphometric methods are most suitable when there is reasonable conservation of 14 form, but lose traction where morphological differences become greater (e.g., in comparisons 15 across higher taxa). Discrete character matrices offer one means to compare a greater 16 diversity of forms. We explore morphospaces derived from eight discrete data sets for major 17 plant clades, and discuss their macroevolutionary implications.

18 Key Results

Most of the plant clades in our study show initial, high levels of disparity that approach or attain the maximum levels reached subsequently. These plant clades are characterised by an initial phase of evolution during which most regions of their empirical morphospaces are colonised. Angiosperms, palms, pines and ferns show remarkably little variation in disparity through time. Conifers furnish the most marked exception, appearing at relatively low disparity in the latest Carboniferous, before expanding incrementally with the radiation of successive, tightly clustered constituent subclades.

2 Conclusions

Many cladistic datasets can be repurposed for investigating the morphological disparity of
plant clades through time, and offer insights that are complimentary to more focused
morphometric studies. The unique structural and ecological features of plants make them
ideally suited to investigating intrinsic and extrinsic constraints on disparity.

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Key Words: Disparity, Embryophyta, Morphological diversity, Morphospace, Angiosperms,
Conifers, Ferns, Macroevolution, Clade shapes.

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INTRODUCTION

13

The number of species within higher taxa, or within clades of a similar age (Magallón and 14 15 Sanderson 2001), is hugely variable, even for sister groups diverging (by definition) at the same time. While rates and patterns of extinction are clearly influential, some clades appear 16 much more adept at subdividing niche space and speciating than others; even in comparison 17 with their closest relatives. Some groups foster enormous radiations in diversity despite 18 maintaining conservative bodyplans and displaying only modest morphological variety 19 relative to that in their parent clades. Insects, as the best example, have a highly constrained 20 body organisation (a fixed number of appendages and tagmata) relative to other groups of 21 arthropods (c.f. crustaceans and branchiopods in particular), yet constitute over half of all 22 described arthropod species (Mayhew 2007). Similarly, beetles display remarkably 23 24 conservative organisation within insects, despite their notoriously high contribution to global species richness (Erwin 1997). There is no necessary relationship, therefore, between the 25

number of species within a group (species richness or diversity) and its morphological
diversity. Indeed, there are suggestions that a constrained and entrenched bodyplan might
actually be conducive to higher diversity (Rabosky *et al.* 2012).

4 In order to study the relationship between species richness and bodyplan conservation, we need to quantify both diversity and morphological variety or disparity for large groups. 5 Methods for studying diversity are well established (Peet 1974; Gotelli and Colwell 2001; 6 Benton 2009; Ezard et al. 2011; Mayhew et al. 2012), but approaches for quantifying 7 disparity are less familiar; particularly in the botanical literature (Chartier et al. 2014). While 8 9 it is possible and informative to study diversity and disparity across clades within the extant biota (or, indeed, in any time slice), insights into the dynamics of their interaction are most 10 fruitfully gained by investigating the trajectories of clades throughout their evolution. Most 11 12 studies to date have focussed on animals (Foote 1994, 1997; Moyne and Neige 2007; Hughes et al. 2013), but the long evolutionary history (Wellman 2014) and rich fossil record of land 13 plants (embryophytes) make them ideally suited for comparison. Diversity patterns through 14 15 time within vascular plants have been studied for many years, typically deriving from species-level compilations of originations and extinctions (Knoll et al. 1979; Niklas et al. 16 1980; Lidgard and Crane 1990; Kovach and Batten 1993; Cascales-Miñana and Cleal 2012, 17 2014). Results have differed in some details (Niklas and Tiffney 1994), but are broadly 18 19 consistent in showing i) a radiation of pteridophytes and gymnosperms in the Late Devonian-20 Carboniferous ii) a gymnosperm dominated flora in the early-mid Mesozoic of comparatively constant diversity and iii) a mid-late Cretaceous to Tertiary diversity increase, due primarily 21 to the radiation of the angiosperms. The presence of novel morphological features within this 22 group raised the question of whether phases of embryophyte diversification could be 23 explained by the acquisition of 'key innovations' within angiosperms (Endress 2001), seed 24 plants (Rudall and Bateman 2007) and early land plants (Bateman et al. 1998; Renzaglia et al. 25

2000). Advances in plant phylogenetics have revealed that the timing of many plant 1 2 radiations does not match the first appearance of hypothesised innovations (Sanderson and Donoghue 1994; Davies et al. 2004; Vamosi and Vamosi 2010), implying instead that the 3 4 evolution of suites of characters over an extended period of time may enable diversification (Donoghue 2009). The hunt for specific drivers has shifted to focus either on competitive 5 interactions, for example between plants and herbivores (Agrawal 2007; Futuyma and 6 Agrawal 2009), or on environmental factors such as climatic change (McElwain et al. 1999; 7 Beerling et al. 2001; Willis and Niklas 2004; Beerling and Berner 2005; Feild and Arens 8 9 2007; Boyce et al. 2009; Willis and McElwain 2013).

In marked constrast to diversity, for which temporal patterns have been investigated 10 for many years (Crane et al. 1994; Crisp et al. 2011; Donoghue 2008; Kenrick et al. 1997; 11 12 Lupia et al. 1999; Schneider et al. 2004; Soltis et al. 2004), there have been only a handful of studies on the morphological disparity of plants (Lupia 1999; Niklas 1999; Chartier et al. 13 2014). Often these studies have focused on a specific aspect of plant morphology such as 14 15 leaves (Boyce and Knoll 2002; Boyce 2005) or vascular systems (Wilson and Knoll 2010; Feild et al. 2011). Disparity analyses have furnished an important means of assessing 16 macroevolutionary patterns in animals for some years, and we believe that their application to 17 plants would be equally insightful. 18

19

20 *Aims*

This paper has two primary aims. The first is to provide an overview of the methods used to quantify morphological disparity, with particular emphasis on their application to plant evolution. We contrast concepts of disparity with those of diversity or species richness, and explain how exploring both trajectories through time can shed light on the evolutionary dynamics of clades. Morphological disparity is usually quantified with reference to the axes

1 of some form of morphospace; an *n*-dimensional space in which the distances between 2 species or other operational taxonomic units are proportional to some measure of the morphological distances between them. We therefore distinguish between theoretical and 3 4 empirical morphospaces and discuss their relative advantages and disadvantages for the study of plants. We also explore a variety of potential data sources and consider their relative merits. 5 Particular emphasis is given to character-based empirical methods, which have proved 6 broadly applicable to animal clades at a wide range of taxonomic levels (Hughes et al. 2013), 7 but have yet to be utilized in plants. The second objective is to demonstrate the application of 8 9 these methods to a select number of published character matrices for major plant groups. We compare and contrast the observed patterns of disparity through time with those seen in 10 animals and offer a prospectus for future studies of plant disparity. 11

12

13 What is disparity and why should we study it?

The macroevolution of any major clade through deep time can be characterised in a number 14 15 of ways. There is perennial interest in how diversity changes (Sepkoski et al. 1981; Sepkoski 1997; Sepkoski and Miller 1998), particularly with regards to how species and higher 16 taxonomic richness responds to major physical or biotic changes such as mass extinctions, the 17 opening up of new habitats or the origination of other major groups. Equally fundamentally, 18 19 we may wish to know how the constituent taxa of a clade are related, and may use phylogeny 20 to better inform the patterns above. Increasingly, however, palaeobiologists are also focussing on the manner in which groups diversified morphologically to give rise to new bodyplans or 21 architectures (Fortey et al. 1996). The range or variance of morphological form across 22 species or other taxa is usually referred to as 'morphological variety', 'morphological 23 disparity' or simply 'disparity' in context. Disparity is therefore a property of a sample of 24 taxa rather than of individual species, and is also measured relative to some set of 25

1 quantifiable variables. Trajectories of disparity through time are often different from patterns 2 of species and higher taxonomic diversity, and are also difficult to predict from phylogeny.

Although all morphological variety is generated within the context of a phylogeny, 3 4 diversity and disparity are fundamentally decoupled (Foote 1991; Fortey et al. 1996, 1997; Moyne and Neige 2007). Large samples of morphologically very similar species typically 5 have much lower disparity than small groups of morphologically highly dissimilar species. 6 Specifically, numerous basal groups of animals show levels of disparity greater than or equal 7 to their more diverse, derived counterparts (Fig. 1) (Foote 1992, 1994, 1997; Wills et al. 8 9 1994; Wills 1998) although exceptions exist (Benson et al. 2012). At a coarse level, higher taxonomic diversity (e.g., numbers of orders or classes) tends to be a better proxy for 10 disparity than numbers of species or genera (Foote 1990). Plots of relative disparity through 11 12 time are therefore often used alongside plots of diversity in order to understand the dynamics of clade evolution more fully. 13

Much of the initial impetus for quantifying levels of disparity came from claims about 14 15 the evolutionary significance of the fossils from the Middle Cambrian Burgess Shale (Whittington 1985; Conway Morris 1989). In particular, it was claimed (Gould 1989) that the 16 range of morphological variety amongst Cambrian arthropods was far greater than that 17 realised at any time subsequently; an argument couched (at least initially) in the perceived 18 higher taxonomic status (i.e., subphylum or class) of many Burgess Shale genera. Gould 19 20 (1991) subsequently propounded an 'inverted iconography' model for the evolution of life. An initial phase of experimentation and looser constraint on bodyplan evolution was posited 21 to yield early maximal disparity, followed by a phase of winnowing in which most bodyplans 22 23 were lost and the survivors consolidated and canalised. Subsequent evolution would typically yield few new bodyplans, but would see increases in diversity; increasing numbers of 24 variations (species) upon a more limited number of constrained themes. However, empirical 25

studies of marine invertebrates found that the disparity of Cambrian and recent faunas were 1 2 essentially equivalent (Briggs et al. 1992; Wills et al. 1994, 2012; Fortey et al. 1996) (Fig. 2). Subsequent studies have examined the disparity of clades at numerous successive time 3 4 intervals, often demonstrating relatively high early disparity even while diversity is low (Foote 1992, 1994; Wills 1998). Recently, this approach has been applied to a larger dataset 5 of exclusively fossil animal clades (Hughes et al. 2013). The shape of the disparity profile of 6 a clade through time can be summarised as a centre of gravity index (CG). Clades with 7 precisely symmetrical patterns through time have indices of 0.50, those with higher levels of 8 9 disparity early in their history have values <0.5 (bottom heavy), while those peaking late tend to > 0.50 (top heavy). In a sample of 98 extinct clades that did not go extinct coincident with 10 one of the 'big five' (Hallam and Wignall 1997, Bambach 2006) mass events, there was a 11 12 significant bias towards bottom heaviness and early high disparity. Groups persisting to the present tend to have top-heavy profiles; not least because they are artificially truncated by the 13 recent. Those disappearing coincident with one of the big five mass events tend to be top-14 15 heavy, and for similar reasons.

Other research agendas have become increasingly important within particular clades. 16 One is the extent to which bodyplans are modular, and comprise units within which changes 17 are relatively tightly correlated, but between which there is greater flexibility (Klingenberg et 18 19 al. 2004; Monteiro and Nogueira 2010; Cooper et al. 2010; Drake and Klingenberg 2010) 20 Another is the extent to which developmental versus environmental factors constrain bodyplans over evolutionary time (Allen et al. 2008; Anderson et al. 2011). Increasingly, 21 there is also interest in quantifying functional disparity, notably in fish and basal tetrapods 22 23 (Friedman 2010; Anderson et al. 2013).

24

25 Why study the disparity of plants?

In contrast to animals, there have been few studies investigating the morphological disparity 1 2 of plant clades. We suspect that the patterns in plants may differ from those in animals; both the trends observed in statistical samples of clades, and the overall pattern of disparity 3 4 through time for the group as a whole. In this latter context, it may be informative to compare plots of ordinal diversity through time (compiled from Benton, 1993), insofar as counts of 5 higher taxa afford a *very* rough approximation to disparity (Fig. 3). Animals reach relatively 6 high levels of ordinal diversity relatively early in their history; commensurate with the 7 patterns revealed in explicit studies of disparity. The pattern observed in vascular plants 8 9 differs markedly. Even accounting for the much later origin of vascular plants compared to animals, plants show a much more gradual increase in ordinal diversity, reaching 50% of 10 their maximum relatively late in their evolutionary history. Plants show ordinal diversity 11 12 increases in three discrete phases: i) the Late Devonian, corresponding to the initial radiation of pteridophytes and gymnosperms; ii) a smaller increase at the start of the Cretaceous, 13 coincident with the appearance of the angiosperms; iii) a Late Cretaceous increase, 14 15 corresponding to the appearance of many modern angiosperm groups (Niklas and Tiffney 1994). 16

Ordinal diversity profiles (Fig. 3) suggest that vascular plants have fewer 17 fundamentally different modes of morphological organisation than animals, and acquired 18 19 novel bodyplans more gradually. Strikingly, plants appear to be relatively unperturbed by the 20 mass extinction events that were catastrophic for animals; or at least the recovery of plants was rapid enough to mask any significant diversity decreases in the fossil record (Rees 2002; 21 McElwain and Punyasena 2007; Cascales-Miñana and Cleal 2014). Plants therefore appear to 22 have greater resilience to certain types of ecological disturbance than animals (Cascales-23 Miñana and Cleal 2012); a surprising inference given that many aspects of plant morphology 24 are thought to be tightly mechanically and physiologically constrained to optimise 25

photosynthetic efficiency and structural support (Niklas and Kerchner 1984). Even relatively 1 2 simple optimization models with a small number of variables can produce the diverse spectrum of habits and gross phenotypes seen across plant groups (Farnsworth and Niklas 3 4 1995; Niklas 1999) (Fig. 4); ecological disturbance may actually serve as a driver for increasing phenotypic diversity. Therefore, although basic structural components (eg. 5 phytomers in the case of branches) may be relatively morphologically conserved across 6 taxonomic groups, they can nevertheless produce markedly different gross morphologies, 7 even between closely related species or within species. This scale-dependent disparity is one 8 9 of the defining characteristics of vascular plants and likely facilitates the unparalleled level of phenotypic plasticity seen within many plant species (Schlichting 1986, 2002; Bradshaw 10 2006). The hierarchical modularity in many aspects of plant form (Barthélémy and Caraglio 11 12 2007; Klingenberg et al. 2012) may also have profound implications for plant evolution (Friedman and Williams 2003). 13

Studies of plant disparity to date have mostly focused on specific structures in which 14 15 shape variation is believed to be of particular functional importance, rather than on holistic analyses of form. Leaf and shoot disparity, in particular, has been extensively studied. Boyce 16 & Knoll (2002) investigated trends in leaf shape in fossil plant lineages, revealing a rapid 17 expansion of leaf morphospace in the Early/Middle Carboniferous. The genetic controls on 18 19 leaf shape (Langlade et al. 2005; Chitwood et al. 2014) and compound leaf structures are gradually being better understood (Klingenberg et al. 2012). Leaf shape appears to be 20 correlated with shoot morphology (Lacroix et al. 2003; Jeune et al. 2006), although the 21 importance of selective, functional and historical constraints in the evolution of these 22 hierarchical systems is poorly understood (Burns et al. 2008). Floral morphology, despite 23 having long been recognised as a critical component of angiosperm disparity (Stebbins 1951) 24 has received relatively little attention until recently (Whibley et al. 2006; Stournaras et al. 25

2013; Chartier *et al.* 2014). Similar considerations apply to the architecture of inflorescences
(Prusinkiewicz *et al.* 2007). Other work has investigated the evolution and possible adaptive
value of different types of pollen (Lupia 1999; Ressayre and Godelle 2002) as well as
physiological properties in the conductive vessels of major seed plant groups (Wilson and
Knoll 2010). floral and general. Rather than attempt to assess disparity from large collations
of morphological data, more holistic approaches tend to consider habit and gross architecture
(Niklas and Kerchner 1984; Niklas 1999; Silva and Batalha 2011).

The decoupling of diversity and disparity within higher plant clades appears every bit 8 9 as great as that within animal groups (Yu et al. 2014). For example, the true grasses (Poaceae) and the bromeliads (Bromelilaceae) are both families of angiosperms in the order 10 Poales. However, the true grasses are represented by about 10,000 species (The Plant List 11 12 2013) of varying size but relatively limited floral disparity, while the bromeliads contain just over 3,000 species but show huge variation in inflorescence morphology (Benzing 2000; Sajo 13 et al. 2004). It is clear that a complete picture of plant disparity cannot be captured by 14 15 focussing exclusively on the disparity of specific structures (as there is strong scale dependence) or by using diversity as a proxy. Holistic approaches that use a broad suite of 16 characters sampled over large numbers of taxa will probably constitute the best way of 17 quantifying plant disparity at macroevolutionary scales. Here, we take some preliminary steps 18 19 in this direction for a sample of higher plant clades.

20

21 *Types of data*

There are many approaches to quantifying morphology (Moore and Moser 1995; Chapman and Rasskin-Gutman 2001; Lockwood *et al.* 2002), and the most suitable usually depends upon the application and the question being addressed. Where the forms being compared are broadly similar (e.g., typically species within genera or families), a variety of morphometric

approaches can be used to derive sets of continuous variables describing shape and shape 1 2 change, usually with some implicit standardisation for size and orientation (Rohlf and Marcus 1993; Adams et al. 2004) (Fig. 5). Three-dimensional, landmark based approaches operate by 3 4 identifying biologically (or functionally) homologous points (e.g., intersections between homologous structures) across all of the species or higher taxa (hereafter 'operational 5 taxonomic units' or OTUs) being compared (Marcus 2000; Cramon-Taubadel et al. 2007; 6 Mitteroecker and Gunz 2009). Outline based methods describe shapes in more detail. This 7 can either be using a more limited number of discrete points (homologous landmarks), 8 9 possibly interspersed with semi-landmarks to further specify the form (Bookstein 1997; Perez et al. 2006) or using continuous functions (e.g., Fourier analysis) describing shape (Rohlf and 10 Archie 1984; Crampton 1995). Where the forms being compared are more divergent (e.g., 11 12 across higher taxa) it often becomes difficult to identify a sufficient number of homologous or functional landmarks to capture all but the most limited and conservative aspects of form 13 variation (Bocxlaer and Schultheiß 2010). Here, it is possible to use an array of discretely 14 15 coded characters, each recognising two or more alternative states, as descriptors of morphological variation (Wills et al. 1994; Wills 1998). Such data are more flexible, but 16 entail more assumptions and potential subjectivity concerning the selection and discretisation 17 of characters and states. The morphospaces that they define also have properties that differ 18 from those derived from continuous character data (Gavrilets 1999). 19

The first studies that addressed the issue of quantifying disparity explicitly with empirical data sets were published about twenty-five years ago (Foote 1990, 1994; Briggs *et al.* 1992; Wills *et al.* 1994) (Fig. 6). The disparity profiles of numerous major animal clades were investigated over the next ten years, before a wane in apparent interest. The last few years, however, have seen the resurgence of empirical studies, with a particular emphasis on the use of discrete character data sets. As a general rule, metazoan clades tend to show an initial rapid increase in disparity, with early levels of disparity being at or close to the maximum levels
 observed throughout the group's history.

3

4 Biological homology and functional analogy

With all types of data, a distinction can be drawn between those approaches that attempt to 5 capture variation in biologically homologous aspects of morphology (Rohlf 2002; 6 Klingenberg et al. 2004), and those that are more concerned with the functional parameters of 7 shape (Nogueira et al. 2009; Figueirido et al. 2011; O'Higgins et al. 2011; Anderson et al. 8 9 2011, 2013). Morphological disparity can be used to refer to both aspects of variation in form, although the intention is sometimes unspecified (Love 2007). The distinction can be 10 illustrated with reference to the tails of derived sharks and ichthyosaurs, both of which have 11 12 convergent evolved dorsal and ventral lobes with a relatively high aspect ratio for high-speed aquatic locomotion (Motani 2002; Lingham-Soliar 2005; Lingham-Soliar and Plodowski 13 2007). In functional terms, the dorsal lobes of both groups are comparable, as are the ventral 14 15 lobes. However, the vertebral column of sharks extends into the dorsal tail lobe, while that of ichthyosaurs deviates into the ventral lobe. The tip of both dorsal lobes might therefore 16 constitute a valid functional landmark, but the tip of the dorsal lobe of sharks is *biologically* 17 homologous to the tip of the ventral lobe in ichthyosaurs. Similar considerations apply to 18 discrete, character data; much depends upon the manner in which characters and states are 19 20 defined.

The exclusive use of putatively biologically homologous discrete variables restricts consideration to the same pool of characters used by cladists. In practice, and especially when dealing with fossil taxa, cladistic homology is established on operational grounds of detailed similarity and relationships to other structures (Pinna 1991; Butler and Saidel 2000). Such characters may also be functionally analogous, but are not necessarily so (Ruvinsky and

Gibson-Brown 2000; Shubin et al. 2009). Cladistic matrices therefore offer a rich resource 1 for quantifying morphological variety across more conservative suites of putatively 2 biologically homologous characters. Moreover, in the absence of homoplasy, we would 3 4 expect the inter-OTU morphological distances assessed from such data to correlate closely with the evolutionary or patristic distances inferred on most parsimonious or otherwise 5 optimal phylogenetic trees. With the progressive introduction of more character conflict and 6 homoplasy (Sanderson and Donoghue 1989), this correlation will increasingly break down 7 (Kelly et al. 2014), as will the inferred validity of many of the homology statements 8 9 underpinning the data. Cladograms must account for the distribution of states across taxa by introducing hypotheses of convergence and reversal along branches. The metrics of 10 morphological differences underpinning analyses of morphological disparity do not account 11 12 for similarity due to the convergent acquisition or loss of traits, and are therefore intrinsically more phenetic in approach. Indeed, as levels of homoplasy increase (and more putative 13 homologies are revealed to be analogies), patterns of morphological variety inferred from 14 15 homologies and those inferred from statements of functional similarity become progressively more similar. 16

17

18 Morphospaces: theoretical and empirical

Once a set of morphological descriptors or variables has been established for a given group, it is possible to assess the morphological variety of constituent subgroups (e.g., clades) or of chronological subsamples (e.g., taxa from successive geological periods). This can be done directly from the data, but it is more typical to visualise patterns of taxonomic distributions in some form of morphospace; an abstract, multidimensional space in which distances correlate with morphological differences. A distinction (although one not universally embraced; Mitterocker & Huttegger, 2009) can be drawn between theoretical and empirical

morphospaces. Theoretical morphospaces typically have dimensions that each capture a 1 2 single quantifiable aspect of form, and (despite being parameterised with reference to real organisms) are defined a priori without the need for an empirical data set. The most 3 4 frequently cited examples are those describing mollusc shells, which variously quantify form and growth using a very modest number of variables (Raup and Michelson 1965; Skalak et al. 5 1997; Hammer and Bucher 2005; Urdy et al. 2010). Real specimens can be located within 6 theoretical morphospaces, but empirical data are not necessary in order to define them. 7 Empirical morphospaces, by contrast, are constructed from a particular set of empirical 8 9 morphological data. Their dimensionality tends to be high (Raup and Michelson 1965; Foote 1997; McGhee 1999; Mitteroecker and Huttegger 2009); much higher than that of their 10 theoretical counterparts. For this reason, a number of data reduction techniques (usually 11 12 multivariate ordination such as principal components or coordinates analysis) are used to condense the dimensionality of the space. This makes it possible to summarise morphological 13 variation using a smaller number of abstracted variables, whilst minimizing distortion. These 14 15 abstracted axes often cannot be described verbally, but may allow the relative disparity of groups to be visualised and quantified more readily. Many of these approaches necessitate a 16 distillation of the multivariate differences between taxa into a single measure of difference or 17 distance for all possible taxon pairs (often realised as a triangular distance matrix analogous 18 19 to that used to tabulate distances in a road atlas). The precise distance metric used depends 20 upon the nature of the data and the desired properties of the resultant space and/or disparity indices. These complexities are discussed elsewhere at length (Wills, 1998; Wills, 2001a; 21 Hughes et al. 2013). 22

Two issues deserve emphasis. Firstly, all morphospaces are abstractions, and necessarily based upon a subset of morphological variables. Variable choice inevitably determines the nature of the space. Many practitioners seek to sample variables as widely as

possible from all aspects of morphology, thereby deriving spaces that reflect overall form. 1 This is not always possible, however, as in many cases where only variation in particular 2 organs or aspects of form can be codified across taxa (Pretorius and Scholtz 2001; Lindbladh 3 4 2002; Miller and Venable 2003; Neige 2006; Jones et al. 2009). Morphospaces derived from particular aspects of form or using data from particular organ systems or modules may be 5 well-suited to addressing particular evolutionary questions. However, 'morphological 6 disparity' is usually conceived as referring holistically to overall form. Secondly, indices of 7 disparity are necessarily relative and comparisons are only possible within the parameters of 8 9 a given morphospace or underlying data set. Hence, while it is possible to make inferences regarding the relative disparity of a group at different times in its evolutionary history, or to 10 compare the disparity of constituent subgroups within an analysis, it is not possible to make 11 12 comparisons between groups from independently-constructed morphospaces or data sets. This is also the reason why supermatrices uncritically assembled from multiple published 13 data sets (and containing large blocks of inapplicable codes for large groups of taxa) may lose 14 15 traction on some of the largest and deepest comparative questions.

A variety of disparity indices have been discussed in the literature (Foote 1991, 1994, 16 1997; Wills et al. 1994; Wills 2001a; Hughes et al. 2013), but it is not our intention to 17 rehearse the relative merits of these here. Among the most widely used approaches are those 18 19 that distil the dispersion of taxa on multiple axes of the morphospace into a single value. The 20 dispersion on a single axis can be quantified either as the range (defined by the outliers) or the variance of scores; the latter has the advantage of a relative insensitivity to sample size 21 differences. Measures on multiple axes can be combined either as their product – effectively 22 calculating the (hyper)volume of a (hyper)cube – or as their sum. While hypervolumes are 23 superficially more intuitive, they effectively give disproportionate weighting to smaller 24 differences on later axes. Most ordination methods sequester progressively smaller fractions 25

of total variance in later axes, but multiplying the univariate indices of dispersion means that
halving the spread on any axis (whether the first or last) will halve the resultant hypervolume.
Products also collapse to zero whenever the dispersion of taxa on a given axis is also zero.
Summing the univariate indices of dispersion (rather than multiplying them) avoids these
problems. The sum of variances has particularly desirable properties, therefore, and has been
used throughout the present study.

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MATERIALS AND METHODS

9 Data collection

10

In general, we followed the protocols set out in Hughes et al. (2013). Morphological 11 matrices for six major tracheophyte groups (Angiospermae (Doyle et al. 1994; Nandi et al. 12 1998; Doyle and Endress 2014), Arecaceae (Baker et al. 2009), Nymphales (Borsch et al. 13 14 2008), Pinophyta (Hart 1987), Pinaceae (Klymiuk and Stockey 2012) and Polypodiidae (Pryer et al. 1995)) were selected from the literature. These represented the most diverse 15 extant higher taxa of vascular plants, in addition to well-sampled subclades within both the 16 angiosperms and conifers. Diversification and extinction patterns within these last two groups 17 have been relatively well-studied. Outgroup taxa were removed from these source matrices in 18 several cases; either because there were missing taxa between the ingroup and outgroup, or 19 because the outgroup OTUs were sampled at a higher taxonomic level than the ingroup. In 20 some datasets, we also had to overcome inhomogeneity of sampling within the ingroup, 21 22 which we achieved by amalgamating OTUs in such a way as to render them homogeneous at a higher taxonomic level. Character amalgamation utilized modal states. Some characters 23 were rendered uninformative as a result of these condensations, and were therefore removed 24 25 (specifically Pinaceae - 46, 47, 51; Arecales - 6, 10, 15, 21, 22, 48, 78, 91, 92, 10; Nymphales

- 4, 5, 6, 12, 14, 22, 28, 39, 57). Stratigraphic ranges were assigned to stages using the 1 2 International Stratigraphic Chart 2009 (Gradstein et al. 2004; Ogg et al. 2008). Stratigraphic range data were sourced from the Paleobiology Database (http://paleodb.org/), Sepkoski 3 4 Online (Sepkoski, 2002) and the Fossil Record 2 (Benton 1993). Ranges were treated as continuous between first and last occurrences, with data being grouped into stage level time 5 bins. In cases where first and last occurrences were resolved only to intervals above the stage 6 level, we coded for the stage corresponding to the midpoint of the interval. There were very 7 few fossils within the Nymphales, and we therefore estimated ranges using the time 8 9 calibrated molecular phylogeny of (Yoo et al. 2005). Temporal bins with sample sizes of 1 were also amalgamated so that disparity could be calculated for these intervals. 10

11 Analyses

For each exemplary clade, intertaxon distance matrices were calculated using the 12 13 Generalised Euclidean Distance metric (GED) of Wills (1998), and as implemented in Hughes et al. (2013). Distance matrices were ordinated in R (R Core Team 2013) using 14 15 principal coordinates analysis (Wills et al. 1994), and incorporating Caillez's correction for negative eigenvectors (Cailliez 1983). Disparity for each time bin was calculated as the sum 16 of variances on all axes of the morphospace, yielding a trajectory of disparity through time. 17 18 The centre of gravity of each trajectory was used to distinguish between those clades whose temporal mean disparity was located early (bottom-heavy), late (top-heavy) or in the middle of their 19 evolutionary history (symmetrical). A centre of gravity metric (Gould et al. 1987; Uhen 1996) in 20 21 absolute time (CG) was calculated for each clade as:

22

 $CG = \sum d_i t_i / \sum d_i$

23

1 Where d_i is the disparity at the *i*th stratigraphic interval and t_i the temporal midpoint in absolute time 2 (Myr) of the *i*th stratigraphic interval. This was then scaled between the ages of the oldest (t_{oldest}) and 3 youngest ($t_{youngest}$) intervals to yield an index of observed CG (CG_m) between 0 and 1.

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7 The expected CG_m for a clade of constant disparity through time is unlikely to be 0.50, but is 8 determined by the durations of the time bins over which the profile is measured. The observed CG_m 9 was therefore compared with the inherent CG (CG_i) for a clade of uniform disparity spanning the 10 same intervals. A bootstrapping procedure was used to generate a distribution of 1,000 resampled 11 differences between CG_m and CG_i , and clades for which >97.5% of bootstrapped replicates lay either above or below the centre of gravity inherent in the timescale (p-value <0.05) were deemed to be 12 significantly top or bottom heavy respectively (Foote, 1991). Observed CG_m was then expressed 13 14 relative to CG_i as a baseline; hereafter simply CG.

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An ancillary test from Hughes et al. (2013) was used to determine whether the taxa 16 observed in the first two stages had significantly less disparity than the maximum observed in 17 any time bin. The disparity profile of the clade was bootstrapped 1,000 times. For each 18 replicate curve, the difference in disparity between the first two stages and the disparity 19 maximum was calculated, yielding a distribution. If a difference of zero was within the 95% 20 21 limits of this distribution, we were unable to reject the null hypothesis: namely that there was no difference between the initial disparity and the maximum (early high disparity). In such 22 23 cases, maximal disparity was achieved in the earliest stages of the clade's evolution. A similar test was applied to the end of each group's history (late high disparity). 24

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4	RESULTS AND DISCUSSION

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6 Patterns of plant disparity through time

Our results are presented as preliminary explorations of the manner in which our selected
clades have explored one form of morphospace through time. While more detailed work will
certainly follow, our findings highlight several general patterns and permit certain
conclusions.

For extinct clades with homogeneous birth/death dynamics and characters evolving 11 12 under a Brownian model, the null expectation is that clade disparity profiles should be somewhat top heavy on average (a mean clade centre of gravity greater than 0.5) (Foote 13 1991). This is because the morphology of new lineages is contingent upon the morphology of 14 15 those from which they have evolved; clades would therefore be expected to explore morphospaces in a progressive manner. The extinction of lineages, by contrast, can occur in 16 any pattern with respect to the morphospace. Random extinction, in particular, will tend to 17 maintain a relatively wide morphospacial distribution, introducing a fundamental asymmetry 18 into clade evolution. This is an over-simplistic model for the clades studied here, because all 19 20 are extant; the Recent effectively truncates their evolution. As demonstrated by Hughes et al. (2013), extant clades (as well as those becoming extinct coincident with one of the 'big five' 21 mass events) have a much greater tendency towards top-heaviness merely by virtue of their 22 23 persistence to the Recent. It is therefore unsurprising that most of our exemplar clades (with the exception of two of the three angiosperm data sets: Doyle et al. 1994; Nandi et al. 1998) 24 show significantly top-heavy (CG > 0.5) profiles (Table 1). More remarkably, several of 25

these clades show initial disparity levels close to their maxima, or reach this level early in 1 2 their history. Arecaceae (palms) (Baker et al. 2009) first appeared at their maximum disparity, while all three of our angiosperm data sets (Nandi et al. 1998; Doyle et al. 1994; Doyle and 3 4 Endress 2014) showed initial disparity levels over 90% of the maxima in each case. Polypodiales (ferns) (Pryer et al. 1995) and Pinaceae (pines) (Klymiuk and Stockey 2012) 5 both reached their maxima within three time bins. The Nymphales (water lilies) (Borsch et al. 6 2008) are represented by a small data set (just 22 taxa) partitioned into larger time bins. 7 Despite their apparently slow start, early disparity levels were not significantly different from 8 9 the maximum (Table 1).

Conifers (Hart 1987) have the most dynamic disparity trajectory, with initial 10 Carboniferous and Permian levels significantly lower than at any subsequent times (Fig. 7). 11 12 These modest levels persisted until after the end of the Permian, whereupon there were significant increases into the early Mesozoic. Although disparity appears to decline between 13 the Middle and Late Triassic, it increases subsequently to reach maximum levels at the end of 14 15 the Jurassic. Levels then decline gradually until the Recent, with extant disparity being significantly lower than the maximum levels observed at the end of the Jurassic. Conifers 16 also show more intensive clustering of taxa in the morphospace at a variety of spatial scales 17 than do the other clades in our study (Fig. 8). Disparity within the pine family (Fig. 9) shows 18 19 broad similarities with conifers as a whole from their origins in the Jurassic; a reassuring 20 finding given that pines represent a significant proportion of conifer diversity from this time. The initial increase in disparity for pines occurs slightly later than the corresponding increase 21 in conifers as a whole, and is maintained until the present day. 22

Both angiosperms as a whole (Doyle *et al.* 1994) (Fig. 10) and the palm subclade (Baker *et al.* 2009) (Fig. 11) show approximately constant disparity through time. Palm disparity undergoes a slight decrease through the end of the Mesozoic and the early

Palaeogene, such that the disparity of living taxa is lower than the realised maximum of the past. In contrast, our results suggest that the water lilies (Borsch *et al.* 2008) did not reach present levels of disparity until the Neogene (Fig. 12), with markedly lower levels for the first 10 My of their history. We note that this is our smallest data set (22 taxa), resulting in large estimates of error relative to observed fluctuations in disparity.

In polypod ferns, disparity increases through the Permian and Triassic, reaching or
slightly exceeding modern levels by the Early Jurassic (Fig. 13). Disparity increased slightly
thereafter to peak levels around the K-Pg but subsequently declined significantly in the last
few million years.

An unexpected observation is that high levels of disparity were maintained for the 10 past 80+ My in our largest clades (conifers, pines, ferns and angiosperms), despite successive 11 12 radiations of subgroups and catastrophic environmental and faunal upheavals over this time, including the K/Pg event (Ehleringer and Sage 1991; Cerling et al. 1997; Zachos et al. 2001). 13 Indeed, while there is evidence of significant local faunal turnover in plants (McElwain and 14 15 Punyasena 2007), recent work suggests that only two major extinction pulses are supported in the plant fossil record: one at the Carboniferous-Permian transition and another during the 16 middle-late Permian (Cascales-Miñana and Cleal 2014). Of the groups analysed, only 17 conifers spanned this second event and actually show a significant increase in disparity 18 19 during this time. It is therefore possible that conifers were evolving into areas of ecospace 20 formerly occupied by other plant groups that declined at the end of the Permian (Retallack 1995). 21

The high initial disparity of many of the plant groups investigated here results from the appearance of a small number of morphologically highly distinct taxa close to the base of each clade. In most of our groups, fossils quickly define the extremes of the empirical envelope as soon as they appear, with subsequent lineages gradually filing the intervening

morphospace rather than colonising more eccentric regions of it. Conifers exhibit a rather 1 2 different pattern (Fig. 7), with the gradual appearance of subclades that each occupy distinct regions of the space (Fig. 8). Rather than rapid morphospace occupation followed by 3 4 subsequent saturation, conifers appear to show several phases of morphospace colonisation and subsequent diversity increase in tightly defined regions centred around pioneers with 5 novel character combinations. This suggests that the evolution of conifers may have been 6 characterised by the intermittent acquisition of novel morphologies or 'key' innovations, 7 followed by subsequent diversification. Such events may include the radiation of the pines in 8 9 the Jurassic and the cypresses in the Cretaceous and early Palaeogene. The high degree of morphospace clustering may result from competition with other groups (such as 10 angiosperms), constraining the available morphospace. However, it is more likely to be a 11 12 function of greater structural or developmental constraints acting upon suites of characters within the conifer dataset (moreover, conifers appear to show relatively tight clustering in the 13 Triassic and Jurassic, prior to the inferred appearance of basal angiosperms). Pines show 14 15 much weaker clustering than conifers as a whole. Characters within the pine dataset (Klymiuk and Stockey 2012) were derived from cone morphology, strongly implying that 16 Pinacae were able to explore the majority of possible cone forms rapidly and early in their 17 evolution in a relatively unconstrained manner. 18

Because most of the discrete character matrices analysed here included a broad sample of characters from many different anatomical regions, it is reasonable to assume that the gross morphology of the taxa in the sample was reasonably represented. Our three angiosperm matrices had marked differences in character and taxon composition (Fig. 14), but showed similar overall patterns of disparity through time

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25 Why are there so few studies of plant disparity?

1 There are a number of possible reasons why empirical morphospace approaches have been underutilised within the plant sciences, aside from the usual methodological 2 considerations underpinning the choice of data and indices (Rohlf 1998). Many 3 4 morphometric approaches entail time-consuming data collection, which may limit tractable sample sizes. There are also difficulties in establishing variable or character sets that can be 5 measured or coded across higher taxa. Most studies therefore focus upon smaller plant clades 6 or else derive data from particular structures (Chartier et al. 2014) rather than investigating 7 overall morphological disparity. Moreover, the often fragmentary nature of fossil material 8 9 may mean that holistic treatments are impractical, or that many types of morphometric data cannot be obtained (Adams et al. 2004). 10

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12 Utilising existing discrete morphological data matrices

New morphological character matrices for plants are becoming increasingly rare (Gottlieb 13 1988; Sytsma et al. 1991); mounting evidence from molecular phylogenetics implies that 14 15 morphological convergence is obfuscating our understanding of plant relationships (Bowe and Coat 2000; Donoghue and Doyle 2000; Schneider et al. 2009). However, we believe that 16 morphological character data has important uses beyond that of inferring phylogeny (Thorne 17 et al. 2011); not least for quantifying patterns of disparity change throughout morphologically 18 19 and taxonomically diverse clades with long evolutionary histories. In this context, the 20 problems of homoplasy and convergence that bedevil phylogenetic inference are less marked, since morphospaces are conceived for a variety of purposes and can be intended to reflect a 21 variety of aspects of evolution. Discrete character morphospaces offer a framework for 22 quantifying patterns of morphological disparity within large clades, but also highlight 23 questions that can be addressed in a more focussed manner using other morphometric 24 techniques (Goodman 2002). More comprehensive analyses of existing plant character 25

matrices would represent an efficient use of legacy data, allow some of the commonalities
suggested in this paper to be properly tested and would powerfully complement existing and
future morphometric studies.

Despite the abundance of discrete, morphological data in the literature, there are a number 4 of considerations when using explicitly cladistic matrices for disparity studies. Morphological 5 cladists usually seek to resolve phylogeny (Forey et al. 1998), but are not always concerned 6 with representing accurate branch lengths and evolutionary distances. Even in the extreme 7 approach adopted by pattern cladistics, which views the cladistic method as being divorced 8 9 from evolutionary assumptions of descent through modification (Brady 1982; Brower 2000), there is still an imperative to recognise hierarchical groupings within sets of taxa (Hennig 10 1966; Estabrook et al. 1975). There may therefore be a tendency to subdivide morphological 11 12 variety more finely within taxa that are morphologically conservative overall in order to resolve their relationships or structure. Conversely, taxa supported by long evolutionary 13 branches may be morphologically very distinct from their nearest sampled relatives, but there 14 15 may be no imperative to quantify all of these differences to the same degree of resolution as in highly diverse and morphologically similar groups. More generally, it is reasonable to 16 expect character matrices to be biased towards distinctive features and/or those which have 17 been demonstrated to be good at distinguishing groups in previous studies. An allied issue is 18 19 the assumption that all characters should be treated equally. This may not always be desirable, 20 particularly in cases where some groups are characterised by a limited number of highly distinctive and variable characters while others are defined by broader suites of gross 21 morphological features that are nevertheless coded as a single character. For example, it is 22 23 probably simplistic to treat the presence or absence of sclereids in the leaves on an equal footing with scandent versus arborescent growth habits (Foster 1956; Rury and Dickison 24 1984). While there are a variety of objective approaches for the differential weighting of 25

characters in phylogenetic studies, these are derived from predictions or empirical estimates
of levels of homoplasy or the phylogenetic information content of characters (Farris 1969;
Sharkey 1989; Goloboff 1993, 2014) . In disparity analyses, what may be required is rather
some weighting derived from the ontogenetic priority, developmental (Riedl 1977; Arthur
1984, 1988; Wimsatt 1986) or structural depth (Stebbins 1969; Pettersson 2009) of characters,
although such weights are notoriously difficult to assign.

Some cladistic matrices are constructed in order to address particular questions; most 7 commonly sequences of character acquisition across important evolutionary transitions: for 8 9 example, tetrapods from fishes (Wagner and Chiu 2001; Long and Gordon 2004; Ruta et al. 2006; Wagner et al. 2006) and birds from dinosaurs (Garner et al. 1999; Xu 2006; Heers et al. 10 2014; Brusatte et al. 2014). Such data intentionally focus on the taxa and characters 11 12 bracketing these changes, with deliberately much sparser sampling outside of this. More generally, outgroup taxa – often included for rooting purposes – are more sparsely sampled 13 than those of the ingroups (Graybeal 1998; Heath et al. 2008). Morphological cladistic 14 15 characters may therefore sample morphological variation unevenly across taxa and through time. Not all data sets are suitable for investigating temporal and taxonomic patterns of 16 morphological variation therefore, and many require some form of moderation. Hughes et al. 17 (2013), for example, standardised sampling according to higher taxonomy, and removed 18 19 outgroups.

One final issue is the inclusion or otherwise of autapomorphic character states; those present in just a single taxon (Yeates 1992; Bryant 1995). Such states cannot influence inferred cladistic branching structure, but they do affect branch lengths (without introducing homoplasy) and indices of morphological difference. In two state characters, an autapomophic state renders the entire character cladistically (but not phenetically) uninformative. This property is flagged by most phylogenetic software, which usually results

1 in their removal from cladistic matrices. Autapomorphic states are more likely to be retained 2 in multistate characters (those with three or more states), since the character remains informative overall. More generally, cladists do not actively seek to include autapomorphic 3 4 states, such that cladistic matrices usually omit this aspect of morphological variation. Empirically, however, the inclusion/exclusion of autapomorphies makes relatively little 5 difference to assessments of morphological variety (Wills 2001a,b). The precise effect of 6 autapomorphic states will depend upon the overall properties of the data set and the mode of 7 analysis, but in general they merely cause the taxa possessing them to appear marginally 8 9 more divergent from the overall mean morphology than they would otherwise be.

There is an increasing desire for large, complete phylogenies to underpin various 10 forms of evolutionary and ecological analyses (Guyer and Slowinski 1993; Phillimore and 11 12 Freckleton 2006; Tamura et al. 2012). Large matrices of molecular characters (supermatrices) are frequently assembled *de novo* using open data resources and automated algorithms (Liu et 13 al. 2001; Davies et al. 2004; Bininda-Emonds 2004; Davis and Page 2008). There are no 14 15 similar repositories or tools for morphological matrices. Assembling large matrices comprising hundreds or thousands of OTUs and characters from first principles would ensure 16 greater consistency, but is hugely time-consuming. Hence, morphological supermatrices are 17 often assembled by amalgamating the largest data sets or synthetic treatments available for 18 19 constituent groups. However, this approach may entail its own set of problems. The first is 20 alluded to above; the differential sampling of taxa and characters. Taxon sampling can be standardised more readily, but uniform character sampling requires more detailed knowledge 21 and entails greater subjectivity. More problematically, it is often difficult or impossible to 22 code many of the characters in the constituent matrices for the 'outgroup' taxa (those 23 represented in the other matrices), thereby resulting in large blocks of inferred 24 plesiomorphies (typically '0' or absent) and inapplicable codings ('?'). Depending upon the 25

manner in which such inapplicabilities are treated, this phenomenon can result in artificially distinct clusters of taxa, strongly but spuriously demarcated by these discontinuities in knowledge and character sampling (Wilkinson *et al.* 2005; Cotton *et al.* 2006). For these reasons, large published cladistic matrices compiled from first-hand observations of specimens (or from careful treatments of the primary literature) have many potential advantages over those assembled by conjoining data from disparate published sources (de Dequeiroz and Gatesy 2007).

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CONCLUSIONS

1. The concept of morphological disparity is distinct from those of diversity and species 11 12 richness (Wills 2001). Indices of disparity attempt to codify the morphological variety of a sample of taxa, are calculated relative to some set of morphological 13 variables or characters, and often utilise a plot of taxa in a multidimensional 14 morphospace. Morphospaces are abstract spaces in which the geometric distances 15 between taxa are proportional to some measure of the morphological differences 16 between them. The nature of a morphospace is entirely contingent upon the 17 underlying data, the manner in which differences between taxa are summarised as 18 19 distances, and the methods used to project these distances into an *n* dimensional space. 20 The precise approach will depend upon the purpose for which the morphospace is intended. It follows that there is no objective morphospace (in the sense that there is 21 an objective phylogeny), and that the dispersion of taxa in different spaces cannot be 22 23 compared directly (comparisons between subgroups within the space are possible, but these are necessarily only relative). Morphospaces derived from large samples of 24 characters or variables encompassing most aspects of form are most likely to offer 25

insights into overall morphological variety. Indices of disparity variously assess the
 relative dispersion of samples of taxa within a morphospace, or provide some
 distillation of the morphological differences between them.

4 2. Diversity and disparity appear to be fundamentally decoupled. A significant majority of the animal clades investigated show relatively high disparity early in their 5 evolution (Hughes et al. 2013) at times when diversity is still comparatively low (i.e., 6 7 there are modest numbers of taxa but these are morphologically highly distinct from each other). The subsequent evolution of such groups often sees an increase in 8 9 diversity with little or no concomitant increase in disparity; there are increasing numbers of taxa within a restricted number of morphological 'themes'. Disparity may 10 even decline as diversity is rising, since some of the most speciose clades have 11 12 particularly constrained bodyplans but are able to partition ecospace and morphospace particularly finely. A substantial minority of animal clades show other patterns, 13 including high initial disparity at low diversity (Foote 1990). 14

There have been relatively few studies of morphological disparity in plants, and no
 studies have attempted to assess patterns of overall disparity in major clades through
 time. Temporal patterns of diversity in plants and animals show significantly different
 patterns (Knoll *et al.* 1979), with plants counterintuitively being less affected at times
 of global mass extinction (Cascales-Miñana and Cleal 2014). An assessment of
 patterns of disparity in major plant clades is therefore overdue, and may provide
 insights into plant macroevolution to complement those being obtained for animals.

4. There are numerous morphometric methods that allow shape and shape change to be
 quantified across taxa. However, as the morphogical variety of the forms being
 compared increases (usually in tandem with the taxonomic scope of the study), the
 ability of such approaches to compare increasingly disparate forms becomes more

limited. Discrete character data sets have certain advantages in this context. There are
 rich resources of discrete character matrices already available for numerous plant
 clades, and although initially intended for inferring phylogeny, these data sets can be
 repurposed for disparity studies within certain strictures.

5. Our preliminary disparity analyses for 6 exemplary plant clades demonstrate that 5 initial levels of disparity are usually high, if not indistinguishable from (or at) the 6 maximum ultimately achieved by the group. Most regions of the morphospace are 7 colonised early in the history of each plant clade, with subsequent evolution serving 8 9 merely to increase diversity within these regions. The notable exception are the conifers, in which subclades appear intermittently, and progressively colonise distinct 10 regions of the space. This results in conifer disparity increasing incrementally over the 11 12 first half of the group's history. All of our exemplary plant clades have disparity profile shapes with a centre of gravity higher than the intrinsic null (significantly so in 13 all save two angiosperm datasets). This is unsurprising, however, since all are extant 14 groups, with profiles truncated by the Recent (Hughes et al. 2013) (Hughes et al., 15 2013). Combining detailed empirical morphometric studies of specific anatomical 16 regions with the more holistic approach illustrated here will likely be reciprocally 17 illuminating, and offer insights into plant macroevolution. 18

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CONTRIBUTIONS

JWO wrote the manuscript, collated plant morphological and stratigraphic datasets, drafted
figures and analysed data. MH ran disparity analyses and statistics, summarized the disparity
literature and drafted figures. SG produced clustering plots. MAW conceived and designed
the study, wrote the manuscript and drafted one figure.

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2

TABLES

Table 1. Expected (or inherent) and observed centres of gravity (CG_{scaled}) for clade disparity 3 4 profiles, along with the results of bootstrapping tests (CG p-value) to determine if these differ. The expected CG is that determined for a clade with uniform disparity through time, and 5 deviates from 0.5 because stratigraphic intervals and bins are of variable length. Relative CG 6 7 is adjusted relative to the expected or inherent CG as a baseline. Clades that persist to the Recent typically have top-heavy profiles, since they are effectively truncated. Early high and 8 9 late high columns indicate the results of bootstrapping tests to determine if the disparity observed in the first and last intervals is distinguishable from the overall maximum for the 10 clade ('no' indicates a difference with p < 0.05) 11

12

Clade	Dataset	Expected	Observed	Relative	CG p-	Early	Late
		CG	CG	CG	value	high	high
Angiosperms	Doyle & Endress 2014	0.757	0.759	0.502	0.001	no	no
Angiosperms	Doyle <i>et al.</i> 1994	0.718	0.722	0.504	0.228	yes	yes
Angiosperms	Nandi <i>et al</i> . 1998	0.714	0.718	0.504	0.846	no	no
Conifers	Hart 1987	0.556	0.712	0.655	0.001	no	no
(Pinophyta)							
Leptosporangiate	Pryer <i>et al.</i> 1995	0.546	0.669	0.622	0.001	no	no
Ferns							
(Polypodiidae)							
Palms	Baker <i>et al.</i> 2009	0.690	0.761	0.571	0.001	yes	no
(Arecaceae)							
Pines	Klymiuk & Stockey	0.604	0.753	0.649	0.001	no	yes
(Pinaceae)	2012						
Water Lilies	Borsch et al. 2008	0.626	0.794	0.668	0.001	yes	yes
(Nymphaeales)							

2 Appendix 1: Distribution of characters in our plant data	sets
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Publication	Nandi et al. 1998	Doyle & Endress 2000	Doyle & Endress 2013	Hart 1987	Klymiuk & Stockey 2012	Pryer et al. 1995	Borsch 2008	Baker et al. 2005
Group	Extant Angiosperms	Basal Angiosperms	Angiosperms	Conifers	Pine Family	Polypod Ferns	Water Lilies	Palms
Growth & Habit	0	1	1	4	0	1	5	5
Cellular	22	0	4	2	0	2	0	6
Chemical	104	0	0	5	0	0	1	1
Stem	24	18	23	22	0	18	4	0
Leaf	17	17	13	16	0	19	7	14
Ovules/Seeds/Fruit	30	38	30	9	3	NA	6	15
Floral	37	23	54	NA	NA	0	28	52
Embryo & Development	7	0	0	27	0	1	1	3
Pollen	11	11	17	15	0	NA	10	9
Gametophyte	NA	NA	NA	NA	NA	11	NA	NA
Strobilus	NA	NA	NA	23	31	NA	NA	NA
Spores & Sporangia	NA	NA	NA	NA	NA	25	NA	NA
Total	252	108	142	123	34	52	62	105

2

FIGURE CAPTIONS

3 Figure 1. Diversity and disparity are often decoupled, particularly when sampling at lower taxonomic levels. Data for crinoids from Foote (1999). When crinoids first appear in the 4 Ordovician, there are relatively few genera (A), but the mean morphological distances 5 between them (as an index of disparity) are relatively large (B). Part of their subsequent 6 7 history entailed a systemic increase in diversity through to the early Carboniferous, which paradoxically coincided with a decline in disparity over the same interval. Conversely, 8 9 disparity remained relatively high for much of the Mesozoic despite a low diversity following the Permo-Triassic mass extinction. Many groups show a similar overall pattern, with 10 relatively small numbers of morphologically distinct species or genera typifying the early 11 phase of a clade's radiation. 12

Figure 2. Simplified models of the pattern of morphological disparity through the 13 Phanerozoic. The 'traditional' model assumes that patterns of disparity loosely track diversity, 14 15 which increases (albeit irregularly) through time. Gould (1989) espoused an inversion of this model, derived largely from his own interpretation of the significance of fossils from the 16 Middle Cambrian Burgess Shale. Cambrian genera were believed to represent numerous, 17 highly distinct bodyplans, between which there were morphological differences comparable 18 to those distinguishing the living phyla. Most of these Cambrian bodyplans were lost 19 arbitrarily in the early Palaeozoic, resulting is a marked reduction in disparity ('decimation'). 20 Subsequent evolution entailed increasing diversity within this more limited number of themes, 21 but disparity was belived to persits unchanged. Fortey et al. (1996) summarised findings from 22 23 the then-published empirical studies of disparity, which revealed comparable levels of disparity amongst Cambrian invertebrate groups and their living counterparts. Subsequent 24 studies have largely confirmed the validity of the latter picture. 25

Figure. 3. Ordinal diversity of animals (Eumetazoa) and plants (Embryophta) through the Phanerozoic. Numbers of orders per geological stage have been tallied from Benton (1993) for animals and from Cascales-Minãna & Cleal (2014) for plants. The 'Big Five' mass extinctions are marked with vertical arrows.

Figure 4. Simulation of bifurcate branching structures capturing aspects of vascular plant 5 morphology (after Niklas 1999). (A) illustration of the three parameters used: the bifurcation 6 angle ϕ , the rotation angle Υ and the probability of apical bifurcation P. Separate numerical 7 values can be used for each parameter for each axes (e.g. P₁ and P₂). (B) Simplified three-8 9 dimensional morphospace created from the orthogonal alignment of the three parameters of the simulation, showing the spectrum of branching structures produced. Cooksonia-type Y-10 shaped branching structures occupy the upper left region, more complex overtopped 11 structures occupy the lower right rearground and planated lateral 'branches' occupy the lower 12 right foreground. Figures redrawn from Niklas (1999). 13

Figure 5. Types of data underpinning disparity analyses. (A) Landmarks (in red) from Webster & Zelditch (2008) situated on homologous points of a trilobite cephalon. (B) Equidistant semi-landmark points (in red) from MacLeod (2010), defining the outline of a trilobite cephalon (shown in grey). (C) Measurements taken for a Fourier analysis of a trilobite cranidium, from Foote (1989). X is the starting point, XY is the midline, point C is the centroid, L is the length from X to Z, D is the distance from the centroid to Z and θ is the angle XCZ.

Figure 6. The resurgence of disparity analyses for animal clades and the paucity of plant studies. (A) Bar chart of the number and taxonomic distribution of focal clades in disparity analyses from 1990 to 2014. (B) The decline in the use of outline data and the ascendance of discrete character and landmark based studies since 2010. We espouse the use of discrete character data for producing empirical morphospaces of disparate plant clades. Underlying
data in Appendix 1, although we have removed studies in Hughes *et al.* (2013) from the
figure (this further increases the number of discrete character studies in the last five years).

Figure 7. (A) Disparity profile and morphospace plots for conifers from Hart (1987).
Disparity (black circles) calculated as the sum of variances on all principal coordinate axes
within several time bins. Values are the mean of 1,000 bootstrap replicates ±SE. Diversity per
stage is indicated by open, red circles. (B) Distribution of taxa on the first two principal
coordinate axes of the empirical morphospace at four of the period time bins.

9 Figure 8. To what extent are taxa clustered within their respective morphospaces at different levels of granularity? Highly clustered, spatially heterogeneous distributions can be 10 approximated with smaller numbers of principal points than can diffuse, spatially 11 homogenous distributions. The extent to which a principal point distribution matches the 12 empirical distribution is given by the sample mean squared deviation (SMSD). Open circles 13 14 indicate the observed SMSD with an increasing number of principal points. Solid lines denote 15 the expected, null SMSD curve for a multivariate homogeneous distribution containing the same number of points within the same spatial bounds as the observed distribution. Dashed 16 lines are lower and upper bounds of the 95% confidence interval around this null. Where the 17 observed lines (circles) fall below the dashed interval, the empirical distribution is 18 significantly more tightly clustered than expected. Analyses of four plant morphospaces. (A) 19 conifers (Hart 1987). (B). pine family (Klymiuk and Stockey 2012). (C) angiosperms (Doyle 20 and Endress 2014) (D) leptosporangiate ferns (Pryer et al. 1995). Note the particularly tight 21 22 clustering of conifers over a large range of principal point numbers.

Figure 9. (A) Disparity profile and morphospace plots for the pine family from Klymiuk &
Stockey (2012). Disparity (black circles) calculated as the sum of variances on all principal

coordinate axes within several time bins. Values are the mean of 1,000 bootstrap replicates
±SE. Diversity () per stage is indicated by open, red circles. (B) Distribution of taxa on the
first two principal coordinate axes of the empirical morphospace at four of the period time
bins.

Figure 10. (A) Disparity profile and morphospace plots for angiosperms from Doyle &
Endress (2014). Disparity (black circles) calculated as the sum of variances on all principal
coordinate axes within several time bins. Values are the mean of 1,000 bootstrap replicates
±SE. Diversity () per stage is indicated by open, red circles. (B) Distribution of taxa on the
first two principal coordinates of the empirical morphospace at four of the period time bins.

Figure 11. (A) Disparity profile and morphospace plots for palms from Baker *et al.* (2009).
Disparity (black circles) calculated as the sum of variances on all principal coordinate axes
within several time bins. Values are the mean of 1,000 bootstrap replicates ±SE. Diversity ()
per stage is indicated by open, red circles. (B) Distribution of taxa on the first two principal
coordinate axes of the empirical morphospace at four of the period time bins.

Figure 12. (A) Disparity profile and morphospace plots for water lilies from Borsch *et al.* (2008). Disparity (black circles) calculated as the sum of variances on all principal coordinate axes within several time bins. Values are the mean of 1,000 bootstrap replicates ±SE. Diversity () per stage is indicated by open, red circles. (B) Distribution of taxa on the first two principal coordinate axes of the empirical morphospace at four of the period time bins.

Figure 13. (A) Disparity profile and morphospace plots for extant leptosporangiate ferns from Pryer *et al.* (1995). Disparity (black circles) calculated as the sum of variances on all principal coordinate axes within several time bins. Values are the mean of 1,000 bootstrap replicates ±SE. Diversity () per stage is indicated by open, red circles. (B) Distribution of taxa on the first two principal coordinate axes of the empirical morphospace at four of the period
 time bins.

Figure 14. Disparity profiles for three cladistic angiosperm datasets. Disparity (black circles)
calculated as the sum of variances on all principal coordinate axes within several time bins.
Values are the mean of 1,000 bootstrap replicates ±SE. Despite the inclusion of different taxa
and characters, all three profiles show a rapid initial increase in disparity followed by
relatively constant disparity over the rest of their history.











Time (Millions of Years)



















Figure 8









Figure 10









Figure 12











Figure 14