Solar Nowcasting Systems Using Al Techniques

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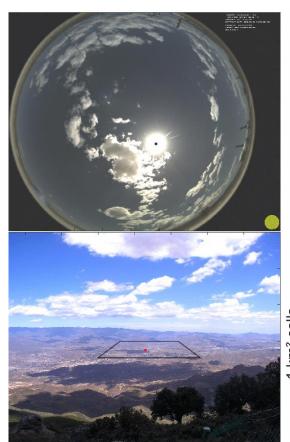


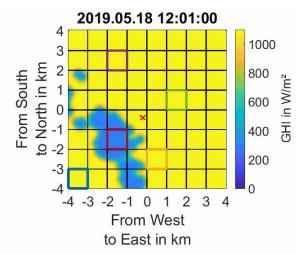
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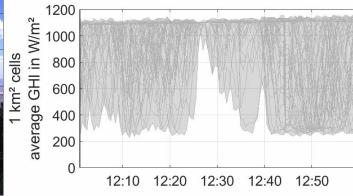


Motivation









Why ASI-based nowcasting?

- Highest variabilities of irradiance on local scale in space and time due to cloud passing
- Local observations enable irradiance forecasts in high temporal and spatial resolutions
- Improved situational awareness helps solar power plant and local grid operators to minimize costs and risks (e.g. power plant/solar field control, less curtailment, cheaper balancing, extended battery life,...) [1,2]

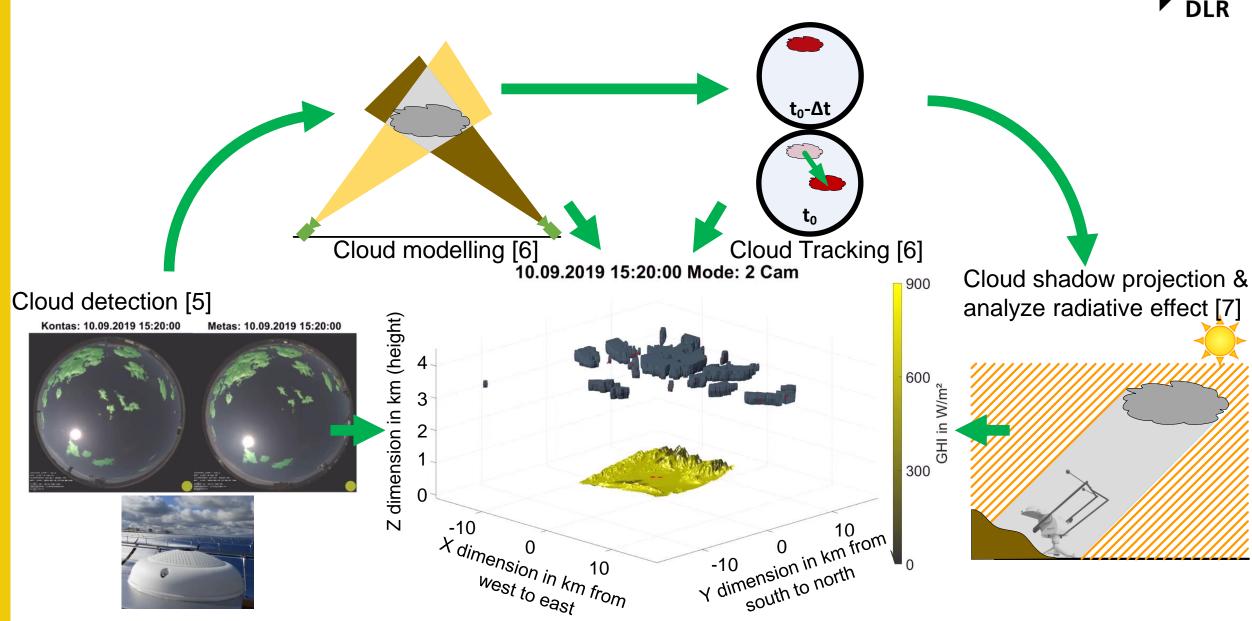
Why using ML for nowcasting?

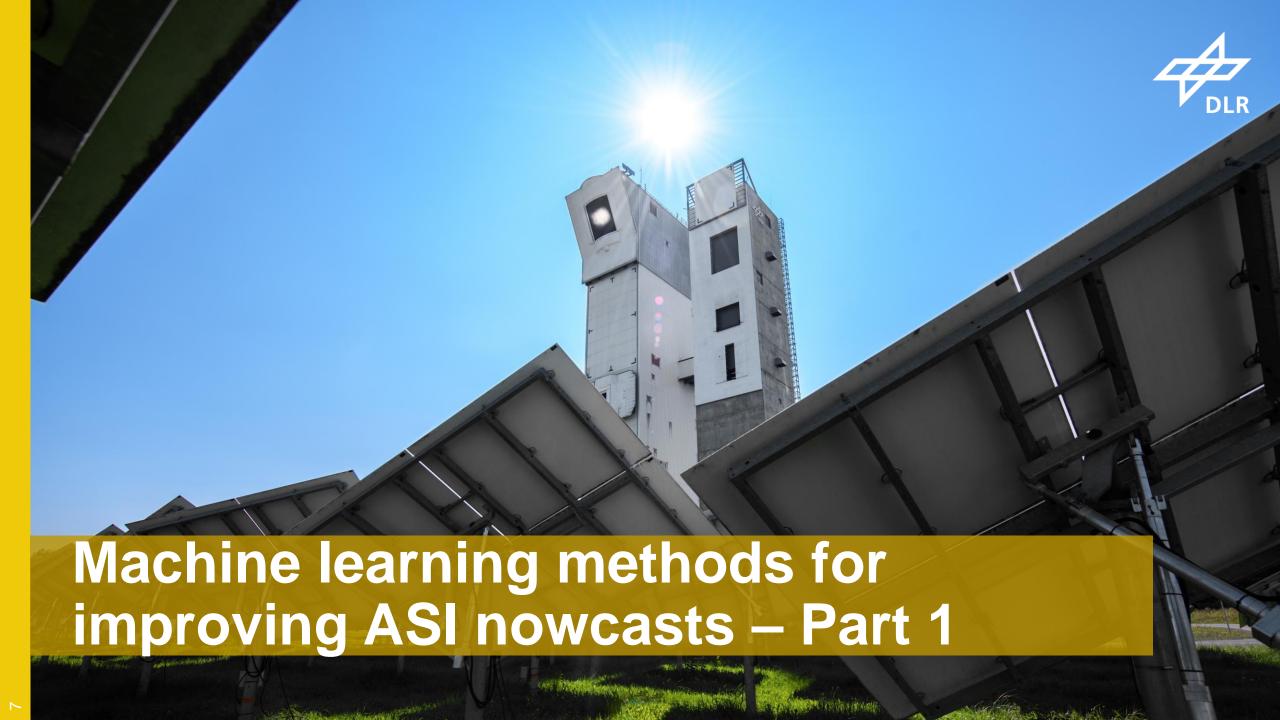
- Deep learning has proven to outperform previous state-of-the-art techniques in many computer vision problems [3]
- ML techniques are widely used in various forecasting problems [4]



Introduction to all sky imager-based nowcasting

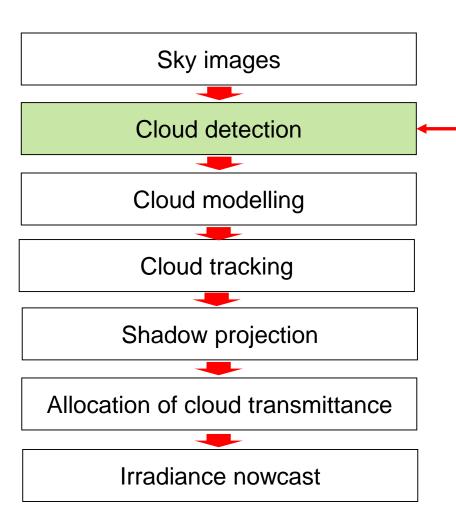




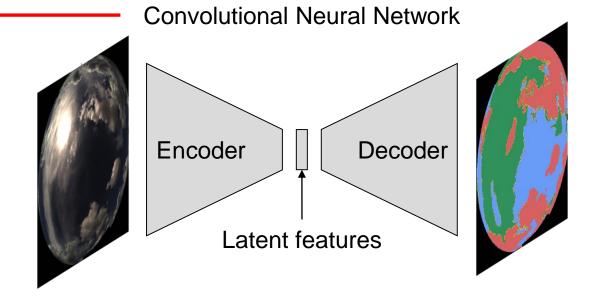


Machine learning methods for improving ASI nowcasts



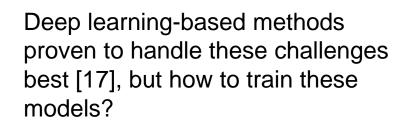


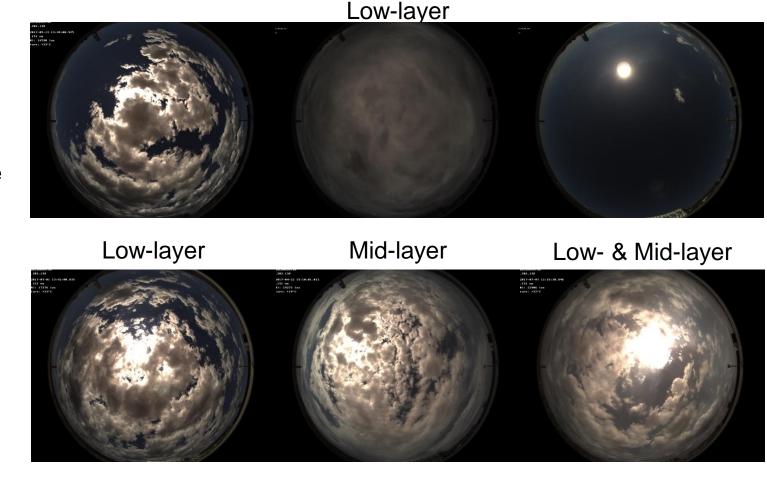
- Option 1: Apply ML to solve individual steps in processing pipeline
 - E.g. Cloud detection using a Convolutional Neural Network (CNN) for semantic segmentation (pixelwise classification)





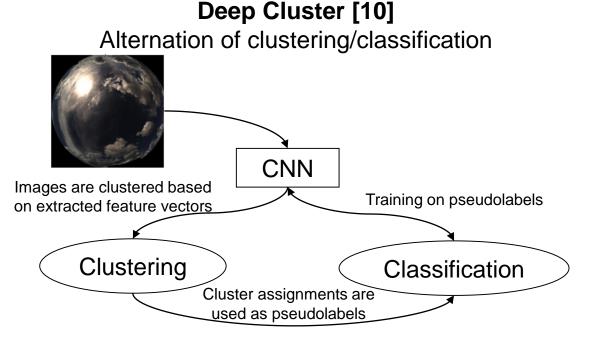
- Cloud detection in all-sky images poses a challenging task:
 - Variable spatial distribution and size
 - Atmospheric conditions and oversaturation of pixels in vicinity of the sun influence visual appearance
 - Distortion effects of fish-eye lens and decreasing resolution towards horizon
 - Multi-layer conditions with high visual similarity of individual layers







- Quality of a ML model strongly depends on the amount and quality of data used for training
- Manual creation of segmentation masks is time consuming (770 images from PSA¹ manually annotated)
 - → More data could help to increase performance but is infeasible on large scale (>10000)
- Alternative: Apply <u>self-supervised learning</u> to enable the model to extract relevant information (latent features) for segmentation
 - → Model solves pretext task based on pseudolabels generated from the data itself, e.g.:



Inpainting – Superresolution (IP-SR) [8,9]

Image reconstruction

CNN

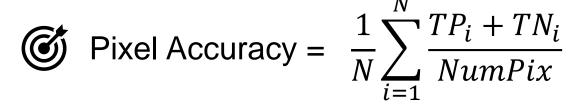
¹ Plataforma Solar de Almería, southern Spain, owned and administrated by CIEMAT



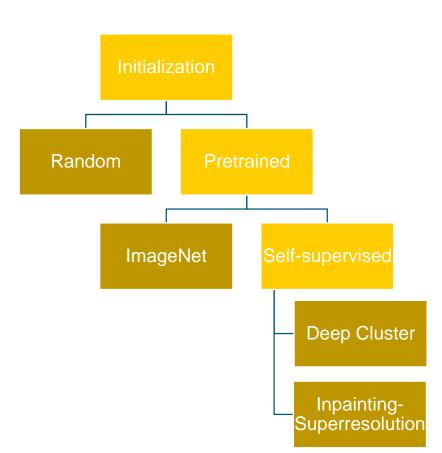


Evaluation of semantic segmentation by comparing 4 different model initializations [5]

- 4 classes: sky, low-/mid-/high-layer cloud
- Training on 616 images
- Validation on 154 images
- Implemented in python's fastai library [11]

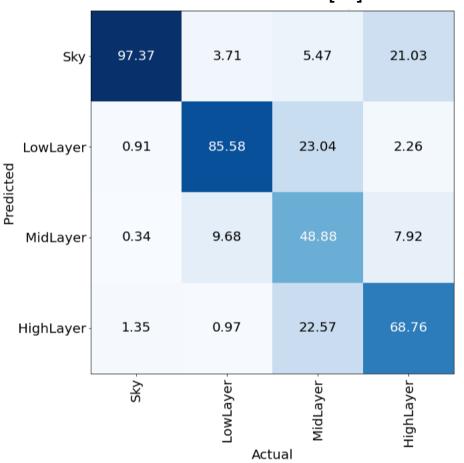


	Random	ImageNet	IP-SR	DC
Accuracy [%]	78.3	82.1	85.8	85.2

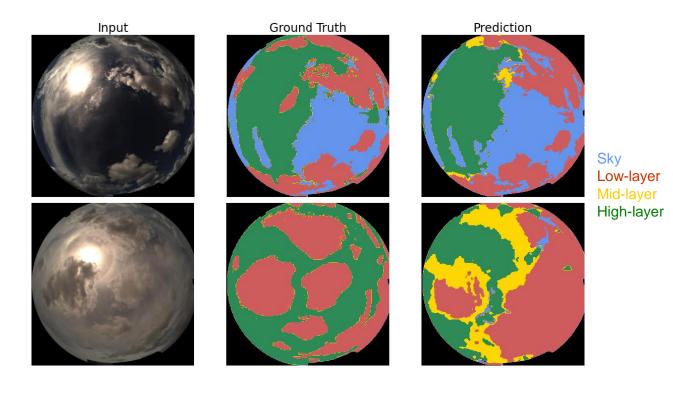




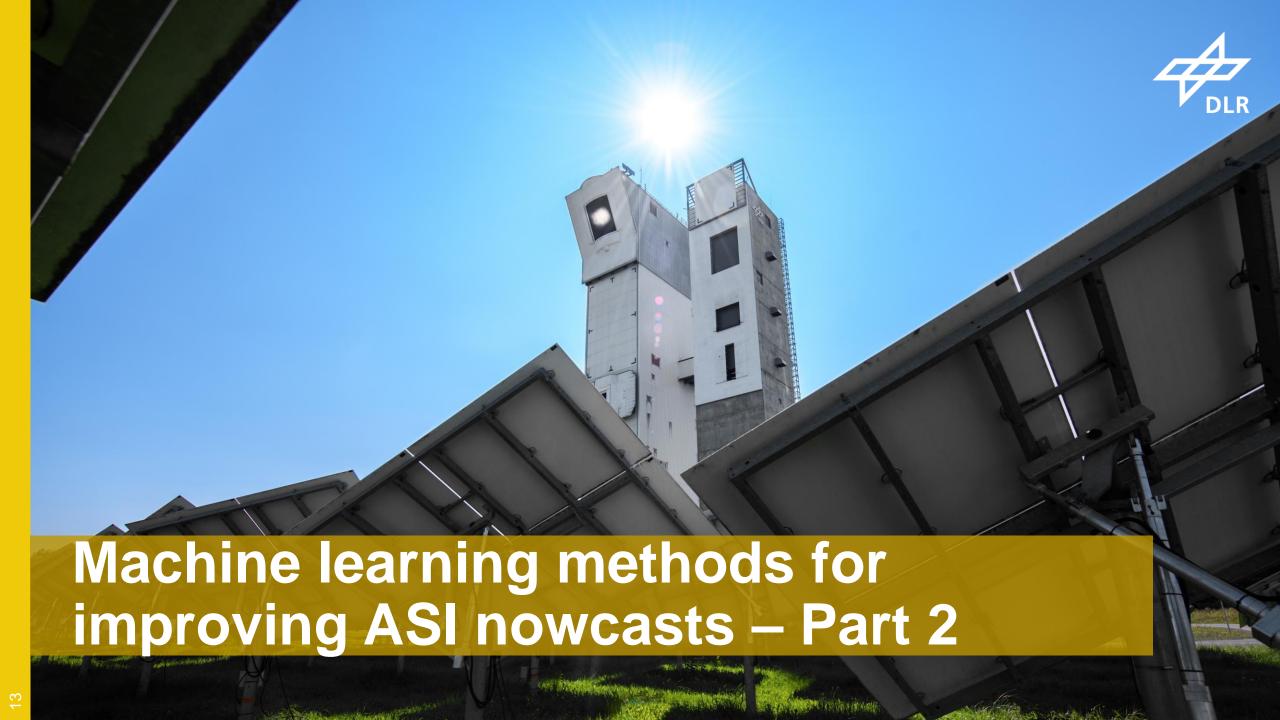
Classwise accuracy of Inpainting-Superresolution initialization [%]



Examples of cloud-layer detection

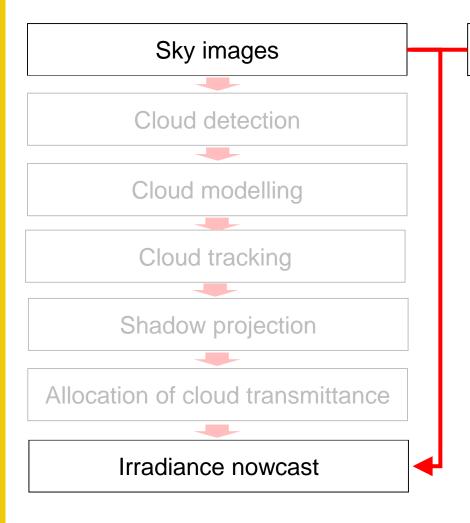


- Confusions mostly between adjacent cloud layers
- 95.2% accuracy on binary segmentation outperforming previous non-ML segmentation approach by over 7% points



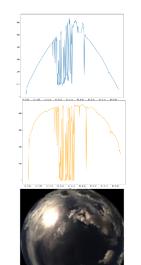
ML methods for improving ASI nowcasts

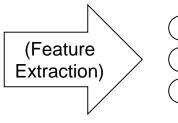


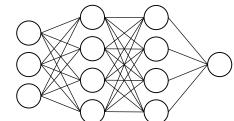


Time series data

- Option 2: Use ML models to generate nowcast from raw data
 - ML models are trained on large amounts of observations or features extracted from observations to learn patterns in the data





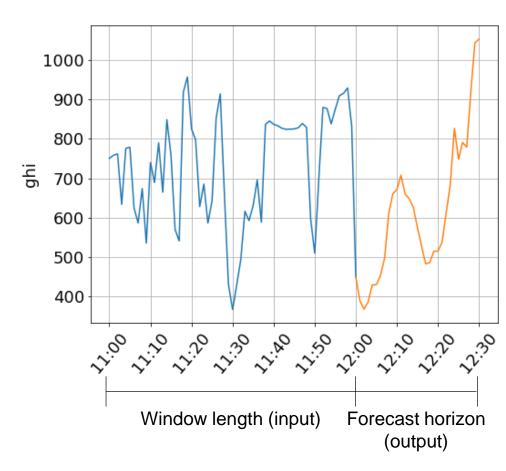


Irradiance nowcast

ML-based time series forecasting for ramp detection



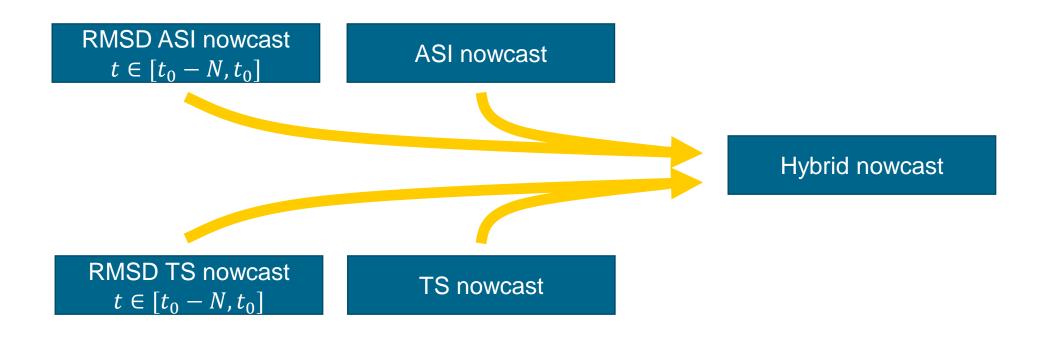
- Possible features for forecasting irradiance:
 - Irradiance measurements: GHI, DNI, DHI
 - Sun azimuth/elevation
 - Weather data: temperature, pressure, Linke turbidity
 - Image data (e.g., cloud coverage)
- 120 days of diverse conditions selected for evaluation
- Analysis of combination of different model hyperparameters and feature sets using tsai library (python) [12]
 - Architecture: LSTM
 - Window length: 30 min
 - Forecast horizon: 20 min
 - Feature set: GHI, DNI, DHI, sun elevation, sun azimuth



ML-based time series forecasting for ramp detection – Combination with ASI-Nowcasting System



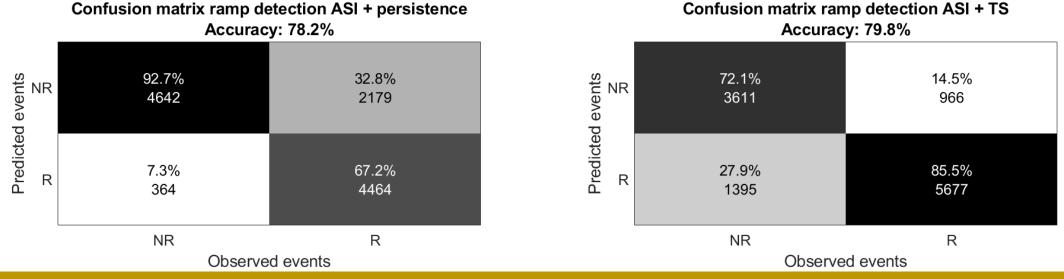
 Combination of physically-based nowcast (ASI) and persistence/time series (TS) nowcast by weighting of RMSD of previous N predictions [13]



ML-based time series forecasting for ramp detection – Combination with ASI-Nowcasting System



- Point-wise evaluation of ramp events [14]:
 - Ramp: Change of normalized irradiance between two points in time exceeds threshold
 - Ramp event: At least one ramp within fixed time horizon (20 min)



- Improved detection of true ramp events for hybrid TS model while increasing the number of falsely detected ramps
 → Fluctuations in irradiance are predicted more frequently
- Same data set as the one used to evaluate various ASI nowcasting systems at PSA [13, 14] allows system comparison
- Advantage ASI system: Areal information of irradiance allows to adjust ramp detection by looking for ramps within irradiance map which further improves the ramp prediction



Summary



- ML methods can improve forecasting/nowcasting systems by:
 - Replacing other methods for individual tasks of complex physically-based systems (e.g., segmentation)
 - Generating forecasts soley based on measurement data
- New ML techniques as self-supervised pretraining offer great potential for dealing with limited labeled data in computer vision problems

ML is a fast and efficient tool for time series forecasting and can be combined with other
 models (e.g., physically-based) to improve the overall performance

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Thank you! Questions?

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Impressum



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