

Ligamentous constraint of the first carpometacarpal joint

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26 **Abstract**

27 To examine the role of the ligaments in maintaining stability of the first carpometacarpal
28 (CMC) joint, a sequential ligament sectioning study of sixteen specimens was performed.
29 While a small compressive force was maintained, loads were applied to displace each specimen
30 in four directions – volar, dorsal, radial, and ulnar. Translations of the specimen in both dorsal-
31 volar and radial-ulnar axes were measured. Initially, the tests were conducted with the
32 specimen intact. These tests were then repeated following sectioning of the CMC anterior
33 oblique ligament (AOL), ulnar collateral ligament (UCL), intermetacarpal ligament (IML) and
34 dorsal radial ligament (DRL). The first CMC joint translation was increased in the absence of
35 IML and DRL ($p<0.05$). Both IML and DRL were important in constraining the first CMC
36 joint translation against external applied loads. Potential applications of these findings include
37 the treatment of joint hypermobility and the reduction or delay of onset or progression of first
38 CMC joint osteoarthritis.

39

40 Keywords: first carpometacarpal joint, sequential ligament sectioning, anterior oblique
41 ligament, ulnar collateral ligament, intermetacarpal ligament, dorsal radial ligament

42

43 **1 Introduction**

44 The shallow biconcave-convex saddle shape of the first carpometacarpal (CMC) joint
45 articulating surface provides little bony stability (Ladd et al., 2013); the joint relies heavily on
46 its surrounding ligaments, as passive stabiliser structures, to prevent subluxation. Joint
47 hypermobility and subluxation have been thought to be one of the causes of first CMC joint
48 osteoarthritis (Jonsson et al., 1996, Freedman et al., 2000, Lane and Henley, 2001, Hunter et
49 al., 2005, Lin et al., 2014).

50

51 The anterior oblique ligament (AOL) (Pellegrini, 1991, Pellegrini et al., 1993, Imaeda et al.,
52 1994), intermetacarpal ligament (IML) (Pagalidis et al., 1981) and dorsal radial ligament
53 (DRL) (Strauch et al., 1994, Najima et al., 1997, Van Brenk et al., 1998, Bettinger et al., 1999,
54 Bettinger et al., 2000, Ladd et al., 2012) have been considered as candidates for the primary
55 passive stabiliser of the first CMC joint. It is important to know which ligament is the primary
56 stabiliser because if the function of this ligament deteriorates due to, for example, trauma,
57 corrective measures that replicate the function of this ligament can be conducted. Partial or full
58 ligament rupture may cause first CMC joint subluxation because the ligaments can no longer
59 resist loads that try to destabilise the joint (Neumann and Bielefeld, 2003). Lamas Gomez et
60 al. (2015) observed that out of 25 specimens in a cadaveric study, isolated DRL rupture
61 occurred most frequently (40%), followed by AOL rupture (28%). In addition, combinations
62 of tears in IML and DRL (16%) were also observed.

63

64 Due to its location near the joint centre, the roles of the AOL are to prevent volar first
65 metacarpal subluxation and to act as the pivot point for internal rotation of the first metacarpal
66 during opposition (Bettinger et al., 1999). The ulnar collateral ligament (UCL) is an
67 extracapsular ligament, with obliquely oriented fibres. Lying ulnar to the AOL (Zhang et al.,
68 2013) it helps to complement the function of the AOL in stabilising the volar aspect of the first
69 CMC joint (Rawat et al., 2016). In a ligament transection study, Colman et al. (2007)
70 determined that the DRL is more important than the AOL in stabilising the first CMC joint
71 during most joint motions. The superiority of the DRL over AOL in stiffness (D'Agostino et
72 al., 2014) and thickness (Ladd et al., 2012, D'Agostino et al., 2014) have made the DRL the
73 most likely candidate for the ligament that is most effective in providing stability and
74 preventing subluxation of the first CMC joint.

75

76 Regardless of which ligaments are the best candidates to be the main stabiliser of the joint,
77 laxity can happen to any of these ligaments. It is not known how isolated or combined
78 disruption of the surrounding ligaments alters the function of the joint. Deterioration in the
79 function of the ligaments requires a complex surgical procedure to repair, such as ligament
80 reconstruction, where the anatomy will be modified. It is important to understand how the
81 ligaments work individually or collectively in maintaining the stability of the joint because this
82 information can be used to design corrective measures that require less modification or remove
83 the need to modify the anatomy of the joint. Since the joint has little bony stability and requires
84 the surrounding ligaments to prevent subluxation, it is still not clear how the ligaments react to
85 loads that try to displace the joint in different directions. Hence, the objective of this study was
86 to determine the effect of ligament disruption on first CMC joint translation in multiple planes.
87 It was hypothesised that the IML and DRL are both important passive stabilisers in resisting
88 external forces that try to displace the first CMC joint.

89

90 **2 Methods**

91 2.1 Specimens

92 Sixteen fresh-frozen cadaveric mid-forearms through fingertip specimens, consisting of 8 male
93 and 8 female (mean age = 52.4 ± 11.7 years, right hand side = 9, left hand side = 7, ten bilateral,
94 six unilateral) and their computed tomography (CT) images were used in this study. With an
95 alpha = 0.05 and power = 0.80, a sample size of fourteen specimens was needed; hence the
96 sixteen specimens used in this in vitro experimental study were satisfactory to achieve the
97 objective. Ethical approval for the use of these specimens and their CT images was obtained
98 from the Tissue Management Committee of the Imperial College Healthcare Tissue Bank
99 according to the Human Tissue Act. All specimens used in this study were donated with written
100 informed consent for use in medical research. Donors were relatively young, no osteophyte
101 formation was observed on the CT images, and all ligaments appeared healthy and fully intact
102 upon visual inspection. The CT images were segmented with semi-automatic segmentation in
103 MIMICS (v.17, Materialise, Belgium) and smoothing of the surfaces was performed in
104 Geomagic v. 12 (3D Systems, Research Triangle Park, NC, United States) to obtain 3D meshes
105 of the first metacarpal, second metacarpal, trapezium and trapezoid.

106 2.2 Specimen preparation

107 2.2.1 Dissection

108 The first metacarpal, second metacarpal, trapezium and trapezoid were dissected from each
109 specimen without violating the first CMC joint capsule. The second metacarpal and trapezoid
110 were included because the intermetacarpal ligament (IML) links the first and second
111 metacarpal, while the trapezoid prevents the second metacarpal from collapse. All specimens
112 were thawed 24 hours prior to the experiment and each dissection was done by a single hand
113 surgeon. The distal half of the second metacarpal was cut to facilitate specimen preparation.

114

115 2.2.2 Specimen alignment

116 The first CMC joint was tested in a standardised neutral orientation. Based on the
117 recommendations from the International Society of Biomechanics, the neutral posture of the
118 first CMC joint is achieved when the proximal (trapezium) and distal (first metacarpal)
119 segmental coordinate systems are aligned (Wu et al., 2005). To construct the segmental
120 coordinate systems for both the first metacarpal and trapezium on the specimens, access to the
121 joint surfaces of these two bones was required; however, this was not possible, as the joint
122 capsule of the first CMC joint had to be preserved.

123

124 The neutral posture of the first CMC joint 3D mesh was achieved by the construction of the
125 local coordinate systems of the first metacarpal and trapezium 3D meshes in 3-Matic
126 (Materialise, Leuven, Belgium). The aligned 3D meshes were exported to computer-aided
127 drafting software, SolidWorks 2016 (Solidworks Corporation, Concord, USA), where they
128 were used to design specimen-specific alignment moulds (see Figure S1 in the supplementary
129 material). The specimen-specific alignment moulds were 3D printed (Ultimaker 3 Extended,
130 Ultimaker B.V., Geldermalsen, Netherlands) and used to orientate each specimen in its neutral
131 posture. Two moulds were required; one to orientate the first metacarpal and the other to
132 orientate the trapezium. The centres of the two moulds were aligned with the centre of the 3D
133 mesh. The mould that secured the trapezium-trapezoid-second metacarpal bones was placed in
134 a fixture made from aluminium (the lower pot) and the mould that secured the distal part of the
135 first metacarpal was placed in a second aluminium fixture (the upper pot; Figure 1). By using
136 a custom-made connector, the aluminium upper pot was attached to a dual-axis materials
137 testing machine (Instron 8874, Instron Corporation, England).

138

139 2.3 Customised testing jig

140 A customised experimental jig was designed and fabricated to displace the specimen by means
141 of external loads and to measure the resultant translation of the first CMC joint. This jig was
142 comprised of three parts: ball table, actuator and sensors (Figure 1). The complete unit was
143 placed on the base of the materials testing machine, which was equipped with a load cell
144 capable of measuring loads up to 1 kN (resolution of 0.001 N) and 25 Nm (resolution of 0.001
145 Nm).

146 The ball table acted as the base on which the specimen could rotate and translate. Twenty-five
147 stainless steel ball transfer units (MSP14SS; OMNITRACK, Stroud, UK) were secured to an
148 aluminium base to allow three degrees of freedom. The ball transfer units were spaced in a 5 x
149 5 grid with 30 mm spacing from centre to centre. This supported the specimen with a minimum
150 of three ball transfer units at all times, while minimising any frictional forces between the lower
151 pot and the base.

152

153 A linear electromechanical actuator (Minimech 32, 100mm stroke length; SMS Machine
154 Automation, Barnsley, UK) with a servomotor (SM23165D; Animatics Corp., Milpitas, USA)
155 was installed to apply external loads to the specimens with the purpose of producing
156 subluxation of the first CMC joint. The servomotor was controlled in real time by a
157 proportional integral derivative (PID) controller built in LabVIEW (ver. 2013 SP 1, National
158 Instruments, Austin, USA) (Shah and Kedgley, 2016).

159

160 A load cell (DBBSMM, 25 kgf; Applied Measurements Ltd., Berkshire, UK) was attached in
161 series with the linear electromechanical actuator to measure the load applied to the specimen.
162 It also served as the feedback to the PID controller, thus enabling the desired external load to
163 be applied to the specimen.

164

165 Two linear variable differential transformers (LVDTs; Figure 1) (Unipolar (DC) output, 30
166 mm measurement range; Solartron Metrology, West Sussex, UK) were used to quantify the
167 translation of the first CMC joint, measured between the centre of the articulating surface of
168 the trapezium and the centre of the articulating surface of the first metacarpal. The translation
169 of the lower pot was measured in two axes: the dorsal-volar axis and ulnar-radial axis (see
170 Figure S2 in the supplementary material). The LVDTs quantified the position of the trapezium
171 relative to the first metacarpal. However, in accordance with convention from the literature, all

172 applied loads and resulting translations were expressed as the first metacarpal relative to the
173 trapezium (Colman et al., 2007).

174

175 2.4 Sequential ligament sectioning

176 2.4.1 Loading protocol

177 A 10 N compressive load was applied to the distal end of the first metacarpal to ensure the
178 articulating surfaces of the first CMC joint were always in contact during testing. External
179 loads were applied by the linear actuator to the lower pot to displace the first CMC joint in four
180 different directions, in the following sequence: volar, dorsal, radial and ulnar. The external load
181 applied to the specimen began at 10 N and increased in increments of 10 N. The maximum
182 external load was defined as the external load that could be applied to the lower pot while still
183 maintaining full contact with the ball table (Figure 2).

184

185 2.4.2 Experiment

186 Joint translations in the intact condition were taken as the baseline values of translation of the
187 first CMC joint. Four ligaments were involved in the sequential ligament sectioning
188 experiment: AOL, UCL, IML, and DRL. They were sectioned in the aforementioned sequence.
189 The baseline translations obtained from the intact state were subtracted from those obtained at
190 each stage of the sectioning experiment.

191

192 2.5 Statistical analysis

193 Changes in translations of the first loaded CMC joint after ligament disruption were compared
194 in the four different directions (IBM SPSS Statistics, ver. 25: IBM Corp., Armonk, USA).
195 Normality tests of the studentised residuals were conducted. If the data passed the normality
196 test, a repeated measures analysis of variance (ANOVA) was performed with a Huynh-Feldt
197 correction, and if not, the non-parametric test equivalent, the Friedman test, was implemented.
198 In this statistical test, ligament transection was the dependent variable, and the direction of the
199 applied external load was the independent variable. If significant interactions with p-values
200 less than 0.05 were observed following either the repeated measures ANOVA or Friedman test,
201 further post-hoc analyses or Wilcoxon signed-rank tests with Bonferroni adjustment were
202 implemented, respectively. Pairwise differences within the groups were present if the post-hoc
203 analysis gave a p-value of less than 0.05 or if the Wilcoxon signed-rank test gave a p-value of
204 less than 0.008.

205

206 **3 Results**

207 The translations of the first CMC joint caused by the external loads applied to the specimens
208 (see Table S1 in the supplementary material) after the transection of AOL, UCL, IML and DRL
209 are listed in Table 1.

210

211 3.1 External load in the volar direction

212 Change in translation of the joint following sequential ligament sectioning did not differ ($p =$
213 0.719 , repeated measures ANOVA) with the application of an external load in the volar
214 direction (Figure 3(a)). However, there was a difference in the change in translation of the first
215 CMC joint with respect to the baseline values along the radial-ulnar axis after the ligaments
216 were sequentially transected ($p = 0.001$, Friedman test). No difference ($p > 0.05$) was found in
217 the change in ulnar-radial translation of the joint between the transection of the AOL ($0.47 \pm$
218 1.01 mm ulnarly) and UCL (0.69 ± 1.17 mm ulnarly). After transection of the IML and DRL,
219 the change in joint translation was in the radial direction (0.39 ± 1.32 mm, $p = 0.003$) and
220 moved further radially following transection of the DRL (0.78 ± 1.50 mm, $p = 0.001$).

221

222 3.4.2 External load in the dorsal direction

223 Change in joint translation increased dorsally after the AOL, UCL, IML and DRL were
224 sequentially transected ($p = 0.0001$, repeated measures ANOVA, Figure 3(b)), with the highest
225 mean translation observed after the transection of DRL (2.23 ± 2.72 mm dorsally). Further
226 post-hoc analysis showed that there were two pairwise differences within this group; these were
227 between AOL and DRL ($p = 0.041$) and UCL and DRL ($p = 0.042$).

228

229 There was also a difference on the change in translation of the first CMC joint along the ulnar-
230 radial axis as the ligaments were transected ($p = 0.002$, repeated measures ANOVA). Post-hoc
231 analysis determined two pairwise differences within this group; these were between UCL and
232 IML ($p = 0.037$) and UCL and DRL ($p = 0.027$). The first CMC joint translated radially after
233 the AOL and UCL were transected and ulnarly following sectioning of the IML and DRL.

234

235 3.4.3 External load in the radial direction

236 There were differences in the change in translation of the first CMC joint along the ulnar-radial
237 axis after the ligaments were sequentially transected ($p = 0.001$; Friedman test, Figure 3(c)).
238 These were comprised of pairwise differences between IML and AOL ($p = 0.003$) and DRL
239 and AOL ($p = 0.008$). The greatest translation was observed after the transection of the DRL
240 (1.66 ± 2.46 mm).

241

242 Translation of the joint in the dorsal-volar direction showed significant differences ($p = 0.0001$,
243 Friedman test), and further post-hoc tests determined pairwise differences between DRL and
244 AOL ($p = 0.005$) and DRL and UCL ($p = 0.003$). When the AOL and UCL were sequentially
245 transected, the first CMC joint translated dorsally; however, this translation changed to the
246 volar direction in response to the further sequential sectioning of the IML and DRL. The start
247 and end locations of the first CMC joint translations, which began in the dorsal-ulnar region
248 following transection of the AOL, processed through the dorsal-radial region with transection
249 of the UCL, and ended in the volar-radial region after transection of the IML and DRL (Figure
250 3(c)). The highest translation was observed after the transection of the DRL (1.27 ± 1.81 mm
251 volarly).

252

253 3.4.4 External load in the ulnar direction

254 There were no significant differences found in the change in translation of the joint along the
255 ulnar-radial ($p = 0.353$, repeated measures ANOVA) and dorsal-volar ($p = 0.087$, Friedman
256 test) directions following sequential sectioning of the four ligaments with external load applied
257 in the ulnar direction.

258

259 4 Discussion

260 In vitro sequential ligament sectioning was done to understand how ligaments surrounding the
261 first CMC joint function against loads that attempt to sublaxate the joint. Within the literature,
262 there is debate about which ligament primarily stabilises the joint, the AOL, IML or the DRL.
263 In this in vitro experiment, UCL was also included because it frequently has been observed to
264 be elongated in first CMC joints with osteoarthritis (Lahiji et al., 2015).

265

266 The findings of this study agree with previous studies regarding the role of the DRL as the
267 primarily ligamentous stabiliser (Strauch et al., 1994, Najima et al., 1997, Bettinger et al., 1999,
268 Ladd et al., 2012). The role played by the DRL and IML in restraining translation of the first

269 CMC joint in the direction perpendicular to that of the applied load describes a screw-home
270 mechanism (Edmunds, 2006; Haines, 1994). Another important finding in this study was the
271 complementary action between the IML and DRL in constraining the translation. When the
272 first CMC joint was loaded in volar, dorsal or radial directions, the translation of the joint was
273 greater after sectioning both IML and DRL than the translation after sectioning the AOL and
274 UCL. After sectioning the IML, the first metacarpal was in the same quadrant as when the DRL
275 was transected. However, joint translation increased with the absence of the DRL. This
276 supports the complementary, but secondary role played by the IML in maintaining the stability
277 of the first CMC joint (Lamas Gomez et al., 2015). No ligaments were found to play a role in
278 counteracting the loads that tried to displace the first CMC joint ulnarly. The anatomical
279 orientation between the first and second metacarpals acted as an anatomical constraint that
280 prevented the joint from undergoing ulnar subluxation.

281

282 When the first CMC joint was loaded in volar, dorsal or radial directions, the DRL and IML
283 were found to constrain the joint along volar and ulnar-radial directions. Translation was
284 increased in the absence of these two ligaments when the joint was loaded in the volar, dorsal
285 and radial directions. Wu et al. (2015) showed a large dorsal CMC joint force during a pipetting
286 task; this study shows the importance of the presence of DRL and IML not just to prevent
287 dorsal subluxation, but also to stabilise the joint along the ulnar-radial axis under such loads.
288 Due to the dense innervation at the dorsal side of the first CMC joint, as compared to the volar
289 site (Ladd et al., 2012), the DRL may also be important in contributing to proprioception, and
290 hence, dynamic stability of the joint. Further study may be required to understand what role
291 muscles play in providing joint stability or how the other passive stabilising components, such
292 as bone morphology, play their roles in stabilising the joint in the presence of damage to either
293 DRL or IML.

294

295 Despite its function to prevent volar subluxation of the first metacarpal (Bettinger et al., 1999),
296 the AOL has been found to be recruited less than the DRL across all motions of the first CMC
297 joint (Halilaj et al., 2015), which may indicate that the ligament is slack in most positions. The
298 AOL slackness might explain the lack of differences in translation of the joint after its
299 sectioning. During internal rotation in thumb opposition tasks, the dorsal base of the first
300 metacarpal acts as a pivot point for rotation (Kawanishi et al., 2018). The strong and thick DRL
301 (D'Agostino et al., 2014) may be required to stabilise the dorsal base of the first metacarpal.

302 Sectioning of the UCL, which is an extracapsular ligament, resulted in differences in translation
303 of the joint, but their translations showed the complementary action of the UCL and AOL.

304

305 During functional activities, such as key pinch, the first metacarpal has been captured
306 performing flexion, internal rotation, and volar translation (Halilaj et al., 2014). When a volar
307 force was applied to the first CMC joint, sectioning of the four ligaments involved in this study
308 caused the first CMC joint to translate towards the volar region. The absence of IML and DRL
309 only significantly increased the translation of the first CMC joint in the ulnar-radial direction,
310 not in the dorsal-volar direction. This may be due to the morphology of the first metacarpal
311 and trapezium. In addition, when a volar force is applied, the convex dorsal region of the first
312 metacarpal articulating surface meets the concave dorsal region of the trapezium articulating
313 surface; thus, this can increase the bony stability by restraining the first metacarpal from
314 translating in the volar direction. Less bony constraint in the ulnar-radial directions might
315 explain the observed increase in translation of the joint in this direction. Further study in
316 understanding the complementary function between the shape of the first metacarpal and
317 trapezium with the ligaments surrounding the joint may be needed, considering the shape
318 variations of these two bones.

319

320 In this experimental study, the inter-individual variation in observed translation of the first
321 CMC joint was substantial. As all aspects in the experiment including the transection of the
322 ligaments were controlled to ensure consistency in the data collected, the variation observed in
323 the first CMC joint translation among the samples may indicate the importance of the
324 morphology of the first metacarpal and trapezium in contributing to the overall stability of the
325 joint. The morphological variations of the first metacarpal and trapezium among all the samples
326 used in this study may have contributed to the variation in the first CMC joint translation. In a
327 computational study, Rusli and Kedgley (2019) determined that there is morphological
328 variation of the first metacarpal and trapezium in a healthy population of first CMC joints.
329 However, in this experimental study the relationship between morphological variation of both
330 the first metacarpal and trapezium; and the first CMC joint translation was not determined.

331

332 In order to prevent first CMC joint degradation in isolated first CMC joint dislocation,
333 diagnosis of ligamentous injury is important. This is to determine whether a surgical
334 intervention is needed, and if needed, Eaton and Littler's ligament reconstruction method has
335 been used (Lane and Henley, 2001). However, this method requires large alterations of the

336 anatomical structures which may put the joint at risk of recurrent trauma. A capsuloligamentous
337 repair can be an alternative to treat instability of the first CMC joint (Annappa et al., 2015).
338 Kerkhof et al. (2018) determined that the biomechanics of the first CMC joint treated with
339 imbrication of the DRL are not consistent. However, favourable clinical outcomes have been
340 observed (Kerkhof et al., 2018).

341

342 This in vitro experiment had several limitations. The order of the ligament sectioning in this
343 experiment was not varied. The anatomy of the joint and the limited number of specimens that
344 could be used in this experiment did not allow for different configurations of the ligament
345 sectioning test. In addition, as force was controlled, rather than displacement, the restraining
346 force of each ligament could not be determined, and the findings are limited to the sequence of
347 ligament sectioning used in this study. Although two distinct structures within the AOL have
348 been identified previously (Ladd et al., 2012), in this study the AOL was tested as a one
349 ligament structure. This was done to ensure that the ligament did not become dehydrated during
350 the experiment due to the time that it would take to identify and correctly section these two
351 structures, if they existed in all specimens, and the risk of not being able to perform the same
352 testing protocol on all specimens. Muscle forces may also play a role in maintaining the
353 stability of the joint; however, due to the need to access the ligaments, the contribution of
354 tendon and muscle was not considered. During the experiment, the orientations of second
355 metacarpal and trapezoid relative to the first CMC joint were not considered. There is no clear
356 definition of how these two bones are oriented relative to the first CMC joint in a neutral
357 orientation. However, the second metacarpal was carefully fixed such that it did not create
358 tension in the IML.

359

360 **5 Conclusion**

361 Sequential sectioning of the ligaments surrounding the first CMC joint was performed. Four
362 ligaments were tested in this study: AOL, UCL, IML and DRL. It was determined that the
363 presence of DRL and IML impose constraint on the first CMC joint and prevent subluxation
364 of the joint. However, this is not the case for AOL and UCL. These findings suggest that the
365 disruption of the DRL or combination of both DRL and IML, which have been observed in
366 first CMC joint osteoarthritis patients, may produce instability and subluxation of the joint that
367 may lead to aberrant mobility, causing pain, loss of strength, and functional limitations. The

368 reconstruction of either the IML or DRL can be done to strengthen the passive stability of the
369 first CMC joint.

370

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374

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Figure Captions

Figure 1: The customised testing rig. A ball table, consisting of an aluminium base and twenty-five ball transfer units, allowed the specimen to translate along dorsal-volar and radial-ulnar axes and rotate. The proximal and distal portions of the specimen were cemented into the upper and lower pots, respectively. The red arrow indicates an external load in the dorsal direction and the orange arrow indicate the direction of the compressive force provided by the materials testing machine. LVDT-1 and LVDT-2 were used to measure the translation of the specimen when subjected to external load.

Figure 2: A moment caused by the applied external load resulted in a loss of contact between the lower pot and the ball table (indicated by θ). Testing was stopped if this was observed.

Figure 3: Translation the first CMC joint due to the application of an external load in the (a) volar, (b) dorsal, and (c) radial directions following transection of the anterior oblique ligament (AOL), ulnar collateral ligament (UCL), intermetacarpal ligament (IML) and dorsal radial ligament (DRL). The circles represent the centre of the articulating surface of the first metacarpal plotted relative to the position of the trapezium after an external load was applied to the specimen. The lines represent the mean translation of the joint. DU – dorsal-ulnar, DR – dorsal-radial, VU – volar-ulnar and VR – volar-radial.

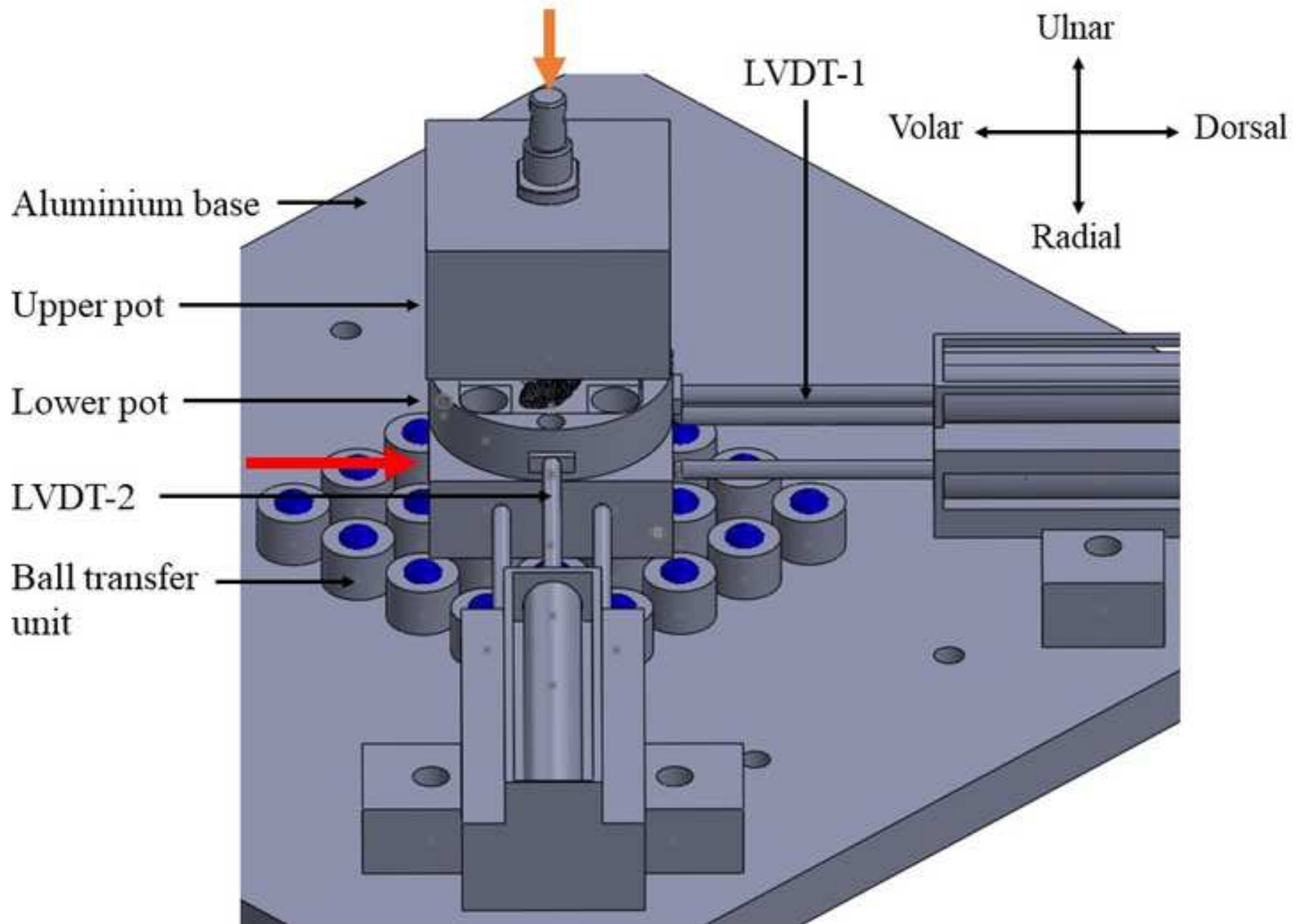
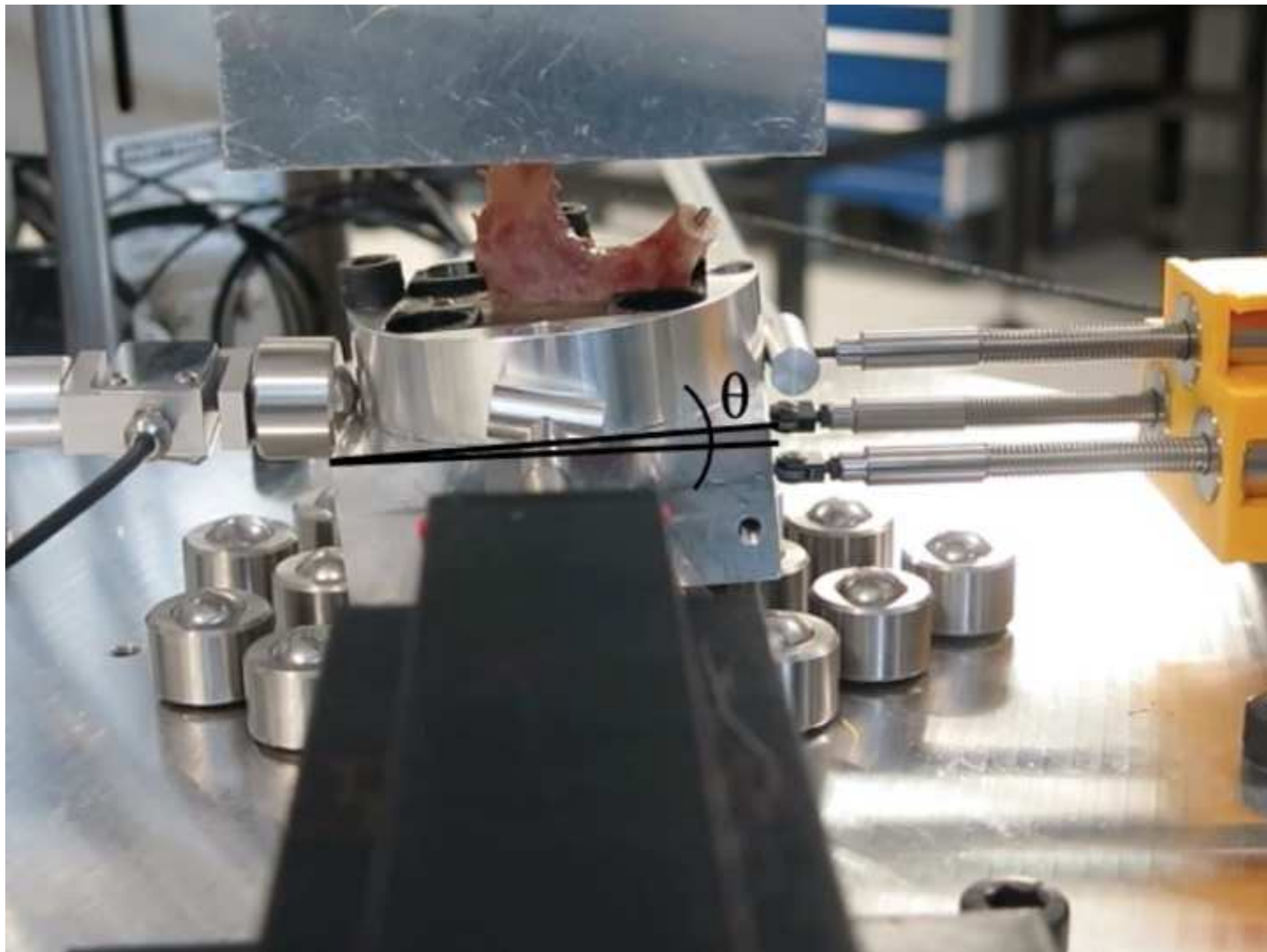
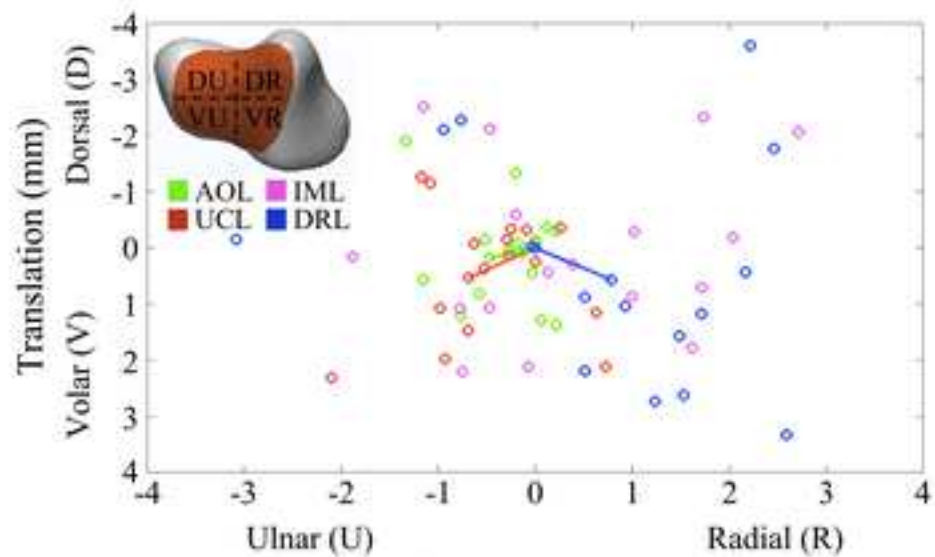


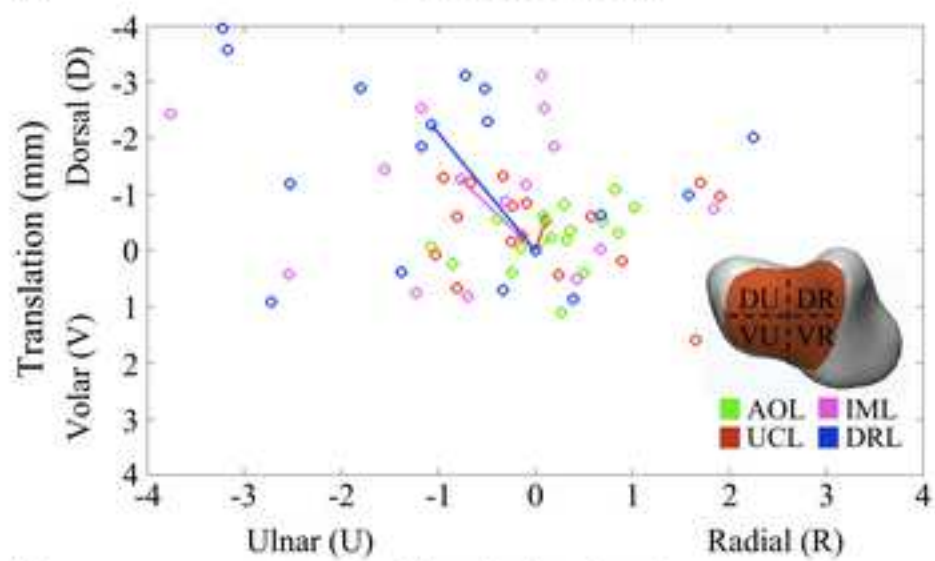
Figure 2

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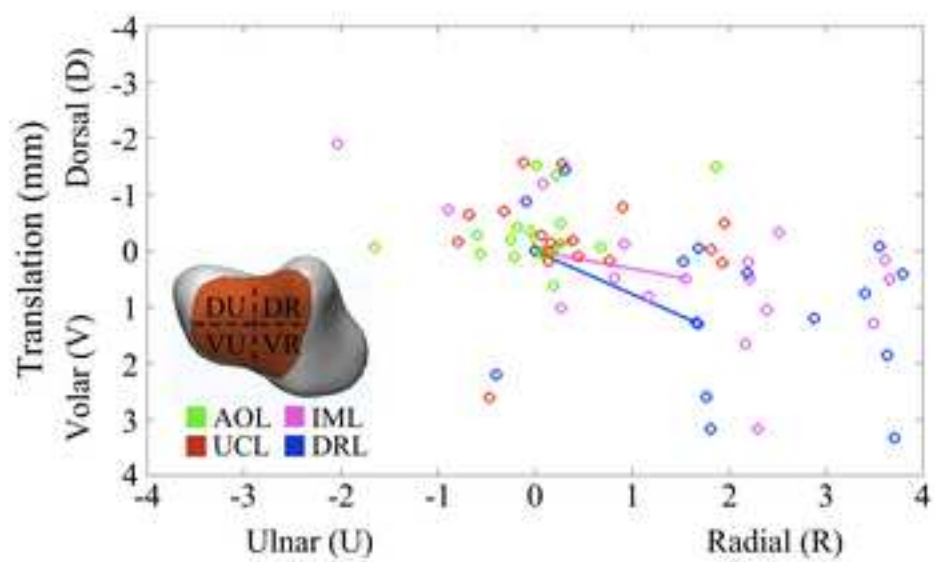




(a) Translation (mm)



(b) Translation (mm)



(c) Translation (mm)

