



## Original Research Paper

# Numerical simulation of a 3-D gas–solid fluidized bed: Comparison of TFM and CPF-D numerical approaches and experimental validation

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## ABSTRACT

This paper presents the results of a 3-D numerical simulation of a freely bubbling fluidized bed, based on the Eulerian–Lagrangian approach, using the software Barracuda (CPF-D-Barracuda). The main results obtained were assessed in terms of frequency analysis, bubble pierced length, bubble size, bubble passage frequency and bubble velocity. The results obtained were also compared with experimental data obtained in a 3-D fluidized bed using pressure and optical probes, and with the numerical results using the more common Eulerian–Eulerian approach, implemented in the commercial software Fluent (TFM-Fluent).

The results show that CPF-D-Barracuda satisfactorily predicts the global behaviour of bubbling beds with a low computational cost, although it computes smaller bubble sizes and lower bubble velocities than TFM-Fluent and experiments. Additionally, the spectra of pressure and particle volume fraction obtained with CPF-D-Barracuda resemble those from the experiments and the TFM-Fluent simulations, but with a larger contribution of lower frequencies. The peaks of the pressure spectra from CPF-D-Barracuda are close to those from the experiments and the TFM-Fluent simulations, whereas those in the solid volume spectra seem to be underestimated by CPF-D-Barracuda. The results also indicate that the particle fraction threshold value chosen to distinguish bubbles contours notably influences the results of the bubble characteristics, especially for TFM-Fluent, whereas CPF-D-Barracuda is less sensitive to this threshold value.

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## 1. Introduction

Fluidized beds are one of the most widely used particle–fluid technologies in a multitude of applications in several industries. They have been used as combustors and gasifiers of coal and biomass [1–3] and many other industrial processes, such as in the pharmaceutical industry [4]. More recently, fluidized beds have also been proposed as a promising alternative to packed beds for solar thermal energy storage, especially for thermochemical and concentrated solar energy applications. The higher heat and mass transfer rates of fluidized beds over fixed beds makes them a more suitable technology [5]. In this context, there is great interest in the development of numerical models that permit bubbling fluidized

beds to be simulated in large-scale industrial facilities with a reasonable computational cost.

Most computational fluid dynamics (CFD) models applied to multiphase flow find it difficult to properly describe the interactions between phases, which is a complex task when using two-phase flows [6]. Two different widely used approaches to model multiphase particle flows can be defined: two-fluid models (TFM), based on the Eulerian–Eulerian approach, and discrete particle model (DPM), based on the Eulerian–Lagrangian approach. TFM consider gas phase and particulate phase as two interpenetrating continua [7]. According to Grace and Taghipour [8], obtaining accurate solutions for multiphase flows is more challenging than for single-phase flows, because certain aspects should be taken into consideration to validate the numerical results, such as to consider particles as perfectly spherical, which might reduce the accuracy of interparticle and interphase stresses, or the influence of the mesh resolution on the accuracy of large gradients appearing at the bubble boundary. Several studies have reported

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that TFM overestimates the bed expansion in a bubbling bed of fluid catalytic cracking (FCC) particles [9,10], which might be improved including particle size distribution in the CFD models [11]. One of the most common simplifications assumed in TFM is that particles are considered to have the same diameter, density and coefficient of restitution, which might reduce the accuracy of the interparticle and interphase stresses [12]. Consideration of different particles in TFM would complicate the computational cost, because continuity and momentum equations should be solved for each size bin separately in the whole numerical domain. Another aspect to consider in TFM models is the accuracy of the results, which depends on the grid size, while the use of fine grids makes it difficult to solve 3-D computational domains with a reasonable computational cost. Recent studies indicate that the grid size to particle diameter ratio should be lower enough to properly reproduce the macroscopic behaviour of the bed when particle clustering appears [13]. Some authors proposed values of this ratio lower than 10 [14]. Nikolopoulos et al. [13] indicate that particle aggregates may be relevant in either Geldart A or B particles. The reduction in the grid size increases the computational cost of TFM models.

An alternative to TFM are DPM, which can be classified in three different approaches: discrete element model (DEM), dense discrete phase model (DDPM) and multiphase particle in cell (MP-PIC). DEM track individual particles in time, and the particle phase is described as discrete and solved according to Newton's laws of motion to every particle. DEMs show a reliable description of the particle–particle collisions and are highly useful for the study of flow details in fluidized beds [15]. Therefore, DEMs require high computing power on tracking each particle trajectory and considering contact collisions of particles [16], and the number of computational particles used ( $\approx 10^5$ ) is lower than the number of particles normally used in real industrial fluidized beds. Recent advances in this numerical approach rely on the use of the Energy Minimization Multi-Scale (EMMS) model for the drag coefficient, as it has been proved to better describe the operation of Circulating Fluidized Beds (CFB). The EMMS model improves the simulation when there are clusters of particles with dimensions smaller than the size of the computational cell, compared with conventional Gidaspow's drag model [17]. An approach to reduce the computational cost of DEM is DDPM, in which the particles are grouped in groups of particles (called parcels or clouds). In this approach, the particle–particle interactions are modeled with the Kinetic Theory of Granular Flow (KTGF). There are few studies in the literature [18,19] that studied the influence of different modeling parameters on the simulation of different fluidization regimes: bubbling, turbulent and circulating fluidized beds. Adnan et al. [19] concluded that EMMS/bubbling drag model predicts better the effects of dissipative structures than the conventional Gidaspow drag model.

Another alternative to DEMs is the multiphase particle in cell method, solving the momentum equation for computing particles, defined as a group of particles with the same properties i.e., parcels, rather than for individual particles as DEMs do, which allows the computational time to be notably reduced [20]. MP-PIC and DDPM conceptually are very similar, although there are some differences between them (apart from to simulate individual or grouped particles). MP-PIC usually uses simple relations for the solid stress, neglecting the shear stresses [21], which is usually included in DDPM; MP-PIC models the particle–particle interactions with the solid stress tensor equation, rather than with the KTGF, as DDPM does [19]; and there are also multiple differences in the numerical implementation [21]. Drawing on the MP-PIC method, a new Eulerian–Lagrangian CFD approach was created (computational particle fluid dynamics, CPFDF) [22], which allows simulating large-scale industrial multiphase flow systems with a

low computational cost, being able to reach real particle number of  $10^{16}$  order of magnitude. MP-PIC is useful to compute particle stress gradient, which is difficult to solve for individual particles [23]. Another point to highlight is that it is enough to use coarse cartesian mesh, because there must be sufficient room in adjacent cells to accommodate any parcels that move into them in a subsequent time step [24].

Several studies have focused on the use of CPFDF applied to industrial applications [25], such as down flow reactors [26], biomass combustion chambers [27], spouted beds [16], cold pilot calciners [28], and biomass gasification [29], among others. Other studies have applied CPFDF to fluidized beds. Some researchers applied this method in 3-D models to study the effect of particle distribution in industrial circulating fluidized bed risers [30] and downers [31], and cylindrical beds [32]. Karimipour and Pugsley [6] analysed the capacity of the MP-PIC approach to model a 3-D bubbling fluidized bed of Geldart-A particles applied to FCC catalyst, analysing three different grid sizes and two drag models. They reported that the influence of the drag model is much lower than the effect of the grid size. Other studies applied CPFDF to study the minimum fluidization velocity [33] in fluidized beds. Lim et al. [34] carried out a 2-D simulation to analyse the bed pressure drop and bubble flow behaviour of bubbling fluidized beds produced using a shroud nozzle distributor. Their findings were consistent with the observed experimental results when the most adequate collision model was selected. Yang et al. [35] simulated flow characteristics of Geldart A particles in bubbling fluidized bed with and without perforated plates implementing a 3-D model. They concluded that the results of predicting the gas–solid flow were not good enough compared with the experimental data and they proposed that the detailed structure of the fluid dynamics should be analysed carefully and not only solid volume fraction profiles.

Few studies have analysed a fluidized bed using a 3-D CPFDF model and validated its results of hydrodynamics behaviour with experiments. In the aforementioned studies, some of them compared the numerical results with correlations for bubble properties, which might not be adequate for predicting the small bubbles that appear in Geldart A particles fluidization [6], or they compared the numerical results with experimental data of other studies, but only focused on solid fraction, bubble diameter and bubble velocity. Besides, there are works mainly focused on analysing solid volume fraction, axial particle velocity and particle residence time [30]. Alternatively, some studies have analysed a 2-D fluidized bed. In this regard, Liang et al. [23] carried out a critical validation study on the 2-D CPFDF model in simulating gas–solid bubbling in fluidized bed. They compared their simulation results with the 2-D TFM model and experimental data of Hernández-Jiménez et al. [36], who used particle image velocimetry technique and digital image analysis in 2-D fluidized bed. In both studies, to analyse bubble and emulsion phases, the same arbitrary threshold particle volume fraction of 0.3 was considered. The authors concluded that the CPFDF model predicted better profiles of solid velocity, but failed to properly simulate the bubble coalescence, suggesting that the parcel number utilized should be at least an order of magnitude lower than the real particle number. Shi et al. [37] studied the effect of model dimensionality (2D versus 3D) on the validation of fluidized bed models concluding that only the 3D simulations allow obtaining physically realistic results that are less sensitive to a choice of numerical parameters.

It is further required to carry out studies aimed at validating CPFDF, to study its applicability to fluidized beds. With this aim, this paper presents the results of a numerical simulation for a freely bubbling fluidized bed, using the CPFDF model. As a novelty, the CPFDF model is applied to a 3-D domain and a broad analysis of

the fluidized bed hydrodynamics is performed. Moreover, results comprising frequency analysis, bubble pierced length, bubble size, bubble passage frequency and bubble velocity are compared with experimental data taken from a bed with the same geometry and operated under the same conditions [12]. These results are also compared with the numerical results of a 3-D model using the most common Two Fluid Model, implemented in the commercial software Fluent (TFM-Fluent) [38] for different values of the threshold value to detect bubbles contour. Hence, the numerical simulation was performed using a computational domain with geometry that can contribute to extrapolate the results in actual applications. Moreover, the influence of the temporal step, number of cells and threshold value on the results obtained with the Barracuda software (CPFD-Barracuda Virtual Reactor v. 17.3.1) is studied.

## 2. Experimental data

This section presents a brief description of the experiments carried out by Acosta-Iborra et al. [12]. In their study, a bubbling fluidized bed (inner diameter of 193 mm and height of 800 mm), filled with Geldart-B silica sand particles (with a mean particle size of  $d_p = 540 \mu\text{m}$ ), with an initial height ( $H_{bed}$ ) of 0.22 m was studied. For the experiments, the superficial fluid velocity ( $u_f$ ) in the bed was set to 0.57 m/s, which guaranteed fully bubbling conditions because the minimum fluidization velocity ( $u_{mf}$ ) experimentally measured was 0.4 m/s. At the bottom inlet, air was distributed through a distributor plate, perforated with 90 holes of 2 mm diameter, to achieve homogeneous bubble generation. To detect the bubble passage along the height of the bed from the distributor and for different radial positions, several pressure and optical probes were installed at different locations inside the bed, yielding measurements of 10 min duration at a sampling frequency of 500 Hz.

## 3. Numerical model

### 3.1. Simulated bed with TFM-Fluent

In a previous study carried out by Acosta-Iborra et al. [12], a computational study on the bubble behaviour in a 3-D fluidized bed was performed, where the results obtained from experimental measurements were compared to the numerical results performed with the CFD software ANSYS Fluent 6.3 [39]. The 3-D computational domain was discretized with a structured grid (28,800 hexahedral cells). As boundary conditions, at the inlet, a uniform velocity was defined (0.57 m/s) for air at 25 °C, with a constant static pressure ( $10^5 \text{ Pa}$ ) at the outlet of the cylinder, because the top of the bed was open to the exterior air. At the lateral wall, a non-slip condition for the air was imposed. For the particles, a free-slip condition was defined at the wall because, in this kind of bed, particles are well fluidized and do not remain attached to the wall and, for simplicity, the drag of the wall on the particles can be neglected. In their study, an implicit finite volume technique (phase coupled SIMPLE) based on an iterative pressure correction was used to

**Table 1**  
Parameters of the TFM-Fluent simulation of Acosta-Iborra et al. [12].

Parameter	Value
Time step (s)	$2.5 \cdot 10^{-4}$
Iterations per time step	40
Maximum pack volume fraction (dimensionless)	0.555
Coefficient of restitution (dimensionless)	0.9
Angle of internal friction (degrees)	30

solve the governing equations, and using a second order discretization in space and time. The Gidaspow's drag model was used to take into account the momentum interchange between gas and particles. The main parameters defined for the numerical solution of Acosta-Iborra et al. [12] are shown in Table 1. More details of the equations and the numerical model are described by Acosta-Iborra et al. [12].

### 3.2. Bed Simulated with CPFD-Barracuda

#### 3.2.1. Governing equations

The governing equations of the MP-PIC for the continuum phase (Eq. (1) and Eq. (2)) [40] and the particle phase (Eq. (3)) [20] are as follows:

Continuity equation:

$$\frac{\partial(\theta_f \rho_f)}{\partial t} + \nabla \cdot (\theta_f \rho_f \vec{u}_f) = 0 \quad (1)$$

Momentum equation:

$$\frac{\partial(\theta_f \rho_f \vec{u}_f)}{\partial t} + \nabla \cdot (\theta_f \rho_f \vec{u}_f \vec{u}_f) = -\nabla p - \vec{F} + \theta_f \rho_f \vec{g} + \nabla \cdot (\theta_f \tau_f) \quad (2)$$

$$\frac{d\vec{u}_p}{dt} = D_p(\vec{u}_f - \vec{u}_p) - \frac{1}{\rho_p} \nabla p - \frac{1}{\theta_p \rho_p} \nabla \cdot \tau_p + \vec{g} \quad (3)$$

where  $\theta_f$  is the fluid volume fraction,  $\rho_f$  is the fluid density,  $u_f$  is the fluid velocity,  $p$  is the pressure,  $F$  is the momentum exchange rate per volume between gas and particles,  $g$  is the gravity acceleration,  $\tau_f$  is the viscous stress term,  $u_p$  is the particle velocity,  $D_p$  is the drag function,  $\rho_p$  is the particle density,  $\theta_p$  is particle volume factor, and  $\tau_p$  is the solid contact stress, which is computed as follows:

$$\tau_p = \frac{P_s \theta_p^\beta}{\max[(\theta_{cp} - \theta_p), \varepsilon(1 - \theta_p)]} \quad (4)$$

where  $P_s$  is the pressure constant,  $\beta$  is a constant,  $\theta_{cp}$  is particle volume fraction at close packing, and  $\varepsilon$  is a constant. The default values used for the constants are  $P_s = 1 \text{ Pa}$ ,  $\varepsilon = 10^{-8}$  and  $\beta = 3$ , which is recommended to be in the range of 2 to 5 [23,27].

The momentum exchange rate  $\vec{F}$  in Eq. (2) is computed as follows:

$$\vec{F} = \iiint f V_p \rho_p \left[ D_p(\vec{u}_f - \vec{u}_p) - \frac{1}{\rho_p} \nabla p \right] dV_p d\rho_p d\vec{u}_p \quad (5)$$

In the above equation,  $V_p$  is the particle volume and  $f$  represents the particle probability distribution function, which is computed using the Liouville equation for the particle position without a collision model:

$$\frac{\partial f}{\partial t} + \nabla \cdot (f \vec{u}_p) + \nabla_{\vec{u}_p} \cdot \left( f \frac{d\vec{u}_p}{dt} \right) = 0 \quad (6)$$

where  $\nabla_{\vec{u}_p}$  is the divergence operator with respect to velocity. The flow is considered isothermal and the changes in the air density are computed with equation of state of the ideal gas:

$$P = \rho_f R_g T \quad (7)$$

where  $R_g$  is the gas constant and  $T$  the absolute temperature.

#### 3.2.2. Drag model

With regard to the drag model, the drag force exerted on the particle ( $F_p$ ) depends on the fluid conditions, on the gas-particle

drag coefficient and on the Reynolds number and can be computed as follows:

$$F_p = m_p C_d |u_f - u_p| \tag{8}$$

where  $m_p$  is the mass of the particle, and  $C_d$  is the gas-particle drag coefficient

Several models are proposed to compute the drag force on solid particles. In the present study, the Wen-Yu model drag force [41] was used, which is expressed as follows:

$$D_p = 0.75 C_d \frac{\rho_f |u_f - u_p|}{\rho_p d_p} \tag{9}$$

and

$$C_d = \frac{24}{Re} \theta_f^{-2.65} \quad \text{for } Re < 0.5 \tag{10}$$

$$C_d = \frac{24}{Re} (1 + 0.15 Re^{0.687}) \theta_f^{-2.65} \quad \text{for } 0.5 \leq Re \leq 1000 \tag{11}$$

$$C_d = 0.44 \theta_f^{-2.65} \quad \text{for } Re > 1000 \tag{12}$$

where  $d_p$  is the particle diameter, and  $Re$  is the Reynolds number.

To compute the particle drag, the Reynolds number is defined as:

$$Re = \frac{\rho_f |u_f - u_p| d_p}{\mu_f} \tag{13}$$

where  $\mu_f$  is the dynamic viscosity of the fluid.

### 3.2.3. Numerical setup

The physical and geometrical parameters included in the CPFD Barracuda software were similar to those used in the study by Acosta-Iborra et al. [12]. Therefore, the computational domain studied using CPFD was a 3-D model, with an inner diameter and height of 193 mm and 800 mm, respectively (Fig. 1). Two grids were implemented to analyse the main results obtained, both of which were based on a uniform grid in directions x, y and z, resulting in a 45,980 cells (Coarser Grid) and 93,296 cells (Finer Grid). Fig. 2 shows a detail of the two grids. As can be observed, CPFD-Barracuda generates a general rectangular domain in the plane x – y with uniform computational cell sizes in the three directions. In consequence, some cells are not in the domain. The number of real cells within the physical domain of the bed is indicated in Table 2.

For the bed, Geldart-B silica sand particles with an initial height of 0.22 m were used, with an initial particle volume fraction at close packing of  $\theta_{cp} = 0.55$  and a real density of  $2632.5 \text{ kg/m}^3$ . The particles were of a uniform size ( $540 \mu\text{m}$  diameter) with a sphericity of  $\Psi_p = 0.8$ . Air enters the domain through the bottom inlet of the bed. The top outlet of the bed is connected to the exterior air at atmospheric conditions ( $25^\circ\text{C}$ ). At the inlet, a constant superficial gas velocity of  $0.57 \text{ m/s}$  was defined with an isothermal flow temperature of  $298.15 \text{ K}$ .

With regard to the particle to wall interaction, default values for parameters such as normal-to-wall momentum retention (0.85), tangent to wall momentum retention (0.85) and diffuse bounce (5) were defined according to [42].

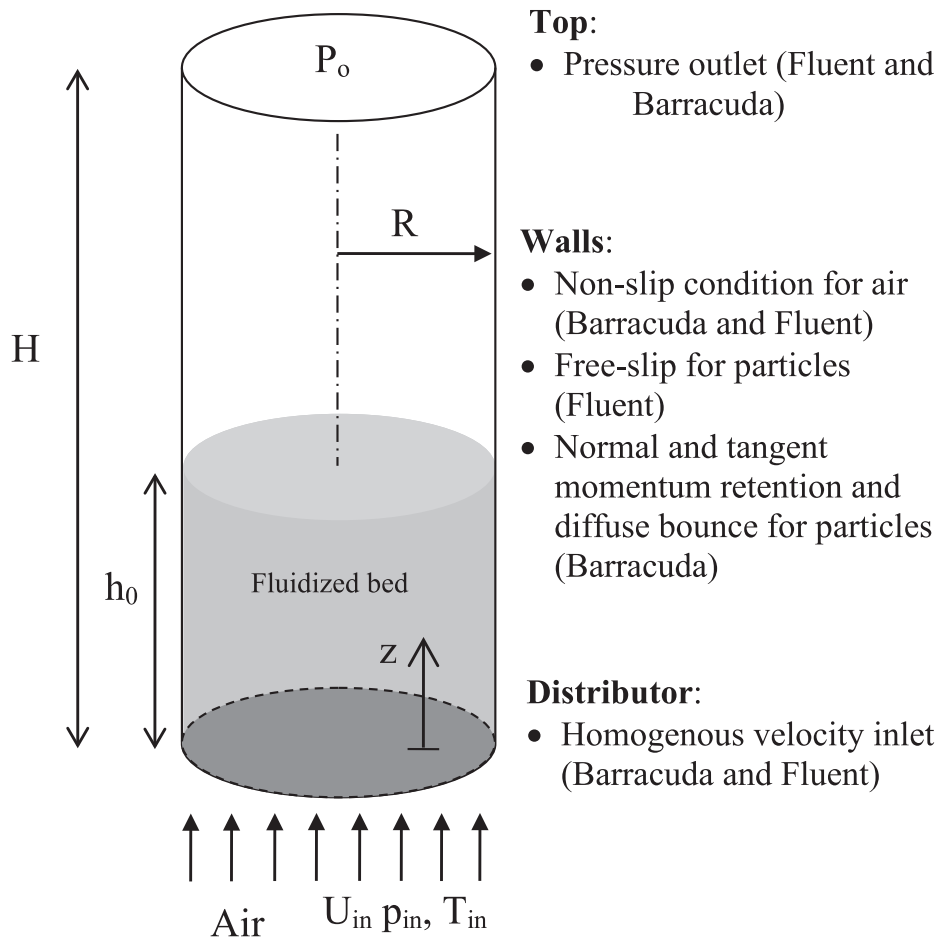
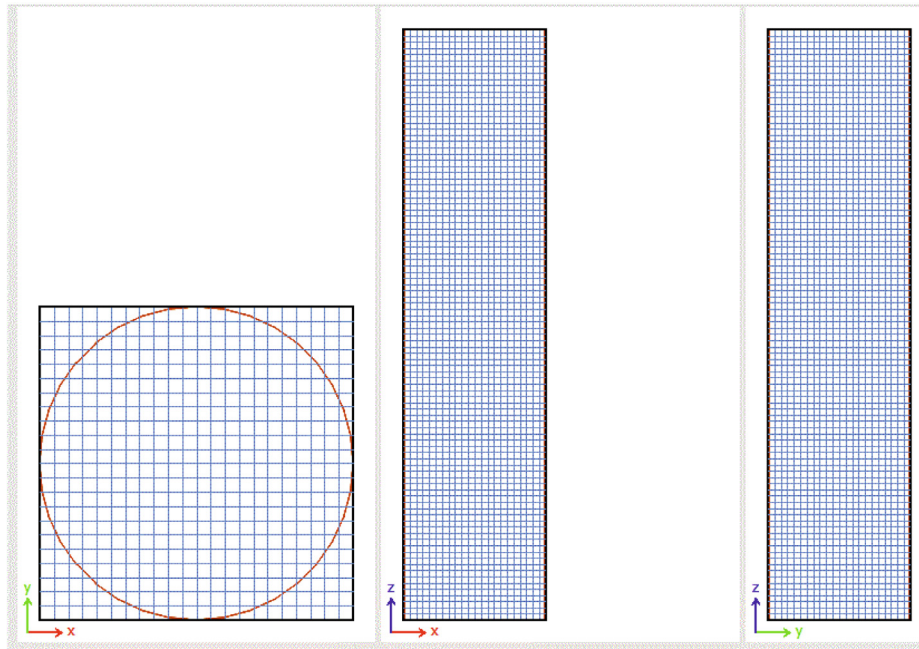
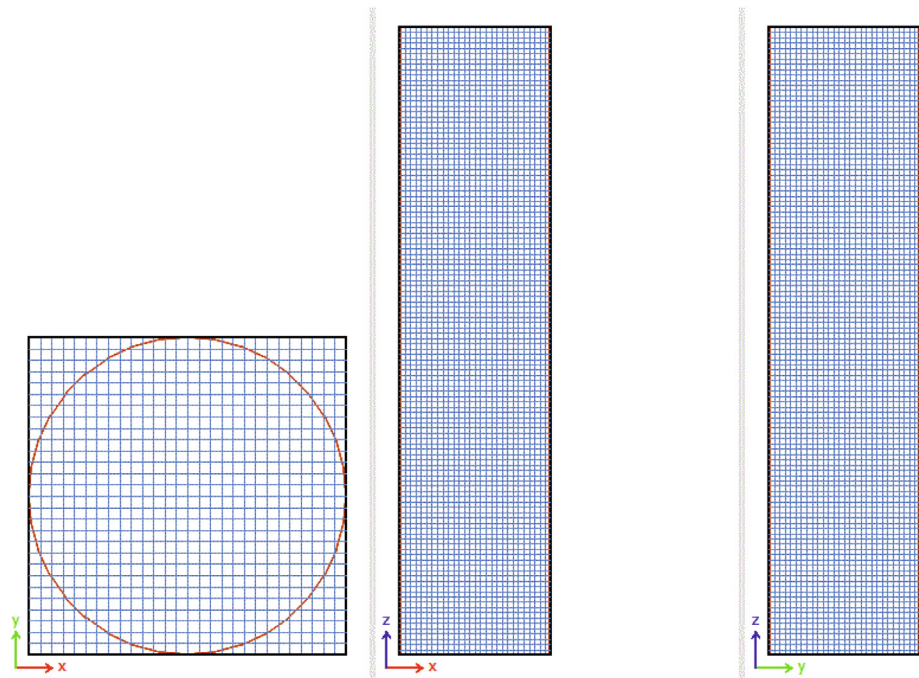


Fig. 1. CPFD model of the fluidized bed.





(a) Coarser grid of Cases 1 and 3



(b) Finer grid of Cases 2 and 4

Fig. 2. Detail of the two grids studied.

At each of the two proposed grids, two time steps were used,  $10^{-3}$  s and  $10^{-4}$  s, whereas the numerical simulations were performed for a time period of 60 s. Tables 2 and 3 summarize the main computational data of the four cases considered in the CPFD-Barracuda simulations. Note that the computational cost in the most restrictive case (Case 4) is approximately 30 h for 60 s of real time operation, i.e., approximately 0.5 h of computing time for 1 s of real time fluidization. The numerical simulations were performed in parallel using Intel Xeon CPU E5-2620 v4

@2.10 GHz (2 sockets and 8 cores per socket) with 64 GB RAM memory and the option for CUDA computing was enabled, with a Nvidia RTX A6000 graphics card.

In the CPFD-Barracuda simulations performed, absolute pressure and void fraction were obtained. To this end, several points placed at different heights along the bed and for different radial positions were defined along the computational domain, so some of these points were located in the same place as the experimental and numerical simulation carried out by Acosta-Iborra et al. [12].

**Table 2**

Cell and computational parameters for the different cases studied in the CPFD-Barracuda simulations: total number of cells  $N_{\text{cells,total}}$ , real number of cells  $N_{\text{cells,real}}$ , computational time  $t_{\text{comp}}$ , CFL factor and number of time iterations  $N_{\text{iter}}$ .

	$\Delta t$ [s]	$N_{\text{cells,total}}$	$N_{\text{cells,real}}$	$t_{\text{comp}}$ [s]	CFL	$N_{\text{iter}}$
Case 1	$10^{-3}$	45980	38760	$1.56 \times 10^4$	0.8–1.5	$7.58 \times 10^4$
Case 2		93296	77112	$2.69 \times 10^4$	0.8–1.5	$1.11 \times 10^5$
Case 3	$10^{-4}$	45980	38760	$7.62 \times 10^4$	0.1–0.4	$6.01 \times 10^5$
Case 4		93296	77112	$1.06 \times 10^5$	0.1–0.4	$6.01 \times 10^5$
Case 4a	$10^{-5}$	93296	77112	$5.86 \times 10^5$	0.01–0.04	$5.91 \times 10^6$
Case 4b	$10^{-4}$	149193	121245	$1.07 \times 10^5$	0.1–0.4	$6.01 \times 10^5$

**Table 3**

Particle and mass parameters for the different cases studied in the CPFD-Barracuda simulations: Number of particles  $N_{\text{part}}$ , number of clouds  $N_{\text{clouds}}$ , total mass of simulated particles, initial particle volume fraction  $\theta_p$  and deviation in the mass  $e_{\text{mass}}[\%]$ .

	$\Delta t$ [s]	$N_{\text{part}}$	$N_{\text{clouds}}$	$m_{\text{sim}}$ [kg]	$\theta_p$	$e_{\text{mass}}[\%]$
Case 1	$10^{-3}$	$4.24 \times 10^7$	$4.23 \times 10^5$	9.211	0.5437	–1.15
Case 2		$4.30 \times 10^7$	$8.49 \times 10^5$	9.343	0.5514	0.259
Case 3	$10^{-4}$	$4.24 \times 10^7$	$4.23 \times 10^5$	9.211	0.5437	–1.15
Case 4		$4.30 \times 10^7$	$8.49 \times 10^5$	9.343	0.5514	0.259
Case 4a	$10^{-5}$	$4.30 \times 10^7$	$8.49 \times 10^5$	9.343	0.5514	0.259
Case 4b	$10^{-4}$	$4.30 \times 10^7$	$1.34 \times 10^6$	9.343	0.5514	0.259

3.2.4. Sensitivity analysis of the cases studied

The influence of the time step and the grid size was studied through the four cases of the CPFD-Barracuda simulations. Firstly, the Courant-Friedrichs-Lewy (CFL) number is shown in Fig. 3, which is useful to determine the adequate time step based on the simulated meshes and parcels [23]. The software CPFD-Barracuda recommends a CFL value of between 0.8 and 1.5 to maintain a compromise between stability, accuracy, and speed of the calculation. If, during the simulations, the CFL reaches a value higher than 1.5, CPFD-Barracuda automatically reduces the time step for getting CFL = 0.8. For the cases with the highest time step (Cases 1 and 2), the software maintained the CFL factor between the default limits, reducing the time step when CFL > 1.5. In contrast, for Cases 3 and 4, with the lowest time step ( $10^{-4}$  s), the CFL was not modified by the software during the simulations because it was under the maximum limit of CFL = 1.5, ranging between 0.1 and 0.4. The CFL behaviour helps to explain why the number of temporal iterations in Case 2 is higher than in Case 1, with the same time step. Case 2 had a lower cell size, so the CFL

was higher and was corrected more times and, consequently, more iterations in time were needed. Regarding Cases 3 and 4, the number of iterations remained constant because no CFL correction was performed, so the difference in the computational time is only related to the different number of cells. Although CFL showed low values in the cases with the reduced time step, the highest computational cost (Case 4) showed a reasonable duration (Table 2). In addition to the four main cases studied, two extra cases (Cases 4a and 4b) were studied to check the independence of the numerical model from the time step and the number of cells. The only differences with respect to Case 4 is that in Case 4a the time step was reduced to  $10^{-5}$  s, with the rest of parameters unchanged, whereas in Case 4b, the time step was the same as in Case 4 but the number of computational cells was augmented up to 149000. CFL data for Case 4a are very low, and the computational cost of this case is very high. Case 4b, shows similar values of the CFL to Case 4 with also a higher computational cost.

Table 3 includes the total number of real particles and clouds or clusters (a group of particles with the same properties) for each

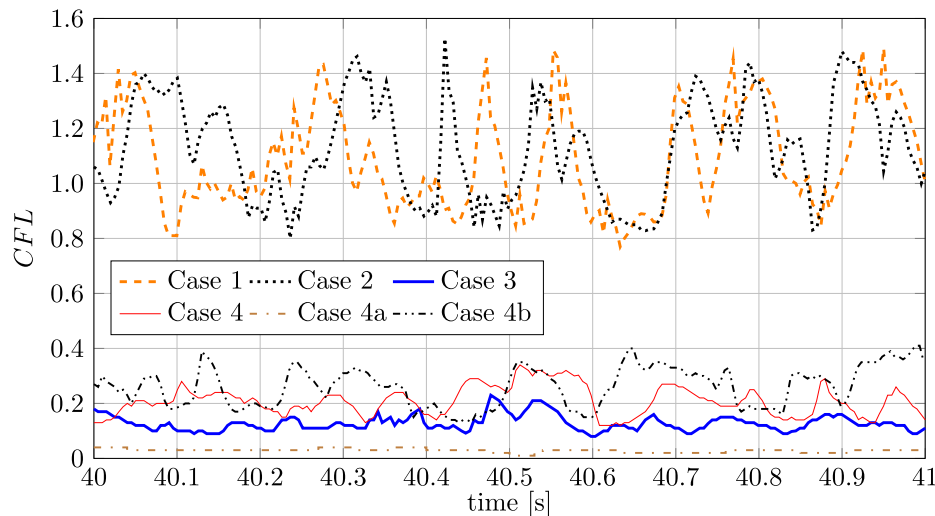


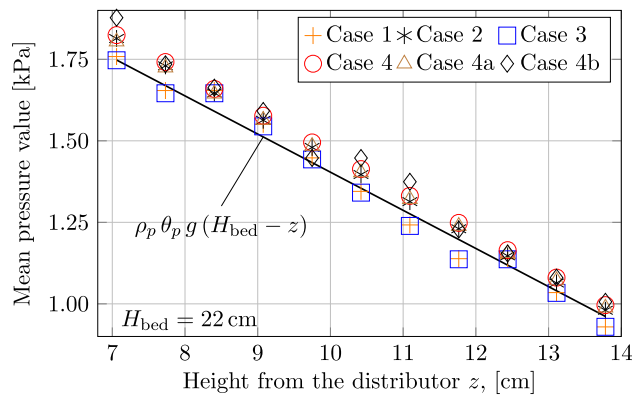
Fig. 3. Evolution of CFL factor for the four cases studied with CPFD-Barracuda.

case, which shows that the number of clouds increased proportionally to the number of computational cells, as expected. This table also includes the simulated mass of particles, which differs slightly from the theoretical mass imposed as the initial condition. This was reported by Liang et al. [23], who indicated that the change in the initial total solid mass is related to the way in which parcels are arranged in every cell, which depends on the cell shape and dimension. In this regard, CPFD-Barracuda maintains the height of the bed but modifies the mass in the bed, and consequently the initial particle fraction, to accommodate the total number of computational clouds in a rectangular array, that is, uniform in the three dimensions (the particles are initially located forming a regular hexahedron). Following this, the error in the initial mass ( $e_{mass}$ ) was computed (Eq. (14)), resulting in a low value in all the analysed cases. Liang et al. [23] observed much higher values of  $e_{mass}$ , i.e. up to 15–20%, due to their 2-D numerical scheme with only one cell in the third dimension. This geometry limitation generated large mass variations to maintain the height of the bed.

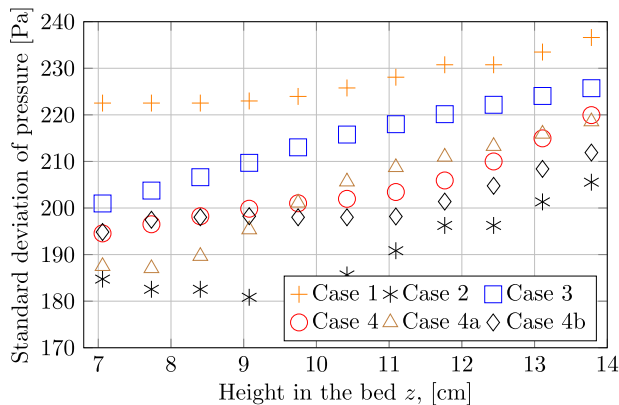
$$e_{mass} = \frac{m_{sim} - m_{theo}}{m_{theo}} \times 100 \quad (14)$$

In Eq. (14),  $m_{sim}$  is the simulated initial particle mass and  $m_{theo}$  is the theoretical initial particle mass.

The mean manometric pressure during the 60 s of the simulations and the power spectral density (PSD) of pressure measurements are shown in Figs. 4 and 5, respectively. Fig. 4(a) shows the mean manometric pressure during the 60 s of the simulations. The first 2 s of each simulation were discarded due to the transient

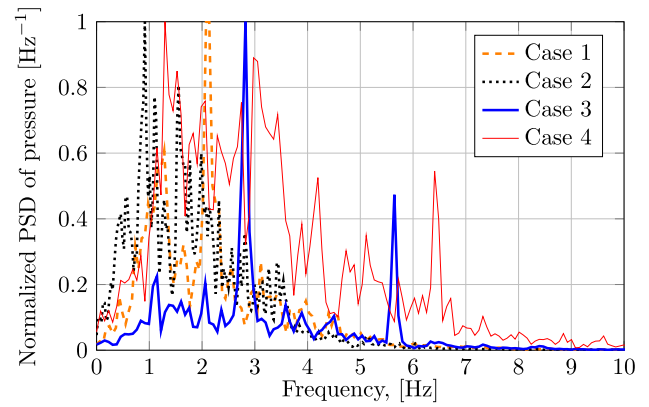


(a) Mean value

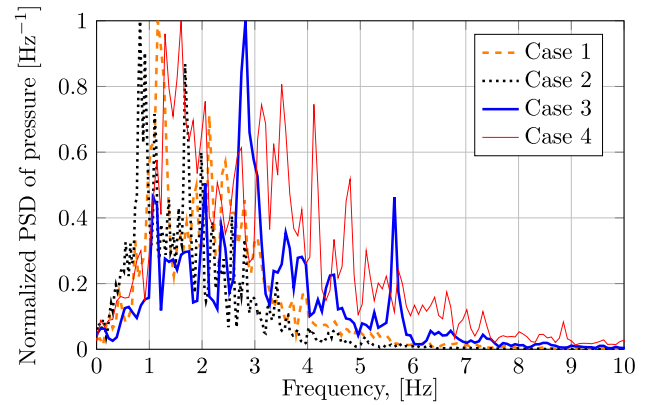


(b) Standard deviation

Fig. 4. Mean values of the manometric pressure (with  $\theta_p = 0.45$ ) (a) and standard deviation (b) of pressure signal for different heights in the centre of the bed for the four cases studied with CPFD-Barracuda.



(a)  $z = 7$  cm



(b)  $z = 13$  cm

Fig. 5. Comparison of normalized power spectral densities (PSD) for absolute pressure at  $z = 7$  cm (a) and  $z = 13$  cm (b), in the bed axis for the different cases studied with CPFD-Barracuda.

start-up of the bed. There are no noticeable differences between the analysed cases. In Fig. 4(a) the theoretical line was calculated with a value of  $\theta_p = 0.45$ , which was the mean value computed in the simulations. It is observed that the theoretical value properly fits with the computed data with small differences between the different cases. Note that the mean pressure value is similar in the cases with an equal number of cells (Cases 1 and 3 and Cases 2 and 4), in which the mass of particles is also the same (see Table 3). Fig. 4(b) shows the standard deviation of the pressure measurements. It can be observed that, for a fixed time step, the standard deviation decreases when the number of computational cells increases. These differences are larger in the case of the largest time step ( $10^{-3}$  s). The reduction in the standard deviation could be related with an increase in the bubble size with a coarser mesh. With a lower spatial resolution, the fraction of particles within a bubble is higher, and this provokes that the bubbles growth in size for the same excess air flow over minimum fluidization conditions.

To check the independence of the numerical results from the time step and the mesh, the data for Cases 4a and 4b are also plotted in Fig. 4(b). It can be observed that the standard deviation of the pressure fluctuation in Cases 4a and 4b are similar to the values obtained in Case 4. Thus, reducing the numerical time step below  $10^4$  s and increasing the number of cells over  $10^5$  elements did not improve the numerical results but augmented the computational cost. Regarding the time step influence, when comparing Case 4a and Case 4, the maximum discrepancy between the

standard deviation of pressure was 2.3% (at  $H_{bed} = 8$  cm), whereas the computational cost at Case 4a was approximately 450 % higher than Case 4. Regarding the influence of the grid size, when comparing Case 4b and Case 4, the standard deviation of pressure was similar, obtaining maximum discrepancies close to 1.8%.

Fig. 5 shows the PSD of pressure measurements at two different heights in the bed ( $z = 7$  cm and  $z = 13$  cm). The procedure to obtain the PSD is similar to that reported in [12], and is described in more detail in Section 4.1. In general, it can be observed that Cases 1 and 2 present one dominant peak in the spectrum, whereas Cases 3 and 4 present peaks with more energy for frequencies over 2.5 Hz. In general, for frequencies higher than 3Hz, Case 4 shows larger peaks, which are not detected in the other cases, except a large peak detected in Case 3 at 5.75Hz for both heights. The high peaks observed in the Case 4 at large frequencies could be related with the combination of a small mesh size and time step of this case. The small mesh size may not filter the perturbations propagation, as occurs in higher mesh sizes, and the small time step could detect the high frequency fluctuations of the pressure, which are not observed or mitigated with a higher time step.

Fig. 6 compares the bubble frequency along the height of the bed for two different radial positions, at the central axis of the bed (Fig. 6a) and Fig. 6(b)) and at a radial position of 0.8R (Fig. 6b) and Fig. 6(d)). This bubble frequency was calculated considering that a bubble is passing at a given point if the particle volume fraction at this point falls below a threshold value. Figs. 6(a) and 6(b) show the data obtained for a threshold ( $th$ ) in the particle fraction obtained as the mean value at each point,  $th = \bar{\theta}_p$ , and Figs. 6(c) and 6(d) with a value of  $th$  of 0.3. The mean value  $\bar{\theta}_p$  was calculated as the mean value over the 58 s of the simulations, as the two first seconds were discarded, resulting in  $\bar{\theta}_p \approx 0.5$ . The  $th$  value selected to detect bubbles in fluidized beds varies in the literature. Acosta-Iborra et al. [12] performed a sensibility analysis of the  $th$  value for the same case studied in this work and observed that the number of bubbles and the chord lengths decreased when  $th$  decreases. They finally assumed  $th = \bar{\theta}_p$ , which has the advantage of being adaptive for each bed regime. Other works [36,38] used  $th = 0.3$ . There are no great differences between the four cases. Only in Fig. 6(b) can it be clearly observed that Cases 3 and 4 (with the

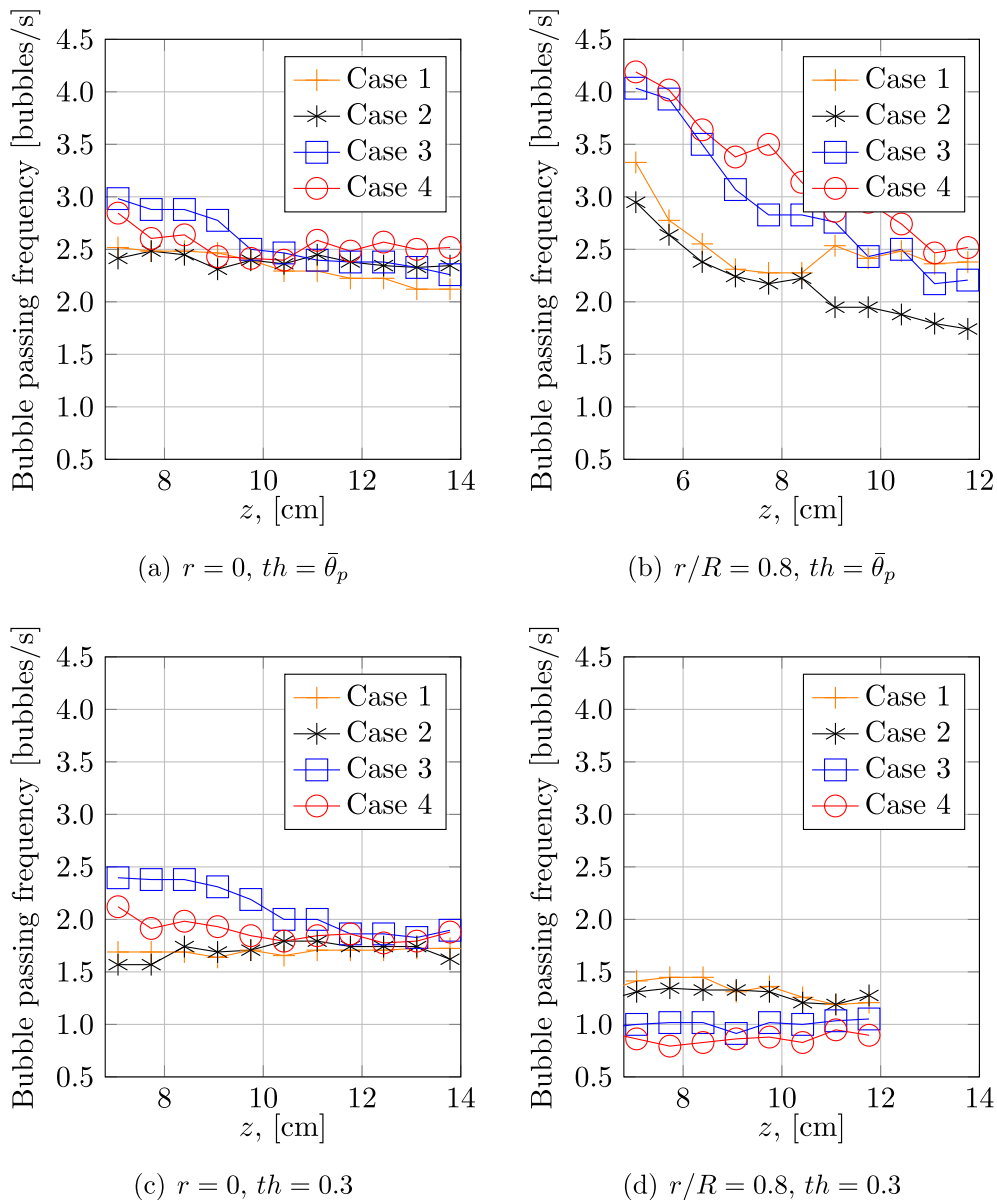


Fig. 6. Comparison of bubble frequency at different radial positions  $r = 0$  and  $r = 0.8R$  for two different values of the threshold of the particle fraction used to detect the bubbles in the CPF-D-Barracuda simulations.



lowest time step,  $10^{-4}$  s) predict higher bubble frequency, especially close to the bed bottom. With a  $th = 0.3$ , the bubble frequency is always smaller in comparison with the bubble frequencies obtained with the mean  $th = \bar{\theta}_p \approx 0.5$ , especially for the case at  $r = 0.8R$ . These results coincide with the numerical results of Acosta-Iborra et al. [12], as the number of bubbles detected increases when  $th$  is augmented. In the four cases studied, the bubble frequency decreases along the bed height due to the bubble coalescence, so at higher heights in the bed the number of bubbles is reduced and their size increases.

In accordance with the aforementioned results, Case 4 was selected in the comparison analysis of the CPF-D-Barracuda results with the main experimental and the numerical results obtained by Acosta-Iborra et al. [12]. For the cases with the lowest time step (Cases 3 and 4), more frequency peaks were detected. Moreover, Cases 1 and 2 were discarded because they detected peaks of energy for frequencies slightly different to the other cases. It is worth noting that Cases 3 and 4 showed similar results for the frequencies of the spectrum and bubble frequency, although Case 4 detected peaks at frequencies higher than 5.75 Hz and showed less  $e_{\text{mass}}$  (-1.15% for Case 3 and 0.26% for Case 4). Moreover, although the number of computational cells in Case 4 was approximately 100% higher than in Case 3, the computational cost was not exceptionally high, thus finding this case adequate to show accurate results. Cases 4a and 4b are discarded due to their higher computational cost without improving the accuracy of the results.

## 4. Results

Fig. 7 shows snapshots of the evolution of the particle volume fraction in the bed over 0.9 s starting from  $t = 10$  s. The snapshots clearly show different bubbles (regions of low particle concentration) ascending along the bed height and erupting at the bed surface. At  $t = 10$  s, close to the bed surface, there is a chain of bubbles, which erupt at the bed surface at  $t = 10.1$  s. The bubble eruption causes a large projection of particles over the free surface, which are clearly observed from  $t = 10.2$  s up to  $t = 10.4$  s. When two or more bubbles coalesce at the bed surface, the velocity of the projected particles are notably increased [43]. They are projected either from the dome of the leading bubble or from the wake of the trailing bubble. A similar behaviour is observed in the second half of the period, between  $t = 10.5$  s and  $t = 10.9$  s. a chain of bubbles ascends and coalesces until reaching the bed surface, where it projects the solids.

### 4.1. Frequency analysis

Figs. 8 and 9 show, respectively, the time evolution of the pressure fluctuations and the particle fraction (or, equivalently, the optical signal) obtained at  $r/R = 0.8$  and  $z = 12$  cm. Both figures show the experimental (black solid line) and numerical results carried out with TFM-Fluent by Acosta-Iborra et al. [12] (red dotted line) and the ones obtained in this work with CPF-D-Barracuda (blue shaded line). In particular, Fig. 8 shows the pressure fluctuations over the mean pressure, i.e.  $p - \bar{p}$ , and it can be clearly observed that the amplitude of the experimental values are much higher than that of the two numerical models. In the experimental data, there are fluctuations up to 1 kPa, whereas in the numerical simulations these fluctuations are less than 0.5 kPa. Fig. 9(a) shows the signal in volts acquired using optical probes which is related to the local particle fraction in the bed at the measurement point. When a bubble passes in front of the probe the reflected light is lower than the reflected light by the emulsion phase (high concentration of particles) and the voltage falls rapidly [44]. Separately, due to the scale difference, Fig. 9(b) represents the time evolution

of the solid fraction  $\theta_p$  obtained at the same sampling point with TFM-Fluent and CPF-D-Barracuda. A qualitative comparison indicates that experimental measurements detect more fluctuations of high frequency than the numerical simulations. These fluctuations are related to the random noise present in any experimental measurement. The particle fraction in both the TFM-Fluent and the CPF-D-Barracuda simulations are practically invariable, with a value of approximately 0.54, excepting when a bubble pierces the sampling point, which is clearly observed as a large reduction in  $\theta_p$ .

The PSD of the absolute and differential pressure measurements and local particle volume fraction were obtained to analyse the bed dynamics. The sub-spectral densities of data were averaged to reduce their variance [45,12]. The analysis of the numerical results obtained from CPF-D-Barracuda were pre-processed following the methodology proposed by Acosta-Iborra et al. [12]. More specifically, the PSD were obtained with the average spectrum from eight consecutive sections of the signal with 50% overlapping and a Hamming window to smooth the signal at the section endpoints.

Fig. 10 compares the results of the normalized PSD obtained from absolute (i.e. manometric) and differential pressure signals reported by Acosta-Iborra et al. [12] from experimental data and from TFM-Fluent numerical simulations, together with the new values obtained with CPF-D-Barracuda. Note that the absolute pressure data are representative of the global behaviour of the bed, which is primarily affected by the level fluctuations of the bed surface due to bubble bursting. In contrast, the signal of a pressure difference is indicative of the bubble passing frequency at a given point, which is representative of the local bed dynamics at that point.

Figs. 10(a) and 10(b) show the global behaviour of the bed by means of the PSD obtained from the absolute pressure data at two different heights from the distributor:  $z = 7$  cm and  $z = 12$  cm. On first glance, at  $z = 12$  cm, the PSD from absolute pressure signals obtained with CPF-D-Barracuda contains the largest peaks of the spectrum at low frequencies (below 2 Hz), which is not observed in both the experimental results and the TFM-Fluent simulation. These low frequency peaks of the CPF-D-Barracuda results are also observed in the PSD obtained at  $z = 7$  cm (Fig. 10(a)). However, the low frequency peaks do not appear in the PSD of the differential pressure signals from the CPF-D-Barracuda simulation, as shown in Fig. 10(c) at  $z = 12.5$  cm. This differential pressure signal was calculated as the difference between the absolute pressure signal at  $z = 13.0$  and 12.0 cm. A similar behaviour is observed with TFM, as the dominant frequency for absolute pressure signals (Figs. 10(a) and 10(b)) is lower than the predicted from differential pressure data (Fig. 10(c)). This fact suggests that these low frequency peaks could be related to the level oscillations of the free surface of the bed, which are observed in the PSD of absolute pressure signal with CPF-D-Barracuda and TFM-Fluent, but not in the differential pressure signal. In addition, the bubble frequency in the center of the bed at  $z = 7$  cm (Fig. 10)) and  $z = 12$  cm (Fig. 10(b)) in CPF-D-Barracuda is 2.5 Hz, whereas it is 4.4 Hz for TFM-Fluent. The higher bubble frequency (and consequently larger number of bubbles erupting at the bed surface) in TFM-Fluent is in concordance with the higher frequencies observed in Figs. 10(a) and 10(b).

Table 4 summarizes the main frequencies of the PSD observed in Fig. 10 at  $z = 12$  cm. The main peak of the PSD obtained from the experimental signal of absolute pressure is 2.7 Hz, slightly different to the natural frequency of the bed, 2.1 Hz, as shown in Acosta-Iborra et al. [12]. The results from CPF-D-Barracuda at  $z = 12$  cm have a frequency peak at 3.1 Hz, which is quite close to the 2.7 Hz peak of the experiments. However, as mentioned before, the PSD of the absolute pressure from the CPF-D-Barracuda also shows a main peak at lower frequencies (i.e.

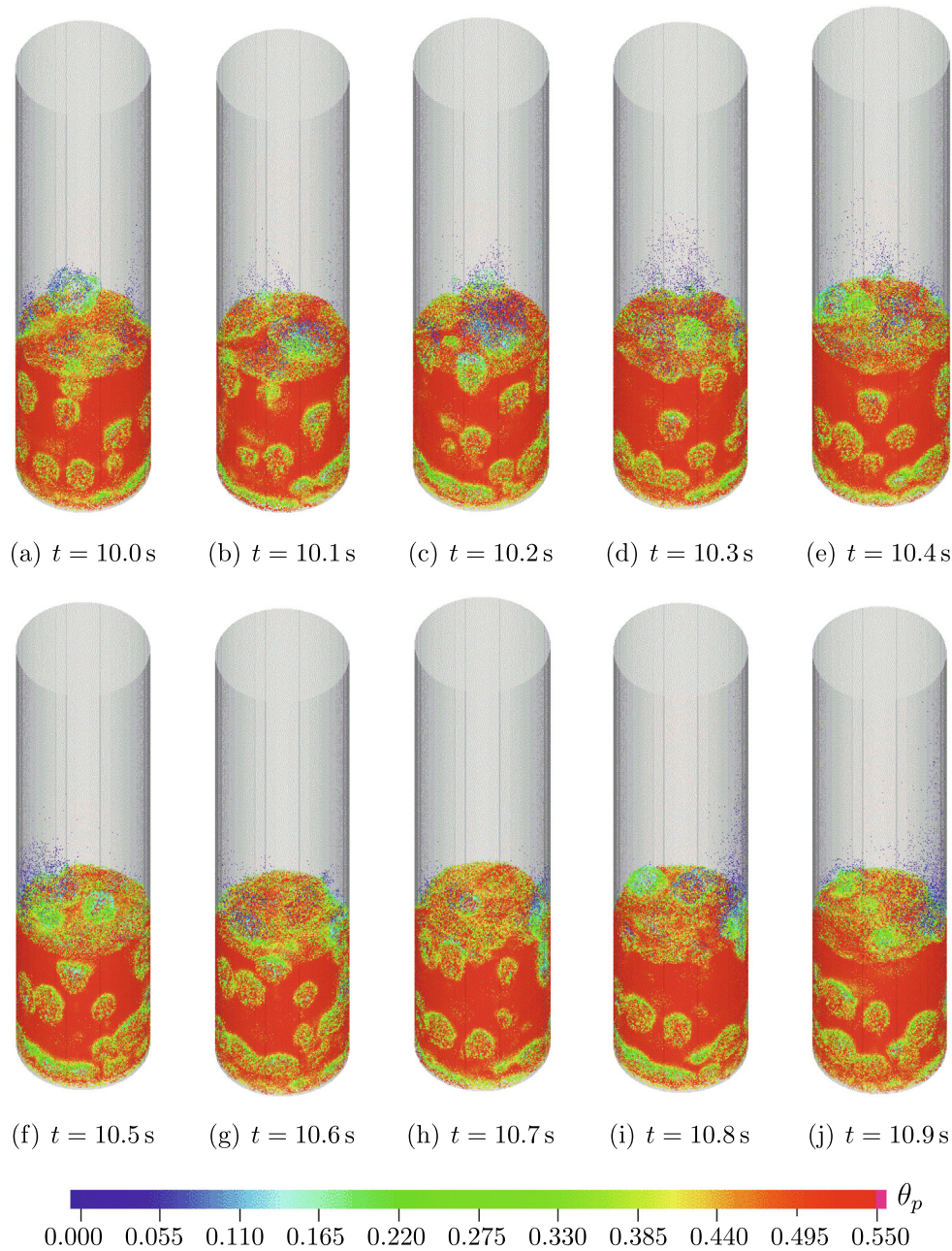


Fig. 7. Snapshots of particle volume fraction  $\theta_p$  evolution between  $t = 10.0\text{ s}$  and  $t = 10.9\text{ s}$  obtained with CPF-D-Barracuda.

1.3 Hz). This main frequency is close to the experimental result. The TFM-Fluent simulation yields a main frequency of the absolute pressure of 3.4 Hz, which is slightly higher than that from CPF-D-Barracuda. These discrepancies could be related with the higher bubble frequency predicted by TFM-Fluent, as commented in the previous paragraph.

Figs. 10(c) and 10(d) show the PSD obtained from differential pressure and particle volume fraction, respectively. In both cases, the PSD obtained with CPF-D-Barracuda has a very reduced contribution of frequencies over 7 Hz, compared to that in the experiment and the TFM-Fluent spectra. This is arguably due to the way CPF-D-Barracuda obtains the particle volume fraction. As CPF-D-Barracuda simulates discrete particles or clouds, this discrete information has to be spatially filtered to be transformed into a continuous field of particle volume fraction for each computing cell

[46]. In particular, CPF-D-Barracuda calculates the Particle Volume Fraction in an Eulerian cell using linear interpolation functions that takes into account the cells adjacent to the location of the computational particle or cluster [20]. This transformation could reduce the high frequencies in the resulting PSD of particle volume fraction.

The main frequencies of the differential pressure spectrum and the particle volume fraction (or optical signal) spectrum are listed in Table 4. The first frequency peak  $f_{dif,1}$  in terms of intensity in the PSD of differential pressure, excluding the frequency peaks coincident to those of the absolute pressure spectrum, appears at 6.3 Hz in the experiments and at 6.1 Hz in the TFM-Fluent simulation. In the CPF-D-Barracuda simulation,  $f_{dif,1}$  is located at the lower, but relatively close, frequency of 4.8 Hz. As expected, the results for the frequency peak with the second largest intensity,  $f_{dif,2}$ , are

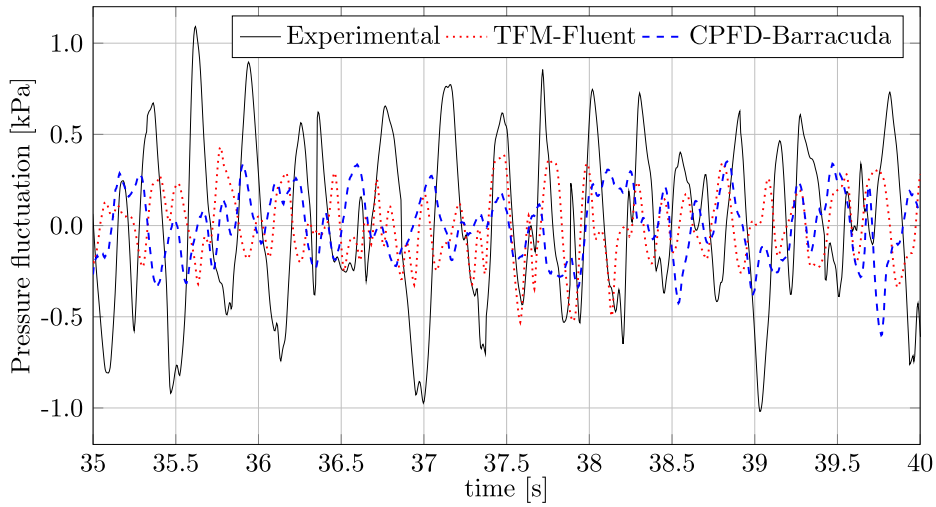
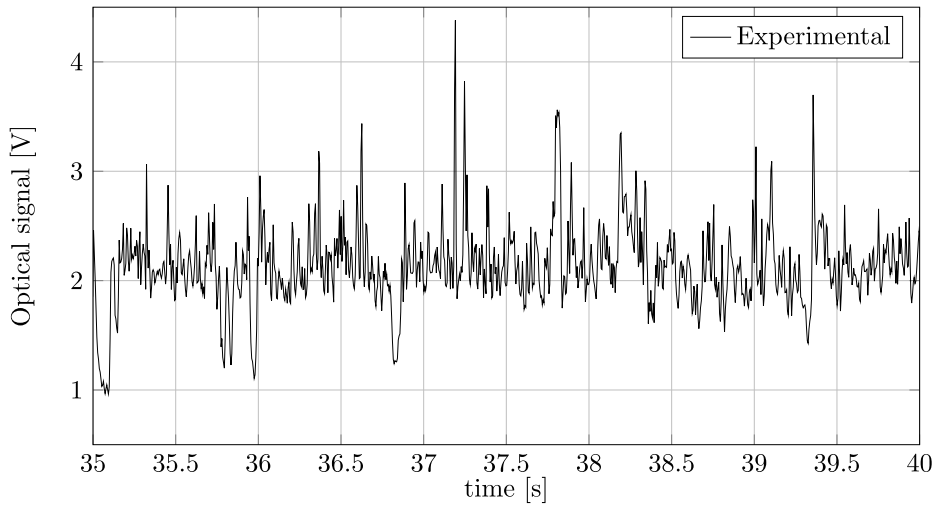
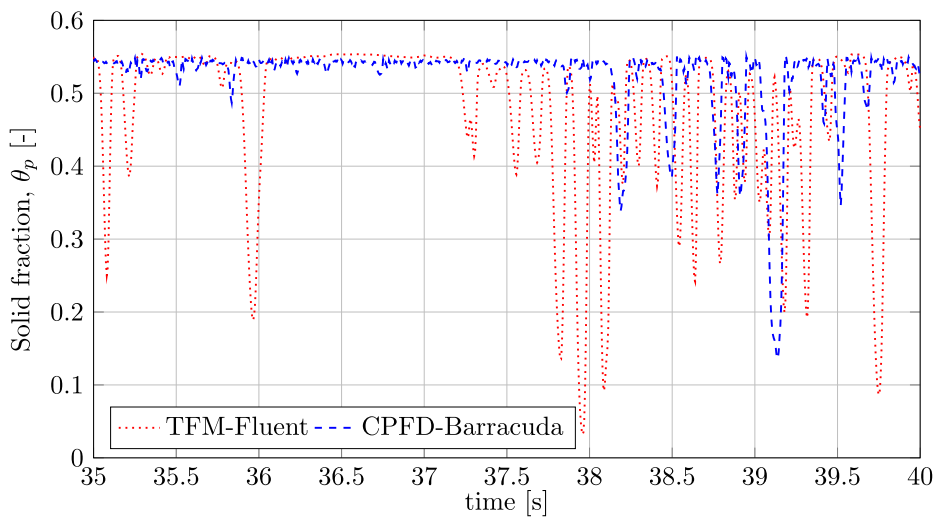


Fig. 8. Pressure fluctuation over the mean value ( $p - \bar{p}$ ) during 5 s at  $z = 12$  cm and  $r/R = 0.8$ .

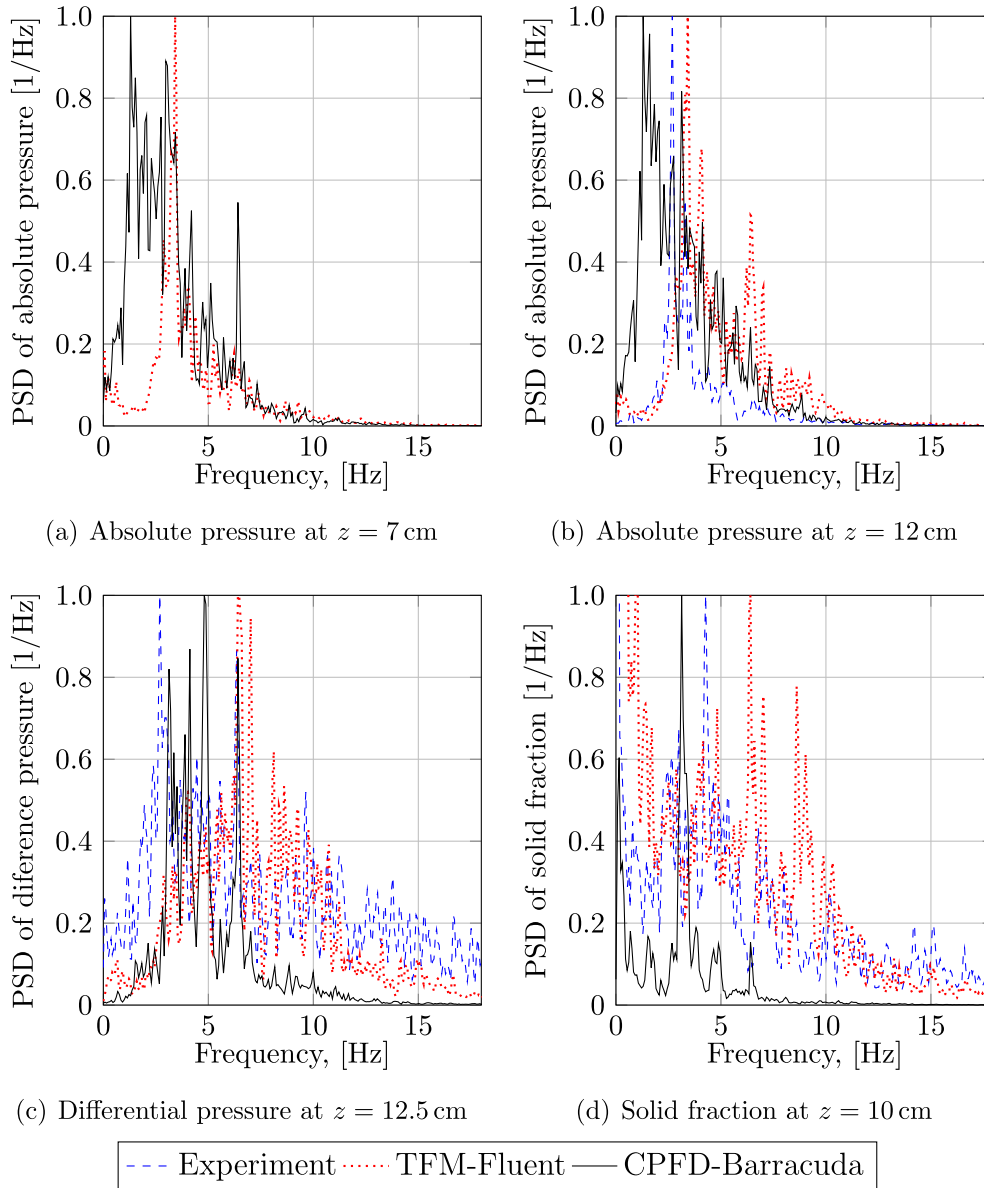


(a) Experimental optical signal



(b) Numerical solid fraction

Fig. 9. Optical signal experimentally measured [12] during 5 s (a) and solid fraction numerically obtained (b) at  $z = 12$  cm and  $r/R = 0.8$ .



**Fig. 10.** Normalized PSD obtained from experimental results [12] (dashed blue lines), from TFM Fluent [12] (dotted red lines) and from CPF-D-Barracuda (solid black lines). Figures (a) and (b) show the data obtained from absolute pressure at  $z = 7$  and  $z = 12$  cm, respectively, Figure (c) the data obtained from differential pressure at  $z = 12.5$  cm and Figure (d) the data obtained from particle fraction at  $z = 10$  cm. All the data were obtained in the centre of the bed ( $r/R = 0$ ).

**Table 4**  
Main peaks obtained from the different PSD shown in Fig. 10.

	Experiments	TFM-Fluent	CPF-D-Barracuda
Absolute pressure			
$f_d$ [Hz]	2.7	3.4	3.1
Differential pressure			
$f_{dif,1}$ [Hz]	6.3	6.5	4.8
$f_{dif,2}$ [Hz]	4.5	8.1	6.4
Optical signal or particle volume fraction			
$f_{opt,1}$ [Hz]	6.8	6.4	3.1
$f_{opt,2}$ [Hz]	4.3	8.0	1.5

more scattered. While the differential pressure signal from the experiment yields  $f_{dif,2} = 4.5$  Hz, this value is  $f_{dif,2} = 6.4$  Hz in the CPF-D-Barracuda simulations and reaches  $f_{dif,2} = 8.1$  Hz in the case of the TFM-Fluent simulation. An analogous situation occurs for the particle volume fraction, as shown in Table 4. The first peak

of the spectrum of the particle volume fraction  $f_{opt,1}$  obtained from the CPF-D-Barracuda simulation is 3.1 Hz, which is nearly half that from the experimental optical signal (6.8 Hz) and from the particle volume fraction simulated with TFM-Fluent (6.4 Hz). In the CPF-D-Barracuda simulation,  $f_{opt,1}$  is nearly 40% smaller than  $f_{dif,1}$ , and this difference is higher than in the experimental and TFM model results. This also happens with the second peak of the particle volume spectrum,  $f_{opt,2}$ . The CPF-D-Barracuda simulation leads to  $f_{opt,2} = 1.5$  Hz, which is much smaller than  $f_{dif,2}$  obtained from the same code. This reinforces the hypothesis of high frequency filtering in the particle volume fraction results and the lower bubble frequency from CPF-D-Barracuda.

#### 4.2. Bubble characteristics: pierced length, velocity and frequency

Bubble pierced length, velocity and frequency were calculated from the simulation particle fraction signal and from the optical probe experimental signal. For the detection of bubbles using the



optical probes, when the voltage signal falls below a threshold value, a bubble passage is considered to be occurring. The threshold value was determined by plotting the histogram of the voltage output signal of the optical probes. The histogram exhibits a peak corresponding to the dense phase and a tail corresponding to the gas bubble phase. The bubble detection threshold was defined as the voltage where the histogram tail begins and the slope of the histogram becomes nearly zero. A more detailed explanation can be found in Sobrino et al. [44]. For both simulated and experimental signals, bubble velocity can be calculated dividing the vertical distance between two consecutive virtual or experimental probes by the time the bubble takes to travel from the lower to the upper probe. The bubble pierced length is then calculated by multiplying the bubble rise velocity by the bubble passage time. The bubble passage time is the period during which the particle volume fraction signal or the optical probe signal falls below a given threshold. Further details on the determination of bubble characteristics can be found in [12].

Fig. 11(a) shows the mean pierced length ( $\bar{y}$ ) and the mean bubble velocity ( $u_b$ ) measured at height of  $z = 7.5$  cm for different radial positions in the bed. The results are presented for two threshold values for bubble detection:  $\bar{\theta}_p$  and 0.3. It can be clearly observed that for  $th = 0.3$  the pierced lengths are smaller than for  $th = \bar{\theta}_p$ , as expected. Nevertheless, the variations in  $\bar{y}$  with the threshold value are higher in the TFM-Fluent simulations, with a reduction of approximately 1 cm (from 4 to 3 cm), whereas the reduction in CPF-D-Barracuda is 0.3 cm, approximately. These

results indicate that CPF-D-Barracuda is less sensitive to the threshold value than TFM-Fluent. Regarding bubble velocity (Fig. 11(b)), the CPF-D-Barracuda results are not influenced by the threshold value, except for the region close to the bed wall ( $r/R = 0.8$ ), while in TFM-Fluent, the bubble velocity varied slightly with the threshold (approximately 0.1 m/s). In view of this figure, the arbitrary threshold value selected to define bubble contour in TFM-Fluent can notably influence on the results. As TFM-Fluent models the system as two interpenetrating fluids, the selection of the bubble threshold defines the limit between the bubble and the dense phase. In contrast, CPF-D-Barracuda has the advantage of modeling the motion of groups of particles, and consequently, the numerical results are much less dependent of the selection of an arbitrary threshold value. The transition from the dense to the bubble phase in the TFM is by nature smoother than the lagrangian perspective of CPF-D-Barracuda. Nevertheless, in the procedure to calculate Particle Volume Fraction with CPF-D-Barracuda, it is obtained using linear interpolations factors that takes into account the computational cells adjacent to the location of the computational particle. This fact may smooth also the results. Another important factor that may explain the differences in the threshold sensibility is the differences in the cell size, which are smaller in CPF-D-Barracuda (93296 cells) than in TFM-Fluent (28800 cells). A lower number of cells provokes larger spatial variations in the bubble contour detection when the threshold value is varied.

Fig. 11 shows that in the region closer to the wall ( $r/R = 0.8$ ) CPF-D-Barracuda predicts higher bubble velocities when  $th = \bar{\theta}_p$  is used. This fact is related with the change in the threshold value calculated for this case. For values of  $r/R \leq 0.6$ ,  $\bar{\theta}_p \approx 0.55$ , whereas at  $r/R = 0.8$  this value is reduced to  $\bar{\theta}_p = 0.49$ . The lower value of the average in time particle volume fraction is related with a preferential bubble path in this zone [47]. TFM-Fluent does not predicts an increase of the bubble velocity close to the wall, which could be related with the differences in the boundary conditions in both models. As it is explained in Fig. 1, TFM-Fluent imposes a free-slip condition for the particles, whereas CPF-D-Barracuda uses a coefficient for the normal and tangent momentum retention and diffuse bounce when the particles are in contact with the wall.

According to the results showed in Fig. 11 CPF-D-Barracuda underestimates the experimental results for bubble pierced lengths and velocities. These differences could be related with the drag model used in CPF-D-Barracuda. Pal and Theuerkauf [48] adjusted the model multiplier of Wen-Yu model to make the model more suitable for close packing. These authors observed that there are different optimum coefficients, depending on the particle size and density. TFM-Fluent used Gidaspow drag model. The differences between both models could explain the lower values predicted by CPF-D-Barracuda in comparison with TFM-Fluent.

Compared with experimental data obtained with optical probes, CPF-D-Barracuda, regardless of the threshold value, predicts smaller bubble lengths with smaller bubble velocities. The TFM-Fluent results obtained with the mean threshold are closer to the experiments, but TFM-Fluent is highly influenced by the threshold value selected to determine bubbles in the bed.

Fig. 12 also shows the mean pierced length,  $\bar{y}$  and bubble velocity,  $u_b$ , along the height of the bed for a fixed radial position of  $r/R = 0.8$ . Comparing the results along the bed height, the conclusions are similar to Fig. 11: the mean pierced length obtained for TFM-Fluent is largely influenced by the threshold value and these variations are smaller in CPF-D-Barracuda. Moreover, both models show the pierced length increase with the bed height (see Fig. 12 (a)). Regarding bubble velocity (Fig. 12(b)), it is less influenced by the threshold value in both numerical models. TFM-Fluent overpredicts the experimental data and predicts an increase in the bubble velocity along the bed height, as also observed for the

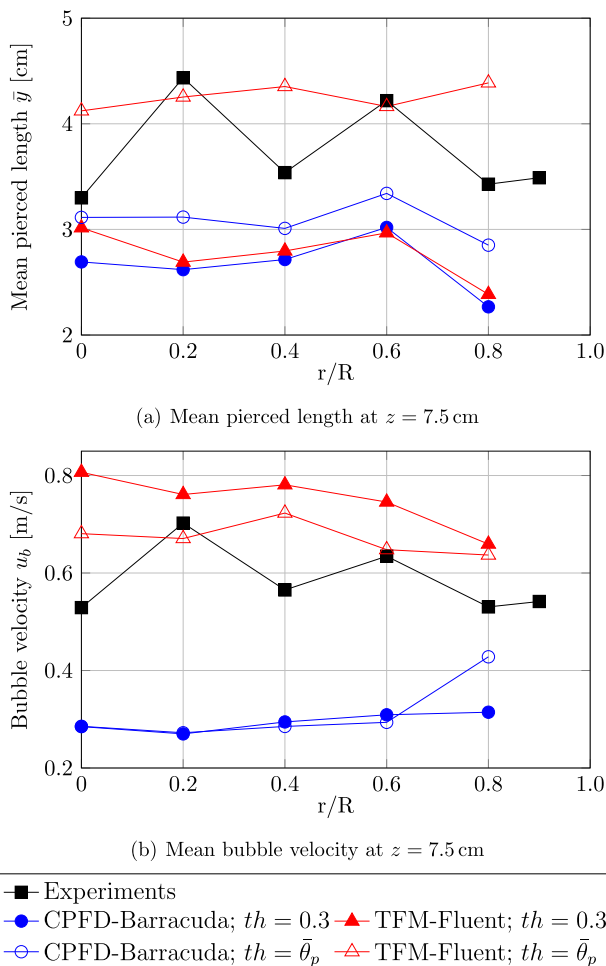
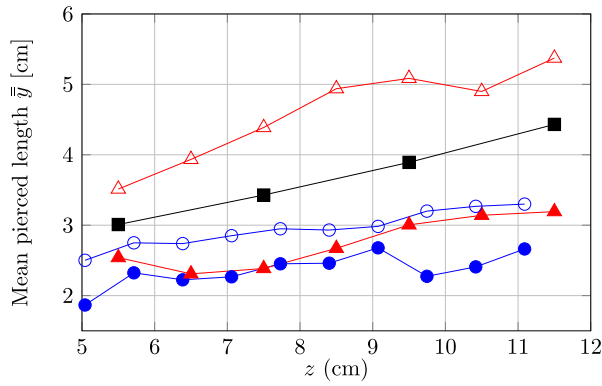
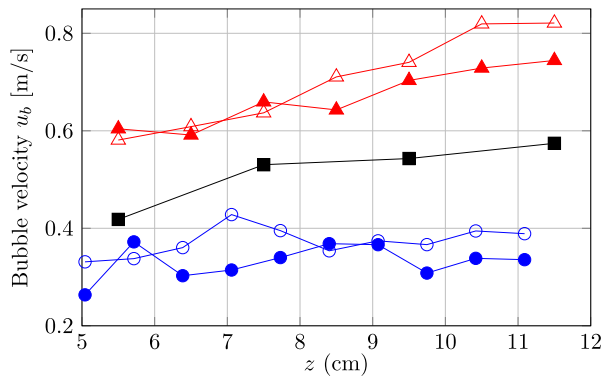


Fig. 11. Time averaged pierced length (a) and bubble velocity (b) for different radial positions in the bed at  $z = 7.5$  cm.



(a) Mean pierced length at  $r/R = 0.8$



(b) Mean bubble velocity at  $r/R = 0.8$

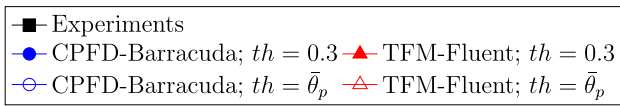


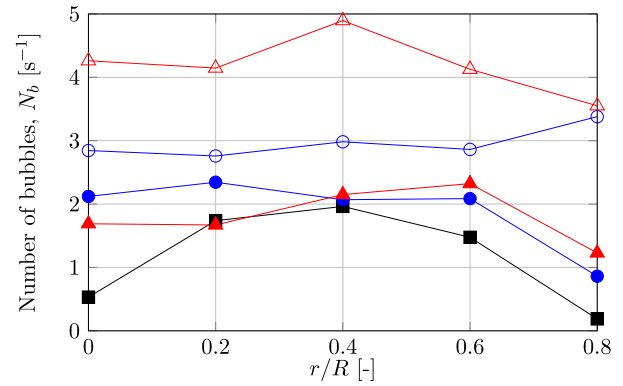
Fig. 12. Time averaged pierced length (a) and bubble velocity (b) for different heights in the bed at  $r/R = 0.8$ .

experiments, while CPFD-Barracuda obtains lower values and shows and almost constant bubble velocity with the bed height. A cause of these distinct behaviour in bubble velocity observed in the simulations can be the drag model employed in CPFD-Barracuda (Wen-Yu) and TFM-Fluent (Gidaspow).

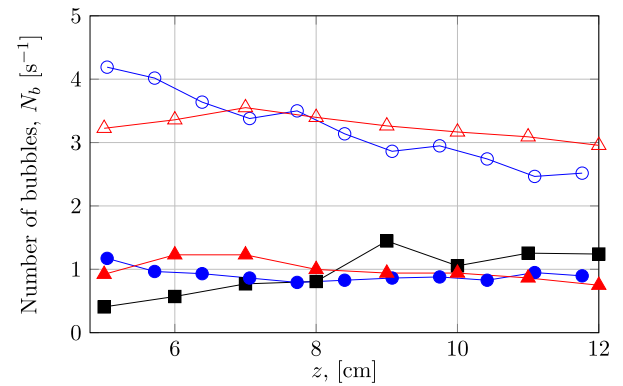
Finally, the number of bubbles per second (bubble frequency) detected is shown in Fig. 13. Fig. 13(a) shows the radial variation at a height of  $z = 7$  cm from the distributor and Fig. 13(b) shows the variation with height for a radial position  $r/R = 0.8$ , for the experimental and numerical results considering a threshold value calculated as the mean in each point and  $th = 0.3$ . In Fig. 13(b) the two numerical models present similar results for the same threshold value, although the numerical data obtained with the mean threshold tend to overestimate the experimental results. A threshold of  $th = 0.3$  obtains numerical results closer to the experiments. Regarding the radial distribution (Fig. 13(a)), the experimental results indicate there are more bubbles in the region  $0.2 < r/R < 0.6$  and fewer in the centre of the bed ( $r/R = 0$ ) and close to the wall ( $r/R = 0.8$ ). CPFD-Barracuda and TFM-Fluent also reduce the bubble frequency close to the bed wall, although they present a higher number of bubbles in the centre of the bed than in the experiments.

### 4.3. Equivalent volume bubble diameter

Fig. 14 shows the Probability Density Functions (PDF) for the pierced length,  $y$ , the volume equivalent bubble diameter  $D_v$  and



(a)  $z = 7$  cm



(b)  $r/R = 0.8$

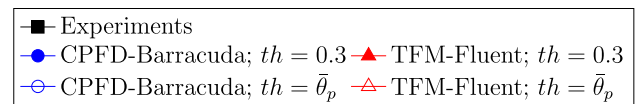


Fig. 13. Number of bubble per second detected for different radial positions at  $z = 7$  cm (a) and for different heights at  $r/R = 0.8$  (b).

the bubble velocity  $u_b$ . The PDFs were obtained using the maximum entropy method [49,44]. This method has been used to obtain the PDF of  $y$  and  $u_b$  and a continuous distribution of the bubble size  $D_v$  in a two-phase system from pierced lengths, assuming a bubble geometry. Santana et al. [49] applied this method to gas bubbles in water with an ellipsoidal geometry. Later, Sobrino et al. [44] extended this method for bubbling fluidized beds, assuming a truncated oblate ellipsoidal bubble and applied to both pressure and optical experimental signals. The reader is referred to these works for a detailed description and numerical implementation of the Maximum Entropy Method, which is beyond the scope of this work.

The PDF is presented for two heights ( $z = 7.5$  cm and  $9.5$  cm) for a threshold  $th = \bar{\theta}_p$  to determine the pierced lengths and bubble velocities in TFM-Fluent and CPFD-Barracuda. The shape of the PDFs obtained with  $th = \bar{\theta}_p$  for TFM-Fluent and CPFD-Barracuda are similar to the experimental ones, although CPFD-Barracuda predicts slightly smaller pierced lengths and diameters and less wide distributions than the experiments. Overall, pierced length, diameter and bubble velocity distributions predicted by CPFD-Barracuda are smaller than the experimental and TFM-Fluent results.

Fig. 15 shows the mean value and the standard deviation of  $D_v$  along the bed height for a radial position  $r/R = 0.8$ . The results are similar to those shown in Fig. 12(a) for pierced lengths, as the volume equivalent bubble diameter is inferred from pierced lengths. It

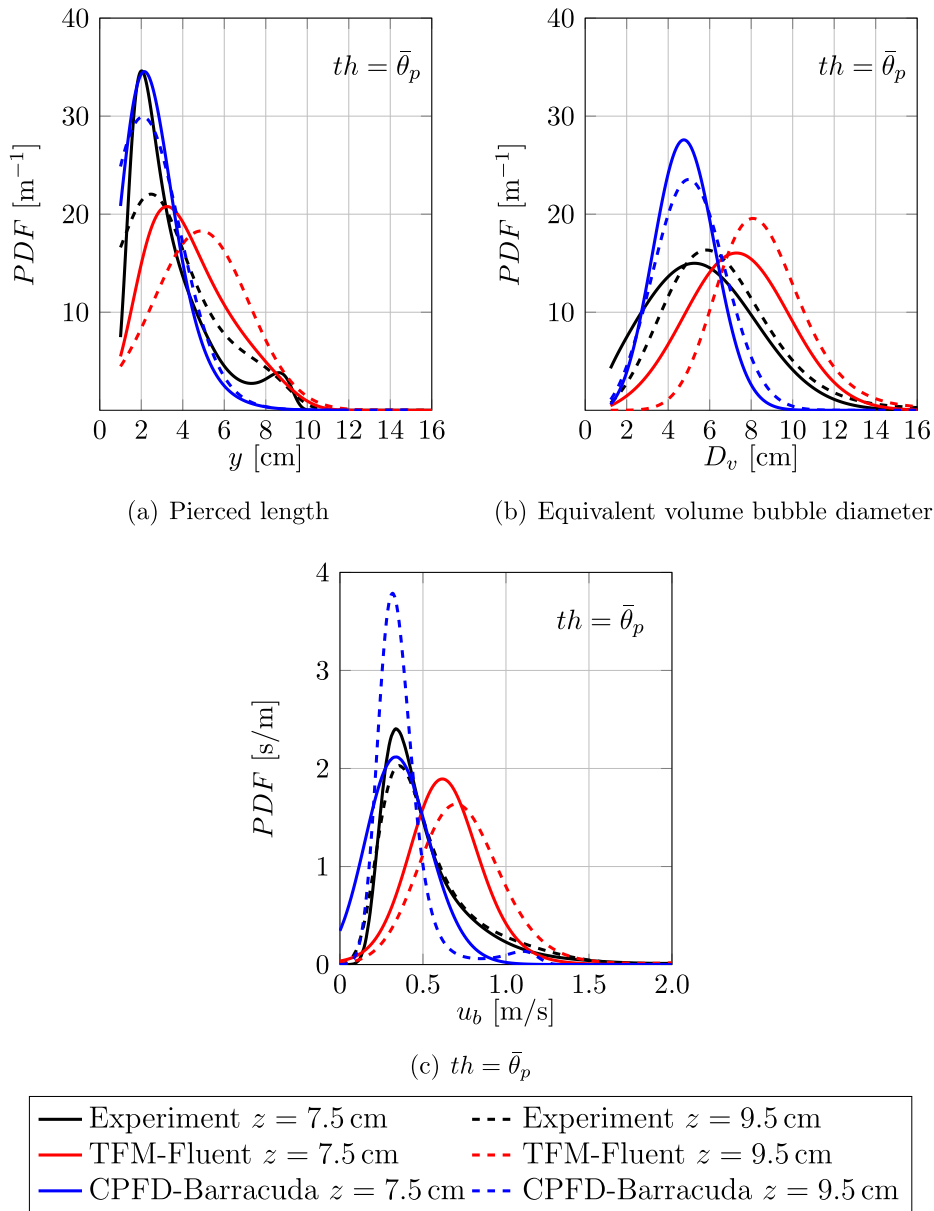


Fig. 14. Probability density function of the pierced length (a), of the equivalent volume bubble diameter (b) and of the bubble velocity (c) at  $r/R = 0.8$  for different heights.

can be observed that CPF-D-Barracuda underpredicts the experimental bubble size, whereas TFM-Fluent overpredicts this value. The same figure shows the mean pierced lengths,  $\bar{y}$  obtained from CPF-D-Barracuda, for a threshold  $th = \bar{\theta}_p$  and the correlation proposed by Agarwal [50], which is in close agreement with the CPF-D-Barracuda results. Karimipour and Pugsley [51] and Rüdüsüli et al. [52] reported that the mean value of the bubble equivalent diameter can be computed as 1.744 times the mean values of the pierced lengths. This is well in line with the Agarwal correlation and CPF-D-Barracuda results.

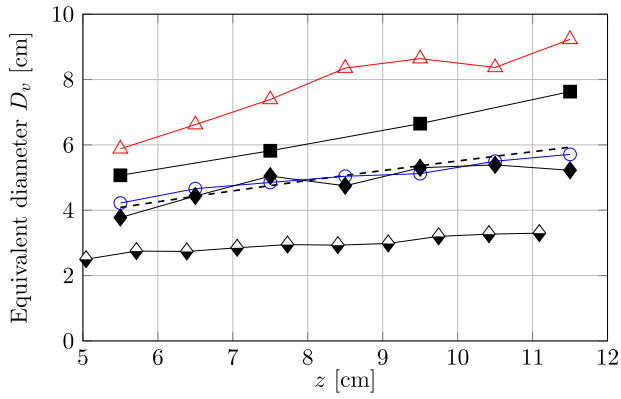
The standard deviation of  $D_v$  along the bed height is shown in Fig. 15(b). It can be observed that the CPF-D-Barracuda results predict smaller standard deviation of the bubble size distribution than the experiments and TFM-Fluent, which both present similar values. However, the CPF-D-Barracuda results show a monotonic increase in the standard deviation with height, which is also revealed in the experiments, while the standard deviation remains more approximately constant for TFM-Fluent simulation. As it was commented previously in Section 4.2, at  $r/R = 0.8$  CPF-D-Barracuda

predicts a preferential path of the bubbles in the bottom of the bed ( $z \leq 7$  cm), in which there is a chain of bubbles of similar sizes. This justifies the lower values of the standard deviation in this zone.

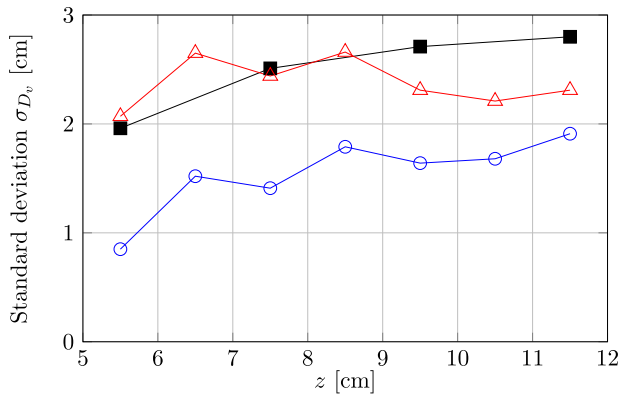
### 5. Conclusions

The analysis carried out in this work, comparing CPF-D-Barracuda and TFM-Fluent simulations as well as experimental data, reveals that the threshold value of the particle fraction selected for detecting and demarcate bubble borders in fluidized beds notably affects the mean pierced length of the bubbles simulated by TFM-Fluent. However, the influence of the selected threshold in  $\bar{y}$  is much smaller for CPF-D-Barracuda simulations. The bubble frequency also varies with the threshold value. In this case, both simulation models yield bubble frequencies around  $1 \text{ s}^{-1}$  for  $th = 0.3$ , while they lead to frequencies around  $3 - 4 \text{ s}^{-1}$  for  $th = \bar{\theta}_p$ .

The spectra of absolute pressure, differential pressure and particle volume fraction obtained with CPF-D-Barracuda resemble



(a) Mean value of the equivalent volume bubble diameter



(b) Standard deviations of the equivalent volume bubble diameter

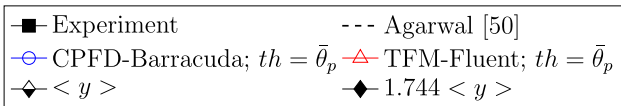


Fig. 15. Mean value (a) and standard deviation (b) of the bubble size for different bed heights at  $r/R = 0.8$ .

those from the experiments and the TFM-Fluent simulations, but with a larger contribution of lower frequencies. The peaks of the spectrum of particle volume fraction from CPF-D-Barracuda are located at lower frequencies than the differential pressure ones. This suggests a high frequency filtering in the particle volume fraction results from CPF-D-Barracuda.

The PDF obtained with both numerical models for  $\bar{y}$  and  $D_v$  and  $u_b$  with  $th = \bar{\theta}_p$  are similar to those obtained experimentally, although the CPF-D-Barracuda distributions are closer to the experimental ones than the TFM-Fluent distributions. The equivalent diameter and velocities of the bubbles calculated with  $th = \bar{\theta}_p$  by TFM-Fluent are higher than the experimental ones, while those calculated by CPF-D-Barracuda are lower. In general, for the experimental conditions of this work, CPF-D-Barracuda predicts smaller bubbles with lower velocities than TFM-Fluent.

The above results show that CPF-D-Barracuda is, in general, able to predict the behaviour of bubbling beds with reasonable accuracy and with a computational cost of, approximately, 30 h to simulate 60 s of real time operation.

6. Notation

- CFL Courant-Friedrichs Lewy
- $C_d$  Gas-particle drag coefficient
- CFD Computational fluid dynamics

- CPFD Computational particle fluid dynamic
- DEM Discrete element models
- $D_p$  Drag function
- $D_v$  Volume equivalent bubble diameter
- $D_{wy}$  Wen-Yu model drag force
- $d_p$  Particle diameter
- $e_{mass}$  Error in the initial mass
- $F$  Momentum exchange rate per volume between gas and particles
- FCC Fluid catalytic cracking
- $F_p$  Drag force exerted on the particle
- $H_{bed}$  Initial bed height
- $m_p$  Mass of the particle
- $m_{sim}$  Simulated initial particle mass
- $m_{theo}$  Theoretical initial particle mass

MP – PIC Multiphase particle in cell

- $p$  Pressure
- $P_s$  Pressure constant
- PDF Probability density function
- PSD Power spectral density
- $R$  Radius of the bed
- $R_g$  Gas constant
- $Re$  Reynolds number
- $T$  Absolute temperature
- TFM Two-fluid models
- $th$  Threshold
- $u_b$  Time averaged bubble velocity
- $u_f$  Fluid velocity
- $u_p$  Particle velocity
- $u_{mf}$  Minimum fluidization velocity
- $V_p$  Particle volume
- $y$  Pierced length
- $\bar{y}$  Mean pierced length

6.1. Greek symbols

- $\tau_p$  Stress tensor
- $\theta_p$  Particle volume fraction
- $\bar{\theta}_p$  Average particle volume fraction
- $\beta$  Constant
- $\theta_{cp}$  Particle volume fraction at close packing
- $\varepsilon$  Constant
- $\mu_f$  Dynamic fluid viscosity
- $\rho_f$  Fluid density
- $\rho_p$  Particle density
- $\Psi_p$  Sphericity
- $\theta_f$  Fluid volume fraction
- $\bar{\theta}_p$  Time averaged particle volume fraction
- $\tau_f$  Viscous stress term

Declaration of Competing Interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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