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Discrete Optimization

A branch-and-price approach for the continuous multifacility monotone ordered median problem

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ABSTRACT

In this paper, we address the Continuous Multifacility Monotone Ordered Median Problem. The goal of this problem is to locate p facilities in \mathbb{R}^d minimizing a monotone ordered weighted median function of the distances between given demand points and its closest facility. We propose a new branch-and-price procedure for this problem, and three families of matheuristics based on: solving heuristically the pricer problem, aggregating the demand points, and discretizing the decision space. We give detailed discussions of the validity of the exact formulations and also specify the implementation details of all the solution procedures. Besides, we assess their performances in an extensive computational experience that shows the superiority of the branch-and-price approach over the compact formulation in medium-sized instances. To handle larger instances it is advisable to resort to the matheuristics that also report rather good results.

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1. Introduction

In the last years, a lot of attention has been paid to the discrete aspects of location theory and a large body of literature has been published on this topic (see, e.g., Beasley, 1985; El-loumi, Labbé, & Pochet, 2004; Espejo, Marín, Puerto, & Rodríguez-Chía, 2009; García, Labbé, & Marín, 2010; Marín, Nickel, Puerto, & Velten, 2009; Marín, Nickel, & Velten, 2010; Puerto, Ramos, & Rodríguez-Chía, 2013; Puerto & Tamir, 2005). One of the reasons of this flourish is the recent development of integer programming and the success of MIP solvers. In spite of that, the reader might notice that the mathematical origins of this theory emerged very close to some classical continuous problems such as the well-known Fermat-Torricelli or Weber problem, and the Simpson problem (see, e.g., Drezner & Hamacher, 2002; Laporte, Nickel, & Saldanha da Gama, 2015; Nickel & Puerto, 2005). However, the continuous counterparts of location problems have been mostly analyzed and solved using geometric constructions, valid on

the plane and the three dimensional space, that are difficult to extend when the dimensions grow or the problems are slightly modified to include some side constraints (Blanco & Ǵzquez, 2021; Blanco, Puerto, & Ponce, 2017; Carrizosa, Conde, Muńoz, & Puerto, 1995; Carrizosa, Muńoz Ḿrquez, & Puerto, 1998; Fekete, Mitchell, & Beurer, 2005; Nickel, Puerto, & Rodŕguez-Chía, 2003; Puerto & Rodŕguez-Chía, 2011). These problems, although very interesting, quickly fall within the field of global optimization and they become very hard to solve. Even those problems that might be considered easy, as for instance the classical Weber problem with Euclidean norms, are most of the times solved with algorithms (as the Weiszfeld algorithm, Weiszfeld, 1937), whose convergence is still unknown (Chandrasekaran & Tamir, 1989). Moreover, most problems studied in continuous location assume that a single facility is to be located, since their multifacility counterparts lead to difficult non-convex problems (Manzour-al Ajdad, Torabi, & Eshghi, 2012; Blanco, 2019; Blanco, ElHaj BenAli, & Puerto, 2014; Brimberg, 1995; Carrizosa et al., 1998; Mallozzi, Puerto, & Rodŕguez-Madrena, 2019; Puerto, 2020; Rosing, 1992; Valero-Franco, Rodŕguez-Chía, & Espejo, 2013).

Motivated by the recent advances on discrete multifacility location problems with ordered median objectives (Deleplanque, Labbé, Ponce, & Puerto, 2020; Espejo, Puerto, & Rodŕguez-Chía,

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2021; Fernández, Pozo, & Puerto, 2014; Labbé, Ponce, & Puerto, 2017; Marín, Ponce, & Puerto, 2020), and the available results on conic optimization (Blanco et al., 2014; Puerto, 2020), we analyze here a family of difficult continuous multifacility location problems with ordered median objectives and distances induced by a general family of norms. These problems gather the essential elements of discrete and continuous location analysis, making their solution a challenging question.

In this paper, we develop an *ad hoc* branch-and-price algorithm for solving this general family of continuous location problems. The continuous multifacility Weber problem has been already studied using branch-and-price methods (Krau, 1997; du Merle, Villeneuve, Desrosiers, & Hansen, 1999; Righini & Zaniboni, 2007; Venkateshan & Mathur, 2015). In addition, in discrete location, these techniques have also been applied to the p -median problem (Avella, Sassano, & Vasilev, 2007, see, e.g.,). However, to the best of our knowledge, a branch-and-price approach for location problems with ordered median objectives has only been developed for the discrete version in Deleplanque et al. (2020) beyond a multisource hyperplanes application (Blanco, Japón, Ponce, & Puerto, 2021).

Our goal in this paper is to analyze the *Continuous Multifacility Monotone Ordered Median Problem* (MFMOMP, for short), in which we are given a finite set of demand points, \mathcal{A} , and the goal is to find the optimal location of p new facilities such that: (1) each demand point is allocated to a single facility; and (2) the measure of the goodness of the solution is an ordered weighted aggregation of the distances of the demand points to their closest facility (see, e.g., Nickel & Puerto, 2005). We consider a general framework for the problem, in which the demand points (and the new facilities) lie in \mathbb{R}^d , the distances between points and facilities are polyhedral- or ℓ_τ -norms for $\tau \geq 1$, and the ordered median functions are assumed to be defined by non-decreasing monotone weights. These problems are analyzed in Blanco, Puerto, & ElHaj BenAli (2016), in which the authors provide a Mixed Integer Second Order Cone Optimization (MISOCO) reformulation of the problem able to solve, for the first time, problems of small to medium size (up to 50 demand points), using off-the-shelf solvers.

The family of problems under analysis has a broad range of applications in different fields. On the one hand, continuous location has been proven to be an adequate tool in case the services to be located are sensors, surveillance cameras, etc., that are allowed to be flexibly positioned in the space. Also, multifacility location problems can be seen as a unified modelling tool to extend classical clustering algorithms, as the k -means or k -median approaches, or more general approaches (Blanco et al., 2021). The use of ordered median objective functions determines, at the same time, the positions of the *optimal* location of the services balancing equity and efficiency of the list of distances from the demand points to their closest facilities (see, e.g., Aouad & Segev, 2019; Calvino, López-Haro, Muñoz-Ocaña, Puerto, & Rodríguez-Chía, 2022; Espejo et al., 2009; Fourour & Lebbah, 2020; Muñoz-Ocaña et al., 2020; Ogryczak, Perny, & Weng, 2011; Olender & Ogryczak, 2019; Tamir, 2001). The connection between discrete location and its continuous counterpart has been a topic of study since the introduction of the continuous problem (Cooper, 1963; Kalczyński, Brimberg, & Drezner, 2021). Thus, the extension of some facility location problems that have been analyzed in a discrete space (voting, exam qualifications, etc.) to the continuous framework, is a topic of interest in the Location Science field (Drezner & Nickel, 2009; Espejo et al., 2009; Ponce, Puerto, Ricca, & Scozzari, 2018). We also refer the reader to Bruno, Genovese, & Improta (2014), Drezner & Hamacher (2002), Love, Morris, & Wesolowsky (1988), Mirchandani & Francis (1990), and the references therein to find more applications in the fields of industry, urban or regional planning, clustering, mobile location, commerce, public service facilities, or transport facilities.

Our contribution in this paper is to introduce a new set partitioning-like (with side constraints) reformulation for this family of problems that allows us to develop a branch-and-price algorithm for solving it. This approach gives rise to a decomposition of the original problem into a master problem (set partitioning with side constraints), and a pricing problem that consists of a special form of the maximal weighted independent set problem combined with a single facility location problem. We compare this new strategy with the one obtained by solving Mixed Integer Nonlinear Programming (MINLP) formulations using standard solvers. Our results show that it is worth using the new reformulation since it allows us to solve larger instances and reduce the gap when the time limit is reached. Moreover, we also exploit the structure of the branch-and-price approach to develop some new matheuristics for the problem that provide good quality feasible solutions for fairly large instances of several hundreds of demand points.

The paper is organized in six sections and two appendixes. Section 2 formally describes the problem considered in this paper, namely the MFMOMP, and develops MISOCO formulations for it. Section 3 is devoted to present the new set partitioning-like formulation and all the details of the branch-and-price algorithm proposed to solve it. There, we present how to obtain initial variables for the restricted master problem, we discuss and formulate the pricing problem and set properties for handling it, and describe the branching strategies and variable selection rules implemented in our algorithm. The next section, namely Section 4, deals with some heuristic algorithms proposed to provide solutions for large-sized instances. In this section, we also describe how to solve heuristically the pricing problem which gives rise to a matheuristic algorithm consisting of applying the branch-and-price algorithm but solving the pricing problem only heuristically. Obviously, since in this case the optimality of the pricing problem is not guaranteed, we cannot ensure optimality for the solution of the master problem, although we always obtain feasible solutions. In addition, we also present another aggregation heuristic based on clustering strategies that allows us to provide bounds for the problem. Finally, a third heuristic, based on discretizing the space, is developed. Section 5 reports the results of an exhaustive computational study with real-world instances of different nature. There, we compare the standard formulations with the branch-and-price approach and also with the heuristic algorithms. The paper ends with some conclusions in Section 6. Finally, Appendix A reports the details of the computational experiment for different norms showing the usefulness and generality of our approach, and Appendix B shows the computational results disaggregated by different parameters of the instances.

2. The continuous multifacility monotone ordered median problem

In this section, we describe the problem under study and fix the notation for the rest of the paper.

We are given a set of n demand points in \mathbb{R}^d , $\mathcal{A} = \{a_1, \dots, a_n\} \subset \mathbb{R}^d$, and $p \in \mathbb{N}$ ($p > 0$). Our goal is to find p new facilities located in \mathbb{R}^d that minimize a function of the closest distances from the demand points to the new facilities. We denote the index sets of demand points and facilities by $I = \{1, \dots, n\}$ and $J = \{1, \dots, p\}$, respectively. Several elements are involved when finding the *best* p new facilities to provide service to the n demand points. In what follows, we describe them:

- *Closeness Measure*: Given a demand point a_i , $i \in I$, and a facility $x \in \mathbb{R}^d$, we use norm-based distances to measure the point-to-facility closeness. Thus, we consider the following measure for the distance between a_i and x :

$$\delta_i(x) = \|a_i - x\|,$$

Table 1
Examples of Ordered Median aggregation functions.

Notation	λ -vector	Name
W	$(1, \dots, 1)$	p -median
C	$(0, \dots, 0, 1)$	p -center
K	$(0, \dots, 0, \overbrace{1, \dots, 1}^k)$	k -center
D	$(\alpha, \dots, \alpha, 1)$	centdian
S	$(\alpha, \dots, \alpha, \overbrace{1, \dots, 1}^k)$	k -entdian
A	$(0 = \frac{0}{n-1}, \frac{1}{n-1}, \frac{2}{n-1}, \dots, \frac{n-2}{n-1}, \frac{n-1}{n-1} = 1)$	ascendant

where $\|\cdot\|$ is a norm in \mathbb{R}^d . In particular, we will assume that the norm is polyhedral or an ℓ_τ -norm (with $\tau \geq 1$), i.e., $\delta_i(x) =$

$$\left(\sum_{l=1}^d |a_{il} - x_{jl}|^\tau \right)^{\frac{1}{\tau}}.$$

- **Allocation Rule:** Given a set of p new facilities, $\mathcal{X} = \{x_1, \dots, x_p\} \subset \mathbb{R}^d$, and a demand point a_i , $i \in I$, once all the distances between a_i and x_j ($j \in J$) are calculated, one has to allocate the point to a single facility. As usual in the literature, we assume that each point is allocated to its closest facility, i.e., the closeness measure between a_i and \mathcal{X} is:

$$\delta_i(\mathcal{X}) = \min_{x \in \mathcal{X}} \delta_i(x),$$

and the facility $x \in \mathcal{X}$, reaching such a minimum is the one where a_i is allocated to (in case of ties among facilities, a random assignment is performed).

- **Aggregation of Distances:** Given the set of demand points \mathcal{A} , the distances $\{\delta_i(\mathcal{X}) : i \in I\} = \{\delta_1, \dots, \delta_n\}$ must be aggregated abusing of notation, and unless necessary, we will avoid the dependence of \mathcal{X} in the δ -values). To this end, we use the family of ordered median criteria. Given $\lambda \in \mathbb{R}_+^n$ the λ -ordered median function is defined as:

$$OM_\lambda(\mathcal{A}; \mathcal{X}) = \sum_{i \in I} \lambda_i \delta_{(i)}, \tag{OM}$$

where $(\delta_{(i)})_{(i \in I)}$ is a permutation of $(\delta_i)_{(i \in I)}$ such that $\delta_{(1)} \leq \dots \leq \delta_{(n)}$. Some particular choices of λ -weights are shown in Table 1. Note that most of the classical continuous location problems can be cast under this ordered median framework, e.g., the multisource Weber problem, $\lambda = (1, \dots, 1)$, or the multisource p -center problem, $\lambda = (0, \dots, 0, 1)$.

Summarizing all the above considerations, given a set of n demand points in \mathbb{R}^d , $\mathcal{A} = \{a_1, \dots, a_n\} \subset \mathbb{R}^d$ and $\lambda \in \mathbb{R}_+^n$ (with $0 \leq \lambda_1 \leq \dots \leq \lambda_n$), the Continuous Multifacility Monotone Ordered Median Problem (MFOMP $_\lambda$) can be stated as:

$$\min_{\mathcal{X} = \{x_1, \dots, x_p\} \subset \mathbb{R}^d} OM_\lambda(\mathcal{A}; \mathcal{X}). \tag{MFOMP}_\lambda$$

Observe that the problem above is \mathcal{NP} -hard since the multisource p -median problem is just a particular instance of (MFOMP $_\lambda$) where $\lambda = (1, \dots, 1)$ (see Sherali & Nordai, 1988). In the following result we provide a suitable Mixed Integer Second Order Cone Optimization (MISOCO) formulation for the problem.

Theorem 1. Let $\|\cdot\|$ be an ℓ_τ -norm in \mathbb{R}^d , where $\tau = \frac{r}{s}$ with $r, s \in \mathbb{N} \setminus \{0\}$, $r > s$ and $\gcd(r, s) = 1$ or a polyhedral norm. Then, (MFOMP $_\lambda$) can be formulated as a MISOCO problem.

Proof. First, assume that $\{\delta_i(\mathcal{X}) : i \in I\} = \{\delta_1, \dots, \delta_n\}$ are given. Then, sorting the elements and multiplying them by the λ -weights can be equivalently written as the following assignment problem (see Blanco et al., 2014; Blanco et al., 2016), whose dual problem (right side) allows to compute the value of the ordered median

function:

$$\begin{aligned} \sum_{k \in I} \lambda_k \delta_{(k)} &= \max \sum_{i, k \in I} \lambda_k \delta_i \sigma_{ik} &= \min \sum_{i \in I} u_i + \sum_{k \in I} v_k \\ \text{s.t.} \quad &\sum_{k \in I} \sigma_{ik} = 1, \forall i \in I, &\text{s.t.} \quad u_i + v_k \geq \lambda_k \delta_i, \forall i, k \in I, \\ &\sum_{i \in I} \sigma_{ik} = 1, \forall k \in I, &u_i, v_k \in \mathbb{R}, \forall i, k \in I. \\ &\sigma_{ik} \in [0, 1], \forall i, k \in I. \end{aligned}$$

Now, we can embed the above representation of the ordered median aggregation of $\delta_1, \dots, \delta_n$, into (MFOMP $_\lambda$). On the other hand, we have to represent the allocation rule (closest distances). This family of constraints is given by

$$\delta_i = \min_{j \in J} \|a_i - x_j\|, \forall i \in I.$$

In order to represent it, we use the following set of decision variables: $w_{ij} = 1$ if a_i is allocated to facility j , $w_{ij} = 0$ otherwise, $\forall i \in I, j \in J$; in addition, z - and r -variables are auxiliary variables.

Then, a Compact formulation for (MFOMP $_\lambda$) is:

$$\begin{aligned} \min \quad &\sum_{i \in I} u_i + \sum_{k \in I} v_k \\ \text{s.t.} \quad &u_i + v_k \geq \lambda_k r_i, \forall i, k \in I, \end{aligned} \tag{C1}$$

$$z_{ij} \geq \|a_i - x_j\|, \forall i \in I, j \in J, \tag{C2}$$

$$r_i \geq z_{ij} - M(1 - w_{ij}), \forall i \in I, j \in J, \tag{C3}$$

$$\sum_{j \in J} w_{ij} = 1, \forall i \in I, \tag{C4}$$

$$x_j \in \mathbb{R}^d, \forall j \in J, \tag{C5}$$

$$w_{ij} \in \{0, 1\}, \forall i \in I, j \in J, \tag{C6}$$

$$z_{ij} \geq 0, \forall i \in I, j \in J, \tag{C7}$$

$$r_i \geq 0, \forall i \in I, \tag{C8}$$

where (C3) allows to compute the distance between the points and its closest facility and (C4) assures single allocation of points to facilities. Here M is a big enough constant $M > \max_{i, k \in I} \|a_i - a_k\|$.

Finally, in case $\|\cdot\|$ is the $\ell_{\frac{r}{s}}$ -norm, constraint (C2), as already proven in Blanco et al. (2014), can be rewritten as:

$$t_{ijl} + a_{il} - x_{jl} \geq 0, \forall i \in I, j \in J, l = 1, \dots, d,$$

$$t_{ijl} - a_{il} + x_{jl} \geq 0, \forall i \in I, j \in J, l = 1, \dots, d,$$

$$t_{ijl}^r \leq \xi_{ijl}^s z_{ij}^{r-s}, \forall i \in I, j \in J, l = 1, \dots, d,$$

$$\sum_{l=1}^d \xi_{ijl} \leq z_{ij}, \forall i \in I, j \in J,$$

$$t_{ijl}, \xi_{ijl} \geq 0, \forall i \in I, j \in J, l = 1, \dots, d,$$

where t_{ijl} are auxiliary variables that allow to model the absolute values $|a_{il} - x_{jl}|$ being a_{il} and x_{jl} the l th coordinates of the demand point a_i and the facility x_j , respectively. The variables ξ_{ijl} are also auxiliary variables that allow to adequately represent the $\ell_{\frac{r}{s}}$ -norm (see Blanco et al., 2014, for further details on this representation).

If $\|\cdot\|$ is a polyhedral norm, then (C2) is equivalent to:

$$\sum_{l=1}^g e_{gl}(a_{il} - x_{jl}) \leq z_{ij}, \forall i \in I, j \in J, e \in \text{Ext}_{\|\cdot\|, 0},$$

where $\text{Ext}_{\|\cdot\|_0} = \{e_1^0, \dots, e_p^0\}$ are the extreme points of the unit ball of the dual norm of $\|\cdot\|$ (see, e.g., Nickel & Puerto, 2005; Ward & Wendell, 1985).

The final compact formulation depends on the norm, but in any case, we have a MISOCP reformulation for (MFOMP $_\lambda$). \square

Note that (MFOMP $_\lambda$) is an extension of the single-facility ordered median location problem (see, e.g., Blanco et al., 2014), where apart from finding the location of p new facilities, the allocation patterns between demand points and facilities are also determined. In the rest of the paper, we will exploit the combinatorial nature of the problem by means of a set partitioning-like formulation which is based on the following observation:

Proposition 1. Any optimal solution of (MFOMP $_\lambda$) is characterized by p pairs

$(S_1, x_1), \dots, (S_p, x_p)$ with $S_j \subset I$ and $x_j \in \mathbb{R}^d, \forall j \in J$, such that:

1. $\bigcup_{j \in J} S_j = I$.
2. $S_j \cap S_{j'} = \emptyset, j, j' \in J : j \neq j'$.
3. For each $j \in J, x_j \in \arg \min_{x \in \{x_1, \dots, x_p\}} \|a_i - x\|, \forall i \in S_j$.
4. $(x_1, \dots, x_p) \in \arg \min_{y_1, \dots, y_p} \sum_{j \in J} \sum_{i \in S_j} \lambda_{(i)} \|a_i - y_j\|$, where $(i) \in I$ such that $\|a_i - y_j\|$ is the (i) th smallest element in $\{\|a_i - y_j\| : i \in I, j \in J\}$.

From the structure of the optimal solutions of (MFOMP $_\lambda$) described in Proposition 1, we can conclude that there exists a finite candidate set of admissible solutions of this problem given by the different partitions of I in p subsets and one of their associated p best facilities, as defined in Proposition 1 (4). In addition, if the demand points \mathcal{A} are non-collinear and $\tau > 1$ the solution of the problem in Proposition 1 (4) is unique; otherwise, we can always restrict the choices of x_1, \dots, x_p to the extreme points of the set of optimal solutions which is finite. From the above discussion, we conclude that there exists a finite dominating set of candidates, that we will denote as \mathcal{FDS} , to optimal solutions of (MFOMP $_\lambda$).

From now on, we will call a pair (S, x) with $S \subset I$ and $x \in \mathbb{R}^d$ a suitable pair if

1. There exist $(S_2, x_2), \dots, (S_p, x_p)$ such that $\bigcup_{j=2}^p S_j = I \setminus S, S_j \cap S_{j'} = \emptyset$ for $j, j' \in \{2, \dots, p\} : j \neq j', x_j \in \mathbb{R}^d, j = 2, \dots, p$.
2. $(S, x), (S_2, x_2), \dots, (S_p, x_p) \in \mathcal{FDS}$.

In words, a suitable pair is any pair (S, x) that can be part of a candidate solution of (MFOMP $_\lambda$) within the set \mathcal{FDS} . By the finiteness of the sets of admissible solutions, it also follows that the number of suitable pairs is finite as well.

3. A set partitioning-like formulation

The compact formulation shown in the previous section is affected by the size of p and d , and it exhibits the same limitations as many other compact formulations for continuous location models even without ordering constraints. For this reason, in the following we propose an alternative set partitioning-like formulation (du Merle & Vial, 2002; du Merle et al., 1999) for (MFOMP $_\lambda$).

Let $S \subset I$ be a subset of demand points that are assigned to the same facility. Let $R = (S, x)$ be a suitable pair composed by a subset $S \subset I$ and a facility $x \in \mathbb{R}^d$. We denote by δ_i^R the contribution of demand point $i \in S$ in the subset with respect to the facility x . Finally, for each suitable pair $R = (S, x)$ we define the variable

$$y_R = \begin{cases} 1 & \text{if subset } S \text{ is selected and its associated facility is } x, \\ 0 & \text{otherwise.} \end{cases}$$

We denote by $\mathcal{R} = \{(S, x) : \text{suitable pairs}, S \subset I \text{ and } x \in \mathbb{R}^d\}$.

The set partitioning-like formulation is given by the following master problem (MP):

$$\min \sum_{i \in I} u_i + \sum_{k \in I} v_k \tag{MP_1}$$

$$\text{s.t.} \sum_{R=(S,x) \in \mathcal{R}: i \in S} y_R = 1, \forall i \in I, \tag{MP_2}$$

$$\sum_{R \in \mathcal{R}} y_R = p, \tag{MP_3}$$

$$u_i + v_k \geq \lambda_k \sum_{R=(S,x) \in \mathcal{R}: i \in S} \delta_i^R y_R, \forall i, k \in I, \tag{MP_4}$$

$$y_R \in \{0, 1\}, \forall R \in \mathcal{R}, \tag{MP_5}$$

$$u_i, v_k \in \mathbb{R}, \forall i, k \in I. \tag{MP_6}$$

The objective function (MP $_1$) and constraints (MP $_4$) give the correct ordered median function of the distances from the demand points to the closest facility (see Section 2). Constraints (MP $_2$) ensure that all demand points appear in exactly one set S in each feasible solution. Exactly p facilities are open due to constraint (MP $_3$). Finally, (MP $_5$) define the variables as binary.

The reader might notice that this formulation has an exponential number of variables, and therefore in the following we describe the necessary elements to address its solution by means of a branch-and-price scheme, namely:

1. *Initial Pool of Variables:* Generation of initial feasible solutions induced by a set of initial subsets of demand points (and their costs).
2. *Pricing Problem:* In set partitioning problems, instead of solving initially the problem with the whole set of variables, the variables have to be incorporated *on-the-fly* by solving adequate pricing subproblems derived from previously computed solutions until the optimality of the solution is guaranteed. The pricing problem is derived from the relaxed version of the master problem and using the strong duality properties of the induced Linear Programming Problem.
3. *Branching:* The rule that creates new nodes of the branch-and-bound tree when a fractional solution is found at a node of the search tree. We have adapted the Ryan and Foster branching rule to our problem.
4. *Stabilization:* The convergence of column generation approaches can be sometimes erratic since the values of dual variables in the first iterations might oscillate, leading to variables of the master problem that will never appear in the optimal solution of the problem. Stabilization tries to avoid that behaviour.

In what follows, we describe how each of the above items is implemented in our proposal.

3.1. Initial variables

In the solution process of the set partitioning-like formulation using a branch-and-price approach, it is convenient to generate an initial pool of variables before starting solving the problem. The adequate selection of these initial variables might help to reduce the CPU time required to solve the problem. We apply an iterative strategy to generate this initial pool of y -variables. In the first iteration, we randomly generate p positions for the facilities. The demand points are then allocated to their closest facilities, and at most p subsets of demand points are generated. We incorporate the variables associated with these subsets to the master problem

(MP). In the next iterations, instead of generating p new facilities, we keep those with more associated demand points, and randomly generate the remainder. After a fixed number of iterations, an initial set of columns is generated to define the restricted master problem, and also an upper bound of our problem. Since the optimal position of the facilities belongs to a bounded set contained in the rectangular hull of the demand points, the random facilities are generated in the smallest hyperrectangle containing \mathcal{A} .

3.2. The pricing problem

To apply the column generation procedure we restrict and relax (MP), in the following restricted relaxed master problem (RRMP).

$$\begin{aligned} \rho_{MP}^* := \min \quad & \sum_{i \in I} u_i + \sum_{k \in I} v_k && \text{Dual Multipliers (RRMP)} \\ \text{s.t.} \quad & \sum_{R=(S,x) \in \mathcal{R}_0; i \in S} y_R \geq 1, \quad \forall i \in I, && \alpha_i \geq 0 \\ & - \sum_{R \in \mathcal{R}_0} y_R \geq -p, && \gamma \geq 0 \\ & u_i + v_k - \lambda_k \sum_{R=(S,x) \in \mathcal{R}; i \in S} \delta_i^R y_R \geq 0, && \epsilon_{ik} \geq 0 \\ & \forall i, k \in I, && \\ & y_R \geq 0, \quad \forall R \in \mathcal{R}_0, && \\ & u_i, v_k \in \mathbb{R}, \quad \forall i, k \in I, && \end{aligned}$$

where $\mathcal{R}_0 \in \mathcal{R}$ represents the initial pool of columns used to initialize the set partitioning-like formulation (MP). Constraints (MP₂) and (MP₃) are slightly modified from equations to inequalities in order to get nonnegative dual multipliers. This transformations keeps the equivalence with the original formulation since coefficients affecting the y -variables in constraint (MP₄) are nonnegative. The notation for the dual variables associated with each family of constraints is written in the right column (α, γ, ϵ).

The value of the distances is unknown beforehand because the location of facilities can be anywhere in the continuous space. Hence, its determination requires solving continuous optimization problems.

By strong duality, the objective value of the continuous relaxation (RRMP), can be obtained as:

$$\begin{aligned} \rho_{MP}^* = \max \quad & \sum_{i \in I} \alpha_i - p\gamma && \text{(Dual RRMP)} \\ \text{s.t.} \quad & \sum_{i \in I} \epsilon_{ik} = 1, \quad \forall k \in I, && \\ & \sum_{k \in I} \epsilon_{ik} = 1, \quad \forall i \in I, && \\ & \sum_{i \in S} \alpha_i - \gamma - \sum_{i \in S} \sum_{k \in I} \delta_i^R \lambda_k \epsilon_{ik} \leq 0, \quad \forall R = (S, x) \in \mathcal{R}_0, && \\ & \alpha_i, \gamma, \epsilon_{ik} \geq 0, \quad \forall i, k \in I. && \end{aligned}$$

Hence, for any variable y_R in the master problem, its reduced cost is

$$c_R - z_R = - \sum_{i \in S} \alpha_i^* + \gamma^* + \sum_{i \in S} \sum_{k \in I} \delta_i^R \lambda_k \epsilon_{ik}^*,$$

where $(\alpha^*, \gamma^*, \epsilon^*)$ is the dual optimal solution of the current (RRMP).

To certify optimality of the relaxed problem one has to check implicitly that all the reduced costs for the variables not currently included in the (RRMP) are nonnegative. Otherwise, new variables must be added to the pool of columns. This can be done solving the so-called pricing problem.

The pricing problem consists of finding the minimum reduced cost among the variables that have not yet been included in the pool. That is, we have to find the set $S \subset I$ and the position of the facility x (its coordinates) which minimizes the reduced cost.

For a given set of dual multipliers, $(\alpha^*, \gamma^*, \epsilon^*) \geq 0$, the problem to be solved is

$$\begin{aligned} \min_{\substack{S \subset I \\ x \in \mathbb{R}^d}} \quad & - \sum_{i \in S} \alpha_i^* + \gamma^* + \sum_{i \in S} \sum_{k \in I} \delta_i^S \lambda_k \epsilon_{ik}^* \\ \text{s.t.} \quad & \delta_i^S \geq \|x - a_i\|, \quad \forall i \in S. \end{aligned}$$

The above formal problem can be reformulated by means of a mixed integer program. We define variables $w_i = 1, i \in I$ if the demand point belongs to S , and zero otherwise. We also define variables $r_i, i \in I$ to represent the distance from demand point i to facility x and zero in case $w_i = 0$. Finally, $z_i, i \in I$ are auxiliary variables to represent the distances from demand point i to facility x in any case.

$$\min \quad - \sum_{i \in I} \alpha_i^* w_i + \gamma^* + \sum_{i \in I} c_i r_i \quad (3)$$

$$\text{s.t.} \quad z_i \geq \|x - a_i\|, \quad \forall i \in I, \quad (4)$$

$$r_i + M(1 - w_i) \geq z_i, \quad \forall i \in I, \quad (5)$$

$$w_i \in \{0, 1\}, \quad \forall i \in I, \quad (6)$$

$$z_i, r_i \geq 0, \quad \forall i \in I, \quad (7)$$

where M is a big enough constant ($M > \max\{\|a_i - a_{i'}\| : i, i' \in I, i \neq i'\}$) and $c_i = \sum_{k \in I} \lambda_k \epsilon_{ik}^*, i \in I$.

Objective function (10) is the minimum reduced cost associated with the optimal solution of the pricing problem. Constraints (11) define the distances. As in Section 2, this family of constraints is defined *ad hoc* for a given norm. Constraints (12) set correctly the r -variables. Finally, constraints (13) and (14) are the domain of the variables.

As it has been shown in the proof of Theorem 1, the above problem can be formulated as a MISOCP problem in case of polyhedral or ℓ_τ -norms.

The so-called *Farkas pricing* should be adequately defined in case the feasibility of (RRMP) is not ensured. That strategy allows one to detect such an infeasibility by means of solving a pricing problem similar to (RRMP). However, we avoid the use of the Farkas pricing applying the following strategy: (a) we introduce in the firstly solved master problem the initial pool of variables as described in Section 3.1; and (b) since the feasibility of the master problem might be lost along the branching process of our branch-and-price approach, we add an *artificial* variable $y_{(I,x_0)}$ whose local lower bound is never set to zero and with $\delta_i^{(I,x_0)}$ being a big enough value. This strategy allows us to assure that (MP₂) is satisfied by this variable, and the overall master problem is always feasible.

When the pricing problem is optimally solved, one can obtain a theoretical lower bound even if more variables must be added. The following remark explains how the result is applied to our particular problem.

Remark 1. Desrosiers & Lübecke (2005) provide theoretical lower bounds for binary programming problems that are embedded into branch-and-price approaches, in case the number of binary variables that can take value one is upper bounded. In our case, the number of y -variables in (MP) that take value one is exactly p . Thus, one can compute a lower bound for (MP) as:

$$LB = z_{RRMP} + p \min_{S,x} \bar{c}_{(S,x)}, \quad (15)$$

where z_{RRMP} is the objective value of any of the relaxed problems (RRMP) and $\bar{c}_{(S,x)}$ is the reduced cost of the variable defined by (S, x) .

It is important to remark that this bound can be computed at each node of the branch-and-bound tree. The bounds are particularly useful at the root node since they may help to accelerate the optimality certification, or for large instances where the linear relaxation is not solved within the time limit.

Observe also that for adding a variable to the master problem, it suffices to find one variable y_R with negative reduced cost. This search can be performed by solving exactly the pricing problem, although that might have a high computational load. Alternatively, one could also solve heuristically the pricing problem, hoping for variables with negative reduced costs. In what follows, this approach will be called the *heuristic pricer*. The key observation is to check if a candidate facility is promising to this end.

Given the coordinates of a facility, x , we construct a set of demand points, S , compatible with the conditions of the node of the branch-and-bound tree by allocating demand points in S to x whenever the reduced cost $c_{(S,x)} - z_{(S,x)} = \gamma^* + \sum_{i \in S} e_i < 0$, where $e_i = -\alpha_i^* + \sum_{k \in I} \delta_i(x) \lambda_k \epsilon_{ik}^*$. In that case, the variable $y_{(S,x)}$ is candidate to be added to the pool of columns. Here, we detail how the heuristic pricer algorithm is implemented at the root node. For deeper nodes in the branch-and-bound tree we refer the reader to Section 3.3.

For the root node, there is a very easy procedure to solve this problem, just selecting the negative ones, i.e., we define $S = \{i \in I : e_i < 0\}$ and, in case $c_{(S,x)} - z_{(S,x)} < 0$, the variable $y_{(S,x)}$ could be added to the problem. Additionally, the region where the facility is generated can be significantly reduced, in particular to the hyperrectangle defined by demand points with negative e_i .

In both exact and heuristic pricer, we use multiple pricing, i.e., several columns are added to the pool at each iteration, if possible. In the exact pricer, we take advantage that the solver saves different solutions besides the optimal one, so it might provide us more than one column with negative reduced cost. In the heuristic pricer, we add the best variables in terms of reduced cost as long as their associated reduced costs are negative.

3.3. Branching

When the relaxed (MP) is solved, but the solution is not integer, the next step is to define an adequate branching rule to explore the searching tree. In this problem, we apply an adaptation of the Ryan and Foster branching rule (Ryan & Foster, 1981). Given a solution with fractional y -variables in a node, it might occur that

$$0 < \sum_{R=(S,x) \in \mathcal{R}: i_1, i_2 \in S} y_R < 1, \text{ for some } i_1, i_2 \in I, i_1 < i_2. \quad (16)$$

Provided that this happens, in order to find an integer solution, we create the following branches from the current node:

- **Left branch:** i_1 and i_2 must be served by different facilities.

$$\sum_{R=(S,x) \in \mathcal{R}: i_1, i_2 \in S} y_R = 0.$$

- **Right branch:** i_1 and i_2 must be served by the same facility.

$$\sum_{R=(S,x) \in \mathcal{R}: i_1, i_2 \in S} y_R = 1.$$

Remark 2. The above information is easily translated to the pricing problem adding one constraint to each one of the branches: 1) $w_{i_1} + w_{i_2} \leq 1$ for the left branch; and 2) $w_{i_1} = w_{i_2}$ for the right branch.

It might also happen that being some y_R fractional, $\sum_{R=(S,x) \in \mathcal{R}: i_1, i_2 \in S} y_R$ is integer for all $i_1, i_2 \in I, i_1 < i_2$. The following result allows us to use this branching rule and provides a procedure to recover a feasible solution encoded in the current solution of the node.

Theorem 2. If $\sum_{R=(S,x) \in \mathcal{R}: i_1, i_2 \in S} y_R \in \{0, 1\}$, for all $i_1, i_2 \in I$, such that $i_1 < i_2$, then there exists an integer feasible solution of (MP) with the same objective function value.

Proof. Let \mathcal{X}_S be the set of all facilities which are part of a variable $y_{(S,x)}$ belonging to the pool of columns. We define \mathcal{X}_S for all used partitions S . First, it is proven in Barnhart, Johnson, Nemhauser, Savelsbergh, & Vance (1998) that, under the hypothesis of the theorem, the following expression holds for any set S in a partition,

$$\sum_{x \in \mathcal{X}_S} y_{(S,x)} \in \{0, 1\}.$$

If $\sum_{x \in \mathcal{X}_S} y_{(S,x)} = 0$, then $y_{(S,x)} = 0$, for all $x \in \mathcal{X}_S$, because of the nonnegativity of the variables. However, if

$$\sum_{x \in \mathcal{X}_S} y_{(S,x)} = 1, \quad (17)$$

$y_{(S,x)}$ could be fractional, for some $x \in \mathcal{X}_S$.

Observe that, currently, the distance associated with demand point $i \in S$ in the problem is

$$\delta_i^S = \sum_{x \in \mathcal{X}_S} y_{(S,x)} \delta_i(x).$$

Thus, from the above we construct a new facility x^* for S .

$$x_l^* = \sum_{x \in \mathcal{X}_S} y_{(S,x)} x_l, \quad \forall l = 1, \dots, d, \quad (18)$$

so that $\delta_i(x^*) \leq \delta_i^S, \forall i \in S$.

Indeed, by the triangular inequality and by (17),

$$\delta_i(x^*) = \|x^* - a_i\| = \left\| \sum_{x \in \mathcal{X}_S} y_{(S,x)} (x - a_i) \right\| \leq \sum_{x \in \mathcal{X}_S} y_{(S,x)} \|x - a_i\| = \delta_i^S,$$

for all $i \in S$. The inequality being strict unless $x - a_i$, for all $x \in \mathcal{X}_S$, are collinear.

Finally, we have constructed the variable $y_{(S,x^*)} = 1$ as part of a feasible integer solution of the master problem (MP). Therefore, it ensures that either the solution is binary or there exists a binary feasible solution with the same objective function value. \square

Among all the possible choices of pairs i_1, i_2 verifying (16), we propose to select the one provided by the following rule:

$$\arg \max_{\substack{i_1, i_2: \\ 0 < \sum_{R=(S,x) \in \mathcal{R}: i_1, i_2 \in S} y_R < 1}} \left\{ \theta \min \left\{ \sum_{R=(S,x) \in \mathcal{R}: i_1, i_2 \in S} y_R, 1 - \sum_{R=(S,x) \in \mathcal{R}: i_1, i_2 \in S} y_R \right\} + \frac{1 - \theta}{\|a_{i_1} - a_{i_2}\|} \right\}. \quad (\theta\text{-rule})$$

This rule uses the most fractional y -solution, but also pays attention to the pairs of demand points which are close to each other in the solution, assuming they will be part of the same variable with value one at the optimal solution. It has been successfully applied in a related Discrete Ordered Median Problem (Deleplanque

et al., 2020). The parameter θ is chosen in $[0,1]$, where for $\theta = 0$, the closest demand points among the pairs with fractional sum will be selected, while for $\theta = 1$, the most fractional branching will be applied.

The above branching rule affects the heuristic pricer procedure, since not all $S \subset I$ are compatible with the branching conditions leading to a node. In case that we have to respect some branching decisions, the pricing problem gains complexity. Therefore, we develop a greedy algorithm which generates heuristic variables respecting the branching decision in the current node. This algorithm uses the information from the branching rule to build the new variable to add.

The candidate set S is built by means of a greedy algorithm similar to the one presented in Sakai, Togasaki, & Yamazaki (2003). First, we construct a graph of incompatibilities $G = (V, E)$, with V and E defined as follows: for each maximal subset of demand points $i_1 < i_2 < \dots < i_m$, that according to the branching rule have to be assigned to the same subset, we include a vertex v_{i_1} with weight $\omega_{i_1} = \sum_{i \in \{i_1, \dots, i_m\}} e_i$; next, for each $v_i, v_{i'} \in V$, such that i and i' cannot be assigned to the same subset at the current node, we define $\{v_i, v_{i'}\} \in E$. The subset S minimizing the reduced cost for a given x can be calculated solving the Maximum Weighted Independent Set Problem over G . The algorithm solves this problem heuristically applying the GGWMIN selection vertex rule proposed by Sakai et al. (2003).

3.4. Convergence

Due to the huge number of variables that might arise in column generation procedures, it is very important checking the possible degeneracy of the algorithm. Accelerating the convergence has been traditionally afforded by means of stabilization techniques. In recent papers, it has been shown how heuristic pricers avoid degeneracy (e.g., Benati, Ponce, Puerto, & Rodríguez-Chía, 2022; Blanco et al., 2021). Stabilization and heuristic pricers have in common that both do not add in the first iterations variables with the minimum associated reduced cost. This idea has been empirically shown to accelerate convergence (see, e.g., du Merle et al., 1999; Pessoa, Uchoa, de Aragão, & Rodrigues, 2010).

For the sake of readability, all the computational analysis is included in Section 5. There, the reader can see how our heuristic pricer needs less variables to certify optimality than the exact pricer for medium- and large-sized instances, therefore, accelerating the convergence.

4. Matheuristic approaches

(**MFOMP** $_{\lambda}$) is an \mathcal{NP} -hard combinatorial optimization problem, and both the compact formulation and the proposed branch-and-price approach are limited by the number of demand points (n) and facilities (p) to be considered. Actually, as we will see in Section 5, the two exact approaches are only capable of solving, optimally, small- and medium-sized instances. In this section, we derive three different matheuristic procedures, capable to handle larger instances in reasonable CPU times. The first approach is based on using the branch-and-price scheme but solving only heuristically the pricing problem. The second is an aggregation based-approach that will also allow us to derive theoretical error bounds on the approximation. A third heuristic based on discretizing the space is proposed.

4.1. Heuristic pricer

The matheuristic procedure described here has been successfully applied in the literature. See, e.g., Alborno & Zamora (2021); Benati et al. (2022), Deleplanque et al. (2020), and the references

therein. Recall that our pricing problem is \mathcal{NP} -hard. In order to avoid the exact procedure for large-sized instances, where not even a single iteration could be solved exactly, we propose a matheuristic. It consists of solving each pricing problem heuristically. The inconvenience of doing that is that we do not have a theoretic lower bound during the process. Nevertheless, for instances where the time limit is reached, we are able to visit more nodes in the branch-and-bound tree which could allow us to obtain better incumbent solutions than the unfinished exact procedure.

4.2. Aggregation schemes

The second matheuristic approach that we propose is based on applying aggregation techniques to the input data (the set of demand points). This type of approaches has been successfully applied to solve large-scale continuous location problems (see Blanco & Gázquez, 2021; Blanco et al., 2021; Blanco, Puerto, & Salmerón, 2018; Current & Schilling, 1990; Daskin, Haghani, Khanal, & Malandraki, 1989; Irawan, 2016).

Let $\mathcal{A} = \{a_1, \dots, a_n\} \subset \mathbb{R}^d$ be a set of demands points. In an aggregation procedure, the set \mathcal{A} is replaced by a multiset $\mathcal{A}' = \{a'_1, \dots, a'_n\}$, where each point a_i in \mathcal{A} is assigned to a point a'_i in \mathcal{A}' . In order to be able to solve (**MFOMP** $_{\lambda}$) for \mathcal{A}' , the cardinality of the different elements of \mathcal{A}' is assumed to be smaller than the cardinality of \mathcal{A} , and then, several a_i might be assigned to the same a'_i .

Once the points in \mathcal{A} are aggregated into \mathcal{A}' , the procedure consists of solving (**MFOMP** $_{\lambda}$) for the demand points in \mathcal{A}' . We get a set of p optimal facilities for the aggregated problem, $\mathcal{X}' = \{x'_1, \dots, x'_p\}$, associated with its objective value $\text{OM}_{\lambda}(\mathcal{A}'; \mathcal{X}')$. These positions can also be evaluated in the original objective function of the problem for the demand points \mathcal{A} , $\text{OM}_{\lambda}(\mathcal{A}; \mathcal{X}')$. The following result allows us to get upper bound of the error incurred when aggregating demand points.

Theorem 3. Let \mathcal{X}^* be the optimal solution of (**MFOMP** $_{\lambda}$) and $\Delta = \max_{i=1, \dots, n} \|a_i - a'_i\|$. Then

$$|\text{OM}_{\lambda}(\mathcal{A}; \mathcal{X}^*) - \text{OM}_{\lambda}(\mathcal{A}; \mathcal{X}')| \leq 2\Delta \sum_{i=1}^n \lambda_i. \quad (19)$$

Proof. By the triangular inequality and the monotonicity and sublinearity of the ordered median function we have that $\text{OM}_{\lambda}(\mathcal{A}; \mathcal{X}') \leq \text{OM}_{\lambda}(\mathcal{A}'; \mathcal{X}') + \text{OM}_{\lambda}(\mathcal{A}'; \mathcal{A})$ for all $\mathcal{X}' = \{x'_1, \dots, x'_p\} \subset \mathbb{R}^d$. Since $\Delta \geq \|a_i - a'_i\|$ for all $i \in I$ we get that $|\text{OM}_{\lambda}(\mathcal{A}; \mathcal{X}') - \text{OM}_{\lambda}(\mathcal{A}'; \mathcal{X}')| \leq \Delta \sum_{i \in I} \lambda_i$ for all $\mathcal{X}' = \{x'_1, \dots, x'_p\} \subset \mathbb{R}^d$. Applying (Geoffrion, 1977, Theorem 5), we get that $|\text{OM}_{\lambda}(\mathcal{A}; \mathcal{X}^*) - \text{OM}_{\lambda}(\mathcal{A}'; \mathcal{X}')| \leq \Delta \sum_{i \in I} \lambda_i$, and then:

$$\begin{aligned} |\text{OM}_{\lambda}(\mathcal{A}; \mathcal{X}^*) - \text{OM}_{\lambda}(\mathcal{A}; \mathcal{X}')| &\leq |\text{OM}_{\lambda}(\mathcal{A}; \mathcal{X}^*) - \text{OM}_{\lambda}(\mathcal{A}'; \mathcal{X}')| \\ &+ |\text{OM}_{\lambda}(\mathcal{A}'; \mathcal{X}') - \text{OM}_{\lambda}(\mathcal{A}; \mathcal{X}')| \leq 2\Delta \sum_{i \in I} \lambda_i. \end{aligned}$$

□

There are different strategies to reduce the dimensionality by aggregating points. In our computational experiments we consider two differentiated approaches: the *k-Means Clustering* (KMEANS) and the *Pick The Farthest* (PTF). In KMEANS, we replace the original points by the centroids. Alternatively, in PTF, an initial random demand point from \mathcal{A} is chosen and the rest are selected as the farthest demand point from the last one chosen, until a predefined number of points is reached (Daskin et al., 1989).

4.3. Discretization

We propose a third heuristic algorithm, based on an adaptation of similar heuristics applied to a different location problem

Table 2

Average number of pricer iterations, variables and time using the combined heuristic and exact pricers or only using the exact pricer.

n	Heurvar	Iterations		Vars	Time
		Exact	Total		
20	FALSE	13	13	2189	64.92
	TRUE	4	23	2219	18.02
30	FALSE	15	15	2827	1034.97
	TRUE	3	60	2856	191.84
40	FALSE	50	50	4713	9086.33
	TRUE	13	136	4511	2229.21

(see Gamal & Salhi, 2003; Hansen, Mladenović, & Taillard, 1998), which consists of solving a discrete version of our problem, also known as the Discrete Ordered Median Problem (DOMP for short) (Nickel & Puerto, 2005). In this matheuristic, the potential facilities are chosen among the demand points to solve the DOMP with the solution methods developed in Deleplanque et al. (2020).

This approach produces suboptimal solutions since the feasible domain of the DOMP is a discrete set contained in the solution space of (MFMOMP $_{\lambda}$). Discretizing the continuous space is a heuristic technique that has been previously exploited in the literature for the Uncapacitated Multisource Weber Problem (see, e.g., Brimberg, Drezner, Mladenović, & Salhi, 2014; Brimberg, Hansen, Mladenović, & Taillard, 2000; Drezner, Brimberg, Mladenović, & Salhi, 2016; Gamal & Salhi, 2003; Hansen et al., 1998). Here, we adapt those algorithms to (MFMOMP $_{\lambda}$). Firstly, we reduce the solution space to the demand points. Later, the resulting DOMP is solved heuristically by a GRASP algorithm to have a good upper bound and by a branch-price-and-cut procedure to obtain a lower bound and improve the upper bound. Note that the obtained upper bound is valid for the original (MFMOMP $_{\lambda}$), whereas the lower bound is not. The reader can see in Section 5.2 that, for large-sized instances, this methodology provides rather good results.

5. Computational study

In order to compare the performance of our branch-and-price and our matheuristic approaches, we report the results of our computational experiments. We consider different sets of instances used in the location literature with size ranging from 20 to 654 demand points in the plane. In all of them, the number of facilities to be located, p , ranges in $\{2, 5, 10\}$ and we solve the instances for the λ -vectors in Table 1, $\{W, C, K, D, S, A\}$. We set $k = \frac{n}{2}$ for the k -center and k -entdian, and $\alpha = 0.9$ for the centdian and k -entdian.

For the sake of readability, we restrict the computational study of this document to ℓ_1 -norm based distances. However, the reader can find extensive computational results for other norms in Appendix A and Appendix B.

The models were coded in C and solved with SCIP v.7.0.2 (Gamrath et al., 2020) using as optimization solver SoPlex 5.0.2 in a Mac OS Catalina with a Core Intel Xeon W clocked at 3.2 GHz and 96 GB of RAM memory.

5.1. Computational performance of the branch-and-price procedure

In this section we report the results for our branch-and-price approach based on the classical dataset provided by Eilon, Watson-Gandy, & Christofides (1971). From this dataset, we randomly generate five instances with sizes $n \in \{20, 30, 40, 45\}$ and we also consider the entire complete original instance with $n = 50$. Together with the number of facilities p and the different ordered weighted median functions (type), a total of 378 instances has been considered.

Firstly, concerning convergence (Section 3.4), each line in Table 2 shows the average results of 45 instances, five for each type of ordered median objective function to be minimized $\{W, D, S\}$ and $p \in \{2, 5, 10\}$, solved to optimality. The results has been split by size (n) and by Heurvar: FALSE when only the exact pricer is used; TRUE if the heuristic pricer is used and the exact pricer is called when it does not provide new columns to add. The reader can see a significant reduction of the CPU time (Time) caused by a decrease of the number of calls to the exact pricer (Exact) even though the number of total iterations (Total) increases. Additionally, a second effect is that the necessary number of variables to certify optimality (Vars) is slightly less when the heuristic is applied for $n = 40$. Hence, we will use the heuristic pricer for the rest of the experiments.

Secondly, we have tuned the values of θ for the branching rule (θ -rule) for each of the objective functions (different values for the λ -vector) based in our computational experience. In Table 3, we show the average gap at termination of the above-mentioned 378 instances when we apply our branch-and-price approach fixing a time limit of 2 h.

Therefore we set $\theta = 0$ for the center problem (C), $\theta = 0.5$ for the k -center problem (K), and $\theta = 1$ for the p -median (W), centdian (D), k -entdian (S), and ascendant problems (A). Recall that when we use $\theta = 0$, we are selecting a pure distance branching rule. In contrast, when $\theta = 1$, we select the most fractional variable. On the other hand, when $\theta = 0.5$, we use a hybrid selection between the two extremes of the (θ -rule). In the following, the above fixed parameters will be used in the computational experiments for exact and matheuristic methods.

The average results obtained for the Eilon et al. (1971) instances, with a CPU time limit of 2 h, are shown in Table 4. There, for each combination of n (size of the instance), p (number of facilities to be located) and type (ordered median objective function to be minimized), we provide the average results for ℓ_1 -norm with a comparison between the compact formulation (C) (Compact) and the branch-and-price approach (B&P). The table is organized as follows: the first column gives the CPU time in seconds needed to solve the problem (Time) and within parentheses the number of unsolved instances (#Unsolved), i.e., those for which the lower and upper bound do not coincide within the time limit; the second column shows the gap at the root node; the third one gives the gap at termination, i.e., the remaining MIP gap in percentage (GAP(%)) when the time limit is reached, 0.00 otherwise; in the fourth column we show the number of variables (Vars) needed to solve the problem; in the fifth column we show the number

Table 3
GAP (%) for ℓ_1 -norm, Eilon et al. (1971) instances.

type	$\theta = 0.0$	$\theta = 0.1$	$\theta = 0.3$	$\theta = 0.5$	$\theta = 0.7$	$\theta = 0.9$	$\theta = 1.0$
W	0.04	0.04	0.04	0.04	0.04	0.04	0.02
C	27.94	28.34	28.29	28.47	28.64	28.74	28.19
K	12.83	12.63	12.80	12.46	12.73	13.15	12.88
D	0.09	0.07	0.09	0.09	0.09	0.09	0.02
S	0.11	0.14	0.14	0.14	0.14	0.13	0.10
A	7.73	7.66	7.69	7.71	7.64	7.73	7.33

Table 4
Results for Eilon et al. (1971) instances for ℓ_1 -norm.

n	type	p	Time (#Unsolved)			GAProot (%)		GAP (%)		Vars		Nodes		Memory (MB)		
			Compact	B&P		Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	
20	W	2	1.59	(0)	22.90	(0)	93.92	0.00	0.00	0.00	224	2131	9518	1	4	103
		5	1588.99	(1)	8.34	(0)	100.00	0.00	3.38	0.00	470	2408	10967305	1	1278	49
		10	—	(5)	3.95	(0)	100.00	0.46	43.84	0.00	880	2127	19785215	2	3425	28
	C	2	0.06	(0)	237.96	(4)	78.92	22.59	0.00	10.78	224	97635	7	4652	4	2239
		5	12.58	(0)	—	(5)	100.00	29.46	0.00	17.16	470	15251	40379	18660	12	464
		10	511.69	(2)	1831.83	(4)	100.00	37.64	7.59	20.28	880	4243	7928195	21617	725	160
	K	2	0.35	(0)	1412.69	(1)	91.43	7.55	0.00	1.42	224	37917	630	670	3	953
		5	243.88	(0)	404.99	(3)	100.00	15.40	0.00	3.85	470	9363	657827	6642	77	279
		10	32.22	(4)	3156.63	(2)	100.00	18.53	36.95	3.26	880	4071	12150962	9244	2265	111
	D	2	2.18	(0)	30.36	(0)	93.78	0.03	0.00	0.00	224	2135	9222	1	5	108
		5	1535.82	(1)	12.18	(0)	100.00	0.00	6.69	0.00	470	2401	8972062	1	1225	49
		10	5030.79	(4)	6.88	(0)	100.00	0.46	48.19	0.00	880	2127	15660031	4	2798	28
	S	2	2.24	(0)	54.23	(0)	93.77	0.16	0.00	0.00	224	2119	7677	1	5	106
		5	1238.87	(1)	15.75	(0)	100.00	0.06	4.40	0.00	470	2401	8141244	2	745	50
		10	—	(5)	7.61	(0)	100.00	0.53	50.12	0.00	880	2126	16072018	5	2835	28
A	2	0.85	(0)	783.95	(1)	91.63	4.45	0.00	0.35	224	16973	1340	400	4	738	
	5	411.21	(0)	2304.77	(0)	100.00	10.18	0.00	0.00	470	7405	878975	1697	126	222	
	10	60.27	(4)	883.79	(1)	100.00	17.10	31.87	1.73	880	3288	10637608	2721	1723	79	
30	W	2	139.91	(0)	526.92	(0)	93.86	0.00	0.00	0.00	334	3142	787145	1	38	260
		5	—	(5)	64.66	(0)	100.00	0.00	52.05	0.00	700	2963	17382888	1	8647	109
		10	—	(5)	19.51	(0)	100.00	0.00	76.26	0.00	1310	2472	12250097	1	4692	55
	C	2	0.11	(0)	39.44	(4)	79.19	21.41	0.00	15.46	334	125429	66	931	8	1443
		5	30.64	(0)	1564.58	(4)	100.00	31.68	0.00	22.73	700	30216	69019	2817	19	389
		10	4212.55	(3)	—	(5)	100.00	34.18	16.67	27.51	1310	12928	9619002	6027	1823	190
	K	2	4.44	(0)	409.69	(4)	90.88	8.65	0.00	7.58	334	45846	8511	147	10	1696
		5	2956.65	(4)	5199.43	(3)	100.00	12.01	17.79	5.82	700	18893	12169516	815	2570	534
		10	—	(5)	2740.67	(4)	100.00	18.84	69.60	12.31	1310	7416	9299590	2992	3105	187
	D	2	201.28	(0)	454.39	(0)	93.77	0.00	0.00	0.00	334	3087	757445	1	49	258
		5	—	(5)	65.46	(0)	100.00	0.00	57.16	0.00	700	2957	9914066	1	7439	111
		10	—	(5)	21.25	(0)	100.00	0.00	79.34	0.00	1310	2464	10108803	1	4631	55
	S	2	203.04	(0)	370.63	(0)	93.68	0.00	0.00	0.00	334	3184	566382	1	41	263
		5	—	(5)	160.85	(0)	100.00	0.03	56.47	0.00	700	2963	9283122	2	7054	112
		10	—	(5)	42.86	(0)	100.00	0.09	79.91	0.00	1310	2469	9530286	3	4686	56
A	2	21.89	(0)	3640.13	(2)	91.15	4.46	0.00	3.26	334	12721	26764	41	12	845	
	5	5403.72	(4)	2750.01	(3)	100.00	7.76	28.99	2.60	700	8615	8044660	188	2288	357	
	10	—	(5)	804.71	(4)	100.00	13.38	70.51	6.64	1310	5529	7159232	1465	2364	165	
40	W	2	4028.70	(4)	1675.34	(0)	93.79	0.01	12.34	0.00	444	5211	26828725	1	2515	645
		5	—	(5)	1647.86	(0)	100.00	0.02	67.11	0.00	930	4028	12240990	3	10977	229
		10	—	(5)	348.57	(0)	100.00	0.09	81.57	0.00	1740	4001	7841923	2	4267	125
	C	2	0.25	(0)	—	(5)	75.52	30.52	0.00	29.73	444	136451	237	259	15	1541
		5	116.02	(0)	—	(5)	100.00	42.30	0.00	41.65	930	27041	195892	158	42	224
		10	3022.45	(4)	—	(5)	100.00	36.47	31.47	33.88	1740	12733	7126207	667	2024	110
	K	2	58.78	(0)	—	(5)	90.67	14.52	0.00	14.52	444	14164	93918	11	27	897
		5	—	(5)	—	(5)	100.00	21.45	56.58	21.44	930	10132	6803627	28	5632	360
		10	—	(5)	—	(5)	100.00	19.04	75.08	17.71	1740	8823	5436226	280	2606	198
	D	2	5908.68	(4)	436.48	(1)	93.67	0.02	15.22	0.01	444	5669	16542227	2	3164	709
		5	—	(5)	855.62	(1)	100.00	0.11	68.93	0.08	930	4094	7984937	2	10233	233
		10	—	(5)	331.54	(0)	100.00	0.07	83.85	0.00	1740	4004	5704188	2	4413	126
	S	2	4977.44	(4)	429.96	(1)	93.60	0.47	14.33	0.47	444	5195	12853124	1	2430	657
		5	—	(5)	2159.56	(1)	100.00	0.14	70.18	0.02	930	4082	7715457	4	9805	233
		10	—	(5)	615.35	(0)	100.00	0.17	84.62	0.00	1740	3999	5409994	4	4687	126
A	2	533.79	(0)	—	(5)	90.85	8.30	0.00	8.19	444	6506	455652	3	48	769	
	5	—	(5)	—	(5)	100.00	14.76	58.65	14.17	930	5538	3684557	10	3409	331	
	10	—	(5)	—	(5)	100.00	12.35	74.52	10.21	1740	6285	4403838	161	2000	214	
45	W	2	—	(5)	483.59	(1)	94.05	0.04	27.06	0.02	499	7219	24989615	2	5854	1085
		5	—	(5)	1745.55	(2)	100.00	0.32	71.65	0.27	1045	4855	11473640	4	11171	374
		10	—	(5)	635.43	(0)	100.00	0.03	83.54	0.00	1955	4239	5717627	1	3767	168
	C	2	0.46	(0)	—	(5)	74.99	39.01	0.00	38.99	499	109398	628	104	17	1364
		5	144.75	(0)	—	(5)	100.00	40.69	0.00	40.62	1045	20483	215522	31	44	176
		10	—	(5)	—	(5)	100.00	32.80	37.16	31.54	1955	14204	6469050	219	1915	110
	K	2	342.18	(0)	—	(5)	91.23	16.93	0.00	16.93	499	10490	497310	4	59	845
		5	—	(5)	—	(5)	100.00	22.98	64.55	22.98	1045	6631	5434589	11	6520	295
		10	—	(5)	—	(5)	100.00	16.68	77.74	16.48	1955	8738	4555667	78	2681	220
	D	2	—	(5)	364.11	(1)	93.96	0.02	29.64	0.02	499	6473	14042725	1	6338	973
		5	—	(5)	1744.42	(2)	100.00	0.17	73.98	0.11	1045	4731	7322624	3	10301	365
		10	—	(5)	667.13	(0)	100.00	0.02								

Table 4 (continued)

n	type	p	Time (#Unsolved)		GAProot (%)		GAP (%)		Vars		Nodes		Memory (MB)			
			Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P		
50	W	2	—	(1) 331.87	(0)	94.13	0.00	34.44	0.00	554	8094	24416531	1	6585	1464	
		5	—	(1) 410.87	(0)	100.00	0.00	76.08	0.00	1160	5292	9438723	1	9646	466	
		10	—	(1) 1005.02	(0)	100.00	0.00	84.68	0.00	2170	4914	5017512	1	3878	225	
C	2	0.34	(0) —	(1)	75.02	30.33	0.00	30.31	554	80356	367	37	22	1064		
	5	379.06	(0) —	(1)	100.00	41.37	0.00	41.37	1160	15314	443313	14	137	143		
	10	—	(1) —	(1)	100.00	37.49	46.67	36.94	2170	12538	5837062	213	2937	98		
K	2	1135.78	(0) —	(1)	91.28	15.46	0.00	15.46	554	10042	1334361	3	84	926		
	5	—	(1) —	(1)	100.00	24.86	68.28	24.86	1160	6541	4368607	4	6095	324		
	10	—	(1) —	(1)	100.00	23.05	79.98	23.04	2170	7164	2448072	15	1851	205		
D	2	—	(1) 328.07	(0)	94.07	0.00	37.30	0.00	554	8035	12235346	1	7096	1485		
	5	—	(1) 4430.48	(0)	100.00	0.08	78.70	0.00	1160	5415	5502769	5	8618	485		
	10	—	(1) 1408.05	(0)	100.00	0.00	86.81	0.00	2170	4914	3617149	2	4412	219		
S	2	—	(1) 516.57	(0)	93.95	0.00	37.29	0.00	554	7579	8797114	1	4912	1387		
	5	—	(1) —	(1)	100.00	0.57	79.68	0.57	1160	5704	5750451	5	9004	508		
	10	—	(1) 3413.97	(0)	100.00	0.00	87.36	0.00	2170	4962	3126980	5	5175	230		
A	2	—	(1) —	(1)	91.49	10.36	19.20	10.36	554	8056	3163853	2	1161	1369		
	5	—	(1) —	(1)	100.00	19.06	67.25	18.75	1160	5872	2177800	4	3290	542		
	10	—	(1) —	(1)	100.00	10.17	78.48	9.36	2170	5764	2718050	16	1862	268		
Total Average:			645.10	(229)	772.80	(171)	96.71	10.19	35.81	7.98	897	13958	6581088	1111	3014	427

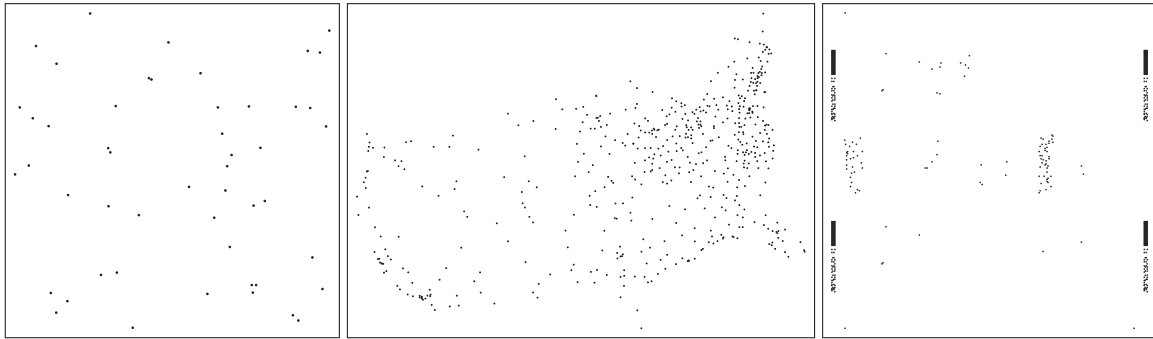


Fig. 1. Demand points of each of the instances that we use in our computational study: $n = 50$, $n = 532$, and $n = 654$ (from left to right).

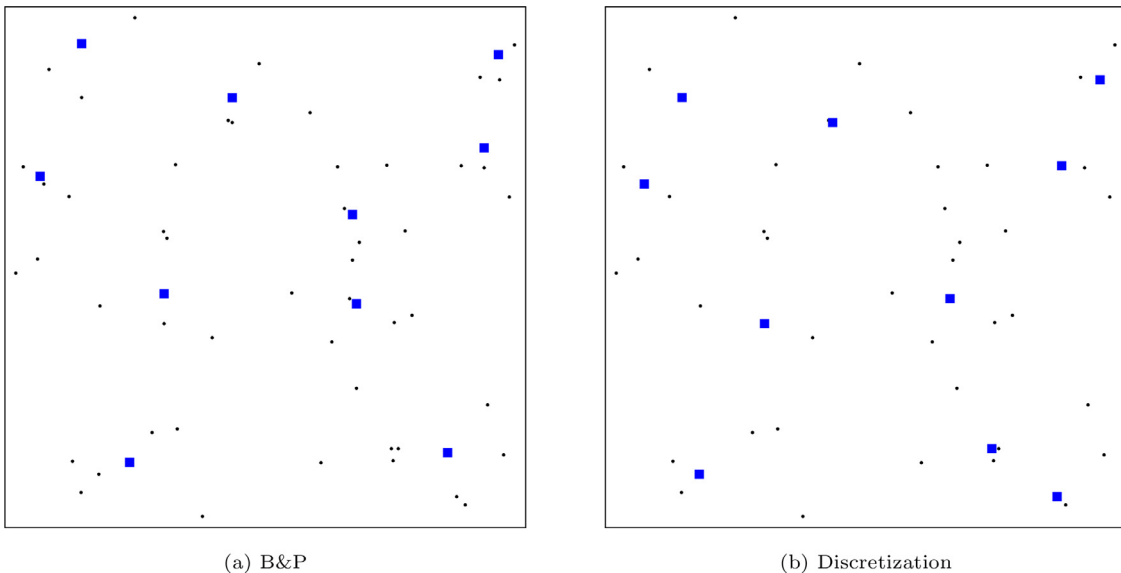


Fig. 2. Solutions for $n = 50$ (Eilon et al., 1971), S , $p = 10$, and ℓ_1 -norm.

of nodes (Nodes) explored in the branch-and-bound tree; and, in the last one, the RAM memory (Memory (MB)) in Megabytes required during the execution process is reported. Within each column, we highlight in bold the best result between the two formulations, namely Compact or B&P.

The branch-and-price algorithm is able to solve optimally 58 instances more than the compact formulation. However, for some instances (mainly Center and k -center problems or when $p = 2$) the solved instances with the compact formulation need less CPU time. Thus, the first conclusion could be that when p increases de-

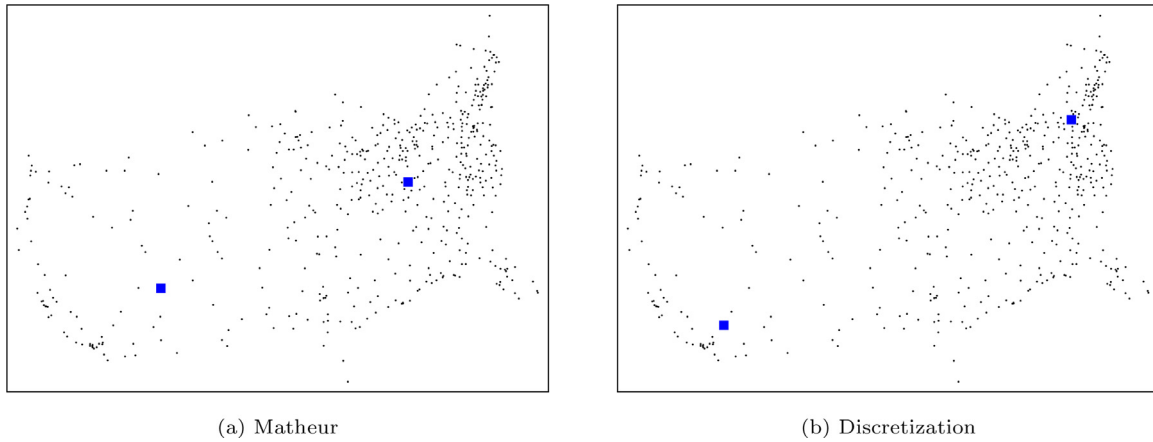


Fig. 3. Solutions for $n = 532$ (Padberg & Rinaldi, 1987), C , $p = 2$, and ℓ_1 -norm.

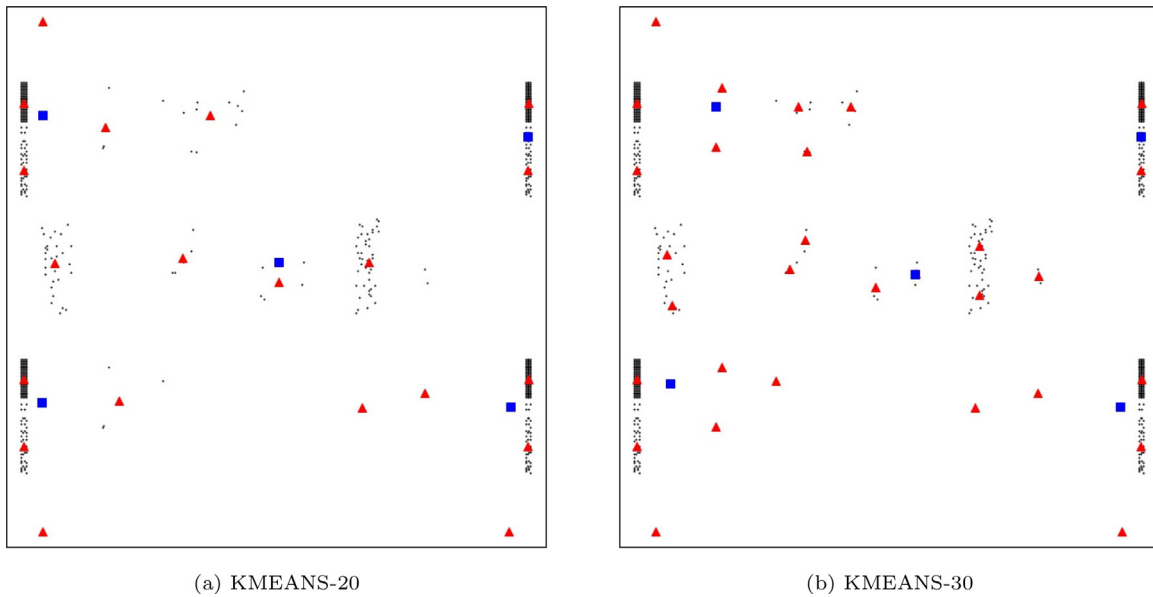


Fig. 4. Solutions for $n = 654$ (Reinelt, 1992), W , $p = 5$, and ℓ_1 -norm.

composition techniques become more important because the number of variables is not so dependant of this parameter. The second conclusion from the results is that the branch-and-price is a very powerful tool when the gap at the root node is close to zero which does not happen when a big percentage of the positions of the λ -vector are zeros. Concerning the memory used by the tested formulations, the compact formulation needs bigger branch-and-bound trees to deal with fractional solutions whereas that branch-and-price uses more variables.

Since the average gap at termination for the branch-and-price algorithm is much smaller than the one obtained by the compact formulation (7.98% against 35.81%), we will use decomposition-based algorithms to study medium- and large-sized instances.

5.2. Computational performance of the matheuristics

In this section, we show the performance of our matheuristic procedures. Firstly, we will test them for $n = 50$ (Eilon et al., 1971) where the solutions can be compared with the theoretic bounds provided by the exact method. Secondly, we will compare them using larger instances. Specifically, we use two instances from the TSP library (Reinelt, 1991), which is a well known repository of complex instances for the the TSP and re-

lated problems (Goldengorin & Krushinsky, 2011): att532.tsp and p654.tsp. They contain the coordinates of 532 cities of the continental US (Padberg & Rinaldi, 1987) and 654 points from a drilling problem example (Reinelt, 1992), respectively. The spatial distribution of the demand points for each of the instances that we use is shown in Fig. 1, where one can see the different nature of the datasets that we test.

Tables 5, 6, and 7 present a similar layout. The instances are solved with 18 different configurations of ordered weighted median functions and number of open facilities. Each of these 18 problems has been solved by means of the following strategies: branch-and-price procedure (B&P); the heuristic used to generate initial columns (InitialHeur); the decomposition-based heuristic (Matheur); the aggregation-based approaches described in Section 4.2 (KMEANS-20, KMEANS-30, PTF-20, PTF-30) for $|\mathcal{A}'| = \{20, 30\}$; and the discretization strategy explained in Section 4.3 (Discretization). The reported results are the CPU time and:

1. the gap ($GAP_{LB}(\%)$) which is calculated with respect to the lower bound of the branch-and-price algorithm when the time limit is reached. Thereby, we have a theoretic gap knowing exactly the room for improvement of our heuristics;

Table 5
Heuristic results for instances of $n = 50$, Eilon et al. (1971).

type	p	B&P		InitialHeur		Matheur		KMEANS-20		KMEANS-30		PTF-20		PTF-30		Discretization	
		Time	GAP _{LB} (%)	Time	GAP _{LB} (%)	Time	GAP _{LB} (%)	Time	GAP _{LB} (%)	Time	GAP _{LB} (%)	Time	GAP _{LB} (%)	Time	GAP _{LB} (%)	Time	GAP _{LB} (%)
W	2	331.87	0.00	0.00	1.44	134.54	0.00	74.60	3.10	5204.85	2.80	35.14	7.58	7200.18	2.50	12.94	1.23
	5	410.87	0.00	0.00	11.53	9.51	0.00	21.47	12.55	398.93	11.25	16.38	17.88	187.03	7.90	2680.48	1.17
	10	1005.02	0.00	0.00	21.57	2.84	0.00	4.23	17.16	59.08	8.79	16.11	23.45	57.35	9.88	4.95	3.11
C	2	7200.64	43.49	0.00	43.49	6.61	39.68	7200.16	47.05	7200.52	32.36	7200.21	31.46	7200.47	41.39	7205.96	43.11
	5	7200.19	70.56	0.00	73.45	7200.00	46.66	7200.09	82.76	7200.10	76.52	7200.09	94.74	7200.09	72.70	7203.66	70.86
	10	7200.19	58.58	0.00	101.43	7200.18	28.93	7200.16	104.98	7200.19	73.44	7200.16	154.72	7200.18	70.54	7203.84	87.77
K	2	7200.13	18.28	0.00	21.40	227.64	19.79	3589.02	21.19	7200.40	22.00	7200.35	20.05	7200.57	18.81	7203.55	16.83
	5	7200.34	33.09	0.00	33.09	392.07	22.37	7200.10	26.84	7200.15	36.08	7200.10	42.99	7200.13	30.43	7203.81	26.59
	10	7200.28	29.94	0.00	41.73	864.26	11.79	7200.17	35.38	7200.20	19.91	7200.17	41.97	7200.19	15.93	7202.90	38.36
D	2	328.07	0.00	0.00	1.45	130.00	0.00	42.82	3.76	5213.35	2.82	18.77	7.70	5105.83	2.47	5730.24	1.25
	5	4430.48	0.00	0.00	11.43	10.73	0.00	7.87	12.53	162.45	10.95	17.50	16.36	191.88	8.13	4714.13	1.12
	10	1408.05	0.00	0.00	21.38	3.06	0.43	4.76	17.00	50.22	10.18	22.26	23.27	135.57	9.07	811.58	3.03
S	2	516.57	0.00	0.00	1.62	111.73	0.00	25.43	2.97	7200.20	2.59	35.77	7.34	7200.27	2.33	7203.79	1.24
	5	7200.43	0.57	0.00	12.28	14.96	0.64	36.68	12.60	498.07	11.81	41.88	18.33	746.57	8.26	7203.80	1.77
	10	3413.97	0.00	0.00	21.24	3.22	0.66	10.99	16.86	29.98	7.98	50.52	23.29	114.10	8.97	2756.51	4.06
A	2	7200.39	11.56	0.00	11.56	155.18	10.91	2611.77	9.05	7200.15	10.62	7200.41	13.49	7200.09	13.69	7203.98	10.27
	5	7200.40	23.08	0.00	23.61	325.35	14.00	7200.10	19.96	7200.16	18.63	7200.11	26.03	7200.13	22.18	7204.38	16.41
	10	7200.24	10.33	0.00	31.65	129.77	6.29	7200.17	17.48	7200.21	16.63	7200.17	33.49	7200.21	21.82	7204.03	22.39
Total Average:		4658.23	16.64	0.00	26.97	940.09	11.23	3157.25	25.73	4645.51	20.85	3614.23	33.56	4763.38	20.39	5330.81	19.48

Table 6
Heuristic results for instances of $n = 532$, Padberg & Rinaldi (1987).

type	p	B&P		InitialHeur		Matheur		KMEANS-20		KMEANS-30		PTF-20		PTF-30		Discretization	
		Time	GAP _{Best} (%)	Time	GAP _{Best} (%)	Time	GAP _{Best} (%)	Time	GAP _{Best} (%)	Time	GAP _{Best} (%)	Time	GAP _{Best} (%)	Time	GAP _{Best} (%)	Time	GAP _{Best} (%)
W	2	86427.79	3.78	0.04	3.78	86427.79	3.78	214.12	13.36	607.50	6.06	29.81	3.09	807.38	12.08	86465.01	0.00
	5	86430.70	3.16	0.04	3.16	86430.70	3.16	15.25	27.80	115.15	21.13	38.83	15.75	296.68	18.38	86417.45	0.00
	10	86431.06	1.62	0.04	2.59	86431.06	1.62	7.16	27.35	310.76	35.82	7.42	40.26	51.25	36.48	86423.45	0.00
C	2	86406.87	0.08	0.04	0.08	38146.48	0.00	86403.24	4.55	86400.09	12.48	86428.73	9.69	86401.42	8.36	86474.06	1.70
	5	86407.73	6.65	0.04	6.65	12456.56	6.65	86400.07	18.75	86400.10	31.08	86400.07	17.39	86400.10	3.09	86427.62	0.00
	10	86407.25	28.72	0.04	28.72	86405.98	28.72	15064.77	33.06	86400.16	0.00	14624.77	59.63	86400.16	18.58	86460.43	7.32
K	2	86419.13	2.23	0.04	2.23	86419.13	2.23	1601.48	7.51	86406.88	9.01	3974.78	7.09	86403.41	8.29	86445.75	0.00
	5	86418.39	2.64	0.04	2.64	86418.39	2.64	86400.08	16.05	86400.12	15.28	86400.09	21.98	86402.98	21.14	86462.28	0.00
	10	86418.91	4.83	0.04	4.83	86418.91	4.83	13699.21	83.01	86400.17	9.35	86400.13	37.08	86400.18	31.92	86446.91	0.00
D	2	86428.55	3.78	0.04	3.78	86428.55	3.78	234.79	12.45	809.15	5.78	17.49	2.85	206.49	12.99	86448.31	0.00
	5	86427.84	3.16	0.04	3.16	86427.84	3.16	35.12	26.28	119.24	21.67	75.10	14.79	241.96	15.48	86466.61	0.00
	10	86427.84	1.61	0.04	2.59	86427.84	1.61	8.04	24.60	656.42	23.75	14.80	45.41	37.98	35.53	86464.28	0.00
S	2	86428.95	3.71	0.04	3.71	86428.95	3.71	518.28	13.83	7700.72	5.74	49.64	2.85	408.46	12.02	86451.83	0.00
	5	86428.30	2.95	0.04	2.95	86428.30	2.95	29.61	26.42	1267.17	20.84	87.31	15.90	661.87	13.14	86427.65	0.00
	10	86428.12	2.63	0.04	2.63	86428.12	2.63	19.91	30.84	1681.79	38.23	40.72	44.90	76.69	35.11	86468.68	0.00
A	2	86428.30	2.79	0.04	2.79	86428.30	2.79	798.53	4.91	86402.27	2.72	1291.04	7.08	74404.87	11.16	86434.48	0.00
	5	86426.24	2.28	0.04	2.28	86426.24	2.28	66616.11	15.03	86400.12	18.50	20039.72	26.95	86400.25	16.98	86419.49	0.00
	10	86426.11	4.03	0.04	4.03	86426.11	4.03	17972.81	10.69	86400.17	16.75	86400.13	31.32	86400.18	29.85	86482.04	0.00
Total Average:		86423.23	4.48	0.04	4.59	79633.63	4.48	20891.03	22.03	43937.66	16.34	26240.03	22.45	42689.02	18.92	86449.24	0.50

Table 7
Heuristic results for instances of $n = 654$, Reinelt (1992).

type	p	B&P		InitialHeur		Matheur		KMEANS-20		KMEANS-30		PTF-20		PTF-30		Discretization	
		Time	GAP _{Best} (%)	Time	GAP _{Best} (%)	Time	GAP _{Best} (%)	Time	GAP _{Best} (%)	Time	GAP _{Best} (%)	Time	GAP _{Best} (%)	Time	GAP _{Best} (%)	Time	GAP _{Best} (%)
W	2	86441.18	18.56	0.06	18.56	86441.18	18.56	13.31	8.04	755.99	40.81	32.59	19.19	697.98	40.02	86426.03	0.00
	5	86444.11	13.10	0.06	13.10	86444.11	13.10	6.56	45.35	97.79	79.07	7.46	68.54	74.85	76.34	86408.63	0.00
	10	86439.34	15.13	0.06	15.13	86439.34	15.13	2.64	101.43	31.49	112.39	1.58	157.47	68.11	133.94	86437.47	0.00
C	2	86407.88	4.16	0.07	4.16	86407.32	0.00	420.97	8.91	86400.83	3.43	5765.05	0.00	86401.06	0.00	86436.12	2.27
	5	86407.52	6.54	0.06	6.54	51003.35	4.47	86424.42	32.61	86400.09	0.00	86400.15	20.98	86400.09	1.64	86420.51	12.42
	10	86408.46	20.39	0.06	20.39	83212.74	3.23	42425.62	31.02	86400.17	1.36	86400.16	63.01	86400.13	2.00	86419.39	0.00
K	2	86424.57	5.30	0.06	5.30	86424.57	5.30	274.39	4.34	40549.49	14.86	365.79	13.07	15942.12	10.65	86404.35	0.00
	5	86424.89	11.27	0.06	11.27	86424.89	11.27	854.51	38.53	86400.13	64.01	2868.28	49.15	86400.26	42.60	86441.63	0.00
	10	86425.31	32.55	0.06	32.55	86425.31	32.55	6695.50	149.41	86400.19	105.65	13189.85	162.33	86400.14	126.61	86436.97	0.00
D	2	86440.98	18.55	0.07	18.55	86440.98	18.55	29.22	6.78	737.65	40.14	23.55	18.85	669.43	39.84	86429.90	0.00
	5	86440.05	13.09	0.06	13.09	86440.05	13.09	15.08	46.33	123.71	81.13	6.47	71.68	96.06	82.16	86444.51	0.00
	10	86439.96	15.12	0.06	15.12	86439.96	15.12	7.19	99.40	21.26	101.71	3.05	156.24	106.33	133.98	86428.90	0.00
S	2	86440.27	17.23	0.07	17.23	86440.27	17.23	19.02	8.52	427.39	37.97	27.17	18.58	515.89	36.72	86424.95	0.00
	5	86439.85	12.69	0.07	12.69	86439.85	12.69	9.14	45.19	200.77	77.05	6.68	68.55	143.32	79.93	86421.39	0.00
	10	86440.73	15.01	0.06	15.01	86440.73	15.01	6.69	102.11	32.23	108.25	2.44	156.15	107.15	134.09	86437.97	0.00
A	2	86439.83	7.51	0.06	7.51	86439.83	7.51	264.51	3.79	11439.37	13.09	416.03	10.15	6083.81	11.98	86432.48	0.00
	5	86443.12	9.69	0.06	9.69	86443.12	9.69	256.67	35.94	40907.89	51.62	414.57	43.77	15986.23	42.06	86405.38	0.00
	10	86438.72	33.58	0.06	33.58	86438.72	33.58	4315.73	86.09	86400.18	121.59	29377.52	127.07	86400.14	121.93	86407.30	0.00
Total Average:		86432.60	14.97	0.06	18.18	84288.13	13.67	7891.18	47.43	34095.92	58.56	12517.13	68.04	31049.62	62.03	86425.77	0.82

2. or $GAP_{Best}(\%)$ as the gap with respect to the best known integer solution. We calculate it for large-sized instances since the branch-and-price provides poor lower bounds even using (15).

In order to obtain Table 5, a time limit of 2 h was fixed for this experiment with $n = 50$. For these instances, B&P and Matheur report the best performance in most of the cases. In general they present less gap and, on average, it is better not wasting the time solving the exact pricer letting the algorithm go further adding columns or branching before certifying optimality. Thus, with the Matheur strategy we obtain an 11.23% of average gap. In fact, this matheuristic finds the optimal solution (certified by the exact method) at least in six instances. Concerning the time, only InitialHeur needs much smaller CPU time, obtaining good quality solutions for some instances. For the Eilon dataset, the aggregation schemes exhibit that the larger the aggregated set the smaller the gap and the larger the CPU time, as expected.

Fig. 2 illustrates the optimal solution (square points) of a particular instance (B&P) and the solution when the solution space is limited to the demand points coordinates (Discretization). One can observe in that figure that although the continuous nature of the problem is not completely captured by the discrete version of the problem, the structure of the clusters of demand points obtained by discretizing the space is similar to the one obtained by the exact approach, being this method an adequate heuristic for larger instances in which the exact approach is not able to certify optimality.

For large-sized problems (Tables 6 and 7) we set the time limit to 24 h. The best solutions are found by the discretization matheuristic except for the center problems (see Fig. 3 where the solutions obtained with the Matheur and the Discretization approaches clearly differ). Among the other strategies, decomposition-based matheuristic stands out, but the improvement from the initial heuristic is null for some cases. The reader may note that in many of these large-sized instances the results of B&P and Matheur coincide. For these instances, the relaxed restricted master problem is big enough to expend in each iteration a considerable amount of time to be solved. Thus, within the time limit, B&P does not solve any pricing subproblem to optimality what makes its results coincide with the ones obtained by Matheur.

Some instances have the best performance using KMEANS-20 or PTF-20 matheuristics. Not much improvement is appreciated taking 30 points instead of 20 for the aggregation method. To find an explanation for that, Fig. 4 depicts the aggregation (triangular points) and the solution for a particular instance. The reader can see how the demand points are concentrated by zones. Adding more points to \mathcal{A}' gives an importance to some aggregated points that does not represent properly the original data of this instance of $n = 654$. In this case, we can see an example for which the aggregation algorithm works better under the *less is more* paradigm.

6. Conclusions

In this work, the Continuous Multifacility Monotone Ordered Median Problem is analyzed. To solve this problem, defined in a continuous space, we have proposed two exact methods, namely a compact formulation and a branch-and-price procedure, using binary variables. Along the paper, we give full details of the branch-and-price algorithm and all its crucial steps: master problem, restricted relaxed master problem, pricing problem, initial pool of columns, feasibility, convergence, and branching.

Moreover, theoretic and empirical results have proven the utility of the obtained lower bound. Using that bound, we have tested three matheuristics that we propose. The decomposition-based heuristics have shown a very good performance on the computa-

tional experiments. For large-sized instances, the best known solutions have been obtained reducing the solution space by means of a discretization of the continuous problem.

Among the extensive computational experiments and configurations of the problem, we highlight the usefulness of the branch-and-price approach for medium- to large-sized instances, but also the utility of the compact formulation and the aggregation-based heuristics for small values of p or for some particular ordered weighted median functions.

Further research on the topic includes the design of similar branch-and-price approaches to other continuous facility location and clustering problems. Specifically, the application of set-partitioning column generation methods to hub location and covering problems with generalized upgrading (see, e.g., Blanco & Marín, 2019) where the index set for the y -variables must be adequately defined.

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Appendix A. Computational results for alternative ℓ_τ -norms

In this section, we show the results of our computational experiments for other ℓ_τ -norms, in particular, we have considered $\tau \in \{\frac{3}{2}, 2, 3\}$. We have shown in Theorem 1 the general way to

Table A1
Constraints for different values of τ to represent ℓ_τ -norms.

$\ell_{\frac{3}{2}}$	ℓ_2	ℓ_3
$t_{ijl} \geq a_{il} - x_{jl},$	$t_{ijl} \geq a_{il} - x_{jl},$	$t_{ijl} \geq a_{il} - x_{jl},$
$t_{ijl} \geq -a_{il} + x_{jl},$	$t_{ijl} \geq -a_{il} + x_{jl},$	$t_{ijl} \geq -a_{il} + x_{jl},$
$z_{ij} \geq \sum_{l=1}^d \xi_{ijl},$	$z_{ij}^2 \geq \sum_{l=1}^d t_{ijl}^2,$	$z_{ij} \geq \sum_{l=1}^d \xi_{ijl}$
$t_{ijl}^2 \leq \psi_{ijl} \xi_{ijl},$		$t_{ijl}^2 \leq \psi_{ijl} z_{ij},$
$\psi_{ijl}^2 \leq z_{ij} t_{ijl},$		$\psi_{ijl}^2 \leq \xi_{ijl} t_{ijl},$

formulate the constraint for general values of τ . In Table A.1, we present the sets of constraints for the τ considered, for all $i \in I, j \in J, l \in \{1, \dots, d\}$. Tables A.2 , A.3 , and A.4 report the results.

Appendix B. Aggregated results

In order to show the influence of p , the Ordered Median aggregation function, and the ℓ_τ -norm, we have aggregated the results of the 1512 instances used in Tables 4, A.2, A.3, and A.4 (Tables B.1, B.2, B.3).

Table A2
Results for Eilon et al. (1971) instances for $\ell_{\frac{3}{2}}$ -norm.

n	type	p	Time (#Unsolved)			GAProot (%)		GAP (%)		Vars		Nodes		Memory (MB)		
			Compact	B&P		Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	
20	W	2	75.10	(0)	966.81	(0)	100.00	0.00	0.00	0.00	524	500	31161	1	187	25
		5	–	(5)	332.73	(0)	100.00	0.00	58.11	0.00	1270	397	2323815	1	11580	12
		10	–	(5)	152.66	(0)	100.00	0.00	97.34	0.00	2480	377	1280023	1	7438	10
	C	2	0.70	(0)	520.73	(4)	100.00	21.46	0.00	17.11	524	13259	317	650	9	174
		5	57.47	(0)	74.10	(4)	100.00	34.21	0.00	33.65	1270	1333	15338	302	44	13
		10	3863.55	(1)	1270.00	(2)	100.00	18.56	2.45	17.81	2480	1638	1164203	1936	1159	15
	K	2	6.23	(0)	1227.76	(2)	100.00	6.46	0.00	2.58	524	7247	3052	197	20	212
		5	–	(5)	824.52	(3)	100.00	10.90	27.82	6.21	1270	2719	3205611	1120	7563	57
		10	–	(5)	2409.37	(3)	100.00	17.66	96.76	8.78	2480	1235	1093174	3003	8496	24
	D	2	63.65	(0)	724.11	(0)	100.00	0.00	0.00	0.00	524	437	31224	1	153	22
		5	–	(5)	284.21	(0)	100.00	0.00	65.95	0.00	1270	383	2204675	1	12441	11
		10	–	(5)	163.89	(0)	100.00	0.08	95.40	0.00	2480	370	1140802	3	9200	9
	S	2	58.41	(0)	1040.72	(0)	100.00	0.00	0.00	0.00	524	519	25556	1	155	25
		5	–	(5)	3423.48	(0)	100.00	0.11	59.03	0.00	1270	397	2398328	3	12161	12
		10	–	(5)	175.32	(0)	100.00	0.34	98.74	0.00	2480	383	878394	4	8683	10
A	2	16.20	(0)	2802.48	(1)	100.00	3.44	0.00	0.35	524	2987	5372	54	37	146	
	5	–	(5)	2131.87	(2)	100.00	10.91	47.25	3.22	1270	2548	1996233	413	8655	69	
	10	–	(5)	3440.13	(1)	100.00	11.84	99.32	2.01	2480	1288	705456	2001	7031	30	
30	W	2	3007.98	(0)	854.86	(4)	86.97	19.38	0.00	19.38	784	852	1101778	1	2823	71
		5	–	(5)	3389.46	(3)	87.13	22.60	79.53	22.60	1900	845	744808	1	12424	47
		10	–	(5)	2960.90	(0)	89.05	0.00	88.07	0.00	3710	773	341608	2	3070	32
	C	2	1.27	(0)	110.41	(4)	81.07	30.05	0.00	26.62	784	10754	416	190	15	137
		5	311.13	(0)	–	(5)	81.71	45.91	0.00	44.26	1900	3340	57541	200	116	33
		10	4.95	(4)	–	(5)	81.93	45.96	75.89	45.96	3710	1758	407909	231	1166	17
	K	2	77.50	(0)	19.84	(4)	85.63	39.16	0.00	38.71	784	1708	28803	5	115	80
		5	–	(5)	20.48	(4)	85.80	18.37	66.83	17.99	1900	1986	956059	19	11102	61
		10	–	(5)	194.29	(4)	86.29	22.05	84.71	21.13	3710	1574	390091	234	2707	42
	D	2	2441.14	(1)	300.79	(4)	86.55	22.86	2.74	22.86	784	918	1208553	1	3490	77
		5	–	(5)	4831.03	(2)	86.99	24.04	74.25	24.04	1900	841	798302	3	10071	48
		10	–	(5)	2546.68	(0)	87.46	0.05	86.29	0.00	3710	774	343890	2	4196	32
	S	2	2363.80	(0)	470.41	(4)	86.86	32.35	0.00	32.35	784	895	822524	1	2187	72
		5	–	(5)	4534.78	(2)	86.78	18.98	76.88	18.98	1900	840	726885	1	10244	48
		10	–	(5)	2666.23	(0)	88.10	0.04	87.16	0.00	3710	776	410399	5	4551	31
A	2	327.89	(0)	93.44	(4)	85.31	49.21	0.00	49.18	784	1259	70967	2	365	104	
	5	–	(5)	95.22	(4)	86.39	7.72	70.59	7.37	1900	1346	626210	9	8166	74	
	10	–	(5)	169.25	(4)	86.14	13.71	84.74	10.99	3710	1487	307003	141	2647	54	
40	W	2	–	(5)	–	(5)	100.00	32.33	45.10	32.33	1044	1292	1282229	1	15092	131
		5	–	(5)	–	(5)	100.00	67.86	96.95	67.86	2530	1298	364182	1	8105	102
		10	–	(5)	–	(5)	100.00	92.83	100.00	92.83	4940	1339	165306	1	2712	83
	C	2	4.22	(0)	–	(5)	100.00	44.51	0.00	44.51	1044	2468	1043	2	20	35
		5	3879.78	(3)	–	(5)	100.00	77.56	41.01	77.56	2530	2525	606460	2	4626	27
		10	–	(5)	–	(5)	100.00	78.16	91.15	78.16	4940	2206	237096	13	883	22
	K	2	2889.87	(0)	–	(5)	100.00	61.39	0.00	61.39	1044	2226	614033	1	2098	125
		5	–	(5)	–	(5)	100.00	83.30	92.54	83.30	2530	2213	451617	1	4187	94
		10	–	(5)	–	(5)	100.00	75.79	100.00	75.79	4940	2169	163856	3	1240	83
	D	2	–	(5)	–	(5)	100.00	32.13	40.95	32.13	1044	1529	1548255	1	11470	153
		5	–	(5)	–	(5)	100.00	68.37	99.29	68.37	2530	1310	360994	1	12324	99
		10	–	(5)	–	(5)	100.00	91.94	100.00	91.94	4940	1357	141565	1	4573	79
	S	2	–	(5)	–	(5)	100.00	30.53	42.63	30.53	1044	1443	1109568	1	14496	145
		5	–	(5)	–	(5)	100.00	72.37	98.23	72.37	2530	1299	358058	1	11144	97
		10	–	(5)	–	(5)	100.00	90.94	100.00	90.94	4940	1362	176603	1	2825	76
A	2	2886.85	(4)	–	(5)	100.00	61.20	14.49	61.20	1044	1876	1127650	1	3383	212	
	5	–	(5)	–	(5)	100.00	82.57	93.62	82.57	2530	1656	402572	1	4383	134	
	10	–	(5)	–	(5)	100.00	75.96	100.00	75.96	4940	1782	145643	1	2437	114	
45	W	2	–	(5)	–	(5)	100.00	34.65	46.87	34.65	1174	1462	974796	1	11024	145
		5	–	(5)	–	(5)	100.00	83.70	97.65	83.70	2845	1444	367765	1	3877	126
		10	–	(5)	–	(5)	100.00	100.00	100.00	100.00	5555	1522	122910	1	1081	101
	C	2	6.63	(0)	–	(5)	100.00	57.24	0.00	57.24	1174	2438	1160	1	23	34
		5	4337.92	(3)	–	(5)	100.00	84.59	49.89	84.59	2845	2696	467399	1	1217	33
		10	–	(5)	–	(5)	100.00	64.84	96.12	64.84	5555	2327	135558	3	578	24
	K	2	6688.87	(4)	–	(5)	100.00	63.44	14.13	63.44	1174	2443	1718920	1	6733	142
		5	–	(5)	–	(5)	100.00	71.76	95.10	71.76	2845	2663	453635	1	3364	169
		10	–	(5)	–	(5)	100.00	91.29	99.70	91.29	5555	2231	158192	1	781	97
	D	2	–	(5)	–	(5)	100.00	30.83	48.64	30.83	1174	1508	933735	1	10637	153
		5	–	(5)	–	(5)	100.00	91.29	98.36	91.29	2845	1470	374986	1	5117	129
		10	–	(5)	–	(5)	100.00	100.00	100.00	100.00	5555	1528	159745	1	1184	106
	S	2	–	(5)	–	(5)	100.00	31.76	45.32	31.76	1174	1556	1059244	1 </		

Table A2 (continued)

n	type	p	Time (#Unsolved)			GAProot(%)		GAP(%)		Vars		Nodes		Memory (MB)		
			Compact	B&P		Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	
50	W	2	—	(1)	—	(1)	100.00	36.39	57.48	36.39	1304	1749	759779	1	11084	186
		5	—	(1)	—	(1)	100.00	88.42	97.49	88.42	3160	1659	270228	1	3125	135
		10	—	(1)	—	(1)	100.00	100.00	100.00	100.00	6170	1777	122705	1	1843	127
	C	2	6.06	(0)	—	(1)	100.00	57.05	0.00	57.05	1304	2813	879	1	28	36
		5	—	(1)	—	(1)	100.00	94.44	86.11	94.44	3160	2767	489141	1	1274	41
		10	—	(1)	—	(1)	100.00	66.91	100.00	66.91	6170	2678	117338	2	535	32
	K	2	—	(1)	—	(1)	100.00	66.85	22.51	66.85	1304	2554	1624297	1	9722	141
		5	—	(1)	—	(1)	100.00	95.48	92.64	95.48	3160	2458	501803	1	1496	132
		10	—	(1)	—	(1)	100.00	99.57	100.00	99.57	6170	2418	128940	1	669	115
	D	2	—	(1)	—	(1)	100.00	31.81	51.21	31.81	1304	1704	1059488	1	10438	182
		5	—	(1)	—	(1)	100.00	91.53	97.42	91.53	3160	1671	405884	1	1222	156
		10	—	(1)	—	(1)	100.00	100.00	100.00	100.00	6170	1710	156712	1	1360	127
	S	2	—	(1)	—	(1)	100.00	23.29	56.18	23.29	1304	2040	757576	1	10234	215
		5	—	(1)	—	(1)	100.00	46.71	98.40	46.71	3160	1772	404250	1	2374	166
		10	—	(1)	—	(1)	100.00	100.00	100.00	100.00	6170	1739	144453	1	764	131
	A	2	—	(1)	—	(1)	100.00	58.75	40.71	58.75	1304	2006	519352	1	6759	215
		5	—	(1)	—	(1)	100.00	86.23	95.15	86.23	3160	2175	396890	1	2119	208
		10	—	(1)	—	(1)	100.00	100.00	100.00	100.00	6170	2127	127758	1	672	183
Total Average:			1016.47	(282)	1438.77	(277)	96.64	44.54	59.19	43.82	2451	1902	628495	143	4813	85

Table A3

Results for Eilon et al. (1971) instances for ℓ_2 -norm.

n	type	p	Time (#Unsolved)			GAProot(%)		GAP(%)		Vars		Nodes		Memory (MB)		
			Compact	B&P		Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	
20	W	2	26.03	(0)	24.22	(0)	100.00	0.00	0.00	0.00	204	2385	50632	1	41	120
		5	—	(5)	20.33	(0)	100.00	0.00	52.53	0.00	470	2504	8992191	1	15633	53
		10	—	(5)	9.15	(0)	100.00	0.00	89.75	0.00	880	2178	5306625	1	13982	28
	C	2	0.16	(0)	757.86	(4)	100.00	18.45	0.00	10.76	204	45528	119	13798	4	962
		5	16.30	(0)	—	(5)	100.00	32.78	0.00	21.37	470	7002	13102	7867	31	148
		10	983.51	(0)	2223.12	(3)	100.00	27.39	0.00	10.97	880	3717	650055	9690	1569	75
	K	2	5.03	(0)	1648.82	(1)	100.00	7.02	0.00	1.49	204	11126	6787	349	11	301
		5	4231.23	(4)	2850.11	(2)	100.00	13.04	23.89	2.37	470	5627	8109266	1830	7136	117
		10	—	(5)	1822.27	(2)	100.00	16.01	85.45	6.61	880	2925	4227203	4287	11279	68
	D	2	25.62	(0)	20.60	(0)	100.00	0.00	0.00	0.00	204	2365	45501	1	37	119
		5	—	(5)	15.53	(0)	100.00	0.00	50.45	0.00	470	2495	9156476	1	11659	52
		10	—	(5)	17.64	(0)	100.00	0.05	87.20	0.00	880	2175	5927899	2	15624	28
	S	2	25.31	(0)	28.86	(0)	100.00	0.00	0.00	0.00	204	2445	42178	1	37	126
		5	—	(5)	49.89	(0)	100.00	0.03	49.72	0.00	470	2491	9117840	3	12277	53
		10	—	(5)	24.45	(0)	100.00	0.25	87.53	0.00	880	2183	5399238	4	15145	29
	A	2	15.72	(0)	1663.90	(1)	100.00	3.21	0.00	0.17	204	6400	13975	133	19	288
		5	—	(5)	1603.15	(2)	100.00	9.93	36.09	1.74	470	5066	6284524	703	9720	138
		10	—	(5)	2420.97	(1)	100.00	15.86	87.63	0.94	880	2987	3478065	2125	11095	60
30	W	2	1214.67	(0)	264.29	(0)	86.79	0.00	0.00	304	3787	1814638	1	559	339	
		5	—	(5)	80.27	(0)	86.91	0.00	72.61	0.00	700	2914	3104800	1	12866	107
		10	—	(5)	34.14	(0)	87.86	0.00	84.94	0.00	1310	2474	1626671	1	18935	54
	C	2	0.43	(0)	104.99	(4)	81.07	14.80	0.00	11.58	304	45929	422	1794	6	643
		5	76.89	(0)	503.59	(4)	81.71	27.87	0.00	20.17	700	8380	40315	1409	165	100
		10	1.89	(4)	—	(5)	81.93	38.05	41.89	33.92	1310	4996	2709802	2978	4156	69
	K	2	54.31	(0)	744.55	(4)	85.50	6.60	0.00	6.45	304	7743	62564	44	58	368
		5	—	(5)	5040.71	(4)	86.00	11.54	67.36	8.59	700	5932	2838928	295	15993	170
		10	—	(5)	—	(5)	87.68	17.84	83.29	13.27	1310	4040	1799130	1270	12831	88
	D	2	1247.78	(0)	222.14	(0)	86.38	0.00	0.00	0.00	304	3810	1731910	1	529	335
		5	—	(5)	139.30	(0)	86.94	0.00	73.46	0.00	700	2939	2824067	1	12906	108
		10	—	(5)	38.85	(0)	87.51	0.00	85.28	0.00	1310	2480	1519282	1	16694	55
	S	2	1271.98	(0)	186.78	(0)	86.69	0.00	0.00	0.00	304	3699	1631950	1	518	324
		5	—	(5)	540.52	(0)	87.12	0.02	73.42	0.00	700	2905	3042832	3	13666	109
		10	—	(5)	94.57	(0)	87.66	0.08	84.50	0.00	1310	2465	1569091	2	13710	55
	A	2	220.34	(0)	3254.28	(3)	85.20	2.15	0.00	1.69	304	4997	136052	16	110	403
		5	—	(5)	1745.13	(4)	86.59	5.37	71.23	3.06	700	4216	1909608	51	10892	174
		10	—	(5)	1207.09	(4)	86.97	11.27	83.28	6.38	1310	3735	1103129	465	10680	106

(continued on next page)

Table A3 (continued)

n	type	p	Time (#Unsolved)			GAProot(%)		GAP(%)		Vars		Nodes		Memory (MB)		
			Compact	B&P		Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	
40	W	2	—	(5)	252.49	(0)	100.00	0.00	31.03	0.00	404	6365	7312331	1	5864	817
		5	—	(5)	364.88	(0)	100.00	0.00	94.01	0.00	930	4168	1925927	1	11549	234
		10	—	(5)	355.67	(0)	100.00	0.00	99.63	0.00	1740	3922	862095	1	8294	120
	C	2	1.55	(0)	—	(5)	100.00	23.26	0.00	22.73	404	29032	1164	419	9	448
		5	594.78	(0)	—	(5)	100.00	36.17	0.00	35.69	930	5983	271138	92	862	57
		10	4207.08	(1)	—	(5)	100.00	37.29	11.40	35.81	1740	4780	1357589	266	5116	40
	K	2	719.29	(0)	—	(5)	100.00	8.69	0.00	8.69	404	5651	701127	4	429	412
		5	—	(5)	—	(5)	100.00	16.32	89.79	16.31	930	4724	1771444	4	11673	171
		10	—	(5)	—	(5)	100.00	16.50	99.43	16.47	1740	4836	700210	44	13117	100
	D	2	—	(5)	259.07	(0)	100.00	0.00	30.59	0.00	404	6694	6885185	1	7289	865
		5	—	(5)	485.52	(0)	100.00	0.00	94.27	0.00	930	4240	2040736	1	9260	238
		10	—	(5)	473.11	(0)	100.00	0.01	99.90	0.00	1740	3891	692838	1	10352	119
	S	2	—	(5)	691.25	(0)	100.00	0.02	29.89	0.00	404	6224	6075474	1	5159	806
		5	—	(5)	244.29	(0)	100.00	0.00	94.33	0.00	930	4120	2196020	1	11994	230
		10	—	(5)	1223.93	(0)	100.00	0.07	99.90	0.00	1740	3910	925128	3	11056	120
	A	2	3347.72	(4)	—	(5)	100.00	4.09	9.28	4.09	404	5760	2823594	2	1885	763
		5	—	(5)	—	(5)	100.00	9.56	91.43	9.08	930	4410	1346465	5	6365	258
		10	—	(5)	—	(5)	100.00	9.54	99.86	8.60	1740	4404	677970	41	9029	141
45	W	2	—	(5)	388.20	(0)	100.00	0.00	41.73	0.00	454	9960	4536228	1	6272	1570
		5	—	(5)	207.18	(0)	100.00	0.00	96.23	0.00	1045	4741	1544401	1	10363	360
		10	—	(5)	282.84	(0)	100.00	0.00	100.00	0.00	1955	4318	494940	1	10023	172
	C	2	2.49	(0)	—	(5)	100.00	22.33	0.00	22.32	454	4517	1618	6	13	67
		5	398.50	(0)	—	(5)	100.00	35.75	0.00	35.62	1045	4850	162356	10	453	46
		10	—	(5)	—	(5)	100.00	35.00	76.29	34.76	1955	4710	1628650	35	5534	36
	K	2	5287.03	(2)	—	(5)	100.00	12.13	5.66	12.12	454	6140	4935475	3	2537	535
		5	—	(5)	—	(5)	100.00	17.38	93.84	17.36	1045	5116	2086094	4	9338	226
		10	—	(5)	—	(5)	100.00	14.67	100.00	14.67	1955	4781	618710	5	11268	120
	D	2	—	(5)	358.37	(0)	100.00	0.00	40.50	0.00	454	9220	4961123	1	5740	1483
		5	—	(5)	207.01	(0)	100.00	0.00	96.12	0.00	1045	4756	1837767	1	8596	363
		10	—	(5)	483.48	(0)	100.00	0.00	100.00	0.00	1955	4310	486390	1	9703	172
	S	2	—	(5)	370.88	(0)	100.00	0.00	40.04	0.00	454	9566	4705056	1	5430	1507
		5	—	(5)	1332.07	(0)	100.00	0.20	95.75	0.00	1045	4809	2080272	4	10194	370
		10	—	(5)	1487.71	(0)	100.00	0.02	99.90	0.00	1955	4315	659990	3	10857	173
	A	2	—	(5)	—	(5)	100.00	6.72	25.73	6.26	454	6957	2069919	4	3364	1078
		5	—	(5)	—	(5)	100.00	11.97	91.39	11.12	1045	4895	1615563	6	3655	373
		10	—	(5)	—	(5)	100.00	7.59	100.00	7.46	1955	4486	483721	6	8786	172
50	W	2	—	(1)	456.01	(0)	100.00	0.00	48.21	0.00	504	10414	4777385	1	6240	2007
		5	—	(1)	615.74	(0)	100.00	0.03	96.50	0.00	1160	5458	1930033	3	6233	470
		10	—	(1)	204.96	(0)	100.00	0.00	100.00	0.00	2170	4971	355938	1	7946	232
	C	2	4.78	(0)	—	(1)	100.00	22.61	0.00	22.61	504	4342	2935	2	17	59
		5	—	(1)	—	(1)	100.00	34.42	67.17	34.37	1160	5142	2940681	4	5728	51
		10	—	(1)	—	(1)	100.00	40.27	83.64	40.21	2170	5198	1333733	18	3970	41
	K	2	—	(1)	—	(1)	100.00	11.24	18.49	11.24	504	6665	4998109	3	3635	673
		5	—	(1)	—	(1)	100.00	17.43	91.41	17.43	1160	5674	3154623	3	5249	284
		10	—	(1)	—	(1)	100.00	14.01	100.00	13.91	2170	5463	567705	7	10827	156
	D	2	—	(1)	405.36	(0)	100.00	0.00	47.33	0.00	504	9675	4367022	1	6329	1789
		5	—	(1)	209.77	(0)	100.00	0.00	94.73	0.00	1160	5302	2598004	1	4692	469
		10	—	(1)	605.10	(0)	100.00	0.00	100.00	0.00	2170	5000	548086	1	7504	233
	S	2	—	(1)	451.37	(0)	100.00	0.00	48.39	0.00	504	10286	3512436	1	6039	1986
		5	—	(1)	815.35	(0)	100.00	0.07	96.27	0.00	1160	5236	3055646	3	6241	459
		10	—	(1)	204.63	(0)	100.00	0.01	100.00	0.01	2170	4900	386889	1	9984	231
	A	2	—	(1)	—	(1)	100.00	5.95	32.08	5.36	504	8326	1790159	4	2035	1513
		5	—	(1)	—	(1)	100.00	12.91	91.62	11.92	1160	5559	1874166	7	3311	483
		10	—	(1)	—	(1)	100.00	7.13	100.00	6.88	2170	5089	462300	9	10198	231
Total Average:			673.68	(267)	557.40	(157)	96.65	8.44	53.08	6.79	886	6179	2347788	663	7186	310

Table A4
Results for Eilon et al. (1971) instances for ℓ_3 -norm.

n	type	p	Time (#Unsolved)		GAProot(%)		GAP(%)		Vars		Nodes		Memory (MB)			
			Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P		
20	W	2	151.03	(0)	743.17	(0)	100.00	0.00	0.00	0.00	524	471	56126	1	418	24
		5	—	(5)	267.56	(0)	100.00	0.00	62.95	0.00	1270	415	2700255	1	13112	14
		10	—	(5)	133.91	(0)	100.00	0.00	98.54	0.00	2480	406	1259405	1	13418	13
	C	2	0.91	(0)	—	(5)	100.00	30.56	0.00	29.19	524	9181	507	417	11	121
		5	71.86	(0)	—	(5)	100.00	35.58	0.00	30.56	1270	3061	17235	1473	62	32
		10	2142.39	(0)	—	(5)	100.00	47.17	0.00	47.00	2480	912	261767	553	879	8
	K	2	16.05	(0)	5363.15	(2)	100.00	9.14	0.00	2.07	524	12397	7592	424	40	352
		5	—	(5)	2946.11	(3)	100.00	14.87	38.13	5.02	1270	3466	2839547	1556	8104	75
		10	—	(5)	3206.51	(2)	100.00	8.25	93.62	5.18	2480	1348	1021924	2630	6013	23
	D	2	125.29	(0)	810.43	(2)	100.00	0.00	0.00	0.00	524	498	53138	1	300	26
		5	—	(5)	230.99	(0)	100.00	0.00	60.85	0.00	1270	382	2732256	1	12124	11
		10	—	(5)	112.30	(0)	100.00	0.09	99.24	0.00	2480	377	1083407	2	11367	10
	S	2	104.35	(0)	973.36	(0)	100.00	0.05	0.00	0.00	524	530	45754	1	239	27
		5	—	(5)	255.50	(0)	100.00	0.11	64.54	0.00	1270	398	2470849	2	10763	12
		10	—	(5)	125.04	(0)	100.00	0.26	99.51	0.00	2480	378	1131966	4	11380	10
A	2	33.54	(0)	2705.24	(1)	100.00	4.22	0.00	0.15	524	3049	11374	71	74	150	
	5	—	(5)	1648.71	(2)	100.00	8.18	42.12	1.90	1270	2262	2117999	329	6961	64	
	10	—	(5)	4194.46	(1)	100.00	13.35	99.33	1.41	2480	1216	842028	2054	8107	29	
30	W	2	2404.31	(4)	435.00	(4)	86.64	14.53	12.54	14.53	784	843	2130171	1	10112	65
		5	—	(5)	3934.80	(2)	86.35	5.57	77.53	5.57	1900	860	830494	1	12706	48
		10	—	(5)	2479.98	(0)	86.89	0.03	86.14	0.00	3710	816	306492	3	4764	37
	C	2	2.30	(0)	1631.39	(4)	81.07	29.54	0.00	29.53	784	7137	675	7559	17	94
		5	571.24	(0)	2360.18	(4)	81.71	48.42	0.00	46.18	1900	2388	71418	386	212	27
		10	8.07	(4)	1801.17	(4)	81.93	48.01	71.16	47.51	3710	1236	316323	33	1003	10
	K	2	211.31	(0)	17.36	(4)	85.39	24.11	0.00	23.96	784	1808	86793	7	303	81
		5	—	(5)	27.59	(4)	86.11	14.05	63.23	13.64	1900	1707	1143862	12	9716	52
		10	—	(5)	34.09	(4)	85.92	22.77	85.05	22.13	3710	1409	365197	168	4413	35
	D	2	4446.26	(3)	3777.09	(3)	86.24	18.03	10.14	18.03	784	946	2197143	1	9689	71
		5	—	(5)	3574.66	(2)	86.38	9.19	74.99	9.19	1900	853	958686	1	12995	45
		10	—	(5)	2472.72	(0)	86.60	0.06	85.43	0.00	3710	796	375899	3	5968	35
	S	2	3256.59	(3)	305.27	(4)	86.54	17.51	9.82	17.51	784	850	1889060	1	8632	70
		5	—	(5)	3697.87	(1)	86.19	1.29	78.49	1.23	1900	760	873284	2	12851	40
		10	—	(5)	2525.29	(0)	87.92	0.12	87.51	0.00	3710	791	351574	4	4490	32
A	2	1365.87	(0)	61.55	(4)	85.11	21.30	0.00	21.04	784	1141	327100	3	1255	96	
	5	—	(5)	11.83	(4)	85.51	7.43	72.18	6.75	1900	1251	643473	8	9003	67	
	10	—	(5)	100.35	(4)	85.84	15.80	84.79	13.75	3710	1385	306764	101	4475	51	
40	W	2	—	(5)	—	(5)	100.00	26.96	51.29	26.96	1044	1248	1344963	1	16445	121
		5	—	(5)	—	(5)	100.00	83.14	95.28	83.14	2530	1267	482105	1	5041	104
		10	—	(5)	—	(5)	100.00	92.94	100.00	92.94	4940	1350	188692	1	3381	85
	C	2	6.66	(0)	—	(5)	100.00	38.00	0.00	37.95	1044	2502	1762	5	22	37
		5	2658.74	(2)	—	(5)	100.00	81.92	39.02	81.92	2530	2235	434526	1	3523	25
		10	—	(5)	—	(5)	100.00	75.34	100.00	75.34	4940	1921	349858	12	1348	18
	K	2	4990.55	(1)	—	(5)	100.00	50.04	3.02	50.04	1044	2202	1651655	1	5136	113
		5	—	(5)	—	(5)	100.00	74.12	97.64	74.12	2530	2018	479613	1	7167	86
		10	—	(5)	—	(5)	100.00	69.68	100.00	69.68	4940	1934	210396	3	2563	72
	D	2	—	(5)	—	(5)	100.00	20.20	42.95	20.20	1044	1247	1505294	1	12264	125
		5	—	(5)	—	(5)	100.00	89.82	98.91	89.82	2530	1248	463628	1	8186	98
		10	—	(5)	—	(5)	100.00	90.59	100.00	90.59	4940	1350	153036	1	5215	87
	S	2	—	(5)	—	(5)	100.00	25.20	43.94	25.20	1044	1323	1360254	1	12167	126
		5	—	(5)	—	(5)	100.00	70.38	96.48	70.38	2530	1294	462667	1	6780	91
		10	—	(5)	—	(5)	100.00	84.09	100.00	84.09	4940	1334	139121	1	6489	81
A	2	—	(5)	—	(5)	100.00	24.46	22.07	24.46	1044	1810	1460678	1	5826	191	
	5	—	(5)	—	(5)	100.00	62.67	99.14	62.67	2530	1646	345643	1	7108	134	
	10	—	(5)	—	(5)	100.00	85.25	100.00	85.25	4940	1767	155190	1	3426	113	
45	W	2	—	(5)	—	(5)	100.00	26.30	54.64	26.30	1174	1398	1133697	1	11416	134
		5	—	(5)	—	(5)	100.00	92.43	99.51	92.43	2845	1413	401143	1	5947	113
		10	—	(5)	—	(5)	100.00	100.00	100.00	100.00	5555	1469	153297	1	2343	104
	C	2	6.40	(0)	—	(5)	100.00	46.67	0.00	46.67	1174	2326	1132	2	24	34
		5	5003.88	(3)	—	(5)	100.00	75.71	60.00	75.71	2845	2532	500043	1	5891	29
		10	—	(5)	—	(5)	100.00	75.66	100.00	75.66	5555	2236	171358	7	722	22
	K	2	—	(5)	—	(5)	100.00	44.43	28.39	44.43	1174	2477	1611616	1	11832	146
		5	—	(5)	—	(5)	100.00	80.52	99.07	80.52	2845	2482	426670	1	6214	157
		10	—	(5)	—	(5)	100.00	84.97	100.00	84.97	5555	2165	160867	1	1944	90
	D	2	—	(5)	—	(5)	100.00	24.77	54.89	24.77	1174	1406	1171833	1	12252	135
		5	—	(5)	—	(5)	100.00	98.15	98.67	98.15	2845	1412	424560	1	4188	113
		10	—	(5)	—	(5)	100.00	100.00	100.00	100.00	5555	1466	152963	1	2822	104
	S	2	—	(5)	—	(5)	100.00	23.69	56.00	23.69	1174	1479	1069851	1	11291	<

Table A4 (continued)

n	type	p	Time (#Unsolved)			GAProot (%)		GAP (%)		Vars		Nodes		Memory (MB)		
			Compact	B&P	(#)	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	
50	W	2	—	(1)	—	(1)	100.00	75.57	61.16	75.57	1304	1616	1047768	1	11081	161
		5	—	(1)	—	(1)	100.00	99.83	100.00	99.83	3160	1623	406553	1	2969	141
		10	—	(1)	—	(1)	100.00	100.00	100.00	100.00	6170	1709	186637	1	934	128
C	2	11.71	(0)	—	(1)	100.00	62.36	0.00	62.36	1304	2575	2112	1	38	37	
	5	—	(1)	—	(1)	100.00	90.14	87.76	90.14	3160	2577	540242	1	1441	34	
	10	—	(1)	—	(1)	100.00	99.12	100.00	99.12	6170	2587	112265	1	572	26	
K	2	—	(1)	—	(1)	100.00	36.29	46.27	36.29	1304	2810	957166	1	10628	164	
	5	—	(1)	—	(1)	100.00	91.13	98.89	91.13	3160	2450	434558	1	4069	127	
	10	—	(1)	—	(1)	100.00	90.03	100.00	90.03	6170	2410	142538	1	1231	108	
D	2	—	(1)	—	(1)	100.00	31.05	63.12	31.05	1304	1666	878351	1	10528	162	
	5	—	(1)	—	(1)	100.00	74.10	100.00	74.10	3160	1695	285611	1	4410	134	
	10	—	(1)	—	(1)	100.00	100.00	100.00	100.00	6170	1777	83410	1	545	129	
S	2	—	(1)	—	(1)	100.00	36.71	60.33	36.71	1304	1577	983547	1	10718	148	
	5	—	(1)	—	(1)	100.00	94.34	99.55	94.34	3160	1635	583530	1	2230	129	
	10	—	(1)	—	(1)	100.00	100.00	100.00	100.00	6170	1737	153870	1	775	135	
A	2	—	(1)	—	(1)	100.00	24.67	48.59	24.67	1304	2258	514472	1	5470	226	
	5	—	(1)	—	(1)	100.00	75.58	100.00	75.58	3160	1998	403520	1	2368	182	
	10	—	(1)	—	(1)	100.00	91.23	100.00	91.23	6170	2051	117660	1	1968	170	
Total Average:			928.16	(292)	1680.95	(276)	96.54	41.27	61.20	40.52	2451	1819	711082	237	5823	82

Table B.1

Results for Eilon et al. (1971) instances disaggregated by p.

n	p	Time (#Unsolved)			GAProot (%)		GAP (%)		Vars		Nodes		Memory (MB)			
		Compact	B&P	(#)	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P		
20	2	31.53	(0)	995.23	(27)	97.64	5.78	0.00	3.18	352	11676	19115	909	76	311	
	5	598.89	(77)	645.63	(36)	100.00	9.40	31.41	5.29	841	3424	4014722	1775	6812	86	
	10	1887.11	(100)	944.99	(27)	100.00	10.49	68.18	5.25	1623	1837	4961903	2579	7318	38	
30	2	800.60	(11)	782.84	(68)	86.56	15.67	1.47	14.99	527	12187	724493	448	1706	341	
	5	605.00	(98)	1716.72	(59)	89.26	13.33	54.38	11.70	1258	4621	3293952	259	8505	124	
	10	1688.00	(115)	1273.04	(52)	89.74	12.60	77.60	10.90	2427	2794	3021553	672	5907	64	
40	2	1269.05	(71)	637.73	(92)	97.42	22.37	18.71	22.30	702	10587	3899173	30	5302	452	
	5	1285.99	(105)	920.48	(92)	100.00	43.95	76.39	43.86	1674	4274	2224552	13	7266	162	
	10	3970.16	(115)	558.03	(90)	100.00	47.30	88.85	46.92	3228	3561	1806857	63	4752	102	
45	2	1404.32	(86)	417.24	(94)	97.47	24.07	27.13	24.05	789	9011	3575284	6	5658	592	
	5	1528.56	(106)	914.34	(99)	100.00	47.27	79.86	47.20	1883	4121	2010197	4	5773	216	
	10	—	(120)	900.91	(90)	100.00	50.95	92.38	50.81	3630	3778	1503232	18	3886	130	
50	2	231.73	(19)	414.88	(18)	97.50	26.53	34.60	26.50	877	8218	3270850	3	5870	733	
	5	379.06	(23)	1296.44	(19)	100.00	49.11	85.88	49.05	2091	4208	2014876	3	4056	261	
	10	—	(24)	1140.29	(18)	100.00	53.29	93.65	53.22	4033	3983	1167240	13	3434	158	
Total Average:			788.01	(1070)	950.76	(881)	96.64	26.11	52.32	24.78	1614	5964	2567113	538	5209	226

Table B.2
Results for Eilon et al. (1971) instances disaggregated by type.

n	type	Time (#Unsolved)				GAProot(%)		GAP(%)		Vars		Nodes		Memory (MB)	
		Compact		B&P		Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P
20	W	317.70	(36)	223.81	(0)	99.49	0.04	42.20	0.00	939	1358	4396856	1	6710	40
	C	586.30	(3)	1167.87	(50)	98.24	29.65	0.84	22.22	939	16897	840935	6801	376	368
	K	208.19	(33)	2302.80	(26)	99.29	12.07	33.55	4.07	939	8287	2776965	2663	4251	214
	D	490.31	(35)	202.43	(0)	99.48	0.05	42.83	0.00	939	1345	3918058	2	6411	39
	S	246.13	(36)	264.52	(0)	99.48	0.16	42.80	0.00	939	1364	3810920	3	6202	41
30	A	94.15	(34)	2244.67	(14)	99.30	9.39	36.97	1.16	939	4622	2247746	1058	4463	168
	W	1513.57	(44)	1106.95	(13)	89.87	5.18	52.47	5.17	1404	1895	3535132	1	7636	102
	C	298.00	(15)	1014.47	(52)	84.44	34.66	17.14	30.95	1404	21207	1107742	2046	725	263
	K	223.54	(39)	1637.34	(48)	88.77	18.00	44.82	15.96	1404	8338	2429087	501	5244	283
	D	1618.90	(44)	1283.18	(11)	89.57	6.19	52.42	6.18	1404	1905	2728170	1	7388	103
40	S	1512.19	(43)	1267.56	(11)	89.80	5.88	52.85	5.84	1404	1883	2558116	2	6886	101
	A	718.27	(39)	1701.10	(44)	88.68	13.30	47.19	11.06	1404	3974	1721747	207	4355	208
	W	4028.70	(59)	774.14	(30)	99.48	33.01	72.86	33.00	1868	2957	5069956	1	7853	233
	C	980.10	(20)	—	(60)	97.96	50.13	26.17	49.58	1868	19156	881914	158	1541	215
	K	2015.89	(41)	—	(60)	99.22	42.57	59.51	42.46	1868	5091	1589810	32	4656	226
45	D	5908.68	(59)	461.24	(32)	99.47	32.77	72.91	32.76	1868	3053	3668574	1	8229	244
	S	4977.44	(59)	865.44	(32)	99.47	31.20	72.88	31.17	1868	2965	3231789	2	8253	232
	A	1271.93	(53)	—	(60)	99.24	37.56	63.59	37.20	1868	3620	1419121	19	4108	281
	W	—	(60)	545.90	(33)	99.50	36.46	76.57	36.45	2101	3670	4325838	1	6928	371
	C	631.76	(26)	—	(60)	97.92	50.86	34.95	50.71	2101	14393	812873	35	1369	165
50	K	2695.65	(51)	—	(60)	99.27	44.77	64.85	44.75	2101	4696	1888145	9	5273	253
	D	—	(60)	565.54	(33)	99.50	37.10	77.13	37.10	2101	3542	3091420	1	6813	355
	S	—	(60)	1176.85	(37)	99.49	34.68	77.24	34.64	2101	3672	2778561	2	6696	369
	A	4681.25	(55)	—	(60)	99.27	40.71	68.02	40.45	2101	3846	1280588	7	3555	361
	W	—	(12)	504.08	(6)	99.51	41.69	79.67	41.68	2333	4106	4060816	1	5964	479
Total Average:	C	80.39	(7)	—	(12)	97.92	56.37	47.61	56.32	2333	11574	985006	25	1392	139
	K	1135.78	(11)	—	(12)	99.27	48.78	68.21	48.77	2333	4721	1721732	3	4630	280
	D	—	(12)	1231.14	(6)	99.51	35.71	79.72	35.71	2333	4047	2644819	1	5596	464
	S	—	(12)	1080.38	(7)	99.50	33.47	80.29	33.47	2333	4097	2304729	2	5704	477
	A	—	(12)	—	(12)	99.29	41.84	72.76	41.59	2333	4273	1188832	4	3434	466
Total Average:		788.01	(1070)	950.76	(881)	96.64	26.11	52.32	24.78	1614	5964	2567113	538	5209	226

Table B.3
Results for Eilon et al. (1971) instances disaggregated by norm.

n	norm	Time (#Unsolved)				GAProot(%)		GAP(%)		Vars		Nodes		Memory (MB)	
		Compact		B&P		Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P	Compact	B&P
20	ℓ_1	436.31	(27)	536.32	(21)	96.86	9.14	12.95	3.27	387	12007	6217790	3685	959	322
	$\ell_{\frac{3}{2}}$	431.87	(51)	988.85	(22)	100.00	7.55	41.56	5.10	1425	2112	1027930	538	5279	49
	ℓ_2	237.07	(49)	695.93	(21)	100.00	8.00	36.12	3.13	518	6200	3712315	2266	6961	154
30	ℓ_3	330.68	(50)	1287.62	(26)	100.00	9.55	42.16	6.80	1425	2264	1036285	529	5743	56
	ℓ_1	507.49	(51)	719.49	(33)	96.81	8.47	33.60	5.77	582	16294	6498700	857	2749	394
	$\ell_{\frac{3}{2}}$	1149.07	(55)	2365.89	(57)	85.90	22.91	48.76	22.36	2131	1818	519097	58	4414	59
40	ℓ_2	567.61	(54)	450.17	(37)	85.92	7.53	45.62	5.84	771	6524	1636955	463	8071	200
	ℓ_3	1098.91	(64)	2343.41	(52)	85.46	16.54	49.94	16.14	2131	1499	731911	461	6256	53
	ℓ_1	895.06	(66)	941.95	(49)	96.56	11.16	44.14	10.67	772	14886	7295651	89	3794	429
45	$\ell_{\frac{3}{2}}$	1932.07	(77)	—	(90)	100.00	67.76	69.78	67.76	2838	1742	514263	2	5889	101
	ℓ_2	1337.71	(70)	483.36	(45)	100.00	8.97	59.71	8.75	1025	6284	2142580	49	7183	330
	ℓ_3	2330.98	(78)	—	(90)	100.00	63.60	71.65	63.60	2838	1650	621616	2	6227	95
50	ℓ_1	1292.16	(70)	984.00	(58)	96.63	11.66	49.03	11.45	868	13141	6512940	30	4305	523
	$\ell_{\frac{3}{2}}$	1924.73	(82)	—	(90)	100.00	73.90	72.99	73.90	3191	1895	489638	1	3902	123
	ℓ_2	1374.31	(77)	568.64	(45)	100.00	9.10	66.84	8.98	1151	5691	1939349	5	6785	490
Total Average:	ℓ_3	1434.25	(83)	—	(90)	100.00	68.40	76.98	68.40	3191	1819	509691	1	5431	113
	ℓ_1	505.06	(15)	1480.61	(10)	96.66	11.82	53.46	11.72	966	11475	5577448	18	4265	634
	$\ell_{\frac{3}{2}}$	6.06	(17)	—	(18)	100.00	74.63	77.52	74.63	3545	2101	443749	1	3651	140
Total Average:	ℓ_2	4.78	(17)	440.92	(9)	100.00	9.23	73.10	9.11	1278	6261	2147547	4	5899	632
	ℓ_3	11.71	(17)	—	(18)	100.00	76.23	81.43	76.23	3545	2042	435212	1	3999	130
	Total Average:		788.01	(1070)	950.76	(881)	96.64	26.11	52.32	24.78	1614	5964	2567113	538	5209

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