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**Interoception as independent cardiac, thermosensory, nociceptive, and affective touch perceptual submodalities**

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**Keywords:** temperature, homeostasis, body awareness, CT system, interoceptive battery

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44 **Abstract**

45 Interoception includes signals from inner organs and thin afferents in the skin, providing  
46 information about the body's physiological state. However, the functional relationships  
47 between interoceptive submodalities are unclear, and thermosensation as skin-based  
48 interoception has rarely been considered. We used five tasks to examine the relationships  
49 among cardiac awareness, thermosensation, affective touch, and nociception. Thermosensation  
50 was probed with a classic temperature detection task and the new *dynamic thermal matching*  
51 *task*, where participants matched perceived moving thermal stimuli in a range of colder/warmer  
52 stimuli around thermoneutrality. We also examined differences between hairy and non-hairy  
53 skin and found superior perception of dynamic temperature and static cooling on hairy skin.  
54 Notably, no significant correlations were observed across interoceptive submodality accuracies  
55 (except for cold and pain perception in the palm), which indicates that interoception at  
56 perceptual levels should be conceptualised as a set of relatively independent processes and  
57 abilities rather than a single construct.

58 **Introduction**

59 Interoception has been defined as the body-to-brain axis of sensations concerning the state of  
60 the visceral body (Cameron, 2001; Sherrington, 1948), thus involving signals originating from  
61 within the body (e.g., cardiac, respiratory, and digestive functions). However, physiological  
62 and anatomical observations led to a redefined and extended concept of interoception that  
63 encompasses information about the physiological condition of the entire body (Craig, 2002;  
64 Khalsa, Rudrauf, Feinstein, & Tranel, 2009), including signals originating from the body  
65 surface carrying thermal, noxious, and pleasant tactile signals (Crucianelli & Ehrsson, 2022).  
66 Such signals are conveyed by specialised afferent pathways from the spinal cord through the  
67 ventral medial posterior nucleus of the thalamus to the insular cortex (Björnsdotter, Löken,  
68 Olausson, Vallbo, & Wessberg, 2009; Craig et al., 2000; Kastrati et al., 2022), a cortical area  
69 involved in the processing of interoceptive information, including visceral signals. The  
70 posterior insula has strong anatomical connections to the anterior insula, where further  
71 processing and integration of various types of interoceptive signals occur; overall, the insular  
72 cortex has been proposed to be a critical region for interoceptive awareness and the experience  
73 of emotions (Critchley et al., 2004). Importantly, interoception is related to the generation of  
74 bodily (affective) feelings, informing the organism about its bodily needs and maintenance of  
75 homeostasis, and ultimately survival (Craig, 2003, 2008, 2009; Seth, 2013; von Mohr &  
76 Fotopoulou, 2018).

77

78 Traditionally, interoception has been quantified using heartbeat detection tasks (Schandry,  
79 1981), in which participants are asked to focus on their own heartbeats by just feeling the  
80 sensation of their heart beating in the chest. This task has been widely used and studied, is easy  
81 to implement, and captures an important aspect of visceral bodily awareness. Moreover,  
82 heartbeat-evoked potentials have been related to activity in interoceptive brain networks, such  
83 as the anterior insular cortex (see Coll et al., 2021 for a review and meta-analysis). However,  
84 the heartbeat counting approach has several problems and limitations (please see Zamariola et  
85 al., 2018; Ainley et al., 2020; Zimprich et al., 2019; Corneille et al., 2020 for a full account of  
86 the recent debate). Performance in heartbeat detection tasks can be influenced by factors other  
87 than awareness of the heartbeats themselves, such as prior knowledge of typical baseline heart  
88 rates, differences in actual heart rates (that influence the difficulty of the task), practice, and  
89 variations in precise experimental instructions (Ring & Brener, 1996; Ring et al., 2015;  
90 Zamariola et al., 2018; Corneille et al., 2020; Desmedt et al., 2020). In addition, some

91 participants use alternative bodily strategies to solve the task, such as feeling pulsations in the  
92 extremities (e.g., fingers and feet, Murphy et al., 2019), tensing their muscles, holding their  
93 breath or otherwise changing their respiration, and such strategies can bias the outcome  
94 measures (Ross & Brener, 1981; Whitehead & Drescher, 1980). From a physiological point of  
95 view, heartbeats produce a multitude of bodily signals that are not restricted to sensory  
96 information about the mechanical and chemical state of the heart but also include sensory inputs  
97 from secondary effects such as vascular reactivity, muscle contractions, and pulsations in other  
98 body parts. Moreover, an obvious limitation of the heartbeat counting task is that the sensory  
99 signal is not under experimental control, making it difficult to use classic perception science  
100 approaches to characterise the relationship between the sensory signal strength and subjective  
101 perception. In contrast, it is easy to deliver stimuli on the skin, making skin-based interoception  
102 an attractive complement to cardiac interoception from an experimental perspective.

103

104 Over the last two decades, there has been increasing interest in skin-mediated interoceptive  
105 modalities, such as pain and affective touch (Craig, 2002; 2003; Werner et al., 2009;  
106 Björnsdotter, Morrison & Olausson, 2010; Weiss et al., 2014; von Mohr & Fotopoulou, 2018).  
107 To a large extent, this interest has been driven by studies on affective touch, which are  
108 motivated by the discovery of a specialised group of skin afferents in humans called C-tactile  
109 afferents (CT; Vallbo, Olausson & Wessberg, 1999). CT afferents are ‘low-threshold  
110 mechanoreceptors’ in mammalian hairy skin that are sensitive to light touch, and  
111 microneurography studies in humans have shown that they discharge optimally to gentle  
112 moving stimuli such as moving finger or light brush over the skin. CT afferents have a  
113 significantly higher density in human hairy skin (Nordin, 1990; Vallbo et al., 1993, 1999) and  
114 are only sparsely present in glabrous skin (Watkins, Dione, Ackerley, Backlund Wasling,  
115 Wessberg, & Löken, 2020). CT afferents have been proposed as a key sensory system for the  
116 detection of affective touch (Löken et al., 2009; Morrison, Löken & Olausson, 2010), and CT  
117 signals reach the posterior insular cortex (Björnsdotter et al., 2009 but see Gazzola et al., 2012).  
118 As mentioned above, nociceptive and thermosensory information also reach the insular cortex  
119 (Craig et al., 2000; Kastrati et al., 2022).

120

121 Although pain, thermosensation, and affective touch are often mediated by external causes and  
122 events occurring on the skin, nociceptive and thermosensory signals can also originate from  
123 within the body, and these modalities are homeostatically relevant since they provide  
124 information about physiological safety or threats (Craig, 2003; von Mohr & Fotopoulou, 2018;

125 Crucianelli & Ehrsson, 2022). However, compared to affective touch, relatively little attention  
 126 has been given to the perception of temperature as a skin-mediated interoceptive modality  
 127 (Craig et al., 2000; Craig, 2014).

128

129 The perception of temperature is mediated by thermoreceptors, which are free nerve endings  
 130 that signal sensations of warmth and coolness (Sinclair, 1981; Abraira & Ginty, 2013; Filingeri,  
 131 2011; Jänig, 2018 for reviews). The skin is innervated by different types of afferent fibres  
 132 encoding temperatures that can range from noxious cold to noxious heat, with innocuous cold  
 133 and innocuous warm perception between the two extremes (Jänig, 2018 for a review). In  
 134 particular, the perception of cold is mainly mediated via A $\delta$  fibres (range  $\approx$  5–40°C; maximally  
 135 discharging at approximately 30°C) and C fibres (e.g., Hensel et al., 1960; Iriuchijima &  
 136 Zotterman, 1960; Iggo, 1969; Hensel & Wurster, 1969; Hensel & Iggo, 1971; Darian-Smith et  
 137 al., 1973; Dubner et al., 1975; Kenshalo & Duclaux, 1977; Jänig, 2018 for a review). Cooling  
 138 (but not warming) of the skin also activates unmyelinated, low-threshold mechanoreceptors  
 139 (CTs; Nordin, 1990). In contrast, warmth perception is mainly mediated by C fibres (range  $\approx$   
 140 29–45°C; maximally discharging at approximately 45°C, e.g., Iriuchijima & Zotterman, 1960,  
 141 Hensel & Huopaniemi, 1969, Konietzny & Hensel, 1975; 1977; La Motte & Campbell, 1978;  
 142 Hallin et al.; 1982). C fibres also contribute to pain. Temperatures  $\approx$  < 15 and > 45°C activate  
 143 cold and hot nociceptors, respectively (Kandel et al., 2000, Jänig, 2018; Table 1). Many C-fibre  
 144 afferents are polymodal, i.e., they respond to various combinations of thermal, mechanical, and  
 145 chemical stimuli. C afferents are the most common receptor type in the body and are believed  
 146 to represent an important source of information about the body’s physiological state.

147

148 **Table 1.** Activation of the different skin receptors in response to thermal stimuli. Adapted from Jänig, 2018

SKIN TEMPERATURE	< 15°C (Noxious cold)	15–30°C (Innocuous cold)	30–45°C (Innocuous warm)		> 45°C (Noxious heat)
SKIN SENSATIONS	Cold pain–burning	Cold	Cool	Warm	Hot
		<b>THERMAL COMFORT ZONE</b>			
MOTOR REACTIONS	Protective body reactions	<b>THERMOREGULATION</b>		Thermoneutrality 30–34°C	Protective body reactions
AFFERENTS NEURONS	Cold nociceptive neurons	Cool-sensitive neurons	Warm-sensitive neurons		Heat nociceptive neurons
RECEPTORS	A $\delta$	A $\delta$ , C	A $\delta$ , C		C

149

150

151 We recently proposed that temperature perception could represent a good model system to  
152 investigate interoception because it offers numerous advantages from experimental, theoretical,  
153 and ethical perspectives compared to other interoceptive submodalities (Crucianelli & Ehrsson,  
154 2022). First, stimulation can be experimentally controlled in the sense that we can  
155 systematically manipulate the temperature we deliver to the skin with precision, which is  
156 difficult in visceral paradigms. Second, in contrast to pain or affective touch in which the  
157 affective facet can be very prominent (e.g., strong emotional distress with pain), thermal stimuli  
158 do not necessarily have a strong affective component when manipulated within the innocuous  
159 range (cool to warm perception) but can be associated with mild experiences of thermal comfort  
160 and discomfort. This is an advantage in experimental studies, as it is easier to match conditions  
161 and raises fewer ethical issues than when administering pain. Third, thermoreception is a non-  
162 invasive way to investigate interoception compared to other modalities, such as gastric and  
163 bladder functions and pain, and therefore raises fewer ethical issues. Fourth, unlike CT and  
164 nociceptors that are largely silent until stimulated, our brain receives continuous signals about  
165 the temperature of the external environment from the receptors in the skin and the body's core.  
166 This constant inflow in thermosensory signals to the brain is similar to the constant signals from  
167 the beating heart that traditionally have been emphasised as one of the advantages of focusing  
168 on cardiac interoception as “a constant signal in our life” (Azzalini, Rebollo & Tallon-Baudry,  
169 2019). Similarly, as in the case of an increasing heart rate, we are prompted to pay attention to  
170 what is happening inside or outside our body as soon as there is a notable deviation from  
171 thermoneutrality. Thus, the body and the brain work in concert to maintain thermoneutrality,  
172 which is a task that involves our whole body (Proffitt, 2006; Davies et al., 2012).

173

174 The first aim of the present study was to investigate the relationships of cardiac interoception  
175 and three skin-based interoceptive submodalities, namely, affective touch, nociception, and  
176 thermosensation. By comparing performance on these tasks targeting both visceral and skin-  
177 mediated signals, we wanted to address the question of whether interoceptive abilities  
178 generalise and can be seen as a single ability or whether interoception is better described as a  
179 set of independent separate submodalities and abilities. This is important because several  
180 accounts of interoception point towards the importance of the insular cortex in processing  
181 interoceptive signals, and this has contributed to a rather widespread assumption in the  
182 psychological literature that interoception might be a unified construct (e.g., Pollatos et al.,  
183 2007; Zaki, Davis, & Ochsner, 2012). However, in line with the general principle of parallel  
184 and hierarchical processing of sensory information in the brain (Ungerleider & Mishkin, 1982),

185 one can also hypothesise that the various interoceptive signals are initially processed relatively  
186 independently only to be gradually and increasingly integrated higher up in the cortical  
187 hierarchy. Moreover, in the psychological literature, cardiac interoception assessed by heartbeat  
188 detection tasks is often used as a proxy for interoception more generally. However, this could  
189 be misleading if the assumption of interoception as a generalised construct and ability is  
190 incorrect. Thus, we reasoned that more studies investigating interoception using a “battery of  
191 tests” are needed to clarify the above questions and obtain a more comprehensive understanding  
192 of interoception.

193

194 Accordingly, we tested a group of healthy participants on a battery of tests; in addition to the  
195 classic heartbeat counting task and the often-used affective touch paradigm, we added two  
196 validated change detection tasks to probe thermosensation and (thermal) nociception. We also  
197 added a new thermal task (see below) that was specifically designed with skin-based  
198 interoception in mind. Since affective touch is typically studied on both hairy and non-hairy  
199 skin due to the greater density of CT fibres in the former and thermosensation has been reported  
200 to differ between these two skin types (Filingeri et al., 2018), we conducted all skin-based  
201 interoceptive tasks on both hairy and non-hairy skin. This gave us the opportunity to directly  
202 test whether the generalisation or separation of interoceptive submodalities would hold true for  
203 both skin types.

204

205 The second aim of this study was to introduce a novel thermosensory task to probe  
206 thermosensation as skin-based interoception. Given that thermosensation has traditionally been  
207 seen as part of somatosensation and exteroception, existing tasks are often designed as  
208 somatosensory detection or discrimination tasks, which is not a problem in itself of course, but  
209 as we have argued elsewhere (Crucianelli & Ehrsson 2022), new thermosensory tasks designed  
210 from the perspective of interoception can make valuable contributions to future research. Thus,  
211 we designed the dynamic thermal matching task inspired by aspects of the heartbeat counting  
212 task, concept of deviations from thermoneutrality, and theoretical consideration from the  
213 affective touch literature. Therefore, we targeted temperatures around the thermoneutrality  
214 range (30–34°C, see Table 1) to probe relatively subtle thermosensory deviations from normal  
215 skin temperature. This is similar to the heartbeat counting task that captures small variations  
216 around resting baseline heart rates. Furthermore, the thermal stimuli were moving at an optimal  
217 speed for CT fibres, and the range of temperatures tested should lead to variations in CT  
218 activity, in addition to activating cold and warm receptors. Recent studies have shown optimal



219 activation of CT afferents in response to light moving stimuli delivered at a typical skin  
220 temperature (i.e., 32°C) compared to cooler (18°C) or warmer (40°C) stimuli, and at such  
221 neutral temperatures, stimulation is perceived as most pleasant (Ackerley et al., 2014). As  
222 described above, we further compared hairy and non-hairy skin.

223

224 Finally, in line with recent theoretical and experimental developments arguing that  
225 interoception should be quantified as a multidimensional construct(s) taking into account both  
226 sensation–perception and metacognition (Garfinkel et al., 2015), for each interoceptive  
227 submodality, we distinguished between *interoceptive accuracy*, that is, the objective  
228 performance on an interoceptive task, i.e., perceptual detection or discrimination; *interoceptive*  
229 *sensibility*, which refers to subjective beliefs about the perception of bodily signals and task  
230 performance and is measured by means of self-report questionnaires or ratings *prior* to  
231 conducting the perceptual tasks; and *interoceptive awareness*, or metacognitive awareness of  
232 interoceptive accuracy, which is one’s subjective confidence about the objective interoceptive  
233 performance that can be measured with confidence ratings directly after the tasks (Garfinkel et  
234 al., 2015). This multidimensional manner of describing interoception allows us to capture both  
235 perceptual and metacognitive levels of interoception and compare the relationships across the  
236 different submodalities at both levels, which has potentially higher translational relevance, as  
237 clinical studies often probe interoception at the metacognitive level using questionnaires where  
238 participants have to describe their degree of awareness of various interoceptive sensations in  
239 everyday life (see Khalsa et al., 2018 for clinical implications of interoceptive research).

240

## 241 **Methods**

### 242 **Participants**

243 A total of sixty-four healthy participants (31 males and 33 females) were recruited using social  
244 media and advertising on the Karolinska Institutet campus. Two participants (one male and one  
245 female) were excluded because they did not meet the inclusion criteria; thus, a total of 62  
246 participants were considered for data analysis. A priori power analysis based on previous  
247 studies in the field of interoception (Garfinkel et al., 2016; Crucianelli et al., 2018) suggested  
248 that a minimum sample of  $N = 62$  provided enough power (92%) to detect our effects of  
249 interests in the thermal matching task ( $\alpha = 0.05$ , effect size  $d = 0.4$ , two-tailed). Inclusion criteria  
250 were being 18-39 years old (mean age = 26.5 years, standard deviation = 5.4 years) and being  
251 right-handed. Exclusion criteria were having a history of any psychiatric or neurological

252 conditions, taking any medications, having sensory or health conditions that might result in skin  
253 conditions (e.g., psoriasis), and having any scars or tattoos on the left forearm or hand. All  
254 participants were requested to wear short sleeves to make stimulation of the forearm easier. The  
255 study was approved by the Swedish Ethical Review Authority. All participants provided signed  
256 written consent, and they received a cinema ticket as compensation for their time. The study  
257 was conducted in accordance with the provisions of the Declaration of Helsinki 1975, as revised  
258 in 2008.

259

### 260 **Self-report measures and interoceptive sensibility**

261 Participants were asked to provide demographic information, such as age, weight and height  
262 (to calculate the body mass index, BMI), handedness and, for female subjects, the phase of the  
263 menstrual cycle at the time of testing (i.e., this is known to influence body temperature and  
264 consequently affect thermoregulatory processes; Kurz, 2008 for a review). Next, participants  
265 were asked to complete the following self-report questionnaires: the *Body Awareness*  
266 *Questionnaire* (BAQ), an 18-item questionnaire assessing body awareness (Shields, Mallory &  
267 Simon, 1989), and the *Body Perception Questionnaire* (very short form, BPQ), a 12-item  
268 questionnaire regarding perception of one's body (Porges, 1993; Cabrera et al., 2017). The  
269 BAQ and BPQ were included as measures of interoceptive sensibility, that is, how aware  
270 participants reported being of their bodily sensations; the former questionnaire addresses more  
271 general body awareness, whereas the latter questionnaire targets bodily sensations more  
272 specifically, such as stomach and gut activity. Participants also completed the *Eating Disorder*  
273 *Examination Questionnaire* (EDE-Q 6.0, Fairburn & Beglin, 1994, 2008; Peterson et al., 2007)  
274 and the *Depression, Anxiety and Stress Scale – 21 Item* (DASS, Lovibond & Lovibond, 1995;  
275 Henry & Crawford, 2005). However, the BMI, EDE-Q and DASS were not considered in any  
276 of the following analyses because their inclusion lies beyond the scope of this manuscript.

277

### 278 **Interoceptive accuracy tasks**

#### 279 ***Heartbeat counting task (HCT)***

280 The experimenter recorded the heartbeat frequency by means of a Biopac MP150 Heart Rate  
281 oximeter attached to the participant's non-dominant index finger and connected to a Windows  
282 laptop with AcqKnowledge software (version 5.0), which enabled extraction of the actual  
283 number of heartbeats using the 'count peak' function. Care was taken to place the soft oximeter  
284 around the finger firmly but without being too tight to reduce the possibility that participants  
285 could perceive their pulse in their finger (Crucianelli et al., 2018; Murphy et al., 2019). As part

286 of the task, a 5-minute heartbeat baseline was recorded to check for the presence of autonomic  
287 neuropathy. During this time, we presented the instructions for the heartbeat counting task  
288 (Schandry, 1981). Participants were instructed to breathe normally and to not cross their legs.  
289 Participants were asked to silently count their heartbeats between two verbal signals of ‘go’ and  
290 ‘stop’, without manually taking their or feeling their chest. They were encouraged to only count  
291 those heartbeats they were sure about, but also instructed to take into account weak sensations,  
292 rather than making their best guess (as in Ferentzi et al., 2018). Both of the participants’ hands  
293 were placed on the table to ensure that no body part was touched. Participants completed a  
294 practice trial of 15 seconds before proceeding to the three experimental trials (interval lengths  
295 of 25 s, 45 s, and 65 s, as in Crucianelli et al., 2018), which were presented in a randomised  
296 order. Short breaks of 30 seconds were taken between each trial.

297

### 298 ***Temperature perception***

#### 299 *(Dynamic) thermal matching task*

300 Before proceeding with the task, the skin temperature of each participant’s palm and forearm  
301 was measured with a contactless thermometer (Microlife NC150) at three different locations at  
302 each site. These values are reported in Table 1 of the Supplementary Materials. This was done  
303 to control for any significant individual differences in skin temperature that could influence  
304 task performance. Then, participants were stroked with a 25x50 mm thermode attached to a  
305 thermal stimulator (Somedic MSA, SenseLab, Sweden) at reference temperatures of 30°, 32°  
306 or 34°C; these temperatures were within the range of neutral/innocuous temperatures so to  
307 mirror the performance at the heartbeat counting task, which is usually performed at rest.  
308 Participants were instructed to pay close attention to this reference temperature because their  
309 task would be to match it by verbally indicating whenever they felt the same temperature again.  
310 That is, participants were asked to tell the experimenter which temperature felt the same as the  
311 reference temperature among a range of warmer or cooler stimuli. Next, in each experimental  
312 trial, the experimenter touched the participant with the thermode set at different temperatures  
313 starting from  $\pm 8^\circ\text{C}$  (which is 25% of the neutral temperature of 32°C; whether the starting  
314 temperature was +8°C or -8°C from the reference temperature was counterbalanced across  
315 participants) of the reference temperature (range 22-38°C for the reference temperature of  
316 30°C; range 24-40°C for the reference temperature of 32°C; range 26-42°C for the reference  
317 temperature of 34°C). The task followed a staircase procedure, that is, the temperature was  
318 either increased (i.e., from cool to warm) or decreased (i.e., from warm to cool) towards the

319 reference temperature in discrete steps of 2°C. Temperature was increased or decreased until  
320 participants verbally indicated they felt the reference temperature or until the maximum or  
321 minimum temperature was reached ( $\pm 8^\circ\text{C}$  from the reference temperature, opposing the  
322 starting temperature) for a total of 9 potential strokes per trial, with a break of 3 seconds between  
323 trials. Participants were instructed to try to match the reference temperature that they previously  
324 experienced. The correct answer was always the reference temperature, and the order in which  
325 the reference temperatures were presented as well as the order of increasing and decreasing  
326 trials varied across trials to avoid anchor effects of the initial values (e.g., if one participant  
327 started with increasing trials based on one reference temperature, then they would start with  
328 decreasing trials for the following reference temperature, see Tajadura-Jiménez et al., 2015 for  
329 a similar approach in an embodiment paradigm). Two trials per reference temperature were  
330 repeated, one increasing and one decreasing, for a total of 6 trials presented in randomised  
331 order. The duration of each stroke was kept constant at 3 seconds; the velocity of tactile  
332 stimulation was CT-optimal (3 cm/s) and the direction of movement was always proximal to  
333 distal with respect to the participant. No additional pressure was applied aside from the weight  
334 of the thermode. The same procedure was repeated on the outer forearm (hairy skin) and on the  
335 palm (non-hairy skin) in areas of 9x4 cm.

336

337 *(Static) temperature detection task*

338 As in the dynamic thermal matching task, the tactile stimulus was delivered using the Somedic  
339 MSA Thermal Stimulator. The detection of cold and warm static thermal stimuli was measured  
340 by means of the well-established **Marstock** methods of the limits (Fruhstorfer et al., 1976), and  
341 we used the same protocol adopted by Heldestad et al., 2010. The experimenter held the  
342 thermode on the area of interest (left forearm or palm) without applying any additional pressure.  
343 The thermode was not secured on the forearm or hand to avoid any additional tactile signals  
344 that could interfere with the detection of temperature. Participants were asked to hold a response  
345 button using their right hand and to press it as soon as they perceived a change in temperature  
346 of any kind (i.e., warmer or colder than the previous perceived temperature, Heldestad et al.,  
347 2010). The starting temperature was always neutral (32°C); the maximum probe temperature  
348 was set to 50°C, and the minimum was set to 10°C for safety reasons. As soon as the button  
349 was pressed, the temperature automatically changed in the opposite direction and returned to  
350 the baseline temperature of 32°C; the temperature stayed at 32°C for 5 seconds before moving  
351 to the next trial. The temperature changed at a rate of 1°C/s and returned to baseline at a speed  
352 of 4°C/s. This method has been widely used to detect neuropathy in clinical settings, and it

353 includes a total of five warm and five cold trials, presented in two blocks (warm and cold  
354 blocks). The procedure was repeated twice: once on the left forearm and once on the left palm,  
355 in a randomised order.

356

### 357 *Affective touch task*

358 This task takes advantage of the discovery that affective, hedonic touch on the skin can be  
359 reliably elicited by soft, light stroking at specific velocities within the range of 1-10 cm/s that  
360 activate a specialised peripheral system of C-tactile afferents (Löken, Wessberg, Morrison,  
361 McGlone & Olausson, 2009; McGlone, Valbo, Olausson, Löken, & Wessberg, 2007). Touches  
362 were delivered using a soft brush (i.e., precision cheek brush No 032, Åhléns, Sweden) on the  
363 left forearm (hairy skin that contains CT afferents) and left palm (non-hairy skin, where CT  
364 afferent activity has only partially been reported), and the task of the participants was always  
365 to verbally rate the pleasantness of the touch using the rating scale. Touches were delivered at  
366 seven velocities (0.3, 1, 3, 6, 9, 18 and 27 cm/s). Two slow velocities of 3 and 6 cm/s are  
367 typically perceived as more pleasant (i.e., CT optimal velocities) compared to the borderline  
368 optimal velocities (1 and 9 cm/s) and the CT non-optimal speeds (0.3, 18 and 27 cm/s, Löken  
369 et al., 2009). Each velocity was presented three times, for a total of 21 stroking trials per location  
370 (palm and forearm, in randomised order) and the direction of movement was always proximal  
371 to distal with respect to the participant.

372

### 373 *(Static) pain detection task*

374 The procedure of this task followed the same protocol to detect thermal pain thresholds used  
375 by Heldestad et al., 2010, and it was similar to the one described for static temperature detection.  
376 However, here, participants were instructed to press the button as soon as they perceived that  
377 the thermal stimulation was becoming uncomfortable or painful (Heldestad et al., 2010). When  
378 providing the instructions, the experimenter clarified that the task was to press the button as  
379 soon as the sensation of discomfort or pain was beginning (i.e., detection) rather than when the  
380 pain was unbearable (i.e., threshold). We performed the procedure in the left palm (non-hairy)  
381 and forearm (hairy), and we tested pain detection following warm stimuli only for a total of  
382 five trials per location. The baseline starting temperature was 32°C, and the maximum  
383 temperature was 50°C for safety reasons. If the participant did not press the button when  
384 reaching 50°C, the trial was considered invalid. The temperature changed at a rate of 2°C/s,  
385 whereas the return to baseline in all tests occurred at a speed of 4°C/s.

386

**387 Interoceptive metacognitive awareness: Confidence and prior beliefs**

388 In line with recent models of interoception (Garfinkel et al., 2015; 2016), we also measured  
389 metacognitive awareness in relation to interoception. We collected information about this  
390 measure as confidence after each answer (i.e., online) and as prior belief before participants  
391 completed each task (i.e., offline); these data have been analysed separately (Fleming et al.,  
392 2016). After receiving the instructions about each task and having been given the opportunity  
393 to ask any questions they might have, participants were asked to provide a prospective  
394 estimation of their ability to successfully complete the task by means of a rating scale ranging  
395 from 0 (not at all accurate/total guess) to 100 (very accurate) (Beck et al., 2019). Furthermore,  
396 participants were also asked after each individual trial within the tasks to rate their confidence  
397 with their answers (as in Garfinkel et al., 2015; Beck et al., 2019). This confidence rating was  
398 chosen on an 11-point scale ranging from 0 (not at all) to 10 (extremely). This was done for  
399 each trial of the tasks except for the static temperature detection task and static pain detection  
400 task, as these followed a standardised method-of-limits procedure, whereby temperature  
401 changes in a continuous manner; providing individual confidence ratings after each trial during  
402 the task would have disrupted the actual performance.

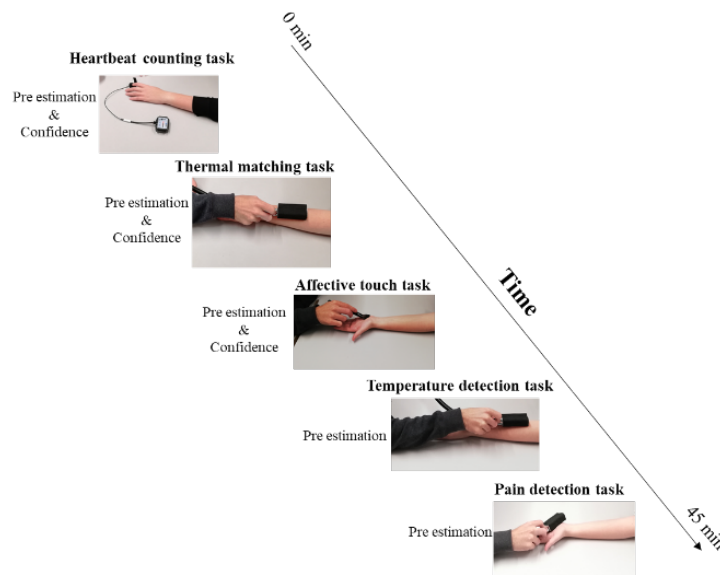
403

**404 Experimental procedure**

405 Participants were welcomed into the experimental room, and they were asked to sit on a table  
406 opposite the experimenter. Upon arrival, they were asked to sign a consent form and to complete  
407 the following questionnaires presented in an online format: the demographic questionnaire,  
408 BAQ, BPQ, EDE-Q and DASS. The questionnaires were always presented at the beginning of  
409 the experimental procedure to ensure that participants were given some time to stay at rest  
410 before completing the *heartbeat counting task*, which was the first interoceptive task that all  
411 participants completed. Previous studies showed that the heartbeat counting task might be  
412 influenced by other activities (e.g., Ring et al., 2015; Brener & Ring, 2016), therefore we  
413 decided to conduct this task first (for an overview of procedures and tasks, see Figure 1 and  
414 Table 2). Participants were given the choice to either keep their eyes closed or open, whichever  
415 helped them feel more comfortable, in order to be as accurate as possible. The aforementioned  
416 experimental procedure prior to the thermal matching task took approximately 30 minutes,  
417 giving participants the opportunity to acclimatise themselves before proceeding with the  
418 dynamic *thermal matching task*. Participants were asked to wear a disposable blindfold and to  
419 place their left arm on the table to complete the dynamic *thermal matching task*, following the  
420 method fully described in Method section above. Participants were asked to pay close attention

421 to each reference temperature because they were given the possibility to feel it just once. Upon  
422 completion, participants removed the blindfold, and they were given a short break before  
423 beginning the *affective touch task*. As part of this task, they were familiarised with the  
424 pleasantness rating scale, and the experimenter identified and marked two identical areas of 9x4  
425 cm on the left forearm and palm with a washable marker, as was done in previous studies  
426 (Crucianelli et al., 2013; 2016; 2018). This was performed to control the stimulated area and  
427 the pressure applied during the touch by checking that the tactile stimulation was applied just  
428 inside the marked areas (more pressure would result in a wider spreading of the brush, that is,  
429 the tactile stimulation would be applied outside of the marked borders). Alternating the  
430 stimulated areas would counteract the fatigue of the CT fibres (McGlone et al., 2012).  
431 Participants were asked to wear the blindfold again for the entire duration of the affective touch  
432 task. Next, participants could take a break from wearing the blindfold before starting the *static*  
433 *temperature detection task*. No break was taken between the cold and warm blocks, but  
434 participants were only allowed to remove the blindfold at the very end of the task. The last part  
435 of the experimental procedure consisted of the *static pain detection task*, for which participants  
436 were asked to wear the blindfold once again. All the experimental tasks were conducted on the  
437 left, non-dominant hand or forearm. The starting location for each task was alternated between  
438 the forearm and the palm (e.g., participants starting one task on the palm next completed the  
439 task with the forearm; those who started one task with the forearm completed the following task  
440 with the palm). The order of the tasks was kept constant (with internal randomisation) (Figure  
441 1 and Table 2). The pain detection task was performed last as to not arouse the body or cause  
442 hypoalgesia, which could affect performance on the other tasks (Gröne et al., 2012). The entire  
443 experimental procedure lasted approximately one hour, and participants were offered a wipe to  
444 remove the marker from the skin and were provided with a full debriefing at the end of the  
445 session. Testing took place in a testing room with constant temperature and humidity, with no  
446 significant changes in temperature between the beginning ( $M = 22.55^{\circ}\text{C}$ ,  $SD = 0.49$ ) and the  
447 end ( $M = 23.10^{\circ}\text{C}$ ,  $SD = 0.47$ ) of the testing session.

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**Figure 1. The experimental procedure.** The heartbeat counting task was conducted using the BioNomadix system of a wearable wireless device connected to a Biopac MP150 system. The thermal matching task, temperature detection task and pain detection task were conducted using the thermode connected to the Somic thermal stimulator. In the affective touch task, tactile stimulation was delivered with a soft brush. All the tasks were repeated on the forearm and on the palm in a randomised order.

**Table 2. Overview of the structure of the different tasks.** The basic tasks are described in the order that they were completed during the experimental procedure. Each row represents a task, and each column describes one step of each task, starting with pre-task estimation (or prior belief of performance), followed by the name of the actual task with its description in terms of method (number of trials and body sites) and outcome measures (interoceptive accuracy). The final column refers to the participants' performance confidence, the data of which were collected after each trial of the heartbeat counting task, dynamic thermal matching task and affective touch task only.

Interoceptive modality	Pre-task estimation	Interoceptive task	Task description	Outcome measures (interoceptive accuracy)	Post-trial confidence
Questionnaires	N/A	Interoceptive sensibility	Body Awareness Questionnaire Body Perception Questionnaire	Values between 18 - 126 Values between 12 - 60	N/A
Cardiac	<i>How well are you going to perform on this task? (0, not well at all - 100, very well)</i>	Heartbeat counting task	3 trials (25 s, 45 s, and 65 s)	Values between 0 - 1	<i>How confident are you with your answer? (0, not at all - 10, very)</i>
Dynamic temperature		Thermal matching task	3 temperatures (30, 32, and 34°C) 2 body locations (palm and forearm) 2 staircase approaches per temperature (increasing and decreasing temperature)	Values between 0 - 1	
Tactile affectivity		Affective touch task	7 velocities (0.3, 1, 3, 6, 9, 18, 27 cm/s) 2 body locations (palm and forearm)	Pleasantness of touch 0-100 & tactile sensitivity (CT – non-CT)	
Static temperature		Temperature detection	Method of limit 5 trials for warm and 5 trials for cold	Detection temperature and standard deviations	N/A
Static pain		Pain detection	Method of limit 5 trails for warm pain	Detection temperature and standard deviations	



**463 Design and plan of analysis**

464 All data were analysed with the Statistical Package for Social Sciences (SPSS), version 26. The  
465 data were tested for normality by means of the Shapiro-Wilk test and were found to be non-  
466 normal ( $p < .05$ ). Subsequent two-step approach transformations (Templeton, 2011) did correct  
467 for the normality violations (see Supplementary Materials); therefore, parametric tests were  
468 used to analyse the data (described below). The false discovery rate (FDR, Benjamini &  
469 Hochberg, 1995) was used to correct for multiple correlations (we reported the corrected values  
470 for the significant effects); this method is widely used when a large number of multiple  
471 comparisons is applied, and it controls the proportions of false rejections out of all rejections  
472 (Benjamini, 2010). Bonferroni-corrected post hoc comparisons were used to follow up  
473 significant effects and interactions. All  $p$  values are 2-tailed unless otherwise specified.

474  
475 First, we focused on the analysis of each task separately. As in Garfinkel et al., 2016, we first  
476 assessed whether there was a relationship between the dimensions of interoception (accuracy,  
477 confidence, and prior beliefs) for each submodality separately (cardiac, dynamic and static  
478 temperature, affective touch, and pain). Then, we investigated the relationship between the  
479 different interoceptive submodalities and dimensions. Specifically, we ran correlational  
480 analyses to investigate the relationship between accuracy and confidence across the  
481 submodalities. In secondary analyses using parametric correlational analyses, we also explored  
482 the relationship between accuracy and prior beliefs of performance, as well as the relationships  
483 between the interoceptive dimensions and individual differences in the questionnaires probing  
484 self-reported interoceptive awareness and bodily awareness (interoceptive sensibility). The  
485 results of secondary analyses are reported in Supplementary Materials only, for brevity.

486  
487 We also performed Bayesian correlations for our main analyses of interest (i.e., correlations  
488 between accuracy - objective performance - across different interoceptive modalities). Bayesian  
489 correlations produce a Bayes factor (BF) as the main output index.  $BF_{01}$  indicates the  
490 probability supporting the null over the alternative hypotheses (e.g., a  $BF_{01} = 8$  means that  $H_0$   
491 is 8 times more likely to be true than  $H_1$ ). By convention, BFs between 0.33 and 3 are considered  
492 inconclusive (see Lee & Wagenmakers, 2014; Biel & Friedrich, 2018 for guidance on the  
493 interpretation of BF).

494

**495 Interoceptive accuracy**

496 We calculated the cardiac interoceptive accuracy (*heartbeat counting task*) by means of the  
 497 following formula that allowed us to compare the counted and recorded heartbeats (Schandry,  
 498 1981):

$$499 \quad \frac{1}{3} \sum \left( 1 - \frac{|\text{recorded heartbeat} - \text{counted heartbeats}|}{\text{recorded heartbeats}} \right)$$

500

501 For the other tasks, the focus was 1) to explore whether there was a significant effect of touch  
 502 location (hairy vs. non-hairy skin) and 2) to obtain an accuracy value that could resemble, and  
 503 therefore be compared to, the interoceptive accuracy measured by means of the heartbeat  
 504 counting task. This was done to ensure that levels of accuracy were equated across the  
 505 modalities.

506

507 For the dynamic *thermal matching task*, we used the following formula:

508

$$509 \quad 1 - \left( \sum \frac{(|\text{reported temperature} - \text{reference temperature}| / 2)}{12} \right)$$

510

511

512 where 12 represents the total number of options presented to participants (regardless of  
 513 direction - overestimation or underestimation of temperature) across the three trials. Both of  
 514 these formulas provide a value between 0 and 1, with 0 suggesting poor performance and 1  
 515 indicating optimal performance on the task. We kept the order of the increasing and decreasing  
 516 stimuli separate given the different mechanisms and skin responses known to be involved when  
 517 perceiving cooling and warming stimuli (Nordin, 1990; Wessberg et al., 2003; Olausson,  
 518 Wessberg, Morrison, McGlone, & Vallbo, 2010, for a review). Thus, for each subject, we  
 519 obtained one increasing and one decreasing accuracy value for the forearm and for the palm.  
 520 We provide an additional control analysis that focused on the perception of the three  
 521 temperatures separately (30, 32, and 34°C) in hairy and non-hairy skin in the Supplementary  
 522 Materials.

523

524 The *affective touch task* was analysed as in previous studies (e.g., Crucianelli et al., 2018). We  
 525 obtained the scores for pleasantness for the CT-optimal, borderline, and CT-non-optimal  
 526 velocities by averaging the scores of tactile pleasantness in each of these categories. This  
 527 allowed us to investigate the main effect of velocity and skin site on pleasantness by means of  
 528 a repeated measures ANOVA. For the purpose of this study, our main variable of interest was

529 the so-called ‘affective touch sensitivity’ (Crucianelli et al., 2018; Kirsch et al., 2020), which  
 530 describes the individual’s ability to differentiate levels of pleasantness between affective and  
 531 neutral touch, without taking into account the total pleasantness. Thus, we averaged the  
 532 pleasantness scores for CT-optimal velocities and for CT-non-optimal velocities, and we  
 533 calculated the differences between these two measurements to obtain one tactile sensitivity  
 534 score for the forearm and one for the palm. This differential score was then used in the analysis  
 535 to investigate the relationship with participants’ performance on the other interoceptive tasks.

536

537 Next, for both *static temperature detection* and *static pain detection*, we were interested in both  
 538 the sensitivity (i.e., the smallest change in temperature a person could detect) and the  
 539 consistency or precision (i.e., the variability in the individual responses across the different  
 540 trials, quantified as standard deviations) of the detection across trials. As a proxy of  
 541 interoceptive accuracy, we calculated the relationship between sensitivity and consistency and  
 542 obtained one detection accuracy value for cold temperature, one value for warm temperature  
 543 and one value for warm pain for both hairy and non-hairy skin using the following formula:

544

$$\left[ \frac{\Sigma(|32 - \text{detection temperature}|)}{5} \right] * \text{standard deviation}$$

545

546

547 where 32°C is the baseline starting temperature, detection temperature is the temperature that  
 548 participants recognise as different (warmer or cooler) from baseline, and 5 is the total number  
 549 of trials; we multiplied by the standard deviation to account for the individual variability in  
 550 responses across trials. We developed this formula to take into account both the accuracy (i.e.,  
 551 how many degrees are necessary for the participants to detect a change) and the precision (i.e.,  
 552 how consistent participants are in their performance across trials). We then used these detection  
 553 accuracy values to investigate the relationship with the other interoceptive modalities.

554

### 555 ***Interoceptive metacognitive awareness: Confidence and prior beliefs***

556 In terms of metacognitive interoception, we focused both on ‘offline’ insight into participants’  
 557 own abilities *before* they completed the tasks and on ‘online’ confidence in their own answers  
 558 reported immediately *after* each trial of the heartbeat counting task, dynamic thermal matching  
 559 task and affective touch task. Specifically, metacognitive awareness for each interoceptive  
 560 modality was operationalised as the extent to which pre-estimation of performance on each task  
 561 and confidence predicted accuracy (Garfinkel et al., 2015; 2016). This was analysed by means  
 562 of multiple regressions, with pre-estimation and confidence as the main predictors and accuracy

563 as the outcome variable. The offline metacognitive measure was computed separately for  
 564 cardiac, dynamic thermal matching task, affective touch, static temperature and static pain  
 565 detection responses to provide five measures of metacognitive awareness. The online  
 566 metacognitive measure (i.e., confidence) was obtained only for the cardiac interoception,  
 567 dynamic thermal matching, and affective touch tasks because the static temperature detection  
 568 task and static pain detection task followed a standardised method-of-limits procedure;  
 569 providing individual confidence ratings after each trial during the task would have disrupted  
 570 the participants' actual performance. Confidence ratings were averaged over trials for all the  
 571 tasks.

572

## 573 **Results**

### 574 **Demographics and interoceptive sensibility**

575 The mean scores and standard deviations for BMI, interoceptive sensibility (as measured by  
 576 means of the BAQ and BPQ), EDE-Q and DASS scores are reported in Table 3. No effect of  
 577 sex on any of these measures was found, except for the EDE-Q.

578

579 **Table 3.** Mean and standard deviations for the participants' body mass index (BMI); Body Awareness  
 580 Questionnaire (BAQ) scores; Body Perception Questionnaire (BPQ) scores; Eating Disorders Examination  
 581 Questionnaire (EDE-Q) scores; and the scores on the depression, anxiety and stress scales.

582

	BMI	BAQ	BPQ	EDE-Q	Depression	Anxiety	Stress
<b>Total sample</b>	22.87 (2.99)	79.79 (18.38)	29.90 (8.77)	1.42 (1.12)	4.13 (3.87)	4.02 (3.52)	5.76 (4.05)
<b>Females (32)</b>	22.19 (2.90)	79.66 (19.86)	30.00 (9.22)	1.70 (1.14)	4.16 (4.05)	3.38 (2.79)	5.88 (4.14)
<b>Males (30)</b>	23.60 (2.95)	79.93 (16.99)	29.80 (8.41)	1.11 (1.04)	4.10 (3.74)	4.70 (4.10)	5.63 (4.02)
<b>F (p) values</b>	3.62 (0.06)	0.03 (0.95)	0.08 (0.93)	4.56 (0.04)*	0.03 (0.96)	2.23 (0.14)	0.05 (0.82)

583

584

### 585 **Interoceptive accuracy across modalities**

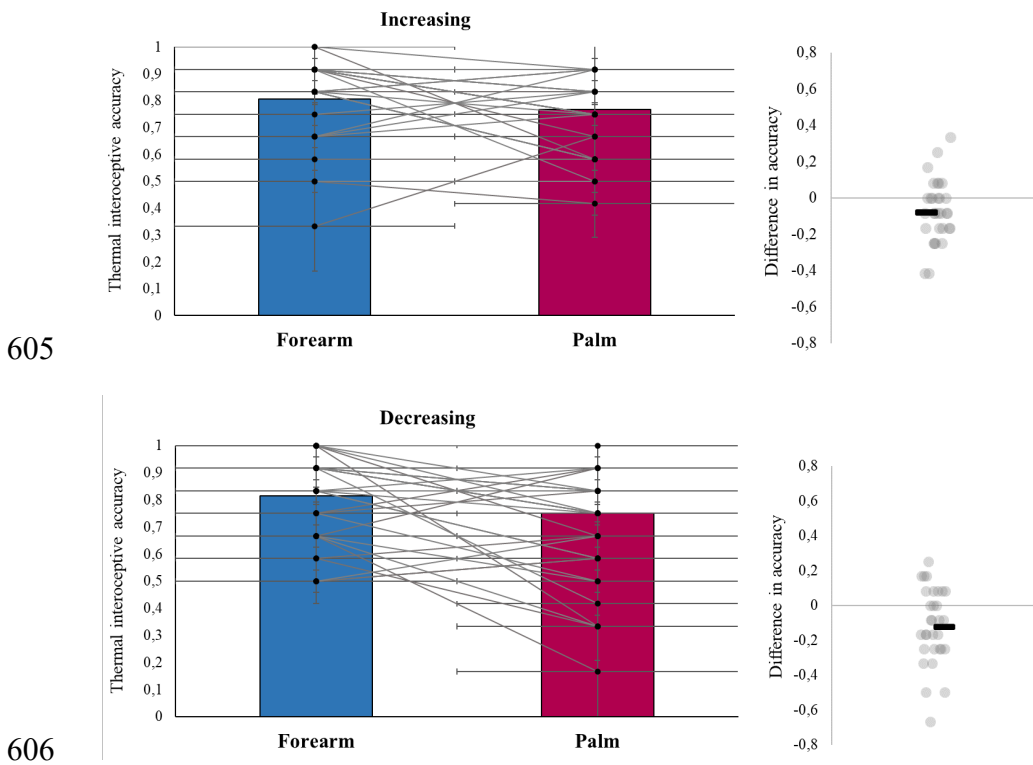
#### 586 *Heartbeat detection task*

587 The mean cardiac interoceptive accuracy score was 0.64 (SD = 0.25) in the present sample.  
 588 This value is in line with those reported in previous studies (e.g., Tsakiris, Jiménez &  
 589 Costantini, 2011; Crucianelli et al., 2018). The mean confidence score was 5.77 (SD = 2.28).  
 590 One-way ANOVA revealed no effect of sex on cardiac accuracy ( $F(1, 61) = 0.128, p = 0.722,$   
 591  $\eta^2 = 0.002$ ).

592

#### 593 *(Dynamic) thermal matching task*

594 As mentioned in the Methods section, we obtained one increasing (staircase) temperature  
 595 accuracy value for the forearm and one for the palm and one decreasing (staircase) value for  
 596 the forearm and one value for the palm. The results of the 2 (location: palm vs. forearm) x 2  
 597 (staircase: increasing vs. decreasing) repeated measure ANOVA revealed a significant main  
 598 effect of location ( $F(1, 61) = 5.00, p = 0.029, \eta_p^2 = 0.084$ , Figure 2), with participants being  
 599 more accurate in the detection of dynamic temperature in the forearm ( $M = 0.81; SD = 0.16$ )  
 600 than in the palm ( $M = 0.76; SD = 0.17$ ). No main effect of staircase ( $F(1, 61) = 0.142; p =$   
 601  $0.707, \eta_p^2 = 0.002$ ) or significant interaction ( $F(1, 61) = 0.299; p = 0.586, \eta_p^2 = 0.005$ ) was  
 602 found. No effect of sex was found for any of the variables of interest as investigated by means  
 603 of separate one-way ANOVAs (all  $F_s$  between 0.024 and 0.467; all  $p_s$  between 0.497 and 0.878);  
 604 thus, sex was not considered in subsequent analyses.

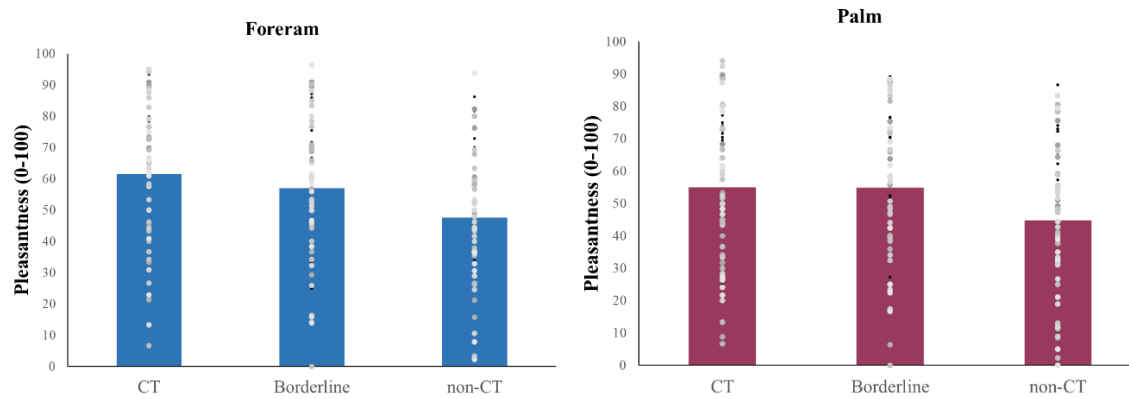


605  
 606  
 607  
 608 **Figure 2.** Mean, data distribution and standard errors for the dynamic thermal matching task, performed on the  
 609 forearms (in blue) and palms (in burgundy) of the participants. The panel on top shows task performance during  
 610 increasing trials, and the panel on the bottom shows task performance on decreasing trials. The graphs on the right-  
 611 hand side represent the distribution of the differences between task performance regarding the forearm and palm  
 612 for each participant.

### 613 *Affective touch task*

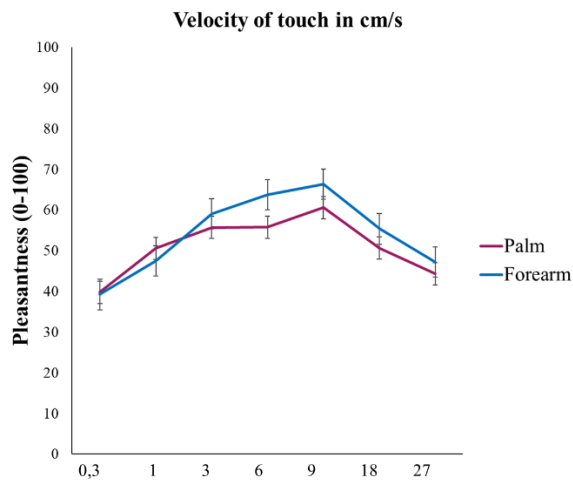
614  
 615  
 616 We averaged the CT optimal velocities (3 and 6 cm/s), borderline velocities (1 and 9 cm/s) and  
 617 the CT-non-optimal velocities (0.3, 18 and 27 cm/s) to obtain three velocity variables. As

618 expected, there was a main effect of velocity on touch pleasantness ( $F(2, 122) = 40.07, p <$   
 619  $0.001, \eta^2 = 0.417$ ). Bonferroni corrected post hoc analysis ( $\alpha = 0.017$ ) revealed that slow, CT-  
 620 optimal touch was rated as more pleasant ( $M = 58.24; SD = 23.02$ ) than fast, CT-non-optimal  
 621 touch ( $M = 46.08; SD = 22.23; t(61) = 6.67; p < 0.001$ , Figure 3, Figure 1 in Supplementary  
 622 Materials) and touch delivered at borderline velocities ( $M = 55.91; SD = 22.87; t(61) = 2.77; p$   
 623  $< 0.001$ ). There was also a significant difference between borderline and CT-non-optimal touch  
 624 ( $t(61) = 6.47; p < 0.001$ ). There was a main effect of location ( $F(1, 61) = 5.708, p = 0.020, \eta^2$   
 625  $= 0.092$ ), with touch being rated overall as more pleasant in the forearm ( $M = 55.32; SD =$   
 626  $22.61$ ) than in the palm ( $M = 51.50; SD = 23.80$ ), consistent with previous findings (Löken,  
 627 Evert & Wessberg, 2011). There was a significant interaction between velocity and location ( $F$   
 628  $(2, 122) = 4.896; p = 0.009, \eta^2 = 0.080$ ). Bonferroni corrected post hoc analysis ( $\alpha = 0.017$ )  
 629 revealed a significant difference between the forearm and palm only in the perception of slow,  
 630 CT-optimal touch ( $t(61) = -2.93; p = 0.005$ ), but not in the perception of borderline ( $t(61) = -$   
 631  $1.19; p = 0.241$ ) or CT-non-optimal touch ( $t(61) = -0.46; p = 0.650$ ). No effect of sex on any of  
 632 the touch pleasantness scores was found (all  $F_s$  between 0.002 and 2.394; all  $p_s$  between 0.127  
 633 and 0.966).  
 634



635

636



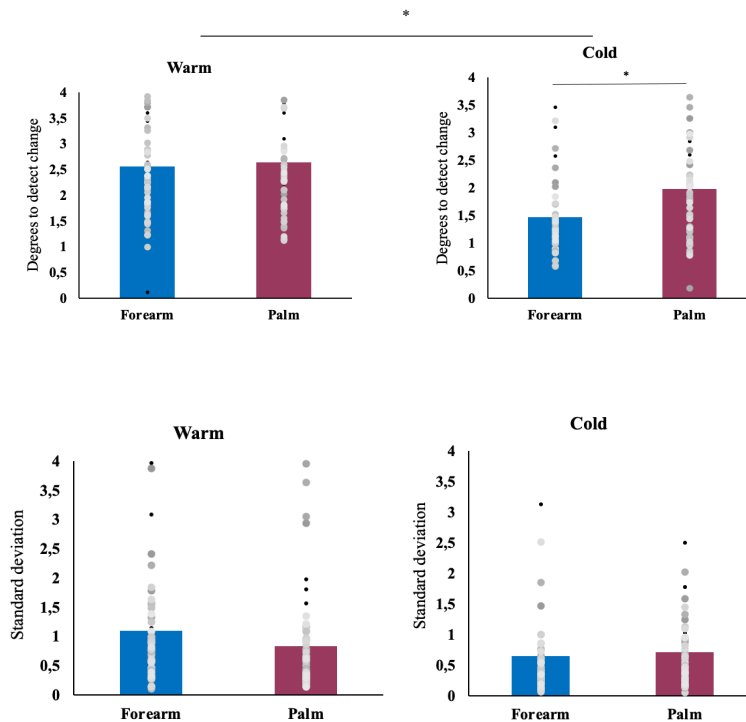
**Figure 3. Top panels:** Mean and data distribution for the pleasantness scores for CT-optimal, borderline and CT-non-optimal velocities for the forearm and palm. **Left panel:** Mean and standard errors for the same dataset of the affective touch task for each velocity (velocities are reported in cm/s), showing the main effect of velocity and location (forearm vs. palm) on touch pleasantness. A full account of the mean pleasantness for each velocity is reported in Figure 1 of the Supplementary Materials.

637

638

639 *(Static) temperature detection task*

640 We compared the smallest change in temperature participants could detect when temperature  
 641 was increasing (warm) or decreasing (cool) from the neutral starting temperature of 32°C in  
 642 both hairy (forearm) and non-hairy skin (palm). The results of the 2 (temperature: warm vs.  
 643 cool) x 2 (location: forearm vs. palm) repeated measures ANOVA revealed a main effect of  
 644 temperature ( $F(1, 61) = 67.74; p < 0.001, \eta^2 = 0.855$ ), suggesting that participants could detect  
 645 cooling ( $M = 1.75^\circ\text{C}; SD = 1.08$ ) quicker or with a significantly smaller change in temperature  
 646 compared to warming ( $M = 2.63^\circ\text{C}; SD = 1.36$ , Figure 4). There was a non-significant main  
 647 effect of location ( $F(1, 61) = 3.71; p = 0.06, \eta^2 = 0.066$ ), with participants needing a smaller  
 648 but non-significant variation in terms of °C to detect changes in temperature in the forearm ( $M$   
 649  $= 2.05^\circ\text{C}; SD = 1.25$ ) compared to the palm ( $M = 2.34^\circ\text{C}; SD = 1.35$ , Figure 4). There was a  
 650 significant interaction between temperature and skin site ( $F(1, 61) = 5.90; p = 0.02, \eta^2 =$   
 651  $0.060$ ). Bonferroni-corrected post hoc analysis ( $\alpha = 0.025$ ) revealed a significant difference  
 652 between hairy and non-hairy skin in the detection of cold temperatures ( $t(61) = -3.47, p < 0.01$ )  
 653 but not warm temperatures ( $t(61) = -0.18, p = 0.86$ , see Figure 4).



654

655 **Figure 4.** Means and data distribution for the static temperature detection task, showing the main effect of  
 656 temperature on participants' ability to detect temperature, and significant difference between palm and forearm in  
 657 detecting the cold, top panels (quantified as degrees to detect the change, measured in °C) and consistency in  
 658 detecting changes in temperature (quantified as standard deviation), bottom panels, for warm and cold  
 659 temperatures. \* indicates significant differences,  $p < 0.05$ .  
 660  
 661

662 The main effect of sex on participants' temperature detection was ( $F(1, 61) = 3.97; p = 0.051$ )  
 663 for warm, and ( $F(1, 61) = 3.88; p = 0.053$ ) for cold temperatures on the palm, and ( $F(1, 61) =$   
 664  $2.56; p = 0.115$ ) for warm and ( $F(1, 61) = 0.05, p = 0.831$ ) for cold, on the forearm. That is,  
 665 female participants could detect changes in temperature more promptly than male participants  
 666 on the palm (female:  $M = 2.03, SD = 0.85$ ; male:  $M = 2.66, SD = 1.61$ ) but not on the forearm  
 667 (female:  $M = 1.94; SD = 0.96$ ; male:  $M = 2.15; SD = 1.20$ ).  
 668

669 In terms of consistency (operationalised as the standard deviation) in the perception of thermal  
 670 static stimuli, the results of the 2 (temperature: cool vs. warm) x 2 (location: forearm vs. palm)  
 671 repeated measures ANOVA revealed a main effect of temperature ( $F(1, 61) = 7.09; p = 0.01,$   
 672  $\eta^2 = 0.104$ ), suggesting that participants were more consistent in the detection of cold  
 673 temperatures ( $M = 0.71; SD = 0.65$ ) than warm temperatures ( $M = 0.96; SD = 0.68$ , Figure 4).  
 674 No significant main effect of location ( $F(1, 61) = 1.19; p = 0.28, \eta^2 = 0.019$ ) or interaction ( $F$   
 675  $(1, 61) = 2.16; p = 0.15, \eta^2 = 0.034$ ) was found. There was an effect of sex on the consistency



676 in the detection of warm temperatures in both the palm ( $F(1, 61) = 6.514; p = 0.013$ ) and  
677 forearm ( $F(1, 61) = 5.041; p = 0.028$ ) but not for the detection of cold temperatures (palm:  $F$   
678  $(1, 61) = 0.094; p = 0.760$ ; forearm:  $F(1, 61) = 0.018; p = 0.893$ ). That is, female participants  
679 were significantly more consistent than male participants in the detection of static warming in  
680 the palm (female:  $M = 0.59; SD = 0.37$ ; male:  $M = 1.09; SD = 1.04$ ) and forearm (female:  $M =$   
681  $0.84; SD = 0.74$ ; male:  $M = 1.37; SD = 1.08$ ).

682

683 *(Static) pain detection task*

684 Two paired sample t-tests were used to investigate differences between hairy (forearm) and  
685 non-hairy (palm) skin in the temperature necessary for participants to detect pain and the  
686 consistency (i.e., standard deviations) in reporting pain sensation. The results showed no  
687 significant main effects of body site on individual thresholds ( $t(61) = -1.12; p = 0.27$ ; forearm,  
688  $M = 42.26; SD = 4.47$ ; palm,  $M = 42.72; SD = 4.50$ ) or on consistency in detection ( $t(56) = -$   
689  $0.70; p = 0.49$ , see Figure 2 in Supplementary Materials). No effect of sex on pain detection  
690 was found (all  $F_s$  between 0.139 and 3.06; all  $p_s$  between 0.086 and 0.711).

691

692 *Relationships across interoceptive modalities*

693 Given the substantial number of analyses, we have applied FDR corrections (Benjamini-  
694 Hochberg adjusted  $p$  value = 0.18). No significant relationship was found between performance  
695 on the heartbeat counting task and the dynamic thermal matching task on the forearm (see Table  
696 4) nor on the palm (see Table 5).  $BF_{01}$  indicated that the null hypothesis (cardiac accuracy not  
697 related to thermal accuracy) was more likely than the alternative hypothesis (cardiac accuracy  
698 related to thermal accuracy) ( $BF_{01} > 1$ ), except for the relationship between cardiac accuracy  
699 and the thermal matching task in the forearm when temperature was decreasing ( $BF_{01} < 1$ ) (see  
700 Lee & Wagenmakers, 2014; Biel & Friedrich, 2018 for guidance on the interpretation of BF).

701

702 In line with previous findings (Crucianelli et al., 2018), performance on the heartbeat counting  
703 task was not related to affective touch sensitivity, that is, the difference in pleasantness between  
704 slow and fast touch on the forearm (see Table 4) or on the palm (see Table 5 and Figure 3 in  
705 Supplementary Materials).  $BF_{01}$  indicated that the null hypothesis (cardiac accuracy not related  
706 to tactile sensitivity) was 7.38 (for the forearm) and 7.64 (for the palm) times more likely than  
707 the alternative hypothesis (cardiac accuracy related to tactile sensitivity) ( $BF_{01} > 1$ ).

708 Cardiac interoceptive accuracy was not significantly related to the detection of static  
709 temperature on the forearm (see Table 4) or on the palm (see Table 5).  $BF_{01}$  indicated that the

710 null hypothesis (cardiac accuracy not related to static temperature detection) was more likely  
 711 than an alternative hypothesis (cardiac accuracy related to static temperature detection) (all  
 712  $BF_{01} > 1$ ). Finally, no significant relationship was found between cardiac interoceptive accuracy  
 713 and (warm) pain detection (see Table 4 for forearm data and Table 5 for palm data).  $BF_{01}$   
 714 indicated that the null hypothesis (cardiac accuracy not related to pain detection) was more  
 715 likely than an alternative hypothesis (cardiac accuracy related to pain detection) (all  $BF_{01} > 1$ ).

716

717 **Table 4.** Correlational matrix describing the relationship between performance on the different interoceptive tasks  
 718 (i.e., interoceptive accuracy) on the forearm. Thermal interoceptive accuracies when the temperature is decreasing  
 719 (cooling) and increasing (warming) are significantly correlated.  $P$  values correspond to original FDR corrected  
 720 values.

721

722

Forearm		Heartbeat counting task	Thermal matching task		Affective touch task	Temperature detection		Pain detection
			Increasing	Decreasing		Warm	Cold	
Heartbeat counting task		1						
Thermal matching task	Increasing	$r = 0.06$ $p = 0.980$ $BF_{01} = 9.47$	1					
	Decreasing	$r = 0.27$ $p = 0.180$ $BF_{01} = 0.62$	$r = 0.36$ $p = 0.020^*$ $BF_{01} = 0.02$	1				
Affective touch task		$r = -0.09$ $p = 0.935$ $BF_{01} = 7.38$	$r = 0.05$ $p = 0.852$ $BF_{01} = 9.99$	$r = 0.06$ $p = 0.980$ $BF_{01} = 8.58$	1			
Temperature detection	Warm	$r = -0.14$ $p = 0.840$ $BF_{01} = 5.66$	$r = -0.13$ $p = 0.840$ $BF_{01} = 5.07$	$r = -0.05$ $p = 0.852$ $BF_{01} = 9.99$	$r = -0.06$ $p = 0.892$ $BF_{01} = 6.19$	1		
	Cold	$r = 0.05$ $p = 0.852$ $BF_{01} = 9.38$	$r = -0.09$ $p = 0.987$ $BF_{01} = 6.87$	$r = -0.06$ $p = 0.927$ $BF_{01} = 8.33$	$r = -0.33$ $p = 0.513$ $BF_{01} = 0.30$	$r = 0.14$ $p = 0.784$ $BF_{01} = 5.61$	1	
Pain detection		$r = 0.04$ $p = 0.818$ $BF_{01} = 9.49$	$r = 0.06$ $p = 0.945$ $BF_{01} = 10.02$	$r = -0.09$ $p = 0.940$ $BF_{01} = 8.04$	$r = -0.01$ $p = 0.942$ $BF_{01} = 6.07$	$r = 0.12$ $p = 0.863$ $BF_{01} = 6.68$	$r = -0.06$ $p = 0.980$ $BF_{01} = 8.92$	1

723

724

725

726 **Table 5.** Correlational matrix describing the relationship between the performances at the different interoceptive  
 727 tasks (i.e., interoceptive accuracy) on the palm. Thermal interoceptive accuracy when the temperature is decreasing  
 728 (cooling) is negatively correlated with cold detection, and the performance in the warm detection task is  
 729 significantly correlated with both cold detection and pain detection tasks in the palm only.  $P$  values correspond to  
 730 original FDR corrected values. \*indicates  $p$  values that are significant after correction for multiple comparisons  
 731 (FDR).

732

733

734

735

736

Palm		Heartbeat counting task	Thermal matching task		Affective touch task	Temperature detection		Pain detection
			Increasing	Decreasing		Warm	Cold	
Heartbeat counting task		1						
Thermal matching task	Increasing	$r = 0.03$ $p = 0.851$ $BF_{01} = 9.67$	1					
	Decreasing	$r = 0.16$ $p = 0.711$ $BF_{01} = 6.31$	$r = 0.32$ $p = 0.105$ $BF_{01} = 1.2$	1				
Affective touch task		$r = -0.04$ $p = 0.840$ $BF_{01} = 7.64$	$r = -0.05$ $p = 0.865$ $BF_{01} = 9.55$	$r = -0.16$ $p = 0.801$ $BF_{01} = 5.34$	1			
Temperature detection	Warm	$r = 0.05$ $p = 0.952$ $BF_{01} = 9.20$	$r = -0.20$ $p = 0.513$ $BF_{01} = 1.89$	$r = -0.05$ $p = 0.921$ $BF_{01} = 6.29$	$r = -0.07$ $p = 0.990$ $BF_{01} = 8.11$	1		
	Cold	$r = 0.01$ $p = 0.990$ $BF_{01} = 10.02$	$r = -0.07$ $p = 0.990$ $BF_{01} = 9.15$	$r = -0.29$ $p = 0.140$ $BF_{01} = 0.30$	$r = -0.21$ $p = 0.577$ $BF_{01} = 2.92$	<b><math>r = 0.41</math></b> <b><math>p = 0.021^*</math></b> <b><math>BF_{01} = 0.04</math></b>	1	
Pain detection		$r = 0.10$ $p = 0.950$ $BF_{01} = 7.31$	$r = -0.17$ $p = 0.798$ $BF_{01} = 5.21$	$r = -0.16$ $p = 0.770$ $BF_{01} = 6.41$	$r = -0.33$ $p = 0.840$ $BF_{01} = 8.54$	<b><math>r = 0.34</math></b> <b><math>p = 0.042^*</math></b> <b><math>BF_{01} = 0.25</math></b>	$r = 0.12$ $p = 0.914$ $BF_{01} = 6.71$	1

737

738 The rest of the correlations among the skin-based interoceptive tasks are shown in Tables 4 and  
739 5, and as can be seen there were mainly no significant relationships in line with relatively  
740 independent processing (see also Supplementary Figure 4 in the Supplementary Materials).  
741 Noteworthy the affective task showed little evidence for correlation with the thermal and  
742 nociceptive tasks, and the thermal and nociceptive tasks were uncorrelated on the forearm. The  
743 only significant correlation across modalities we observed was between warm temperature  
744 detection and pain (Table 5) in the palm.

745

746 However, as could be expected there were some significant correlations between tasks within  
747 sub-modalities. Performances on the thermal matching task in increasing and decreasing scales  
748 were significantly correlated on the forearm (Table 4) but not in the palm. Warm temperature  
749 detection was significantly correlated with cold detection in the palm (Table 5), and pain, as we  
750 just reported above.

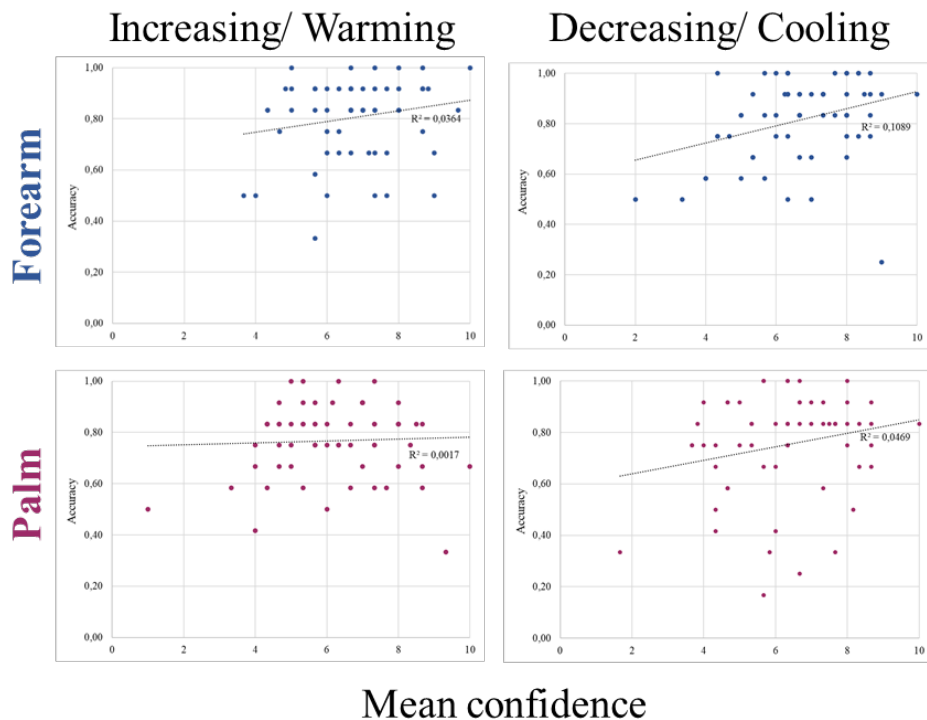
751

752 **Confidence across modalities**

753 A similar approach of analysis was adopted for the confidence scores for cardiac awareness,  
754 dynamic temperature, and affective touch, whereby we focused first on the different tasks  
755 separately and then on the relationship of the participants' confidence in completing the  
756 different tasks. Confidence in one's own performance in the *heartbeat counting task* was not  
757 related to actual performance ( $r = 0.128$ ;  $p = 0.323$ , see Figure 5 in the Supplementary  
758 Materials).

759  
760 In the *thermal matching task*, the results of a 2 (location) x 2 (order) repeated measures ANOVA  
761 showed a significant main effect of location ( $F(1, 61) = 24.64$ ;  $p < 0.001$ ), with participants  
762 being more confident with their answers in the forearm ( $M = 6.73$ ;  $SE = 0.18$ ) than in the palm  
763 ( $M = 6.22$ ;  $SE = 0.20$ ). The order of presentation of temperature (staircase  
764 increasing/decreasing) did not have a significant effect ( $F(1, 61) = 0.184$ ;  $p = 0.67$ ) on  
765 confidence; the interaction between staircase and location was not significant ( $F(1, 61) = 1.54$ ;  
766  $p = 0.22$ ). Regarding the relationship between performance and confidence in the thermal  
767 matching task, the only significant relationship was between confidence and performance in  
768 decreasing (cooling) temperature in the forearm ( $r = 0.287$ ;  $p = 0.025$ , Figure 6). All the other  
769 relationships between confidence and accuracy in the thermal matching task were non-  
770 significant (increasing forearm:  $r = 0.21$ ;  $p = 0.10$ ; decreasing palm:  $r = 0.19$ ;  $p = 0.12$ ;  
771 increasing palm:  $r = 0.04$ ;  $p = 0.73$ ).

772



773  
 774  
 775 **Figure 6: Confidence-accuracy correspondence in the thermal matching task.** Only for the thermal matching  
 776 task (TMT) on the forearm at decreasing (cooling) temperatures was there a correspondence between accuracy and  
 777 the participants' average confidence rating; this indicated that, at the broad group level, subjective and objective  
 778 dimensions were aligned. By contrast, there was no significant relationship between confidence and accuracy for  
 performance on the TMT regarding the palm (in burgundy).

779 Finally, we focused on the *affective touch task*. The results of the 2 (location) x 3 (velocities)  
 780 repeated measures ANOVA showed no main effect of location ( $F(1, 61) = 0.0; p = 1.00$ ) or  
 781 velocity ( $F(2, 122) = 1.72; p = 0.183$ ) on participants' confidence in performance. The  
 782 interaction between location and velocity was non-significant ( $F(2, 122) = 2.62, p = 0.077$ ).  
 783 Regarding the relationship between performance and confidence in the affective touch task, we  
 784 found a significant relationship between confidence and perception of CT-optimal touch ( $r =$   
 785  $0.366; p = 0.003$ ; Benjamini-Hochberg adjusted  $p$  value = 0.009) and borderline touch ( $r =$   
 786  $0.289; p = 0.023$ ; Benjamini-Hochberg adjusted  $p$  value = 0.03) for the forearm only (see Figure  
 787 6 of Supplementary Materials).

788  
 789 Next, we investigated whether the tendency to be confident in one's own performance accuracy  
 790 was generally related across the submodalities. Confidence in cardiac interoception was  
 791 significantly related to confidence in thermal matching task performance for both the forearm

792 (see Table 6) and palm (see Table 7). The correlations between confidence in cardiac  
 793 interoception and affective touch showed a significant relationship between the former and  
 794 confidence in the perception of CT-optimal touch in the palm (see Table 7) but not in the  
 795 forearm (see Table 6). In terms of confidence across the thermal matching task and affective  
 796 touch, correlational analyses revealed a significant relationship between confidence when  
 797 temperature was increasing and CT-optimal touch in the palm. The same applies for confidence  
 798 when the temperature was decreasing in the palm (see Table 7). Similar results were found for  
 799 the forearm (see Table 6).

800

801 **Table 6.** Correlational matrix describing the relationship between confidence on the different interoceptive tasks  
 802 on the forearm. \*indicates  $p$  values that are significant after correction for multiple comparisons (FDR).  
 803

Forearm		Heartbeat counting task	Thermal matching task		Affective touch task
			Increasing	Decreasing	
Heartbeat counting task		1			
Thermal matching task	Increasing	$r = 0.542$ $p = 0.01^*$	1		
	Decreasing	$r = 0.607$ $p = 0.01^*$	$r = 0.36$ $p = 0.180$ $BF_{01} = 0.02$	1	
Affective touch task		$r = 0.147$ $p = 0.253$	$r = 0.260$ $p = 0.05^*$	$r = 0.315$ $p = 0.02^*$	1

804

805

806

807 **Table 7.** Correlational matrix describing the relationship between confidence on the different interoceptive tasks  
 808 on the palm. \*indicates  $p$  values that are significant after correction for multiple comparisons (FDR).  
 809

Palm		Heartbeat counting task	Thermal matching task		Affective touch task
			Increasing	Decreasing	
Heartbeat counting task		1			
Thermal matching task	Increasing	$r = 0.517$ $p = 0.01^*$	1		
	Decreasing	$r = 0.569$ $p = 0.01^*$	$r = 0.32$ $p = 0.105$ $BF_{01} = 1.2$	1	
Affective touch task		$r = 0.28$ $p = 0.03^*$	$r = 0.448$ $p = 0.01^*$	$r = 0.332$ $p = 0.01^*$	1

810

811 **Discussion**

812 **Summary of key findings**

813 The four main findings of the current work were as follows: 1) perceptual accuracy measures  
814 of cardiac awareness, thermosensation, nociception, and affective touch were not significantly  
815 related (with the only exception of pain and warm detection in the palm). This suggests that  
816 interoception should be seen as a set of relatively independent sensory abilities and  
817 submodalities rather than a generalised process and single trait. 2) Beliefs in performance rated  
818 before the tasks were to a large extent correlated across interoceptive submodalities and with  
819 the confidence ratings in task performance rated after the tasks, which collectively suggest that  
820 these metacognitive levels of assessing interoceptive bodily awareness constitute more general  
821 cognitive processes. 3) We found greater affective touch sensitivity (accuracy), lower cold  
822 detection thresholds, and greater accuracy in the dynamic thermal matching task on the hairy  
823 skin (forearm) compared to the non-hairy skin (palm). These observations are consistent with  
824 the view that hairy skin might play a more important role in skin-based interoceptive functions.  
825 4) Finally, we have shown that a novel thermosensory task—the dynamic thermal matching  
826 task—can be used to probe thermosensation as a skin-based interoceptive submodality and,  
827 thus, complement existing approaches. Collectively, our results suggest that interoception at  
828 the perceptual level is best quantified using a battery of tests that captures its various sensory  
829 channels to obtain a more comprehensive picture and that more attention should be given to  
830 thermosensation as skin-based interoceptive submodality in future research.

831

832 **Interoceptive accuracy across modalities**

833 Our results suggest that sensory signals from heartbeats, pleasant touch stimuli, and  
834 thermosensory and nociceptive stimuli on the skin are processed relatively independently, and  
835 interoceptive accuracy measures obtained from the different modalities do not correlate  
836 significantly across individuals. This finding contrasts with the relatively common view in the  
837 psychological literature of interoception as a single integrated function and generalised ability.  
838 Our studies differ from most previous work in that we use a relatively large number of tests  
839 across submodalities, with a particular focus on three different skin-based submodalities.  
840 Previous studies have compared the classic heartbeat detection tasks to a single or a few other  
841 visceral modalities (Whitehead & Drescher, 1980; Herbert et al., 2012; Azzalini, Rebollo &  
842 Tallon-Baudry, 2019; Garfinkel et al., 2016; Faull, Subramanian, Ezra & Pattinson, 2019;  
843 Monti, Porciello, Tieri & Aglioti, 2020). For example, Garfinkel et al., 2016 observed no

844 significant relationship between cardiac interoception and respiratory awareness in terms of  
845 perceptual accuracy measures, and Crucianelli et al., 2018 found no significant relationship  
846 between accuracy in the heartbeat counting task and an affective touch sensitivity measure.  
847 Ferentzi et al., 2018 used a larger battery of tests that included cardiac interoception, gastric  
848 perception, pain, and taste (a non-interoceptive modality) and did not observe any significant  
849 correlations between the perceptual measures. Thus, our results underscore and extend these  
850 previous findings by showing that a lack of correlated perceptual sensitivity/accuracy measures  
851 is not restricted to the visceral versus skin divide but is also observed between three different  
852 skin-based submodalities and between these skin-based channels from hairy and non-hairy skin  
853 and cardiac perception.

854

855 However, whether these negative correlation findings are reliable and whether our and previous  
856 studies failed to detect weak but psychologically relevant relationships are important questions.  
857 First, note that we *did* observe some significant correlations in accuracy measures between  
858 tasks, which suggests that our tasks were well conducted and that the statistical power was  
859 sufficient to detect such relationships. Specifically, cold and warm temperature detection and  
860 pain and cold detection were correlated on the palm. Furthermore, the task measures were  
861 significantly correlated *within* the skin-based interoceptive submodalities when we correlated  
862 accuracy measures across the palm and forearm (see Supplementary material, Table 4).  
863 Furthermore, in a recent follow-up study, we found a similar nonsignificant correlation between  
864 accuracy measures in the thermal matching task and the heartbeat counting task as in the current  
865 study (Radziun, Crucianelli & Ehrsson, 2022). Future studies could pool data across  
866 experiments and conduct meta-analyses to further investigate how strong the evidence is against  
867 a lack of relationship between accuracy measures across interoceptive submodalities.

868

869 We should note that interoceptive tasks are different for the obvious reason that each task has  
870 been optimised to probe a different sensory channel. Thus, the tasks put somewhat different  
871 demands on memory and executive functions, and this might add variability to the measures,  
872 in addition to the differences involved in basic sensory and perceptual processing. In the  
873 introduction, we acknowledged the limitations with the heartbeat counting tasks, and the static  
874 temperature and pain detection tasks put less demands on memory than the thermal matching  
875 task. Nevertheless, these methodological issues considered, we find little evidence that  
876 interoceptive perceptual abilities generalise across submodalities, and we suggest that it is more  
877 useful to think about these as separate abilities.



878

879 The current study investigated interoception using an individual differences approach, but we  
880 have not directly targeted the mechanisms behind interindividual variability in the various  
881 interoceptive submodalities. One can theorise that individual differences in interoceptive  
882 accuracy measures are driven by peripheral factors, such as different receptor densities,  
883 differences in central processing from the spinal cord to the brain (including differences in  
884 myelination of fibre tracts or differences in grey matter thickness in cortical and thalamic  
885 regions), or differences in high-level cognitive processing in terms of how different brain  
886 regions work together as functional circuits and the interplay between bottom-up and top-down  
887 factors. Future behavioural and neuroscience studies could explore the underlying mechanisms  
888 of such interindividual differences in interoceptive submodality processing.

889

890 How should we think about the current findings with respect to the neuroanatomical and  
891 neurophysiological studies that have shown that the insula processes different kinds of visceral  
892 and C-fibre signals from the skin? It is entirely plausible that the neural processing of  
893 information from the different interoceptive submodalities can remain relatively independent  
894 at lower sensory and early perceptual levels and be implemented in different cortical sections  
895 and separate neuronal populations within the posterior insula. We speculate that the neural basis  
896 for this separation may well be preserved up until at least the posterior insula, at which point  
897 such signals gradually become increasingly integrated with each other and with exteroceptive  
898 information and other sources of information (cognition, emotion) in higher brain areas, such  
899 as the anterior insula, cingulate cortex and orbitofrontal cortex, and give rise to more complex  
900 “interoceptive emotions”, such as subjective pain, thermal distress and comfort, and subjective  
901 tactile pleasure (Crucianelli & Ehrsson, 2022).

902

### 903 **Differences in affective touch and thermosensation between hairy and non-hairy skin**

904 The observed differences in performance on the thermal tasks between hairy (forearm) and non-  
905 hairy (palm) skin could be due to fundamental differences in thermoreceptor densities on hairy  
906 and non-hairy skin and, for the affective touch task and perhaps the thermal matching task,  
907 differences in the engagement of the CT system (see below) (Vallbo, Olausson & Wessberg,  
908 1999; Watkins et al., 2020). This conclusion is in line with recent behavioural findings showing  
909 higher thermal sensitivity in hairy skin than in glabrous skin (Filingeri et al., 2018). Notably,  
910 both the thermal matching task and the temperature detection task showed a similar pattern of  
911 results with regard to the perception of cold; the cold detection thresholds were lower for hairy

912 skin than for non-hairy skin when touch was both dynamic and static. The fact that we have a  
913 higher sensitivity to cooling than warming could be explained by the greater abundance of cold  
914 receptors throughout our entire body (1.3–1.6 times stronger sensitivity to cooling than to  
915 warming; Luo et al., 2020). We also replicated earlier studies showing greater affective touch  
916 sensitivity (Crucianelli et al., 2018; Kirsch et al., 2020) on the forearm compared to the palm,  
917 in line with the notion of more numerous CT afferents in hairy skin (e.g., McGlone et al., 2012).

918

919 We suggest that these observed differences in thermal sensitivity on hairy and non-hairy skin  
920 fit the recent theoretical proposal that skin-based interoceptive signals from the hairy skin might  
921 have a privileged role in social thermoregulation and maintenance of homeostasis (IJzerman et  
922 al., 2015; Morrison, 2016; Burlison & Quigley, 2021). In contrast, we theorise that thermal  
923 signals detected through the non-hairy skin of our body (e.g., palm) might potentially have a  
924 more discriminatory role and might therefore be important for experiencing the temperature of  
925 grasped objects, for instance, a role that is less related to thermoregulation and more related to  
926 exploring the properties of external objects (Vallbo & Johansson, 1984; Johansson & Flanagan,  
927 2009; Corniani & Saal, 2020). Furthermore, we hypothesise that thermal dynamic sensations  
928 (and in particular, those at neutral temperatures typical of skin-to-skin contact) play a different  
929 role in daily social interaction compared to static thermal sensations. The characteristics of CT  
930 optimal stimulation (i.e., slow velocity, light pressure, and neutral temperature) closely  
931 resemble those typical of affiliative touch (McGlone et al., 2014; Burlison & Quigley, 2021;  
932 Fotopoulou, von Mohr & Krahé, 2022); thus, we theorise that thermosensory and CT signals  
933 from hairy skin during pleasant touch stimulation at neutral skin temperature might work in  
934 concert to promote social connection, which is of vital importance for our survival.

935

936 Some findings from the non-hairy skin on the palm are worth commenting on. There were  
937 significant correlations between performance on the static temperature detection task and pain  
938 detection task on the palm only. One possible interpretation could be more integration of static  
939 thermal signals and pain in the palm compared to the forearm, where the processing of such  
940 signals remains more segregated. Previous studies have reported that hairy and glabrous skin  
941 share similar nociceptive afferents, with non-significant differences in pain sensations or brain  
942 potentials in terms of latency and amplitude (Iannetti, Zambreanu, & Tracey, 2006) and similar  
943 thresholds for cooling and warming in the forearm and the palm of the hand (Luo et al., 2020).  
944 These observations are in line with the current findings of non-significant differences in heat  
945 pain detection thresholds for the palm and forearm and suggest that the significant correlation

946 between pain and warm detection in the palm is probably not due to basic differences in  
947 nociceptor density or pain thresholds across the two skin sites. We speculate that people learn  
948 to combine or pair painful and thermal sensations from the palm and digits when manipulating  
949 and grasping objects, as objects can sometimes cause pain. Such learned functional correlations  
950 could be less pronounced on hairy skin, which is typically not used when we explore objects.

951

### 952 **Dynamic thermal matching task**

953 The results from the thermal matching task reveal interesting differences between hairy and  
954 non-hairy skin that suggest greater thermal sensitivity in the former skin type for relatively  
955 weak cold and warm stimuli. We argue that this could reflect greater innervation of  
956 thermoreceptors on the forearm and perhaps the engagement of CT afferents. Ackerley et al.  
957 (2014) investigated the CT responses to light tactile stimuli delivered at different speeds and  
958 temperatures; the study showed that the maximum firing rate of the CT afferents from which  
959 they were recording using microneurography was found for mechanothermal stimuli delivered  
960 in the range of velocities between 1–10 cm/s and at neutral temperature (32°C, typical of human  
961 skin; Arens & Zhang, 2006). Moreover, the characteristic significant correlation between  
962 pleasantness ratings and CT discharge rates across velocities was found only for thermoneutral  
963 stimuli. Thus, we think that it is possible that CT signals may have contributed to the  
964 performance on the thermal matching task by providing additional information about how the  
965 stimulation felt in terms of affective sensations. Alternatively, the subjects may have ignored  
966 the possible changes in pleasantness and focused only on the thermal sensations. If this is the  
967 case, the CT contribution to performance on the thermal matching task would be neglectable,  
968 and the task would only probe thermosensation. Future studies could explicitly test this by  
969 varying stroking velocities (CT-optimal and CT-non-optimal velocities), testing temperature  
970 matching within and outside CT-optimal temperatures, and asking participants to match  
971 temperatures, pleasantness, or the ‘overall feeling’.

972

973 During affective touch in natural situations, the combination of the thermoneutral experiences  
974 in the thermal comfort zone are combined with tactile pleasantness into an overall experience  
975 of social touch. In interoceptive terms, we speculate that the CT system might thus contribute  
976 to how the skin affectively ‘feels’ during social touch. However, the fact that we did not find a  
977 relationship between performance on the thermal matching task and the affective touch task is  
978 in line with thermosensation and affective touch being relatively independent submodalities  
979 and recent evidence suggesting that affective touch pathways outside the spinothalamic

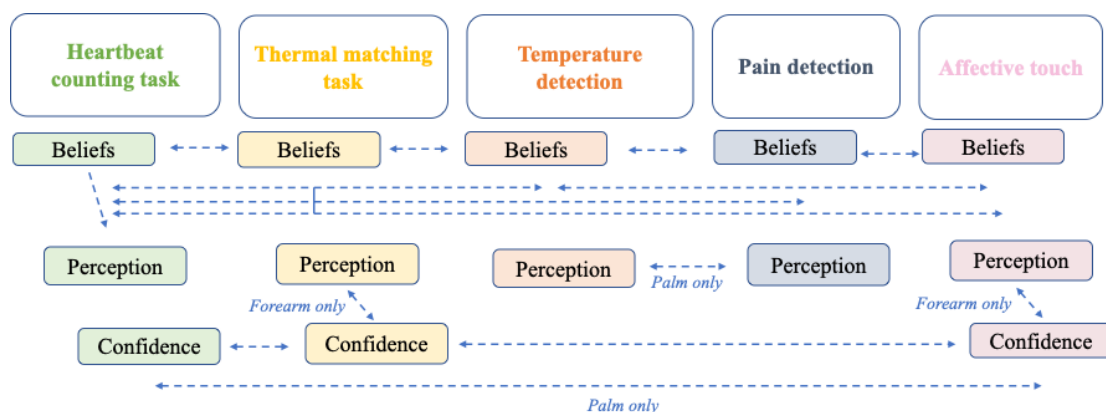
980 pathway signalling pain and temperature may contribute to tactile pleasantness (Marshall et al.,  
 981 2019). Although the results from the dynamic matching task are by no means conclusive with  
 982 respect to the possible involvement of CT signals in the task, they suggest that greater attention  
 983 should be given to potential interactions between thermal experiences and affective touch  
 984 during social physical interactions in future studies.

985

986 **Interoceptive ability across metacognitive dimensions**

987 In terms of the metacognitive dimension, our results highlight a general relationship between  
 988 prior beliefs in performance across tasks (as in Beck et al., 2019). That is, people who had  
 989 higher beliefs in their upcoming performance on the heartbeat counting task or thermal  
 990 matching task also had higher beliefs of performance on the affective touch and pain detection  
 991 task. This might reflect the fact that this metacognitive dimension of interoception is related to  
 992 domain general cognitive abilities and therefore is mainly driven by top-down beliefs that are  
 993 relatively independent from the perceptual processes in the tasks. Similarly, the confidence  
 994 ratings of performance obtained after the heartbeat counting task, the affective touch task, and  
 995 the thermal matching tasks were correlated across modalities (note that such ratings were not  
 996 obtained for the change detection tasks for reasons described in the methods). This suggests  
 997 that the ability to judge task performance, presumably by recalling subjective awareness and  
 998 response decisions (matching, counting, and rating pleasantness), is a generalised ability. Taken  
 999 together, our results show a striking difference between metacognitive and perceptual levels of  
 1000 interoception in that only the former show evidence of significant and systematic correlations  
 1001 across submodalities (see Figure 7).

1002



1003

1004 **Figure 7.** Overview of the findings across modalities. The dashed line indicates a significant correlation.

1005

1006 With respect to the question of how the metacognitive measures were related to perceptual  
1007 accuracy, we found that higher confidence was related to better performance on both the  
1008 thermal matching task and the affective touch task in hairy skin (forearm) only, in keeping with  
1009 recent findings arguing that such ‘metacognitive sensitivity’ is higher in hairy skin than in non-  
1010 hairy skin (von Mohr, Kirsch, Loh & Fotopoulou, 2019). This evidence might suggest that we  
1011 are more precise in or aware of our ability to detect such stimuli on hairy skin (Morrison, 2016;  
1012 Filingeri, Zhang & Arens, 2018) and provide yet another example of differences between hairy  
1013 and non-hairy skin that is relevant to the current data. The reason for this is not clear, but we  
1014 speculate that it may be related to affiliative and thermoregulatory processes being more closely  
1015 linked to hairy skin. The belief ratings regarding task performance on the heartbeat counting  
1016 task significantly correlated with accuracy on the heartbeat counting task (Supplementary  
1017 Material); however, this was the only significant correlation we found between beliefs and  
1018 accuracy measures, so overall, the connection between this metacognitive ability and task  
1019 performance was rather poor.

1020

1021 In terms of *interoceptive sensibility*, we used both the Body Awareness Questionnaire (Shields,  
1022 Mallory & Simon, 1989) and the Body Perception Questionnaire (Porges, 1993), which are two  
1023 commonly used scales. In line with these questionnaires probing metacognitive levels of  
1024 interoception, no significant correlations with accuracy measures were found for the Body  
1025 Awareness Questionnaire scores (Table 2 in Supplementary Materials), and the Body  
1026 Perception Questionnaire scores were correlated only with the affective touch task on the palm  
1027 (see Table 3 in Supplementary Materials).

1028

1029 In contrast, these scales correlated with the confidence ratings for several tasks, but this was  
1030 more apparent with the Body Awareness Questionnaire, in that scores on this scale were  
1031 positively correlated with this metacognitive dimension for cardiac interoception, the thermal  
1032 matching task (both palm and forearm) and the affective touch task on the palm. In contrast,  
1033 Body Perception Questionnaire scores were positively correlated with confidence only for the  
1034 affective touch task on the palm and forearm. Scores on both questionnaires showed little  
1035 relationship with the belief ratings in task performance; scores on the Body Perception  
1036 Questionnaire were correlated only with beliefs in pain detection only, and scores on the Body  
1037 Awareness Questionnaire were correlated only with beliefs in temperature detection.

1038

1039 Nevertheless, these observations are reasonably well in line with previous claims that  
1040 questionnaires mainly capture aspects of interoception at metacognitive levels (see Garfinkel  
1041 et al., 2015; Fairclough & Goodwin, 2007; Schulz et al., 2013 for similar approaches). Here,  
1042 we extend this observation to the current battery of five tasks, including multiple skin-based  
1043 submodalities and the observation that the most convincing relationships seem to be found  
1044 between scores on the Body Awareness Questionnaire and confidence ratings rather than belief  
1045 ratings. Since confidence ratings relate to memory and awareness of task performance, we  
1046 speculate that this may indicate that the questionnaires tap into such mnemonic and attentional  
1047 processes in everyday experiences of interoceptive cues.

1048  
1049 We believe that in future studies, it could be valuable to also include the standardised  
1050 Multidimensional Assessment of Interoceptive Awareness scale (Mehling, Price, Daubenmier,  
1051 Acree, Bartmess & Stewart, 2012), which is organised into eight separate subscales (e.g.,  
1052 emotional awareness, body listening, and self-regulation) and could potentially target different  
1053 facets of self-reported interoception and their possible relationships with interoceptive accuracy  
1054 and metacognitive awareness. Another valuable alternative is the recently developed  
1055 Interoceptive Accuracy Scale (IAS, Murphy et al., 2020), which aims to distinguish the  
1056 attention component from the accuracy component in interoceptive self-report measures.

1057  
1058 Even though we did not find significant relationships between the questionnaires and the  
1059 interoceptive accuracy measures in the present study, this does not mean that the former does  
1060 not provide important information or should not be used in future studies. For instance,  
1061 interoceptive sensibility has proven to be clinically relevant since some individuals have shown  
1062 a dissociation between their self-report abilities to experience their body's physiological and  
1063 inner status and actual performance, such as in individuals with autism spectrum disorder,  
1064 individuals with high levels of anxiety (e.g., Garfinkel et al., 2016) and individuals with an  
1065 eating disorder (Pollatos & Georgiou, 2016; Eshkevari et al., 2014).

1066  
1067 **Limitations and future directions**

1068 One limitation with the dynamic thermal matching task is that the thermosensory stimuli are  
1069 presented during mechanical stimulation of the skin by a moving object. This was a deliberate  
1070 design choice as outlined in the introduction, but it also means that this task involves both  
1071 thermal and exteroceptive stimulation on the skin. Future studies could attempt to investigate  
1072 the interoceptive nature of thermosensation by completely eliminating tactile inputs during the

1073 task (e.g., Ackerley et al., 2018). For example, stimulating thermoreceptors by means of heat  
1074 lamps or lasers can allow us to deliver contactless thermal stimulation. Another approach can  
1075 be to explicitly formulate the perceptual judgements about the interoceptive dimension of  
1076 thermosensation, such as asking participants to report “which limb feels warmer/colder” or  
1077 match thermal comfort or discomfort sensations. Nevertheless, all thermosensory stimuli have  
1078 an intrinsic interoceptive dimension, we argue, given the dual nature of thermosensation as both  
1079 exteroception and interoception and the fact that thermal signals are processed in the  
1080 spinothalamic pathway and reach the posterior insula regardless of the nature of the  
1081 psychological task.

1082  
1083 Future studies should also focus on validating the thermal matching task by exploring more  
1084 body sites, adding more trials, and investigating the test-retest reliability of the task. It would  
1085 also be interesting to explore the relationship between the thermal matching and detection tasks  
1086 and cold pain sensitivity, since here we investigated only heat pain. We did not continuously  
1087 record the skin temperature during the current tasks but only at the beginning, so we could not  
1088 explore possible dynamic interactions between skin temperature and task performance.  
1089 However, our skin temperature data showed no significant variations between skin sites or  
1090 across participants at baseline, so we do not think that this factor played a significant role in the  
1091 current experiments (also the thermal stimulation was mild and brief and unlikely to cause  
1092 significant changes in skin temperature). Finally, with the current battery of tests, we decided  
1093 to present the experimental tasks in a fixed order for reasons explained in the methods section.  
1094 As tasks were not counterbalanced, we cannot exclude order effects. However, since accuracy  
1095 measures are well protected against cognitive bias, we did not observe significant correlations  
1096 between accuracy measures across the individual tasks, and our individual task performance is  
1097 well in line with previous studies that have tested these tasks in isolation or in different  
1098 experimental contexts, we do not think this was a significant issue in the current study.

1099

## 1100 **Conclusions**

1101 Taken together, our results suggest that it is possible to broaden the testable interoceptive  
1102 modalities beyond cardiac signals to include skin-based interoceptive submodalities, including  
1103 temperature perception. Our findings from the thermal matching task and the temperature  
1104 detection task suggest that more attention should be given to differences between hairy and  
1105 non-hairy skin because the former is likely to play a more important role in thermoregulation  
1106 and interoceptive dimensions of thermosensation, as we have argued. The lack of significant

1107 relationships between performance on interoceptive tasks across all modalities and skin types  
1108 tested (i.e., cardiac accuracy, affective touch, temperature, and pain detection; palm and  
1109 forearm; with the only exception being cold and pain detection in the palm) supports the idea  
1110 that interoception might be better conceptualised as a modular construct with relatively  
1111 independent processing in parallel streams. Thus, just as in the case of exteroception, distinct  
1112 interoceptive submodalities might not necessarily be related to one another, and the capacity to  
1113 perceive different kinds of interoceptive signals may vary within an individual. Consequently,  
1114 future basic and clinical studies could benefit from using batteries of interoceptive tests that  
1115 comprise multiple interoceptive modalities, which can collectively provide a complete  
1116 understanding of interoception in health and disease.

1117

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1124

### 1125 **Conflict of interest**

1126 The authors declare that the research was conducted in the absence of any commercial or  
1127 financial relationship that could be construed as potential conflicts of interest.

1140

### 1141 **Authors contribution**

1142 Conceptualisation: LC, HHE; Data curation: LC, AE; Formal analysis: LC; Funding  
1143 acquisition: HHE, LC; Investigation: LC, AE; Methodology: LC, HHE; Project administration:  
1144 LC, HHE; Resources: HHE; Visualisation: LC, AE; Writing – original draft: LC; Writing –  
1145 review & editing: LC, AE, HHE

1146

### 1147 **Data availability statement**

1148 **Data of this study are available as a supplementary file.**

1149



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