POLITECNICO DI TORINO Repository ISTITUZIONALE

Editorial: Smart dust: Micro and nano scale devices for highly-integrated localized and distributed smart systems for precision and personalized medicine

Original Editorial: Smart dust: Micro and nano scale devices for highly-integrated localized and distributed smart systems for precision and personalized medicine / Motto Ros, Paolo; Demarchi, Danilo; Carrara, Sandro In: FRONTIERS IN NEUROROBOTICS ISSN 1662-5218 16:(2022). [10.3389/fnbot.2022.1051124]
Availability: This version is available at: 11583/2972185 since: 2022-10-10T11:39:10Z
Publisher: Frontiers
Published DOI:10.3389/fnbot.2022.1051124
Terms of use: openAccess
This article is made available under terms and conditions as specified in the corresponding bibliographic description in the repository
Publisher copyright

(Article begins on next page)

Editorial "Smart Dust: Micro and Nano Scale Devices for Highly-Integrated Localized and Distributed Smart Systems for Precision and Personalized Medicine"

Paolo Motto Ros 1,* , Danilo Demarchi 1 and Sandro Carrara 2

- 1 Department of Electronics and Telecommunications, Politecnico di Torino, Turin, Italv
- ² Integrated Circuits Laboratory, École Polytechnique Fédérale de Lausanne, Neuchâtel, Switzerland

Correspondence*: Paolo Motto Ros paolo.mottoros@polito.it

- Wearable and implantable devices are nowadays a well established research field, with application and
- devices out of the medicine field too, possibly part of our daily routines. From a historic perspective,
- the paved way is clear: from an overall macro monitoring and diagnostic approach, where only the
- 5 effects of underlying processes are captured as a whole or indirectly, to a micro one, where biological
- 6 and chemical processes are individually locally monitored (and eventually controlled). To this end, new
- 7 bioelectronic devices (biochips) are needed: even if the idea of shrinking down to dust-sized devices has
- been conceived more than 20 years ago, the first real device was demonstrated in the body of a mammalian
- 9 six years ago only, and many challenges are still there. It is not only a matter of simply reducing size,
- 10 performances, figures-of-merit of (some) orders of magnitude while relying on already well-established
- designs and solutions, but new co-design paradigms, architectures, electronic circuits, bio-CMOS interfaces, 11
- 12 nanosensors, have to be investigated and developed. However, designing, developing, and fabricating
- 13 Smart Dust devices are just the first steps for effectively enabling a precision and personalized medicine
- at the micro and nano scale. In these initial (from an application perspective) steps, major focus and
- challenges are at the architectural/system/integration level of sensor/stimulation interfaces and circuits, 15 16
- communication and networking approaches, energy provisioning and management strategies. Broadly
- speaking, the emphasis is mostly in maximizing the efficiency, effectiveness, and reliability of the designed 17
- solution into achieving the specific goal, with a "device-centered" perspective (and often in a short-term 18
- timescale) (Carrara, 2021; Motto Ros et al., 2017; Barbruni et al., 2020).

30

31

32

33

34

35

Next steps in the development of Smart Dust applications should extend such perspective and take into consideration the impact on, and the interaction with, the surrounding (in-vitro, ex-vivo, in-vivo) biological environment (broadly speaking) of the micro and nano scale devices. With the papers published in this research topic we want to report some steps towards this direction.

In the paper "Magnetically Guided Catheters, Micro-and Nanorobots for Spinal Cord Stimulation" (Torlakcik et al., 2021) opportunities and challenges of magnetic navigation systems for steering the tethered devices are investigated in the context of Spinal Cord Stimulation (SCS). Starting from the current techniques in SCS lead placement and seeing magnetically controlled probes as precursors of untethered magnetic devices, the analysis is directed towards how small-scale devices could overcome complications and limitations, thus opening the way to improved (or new) standards of practice.

Magnetic control of micro-robots is the topic of the paper "Study on Magnetic Control Systems of Micro-Robots" (Shao et al., 2021) as well, but here the focus is on remote control systems of micro-robots in a 3D space with up to 8 degrees-of-freedom at a millimetric level. Pioneering works in this field are critically reviewed and categorized, in particular highlighting theoretical and practical pros and cons of stationary electromagnet, permanent magnet, and mobile electromagnet control systems. Finally, a new system is proposed and further challenges to be addressed in future works are outlined.

36 The paper "Tracking the Migration of Injectable Microdevices in the Rodent Brain Using a 9.4 T Magnetic Resonance Imaging Scanner" (Khalifa et al., 2021) then moves a step forward in understanding the long-37 term behavior of implanted micro-devices by assessing their spatial stability under chronic conditions. 38 The devices were precisely injected in six different rodent brain regions. Their position was accurately 39 verified (although with some limitations) and monitored for up to 17 weeks. Histological analysis was 40 then carried out to investigate the immunoreactivity around the micro-devices to better understand the 41 anchoring/migration process. Even if the scar formation could negatively impact on the interface between 42 the micro-device and the surrounding neural system, results show that only minimal drift occurred, thereby 43 effectively opening the way for Smart Dust applications locally operating in the long-term. 44

With the same perspective, the paper "Integrated Micro-Devices for a Lab-in-Organoid Technology 45 Platform: Current Status and Future Perspectives" (Angotzi et al., 2022) aims at assessing the impact 46 of an active silicon micro-device (fully working and targeting chronic recordings of neural activity) on 47 the surrounding neural systems in a Lab-in-Organoid (LIO) context. Major challenges are power-related 48 aspects; here concerns are focused on the biological effects of an inductive wireless power transfer as well. 49 The fully-integrated CMOS design, fabrication, and characterization is discussed and then the impact of 50 sinusoidal RF electromagnetic fields (2–6 GHz, used to power and communicate with the micro-device) is 51 evaluated by means of immunofluorescence and MTT assay. Results show the feasibility and reliability of 52 using specific time windows for wirelessly power and reading out data about the biological activity of the 53 brain organoids, without (very likely) influencing the cellular viability; they overall confirm the feasibility 54 of the proposed solution, both from an electronic engineering and a biological perspective, making it a 55 significant step forward in the development of full Smart Dust applications.

REFERENCES

Angotzi, G. N., Giantomasi, L., Ribeiro, J. F., Crepaldi, M., Vincenzi, M., Zito, D., et al. (2022). Integrated
 micro-devices for a lab-in-organoid technology platform: Current status and future perspectives. *Frontiers* in Neuroscience 16. doi:10.3389/fnins.2022.842265

Frontiers 2

- 60 Barbruni, G. L., Motto Ros, P., Demarchi, D., Carrara, S., and Ghezzi, D. (2020). Miniaturised wireless
- power transfer systems for neurostimulation: A review. *IEEE Transactions on Biomedical Circuits and*
- 62 Systems 14, 1160–1178. doi:10.1109/TBCAS.2020.3038599
- 63 Carrara, S. (2021). Body dust: Well beyond wearable and implantable sensors. *IEEE Sensors Journal* 21,
- 64 12398–12406. doi:10.1109/JSEN.2020.3029432
- 65 Khalifa, A., Weigand-Whittier, J., Farrar, C. T., and Cash, S. (2021). Tracking the migration of injectable
- 66 microdevices in the rodent brain using a 9.4 T magnetic resonance imaging scanner. Frontiers in
- 67 *Neuroscience* 15. doi:10.3389/fnins.2021.738589
- 68 Motto Ros, P., Miccoli, B., Sanginario, A., and Demarchi, D. (2017). Low-power architecture for
- 69 integrated CMOS bio-sensing. In 2017 IEEE Biomedical Circuits and Systems Conference (BioCAS).
- 70 1–4. doi:10.1109/BIOCAS.2017.8325218
- 71 Shao, Y., Fahmy, A., Li, M., Li, C., Zhao, W., and Sienz, J. (2021). Study on magnetic control systems of
- micro-robots. Frontiers in Neuroscience 15. doi:10.3389/fnins.2021.736730
- 73 Torlakcik, H., Sarica, C., Bayer, P., Yamamoto, K., Iorio-Morin, C., Hodaie, M., et al. (2021). Magnetically
- quided catheters, micro-and nanorobots for spinal cord stimulation. Frontiers in Neurorobotics 15.
- 75 doi:10.3389/fnbot.2021.749024

Frontiers 3