## EXTREMITIES

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The undersigned, appointed by the dean of the Graduate School, have examined the thesis entitled

## Methods for Improved Kinematic Measurements of the Lower Extremities

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a candidate for the degree of Master of Science,
and hereby certify that, in their opinion, it is worthy of acceptance.

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## DEDICATION

I am dedicating this thesis to my family and close friends. A special thank you to my loving mother who has always supported me no matter what path I choose. My aunts and uncles - Ed, Darla, Les, Linda, Doris, and Fred - also consistently offered their support and words of wisdom. I would also like to dedicate this work to the memory of my grandmother who encouraged curiosity and a love of learning early on and to my Aunt Marion who left behind a love of music and the fine arts.

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## List of Abbreviations

| ACL | Anterior Cruciate Ligament |
| :--- | :--- |
| ACLd | Anterior Cruciate Ligament deficient |
| IRB | Institutional Review Board |
| LSD | Lateral Step Down |
| MKATS | Mizzou Knee Arthrometer Testing System |
| PFP | Satellofemoral Pain |
| SLS | Step Up and Over |
| SUO |  |

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#### Abstract

An understanding of knee dynamics is vital to treat neurological and musculoskeletal conditions that affect the lower extremities and achieve peak performance from athletes. To obtain and analyze kinematics and kinetics of the knee, clinicians and athletic trainers require accurate, accessible measurement devices. To assess the functionality of one such device, the Mizzou Knee Arthrometer Testing System (MKATS), dynamic motion studies were carried out on healthy, ACL deficient, and patellofemoral pain populations. To assess the validity of the MKATS, the device output was compared to data collected using a SimVitro robotic manipulator. Through this process, discussions with clinicians, technicians, and participants resulted in modifications to both the software and hardware of the device to improve fit and usability. The following thesis summarizes the findings of the dynamic and cadaver motion studies, and the modifications to the device.

We found decreased flexion and internal rotation at specific points $(\mathrm{p}<0.05)$ of the cycle for all dynamic activities for both clinical groups compared to the healthy control group. Due to unperceived amounts of skin artifact and joint laxity, the results of the cadaver study were inconclusive. The MKATS was able to accurately detect kinematic differences in the live study groups and has promise as a useful tool for orthopedic surgeons, physical therapists, and athletic trainers to screen for abnormal dynamics and track treatment success. Further studies utilizing computed tomography on live participants will be needed to further validate the MKATS. The development of such devices is crucial to improve the quality of advice from healthcare and athletic performance specialists.


## 1. Introduction

### 1.1 Motivation

There is a strong link between athletic performance and biomechanics. Biomechanics gives us great insight into the development of power in a golf swing ${ }^{14,51}$, the intricate combination of muscle activations in a violinist's shift ${ }^{64}$, and the loading conditions during an anterior cruciate ligament (ACL) rupture in a soccer player ${ }^{44,45}$. Looking at a combination of kinetics and kinematics provides a scientific basis and justification for the development of training, teaching, and treatment methods for athletes, musicians, and those undergoing rehabilitation therapies ${ }^{37}$. The reasoning behind holding your instrument or golf club a certain way goes beyond historical practices and can be justified by minimal loading at a specific joint or lower activation in a particular muscle group ${ }^{9}$. Understanding the connection between human motion and performance is vital to developing techniques and equipment to minimize injuries and maximize execution ${ }^{37}$.

Injuries are extremely common in string players ${ }^{48}$ and athletes ${ }^{14,50,57}$. The study of knee dynamics is particularly relevant for sports and activities that involve cutting maneuvers and power development such as soccer or basketball as individuals are at increased risks of injury ${ }^{32,50}$. Understanding how healthy knees move can help coaches train to maintain good kinematics and clinicians work to bring injured knees back to that state ${ }^{50}$. However, effective collection of such data may be limited by the scope of current devices. A known connection between motion and performance provides a solid basis of theory for increasing performance but is only applicable in generalized terms. The development of technology to increase accessibility to dynamic kinematic data promises to improve individualized training and treatment.

### 1.2 Background

There is a high prevalence of musculoskeletal disorders affecting the knee such as patellofemoral pain ${ }^{57}$ and ACL injury ${ }^{30,49}$. These disorders are often characterized by differences in stability and altered knee biomechanics ${ }^{1,5,45,46}$. For patients with ACL injuries, decreased stability is evident in altered internal-external rotation angles ${ }^{4}$. The defining features for patients with PFP are altered biomechanics, a compensation developed over time in order to avoid pain elicited during activities that activate the quadriceps ${ }^{2,66}$. Collection and analysis of knee rotation angles about the 3 primary axes (flexion/extension, internal/external rotation, and abduction/adduction rotation) can provide clinicians insight into underlying conditions of the knee ${ }^{45,58}$. In order to analyze and compare data collected from various methods, it is important to use a standard coordinate system to describe knee motion ${ }^{21,27}$.

The coordinate system described by Grood and Suntay in 1983 continues to be one of the most popular coordinate systems in use to describe knee motion ${ }^{27,33}$. This system is comprised of two fixed body axes and one "floating" axis. The first axis is fixed to the femur and describes flexion and extension while the second is fixed to the tibia and describes internal and external rotation. The third non-fixed axis is perpendicular to the other two axes and describes varus and valgus rotation (also known as abduction/adduction rotation) ${ }^{21,27}$. These axes are summarized in Figure 1.


Figure 1. Directions of the rotations and translations according to Grood and Suntay's coordinate system definition of the knee ${ }^{2 l}$. The flexion-extension axis is fixed to the femur and the internalexternal axis is fixed to the tibia. The varus-valgus (or abduction-adduction axis) is perpendicular to the other axes.

Existing methods to measure knee rotation include forms of 3D motion software such as Vicon Nexus. Physical retroreflective markers are placed on the skin on specific landmarks ${ }^{1}$.

Sets of markers are used to define anatomic rigid bony bodies for dynamic analysis. For knee biomechanics, a functional model including Symmetrical Axis of Rotation Analysis (SARA) and Symmetrical Center of Rotation Estimation (SCoRE) methods is often used to define the axes described above ${ }^{27,33}$. For both methods, the optimal common shape technique is applied to each
segment (i.e. femur, tibia, and pelvis) to obtain rigid bodies based on the skin markers ${ }^{33}$. The SCoRE method then uses an optimization algorithm to estimate the hip joint center while the SARA method uses a different optimization algorithm to estimate the knee joint center ${ }^{33}$. When paired with force plates, these data collection methods have proven to be extremely robust and provide a large body of information including forces, moments, power, and joint angles ${ }^{18,33}$. While these systems are effective, they can cost upwards of $\$ 200,000$ and cannot be transported requiring patients to enter a laboratory setting to be evaluated. Due to skin artifact, the accuracy of non-sagittal knee motion is also prone to error ${ }^{7}$. Special training on the software to collect, process, and interpret data is another roadblock to ease of use by clinicians and often such extensive data is not necessary for clinical diagnoses.

One method to reduce skin artifact is the use of bone pins ${ }^{6}$. Often these are used in conjunction with a motion capture software and similar methods to the SCoRE and SARA methods. However, the invasive nature of the pins exposes patients to additional risks and discomfort ${ }^{6}$.

Dual fluoroscopy is another expensive, but robust method to analyze knee motion ${ }^{39,61,62}$. The method consists of taking x-rays in real time in 2 different planes as the participant goes through functional tasks ${ }^{62}$. 3D models of the knee obtained from MRI or CT scans can then be fit to the biplanar x-ray images and used to calculate the kinematics of the knee ${ }^{39,61,62}$. As the images are directly of the bones, there is little motion artifact such as that which may be present in 3D motion analysis with surface retroreflective markers ${ }^{39}$. However, this method is limited by portability and the expertise needed to process such data ${ }^{62}$. Additionally, although low dosage, radiation exposure can be a risk for patients and operating staff ${ }^{60}$.

There are various knee arthrometers such as the KT-2000 and the Genourob ${ }^{35}$. However, these devices are not suitable for dynamic measurements due to their rigid, bulky nature and limit which tests can be used ${ }^{34,56}$. Many of these devices only measure static anterior displacement and were found to have a level of subjectivity depending on the user ${ }^{56}$. While significantly less expensive than dual fluoroscopy or other motion capture methods, these arthrometers are not effective in dynamic settings such as athletic activities and other daily functional tasks ${ }^{34}$. In addition, many of these products have been discontinued by their manufacturers and as such are difficult to obtain ${ }^{34}$.

| Method | Description | Limits | Advantages | Citations |
| :---: | :---: | :---: | :---: | :---: |
| Marker based motion capture | Retroreflective markers are placed, data is collected, processed, and interpreted using various algorithms. | - Expensive (\$200,000+) <br> - Extensive training required <br> - Skin artifact <br> - Not portable | - Triplanar motion - Analysis of multiple joints <br> - Can include kinetic analysis | 1,7,18,27,33 |
| Dual fluoroscopy | Biplanar x-ray images are fit to 3D geometries obtained with MRI or CT scans | - Expensive <br> - Exposure to radiation <br> - Time consuming - Tasks limited by capture space <br> - Not portable | - High accuracy with minimal motion artifact - Triplanar motion | 39,61,62 |
| Arthrometers | Patients are guided to a position, the arthrometer is strapped in place, and a force is applied | - Typically static measurements - Single plane motion <br> - Discontinued products | - Price <br> - Portability | 34,35,56 |
| MKATS | Device is fitted to the patients knee and calibrated before collecting | - Only knee kinematics are measured (no other joints) - Software development | - Price <br> - Portability <br> - Triplanar motion | 23,24 |


|  | dynamic motion <br> data |  |  |
| :--- | :--- | :--- | :--- |

Table 1. Summary of current methods to measure knee motion with limits and advantages. While the MKATS is limited to measurements of tibiofemoral motion, it is cheaper and more portable which is important in a clinical setting.

The MKATS is a novel design of a knee arthrometer. It consists of a femur clamp and a tibia clamp which can be easily placed by a clinician during a data collection session. Each clamp has an electromagnetic sensor that detects the clamps' positions relative to each other. A visualization of the two sensors can be seen in Figure 2. These sensors use the Polhemus Patriot motion tracking system to collect raw data on the relative positions. Custom algorithms are then applied to the raw data to calculate joint angles in the three primary knee axes as described above. This gives a cheaper, more portable alternative to other knee kinematic measurement methods by providing real time data. Unlike methods such as dual fluoroscopy and instrumented marker-based motion analysis, the MKATS does not require other anatomical features (i.e. femoral head anatomy) to calculate rotation angles.


Figure 2. (a) Model of the Mizzou Knee Arthrometer Testing System (MKATS). The upper clamp is positioned across the femoral condyles while the lower clamp is positioned along the anterior tibial crest beneath the tibial tuberosity. (b) Prototyped device on a research participant. The main clamps are 3D printed with the associated electromagnetic sensors attached. Both clamps are secured with straps.

The MKATS was designed for use by clinicians such as physical therapists, orthopedic surgeons, and athletic trainers who evaluate and treat conditions of the knee. Joint angles collected during weight bearing functional activities may have the following clinical applications: diagnosis of ligament injuries, diagnosis of iliotibial band syndrome, diagnosis of osteoarthritis, screening for ACL injury risk, screening for return to sports, screening for patellofemoral pain, and screening for osteoarthritis. A small market analysis has been performed to identify appropriate testing procedures, but there will likely be a more thorough one required prior to putting the product on the market in order to comply with the Food and Drug Administration (FDA) and other regulatory agencies.

Functional tasks frequently used in the evaluation of common knee conditions such as PFP and ACL injuries were compared to identify an appropriate testing procedure for objective 1. Such tasks look to identify knee instability and determine if individuals are prepared to return to sports ${ }^{20,66}$. In looking at how the knee is loaded during functional tasks for the diagnosis and screening of these ailments, a comprehensive list can be made. This list includes standard tests such as single leg squats ${ }^{2}$, dual limb squats ${ }^{2}$, y balance tests ${ }^{4}$, single leg hop tests ${ }^{20,29,54}$, triple hop tests ${ }^{54}$, crossover hop tests ${ }^{20,38}$, step up tasks ${ }^{2,52,53}$, lateral step downs ${ }^{2,52,53}$, and drop cut jumps ${ }^{20}$. Currently evaluation with these tasks primarily relies on limited information such as the patient's subjectively reported pain or the clinician's visual assessment during the activity ${ }^{32,66}$. As such, objective kinematics could be greatly beneficial to clinicians evaluating knee function. Due to the relationship between internal knee loads and joint stability, the use of dynamic tasks with internal loading are effective methods for diagnosis ${ }^{28,35}$.

### 1.3 Objectives and Aims

We hypothesized that the Mizzou Knee Arthrometer Testing System (MKATS) will prove to be an effective, noninvasive method to measure joint angles during functional activities. The primary objective of this study was to validate and assess the functionality of the MKATS so that it may be used by clinicians. This was achieved through a series of functional tests and comparisons to existing data sets and methods. The two primary objectives were to show that the MKATS is functional and to validate it with other existing methods. Additional objectives were to increase the modularity of the data collection software and assess the marketability of the device.

Objective I: Assess functionality

Demonstrate that the MKATS can adequately collect reasonable knee rotation data for the three primary axes for a series of functional tasks in a clinical setting. These three axes describe flexion/extension, internal/external rotation, and abduction/adduction rotation. To assess functionality of the MKATS, the following aims were met:
(1) Development of an appropriate testing protocol that covers a range of functional motion about the knee.
(2) Collection and analysis of control participant data to act as a baseline.
(3) Collection and analysis of clinical patient data from populations with patellofemoral pain and ACL deficiencies.

## Objective II: Validation

Show that data collected from the MKATS is reliable and clinically relevant to assess musculoskeletal disorders and abnormal motion of the knee joint. This included comparing data to that collected from other existing standard methods with known validation. For this objective, the following aims were met:
(1) Simultaneous data collection on cadaver specimens with both SimVitro and MKATS systems.
(2) Simultaneous data collection with CT scans and the MKATS.

## Objective III: Modularity

The primary program used to collect data for the MKATS uses a custom C\# code that interfaces with the Unity Game Engine. It is limited by being unidirectional with fixed data collection times. Additionally, the program holds each sample for two data collection points thus
decreasing the frequency of recorded values. To increase modularity of the user interface and fidelity of the data stream, the following was done:
(1) Development of a new code to collect data with adjustable collection times. Users will be able to input file names and data collection time.

Objective IV: Explore marketability

Interact with clinicians and potential future users of the MKATS to explore customer segments and determine a value proposition model.
(1) This was done in part with the regional NSF Innovation Corps program through interviewing potential customer segments including physical therapists and athletic trainers specializing in orthopedic practice.
(2) A multidisciplinary team participated in training sessions and summarized the findings in a value proposition format to be presented and critiqued by other groups.

## 3. Methods

3.1 Live Participant Trials

### 3.1.1 Participants

University Institutional Review Board approved this study design. Three groups of participants were recruited - healthy control, ACL deficient (ACLd), and those with PFP. Inclusion criteria for the control group included above 18 years of age with no history of ACL injury or patellofemoral pain. Inclusion criteria for the ACL group included above 18 years of age with a known ACL deficiency. Inclusion for the PFP group similarly included known diagnosis of PFP. Exclusion criteria included incarceration, incapable of making medical
decisions, and pregnancy. Participants were asked about exclusion criteria prior to taking part in the study and provided written consent.

### 3.1.2 Device

Electromagnetic motion sensors were used to collect tibiofemoral motion data (Polhemus Patriot System; Polhemus, Colchester, VT). Sensors were secured to custom nylon fixtures on the bony surfaces of the distal femur and proximal tibia. The femoral fixture was compression clamped to the medial and lateral epicondyles and further secured with elastic strapping. The tibial unit was fixated to the anterior tibial crest immediately inferior to the tuberosity and secured with elastic strapping (see Figure 2. (a) Model of the Mizzou Knee Arthrometer Testing System (MKATS). The upper clamp is positioned across the femoral condyles while the lower clamp is positioned along the anterior tibial crest beneath the tibial tuberosity. (b) Prototyped device on a research participant. The main clamps are 3D printed with the associated electromagnetic sensors attached. Both clamps are secured with straps.). By targeting these bony landmarks, skin and motion artifact concerns were minimized. A custom Unity code was used to interface with the Patriot and convert the raw orthogonal data into anatomically relevant joint angles consistent with the Grood and Suntay model ${ }^{21}$. Two coordinate axes are from the local coordinate systems of the tibial and femoral segments while the third axis is a cross product of those axes. The femoral epicondyles define the axis of flexion, and the long axis of the tibia defines the axis of internal rotation. The cross product of these axes defines abduction-adduction rotation.

### 3.1.3 Data Collection

All participant groups were asked to perform dynamic tasks after being fitted with the clamps during a single data collection. The clamps were placed by those trained to palpate the previously described bony landmarks. ACL deficient and PFP participants only performed tasks on the affected limb while control participants performed tasks bilaterally. Prior to testing, ACL deficiency or diagnosis of PFP and ability to perform tasks was confirmed by an orthopedic surgeon for the clinical groups. Participants first performed range of motion and static tasks followed by a minimum of three trials each of step up and over, posteromedial Y-balance, posterolateral Y-balance, lateral step-down, medial single leg squat, and lateral single leg squat tasks. Table 1 summarizes the tasks with a brief description of each.

| Task Name | Description | Specific Equipment/Setup |
| :--- | :--- | :--- |
| Step up and over | The participant steps up and <br> over a box in a continuous <br> motion, pausing between <br> each cycle. | 20 cm height wooden box. |
| Y balance posterolateral | The participant balances on <br> one leg while sliding the <br> other leg behind and across <br> the body along fixed line as <br> marked on the floor. | Three lines on the floor <br> situated at $135^{\circ}, 135^{\circ}$, and <br> $90^{\circ}$. |
| Y balance posteromedial | The participant balances on <br> one leg while sliding the <br> other leg behind and to the <br> side along a fixed line as <br> marked on the floor. | Three lines on the floor <br> situated at $135^{\circ}, 135^{\circ}$, and <br> $90^{\circ}$. |
| Single leg squat turned <br> medially | The participant turns upper <br> body $90^{\circ}$ toward the leg they <br> are squatting on. | The participant will begin on <br> a floor marking and be asked <br> to rotate $90^{\circ}$ toward the wall <br> nearest to the squatting leg. |
| Single let squat turned <br> laterally | The participant turns upper <br> body $90^{\circ}$ away from the leg <br> they are squatting on. | The participant will begin on <br> a floor marking and be asked <br> to rotate $90^{\circ}$ toward the wall <br> farthest from the squatting <br> leg. |


| Lateral step down | The participant will stand <br> atop a box on a single limb <br> with the other limb positioned <br> over the floor. They will then <br> bend the knee of the first limb <br> to gently touch the heel of the <br> other limb to the floor before <br> rising again to the starting <br> position. | 20 cm height wooden box. |
| :--- | :--- | :--- |

Table 2. Summary of dynamic trials and descriptions performed by voluntary participants.

### 3.1.4 Data Analysis

Custom Matlab code (MATLAB R2019b; MathWorks, Inc, Natick, MA) was used to identify cycle start and end points and extract trial cycles (see Figure 3. Flexion-extension angle over time for representative participant during step-up and over task. Three cycles were identified for each trial. Stars represent chosen cycle peaks. Circles represent the start of the cycle and plus signs represent the end of the cycle.). Step up and over cycles were normalized to 151 data points while all other tasks were normalized to 101 data points by fitting to a cubic spline. Ensemble averages of three clean trials for each task were calculated for all participants. Discrete TF motion values and cycle times were compared between left and right control, and bilateral control and clinical group data sets using paired t-tests for each normalized data point. The Wilk-Shapiro test assured normal distribution of the data. Discrete TF values were compared at every normalized data point. Statistical significance was identified as $\mathrm{p}<0.05$ a priori. Values were seen as statistically significant with $\mathrm{p}<0.05$. All calculations were performed in Matlab.


Figure 3. Flexion-extension angle over time for representative participant during step-up and over task. Three cycles were identified for each trial. Stars represent chosen cycle peaks. Circles represent the start of the cycle and plus signs represent the end of the cycle.

### 3.2 Cadaver Trials

### 3.2.1 Specimens

Specimens were obtained with IRB approval. All fresh-frozen specimens were male (60.3 $\pm 8.65$ years, $141 \pm 36.4 \mathrm{lbs}$.) and went from mid-femur to mid-tibia. Flesh was removed from the femur and tibia 15 cm down to prepare the specimens for potting in woods metal. The remaining fibula was removed from the inferior tibia. All ligaments, muscle, tendons, and skin remained over the knee joint.

### 3.2.2 Devices

A simVITRO robotic testing system (Cleveland Clinic, Cleveland, OH) with a KUKA KR300 r2500 Ultra robot (Kuka, Ausburg, Germany) and an Omega 160 IP65 load cell with a SI-1000-120 calibration (ATI Industrial Automation, Apex, North Carolina, US) was used to apply the controlled loads and motions. The potted specimens were loaded into the testing system and the system was calibrated. Each specimen underwent simulation of internal-external rotation, varus-valgus rotation, and flexion-extension rotation. Specimens were also subjected to a simulated pivot shift. This is a common test utilized by clinicians to diagnose rotatory instability related to ACL tears because it simulates the event that occurs during ACL rupture ${ }^{63}$. The knee is flexed from $0^{\circ}$ to $90^{\circ}$ of flexion while applying external rotation stress to the tibia and an abduction stress to the knee ${ }^{3}$.

See section 3.1.2 for a description of the electromagnetic sensors and clamps used collectively as the Mizzou Knee Arthrometer Testing System (MKATS). The MKATS was fitted to the specimen prior to data collection start and cycles of each task were collected simultaneously using the SimVitro and MKATS systems. A custom code was used to record the Patriot system data stream.

### 3.2.3 Data Collection

All specimens were loaded into the robotic manipulator and fitted with the MKATS clamps during a single data collection. The clamps were placed by those trained to palpate the previously described bony landmarks. Data were collected simultaneously from the load cells and MKATS system to be later compared.

### 3.2.4 Data Analysis

No in-depth analysis was performed as cadaver data was not comparable to live participants. Cursory comparison of load cell data from SimVitro and MKATS output was not comparable which led to pursuit of another validation method. MKATS data was collected simultaneously with CT scans for later joint angle comparison.

### 3.3 Software solution

An alternate program was written in C++ using the Polhemus Developer Interface (PDI). It was modified from the sample program that used Microsoft Foundation Classes (MFCs) to record data in metric units and to record quaternions instead of Euler angles. This program was used in the cadaver trials to collect joint angle data and is more modular than the Unity code. The data stream from the Patriot can be collected for a set amount of time in minutes or seconds and is recorded in a .txt file.
4. Results

### 4.1 Dynamic Motion Tests In Vivo

The step-up and over and lateral step-down tasks produced the cleanest data. As such, those data sets were analyzed in greater detail. Some participant data sets had to be excluded on a trial by trial basis due to sliding of the femoral clamp or participant inability to perform certain tasks. Compensation mechanisms for balance on the twisted squats varied greatly among participants. Due to the timing of the Y-balance tasks, most participants only had two posteromedial and two posterolateral trials. For all other tasks, three trials for each task were used in ensemble averages.

### 4.1.1 Participant Demographics

Twenty control participants ( $\mathrm{n}=20,14$ female, $25.6 \pm 4.96$ years), twenty ACL deficient patients ( $n=20,8$ female, $31.3 \pm 10.5$ years), and twenty PFP patients ( $n=20,10$ female, $32.6 \pm$ 10.3 years) were recruited for this study. Within the ACLd group there were 10 right and 10 left ACL deficient knees. The ACLd group had 2 outliers with regards to injury timing. Outliers were identified as any data points 1.5 times below the first quartile or above the third quartile. Demographic statistics were recalculated excluding these outliers. Within the PFP group, there were 14 right and 6 left affected knees.

|  | Control | ACLd | ACLd without <br> outliers | PFP |
| :--- | :--- | :--- | :--- | :--- |
| Gender | 14 female, 6 <br> male | 8 female, 12 male | 8 female, 10 male | 10 female, 10 <br> male |
| Age | $25.6 \pm 4.96$ <br> years | $31.3 \pm 10.5$ years | $30.3 \pm 10.4$ years | $32.6 \pm 10.3$ <br> years |
| Weight | $150 \pm 27.5 \mathrm{lbs}$ | $192 \pm 30.7 \mathrm{lbs}$ | $191 \pm 32.3 \mathrm{lbs}$ | $178.1 \pm 43.6 \mathrm{lbs}$ |
| Height | $66.8 \pm 3.30$ <br> inches | $68.4 \pm 3.77$ inches | $68.9 \pm 3.55$ <br> inches | $68.2 \pm 3.9$ <br> inches |
| PROMIS <br> Physical <br> Function | NA | $40.5 \pm 6.11$ | $40.9 \pm 6.32$ | NA |
| Affected Knee | NA | 10 right, 10 left | 9 right, 9 left | 14 right, 6 left |
| Prehab | NA | 2 some prehab, 18 <br> none | 2 some prehab, <br> 16 none | NA |
| Injury to Data <br> Collection | NA | $17.7 \pm 34.5$ <br> months* | $6.29 \pm 5.33$ <br> months | $8.55 \pm 5.16$ <br> months |
| Contralateral <br> Knee History | NA | 3 with history | 2 with history | 3 with history |
| Repeat Injury | NA | 9 repeat, 11 <br> primary | 8 repeat, 11 <br> primary | NA |

Table 3. Summary of demographic data for participants. (*) Strongly affected by 2 outliers injured over a decade prior to data collection.

### 4.1.2 Step Up and Over

Table 4 summarizes the p-values during the step up and over task for all participant
groups.

|  | LR |  |  | ACLd |  |  | PFP |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| \% of Cycle | Flex/Ext | Int/Ext | Ad/Ab | Flex/Ext | Int/Ext | Ad/Ab | Flex/Ext | Int/Ext | Ad/Ab |
| 0.00 | 0.8366 | 0.8255 | 0.3604 | 0.1262 | 0.1816 | 0.4652 | 0.0027 | 0.0791 | 0.9239 |
| 0.67 | 0.8000 | 0.6943 | 0.2958 | 0.2082 | 0.1261 | 0.4206 | 0.0063 | 0.0501 | 0.7957 |
| 1.33 | 0.9126 | 0.6037 | 0.2001 | 0.1613 | 0.1217 | 0.4726 | 0.0049 | 0.0579 | 0.7295 |
| 2.00 | 0.9345 | 0.6451 | 0.1369 | 0.1285 | 0.1172 | 0.5725 | 0.0053 | 0.0978 | 0.7081 |
| 2.67 | 0.9405 | 0.8625 | 0.1031 | 0.1044 | 0.1268 | 0.7132 | 0.0068 | 0.2043 | 0.7884 |
| 3.33 | 0.9745 | 0.8393 | 0.0851 | 0.0790 | 0.1525 | 0.9140 | 0.0052 | 0.4320 | 0.9950 |
| 4.00 | 0.9529 | 0.5518 | 0.0795 | 0.0602 | 0.1800 | 0.8777 | 0.0046 | 0.7562 | 0.7504 |
| 4.67 | 0.8444 | 0.3557 | 0.0696 | 0.0404 | 0.2154 | 0.6604 | 0.0057 | 0.9370 | 0.4719 |
| 5.33 | 0.7996 | 0.2469 | 0.0612 | 0.0309 | 0.2030 | 0.4687 | 0.0062 | 0.7922 | 0.2700 |
| 6.00 | 0.7847 | 0.2043 | 0.0538 | 0.0237 | 0.1628 | 0.3543 | 0.0045 | 0.8288 | 0.1711 |
| 6.67 | 0.7476 | 0.2168 | 0.0578 | 0.0258 | 0.1081 | 0.3100 | 0.0033 | 0.9889 | 0.1593 |
| 7.33 | 0.7136 | 0.2559 | 0.0677 | 0.0263 | 0.0656 | 0.3339 | 0.0040 | 0.7385 | 0.2039 |
| 8.00 | 0.6175 | 0.2777 | 0.0713 | 0.0271 | 0.0378 | 0.3951 | 0.0045 | 0.5037 | 0.2863 |
| 8.67 | 0.5372 | 0.2851 | 0.0832 | 0.0263 | 0.0241 | 0.4757 | 0.0042 | 0.3450 | 0.3623 |
| 9.33 | 0.4902 | 0.2967 | 0.1025 | 0.0259 | 0.0161 | 0.5553 | 0.0030 | 0.2849 | 0.4512 |
| 10.00 | 0.4605 | 0.3022 | 0.1302 | 0.0241 | 0.0120 | 0.6525 | 0.0019 | 0.2787 | 0.5810 |
| 10.67 | 0.4117 | 0.3498 | 0.1503 | 0.0218 | 0.0094 | 0.7461 | 0.0014 | 0.2886 | 0.7546 |
| 11.33 | 0.3486 | 0.4257 | 0.1697 | 0.0154 | 0.0074 | 0.8030 | 0.0010 | 0.2890 | 0.9258 |
| 12.00 | 0.2789 | 0.5009 | 0.1968 | 0.0118 | 0.0048 | 0.8326 | 0.0007 | 0.2463 | 0.9548 |
| 12.67 | 0.2390 | 0.5389 | 0.2193 | 0.0102 | 0.0025 | 0.8241 | 0.0005 | 0.1833 | 0.8679 |
| 13.33 | 0.2101 | 0.5564 | 0.2469 | 0.0079 | 0.0012 | 0.8274 | 0.0004 | 0.1255 | 0.8287 |
| 14.00 | 0.1858 | 0.5832 | 0.2771 | 0.0057 | 0.0005 | 0.8324 | 0.0003 | 0.0858 | 0.8093 |
| 14.67 | 0.1718 | 0.5846 | 0.3198 | 0.0041 | 0.0003 | 0.8293 | 0.0003 | 0.0643 | 0.8146 |
| 15.33 | 0.1630 | 0.5604 | 0.3521 | 0.0037 | 0.0002 | 0.8108 | 0.0003 | 0.0539 | 0.8301 |
| 16.00 | 0.1555 | 0.5088 | 0.3887 | 0.0038 | 0.0001 | 0.7909 | 0.0003 | 0.0462 | 0.8510 |
| 16.67 | 0.1475 | 0.4416 | 0.4287 | 0.0039 | 0.0001 | 0.7750 | 0.0003 | 0.0409 | 0.8514 |
| 17.33 | 0.1553 | 0.3678 | 0.4696 | 0.0043 | 0.0001 | 0.7498 | 0.0004 | 0.0362 | 0.8399 |
| 18.00 | 0.1608 | 0.3067 | 0.4902 | 0.0048 | 0.0001 | 0.7117 | 0.0004 | 0.0317 | 0.8413 |
| 18.67 | 0.1722 | 0.2602 | 0.5143 | 0.0052 | 0.0001 | 0.6936 | 0.0004 | 0.0268 | 0.8381 |
| 19.33 | 0.1934 | 0.2193 | 0.5351 | 0.0051 | 0.0001 | 0.6670 | 0.0004 | 0.0215 | 0.8507 |
| 20.00 | 0.2318 | 0.1870 | 0.5526 | 0.0051 | 0.0002 | 0.6263 | 0.0003 | 0.0173 | 0.8591 |
| 20.67 | 0.2491 | 0.1687 | 0.5646 | 0.0045 | 0.0002 | 0.5692 | 0.0002 | 0.0128 | 0.8820 |
| 21.33 | 0.2568 | 0.1521 | 0.5693 | 0.0040 | 0.0002 | 0.5226 | 0.0002 | 0.0092 | 0.9154 |
| 22.00 | 0.2649 | 0.1316 | 0.5740 | 0.0033 | 0.0003 | 0.4862 | 0.0001 | 0.0071 | 0.9630 |


| 22.67 | 0.2754 | 0.1049 | 0.5682 | 0.0025 | 0.0003 | 0.4438 | 0.0001 | 0.0062 | 0.9557 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 23.33 | 0.2878 | 0.0812 | 0.5749 | 0.0017 | 0.0003 | 0.3965 | 0.0001 | 0.0050 | 0.8557 |
| 24.00 | 0.2916 | 0.0640 | 0.6069 | 0.0011 | 0.0002 | 0.3466 | 0.0001 | 0.0041 | 0.7409 |
| 24.67 | 0.3048 | 0.0539 | 0.6466 | 0.0007 | 0.0001 | 0.3074 | 0.0000 | 0.0034 | 0.6564 |
| 25.33 | 0.3092 | 0.0465 | 0.6772 | 0.0005 | 0.0001 | 0.2851 | 0.0000 | 0.0029 | 0.5972 |
| 26.00 | 0.3133 | 0.0428 | 0.7082 | 0.0004 | 0.0001 | 0.2846 | 0.0000 | 0.0026 | 0.5548 |
| 26.67 | 0.3267 | 0.0384 | 0.7262 | 0.0003 | 0.0000 | 0.2902 | 0.0000 | 0.0029 | 0.5260 |
| 27.33 | 0.3365 | 0.0352 | 0.7474 | 0.0002 | 0.0000 | 0.2924 | 0.0000 | 0.0032 | 0.4953 |
| 28.00 | 0.3333 | 0.0344 | 0.7809 | 0.0002 | 0.0000 | 0.3002 | 0.0000 | 0.0036 | 0.4863 |
| 28.67 | 0.3295 | 0.0363 | 0.8233 | 0.0003 | 0.0000 | 0.3311 | 0.0001 | 0.0041 | 0.5125 |
| 29.33 | 0.3285 | 0.0407 | 0.8321 | 0.0003 | 0.0000 | 0.3672 | 0.0001 | 0.0048 | 0.5662 |
| 30.00 | 0.3304 | 0.0453 | 0.8438 | 0.0004 | 0.0000 | 0.3912 | 0.0001 | 0.0061 | 0.6147 |
| 30.67 | 0.3387 | 0.0549 | 0.8648 | 0.0004 | 0.0000 | 0.4095 | 0.0001 | 0.0077 | 0.6432 |
| 31.33 | 0.3577 | 0.0663 | 0.8867 | 0.0005 | 0.0000 | 0.4207 | 0.0001 | 0.0089 | 0.6562 |
| 32.00 | 0.3772 | 0.0811 | 0.9033 | 0.0006 | 0.0000 | 0.4305 | 0.0001 | 0.0092 | 0.6881 |
| 32.67 | 0.3860 | 0.0925 | 0.9242 | 0.0006 | 0.0000 | 0.4382 | 0.0001 | 0.0086 | 0.7281 |
| 33.33 | 0.3932 | 0.1035 | 0.9633 | 0.0007 | 0.0000 | 0.4410 | 0.0001 | 0.0078 | 0.7479 |
| 34.00 | 0.4156 | 0.1138 | 0.9952 | 0.0009 | 0.0000 | 0.4389 | 0.0002 | 0.0069 | 0.7665 |
| 34.67 | 0.4527 | 0.1251 | 0.9690 | 0.0011 | 0.0000 | 0.4254 | 0.0002 | 0.0061 | 0.7730 |
| 35.33 | 0.5069 | 0.1227 | 0.9734 | 0.0014 | 0.0000 | 0.4129 | 0.0002 | 0.0059 | 0.7616 |
| 36.00 | 0.5801 | 0.1120 | 0.9989 | 0.0017 | 0.0000 | 0.4085 | 0.0004 | 0.0061 | 0.7673 |
| 36.67 | 0.6657 | 0.1023 | 0.9635 | 0.0020 | 0.0000 | 0.3943 | 0.0006 | 0.0062 | 0.7668 |
| 37.33 | 0.7394 | 0.0963 | 0.9482 | 0.0025 | 0.0000 | 0.3628 | 0.0010 | 0.0064 | 0.7441 |
| 38.00 | 0.8017 | 0.0938 | 0.9302 | 0.0038 | 0.0000 | 0.3336 | 0.0017 | 0.0062 | 0.7204 |
| 38.67 | 0.8751 | 0.0879 | 0.8867 | 0.0055 | 0.0000 | 0.3023 | 0.0034 | 0.0057 | 0.6913 |
| 39.33 | 0.9494 | 0.0797 | 0.8419 | 0.0083 | 0.0000 | 0.2744 | 0.0061 | 0.0052 | 0.6544 |
| 40.00 | 0.9636 | 0.0718 | 0.8017 | 0.0130 | 0.0000 | 0.2573 | 0.0089 | 0.0046 | 0.5988 |
| 40.67 | 0.9009 | 0.0646 | 0.7701 | 0.0196 | 0.0000 | 0.2499 | 0.0117 | 0.0043 | 0.5605 |
| 41.33 | 0.8453 | 0.0546 | 0.7225 | 0.0292 | 0.0000 | 0.2463 | 0.0173 | 0.0047 | 0.5381 |
| 42.00 | 0.8091 | 0.0456 | 0.6687 | 0.0445 | 0.0000 | 0.2489 | 0.0246 | 0.0060 | 0.5377 |
| 42.67 | 0.8153 | 0.0382 | 0.6295 | 0.0666 | 0.0000 | 0.2633 | 0.0316 | 0.0083 | 0.5492 |
| 43.33 | 0.7991 | 0.0309 | 0.6085 | 0.0960 | 0.0000 | 0.2751 | 0.0361 | 0.0120 | 0.5529 |
| 44.00 | 0.7925 | 0.0236 | 0.5924 | 0.1268 | 0.0000 | 0.2941 | 0.0369 | 0.0176 | 0.5492 |
| 44.67 | 0.7534 | 0.0192 | 0.5540 | 0.1737 | 0.0001 | 0.3282 | 0.0369 | 0.0242 | 0.5319 |
| 45.33 | 0.7478 | 0.0178 | 0.5169 | 0.2342 | 0.0001 | 0.3658 | 0.0426 | 0.0296 | 0.5157 |
| 46.00 | 0.7389 | 0.0211 | 0.4829 | 0.2977 | 0.0002 | 0.3840 | 0.0494 | 0.0332 | 0.4975 |
| 46.67 | 0.7354 | 0.0273 | 0.4458 | 0.3678 | 0.0004 | 0.3997 | 0.0595 | 0.0383 | 0.4958 |
| 47.33 | 0.7103 | 0.0344 | 0.4067 | 0.4641 | 0.0007 | 0.4077 | 0.0709 | 0.0470 | 0.5102 |
| 48.00 | 0.6607 | 0.0437 | 0.3651 | 0.5911 | 0.0009 | 0.4242 | 0.0748 | 0.0605 | 0.5207 |
| 48.67 | 0.6085 | 0.0547 | 0.3331 | 0.7156 | 0.0011 | 0.4432 | 0.0749 | 0.0716 | 0.5187 |
| 49.33 | 0.5843 | 0.0632 | 0.3172 | 0.8318 | 0.0012 | 0.4571 | 0.0763 | 0.0765 | 0.5274 |
| 50.00 | 0.5765 | 0.0712 | 0.3260 | 0.9520 | 0.0017 | 0.4738 | 0.0810 | 0.0759 | 0.5560 |
| 50.67 | 0.5661 | 0.0796 | 0.3368 | 0.9443 | 0.0023 | 0.4807 | 0.0827 | 0.0752 | 0.6003 |


| 51.33 | 0.5535 | 0.0810 | 0.3412 | 0.8497 | 0.0030 | 0.4833 | 0.0751 | 0.0766 | 0.6309 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 52.00 | 0.5476 | 0.0728 | 0.3557 | 0.7686 | 0.0032 | 0.5079 | 0.0686 | 0.0764 | 0.6465 |
| 52.67 | 0.5507 | 0.0605 | 0.3700 | 0.6878 | 0.0037 | 0.5463 | 0.0632 | 0.0749 | 0.6416 |
| 53.33 | 0.5691 | 0.0530 | 0.3954 | 0.6074 | 0.0046 | 0.5836 | 0.0502 | 0.0810 | 0.6419 |
| 54.00 | 0.5993 | 0.0456 | 0.4295 | 0.5528 | 0.0058 | 0.6115 | 0.0378 | 0.1022 | 0.6359 |
| 54.67 | 0.6403 | 0.0408 | 0.4784 | 0.5317 | 0.0083 | 0.6155 | 0.0252 | 0.1322 | 0.6230 |
| 55.33 | 0.7013 | 0.0373 | 0.5195 | 0.5352 | 0.0095 | 0.6012 | 0.0160 | 0.1606 | 0.5780 |
| 56.00 | 0.7757 | 0.0350 | 0.5559 | 0.5396 | 0.0106 | 0.5979 | 0.0104 | 0.1744 | 0.5424 |
| 56.67 | 0.8514 | 0.0337 | 0.5943 | 0.5500 | 0.0126 | 0.6052 | 0.0063 | 0.1700 | 0.5237 |
| 57.33 | 0.9181 | 0.0336 | 0.6287 | 0.5681 | 0.0120 | 0.6108 | 0.0035 | 0.1571 | 0.5250 |
| 58.00 | 0.9742 | 0.0387 | 0.6494 | 0.6149 | 0.0097 | 0.6069 | 0.0019 | 0.1495 | 0.5314 |
| 58.67 | 0.9820 | 0.0450 | 0.6932 | 0.6860 | 0.0077 | 0.5924 | 0.0010 | 0.1346 | 0.5355 |
| 59.33 | 0.9204 | 0.0659 | 0.7664 | 0.7347 | 0.0055 | 0.5774 | 0.0006 | 0.1081 | 0.5305 |
| 60.00 | 0.8901 | 0.0961 | 0.8165 | 0.7944 | 0.0036 | 0.5486 | 0.0003 | 0.0833 | 0.5273 |
| 60.67 | 0.8628 | 0.1256 | 0.8122 | 0.9021 | 0.0029 | 0.4873 | 0.0002 | 0.0687 | 0.5234 |
| 61.33 | 0.8542 | 0.1415 | 0.7824 | 0.9562 | 0.0027 | 0.4109 | 0.0001 | 0.0537 | 0.5042 |
| 62.00 | 0.7859 | 0.1526 | 0.7864 | 0.8287 | 0.0021 | 0.3484 | 0.0001 | 0.0413 | 0.5008 |
| 62.67 | 0.7661 | 0.1559 | 0.8156 | 0.7375 | 0.0012 | 0.3037 | 0.0000 | 0.0331 | 0.5044 |
| 63.33 | 0.7035 | 0.1766 | 0.8594 | 0.6568 | 0.0006 | 0.2798 | 0.0000 | 0.0255 | 0.4999 |
| 64.00 | 0.6822 | 0.1934 | 0.8704 | 0.5795 | 0.0002 | 0.2599 | 0.0000 | 0.0177 | 0.4780 |
| 64.67 | 0.6341 | 0.2164 | 0.8685 | 0.5002 | 0.0001 | 0.2304 | 0.0000 | 0.0133 | 0.4488 |
| 65.33 | 0.6197 | 0.2305 | 0.8459 | 0.4671 | 0.0000 | 0.2083 | 0.0000 | 0.0119 | 0.4291 |
| 66.00 | 0.5737 | 0.2470 | 0.8097 | 0.4445 | 0.0000 | 0.1980 | 0.0000 | 0.0121 | 0.4536 |
| 66.67 | 0.5377 | 0.2955 | 0.7695 | 0.4234 | 0.0000 | 0.2069 | 0.0000 | 0.0129 | 0.5008 |
| 67.33 | 0.5070 | 0.3563 | 0.7562 | 0.4045 | 0.0000 | 0.2107 | 0.0000 | 0.0153 | 0.5381 |
| 68.00 | 0.4926 | 0.3948 | 0.7700 | 0.3802 | 0.0000 | 0.1866 | 0.0000 | 0.0190 | 0.5240 |
| 68.67 | 0.4780 | 0.3948 | 0.8036 | 0.3595 | 0.0000 | 0.1626 | 0.0000 | 0.0203 | 0.5102 |
| 69.33 | 0.4582 | 0.4081 | 0.8304 | 0.3232 | 0.0000 | 0.1465 | 0.0000 | 0.0200 | 0.5165 |
| 70.00 | 0.4457 | 0.4568 | 0.8167 | 0.2753 | 0.0000 | 0.1464 | 0.0000 | 0.0217 | 0.5481 |
| 70.67 | 0.4253 | 0.5319 | 0.7879 | 0.2466 | 0.0000 | 0.1604 | 0.0000 | 0.0233 | 0.6031 |
| 71.33 | 0.3995 | 0.6121 | 0.8053 | 0.2246 | 0.0000 | 0.1801 | 0.0001 | 0.0230 | 0.6512 |
| 72.00 | 0.3646 | 0.6523 | 0.8463 | 0.2054 | 0.0000 | 0.2087 | 0.0001 | 0.0232 | 0.7009 |
| 72.67 | 0.3320 | 0.6859 | 0.8596 | 0.1631 | 0.0000 | 0.2636 | 0.0003 | 0.0258 | 0.7389 |
| 73.33 | 0.2928 | 0.6941 | 0.8080 | 0.1285 | 0.0000 | 0.3192 | 0.0005 | 0.0351 | 0.7786 |
| 74.00 | 0.2320 | 0.6741 | 0.7344 | 0.0998 | 0.0000 | 0.3680 | 0.0009 | 0.0521 | 0.8253 |
| 74.67 | 0.1772 | 0.6188 | 0.6653 | 0.0798 | 0.0000 | 0.4246 | 0.0013 | 0.0843 | 0.9116 |
| 75.33 | 0.1416 | 0.5441 | 0.6095 | 0.0553 | 0.0000 | 0.4935 | 0.0014 | 0.1408 | 0.9928 |
| 76.00 | 0.1282 | 0.4763 | 0.5803 | 0.0352 | 0.0000 | 0.5738 | 0.0014 | 0.2214 | 0.9289 |
| 76.67 | 0.1113 | 0.4195 | 0.5784 | 0.0196 | 0.0000 | 0.5864 | 0.0011 | 0.2892 | 0.9081 |
| 77.33 | 0.0973 | 0.3628 | 0.6011 | 0.0105 | 0.0000 | 0.5530 | 0.0009 | 0.3293 | 0.9115 |
| 78.00 | 0.0928 | 0.3225 | 0.6122 | 0.0052 | 0.0000 | 0.5332 | 0.0007 | 0.3277 | 0.9580 |
| 78.67 | 0.0991 | 0.2966 | 0.6073 | 0.0025 | 0.0000 | 0.5098 | 0.0005 | 0.3066 | 0.9910 |
| 79.33 | 0.1090 | 0.2762 | 0.5910 | 0.0013 | 0.0000 | 0.4848 | 0.0004 | 0.2700 | 0.9663 |


| $\mathbf{8 0 . 0 0}$ | 0.1247 | 0.2617 | 0.5897 | 0.0007 | 0.0000 | 0.4534 | 0.0004 | 0.2358 | 0.9622 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathbf{8 0 . 6 7}$ | 0.1471 | 0.2489 | 0.6082 | 0.0004 | 0.0000 | 0.4301 | 0.0004 | 0.2082 | 0.9579 |
| $\mathbf{8 1 . 3 3}$ | 0.1820 | 0.2443 | 0.6356 | 0.0003 | 0.0000 | 0.4058 | 0.0006 | 0.1970 | 0.9521 |
| $\mathbf{8 2 . 0 0}$ | 0.2161 | 0.2401 | 0.6619 | 0.0003 | 0.0000 | 0.3984 | 0.0008 | 0.2005 | 0.9446 |
| $\mathbf{8 2 . 6 7}$ | 0.2350 | 0.2597 | 0.6842 | 0.0004 | 0.0000 | 0.3968 | 0.0014 | 0.2032 | 0.9368 |
| $\mathbf{8 3 . 3 3}$ | 0.2609 | 0.2912 | 0.7286 | 0.0006 | 0.0000 | 0.3776 | 0.0030 | 0.1936 | 0.9278 |
| $\mathbf{8 4 . 0 0}$ | 0.2920 | 0.3083 | 0.7858 | 0.0011 | 0.0000 | 0.3511 | 0.0070 | 0.1700 | 0.8946 |
| $\mathbf{8 4 . 6 7}$ | 0.3282 | 0.2978 | 0.8128 | 0.0024 | 0.0001 | 0.3389 | 0.0159 | 0.1427 | 0.8354 |
| $\mathbf{8 5 . 3 3}$ | 0.3760 | 0.2705 | 0.8104 | 0.0065 | 0.0001 | 0.3420 | 0.0374 | 0.1149 | 0.7973 |
| $\mathbf{8 6 . 0 0}$ | 0.4337 | 0.2505 | 0.7777 | 0.0179 | 0.0001 | 0.3653 | 0.0759 | 0.0929 | 0.7850 |
| $\mathbf{8 6 . 6 7}$ | 0.4857 | 0.2428 | 0.7398 | 0.0449 | 0.0001 | 0.3909 | 0.1393 | 0.0777 | 0.7909 |
| $\mathbf{8 7 . 3 3}$ | 0.5073 | 0.2597 | 0.7145 | 0.0969 | 0.0001 | 0.4024 | 0.2300 | 0.0742 | 0.8421 |
| $\mathbf{8 8 . 0 0}$ | 0.5389 | 0.2553 | 0.6742 | 0.1938 | 0.0002 | 0.3897 | 0.3553 | 0.0763 | 0.9249 |
| $\mathbf{8 8 . 6 7}$ | 0.5831 | 0.2231 | 0.6079 | 0.3263 | 0.0005 | 0.3853 | 0.4926 | 0.0863 | 0.9889 |
| $\mathbf{8 9 . 3 3}$ | 0.6425 | 0.1561 | 0.4881 | 0.4663 | 0.0010 | 0.3851 | 0.6156 | 0.0956 | 0.9938 |
| $\mathbf{9 0 . 0 0}$ | 0.6329 | 0.0965 | 0.3641 | 0.6067 | 0.0016 | 0.3717 | 0.6798 | 0.0987 | 0.9711 |
| $\mathbf{9 0 . 6 7}$ | 0.6219 | 0.0534 | 0.2756 | 0.7354 | 0.0019 | 0.3619 | 0.6968 | 0.0866 | 0.9021 |
| $\mathbf{9 1 . 3 3}$ | 0.6232 | 0.0273 | 0.2354 | 0.8274 | 0.0021 | 0.3663 | 0.6813 | 0.0785 | 0.8033 |
| $\mathbf{9 2 . 0 0}$ | 0.6564 | 0.0170 | 0.2172 | 0.9085 | 0.0024 | 0.3906 | 0.7213 | 0.0783 | 0.7042 |
| $\mathbf{9 2 . 6 7}$ | 0.6477 | 0.0150 | 0.2230 | 0.9397 | 0.0020 | 0.4038 | 0.7194 | 0.0803 | 0.5871 |
| $\mathbf{9 3 . 3 3}$ | 0.6155 | 0.0144 | 0.2352 | 0.9338 | 0.0012 | 0.4062 | 0.6627 | 0.0982 | 0.5292 |
| $\mathbf{9 4 . 0 0}$ | 0.5797 | 0.0146 | 0.2406 | 0.8617 | 0.0006 | 0.4083 | 0.5391 | 0.1150 | 0.5006 |
| $\mathbf{9 4 . 6 7}$ | 0.6705 | 0.0202 | 0.2502 | 0.7728 | 0.0005 | 0.3978 | 0.3776 | 0.1475 | 0.5317 |
| $\mathbf{9 5 . 3 3}$ | 0.7375 | 0.0331 | 0.2437 | 0.6648 | 0.0005 | 0.3927 | 0.2767 | 0.1720 | 0.5908 |
| $\mathbf{9 6 . 0 0}$ | 0.7884 | 0.0545 | 0.2445 | 0.5383 | 0.0010 | 0.3964 | 0.1998 | 0.1963 | 0.6487 |
| $\mathbf{9 6 . 6 7}$ | 0.7917 | 0.0818 | 0.2340 | 0.4599 | 0.0027 | 0.3885 | 0.1190 | 0.1466 | 0.6411 |
| $\mathbf{9 7 . 3 3}$ | 0.8519 | 0.1227 | 0.2090 | 0.3715 | 0.0074 | 0.3921 | 0.0591 | 0.1099 | 0.6449 |
| $\mathbf{9 8 . 0 0}$ | 0.9918 | 0.1685 | 0.1633 | 0.2832 | 0.0170 | 0.3985 | 0.0233 | 0.0813 | 0.6614 |
| $\mathbf{9 8 . 6 7}$ | 0.9219 | 0.2054 | 0.1193 | 0.1988 | 0.0385 | 0.4043 | 0.0108 | 0.0588 | 0.7119 |
| $\mathbf{9 9 . 3 3}$ | 0.8599 | 0.1977 | 0.0918 | 0.1582 | 0.0844 | 0.4334 | 0.0062 | 0.0402 | 0.7701 |
| $\mathbf{1 0 0 . 0 0}$ | 0.7856 | 0.1807 | 0.1098 | 0.1536 | 0.1659 | 0.4998 | 0.0034 | 0.0295 | 0.7783 |
| $\mathbf{T a b l}$ | $\mid$ |  |  |  |  |  |  |  |  |

Table 4. Summary of p-values for flexion-extension, internal-external, and abduction-adduction rotation angles during step up and over task for bilateral control (LR), ACLd, and PFP populations.

## Bilateral Differences in Healthy Control Group

During the step-up and over task significant differences ( $\mathrm{p}<0.05$ ) were observed for internal-external rotation between $26-31 \%, 42-48 \%, 54-59 \%$, and $92-96 \%$ of the cycle. No other differences were observed between bilateral control subjects during step up and over.


Figure 4. Rotation angles during step-up and over for bilateral control group. (a) Flexionextension. (b) Internal-external. Significantly less left internal rotation between $26-31 \%, 42-48 \%$, $54-59 \%$, and $92-96 \%$ of the cycle. (c) Varus-valgus. Shaded regions indicate areas of significant differences.

## ACLd Group

For the step up and over task, more external rotation was observed between $8-99 \%$ of the cycle and flexion-extension angles were significantly different between 5-42\% and 76-87\% of the cycle.


Figure 5. Rotation angles during step-up and over for ACLd group. (a) Flexion-extension.
Significantly lower ACLd flexion rotation between 5-42\% and 76-87\% (b) Internal-external. Significantly more ACLd external rotation between $8-99 \%$ of the cycle. (c) Varus-valgus. Shaded regions indicate areas of significant differences.

## PFP Group

Comparison of cycle normalized ensemble averages showed statistically significant differences ( $\mathrm{p}<0.05$ ) in internal-external rotation between PFP and healthy control group for $42 \%$ of the cycle during step-up and over tasks and $30 \%$ of the cycle for lateral step-down tasks. Flexion-extension rotation had significant differences for $76 \%$ of step-up and over tasks and $99 \%$ of lateral step-down tasks.


Figure 6. Rotation angles during step-up and over for PFP group. (a) Flexion-extension. Significantly lower PFP flexion rotation between 0-46\% and 54-85\% (b) Internal-external. Significantly less PFP internal rotation between $17-48 \%$ and $62-74 \%$ of the cycle. (c) Varusvalgus. Shaded regions indicate areas of significant differences.

### 4.1.3 Lateral Step Down

Table 5 summarizes the p -values during the lateral step-down task for all participant groups.

|  | LR |  |  | ACLd |  |  | PFP |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \hline \text { \% of } \\ & \text { Cycle } \end{aligned}$ | Flex/Ext | Int/Ext | Ad/Ab | Flex/Ext | Int/Ext | Ad/Ab | Flex/Ext | Int/Ext | Ad/Ab |
| 0 | 0.3901 | 0.8222 | 0.1508 | 0.5689 | 0.0166 | 0.0879 | 0.0858 | 0.0411 | 0.9351 |
| 1 | 0.3775 | 0.7646 | 0.1572 | 0.5213 | 0.0122 | 0.1011 | 0.0671 | 0.0313 | 0.9653 |
| 2 | 0.3686 | 0.7376 | 0.1401 | 0.5133 | 0.0098 | 0.1217 | 0.0635 | 0.0292 | 0.9114 |
| 3 | 0.3639 | 0.7004 | 0.1324 | 0.5305 | 0.0079 | 0.1417 | 0.0569 | 0.0272 | 0.8664 |
| 4 | 0.3698 | 0.6908 | 0.1428 | 0.5741 | 0.0063 | 0.1646 | 0.0501 | 0.0233 | 0.8008 |
| 5 | 0.3672 | 0.7204 | 0.1713 | 0.6482 | 0.0054 | 0.1912 | 0.0402 | 0.0197 | 0.7305 |
| 6 | 0.3859 | 0.7450 | 0.2008 | 0.7342 | 0.0046 | 0.2092 | 0.0314 | 0.0188 | 0.6828 |
| 7 | 0.4200 | 0.7583 | 0.2278 | 0.8129 | 0.0038 | 0.2072 | 0.0230 | 0.0184 | 0.6743 |
| 8 | 0.4646 | 0.7719 | 0.2729 | 0.9126 | 0.0033 | 0.2047 | 0.0197 | 0.0167 | 0.6753 |
| 9 | 0.4887 | 0.8436 | 0.3227 | 0.9642 | 0.0029 | 0.1963 | 0.0174 | 0.0151 | 0.6681 |
| 10 | 0.5414 | 0.9021 | 0.3576 | 0.8468 | 0.0026 | 0.1812 | 0.0161 | 0.0143 | 0.6644 |
| 11 | 0.5909 | 0.9503 | 0.3759 | 0.7366 | 0.0022 | 0.1603 | 0.0150 | 0.0140 | 0.7062 |
| 12 | 0.6709 | 0.9840 | 0.4098 | 0.6386 | 0.0019 | 0.1384 | 0.0129 | 0.0144 | 0.7632 |
| 13 | 0.7581 | 0.9808 | 0.4428 | 0.5273 | 0.0016 | 0.1159 | 0.0127 | 0.0152 | 0.8282 |
| 14 | 0.8043 | 0.9067 | 0.4487 | 0.4235 | 0.0014 | 0.0995 | 0.0154 | 0.0159 | 0.9038 |
| 15 | 0.8557 | 0.8341 | 0.4236 | 0.3307 | 0.0011 | 0.0889 | 0.0173 | 0.0181 | 0.9758 |
| 16 | 0.8953 | 0.7775 | 0.3991 | 0.2763 | 0.0008 | 0.0855 | 0.0170 | 0.0213 | 0.9675 |
| 17 | 0.9579 | 0.7686 | 0.3894 | 0.2288 | 0.0005 | 0.0829 | 0.0163 | 0.0247 | 0.8964 |
| 18 | 0.9999 | 0.8054 | 0.3843 | 0.1910 | 0.0003 | 0.0795 | 0.0176 | 0.0249 | 0.8276 |
| 19 | 0.9385 | 0.8550 | 0.3911 | 0.1450 | 0.0002 | 0.0719 | 0.0169 | 0.0216 | 0.7810 |
| 20 | 0.8558 | 0.8958 | 0.4081 | 0.1107 | 0.0002 | 0.0657 | 0.0175 | 0.0187 | 0.7541 |
| 21 | 0.7843 | 0.9218 | 0.4280 | 0.0845 | 0.0001 | 0.0616 | 0.0179 | 0.0169 | 0.7325 |
| 22 | 0.7542 | 0.9051 | 0.4305 | 0.0684 | 0.0001 | 0.0602 | 0.0179 | 0.0175 | 0.6878 |
| 23 | 0.7457 | 0.9242 | 0.4283 | 0.0532 | 0.0001 | 0.0620 | 0.0165 | 0.0217 | 0.6369 |
| 24 | 0.7258 | 0.9876 | 0.4426 | 0.0409 | 0.0001 | 0.0648 | 0.0161 | 0.0270 | 0.6120 |
| 25 | 0.6846 | 0.9495 | 0.4847 | 0.0308 | 0.0001 | 0.0662 | 0.0159 | 0.0304 | 0.5909 |
| 26 | 0.6437 | 0.9202 | 0.5315 | 0.0244 | 0.0001 | 0.0657 | 0.0158 | 0.0301 | 0.5715 |
| 27 | 0.6108 | 0.9022 | 0.5492 | 0.0184 | 0.0001 | 0.0657 | 0.0150 | 0.0294 | 0.5669 |
| 28 | 0.6159 | 0.8845 | 0.5477 | 0.0143 | 0.0000 | 0.0691 | 0.0154 | 0.0308 | 0.5849 |
| 29 | 0.6092 | 0.8530 | 0.5611 | 0.0112 | 0.0000 | 0.0749 | 0.0168 | 0.0350 | 0.6072 |
| 30 | 0.5983 | 0.8054 | 0.5832 | 0.0096 | 0.0000 | 0.0778 | 0.0175 | 0.0374 | 0.6030 |
| 31 | 0.5862 | 0.7561 | 0.6199 | 0.0083 | 0.0000 | 0.0789 | 0.0179 | 0.0390 | 0.5861 |
| 32 | 0.5678 | 0.7192 | 0.6717 | 0.0070 | 0.0000 | 0.0804 | 0.0169 | 0.0406 | 0.5813 |


| 33 | 0.5615 | 0.7100 | 0.7005 | 0.0057 | 0.0000 | 0.0819 | 0.0162 | 0.0466 | 0.5936 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 34 | 0.5469 | 0.7035 | 0.7063 | 0.0048 | 0.0000 | 0.0855 | 0.0156 | 0.0517 | 0.5965 |
| 35 | 0.5168 | 0.6854 | 0.7058 | 0.0045 | 0.0000 | 0.0908 | 0.0155 | 0.0554 | 0.5933 |
| 36 | 0.4871 | 0.6662 | 0.7223 | 0.0041 | 0.0000 | 0.0973 | 0.0152 | 0.0587 | 0.5958 |
| 37 | 0.4599 | 0.6473 | 0.7377 | 0.0036 | 0.0000 | 0.1013 | 0.0136 | 0.0632 | 0.6053 |
| 38 | 0.4475 | 0.6368 | 0.7406 | 0.0034 | 0.0000 | 0.1069 | 0.0122 | 0.0681 | 0.6170 |
| 39 | 0.4302 | 0.6269 | 0.7383 | 0.0033 | 0.0000 | 0.1145 | 0.0116 | 0.0739 | 0.6318 |
| 40 | 0.4079 | 0.6206 | 0.7531 | 0.0033 | 0.0000 | 0.1220 | 0.0112 | 0.0805 | 0.6384 |
| 41 | 0.3842 | 0.6207 | 0.7807 | 0.0031 | 0.0000 | 0.1272 | 0.0103 | 0.0888 | 0.6376 |
| 42 | 0.3651 | 0.6225 | 0.8044 | 0.0031 | 0.0000 | 0.1344 | 0.0097 | 0.0928 | 0.6351 |
| 43 | 0.3475 | 0.6157 | 0.8282 | 0.0030 | 0.0000 | 0.1408 | 0.0089 | 0.0931 | 0.6370 |
| 44 | 0.3361 | 0.6048 | 0.8596 | 0.0029 | 0.0000 | 0.1437 | 0.0082 | 0.0914 | 0.6468 |
| 45 | 0.3316 | 0.5970 | 0.8750 | 0.0026 | 0.0000 | 0.1450 | 0.0075 | 0.0933 | 0.6599 |
| 46 | 0.3255 | 0.5841 | 0.8804 | 0.0023 | 0.0000 | 0.1460 | 0.0066 | 0.0981 | 0.6778 |
| 47 | 0.3164 | 0.5754 | 0.8775 | 0.0022 | 0.0001 | 0.1480 | 0.0061 | 0.1020 | 0.6959 |
| 48 | 0.3065 | 0.5696 | 0.8650 | 0.0021 | 0.0001 | 0.1543 | 0.0056 | 0.1047 | 0.7145 |
| 49 | 0.3100 | 0.5580 | 0.8638 | 0.0020 | 0.0001 | 0.1609 | 0.0052 | 0.1078 | 0.7341 |
| 50 | 0.3071 | 0.5382 | 0.8706 | 0.0019 | 0.0001 | 0.1679 | 0.0047 | 0.1127 | 0.7576 |
| 51 | 0.3025 | 0.5167 | 0.8854 | 0.0018 | 0.0001 | 0.1742 | 0.0042 | 0.1199 | 0.7862 |
| 52 | 0.2978 | 0.5021 | 0.8977 | 0.0018 | 0.0001 | 0.1838 | 0.0038 | 0.1290 | 0.8225 |
| 53 | 0.2950 | 0.4950 | 0.9096 | 0.0018 | 0.0002 | 0.1950 | 0.0034 | 0.1376 | 0.8542 |
| 54 | 0.2926 | 0.4813 | 0.9197 | 0.0018 | 0.0002 | 0.2001 | 0.0032 | 0.1449 | 0.8761 |
| 55 | 0.2886 | 0.4730 | 0.9235 | 0.0019 | 0.0002 | 0.1992 | 0.0030 | 0.1522 | 0.8986 |
| 56 | 0.2834 | 0.4683 | 0.9285 | 0.0020 | 0.0002 | 0.1986 | 0.0028 | 0.1596 | 0.9185 |
| 57 | 0.2807 | 0.4682 | 0.9357 | 0.0020 | 0.0002 | 0.2002 | 0.0027 | 0.1667 | 0.9430 |
| 58 | 0.2726 | 0.4739 | 0.9446 | 0.0019 | 0.0002 | 0.1991 | 0.0027 | 0.1747 | 0.9643 |
| 59 | 0.2683 | 0.4859 | 0.9518 | 0.0016 | 0.0002 | 0.1976 | 0.0027 | 0.1810 | 0.9884 |
| 60 | 0.2602 | 0.4936 | 0.9500 | 0.0013 | 0.0002 | 0.1958 | 0.0027 | 0.1919 | 0.9961 |
| 61 | 0.2521 | 0.4973 | 0.9400 | 0.0011 | 0.0002 | 0.1901 | 0.0028 | 0.2039 | 0.9809 |
| 62 | 0.2458 | 0.5011 | 0.9188 | 0.0009 | 0.0002 | 0.1879 | 0.0031 | 0.2147 | 0.9751 |
| 63 | 0.2455 | 0.4973 | 0.8927 | 0.0007 | 0.0002 | 0.1878 | 0.0035 | 0.2185 | 0.9791 |
| 64 | 0.2505 | 0.4829 | 0.8736 | 0.0006 | 0.0002 | 0.1897 | 0.0038 | 0.2183 | 0.9771 |
| 65 | 0.2632 | 0.4691 | 0.8480 | 0.0006 | 0.0002 | 0.1920 | 0.0042 | 0.2141 | 0.9633 |
| 66 | 0.2732 | 0.4607 | 0.8111 | 0.0006 | 0.0002 | 0.1930 | 0.0046 | 0.2030 | 0.9486 |
| 67 | 0.2865 | 0.4548 | 0.7813 | 0.0006 | 0.0002 | 0.1895 | 0.0053 | 0.1909 | 0.9470 |
| 68 | 0.2979 | 0.4434 | 0.7708 | 0.0006 | 0.0002 | 0.1825 | 0.0062 | 0.1847 | 0.9547 |
| 69 | 0.3270 | 0.4272 | 0.7619 | 0.0006 | 0.0001 | 0.1727 | 0.0072 | 0.1824 | 0.9668 |
| 70 | 0.3550 | 0.4065 | 0.7453 | 0.0007 | 0.0001 | 0.1612 | 0.0088 | 0.1864 | 0.9820 |
| 71 | 0.3705 | 0.3765 | 0.7327 | 0.0009 | 0.0001 | 0.1537 | 0.0108 | 0.1949 | 0.9982 |
| 72 | 0.3910 | 0.3310 | 0.7288 | 0.0010 | 0.0002 | 0.1483 | 0.0124 | 0.2125 | 0.9780 |
| 73 | 0.4132 | 0.2934 | 0.7319 | 0.0012 | 0.0002 | 0.1437 | 0.0126 | 0.2313 | 0.9636 |
| 74 | 0.4389 | 0.2587 | 0.7250 | 0.0015 | 0.0003 | 0.1436 | 0.0118 | 0.2570 | 0.9635 |
| 75 | 0.4567 | 0.2359 | 0.7070 | 0.0023 | 0.0004 | 0.1464 | 0.0120 | 0.2768 | 0.9956 |


| 76 | 0.4810 | 0.2238 | 0.6896 | 0.0032 | 0.0006 | 0.1518 | 0.0136 | 0.2881 | 0.9632 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 77 | 0.5079 | 0.2284 | 0.6699 | 0.0043 | 0.0008 | 0.1523 | 0.0135 | 0.2979 | 0.9394 |
| 78 | 0.5387 | 0.2284 | 0.6449 | 0.0060 | 0.0011 | 0.1548 | 0.0129 | 0.3156 | 0.9242 |
| 79 | 0.5868 | 0.2235 | 0.6181 | 0.0093 | 0.0014 | 0.1579 | 0.0124 | 0.3333 | 0.9129 |
| 80 | 0.6368 | 0.2303 | 0.5905 | 0.0133 | 0.0016 | 0.1620 | 0.0123 | 0.3436 | 0.8893 |
| 81 | 0.6839 | 0.2396 | 0.5782 | 0.0198 | 0.0019 | 0.1684 | 0.0126 | 0.3451 | 0.8603 |
| 82 | 0.6925 | 0.2477 | 0.5694 | 0.0282 | 0.0023 | 0.1765 | 0.0142 | 0.3479 | 0.8342 |
| 83 | 0.7356 | 0.2638 | 0.5217 | 0.0464 | 0.0028 | 0.1809 | 0.0162 | 0.3480 | 0.8093 |
| 84 | 0.8133 | 0.2742 | 0.4495 | 0.0730 | 0.0035 | 0.1864 | 0.0177 | 0.3391 | 0.7930 |
| 85 | 0.8855 | 0.2872 | 0.3903 | 0.1035 | 0.0041 | 0.1892 | 0.0199 | 0.3142 | 0.7865 |
| 86 | 0.9531 | 0.3130 | 0.3380 | 0.1427 | 0.0044 | 0.1941 | 0.0220 | 0.2718 | 0.7560 |
| 87 | 0.9662 | 0.3462 | 0.3049 | 0.2018 | 0.0049 | 0.2028 | 0.0236 | 0.2325 | 0.7304 |
| 88 | 0.9100 | 0.3829 | 0.2759 | 0.2829 | 0.0057 | 0.2085 | 0.0258 | 0.1950 | 0.7130 |
| 89 | 0.8044 | 0.4330 | 0.2428 | 0.3961 | 0.0061 | 0.2125 | 0.0289 | 0.1589 | 0.6987 |
| 90 | 0.7481 | 0.4789 | 0.2193 | 0.5112 | 0.0064 | 0.2157 | 0.0324 | 0.1350 | 0.6807 |
| 91 | 0.7476 | 0.5147 | 0.2072 | 0.6377 | 0.0067 | 0.2206 | 0.0387 | 0.1196 | 0.6532 |
| 92 | 0.6986 | 0.5598 | 0.2141 | 0.7678 | 0.0070 | 0.2159 | 0.0437 | 0.0999 | 0.6416 |
| 93 | 0.6424 | 0.6237 | 0.2233 | 0.9007 | 0.0073 | 0.2005 | 0.0468 | 0.0875 | 0.6544 |
| 94 | 0.5821 | 0.7076 | 0.2392 | 0.9971 | 0.0070 | 0.1807 | 0.0441 | 0.0781 | 0.6726 |
| 95 | 0.5204 | 0.8121 | 0.2507 | 0.8995 | 0.0071 | 0.1665 | 0.0454 | 0.0723 | 0.6719 |
| 96 | 0.4949 | 0.9188 | 0.2560 | 0.8191 | 0.0078 | 0.1543 | 0.0481 | 0.0694 | 0.6748 |
| 97 | 0.4755 | 0.9494 | 0.2451 | 0.7077 | 0.0083 | 0.1370 | 0.0493 | 0.0627 | 0.7080 |
| 98 | 0.4397 | 0.9280 | 0.2281 | 0.6170 | 0.0085 | 0.1173 | 0.0523 | 0.0568 | 0.7577 |
| 99 | 0.4215 | 0.8902 | 0.2112 | 0.5653 | 0.0091 | 0.1005 | 0.0528 | 0.0563 | 0.8056 |
| 100 | 0.3982 | 0.8349 | 0.2063 | 0.5266 | 0.0104 | 0.0842 | 0.0583 | 0.0583 | 0.8562 |

Table 5. Summary of p-values for flexion-extension, internal-external, and abduction-adduction rotation angles during lateral step-down task for bilateral control (LR), ACLd, and PFP populations.

## ACLd Group

Data from the lateral step-down task shows an increase in external rotation for $100 \%$ of the cycle and an increase in flexion for $25-82 \%$ of the cycle. There were no significant differences in abduction-adduction rotation angles. No differences were observed between left and right control data. Most participants were able to perform the lateral step down, but in varying degrees. One ACLd participant data set was excluded for reasons mentioned in Section 4.1.


Figure 7. Rotation angles during lateral step-down for ACLd group. (a) Flexion-extension. Significantly lower ACLd flexion rotation for $25-82 \%$ of the cycle. (b) Internal-external. Significantly less ACLd internal rotation for $100 \%$ of the cycle. (c) Varus-valgus. Shaded regions indicate areas of significant differences.

## PFP Population

Data from the lateral step-down task shows an increase in external rotation between 0$33 \%$ of the cycle and an increase in flexion for $5-97 \%$ of the cycle. There were no significant
differences in abduction-adduction rotation angles. No differences were observed between left and right control data. Most participants were able to perform the lateral step down, but in varying degrees.


(c)


Figure 8. Rotation angles during lateral step-down for PFP group. (a) Flexion-extension. Significantly lower PFP flexion rotation between 5-97\% (b) Internal-external. Significantly less PFP internal rotation between $0-33 \%$ of the cycle. (c) Varus-valgus. Shaded regions indicate areas of significant differences.

### 4.1.4 Y-balance (posteromedial and posterolateral)

Table 6 summarizes the p-values during the posteromedial Y-balance task for all participant groups.

|  | LR |  |  | ACLd |  |  | PFP |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| \% of Cycle | Flex/Ext | Int/Ext | Ad/Ab | Flex/Ext | Int/Ext | Ad/Ab | Flex/Ext | Int/Ext | Ad/Ab |
| 0 | 0.5995 | 0.1550 | 0.0328 | 0.3205 | 0.0197 | 0.0719 | 0.0812 | 0.0031 | 0.9716 |
| 1 | 0.7404 | 0.1528 | 0.0309 | 0.3091 | 0.0170 | 0.0885 | 0.0851 | 0.0027 | 0.9431 |
| 2 | 0.7563 | 0.1361 | 0.0459 | 0.2763 | 0.0145 | 0.1049 | 0.0705 | 0.0026 | 0.9155 |
| 3 | 0.7473 | 0.1213 | 0.0615 | 0.2394 | 0.0126 | 0.1120 | 0.0576 | 0.0028 | 0.8982 |
| 4 | 0.7322 | 0.1166 | 0.0769 | 0.2024 | 0.0113 | 0.1144 | 0.0431 | 0.0031 | 0.8637 |
| 5 | 0.6869 | 0.1168 | 0.1032 | 0.1587 | 0.0096 | 0.1105 | 0.0301 | 0.0034 | 0.8164 |
| 6 | 0.6341 | 0.1306 | 0.1454 | 0.1185 | 0.0080 | 0.1041 | 0.0209 | 0.0039 | 0.7753 |
| 7 | 0.5873 | 0.1521 | 0.2082 | 0.0844 | 0.0066 | 0.1034 | 0.0138 | 0.0039 | 0.7545 |
| 8 | 0.5892 | 0.1689 | 0.2751 | 0.0595 | 0.0054 | 0.1081 | 0.0086 | 0.0036 | 0.7365 |
| 9 | 0.5816 | 0.1920 | 0.3555 | 0.0430 | 0.0042 | 0.1106 | 0.0044 | 0.0027 | 0.7335 |
| 10 | 0.5440 | 0.2237 | 0.4464 | 0.0304 | 0.0034 | 0.1095 | 0.0025 | 0.0021 | 0.7315 |
| 11 | 0.5211 | 0.2529 | 0.5271 | 0.0206 | 0.0026 | 0.1079 | 0.0014 | 0.0018 | 0.7421 |
| 12 | 0.5107 | 0.2519 | 0.5790 | 0.0142 | 0.0018 | 0.1083 | 0.0008 | 0.0017 | 0.7412 |
| 13 | 0.5272 | 0.2263 | 0.6237 | 0.0102 | 0.0012 | 0.1029 | 0.0004 | 0.0018 | 0.7475 |
| 14 | 0.5310 | 0.2147 | 0.6464 | 0.0079 | 0.0008 | 0.0958 | 0.0002 | 0.0020 | 0.7726 |
| 15 | 0.5077 | 0.2275 | 0.6504 | 0.0056 | 0.0007 | 0.0904 | 0.0001 | 0.0019 | 0.8361 |
| 16 | 0.4949 | 0.2573 | 0.6457 | 0.0039 | 0.0008 | 0.0861 | 0.0000 | 0.0016 | 0.8799 |
| 17 | 0.5228 | 0.2761 | 0.6259 | 0.0029 | 0.0008 | 0.0814 | 0.0000 | 0.0012 | 0.9273 |
| 18 | 0.5332 | 0.2814 | 0.6293 | 0.0021 | 0.0008 | 0.0776 | 0.0000 | 0.0010 | 0.9460 |
| 19 | 0.5224 | 0.2747 | 0.6868 | 0.0018 | 0.0007 | 0.0770 | 0.0000 | 0.0012 | 0.9473 |
| 20 | 0.5088 | 0.2942 | 0.7570 | 0.0016 | 0.0007 | 0.0758 | 0.0000 | 0.0013 | 0.9633 |
| 21 | 0.5334 | 0.3299 | 0.8069 | 0.0013 | 0.0007 | 0.0728 | 0.0000 | 0.0013 | 0.9949 |
| 22 | 0.5509 | 0.3788 | 0.8228 | 0.0011 | 0.0006 | 0.0716 | 0.0000 | 0.0010 | 0.9756 |
| 23 | 0.5454 | 0.3992 | 0.8304 | 0.0011 | 0.0005 | 0.0689 | 0.0000 | 0.0011 | 0.9292 |
| 24 | 0.5334 | 0.3895 | 0.8691 | 0.0011 | 0.0004 | 0.0680 | 0.0000 | 0.0012 | 0.8916 |
| 25 | 0.5298 | 0.3924 | 0.9029 | 0.0010 | 0.0003 | 0.0666 | 0.0000 | 0.0013 | 0.8597 |
| 26 | 0.5172 | 0.4205 | 0.9211 | 0.0010 | 0.0002 | 0.0668 | 0.0000 | 0.0012 | 0.8481 |
| 27 | 0.5259 | 0.4397 | 0.9267 | 0.0010 | 0.0002 | 0.0707 | 0.0000 | 0.0010 | 0.8838 |
| 28 | 0.5351 | 0.4573 | 0.9236 | 0.0010 | 0.0001 | 0.0732 | 0.0000 | 0.0008 | 0.9341 |
| 29 | 0.5497 | 0.4792 | 0.9370 | 0.0011 | 0.0001 | 0.0756 | 0.0000 | 0.0008 | 0.9736 |
| 30 | 0.5463 | 0.5247 | 0.9624 | 0.0011 | 0.0001 | 0.0751 | 0.0000 | 0.0008 | 0.9861 |
| 31 | 0.5578 | 0.5694 | 0.9924 | 0.0011 | 0.0001 | 0.0806 | 0.0000 | 0.0007 | 0.9938 |
| 32 | 0.5655 | 0.6080 | 0.9399 | 0.0011 | 0.0001 | 0.0886 | 0.0000 | 0.0006 | 0.9584 |


| 33 | 0.5726 | 0.6354 | 0.9051 | 0.0011 | 0.0001 | 0.1018 | 0.0000 | 0.0006 | 0.9169 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 34 | 0.5727 | 0.6748 | 0.8774 | 0.0012 | 0.0001 | 0.1164 | 0.0000 | 0.0006 | 0.8705 |
| 35 | 0.5766 | 0.7319 | 0.8662 | 0.0012 | 0.0001 | 0.1321 | 0.0000 | 0.0007 | 0.8305 |
| 36 | 0.5966 | 0.7727 | 0.8531 | 0.0013 | 0.0001 | 0.1481 | 0.0000 | 0.0008 | 0.8031 |
| 37 | 0.5956 | 0.7975 | 0.8382 | 0.0014 | 0.0000 | 0.1715 | 0.0000 | 0.0010 | 0.7890 |
| 38 | 0.5988 | 0.8002 | 0.8179 | 0.0015 | 0.0000 | 0.1915 | 0.0000 | 0.0012 | 0.7815 |
| 39 | 0.6001 | 0.8064 | 0.8058 | 0.0015 | 0.0001 | 0.2138 | 0.0000 | 0.0015 | 0.7697 |
| 40 | 0.6036 | 0.8107 | 0.7955 | 0.0016 | 0.0001 | 0.2312 | 0.0000 | 0.0018 | 0.7461 |
| 41 | 0.6157 | 0.8212 | 0.7923 | 0.0017 | 0.0001 | 0.2394 | 0.0000 | 0.0021 | 0.7291 |
| 42 | 0.6370 | 0.8242 | 0.7739 | 0.0018 | 0.0001 | 0.2428 | 0.0000 | 0.0022 | 0.7151 |
| 43 | 0.6532 | 0.8201 | 0.7495 | 0.0020 | 0.0001 | 0.2499 | 0.0000 | 0.0024 | 0.6963 |
| 44 | 0.6647 | 0.8123 | 0.7240 | 0.0020 | 0.0001 | 0.2553 | 0.0000 | 0.0028 | 0.6847 |
| 45 | 0.6799 | 0.8028 | 0.7194 | 0.0021 | 0.0001 | 0.2585 | 0.0000 | 0.0033 | 0.6881 |
| 46 | 0.6971 | 0.7889 | 0.7087 | 0.0021 | 0.0001 | 0.2727 | 0.0000 | 0.0039 | 0.6906 |
| 47 | 0.7162 | 0.7710 | 0.6987 | 0.0023 | 0.0001 | 0.2952 | 0.0000 | 0.0045 | 0.6769 |
| 48 | 0.7385 | 0.7529 | 0.6937 | 0.0023 | 0.0001 | 0.3134 | 0.0000 | 0.0049 | 0.6559 |
| 49 | 0.7632 | 0.7385 | 0.6826 | 0.0023 | 0.0001 | 0.3292 | 0.0000 | 0.0053 | 0.6329 |
| 50 | 0.7817 | 0.7362 | 0.6797 | 0.0023 | 0.0001 | 0.3453 | 0.0000 | 0.0057 | 0.6114 |
| 51 | 0.7965 | 0.7358 | 0.6854 | 0.0022 | 0.0001 | 0.3532 | 0.0000 | 0.0064 | 0.6043 |
| 52 | 0.8144 | 0.7334 | 0.6838 | 0.0022 | 0.0001 | 0.3580 | 0.0000 | 0.0071 | 0.6039 |
| 53 | 0.8355 | 0.7151 | 0.6791 | 0.0021 | 0.0001 | 0.3604 | 0.0000 | 0.0075 | 0.6126 |
| 54 | 0.8558 | 0.6998 | 0.6758 | 0.0020 | 0.0001 | 0.3581 | 0.0000 | 0.0080 | 0.6255 |
| 55 | 0.8681 | 0.6821 | 0.6675 | 0.0019 | 0.0001 | 0.3580 | 0.0000 | 0.0083 | 0.6349 |
| 56 | 0.8773 | 0.6636 | 0.6621 | 0.0017 | 0.0001 | 0.3599 | 0.0000 | 0.0084 | 0.6386 |
| 57 | 0.8855 | 0.6466 | 0.6613 | 0.0016 | 0.0001 | 0.3689 | 0.0000 | 0.0085 | 0.6385 |
| 58 | 0.8959 | 0.6289 | 0.6641 | 0.0015 | 0.0001 | 0.3720 | 0.0000 | 0.0089 | 0.6372 |
| 59 | 0.9141 | 0.6126 | 0.6595 | 0.0013 | 0.0001 | 0.3779 | 0.0000 | 0.0096 | 0.6300 |
| 60 | 0.9241 | 0.5933 | 0.6577 | 0.0012 | 0.0001 | 0.3843 | 0.0000 | 0.0104 | 0.6229 |
| 61 | 0.9301 | 0.5764 | 0.6569 | 0.0011 | 0.0001 | 0.3840 | 0.0000 | 0.0110 | 0.6230 |
| 62 | 0.9400 | 0.5532 | 0.6644 | 0.0010 | 0.0001 | 0.3804 | 0.0000 | 0.0117 | 0.6264 |
| 63 | 0.9602 | 0.5311 | 0.6663 | 0.0008 | 0.0001 | 0.3701 | 0.0000 | 0.0129 | 0.6304 |
| 64 | 0.9820 | 0.5060 | 0.6762 | 0.0007 | 0.0001 | 0.3606 | 0.0000 | 0.0137 | 0.6336 |
| 65 | 0.9997 | 0.4804 | 0.6953 | 0.0007 | 0.0001 | 0.3355 | 0.0000 | 0.0135 | 0.6492 |
| 66 | 0.9787 | 0.4512 | 0.7195 | 0.0006 | 0.0001 | 0.3048 | 0.0000 | 0.0128 | 0.6771 |
| 67 | 0.9666 | 0.4210 | 0.7401 | 0.0005 | 0.0001 | 0.2788 | 0.0000 | 0.0119 | 0.6970 |
| 68 | 0.9534 | 0.3939 | 0.7597 | 0.0005 | 0.0001 | 0.2591 | 0.0000 | 0.0112 | 0.7156 |
| 69 | 0.9329 | 0.3692 | 0.7808 | 0.0005 | 0.0001 | 0.2388 | 0.0000 | 0.0106 | 0.7341 |
| 70 | 0.9080 | 0.3426 | 0.8000 | 0.0004 | 0.0001 | 0.2113 | 0.0000 | 0.0098 | 0.7583 |
| 71 | 0.9050 | 0.3217 | 0.8110 | 0.0004 | 0.0001 | 0.1850 | 0.0000 | 0.0095 | 0.7836 |
| 72 | 0.8934 | 0.3020 | 0.8279 | 0.0004 | 0.0001 | 0.1561 | 0.0000 | 0.0086 | 0.8138 |
| 73 | 0.8711 | 0.2734 | 0.8788 | 0.0004 | 0.0002 | 0.1318 | 0.0000 | 0.0073 | 0.8512 |
| 74 | 0.8529 | 0.2297 | 0.9447 | 0.0004 | 0.0002 | 0.1072 | 0.0000 | 0.0063 | 0.8818 |
| 75 | 0.8622 | 0.1901 | 0.9852 | 0.0003 | 0.0002 | 0.0896 | 0.0000 | 0.0056 | 0.8981 |


| $\mathbf{7 6}$ | 0.8921 | 0.1587 | 0.9868 | 0.0003 | 0.0002 | 0.0800 | 0.0000 | 0.0051 | 0.9112 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathbf{7 7}$ | 0.8806 | 0.1350 | 0.9403 | 0.0004 | 0.0003 | 0.0734 | 0.0000 | 0.0045 | 0.9259 |
| $\mathbf{7 8}$ | 0.8903 | 0.1083 | 0.8864 | 0.0004 | 0.0003 | 0.0679 | 0.0000 | 0.0038 | 0.9531 |
| $\mathbf{7 9}$ | 0.9032 | 0.0821 | 0.8384 | 0.0004 | 0.0003 | 0.0589 | 0.0000 | 0.0032 | 0.9827 |
| $\mathbf{8 0}$ | 0.9149 | 0.0614 | 0.7872 | 0.0004 | 0.0003 | 0.0529 | 0.0000 | 0.0026 | 0.9991 |
| $\mathbf{8 1}$ | 0.9409 | 0.0452 | 0.7379 | 0.0005 | 0.0003 | 0.0488 | 0.0000 | 0.0023 | 0.9883 |
| $\mathbf{8 2}$ | 0.9556 | 0.0305 | 0.6758 | 0.0007 | 0.0003 | 0.0478 | 0.0000 | 0.0021 | 0.9863 |
| $\mathbf{8 3}$ | 0.9807 | 0.0230 | 0.6243 | 0.0008 | 0.0003 | 0.0469 | 0.0001 | 0.0018 | 0.9962 |
| $\mathbf{8 4}$ | 0.9866 | 0.0212 | 0.5643 | 0.0009 | 0.0003 | 0.0466 | 0.0001 | 0.0015 | 0.9795 |
| $\mathbf{8 5}$ | 0.9866 | 0.0217 | 0.5053 | 0.0009 | 0.0004 | 0.0462 | 0.0001 | 0.0013 | 0.9807 |
| $\mathbf{8 6}$ | 0.9450 | 0.0226 | 0.4543 | 0.0014 | 0.0005 | 0.0475 | 0.0002 | 0.0012 | 0.9598 |
| $\mathbf{8 7}$ | 0.8924 | 0.0248 | 0.4026 | 0.0022 | 0.0006 | 0.0498 | 0.0004 | 0.0011 | 0.9164 |
| $\mathbf{8 8}$ | 0.9097 | 0.0241 | 0.3464 | 0.0030 | 0.0007 | 0.0518 | 0.0005 | 0.0010 | 0.8811 |
| $\mathbf{8 9}$ | 0.9020 | 0.0236 | 0.2939 | 0.0038 | 0.0008 | 0.0536 | 0.0008 | 0.0009 | 0.8636 |
| $\mathbf{9 0}$ | 0.8670 | 0.0245 | 0.2613 | 0.0056 | 0.0008 | 0.0587 | 0.0014 | 0.0008 | 0.8418 |
| $\mathbf{9 1}$ | 0.8030 | 0.0276 | 0.2490 | 0.0094 | 0.0009 | 0.0658 | 0.0023 | 0.0008 | 0.8000 |
| $\mathbf{9 2}$ | 0.7930 | 0.0305 | 0.2269 | 0.0169 | 0.0013 | 0.0706 | 0.0037 | 0.0009 | 0.7686 |
| $\mathbf{9 3}$ | 0.7893 | 0.0322 | 0.2000 | 0.0290 | 0.0019 | 0.0759 | 0.0061 | 0.0012 | 0.7744 |
| $\mathbf{9 4}$ | 0.7728 | 0.0338 | 0.1655 | 0.0450 | 0.0028 | 0.0839 | 0.0100 | 0.0014 | 0.7859 |
| $\mathbf{9 5}$ | 0.7333 | 0.0376 | 0.1340 | 0.0673 | 0.0040 | 0.0887 | 0.0167 | 0.0015 | 0.8006 |
| $\mathbf{9 6}$ | 0.7003 | 0.0434 | 0.0990 | 0.1024 | 0.0054 | 0.0903 | 0.0261 | 0.0016 | 0.8189 |
| $\mathbf{9 7}$ | 0.7045 | 0.0471 | 0.0719 | 0.1580 | 0.0067 | 0.0923 | 0.0410 | 0.0016 | 0.8157 |
| $\mathbf{9 8}$ | 0.7004 | 0.0521 | 0.0557 | 0.2214 | 0.0077 | 0.0975 | 0.0588 | 0.0018 | 0.7942 |
| $\mathbf{9 9}$ | 0.6973 | 0.0592 | 0.0482 | 0.2813 | 0.0088 | 0.1055 | 0.0782 | 0.0024 | 0.7818 |
| $\mathbf{1 0 0}$ | 0.6997 | 0.0657 | 0.0370 | 0.3228 | 0.0101 | 0.1165 | 0.0904 | 0.0033 | 0.7824 |

Table 6. Summary of p-values for flexion-extension, internal-external, and abduction-adduction rotation angles during posteromedial Y-balance task for bilateral control (LR), ACLd, and PFP populations.

Table 7 summarizes the p-values during the posterolateral Y-balance task for all participant groups.

|  | LR |  |  | ACLd |  |  | PFP |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| \% of <br> Cycle | Flex/Ext | Int/Ext | Ad/Ab | Flex/Ext | Int/Ext | Ad/Ab | Flex/Ext | Int/Ext | Ad/Ab |
| $\mathbf{0}$ | 0.8878 | 0.1059 | 0.0778 | 0.4141 | 0.0174 | 0.2465 | 0.0497 | 0.0064 | 0.3107 |
| $\mathbf{1}$ | 0.8478 | 0.1541 | 0.0805 | 0.4108 | 0.0228 | 0.2453 | 0.0406 | 0.0072 | 0.3018 |
| $\mathbf{2}$ | 0.8775 | 0.1584 | 0.0904 | 0.3476 | 0.0288 | 0.2200 | 0.0281 | 0.0078 | 0.2947 |
| $\mathbf{3}$ | 0.9400 | 0.1563 | 0.1130 | 0.2861 | 0.0333 | 0.1950 | 0.0168 | 0.0088 | 0.3027 |
| $\mathbf{4}$ | 0.9929 | 0.1656 | 0.1416 | 0.2332 | 0.0363 | 0.1754 | 0.0092 | 0.0110 | 0.3327 |
| $\mathbf{5}$ | 0.9379 | 0.1804 | 0.1914 | 0.1827 | 0.0380 | 0.1503 | 0.0044 | 0.0138 | 0.3866 |
| $\mathbf{6}$ | 0.8808 | 0.1990 | 0.2603 | 0.1392 | 0.0370 | 0.1272 | 0.0020 | 0.0152 | 0.4384 |
| $\mathbf{7}$ | 0.8429 | 0.2287 | 0.3329 | 0.1066 | 0.0364 | 0.1106 | 0.0009 | 0.0153 | 0.4816 |


| 8 | 0.8294 | 0.2530 | 0.3939 | 0.0779 | 0.0381 | 0.0925 | 0.0003 | 0.0168 | 0.5428 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 9 | 0.8522 | 0.2580 | 0.4669 | 0.0591 | 0.0393 | 0.0797 | 0.0001 | 0.0181 | 0.6054 |
| 10 | 0.8431 | 0.2683 | 0.5465 | 0.0446 | 0.0414 | 0.0660 | 0.0001 | 0.0195 | 0.6615 |
| 11 | 0.8418 | 0.2893 | 0.5802 | 0.0360 | 0.0414 | 0.0545 | 0.0000 | 0.0194 | 0.7149 |
| 12 | 0.8431 | 0.2903 | 0.5662 | 0.0277 | 0.0421 | 0.0459 | 0.0000 | 0.0193 | 0.7851 |
| 13 | 0.8357 | 0.2727 | 0.5691 | 0.0230 | 0.0452 | 0.0395 | 0.0000 | 0.0193 | 0.8510 |
| 14 | 0.8749 | 0.2703 | 0.5436 | 0.0212 | 0.0519 | 0.0321 | 0.0000 | 0.0197 | 0.9310 |
| 15 | 0.8914 | 0.2813 | 0.5268 | 0.0189 | 0.0576 | 0.0238 | 0.0000 | 0.0199 | 0.9888 |
| 16 | 0.9194 | 0.3250 | 0.5405 | 0.0168 | 0.0599 | 0.0177 | 0.0000 | 0.0225 | 0.9153 |
| 17 | 0.9402 | 0.3829 | 0.5522 | 0.0148 | 0.0619 | 0.0135 | 0.0000 | 0.0249 | 0.8623 |
| 18 | 0.9443 | 0.3961 | 0.5600 | 0.0140 | 0.0611 | 0.0110 | 0.0000 | 0.0273 | 0.7847 |
| 19 | 0.9838 | 0.3591 | 0.5899 | 0.0138 | 0.0582 | 0.0099 | 0.0000 | 0.0266 | 0.7239 |
| 20 | 0.9893 | 0.3593 | 0.6454 | 0.0127 | 0.0502 | 0.0095 | 0.0000 | 0.0249 | 0.6928 |
| 21 | 0.9732 | 0.3727 | 0.6821 | 0.0120 | 0.0408 | 0.0094 | 0.0000 | 0.0239 | 0.6738 |
| 22 | 0.9704 | 0.4057 | 0.7168 | 0.0111 | 0.0339 | 0.0085 | 0.0000 | 0.0261 | 0.6335 |
| 23 | 0.9824 | 0.4330 | 0.7556 | 0.0106 | 0.0304 | 0.0079 | 0.0000 | 0.0284 | 0.5752 |
| 24 | 0.9773 | 0.4439 | 0.7894 | 0.0097 | 0.0284 | 0.0073 | 0.0000 | 0.0307 | 0.5318 |
| 25 | 0.9980 | 0.4452 | 0.8144 | 0.0099 | 0.0262 | 0.0076 | 0.0000 | 0.0279 | 0.5286 |
| 26 | 0.9949 | 0.4743 | 0.8273 | 0.0107 | 0.0234 | 0.0087 | 0.0000 | 0.0260 | 0.5371 |
| 27 | 0.9804 | 0.5043 | 0.8301 | 0.0105 | 0.0206 | 0.0095 | 0.0000 | 0.0225 | 0.5649 |
| 28 | 0.9488 | 0.5148 | 0.8501 | 0.0095 | 0.0195 | 0.0094 | 0.0000 | 0.0196 | 0.5756 |
| 29 | 0.9418 | 0.4984 | 0.8882 | 0.0099 | 0.0193 | 0.0092 | 0.0000 | 0.0168 | 0.5807 |
| 30 | 0.9188 | 0.4364 | 0.9337 | 0.0108 | 0.0183 | 0.0093 | 0.0000 | 0.0152 | 0.5636 |
| 31 | 0.8953 | 0.3693 | 0.9558 | 0.0113 | 0.0165 | 0.0090 | 0.0000 | 0.0138 | 0.5362 |
| 32 | 0.8832 | 0.3443 | 0.9618 | 0.0113 | 0.0146 | 0.0085 | 0.0000 | 0.0121 | 0.5077 |
| 33 | 0.8878 | 0.3414 | 0.9993 | 0.0113 | 0.0130 | 0.0086 | 0.0000 | 0.0100 | 0.5118 |
| 34 | 0.8892 | 0.3649 | 0.9578 | 0.0118 | 0.0113 | 0.0089 | 0.0000 | 0.0085 | 0.5283 |
| 35 | 0.8839 | 0.3867 | 0.9379 | 0.0123 | 0.0087 | 0.0099 | 0.0000 | 0.0081 | 0.5431 |
| 36 | 0.8784 | 0.3916 | 0.9220 | 0.0128 | 0.0066 | 0.0107 | 0.0000 | 0.0080 | 0.5559 |
| 37 | 0.8875 | 0.3902 | 0.9026 | 0.0128 | 0.0052 | 0.0109 | 0.0000 | 0.0084 | 0.5516 |
| 38 | 0.8800 | 0.4066 | 0.8782 | 0.0124 | 0.0047 | 0.0106 | 0.0000 | 0.0088 | 0.5373 |
| 39 | 0.8922 | 0.4243 | 0.8510 | 0.0122 | 0.0040 | 0.0104 | 0.0000 | 0.0087 | 0.5389 |
| 40 | 0.9032 | 0.4358 | 0.8426 | 0.0123 | 0.0036 | 0.0103 | 0.0000 | 0.0086 | 0.5502 |
| 41 | 0.9334 | 0.4445 | 0.8349 | 0.0123 | 0.0033 | 0.0096 | 0.0000 | 0.0080 | 0.5585 |
| 42 | 0.9477 | 0.4394 | 0.8332 | 0.0122 | 0.0030 | 0.0092 | 0.0000 | 0.0076 | 0.5774 |
| 43 | 0.9655 | 0.4225 | 0.8243 | 0.0119 | 0.0025 | 0.0094 | 0.0000 | 0.0075 | 0.6033 |
| 44 | 0.9808 | 0.4003 | 0.8042 | 0.0118 | 0.0021 | 0.0101 | 0.0000 | 0.0078 | 0.6287 |
| 45 | 0.9958 | 0.3947 | 0.7952 | 0.0118 | 0.0017 | 0.0110 | 0.0001 | 0.0083 | 0.6456 |
| 46 | 0.9758 | 0.3967 | 0.8023 | 0.0117 | 0.0016 | 0.0115 | 0.0001 | 0.0087 | 0.6456 |
| 47 | 0.9644 | 0.3912 | 0.8061 | 0.0112 | 0.0015 | 0.0116 | 0.0001 | 0.0088 | 0.6443 |
| 48 | 0.9614 | 0.3817 | 0.7943 | 0.0107 | 0.0015 | 0.0117 | 0.0001 | 0.0087 | 0.6487 |
| 49 | 0.9653 | 0.3749 | 0.7800 | 0.0101 | 0.0015 | 0.0126 | 0.0001 | 0.0084 | 0.6519 |
| 50 | 0.9597 | 0.3807 | 0.7711 | 0.0095 | 0.0014 | 0.0135 | 0.0001 | 0.0083 | 0.6612 |


| 51 | 0.9586 | 0.3933 | 0.7508 | 0.0092 | 0.0013 | 0.0150 | 0.0001 | 0.0080 | 0.6787 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 52 | 0.9631 | 0.3995 | 0.7305 | 0.0086 | 0.0014 | 0.0158 | 0.0001 | 0.0076 | 0.7010 |
| 53 | 0.9622 | 0.4050 | 0.7207 | 0.0080 | 0.0014 | 0.0162 | 0.0001 | 0.0068 | 0.7210 |
| 54 | 0.9522 | 0.4069 | 0.7313 | 0.0073 | 0.0014 | 0.0160 | 0.0001 | 0.0059 | 0.7370 |
| 55 | 0.9421 | 0.4253 | 0.7367 | 0.0067 | 0.0014 | 0.0154 | 0.0001 | 0.0049 | 0.7438 |
| 56 | 0.9334 | 0.4446 | 0.7283 | 0.0061 | 0.0015 | 0.0148 | 0.0001 | 0.0043 | 0.7482 |
| 57 | 0.9309 | 0.4622 | 0.7325 | 0.0055 | 0.0016 | 0.0139 | 0.0001 | 0.0040 | 0.7416 |
| 58 | 0.9239 | 0.4670 | 0.7383 | 0.0049 | 0.0016 | 0.0127 | 0.0001 | 0.0038 | 0.7422 |
| 59 | 0.9184 | 0.4777 | 0.7467 | 0.0044 | 0.0017 | 0.0119 | 0.0001 | 0.0036 | 0.7483 |
| 60 | 0.9067 | 0.4951 | 0.7567 | 0.0038 | 0.0017 | 0.0107 | 0.0001 | 0.0034 | 0.7571 |
| 61 | 0.8990 | 0.5192 | 0.7690 | 0.0034 | 0.0019 | 0.0096 | 0.0001 | 0.0033 | 0.7586 |
| 62 | 0.9001 | 0.5395 | 0.7800 | 0.0030 | 0.0020 | 0.0086 | 0.0001 | 0.0033 | 0.7638 |
| 63 | 0.8919 | 0.5561 | 0.7887 | 0.0026 | 0.0020 | 0.0078 | 0.0002 | 0.0032 | 0.7769 |
| 64 | 0.8925 | 0.5519 | 0.7963 | 0.0023 | 0.0020 | 0.0069 | 0.0002 | 0.0031 | 0.7960 |
| 65 | 0.8916 | 0.5578 | 0.8021 | 0.0021 | 0.0021 | 0.0063 | 0.0001 | 0.0030 | 0.7996 |
| 66 | 0.8864 | 0.5706 | 0.8204 | 0.0021 | 0.0023 | 0.0058 | 0.0001 | 0.0031 | 0.7988 |
| 67 | 0.8792 | 0.5704 | 0.8399 | 0.0020 | 0.0024 | 0.0053 | 0.0001 | 0.0033 | 0.7896 |
| 68 | 0.8608 | 0.5590 | 0.8512 | 0.0017 | 0.0024 | 0.0047 | 0.0001 | 0.0034 | 0.7793 |
| 69 | 0.8795 | 0.5371 | 0.8712 | 0.0016 | 0.0022 | 0.0042 | 0.0001 | 0.0035 | 0.7629 |
| 70 | 0.8986 | 0.5264 | 0.8955 | 0.0014 | 0.0021 | 0.0039 | 0.0001 | 0.0040 | 0.7594 |
| 71 | 0.8913 | 0.5169 | 0.9264 | 0.0014 | 0.0019 | 0.0040 | 0.0000 | 0.0045 | 0.7636 |
| 72 | 0.8711 | 0.4820 | 0.9630 | 0.0014 | 0.0019 | 0.0043 | 0.0000 | 0.0051 | 0.7680 |
| 73 | 0.8793 | 0.4615 | 0.9849 | 0.0014 | 0.0020 | 0.0049 | 0.0000 | 0.0060 | 0.7640 |
| 74 | 0.8728 | 0.4457 | 0.9430 | 0.0014 | 0.0024 | 0.0053 | 0.0000 | 0.0072 | 0.7690 |
| 75 | 0.8677 | 0.4216 | 0.9318 | 0.0014 | 0.0027 | 0.0059 | 0.0000 | 0.0088 | 0.7788 |
| 76 | 0.8620 | 0.3694 | 0.9198 | 0.0014 | 0.0028 | 0.0065 | 0.0000 | 0.0101 | 0.7936 |
| 77 | 0.8814 | 0.3211 | 0.8897 | 0.0014 | 0.0029 | 0.0073 | 0.0000 | 0.0109 | 0.7980 |
| 78 | 0.8818 | 0.3001 | 0.8566 | 0.0015 | 0.0031 | 0.0077 | 0.0000 | 0.0117 | 0.7969 |
| 79 | 0.8889 | 0.2951 | 0.8227 | 0.0015 | 0.0035 | 0.0079 | 0.0000 | 0.0120 | 0.8034 |
| 80 | 0.8927 | 0.2888 | 0.7879 | 0.0016 | 0.0040 | 0.0079 | 0.0000 | 0.0131 | 0.8190 |
| 81 | 0.8891 | 0.2795 | 0.7514 | 0.0019 | 0.0045 | 0.0084 | 0.0000 | 0.0137 | 0.8556 |
| 82 | 0.8620 | 0.2661 | 0.7090 | 0.0022 | 0.0044 | 0.0100 | 0.0000 | 0.0134 | 0.8959 |
| 83 | 0.8345 | 0.2648 | 0.6628 | 0.0024 | 0.0046 | 0.0117 | 0.0000 | 0.0127 | 0.9415 |
| 84 | 0.8414 | 0.2584 | 0.6098 | 0.0026 | 0.0051 | 0.0141 | 0.0000 | 0.0121 | 0.9777 |
| 85 | 0.8385 | 0.2492 | 0.5615 | 0.0033 | 0.0061 | 0.0171 | 0.0000 | 0.0129 | 0.9683 |
| 86 | 0.8179 | 0.2270 | 0.5103 | 0.0040 | 0.0069 | 0.0209 | 0.0000 | 0.0141 | 0.9564 |
| 87 | 0.7880 | 0.1972 | 0.4567 | 0.0049 | 0.0076 | 0.0248 | 0.0000 | 0.0151 | 0.9366 |
| 88 | 0.7456 | 0.1755 | 0.4178 | 0.0058 | 0.0082 | 0.0305 | 0.0000 | 0.0162 | 0.8980 |
| 89 | 0.7573 | 0.1570 | 0.3473 | 0.0073 | 0.0094 | 0.0357 | 0.0000 | 0.0172 | 0.8608 |
| 90 | 0.7461 | 0.1418 | 0.2979 | 0.0113 | 0.0104 | 0.0442 | 0.0000 | 0.0173 | 0.8249 |
| 91 | 0.7820 | 0.1307 | 0.2772 | 0.0179 | 0.0115 | 0.0509 | 0.0001 | 0.0163 | 0.7920 |
| 92 | 0.7917 | 0.1343 | 0.2739 | 0.0260 | 0.0117 | 0.0558 | 0.0002 | 0.0144 | 0.7635 |
| 93 | 0.8037 | 0.1478 | 0.2554 | 0.0367 | 0.0116 | 0.0607 | 0.0003 | 0.0121 | 0.7276 |


| $\mathbf{9 4}$ | 0.8393 | 0.1707 | 0.2243 | 0.0544 | 0.0107 | 0.0653 | 0.0009 | 0.0099 | 0.6821 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathbf{9 5}$ | 0.8970 | 0.1897 | 0.1837 | 0.0868 | 0.0101 | 0.0740 | 0.0028 | 0.0085 | 0.6200 |
| $\mathbf{9 6}$ | 0.9479 | 0.1884 | 0.1487 | 0.1322 | 0.0101 | 0.0809 | 0.0065 | 0.0076 | 0.5673 |
| $\mathbf{9 7}$ | 0.9728 | 0.1707 | 0.1336 | 0.1879 | 0.0092 | 0.0851 | 0.0114 | 0.0063 | 0.5415 |
| $\mathbf{9 8}$ | 0.9277 | 0.1667 | 0.1273 | 0.2604 | 0.0079 | 0.0868 | 0.0200 | 0.0050 | 0.5258 |
| $\mathbf{9 9}$ | 0.9061 | 0.1760 | 0.1046 | 0.3434 | 0.0073 | 0.0840 | 0.0345 | 0.0043 | 0.5342 |
| $\mathbf{1 0 0}$ | 0.8714 | 0.1616 | 0.0811 | 0.4303 | 0.0063 | 0.0855 | 0.0553 | 0.0034 | 0.5401 |

Table 7. Summary of p-values for flexion-extension, internal-external, and abduction-adduction rotation angles during posterolateral Y-balance task for bilateral control (LR), ACLd, and PFP populations.

## Bilateral Differences in Control Data

During the posteromedial Y-balance task significant differences ( $\mathrm{p}<0.05$ ) were observed for internal-external rotation between 81-97\% and for abduction-adduction between 0-3\% and at $99 \%$ of the cycle. There were no significant differences observed during the posterolateral Ybalance task. One control participant data set had to be excluded for reasons mentioned in Section 4.1.

## ACLd Group Posteromedial

Data from the posteromedial Y-balance shows an increase in external rotation for $100 \%$ of the cycle, an increase in abduction rotation for $82-88 \%$ of the cycle, and an increase in flexion for 994\% of the cycle for ACLd participants compared to controls. Two ACLd participant data sets were excluded for reasons mentioned in Section 4.1.


Figure 9. Rotation angles during posteromedial Y-balance for ACLd group. (a) Flexionextension. Significantly lower ACLd flexion rotation between 9-94\% (b) Internal-external. Significantly less ACLd internal rotation for $100 \%$ of the cycle. (c) Abduction-adduction. Significantly less ACLd adduction rotation between 82-88\%. Shaded regions indicate areas of significant differences.

## ACLd Group Posterolateral

Data from the posterolateral Y-balance shows an increase in external rotation for $93 \%$ of the cycle, an increase in abduction rotation between $12-90 \%$ of the cycle, and an increase in flexion
from 10-93\% of the cycle for ACLd participants compared to controls. Two ACL participant data sets were excluded for reasons mentioned in Section 4.1.


Figure 10. Rotation angles during posterolateral Y-balance for ACLd group. (a) Flexionextension. Significantly lower ACLd flexion rotation between 10-93\% (b) Internal-external. Significantly more ACLd external rotation between $0-13 \%$ and $21-100 \%$ of the cycle. (c) Abduction-adduction. Significantly less ACLd adduction rotation between 12-90\%. Shaded regions indicate areas of significant differences.

## PFP Group Posteromedial

Data from the posteromedial Y-balance shows an increase in external rotation for $100 \%$ of the cycle and an increase in flexion for $4-97 \%$ of the cycle for PFP participants compared to controls. There were no significant differences in abduction-adduction rotation angles. Two ACL participant data sets had to be excluded due to unclear cycle definitions. One PFP participant data set was excluded for reasons mentioned in Section 4.1.


Figure 11. Rotation angles during posteromedial Y-balance for PFP group. (a) Flexion-extension. Significantly lower PFP flexion rotation between 4-97\% (b) Internal-external. Significantly less PFP internal rotation for $100 \%$ of the cycle. (c) Abduction-adduction. Shaded regions indicate areas of significant differences.

PFP Group Posterolateral

Data from the posterolateral Y-balance shows an increase in external rotation for $100 \%$ of the cycle and an increase in flexion from $0-99 \%$ of the cycle for PFP participants compared to
controls. There were no significant differences in abduction-adduction rotation angles. One PFP participant data set was excluded for reasons mentioned in Section 4.1.


Figure 12. Rotation angles during posterolateral Y-balance for PFP group. (a) Flexion-extension. Significantly lower PFP flexion rotation between 0-99\%\% of the cycle. (b) Internal-external.
Significantly more PFP external rotation for $100 \%$ of the cycle. (c) Abduction-adduction. Shaded regions indicate areas of significant differences.

### 4.1.5 Medial and lateral single leg squats

Table 8 summarizes the p-values during the medial SLS task for all participant groups.

|  | LR |  |  | ACLd |  |  | PFP |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| \% of Cycle | Flex/Ext | Int/Ext | Ad/Ab | Flex/Ext | Int/Ext | Ad/Ab | Flex/Ext | Int/Ext | Ad/Ab |
| 0 | 0.6231 | 0.5194 | 0.7170 | 0.0424 | 0.0004 | 0.0963 | 0.0064 | 0.0605 | 0.7339 |
| 1 | 0.6529 | 0.4747 | 0.6780 | 0.0398 | 0.0003 | 0.1145 | 0.0048 | 0.0505 | 0.7306 |
| 2 | 0.6755 | 0.4472 | 0.6811 | 0.0280 | 0.0003 | 0.1411 | 0.0028 | 0.0427 | 0.7088 |
| 3 | 0.6953 | 0.4253 | 0.6917 | 0.0218 | 0.0003 | 0.1608 | 0.0019 | 0.0344 | 0.6886 |
| 4 | 0.7075 | 0.3997 | 0.6978 | 0.0156 | 0.0003 | 0.1779 | 0.0013 | 0.0283 | 0.6485 |
| 5 | 0.6885 | 0.3708 | 0.7011 | 0.0111 | 0.0003 | 0.1979 | 0.0009 | 0.0252 | 0.6142 |
| 6 | 0.6786 | 0.3476 | 0.7087 | 0.0083 | 0.0003 | 0.2183 | 0.0006 | 0.0247 | 0.6070 |
| 7 | 0.7098 | 0.3302 | 0.7283 | 0.0069 | 0.0004 | 0.2367 | 0.0006 | 0.0260 | 0.6145 |
| 8 | 0.7399 | 0.3147 | 0.7309 | 0.0054 | 0.0004 | 0.2592 | 0.0006 | 0.0271 | 0.6303 |
| 9 | 0.7482 | 0.3037 | 0.7291 | 0.0042 | 0.0005 | 0.2791 | 0.0006 | 0.0282 | 0.6412 |
| 10 | 0.7178 | 0.3048 | 0.7198 | 0.0034 | 0.0005 | 0.2842 | 0.0006 | 0.0310 | 0.6821 |
| 11 | 0.6841 | 0.3105 | 0.6991 | 0.0027 | 0.0006 | 0.2807 | 0.0006 | 0.0349 | 0.7555 |
| 12 | 0.7073 | 0.3166 | 0.6801 | 0.0021 | 0.0005 | 0.2788 | 0.0006 | 0.0365 | 0.8214 |
| 13 | 0.7498 | 0.3267 | 0.6658 | 0.0018 | 0.0005 | 0.2820 | 0.0006 | 0.0365 | 0.8606 |
| 14 | 0.7613 | 0.3362 | 0.6673 | 0.0015 | 0.0005 | 0.2895 | 0.0006 | 0.0366 | 0.8837 |
| 15 | 0.7818 | 0.3524 | 0.6764 | 0.0012 | 0.0004 | 0.2945 | 0.0006 | 0.0401 | 0.9371 |
| 16 | 0.7884 | 0.3534 | 0.6926 | 0.0010 | 0.0004 | 0.2971 | 0.0006 | 0.0438 | 0.9871 |
| 17 | 0.8114 | 0.3517 | 0.7012 | 0.0008 | 0.0004 | 0.3047 | 0.0006 | 0.0459 | 0.9892 |
| 18 | 0.8479 | 0.3579 | 0.6926 | 0.0007 | 0.0004 | 0.3151 | 0.0006 | 0.0492 | 0.9734 |
| 19 | 0.8717 | 0.3667 | 0.6719 | 0.0006 | 0.0004 | 0.3161 | 0.0005 | 0.0507 | 0.9447 |
| 20 | 0.8983 | 0.3648 | 0.6774 | 0.0005 | 0.0004 | 0.3158 | 0.0005 | 0.0534 | 0.9111 |
| 21 | 0.8829 | 0.3633 | 0.6893 | 0.0004 | 0.0004 | 0.3178 | 0.0004 | 0.0547 | 0.8834 |
| 22 | 0.8789 | 0.3707 | 0.6692 | 0.0003 | 0.0004 | 0.3238 | 0.0004 | 0.0547 | 0.8639 |
| 23 | 0.8939 | 0.3740 | 0.6495 | 0.0003 | 0.0004 | 0.3273 | 0.0004 | 0.0525 | 0.8402 |
| 24 | 0.9092 | 0.3775 | 0.6488 | 0.0003 | 0.0004 | 0.3318 | 0.0003 | 0.0491 | 0.8267 |
| 25 | 0.9029 | 0.3898 | 0.6523 | 0.0003 | 0.0003 | 0.3295 | 0.0003 | 0.0462 | 0.8424 |
| 26 | 0.8851 | 0.4030 | 0.6811 | 0.0002 | 0.0003 | 0.3351 | 0.0003 | 0.0449 | 0.8699 |
| 27 | 0.8926 | 0.3968 | 0.7281 | 0.0002 | 0.0003 | 0.3624 | 0.0003 | 0.0461 | 0.8864 |
| 28 | 0.8779 | 0.3964 | 0.7680 | 0.0002 | 0.0003 | 0.3873 | 0.0003 | 0.0458 | 0.8846 |
| 29 | 0.8746 | 0.4028 | 0.8076 | 0.0002 | 0.0002 | 0.3980 | 0.0003 | 0.0432 | 0.8884 |
| 30 | 0.8645 | 0.4198 | 0.8617 | 0.0003 | 0.0002 | 0.4234 | 0.0003 | 0.0395 | 0.9097 |
| 31 | 0.8496 | 0.4467 | 0.9205 | 0.0003 | 0.0001 | 0.4566 | 0.0002 | 0.0379 | 0.9276 |
| 32 | 0.8316 | 0.4701 | 0.9611 | 0.0004 | 0.0001 | 0.4898 | 0.0003 | 0.0368 | 0.9474 |
| 33 | 0.8134 | 0.4836 | 0.9835 | 0.0004 | 0.0001 | 0.5115 | 0.0003 | 0.0353 | 0.9708 |
| 34 | 0.8016 | 0.4817 | 0.9962 | 0.0005 | 0.0001 | 0.5199 | 0.0003 | 0.0369 | 0.9891 |


| 35 | 0.7906 | 0.4781 | 0.9761 | 0.0006 | 0.0001 | 0.5272 | 0.0003 | 0.0388 | 0.9910 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 36 | 0.7834 | 0.4870 | 0.9539 | 0.0007 | 0.0001 | 0.5404 | 0.0003 | 0.0400 | 0.9593 |
| 37 | 0.7604 | 0.4960 | 0.9462 | 0.0008 | 0.0001 | 0.5648 | 0.0003 | 0.0399 | 0.9289 |
| 38 | 0.7418 | 0.4946 | 0.9585 | 0.0009 | 0.0001 | 0.5793 | 0.0003 | 0.0401 | 0.8990 |
| 39 | 0.7236 | 0.4828 | 0.9760 | 0.0010 | 0.0001 | 0.5902 | 0.0003 | 0.0418 | 0.8816 |
| 40 | 0.7113 | 0.4702 | 0.9768 | 0.0011 | 0.0001 | 0.6102 | 0.0004 | 0.0425 | 0.8699 |
| 41 | 0.6994 | 0.4672 | 0.9691 | 0.0012 | 0.0001 | 0.6364 | 0.0004 | 0.0411 | 0.8585 |
| 42 | 0.6921 | 0.4677 | 0.9608 | 0.0013 | 0.0001 | 0.6707 | 0.0004 | 0.0420 | 0.8470 |
| 43 | 0.6817 | 0.4565 | 0.9531 | 0.0014 | 0.0001 | 0.6896 | 0.0005 | 0.0438 | 0.8415 |
| 44 | 0.6702 | 0.4474 | 0.9500 | 0.0015 | 0.0001 | 0.7026 | 0.0005 | 0.0460 | 0.8265 |
| 45 | 0.6640 | 0.4476 | 0.9330 | 0.0016 | 0.0001 | 0.7219 | 0.0005 | 0.0475 | 0.8041 |
| 46 | 0.6616 | 0.4571 | 0.9111 | 0.0016 | 0.0000 | 0.7498 | 0.0005 | 0.0497 | 0.7845 |
| 47 | 0.6556 | 0.4694 | 0.8943 | 0.0017 | 0.0000 | 0.7618 | 0.0006 | 0.0515 | 0.7669 |
| 48 | 0.6540 | 0.4839 | 0.8725 | 0.0017 | 0.0000 | 0.7624 | 0.0006 | 0.0536 | 0.7589 |
| 49 | 0.6571 | 0.4989 | 0.8510 | 0.0018 | 0.0000 | 0.7570 | 0.0007 | 0.0555 | 0.7494 |
| 50 | 0.6594 | 0.5071 | 0.8408 | 0.0018 | 0.0000 | 0.7488 | 0.0007 | 0.0578 | 0.7483 |
| 51 | 0.6547 | 0.5085 | 0.8393 | 0.0018 | 0.0000 | 0.7403 | 0.0008 | 0.0597 | 0.7519 |
| 52 | 0.6535 | 0.5192 | 0.8395 | 0.0019 | 0.0000 | 0.7427 | 0.0008 | 0.0616 | 0.7499 |
| 53 | 0.6534 | 0.5302 | 0.8272 | 0.0019 | 0.0000 | 0.7531 | 0.0008 | 0.0628 | 0.7454 |
| 54 | 0.6481 | 0.5331 | 0.8101 | 0.0019 | 0.0000 | 0.7618 | 0.0009 | 0.0636 | 0.7444 |
| 55 | 0.6403 | 0.5157 | 0.8030 | 0.0018 | 0.0000 | 0.7650 | 0.0009 | 0.0642 | 0.7361 |
| 56 | 0.6371 | 0.5083 | 0.8003 | 0.0018 | 0.0000 | 0.7685 | 0.0009 | 0.0651 | 0.7308 |
| 57 | 0.6363 | 0.5017 | 0.8031 | 0.0018 | 0.0000 | 0.7750 | 0.0009 | 0.0670 | 0.7318 |
| 58 | 0.6314 | 0.4966 | 0.8005 | 0.0017 | 0.0000 | 0.7749 | 0.0009 | 0.0692 | 0.7321 |
| 59 | 0.6264 | 0.4886 | 0.7973 | 0.0015 | 0.0000 | 0.7768 | 0.0008 | 0.0693 | 0.7364 |
| 60 | 0.6221 | 0.4793 | 0.8008 | 0.0013 | 0.0000 | 0.7819 | 0.0008 | 0.0676 | 0.7431 |
| 61 | 0.6207 | 0.4750 | 0.7974 | 0.0011 | 0.0000 | 0.7727 | 0.0008 | 0.0649 | 0.7440 |
| 62 | 0.6230 | 0.4741 | 0.7887 | 0.0010 | 0.0000 | 0.7560 | 0.0007 | 0.0615 | 0.7366 |
| 63 | 0.6246 | 0.4782 | 0.7907 | 0.0008 | 0.0000 | 0.7363 | 0.0007 | 0.0591 | 0.7292 |
| 64 | 0.6320 | 0.4815 | 0.7881 | 0.0006 | 0.0000 | 0.7170 | 0.0006 | 0.0570 | 0.7261 |
| 65 | 0.6323 | 0.4840 | 0.7751 | 0.0005 | 0.0001 | 0.6949 | 0.0006 | 0.0541 | 0.7370 |
| 66 | 0.6304 | 0.4944 | 0.7690 | 0.0003 | 0.0001 | 0.6680 | 0.0005 | 0.0527 | 0.7550 |
| 67 | 0.6293 | 0.5124 | 0.7638 | 0.0002 | 0.0001 | 0.6437 | 0.0005 | 0.0509 | 0.7672 |
| 68 | 0.6192 | 0.5317 | 0.7567 | 0.0002 | 0.0001 | 0.6205 | 0.0005 | 0.0491 | 0.7853 |
| 69 | 0.6038 | 0.5429 | 0.7396 | 0.0001 | 0.0001 | 0.6007 | 0.0004 | 0.0476 | 0.8106 |
| 70 | 0.5915 | 0.5426 | 0.7235 | 0.0001 | 0.0001 | 0.5865 | 0.0004 | 0.0464 | 0.8291 |
| 71 | 0.5879 | 0.5264 | 0.7209 | 0.0001 | 0.0001 | 0.5746 | 0.0004 | 0.0457 | 0.8500 |
| 72 | 0.5753 | 0.4961 | 0.7376 | 0.0000 | 0.0001 | 0.5623 | 0.0004 | 0.0437 | 0.8700 |
| 73 | 0.5487 | 0.4649 | 0.7524 | 0.0000 | 0.0001 | 0.5481 | 0.0004 | 0.0431 | 0.8904 |
| 74 | 0.5260 | 0.4403 | 0.7802 | 0.0000 | 0.0001 | 0.5349 | 0.0004 | 0.0445 | 0.9123 |
| 75 | 0.5071 | 0.4269 | 0.8171 | 0.0000 | 0.0001 | 0.5269 | 0.0003 | 0.0479 | 0.9269 |
| 76 | 0.4947 | 0.4113 | 0.8575 | 0.0000 | 0.0001 | 0.5200 | 0.0003 | 0.0521 | 0.9494 |
| 77 | 0.4975 | 0.3914 | 0.8952 | 0.0000 | 0.0001 | 0.5116 | 0.0003 | 0.0576 | 0.9671 |


| $\mathbf{7 8}$ | 0.4971 | 0.3608 | 0.9206 | 0.0000 | 0.0001 | 0.5045 | 0.0004 | 0.0664 | 0.9734 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathbf{7 9}$ | 0.4738 | 0.3360 | 0.9466 | 0.0000 | 0.0001 | 0.4979 | 0.0004 | 0.0770 | 0.9799 |
| $\mathbf{8 0}$ | 0.4543 | 0.3142 | 0.9690 | 0.0000 | 0.0001 | 0.4858 | 0.0004 | 0.0871 | 0.9937 |
| $\mathbf{8 1}$ | 0.4711 | 0.2930 | 0.9896 | 0.0000 | 0.0002 | 0.4765 | 0.0004 | 0.0934 | 0.9939 |
| $\mathbf{8 2}$ | 0.4888 | 0.2762 | 0.9991 | 0.0000 | 0.0002 | 0.4611 | 0.0004 | 0.1007 | 0.9929 |
| $\mathbf{8 3}$ | 0.4883 | 0.2724 | 0.9973 | 0.0000 | 0.0003 | 0.4501 | 0.0005 | 0.1110 | 0.9854 |
| $\mathbf{8 4}$ | 0.5001 | 0.2704 | 0.9925 | 0.0000 | 0.0003 | 0.4233 | 0.0007 | 0.1200 | 0.9745 |
| $\mathbf{8 5}$ | 0.5354 | 0.2708 | 0.9707 | 0.0000 | 0.0003 | 0.3989 | 0.0007 | 0.1197 | 0.9877 |
| $\mathbf{8 6}$ | 0.5713 | 0.2783 | 0.9483 | 0.0001 | 0.0004 | 0.3981 | 0.0009 | 0.1256 | 0.9747 |
| $\mathbf{8 7}$ | 0.5865 | 0.2894 | 0.9072 | 0.0001 | 0.0004 | 0.4022 | 0.0010 | 0.1357 | 0.9533 |
| $\mathbf{8 8}$ | 0.6200 | 0.2856 | 0.8559 | 0.0002 | 0.0004 | 0.3907 | 0.0012 | 0.1448 | 0.9405 |
| $\mathbf{8 9}$ | 0.6118 | 0.2805 | 0.8023 | 0.0003 | 0.0005 | 0.3731 | 0.0014 | 0.1485 | 0.9107 |
| $\mathbf{9 0}$ | 0.5964 | 0.2845 | 0.7714 | 0.0006 | 0.0005 | 0.3610 | 0.0018 | 0.1490 | 0.8801 |
| $\mathbf{9 1}$ | 0.6261 | 0.2971 | 0.7476 | 0.0011 | 0.0004 | 0.3424 | 0.0020 | 0.1450 | 0.8624 |
| $\mathbf{9 2}$ | 0.6505 | 0.3118 | 0.7022 | 0.0019 | 0.0005 | 0.3202 | 0.0018 | 0.1373 | 0.8634 |
| $\mathbf{9 3}$ | 0.6632 | 0.3253 | 0.6456 | 0.0031 | 0.0005 | 0.2859 | 0.0021 | 0.1322 | 0.8695 |
| $\mathbf{9 4}$ | 0.6322 | 0.3274 | 0.5846 | 0.0049 | 0.0006 | 0.2498 | 0.0025 | 0.1242 | 0.8779 |
| $\mathbf{9 5}$ | 0.6181 | 0.3194 | 0.5403 | 0.0070 | 0.0006 | 0.2126 | 0.0025 | 0.1098 | 0.8950 |
| $\mathbf{9 6}$ | 0.6104 | 0.3127 | 0.5087 | 0.0102 | 0.0006 | 0.1828 | 0.0023 | 0.0966 | 0.9031 |
| $\mathbf{9 7}$ | 0.6207 | 0.3174 | 0.4954 | 0.0147 | 0.0006 | 0.1580 | 0.0026 | 0.0872 | 0.9069 |
| $\mathbf{9 8}$ | 0.6278 | 0.3384 | 0.4727 | 0.0209 | 0.0006 | 0.1344 | 0.0031 | 0.0790 | 0.9006 |
| $\mathbf{9 9}$ | 0.6537 | 0.3649 | 0.4405 | 0.0287 | 0.0006 | 0.1124 | 0.0033 | 0.0703 | 0.9077 |
| $\mathbf{1 0 0}$ | 0.6427 | 0.3853 | 0.4243 | 0.0371 | 0.0006 | 0.0925 | 0.0042 | 0.0657 | 0.9173 |

Table 8. Summary of p-values for flexion-extension, internal-external, and abduction-adduction rotation angles during medial SLS task for bilateral control (LR), ACLd, and PFP populations.

Table 9 summarizes the p-values during the lateral SLS task for all participant groups.

|  | LR |  |  | ACLd |  |  | PFP |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| \% of <br> Cycle | Flex/Ext | Int/Ext | Ad/Ab | Flex/Ext | Int/Ext | Ad/Ab | Flex/Ext | Int/Ext | Ad/Ab |
| $\mathbf{0}$ | 0.6369 | 0.9740 | 0.2530 | 0.3906 | 0.1185 | 0.7175 | 0.0319 | 0.3950 | 0.5004 |
| $\mathbf{1}$ | 0.5996 | 0.9572 | 0.2797 | 0.2865 | 0.1304 | 0.6017 | 0.0216 | 0.4663 | 0.5799 |
| $\mathbf{2}$ | 0.6024 | 0.9655 | 0.3215 | 0.2399 | 0.1242 | 0.5329 | 0.0153 | 0.4840 | 0.6321 |
| $\mathbf{3}$ | 0.6246 | 0.9864 | 0.3831 | 0.2006 | 0.1139 | 0.4949 | 0.0111 | 0.4946 | 0.6786 |
| $\mathbf{4}$ | 0.6382 | 0.9994 | 0.4551 | 0.1653 | 0.1055 | 0.4690 | 0.0074 | 0.5060 | 0.7244 |
| $\mathbf{5}$ | 0.6568 | 0.9932 | 0.5044 | 0.1253 | 0.0978 | 0.4463 | 0.0047 | 0.5112 | 0.7887 |
| $\mathbf{6}$ | 0.6747 | 0.9978 | 0.5517 | 0.0944 | 0.0885 | 0.4322 | 0.0032 | 0.5027 | 0.8633 |
| $\mathbf{7}$ | 0.6963 | 0.9971 | 0.5979 | 0.0717 | 0.0837 | 0.4117 | 0.0023 | 0.4937 | 0.9294 |
| $\mathbf{8}$ | 0.7156 | 0.9837 | 0.6363 | 0.0511 | 0.0803 | 0.3845 | 0.0017 | 0.4734 | 0.9932 |
| $\mathbf{9}$ | 0.7446 | 0.9375 | 0.6855 | 0.0349 | 0.0764 | 0.3662 | 0.0012 | 0.4481 | 0.9622 |
| $\mathbf{1 0}$ | 0.8001 | 0.8786 | 0.7431 | 0.0234 | 0.0730 | 0.3524 | 0.0009 | 0.4277 | 0.9273 |
| $\mathbf{1 1}$ | 0.8084 | 0.8193 | 0.8297 | 0.0187 | 0.0720 | 0.3436 | 0.0007 | 0.4143 | 0.8911 |


| 12 | 0.8280 | 0.7897 | 0.8913 | 0.0147 | 0.0718 | 0.3312 | 0.0005 | 0.4261 | 0.8419 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 13 | 0.8384 | 0.7957 | 0.9254 | 0.0116 | 0.0682 | 0.3182 | 0.0005 | 0.4443 | 0.7757 |
| 14 | 0.8507 | 0.7983 | 0.9386 | 0.0083 | 0.0610 | 0.3169 | 0.0005 | 0.4424 | 0.7099 |
| 15 | 0.8493 | 0.8000 | 0.9403 | 0.0060 | 0.0558 | 0.3209 | 0.0004 | 0.4329 | 0.6707 |
| 16 | 0.8547 | 0.8296 | 0.9469 | 0.0046 | 0.0526 | 0.3317 | 0.0003 | 0.4320 | 0.6504 |
| 17 | 0.8748 | 0.8727 | 0.9600 | 0.0040 | 0.0495 | 0.3487 | 0.0003 | 0.4319 | 0.6379 |
| 18 | 0.9213 | 0.9036 | 0.9407 | 0.0036 | 0.0440 | 0.3659 | 0.0004 | 0.4259 | 0.6266 |
| 19 | 0.9290 | 0.9080 | 0.8931 | 0.0034 | 0.0403 | 0.3811 | 0.0004 | 0.4307 | 0.5966 |
| 20 | 0.9189 | 0.9232 | 0.8599 | 0.0034 | 0.0367 | 0.3925 | 0.0004 | 0.4289 | 0.5668 |
| 21 | 0.8782 | 0.9552 | 0.8562 | 0.0035 | 0.0330 | 0.4080 | 0.0004 | 0.4188 | 0.5643 |
| 22 | 0.8510 | 0.9704 | 0.8434 | 0.0036 | 0.0294 | 0.4223 | 0.0005 | 0.4026 | 0.5683 |
| 23 | 0.8495 | 0.9608 | 0.8292 | 0.0036 | 0.0257 | 0.4396 | 0.0005 | 0.3769 | 0.5573 |
| 24 | 0.8516 | 0.9520 | 0.8300 | 0.0037 | 0.0229 | 0.4411 | 0.0005 | 0.3495 | 0.5421 |
| 25 | 0.8542 | 0.9288 | 0.8458 | 0.0038 | 0.0223 | 0.4426 | 0.0006 | 0.3333 | 0.5450 |
| 26 | 0.8212 | 0.8870 | 0.8671 | 0.0040 | 0.0235 | 0.4465 | 0.0007 | 0.3249 | 0.5471 |
| 27 | 0.7842 | 0.8603 | 0.8977 | 0.0044 | 0.0250 | 0.4606 | 0.0007 | 0.3144 | 0.5447 |
| 28 | 0.7652 | 0.8590 | 0.9294 | 0.0047 | 0.0255 | 0.4746 | 0.0008 | 0.3164 | 0.5415 |
| 29 | 0.7655 | 0.8788 | 0.9666 | 0.0052 | 0.0225 | 0.4856 | 0.0008 | 0.3171 | 0.5365 |
| 30 | 0.7646 | 0.8910 | 0.9928 | 0.0058 | 0.0193 | 0.4971 | 0.0009 | 0.3231 | 0.5341 |
| 31 | 0.7571 | 0.8832 | 0.9520 | 0.0066 | 0.0167 | 0.5195 | 0.0009 | 0.3279 | 0.5398 |
| 32 | 0.7376 | 0.8712 | 0.9252 | 0.0073 | 0.0149 | 0.5368 | 0.0010 | 0.3317 | 0.5373 |
| 33 | 0.7137 | 0.8713 | 0.9224 | 0.0082 | 0.0129 | 0.5405 | 0.0012 | 0.3413 | 0.5209 |
| 34 | 0.6854 | 0.8647 | 0.9395 | 0.0098 | 0.0119 | 0.5297 | 0.0014 | 0.3522 | 0.4963 |
| 35 | 0.6663 | 0.8646 | 0.9423 | 0.0117 | 0.0116 | 0.5191 | 0.0014 | 0.3556 | 0.4788 |
| 36 | 0.6604 | 0.8667 | 0.9285 | 0.0130 | 0.0113 | 0.5149 | 0.0016 | 0.3520 | 0.4667 |
| 37 | 0.6488 | 0.8688 | 0.9216 | 0.0139 | 0.0106 | 0.5189 | 0.0019 | 0.3476 | 0.4678 |
| 38 | 0.6438 | 0.8778 | 0.9161 | 0.0148 | 0.0097 | 0.5191 | 0.0022 | 0.3463 | 0.4744 |
| 39 | 0.6335 | 0.8808 | 0.9067 | 0.0163 | 0.0090 | 0.5143 | 0.0023 | 0.3388 | 0.4716 |
| 40 | 0.6242 | 0.8751 | 0.9054 | 0.0179 | 0.0081 | 0.5157 | 0.0024 | 0.3229 | 0.4611 |
| 41 | 0.6100 | 0.8728 | 0.9131 | 0.0197 | 0.0071 | 0.5231 | 0.0027 | 0.3133 | 0.4552 |
| 42 | 0.6094 | 0.8709 | 0.9140 | 0.0213 | 0.0066 | 0.5280 | 0.0030 | 0.3076 | 0.4519 |
| 43 | 0.6064 | 0.8716 | 0.9063 | 0.0228 | 0.0065 | 0.5284 | 0.0032 | 0.3055 | 0.4492 |
| 44 | 0.6021 | 0.8777 | 0.8876 | 0.0244 | 0.0065 | 0.5235 | 0.0033 | 0.3054 | 0.4347 |
| 45 | 0.5902 | 0.8855 | 0.8737 | 0.0252 | 0.0063 | 0.5219 | 0.0033 | 0.3011 | 0.4267 |
| 46 | 0.5855 | 0.8919 | 0.8722 | 0.0263 | 0.0060 | 0.5179 | 0.0033 | 0.2949 | 0.4242 |
| 47 | 0.5830 | 0.8942 | 0.8796 | 0.0274 | 0.0056 | 0.5192 | 0.0035 | 0.2874 | 0.4235 |
| 48 | 0.5802 | 0.8980 | 0.8920 | 0.0280 | 0.0055 | 0.5216 | 0.0038 | 0.2853 | 0.4215 |
| 49 | 0.5737 | 0.9014 | 0.8932 | 0.0285 | 0.0055 | 0.5201 | 0.0039 | 0.2818 | 0.4195 |
| 50 | 0.5686 | 0.9066 | 0.8906 | 0.0282 | 0.0054 | 0.5184 | 0.0040 | 0.2803 | 0.4199 |
| 51 | 0.5652 | 0.9113 | 0.8865 | 0.0275 | 0.0052 | 0.5070 | 0.0041 | 0.2763 | 0.4147 |
| 52 | 0.5653 | 0.9058 | 0.8866 | 0.0274 | 0.0051 | 0.4994 | 0.0042 | 0.2705 | 0.4062 |
| 53 | 0.5674 | 0.9086 | 0.8878 | 0.0264 | 0.0050 | 0.4931 | 0.0043 | 0.2670 | 0.3956 |
| 54 | 0.5670 | 0.9198 | 0.8880 | 0.0248 | 0.0050 | 0.4845 | 0.0044 | 0.2670 | 0.3920 |


| 55 | 0.5642 | 0.9273 | 0.8847 | 0.0232 | 0.0050 | 0.4791 | 0.0043 | 0.2677 | 0.3905 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 56 | 0.5701 | 0.9189 | 0.8829 | 0.0215 | 0.0048 | 0.4784 | 0.0041 | 0.2670 | 0.3864 |
| 57 | 0.5748 | 0.9107 | 0.8855 | 0.0198 | 0.0046 | 0.4779 | 0.0039 | 0.2649 | 0.3869 |
| 58 | 0.5776 | 0.9088 | 0.8862 | 0.0178 | 0.0044 | 0.4762 | 0.0037 | 0.2609 | 0.3976 |
| 59 | 0.5805 | 0.9071 | 0.8792 | 0.0158 | 0.0043 | 0.4692 | 0.0036 | 0.2596 | 0.4071 |
| 60 | 0.5900 | 0.9051 | 0.8740 | 0.0140 | 0.0044 | 0.4712 | 0.0033 | 0.2619 | 0.4172 |
| 61 | 0.5912 | 0.8960 | 0.8589 | 0.0123 | 0.0045 | 0.4748 | 0.0031 | 0.2642 | 0.4242 |
| 62 | 0.5898 | 0.8903 | 0.8436 | 0.0107 | 0.0044 | 0.4676 | 0.0028 | 0.2613 | 0.4180 |
| 63 | 0.5836 | 0.8864 | 0.8323 | 0.0090 | 0.0043 | 0.4580 | 0.0026 | 0.2524 | 0.4073 |
| 64 | 0.5902 | 0.8827 | 0.8279 | 0.0075 | 0.0042 | 0.4537 | 0.0024 | 0.2406 | 0.3960 |
| 65 | 0.5957 | 0.8772 | 0.8378 | 0.0064 | 0.0041 | 0.4514 | 0.0023 | 0.2316 | 0.3854 |
| 66 | 0.6084 | 0.8777 | 0.8582 | 0.0054 | 0.0040 | 0.4478 | 0.0020 | 0.2268 | 0.3755 |
| 67 | 0.6145 | 0.8841 | 0.8661 | 0.0046 | 0.0039 | 0.4427 | 0.0019 | 0.2248 | 0.3669 |
| 68 | 0.6222 | 0.8820 | 0.8657 | 0.0038 | 0.0041 | 0.4345 | 0.0018 | 0.2299 | 0.3563 |
| 69 | 0.6117 | 0.8729 | 0.8684 | 0.0032 | 0.0043 | 0.4230 | 0.0016 | 0.2399 | 0.3544 |
| 70 | 0.6005 | 0.8583 | 0.8723 | 0.0028 | 0.0050 | 0.4123 | 0.0014 | 0.2521 | 0.3564 |
| 71 | 0.6060 | 0.8340 | 0.8709 | 0.0024 | 0.0059 | 0.4026 | 0.0013 | 0.2659 | 0.3477 |
| 72 | 0.6077 | 0.8226 | 0.8732 | 0.0020 | 0.0071 | 0.3901 | 0.0014 | 0.2825 | 0.3337 |
| 73 | 0.6069 | 0.8254 | 0.8712 | 0.0018 | 0.0079 | 0.3819 | 0.0013 | 0.3011 | 0.3201 |
| 74 | 0.5885 | 0.8331 | 0.8678 | 0.0017 | 0.0082 | 0.3786 | 0.0014 | 0.3143 | 0.3089 |
| 75 | 0.5960 | 0.8198 | 0.8705 | 0.0017 | 0.0085 | 0.3715 | 0.0014 | 0.3282 | 0.2990 |
| 76 | 0.5896 | 0.7986 | 0.8784 | 0.0017 | 0.0090 | 0.3655 | 0.0013 | 0.3473 | 0.2930 |
| 77 | 0.5881 | 0.7659 | 0.8804 | 0.0016 | 0.0102 | 0.3609 | 0.0011 | 0.3655 | 0.2875 |
| 78 | 0.5722 | 0.7484 | 0.8853 | 0.0016 | 0.0120 | 0.3579 | 0.0012 | 0.3849 | 0.2838 |
| 79 | 0.5520 | 0.7406 | 0.8829 | 0.0017 | 0.0143 | 0.3439 | 0.0012 | 0.4066 | 0.2846 |
| 80 | 0.5438 | 0.7333 | 0.8728 | 0.0019 | 0.0172 | 0.3298 | 0.0013 | 0.4348 | 0.2880 |
| 81 | 0.5322 | 0.7145 | 0.8632 | 0.0020 | 0.0204 | 0.3169 | 0.0013 | 0.4567 | 0.2868 |
| 82 | 0.5228 | 0.7000 | 0.8581 | 0.0019 | 0.0252 | 0.3116 | 0.0012 | 0.4813 | 0.2923 |
| 83 | 0.5177 | 0.6951 | 0.8672 | 0.0022 | 0.0320 | 0.3096 | 0.0012 | 0.5060 | 0.3003 |
| 84 | 0.5191 | 0.6769 | 0.8910 | 0.0026 | 0.0391 | 0.3120 | 0.0013 | 0.5266 | 0.3092 |
| 85 | 0.5113 | 0.6481 | 0.9073 | 0.0031 | 0.0455 | 0.3108 | 0.0012 | 0.5380 | 0.3235 |
| 86 | 0.5081 | 0.6140 | 0.9205 | 0.0038 | 0.0516 | 0.3081 | 0.0012 | 0.5412 | 0.3295 |
| 87 | 0.5209 | 0.5953 | 0.9397 | 0.0043 | 0.0579 | 0.2914 | 0.0012 | 0.5399 | 0.3322 |
| 88 | 0.5340 | 0.5762 | 0.9648 | 0.0052 | 0.0617 | 0.2808 | 0.0014 | 0.5194 | 0.3425 |
| 89 | 0.5557 | 0.5664 | 0.9863 | 0.0068 | 0.0640 | 0.2770 | 0.0015 | 0.5064 | 0.3685 |
| 90 | 0.5662 | 0.5777 | 0.9718 | 0.0091 | 0.0651 | 0.2856 | 0.0012 | 0.4990 | 0.3964 |
| 91 | 0.5807 | 0.5916 | 0.9053 | 0.0135 | 0.0669 | 0.3030 | 0.0014 | 0.4933 | 0.4426 |
| 92 | 0.5831 | 0.6008 | 0.8140 | 0.0191 | 0.0699 | 0.3071 | 0.0019 | 0.4772 | 0.4857 |
| 93 | 0.5950 | 0.6111 | 0.7258 | 0.0281 | 0.0721 | 0.3070 | 0.0028 | 0.4721 | 0.5211 |
| 94 | 0.6014 | 0.6390 | 0.6518 | 0.0409 | 0.0728 | 0.3033 | 0.0039 | 0.4752 | 0.5536 |
| 95 | 0.5953 | 0.6790 | 0.5965 | 0.0586 | 0.0771 | 0.3107 | 0.0048 | 0.4893 | 0.5890 |
| 96 | 0.6138 | 0.7152 | 0.5350 | 0.0868 | 0.0833 | 0.3214 | 0.0063 | 0.5099 | 0.6401 |
| 97 | 0.6272 | 0.7298 | 0.4621 | 0.1273 | 0.0897 | 0.3375 | 0.0083 | 0.5221 | 0.7088 |


| $\mathbf{9 8}$ | 0.6439 | 0.7322 | 0.3935 | 0.1842 | 0.0968 | 0.3530 | 0.0124 | 0.5286 | 0.8095 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathbf{9 9}$ | 0.6151 | 0.7359 | 0.3483 | 0.2479 | 0.1076 | 0.3654 | 0.0170 | 0.5397 | 0.9084 |
| $\mathbf{1 0 0}$ | 0.6107 | 0.7430 | 0.3171 | 0.3046 | 0.1215 | 0.3856 | 0.0216 | 0.5513 | 0.9923 |

Table 9 . Summary of p-values for flexion-extension, internal-external, and abduction-adduction rotation angles during lateral SLS task for bilateral control (LR), ACLd, and PFP populations.

ACLd Group Medial
Data from the medially twisted SLS shows an increase in external rotation for $100 \%$ of the cycle and an increase in flexion for $100 \%$ of the cycle for ACLd participants compared to controls. There were no significant differences in abduction-adduction rotation angles. Three ACLd participant data sets were excluded for reasons mentioned in Section 4.1.


Figure 13. Rotation angles during medial SLS for ACLd group. (a) Flexion-extension.
Significantly lower ACLd flexion rotation for $100 \%$ of the cycle. (b) Internal-external. Significantly less ACLd internal rotation for $100 \%$ of the cycle. (c) Abduction-adduction. Shaded regions indicate areas of significant differences.

## ACL Group Lateral

Data from the laterally twisted SLS shows an increase in external rotation from 17-85\% of the cycle and an increase in flexion from $9-94 \%$ of the cycle for ACLd participants compared to controls. There were no significant differences in abduction-adduction rotation angles. Three ACLd participant data sets were excluded for reasons mentioned in Section 4.1.


Figure 14. Rotation angles during lateral SLS for ACLd group. (a) Flexion-extension. Significantly lower ACLd flexion rotation between $9-94 \%$ of the cycle. (b) Internal-external. Significantly more ACLd external rotation between $17-85 \%$ of the cycle. (c) Abductionadduction. Shaded regions indicate areas of significant differences.

## PFP Group Medial

Data from the medially twisted SLS shows an increase in external rotation from 2-18\%, 24-46\%, and $68-75 \%$ and a decrease in flexion for $100 \%$ of the cycle for PFP participants compared to
controls. There were no significant differences in abduction-adduction rotation angles. Two PFP participant data sets were excluded for reasons mentioned in Section 4.1.


Figure 15. Rotation angles during medial SLS for PFP group. (a) Flexion-extension. Significantly lower PFP flexion rotation for $100 \%$ of the cycle. (b) Internal-external. Significantly less PFP internal rotation between 2-18\%, 24-46\%, and 68-75\% of the cycle. (c) Abduction-adduction. Shaded regions indicate areas of significant differences.

## PFP Group Lateral

Data from the laterally twisted SLS shows a decrease in flexion for $100 \%$ of the cycle for PFP participants compared to controls. There were no significant differences in abduction-adduction or internal-external rotation angles. One PFP participant data set was excluded for reasons mentioned in Section 4.1.


Figure 16. Rotation angles during lateral SLS for PFP group. (a) Flexion-extension. Significantly lower PFP flexion rotation for $100 \%$ of the cycle. (b) Internal-external. (c) Abduction-adduction. Shaded regions indicate areas of significant differences.

### 4.2 SimVitro testing

The results from the SimVitro testing were not true reflections of the MKATS device itself due to unperceived amounts of skin artifact and laxity in the cadaver knees compared to living participants. Further testing was done with simultaneous data collection during CT scans on live
participants to compare joint angles calculated from geometries derived from the CT scan with joint angles output from the MKATS.

## 5. Discussion

These analyses may be limited as right and left control data were lumped together thus neglecting bilateral asymmetries. However, bilateral differences observed between control participants during the step up and over task were of a lesser magnitude than between control and clinical populations. Healthy individuals may have bilateral differences in kinematics related to asymmetries in muscle strength and flexibility ${ }^{28}$ as shown in Figure 17. Rotation angles from the 3 step-up-and-over tasks from a representative control participant with bilateral asymmetrical internal-external rotation angles (a) and rotation angles from a representative control participant with relative symmetry between limbs (b). It has also been shown that there are inherent differences in side-to-side morphology and kinematics for healthy individuals during the gait cycle ${ }^{6,13,28}$. It was hypothesized that participant familiarity with the tasks may be a cause of the altered side-to-side kinematics during the step-up and over task. For all control participants, data was collected first on the right followed by the left, which is a study limitation. The participants may have been more familiar with the tasks the second time and thus performed them faster or with less hesitation. In future studies, alternating which leg is tested first for each participant may reduce biases related to task familiarity.


Figure 17. Rotation angles from the 3 step-up-and-over tasks from a representative control participant with bilateral asymmetrical internal-external rotation angles (a) and rotation angles from a representative control participant with relative symmetry between limbs (b).

While tasks such as the lateral step-down, step-up and over, and Y balance tests were all selected from standard tests, the large statistically significant differences between healthy control and clinical populations during SLS with rotation suggest that such a task may capture pathological kinematics well. However, more work needs to be done to establish a standardized testing method so that clinical significance can be applied to metrics obtained from such tasks. Some participants chose to place their contralateral toes on the ground for support while others did not. Additionally, placement of the contralateral leg varied. One way to make this test more standard would be give explicit instruction on where to place the contralateral leg and how much to rotate.

### 5.1 Relevance to ACL Population

Studies evaluating knee motion in ACLd or ACL reconstructed populations have varied and often report conflicting results ${ }^{1,11,13,18,67}$. Many studies have observed more internal rotation with increased flexion, but it should be noted that most of these are cadaver studies which are limited to testing passive stability ${ }^{67}$. These studies can measure relative bone motion very accurately, but often neglect the influence of muscle forces. Some gait studies on healthy populations found the knee to be in internal rotation throughout the cycle ${ }^{1,11}$ while others found the knee to be in external rotation throughout the cycle ${ }^{28,31,42}$. Other studies found more external rotation in the stance phase with more internal rotation in the swing phase ${ }^{13,25,36}$. These studies all used instrumented motion analysis, but the algorithms used for data processing varied. In this study, ACLd patients had increased external rotation for $\geq 90 \%$ of LSD, SUO, and Y-balance tasks. The ACLd population also had decreased peak flexion during flexed periods for dynamic tasks which may be another indicator of decreased stability of the joint and aligns with a systemic review by Zhang et al ${ }^{68}$.

In all tasks, knee arthrokinematics result from external knee loading and muscle forces as well as geometric and soft tissue constraints ${ }^{8,12}$. Patients with a history of ACL deficiency have not only a change in passive support at the knee, but changes to motor control and muscle activation as well ${ }^{19,22}$. The observed changes in kinematics are likely a combination of many things including the loss in passive support from the ACL, the loss of mechanoreceptors near the TF joint, and subsequent altered input from the central nervous system ${ }^{19,22}$. Such altered kinematics are indicative of instability, changing compensation mechanisms, and altered loading of the joint ${ }^{22}$. One cadaver study found that sectioning of the ACL increased forces carried by both the lateral meniscus and the medial femoral condyle through cartilage-to-cartilage contact ${ }^{45}$.

Increased antagonistic muscle activation can lead to increased compressive forces on the knee which can accelerate progression of cartilage degeneration ${ }^{18}$. Such abnormalities in kinematics and changes in the contact pattern of the articular surfaces can be aggravated with extensive cycles of loading and lead to post-traumatic osteoarthritis ${ }^{18,47}$. These long-term degenerative changes typically require additional costly treatment regardless of if the patient was treated surgically or conservatively ${ }^{44}$.

One limitation of this data set includes the range of injury timing. Most participants were injured within one year. However, there were six participants whose initial injury occurred more than a year prior to data collection and two whose initial injury occurred more than a decade prior. Injury timing may affect the compensation mechanisms that individuals develop following injury ${ }^{18}$. While most initial swelling post injury should be gone within a week, studies have found increased levels of inflammatory cytokines and biomarkers associated with increased collagen turnover up to a decade after injury ${ }^{26}$. One patient was injured one week prior to data collection and may have had increased swelling or pain that further altered their performance ${ }^{26}$. A patient who ruptured their ACL 3 weeks prior may have different compensation patterns than one who has been ACLd for a year with rehabilitation/physical therapy before surgical interventions ${ }^{18}$.

Triplanar metrics such as those used in this study may be useful for tracking progress of both conservative and surgical treatments of ACL related pathologies. Metrics that align more closely with normative data can indicate that an athlete is ready to return to sport ${ }^{4}$. Additionally, such kinematic metrics may be useful for screening uninjured athletes for ACL injury risk ${ }^{43}$. It has been found that smaller ACLs are associated with less linear stiffness ${ }^{10}$, lower load at failure ${ }^{10}$, and greater anterior knee laxity ${ }^{65}$. As those with greater knee laxity have been
associated with a greater ACL injury risk ${ }^{58}$, objective and noninvasive metrics could be used in preventative training protocols.

### 5.2 Relevance to PFP Population

Patellofemoral pain syndrome is typically a diagnosis of exclusion after other pathologies have been ruled out ${ }^{46}$. One of the most accepted symptoms is retropatellar or peripatellar pain that has gone on for more than 3 months ${ }^{5,15,41}$. While the primary characteristics are altered patellar tracking and increased lateral stress at the patellofemoral joint, the cause of these characteristics is multifactorial ${ }^{5}$. As such, there is a wide range of symptoms and severity within those diagnosed with PFP. Most patients have soft tissue swelling which can progress into severe arthritic changes ${ }^{41,66}$. One suggested mechanism is that increased stress at the patellofemoral joint during loaded flexed activity transmits through the cartilage to nociceptors in the subchondral bone thus causing pain ${ }^{41}$. Typical criterion for diagnosis includes pain during loaded functional tasks such as those previously mentioned in Section $1^{41,66}$. While a correlation between kinematics and pain has been associated, there is a debate over whether poor kinematics lead to pain or whether pain led to compensation mechanisms to decrease the patellofemoral joint load ${ }^{5}$.

Due to the complex definition of the pathology and range of severity, there is a paucity of studies looking at dynamics in PFP populations. Barton et al. found altered dynamics including a reduction in gait velocity, reduced internal hip rotation, and increased pronation of the foot ${ }^{5}$. While peak flexion is not consistently different in level walking, other studies have found reduced peak flexion on stair ascent and there is general agreement that altered kinematics are related to increased patellofemoral joint loads ${ }^{17,66}$. This history supports the findings observed
with the MKATS as all tasks produced some degree of decreased peak flexion and decreased internal rotation.

Another factor to consider in the kinematics of those with PFP, is muscle activation. Resisted isometric quadriceps femoris muscle activation is another common test utilized in diagnosis and treatment of PFP $^{55,66}$. Lankhorst et al found that quadriceps strength in PFP populations was considerably diminished using dynamometry ${ }^{40}$. It has been suggested that decreased quadriceps activation may be related to inhibited central neural drive as a result of pain feedback ${ }^{59}$. Studies utilizing electromyography have found that some PFP populations have delayed vastus medialis obliquus activation relative to the vastus lateralis ${ }^{17}$. Such activation patterns may alter the alignment of the patella thus contributing to increased pain and development of osteoarthritis ${ }^{16,66}$. Further investigation is needed to understand the relationship between the symptom of pain and the factors of joint loading, muscle activation, and kinematics.

While treatment options for PFP are usually nonsurgical, objective triplanar metrics can be useful to physical therapists treating PFP to track patient progression. Proper treatment of PFP may be able to correct loading patterns and prevent further degenerative changes ${ }^{66}$.

### 5.3 Further Device Development

Discussions with physical therapists, athletic trainers, and other orthopedic clinicians during interviews for the NSF Innovation Corps bootcamp confirmed that potential users desire objective assessment of knee function and that tibial rotation is difficult to assess visually. Some of the current limitations they experience are adequate objective measures to show patient improvement in documentation for payers, costs of instrumented assessment tools, standardized metrics, and proper space to perform assessments. Part of a physical therapist's job is to
objectively assess patient progression and advocate for their patients to healthcare payers and other parties. A device such as the MKATS can provide objective documentable metrics, biofeedback for the patient, dynamic realistic assessments for sports, and justification for marketing their services. These metrics can help clinicians decide if the patient is ready for discharge, if the patient is ready to return to sports or other activities, and if the intervention is effective or not. Within the customer segments interviewed the following should be considered with further MKATS development:

- The device is portable and space efficient.
- The device is inexpensive $(\sim \$ 2,000)$.
- Data from the device is validated and standardized.
- The device provides dynamic real time data with a straightforward user interface.
- Objective data from the device can easily be documented for insurance.

In addition to improving the current device which has three adult sizes, the femur and tibia fixtures can be altered to fit more populations such as pediatric populations. An example of a smaller clamp with less side material is shown in Figure 18.


Figure 18. Computer-aided design for one pediatric clamp size in SolidWorks. Note that the design was altered to be overall smaller and the sides were trimmed down to reduce bulk and be more accommodating to scissoring action.
6. Conclusion

The MKATS device was able to measure triplanar joint angles for more than 60 healthy and clinical participants. Such data is greatly beneficial for clinicians seeking to evaluate pathologies of the knee such as ACL deficiencies and PFP. This could be extremely useful as an
objective metric for determining when fit to return to sport and justifying continuing treatment in physical therapy. Easily accessible objective metrics allow clinicians to justify compensation from healthcare payers (e.g. insurance companies) and track treatment progression.

## 7. References

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