HyperQueue: Overcoming Limitations of HPC Job Managers

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ABSTRACT

In recent years, HPC workloads and communities have undergone substantial paradigm shifts. There is an increasing amount of users that want to leverage HPC clusters to execute many simple and embarrassingly parallel tasks as easily as possible. However, due to the limitations of traditional HPC job managers, these users must often resort to manual aggregation of tasks into a smaller number of jobs to reduce job manager overhead. This approach is both labour-intensive and inefficient, as it lacks dynamic load balancing required to fully utilize computational nodes with tens or hundreds of cores. We introduce *HyperQueue* - a task scheduling runtime that can execute a large amount of tasks into jobs and dynamically load balancing them across all allocated nodes and CPU cores. *HyperQueue* is an open-source tool that is designed for ease of use and deployment.

KEYWORDS

scheduling, task management, resource management, cluster

1 INTRODUCTION

Modern HPC systems contain a large number of computational nodes, with each node having tens or hundreds of CPU cores. There is an increasing number of HPC users that want to leverage all this computational power with quite simple workloads, for example by running a large number of single-node, relatively short-lived tasks in an embarrassingly parallel manner [1].

While HPC systems are prepared for almost arbitrarily complex distributed computations, it can be surprisingly difficult to execute a large number of such simple tasks on them efficiently. HPC job managers such as SLURM [2] or PBS are almost ubiquitously used to manage computational resources of HPC clusters. The most straightforward approach in this scenario is thus to simply map each task directly to a single job.

However, this is usually infeasible, because the manager introduces nontrivial overhead and thus severely limits the amount of jobs that can be submitted by a single user. The manager is also usually configured in a way that does not allow allocating sub-node resources (running multiple jobs on a single node concurrently), either for security or performance stability reasons. Therefore, if the tasks only use a few cores, they cannot fully utilize the provided computational nodes. These limitations can pose a barrier to entry for new HPC users, since they cannot submit tasks to the cluster in a straightforward way.

To overcome these limitations, we are introducing *HyperQueue*, a task execution runtime that can efficiently execute many singlenode tasks on top of a SLURM/PBS cluster. Users can submit a large amount of tasks into *HyperQueue* in a simple way; it will then automatically aggregate tasks into a smaller amount of jobs. Once the jobs are started, it will distribute and dynamically load balance the tasks across all allocated jobs, nodes and cores to efficiently utilize available resources.

HyperQueue is an open-source Rust project released under the MIT licence: https://github.com/It4innovations/hyperqueue.

2 RELATED WORK

There are several other approaches that can be used instead of creating a separate job for each task. One alternative is to run an additional scheduler on top of ("outside") the internal job manager. Snakemake [3] can aggregate multiple tasks into groups. This approach reduces the number of submitted jobs and thus decreases the overhead introduced by the job manager. Nevertheless, this aggregation is performed eagerly, before the tasks even start to execute. Therefore, the tasks cannot be load balanced dynamically in response to actual node and core utilization.

Another option is to start a scheduling runtime within ("inside") a SLURM/PBS job to enable load balancing of tasks independently of the outer job manager. The main disadvantage of this approach is

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that the user has to manually aggregate tasks into jobs to avoid creating too many of them. Such aggregation is not always trivial and it does not enable task load balancing across different jobs, which may cause inefficient node utilization. As an example, Dask [5] can be used in this way.

To achieve both load balancing and automatic task aggregation, a scheduling system has to run both outside the job manager as well as inside the submitted jobs. Merlin [4] uses this approach, but introduces several other limitations. Its load balancing is limited, because it requires users to specify queues with predetermined concurrency and also does not allow specifying task resource requirements. It is also nontrivial to deploy, since it requires setting up several complex dependencies.

We are not aware of any existing tool that automatically aggregates tasks and also fully dynamically load balances them while being easy to deploy and use. We consider these properties crucial for enabling user-friendly execution of workflows containing many embarrassingly parallel tasks on HPC clusters.

3 HYPERQUEUE

HyperQueue is a task scheduling runtime designed to efficiently execute a large number of embarrassingly parallel tasks on a SLURM/PBS cluster in a simple way. We list the key features of HyperQueue in the following list.

Task Aggregation HyperQueue does not require any manual task aggregation. Users simply submit tasks into HyperQueue and it takes care of distributing them to computational resources (nodes and cores) allocated by SLURM/PBS. HyperQueue can either use computational resources (jobs) allocated externally, or it can submit jobs automatically, as needed by the current workload.

Load balancing HyperQueue uses a work-stealing scheduler that supports task resource requirements (how many cores does a task need), task priorities, core pinning and is NUMA-aware. The scheduler is dynamic with respect to computational resources; new workers may be added or removed during workload computation and new tasks may be submitted at any time.

Scaling HyperQueue supports task arrays and also output streaming, which reduces pressure on network filesystems commonly present on HPC clusters. The average runtime overhead is around 100μ s per task, which allows processing of fine-grained tasks.

Deployment HyperQueue is distributed as a single binary that depends only on libc, does not need any third-party services, and does not require any elevated privileges; it is thus trivial to deploy.

3.1 Architecture

The architecture of HyperQueue is depicted in Figure 1. The central component is the server, which manages workers and schedules tasks onto them. It is designed to be a long-lived process which can be deployed e.g. on a login node. Users can connect to it in order to submit tasks or observe the status of computation.

The worker component runs on the computational nodes of a cluster, inside a SLURM or a PBS job. Its main purpose is to execute tasks assigned to it by the server. The workers communicate with the server over the network; they must be able to initiate a TCP/IP connection to the server.



Figure 1: HyperQueue architecture

3.2 Usage example

- (1) Start server on a login node:
 - \$ hq server start &
- (2) Ask for a Slurm/PBS job and start HyperQueue worker
 - Ask for nodes in PBS:
 - \$ qsub <qsub-args> -- hq worker start
 - Ask for nodes in SLURM:
- \$ sbatch <sbatch-args> --wrap "hq worker start"
 (3) Submit a task:
 - \$ hg submit my-computation.sh
- (4) Check the status of the computation:

\$ hq	jobs		
Id	Name	State	Tasks
1	my-computation.sh	FINISHED	1

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HyperQueue

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HyperQueue lets you easily execute millions of embarrassingly parallel tasks on a Slurm/PBS cluster with dynamic load balancing and NUMA-aware scheduling

Motivation

1

Many simple tasks

Slurm/PBS Cluster

HyperQueue

Runtime designed for executing a large number of tasks.

Transparent task execution on top of a Slurm/PBS cluster



5



Execute a large number of simple, embarrassingly parallel tasks on an HPC cluster as easily as possible.

Challenges

2

Task duration x Job manager overhead

- Tasks can be very short (milliseconds)
- Workflows can contain a large number of tasks
- HPC job managers introduce a lot of overhead per each task Challenge #1: Keep overhead per task minimal

Task core granularity x Node utilization

Tasks use diverse (often small) amounts of threads/cores

Tasks are distributed amongst jobs, nodes and cores Slurm/PBS jobs with HQ workers are started automatically

Dynamic load balancing across jobs

NUMA-aware work-stealing scheduler Supports core pinning, task priorities, task arrays Nodes and tasks may be added/removed on the fly

• Scalability

Low overhead per task (~100 µs) Handles hundreds of nodes and millions of tasks *Output streaming* avoids creating many files on network filesystems

• Easy deployment

Single binary, no installation, depends only on *libc* No elevated privileges required

• Open source

Usage example

HPC nodes contain many (tens, hundreds) cores
HPC job managers often allow only a single job per node
Challenge #2: Achieve high node utilization

Limitations of existing approaches

3

Submit tasks directly as Slurm/PBS jobs

- \square High overhead per task \rightarrow limited task throughput
- \bigcirc Usually only a single job per node allowed \rightarrow inefficient node usage
- Manual aggregation of tasks into jobs is required to reduce overhead

Run a meta-scheduler outside of Slurm/PBS e.g. Snakemake

- More tasks may be submitted than what Slurm/PBS allows
- \bigcirc No dynamic task load balancing \rightarrow inefficient node usage
- Manual aggregation of tasks into jobs is required to reduce overhead

Distribute tasks inside each Slurm/PBS job

e.g. Dask, GNU Parallel

- Load balancing across nodes inside a job
- No load balancing across jobs





Manual aggregation of tasks into jobs is required to reduce overhead

Run both outside Slurm/PBS and inside its jobs Merlin

- Automatically load balances tasks into jobs
- Load balances tasks inside jobs
- Queues with fixed concurrency \rightarrow balancing not fully dynamic
- Obes not allow specification of CPU task requirements
- Nontrivial to deploy



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