Constraining galaxy-halo connection with high-order statistics

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ABSTRACT

We investigate using three-point statistics in constraining the galaxy-halo connection. We show that for some galaxy samples, the constraints on the halo occupation distribution parameters are dominated by the three-point function signal (over its two-point counterpart). We demonstrate this on mock catalogues corresponding to the Luminous red galaxies (LRGs), Emission-line galaxies (ELGs), and quasars (QSOs) targeted by the Dark Energy Spectroscopic Instrument (DESI) Survey. The projected three-point function for triangle sides less up to $20 h^{-1}$ Mpc measured from a cubic Gpc of data can constrain the characteristic minimum mass of the LRGs with a preci sion of 0.46 per cent. For comparison, similar constraints from the projected two-point function are 1.55 per cent. The improvements for the ELGs and QSOs targets are more modest. In the case of the QSOs, it is caused by the high shot-noise of the sample, and in the case of the ELGs, it is caused by the range of halo masses of the host haloes. The most time-consuming part of our pipeline is the measurement of the three-point functions. We adopt a tabulation method, proposed in earlier works for the two-point function, to significantly reduce the required compute time for the three-point analysis.

Key words: cosmology: theory - galaxies: haloes - large-scale structure of Universe.

1 INTRODUCTION

Simulations of structure formation have proven to be invaluable in analysing cosmological data (Bertschinger 1998; Vogelsberger et al. 2020). They are used for studying nonlinear gravitational evolution, validating and calibrating theoretical models of structure formation, and estimating covariance matrices of clustering measurements. Cold dark matter simulations are the easiest to produce. They provide us with an accurate picture for the clustering of dark matter haloes (Bagla 2005; Dehnen & Read 2011). The positions of galaxies cannot be obtained from the cold dark matter simulations. They depend on baryonic physics that is not captured by the cold dark matter simulations (Vogelsberger et al. 2014; Schaye et al. 2015). In

addition, resolving galaxies in large volumes requires a much higher mass resolution that cannot be realized with current computers. Galaxy surveys, on the other hand, measure positions of galaxies rather than their host dark matter haloes. It is essential to have an accurate method of placing galaxies in these dark matter simulations for the robust analysis of such data.

The Halo Occupation Distribution (HOD) approach is currently one of the most widely used methods to achieve this goal (Jing, Mo & Börner 1998; Seljak 2000; Peacock & Smith 2000; Scoccimarro et al. 2001; Berlind & Weinberg 2002; Cooray & Sheth 2002; Zheng et al. 2005; Zheng, Coil & Zehavi 2007; Zheng et al. 2009). In the HOD framework, galaxies are placed in haloes based on some probabilistic prescription that depends on the properties of the host halo and its neighbourhood. In the basic HOD models, the probability of a halo to host a certain number of galaxies only depends on its mass. In more complicated models, it can also depend on the local density

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of haloes around the host and some features of the history of the halo formation. Models of various complexity have been offered for where exactly to place the galaxies inside the halo and how to assign velocities to those galaxies.

An alternative approach to connect galaxies and haloes is the subhalo abundance matching (SHAM) method (Kravtsov et al. 2004; Vale & Ostriker 2004, 2006; Conroy, Wechsler & Kravtsov 2006; Behroozi, Conroy & Wechsler 2010; Guo et al. 2016). By assuming a monotonic relation between certain halo properties and certain galaxy properties, a galaxy catalogue can be generated by matching the observed list of galaxies sorted by galaxy property with a list of haloes (and sub-haloes) sorted by halo property from simulations. The method based on a Conditional Luminosity Function, which models galaxies as a function of both their luminosity and host halo mass, is another alternative (Yang et al. 2003; Cooray 2006; Cooray & Ouchi 2006; Wang et al. 2010).

The HOD models have adjustable parameters that are tuned to obtain galaxies as similar as possible to the observed sample. Traditionally, they are constrained by their two-point correlation function (2PCF), which is the likelihood of finding a pair of galaxies with a certain separation. The 2PCF for separations up to $20 h^{-1}$ Mpc is usually used for this purpose (White et al. 2011; Richardson et al. 2012; Zhai et al. 2017; Alam et al. 2020; Avila et al. 2020; Rossi et al. 2021; Zhou et al. 2021).

The 2PCF alone does not always have enough constraining power. Many different combinations of HOD parameters may result in a 2PCF that is consistent with the data within the measurement errors. One way of improving the constraints is to also fit the observed three-point correlation function (3PCF), which is a probability of finding a triplet of galaxies with certain side lengths and orientation concerning the line of sight with respect to an observer (Hoffmann et al. 2018; Hoffmann, Bel & Gaztañaga(2017.

The usage of the 3PCF to constrain galaxy–halo connection has a long history (Wang et al. 2004; Gaztañaga & Scoccimarro 2005; Fosalba et al. 2005; Marín et al. 2008). In more recent work, Kulkarni et al. (2007) studied the shape dependence of reduced 3PCF and found that signal from reduced 3PCF could help break the degeneracy between HOD parameters. Marín (2011) measured the redshift-space 3PCF of LRGs from SDSS on large scales up to 90 h^{-1} Mpc and used the 3PCF to constrain bias parameters, which in turn helps estimate the LRG HOD parameters. Guo et al. (2015b) explored the constraining power of redshift space 3PCF on HOD parameters, including the galaxy velocity bias. Yuan, Eisenstein & Garrison (2018) tested the potential extra constraining power of HOD parameters from squeezed 3PCF (Yuan, Eisenstein & Garrison 2017).

The top panel in Fig. 1 schematically shows the steps required to constrain the HOD parameters with a 2PCF or a 3PCF. For a set of HOD parameters, we populate mocks with galaxies according to that model. We then measure the clustering statistics of interest, it is compared with a similar measurement from the data, and the posterior likelihood is assessed. This process is repeated many times for various HOD parameter sets until the posterior likelihood is well explored. The most time-consuming part of this algorithm is computing the 2PCF and the 3PCF. Computing the 3PCF is especially time-consuming. The number of all possible triplets scales as N_{gal}^3 , where N_{gal} is the number of galaxies in the sample. For a big sample, this requires looking at many millions of triangular configurations. This computation needs to be performed at each point in the MCMC chain. Recent works have proposed algorithms that make it possible to compute certain combinations of 3PCF with N_{gal}^2 complexity (Slepian & Eisenstein 2015, 2016; Philcox et al. 2022), but even The bottom panel in Fig. 1 shows similar schematics for the tabulation approach that has been first proposed by Neistein et al. (2011) and extended by Zheng & Guo (2016). In this approach, the 2PCF of some subsets of haloes is precomputed separately before the MCMC stage. These measurements are then combined with certain weights to statistically emulate various HOD population schemes. We describe the tabulation method in detail in Section 3. This approach saves a lot of computation time since the most time-consuming part of the algorithm is performed only once before launching the MCMC chain.

The tabulation method was initially developed for the 2PCF-based fits, but it is trivially generalizable to the 3PCF. Many of the 3PCFbased results that we present in this paper would have required prohibitive computation times with the traditional approach.

We test our method on the galaxies designed to emulate the Luminous red galaxies (LRGs), the Emission line galaxies (ELGs), and the quasars (QSOs) targeted by the Dark Energy Spectroscopic Survey (DESI Collaboration et al. 2016). We show the 3PCF constraints on the HOD parameters dominate the 2PCF results for the DESI-like LRGs. 3PCF has up to 70 per cent improvement for a certain parameter. For the ELG and the QSO galaxies, the improvements offered by adding the 3PCF are more modest because of the lower typical host halo mass and lower density of those tracers.

2 HOD ANALYSIS PIPELINE

2.1 HOD model

We use a HOD prescription in which the expectation value of galaxies hosted by a dark matter halo only depends on the virial mass of the halo. The expectation value is different for central galaxies that occupy the centre of the halo, and for satellites that are in virial motion around the centre.

For the LRGs, we use

$$\langle N_{\rm lrg}^{\rm c} \rangle(M) = \frac{A_{\rm c}}{2} \left(1 + \operatorname{erf}\left[\frac{\log(M) - \log(M_{\rm cut})}{\sigma}\right] \right).$$
 (1)

$$\langle N_{\rm lrg}^{\rm s} \rangle(M) = A_{\rm s} \left(\frac{M-M_0}{M1}\right)^{\alpha} H(M-M_0). \tag{2}$$

The central probability increases with mass until it saturates at some high mass value. The satellite probability is zero below some threshold mass but increases as a power law above that mass.

In both formulas, M is the mass of the host halo. A_c , referred to as a duty cycle in the literature, is a maximum probability for high mass haloes to host an LRG. M_{cut} is the characteristic minimum mass to host an LRG. σ describes how steeply the probability increases with halo mass around M_{cut} . M_0 is a mass threshold for the satellite galaxies. α controls the steepness of the increase in the satellite probability with the host halo mass. M_1 is the extra mass above the threshold that the halo must have for the expected number of satellites to be equal to one. A_s sets an overall amplitude of the probability. In principle, this parameter is fully degenerate with M_1 . We use A_s for convenience when creating mock catalogues because it can be changed independently of other parameters to adjust the overall number density of the galaxies without affecting their distribution across masses. H is a Heaviside step function.

This model has been demonstrated to describe well the LRGs in BOSS and eBOSS surveys (e.g. White et al. 2011; Zhai et al. 2017; Alam et al. 2020; Rossi et al. 2021; Zhou et al. 2021).



Figure 1. The flow chart in the top panel shows the conventional sequence of steps leading to the HOD constraints. The bottom panel shows the same flow chart for the tabulation approach.

For the ELGs (e.g. Avila et al. 2020), the central probability is a Gaussian function that decays at both high and low mass ends. The satellite probability is similar to the LRGs,

$$\langle N_{\text{elg}}^{\text{c}} \rangle(M) = \frac{A_{\text{c}}}{\sqrt{2\pi\sigma}} \exp\left(-\frac{\left[\log(M) - \log(M_{\text{cut}})\right]^2}{2\sigma^2}\right)$$
(3)

$$\langle N_{\text{elg}}^{s} \rangle(M) = A_{s} \left(\frac{M - M_{0}}{M_{1}}\right)^{\alpha} H(M - M_{0}).$$

$$(4)$$

 $M_{\rm cut}$, in this case, describes the most probable halo mass to host a central ELG and σ is the variance in the width of this pdf as a function of mass.

For the QSOs, we use a similar formula for the central probability but a slightly modified formula for a satellite probability.

$$\langle N_{\rm qso}^{\rm c} \rangle(M) = \frac{A_{\rm c}}{2} \left(1 + \operatorname{erf}\left[\frac{\log(M) - \log(M_{\rm cut})}{\sigma}\right] \right),$$
 (5)

$$\langle N_{\rm qso}^{\rm s} \rangle(M) = A_{\rm s} \left(\frac{M}{M_1}\right)^{\alpha} \exp\left(-\frac{M_0}{M}\right).$$
 (6)

The difference from the LRG is that the QSO hosting probability decays exponentially at lower masses instead of having a sharp cutoff. M_0 , in this case, controls the decay rate as we go to the lower masses, while M_1 sets the normalization (e.g. Richardson et al. 2012; Smith et al. 2020).

There is substantial evidence that the probability of a halo hosting a certain galaxy may depend on other parameters in addition to the virial mass, a phenomenon called an assembly bias (Croton, Gao & White 2007; Gao, Springel & White 2005; Pujol et al. 2017; Artale et al. 2018; Zehavi et al. 2018; Hadzhiyska et al. 2020, 2021). In this work, we ignore the assembly bias. This does not affect our main conclusions, since the main objective of our work is to study a potential improvement in the HOD parameter constraints, and we don't expect our conclusions to be sensitive to the exact nature of the HOD model.

2.2 Mock galaxy catalogue

We use the ABACUSSUMMIT cosmological N-body simulation to create mock galaxy catalogues (Garrison et al. 2021; Bose et al. 2021; Garrison, Eisenstein & Pinto 2019; Garrison et al. 2018, 2016; Metchnik 2009). ABACUSSUMMIT was designed to meet the cosmological simulation requirements of DESI. Specifically, we use the AbacusSummit_highbase_c000_ph100 box of ABACUSSUM-MIT with Planck 2018 cosmology, box size of $1000 h^{-1}$ Mpc per side, and 3456³ dark matter particles with the mass of $2.1 \times 10^9 \, h^{-1} \, \mathrm{M_{\odot}}$ per particle. We use the cleaned COMPASO (Hadzhiyska et al. 2022) halo catalogue at the z = 0.8, 1.1, and 1.4 snapshots to create the LRG, ELG, and QSO samples, respectively. These are the redshifts at which the number densities of the tracers are expected to peak.ABACUSSUMMIT suite provides multiple nested definitions of haloes, out of which we use the level two (L2) haloes (see, Hadzhiyska et al. 2022, for the details of the halo definition). We use the centre of mass position and velocity of the largest L2 subhalo fields, x_L2com and v_L2com, and generate our mocks in redshift space. ABACUSSUMMIT simulations come with a subsample (3 per cent) of particles that make each halo, which will then be used for satellite population. Based on the HOD parameters we chose, galaxies with a host halo mass lower than $10^{11} h^{-1} M_{\odot}$ barely exist. We then set a cut-off mass and removed all halo with a mass smaller than $10^{11} h^{-1} M_{\odot}$ when populating HOD mock catalogues for all tracers (see Appendix A).

Table 1 shows the fiducial parameter values that we use to create LRG, ELG, and QSO catalogues. They were obtained by fitting to the early version of the DESI Survey Validation data. These values may change as more DESI data is accumulated. For the purposes of our project, however, the exact fiducial values do not matter. The top panel in Fig. 2 shows the expected number of galaxies per halo as a function of the halo mass, and the bottom panel shows the probability distribution of host halo mass for a galaxy normalized as the probability per log (M), based on fiducial parameter values in

Table 1. Fiducial values of HOD parameters for each tracer and the resulting comoving number density in units of $10^{-4} h^{-1} Mpc^{-3}$.

Parameters	LRG	ELG	QSO
$\log(M_{\rm cut})$	12.70	11.70	12.50
σ	0.17	0.08	0.30
$\log(M_1)$	13.80	12.00	15.00
$\log(M_0)$	12.13	11.60	12.00
α	1.28	0.33	1.20
Ac	0.70	0.025	0.05
As	0.70	0.03	1.00
n	5.14	6.35	0.415
z	0.8	1.1	1.4



Figure 2. The top panel shows the expected number of galaxies hosted by a halo as a function of halo mass for the fiducial HOD parameters. The blue, orange, and green colours are for the LRG, ELG, and QSO, respectively. The solid, dash, and dash–dotted lines represent the expected number of all (cen + sat), central, and satellite galaxies. The bottom panel shows the probability distribution of host halo mass for a galaxy of each tracer. The solid line shows the host halo mass distribution for all, normalized as the probability per log (*M*), and the dashed and dash–dotted line show central and satellite host halo mass distribution, respectively.

Table 1. The host halo mass of ELG is smaller and more concentrated than that of LRG and QSO.

For each dark matter halo, we make a random decision on whether to put a central galaxy in it and how many satellites (if any) we put in the halo. We compute the probability of a central galaxy and make a random draw from the Bernoulli distribution $B(1, \langle N^c \rangle)$ and if it results in 1, we put a galaxy in the centre of the halo. As for satellites, we chose the particle-based population approach (e.g. Yuan et al. 2018), we compute the average number of satellites, then make a random draw from Bernoulli distribution $B(1, \langle N^s \rangle / N_p)$ and if it results in 1, we put a galaxy in the particle position, where N_p is the number of particles attached to the halo. The total number of galaxy distribution is then Poissonian, $p(N|M) = \text{Pois}(\langle N|M \rangle)$.

We assign the velocity of the halo to the central galaxy and the velocity of the particle to the satellite galaxy. Recent works (Guo et al. 2015a, c) have shown that there is evidence for the velocity bias, the velocity of galaxies being systematically different from the velocity of the dark matter field at the same position. We ignore velocity bias in this work. This should not affect our results for the reasons outlined in the previous paragraph.

The procedure for creating mock catalogues is intrinsically stochastic. Depending on the outcomes of random draws, we can get many different equivalent realizations of the galaxy population following the same HOD model on average.

2.3 Projected correlation functions

2PCF, $\xi^{(2)}(\mathbf{r})$, describes a probability of finding two galaxies in infinitesimal volumes dV_1 and dV_2 that are separated by r. This probability is proportional to $dV_1 dV_2 [1 + \xi^{(2)} r)]$ and is conventionally normalized so that for particles distributed in space with uniform probability (all spatial points are equally likely to host a particle) $\xi^{(2)}(\mathbf{r}) = 0$. The 3PCF, $\xi^{(3)}(\mathbf{r}_{12}, \mathbf{r}_{23}, \mathbf{r}_{31})$, is similarly defined as an excess probability (over spatially uniform distribution) of finding a triplet of galaxies to be separated by r_{12} , r_{23} , and r_{31} (Peebles 1980). 2PCF of observed galaxies depends only on the along and across the line-of-sight separations (with respect to the observer) of galaxies instead of the full separation vector, $\xi^{(2)}(\mathbf{r}) = \xi^{(2)}(r_{\rm p}, \pi)$ where $r_{\rm p}$ is a distance perpendicular to the line of sight and π is a distance along the line of sight. The 3PCF similarly depends on three perpendicular separations and two relative distances along the line of sight, $\xi^{(3)}(\mathbf{r}_{12}, \mathbf{r}_{23}, \mathbf{r}_{31}) = \xi^{(3)}(r_{p12}, r_{p23}, r_{p31}, \pi_{12}, \pi_{23})$. The variations in the line of sight separation in these correlation functions depend on the velocities of the galaxies in addition to their positions. To make HOD modelling easier, projected correlation functions are often used (Davis & Peebles 1983; Zheng 2004). They are defined by

$$w_{\rm p}^{(2)}(r_{\rm p}) = \int_{-\pi^{\star}}^{\pi^{\star}} \mathrm{d}\pi\xi^{(2)}(r_{\rm p},\pi),\tag{7}$$

$$w_{\rm p}^{(3)}(r_{\rm p12}, r_{\rm p23}, r_{\rm p31}) = \int_{-\pi^{\star}}^{\pi^{\star}} d\pi_1 d\pi_2 \xi^{(3)}(r_{\rm p12}, r_{\rm p23}, r_{\rm p31}, \pi_1, \pi_2).$$
(8)

The value of π^* is usually chosen to be of the order of a few tens of megaparsecs. This is done to smooth over peculiar velocity effects that affect the functional dependence of the correlation functions in the parallel to the line-of-sight direction. We derive our main results using the value of $\pi^* = 100 h^{-1}$ Mpc for the projected 2PCF. This value is large enough for the residual peculiar velocity effects to be negligible. Although, these projected correlation functions will depend on the velocities of the galaxies unless $\pi^* \to \infty$ (see e.g. Norberg et al. 2009; van den Bosch et al. 2013). Lower values of π^* maybe optimal because they do not depend on large-scale correlations that are noisier, but using a lower integration limit would require careful modelling of the peculiar velocity effects, and the difference turns out not to be big enough to affect any of our main conclusions (see Appendix B).

2.4 Measuring projected correlation functions

The 2PCF and 3PCF are usually measured by counting the number of galaxy pairs and triplets for the data and for uniform distribution in the same volume. They can be estimated from these pair and triplet counts by

$$\xi^{(2)}(r_{\rm p},\pi) = \frac{DD(r_{\rm p},\pi)}{RR(r_{\rm p},\pi)} - 1,$$

$$\xi^{(3)}(r_{\rm p12}, r_{\rm p23}, r_{\rm p31}, \pi_1, \pi_2) = \frac{DDD(r_{\rm p12}, r_{\rm p23}, r_{\rm p31}, \pi_1, \pi_2)}{RRR(r_{\rm p12}, r_{\rm p23}, r_{\rm p31}, \pi_1, \pi_2)} - 1,$$
(10)

where *DD* is the number of pairs of galaxies separated by certain radial and transverse distances, *DDD* is the number of triplets of galaxies having a specific triangular configuration, and *RR* and *RRR* are the equivalent number of pairs and triplets from a uniform random distribution. Additive factors of -1 normalize the correlations to be zero when $DD \sim RR$ and $DDD \sim RRR$.

We compute the two-point projected correlation functions by estimating the 2PCF first and then integrating the estimated correlation functions over π . For the three-point projected correlation function, we use a slightly modified algorithm. Instead of equation (8), we compute a simplified version (SV),

$$w_{p(SV)}^{(3)} = \frac{\sum_{\pi_1,\pi_2} DDD(r_{p12}, r_{p23}, r_{p31}, \pi_1, \pi_2)}{\sum_{\pi_1,\pi^2} RRR(r_{p12}, r_{p23}, r_{p31}, \pi_1, \pi_2)} - 1$$
$$= \frac{DDD(r_{p12}, r_{p23}, r_{p31})}{RRR(r_{p12}, r_{p23}, r_{p31})} - 1.$$
(11)

This is not the same projected correlation function as the one defined in equation (8). Equation (8) computes the integral over π_1 and π_2 , which still needs triangle counting in a five-dimensional (5D) space. On the other hand, equation (11) computes a ratio of sums over π_1 and π_2 , which reduces triangle counting to a 3D space only based on r_{p12} , r_{p23} , and r_{p31} . What we estimate with equation (11) is still a three-point function that depends on the distribution of triangular configurations, and it is projected in a sense that it is insensitive to the radial separation between the three galaxies (and therefore also insensitive to the velocities of the galaxies). The second function is significantly easier and faster to compute. We choose the \hat{z} -direction of the ABACUSSUMMIT boxes to be the line of sight of the observer. This makes the projected distance along z the π and the projected distance in the x-y plane the r_p . This lets us completely ignore the \hat{z} -direction and significantly accelerate the triplet counting part of the algorithm. We use a modified version of the GANPCF package.¹ which is a GPU accelerated tool for N-point correlation function measurements, to compute the DDD counts defined this way.

We measure the *DD* counts of the projected 2PCF using COR-RFUNC package (Sinha & Garrison 2020; Sinha & Garrison 2019) setting $\pi^* = 100 h^{-1}$ Mpc. A smaller value of π^* would result in a less noisy measurement, but since our main objective is to compare the relative constraining power of the two- and three-point clustering, we need to compute both in similar settings.

Our volume is a simple periodic cube, and the *RR* and *RRR* counts for the uniform distribution can be computed analytically (see Appendix C for analytical *RRR* computation).

The correlation functions change more rapidly at small separations. We require narrower bins at smaller separations in order not

¹https://github.com/dpearson1983/ganpcf



Figure 3. projected separation as a function of the triangular index.

to lose too much information to the binning effects. To achieve this, we measure $w_p^{(2)}(r_p)$ in 12 bins equally spaced in $\log_{10} r_p$ between 0.1 and 20 h^{-1} Mpc.

We use the same binning for the three sides of the $w_{p(SV)}^{(3)}(r_{p12}, r_{p23}, r_{p31})$. We arrange triplets of separations by starting with all possible unique triplets that satisfy $r_{p12} \leq r_{p23} \leq r_{p31}$. We start with the triplet that has all three sides belonging to the shortest separation bin. We then arrange all other triplets so that each following triplet is in increasing order of r_{p12} . Triplets that have equal r_{p12} are internally arranged by increasing r_{p23} . Finally, the triplets that have both r_{p12} and r_{p23} equal are arranged by increasing r_{p31} . We remove triplets for which the midpoints of the bins do not satisfy the triangular condition $r_{p31} \leq r_{p12} + r_{p23}$. Once the triplets are arranged and sorted in this way, we assign to each one of them an integer 'triangular index'. For our choice of binning, we end up with 99 unique triangular configurations. Fig. 3 shows the values of r_{p12} , r_{p23} , and r_{p31} as a function of the triangular index.

2.5 Covariance matrix of projected correlation functions

We use the jackknife re-sampling method to estimate the variance of clustering. We divide the simulation volume into N_{sub} sub-volumes. We compute the projected 2PCF and 3PCF by omitting each one of the subvolumes. This results in N_{sub} measurements corresponding to $(N_{sub} - 1)/N_{sub}$ fraction of the origin volume. Covariance matrix from the jackknife method is then estimated by:

$$C_{i,j}^{jk} = \frac{(N_{\text{sub}} - 1)}{N_{\text{sub}}} \sum_{k=1}^{N_{\text{sub}}} (X_i^k - \bar{X}_i)(X_j^k - \bar{X}_j)$$
(12)

where X_i^k is the clustering measurements (either 2PCF or 3PCF) in the *i*th bin from the *k*th jackknife realization. Overline denotes an average measurement over all realizations.

$$\bar{X}_{i} = \frac{1}{N_{\text{sub}}} \sum_{k=1}^{N_{\text{sub}}} X_{i}^{k}.$$
(13)

This version of the jackknife realization is referred to as 'delete-one' version in the literature.

We set $N_{sub} = 400$ to make sure we have enough sub-volumes to estimate the error of 3PCF. We slice the box Z (LOS) axis into rectangles with an equal area squared base on X-Y plane. Fig. 4 shows the correlation matrices for LRGs, ELGs, and QSOs measured by the jackknife method using the HOD mock catalogue we populated as described in Section 2.2. Each panel shows a matrix



Figure 4. Correlation matrices including the projected 2PCF and projected 3PCF (simplified version) for LRGs (left-hand panel), ELGs (mid panel), and QSOs (right-hand panel) used in this analysis derived by the Jackknife re-sampling. We include all bins between $r_p = 0.1-20 h^{-1}$ Mpc for the projected 2PCF, all triangles of LRGs, triangle index from 15 to 99 of ELGs, and triangle index from 28 to 99 of QSOs for the projected 3PCF. The colour indicates the level of correlation, where red represents 100 per cent correlation and dark blue means a low level of anticorrelation.

with horizontal and vertical division dash lines. The first column displays the correlation between r_p bins in the projected 2PCF with itself (bottom) and with the triangles in the projected 3PCF(top). The second column is the correlation between the 2PCF and 3PCF (bottom) and 3PCF with itself. For the correlation matrix of LRGs, there is a strong auto-correlation for the projected 2PCF at scale $r_p > 1.4 h^{-1}$ Mpc (after 6th bin) and for the projected 3PCF with at least two triangle side lengths $r_p > 1.4 h^{-1}$ Mpc. There is a cross-correlation between 2PCF at a relatively large scale and 3PCF with at least two triangle side lengths at a corresponding scale, while other cross-correlation is quite weak. The correlation matrices of ELGs and QSOs show similar patterns as LRGs, but with a weaker correlation.

These covariances correspond to the constraining power of a one cubic Gigaparsec box. The actual DESI samples will cover a much larger volume. For small separations, the covariances on both the 2PCF and the 3PCF will scale as an inverse of a volume.

Solid circles in Fig. 5 show the projected 2PCF measurements from the mock catalogue for different tracers and the jackknife errorbars. The first bin of the ELG and the first three bins of the QSO projected correlation function have been omitted. For ELGs, it is a conservative choice to omit the smallest scale bin (see Appendix A). For QSOs, the number density of QSOs is too small to have a sufficient number of pairs on those small scales. Fig. 6 shows a similar plot for the projected 3PCF where all triangles that include the bins omitted for the 2PCF have been removed. This results in 99, 85, and 60 triangular configurations for LRGs, ELGs, and QSOs, respectively. We keep the original triangular indexes that have been assigned before the removal of the low separation triangles. As a result, the ELG triangular index starts with 15, and the QSO triangular index starts with 40.

2.6 Constraining HOD parameters

Not all three galaxy samples we consider can be constrained equally well with data from a one cubic Gigaparsec box. We find that for the LRGs it is possible to constrain all five parameters: $\log (M_{cut})$, σ , $\log (M_1)$, $\log (M_0)$, and α (A_c and A_s are used for the tuning of the number density of the LRG sample and do not affect the 2 and 3 PCF). For ELGs, constraining all five parameters turns out to be more difficult. We only let the $\log (M_{cut})$, α and A_s be free parameters and fix the remaining two to their fiducial values. A_s is degenerate in its effects with $\log (M_1)$. We choose to vary A_s in our computations for convenience. For QSOs, we need to further reduce the number of free parameters because the QSO sample has a much lower number density. We set $\log (M_{cut})$ and $\log (M_1)$ as free parameters and fix the remaining three to their fiducial values. We apply flat priors for all free parameters. The intervals are listed in Table 2. The fiducial values for the fixed parameters are listed in Table 1.

We perform Markov chain Monte Carlo (MCMC) to obtain the posterior probability distribution of parameter space. The likelihood function $\mathcal{L} \propto \exp -\chi^2/2$, where χ^2 is given by

$$\chi^2 = \Delta X_i (S')_{ij}^{-1} \Delta X_j, \tag{14}$$

where ΔX_i is the difference of binned 2PCF and 3PCF between theory and observation, which corresponding to tabulated estimation and HOD mock measurements in our case, and $(S')^{-1}$ is the inverse of the re-scaled covariance matrix. Here, we follow Percival et al. (2021) to take into account the error propagation from the error in the covariance matrix into the fitting parameters.

$$S' = \frac{(n_{\rm s} - 1)[1 + B(n_{\rm d} - n_{\rm p})]}{n_{\rm s} - n_{\rm d} + n_{\rm p} - 1}S,$$
(15)

$$B = \frac{(n_{\rm s} - n_{\rm d} - 2)}{(n_{\rm s} - n_{\rm d} - 1)(n_{\rm s} - n_{\rm d} - 4)},\tag{16}$$

where n_s is the number of jackknife realizations, n_d is the number of data points we are fitting to, and n_p is the number of free parameters in the model. *S* is the original covariance matrix.

We use a modified version of COSMOMC (Lewis & Bridle 2002) as an MCMC engine, which uses the Metropolis–Hastings algorithm, to sample the parameter space and search for the minimum χ^2 . We run 16 chains in parallel with MPI and we ignore the first 30 per cent of each chain as burn-in. We apply the Gelman and Rubin R statistic (An, Brooks & Gelman 1998) as convergence criteria, all of our chains have R - 1 < 0.01, which represents a good convergence. Since the tabulation method provides us a fast estimation of projected 2PCF and 3PCF (see Section 3), the MCMC stage takes less than half an hour to converge for a joint run using both 2PCF and 3PCF.

3 TABULATION METHOD OF COMPUTING GALAXY *N*-POINT CORRELATION FUNCTIONS

3.1 Tabulated 2PCF

The two steps leading to the pair counts of the mock catalogue - populating *N*-body mocks with galaxies and counting pairs of



Figure 5. Panels on top are the projected 2PCF from HOD mock catalogue and tabulation method with fiducial HOD parameters for different tracers. The blue, orange, and green colours are for LRGs, ELGs, and QSOs, respectively. Filled markers are measurements from the fiducial HOD mock catalogue, and errors are calculated using the jackknife method. Solid lines represent measurements from the tabulation method. Bottom sub-panel: Dot–dashed lines are absolute values of percentage difference and the light-shaded areas represent jackknife errors.



Figure 6. A similar plot for 3PCF. Panels on top are the simplified projected 3PCF from HOD mock catalogue and tabulation method with fiducial HOD parameters for different tracers. The blue, orange, and green colours are for LRGs, ELGs, and QSOs, respectively. Filled markers are measurements from the fiducial HOD mock catalogue, and errors are calculated using the jackknife method. Solid lines represent measurements from the tabulation method. Bottom sub-panel: Dot–dashed lines are absolute values of percentage difference and the light-shaded areas represent jackknife errors.

Table 2. The flat prior interval on HOD parameter for different tracer, fitting to LRG, ELG, and QSO HOD mock catalogue have 5, 3, and 2 free parameters, respectively.

Parameters	LRG	ELG	QSO
$\log(M_{\rm cut})$	[12.0, 13.5]	[11.0, 13.5]	[11.5, 13.5]
σ	[0.0001, 1.0]	_	-
$\log(M_1)$	[12.5, 14.5]	_	[13.0, 17.0]
$\log(M_0)$	[11.0, 15]	_	_
α	[0.0, 2.0]	[0.0, 2.0]	-
Ac	-	-	_
As	-	[0.0, 0.2]	-

Note. The dash represents the fiducial value.

galaxies - can be formally summarized with the equation

$$DD(r_{\rm p}) = \sum_{ij} \Theta_{ij}^{r_{\rm p}} D_i D_j, \qquad (17)$$

where each index in the double summation goes over all halo centres and halo particles,

$$\Theta_{ij}^{r_{\rm p}} = \begin{cases} 1, & \text{if distance between (i,j) pair falls within} \\ & \text{the specified } r_{\rm p} \text{ bin} \\ 0, & \text{otherwise} \end{cases}, \qquad (18)$$

and D is a stochastic variable,

$$D_i = \begin{cases} 1, & \text{if the } i \text{ th halo/particle got populated by a galaxy} \\ 0, & \text{otherwise} \end{cases}$$
 (19)

We rewrite equation (17) as

$$DD = \sum_{ij}^{N_{h}} \Theta_{ij}^{hh} D_{i}^{h} D_{j}^{h} + 2 \sum_{i,j}^{N_{h},N_{p}} \Theta_{ij}^{hp} D_{i}^{h} D_{j}^{p} + \sum_{ij}^{N_{p}} \Theta_{ij}^{pp} D_{i}^{p} D_{j}^{p}$$
(20)

explicitly separating haloes and particles, where superscripts h and p refer to the haloes and particles, respectively, $N_{\rm h}$ and $N_{\rm p}$ are the numbers of haloes and particles, and we dropped the $r_{\rm p}$ label for brevity. In the traditional approach (top panel of Fig. 1), the random numbers *D* have to be drawn for and the double sum over all

occupied haloes and particles computed for every HOD model under consideration.

The tabulation approach reduces the complexity of this computation by employing the following trick. The expectation value of the pair count is

$$\langle DD \rangle = \sum_{ij}^{N_{\rm h}} \Theta_{ij}^{hh} \lambda_i^{\rm c} \lambda_j^{\rm c} + 2 \sum_{i,j}^{N_{\rm h},N_{\rm p}} \Theta_{ij}^{hp} \lambda_i^{\rm c} \lambda_j^{\rm s} + \sum_{ij}^{N_{\rm p}} \Theta_{ij}^{pp} \lambda_i^{\rm s} \lambda_j^{\rm s}, \qquad (21)$$

where λ^c and λ^s are the expected values of that particular halo or a particle to host a central or satellite galaxy in a given HOD model. Since these numbers only depend on the mass of the host halo, we can simplify the computation by binning the haloes and particles into bins of mass in log space narrow enough to prevent a significant change in the expected values within it. The pair count can then be rewritten as

$$\langle DD \rangle = \sum_{i,j}^{N_{h}^{k},N_{h}^{\ell}} \sum_{k\ell}^{N_{b}} \Theta_{ij,k\ell}^{hh} \bar{\lambda}_{k}^{c} \bar{\lambda}_{\ell}^{c}$$

$$+ 2 \sum_{i,j}^{N_{h}^{k},N_{p}^{\ell}} \sum_{k\ell}^{N_{b}} \Theta_{ij,k\ell}^{hp} \bar{\lambda}_{k}^{c} \bar{\lambda}_{\ell}^{s} + \sum_{i,j}^{N_{p}^{k},N_{p}^{\ell}} \sum_{k\ell}^{N_{b}} \Theta_{ij,k\ell}^{pp} \bar{\lambda}_{k}^{s} \bar{\lambda}_{\ell}^{s},$$

$$(22)$$

where the indices k and ℓ now go over N_b number of mass bins, N_h^k is the number of haloes in the kth mass bin (similarly for particles), and λ^c and λ^s are the effective average expected values in each mass bin,

$$\bar{\lambda_k^{\rm c}} = \langle N^{\rm c} \rangle (M_k), \tag{23}$$

$$\bar{\lambda_k^{\rm s}} = \langle N^{\rm s} \rangle (M_k) \frac{N_{\rm h}^k}{N_{\rm p}^k},\tag{24}$$

where $\langle N^c \rangle (M_k)$ and $\langle N^s \rangle (M_k)$ are the expected numbers of central and satellite galaxies hosted by a halo in the *k*th mass bin; M_k is the representative mass in the *k*th mass bin, $\log M_k \pm (\Delta \log M)/2$, where $\Delta \log M$ is the width of log space mass bin; and $\overline{\lambda_k^s}$ [the expected total number of satellite galaxies in the *k*th mass bin, $\langle N^s \rangle (M_k) N_h^k$, divided by N_p^k] gives the average expected value for each particle to host a satellite galaxy.

Switching the order of summation, we get

$$\langle DD \rangle = \sum_{k\ell}^{N_{\rm b}} \bar{\lambda}_k^{\rm c} \bar{\lambda}_\ell^{\rm c} DD_{k\ell}^{hh} + 2 \sum_{k\ell}^{N_{\rm b}} \bar{\lambda}_k^{\rm c} \bar{\lambda}_\ell^{\rm s} DD_{k\ell}^{hp} + \sum_{k\ell}^{N_{\rm b}} \bar{\lambda}_k^{\rm s} \bar{\lambda}_\ell^{\rm s} DD_{k\ell}^{pp},$$
(25)

where

$$DD_{k\ell}^{hh} = \sum_{i,j}^{N_p^h, N_p^h} \Theta_{ij,k\ell}^{hh}$$
(26)

is the number of halo pairs with a separation that falls in the specified bin, where one member of the pair is in mass bin k while another is in mass bin ℓ (similarly for the particle–halo and particle–particle pairs).

Equation (26) is equivalent to equation (21) but has two advantages. First, it gives an average value of the number count expected for a given HOD model instead of a specific realization that includes stochastic noise. Secondly, it has the potential to save a significant amount of computational time. The most time-consuming part of the computation – the double sum over haloes and particles – can be performed only once. Changing the HOD model amounts to simply summing up precomputed pair counts with different weights, a procedure that is orders of magnitude faster. Haloes and particles live in the same periodic box, so the *RR* counts are identical for them. This means that the projected 2PCF is also a weighted average of the cross-2PCF of different mass haloes (and particles)

$$w_{p,gg}^{(2)}(r_{p}) = \sum_{k,\ell}^{N_{b}} w^{c}(M_{k})w^{c}(M_{\ell})w_{p,hh}^{(2)}(r_{p}, M_{k}, M_{\ell}) + 2\sum_{k,\ell}^{N_{b}} w^{c}(M_{k})w^{s}(M_{\ell})w_{p,hp}^{(2)}(r_{p}, M_{k}, M_{\ell}) + \sum_{k,\ell}^{N_{b}} w^{s}(M_{k})w^{s}(M_{\ell})w_{p,pp}^{(2)}(r_{p}, M_{k}, M_{\ell}),$$
(27)

where $w_{p,hh}^{(2)}(r_p, M_i, M_j)$ is the two-point cross-correlation function of haloes in the *i*th and *j*th mass bins (similarly for the halo-particle and particle–particle correlation functions) and naively, we could take the weight as

$$w_{\rm raw}^{\rm c}(M_k) = \overline{\lambda_k^{\rm c}} = \langle N^{\rm c} \rangle(M_k),$$
 (28)

$$w_{\rm raw}^{\rm s}(M_k) = \bar{\lambda_k^{\rm s}} = \langle N^{\rm s} \rangle(M_k) \frac{N_{\rm h}^k}{N_{\rm p}^k}.$$
(29)

We define equations (29) and (30) as raw weights, raw weights are a good approximation in most cases but have some exceptions. We will further explain this in Section 3.3.

Solid lines in the top panels of Fig. 5 show the galaxy projected 2PCF computed using the tabulation method. The bottom panels show the fractional deviation between the projected 2PCF computed with the tabulated method and a specific realization. The offset is, in all cases, within the expected standard deviation. The offsets are caused by the stochasticity in a specific realization, the tabulated method being almost noise-free. There is a very small stochastic noise in the tabulated 2PCF related to the finite number of haloes and particles in the box, but it is negligible compared to the noise in a single realization.

3.2 Tabulated 3PCF

We further generalize derivation in the previous section to the 3PCF. Similar arguments lead to the expression

$$w_{p,ggg}^{(3)}(\Delta) = \sum_{i,j,k} w^{c}(M_{i})w^{c}(M_{j})w^{c}(M_{k})w_{p,hhh}^{(3)}(\Delta, M_{i}, M_{j}, M_{k}) + 3\sum_{i,j,k} w^{c}(M_{i})w^{s}(M_{j})w^{s}(M_{k})w_{p,hpp}^{(3)}(\Delta, M_{i}, M_{j}, M_{k}) + 3\sum_{i,j,k} w^{s}(M_{i})w^{c}(M_{j})w^{c}(M_{k})w_{p,phh}^{(3)}(\Delta, M_{i}, M_{j}, M_{k}) + \sum_{i,j,k} w^{s}(M_{i})w^{s}(M_{j})w^{s}(M_{k})w_{p,ppp}^{(3)}(\Delta, M_{i}, M_{j}, M_{k}),$$
(30)

where r_{p12} , r_{p23} , and r_{p31} are abbreviated as \triangle . Solid lines on top panels of Fig. 6 show the galaxy projected 3PCF computed using the tabulation method. Similarly to the 2PCF, the measurement from a single realization is noisier but consistent within expected errors for all tracers.

3.3 Mass binning effects

We bin the mass of the host halo in 20 bins between around $11 < \log M_{\star} < 14.8$ (see Appendix A for details about downsampling). The bins are narrow enough to prevent a significant change in the hosting probabilities within the bins, and assigning to each halo and particle a probability at the middle of the bin (we referred to this practice as a raw probability) is in most cases a good approximation. However, there are some exceptions if we shift the satellite parameter $\log (M_0)$ of ELG a little bit to 11.7, where hosting probability drops very steeply below $\log (M_{halo}) \sim 11.7$, and the middle of the bin fails to capture satellite information. Fig. 7 demonstrates the nature of this problem.

The black dashed and dot-dashed lines in the top panel of Fig. 7 show the expected number of the central and satellite ELGs in our fiducial HOD model. Bold grey vertical dash lines and grey vertical dot-dashed lines show the edges and the middle of the mass bin. The peach and lavender histogram shows the number of haloes and particles in each mass bin. Empty triangles pointing to the right show the raw weights based on the value in the middle of the mass bin and the filled triangles pointing to the left show the refined weights. For most of the mass range, the two are very consistent. The last nonzero bin on the left (fourth bin) is the exception. The mean number drops so steeply with the mass that it reaches an extremely low number for the middle mass of that bin. If we applied weight based on that value, very few of the haloes in that mass bin would acquire a satellite. This would incorrectly down-weight the haloes close to the right edge of the mass bin that has a substantial probability of hosting a satellite.

Increasing the number of mass bins is, however, impractical as it would significantly increase the number of separate cross-correlation functions that we need to keep track of. However, this problem would go away if we used a finer binning for the mass of the host halo. We modify our probabilities as

$$w_{\rm ref}^{\rm c}(M_k) = \sum_{k'}^{N_{\rm sub}} \frac{N_{\rm h}^{k,k'}}{N_{\rm h}^k} w_{\rm raw}^{\rm c}(M_{k,k'}) = \sum_{k'}^{N_{\rm sub}} \frac{N_{\rm h}^{k,k'}}{N_{\rm h}^k} \langle N^{\rm c} \rangle(M_{k,k'})$$
(31)

$$w_{\rm ref}^{\rm s}(M_k) = \sum_{k'}^{N_{\rm sub}} \frac{N_{\rm h}^{k,k'}}{N_{\rm h}^k} w_{\rm raw}^{\rm s}(M_{k,k'}) = \sum_{k'}^{N_{\rm sub}} \frac{N_{\rm h}^{k,k'}}{N_{\rm p}^k} \langle N^{\rm s} \rangle(M_{k,k'}).$$
(32)

As shown in the lower left-hand panel of Fig. 7, we further subdivided the mass bin into $N_{sub} = 20$ sub-bins, and took a weighted average of raw weights for each sub-mass bin $w_{raw}(M_{k,k'})$ based on the number of haloes $N_h^{k,k'}$ in this sub-mass bin. The dashed line on this panel shows the raw weight of this mass bin before correction; the solid line shows the refined weight. For central weight, the difference is subtle. For satellite weight, refined weight accurately accounts the contribution of satellites from this mass bin, while raw weight failed to capture a number.

The lower right-hand panel of Fig. 7 compares the tabulated projected 2PCF computed with the raw weights and the refined weights. The raw weights clearly fail to describe the 2PCF on the scales of $r_{\rm p} < 0.1$ where the systematic offsets are more than 50 per cent of the signal.

This problem will appear whenever there are variations in the expected number of galaxies (either satellites or centrals) across the width of the bin. When using raw weights we are making an approximation

$$\int_{M_{\min}}^{M_{\max}} \mathrm{d}M \ w(M) \frac{\mathrm{d}N}{\mathrm{d}M} \approx w(\overline{M}) N^{\mathrm{tot}},\tag{33}$$

where \overline{M} is the middle of the bin, ΔM is the width of the bin, the integration is between $\overline{M} - \Delta M/2$ and $\overline{M} + \Delta M/2$, and the N^{tot} is the total number of galaxies in that bin. To see when this approximation may fail, we can expand the weight function on the left side of the equation in the Taylor series around the middle point as

$$w(M) = w(\overline{M}) + \frac{\mathrm{d}w}{\mathrm{d}M}\Big|_{M=\overline{M}} (M-\overline{M}) + \frac{1}{2} \frac{\mathrm{d}^2 w}{\mathrm{d}M^2}\Big|_{M=\overline{M}} (M-\overline{M})^2 + \mathcal{O}[(M-\overline{M})^3].$$
(34)

The integral over the first term results in $w(\overline{M})N^{\text{tot}}$, which exactly matches with our approximation. The second term integrates to zero (as an odd function over symmetric limits). The third term integrates to $w''(\overline{M})(\Delta M)^3 N^{\text{tot}}/24$, here the double prime denotes the second derivative with respect to halo mass, ΔM is the width of the bin.² This is the leading error term and it needs to be small for the approximation to be valid. The condition is

$$\frac{w''(M)}{w(\overline{M})} \ll \frac{24}{(\Delta M)^3}.$$
(35)

If this condition between the second derivative of the weights and the width of the mass bin starts breaking down the weight refining procedure described in this section may be in order. This condition is obviously broken for our HOD models since they contain a discontinuous function in the satellite probability in equations (2) and (4).

4 RESULTS

We create DESI like LRG, ELG, and QSO samples as described in Section 2.2. We then use the MCMC method to fit the HOD parameters for the model described in Section 2.6 with the covariance matrix obtained as described in Section 2.4. The covariance matrix represents the variance in the measurements expected from a cosmic volume of 1 cubic GigaParsecs. The actual DESI measurements will be obtained from larger volumes, but since the errors on both the 2PCF and the 3PCF scale similarly with the volume, the relative strength of the constraints coming from the two will not change.

Fig. 8 shows 1σ uncertainty band of LRG sample HOD function from 2PCF only fitting and 2PCF + 3PCF joint fitting. The light blue band shows 68 per cent CL uncertainty from 2PCF only, and the dark blue band shows the band from 2PCF + 3PCF joint fitting. The orange line represents the fiducial HOD setting as the truth behind the mock we fit to. It is clear to see that joint fitting has a much narrow band compared to the one using 2PCF only, especially for the range log ($M_{halo} > 12.7$), which indicate a much better constraint on satellite parameters from joint fitting. Fiducial HOD lie in the 1σ band shows a good recovery for both cases.

 2 We are assuming that the fundamental quantities, such as the number of haloes and the bias of haloes, do not change significantly within the bin. If this is not the case, the binning is obviously too broad and needs to be refined.



Figure 7. Mass binning effects for ELGs when shift satellite parameter $\log(M_0)$ slightly to 11.7 from fiducial, all other parameters remain at fiducial value. Top panel: Gray vertical lines show the edges (dashed) and the middle points (dashed–dotted) of the mass bins. The lines show the expected number of centrals (dashed) and satellites (dashed–dotted). The bars show the available number of haloes (peach) and particles (lavender) in the simulation. Triangles show the weight of satellites computed with the raw probabilities (open) and refined probabilities (filled). The open and filled circles show the same information for the centrals. Bottom left-hand panel: A zoom-in version of the fourth mass bin, where raw weights do not work. Thin dotted vertical lines show the edges of sub-mass bin. The peach bars show the number of haloes in each sub-mass bin. The open circles and triangles show values of raw weights for each sub-mass bin. The orange horizontal dash line shows refined satellite weight for the fourth mass bin, and the orange solid line shows refined central weight for the fourth mass bin, and there is no dash purple line for raw satellite weight because the value is zero. Bottom right-hand panel: blue squares show the measured projected 2PCF of the galaxies from the ELG HOD mock catalogue using HOD parameters plotted. Lines show the projected 2PCF computed with the tabulated method using the raw (dashed) and refined (solid) weights.



Figure 8. 1σ band of LRG sample HOD. The light blue is the 68 per cent CL uncertainty from projected 2PCF only, and the dark blue band is the 68 per cent CL uncertainty from joint fitting of projected 2PCF and simplified version projected 3PCF. Orange line is the fiducial HOD of an LRG sample.

Fig. 9 shows 1 and 2σ confidence level contours on the HOD parameters for the LRG sample. These constraints are dominated by the $w_{p(SV)}^{(3)}$. The improvement is especially large for the parameters log M_{cut} , σ , and log M_1 . The 3PCF constraints on those parameters improve by 70, 49, and 62 per cent, respectively, compared to the 2PCF results. Combined fitting does not significantly differ from the 3PCF only results. Table 3 summarizes the marginalized statistic for each fit. From the 1D distribution of each parameter in Fig. 9, all cases successfully recover the fiducial HOD parameters.

Figs 12 and 13 show 1 and 2σ confidence level contours for the ELG at redshift 1.1 and 0.8 and QSO samples at redshift 1.4, respectively. We only free HOD parameters as shown in the contours for these tracers. For the ELG and QSO, the constraints are dominated by the projected 2PCF. Improvements offered by the addition of the projected 3PCF are negligible.

There could be several reasons why the LRGs benefit greatly from the addition of the 3PCF information while ELGs and QSOs do not. One potential explanation is that the ELGs and QSOs are at higher redshifts where matter underwent less nonlinear evolution



Figure 9. Marginalized probability distribution of HOD parameters for DESI like LRG sample at z = 0.8. The results from the projected 2PCF and 3PCF are shown in grey and red, respectively. Blue shows the joint constraints from the two. The contours represent 68 and 95 per cent confidence levels. 1D marginalized distribution for each parameter is shown on top of each column. The dash line and light yellow cross markers show fiducial HOD parameter values.

and the three-point signal is not as pronounced. Another potential explanation is that galaxies of different host halo masses are not equally sensitive to the three-point information (see e.g. Kulkarni et al. 2007).

To study the sensitivity of 2PCF and 3PCF to HOD parameters at different fiducial values we make a plot of the partial derivative of $w_p^{(2)}$ and $w_{p(SV)}^{(3)}$ with respect to log (M_{cut}) normalized to the variance in the measurement at the fiducial value. Fig. 10 shows partial derivatives of the 2PCF and the 3PCF with respect to log (M_{cut}) with other parameters fixed to their fiducial value. To make the plot more readable, we separate it into two parts. The top panel covers the range 12 < log (M_{cut}) < 13.5 while the bottom panel covers 13.5 < log (M_{cut}) < 14. High values of this derivative mean that the measurement at that specific bin is highly sensitive to small changes in M_{cut}

The derivative of $w_{\rm p}^{(2)}$ reaches its highest value at $\log (M_{\rm cut}) = 13.28$ then drops back, while the derivative of $w_{\rm p(SV)}^{(3)}$ keeps increasing up until 13.5 and only then drops down. The 3PCF displays a larger cumulative sensitivity in the range $\log (M_{\rm cut}) > 13.16$, below which the 3PCF is not as sensitive to small changes in $M_{\rm cut}$ as $w_{\rm p}^{(2)}$.

Another thing apparent from the figure is that the small-scale triangles are more sensitive to $\log (M_{cut})$ compared to their large-scale counterparts (as evident by the local peaks in the right-hand panel). Those triangles with all side lengths within the first 6 bins (side lengths $r_p < 1.41 h^{-1}$ Mpc, corresponding to triangle indices 1-8, 15-21, 28-33, 40-43, 51-53, 61), peak at $\log (M_{cut}) = 13.5$, while other triangles behave just like $w_p^{(2)}$, dropping back at $\log (M_{cut}) =$



Figure 10. Partial derivative of w_p with respect to log (M_{cut}) normalized using error of w_p when fixing other HOD parameters. Plot has been separated into two panels to avoid overlap when partial derivative drop down.



Figure 11. Similar plot as Fig. 10 for ELG sample at fiducial redshift z = 1.1.

13.28. The different behaviour of small scale triangles and small scale pairs leads to a higher sensitivity to HOD parameter changes for small scale $w_{pSV}^{(3)}$. The normalized derivative of $w_{p(SV)}^{(3)}$ hit around 3000 while $w_{p}^{(2)}$ remains at 1500.

Fig. 11 shows the similar plots for ELG sample at z = 1.1. The sensitivity in both the 2PCF and the 3PCF increases in the range of 11.3 < log (M_{cut}) < 11.98 and then drops in the range of 11.98 < log (M_{cut}) < 13.5. At this redshift, the top sensitivity is achieved at the values of around log (M_{cut}) = 11.98. The sensitivity of $w_p^{(2)}$ at the top is higher than the sensitivity of the $w_{p(SV)}^{(3)}$. For ELGs, means a lower sensitivity for 3PCF. The cumulative sensitivity at the peak is also larger for the 2PCF compared to the 3PCF. Small scale triplets do not show the same behaviour as the LRG sample, remaining at low sensitivity compared to small scale pairs.

These two plots show that both the redshift and the typical halo mass are responsible for the difference between the LRG and the ELG cases. The DESI LRGs happen to be in the halo mass range where the 3PCF is more sensitive to the HOD parameters, while ELGs are in the haloes with the opposite property. This is the main reason why the improvement in our ELG constraints is modest while the improvement in the LRG constraints is significant.

Plots similar to the ones presented in Figs 10 and 11 can be used to determine whether the 3PCF is expected to affect the overall HOD constraints in a meaningful way. For example, one could populate the simulation with the best-fitting HOD parameters resulting from the 2PCF fits and do the same thing with slightly offset values of HOD parameters. Derivatives of 3PCF with respect to HOD parameters can be estimated by computing the 3PCF for these mocks (using

$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	er		LRG			ELG			OSO	
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	ł .	$w_{\mathrm{p}}^{(2)}$	$w_{\mathrm{p(SV)}}^{(3)}$	$w_{\rm p}^{(2)} + w_{\rm p(SV)}^{(3)}$	$w_{\mathrm{p}}^{(2)}$	$w_{\mathrm{p(SV)}}^{(3)}$	$w_{\rm p}^{(2)} + w_{{ m p(SV)}}^{(3)}$	$w_{\mathrm{p}}^{(2)}$	$w_{p(SV)}^{(3)}$	$w_{\rm p}^{(2)} + w_{\rm p(SV)}^{(3)}$
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	$l_{\rm cut}$	12.88 ± 0.199	12.73 ± 0.058	12.73 ± 0.059	11.83 ± 0.059	11.74 ± 0.125	11.83 ± 0.054	12.47 ± 0.060	12.43 ± 0.130	12.48 ± 0.058
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$		0.315 ± 0.200	0.151 ± 0.103	0.162 ± 0.105	I	I	I	I	I	I
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	I_1	13.93 ± 0.141	13.83 ± 0.053	13.82 ± 0.047	I	I	I	15.49 ± 0.766	15.53 ± 0.851	15.53 ± 0.755
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	I_0	11.73 ± 0.431	11.76 ± 0.407	11.78 ± 0.400	I	I	I	I	I	I
$\begin{array}{cccccccccccccccccccccccccccccccccccc$		1.279 ± 0.055	1.300 ± 0.040	1.301 ± 0.038	0.188 ± 0.097	0.268 ± 0.161	0.178 ± 0.095	I	I	I
$A_{\rm s}$ – – – 0.015 ± 0.007 0.023 ± 0.016 0.015 ± 0.006		I	I	I	I	I	I	I	I	I
$\sqrt{2}/4 \circ f$ $2 \circ 5/(12 - 5)$ $36 \circ 5/(100 - 5)$ $3.4 \circ 0/(111 - 5)$ $0 \circ 0/(11 - 3)$ $57 \circ 5/(85 - 3)$ $56 \circ 7/(96 - 3)$	e f	- 2 5/(17 - 5)	- 29 5//00 - 5)	- 34 0//111 - 51	0.015 ± 0.007	0.023 ± 0.016 57 5/(85 - 3)	0.015 ± 0.006 56 7//06 $- 3$)		- 30 4//60 - 3)	- 17 6/(60 - 2)



Figure 12. Marginalized probability distribution of selected HOD parameters for DESI like ELG sample at z = 1.1 and 0.8. The results from the projected 2PCF and 3PCF are shown in grey and red, respectively. Blue shows the joint constraints between the two. The contours represent 68 and 95 per cent confidence levels. 1D marginalized distribution for each parameter is shown on top of each column. The dashed line and light yellow cross markers show fiducial HOD parameter values.

finite differences). The covariance matrix (standard error) can be computed using the jackknife method Unlike MCMC chains that typically require an order of 10 000 computations, this can be done with just a handful of 3PCF computations (a few for the numerical derivatives and an order of 100 3PCF computations for the jackknife covariance) and can be done without preparing the tabulated triplet counts. A comparison of these integrated sensitivities of the 3PCF and the 2PCF can then be used to decide whether the additional



Figure 13. Marginalized probability distribution of selected HOD parameters for DESI like QSO sample at z = 1.4. The results from the projected 2PCF and 3PCF are shown in grey and red, respectively. Blue shows the joint constraints between the two. The contours represent 68 and 95 per cent confidence levels. 1D marginalized distribution for each parameter is shown on top of each column. The dashed line and light yellow cross markers show fiducial HOD parameter values.

investment of computational resources for the computation of the tabulated triplet counts is warranted.

To test the pure redshift dependence of the constraining power of the 3PCF, we populate our ELG mock catalogue at redshift 0.8 with the same HOD parameters (tuned to the same number density, i.e. ratio of A_c and A_s remains unchanged). The results are presented on the bottom panel of Fig. 12. We do not find a significant change in the overall picture. The constraints are still dominated by the 2PCF signal. We do notice, however, that the addition of the 3PCF makes the likelihood contours more Gaussian and moves the most likely values closer to the true values somewhat, debiasing the results.

5 CONCLUSION

We studied the performance of projected 3PCFs in constraining HOD parameters for different mock galaxy samples, which are based on ABACUSSUMMIT simulation, targeted by DESI. We generalized the tabulation method to 3PCF computations to make a fast evaluation of the posterior likelihood possible.

We find that the constraints on the basic HOD parameters of the mock LRG sample with an input HOD parameter as shown in Table 1 at redshift $z \sim 0.8$ can be significantly improved by the addition of the 3PCF. The constraints on some parameters have improved by as much as 70 per cent. For the characteristic minimum mass of the central LRGs, we get the constraints $\log (M_{cut}) =$ 12.88 ± 0.199 with the 2PCF and $\log (M_{cut}) = 12.73 \pm 0.058$ with the 3PCF. For the threshold mass of the satellite LRGs, we get the constraints $\log (M_1) = 13.93 \pm 0.141$ with the 2PCF and $\log (M_1) = 13.83 \pm 0.053$ with the 3PCF. All at 1σ confidence level.

We also find that the additional constraining power offered by the 3PCF depends on the redshift of the galaxy sample as well as the typical halo mass that its galaxies occupy. The relative strength of the 3PCF increases at lower redshifts. 3PCF is also a more sensitive measurement for the samples that incorporate more massive haloes. The ELG samples of DESI are at higher redshifts and occupy less massive haloes. This results in the 3PCF not being as efficient in constraining their host halo mass ranges. For the mock ELG sample with input HOD parameter as shown in Table 1 at redshift $z \sim 1.1$ the constraints of the characteristic minimum mass of the central are $\log (M_{cut}) = 11.83 \pm 0.059$ with the 2PCF and $\log (M_{cut}) = 11.74 \pm 0.125$ with the 3PCF. For the mock QSOs with lower number density and higher redshift $z \sim 1.4$ compared to the other tracers, we get $\log (M_{cut}) = 12.47 \pm 0.060$ with the 2PCF and 12.43 ± 0.130 with the 3PCF and 2PCF remains dominant.

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DATA AVAILABILITY

The data products related to this study, including tabulated two-point and three-point counts, HOD mock catalogues, jackknife covariance matrices, and MCMC chains, are available at https://doi.org/10.528 1/zenodo.6380446.

The AbacusSummit simulations used in this study are publicly available (https://abacusnbody.org/).

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APPENDIX A: DOWNSAMPLING

The number of haloes in simulations increases rapidly towards the



Figure A1. Fraction of haloes we take from all haloes as a function of halo mass.

lower mass range. However, the contribution of low mass haloes to the 2PCF and 3PCF is negligible for the hod parameter range we are interested in (see Fig. 2).

When populating mocks, we set a hard cut-off mass for halo samples at the lower mass end. We remove all haloes with a mass less than $10^{11} h^{-1} M_{\odot}$.

For the tabulation method, to speed up pair and triangle counting when preparing tables, we downsample the lower mass haloes using the filter,

$$frac_{haloes}(M_{halo}) = \frac{1}{1 + 10 \exp\left(-25 \log(M_{halo}) - 11.2\right)},$$
 (A1)

from the ABACUSHOD package (Yuan et al. 2021). Fig. A1 shows the halo sample fraction as a function of halo mass following equation (A1). This filter will further remove excess haloes that have trivial contributions to the clustering in low-mass bins.

For the particles in the table preparation process, we randomly select 0.15 per cent of particles to make each halo for the pair and triangle counting. This small percentage is still larger than the mean satellite number for each halo.

We explicitly checked that the clustering from the tabulation method, which applied the filter, could perfectly match the clustering from mocks, which applied only a hard cut-off, around the fiducial HOD parameter area we are interested in (see Figs 5 and 6).

ELGs have a lower typical host halo mass compared to other samples, and they could in principle be affected by the filter. We omit the first separation bin for the ELGs to protect against this eventuality for some extreme HOD parameter values.

APPENDIX B: CHOICE OF MAXIMUM RADIAL SEPARATION

The choice of π^* value affects the resulting constraints on HOD parameters. To minimize the RSD effect and make the comparison more direct to the simplified projected 3PCF, which ignored line-of-sight separation, we extended this value to $100 h^{-1}$ Mpc in the main analysis. To check that this does not significantly alter results we also ran MCMC chains where this value was set to a more conventional $\pi^* = 40 h^{-1}$ Mpc for the projected 2PCF. These results are presented in Fig. B1. The figure is identical to Fig. 9 except we added green contours that correspond to the projected 2PCF results with $\pi^* = 40 h^{-1}$ Mpc. This choice of π^* is indeed more optimal, but the likelihood surfaces do not change enough to alter any of our main conclusions. The projected 3PCF(SV) still dominates the joint constraints. Applying full definition projected 3PCF would likely also increase its constraining power.

APPENDIX C: ANALYTICAL RANDOM TRIPLET COUNTS

The *RRR* (r_{12}^{\min} , r_{12}^{\min} , r_{23}^{\min} , r_{31}^{\max} , r_{31}^{\max}) represent the average number of triplets of a random (spatially uncorrelated) distribution of galaxies, where the perpendicular to the line-of-sight distance between the triplet points satisfies conditions $r_{12}^{\min} < r_{p12} < r_{12}^{\max}$, $r_{23}^{\min} < r_{p23} < r_{23}^{\min}$, and $r_{31}^{\min} < r_{p31} < r_{31}^{\max}$. They are usually computed by explicitly counting triplets of a random distribution of points, but for a box with periodic boundaries, these triplet-counts are easy to compute analytically. We follow the approach similar to Pearson & Samushia (2019) when computing these triplet counts.

We start by computing a simpler quantity, $RRR^{\star}(r_{12}, r_{23}^{\min}, r_{23}^{\min}, r_{31}^{\min}, r_{31}^{\max})$, the average number of third neighbours for a fixed pair separated by an exact perpendicular distance of r_{12} . Fig. C1 shows the geometry of the problem. For a fixed pair of points, RRR^{\star} is an average number of points falling within the shaded areas.

$$RRR^{\star} \left(r_{12}, r_{23}^{\min}, r_{23}^{\max}, r_{31}^{\min}, r_{31}^{\max} \right) = \overline{\sigma} S^{\star} (r_{12}, r_{23}^{\min}, r_{23}^{\max}, r_{31}^{\min}, r_{31}^{\max}),$$
(C1)

where $\overline{\sigma} = N/L^2$, is the projected density of the points (*N* being the number of points, and *L* the side of the cube).



Figure B1. A similar plot as 9 with additional green contours shows results from the projected 2PCF but with a value of $\pi^* = 40 h^{-1}$ Mpc.



Figure C1. Geometry of random triplets problem. A fixed pair r_{12} with a certain binning setting can only have triplets shown in the shaded area.

The relationship of this simplified quantity with the full triplet count is,

$$RRR\left(r_{12}^{\min}, r_{12}^{\max}, r_{23}^{\min}, r_{23}^{\max}, r_{31}^{\min}, r_{31}^{\max}\right) = \int_{r_{12}^{\min}}^{r_{12}^{\max}} RRR^{\star}\left(r_{12}, r_{23}^{\min}, r_{23}^{\max}, r_{31}^{\min}, r_{31}^{\max}\right) N(\rho 2\pi r_{12} dr_{12}), \quad (C2)$$

where *N* is the total number of possible first particles in the triplet and $(\rho 2\pi r_{12}dr_{12})$ is the average number of second particles in the triplet as we integrate over the r_{12} bin.



Figure C2. Intersection of two circles with radius R, r, and distance of centres d. Intersection area A has been shaded.

We compute S^* using the expression for the area of the intersection of two circles

$$A(d, R, r) = r^{2} \arccos\left(\frac{d^{2} + r^{2} - R^{2}}{2dr}\right) + R^{2} \arccos\left(\frac{d^{2} - r^{2} + R^{2}}{2dR}\right) - \frac{1}{2}\sqrt{(-d + r + R)(d + r - R)(d - r + R)(d + r + R)}.$$
(C3)

Here, d is the distance between the two circles, R and r are the two radii, and A is the shaded area in Fig. C2. From Figs C1 and C2, it is clear that

$$S^{\star} = A(r_{12}, r_{23}^{\max}, r_{31}^{\max}) - A(r_{12}, r_{23}^{\max}, r_{31}^{\min}) - A(r_{12}, r_{23}^{\min}, r_{31}^{\max}) + A(r_{12}, r_{23}^{\min}, r_{31}^{\min}).$$
(C4)

In our code, we keep track of identical triplets by imposing the condition $r_{p12} < r_{p23} < r_{p31}$. This ensures that we don't count the same physical triplet corresponding to the same particles several times by relabeling the particles 1, 2, and 3. This does not happen (because of the way our code is written) for the triplets for which either three sides or at least two sides of the triangle fall into the same bin, so those triplets are counted more than once. To correct this, we apply a permutation factor N_{perm} to our *RRR* counts. The permutation factor is

$$N_{\text{perm}}(r_1, r_2, r_3) = \begin{cases} 6 \text{ for } r_1 \neq r_2 \neq r_3, \\ 3 \text{ for } r_1 = r_2 \neq r_3 \text{ or} \\ r_1 = r_3 \neq r_2 \text{ or} \\ r_2 = r_3 \neq r_1, \\ 1 \text{ for } r_1 = r_2 = r_3. \end{cases}$$
(C5)

This paper has been typeset from a $T_{\!E\!}X/\!L\!\!\!\!\!\!^{A}\!T_{\!E\!}X$ file prepared by the author.