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46

47 ABSTRACT

48

49 Changing material surface micro/nano structures using laser beam texturing is a valuable approach in 50 wide applications such as control of cell/bacterial adhesion and proliferation, solar cells and optical 51 metamaterials. Here we report a comparison of the characteristics of surface micro/nano structures 52 produced using single beam laser direct writing and particle lens array parallel laser beam patterning. A 53 Nd:YVO₄ nanosecond pulsed laser at 532 nm wavelength was used in the laser direct writing method to 54 texture the stainless steel surface submerged in water and in air with different scanning patterns. Changes 55 in surface morphology, wettability, surface chemistry and optical reflectivity were analyzed. In the particle 56 lens array method, an excimer nanosecond laser at 248 nm wavelength was adopted to produce surface 57 patterns on GeSbTe (GST) film coated on a polycarbonate substrate by splitting and focusing a single laser 58 beam into millions of parallel breams. Single beam laser direct writing shows that the surface of high 59 roughness and oxygen percentage content presented high wettability and low reflectivity characteristics. 60 However, the controllability of the type of surface micro/nano patterns is limited. The parallel laser beam 61 processing using particle lens array allows rapid production of user designed periodic surface patterns at 62 nano-scale overcoming the optical diffraction limit with a high degree of controllability. Controlling the 63 uniformity of the particle lens array is a challenge. 64 65 Keywords: Laser; surface texture; structure; micro; nano; pattern; microsphere; parallel; morphology;

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wettability; reflectivity; and particle lens array.

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- 69

1. INTRODUCTION

71

72 Modifying surface properties by producing tailored nano/microstructures have 73 been extensively died and has found wide applications in several fields including self-74 cleaning, coating adhesion, wear resistance, anti-icing, and biological applications. 75 Moreover, changing the surface optical properties is used for solar cell and photoresist 76 applications [1–8]. Many surface engineering methods are available to modify the 77 surface structures, including chemical etching, sandblasting, mechanical machining, 78 corona discharge, plasma etching, and laser surface texturing. Among these techniques, 79 laser surface texturing is one of the most efficient and flexible techniques. It has been 80 used to produce smart surfaces that meet the requirements for more stringent surface 81 structure designs and properties. Besides, laser surface texturing has the advantages of 82 fast processing speed, non-contact processing, ease for automation, zero tool wear, and 83 non-dross ablation [9,10].

84 Different techniques have been used in laser surface texturing for producing 85 different structures, including laser direct writing with or without using a mask, two or 86 multi-beam interference and particle lens array multiple laser beam patterning [11]. 87 According to the surface feature size, laser surface texturing can be classified as micro-88 scale, nano-scale, or multi-scale surfaces (hierarchal structures, with a combination of 89 micro/nano features). Various structures such as holes, grooves, bumps, protrusions, 90 periodic surface structures, spikes, conic structures have been produced using laser 91 direct writing [9,12,13]. The generation of various types of surface patterns depends 92 mainly on the laser parameters, such as including fluence/power density, wavelength,

93 pulse duration, scanning speed, and the number of pulses; processing environment; and 94 material parameters. These parameters' relationship affects the generated surface 95 properties and quality [9,13,14]. 96 For micro/nano structuring, short and ultrashort lasers have been used using 97 laser direct writing method. The laser surface texturing process using ultrashort lasers is 98 mainly due to vaporization and plasma formation, while melting, splashing, and 99 solidification dominate the process of laser surface texturing using short pulse duration 100 like nanosecond laser. Using a nanosecond laser, high throughput can be achieved 101 compared to ultrashort laser processing due to the high laser fluence of melting and 102 solidification [15,16].

103 The laser surface structuring technique using contact particle lens array is a near-104 field technique in which the microspheres are deposited on the substrate, forming a 105 self-assembled monolayer on the substrate. These microspheres behave as lenses 106 splitting and focusing a single laser beam to many beams on the substrate, and each 107 spot generates tailored features forming periodic nano-scale surface structures. 108 Implementing this technique, it is possible achieve features with a resolution down to 109 $\lambda/3$ [11,17]. Different techniques have been used for microsphere deposition including 110 dip coating, spin coating, and convective coating. The convective coating has been the 111 most commonly used technique. The efficiency of the monolayer microsphere lens array 112 depends on the capillary force between particles and the adhesion force in which the 113 monolayer adheres to the substrate. Various nano-features such as star, bumps, holes, 114 and grooves have been generated using particle lens array laser patterning [18–20].

115	This work was motivated by the practical engineering challenges of producing surfaces
116	with various micro and nanostructures using flexible and efficient ways. Therefore, in
117	this paper, two laser surface texturing techniques are compared to examine the
118	properties of surfaces with various structures and properties. The first technique is the
119	laser direct writing. This process is performed using nanosecond laser processing of a
120	stainless steel surface to modify the surface structure and properties. The second
121	technique is the contact particle lens array used to generate micro/ nanostructures on a
122	thin film of GeSbTe (GST) film coated on a polycarbonate substrate.
123 124	2. EXPERIMENTAL PROCEDURE
125	For the laser direct writing method, AISI 316L stainless steel sheets were used in
126	this work. These sheets were cut to the dimensions of 10 mm x 10 mm x 0.7 mm. Before
127	the laser treatment, the sheets were cleaned ultrasonically using acetone, ethanol, and
128	di-ionized water, for 10 minutes each and dried used compressed air.
129	A Nd:YVO ₄ , nanosecond laser (Laserline Laserval Violino) was selected to study
130	the effect of laser processing parameters such as scanning speed and hatch distances on
131	micro structuring wettability, reflectivity and oxygen surface content. The effect of
132	scanning direction, laser fluence, laser scanning speed and scanning environment on the
133	surface morphology were examined. The laser beam was directed using a set of x-y
134	Galvo scanning mirrors and an F-theta lens. In some experiments, the sample was
135	submerged in water in order to reduce surface oxidation and reduce the feature sizes
136	and compared that processed in air. The level of water for the submerged sample
137	experiments was 1 mm above the sample. The laser scanning was performed in one

138	direction, two or more directions. The effect of scanning direction on the surface
139	morphology was studied. The experimental scheme is shown in Fig. 1. Table 1 listed the
140	laser processing parameters used in this work.
141	Prior to the surface characterization after laser treatment, the samples were
142	ultrasonically cleaned using Ethanol then compressed air to remove any ablated
143	materials and contamination. Scanning electron microscopy (Philips XL30 FEG-SEM) was
144	used to examine the surface morphology. This SEM is combined with energy dispersive
145	X-ray (EDX) which was used to characterize the surface oxygen contents. A confocal
146	laser scanning microscope (type: Keyence 3D profiler) was used to examine the surface
147	roughness. Water drops sessile method using a contact angle analyzer (type: FTA 188)
148	was used to investigate laser textured surfaces' wettability characteristics. In this
149	method, a contact angle of 10 μ l droplets of de-ionized water that contact the surface
150	was measured.
151	For particle lens array experiment, GeSbTe (GST) film coated on a polycarbonate
152	substrate was used in this work. GeSbTe is a composite of three materials (germanium-
153	antimony-tellurium or GST) and it is a phase-change material from the group
154	of chalcogenide glasses used in rewritable optical discs and phase-change
155	memory applications. The crystallization temperature of this alloy is between 100 and
156	150 °C, and its melting point is around 600 °C. It is characterized as a high speed phase
157	change material and its crystallization time around 20 nanoseconds which make it easy
158	for patterning. The reason for the selection of this material is because it requires very
159	low laser energy density to cause surface morphology change, ideal for the particle lens

160	surface patterning applications. The sample was a 20 nm thick Germanium-Antimony-
161	Tellurium (GST) film coated on a polycarbonate substrate. A low concentration of 4.74
162	μm SiO_2 microspheres was prepared by buffering the microspheres solution in de-
163	ionized water. The solution was spread over the substrate to form a monolayer. Then
164	the water evaporated when the samples were placed with a 90° angle.
165	A KrF Excimer laser (GSI-Lumonic IPEX848) was used to irradiate the samples using
166	the setup shown in Fig. 2. The laser beam size was 25×25 mm with a uniform intensity
167	distribution and a lens (focal length = 10 mm) was used to focus the laser on the sample
168	with a spot area 10 mm $ imes$ 10 mm. the laser processing parameters are listed in Table 2.
169	For imaging the microsphere morphology formed on a film substrate and nano patterns
170	generated after laser irradiation, optical microscopy (type: Leica CH-9435) was used.
171	3. RESULTS AND DISCUSSION
172	3.1 Laser direct writing
173	3.1.1 Surface morphology
173 174	3.1.1 Surface morphology Figures 3-6 show different scanning techniques that have been conducted in this work.
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 173 174 175 176 177 178 	3.1.1 Surface morphology Figures 3-6 show different scanning techniques that have been conducted in this work. Various and homogeneous structures ranging from ripples to porous and conical structures were achieved by changing the scanning directions, scanning speed, laser fluence, and processing environment. Figure 3 shows the nanosecond laser surface texturing's typical surface morphology using five different scanning patterns. It can be
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182 performed at a 100 mm/s scanning speed, a 50 μm hatch distance, a 7 ns pulse

duration, a 30 kHz pulse repetition rate, a 3.9 J/cm² laser fluence and 10 repeat scanning
passes.

185	The effect of laser scanning speed on the microstructure morphology was also
186	studied (Fig. 4). The scanning was performed using one direction scanning and laser
187	parameters of (9.8 J/cm ² laser fluence, one pass, and 50 μm hatch distance). It can be
188	seen that changing the scanning speed from 2000 mm/s to 1 mm/s changed the
189	microstructure from an oval-like structure to a cauliflower-like structure.
190	Figure 5 shows the microstructure of surfaces generated using three laser
191	fluences. The scanning was performed using two directions (30° and 60°), using laser
192	parameters of (100 mm/s scanning speed, 50 μ m hatch distance and 10 times passes). It
193	can be seen that micro ripples were formed using low laser fluence (0.9 J/cm ²) (Fig. 5a),
194	while it changed to a hierarchal microstructure using a high laser fluence (9.8 J/cm ²)
195	(Fig. 5c).
196	Figure 6 shows the difference between the microstructures generated in water
197	and air. Using laser parameters of (9.8 J/cm², 10 mm/s scanning speed, 25 μm hatch
198	distance, and 1 pass), the microstructure in the air was cauliflower likes structure, while,

199 in water, a uniform conical like structure was formed.

200 Changing the scanning direction and scanning speeds affects the number of 201 pulses and the laser overlapping which in turn affected the surface structure. The pulse 202 overlapping can be calculated as [9,21]:

$$203 \qquad \left(1 - \frac{\Delta x}{spot \ size}\right) \times 100 \tag{1}$$

204 The line overlapping can be calculated as [9,21]:

$$205 \qquad (1 - \frac{\Delta z}{spot \, size}) \times 100 \tag{2}$$

206 Where, $\Delta x = \frac{speed}{repetition rate}$ and Δz is the hatch distance.

207 In this work, the line overlapping was 81.8 %, and the pulse overlapping was 39

208 % and 99.9 % at 1000 mm/s and 1 mm/s laser speeds, respectively. The number of

209 pulses per spot can be estimated as $\frac{Spot \ size * repetition \ rate}{scanning \ speed}$, and it was 2 and 1650 at a

210 laser speed of 1000 mm/s and 1 mm/s, respectively.

211 By increasing the laser fluence from 0.9 J/cm² to 9.8 J/cm², the surface

212 microstructure changed from micro ripples to a 3D complex structure. This is related to

213 the increase the material removal by increasing the laser fluence. The removed

214 materials could be solidified around the laser scanning area forming complicated 3D

215 structures [22].

216 By changing the laser-processing environment from air to water, the

217 microstructure was changed to be smooth and free of solidified material and particles

218 over the microstructure. The reason behind this is that the ablated particles were

219 moved with water movement and they did not redeposit over the surface during laser

- 220 processing of the material in water [9,23,24].
- 221 **3.1.2 Surface characteristics**

The surface roughness (Ra) measurements of as-received surface (control) were 10.9±3.54 nm. Figure 7 shows the roughness values of laser treated surfaces using a range of scanning speeds and hatch distances. It is clear that the surface roughness was

225	proportional to the hatch distances and inversely proportional to the laser scanning
226	speed. The surface generated using a hatch distance of 100 μm and a scanning speed of
227	10 mm/s recorded the highest surface roughness Ra value (11.12 \pm 1.8 μm) compared to
228	those of other surfaces. Surface generated using a 10 μm hatch distance and a 1000
229	mm/s scanning speed, on the other hand, showed the smallest surface roughness (0.12
230	± 0.007 μm) compared to other surfaces.

231 Figure 8 shows the analysis data of the energy-dispersive X-ray spectroscopy 232 (EDXs) for surfaces. As received surface (control) was free of oxidation as its' measured 233 oxygen percentage was zero. However, after laser processing, it was noticed that the 234 surface oxygen content of all processed samples was increased. By increasing the laser 235 scanning speed and the hatch distance, the oxygen percentage decreased. For example, 236 at a speed of 10 mm/s, the oxygen percentage recorded 21.8 % and 7.8 % using, 237 respectively, 10 μ m and 100 μ m hatch distances. However, at a speed of 1000 mm/s, 238 the oxygen percentage was 0.93 % at 10 µm hatch distance and less than 0.4 % using 239 100 µm hatch distance.

In this work, the effect of ns laser generated surface structures on the change of the stainless steel (SS) wettability was investigated. The contact angle of as received substrate (control) was 90.5°±3.5°. After laser treatment, all the surfaces performed superhydrophilic properties with a contact angle CA=0° immediately after the laser processing. However, the wettability characteristics of all processed samples changed with time. Therefore, the contact angle was measured again at one month after laser processing. Figure 9 shows the surface wettability change as a function of the laser

scanning speed and hatch distances. It is clear that the contact angle increased with
increasing scanning speed and hatch distance. The surface produced at a 1000 mm/s
and 100 µm hatch distance was superhydrophobic with maximum contact angles (CAs)
around 158°. However, the minimum CA was 2125° for the surface generated at a 10
mm/s scanning speed and 10 µm hatch distance. Generally, the wettability of surfaces
was inversely proportional to the scanning speed and hatch distance.

253 Figures 10 and 11 show the change of surface reflectivity within the visible light 254 spectrum (400 – 700 nm) after the laser processing. The reflectivity was investigated for 255 samples treated using different laser speeds and hatch distances. It can be seen that the 256 reflectivity of all processed surfaces was decreased compared to the reflectivity of as 257 received substrate (control) (Fig. 10). Furthermore, at a specific hatch distance, it can be 258 seen that the reflectivity of surfaces was increased with increasing the scanning speed 259 (Fig. 10). Moreover, at a specific scanning speed, the results show that the reflectivity of 260 laser-treated surfaces was increased with increasing hatch distance (Fig. 11). The 261 reflectivity of as received stainless steel (control) was about 60 %. However, the 262 reflectivity was decreased to less than 2 % for samples treated using 10 mm/s laser 263 speed and 10 µm hatch distance. 264 In this work, it was observed that laser processing parameters affected the 265 surface properties. Changing the surface characteristics with changing the laser

266 processing parameters has been extensively studied before. Some researchers have

267 reported that the surface wettability increases with increasing the surface oxygen

268 contents and surface roughness [25] . With increasing surface roughness, the contact

269	area between the surface and water droplets increased due to the natural gravitational
270	desire to settle on the surface [26,27]. Cui et al. [28] reported that heating the stainless
271	steel increased the oxygen contents from the surrounding environment forming Fe_2O_3
272	and Cr_2O_3 . The hydroxyl group (OH density) increased the surface oxygen contents,
273	thereby increasing the surface adsorption and surface wettability [26,27]. In our work,
274	during material processing, it was noticed that the surface reflectivity was decreased,
275	and some surfaces switched to black. Other researchers also noticed this behavior
276	during different processing materials such as Si [29]. This is related to increasing the
277	surface roughness, which leads to increased surface area and multiple reflections inside
278	the surface features [9,30].
279	3.2 Particle lens array parallel laser beam surface patterning

280 Parallel processing techniques are essential to generate micro/nano-textures 281 over a large area. Particle lens arrays can be used to produce micro and nanostructures 282 by splitting a single laser beam into millions or billions of laser beams and focusing 283 locally without diffraction limit. This technique is based on near-field effect of small 284 transparent microspheres to produce micro/nano-patterns. Using this technique, it is 285 possible to produce a feature size below the diffraction limit. Monodispersed 4.74 µm 286 spherical silica (SiO₂, Duke Scientific) particles were diluted with de-ionized water and applied to the film surface. After the water evaporated, a hexagonally closed-packed 287 288 monolayer was formed on the surface due to the self-assembly process. The sample was 289 then laser processed and characterized using a Leica CH-9435 microscope (Fig. 12).

290	Normal incidence of a laser beam onto the substrate surface removes most of
291	the particles (spheres) from the substrate after a single laser pulse irradiation. The
292	disappearance of the particles makes it impossible to fabricate arbitrary shaped
293	patterns. To keep particles on the substrate surface for multiple pulses processing, an
294	angled beam scanning technique was used and a software tool was developed using
295	this principle. As the incident angle increases, a higher percentage of the particles are
296	left on the sample surface. This effect is because the ablation point is not located at the
297	contacting point of the particle and the substrate. With the developed technique,
298	different user defined nanostructures have been produced by a certain number of laser
299	pulses. Virtually, millions of parallel features like lines, curves and even more complex
300	profiles could be written simultaneously over large surface areas. Patterns of a complex
301	shape were created on the substrate surface using software developed in Matlab 2010b
302	(32 bits edition), which is a powerful programming environment for professional
303	scientific and engineering applications. The software is compatible to all the Newport
304	Motion Controllers/Drivers (due to their common commands and answers) and can be
305	easily adjusted for other motion control systems and lasers according to the forward
306	documentation.
307	User-defined complex shapes can be fabricated within regions $d_p \leq r$, as shown in

Fig. 13. The position of ablation spot $p(\alpha, \phi)$ is a function of the incident angle α and sample rotating angle φ . Angle α controls the position of p in radial direction, while angle φ moves p in circumferential direction. The ranges of angles are $\alpha(-45^\circ, 0^\circ)$ and $\phi(-$

311 180°, 180°). By applying a relative angle $\alpha(\varphi)$ with every rotated angle φ , user-defined 312 patterns can be easily fabricated.

According to the Mie theory, the induced near-field enhancement is located around the particle and along to incident direction. It is known that the enhanced intensity will decay along the incident direction before it reaches the substrate surface. If the laser energy is sufficient, this enhanced field is still able to ablate materials for the substrate surface. The shift of these peak positions away from the contact point with a distance close to that is given by the geometrical optics:

(3)

319
$$d_p \cong r \cdot \tan(\alpha)$$

320 where *r* is the radius of the particle.

321 Figures 14 and 15 show two periodic patterns generated on the GeSbTe film 322 using an excimer laser. Figures 14a and 15a show the computer design of a square 323 shape and (nano) in the software interface, which led to the patterning of the GeSbTe 324 (GST) film with uniform periodic patterns. The gaps between dots cannot be 325 distinguished due to their overlapping (one can see in Figs. 14a and 15a) and of melting 326 of the film during the laser processing. The fluence used was 1 mJ/cm². The experiments 327 were performed with two Newport PR 50 Series computer-controlled rotation stages 328 and a Newport ESP300 controller. One stage controls the laser incident angle α by tilting 329 the sample with angles ranged from 0° to 45°. The other stage rotates the sample within 330 the tilted plane with an angle ϕ with angles ranged from -180° to 180°. Therefore, any 331 point p (α , ϕ) within the shade of particle on the substrate surface could be reached by 332 a geometrical calculation of angles α and φ .

333	The developed technique could provide means to produce arbitrary patterned
334	surfaces on small objects such as MEMS (for improved tribological characteristics),
335	OLEDs (for improved emission efficiency), optical metamaterials, uniform structures for
336	cell and bacterial adhesion and migration, and medium-sized objects.
337	In this work, the results showed that the surface properties and structure could be
338	controlled by controlling the processing method. Using laser direct writing method, the
339	results showed that increasing the surface wettability and absorptivity were related to
340	increasing the surface roughness and oxygen percentage content. However, the
341	controllability of the type of surface micro/nano patterns is limited. The parallel laser
342	beam processing using a particle lens array, on the other hand, allowed rapid production
343	of user-designed periodic surface patterns at nano-scale, overcoming the optical
344	diffraction limit with a high degree of controllability where controlling the uniformity of
345	the particle lens array is a challenge.
346	4. CONCLUSION
347	In this work, nanosecond pulsed lasers were used to generate different
348	micro/nanostructures using two different techniques: direct writing and particle lens
349	array parallel writing. In the laser direct writing technique, the substrate was melted and
350	evaporated, and then the re-deposition and solidification of molten materials generated
351	different microstructures. Therefore, the formation of different structures using the ns
352	laser was mainly due to the thermal effects on treated surfaces. The surface
353	morphology and properties were changed with changing laser-processing parameters.
354	Moreover, the surfaces processed a low scanning speed (10 mm/s) recorded the highest
355	roughness and oxygen percentage content and the minimal wettability and reflectivity

356	compared to other surfaces. Furthermore, the surfaces produced at 100 μm recorded
357	the highest roughness, water contact angle and reflectivity and minimal oxygen
358	percentage contents compared to other surfaces generated using 10 μm and 50 μm
359	hatch distances. Thus, the surface of high roughness and oxygen percentage content
360	presented a high wettability and turned to black with low reflectivity characteristics.
361	Using particle lens array technique, two nano-patterns were demonstrated. This is a
362	very efficient way of producing tailored surface micro/nano patterns. Both processing
363	methods presented effective surfaces. This study shows that nanosecond lasers could
364	generate distinctive morphologies and properties using easy and efficient ways. These
365	surfaces could be useful in various applications, including biological applications, wear
366	resistance, self-cleaning, anti-icing, coating adhesion, and solar cells.
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Shephard, J. D., 2015, "Nanosecond Laser Textured Superhydrophobic Metallic Surfaces and Their
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499 500	Figure Captions List			
	Fig. 1	(a) Experimental set up and (b) scanning directions with: (b1) one direction		
		scanning, (b2) two directions scanning, (b3) four directions scanning, (b4)		
		two directions with 30° & 60° scanning and (b5) two directions with 10 ${}^\circ$ &		
		130 [°] scanning		
	Fig. 2	Experimental set up of surface texturing using particle lens array		
	Fig. 3	Effect of the scanning direction on the microstructure morphology: (a)		
		conical, (b) micro-pores, (c) beehive and (d) diamond-like structures.		
	Fig. 4	Effect of scanning speed on the microstructure morphology using: (a) 2000		
		mm/s, (b) 500 mm/s, (c) 100 mm/s and (d) 1 mm/s. Scale bar is 200 μm		
	Fig. 5	Effect of laser fluence on the microstructure morphology using: (a) 0.9		
		J/cm ² , (b) 3.9 J/cm ² , and (c) 9.8 J/cm ²		
	Fig. 6	The microstructure morphology generated in: (a) water, and (b) air, the		
		scale bar is 50 μm		
	Fig. 7	The surface roughness measurements of laser treated surfaces		
	Fig. 8	The surface oxygen contents measurements of laser treated surfaces		
	Fig. 9	The contact angle measurements of laser treated surfaces		
	Fig. 10	The surface reflectivity measurements of laser treated surfaces		
	Fig. 11	The surface reflectivity measurements as a function of changing hatch		
		distances at a scanning speed of 10 mm/s		

Fig. 12	Optical microscope image of a uniform layer of SiO_2 microsphere using: (a)
	10X magnification and (c) 20X magnification

- Fig. 13 Schematic diagram of geometric algorithm between the position of spot p, incident angle α and sample rotating angle ϕ
- Fig. 14 a. Matlab[®] software interface; b. 2D generated square micro-patterns onto a GeSbTe film using a laser fluence of $1mJ/cm^2$ and $4.74 \mu m$ diameter SiO₂ microspheres
- Fig. 15 a. Matlab[®] software interface; b. 2D generated (nano) micro-patterns onto a GeSbTe film using a laser fluence of $1mJ/cm^2$ and $4.74 \mu m$ diameter SiO₂ microspheres









scanning, (b2) two directions scanning, (b3) four directions scanning, (b4) two directions

with 30° & 60° scanning and (b5) two directions with 10° & 130° scanning





575576 Fig. 3 Effect of the scanning direction on the microstructure morphology: (a) conical, (b)

577 micro-pores, (c) beehive and (d) diamond-like structures.

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634	а	b
635	Fig. 6 The microstructure morphology genera	ated in: (a) water, and (b) air, the scale bar
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Fig. 10 The surface reflectivity measurements of laser treated surfaces







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GeSbTe film using a laser fluence of 1 mJ/cm^2 and 4.74 μm diameter SiO_2

microspheres

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GeSbTe film using a laser fluence of 1 mJ/cm^2 and 4.74 μm diameter SiO_2

microspheres

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770 771	Table Caption ListTable 1The used nanosecond laser parameters for texturing the stainless steel				
//1					
	Table 2	Laser parameters for inducing different surface textures using Excimer			
		laser			
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Laser parameters	
	(Nd:YVO4)
Wavelength [nm]	532
Pulse duration	7 ns
Pulse repetition frequency [kHz]	30
Focused diameter [µm]	55
Fluence [J/cm ²]	0.9, 3.9 and 9.26
Speed [mm/s]	1, 10, 50, 100, 500, 1000 and 2000
Hatch distance [µm]	10, 50 and 100
Focal length [mm]	245

790 Table 1 The used nanosecond laser parameters for texturing the stainless steel

821 Table 2 Laser parameters for inducing different surface textures using Excimer laser

Logor poromotors	Nanosecond Laser	822
	(Excimer Laser)	823
Wavelength [nm]	248	824
Pulse duration [ns]	15	825
Pulse repetition frequency [Hz]	1	826
Focused beam size [mm]	10×10	827
Fluence [mJ/cm ²]	1	828
		829