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# Accurate glottal model parametrization by integrating audio and high-speed endoscopic video data

Carlo Drioli · Gian Luca Foresti

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Abstract The aim of this paper is to evaluate the effec-1 tiveness of using video data for voice source parametrization 2 in the representation of voice production through physical з modeling. Laryngeal imaging techniques can be effectively Δ used to obtain vocal fold video sequences and to derive time 5 patterns of relevant glottal cues, such as folds edge position or glottal area. In many physically based numerical models of the vocal folds, these parameters are estimated from the 8 inverse filtered glottal flow waveform, obtained from audio c recordings of the sound pressure at lips. However, this model 10 inversion process is often problematic and affected by accu-11 racy and robustness issues. It is here discussed how video 12 analysis of the fold vibration might be effectively coupled to 13 the parametric estimation algorithms based on voice record-14 ings, to improve accuracy and robustness of model inversion. 15

Keywords Physical glottal modeling · Videokymography ·
 Voice data analysis · Model inversion · Video analysis

# 18 **1 Introduction**

The glottal flow waveform has a fundamental role in the characterization of a speaker's voice. There is experimental evidence that flow waveforms obtained by inverse filtering actual voice recordings are characterized by a wide variety of different shapes and cues. The waveform of the glottal volume velocity is influenced by a number of factors, e.g., the sex and the age of the speaker, the vocal fold

Department of Mathematics and Computer Science, University of Udine, Via delle Scienze 206, 33100 Udine, Italy e-mail: carlo.drioli@uniud.it

G. L. Foresti e-mail: gianluca.foresti@uniud.it health, the style of phonation. Physiological parameters used 26 to control the glottal cycle characteristics include the subglot-27 tal pressure, the laryngeal muscles tension, and the resting 28 position of the vocal folds [1]. Vocal fold vibration consists 20 of a back-and-forth movement, which can be induced and 30 sustained over time, and whose source of energy is a steady 31 stream of air flowing through the glottis. This phenomenon is 32 called flow-induced oscillation. In the early 1950s and 1960s, 33 the vocal fold oscillation was explained with the myoelastic-34 aerodynamic theory. According to these theories, Bernoulli 35 forces (negative pressure) cause the vocal folds to be sucked 36 together, creating a closed airspace below the glottis. Con-37 tinued air pressure from the lungs builds up underneath the 38 closed folds. Once this pressure becomes high enough, the 39 folds are blown outward, thus opening the glottis and releas-40 ing a single "puff" of air. Since the 1970s, a large number of 41 studies addressed the acoustic characterization of the glot-42 tal air flow during voiced phonation by accurate modeling 43 of the folds vibration phenomenon [2-5]. Among these, the 44 lumped-element model proposed in 1972 by Ishizaka and 45 Flanagan [2], in which the folds are represented by two cou-46 pled mass-spring oscillating systems, is most representative. 47 To date, the main achievement of the studies on voice source 48 dynamics has been to assist us in understanding the principles 49 of flow-induced oscillatory phenomena and the causes under-50 lying vocal fold pathologies, e.g., [6,7]. The potentialities of 51 employing source model tracking in conjunction with vocal 52 tract analysis in voice modeling and disorder diagnosis [8] 53 are interesting, yet poorly investigated if compared with other 54 non-dynamical representations of the glottal source [9–11]. 55

On the other hand, video data acquisition and processing became in the last decades an essential tool for medical practical applications such as larynx examination and pathology diagnosis. Visual analysis techniques that are widely used, especially for clinical investigation, include laryngeal (video)

C. Drioli (🖂) · G. L. Foresti

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addressing the fitting of visual and acoustic data, is presented. 96 In Sect. 3, the proposed method is assessed on a dataset con-97 sisting of a videokymographic plus acoustic recordings of 98 sustained phonation, and the results are discussed. In Sect. 4, 99 the conclusions are presented. 100

# 2 Method

The proposed voice modeling method is based on the joint 102 analysis of audio and video data with the aim of inverting a 103 physiologically inspired model representing the dynamics of 104 the vocal folds and the vocal tract resonances. The acoustic 105 pressure recorded at lips is used to gather information on the 106 vocal tract formants and to provide an estimation of the glot-107 tal source by inverse filtering; the videokymographic data, 108 providing accurate information on the closure and opening 109 glottal instants and on the duration of closed and open phases, 110 are used to improve the accuracy in the fitting of the glottal 111 model to the acoustic data. 112

In our modeling scheme, the lip pressure signal measured 113 by the microphone is given by 114

$$y(t) = -\sum_{k=1}^{N} a_k y(t-k) + \dot{u}_g(t)$$
(1) 115

where  $a_1, \ldots, a_N$  are the auto regressive (AR) coefficients 116 of an all-pole model of the vocal tract, and  $\dot{u}_g(t)$  is the first 117 derivative of  $u_g(t)$ , the excitation glottal pulse waveform. 118 The voice source model used to represent  $u_{g}$  relies on the 119 mass-spring paradigm adopted, among others, by the well-120 known Ishizaka-Flanagan one-mass and two-mass models. 121 The details of the glottal excitation model, illustrated in 122 Fig. 1, can be found elsewhere [17], and here we only briefly 123 recall the essential components. 124



modeled through the propagation of the fold displacement along the thickness of the fold. Right the discrete counterpart of the mass-spring model

stroboscopy, high-speed videolaryngoscopy, and videoky-61 mography (high-speed line scanning of vocal fold vibra-62 tions). The acquisition of visual information about voice pro-63 duction requires that an endoscope is inserted in the mouth 64 or in the nasal cavity to reach the vocal folds. Digital image 65 processing algorithms can provide time patterns of visual 66 cues related to the oscillations of the vocal fold edges for 67 further analysis (vocal fold boundary detection and tracking) 68 [12,13]. Recently, a video processing-based analysis scheme 69 relying on the computation of a set of spatiotemporal geo-70 metric features from the glottal area has been proven useful in 71 quantifying and differentiating normal and disordered vocal 72

fold vibrations in adults and in children [14,15]. Despite the wide number of investigations dedicated in 74 the analysis of acoustic data on one side and of video endo-75 scopic data on the other, effective analysis schemes exploit-76 ing both modalities have been rarely addressed to date. An 77 example is [16], in which vocal fold vibrations were analyzed 78 using a high-speed camera and related to sound characteris-79 tics. Analysis included automatic glottal edge detection and 80 calculation of glottal area variations, as well as kymography. 81

In this paper, we illustrate an approach to phonation mod-82 eling that relies on both acoustic and videokymographic 83 data analysis. The information gathered from the audiovi-84 sual analysis is used to accurately fit a source-plus-vocal tract 85 model, in which the voice source is represented by a dynam-86 ical model of the vocal folds. The videokymographic data in 87 particular is used to improve the parametrization of the source 88 model, by controlling the principal glottal sub-cycle features 80 such as open/closed interval durations. A pilot experiment is 90 presented in which the method is used on a dataset featuring 91 two different subjects uttering a sustained vowel. 92

The paper is organized as follows: in Sect. 2, the numerical 93 model of the voice source and the parametrization algorithm, 94 95



Fig. 1 Scheme of the low-dimensional voice source used as glottal waveform generator (note that the vocal tract model is not represented here). Left representation of the vocal folds in terms of a mass-spring system; phase delay between lower and upper edges of the fold are

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The lower edge of the folds is represented by a single 125 mass-spring system k, r, m and the propagation of the dis-126 placement x along the thickness Th of the fold is represented 127 by a propagation line of length  $\tau$ . Let  $x_1$  be the displacement 128 of the fold at glottis entrance, and  $x_2$  the displacement at the 129 exit. An impact model reproduces the impact distortions on 130 the fold displacement and adds an offset  $x_0$  (the resting posi-131 tion of the folds). The driving pressure  $P_m$  acting on the folds 132 is computed from the lung pressure  $P_1$ , the flow  $u_g$  and the 133 lower glottal area  $A_1$ , using Bernoulli's law:  $P_{\rm m} = P_1 - \frac{1}{2}\rho \frac{u_g}{A_1}$ 134









Fig. 2 A simulation of the glottal model, for different values of the phase delay parameter  $\tau$  (in samples): folds edge displacements (*upper plots*), and glottal source (*lower plots*). The plots show how the phase delay parameter  $\tau$  directly affects the closed-phase interval of the glottal flow cycle, i.e., the interval in which  $x_1$  or  $x_2$  is in the closed position

( $\rho$  being the air density). In Fig. 1, the vocal folds and the 135 Bernoulli term are enclosed in the fluid mechanical compo-136 nent  $\mathcal{M}$ . A flow model  $\mathcal{F}$  converts the glottis area given by 137 the fold displacements into the airflow at the entrance of the 138 vocal tract. In its simplest form, the glottis area is computed as 139 the minimum cross-sectional area between the area at lower 140 vocal fold edge,  $A_1 = L \cdot x_1$ , and the area at upper vocal fold 141 edge,  $A_2 = L \cdot x_2$ . The flow is then assumed proportional to 142 the glottal area, i.e.,  $u_g = \mathcal{F}(x_1, x_2) = k_g \min(x_1, x_2)$  (where 143 the lung pressure  $P_1$  is included in  $k_g$ ). The propagation line 144 of length  $\tau$  reproduces the vertical phase difference of the 145 vibration of the cord edges, which is essential for the pro-146 duction of self-sustained oscillations without a vocal tract 147 load. The pressure lung,  $P_1$ , has a role in determining the 148 onset and offset of the oscillation. In our simulations, it is 149 kept constant during the system evolution and is omitted for 150 simplicity in what follows. The mass-spring system k, r, m is 151 modeled as a second-order resonant filter, characterized by a 152 resonance frequency  $f_0 = \frac{1}{2\pi} \sqrt{k/m}$ . 153

In previous investigations, this model has shown to pro-154 vide stable oscillatory behavior in a wide range of parametric 155 configurations of interest [18], and to be suited for applica-156 tions in which automatic fitting to recorded speech data is 157 involved [17, 19]. Moreover, with respect to traditional multi-158 mass-based glottal models, it has the property that the phase 159 delay parameter  $\tau$  directly affects the closed/open-phase ratio 160 of the glottal flow waveform, as shown in Fig. 2. This is of 161 particular interest here, since the method that we propose 162 relies especially on the optimization of  $\tau$  in order to match 163 the closed/open-phase ratio measured from the visual data. 164

An example of the analysis data used in this investigation is shown in Fig. 3. It reproduces a videokymography, i.e., a high-speed line scanning of vocal fold vibrations in a given point along the vocal folds length [20,21]. Given the video



Fig. 3 The audio visual data used in this investigation. The acoustic pressure recorded at lips (*upper plot*) is used to gather information on the vocal tract formants and to provide an estimation of the glottal source by inverse filtering; the video kymograph data (*lower plot*) provides accurate information on the closure and opening glottal instants and on the duration of closed and open phases, which is used in turn to accurately fit the glottal model to the acoustic data



Fig. 4 The pitch-synchronous parameter identification procedure performing a joint source-vocal tract identification

frame rate  $Fps_v$  and the image resolution  $Xres_v$  along the time axis, the time interval Tpix corresponding to an image pixel can be computed as  $Tpix = (1/Fps_v)Xres_v$ . In the example shown, the image has an *x*-axis resolution of 512 pixel at 25 frames per second, resulting in a pixel time Tpix = 0.0781 ms. The available acoustic pressure at lips is recorded with a 44.1 kHz sampling rate and 16 bit resolution.

The voice model (glottal source plus vocal tract) is fitted to time-varying recorded speech data, by a pitch-synchronous parameter identification procedure which performs a joint source-vocal tract identification. The procedure is summarized in Fig. 4 and operates through the following steps:

- a fixed length running analysis window is shifted by a
   variable hop size equal to the period length.
- <sup>183</sup> 2. for the audiovisual analysis frame under investigation, <sup>184</sup> whose length corresponds to around three periods of <sup>185</sup> speech, a traditional LPC analysis is performed on the <sup>186</sup> audio signal to obtain a rough estimate of the vocal tract <sup>187</sup> model parameters  $a_k$ , which also represent its principal <sup>188</sup> resonances called formants.
- the fundamental frequency is estimated through an audio
  pitch detector (and the analysis of the videokymography);
  the GCI (glottal closure instants) and the closed/openphase durations of the glottal cycle are estimated from
  the videokymography through video analysis routines.
- <sup>194</sup> 4. the cues computed in the previous step are used to syn-<sup>195</sup> chronize and tune the mass-spring system representing <sup>196</sup> the folds (through the mass-spring system resonance fre-<sup>197</sup> quency  $f_0$  and the folds edges delay parameter  $\tau$ ), and <sup>198</sup> the glottal model is used to generate a glottal pulse.
- <sup>199</sup> 5. a least-square fitting procedure, based on QR factoriza-<sup>200</sup> tion, is used to solve the estimation problem which pro-<sup>201</sup> vides the final parameters  $a_k$  of the vocal tract filter, given

its time aligned input (the glottal source) and output (the target speech signal) time series. 203

In the procedure sketched above, the cues provided by the 204 video analysis procedure in Step 3 are used in Step 4 to accu-205 rately tune those parameters of the model that principally 206 affect the open-phase to close-phase duration ratio, i.e., prin-207 cipally, the phase parameter  $\tau$  (the vocal fold resting position 208  $x_0$  and the lung pressure  $P_1$  may also affect the glottal cycle, 209 however, the focus in this paper will be on the phase delay 210 control, and the other parameters are held constant during the 211 simulations). To this purpose, a Levenberg-Marquardt non-212 linear least-square optimization is used, which searches for 213 the best  $\tau$  parameter that minimizes a cost function propor-214 tional to the distances between target and reproduced open-215 phase/closed-phase duration ratio. 216

## 2.1 Video features extraction

Several cues of the glottal waveform can be extracted from 218 videokymographic data in order to estimate voice source 219 parameters. Glottal opening and closing instants are clearly 220 identified as the left and right corners of the rhomboid-shaped 221 convex regions, denoting the open phase of the glottal cycle. 222 Closed- and open-phase time localization and duration are 223 the principal parameters that will be used here to tune the 224 model fitting. The skewness of the rhomboid-shaped regions 225 is potentially interesting as well, since it relates to the degree 226 of left-right asymmetry in the vocal folds oscillation. Here, 227 we will adopt a symmetrical model of the folds oscillation 228 and will not take left-right asymmetries into consideration. 229

The input image I(x, y, t) is considered as a set of pixels that belong to one of two regions: rhomboid-shaped convex areas or background. Convex area pixels are those which 232

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Fig. 5 A frame showing sub-cycle timing details. GCI are glottal closure instants, T is the glottal cycle period,  $T_c$  and  $T_o$  are the closed- and open-phase intervals

belong to a region associated with the open phase, while 233 background pixels between two convex areas are associated 234 with the closed phase (see Fig. 5). The first step of the pro-235 posed method is to detect figure pixels in each frame of the 236 temporal sequence. There is a wide variety of techniques that 237 could be used for the identification of whether a pixel is part 238 of the figure or the background. For example, a model of the 239 average shape of the figure can be built and an attempt to fit 240 this model to locations within the image can be done. How-24 ever, model-based identification schemes are computation-242 ally intensive and may not be able to complete the detection 243 in real-time. In order to satisfy the real-time constraint and to 244 reach a high level of accuracy, the change detection method 245 based on the fast Euler number (FEN) has been applied [22]. 246 Such a method consists in thresholding the difference image 247 at g different levels, computing the Euler number for each 248 binarization, and choosing the "optimal" threshold value that 249 better separates signal from noise. At the end of this process, 250 a binary image B(x, y, t) is obtained where figure pixels are 25 set to 1 and background pixels are set to 0. The output of 252 this step can be seen in Fig. 6a. However, noise points may 253 appear in B(x, y, t), due to wrong illumination conditions or 254 errors of the FEN method. In practice, isolated points rep-255 resent noise points, while compact regions of black pixels 256 represent possible regions associated with the open phase. In 257 order to reduce noise and obtain a binary image characterized 258 by uniform and compact regions, a morphological focus of 259 attention mechanism is used [23]. First, a statistical erosion is 260 applied to the binary image B(x, y, t),  $B' = B \ominus_{\beta_1} S$ , where 261 S is a 3  $\times$  3 square structuring (SE) element and  $\beta_1$  is a para-262 meter which regulates statistical operators [23,24]. Then, a 263 statistical dilation is applied to the set B',  $B'' = B' \oplus_{\beta_2} S'$ , 264 where S' is a cross SE and  $\beta_2 > \beta_1$ . The resulting denoised 265 video frame is shown in Fig. 6b. Finally, a fast active con-266



Fig. 6 A frame showing the image processing steps for sub-cycle cues analysis: thresholding for convex regions-background separation (a), denoising (b), contour detection (c), computation of opening and closing instants (d)

The procedure discussed so far has been implemented in 274 Matlab as a semi-automatic program. It requires a certain 275 amount of supervision, including the preliminary segmentation of the portion of data to be analyzed, the tuning of 277 the parameters of the numerical model not involved in the 278 adaptation procedure, and the tuning of the video analysis 278 threshold parameters. 280

# **3** Results and discussion

In this section, the proposed fitting procedure is assessed 282 on a dataset consisting of a videokymographic plus acoustic 283 recordings of sustained phonation from two healthy subjects. 284 The subjects, both males, uttered a sustained vowel (/a/ for 285 S1, and /i/ for S2) for approximately 7s, subject S1 with 286 a fundamental frequency of 130.0 Hz, and subject S2 with 287 a fundamental frequency of 178.6 Hz. The procedure was 288 applied on a total of 30 frames for each subject, in the sta-289 tionary portions of the recordings (voice onsets and offsets 290 were discarded in this investigation). 291

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The video analysis process aimed at measuring the prin-292 cipal cues that could be of interest for the parametrization 293 of a glottal model able to represent the motion of the vocal folds and the fluid dynamics of the airflow passing through 295 the folds and originating the glottal waveform. Some cues of 296 the glottal waveform have been recognized to be particularly relevant for the study of the perceptual influence of the voice 298 source characteristics, and for comparing different voice 290 qualities. Well-established voice source quantification para-300 meters, computed from the flow and the differentiated flow, are usually defined in terms of the time intervals in which air 302 is allowed to flow through the glottis (opening and closing 303 intervals) or not (closed interval), and in terms of flow ampli-304 tude [1,26]. We define here a set of glottal area time parame-305 ters which are strictly related to the ones used in the literature 306 to characterize the air flow. If T is the glottal cycle period, and 307  $F_0 = 1/T$  the fundamental frequency of oscillation, we call 308  $T_{\rm c}$  the closed glottis interval,  $T_{\rm op}$  the opening interval,  $T_{\rm cl}$  the 309 closing interval, and  $T_{\rm o} = T_{\rm op} + T_{\rm cl}$  the open interval. Also, 310 the following derived parameters are defined: the closed quo-31 tient CQ =  $T_c/T$ , the opening quotient OQ =  $T_o/T$ , the 312 speed quotient SQ =  $T_{op}/T_{cl}$ . Table 1 reports the values 313 of time-related area function parameters computed from the 314 video data, upon segmentation of the visual glottal area cues 315 as illustrated in the video analysis section. 316

In the speech model adaptation procedure sketched in 317 Sect. 2, part of the parameters adaptation relies on the mea-318 sure of the acoustic pressure radiated at lips, whereas part 319 of the glottal source parameters are tuned using the visual 320 information related to the glottal area function evolution in 321 time. Specifically, the visual-related adaptation step is per-322 formed using a Levenberg-Marquardt gradient descent opti-323 mization method, targeted at reproducing the same closed 324 and open glottis intervals as measured from the videoky-325 mography frames. The cost function used here in the gradient 326 descent algorithm, referred to a frame of data, is defined as: 327

$$F(\tau, f_0) = \alpha_1 (T_c^M(\tau, f_0) - T_c^V)^2 + \alpha_2 ||(\mathbf{y} - \tilde{\mathbf{y}}(\tau, f_0)||_{L_2}$$
(2) 324

where  $T_c^M$  and  $T_c^V$  are the closed interval durations from 330 the model and from the video analysis respectively, y =331  $[y(n_i), ..., y(n_i + N_{fr})]$  and  $\mathbf{y} = [\tilde{y}(n_i), ..., \tilde{y}(n_i + N_{fr})]$  are 332 the target and reproduced speech waveforms, respectively. 333 The parameters  $\alpha_1$  and  $\alpha_2$  allow to weight the importance 334 of the glottal time parameter term over the speech waveform 335 term and are set both to 0.5 in our experiments. The order 336 of the AR filter representing the vocal tract filter was set to 337 40 (the sampling rate of the audio data being 44,100 Hz). 338 Figures 7 and 8 show the result of the adaptation of the folds 339 340

 
 Table 1
 Time-based parameters (mean values and standard deviations)
 computed from the video data for subject S1 (male, pitch: 130.0Hz), and S2 (male, pitch; 178.6 Hz). Parameters reported are T (period),  $T_c$ 

(closed interval),  $T_{op}$  (opening interval),  $T_{cl}$  (closing interval), expressed in milliseconds, and OQ (open quotient), SQ (speed quotient)

Subj.	Т	T <sub>c</sub>	T <sub>op</sub>	T <sub>cl</sub>	CQ	SQ
S1	7.4 (130.0 Hz)	3.4	2.0	2.0	0.46	1.0
S2	5.6 (178.6 Hz)	2.6	1.0	2.0	0.46	0.5



Fig. 7 An analysis frame from subject S1 showing the adaptation of the folds model with respect to glottal area time intervals measured from videokymographic image: a shows the acoustic pressure recorded at lips and the videokymographic data and reports the closed and open intervals ( $T_c$  and  $T_o$ , respectively) estimated by the image analysis process; b shows the reproduced lip pressure and the time evolution of the modeled folds (lateral displacement of lower edge and upper delayed edge),

when the model is fitted to the acoustic data using a randomly chosen value for the parameter  $\tau$ , affecting the edges phase difference. An arbitrary value of 2 samples was used for the parameter  $\tau$ , resulting in a short closed interval and longer open interval; c shows the reproduced lip pressure and the time evolution of the modeled folds when the target intervals measured from video are used to tune the parameter  $\tau$  (reaching the final value of 39 samples)

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Fig. 8 An analysis frame from subject S2 [plots and parameters are as in Fig. 7. For this subject, the arbitrary value used in the audio-only procedure for  $\tau$  was 60 samples, providing a wide closed phase (b)]. The parameter reached a value of 32 samples upon tuning (c)

<b>Table 2</b> Segmental SNR and ISspectral distance values for	Subj.	Glottal are	a (rel. error)			Speech wave	form
distinct modeling settings, referring to audiovisual data		T (%)	T <sub>c</sub>	<i>T</i> <sub>op</sub> (%)	$T_{\rm cl}$	SNR	IS
from subjects S1 and S2	S1	<1	3.1% (23%)	18	7_	1.8 (0.8)	3.8 (5.0)
(average values, calculated over 20 frames for each subject)	<u>S2</u>	<1	3.8% (19%)	32	-	2.7 (0.6)	2.9 (8.1)

model with respect to the target waveforms and area parame-34 ters. Note that here we only addressed the matching of the 342 open and closed glottis time intervals and did not attempted 343 at matching the correct opening and closing intervals within 344 each open phase. This is because, given the present design of 345 the model, there is no direct relation that links these intervals 346 to one prevailing parameter, as it is the case for the phase 347 delay parameter  $\tau$  and the closed phase. Most probably, all 348 the parameters of the fluid mechanical model of the folds 349 affect the evolution of the open phase, as well as the inter-350 action with the vocal tract. This issue will be the object of 351 future investigation. 352

Looking at Figs. 7 and 8, it can be seen that in both 353 cases the fitting procedure which also relies on video analy-354 sis (Figs. 7c, 8c) allows to match the closed and open inter-355 vals with good approximation. To provide a measure of the 356 acoustic reconstruction quality, two objective measures are 35 adopted: the SNR, defined as the ratio of signal energy over 358 the reconstruction error energy, and Itakura-Saito (IS) spec-359 tral distance, a measure of the perceptual difference between 360 the target signal spectrum and the modeled signal spec-361 trum. With respect to the fitting results based only on audio 362 (Figs. 7b, 8b), in which the parameter  $\tau$  was chosen arbitrar-363 ily, the quality measures computed on the speech waveform 364 also are improved for this specific frame: SNR improves from 365 0.91 to 1,93 for subject S1, and from 0.60 to 2.92 for subject 366 S2; the IS distance decreases from 4.7 to 3.68 for subject 367 S1, and from 6.5 to 0.5 for subject S2. In Table 2, the fitting 368 performances of the proposed model are compared in terms 369 of glottal area time-related parameters, and in terms of SNR 370

and IS distance. Values refers to the average of SNR and IS values, calculated on the acoustic speech signal over a total of 20 analysis frames for each subject (segmental measures). The glottal area-related parameters are expressed as relative errors given by modeled values compared with the target values computed from video: rel\_err =  $|(T^M - T^V)|/T^V$ .

First column refers to the glottal period, and error is below 377 1% in both cases; the second column shows the average 378 improvement provided by using video data analysis if com-379 pared with audio-only analysis (values in parentheses). The 380 third column reports the values related to the opening inter-381 val, although the fitting of opening and closing intervals 382 is not addressed here. The value for subject S1 is around 383 20% and does not improve significantly with the video-384 based analysis. This happens for subject S2 too, for which, 385 however, the error value is rather high, probably because 386 the opening interval is shorter in average than the closing 387 interval, whereas the model shows rather symmetrical open-388 ing and closing intervals with the parametric configuration 389 used here. 390

It is to be stressed that the experiments were conducted 391 on a minimal dataset, due to the limited availability of 392 pre-recorded audiovisual endoscopic data and to the semi-393 automatic nature of the procedure illustrated. Thus, the 394 improvements documented here cannot be claimed to be sta-395 tistically significant. Nonetheless, we believe that the out-396 come of this experiment provides interesting information on 397 the potentials of such a data analysis setting, in which a phys-398 iologically motivated model is adapted to both acoustic and 399 video endoscopic data. 400

#### 4 Conclusions 401

The use of videokymographic data to improve the audio-402 based parametrization of a nonlinear dynamical model of 403 the vocal folds has been investigated. A low-dimensional 404 glottal model, provided with features which permit to accurately control glottal sub-cycle features such as open- and 40F closed-phase durations, was adopted. A video processing 407 analysis procedure was designed, to extract glottal cues form 408 the high-speed video data, which are not directly observ-409 able from lip pressure signals. The video cues were used 410 in a joint audio-video parametric identification procedure, 411 to obtain an accurate tuning of the glottal numerical model. 412 This in turn provides an improved superposition of actual and 413 modeled vocal fold edge displacement and an accurate open 414 phase/closed phase-related glottal cues. It has finally been 415 shown that improved glottal closed/open intervals is also ben-416 eficial to the vocal tract parameter identification, resulting in 417 improved speech signal reconstruction error and IS spectral 418 distance. 419

Given the pilot nature of this investigation and due to the 420 scarce availability of audiovisual videokymographic record-421 ings, the experiments were conducted on a limited amount 422 of data. Future experiments will address the statistical sig-423 nificance of the method by assessing it on a larger number 424 of subjects and on wider spectrum of variables, including 425 gender, age, and phonatory settings. 426

Further developments are also foreseen in terms of model details and tracking procedure. The model used here is intrin-428 sically symmetrical, i.e., only one fold is actually represented 429 by a moving mass. It is often the case that the motion of the 430 left and of the right fold is slightly asymmetrical, even in 43 healthy subjects. An improved representation of the folds 432 motion is possible by explicitly modeling each fold indepen-433 dently. 434

Also, it has been noted that the fitting of opening and clos-435 ing time intervals, summing up to the open interval, has not 436 been addressed in this paper. The ratio of these two intervals 437 is considered to be an interesting glottal parameter (speed quotient) to characterize non-modal phonation. The possi-439 bility of accurately matching these cues by extending the 440 proposed procedure will be further investigated. 44

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