

HUMAN FACE DETECTION AND RECOGNITION

**A THESIS SUBMITTED IN PARALLEL FULFULMENT
OF THE REQUIREMENTS FOR THE DEGREE OF**

**Bachelor in Technology
In
Electronics and Communication Engineering
by**

K Krishan Kumar Subudhi (107EC020)

And

Ramshankar Mishra(107EC004)



**Department of Electronics and Communication Engineering
National Institute of Technology, Rourkela**

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Under the guidance of

Prof. S Meher



Department of Electronics and Communication Engineering
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National Institute of Technology
Rourkela

CERTIFICATE

This is to certify that the thesis titled “Human Face Recognition and Detection” submitted by K Krishan Kumar Subudhi (107EC020) and Ramshankar Mishra (107EC004) in partial fulfilment for the requirements for the award of Bachelor of Technology Degree in Electronics and Communication Engineering at National Institute of Technology, Rourkela (Deemed University) is an authentic work carried out by them under my supervision and guidance.

Date:

Prof. S Meher

Department of Electronics and
Communication Engineering

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ABSTRACT

Human face detection and recognition play important roles in many applications such as video surveillance and face image database management. In our project, we have studied worked on both face recognition and detection techniques and developed algorithms for them. In face recognition the algorithm used is PCA (principal component analysis), MPCA(Multilinear Principal Component Analysis) and LDA(Linear Discriminant Analysis) in which we recognize an unknown test image by comparing it with the known training images stored in the database as well as give information regarding the person recognized. These techniques works well under robust conditions like complex background, different face positions. These algorithms give different rates of accuracy under different conditions as experimentally observed.

In face detection, we have developed an algorithm that can detect human faces from an image. We have taken skin colour as a tool for detection. This technique works well for Indian faces which have a specific complexion varying under certain range. We have taken real life examples and simulated the algorithms in MATLAB successfully.

CHAPTER-1

INTRODUCTION

1 INTRODUCTION

The face is our primary focus of attention in social life playing an important role in conveying identity and emotions. We can recognize a number of faces learned throughout our lifespan and identify faces at a glance even after years of separation. This skill is quite robust despite of large variations in visual stimulus due to changing condition, aging and distractions such as beard, glasses or changes in hairstyle.

Computational models of face recognition are interesting because they can contribute not only to theoretical knowledge but also to practical applications. Computers that detect and recognize faces could be applied to a wide variety of tasks including criminal identification, security system, image and film processing, identity verification, tagging purposes and human-computer interaction. Unfortunately, developing a computational model of face detection and recognition is quite difficult because faces are complex, multidimensional and meaningful visual stimuli.

Face detection is used in many places now a days especially the websites hosting images like picassa, photobucket and facebook. The automatically tagging feature adds a new dimension to sharing pictures among the people who are in the picture and also gives the idea to other people about who the person is in the image. In our project, we have studied and implemented a pretty simple but very effective face detection algorithm which takes human skin colour into account.

Our aim, which we believe we have reached, was to develop a method of face recognition that is fast, robust, reasonably simple and accurate with a relatively simple and easy to understand algorithms and techniques. The examples provided in this thesis are real-time and taken from our own surroundings.

CHAPTER 2

FACE RECOGNITION

2 FACE RECOGNITION

The face recognition algorithms used here are Principal Component Analysis(PCA), Multilinear Principal Component Analysis (MPCA) and Linear Discriminant Analysis(LDA).

Every algorithm has its own advantage. While PCA is the most simple and fast algorithm, MPCA and LDA which have been applied together as a single algorithm named MPCALDA provide better results under complex circumstances like face position, luminance variation etc. Each of them have been discussed one by one below.

2.1 PRINCIPAL COMPONENT ANALYSIS (PCA)

Principal component analysis (PCA) was invented in 1901 by Karl Pearson. PCA involves a mathematical procedure that transforms a number of possibly correlated variables into a number of uncorrelated variables called principal components, related to the original variables by an orthogonal transformation. This transformation is defined in such a way that the first principal component has as high a variance as possible (that is, accounts for as much of the variability in the data as possible), and each succeeding component in turn has the highest variance possible under the constraint that it be orthogonal to the preceding components. PCA is sensitive to the relative scaling of the original variables. Depending on the field of application, it is also named the discrete **Karhunen–Loève transform (KLT)**, the **Hotelling transform** or **proper orthogonal decomposition (POD)**.

The major advantage of **PCA** is that the eigenface approach helps reducing the size of the database required for recognition of a test image. The trained images are not stored as raw images rather they are stored as their weights which are found out projecting each and every trained image to the set of eigenfaces obtained.

2.1.1 The eigenface approach

In the language of information theory, the relevant information in a face needs to be extracted, encoded efficiently and one face encoding is compared with the similarly encoded database. The trick behind extracting such kind of information is to capture as many variations as possible from the set of training images.

Mathematically, the principal components of the distribution of faces are found out using the eigenface approach. First the eigenvectors of the covariance matrix of the set of face images is found out and then they are sorted according to their corresponding eigenvalues. Then a threshold eigenvalue is taken into account and eigenvectors with eigenvalues less than that threshold values are discarded. So ultimately the eigenvectors having the most significant eigenvalues are selected. Then the set of face images are projected into the significant eigenvectors to obtain a set called eigenfaces. Every face has a contribution to the eigenfaces obtained. The best M eigenfaces from a M dimensional subspace is called “face space”

Each individual face can be represented exactly as the linear combination of “eigenfaces” or each face can also be approximated using those significant eigenfaces obtained using the most significant eigen values.



Figure 1 : eigenfaces

Now the test image subjected to recognition is also projected to the face space and then the weights corresponding to each eigenface are found out. Also the weights of all the training images are found out and stored. Now the weights of the test image is compared to the set of weights of the training images and the best possible match is found out. The comparison is done using the “**Euclidean distance**” measurement. Minimum the distance is the maximum is the match.

The approach to face recognition involves the following initialisation operations:

1. Acquire an initial set of N face images (training images).
2. Calculate the eigenface from the training set keeping only the M images that correspond to the highest eigenvalues. These M images define the “facespace”. As

new faces are encountered, the “eigenfaces” can be updated or recalculated accordingly.

3. Calculate the corresponding distribution in M dimensional weight space for each known individual by projecting their face images onto the “face space”.
4. Calculate a set of weights projecting the input image to the M “eigenfaces”.
5. Determine whether the image is a face or not by checking the closeness of the image to the “face space”.
6. If it is close enough, classify, the weight pattern as either a known person or as an unknown based on the Euclidean distance measured.
7. If it is close enough then cite the recognition successful and provide relevant information about the recognised face form the database which contains information about the faces.

2.1.2 Mathematical approach

Let $\Gamma_1, \Gamma_2, \dots, \Gamma_m$ be the set of train images.

Average face of set can be defined as $\Psi = (1/M) \sum_{n=1}^M (\Gamma_n)$

Each face differs from the average by the vector $\Phi_i = \Gamma_i - \Psi$

when subjected to PCA, this large set of vectors seeks a set of M orthogonal vectors U_n , which best describes the distribution of data.

The k_{th} vector U_k is chosen such that

$$\lambda_k = (1/M) \sum_{n=1}^M [(U_k)^T * \Phi_n]^2$$

is maximum, subject to $(U_l)^T U_k = \delta_{lk} = \begin{cases} 1, & \text{if } l=k \\ 0, & \text{otherwise} \end{cases}$

The vector U_k and scalar λ_k are the eigenvectors and eigenvalues respectively of the covariance matrix

$$C = (1/M) \sum_{n=1}^M (\Phi_n)(\Phi_n)^T$$
$$= AA^T$$

Where the matrix $A = [\Phi_1 \Phi_2 \dots \Phi_M]$.

2.2 Experimental analysis

We created a student database of *NIT Rourkela* which contains their photographs and information (*name, age, roll no*).

2.2.1 Student database.....

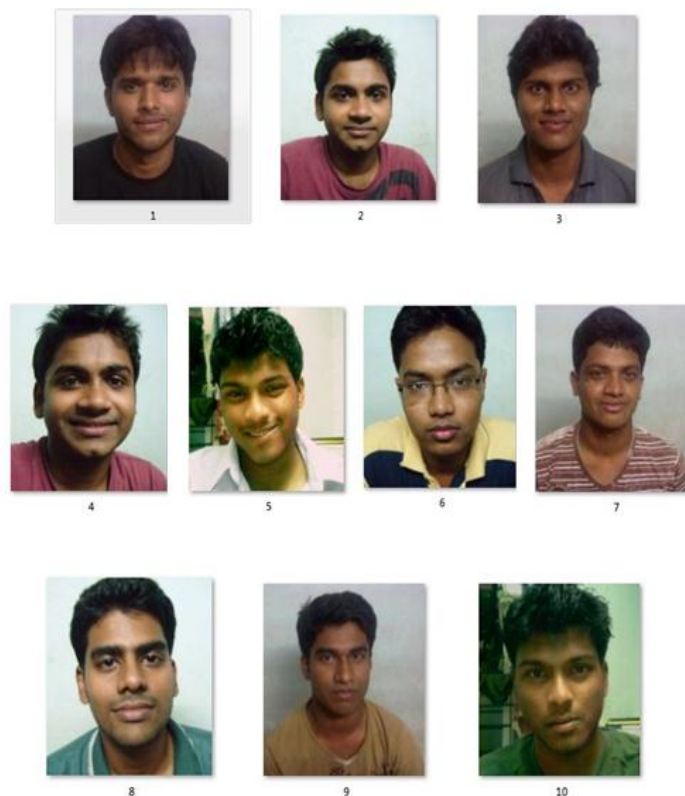


Figure 2 face database

2.2.1.1 Student information

	NAME	AGE	ROLL NUMBER
1	ramshankar	21	107ec004
2	fun	20	107ec019
3	sridhar	21	107mm028
4	fun	20	107ec019
5	krish	21	107ec020
6	srijeya	21	107ec017
7	rampadhy	21	107cs044
8	goutam	21	107cs026
9	santosh	21	107ei033

9 eigenfaces were obtained from the 10 test images. Since the database is not large enough, the threshold eigenvalue was kept low.



Figure 3 eigenfaces obtained

2.2.2 Testing

According to the procedure given above “eigen faces” of the stored database is found out.

Then feature vector of the each individual is calculated by projecting it onto the set of

eigenface. When a test image comes feature vector is calculated exactly in the same way. It compares with the stored database by calculating the distance between two vectors. The training image who has minimum distance with the test image vector is our desired result.



Figure 4 test image

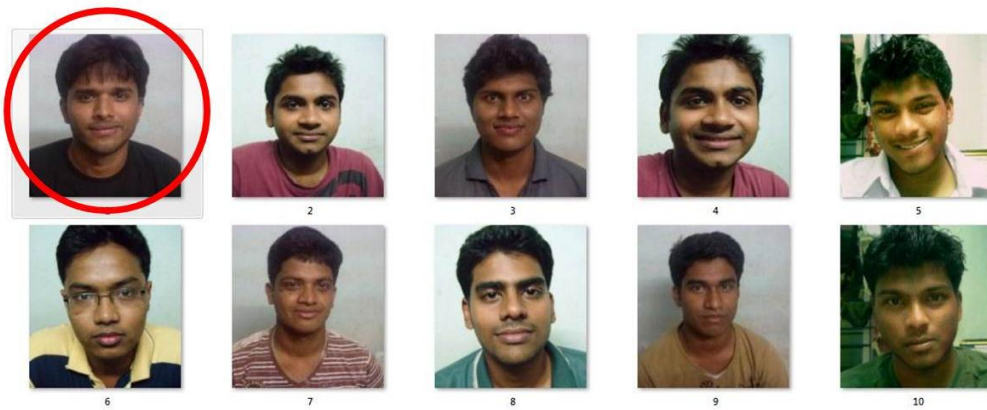


Figure 5 comparison with the database

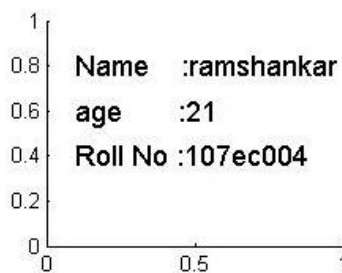


Figure 6 result after comparison

2.3 Advantages of PCA

1. It's the simplest approach which can be used for data compression and face recognition.
2. Operates at a faster rate.

2.4 Limitations of PCA

1. Requires full frontal display of faces
2. Not sensitive to lighting conditions, position of faces.
3. Considers every face in the database as a different image. Faces of the same person are not classified in classes.

A better approach was studied and used to compensate these limitations which are called MPCALDA. While MPCA considers the different variations in images, LDA classifies the images according to same or different person.

2.5 MPCALDA

2.5.1 MPCA

Multilinear Principal Component Analysis (MPCA) is the extension of PCA that uses multilinear algebra and proficient of learning the interactions of the multiple factors like different viewpoints, different lighting conditions, different expressions etc.

In PCA the aim was to reduce the dimensionality of the images. For example a $20 \times 32 \times 30$ dataset was converted to 640×30 that is images are converted to 1D matrices and then the eigenfaces were found out of them. But this approach ignores all other dimensions of an image as an image of size 20×32 speaks of a lot of dimensions in a face and 1D vectorizing

doesn't take advantage of all those features. Therefore a dimensionality reduction technique operating directly on the tensor object rather than its 1D vectorized version is applied here.

The basic idea behind consideration of different dimensions can be explained by the below formula.

$$Y_i = X_i \times_1 \bar{U}^{(1)\tau} \times_2 \bar{U}^{(2)\tau} \dots \times_N \bar{U}^{(N)\tau}$$

Where Y_i = output , X_i = input, $U^{(n)}$ = transformation vectors

The approach is similar to PCA in which the features representing a face are reduced by eigenface approach. While in PCA only one transformation vector was used, in MPCA N number of different transformation vectors representing the different dimensionality of the face images are applied.

2.5.2 LDA

LDA which is known as Linear Discriminant Analysis is a computational scheme for evaluating the significance of different facial attributes in terms of their discrimination power. The database is divided into a number of classes each class contains a set of images of the same person in different viewing conditions like different frontal views, facial expression, different lighting and background conditions and images with or without glasses etc. It is also assumed that all images consist of only the face regions and are of same size.

By defining all the face images of the same person in one class and faces of other people in different classes we can establish a model for performing cluster separation analysis. We have achieved this objective by defining two terms named “between class scatter matrix” and “within class scatter matrix”. The database used here is a FERET database which is a reference database for the testing of our studied algorithm.

2.5.3 Procedure

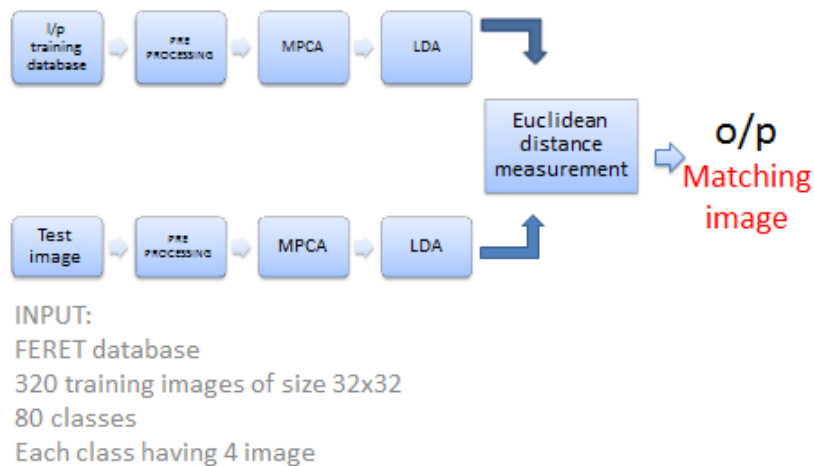


Figure 7 block diagram of MPCALDA

2.5.4 Testing



$$S_w^{(V)} = \sum_{i=1}^L \Pr(C_i) \Sigma_i$$

$$\Sigma_i = E[(V - \mu_i)(V - \mu_i)^T | C = C_i]$$

V= images
 μ_i = within class mean
 of images

$$S_b^{(V)} = \sum_{i=1}^L \Pr(C_i) (\mu - \mu_i)(\mu - \mu_i)^T$$

μ = mean of the whole
 image dataset

Figure 8 representation of scatter matrices

Now the TSB and TSW values are compared with each other to find a relation between them and the “fisher ratio” is found out which is the ratio of TSB & TSW.

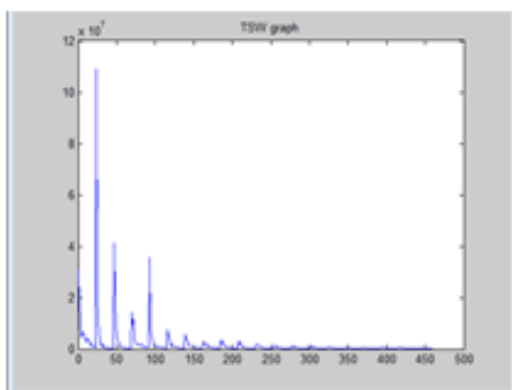
$$\text{Fisher ratio} = \text{TSB}/\text{TSW}$$

Then the fisher ratio is sorted in the descending order. Then it is truncated to discard the features having a low fisher ratio values. Thereby we can minimise the dimensions of the database considering both within class and between class variations. In this method we are emphasizing the between class (different people) variation supressing the within class variations (same person) which adds a new dimension to faster face recognition reducing the computational complexities.

2.5.5 Results

2.5.5.1 *TSB, TSW and fisher ratio:*

TSB vs feature index



TSW vs feature index

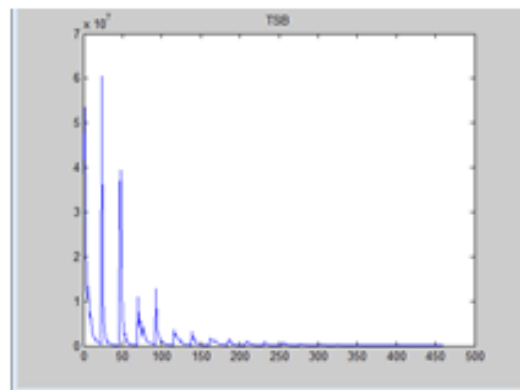


Figure 9 comparison between TSB and TSW

$$\text{Fisher ratio} = \text{TSB.}/\text{TSW}$$

Fisher ratio vs feature index

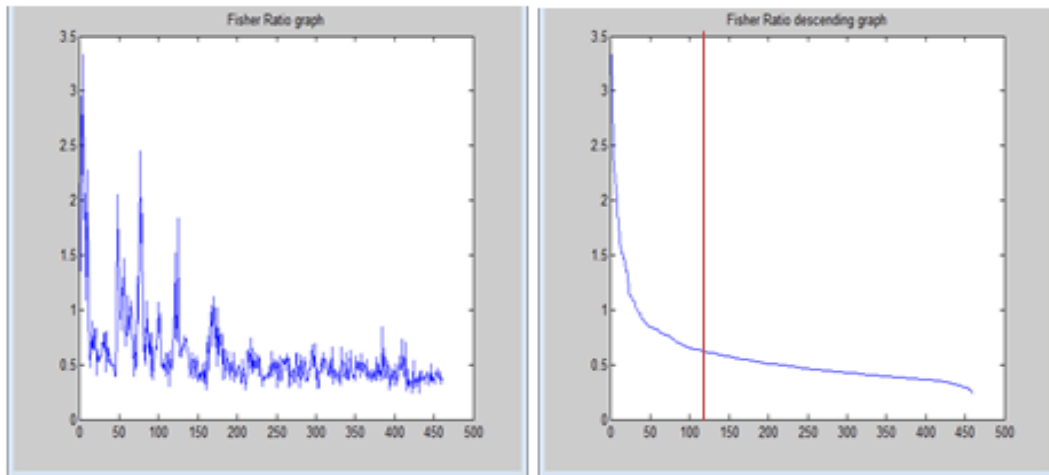


Figure 10 fisher ration vs feature index

2.5.5.2 Eigenvalues and eigenvectors:

TSW and TSB are truncated according to the fisher ratio and the truncated scatter matrices are named as SW and SB. Now the eigenvectors of $inv(SW)*SB$ are calculated to emphasise more on between class variations than within class variations. Then the eigenvalues are also found out and sorted in descending order and the eigenvectors having the most significant eigenvalues are taken into consideration.

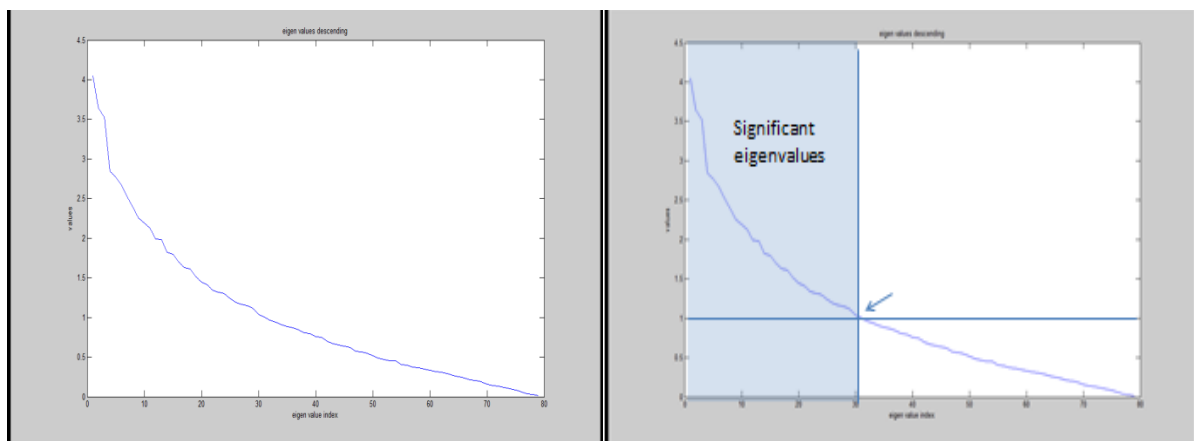


Figure 11 fisher ration in descending order

2.5.5.3 Recognition:

The features of test image were also extracted in the same fashion and were compared with the trained database. The recognition was successful on 95% of the occasion. The recognition algorithm was same as PCA and it involved the minimum



Figure 12 recognition using MPCALDA

Euclidian distance approach. Hence either way it detected a face either true or false. The quantitative success rates are provided below. Also a comparison between PCA and MPCALDA algorithm is done to highlight the advantages of this algorithm over PCA.

Table 1 comparison between PCA and MPCALDA

PCA	MPCALDA
<ul style="list-style-type: none"> Requires full frontal display Each face is a single entity in the database 	<ul style="list-style-type: none"> Works well with different viewpoints, expressions and lighting conditions Faces of same person are grouped together classes

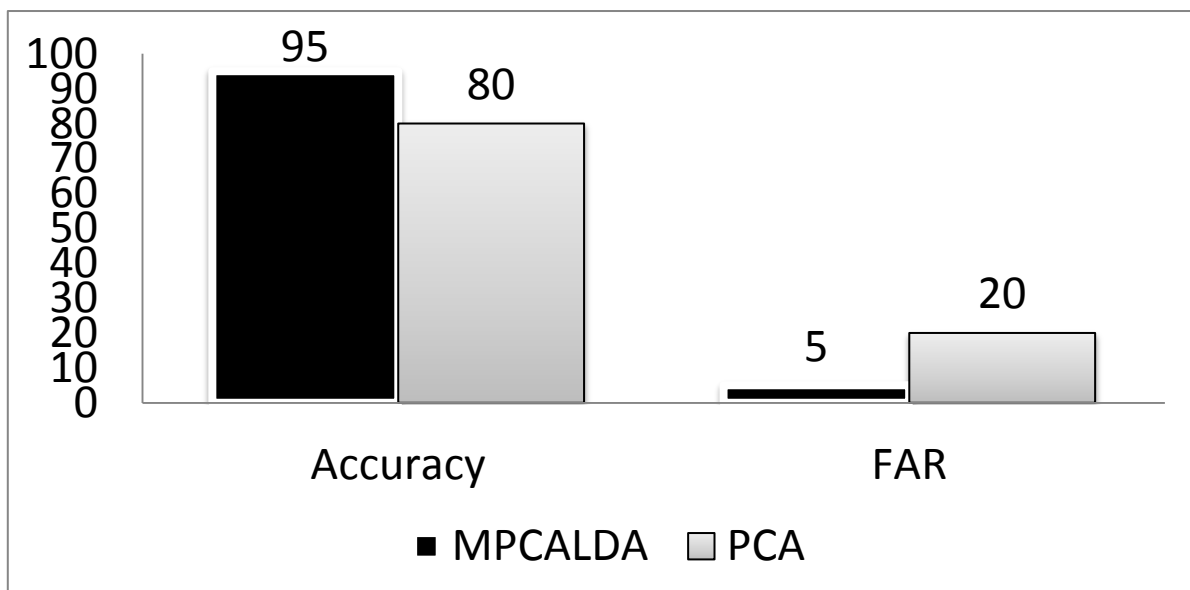


Figure 13 success rates

Chapter 3

Face detection

3 Face detection

3.1 Introduction

Face detection is the first step of face recognition as it automatically detects a face from a complex background to which the face recognition algorithm can be applied. But detection itself involves many complexities such as background, poses, illumination etc.

There are many approaches for face detection such as, colour based, feature based (mouth, eyes, nose), neural network. The approach studied and applied in this thesis is the skin colour based approach. The algorithm is pretty robust as the faces of many people can be detected at once from an image consisting of a group of people. The model to detect skin colour used here is the YCbCr model.

The different steps of this face detection algorithm can be explained as below.

3.2 YCbCr model:

YCbCr or Y'CbCr is a family of color space used generally in digital image processing. Y is the luminance, Y' is the luma component while Cb and Cr are the blue difference and red difference of the chroma component. YCbCr is not an actual colour space, it is just a way of encoding the RGB colour space. YCbCr values can only be obtained only if the original RGB information of the image are available.

$$Y = 0.299R + 0.587G + 0.114B$$

$$Cb = -0.169R - 0.332G + 0.500B$$

$$Cr = 0.500R - 0.419G - 0.081B$$

RGB components are subject to the lighting conditions thus the face detection may fail if the lighting condition changes. Human skin colour has a specific range of chrominance values while luminance is dependent on external variables.

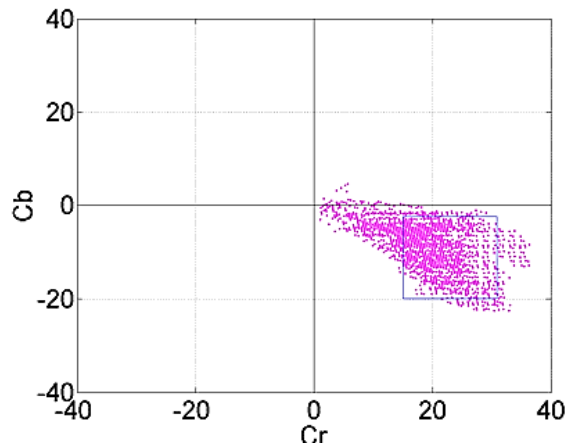


Figure 14 Cb vs Cr

3.2.1 Real time data

A real time experiment was conducted by taking 30 faces of our college students (figure 15) and their skin composition was studied to find out the range of Y, Cb and Cr.

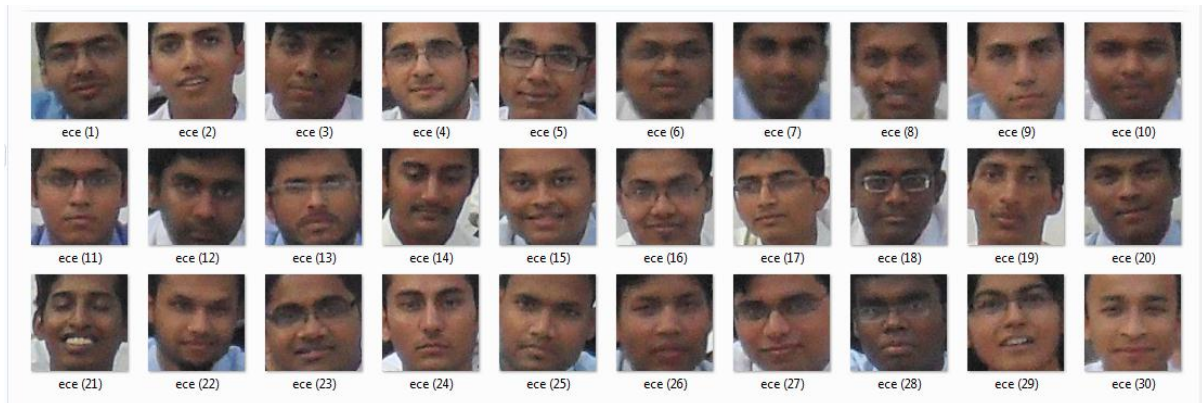


Figure 15 test image database for skin color analysis

The histogram of the Y, Cb, Cr values were obtained (figure 16) from which the mean and the standard deviation was calculated.

The mean and standard deviation of luminance were found as 77 and 31 respectively while for Cb and Cr the values obtained were -6, 6.654 and 10, 7.74 respectively.

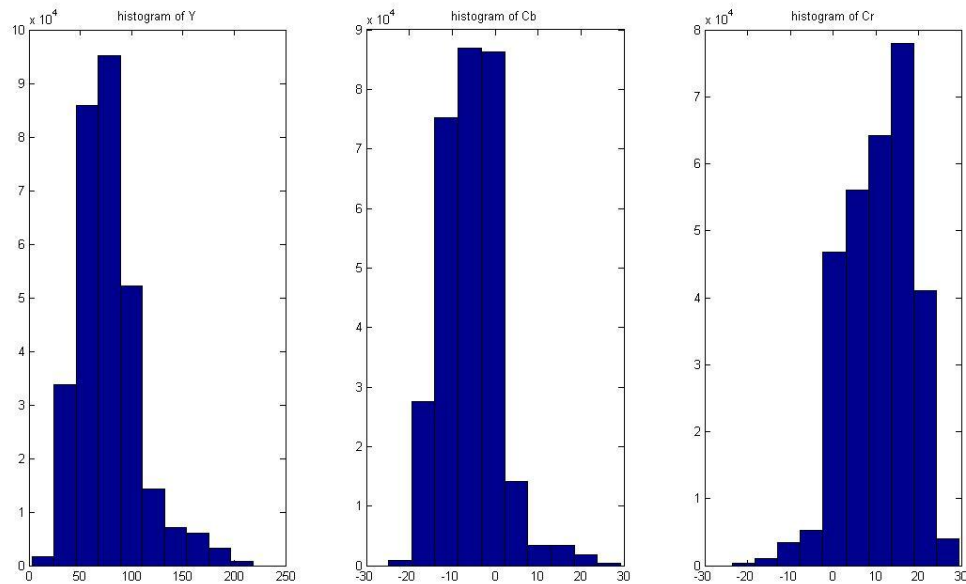


Figure 16 histograms of Y, Cb and Cr values

3.3 Colour segmentation

A test image shown in figure 17 was taken and the parts of the image having colours coming under the range of skin colours were highlighted.



Figure 17 test image for face detection

This image in figure 17 was studied as a test image and the image was converted into a binary image in which the skin colours were highlighted as white and the rest as black. The output of this filtering process is shown in figure 18.



Figure 18 image after passing through YCbCr filter

3.4 Image segmentation

The binary image obtained was found to consist of many small white and black regions which are removed by further filtering processes as shown in figure 19 and 20.



Figure 19 black isolated hole rejection

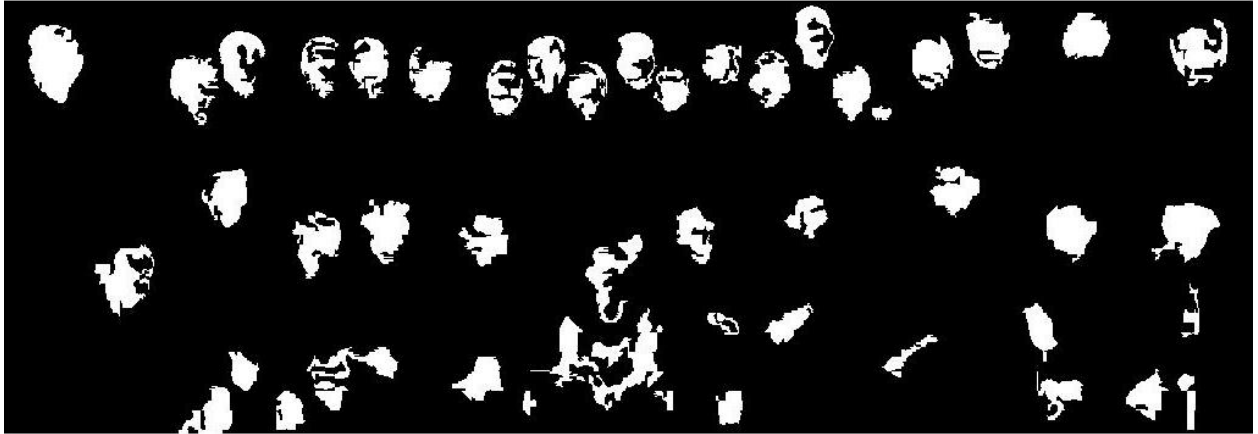


Figure 20 white isolated holes less than small area rejection

As some face regions may be integrated with other face regions, they need to be separated. For that purpose, Robert Cross Edge detection Algorithm is used. The Robert algorithm finds the edges or the first gradient of the test image.

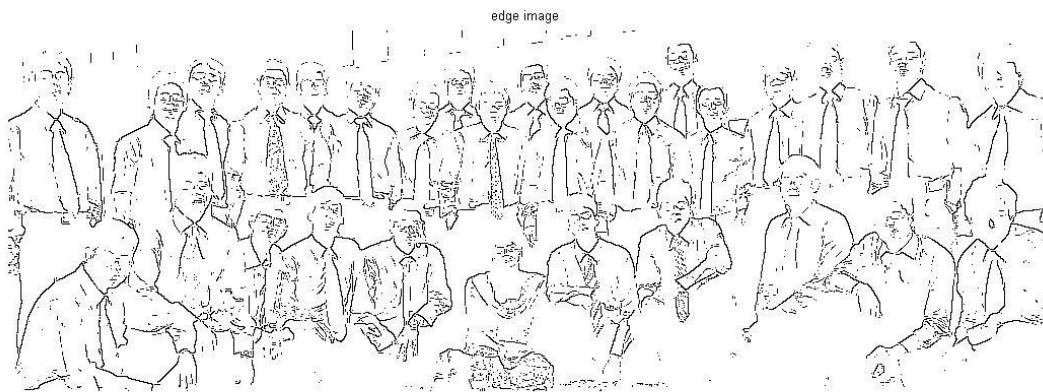


Figure 21 edges detected by Roberts cross operator

Now the filtered image and the edge images both are integrated to remove relatively small white and black areas and the the image is again passed through the filters to obtain the final filtered binary image. Figure 24 shows the final binary image.

integration of two images, edge + filtered image

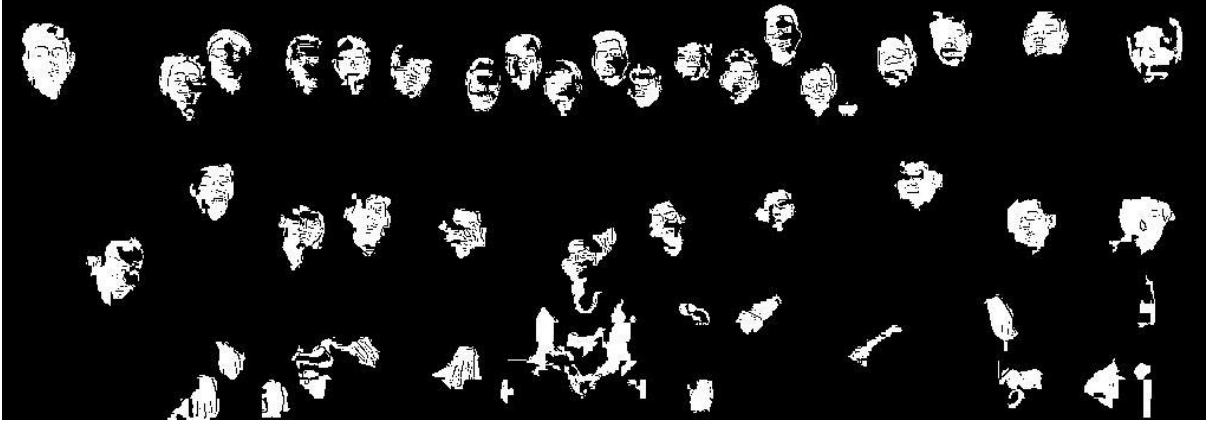


Figure 22 integration of two images edge+filtered

second black isolated hole rejection



Figure 23 second black isolated hole rejection

small areas less than minimum area of face rejection



Figure 24 small areas less than minimum area rejection

3.5 Box formation

Around each white area a box is formed using 8-connectivity as shown in figure 25.

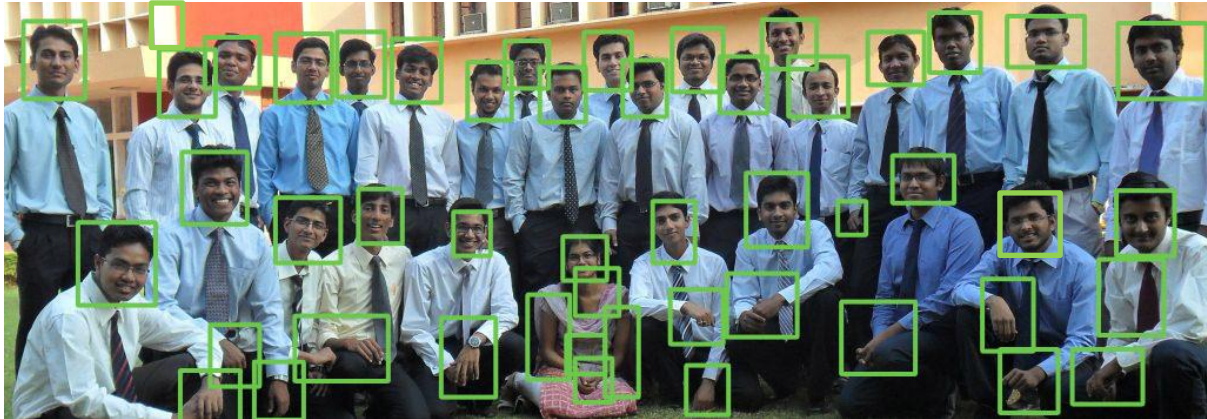


Figure 25 initial box formation

3.6 Unwanted box rejection

Many non-face areas are also selected like hands and areas having colours similar to the skin colour. So those boxes need to be rejected. 3 approaches are used for this purpose as mentioned below.

3.6.1 Thresholding

As faces generally don't fall far below the image, lower boxes around 100 pixels below the image were discarded.

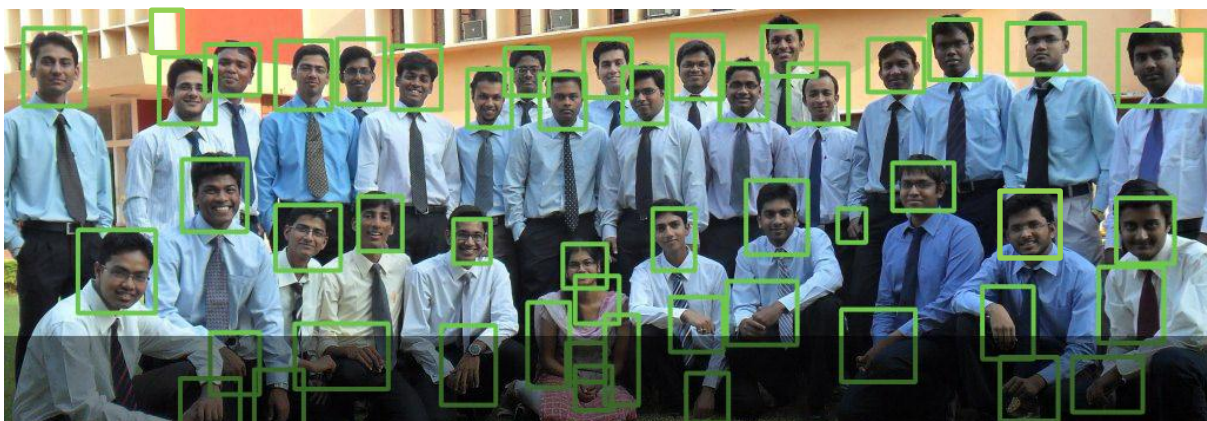


Figure 26 thresholding

3.6.2 Box merging

Many times the face and the necks are found to be detected as two separate boxes. Hence

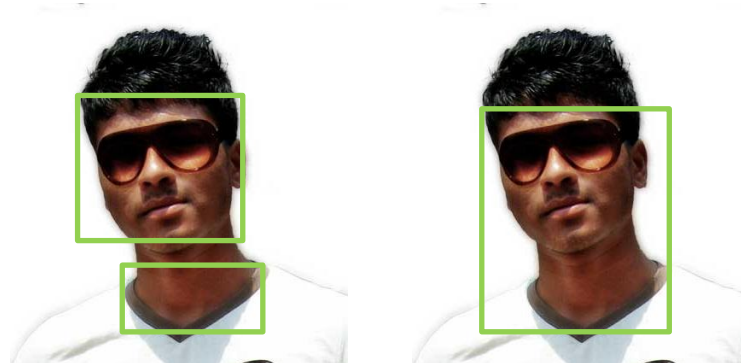


Figure 27 box merging

they need to be merged as a single box. so boxes close to each other are merged. The threshold for row width is taken as 70 pixels while for column width it is taken as 25 .

3.6.3 Image matching

The eigen faces of a set of images are obtained and the mean eigenface is taken as the reference for a face structure. All the images in the box areas are compared with the eigenface and the correlation between them is found out. Non-face areas will have low correlation while face areas will have high correlation. Then the boxes having less value of correlation are discarded. Since the boxes can be of any size, the eigenface is stored in different sizes starting from 30 pixels to 220 pixels at the step of 10 pixels (boxes are square boxes). The test images for the eigenface generation are taken as 100x100 square images.

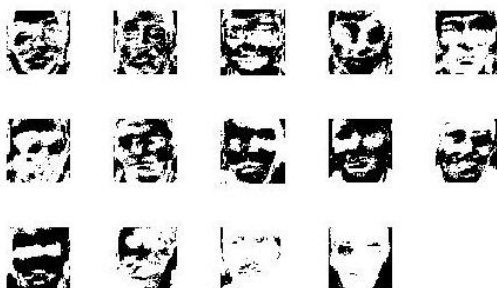


Figure 28 mean eigen face



Figure 29 eigenfaces

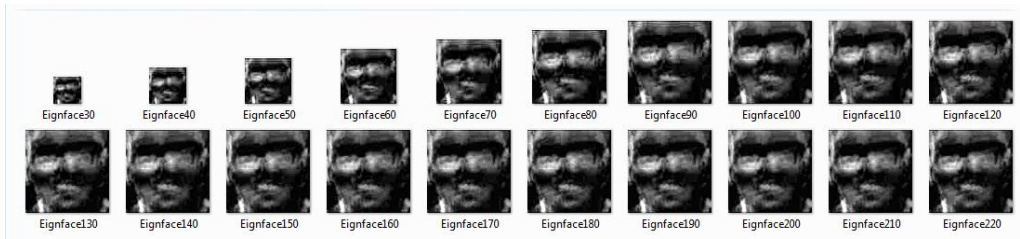


Figure 30 different sized eigen face

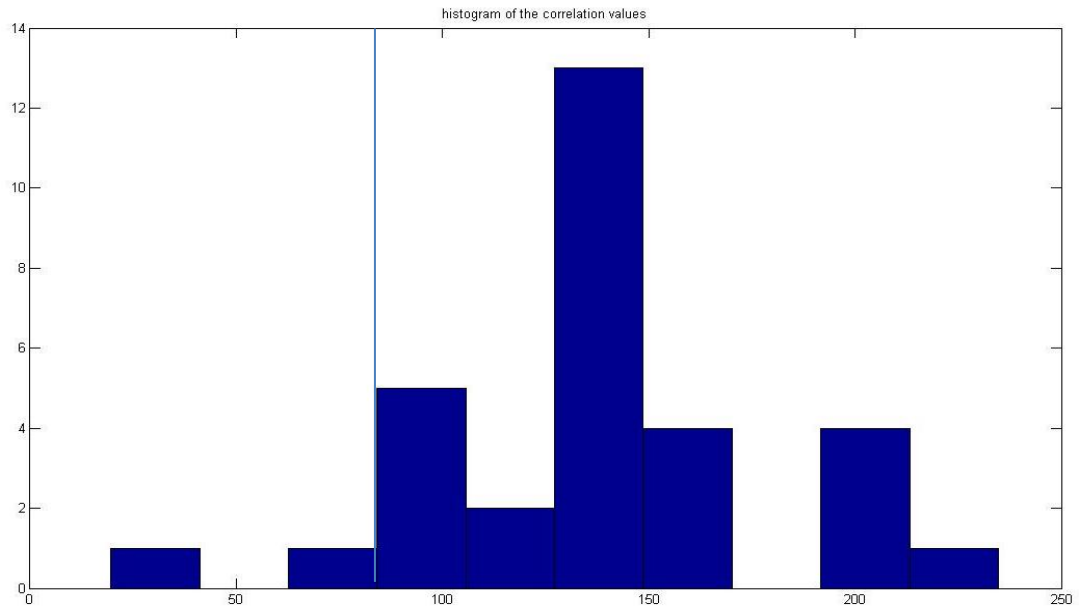


Figure 31 histogram of correlated values

3.7 Result



Figure 32 final detected image

Some of the faces were not detected properly and one nonface area was also detected as face.

The experiment was conducted again after colouring the background which provided a 100% result. Also the experiment was conducted on another image.



Figure 33 detection with a coloured background



Figure 34 another image

Images having high ranges of color (most of them falling under skin color category) showed false results.

After adjusting the filter coefficients and changing the color range, a better result was obtained.



Figure 35 better result

Table 2 table of results

Serial no	resolution	No of faces	No of hit	No of merge	No of false detection	Not detected	timing
Img 1	1024x355	30	28	1	1	0	30 sec
Img 2	1024x355	30	30	0	0	0	30 sec
Img 3	3504x1788	12	8	1	1	1	45 sec

4 Conclusion

The face recognition and detection algorithms were thoroughly studied taking a number of test images and varying the conditions and variables. All the work mentioned above involved real time data. The PCA and MPCALDA success rates were given while for face detection, the success rate was different for different images depending on the external factors. The overall success rate was 95%.

5 References

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