# THE LOCAL AND GLOBAL GEOMETRICAL ASPECTS OF THE TWIN PARADOX IN STATIC SPACETIMES: II. REISSNER-NORDSTRÖM AND ULTRASTATIC METRICS 

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This is a consecutive paper on the timelike geodesic structure of static spherically symmetric spacetimes. First, we show that for a stable circular orbit (if it exists) in any of these spacetimes all the infinitesimally close to it timelike geodesics constructed with the aid of the general geodesic deviation vector have the same length between a pair of conjugate points. In Reissner-Nordström black hole metric, we explicitly find the Jacobi fields on the radial geodesics and show that they are locally (and globally) maximal curves between any pair of their points outside the outer horizon. If a radial and circular geodesics in $\mathrm{R}-\mathrm{N}$ metric have common endpoints, the radial one is longer. If a static spherically symmetric spacetime is ultrastatic, its gravitational field exerts no force on a free particle which may stay at rest; the free particle in motion has a constant velocity (in this sense the motion is uniform) and its total energy always exceeds the rest energy, i.e. it has no gravitational energy. Previously, the absence of the gravitational force has been known only for the global Barriola-Vilenkin monopole. In the spacetime of the monopole, we explicitly find all timelike geodesics, the Jacobi fields on them and the condition under which a generic geodesic may have conjugate points.

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## 1. Introduction

This work is fourth in a series of papers [1-3] on the geodesic structure of various spacetimes. These investigations have originated from recent interest

[^0]in the twin paradox in curved spacetimes [4-9]. As is well known, there is no paradox at all and there is a purely geometrical problem of which curve of all timelike paths connecting two given spacetime points is the longest one. Actually, the problem consists of two different problems. Firstly, one is interested in the problem of determining the locally maximal curve. Assume that two given points, $p$ and $q$, are connected by a timelike geodesic $\gamma(0)$ and let us take a bundle of nearby timelike curves from $p$ to $q$, that is the curves which are everywhere at $\varepsilon$-distance from $\gamma(0)$. Then, one seeks for the longest curve in the bundle. A general formalism for dealing with this local maximality problem was presented in the monograph [10] and the most relevant theorems were quoted in [1]. The method of solving it is algorithmic: one solves the geodesic deviation equation on $\gamma(0)$ and finds the points at which the geodesic deviation vector field vanishes, these are conjugate points on the geodesic. If the segment of $\gamma(0)$ from $p$ to $q$ contains no points conjugate to $p$, the geodesic is locally the longest curve. In practice, one expands the deviation vector field in a suitably chosen basis of three spacelike mutually orthogonal and parallelly transported along $\gamma(0)$ vector fields, then the geodesic deviation equation containing second absolute derivatives of the deviation vector is replaced by three equations for the Jacobi scalars (the coefficients of the expansion).

Yet the global problem concerns finding out the longest curve among all possible timelike curves joining $p$ and $q$ and one should take into account curves which are arbitrarily far from each other (besides the endpoints). Clearly, the problem is different from the local one because it is not algorithmic: there is no effective method allowing one to determine in a finite number of steps the globally maximal worldline. In [2], we briefly show what is known on the subject by quoting the most relevant 'existence theorems' from the monograph [11]. It turns out that a timelike geodesic is not globally maximal beyond the future cut point which in the problem takes place of the conjugate point. If the spacetime admits an isometry, such as spherical symmetry, it is possible to determine globally maximal timelike geodesics between pairs of points which are distinguished by the isometry.

Our investigations here are heavily based on the formalisms developed in [2] and partially in [1]. The paper is organised as follows. In Section 2 we deal with one aspect of the problem of the locally maximal worldlines. A future directed timelike geodesic from $p$ to $q$ is locally maximal if the first future conjugate point to $p$ lies beyond the segment $p q$. Yet to the best of our knowledge, there are no theorems stating what occurs if $q$ is conjugate to $p$ besides the fact that the geodesic $\gamma(0)$ is not the unique one locally maximal; the question is whether the geodesics $\gamma(\varepsilon)$ nearby to $\gamma(0)$ are of equal length or not. Here (Sect. 2) we show that in the case of static spherically symmetric spacetimes and circular geodesics, all the
nearby geodesic curves determined by the general geodesic deviation vector field have the same length as the circular one from any $p$ to the first conjugate point $q$. One is unable to determine conjugate points (and possibly cut points) on a generic timelike geodesic in the given spacetime due to technical difficulties: the geodesic deviation equation is intractable in the general case, even for high symmetries. Usually, the investigation must be restricted to geometrically distinguished geodesic lines, such as radial or circular ones (if exist). Therefore, in Section 3 we study radial and circular geodesics in the Reissner-Nordström black hole metric. An exception to the restriction is provided by a narrow class of Lorentzian manifolds, the ultrastatic spherically symmetric spacetimes which are so simple that allow one to explicitly find generic timelike geodesic curves and furthermore to explicitly solve (in the form of some integrals) the equations for the Jacobi scalars along these lines. In Section 4, we develop a general formalism for these spacetimes. The formalism is applied in Section 5 to the spacetime of the global Barriola-Vilenkin monopole without mass. Brief conclusions are contained in Section 6.

For concreteness and as a trace of the original twin paradox, we assume that a circular geodesic is followed by the twin B and the radial one is the worldline of the twin C . We consider only timelike geodesics and do not mark this fact each time. We use all the concepts and conventions as in [2] and [1].

## 2. Properties of timelike geodesics which intersect the timelike circular geodesics in two points in static spherically symmetric spacetimes

In [2], we investigated the conjugate points for timelike circular geodesic curves in a general static spherically symmetric (SSS) spacetime with the metric in the standard coordinates

$$
\begin{equation*}
d s^{2}=e^{\nu(r)} d t^{2}-e^{\lambda(r)} d r^{2}-r^{2}\left(d \theta^{2}+\sin ^{2} \theta d \phi^{2}\right) \tag{1}
\end{equation*}
$$

for arbitrary functions $\nu(r)$ and $\lambda(r)$. It was found that a timelike circular geodesic exists at $r=r_{0}$ if and only if $\nu_{0}^{\prime} \equiv d \nu / d r\left(r_{0}\right)>0$ and $r_{0} \nu_{0}^{\prime}<2$. In other terms, if $g_{00}=e^{\nu}$ is a decreasing function (e.g. in the de Sitter space), circular particle orbits do not exist. On physical grounds, one is interested in stable particle orbits and the orbit $r=r_{0}$ is stable if the effective potential reaches minimum on it, what amounts to [2]

$$
\begin{equation*}
\nu_{0}^{\prime \prime}-\nu_{0}^{\prime 2}+\frac{3 \nu_{0}^{\prime}}{r_{0}}>0 \tag{2}
\end{equation*}
$$

and this means that $r_{0}$ is larger than the radius $r_{\mathrm{I}}$ of the innermost stable circular orbit (ISCO). It is also clear that an unstable geodesic (circular or
not) cannot contain conjugate points to any of its points and the explicit form of the deviation vectors confirms this expectation in the case of circular orbits.

Let $r=r_{0}>r_{\mathrm{I}}$ be a stable circular orbit denoted by B. As it was shown in [2] there are, in general, three infinite sequences of points conjugate to each point of the curve (assuming that the geodesic is infinitely extended to the future). Each sequence determines a continuous set of timelike geodesics intersecting B at points conjugate to an arbitrary initial point $P_{0}$. Here, we shall compute the lengths of geodesics in each of the three sets from $P_{0}$ to a conjugate point. Let B be parametrized by its arc length $\tau$ (we shall denote by $s$ the arc length of the geodesics intersecting B at the conjugate points) and, as usual, the angular coordinates are so chosen that the spatial circle of B lies in the 2-surface $\theta=\pi / 2$, then its equation is $x^{\alpha}=x_{0}^{\alpha}(\tau)$ with

$$
\begin{equation*}
t-t_{0}=\frac{k}{\kappa} e^{-\nu_{0}} \tau \quad \text { and } \quad \phi-\phi_{0}=\frac{L}{r_{0}^{2}} \tau \tag{3}
\end{equation*}
$$

where

$$
\begin{equation*}
\frac{k^{2}}{\kappa^{2}}=\frac{2 e^{\nu_{0}}}{2-r_{0} \nu_{0}^{\prime}} \quad \text { and } \quad L^{2}=\frac{r_{0}^{3} \nu_{0}^{\prime}}{2-r_{0} \nu_{0}^{\prime}} \tag{4}
\end{equation*}
$$

Here, $k$ is the conserved (dimensionless) energy per unit particle's mass determined by the unique timelike Killing vector (and $\kappa$ is the normalization factor of the Killing field) and $L$ is the conserved angular momentum. An infinitesimal deviation vector $\varepsilon Z^{\alpha}(\tau)$ (Jacobi vector field) being any solution of the geodesic deviation equation on B connects the point $x_{0}^{\alpha}(\tau)$ on B to the corresponding point $x^{\alpha}(\tau)$ on an infinitesimally close geodesic $\gamma(\varepsilon)$. In other terms, the nearby geodesic $\gamma(\varepsilon)$ is parametrized by the arc length of B

$$
\begin{equation*}
x^{\alpha}(\tau)=x_{0}^{\alpha}(\tau)+\varepsilon Z^{\alpha}(\tau), \quad|\varepsilon| \ll 1 \tag{5}
\end{equation*}
$$

Whereas the functions $x_{0}^{\alpha}(\tau)$ exactly represent a timelike geodesic, the coordinates $x^{\alpha}(\tau)$ satisfy the geodesic equation merely in the linear approximation in $\varepsilon$. In this sense, the curve $\gamma(\varepsilon)$ is regarded as a geodesic one and if emanates from $P_{0}$ on B , then it intersects B at points conjugate to $P_{0}$. According to the well known theorem (cited in [1]), a timelike geodesic has the locally maximal length between points $P_{0}$ and $P_{1}$ if and only if there is no point conjugate to $P_{0}$ in the open segment $P_{0} P_{1}$, otherwise there is a nearby timelike curve from $P_{0}$ to $P_{1}$ which is longer than the geodesic. Here, we compare the lengths of the geodesic curves $\gamma(\varepsilon)$ with the length of B from $P_{0}$ to the first conjugate point.

We first generally show that the variation of the geodesic length is of the order of $\varepsilon^{2}$. Let $\gamma_{0}=\gamma(0)$ be any timelike geodesic parametrized by its arc length $\tau, x_{0}^{\alpha}=x_{0}^{\alpha}(\tau)$, and let $\gamma(\varepsilon)$ be any timelike (not necessarily geodesic)
infinitesimally close curve also parametrized by $\tau$, given by Eq. (5), where $Z^{\alpha}(\tau)$ is a vector field (not necessarily a Jacobi field) orthogonal to $\gamma_{0}$, i.e. $g_{\alpha \beta} u_{0}^{\alpha} Z^{\beta}=0$ along $\gamma_{0}$; here $u_{0}^{\alpha}=d x_{0}^{\alpha} / d \tau$ is the unit tangent vector to $\gamma_{0}$. The vector tangent to $\gamma(\varepsilon)$ is

$$
\begin{equation*}
u^{\alpha}=\frac{d x_{0}^{\alpha}}{d \tau}+\varepsilon \frac{d Z^{\alpha}}{d \tau} \equiv u_{0}^{\alpha}+\varepsilon \dot{Z}^{\alpha} . \tag{6}
\end{equation*}
$$

Denoting by $D / d \tau$ the absolute derivative along $\gamma_{0}$, one finds

$$
\begin{align*}
\frac{d}{d \tau}\left(g_{\alpha \beta} u_{0}^{\alpha} Z^{\beta}\right) & =\frac{D}{d \tau}\left(g_{\alpha \beta} u_{0}^{\alpha} Z^{\beta}\right)=g_{\alpha \beta} u_{0}^{\alpha} \frac{D}{d \tau} Z^{\beta}=g_{\alpha \beta} u_{0}^{\alpha}\left(\dot{Z}^{\beta}+\Gamma_{\mu \nu}^{\beta} u_{0}^{\mu} Z^{\nu}\right) \\
& =g_{\alpha \beta} u_{0}^{\alpha} \dot{Z}^{\beta}+\frac{1}{2} g_{\alpha \beta, \mu} u_{0}^{\alpha} u_{0}^{\beta} Z^{\mu}=0, \tag{7}
\end{align*}
$$

where we have used the symmetric Levi-Civita connection. On the other hand, the squared length of the tangent vector $u^{\alpha}$ on $\gamma(\varepsilon)$ is

$$
\begin{align*}
g_{\alpha \beta}\left(x^{\mu}\right) u^{\alpha} u^{\beta}= & g_{\alpha \beta}\left(x_{0}^{\mu}+\varepsilon Z^{\mu}\right)\left(u_{0}^{\alpha}+\varepsilon \dot{Z}^{\alpha}\right)\left(u_{0}^{\beta}+\varepsilon \dot{Z}^{\beta}\right) \\
\cong & 1+\varepsilon\left(2 g_{\alpha \beta}\left(x_{0}\right) u_{0}^{\alpha} \dot{Z}^{\beta}+g_{\alpha \beta, \mu} Z^{\mu} u_{0}^{\alpha} u_{0}^{\beta}\right) \\
& +\varepsilon^{2}\left(g_{\alpha \beta}\left(x_{0}\right) \dot{Z}^{\alpha} \dot{Z}^{\beta}+2 g_{\alpha \beta, \mu} u_{0}^{\alpha} \dot{Z}^{\beta} Z^{\mu}+\frac{1}{2} g_{\alpha \beta, \mu \nu} u_{0}^{\alpha} u_{0}^{\beta} Z^{\mu} Z^{\nu}\right) \tag{8}
\end{align*}
$$

and applying (7) one sees that $u^{\alpha} u_{\alpha}$ differs from 1 by a term of the order of $\varepsilon^{2}, u^{\alpha} u_{\alpha}=1+\varepsilon^{2} W$ with some scalar function $W$.

We now return to the circular geodesic B in an SSS spacetime, $r=r_{0}$. Its length from $P_{0}$ to the first conjugate point at distance $\tau_{c}$ is by definition $L(B)=\tau_{c}$, whereas the length of each geodesic $\gamma(\varepsilon)$ from $P_{0}$ to that point is

$$
\begin{equation*}
L(\gamma(\varepsilon))=\int_{0}^{\tau_{c}}\left[g_{\mu \nu}\left(x^{\alpha}\right) \frac{d x^{\mu}}{d \tau} \frac{d x^{\nu}}{d \tau}\right]^{1 / 2} d \tau \cong \tau_{c}+\frac{1}{2} \varepsilon^{2} \int_{0}^{\tau_{c}} W d \tau \tag{9}
\end{equation*}
$$

1. The simplest deviation field on B is $Z^{\alpha}=C \sin \left(L \tau / r_{0}^{2}\right)(0,0,1,0)$ with arbitrary dimensionless constant $C$ and $\gamma(\varepsilon)$ is given by

$$
\begin{equation*}
t-t_{0}=\frac{k}{\kappa} e^{-\nu_{0}} \tau, \quad r=r_{0}, \quad \theta=\frac{\pi}{2}+\varepsilon C \sin \left(\frac{L \tau}{r_{0}^{2}}\right), \quad \phi-\phi_{0}=\frac{L}{r_{0}^{2}} \tau . \tag{10}
\end{equation*}
$$

The points conjugate to $P_{0}\left(t_{0}, r_{0}, \pi / 2, \phi_{0}\right)$ are at equal distances $\tau_{n}=$ $n \pi r_{0}^{2} / L, n=1,2, \ldots$ and from (3) one sees that they are located in space at $\phi_{n}=\phi_{0}+n \pi$. The first conjugate point $Q_{1}$ is antipodal to $P_{0}$ in
the 2-surface $\theta=\pi / 2$. Geometrically this is obvious, for if one rotates in the space the surface by any angle about the axis joining the points $\phi=\phi_{0}$ and $\phi=\phi_{0}+\pi$ one gets a circular geodesic intersecting B at these two points. By symmetry, one expects that each geodesic (including the nearby $\gamma(\varepsilon)$ ) formed in this way has the same length as B. In fact, applying (10), (8) and (9) one gets $L(\gamma(\varepsilon))=L(B)=\tau_{1}=\pi r_{0}^{2} / L$.
2. Next, we take a special solution to the geodesic deviation equation depending on one integration constant, which generates a family of close geodesics $\gamma(\varepsilon)$ whose spatial orbits also lie in the surface $\theta=\pi / 2$. These are given by [2]

$$
\begin{align*}
t-t_{0} & =\frac{k}{\kappa} e^{-\nu_{0}} \tau-\varepsilon T A(1-\cos y) \\
r-r_{0} & =\frac{1}{2} \varepsilon X A \sqrt{4-b} \sin y, \quad \theta=\frac{\pi}{2} \\
\phi-\phi_{0} & =\frac{L}{r_{0}^{2}} \tau-\varepsilon Y A(1-\cos y) \tag{11}
\end{align*}
$$

where $y \equiv \sqrt{4-b} q \tau$ and $T, X, Y, b$ and $q$ are constants determined by the values of $r_{0}, \nu_{0}^{\prime}, \nu_{0}^{\prime \prime}$ and $\lambda_{0}$. For the stable circular orbits, the condition (2) implies $b<4$. The curves of this family intersect B at the conjugate points $Q_{n}^{\prime}\left(\tau_{n}^{\prime}\right), n=1,2, \ldots$, where

$$
\begin{equation*}
\tau_{n}^{\prime}=\frac{2 n \pi}{q \sqrt{4-b}}=2 n \pi\left(\frac{r_{0}\left(2-r_{0} \nu_{0}^{\prime}\right) e^{\lambda_{0}}}{3 \nu_{0}^{\prime}+r_{0} \nu_{0}^{\prime \prime}-r_{0} \nu_{0}^{\prime 2}}\right)^{1 / 2} \tag{12}
\end{equation*}
$$

For $\gamma(\varepsilon)$, the scalar $W$ defined in (9) is

$$
\begin{equation*}
W=-A^{2} \frac{e^{-\lambda_{0}}}{2 r_{0} \nu_{0}^{\prime}}\left(2-r_{0} \nu_{0}^{\prime}\right)^{-2}\left(3 \nu_{0}^{\prime}+r_{0} \nu_{0}^{\prime \prime}-r_{0} \nu_{0}^{\prime 2}\right)^{2} \cos 2 y \equiv-D^{2} \cos 2 y \tag{13}
\end{equation*}
$$

and its length from $P_{0}$ to $Q_{1}^{\prime}$ is

$$
\begin{equation*}
L(\gamma(\varepsilon))=\tau_{1}^{\prime}-\frac{1}{2} \varepsilon^{2} D^{2} \int_{0}^{2 \pi} \cos 2 y \frac{d y}{q \sqrt{4-b}}=\tau_{1}^{\prime}=L(B) \tag{14}
\end{equation*}
$$

3. Finally, we consider the most general Jacobi vector field depending on two integration constants $A_{1}$ and $A_{4}$ and, again, giving rise to orbits in the 2 -surface $\theta=\pi / 2$. Since the Jacobi field is determined up to a constant
factor, we can put $A_{1}=2$ and the modified value of $A_{4}$ denote by $A$. (The solution (11) corresponds to $A_{4}=0$ and $A_{1} \equiv A \neq 0$.) Then $\gamma(\varepsilon)$ is [2]

$$
\begin{align*}
t-t_{0} & =\frac{k}{\kappa} e^{-\nu_{0}} \tau+\varepsilon T F(y) \\
r-r_{0} & =\varepsilon X \sqrt{4-b}[\sin y+A(\cos y-1)], \quad \theta=\frac{\pi}{2} \\
\phi-\phi_{0} & =\frac{L}{r_{0}^{2}} \tau+\varepsilon Y F(y) \tag{15}
\end{align*}
$$

with

$$
\begin{equation*}
F(y) \equiv 2(\cos y-1)+A\left(\frac{1}{2} b y-2 \sin y\right) \tag{16}
\end{equation*}
$$

As previously, $y=\sqrt{4-b} q \tau$. If $\gamma(\varepsilon)$ is to intersect B at some $y>0$, then two equations should hold, $A(\cos y-1)+\sin y=0$ and $F(y)=0$. These have an infinite sequence of roots, $y_{n}(b), n=1,2, \ldots$, and each root is a solution of

$$
\begin{equation*}
\cos y+\frac{b}{8} y \sin y-1=0 \tag{17}
\end{equation*}
$$

and, in consequence, it determines $A$,

$$
\begin{equation*}
A(n, b)=\frac{\sin y_{n}(b)}{1-\cos y_{n}(b)} \tag{18}
\end{equation*}
$$

This means that one actually has a two-parameter family of geodesics $\gamma\left(\varepsilon, n, b\left(r_{0}\right)\right)$ close to the circular B. Each geodesic of this family emanates from $P_{0}(\tau=0)$ on B , spatially belongs to the 2 -surface $\theta=\pi / 2$ and intersects B only once at $\bar{Q}_{n}\left(\bar{\tau}_{n}\right)$,

$$
\begin{equation*}
\bar{\tau}_{n}=\frac{y_{n}\left(b\left(r_{0}\right)\right)}{q \sqrt{4-b\left(r_{0}\right)}}=\left(\frac{r_{0}\left(2-r_{0} \nu_{0}^{\prime}\right) e^{\lambda_{0}}}{3 \nu_{0}^{\prime}+r_{0} \nu_{0}^{\prime \prime}-r_{0} \nu_{0}^{\prime 2}}\right)^{1 / 2} y_{n}(b) \tag{19}
\end{equation*}
$$

In fact, for given $A(n, b)$ the two equations have no roots other than $y_{n}(b)$. By expanding Eq. (17) into a power series around $y=(2 n+1) \pi$, one finds an analytic approximate expression for $y_{n}(b)$. The first few roots are well approximated by

$$
\begin{equation*}
y_{n}(b)=\frac{(2 n+1)^{2} \pi^{2} b-16}{(2 n+1) \pi b}, \quad n<10 \tag{20}
\end{equation*}
$$

whereas for large $n$ a good approximation is

$$
\begin{equation*}
y_{n}=(2 n+1) \pi-\delta_{n}(b), \quad \delta_{n}(b)=\frac{16(2 n+1) \pi}{(2 n+1)^{2} \pi^{2} b-16} \tag{21}
\end{equation*}
$$

For example, for $b=3.6$ the difference between the numerically found value $y_{15}=97.3437$ and the analytic value given by (21) is of the order of $10^{-5}$. The geometrical interpretation of the origin of these conjugate points is unclear.

One computes the length of $\gamma\left(\varepsilon, n, b\left(r_{0}\right)\right)$ between $P_{0}$ and $\bar{Q}_{n}\left(\bar{\tau}_{n}\right)$ applying (15), (16) and (9)

$$
\begin{align*}
L(\gamma(\varepsilon, n, b)) \cong & \bar{\tau}_{n}+\varepsilon^{2} \frac{\nu_{0}^{\prime}}{16 r_{0} q}(4-b)^{3 / 2} e^{-\lambda_{0}}\left(\frac{\sin y_{n}}{1-\cos y_{n}}\right)^{2} \\
& \times\left(b y_{n}-\frac{8\left(1-\cos y_{n}\right)}{\sin y_{n}}\right) \tag{22}
\end{align*}
$$

By applying Eq. (17), one immediately sees that the last round bracket vanishes implying that for each geodesic of this family its length between the two conjugate points $P_{0}$ and $\bar{Q}_{n}$ is also equal to the length of the circular geodesic $B, L(\gamma(\varepsilon, n, b))=L(B)=\bar{\tau}_{n}$.

One concludes from these three cases that at least in the case of circular geodesics in SSS spacetimes all the nearby geodesic curves determined by the infinitesimal deviation vector fields have the same length from any initial point to the first future point conjugate to it, equal to the length of the circular geodesic. It is well known (see Theorem 1 cited in [2]) that the future cut point of $P_{0}$ comes no later than the first future conjugate point to $P_{0}$. Whether or not there exist distant timelike geodesics joining the two points which are longer than the circular B remains an open problem. A definite answer is known in the case of the first sequence of conjugate points on B if one asks about geodesic lengths to the second conjugate point. In this case, the second conjugate point $Q_{2}$ coincides in the space with $P_{0}$ (B makes one revolution) and in the Schwarzschild metric it is known [1] that the radial geodesic directed outwards and returning to $r=r_{0}$ simultaneously with B is longer than the latter. We will see in the next section that the same holds in the Reissner-Nordström spacetime.

## 3. Reissner-Nordström spacetime

We assume that the spacetime represents a non-rotating charged black hole, then the metric is

$$
\begin{equation*}
d s^{2}=\left(1-\frac{2 M}{r}+\frac{Q^{2}}{r^{2}}\right) d t^{2}-\left(1-\frac{2 M}{r}+\frac{Q^{2}}{r^{2}}\right)^{-1} d r^{2}-r^{2} d \Omega^{2} \tag{23}
\end{equation*}
$$

$(c=G=1)$ with the mass parameter exceeding the charge, $M^{2}>Q^{2}$. The timelike Killing vector $K^{\alpha}=\delta_{0}^{\alpha}$, normalized to +1 at the spatial infinity,
actually remains timelike in the region where $g_{00}=e^{\nu}>0$, i.e. for $r>r_{+}$, and for $r<r_{-}$where $r_{ \pm}=M \pm \sqrt{M^{2}-Q^{2}}$. We shall deal only with the region outside the outer event horizon, $r>r_{+}=M+\sqrt{M^{2}-Q^{2}}$. The equations for a timelike geodesic reduce to an equation for the radial coordinate

$$
\begin{equation*}
-\ddot{r}+\frac{M r-Q^{2}}{r\left(r^{2}-2 M r+Q^{2}\right)}\left(\dot{r}^{2}-k^{2}\right)+\frac{L^{2}}{r^{3}}\left(1-\frac{2 M}{r}+\frac{Q^{2}}{r^{2}}\right)=0 \tag{24}
\end{equation*}
$$

( $\dot{f} \equiv d f / d s$ ) plus the integral of energy $k$ per unit particle's mass, $k \equiv$ $E /\left(m c^{2}\right), E \equiv m c^{2} \dot{x}^{\alpha} K_{\alpha}$, giving rise to

$$
\begin{equation*}
\dot{t}=k\left(1-\frac{2 M}{r}+\frac{Q^{2}}{r^{2}}\right)^{-1} \tag{25}
\end{equation*}
$$

and the conserved angular momentum $L, \dot{\phi}=L / r^{2}$. The motion is 'flat', $\theta=\pi / 2$, and the universal integral of motion, $g_{\alpha \beta} \dot{x}^{\alpha} \dot{x}^{\beta}=1$, allows one to replace Eq. (24) by the following first order equation

$$
\begin{equation*}
\dot{r}^{2}=k^{2}-\left(\frac{L^{2}}{r^{2}}+1\right)\left(1-\frac{2 M}{r}+\frac{Q^{2}}{r^{2}}\right) . \tag{26}
\end{equation*}
$$

We first consider radial geodesics.

### 3.1. Radial timelike geodesics

We assume that the radial timelike geodesic representing the worldline of the twin C emanates from the event $P_{0}\left(t=t_{0}, r=r_{0}>r_{+}, \theta=\pi / 2, \phi=\phi_{0}\right)$ outwards with initial velocity $\dot{r}\left(t_{0}\right)=u>0$, reaches the maximal height $r=r_{M}$ at $t=t_{M}$, turns down and at $P_{1}\left(t=t_{1}\right)$ returns to the initial point $r=r_{0}$ and then goes downwards to the outer horizon $r=r_{+}$. We do not follow farther the geodesic which actually crosses the horizon since it would require the appropriate change of the chart. The integral of motion (26) is reduced to

$$
\begin{equation*}
\dot{r}^{2}=k^{2}-1+\frac{2 M}{r}-\frac{Q^{2}}{r^{2}} \tag{27}
\end{equation*}
$$

and one sees that $\dot{r} \geq 0$ for $r \rightarrow \infty$ if $k \geq 1$, what means that (as in the Schwarzschild spacetime) if the total energy (kinetic, potential and rest mass one) exceeds the rest energy, the twin C may escape to the spatial infinity and will not return. We, therefore, assume that the energy of the geodesic C is $0<k<1$. Then, the height of the flight is

$$
\begin{equation*}
r_{M}=\frac{1}{1-k^{2}}\left(M+\sqrt{M^{2}-\left(1-k^{2}\right) Q^{2}}\right), \tag{28}
\end{equation*}
$$

this is a monotonically growing function of $k$ from $r_{M}=r_{0}$ for $k^{2}=g_{00}\left(r_{0}\right)$ to infinity for $k \rightarrow 1$. Conversely, the energy may be expressed in terms of $r_{M}$ as $k^{2}=g_{00}\left(r_{M}\right)$. It is convenient to parametrize C on the entire arc from $P_{0}$ to the horizon by an angle $\eta$,

$$
\begin{equation*}
r(\eta)=r_{M} \cos ^{2} \eta \equiv \frac{1}{2} r_{M}(\cos 2 \eta+1) \tag{29}
\end{equation*}
$$

Then $\eta=-\alpha / 2$ at $P_{0}$ and $\eta=+\alpha / 2$ at $P_{1}$, or $r( \pm \alpha / 2)=\frac{1}{2} r_{M}(\cos \alpha+1)=r_{0}$ and it follows that $\cos \alpha=2 r_{0} / r_{M}-1$ or $\cos ^{2} \frac{\alpha}{2}=r_{0} / r_{M}$. If $r_{M}=r_{0}$ then $\alpha=0$ and if $r_{M} \rightarrow \infty$ then $\alpha \rightarrow \pi$, hence $0 \leq \alpha<\pi$. The initial point is $-\alpha / 2<0$, since $r(0)=r_{M}$. On the ingoing segment of the geodesic $\eta>0$ and it reaches the outer horizon for $\eta_{\mathrm{H}}, r\left(\eta_{\mathrm{H}}\right)=r_{+}=r_{M} \cos ^{2} \eta_{\mathrm{H}}$, what implies $\eta_{\mathrm{H}}=\arccos \left(r_{+} / r_{M}\right)^{1 / 2}$ and since $\cos \frac{\alpha}{2}=\sqrt{\frac{r_{0}}{r_{M}}}>\sqrt{\frac{r_{+}}{r_{M}}}$, one finally gets $\eta \in\left[-\frac{\alpha}{2}, \eta_{\mathrm{H}}\right)$, where $0 \leq \alpha / 2<\eta_{\mathrm{H}}<\pi / 2$. The radial component of the velocity $\dot{r}$ may be expressed from (27) in terms of $\eta$ as

$$
\begin{equation*}
\frac{d r}{d s}=-\left(1-k^{2}-\frac{Q^{2}}{r_{M}^{2} \cos ^{2} \eta}\right)^{1 / 2} \tan \eta \tag{30}
\end{equation*}
$$

The length of the geodesic C from $P_{0}$ to any point $\eta$ may be computed as follows. The metric along this curve is $d s^{2}=e^{\nu} d t^{2}-e^{-\nu} d r^{2}$ and one finds from it that

$$
\begin{equation*}
\left(\frac{d s}{d \eta}\right)^{2}=e^{-\nu}\left(\frac{d r}{d \eta}\right)^{2}\left[e^{\nu}\left(\frac{d t}{d s}\right)^{2}-1\right]^{-1} \tag{31}
\end{equation*}
$$

Then applying (25) and (29), one gets after some manipulations that for both the outgoing and ingoing segments of C

$$
\begin{equation*}
\frac{d s}{d \eta}=2\left(\frac{r_{M}^{3}}{M}\right)^{1 / 2}\left[(2-\beta) \cos ^{2} \eta-\beta\right]^{-1 / 2} \cos ^{3} \eta \tag{32}
\end{equation*}
$$

where $\beta \equiv Q^{2} /\left(M r_{M}\right)<1 / 2$. This expression is integrated out and the outcome is expressed in terms of the function

$$
\begin{equation*}
F(\beta, \eta) \equiv(2-\beta) \cos ^{2} \eta-\beta \tag{33}
\end{equation*}
$$

as

$$
\begin{align*}
s(\eta)= & \left(\frac{r_{M}^{3}}{M}\right)^{1 / 2}(2-\beta)^{-3 / 2}\left[2 \arctan \left[\sqrt{\frac{2-\beta}{F(\beta, \eta)}} \sin \eta\right]\right. \\
& +2 \arctan \left[\sqrt{\frac{2-\beta}{F\left(\beta, \frac{\alpha}{2}\right)}} \sin \frac{\alpha}{2}\right] \\
& \left.+\sqrt{2-\beta}\left[\sqrt{F(\beta, \eta)} \sin \eta+\sqrt{F\left(\beta, \frac{\alpha}{2}\right)} \sin \frac{\alpha}{2}\right]\right] \tag{34}
\end{align*}
$$

and this formula immediately gives the length of C from $P_{0}$ to $P_{1}$

$$
\begin{align*}
s_{\mathrm{C}}=s\left(\frac{\alpha}{2}\right)= & \left(\frac{r_{M}^{3}}{M}\right)^{1 / 2}(2-\beta)^{-3 / 2}\left[4 \arctan \left[\sqrt{\frac{2-\beta}{F\left(\beta, \frac{\alpha}{2}\right)}} \sin \frac{\alpha}{2}\right]\right. \\
& \left.+2 \sqrt{2-\beta} \sqrt{F\left(\beta, \frac{\alpha}{2}\right)} \sin \frac{\alpha}{2}\right] \tag{35}
\end{align*}
$$

The last two formulae make sense if $F>0$ in the whole interval $-\alpha / 2 \leq$ $\eta<\eta_{\mathrm{H}}$. This requires $\cos ^{2} \eta>\beta /(2-\beta)$ in the interval and since the lowest value of $\cos ^{2} \eta$ is for $\eta=\eta_{\mathrm{H}}$, one gets $r_{+} / r_{M}>\beta /(2-\beta)$. The ratio of these two quantities is

$$
\frac{r_{+}}{r_{M}}\left(\frac{\beta}{2-\beta}\right)^{-1}=r_{+}\left(\frac{2 M}{Q^{2}}-\frac{1}{r_{M}}\right)
$$

and applying $r_{+}>M, 2 M / Q^{2}>2 / M$ and $1 / r_{M}<1 / M$, one finds that the ratio is greater than 1 showing that $F>0$ along the geodesic up to the horizon.

Our aim is to compare the length of C between $P_{0}$ and $P_{1}$ with the length of the circular geodesic connecting these two points in the spacetime. The coordinate time of making one circle $\Delta t_{\mathrm{B}}$ on the circular geodesic is uniquely determined by its radius $r_{0}$, yet the time of flight on the radial C from $r_{0}$ to $r_{M}$ and back to $r_{0}$ depends on $r_{M}$ (or equivalently on the energy $k$ ). Thus if the twin B following the circular geodesic and the twin C on the radial curve start from $P_{0}$ and are to meet again at $P_{1}$ the height of flight $r_{M}$ must be precisely tuned to make the flight duration equal to $\Delta t_{\mathrm{B}}$. To this end, one expresses the time coordinate on C as a function of $\eta$. From (25) and (32), one gets

$$
\begin{equation*}
\frac{d t}{d \eta}=2 k\left(\frac{r_{M}^{5}}{M^{3}}\right)^{1 / 2}\left(\frac{r_{M}}{M} \cos ^{4} \eta-2 \cos ^{2} \eta+\beta\right)^{-1}[F(\beta, \eta)]^{-1 / 2} \cos ^{7} \eta \tag{36}
\end{equation*}
$$

It is quite surprising and fortunate that $t(\eta)$ is expressed in terms of elementary functions. By substitution $x \equiv \cos ^{2} \eta$ the indefinite integral of Eq. (36) is reduced to

$$
\begin{equation*}
-\varepsilon k\left(\frac{r_{M}^{5}}{M^{3}}\right)^{1 / 2} \int \frac{x^{3}[F(\beta, x)]^{-1 / 2}}{\frac{r_{M}}{M} x^{2}-2 x+\beta} \frac{d x}{\sqrt{1-x}} \equiv \varepsilon J(x) \tag{37}
\end{equation*}
$$

where $\varepsilon=-1$ for $\sin \eta<0$ and $\varepsilon=+1$ for $\sin \eta>0$. Calculating this integral requires considerable amount of ingenious work supported by the
program Mathematica and the outcome reads

$$
\begin{align*}
J(x)= & -k\left(\frac{r_{M}^{5}}{M^{3}}\right)^{1 / 2}\left\{-\frac{g(x)}{2 \frac{r_{M}}{M}-\mu}+\frac{1}{\sigma}(2-\beta)^{-3 / 2} \arcsin \left[\frac{(2-\beta) x-1}{1-\beta}\right]\right. \\
& -\frac{2 M^{2}}{\sqrt{2-\beta}} \frac{(\sigma+\beta-2)}{r_{M}^{2} \sigma} \arctan \left[\frac{(2-\beta)(1-x)}{(2-\beta) x-\beta}\right]^{1 / 2} \\
& \left.+a_{+} b_{+} \ln \left|\frac{f(x)+a_{+}}{f(x)-a_{+}}\right|-a_{-} b_{-} \ln \left|\frac{f(x)+a_{-}}{f(x)-a_{-}}\right|\right\} \tag{38}
\end{align*}
$$

Here,

$$
\begin{align*}
g(x) & =\sqrt{1-x} \sqrt{(2-\beta) x-\beta}=\sqrt{(1-x) F(\beta, x)} \\
f(x) & =\left(\frac{1-x}{F(\beta, x)}\right)^{1 / 2}, \quad \mu=\frac{Q^{2}}{M^{2}}, \quad \sigma=\frac{r_{M}}{M}+\beta-2 \\
a_{ \pm} & =\frac{1}{\beta \sqrt{\sigma}}\left[2(1-\beta)(1 \pm \sqrt{1-\mu})-\mu+\beta^{2}\right]^{1 / 2} \\
b_{ \pm} & =\frac{\beta^{3}(1-\beta \pm \sqrt{1-\mu})}{2 \sqrt{1-\mu}[(2-\beta)(1 \pm \sqrt{1-\mu})-\mu]^{2}} \tag{39}
\end{align*}
$$

all the functions are well defined for $\beta /(2-\beta)<x \leq 1$ and this condition is satisfied along the geodesic from $\eta=-\alpha / 2$ up to $r_{M}$ and down to the outer horizon. The time lapse to any $\eta>0$ is then $t(\eta)-t_{0}=\left[t(0)-t_{0}\right]+[t(\eta)-$ $t(0)]=(-1)\left[J(1)-J\left(\cos ^{2} \alpha / 2\right)\right]+(+1)\left[J\left(\cos ^{2} \eta\right)-J(1)\right]$. We need the time of flight to $r_{M}$ and back to $r_{0}$

$$
\begin{equation*}
t\left(\frac{\alpha}{2}\right)-t_{0}=2 J\left(\cos ^{2} \frac{\alpha}{2}\right)-2 J(1) \tag{40}
\end{equation*}
$$

where

$$
\begin{equation*}
J(1)=-\frac{\pi}{2} k \frac{1}{\sigma}\left(\frac{r_{M}^{5}}{M^{3}}\right)^{1 / 2}(2-\beta)^{-3 / 2} \tag{41}
\end{equation*}
$$

We shall use this result in Subsect. 3.3.

### 3.2. The deviation vector fields on the radial timelike geodesics

As mentioned in Introduction, we replace the geodesic deviation equation for the deviation vector by three scalar equations for the Jacobi scalars $Z_{a}(s)$, $a=1,2,3$. The spacelike orthonormal basis triad orthogonal to the radial geodesic C is chosen as in [2]

$$
\begin{equation*}
e_{1}^{\mu}=\left[\varepsilon e^{-\nu}\left(k^{2}-e^{\nu}\right)^{1 / 2}, k, 0,0\right], \quad e_{2}^{\mu}=\frac{1}{r} \delta_{2}^{\mu}, \quad e_{3}^{\mu}=\frac{1}{r} \delta_{3}^{\mu} \tag{42}
\end{equation*}
$$

where $\varepsilon=+1$ on the outward directed segment of C and $\varepsilon=-1$ for the ingoing one; $r=r(\eta)$ according to (29). In terms of this basis, the equations read

$$
\begin{align*}
\frac{d^{2} Z_{1}}{d s^{2}} & =\frac{2 M r-3 Q^{2}}{r^{4}} Z_{1} \\
\frac{d^{2} Z_{2}}{d s^{2}} & =\frac{Q^{2}-M r}{r^{4}} Z_{2} \\
\frac{d^{2} Z_{3}}{d s^{2}} & =\frac{Q^{2}-M r}{r^{4}} Z_{3} \tag{43}
\end{align*}
$$

Simplicity of these decoupled equations is deceptive, for their left-hand sides are derivatives with respect to the proper time instead of $r$ or $\eta$. Replacing $d / d s$ by derivatives with respect to $\eta$, one arrives at

$$
\begin{align*}
& F(\beta, \eta) \frac{d^{2} Z_{1}}{d \eta^{2}}+\frac{\sin 2 \eta}{\cos 2 \eta+1}[2 F(\beta, \eta)-\beta] \frac{d Z_{1}}{d \eta} \\
& -\frac{8}{\cos 2 \eta+1}(\cos 2 \eta+1-3 \beta) Z_{1}=0 \\
& F(\beta, \eta) \frac{d^{2} Z_{2}}{d \eta^{2}}+\frac{\sin 2 \eta}{\cos 2 \eta+1}(2 F(\beta, \eta)-\beta) \frac{d Z_{2}}{d \eta} \\
& -\frac{8}{\cos 2 \eta+1}\left(\beta-\frac{1}{2}(\cos 2 \eta+1)\right) Z_{2}=0 \tag{44}
\end{align*}
$$

( $F$ as in (33)) and the equation for $Z_{3}$ is identical with that for $Z_{2}$. The first integrals for these equations [2] are generated by the timelike Killing vector $K_{t}^{\alpha}=\delta_{0}^{\alpha}$ and the three spacelike rotational Killing fields, which at the points of C are equal to

$$
\begin{equation*}
K_{x}^{\alpha}=\left(0,0,-\sin \phi_{0}, 0\right), \quad K_{y}^{\alpha}=\left(0,0, \cos \phi_{0}, 0\right), \quad K_{z}^{\alpha}=\delta_{3}^{\alpha} \tag{45}
\end{equation*}
$$

clearly $K_{x}^{\alpha}$ and $K_{y}^{\alpha}$ give rise to the same conserved quantity. Applying the general formalism [2], one finds that $K_{t}^{\alpha}$ generates a first integral for $Z_{1}$,

$$
\begin{equation*}
F(\beta, \eta) \sin 2 \eta \frac{d Z_{1}}{d \eta}-2(\cos 2 \eta+1-2 \beta) Z_{1}=C_{1}(\cos 2 \eta+1)^{3} \tag{46}
\end{equation*}
$$

whereas $K_{x}^{\alpha}$ and $K_{y}^{\alpha}$ generate the same first integral for $Z_{2}$,

$$
\begin{equation*}
\frac{d Z_{2}}{d \eta}+2 Z_{2} \tan \eta=\frac{C_{2} \cos \eta}{[F(\beta, \eta)]^{1 / 2}} \tag{47}
\end{equation*}
$$

ultimately $K_{z}^{\alpha}$ generates the first integral for $Z_{3}$ which is identical with (47) for a different constant $C_{3}$. Clearly, $C_{1}, C_{2}$ and $C_{3}$ are arbitrary constants.

Equations (44) are linear homogeneous, hence their general solutions are $Z_{a}(\eta)=C_{a 1} Z_{a 1}(\beta, \eta)+C_{a 2} Z_{a 2}(\beta, \eta), a=1,2,3$. Equations (44) are symmetric (invariant) under the inversion $\eta \rightarrow-\eta$, also the first integral (46) is symmetric, whereas the first integrals for $Z_{2}$ and $Z_{3}$ are antisymmetric. This means that the special solutions $Z_{a 1}$ and $Z_{a 2}$ have definite symmetry and if their symmetry agrees with that of the first integral (46) (resp. (47)), then the solutions satisfy the first integral equations for some $C_{a} \neq 0$, otherwise they satisfy the latter for $C_{a}=0$.

1. Solutions for $Z_{1}$. The first solution is

$$
\begin{equation*}
Z_{11}(\beta, \eta)=\sqrt{F(\beta, \eta)} \frac{\sin \eta}{\cos ^{2} \eta}=-Z_{11}(\beta,-\eta) \tag{48}
\end{equation*}
$$

and (46) holds for $C_{1}=0$. The second solution is quite complicated,

$$
\begin{align*}
Z_{12}(\beta, \eta)= & \left\{6 \sqrt{\frac{F(\beta, \eta)}{2-\beta}} \sin \eta \arctan \left[\sqrt{\frac{2-\beta}{F(\beta, \eta)}} \sin \eta\right]\right. \\
& +\frac{1}{(1-\beta)^{2}}\left[-3 \beta+4 \beta^{2}-2 \beta^{3}+\left(6-10 \beta+5 \beta^{2}\right) \cos ^{2} \eta\right. \\
& \left.\left.+\left(-2+5 \beta-4 \beta^{2}+\beta^{3}\right) \cos ^{4} \eta\right]\right\} \frac{1}{\cos ^{2} \eta} \tag{49}
\end{align*}
$$

and is symmetric, $Z_{12}(\beta,-\eta)=+Z_{12}(\beta, \eta)$, and it satisfies (46) for $C_{1}=-1$. In the limit $\beta \rightarrow 0\left(Q^{2} \rightarrow 0\right)$, one recovers the solutions valid for the Schwarzschild metric [1].
2. The first solution for $Z_{2}$,

$$
\begin{equation*}
Z_{21}=\cos ^{2} \eta \tag{50}
\end{equation*}
$$

is independent of $\beta$, symmetric and satisfies (47) for $C_{2}=0$, clearly it also holds for the Schwarzschild metric. Yet the second solution,

$$
\begin{equation*}
Z_{22}(\beta, \eta)=\cos ^{2} \eta \arctan \left(\sqrt{\frac{\beta}{F(\beta, \eta)}} \sin \eta\right) \tag{51}
\end{equation*}
$$

is antisymmetric, yields $C_{2}=\sqrt{\beta}$ in (47), is non-analytic for $\beta=0$ and in this limit tends to 0 . (The corresponding special solution for $Q^{2}=0$ is just $\sin 2 \eta[1]$.)

We now seek for points conjugate on the geodesic C to $P_{0}(\eta=-\alpha / 2)$. Since the generic deviation vector is $Z^{\mu}=\sum_{a=1}^{3} Z_{a} e_{a}^{\mu}$, all the Jacobi scalars $Z_{a}$ should vanish both at $P_{0}$ and at the sought for conjugate points. In the search, one sets two scalars identically zero and seeks for zeros of the third scalar.
(a) First, we set $Z_{2}=Z_{3}=0$. From (48) and (49), one finds that $Z_{11}(\beta,-\alpha / 2) \neq 0$ and $Z_{12}(\beta,-\alpha / 2) \neq 0$. We set $C_{12}=1$, then the condition $Z_{1}(\beta,-\alpha / 2)=C_{11} Z_{11}(\beta,-\alpha / 2)+Z_{12}(\beta,-\alpha / 2)=0$ determines $C_{11}(\beta,-\alpha / 2)$ and we seek for roots of the function $Z_{1}\left(\beta, C_{11}, \eta\right)$ for $\eta>-\alpha / 2$. The numerical analysis shows that this $Z_{1}$ has no roots.
(b) Let $Z_{1}=Z_{3}=0$. Since $Z_{21}$ and $Z_{22}$ are different from 0 for $\eta=-\alpha / 2$, we set $C_{22}=1$ and analogously from the condition $Z_{2}(\beta,-\alpha / 2)=0$ determine $C_{21}(\beta,-\alpha / 2)$. Again, the function $Z_{2}\left(\beta, C_{21}, \eta\right)$ nowhere vanishes.

The case $Z_{1}=Z_{2}=0$ is identical to the second one. In this way, we have shown that the radial timelike geodesic C has no conjugate points to the initial point $P_{0}$ for any $r_{0}>r_{+}$; this means that C is the locally maximal curve between any pair of its points. In [2], we have shown that in the $\mathrm{R}-\mathrm{N}$ spacetime one can introduce the Gaussian normal geodesic (GNG) coordinates, i.e. the comoving ones, and the domain of these at least covers the same domain of the manifold as the standard coordinates $(t, r, \theta, \phi)$ do, i.e. from the outer horizon to the spatial infinity. In the GNG coordinates, the radial geodesic C becomes the time coordinate line (the spatial coordinates are constant) and it is straightforward to prove [2] that there is no timelike curve joining any pair of points on C whose length would be equal or greater than the length of the segment of $C$ between these points. This means that each radial timelike geodesic is the globally maximal curve between its points.

### 3.3. Circular timelike geodesics

In this spacetime, the general conditions of Sect. 2 for the existence of circular geodesics reduce to $2-r_{0} \nu_{0}^{\prime}>0$ since $\nu^{\prime}$ is positive outside the outer horizon, $r>r_{+}$(and for $M^{2}>Q^{2}$ ). The former condition implies $N \equiv r_{0}^{2}-3 M r_{0}+2 Q^{2}>0$ and this amounts to

$$
\begin{equation*}
r_{0}>r_{m} \equiv \frac{3}{2} M\left(1+\sqrt{1-\frac{8 Q^{2}}{9 M^{2}}}\right) \tag{52}
\end{equation*}
$$

where $2 M<r_{m}<3 M$. The value of $r_{0}$ determines all the parameters of the circular orbit, the energy $k$ and the angular momentum $L$. From (3)

$$
\begin{equation*}
k^{2}=\frac{\left(r_{0}^{2}-2 M r_{0}+Q^{2}\right)^{2}}{r_{0}^{2} N}, \quad L^{2}=\frac{r_{0}^{2}}{N}\left(M r_{0}-Q^{2}\right) \tag{53}
\end{equation*}
$$

and according to (3), the time and azimuthal coordinate are parametrized by the arc length of the geodesic B,

$$
\begin{equation*}
t-t_{0}=k e^{-\nu_{0}} s=\frac{r_{0}}{\sqrt{N}} s, \quad \phi-\phi_{0}=\frac{1}{r_{0}}\left(\frac{M r_{0}-Q^{2}}{N}\right)^{1 / 2} s \tag{54}
\end{equation*}
$$

The length of B corresponding to one revolution around the black hole is then

$$
\begin{equation*}
s_{\mathrm{B}}=\frac{2 \pi}{L} r_{0}^{2}=2 \pi r_{0}\left(\frac{N}{M r_{0}-Q^{2}}\right)^{1 / 2} \tag{55}
\end{equation*}
$$

and the corresponding lapse of the coordinate time is

$$
\begin{equation*}
\Delta t_{\mathrm{B}}=t\left(s_{\mathrm{B}}\right)-t_{0}=\frac{2 \pi r_{0}^{2}}{\left(M r_{0}-Q^{2}\right)^{1 / 2}} \tag{56}
\end{equation*}
$$

If $r_{0}$ is very close to $r_{m}$ the geodesic is unstable. In the $\mathrm{R}-\mathrm{N}$ spacetime the radius $r_{I}$ of the ISCO is given by the unique real root of the cubic equation

$$
\begin{equation*}
J\left(r_{\mathrm{I}}\right) \equiv r_{\mathrm{I}}^{3}-6 M r_{\mathrm{I}}^{2}+9 Q^{2} r_{\mathrm{I}}-4 \frac{Q^{4}}{M}=0 \tag{57}
\end{equation*}
$$

For fixed mass $M$, the values of $r_{\mathrm{I}}(Q)$ are given in Table I as a function of the ratio $\mu \equiv Q^{2} / M^{2}, 0<\mu<1$.

TABLE I
The values of $r_{\mathrm{I}}(Q) / M$ as a function of $\mu=Q^{2} / M^{2}$.

| $\mu$ | $r_{\mathrm{I}} / M$ |
| :---: | :---: |
| 0 | 6 |
| 0.1 | 5.84725 |
| 0.2 | 5.68852 |
| 0.3 | 5.52293 |
| 0.4 | 5.34939 |
| 0.5 | 5.16646 |
| 0.6 | 4.97221 |
| 0.7 | 4.76392 |
| 0.8 | 4.53759 |
| 0.9 | 4.28678 |
| 1 | 4 |

One sees that $r_{\mathrm{I}}(Q)$ decreases approximately linearly from $6 M$ to $4 M$. We shall assume that the geodesic B is stable, $r_{0}>r_{\mathrm{I}}(Q)$, then, as it was mentioned in Sect. 2, B has infinite number of conjugate points ordered in three sequences.

We are now able to compare the lengths of the radial and the circular geodesic having common endpoints $P_{0}$ and $P_{1}$. The time interval between these two events is equal to $t(\alpha / 2)-t_{0}$ if counted along the radial C and $\Delta t_{\mathrm{B}}$ as necessary for one revolution around the black hole. Equating the two intervals, (40) and (56),

$$
\begin{equation*}
\frac{2 \pi r_{0}^{2}}{\left(M r_{0}-Q^{2}\right)^{1 / 2}}=2 J\left(\cos ^{2} \frac{\alpha}{2}\right)-2 J(1) \tag{58}
\end{equation*}
$$

one gets an algebraic transcendental equation for the height $r_{M}$ of the radial flight. The roots of the equation depend on two parameters: $r_{0}$ and the ratio $\mu=Q^{2} / M^{2}$. The equation was numerically solved for three values of $\mu$; for each value of $\mu$, two values of $r_{0}$ were taken: one very close to the corresponding radius of the ISCO and the other was larger. The solutions $r_{M}\left(r_{0}, \mu\right)$ are unique (in the space of variables $r_{0}, r_{M}$ and $\mu \mathrm{Eq}$. (58) represents a surface which is almost exactly a plane) and are inserted into Eq. (35) for the length $s_{\mathrm{C}}$ of the radial geodesic and this length is compared with the length $s_{\mathrm{B}}$ of the circular one in (55). Table II shows values of $r_{M} / r_{0}$ and $s_{\mathrm{C}} / s_{\mathrm{B}}$ for the chosen values of $r_{0}$ and $\mu$.

TABLE II
Six values of $r_{M} / r_{0}$ and $s_{\mathrm{C}} / s_{\mathrm{B}}$ for chosen values of $r_{0} / M$ and $\mu=Q^{2} / M^{2}$.

| $\mu=0.1$ |  |  |
| :---: | :---: | :---: |
| $r_{0} / M$ | $r_{M} / r_{0}$ | $s_{\mathrm{C}} / s_{\mathrm{B}}$ |
| 5.86 | 2.07086 | 1.23795 |
| 10 | 2.14253 | 1.10736 |
| $\mu=0.5$ |  |  |
| $r_{0} / M$ | $r_{M} / r_{0}$ | $s_{\mathrm{C}} / s_{\mathrm{B}}$ |
| 5.17 | 2.07478 | 1.26553 |
| 6 | 2.09954 | 1.20797 |
| $\mu=0.9$ |  |  |
| $r_{0} / M$ | $r_{M} / r_{0}$ | $s_{\mathrm{C}} / s_{\mathrm{B}}$ |
| 4.3 | 2.07995 | 1.4321 |
| 10 | 2.17053 | 1.11617 |

One sees that $s_{\mathrm{C}}$ is always larger than $s_{\mathrm{B}}$ and their ratio slowly diminishes with growing $r_{0}$. A similar behaviour was found for the Schwarzschild black hole [1].

### 3.4. Jacobi fields and conjugate points on circular timelike geodesics

For all SSS spacetimes, all quantities and equations concerning stable circular geodesics are the same, only the constants appearing in the formalism depend in a different way on the radius $r_{0}$; we therefore refer the reader to [2] for all definitions and equations. We only recall the orthonormal spacelike basis triad which is orthogonal to the circular geodesic B and parallelly transported along it

$$
\begin{align*}
e_{1}^{\mu} & =[-T \sin q s, X \cos q s, 0,-Y \sin q s], \quad e_{2}^{\mu}=\left[0,0, \frac{1}{r_{0}}, 0\right] \\
e_{3}^{\mu} & =[T \cos q s, X \sin q s, 0, Y \cos q s] \tag{59}
\end{align*}
$$

The constants already appeared in (11) and now are equal to

$$
\begin{align*}
T & =\left[\frac{1}{N} e^{-\nu_{0}}\left(M r_{0}-Q^{2}\right)\right]^{1 / 2}, \quad X=e^{\nu_{0} / 2}, \quad Y=\left[\frac{e^{\nu_{0}}}{N}\right]^{1 / 2} \\
q^{2} & =\frac{1}{r_{0}^{4}}\left(M r_{0}-Q^{2}\right) \tag{60}
\end{align*}
$$

furthermore, in the equations for the Jacobi scalars $Z_{a}[2]$, there appears the constant

$$
\begin{equation*}
b \equiv 3+\frac{1}{N}\left(3 M r_{0}-4 Q^{2}\right)-\frac{Q^{2}}{M r_{0}-Q^{2}} \tag{61}
\end{equation*}
$$

which varies in the range $3<b<\infty$. The ISCO corresponds to $b=4$ and for stable orbits $3<b<4$. The two equations for $Z_{1}$ and $Z_{3}$ are coupled and possess one first integral generated by both the Killing vectors $K_{t}^{\alpha}$ and $K_{z}^{\alpha}$. On the other hand, the equation for $Z_{2}$ is simple and may easily be integrated, what is actually unnecessary since its solutions are determined (without any integration) by the two first integrals generated by $K_{x}^{\alpha}$ and $K_{y}^{\alpha}$,

$$
\begin{equation*}
Z_{2}(s)=C^{\prime} \sin \left(\frac{L}{r_{0}^{2}} s\right)+C^{\prime \prime} \cos \left(\frac{L}{r_{0}^{2}} s\right) \tag{62}
\end{equation*}
$$

and from (53), $L / r_{0}^{2}=\frac{1}{r_{0}} N^{-1 / 2}\left(M r_{0}-Q^{2}\right)^{1 / 2}$.
The Jacobi vector field generated by $Z_{2}$ and vanishing at $P_{0}(s=0)$ is

$$
\begin{equation*}
Z^{\mu}=C \delta_{2}^{\mu} \sin \left(\frac{L}{r_{0}^{2}} s\right) \tag{63}
\end{equation*}
$$

(this is the case 1 in Sect. 2) and gives rise to the first infinite sequence of points $Q_{n}\left(s_{n}\right)$ conjugate to $P_{0}$ and located at distances

$$
\begin{equation*}
s_{n}=n \pi \frac{r_{0}^{2}}{L}=n \pi r_{0} N^{1 / 2}\left(M r_{0}-Q^{2}\right)^{-1 / 2} \tag{64}
\end{equation*}
$$

The subsequent points $Q_{n}$ are separated by equal angular distance $\Delta \phi=\pi$. The deviation vectors spanned on the basis vectors $e_{1}^{\mu}$ and $e_{3}^{\mu}$ give rise to two other infinite sequences of conjugate points.

1. The second sequence (the case 2 in Sect. 2) $Q_{n}^{\prime}\left(s_{n}^{\prime}\right)$ consists of points on B at distances (12) from $P_{0}$,

$$
\begin{equation*}
s_{n}^{\prime}=2 n \pi r_{0}^{2} N^{1 / 2}\left(M J\left(r_{0}\right)\right)^{-1 / 2} \tag{65}
\end{equation*}
$$

where $J(r)$ is defined as the left-hand side of Eq. (57). To find out the spatial location of the first conjugate point $Q_{1}^{\prime}$, one computes from (55) the ratio

$$
\begin{equation*}
\frac{s_{1}^{\prime}}{s_{\mathrm{B}}}=r_{0}\left(M r_{0}-Q^{2}\right)^{1 / 2}\left(M J\left(r_{0}\right)\right)^{-1 / 2} \tag{66}
\end{equation*}
$$

clearly $J\left(r_{0}\right)>0$ since $r_{0}>r_{\mathrm{I}}$. For the orbits tending to the ISCO, one has $r_{0}\left(M r_{0}-Q^{2}\right)^{1 / 2}>r_{\mathrm{I}}\left(M r_{\mathrm{I}}-M^{2}\right)^{1 / 2}>0$ and $J\left(r_{0}\right) \rightarrow 0$, then the twin B following a circular orbit close to the ISCO must make a large number of revolutions to encounter the first conjugate point $Q_{1}^{\prime}$. For example, for $Q^{2}=0.5 M^{2}$ and $r_{0}=5.17 M$, there is $s_{1}^{\prime} / s_{\mathrm{B}}=38.32$. The ratio quickly diminishes and again for $Q^{2}=0.5 M^{2}$ and $r_{0}=6 M$ it is 2.760, nevertheless it is always larger than 1 and for $r_{0} \rightarrow \infty$ it tends to 1 from above. Qualitatively, the behaviour is the same as in the Schwarzschild spacetime [1].
2. For the third sequence (the case 3 in Sect. 2), the Eq. (19) for the distance of $\bar{Q}_{n}$ from $P_{0}$ on B takes now on the form

$$
\begin{equation*}
\bar{s}_{n}=r_{0}^{2} N^{1 / 2}\left(M J\left(r_{0}\right)\right)^{-1 / 2} y_{n} \tag{67}
\end{equation*}
$$

and from (65) one sees that the relative location of the conjugate points $Q_{n}^{\prime}$ and $\bar{Q}_{n}$ is given by

$$
\begin{equation*}
\frac{\bar{s}_{n}}{s_{n}^{\prime}}=\frac{y_{n}}{2 n \pi} \tag{68}
\end{equation*}
$$

and for $n \rightarrow \infty$ this ratio tends to $1+1 /(2 n)-4 /\left(n^{2} \pi^{2} b\right)$ and for all $n$ it is larger than 1.

## 4. Ultrastatic spherically symmetric spacetimes

The class of SSS spacetimes contains a special subclass of ultrastatic spherically symmetric (USSS) manifolds. We first provide a brief description of ultrastatic spacetimes. These are static spacetimes such that the unique timelike hypersurface orthogonal Killing vector field $K_{t}^{\alpha}$ is actually a gradient, $K_{t \alpha}=\partial_{\alpha} \Phi$. One chooses (in a non-unique way) a coordinate system $\left(x^{\alpha}\right)$ in which the metric is time-independent, what is equivalent to $K_{t}^{\alpha}=\delta_{0}^{\alpha}$. Then, $K_{t \alpha}=g_{\alpha 0}=\partial_{\alpha} \Phi$ or $\Phi=C t+f\left(x^{k}\right)$, with $C>0$ constant and an arbitrary function $f\left(x^{k}\right)$. Next, one makes a coordinate transformation $t^{\prime}=t+\frac{1}{C} f\left(x^{k}\right)$ and $x^{\prime i}=x^{i}$ yielding $g_{0 i}^{\prime}=0, \Phi=C t^{\prime}$ and again $K_{t}^{\prime \alpha}=\delta_{0}^{\alpha}$. Then rescaling time, $t^{\prime} \rightarrow C^{-1 / 2} t$, and denoting the new coordinates by $x^{\alpha}$, one gets $d s^{2}=d t^{2}+g_{i j}\left(x^{k}\right) d x^{i} d x^{j}$ and the Killing vector has the constant length, $g_{\alpha \beta} K_{t}^{\alpha} K_{t}^{\beta}=+1$. Any USSS metric furthermore admits the three rotational Killing vectors, $K_{x}^{\alpha}, K_{y}^{\alpha}$ and $K_{z}^{\alpha}$ and in the standard chart it reads

$$
\begin{equation*}
d s^{2}=d t^{2}-e^{\lambda(r)} d r^{2}-r^{2} d \Omega^{2} \tag{69}
\end{equation*}
$$

in other words the metric function $\nu(r)=0$. These coordinates are, at the same time, the comoving ones, i.e. the metric in the comoving coordinates is time-independent. The best known USSS spacetime is the Einstein static universe with $\lambda=-\ln \left(1-r^{2} / a^{2}\right)$, where the constant $a$ has the dimension of length and $r \geq 0$; the spacetime physically is of merely historical significance since it is unstable. Other known USSS spacetimes do not include physically significant solutions, nevertheless, they are interesting from the geometrical viewpoint because one is able to study not only radial and/or circular geodesic curves, but all properties of generic timelike geodesics including deviation vector fields and conjugate points. It is also interesting to notice that the comoving coordinates in each USSS spacetime imitate the inertial frame in special relativity: a free particle initially at rest remains always at rest and interparticle distances (between free particles at rest in the system) are time-independent. Furthermore, as we shall see below, a particle in a free motion has a constant velocity with respect to the comoving frame; the motion is not rectilinear since the notion is not well defined in these spacetimes. The similarity is not complete since there is a fundamental geometric difference: the space $t=$ const in any USSS spacetime is not flat, although in the special cases where the space is the 3 -sphere $S^{3}$ or Lobatchevsky (hyperbolic) space $H^{3}$, it is homogeneous and isotropic (i.e. maximally symmetric). In other words, the similarity of the system to the inertial frame concerns its dynamical properties.

A particle of mass $m$ moving on a timelike geodesic has the conserved energy $E$ and as previously $k \equiv E /\left(m c^{2}\right)$ and

$$
\begin{equation*}
\dot{t} \equiv \frac{d t}{d s}=k>0 \quad \Rightarrow \quad t-t_{0}=k s \tag{70}
\end{equation*}
$$

The geodesic spatially lies in the 2 -surface $\theta=\pi / 2$, has the angular momentum $L$ and $\dot{\phi} \equiv d \phi / d s=L / r^{2}$. The radial component of the velocity $u^{\alpha}=d x^{\alpha} / d s$ satisfies

$$
\begin{equation*}
\ddot{r}+\frac{1}{2} \lambda^{\prime} \dot{r}^{2}-\frac{L^{2}}{r^{3}} e^{-\lambda}=0 \tag{71}
\end{equation*}
$$

( $\lambda^{\prime}=d \lambda / d r$ ) and from the integral of motion $u^{\alpha} u_{\alpha}=1$ is equal to

$$
\begin{equation*}
\dot{r}^{2}=e^{-\lambda}\left(k^{2}-1-\frac{L^{2}}{r^{2}}\right) . \tag{72}
\end{equation*}
$$

The particle freely moving with respect to the coordinate frame has 3 -velocity $v^{i} \equiv d x^{i} / d t$ with the constant modulus,

$$
\begin{equation*}
|\boldsymbol{v}|^{2}=-g_{i j} v^{i} v^{j}=\frac{k^{2}-1}{k^{2}}<1 \tag{73}
\end{equation*}
$$

or the motion is uniform.
From (72), one sees that $k^{2}-1 \geq 0$. If $k=1 \Leftrightarrow E=m c^{2}$, one gets $\dot{r}^{2} \leq 0$ and this is possible only for $L=0$, the radial motion, which actually reduces to $\dot{r}=0$ and $r(s)=$ const. The particle stands still in the space what means that no gravitational force is exerted on it; this surprising effect was first found in the special case of the global Barriola-Vilenkin monopole [12], here we show that this is a common feature of all USSS spacetimes. Conversely, this fact implies that circular geodesics in any USSS manifold reduce to the trivial case of remaining at rest in the space. In fact, for $r=r_{0}=$ const it follows from (71) that $L=0$, there is no azimuthal motion, then (72) implies $k=1$ and the geodesic is $t-t_{0}=s, r=r_{0}, \theta=\pi / 2$ and $\phi=\phi_{0}$.

We, therefore, separately study radial and general non-radial geodesics.

### 4.1. Radial geodesics

By definition, the radial geodesic C has $L=0$ and is given by $t-t_{0}=k s$ with $k>1, \theta=\pi / 2$ and $\phi=\phi_{0}$. We assume that the radial coordinate in the comoving system varies in the range $0 \leq r_{1} \leq r \leq r_{2} \leq \infty$. Let the initial point of C be $P_{0}\left(t_{0}, r_{0}>r_{1}, \pi / 2, \phi_{0}\right)$ with the initial velocity $\dot{r}^{2}\left(t_{0}\right)=u^{2}$. The formula (72) is reduced to

$$
\begin{equation*}
\dot{r}^{2}=\left(k^{2}-1\right) e^{-\lambda} . \tag{74}
\end{equation*}
$$

If $u>0$, then $u=+\sqrt{k^{2}-1} \exp \left(-\frac{1}{2} \lambda\left(r_{0}\right)\right)$ and $\dot{r}=+\sqrt{k^{2}-1} \exp \left(-\frac{1}{2} \lambda(r)\right)$ for $t>t_{0}$, similarly $\dot{r}=-\sqrt{k^{2}-1} \exp \left(-\frac{1}{2} \lambda(r)\right)$ for $u<0$. In both the cases, the sign of $\dot{r}$ remains unaltered for all times $t>t_{0}$ and the motion is unbounded, the radial coordinate either grows to the upper boundary $r_{2}$ or decreases to $r_{1}$ and this is in accordance with the fact that the particle is subject to no gravitational force. From (74), one finds the length of the geodesic C between $r_{0}$ and $r(s)$

$$
\begin{equation*}
s(r)=\frac{\varepsilon}{\sqrt{k^{2}-1}} \int_{r_{0}}^{r} e^{\lambda / 2} d r \tag{75}
\end{equation*}
$$

where $\varepsilon=+1$ for the outgoing geodesic and $\varepsilon=-1$ for the ingoing one. For some functions $\lambda(r)$, it is possible to invert this relationship to $r=r(s)$.

Now, we seek for Jacobi fields on the radial C. Applying the general formalism [2], we introduce the spacelike orthonormal basis triad which represents the special case $\nu=0$

$$
\begin{equation*}
e_{1}^{\mu}=\left[\varepsilon \sqrt{k^{2}-1}, k e^{-\lambda / 2}, 0,0\right], \quad e_{2}^{\mu}=\frac{1}{r} \delta_{2}^{\mu}, \quad e_{3}^{\mu}=\frac{1}{r} \delta_{3}^{\mu} \tag{76}
\end{equation*}
$$

and the equations for the Jacobi scalars are

$$
\begin{align*}
\frac{d^{2} Z_{1}}{d s^{2}} & =0  \tag{77}\\
\frac{d^{2} Z_{2}}{d s^{2}} & =-\frac{k^{2}-1}{2 r} \lambda^{\prime} e^{-\lambda} Z_{2} \tag{78}
\end{align*}
$$

and the equation for $Z_{3}$ is identical to that for $Z_{2}$. The vector $Z^{\mu}=Z_{1} e_{1}^{\mu}$ varies linearly since $Z_{1}=C_{11} s+C_{12}$. In (78) one replaces the derivative with respect to $s$ by derivatives w.r.t. $r$ and denoting collectively $Z_{2}$ and $Z_{3}$ by $Z$, one gets

$$
\begin{equation*}
\frac{d^{2} Z}{d r^{2}}-\frac{1}{2} \lambda^{\prime} \frac{d Z}{d r}+\frac{\lambda^{\prime}}{2 r} Z=0 \tag{79}
\end{equation*}
$$

This equation may be solved for a given function $\lambda=\ln \left(-g_{11}\right)$.
It is known from [2] that the radial geodesics are globally maximal in the domain of the comoving coordinate chart, hence in the range $r_{1}<r<r_{2}$ they contain neither cut nor conjugate points to any of their points in this range.

### 4.2. Properties of generic non-radial timelike geodesics

A non-radial geodesic has $L \neq 0$ (we always assume that $L>0$ ). These curves require a separate treatment since most of their properties depend
on $0<L^{-2}<\infty$. We denote such a geodesic by G (and as usual $\theta=\pi / 2$ along it) and assume that it emanates from $P_{0}\left(t_{0}, r_{0}, \pi / 2, \phi_{0}\right)$. Its behaviour depends on whether its initial radial velocity $\dot{r}\left(t_{0}\right)=u$ is positive or negative.
I. The initial velocity $u>0$.

Let $\lambda\left(r_{0}\right)=\lambda_{0}$. Then from (72) $u=+\left(k^{2}-1-L^{2} / r_{0}^{2}\right)^{1 / 2} \exp \left(-\lambda_{0} / 2\right)$ and G is directed outwards and $r$ increases. Since $k^{2}-1-L / r^{2}>$ $k^{2}-1-L / r_{0}^{2}>0$ for $r>r_{0}$, the radial velocity is always $\dot{r}>0$ (assuming $e^{-\lambda}>0$ for all finite $r$ ) and $r(s)$ is unbounded and tends to the chart boundary $r=r_{2}$. The non-radial G qualitatively behaves as the radial C. For $L \neq 0$, one introduces a parameter $p$ by $p^{2} \equiv\left(k^{2}-1\right) / L^{2}, 0<p<\infty$. The length of G between $r_{0}$ and any $r \geq r_{0}$ is then

$$
\begin{equation*}
s(r)=\frac{1}{L} \int_{r_{0}}^{r} \frac{r e^{\lambda / 2}}{\sqrt{p^{2} r^{2}-1}} d r \tag{80}
\end{equation*}
$$

In general, this relationship cannot be inverted, therefore, instead of $\phi(s)$ we seek for the dependence $\phi=\phi(r)$. From $d \phi / d r=\frac{L}{r^{2}}(d r / d s)^{-1}$, one easily derives

$$
\begin{equation*}
\phi(r)-\phi_{0}=\int_{r_{0}}^{r} \frac{e^{\lambda / 2}}{r} \frac{d r}{\sqrt{p^{2} r^{2}-1}} \tag{81}
\end{equation*}
$$

II. The initial velocity $u<0$.

For some time interval after $t=t_{0}$, there is $\dot{r}=-\left(k^{2}-1-L^{2} / r^{2}\right)^{1 / 2}$ $\exp (-\lambda / 2)<0$ and $r(s)$ monotonically decreases. Further evolution depends on the value of $p$.
(a) If $p^{2} \geq 1 / r_{1}^{2}$, the geodesic $G$ reaches (at least asymptotically) the lower boundary of the chart $r=r_{1}$ and its further evolution cannot be traced in the formalism we apply here. In this sense, $G$ is akin to the ingoing radial C .
(b) If $p^{2}=1 / r_{m}^{2}$ for some $r_{m}>r_{1}$ the geodesic $G$ reaches the lowest point $r=r_{m}$ where its radial velocity vanishes, $\dot{r}\left(r_{m}\right)=$ $-L \sqrt{p^{2}-1 / r_{m}^{2}} \exp (-\lambda / 2)=0$, while its azimuthal velocity $\dot{\phi}=$ $L / r^{2} \neq 0$. The full 3 -velocity squared is still equal to $\left(k^{2}-1\right) / k^{2}$ at $r_{m}$ and the particle is expelled outwards with positive radial acceleration following from (71)

$$
\ddot{r}\left(r_{m}\right)=+\frac{L^{2}}{r_{m}^{3}} e^{-\lambda\left(r_{m}\right)}
$$

For later times $r(s)$ increases and correspondingly $\dot{r}>0$ increases and $\dot{\phi}$ diminishes. The geodesic G qualitatively behaves as that emanating from $P_{0}$ with $u>0$. Analogously to (80), one finds that the length of G from $r_{0}$ down to $r_{m}$ and then upwards to $r$ is

$$
\begin{equation*}
s\left(r_{0}, r_{m}, r\right)=\frac{1}{L}\left(\int_{r_{m}}^{r_{0}}+\int_{r_{m}}^{r}\right) \frac{r e^{\lambda / 2}}{\sqrt{p^{2} r^{2}-1}} d r \tag{82}
\end{equation*}
$$

and if the indefinite integral of the integrand is $F(r)$, then $s\left(r_{0}, r_{m}, r\right)=F(r)-F\left(r_{0}\right)-2 F\left(r_{m}\right)$. The $\phi(r)$ dependence may be found in the similar way.

### 4.3. The geodesic deviation equations for a generic non-radial geodesic

For the sake of simplicity, we consider geodesics consisting only of one segment, i.e. the curves emanating outwards $(\dot{r}>0)$ from the initial $P_{0}$, then $t-t_{0}=k s$ and (80) and (81) hold. The vector tangent to G is

$$
\begin{equation*}
u^{\alpha}=\left[k, \frac{L}{r} e^{-\lambda / 2}\left(p^{2} r^{2}-1\right)^{1 / 2}, 0, \frac{L}{r^{2}}\right] \tag{83}
\end{equation*}
$$

(Here and below always $p^{2} r^{2}>1$.) It is not easy to find the spacelike basis triad possessing the required properties on G [2] and only after many manipulations and solving a system of two coupled first order ODEs one arrives at

$$
\begin{align*}
e_{1}^{\mu} & =\left[0, \frac{1}{p r} e^{-\lambda / 2}, 0,-\frac{1}{p r^{2}} \sqrt{p^{2} r^{2}-1}\right], \quad e_{2}^{\mu}=\frac{1}{r} \delta_{2}^{\mu}, \\
e_{3}^{\mu} & =\left[\sqrt{k^{2}-1}, \frac{k}{p r} e^{-\lambda / 2} \sqrt{p^{2} r^{2}-1}, 0, \frac{k}{p r^{2}}\right] . \tag{84}
\end{align*}
$$

The curvature tensor for the metric (69) is

$$
\begin{equation*}
R_{1212}=-\frac{r}{2} \lambda^{\prime}, \quad R_{1313}=-\frac{r}{2} \lambda^{\prime} \sin ^{2} \theta, \quad R_{2323}=r^{2}\left(e^{-\lambda}-1\right) \sin ^{2} \theta \tag{85}
\end{equation*}
$$

Applying (83), (84) and (85), one derives the equations for the Jacobi scalars

$$
\begin{align*}
\frac{d^{2} Z_{1}}{d s^{2}} & =-\frac{1}{2}\left(k^{2}-1\right) \frac{\lambda^{\prime}}{r} e^{-\lambda} Z_{1}  \tag{86}\\
\frac{d^{2} Z_{2}}{d s^{2}} & =\frac{L^{2}}{r^{3}}\left[\frac{1}{r}\left(e^{-\lambda}-1\right)-\frac{\lambda^{\prime}}{2} e^{-\lambda}\left(p^{2} r^{2}-1\right)\right] Z_{2}  \tag{87}\\
\frac{d^{2} Z_{3}}{d s^{2}} & =0 \tag{88}
\end{align*}
$$

Since $Z_{3}=C_{31} s+C_{32}$, one sees that the deviation vector $Z^{\mu}=Z_{3} e_{3}^{\mu}$ does not generate conjugate points on G . To make the equations for $Z_{1}$ and $Z_{2}$ solvable, one replaces $d / d s$ by $d / d r$, then the equivalent equations read

$$
\begin{align*}
& \frac{d^{2} Z_{1}}{d r^{2}}+\left[\frac{1}{r\left(p^{2} r^{2}-1\right)}-\frac{\lambda^{\prime}}{2}\right] \frac{d Z_{1}}{d r}+\frac{1}{2} \frac{p^{2} r \lambda^{\prime}}{p^{2} r^{2}-1} Z_{1}=0  \tag{89}\\
& \frac{d^{2} Z_{2}}{d r^{2}}+\left[\frac{1}{r\left(p^{2} r^{2}-1\right)}-\frac{\lambda^{\prime}}{2}\right] \frac{d Z_{2}}{d r}-\frac{1}{r}\left[\frac{1-e^{\lambda}}{r\left(p^{2} r^{2}-1\right)}-\frac{\lambda^{\prime}}{2}\right] Z_{2}=0 \tag{90}
\end{align*}
$$

The timelike and the three rotational Killing vector fields generate four integral of motion; that generated by $K_{t}^{\alpha}=\delta_{0}^{\alpha}$ gives rise to the solution for $Z_{3}$. The vectors $K_{x}^{\alpha}$ and $K_{y}^{\alpha}$ generate two independent first integrals for Eq. (90)

$$
\begin{align*}
f(r) \frac{d Z_{2}}{d r} \sin \phi-\frac{1}{r}(f(r) \sin \phi+\cos \phi) Z_{2} & =C_{1},  \tag{91}\\
-f(r) \frac{d Z_{2}}{d r} \cos \phi+\frac{1}{r}(f(r) \cos \phi-\sin \phi) Z_{2} & =C_{2} \tag{92}
\end{align*}
$$

with $f(r) \equiv e^{-\lambda / 2} \sqrt{p^{2} r^{2}-1}$. Multiplying (91) by $\cos \phi$ and (92) by $\sin \phi$ and adding the two equations, one gets $Z_{2}$ without any integration; the general solution is

$$
\begin{equation*}
Z_{2}(r)=C_{21} r \cos \phi(r)+C_{22} r \sin \phi(r), \tag{93}
\end{equation*}
$$

here $\phi(r)$ is given by (81). A first integral for $Z_{1}$ is generated by $K_{z}^{\alpha}=\delta_{3}^{\alpha}$ and reads

$$
\begin{equation*}
\frac{1}{r}\left(p^{2} r^{2}-1\right) \frac{d Z_{1}}{d r}-p^{2} Z_{1}=C_{1} e^{\lambda / 2} \tag{94}
\end{equation*}
$$

and is easily solved by the following general solution

$$
\begin{equation*}
Z_{1}(r)=C_{11} \sqrt{p^{2} r^{2}-1}+C_{12} \sqrt{p^{2} r^{2}-1} \int r e^{\lambda / 2}\left(p^{2} r^{2}-1\right)^{-3 / 2} d r \tag{95}
\end{equation*}
$$

Without knowledge of $\lambda(r)$, one can say very little about this solution. Yet concerning $Z_{2}(r)$, one can find a generic condition for the existence of conjugate points to $P_{0}$ generated by $Z^{\mu}=Z_{2} e_{2}^{\mu}=\left(C_{21} \cos \phi+C_{22} \sin \phi\right) \delta_{2}^{\mu}$. This vector is directed off the 2 -surface $\theta=\pi / 2$. Without loss of generality, one can rotate the coordinate system in the surface to put $\phi_{0}=0$. Then the deviation vector vanishing for $\phi=0$ is

$$
\begin{equation*}
Z^{\mu}(r)=C_{22} \delta_{2}^{\mu} \sin \phi(r) \tag{96}
\end{equation*}
$$

and is zero at points $\phi_{n}(r)=n \pi, n=1,2, \ldots$ The first conjugate point exists if the difference $\phi(r)-\phi_{0}$ given in (81) exceeds $\pi$ for some $r<\infty$ and this may be concluded only when $\lambda(r)$ is known.

In this work, we discuss only one special case of USSS spacetimes and postpone other examples to a forthcoming paper.

## 5. The global Barriola-Vilenkin monopole

This is an approximate solution of Einstein's field equations with a source being a triplet of scalar fields, describing the spacetime outside a monopole resulting from the breaking of a global $O(3)$ symmetry of the triplet [12]. Assuming that in the astrophysically relevant situations, the monopole mass is negligibly small, the resulting metric is approximated by [12]

$$
\begin{equation*}
d s^{2}=d t^{2}-\frac{1}{h^{2}} d r^{2}-r^{2} d \Omega^{2} \tag{97}
\end{equation*}
$$

here $r$ is larger than some $r_{1}>0$ and $h$ is a dimensionless constant, $0<h<1$ (to fit the general USSS formalism of Sect. 4, we have rescaled the radial coordinate applied in [12]). The metric function $\lambda=-2 \ln h=$ const.

The general outgoing $(\dot{r}>0)$ non-radial geodesic has the length

$$
\begin{equation*}
s(r)=\frac{1}{h p^{2} L}\left(\sqrt{p^{2} r^{2}-1}-\sqrt{p^{2} r_{0}^{2}-1}\right) \tag{98}
\end{equation*}
$$

and this function may be inverted to

$$
\begin{equation*}
r^{2}(s)=(h p L)^{2} s^{2}+2 h L \sqrt{p^{2} r_{0}^{2}-1} s+r_{0}^{2} \tag{99}
\end{equation*}
$$

whereas the integral (81) is

$$
\begin{equation*}
\phi(r)-\phi_{0}=\frac{1}{h}\left[\arccos \left[\frac{1}{p r}\right]-\arccos \left[\frac{1}{p r_{0}}\right]\right] \tag{100}
\end{equation*}
$$

here, $0<1 /(p r) \leq 1 /\left(p r_{0}\right) \leq 1$. That the spacetime admits no bound orbits was found by Chakraborty [13] using the Hamilton-Jacobi formalism; the coordinates of a timelike geodesic were given as integrals with respect to the radial coordinate without employing the fact that the motion is 'flat'.

1. The outgoing radial geodesic C has the length

$$
\begin{equation*}
s(r)=\frac{r-r_{0}}{h \sqrt{k^{2}-1}} \quad \text { and } \quad r-r_{0}=h \sqrt{k^{2}-1} s \tag{101}
\end{equation*}
$$

For $\lambda^{\prime}=0$, the equations for the Jacobi scalars reduce to $d^{2} Z_{a} / d s^{2}=0$, hence $Z_{a}(s)=C_{a 1} s+C_{a 2}$ and the distances between the radial geodesics (all in $\theta=\pi / 2$ ) grow linearly.
2. For the non-radial $(L>0)$ outgoing geodesic $G$, the Jacobi scalars are

$$
\begin{equation*}
Z_{1}(r)=C_{11} \sqrt{p^{2} r^{2}-1}+C_{12} \tag{102}
\end{equation*}
$$

from (95), $Z_{2}$ is as in (93) and $Z_{3}=C_{31} s+C_{32}$. We check whether $Z_{1}$ generates a conjugate point. We put $Z_{2}=Z_{3}=0$ and require $Z_{1}\left(r_{0}\right)=0$, this yields (for $C_{11}=1$ )

$$
\begin{equation*}
Z_{1}(r)=\sqrt{p^{2} r^{2}-1}-\sqrt{p^{2} r_{0}^{2}-1} \tag{103}
\end{equation*}
$$

and this function has no roots for $r>r_{0}$. It remains to study the vector $Z^{\mu}=Z_{2} e_{2}^{\mu}$ and we know that the candidates for the conjugate points are at $\phi_{n}=n \pi$. We denote $\alpha \equiv \arccos \left(1 /\left(p r_{0}\right)\right)$ and since $p r_{0} \geq 1$, one gets $0<\alpha \geq \pi / 2$ and setting $\phi_{0}=0$, Eq. (100) is replaced by

$$
\begin{equation*}
\phi(r)=\frac{1}{h}\left[\arccos \left[\frac{1}{p r}\right]-\alpha\right] . \tag{104}
\end{equation*}
$$

For $r \rightarrow \infty$, this expression tends to $\frac{1}{h}(\pi / 2-\alpha)$ and for $\alpha<\pi / 2$ and $h$ sufficiently small it is arbitrarily large admitting many conjugate points. The first conjugate point $Q_{1}$ to $P_{0}$ occurs for $r=r_{\mathrm{c}}$ such that $\arccos \left(\frac{1}{p r_{\mathrm{c}}}\right)-\alpha=h \pi$ and the obvious inequality $0<\arccos \left(\frac{1}{p r_{\mathrm{c}}}\right)<\pi / 2$ is equivalent to $0<h \pi+\alpha<\pi / 2$ or $0<\alpha<\pi / 2-h \pi$. The last inequality means that $\cos \alpha=1 /\left(p r_{0}\right)>\cos (\pi / 2-h \pi)=\sin h \pi$. The value of $h$ is fixed and assigned to the spacetime. Therefore, the necessary condition for the existence of the conjugate points on some timelike geodesics is $h<1 / 2$. If it holds then the sufficient condition for the geodesic G to contain the conjugate point $Q_{1}$ (and possibly the successive points) to $P_{0}$ is

$$
\begin{equation*}
p r_{0}<\frac{1}{\sin h \pi} . \tag{105}
\end{equation*}
$$

It is worth stressing that all these properties hold if the spacetime outside the monopole is described in the astrophysical approximation of negligible mass. If $M \neq 0$, all the geometrical features of the resulting spacetime are significantly altered. For a positive mass, one gets an SSS manifold outside the USSS subclass and its metric may be rescaled to take on the Schwarzschild form implying the geodesic structure as in the latter spacetime, whereas for $M<0$ the gravitation is repulsive and there are no bound orbits [14].

## 6. Conclusions

Our conclusions to this work are brief and partial because any general rules concerning the qualitative properties of timelike worldines in various spacetimes may be formulated only after completing the research programme, i.e. after studying a sufficiently large number of different Lorentzian
manifolds. In our opinion, this statement should not be interpreted as a declaration that the research programme will never terminate. On the contrary, we believe that the wealth of geodesic structures in various gravitational fields is not immense and can be grasped in its dominant features in a not far future.

We have shown in the previous three papers that static spherically symmetric spacetimes are different in some properties of timelike geodesic curves and very similar in many other ones. Here, we show that for all stable circular orbits in these spacetimes all the infinitesimally close geodesics to the circular ones, constructed by means of the geodesic deviation vector fields, have the same length between a pair of conjugate points on the circular curves. The radial and circular geodesics in the Reissner-Nordström spacetime behave similarly to those in the Schwarzschild field, in particular if a circular and radial geodesics have common endpoints, the radial one is longer. Spherically symmetric spacetimes which furthermore are ultrastatic, exhibit a rather astonishing property that a free test particle may be in the state of absolute rest, i.e. no gravitational force is exerted on it. If a free particle moves, its velocity is constant - this means that the comoving frame in these spacetimes is dynamically akin to the inertial frame in Minkowski space of special relativity. Here, we have studied one example of ultrastatic manifolds, the Barriola-Vilenkin global (massless) monopole; the metric contains one arbitrary function which in this case is a constant and a generic non-radial geodesic may have conjugate points if the constant is sufficiently small.

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