

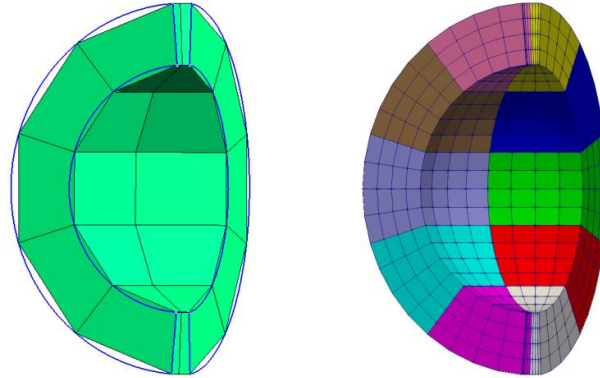
Constructing a Volume Geometry Map For Hexahedra With Curved Boundary Geometries

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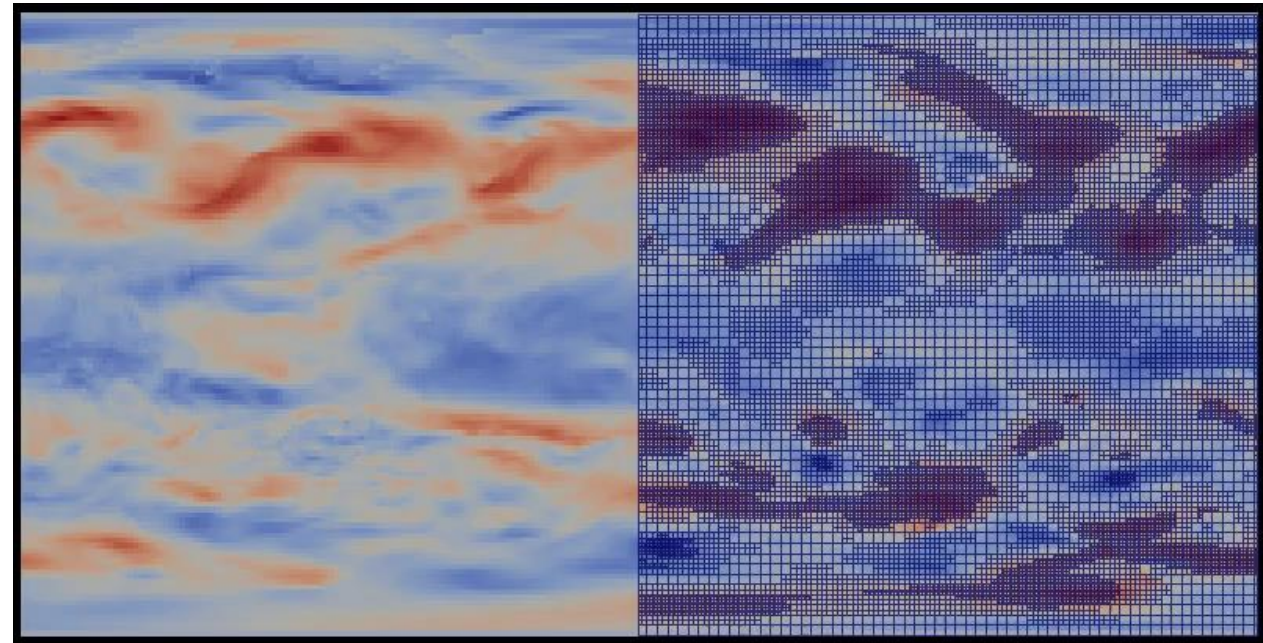
²Hochschule Bonn-Rhein-Sieg
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Electrical Engineering, Mechanical Engineering and Technical Journalism



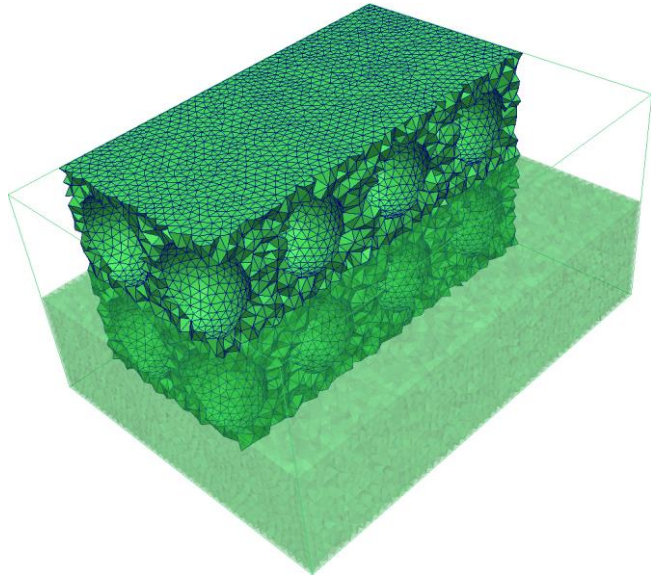
Knowledge for Tomorrow

Dynamic adaptive mesh refinement (AMR) with t8code

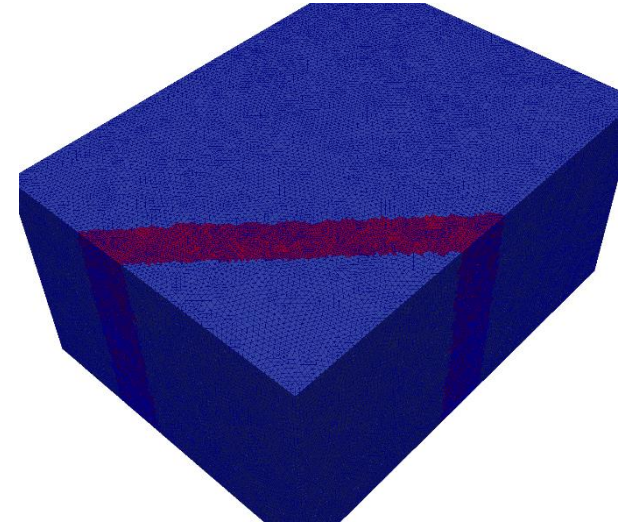
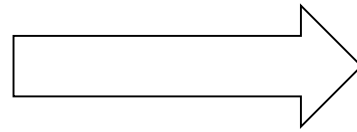
- t8code is a library for parallel (dynamic) adaptive mesh refinement
- During the simulation the mesh is arbitrarily refined and coarsened
- Algorithms for mesh adaptation, load-balancing, ghost elements, mesh iteration, search, etc.



Our work starts when the mesh generation is finished



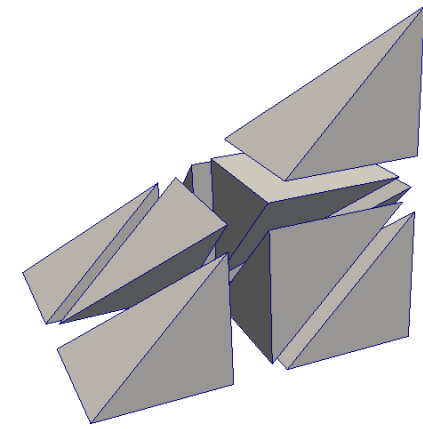
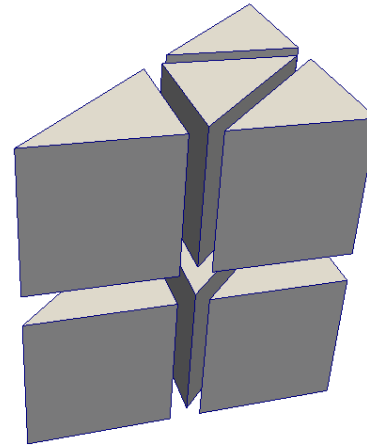
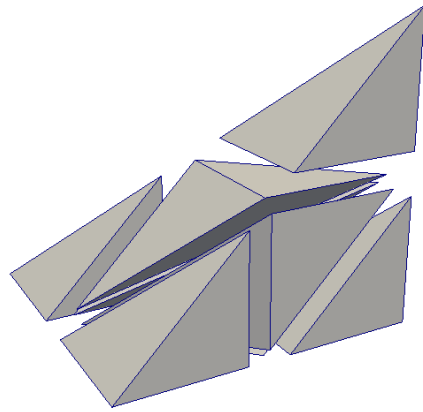
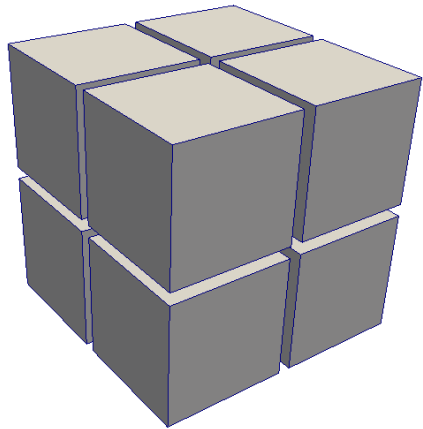
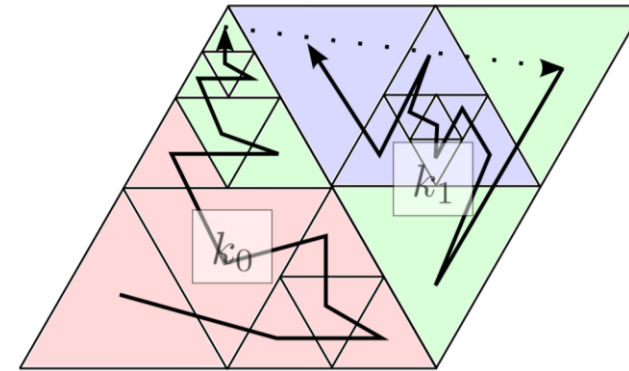
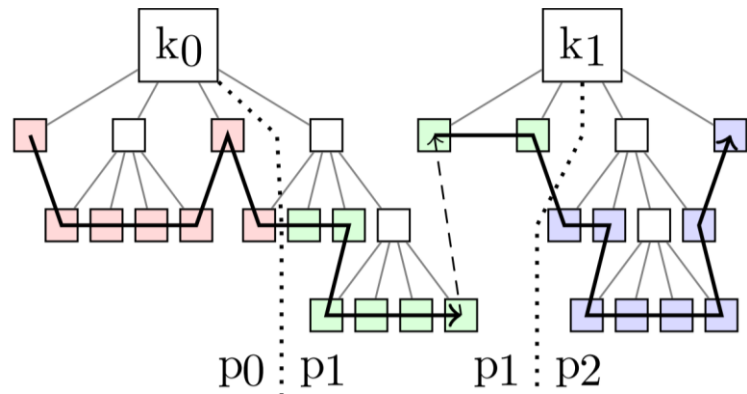
„Coarse“ input mesh from mesh generator



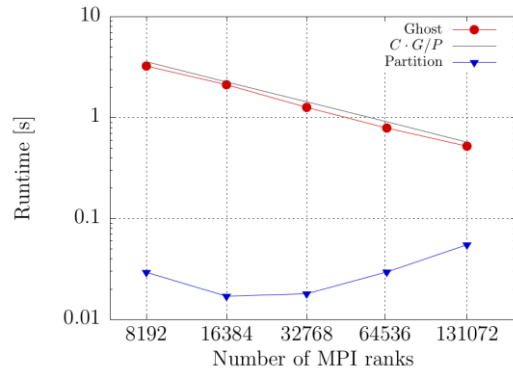
Adaptively refined during simulation



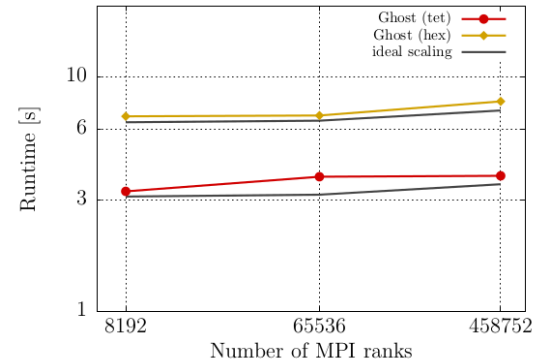
Space-filling curve



These methods are very efficient and massively scalable



Strong scale 1.9 billion tets



Weak scale, up to 142 billion elements

Recent milestone 1 Trillion element mesh:

#processes	#Elements	#Elements/process	Ghost	Partition
98,304	1,099,511,627,776 \approx 1.1e12	11,184,811	1.43s	0.33s



Geometry

All information on the geometry lies in the coarse mesh

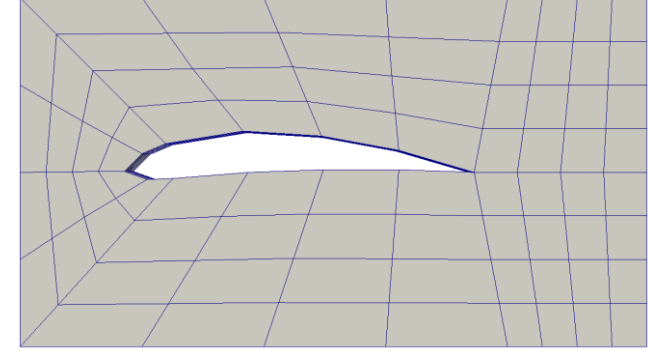
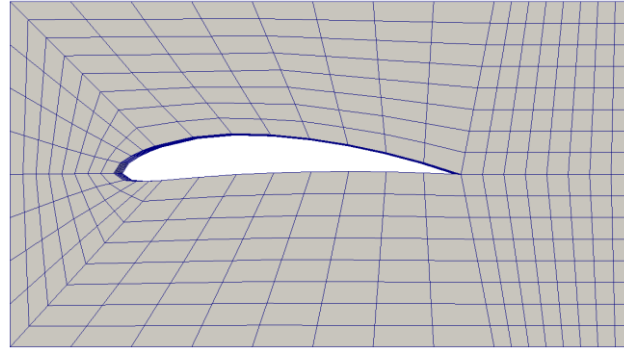
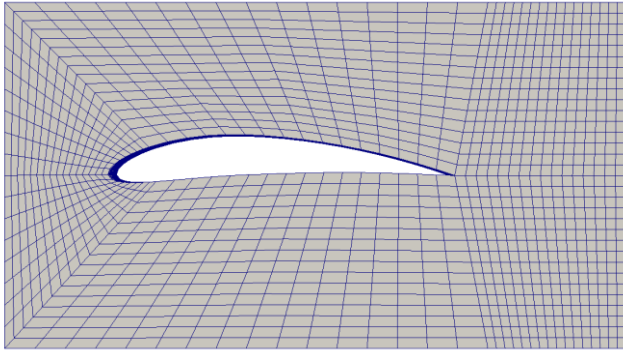
The smaller the coarse mesh, the better

- Less memory
- Faster computation
- More hierarchy levels
- Less pre-processing overhead

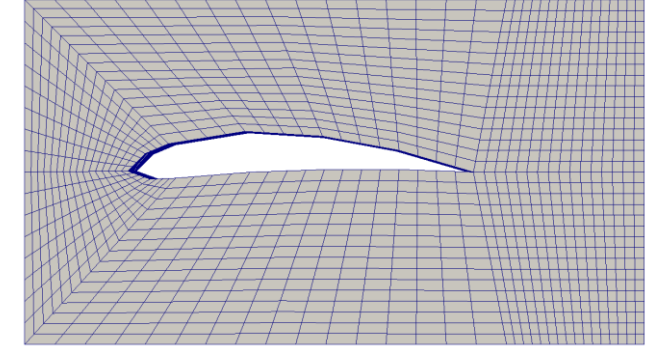
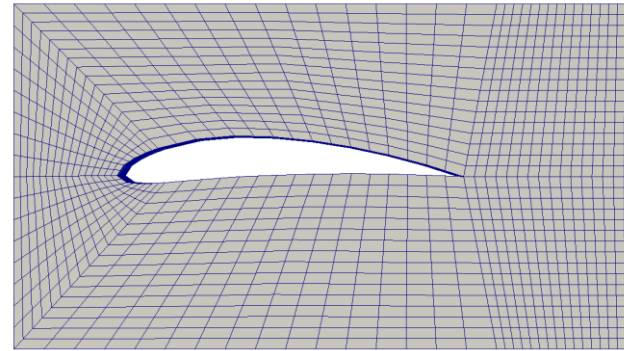
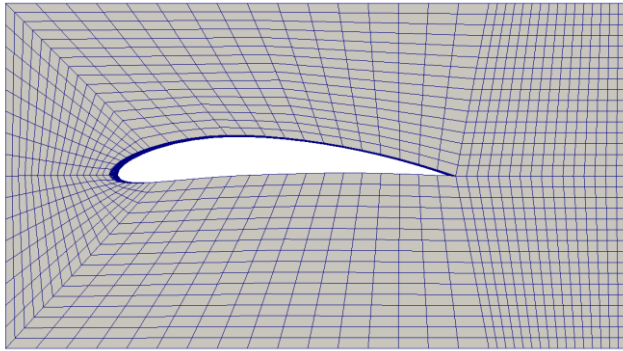


Refinement without geometry information loses information

Coarse mesh



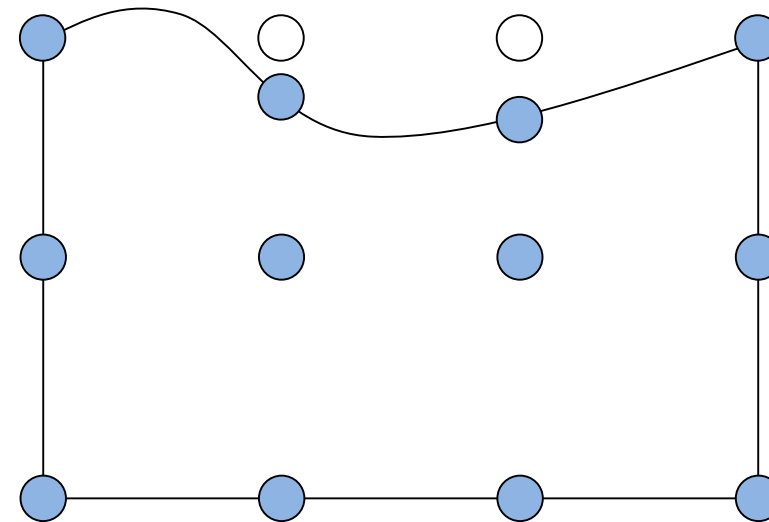
Fine mesh



Common approach

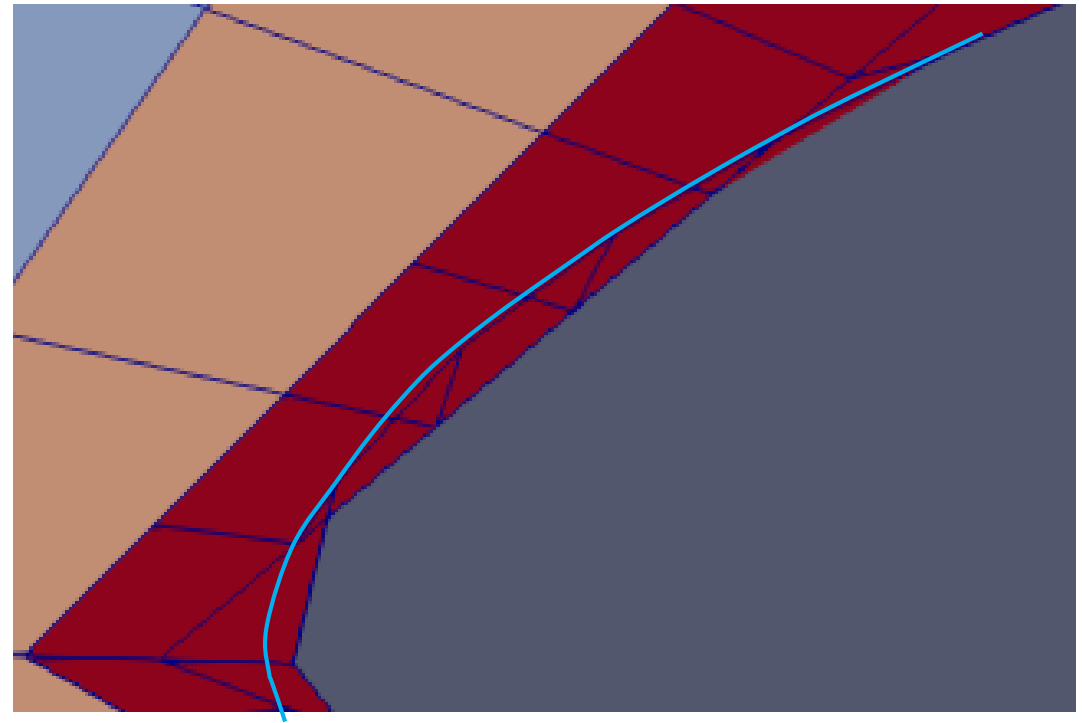
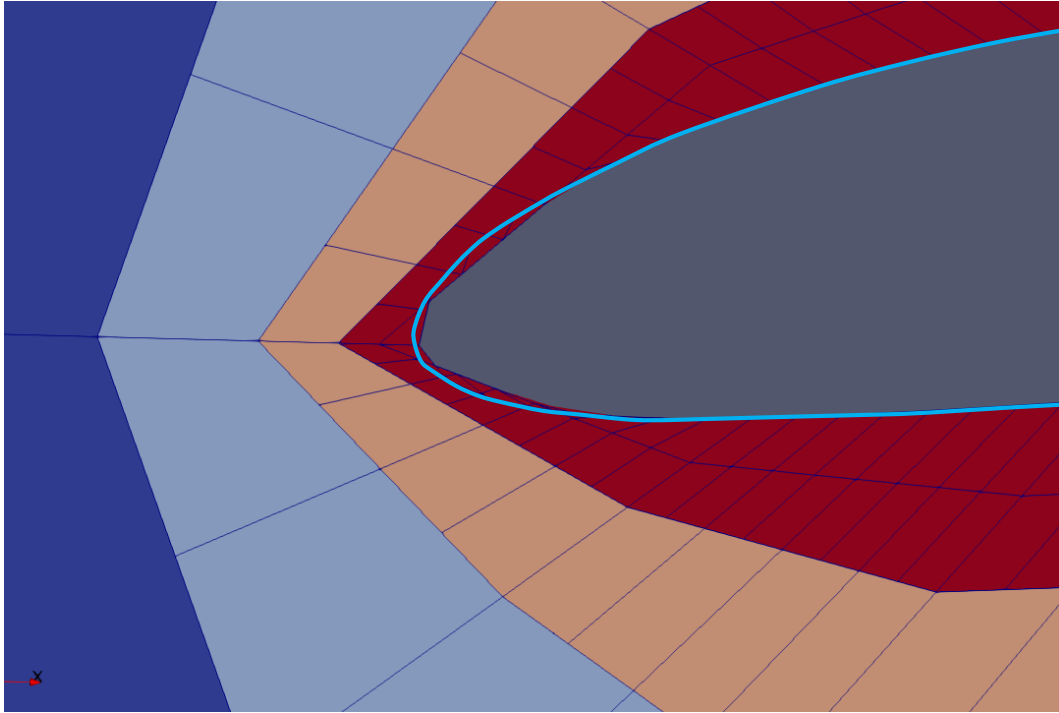
- ➔ Equip the coarse mesh with additional geometry information (High-order, CAD, etc.)
Use this information to evaluate geometry for fine mesh elements

Common approach: Surface projections



Why it fails

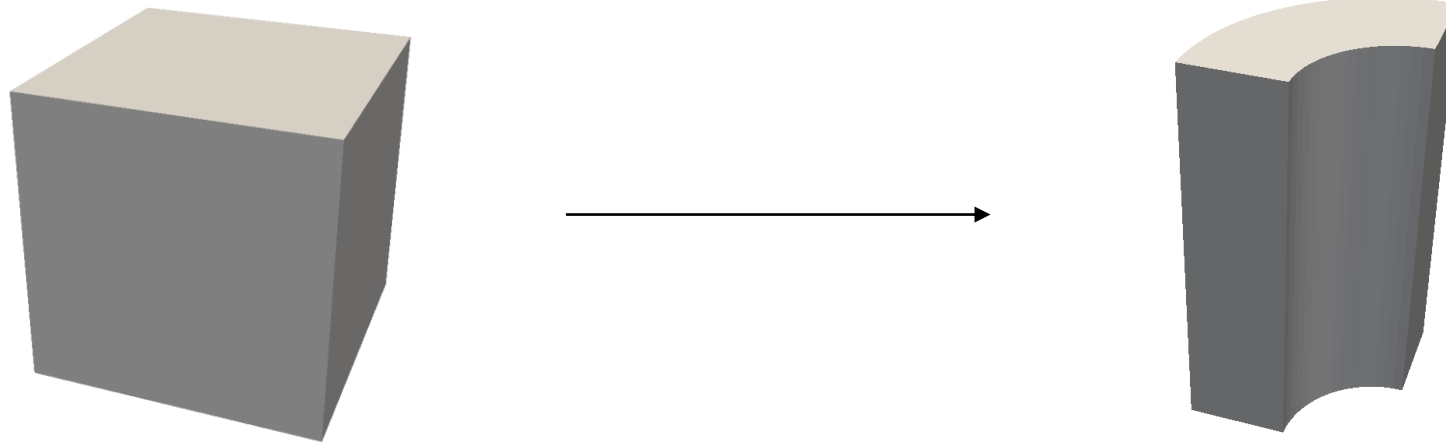
- We have **no a priori knowledge** of where fine mesh elements will arise
- Only projecting the elements closest to the surface will **distort the mesh** and may introduce **self intersections**



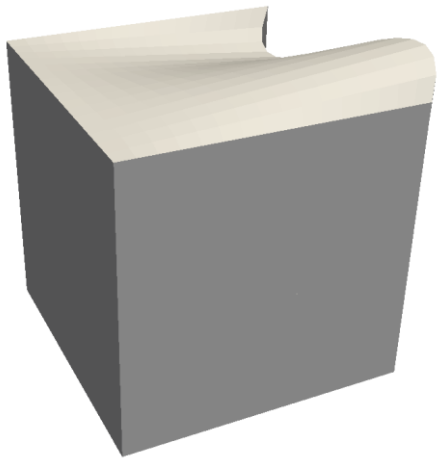
A volume geometry map

- We need to be able to evaluate the geometry **for every possible element** at **every possible position** in the original volume
- Therefore, we require a volume map

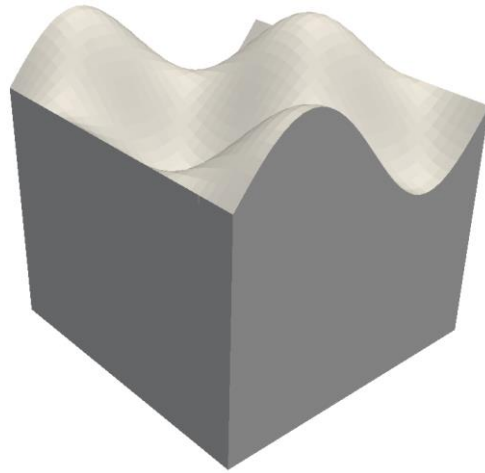
G : Reference volume $\longrightarrow \mathbb{R}^3$



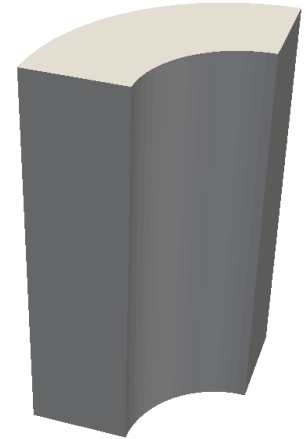
Possible cases



Curved edges



Curved surfaces



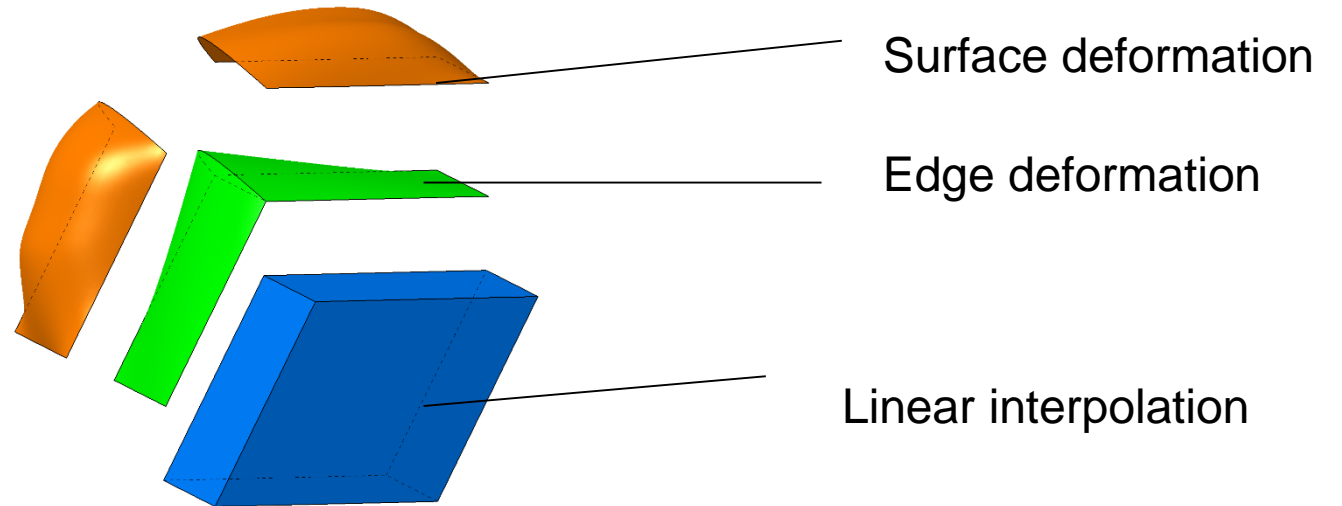
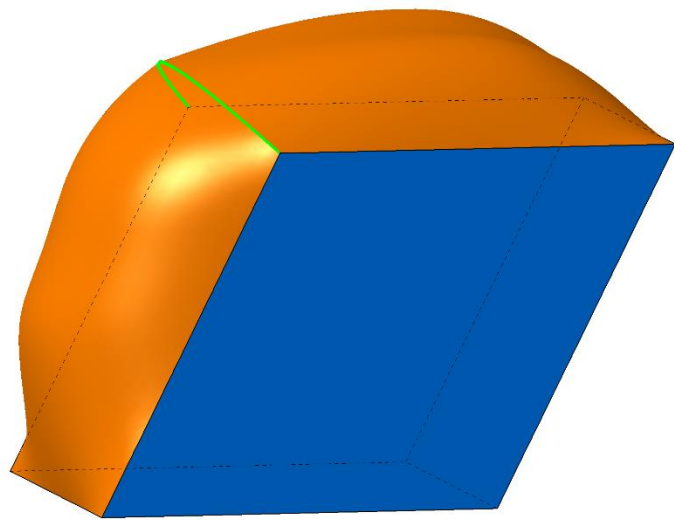
Any combination



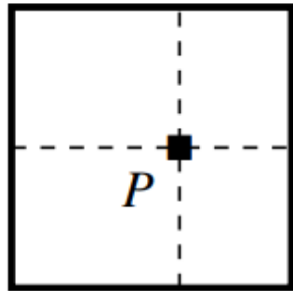
Outline

Input:

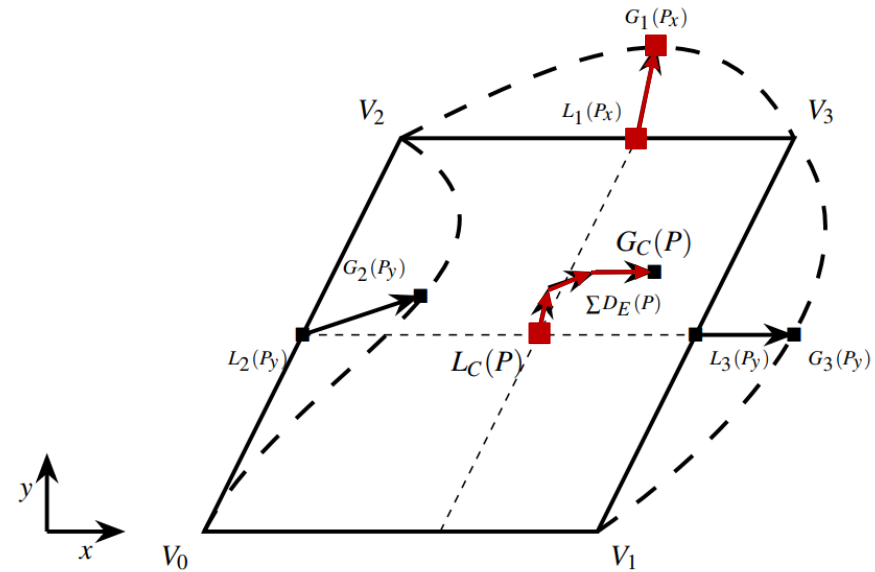
- Coarse mesh Cell
- Curved edges and surfaces with parameter space



The volume map



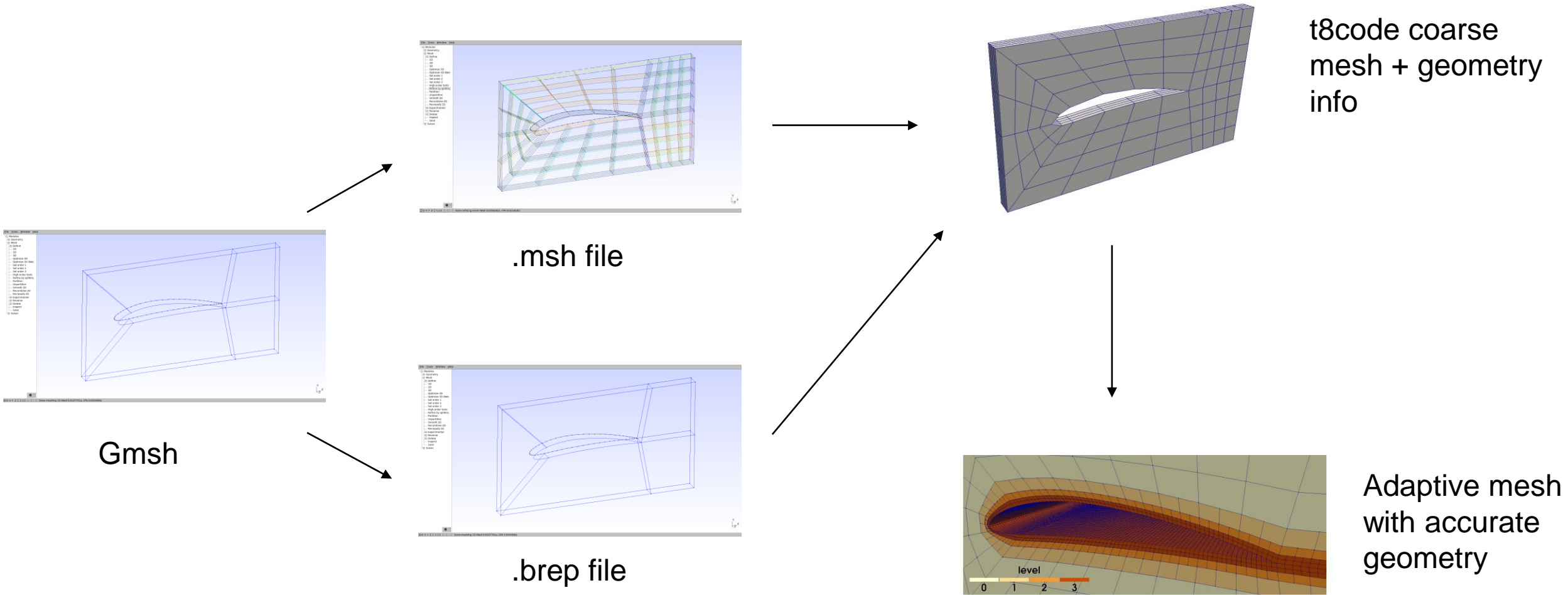
$G_C()$



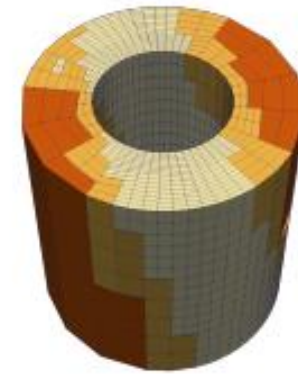
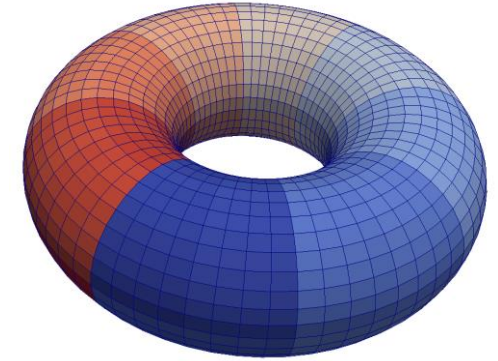
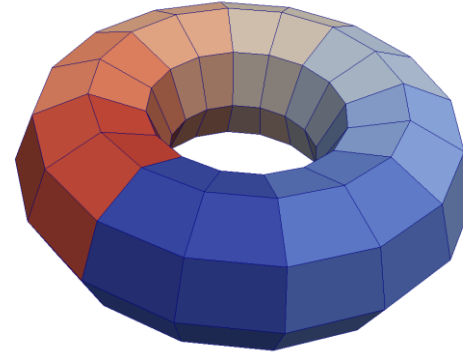
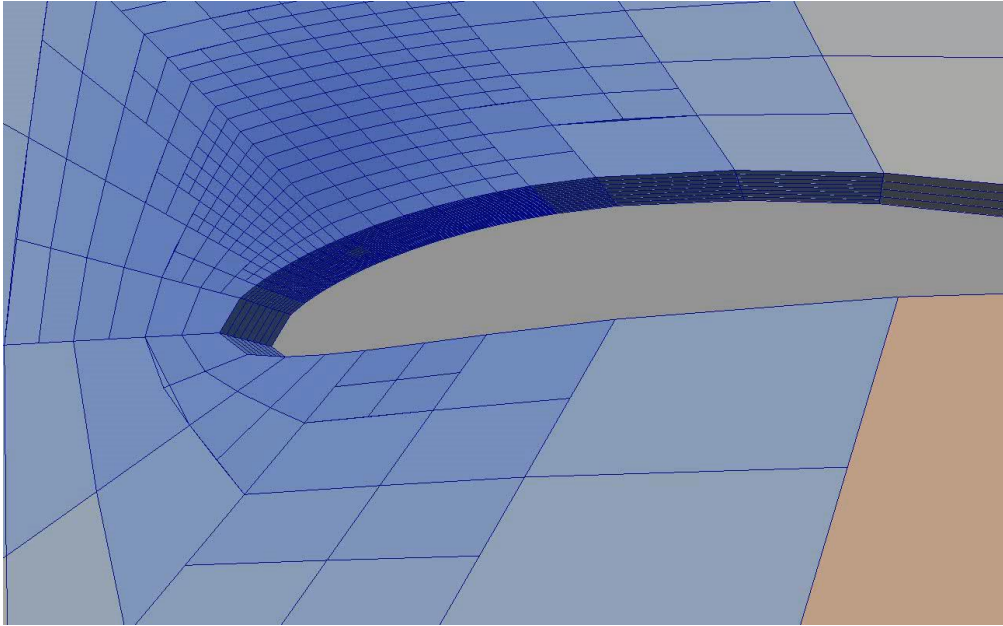
$$G_C(P) = L_C(P) + \sum_{\text{linked edges } E} D_E(P) + \sum_{\text{linked faces } F} D_F(P)$$



Workflow with Gmsh



Some more examples



References

Checkout t8code at: www.github.com/holke/t8code

(Work in progress on https://github.com/sandro-elsweijer/t8code/tree/feature-brep_geometry_2)

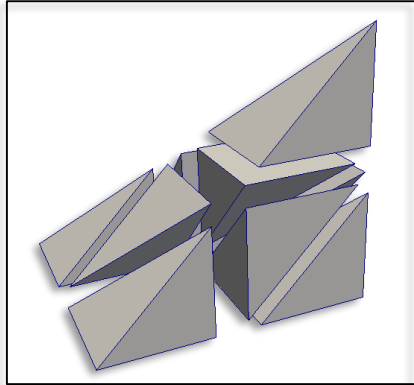
Holke J. *Scalable algorithms for parallel tree-based adaptive mesh refinement with general element types*
PhD thesis, Rheinische Friedrich-Wilhelms-Universität, Bonn, 2018

Holke J., Knapp D., Burstedde C. *An Optimized, Parallel Computation of the Ghost Layer for Adaptive Hybrid Forest Meshes*
SIAM Journal on Scientific Computing, Vol. 43 (6), <https://doi.org/10.1137/20M1383033>

Elsweijer S. "Curved Domain Adaptive Mesh Refinement with Hexahedra." Tech. rep., Hochschule Bonn-Rhein-Sieg, Jul. 2021. URL <https://elib.dlr.de/143537/>

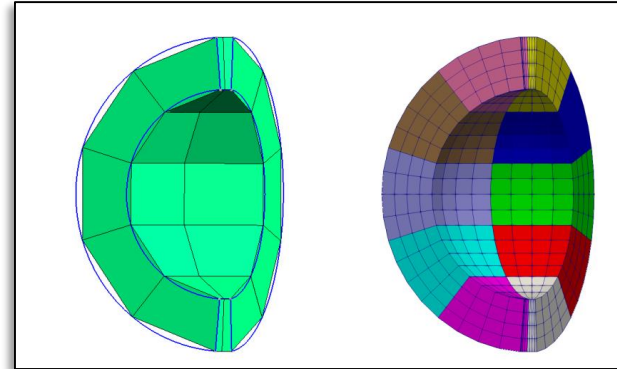


t8code @ SIAMPP22



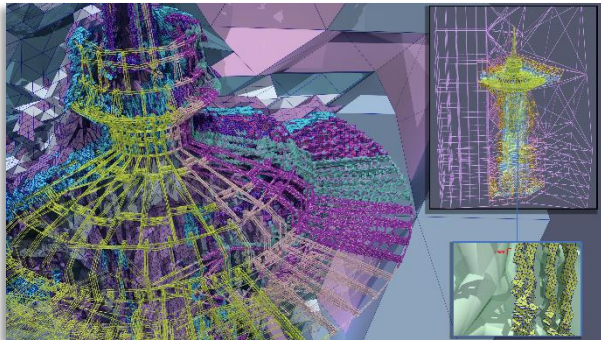
MS28 Thursday, 24th, 11:45 UTC-8 / 19:45 GMT

A space-filling curve for pyramids
David Knapp, J. Holke, C. Burstedde



IMR22, Thursday, 24th, 17:10 GMT / 09:10 UTC-8

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Meshing contest @IMR22

