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1 Title page 2 Title: Changes in postural control strategy during quiet standing in individuals with knee 3 4 osteoarthritis. 5 6 **Authors:** Kento Sabashi^{1,2}, Satoshi Kasahara¹, Harukazu Tohyama¹, Takeshi Chiba^{1,2}, Yuta Koshino¹, 7 Tomoya Ishida¹, Mina Samukawa¹, Masanori Yamanaka³ 8 ¹ Faculty of Health Sciences, Hokkaido University, Kita 12, Nishi 5, Kita-ku, Sapporo, 9 10 Hokkaido, 060-0812, Japan. ² Department of Rehabilitation, Hokkaido University Hospital, Kita 14, Nishi 5, Kita-ku, 11 Sapporo, Hokkaido, 060-8648, Japan. 12 ³ Faculty of Health Science, Hokkaido Chitose College of Rehabilitation, Satomi 2-10, 13 14 Chitose, Hokkaido, 066-0055, Japan. 15 16 **Corresponding author:** 17 Satoshi Kasahara, PT, PhD Department of Rehabilitation Science, Faculty of Health Sciences, Hokkaido University 18 19 Kita 12, Nishi 5, Kita-ku, Sapporo, Hokkaido, 060-0812, Japan Tel/Fax: +81-11-706-3390 20 E-mail: kasahara@hs.hokudai.ac.jp

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BACKGROUND: Knee osteoarthritis (OA) impairs postural control, which may be affected 27 28 by how to use lower limb joints. 29 **OBJECTIVE:** To investigate how individuals with knee OA use lower limb joints for static 30 postural control. 31 **METHODS:** Ten patients with knee OA and thirteen healthy controls performed quiet 32 standing for 30 s. The standard deviation of the center of mass (COM) and lower limb joint motions in the anterior-posterior (AP) and medial-lateral (ML) planes were calculated from 33 three-dimensional marker trajectories. Pearson's correlation analysis and independent *t*-tests 34 35 were conducted to investigate the relationship between COM and lower limb joint motions and to compare group difference, respectively. 36 37 **RESULTS:** The AP hip angular velocity alone in the knee OA group and the AP hip and 38 knee angular velocity in the control group were significantly correlated with the AP COM velocity. The ML hip angular velocity was significantly correlated with the ML COM 39 40 velocity in both groups. The knee OA group exhibited a significantly larger standard deviation of AP COM velocity than the control group. 41 CONCLUSIONS: Individuals with knee OA depended solely on the contribution of the hip 42 43 to the AP COM velocity, which could not be successfully controlled by the knee. 44 **Keywords:** 45 Knee osteoarthritis, Quiet standing, Postural control, Center of mass, Kinematics 46 47 48 49 50

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Abstract.

1. Introduction

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Osteoarthritis (OA) of the knee is substantially prevalent in the elderly [1,2]. Patients with knee OA have knee pain [3], quadriceps weakness [4], limited knee range of motion [5], impaired proprioception of the knee [6], and structural changes (e.g., knee malalignment and cartilage degradation) [7]. Consequently, knee OA is considered one of the main causes that limits activities of daily living [8], deteriorates the quality of life [9], and increases the likelihood of falling [10]. The prevention of falls is a research priority in patients with knee OA because falls may induce incident fractures [10–12]. Poor postural control in patients with knee OA is considered to increase the likelihood of falling [13]. Patients with knee OA exhibit impairments in postural control, including increased postural sway during quiet standing compared to healthy adults [14]. Previous studies demonstrated that the amount of postural sway in this patient population is associated with knee pain [15,16], severity of knee OA [17], and knee muscle strength [18]. For the clinical assessment and rehabilitation of individuals with knee OA, it is important to understand how these factors affect joint motion during postural control. The goal of static postural control is to stabilize the center of mass (COM) within the base of support. All joint motions, particularly those in the lower limbs, play a vital role in postural control. In general, the maintenance of equilibrium in the anterior-posterior (AP) and medial-lateral (ML) planes during quiet standing is mainly controlled by ankle and hip joint motions [19,20], while a recent study showed that knee joint motion additionally contributes to static postural control [21]. Individuals with knee OA have impaired hip and ankle joint functions as well as knee joint functions [4–6,22–25]. However, it remains unknown whether the use of lower limb joints for postural control in this patient population differs from that in healthy adults. Therefore, the purpose of this study was to investigate the changes in postural

control strategies during quiet standing in individuals with knee OA. We hypothesized that

the lower limb joint motions used to control the COM motion were different between individuals with knee OA and age-matched healthy controls.

2. Methods

This study was a case-control type investigation. We received ethical approval from the Institutional Review Board of our institute, and written informed consent was obtained from all participants.

2.1. Participants

Twenty-three participants, ten individuals diagnosed with unilateral or bilateral knee OA (one male and nine females) and thirteen healthy controls (three male and ten females), participated in this study (Table 1). Knee pain in patients with knee OA was assessed using a visual analogue scale (VAS), which ranged from 0 (no pain) to 100 mm (severe pain), and the average VAS score was 23.8 mm. All participants with and without knee OA were recruited from several hospitals and local communities. *A priori* power analysis was conducted using the t-test model of G*Power 3.1.9.2 (Kiel University, Kiel, Germany). Based on our pilot study of knee angular velocity data with seven participants (three patients with knee OA and four healthy controls), the minimum sample size for this study was 10 participants per group (effect size = 1.39, alpha = 0.05, and power = 0.80).

Participants in the knee OA group were included if they were aged 50–79 years and had radiographically diagnosed knee OA with a Kellgren–Lawrence grade 2–4 in at least one knee [26]. Potential participants in both groups were excluded if they had any previous lower limb or back surgery, severe disability in walking and standing without an assistive device, any musculoskeletal disorder other than knee OA that would influence balance, or any neurological disorder.

2.2. Experimental protocol

All participants were instructed to stand as still as possible and to keep looking straight ahead with their feet hip-width apart and their arms folded across the chest. During testing, participants were not provided with any information on body sway. The examination was performed twice for 30 s.

All data were collected using a motion-capture system (Cortex; Motion Analysis Corporation, Santa Rosa, CA, USA), which consisted of seven cameras (Hawk cameras; Motion Analysis Corporation) with a sampling rate of 200 Hz. According to the modified Helen Hayes marker set [27], 25 reflective markers were positioned at the following anatomical landmarks: dorsum of the foot, heel, lateral and medial malleoli, lateral shank, lateral and medial femoral epicondyle, lateral thigh, anterior superior iliac spine, sacral, acromion, lateral humeral epicondyle, and wrist. All markers, except the sacral, were attached bilaterally.

2.3. Data analysis

All signals were processed using a custom MATLAB program (MathWorks Inc., Natick, MA, USA). Three-dimensional marker trajectories were low-pass filtered at a cutoff frequency of 5 Hz using a fourth-order Butterworth filter [28].

The time series of AP and ML COM positions were calculated from the marker data based on previously reported anthropometric data [29]. The time series of AP and ML COM velocities were calculated as the first-time derivatives of COM positions. The following COM-based parameters in each direction were calculated to assess the amount of body sway during quiet standing: (1) standard deviation (SD) of COM position and (2) SD of COM velocity [20,30].

The time series of AP and ML hip, knee, and ankle angles were calculated using Visual 3D software (C-Motion Inc., Germantown, MD, USA). Subsequently, the time series of AP and ML angular velocities were calculated as the first-time derivatives of each lower limb joint angle. Knee joint motion analysis in the ML plane, or knee adduction-abduction, was excluded based on the method presented in [31]. Additionally, the following kinematic parameters in each direction were calculated to assess the amount of lower limb joint motions during quiet standing: (1) SD of lower limb joint angle and (2) SD of lower limb joint angular velocity [20]. The affected limb in patients with unilateral knee OA, the most affected limb in patients with bilateral knee OA, and a randomly selected limb in healthy controls were adopted in this study.

To compare the differences in standing posture, the mean values of COM positions and lower limb joint angles during static standing were calculated. The mean values of COM positions were defined as the distance from the midpoint of the bilateral heel markers in the AP and ML planes. The mean values of COM positions in the AP plane were expressed as positive if the COM position was anterior relative to the midpoint of the bilateral heel markers, while those in the ML plane were expressed as positive if the COM position was in the direction of the study limb relative to the midpoint of the bilateral heel markers. In addition, lower limb joint angles in the AP plane were represented as positive for flexion (dorsiflexion), while those in the ML plane were represented as positive for adduction (inversion).

2.4. Statistical analysis

An independent *t*-test was used to compare the demographic data, the mean values of COM positions, the mean values of lower limb joint angles, the SDs of COM position and velocity, and the SDs of lower limb joint angles and angular velocities between the groups.

Then, the mean difference (the knee OA group minus the control group) and 95% confidence interval (CI) for each variable was calculated. Pearson's product correlation analysis was performed to investigate the relationship between lower limb joint motion and COM motion in the AP and ML planes in each group. In addition, Pearson's product correlation analysis was carried out to investigate the associations of the amount of body sway and lower limb joint motions with knee pain in patients with knee OA. The statistical significance level was set at P < 0.05. All statistical analyses were performed using IBM SPSS Statistics version 26.0 (IBM Corporation, Armonk, NY, USA).

3. Results

The mean values of COM positions for the groups in the AP (mean difference = 4.91mm, 95% CI = -6.85 to 16.67 mm, P = 0.395) and ML planes (mean difference = -0.95 mm, 95% CI = -7.02 to 5.12 mm, P = 0.748) did not change significantly. In addition, no significant difference was found between the mean values of lower limb joint angles of groups in the AP (hip: mean difference = -0.58° , 95% CI = -6.76 to 5.60° , P = 0.847; knee: mean difference = 2.71° , 95% CI = -2.97 to 8.38° , P = 0.332; ankle: mean difference = 0.68° , 95% CI = -2.92 to 4.28°, P = 0.698) and ML planes (hip: mean difference = -0.55°, 95% CI = -2.66 to 1.57°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, 95% CI = -8.21 to 3.35°, P = 0.597; ankle: mean difference = -2.43°, P = 0.597; ankle: mean difference 0.391). For the SD of AP and ML COM positions, there was no significant difference between the groups (AP: mean difference = 0.06 mm, 95% CI = -0.91 to 1.02 mm, P = 0.903; ML: mean difference = 0.51 mm, 95% CI = -0.14 to 1.16 mm, P = 0.115) (Fig. 1a). The SD of AP COM velocity was significantly larger in the knee OA group than that of the control group (mean difference = 0.79 mm/s, 95% CI = 0.24 to 1.35 mm/s, P = 0.007). Furthermore, there was no significant difference in the ML COM velocity of groups (mean difference = 0.18

mm/s, 95% CI = -0.27 to 0.63 mm/s, P = 0.408) (Fig. 1b).

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177 For the SD of lower limb joint angles in the AP plane, there was no significant difference between the groups (hip: mean difference = 0.06° , 95% CI = -0.09 to 0.20° , P =178 179 0.433; knee: mean difference = 0.02° , 95% CI = -0.08 to 0.11°, P = 0.705; ankle: mean difference = 0.03° , 95% CI = -0.03 to 0.09° , P = 0.296) (Fig. 2a). Regarding the ML plane, 180 the SD of hip angle was significantly larger in the knee OA group than that of the control 181 182 group (mean difference = 0.07° , 95% CI = 0.02 to 0.12° , P = 0.007). Moreover, the SD of ankle angle was not significantly different between the groups (mean difference = 0.01°, 95% 183 CI = -0.08 to 0.09° , P = 0.853) (Fig. 2b). As for the lower limb joint angular velocities, the 184 185 SD of AP hip and knee angular velocities were significantly larger in the knee OA group than those of the control group (hip: mean difference = $0.22 \, ^{\circ}$ /s, $95\% \, \text{CI} = 0.08$ to $0.35 \, ^{\circ}$ /s, P =186 0.003; knee: mean difference = 0.17 °/s, 95% CI = 0.04 to 0.30 °/s, P = 0.010). In addition, 187 188 the SD of AP ankle angular velocity was not significantly different between groups (mean difference = $0.04 \, ^{\circ}/s$, 95% CI = -0.06 to $0.15 \, ^{\circ}/s$, P = 0.372) (Fig. 3a). The SD of ML hip 189 190 angular velocity was significantly larger in the knee OA group than that of the control group (mean difference = 0.16 °/s, 95% CI = 0.02 to 0.31 °/s, P = 0.030). Furthermore, the SD of 191 ML ankle angular velocity was not significantly different between groups (mean difference = 192 193 -0.14 °/s, 95% CI = -0.60 to 0.31 °/s, P = 0.523) (Fig. 3b). 194 Pearson's correlation analysis showed that the SD of AP ankle angle was positively correlated with the SD of AP COM position in both groups (OA: r = 0.662, P = 0.037; 195 control: r = 0.777, P = 0.002) (Table 2). In the knee OA group, the SD of ML hip angle was 196 197 positively correlated with the SD of ML COM position (r = 0.925, P < 0.001), whereas in the control group, the SD of ML ankle angle was positively correlated with the SD of ML COM 198 199 position (r = 0.726, P = 0.005). The SD of AP hip angular velocity was positively correlated with the SD of AP COM velocity in the knee OA group (r = 0.644, P = 0.044). In addition, 200

the SDs of AP hip and knee angular velocities were positively correlated with the SD of AP COM velocity in the control group (hip: r = 0.562, P = 0.046; knee: r = 0.673, P = 0.012) (Table 3). The SD of ML hip angular velocity was positively correlated with the SD of ML COM velocity in both groups (OA: r = 0.820, P = 0.004; control: r = 0.846, P < 0.001). In addition, there was no significant correlation between the SDs of COM and lower

limb joint motions and the VAS score for knee pain (P = 0.092 - 0.966) (Table 4).

4. Discussion

The current study revealed that the characteristics of the postural control strategy during quiet standing in individuals with knee OA differed from those of age-matched healthy adults. The knee OA group exhibited significantly larger SDs of AP COM velocity, ML hip angle, AP hip angular velocity, AP knee angular velocity, and ML hip angular velocity than the control group. The AP ankle angle was significantly correlated with the AP COM position in both groups, while the ML hip angle and ML ankle angle were significantly correlated with the ML COM position in the knee OA and control groups, respectively. In the knee OA group, the AP hip angular velocity was significantly correlated with the AP COM velocity, while in the control group, the AP hip and knee angular velocities were significantly correlated. The ML hip angular velocity was significantly correlated with the ML COM velocity in both groups.

Previous studies suggested that the amplitude of postural sway in the AP and ML planes is generally controlled by ankle and hip joint motions [19,20]. In this study, the amplitude of AP COM position was controlled by the ankle strategy in both groups, and there was no significant difference in the amplitude of AP hip, knee, and ankle angles between the groups. In other words, the postural control strategy for controlling the AP COM position may be identical in both groups. The knee OA group used the hip strategy to control the amplitude

of ML COM position, whereas the control group used the ankle strategy. Furthermore, the amplitude of ML hip angle of the knee OA group was larger than that of the control group; however, there was no significant difference in the amplitude of ML ankle angles of the groups. Compared with healthy adults, patients with knee OA have an impaired sense of motion of the ankle joint in the ML plane; however not in the hip joint [25]. Those with knee OA may be unable to adequately control the ML COM position with the ankle strategy. Therefore, they may prefer to use the hip strategy to control the ML COM position.

Furthermore, the hip strategy has less COM motion than the ankle strategy even with the same angle change because the center of rotation of hip joint is closer to the COM than that of the ankle joint [32]. Therefore, the knee OA group may have required greater ML hip joint motion than the control group.

It is believed that the hip strategy is preferable to the ankle strategy for fast COM motion in postural control [33]. The hip strategy, which results in predominant hip joint motion, includes thigh muscle activity that causes knee joint motion, although the muscles around the ankle joint are extremely unresponsive [34]. As for the control of AP COM velocity, the knee OA group used a postural control strategy using the hip joint alone, while the control group used a mixed postural control strategy using the hip and knee joints. In other words, the knee OA group depended only on the contribution of hip joint to the AP COM velocity, while the control group depended on the contribution of hip and knee joints. Therefore, the knee OA group exhibited increased body sway velocity and hip angular velocity in the AP plane. In addition, the knee joint possibly cannot be used well to control body sway velocity in the AP plane because the AP knee angular velocity in the knee OA group was not correlated with the body sway velocity in the AP plane and was larger than that of the control group. This may be affected by knee joint dysfunctions, such as quadriceps weakness [4], limited knee range of motion [5], and impaired proprioception of the knee [6]

in patients with knee OA. Our study showed that it might be necessary to maintain hip joint function and improve knee joint function for balance training in patients with knee OA. As for the control of ML COM velocity, both groups used a postural control strategy using the hip joint. Furthermore, the SD of hip angular velocity in the knee OA group was larger than that of the control group, while there was no significant difference in the SD of ML COM velocity for both groups. Postural sway velocity, such as the COM velocity, includes the direction and position changes at the next moment. Therefore, this information is considered significant for maintaining equilibrium [30,35]. The knee OA group may maintain postural stability because of an increased sensory information resulting from an increased ML hip angular velocity to compensate for an impaired sense of motion of the ankle joint in the ML plane.

Previous studies presented that knee pain was associated with postural sway in patients with mild-to-severe knee OA whose VAS score for knee pain was greater than 30 mm [15,18]. However, in this study, knee pain did not correlate with the SDs of COM and lower limb joint motions in patients with knee OA. This might be caused by mild knee pain and mild-to-moderate knee OA in this study.

This study had several limitations. First, the participants in this study had mild-to-moderate knee OA, and the average knee pain was less severe. The average knee pain in this study may have been mild because of mild-to-moderate knee OA [9]. Therefore, the participants in this study might not represent the overall characteristics of patients with knee OA. Second, the task examined in this study was quiet standing, and results from dynamic tasks, such as external perturbations, may differ from those in this study. Therefore, dynamic tasks need to be investigated in the future. Third, we used three-dimensional motion analysis to calculate the COM and lower limb joint motions. Measurement errors due to soft tissue artifacts in three-dimensional motion analysis may have affected the results of quiet standing performed in this study [36]. Finally, the number of participants in this study was limited.

Further studies with a large number of participants are needed to take into account the severity of knee OA and knee pain.

5. Conclusions

We investigated the alterations in the postural control strategies during quiet standing in individuals with knee OA. Both the knee OA and control groups utilized the ankle joint to control the AP COM position. For the control of ML COM position, the knee OA group used the hip joint, whereas the control group used the ankle joint. The knee OA group successfully controlled the AP and ML COM positions because there was no significant group difference in the amplitude of COM position. To control the AP COM velocity, the knee OA group relied on the contribution of hip joint solely, whereas the control group relied on the contribution of hip and knee joints. Both the knee OA and control groups used the hip joint to control the ML COM velocity. The knee OA group exhibited postural control impairment in the amplitude of COM velocity in the AP plane, and not in the ML plane though. Our findings suggested that the knee OA group could not successfully control the AP COM velocity using the knee joint.

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401 Tables
402 Table 1
403 Demographic data of the knee OA and control groups

| Knee OA | Control | P |
|-------------|--|--|
| 67.8 (8.9) | 63.5 (8.6) | 0.258 |
| 153.8 (7.5) | 156.1 (8.2) | 0.488 |
| 56.8 (15.2) | 57.7 (10.3) | 0.866 |
| 23.7 (4.1) | 23.6 (3.1) | 0.924 |
| | | |
| 4 | | |
| 6 | | |
| 23.8 (17.8) | | |
| | 67.8 (8.9) 153.8 (7.5) 56.8 (15.2) 23.7 (4.1) | 67.8 (8.9) 63.5 (8.6) 153.8 (7.5) 156.1 (8.2) 56.8 (15.2) 57.7 (10.3) 23.7 (4.1) 23.6 (3.1) |

Data are reported as mean values (standard deviation).

OA: osteoarthritis, BMI: body mass index, VAS: visual analogue scale.

^a VAS score for knee pain ranges from 0 (no pain) to 100 mm (severe pain).

Table 2
 Pearson's correlation coefficients between each lower limb joint angle and COM
 position

| | Knee OA | | Control | |
|-----------------------|---------|----------|---------|--------|
| | r | p | r | p |
| SD of AP COM position | | | | |
| SD of AP hip angle | 0.129 | 0.722 | 0.207 | 0.497 |
| SD of AP knee angle | 0.311 | 0.382 | 0.418 | 0.155 |
| SD of AP ankle angle | 0.662 | 0.037* | 0.777 | 0.002* |
| SD of ML COM position | | | | |
| SD of ML hip angle | 0.925 | < 0.001* | 0.366 | 0.219 |
| SD of ML ankle angle | 0.239 | 0.507 | 0.726 | 0.005* |

COM: center of mass, OA: osteoarthritis, SD: standard deviation, AP: anterior-

⁴²¹ posterior, ML: medial-lateral.

^{422 *} *P* < 0.05.

Table 3
 Pearson's correlation coefficients between each lower limb joint angular velocity and
 COM velocity

| | Knee OA | | Control | |
|---------------------------------|---------|--------|---------|----------|
| | r | P | r | P |
| SD of AP COM velocity | | | | |
| SD of AP hip angular velocity | 0.644 | 0.044* | 0.562 | 0.046* |
| SD of AP knee angular velocity | 0.539 | 0.108 | 0.673 | 0.012* |
| SD of AP ankle angular velocity | 0.424 | 0.222 | 0.427 | 0.146 |
| SD of ML COM velocity | | | | |
| SD of ML hip angular velocity | 0.820 | 0.004* | 0.846 | < 0.001* |
| SD of ML ankle angular velocity | -0.023 | 0.949 | 0.212 | 0.488 |

COM: center of mass, OA: osteoarthritis, SD: standard deviation, AP: anterior-

posterior, ML: medial-lateral.

438 * *P* < 0.05.

Table 4
 Pearson's correlation coefficients between the COM and lower limb joint motions and
 knee pain in patients with knee OA

| | Knee OA | |
|---------------------------------|---------|-------|
| | r | P |
| VAS score for knee pain | | |
| SD of AP COM position | -0.352 | 0.319 |
| SD of ML COM position | -0.196 | 0.588 |
| SD of AP COM velocity | -0.182 | 0.614 |
| SD of ML COM velocity | -0.105 | 0.772 |
| SD of AP hip angle | 0.467 | 0.173 |
| SD of AP knee angle | 0.449 | 0.193 |
| SD of AP ankle angle | -0.322 | 0.364 |
| SD of ML hip angle | -0.015 | 0.966 |
| SD of ML ankle angle | 0.561 | 0.092 |
| SD of AP hip angular velocity | -0.196 | 0.587 |
| SD of AP knee angular velocity | -0.044 | 0.904 |
| SD of AP ankle angular velocity | 0.145 | 0.689 |
| SD of ML hip angular velocity | -0.134 | 0.711 |
| SD of ML ankle angular velocity | 0.495 | 0.146 |
| | | |

⁴⁵² COM: center of mass, OA: osteoarthritis, VAS: visual analogue scale, SD: standard

454

455

deviation, AP: anterior-posterior, ML: medial-lateral.

Figure captions Fig. 1. Group-averaged SD of COM position (a) and velocity (b) in the AP and ML planes. The white bar indicates the knee OA group and the black bar indicates the control group. * P < 0.05. Fig. 2. Group-averaged SD of hip, knee, and ankle angles in the AP (a) and ML (b) planes. The White bar indicates the knee OA group and the black bar indicates the control group. * P < 0.05. Fig. 3. Group-averaged SD of hip, knee, and ankle angular velocities in the AP (a) and ML (b) planes. The white bar indicates the knee OA group and the black bar indicates the control group. * P < 0.05.

482 Figures

Figure 1

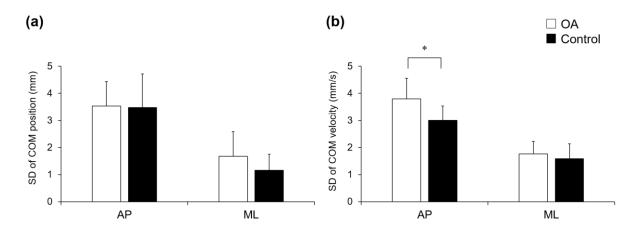


Figure 2

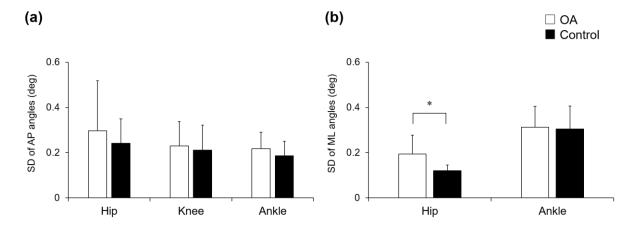


Figure 3

