



TITLE:

Latest progresses in ShUREX (2015-2017) data analyses

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RIGHT:

Latest progresses in ShUREX* (2015-2017) data analyses

(Estimation of kinetic energy dissipation rates from Pitot, CWT and radar data)

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*ShUREX: Shigaraki-UAV - Radar Experiment

Introduction to ShUREX campaigns


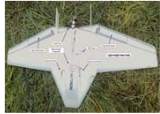
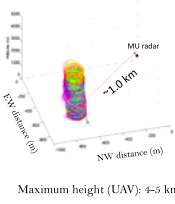
P.I.: Prof. Lakshmi Kantha (Colorado University, USA)



The ShUREX dream team!



Instrumental set up (2016, 2017)

MU Radar
5 beams (0°, 0°, (0°, 10°), (90°, 10°))

A **Datatahawk UAV** equipped with multiple sensors (Kantha et al., 2017).

Sensor type	CWT / Pitot
Sampling rate	800 Hz / 100 Hz

Number of useable flights (on Sep 2018): 39

Maximum height (UAV): 4-5 km

Acquisition time for one Doppler spectrum: 24.57 sec
Range sampling from 1.39 km to 20.35 km ($\Delta r = 150$ m)

Examples of UAV trajectories

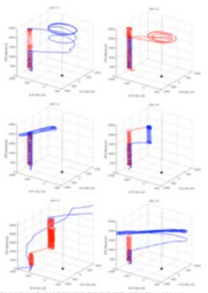
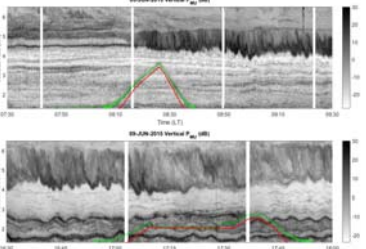



Figure 3: (a) Time-height cross-section of echo power P_{MU} (dB) at vertical incidence after doing the Capon processing in the height range 1.27-6.5 km from 07:30 LT to 09:30 LT on 05 June 2015. (b) Same as (a) from 16:30 LT to 18:00 LT on 09 June 2015.

Focus of the presentation

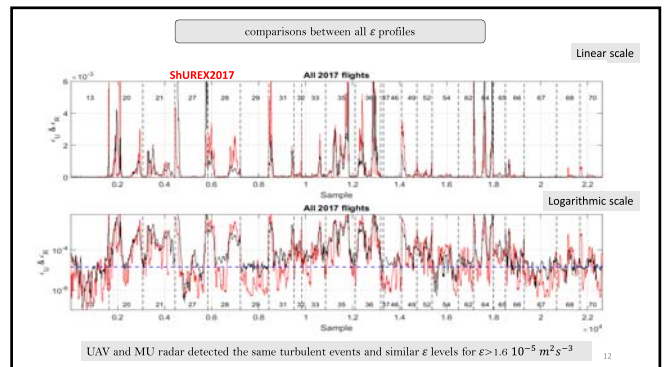
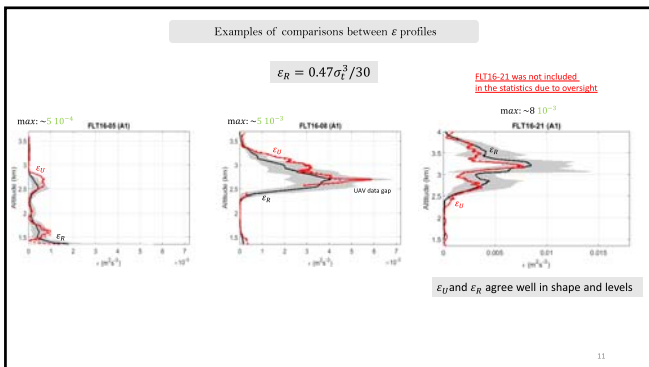
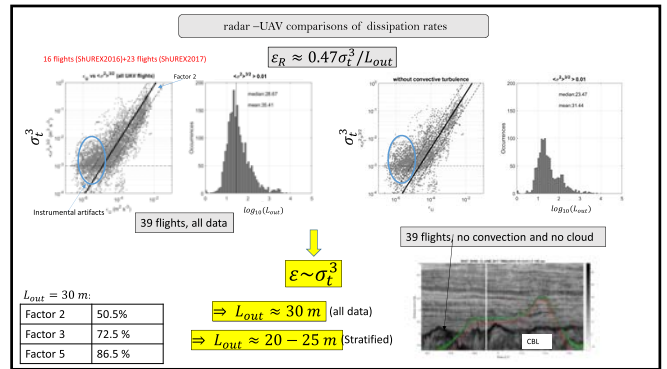
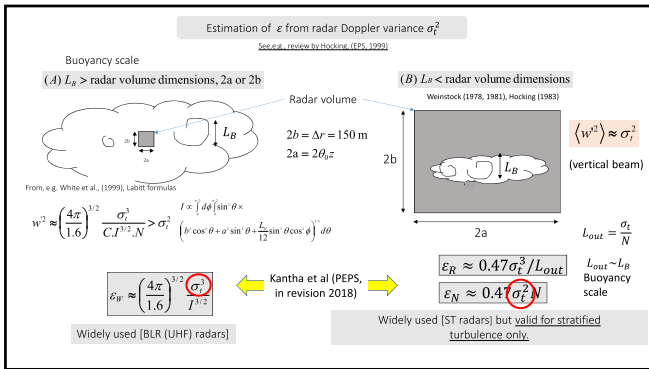
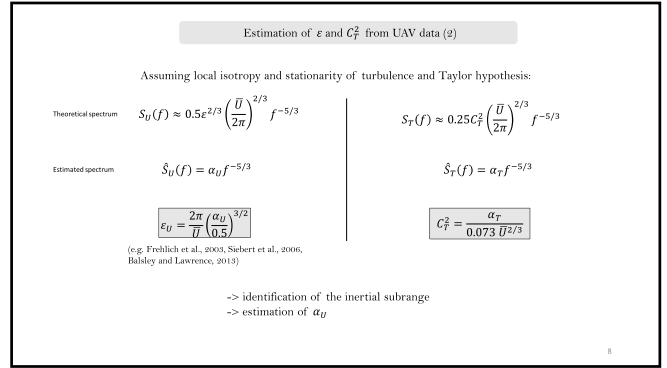
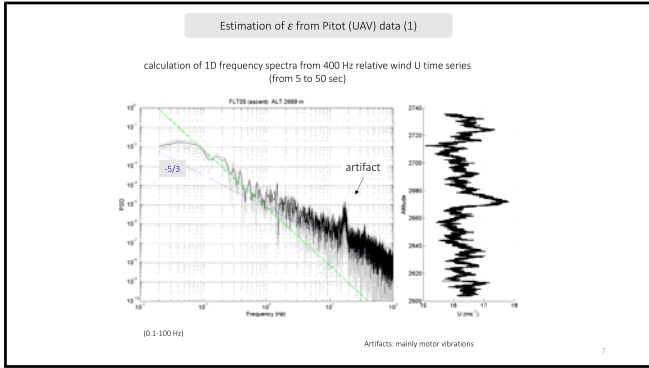
Comparing turbulence kinetic energy (TKE) dissipation rates ϵ estimated from:

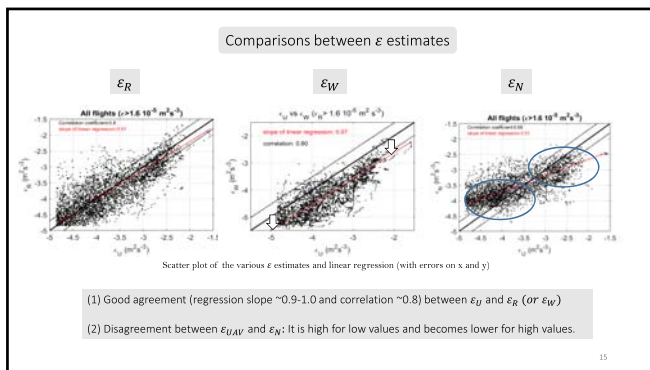
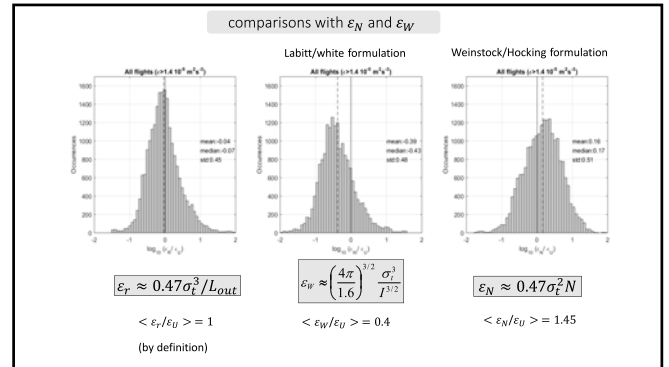
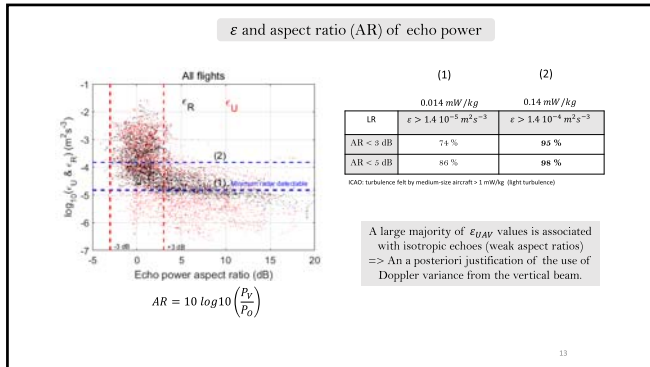
- (1) relative air speeds measured by Pitot sensor (UAV)
- (2) MU radar Doppler spectral width using various models
- (3) Temperature measurements by CWT sensors using a theoretical relationship between C_T^2 and ϵ

Part I

Part II

Part I: radar – Pitot comparisons





Conclusions of part I

- The UAV and radar captured the same turbulent events with peaks of ϵ and σ_t at the same altitudes and times => quantitative comparisons could be made.
- $\epsilon_{UAV} \sim \sigma^3 / L_{out}$ with $L_{out} \approx 30$ m. Energy dissipation rates can be estimated from the sole Doppler variance: at least in the lower troposphere
- The asymptotic models ϵ_W and ϵ_N provide quite consistent levels:
 $\epsilon_W \sim 0.4 \epsilon_{UAV}$, in average, slight underestimation but no bias,
 $\epsilon_N \sim 1.45 \epsilon_{UAV}$, in average, BUT overestimates for low values and underestimates for high values ($\sim > 0.3$ mW/kg)
- In addition, since ϵ_R and ϵ_W are relevant for turbulence generated by convections or shear flow instabilities but ϵ_N is applicable to stratified turbulence only, the Weinstock model may not be suitable at least for tropospheric data.

Part II: CWT – Pitot comparisons

Estimation of ϵ from C_T^2

For stratified turbulence (e.g. Ottersten, 1969; Gossard, 1982; Gavrilov et al. 2005):

$$\epsilon_{CT2} = \left(\gamma \frac{g^2 C_T^2}{T^2 N^2} \right)^{3/2}$$

Valid for dry or moist (unsaturated) air

$$\gamma = \frac{1 - P_r - Ri}{\beta_\theta - Ri} = \frac{1 - Rf}{\beta_\theta - Rf} \quad \beta_\theta = 3.2 \text{ (universal constant)}$$

Ri : Richardson number, P_r : Turbulent Prandtl number
 $Rf = Ri/P_r$: Flux Richardson number

Change in background potential energy due to mixing
Energy expended

Mixing efficiency coefficient:
 $\gamma_{Rf} \equiv Rf / (1 - Rf)$

1. It has long been understood that mixing efficiency is unlikely to be constant, but, because K_p from tracers and microstructure evaluated with $\gamma_{Rf} = \gamma_{m1} = 0.2$ agree better than do coefficients and efficiencies from simulations and experiments. Reasons for this agreement are not understood, particularly in view of the loss of po-

Gregg et al., 2018
Oceanic turbulence

