



TITLE:

# Retrieval of Temperature Profiles using Radio Acoustic Sounding System (RASS) with the Equatorial Atmosphere Radar (EAR) in West Sumatra, Indonesia

AUTHOR(S):

Juaeni, Ina; Tabata, Hiraku; Noersomadi; Halimurrahman; Hashiguchi, Hiroyuki; Tsuda, Toshitaka

---

CITATION:

Juaeni, Ina ...[et al]. Retrieval of Temperature Profiles using Radio Acoustic Sounding System (RASS) with the Equatorial Atmosphere Radar (EAR) in West Sumatra, Indonesia. 第12回MUレーダー・赤道大気レーダーシンポジウム (第379回生存圏シンポジウム) 2018: 37-40

ISSUE DATE:

2018-09

URL:

<http://hdl.handle.net/2433/269045>

RIGHT:

### Retrieval of Temperature Profiles using Radio Acoustic Sounding System (RASS) with the Equatorial Atmosphere Radar (EAR) in West Sumatra, Indonesia

Ina Juaeni<sup>1</sup>, Hiraku Tabata<sup>2</sup>, Noersomadi<sup>2,1</sup>, Halimurrahman<sup>1</sup>, Hiroyuki Hashiguchi<sup>2</sup> and Toshihisa Tsuda<sup>2</sup>

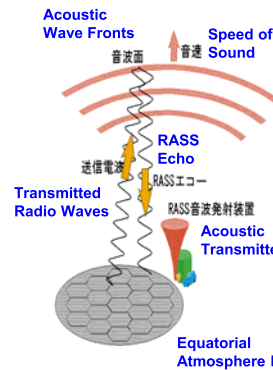
1: National Institute of Aeronautics and Space (LAPAN), Indonesia  
2: Research Institute for Sustainable Humanosphere (RISH), Kyoto University

Earth, Planets and Space, 70:22, doi:10.1186/s40623-018-0784-x, 2018.



We carried out **eight campaign observations in 2016**, testing the performance of EAR-RASS. We intensively analyzed the RASS results from **August 29 to September 3, 2016**, when **radiosondes were launched 12 times** from the EAR site.

### RASS (Radio Acoustic Sounding System)



- (1) To emit sound pulse by a high-power acoustic transmitter
- (2) Refractive index fluctuations are produced due to density perturbations caused by sound waves
- (3) To detect scattered echo from acoustic wave fronts (RASS echo), and to determine Doppler shift (sound speed)
- (4) From a relation; temperature  $\propto$  (sound speed)<sup>2</sup>, a temperature profile is obtained.

### RASS Observations

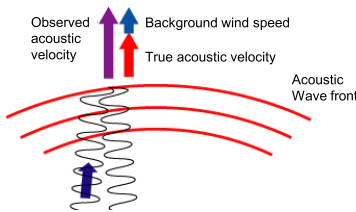
#### advection by wind

$$C_a = C_s + v$$

$C_a$ : Apparent sound speed  
 $C_s$ : True sound speed  
 $v$ : Wind speed

$$T_v = \left(\frac{C_a - v}{K_a}\right)^2$$

$T_v$ : Virtual temperature (K)  
 $K_a = 20.047$



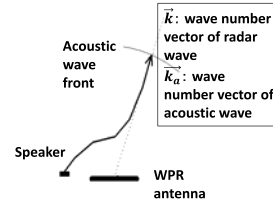
### Bragg condition

#### Bragg condition of RASS :

$$2\vec{k} = \vec{k}_a$$

$$(1): 2|\vec{k}| = |\vec{k}_a|$$

$$(2): \vec{k} // \vec{k}_a$$



- Condition (1)  
Because the temperature decreases along altitude, we need to select appropriate acoustic frequency that satisfies the condition (1).  
We employ the FM chirped signal that sweeps from 85 to 115 Hz to cover up to 20 km.
- Condition (2)  
As the acoustic propagation is affected by the background wind velocity and temperature,  $\vec{k}_a$  varies accordingly.  
We apply a ray-tracing technique to know the variation of  $\vec{k}_a$ .  
Antenna beam is steered into appropriate direction, considering the results of the ray-tracing

### Bragg condition to obtain strong RASS echoes

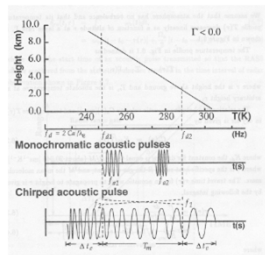
#### Bragg condition

acoustic wavefront

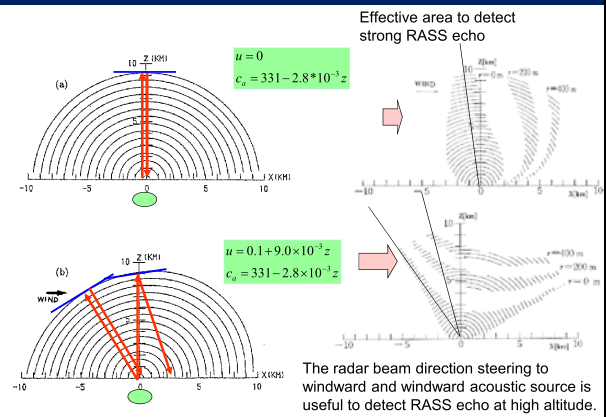
$$\lambda_a = \frac{c_a}{f_a} \propto \frac{\sqrt{T_v}}{f_a}$$

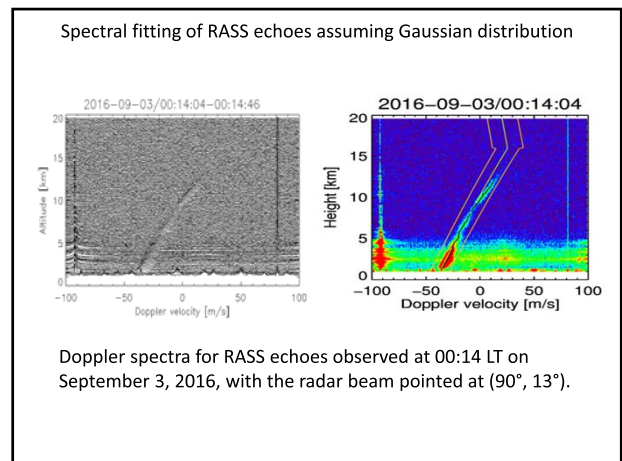
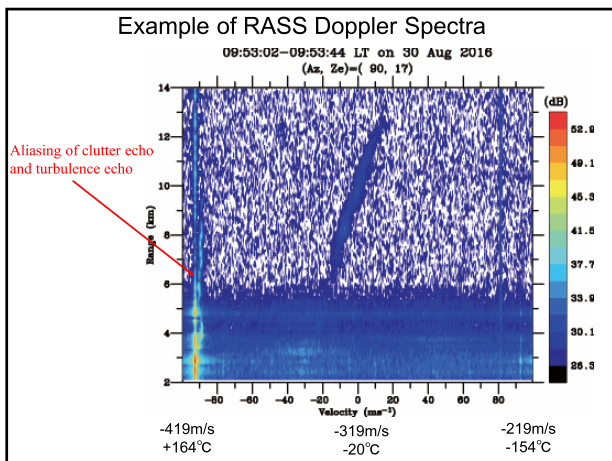
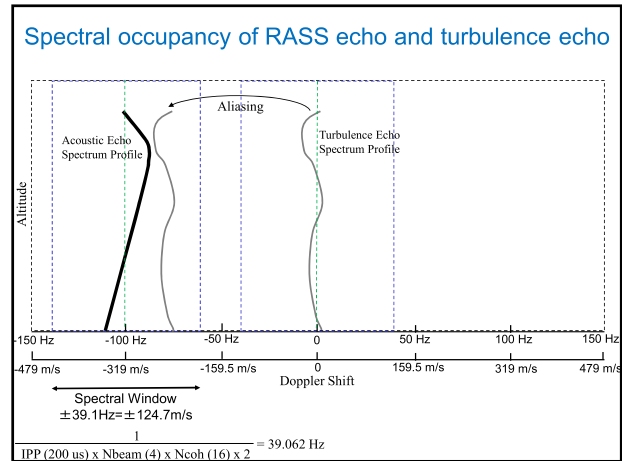
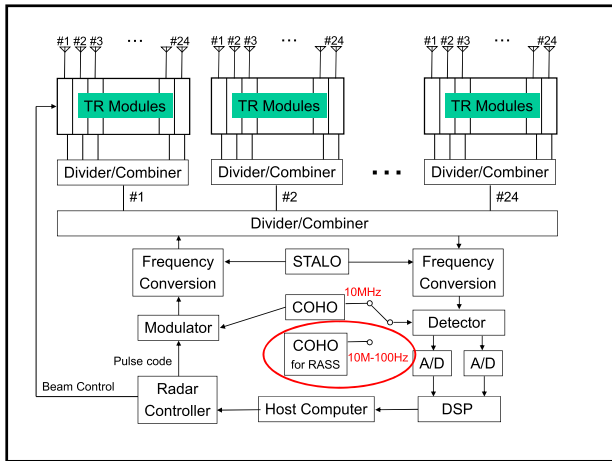
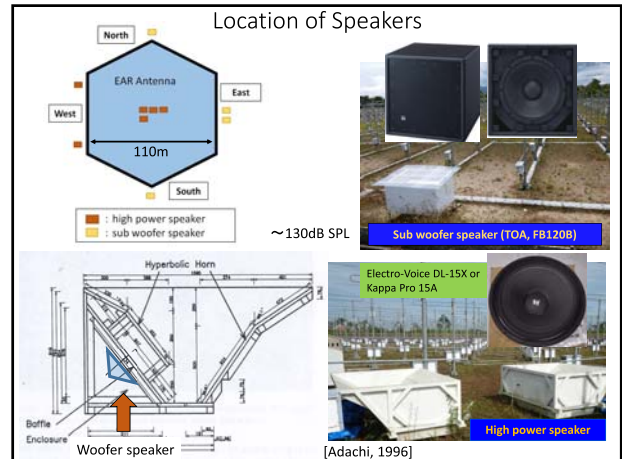
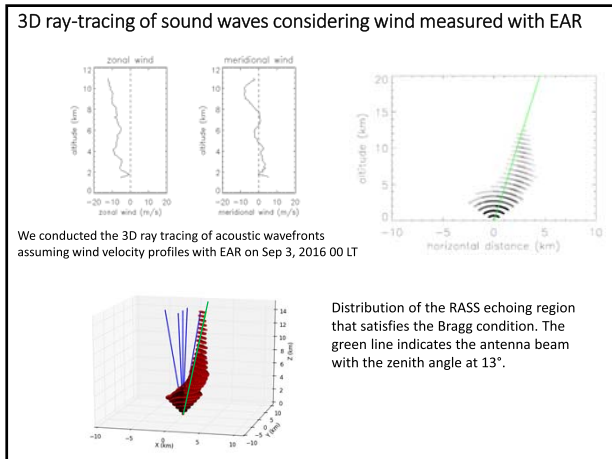
radar wavelength :  $\lambda_r$   
acoustic wavelength :  $\lambda_a$   
 $\lambda_r = 2\lambda_a$

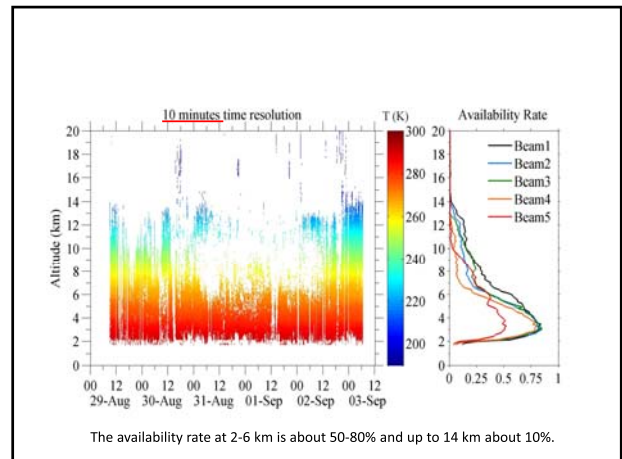
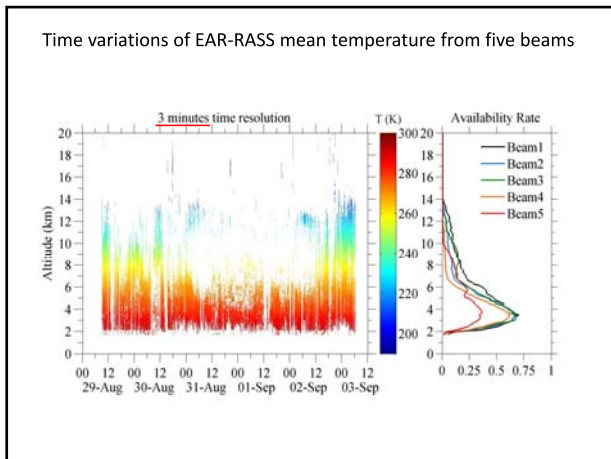
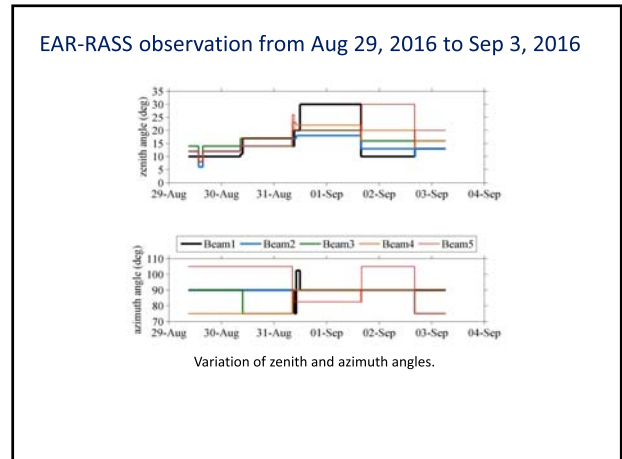
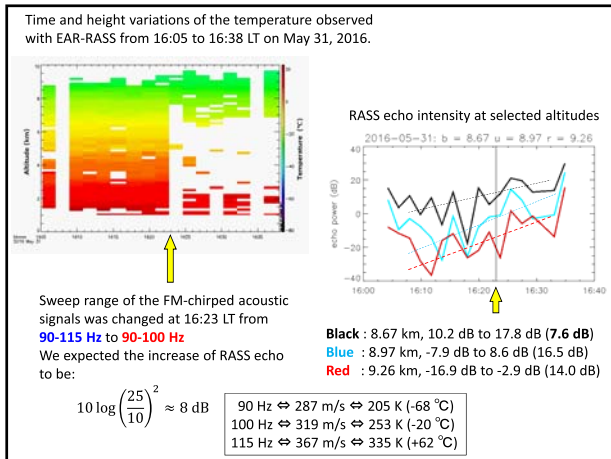
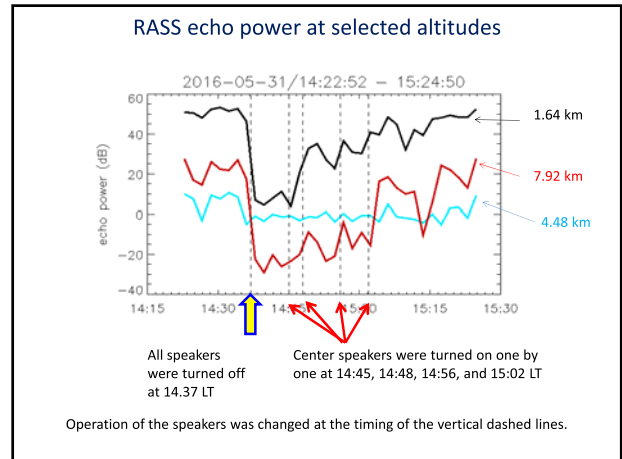
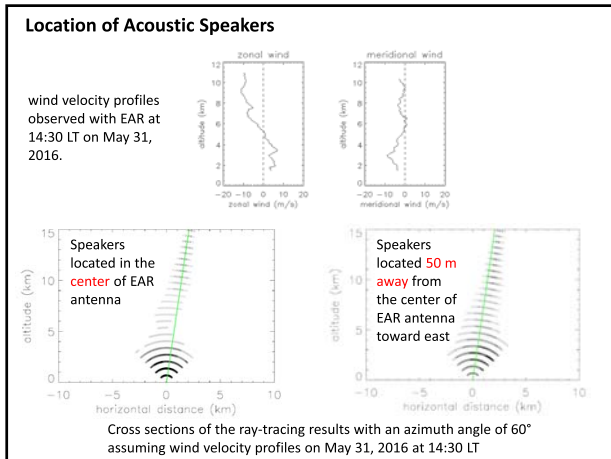
FM-chirped sound is used to satisfy the Bragg condition in a wide height range

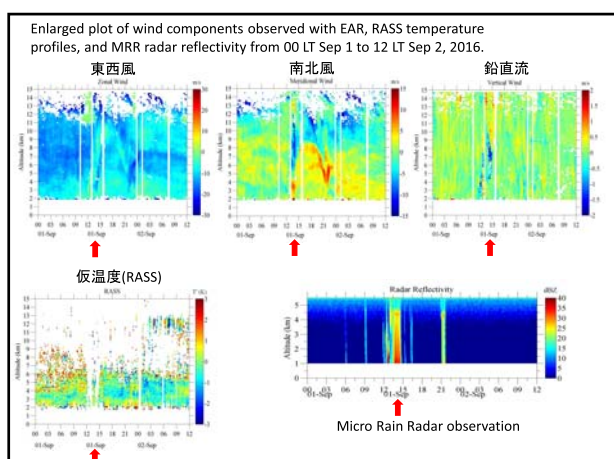
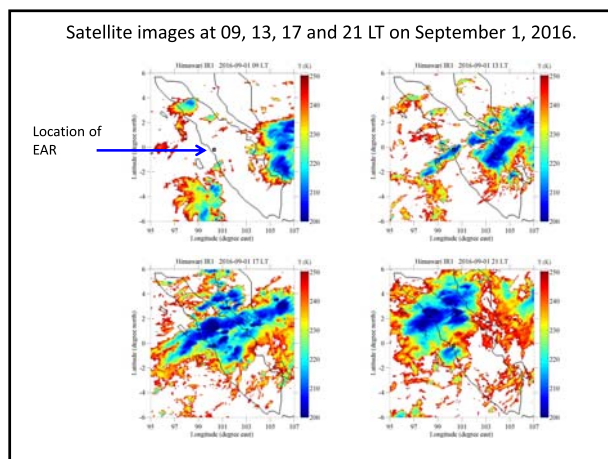
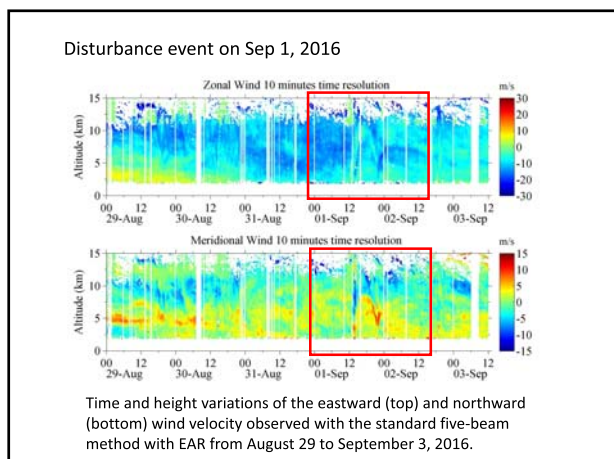
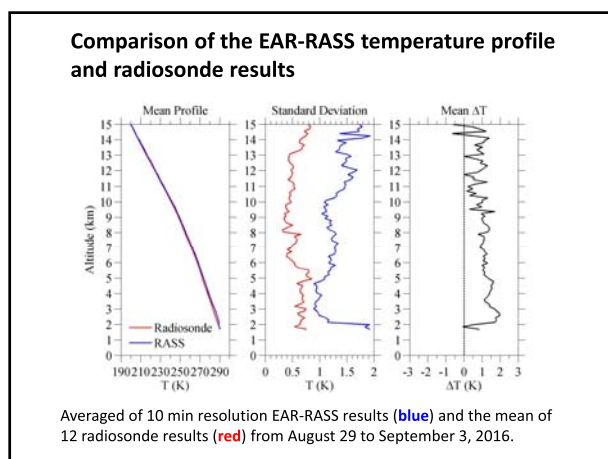
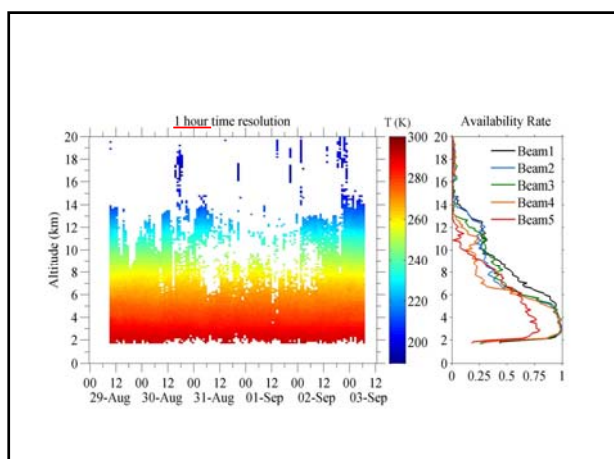


### Modulation of acoustic wave front by wind









### Concluding remarks

- We carried out EAR-RASS observations during 2016 and examined the Bragg condition of RASS echoes.
- We adopted the 3-D ray tracing of acoustic waves for determining the appropriate antenna directions for obtaining RASS echoes.
- We investigated the acoustic sources, including the location of speakers and the sweep frequency range of the FM-chirped acoustic signals. The speakers located in the center of the EAR antenna were most effective, but speakers outside the antenna were also useful for obtaining the RASS echoes in the lower altitudes when the wind velocity became large.
- The RASS temperature with 10-min resolution was determined at 2–6 km with 50–80% availability, and up to about 14 km with about 10% availability.
- The standard deviation from the mean temperature difference was about 0.4 K.
- We found a few interesting meteorological disturbances that occurred between August 30 and September 1, 2016. A preliminary report was presented on the behavior of the wind velocity and temperature variations in association with the rain data and satellite images on September 1.