

Some research results of the DICE project

<http://www.dice-consortium.fr/>

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OUTLINE

1 - The DICE project at a glance

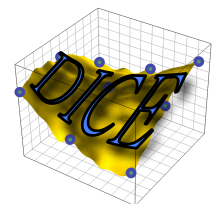
- Organization and partners
- Scientific production and R packages

2 - Overview of the methodological issues

- Spotlight on 9 topics

3 - Focus I: Construction of Space-Filling Designs

4 - Focus II: Approximation of a target region



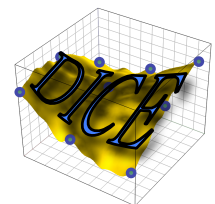
DICE project – The participants

Academic participants

- Mines St-Etienne (ARMINES/3MI - size \approx 5) **PROJ. LEADER**
- Université Paul Cézanne (LMRE Pr. Michelle Sergent)
- Université d'Orsay (Pr. Georges Oppenheim)
- Université Joseph Fourier (Pr. Anestis Antoniadis)

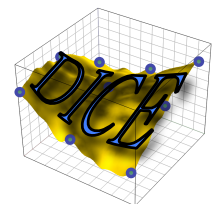
Industrial partners

- TOTAL – *petroleum*
- EDF – *electricity, nuclear engineering*
- IRSN – *nuclear engineering*
- Renault – *automotive*
- ONERA – *aerospatial*



DICE project – General description

- 3 years project – Dec 2006 to Dec 2009
- Topic: analysis of time-consuming computer codes
- Sequenced in 6-months research periods
- Steering committee (2 days)
 - 1.5 days: presentation of scientific results
 - 0.5 days: organization & case studies def.
- Ticket for each “industrial” partner



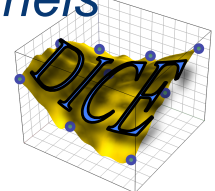
DICE project – Outputs (1/2)

- Defended PhD thesis

- J. Franco, *research engineer at Total*
 - *Keywords: design of computer experiments, SFDs*
- D. Ginsbourger, *ass. Prof. at Bern University*
 - *Keywords: metamodelling, Kriging-based optimization*
- V. Picheny, *post-doc. at Ecole Centrale de Paris*
 - *Keywords: metamodelling, Reliability*

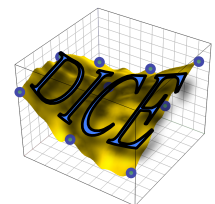
Outstanding:

- B. Gauthier, *EMSE, started in 2007*
 - *Keywords: RKHS, Continuous constraints*
- N. Durrande, *EMSE, started in 2008*
 - *Keywords: Dimension reduction, Additive functions, Kernels*



DICE project – Outputs (2/2)

- \approx 10 publications
- 30 internal research reports – *restricted access*
- 4 R packages
 - DiceDesign, DiceKriging, DiceOptim, DiceEval
 - Now published on CRAN, <http://cran.r-project.org/>
 - Supplementary materials
 - General presentation in preparation
 - Vignette for DiceKriging&DiceOptim, www.emse.fr/~roustant

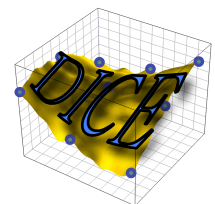


DICE project – “Closing” conference

- At least another conference dedicated only to computer experiments!

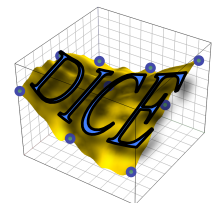


- Link: <http://www.emse.fr/enbis-emse2009/>



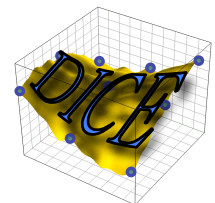
DICE project – Publications list (1/3)

1. Sergent M., Dupuy D., Corre B., Clayes-Bruno M., Comparaison de méthodes de criblage pour la simulation numérique, HAL,
<http://hal.archives-ouvertes.fr/inria-00386602/fr/>
2. Franco J., Bay X., Dupuy D. et Corre B. (2008), Planification d'expériences numériques à partir du processus ponctuel de Strauss, HAL,
<http://hal.archives-ouvertes.fr/hal-00260701/fr/>
3. Ginsbourger D., Dupuy D., Badea A., Roustant O. et Carraro L. (2009), A note on the choice and the estimation of Kriging models for the analysis of deterministic computer experiments, *Applied Stochastic Models for Business and Industry*, **25** (2), 115-131.
4. Ginsbourger D., Helbert C. et Carraro L. (2008), Discrete mixtures of kernels for Kriging-based optimization, *Quality and Reliability Engineering International*, **24** (6), 681-691.
5. Ginsbourger D., Le Riche R. et Carraro L., A Multi-points Criterion for Deterministic Parallel Global Optimization based on Gaussian Processes, *Journal of Global Optimization*.



DICE project – Publications list (2/3)

6. Helbert C., Dupuy D. et Carraro L. (2009), Assessment of uncertainty in computer experiments : from Universal to Bayesian Kriging, *Applied Stochastic Models for Business and Industry*, **25**, 99-113.
7. Picheny V., Ginsbourger D., Roustant O., Haftka R.T. et Kim, N.-H., Adaptive Designs of Experiments for Accurate Approximation of Target Regions, to appear in *Journal of Mechanical Design*.
8. Ginsbourger D., Bay X. et Carraro L., Noyaux de covariance pour le Krigeage de fonctions symétriques, to appear in *C. R. Acad. Sci. Paris, section Maths*.
9. Pujol G. (2009), Simplex-based screening designs for estimating metamodels, *Reliability Engineering and System Safety*, **94**, 1156-1160.
10. Roustant O., Franco J., Carraro L. et Jourdan A. (2010), A radial scanning statistic for selecting space-filling designs in computer experiments, in A. Giovagnoli, A.C. Atkinson, B. Torsney (éditeurs) et C. May (editeur) "mODa 9 – Advances in Model-Oriented Design and Analysis, Contributions to statistics", Springer (Physica-Verlag), p. 189-196.



DICE project – Publications list (3/3)

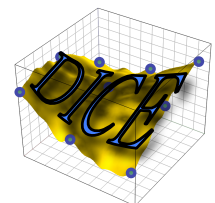
Submitted or in preparation

J. Franco, X. Bay, B. Corre and D. Dupuy, "Strauss Processes: A new approach in Computer Experiments"

D. Dupuy, C. Helbert, J. Franco, "DiceDesign and DiceEval: new R packages for Design and Analysis of Computer Experiments." In preparation.

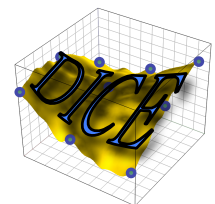
O. Roustant, D. Ginsbourger, Y. Deville, "DiceKriging, DiceOptim: two R packages for the analysis of computer experiments by kriging-based metamodeling and optimization", submitted to Journal of Statistical Software,

<http://hal.archives-ouvertes.fr/hal-00495766/fr/>



PART I

- General overview

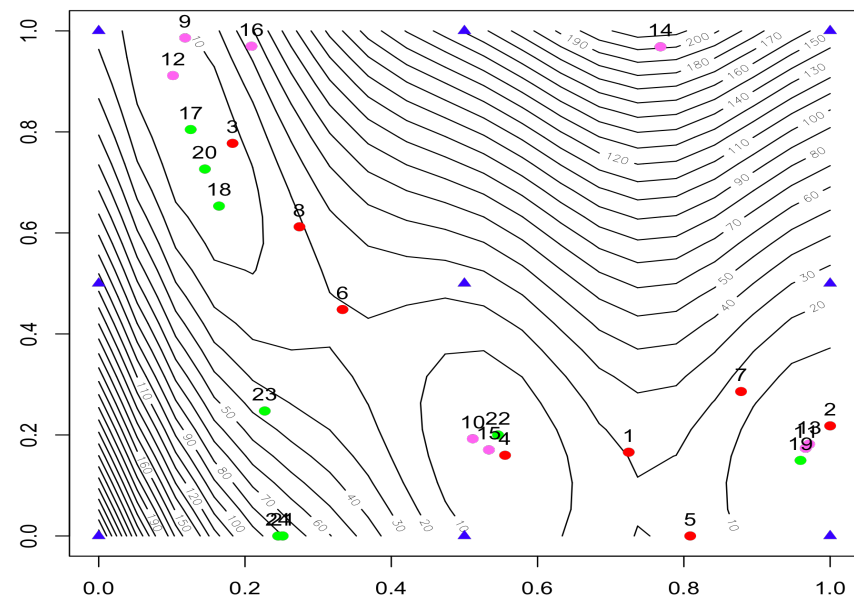


General overview – Kriging-based Optimization

- Extension of EGO method for parallel computing

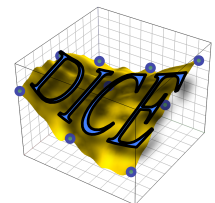
- EGO method: EI criterion with analytical gradient, EI maximization with a genetic algorithm
- Parallel computing: Constant liar heuristic, multipoints EI

3 iterations of Constant Liar with 8 parallel searches



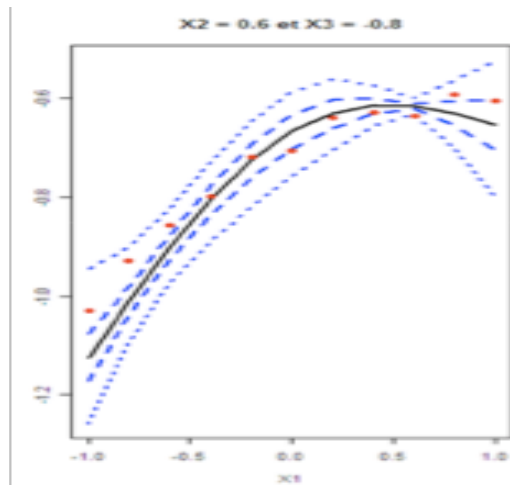
Related package: DiceOptim

Scientific production. R Package « *DiceOptim* », D. Ginsbourger thesis (part I & III), 1 deliverable, 2 publications ([4], [5]).



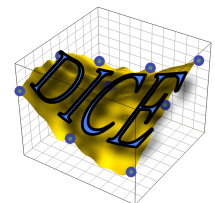
General overview – Uncertainty propagation

- Uncertainty propagation in a Bayesian framework
- Bayesian interpretation of Universal Kriging



- UK formulas can be obtained assuming an improper uniform prior for beta... but constant variance and correlation
- Get informative priors from a degraded simulator. Test and comparison on a 3D case study

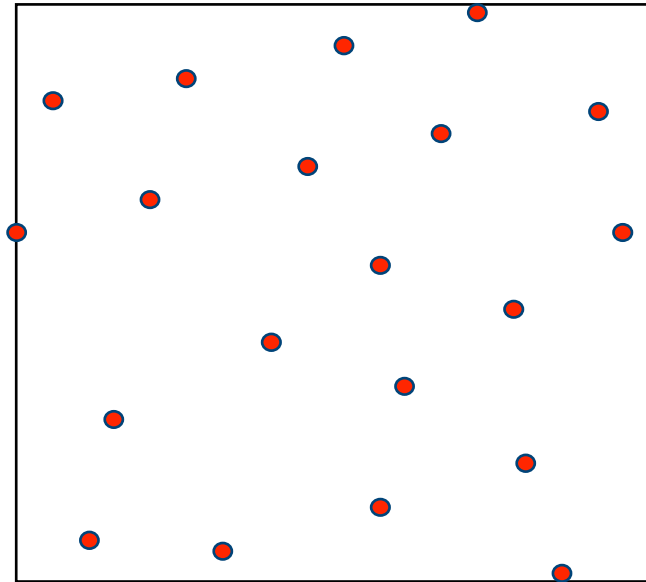
Scientific production. 1 deliverable, 1 publication ([6])



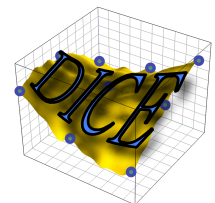
General overview – Design of experiments (1)

- Construction of space-filling designs for a first investigation with Strauss point processes

-> see focus I

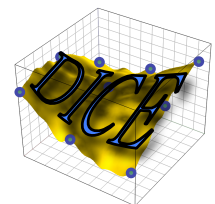
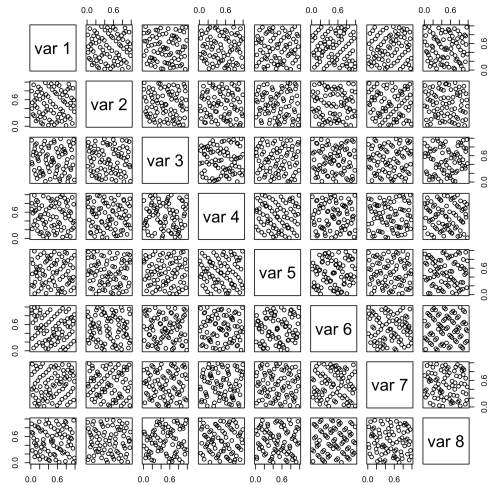


Related package: DiceDesign



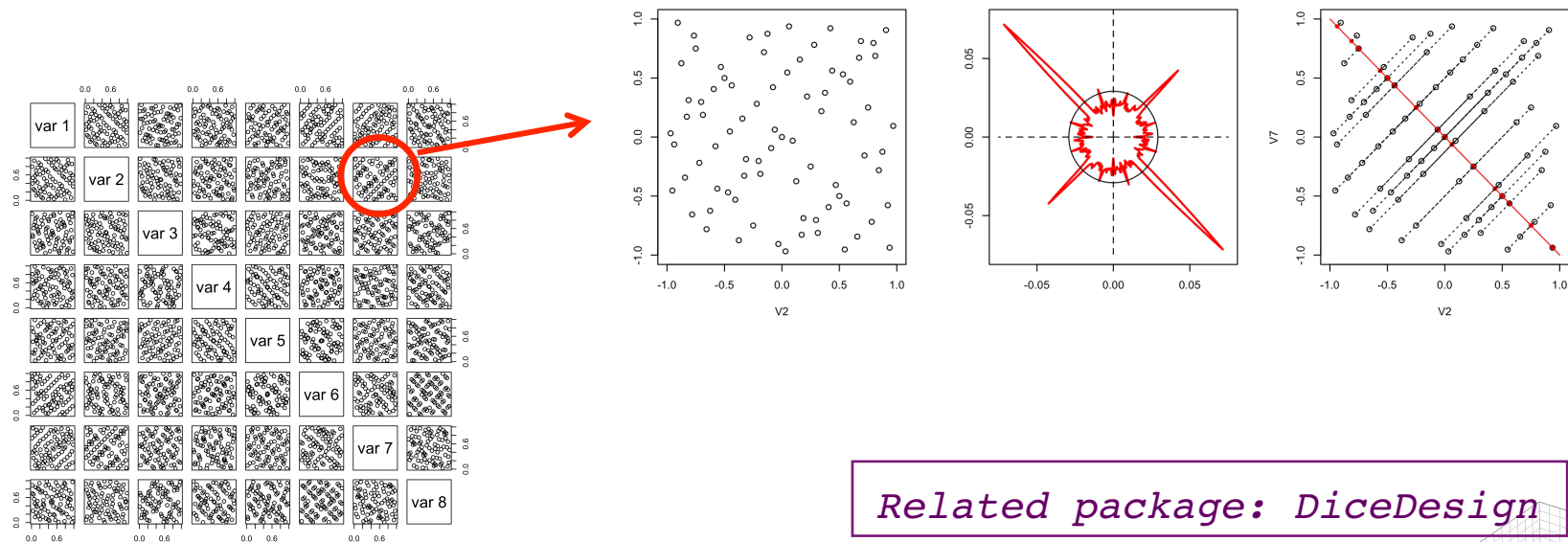
General overview – Design of experiments (2)

- Evaluation and selection of SFDs designs with the Radial Scanning Statistic
 - Fact: dimension reduction techniques \rightarrow variables of the form $\beta'x \rightarrow$ we want more than good properties onto marginals
 - Aim: check automatically good properties of SFDs onto oblique directions

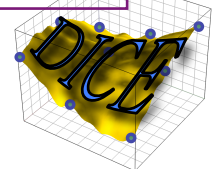


General overview – Design of experiments (2)

- Evaluation and selection of SFDs designs with the Radial Scanning Statistic
 - Underlying maths: law of a sum of uniforms, GOF tests for uniformity based on spacings



Related package: DiceDesign

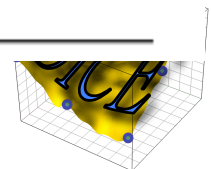


General overview – Design of experiments (2)

- Evaluation and selection of SFDs designs with the Radial Scanning Statistic
 - Comparison of 80-point 8D SFDs

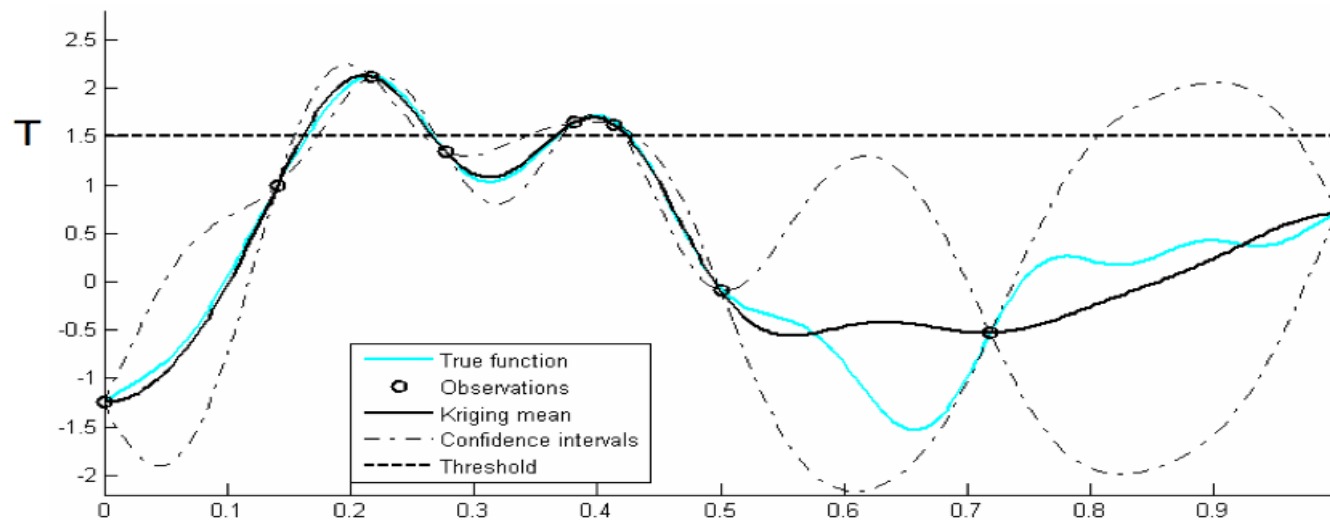
Table 1 Worst value of Greenwood statistic for 8-dimensional SFDs of size 80

Design type ^a	Statistic value ^b
Uniform	0.039 (0.003)
Maximin Latin hypercube	0.048
<u>Audze-Eglais Latin hypercube</u>	0.037
<u>Halton sequence</u>	0.244
Faure sequence	0.161
Sobol sequence	0.101
<u>Sobol sequence, with Owen scrambling</u>	0.041 (0.006)
<u>Sobol sequence, with Faure-Tezuka scrambling</u>	0.088 (0.010)
<u>Sobol sequence, with Owen + Faure-Tezuka scrambling</u>	0.041 (0.006)
<u>Strauss</u>	0.040 (0.004)

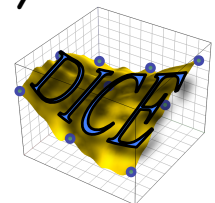


General overview – Design of experiments (3)

- Adaptive designs for the approximation of a target region
-> *see focus II*



Scientific production. R package « DiceDesign », J. Franco thesis, V. Picheny thesis (chapter 5), 1 deliverable, 3 publications ([2], [7], [10])

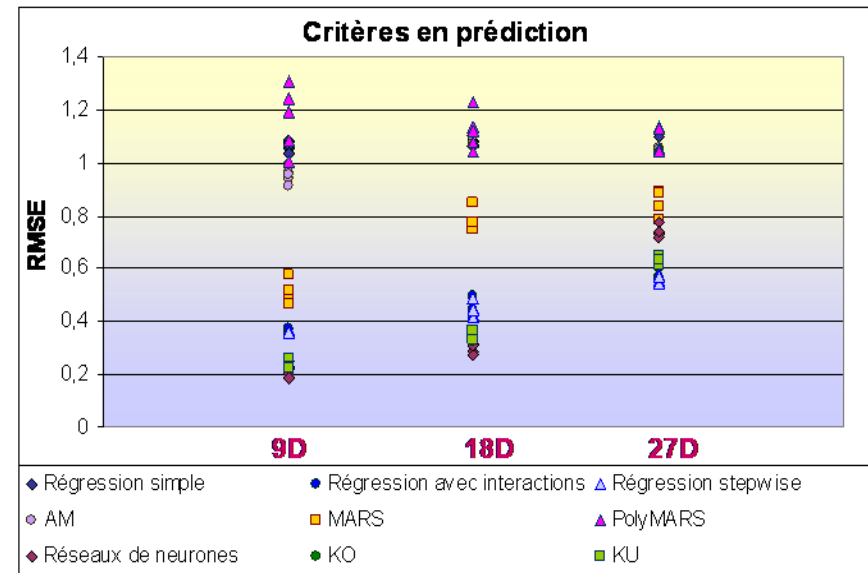


General overview – Kriging & other metamodels (1)

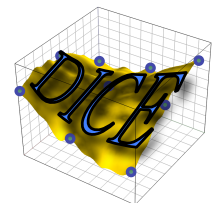
- Comparison of some famous metamodels
- Various case studies (mostly internal)

- Kriging
- Linear regression
- MARS, polyMARS
- Neural networks
- Additive models

- Case studies for d-dimensional problems ($1 \leq d \leq 30$)

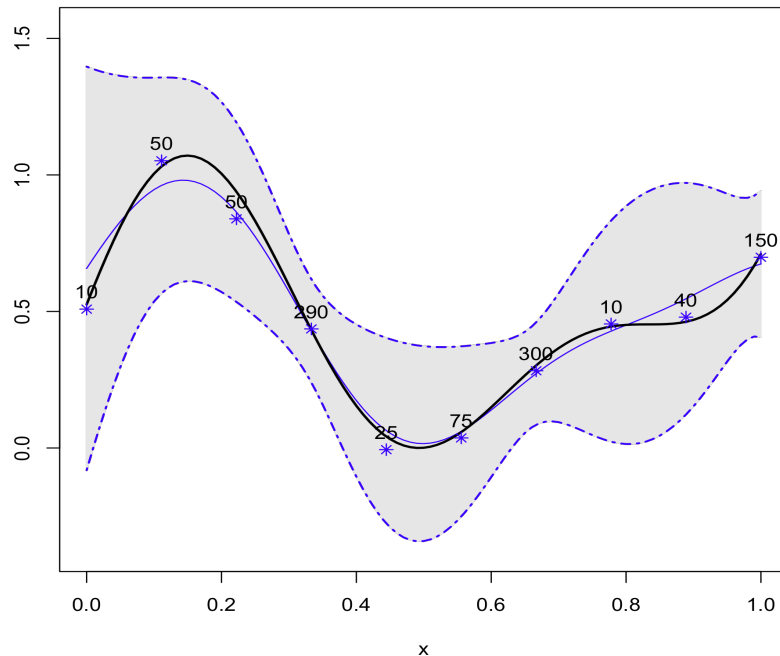


Related packages: DiceKriging, DiceEval



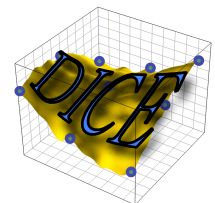
General overview – Kriging & other metamodels (2)

- Case of stochastic simulators



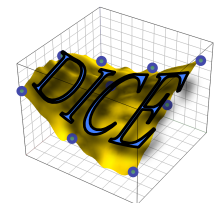
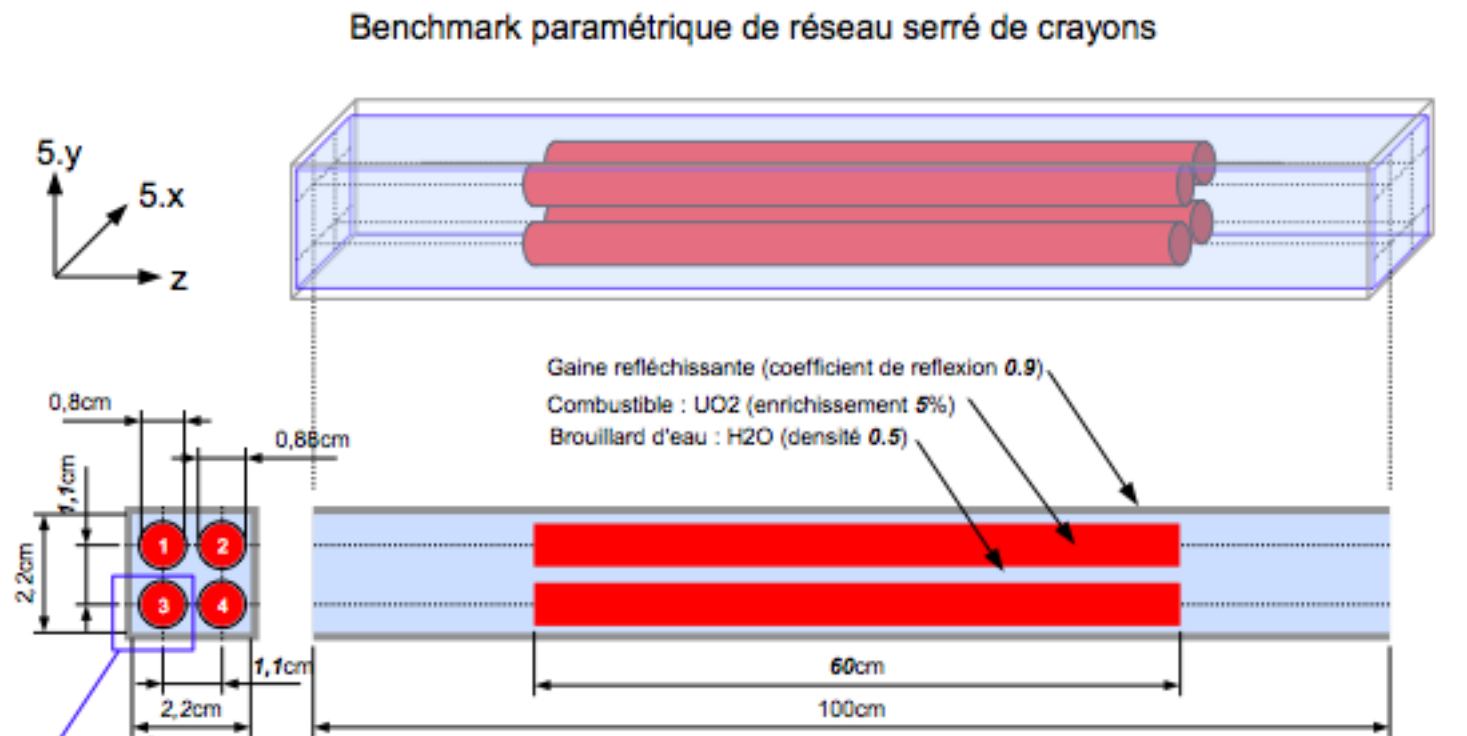
- Adaptation (and implementation) of Kriging for noisy observations
- First answer to the question: given a total budget, how do we distribute runs?

Related package: DiceKriging



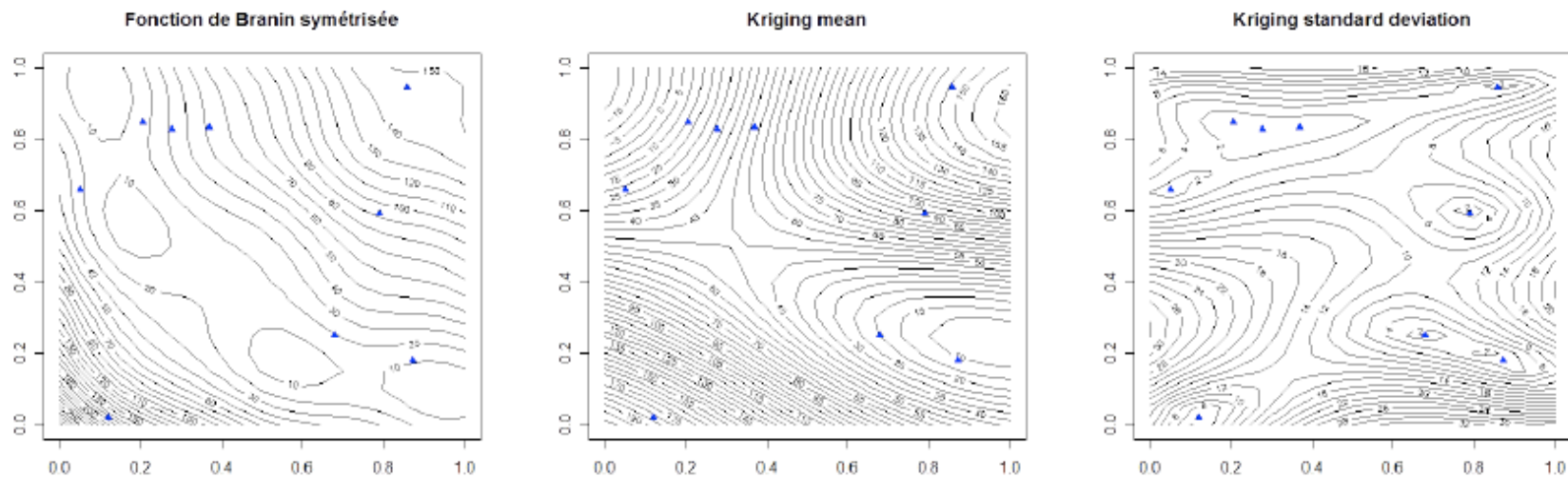
General overview – Kriging & other metamodels (3)

- Taking into account additional information
 - Example: symmetries with a suitable kernel

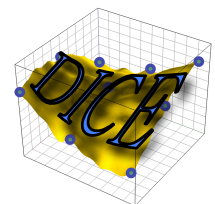


General overview – Kriging & other metamodels (3)

- Taking into account additional information
 - Example: symmetries with a suitable kernel

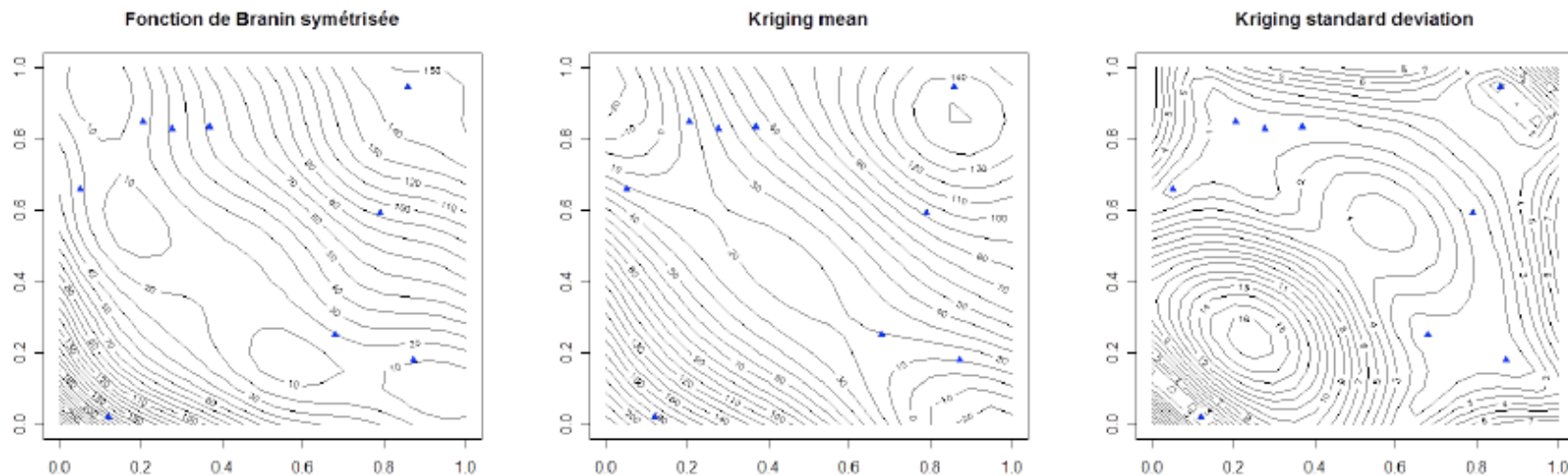


Gaussian covariance, 9-point design – IMSE over a 21-point test design: **820.93**



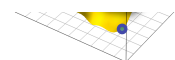
General overview – Kriging & other metamodels (3)

- Taking into account additional information
 - Example: symmetries with a suitable kernel



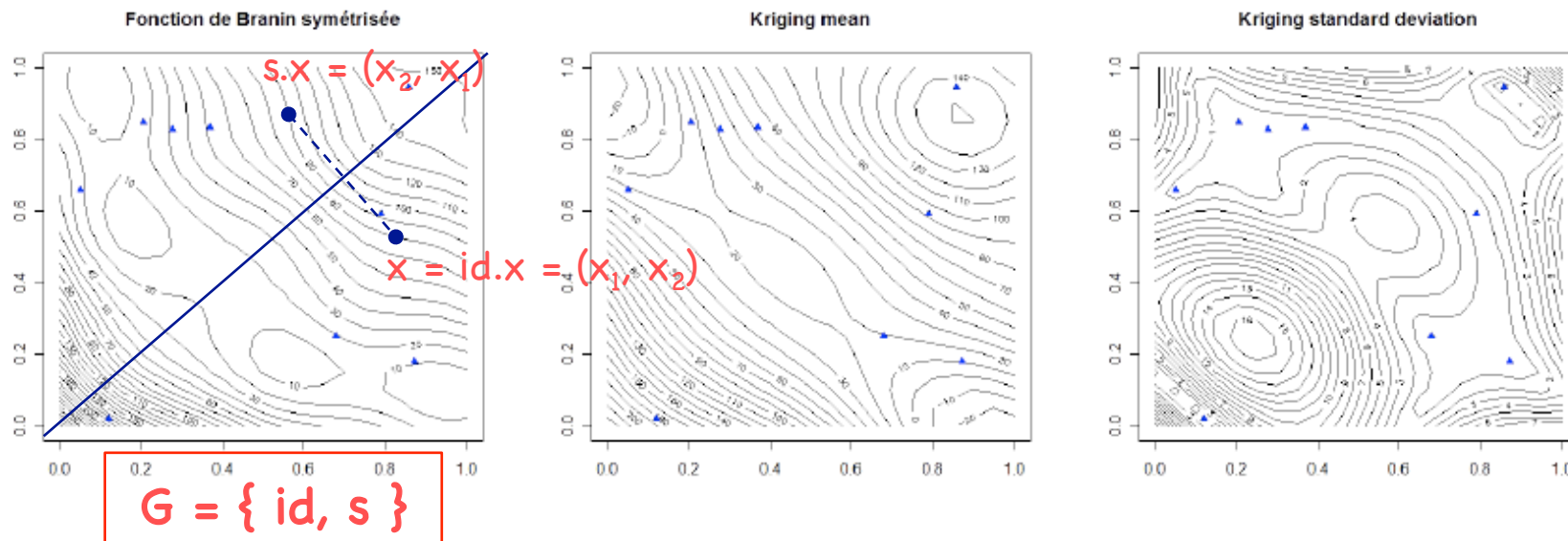
Symmeterized Gaussian covariance, 9-point design – IMSE : **330.26**

Scientific production. R packages DiceEval & DiceKriging, thesis: D. Ginsbourger (part II) & V. Picheny (chapter 6), B. Gauthier, N. Durrande, 2 deliverables, 2 publications ([3], [8]).



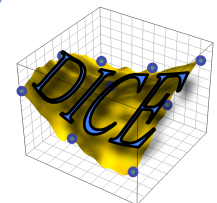
General overview – Kriging & other metamodels (3)

- Taking into account additional information
 - The underlying maths



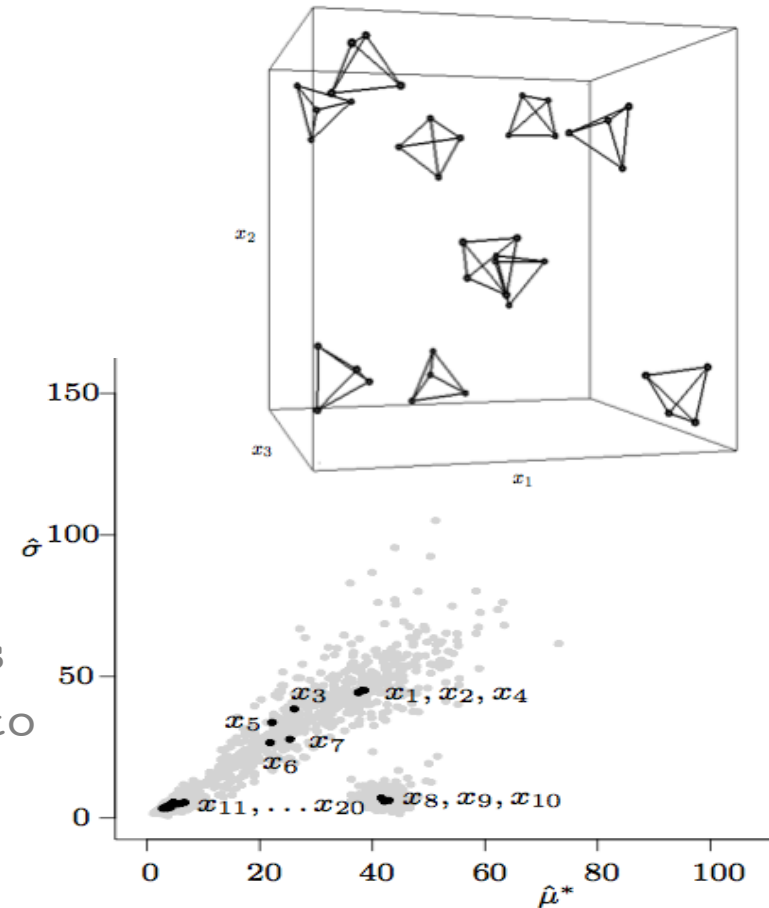
Symmeterized Gaussian covariance, 9-point design – IMSE : 330.26

$$Y_x = \sum_{g \in G} z_{g.x} \quad \Longrightarrow \quad k_Y(x, x') = \sum_{(g, g') \in G^2} k_Z(g.x, g'.x')$$

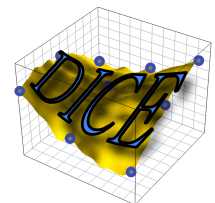


General overview – Screening & Sensitivity Analys.

- A bibliography study
+ An original method
- Simplex-based screening designs
 - Few model assumptions (in the same spirit as Morris)
 - The design can be re-used for modeling (the sample size does not collapse in projection onto subspaces)



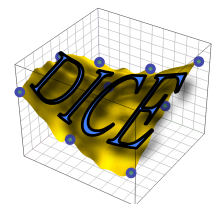
Scientific production. 2 deliverables, 2 publications ([1], [9]).



PART II

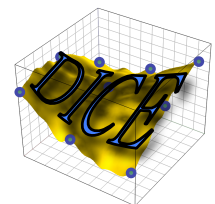
- Focus I

Construction of Space-Filling Designs



Strauss designs - Objectives

- First investigation of a costly simulator
 - Space Filling Designs
- Good behavior on projections
 - Randomness reduces « aliasing » phenomenons
- Construction of designs with a fixed number of experiments
 - e.g. Wooton, Sergeant, Phan-Tan-Luu designs



Strauss designs - Algorithm and example

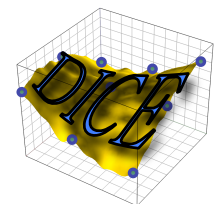
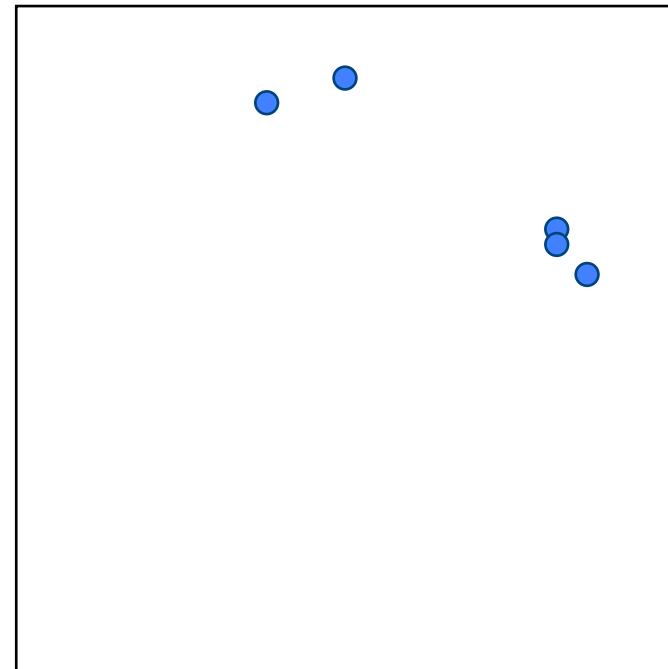
- Initial design : 5 points in the unit square $[0,1]^2$

Objective

Iterative construction of a

« well distributed » new population

System of interacting particles (repulsion)



Strauss designs – Example, first iteration

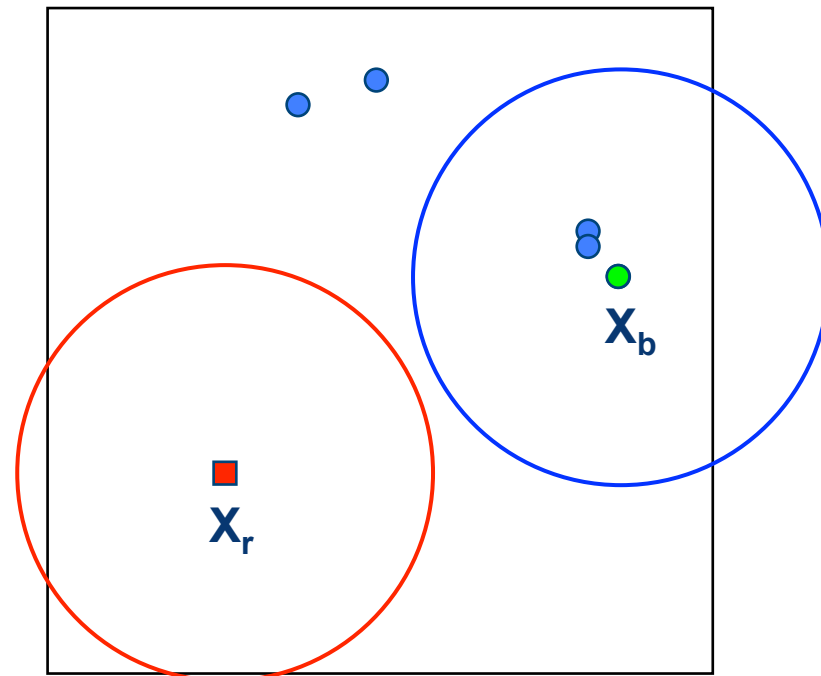
We choose a blue point X_b (he becomes green) and introduce a new random (red) point X_r .

New point is accepted with probability 1 if :

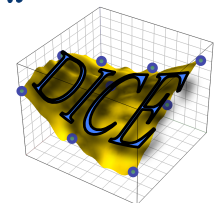
$$n(S_{X_r}) \leq n(S_{X_b})$$

Otherwise, acceptance probability of X_r is given by :

$$\gamma^{n(S_{X_r}) - n(S_{X_b})}$$

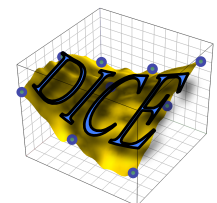
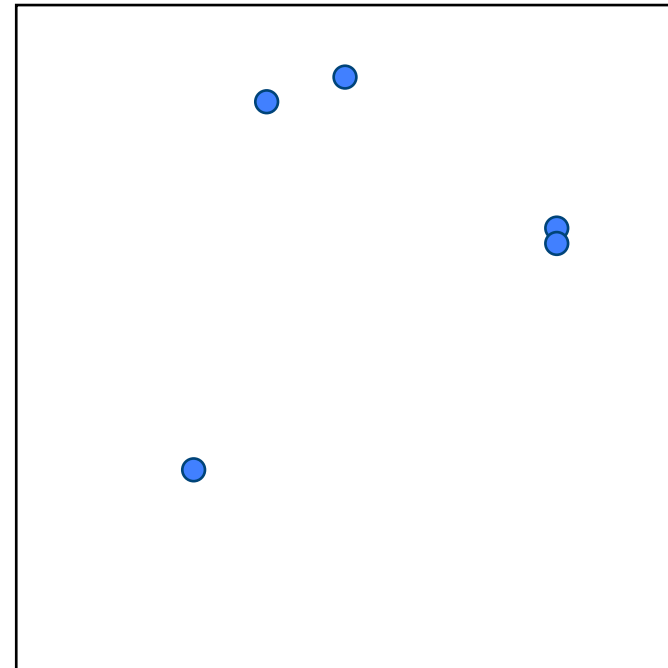


$n(S_x)$ is the number of points in a ball of radius R centered on X .



Strauss designs - Example, after first iteration

Here is the new design



Strauss designs – Example, second iteration

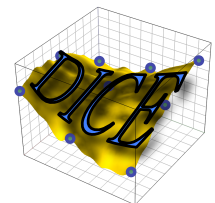
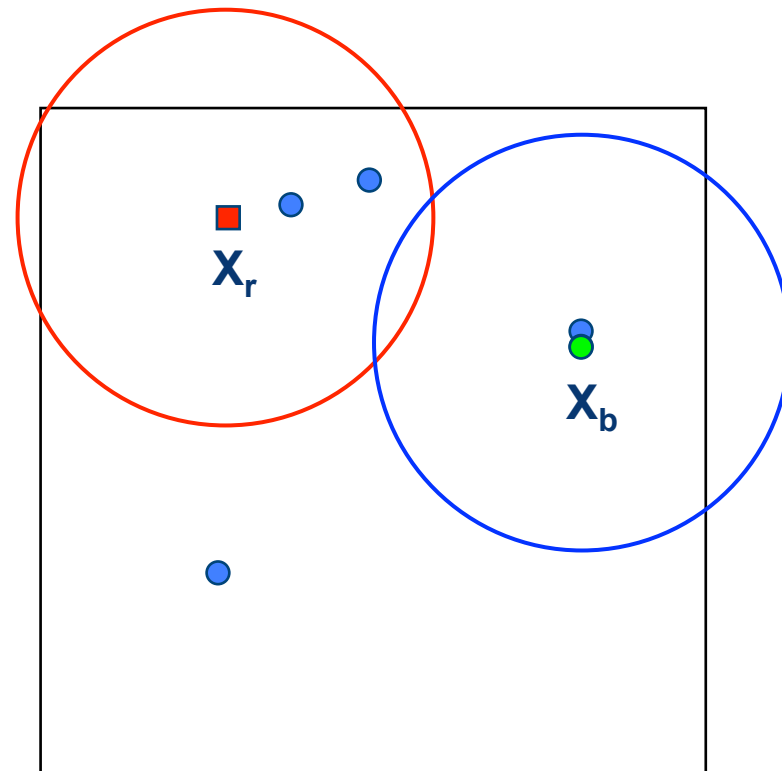
New iteration

Interaction between X_r and X_b

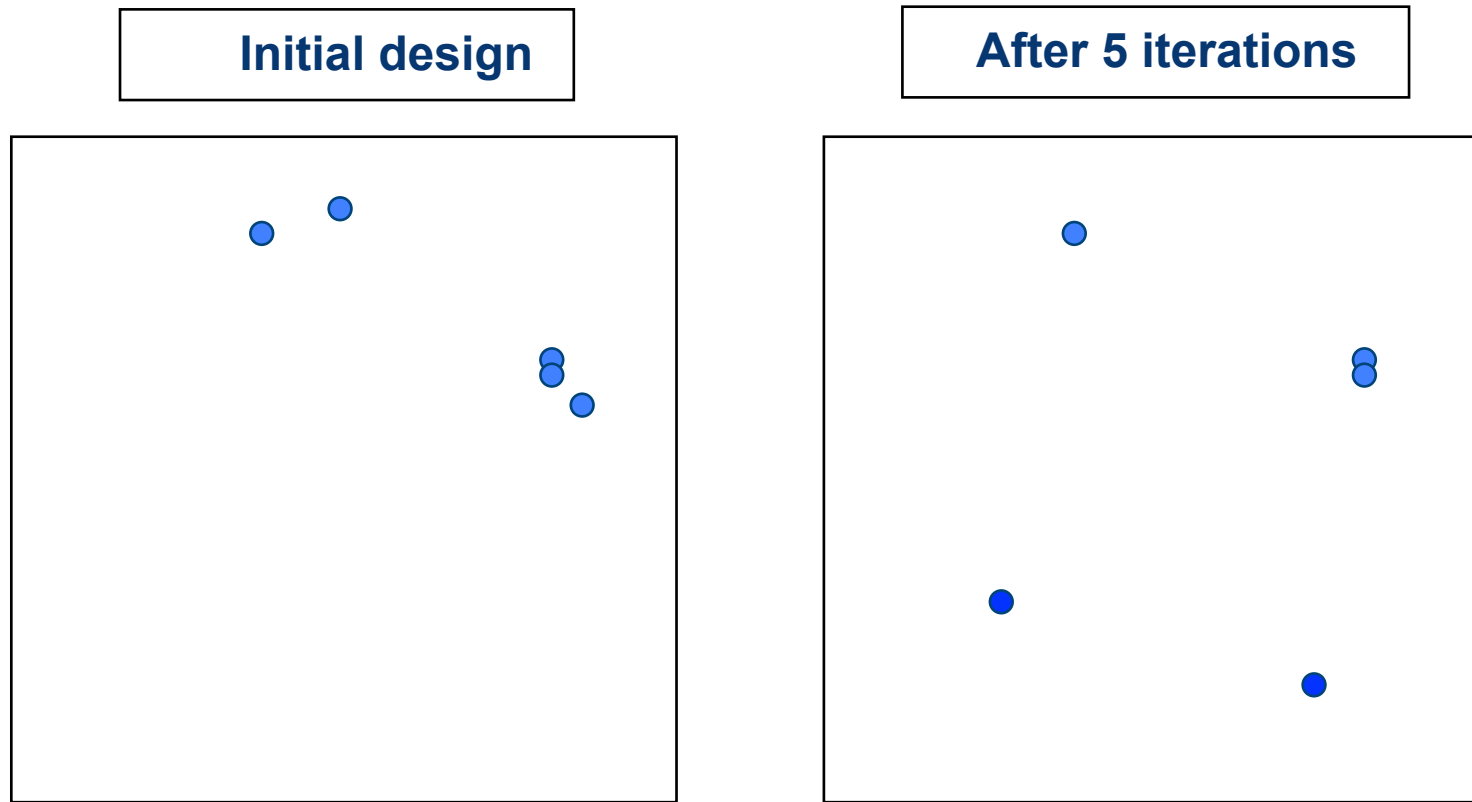
For $\gamma = 0.1$

Acceptance probability of X_r is 0.1
(γ^{2-1}).

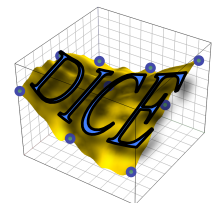
Here, X_r is rejected.



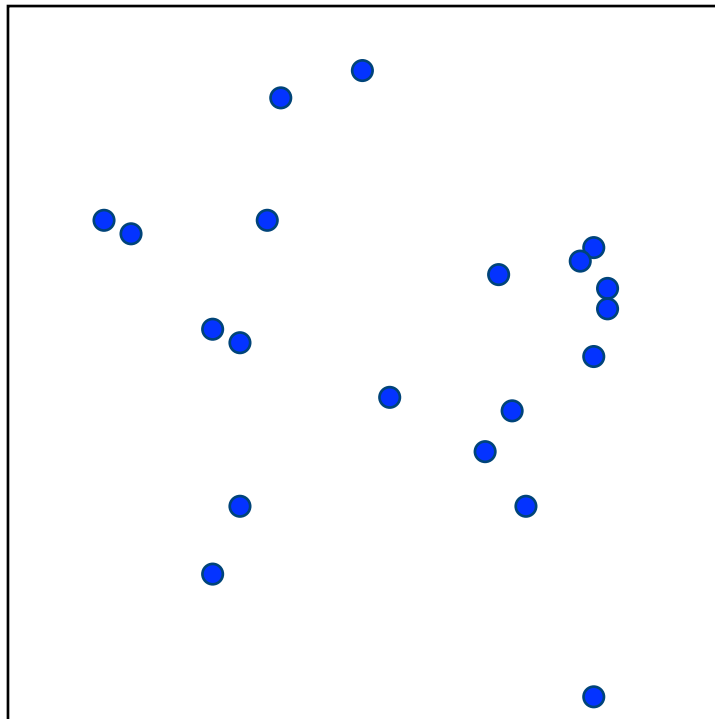
Strauss designs – Example, after 5 iterations



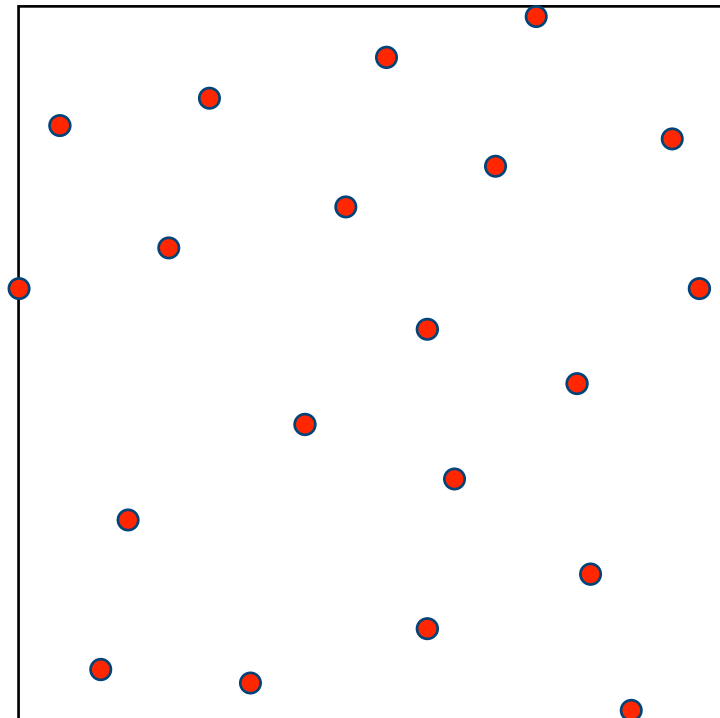
Here, only two points have been changed.



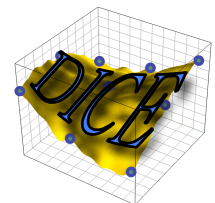
Strauss designs - A more realistic example



Initial design



Stationnary state



Strauss designs – Mathematical framework

The pdf of a Strauss design is, conditionally to the number of points in the hypercube is given by :

$$x = (x_1, \dots, x_N), x_i \in \mathbb{R}^d$$
$$f(x_1, \dots, x_N) = c\gamma^{S(x)} \text{ où } S(x) = \sum_{i < j} 1_{\|x_i - x_j\| \leq R}$$

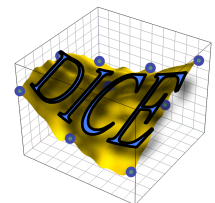
Strauss design is a particular case of Gibbs point process :

$$f(x_1, \dots, x_N) = c \cdot \exp(-\beta \cdot U(x))$$
$$\text{où } \begin{cases} \beta = -\ln \gamma \\ U(x) = S(x) \end{cases}$$

Metropolis-Hastings algorithm (MCMC method)

U is the so-called potential

- interactions on 1-dimensional margins are possible



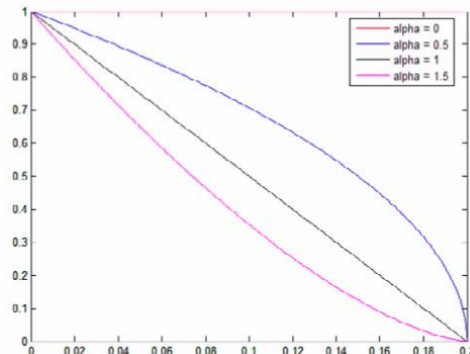
Strauss designs – With 1D margins interaction

$$\pi(x) \propto e^{-U(x)}$$

$$U(x) = \beta \sum_{i < j} \varphi(\|x^i - x^j\|) + \sum_{k=1}^d \beta_k \sum_{i < j} \varphi_k(|x_k^i - x_k^j|)$$

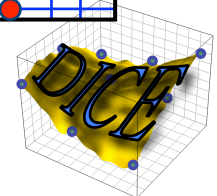
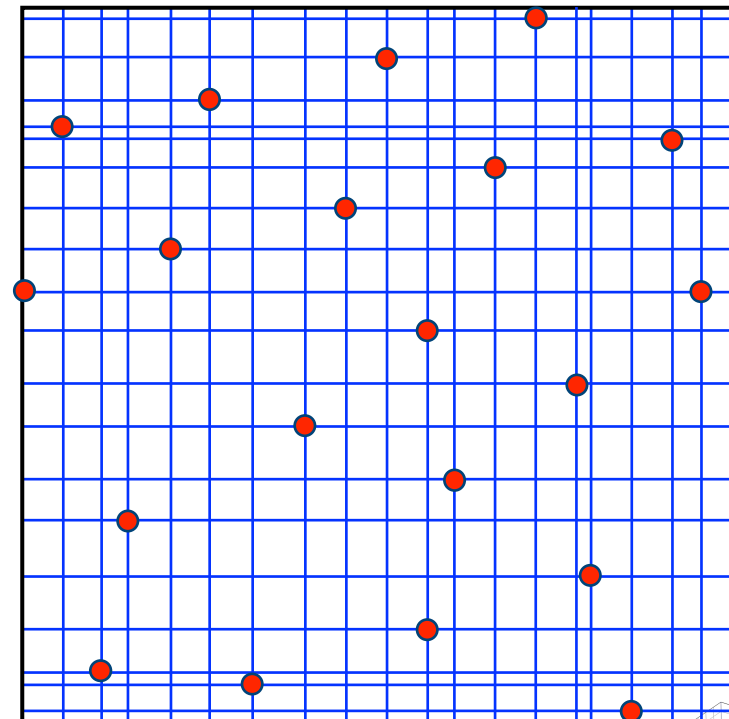
$$\beta = -\ln \gamma > 0; \quad \beta_k = -\ln \gamma_k > 0, \quad k = 1, \dots, d$$

$$\varphi(r) = \left(1 - \frac{r}{R}\right)^\alpha$$



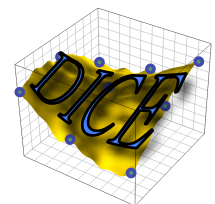
Projections on margins are approximately uniform

Note so far from LH designs



Strauss designs - Conclusion

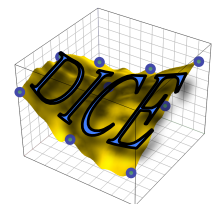
- Stochastic designs, governed by the potential U
 - Regular U gives better designs
 - Designs in constrained domains
- Good results on synthetic and industrial cases
- Package DiceDesign



PART II

- Focus II

Approximation of a target region

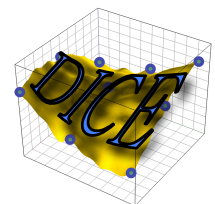


Approximation of a target region

- In frequent situations, global accuracy of metamodels is not required
- Example:

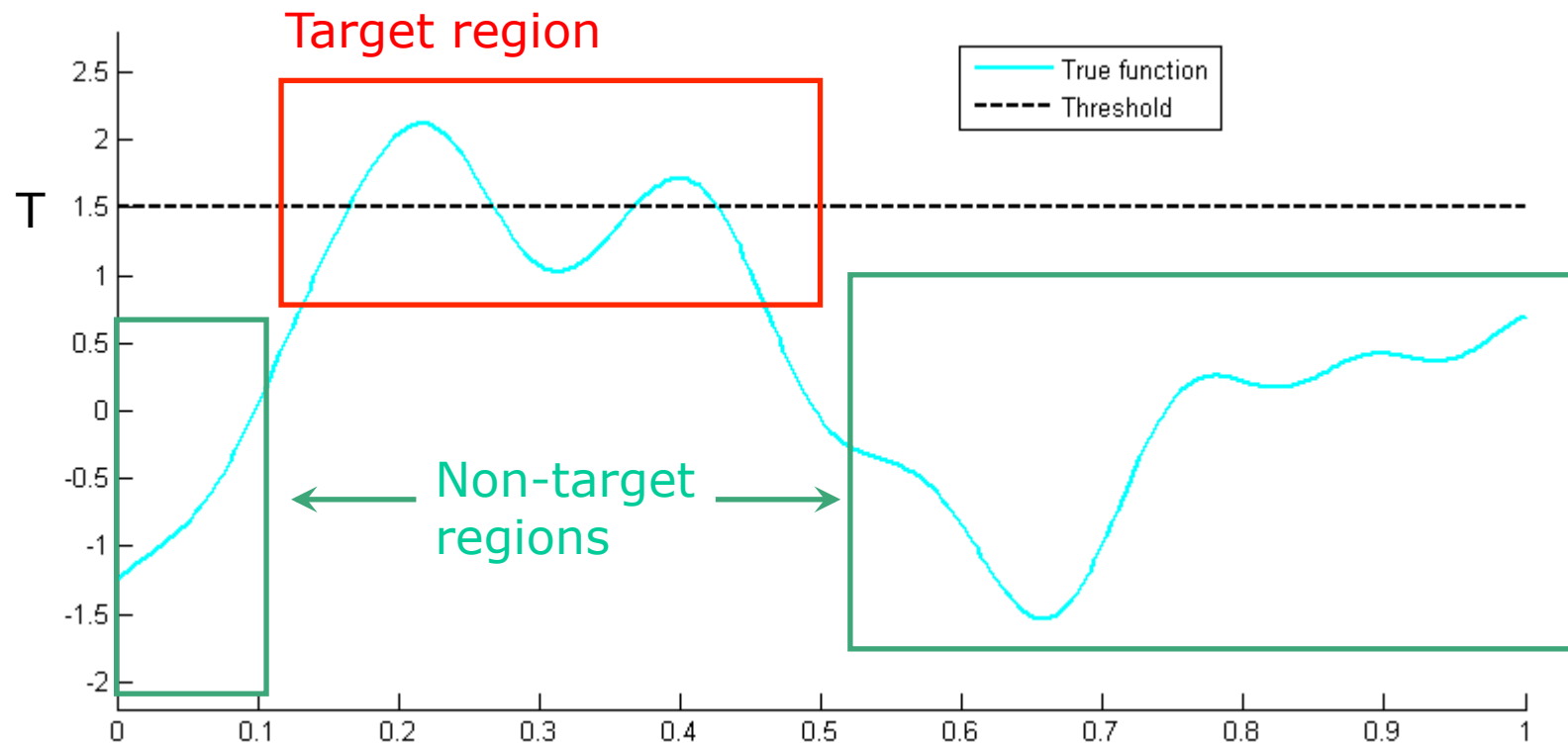
$$\begin{array}{ll} \text{Min}_{\mathbf{x}} & F(\mathbf{x}) \\ \text{s.t.} & G(\mathbf{x}) \leq T \end{array} \quad P_f = \text{Prob}(G(\mathbf{X}) \geq T)$$

Good accuracy for $G(\mathbf{x}) \approx T$

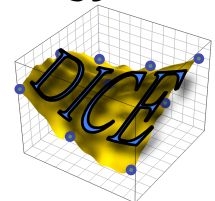


Approximation of a target region – Example (1)

Function to approximate:

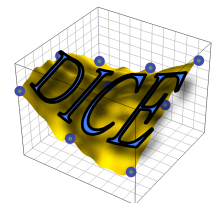
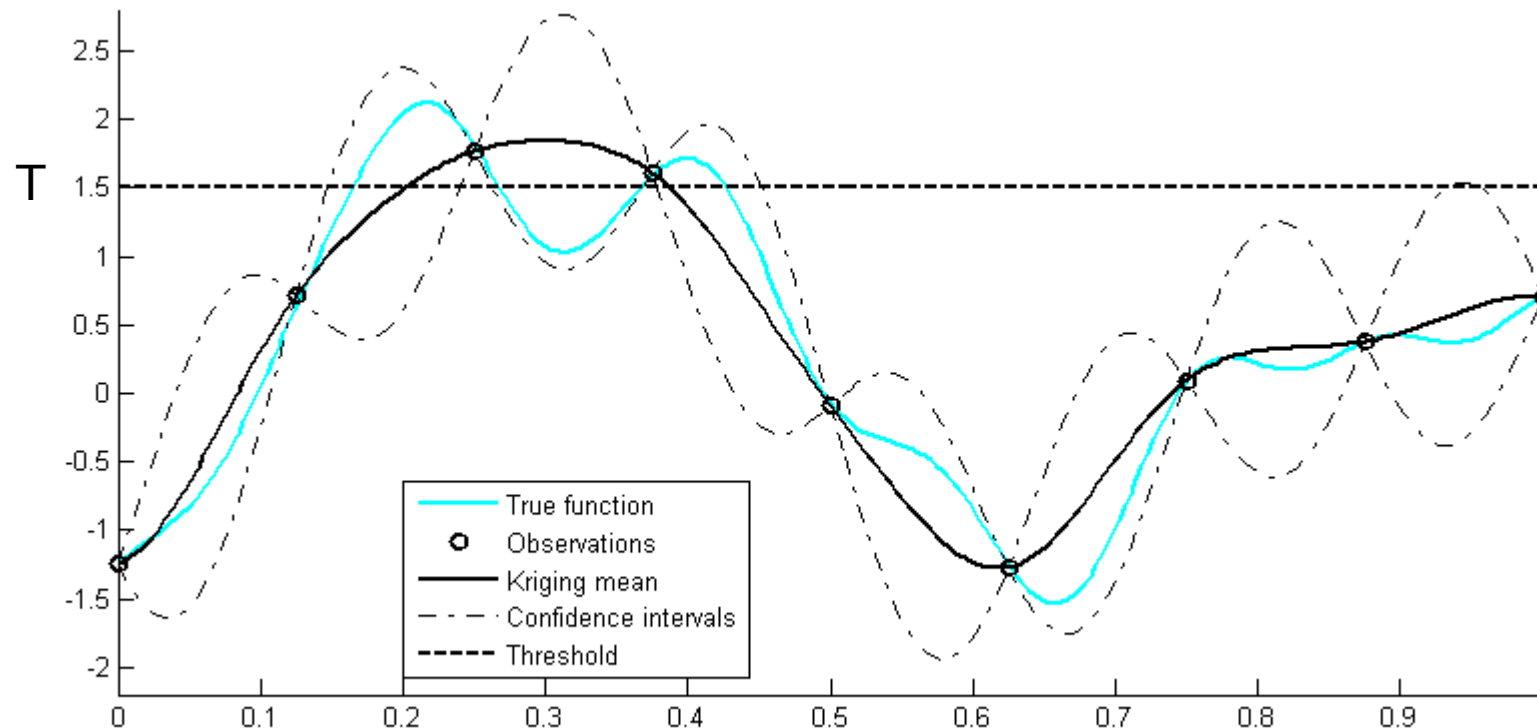


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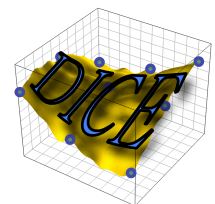
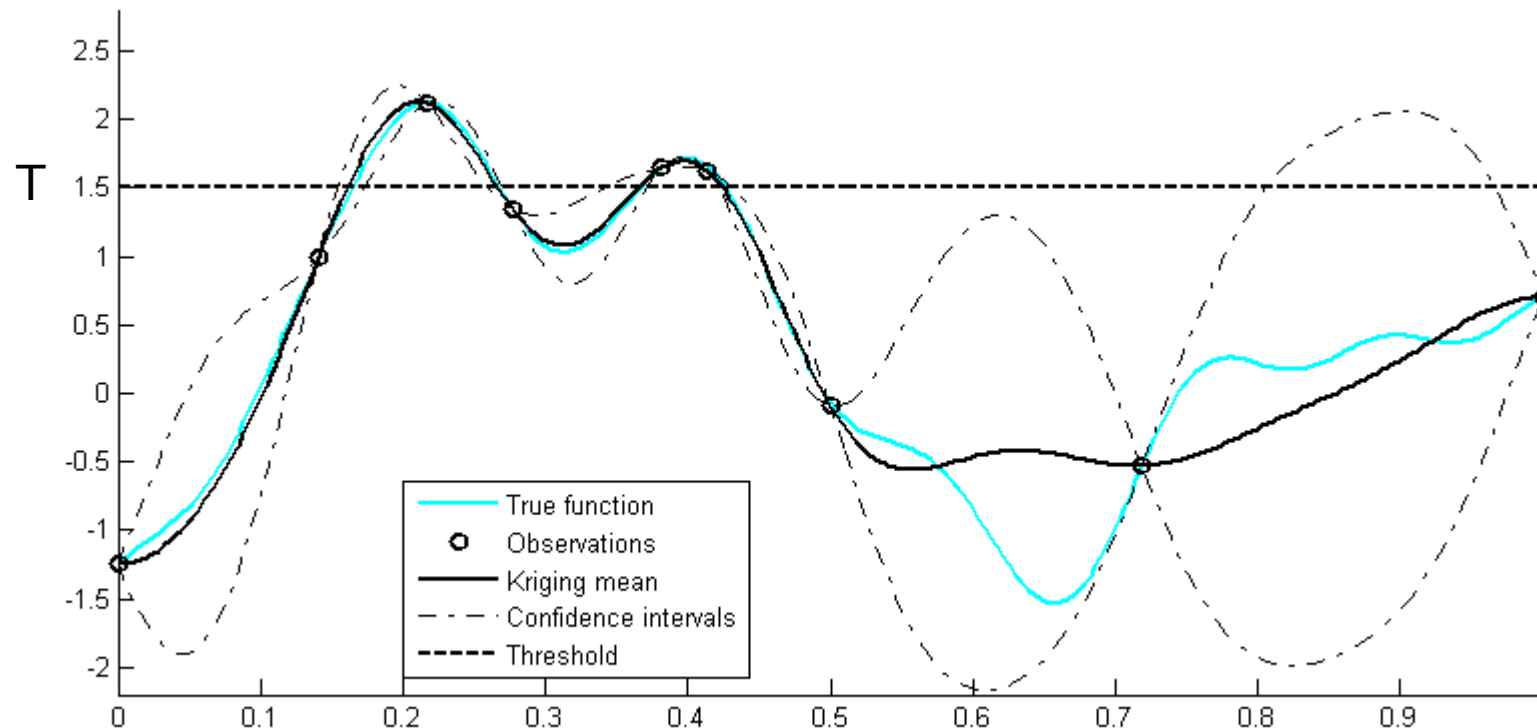
Approximation of a target region – Example (2)

- Kriging based on a uniform design:
 - Reasonable variance everywhere
 - Large errors in the target region



Approximation of a target region – Example (2)

- Customized design:
 - Large variance in non-target regions
 - Good accuracy in target regions



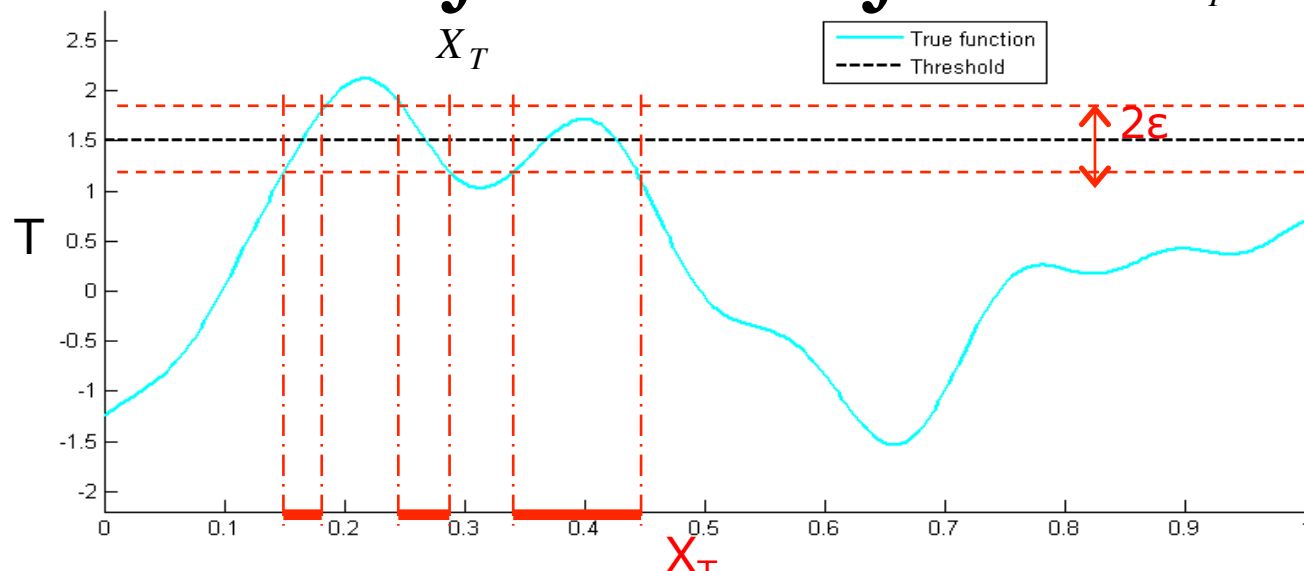
Approximation of a target region – Criterion (1)

- Target region = close to the threshold T

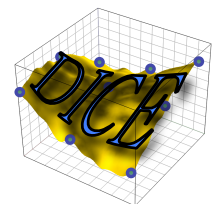
$$X_T = \{ \mathbf{x} \in D / |G(\mathbf{x}) - T| \leq \varepsilon \}$$

- Ideal criterion: MSE, with integration over X_T only:

$$IMSE_T = \int_{X_T} MSE(x) dx = \int MSE(x) 1_{X_T}(x) dx$$



➔ Problem: X_T is unknown!



Approximation of a target region – Criterion (2)

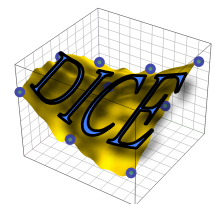
- Idea: replace $1_{X_T}(x)$ by $E(1_{X_T}(x)) = P(x \in X_T) = P(|G(x) - T| < \varepsilon)$

the probability of belonging to the target region, and replace G by the conditional Gaussian Process.

- Using the properties of Gaussian process, we get:

$$W_\varepsilon(x) := P(x \in X_T) = \Phi\left(\frac{T + \varepsilon - m_k(x)}{s_k(x)}\right) - \Phi\left(\frac{T - \varepsilon - m_k(x)}{s_k(x)}\right)$$

where $m_k(x)$ and $s_k(x)$ are the kriging mean and s.d.



Approximation of a target region – Criterion (3)

- The criterion: $IMSE_T = \int MSE(x)W_\varepsilon(x)dx$

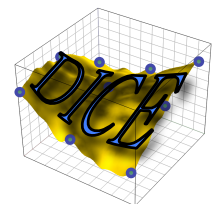
- Limit case: $\varepsilon \rightarrow \infty$, $IMSE_T \rightarrow IMSE$

- Limit case: $\varepsilon \rightarrow 0$, replace W_ε by the pure local W where

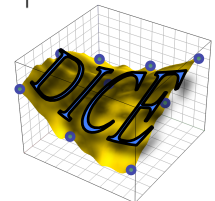
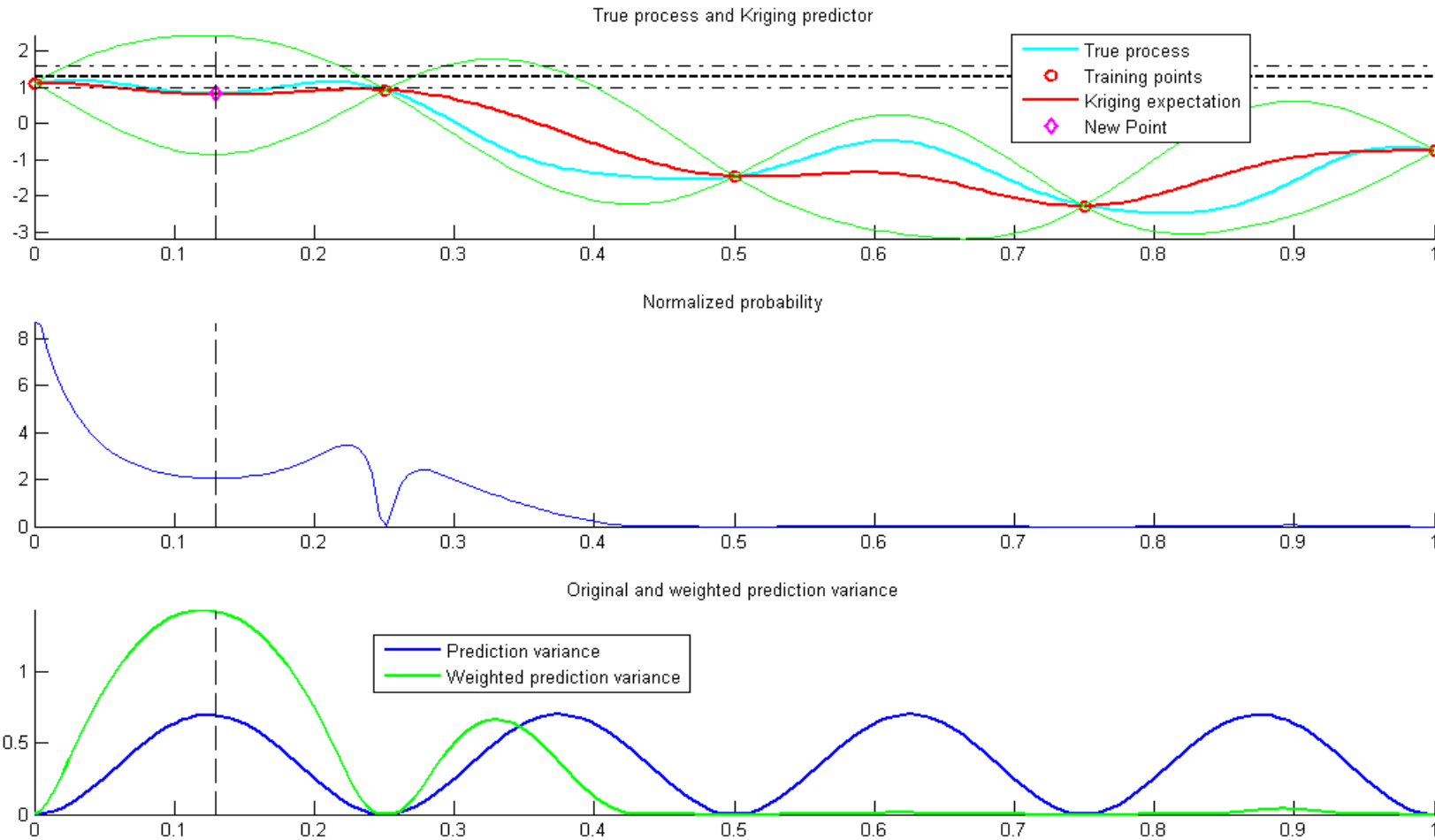
$$W(x) = \lim_{\varepsilon \rightarrow 0} \frac{W_\varepsilon(x)}{2\varepsilon} = f_{N(m_k(x), s_k(x)^2)}(T)$$

the density of the conditional distribution of the Gaussian Process.

- $W(x)$ is large if:
 - $G(x)$ is near the target region
 - x belongs to an unexplored area



Approximation of a target region – Illustration



Approximation of a target region – Algorithm

- Iterative procedure:

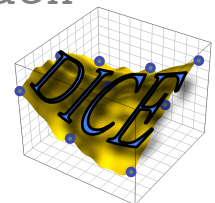
- Create an initial design, compute the observations
- Estimate the Kriging model, and compute $W(x)$
- Find x^* that minimize the practical criterion

$$IMSE_T(x^*) = \int MSE(x | X_i, x^*) W(x | X_i, Y_i) dx$$

- Run the simulator at x^*
- Continue until the maximal number of iterations is reached

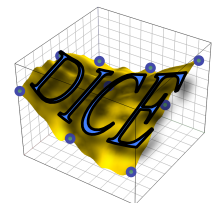
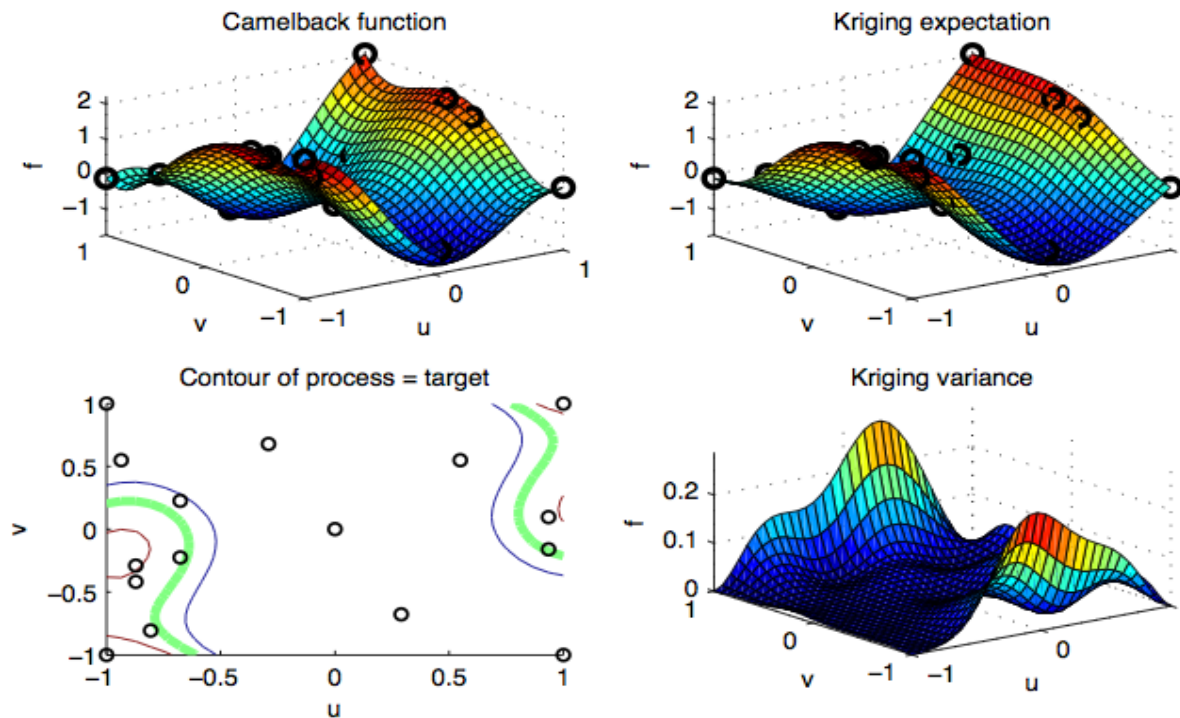
- Kriging model parameters:

- Estimated at the beginning, or re-estimated at each step



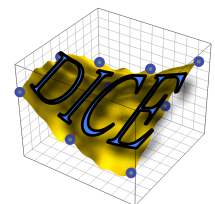
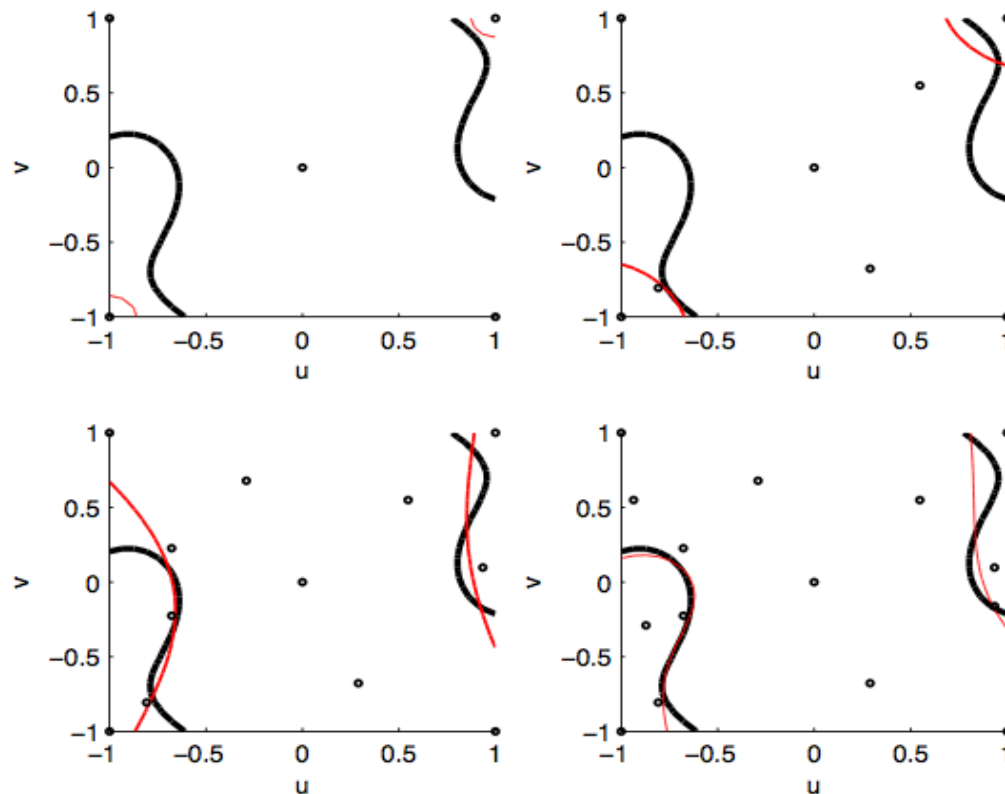
Approximation of a target region – 2D-example

- A 2-dimensional example (Camelback function)
 - Target region $G(x,y) = 1.3$
 - Optimal design after 11 iterations



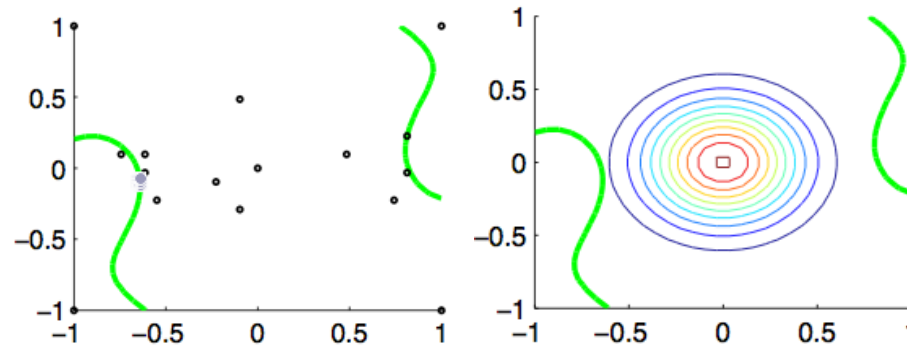
Approximation of a target region – 2D-example

- A 2-dimensional example (Camelback function)
 - Evolution of Kriging target contour line

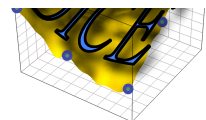


Approximation of a target region – 2D-example

- Application to the assessment of probability of failure
 - $P(G(U,V) > 1.3)$ with $U, V, \text{ i.i.d. } N(0, 0.028^2)$

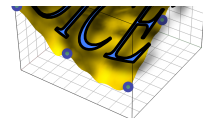
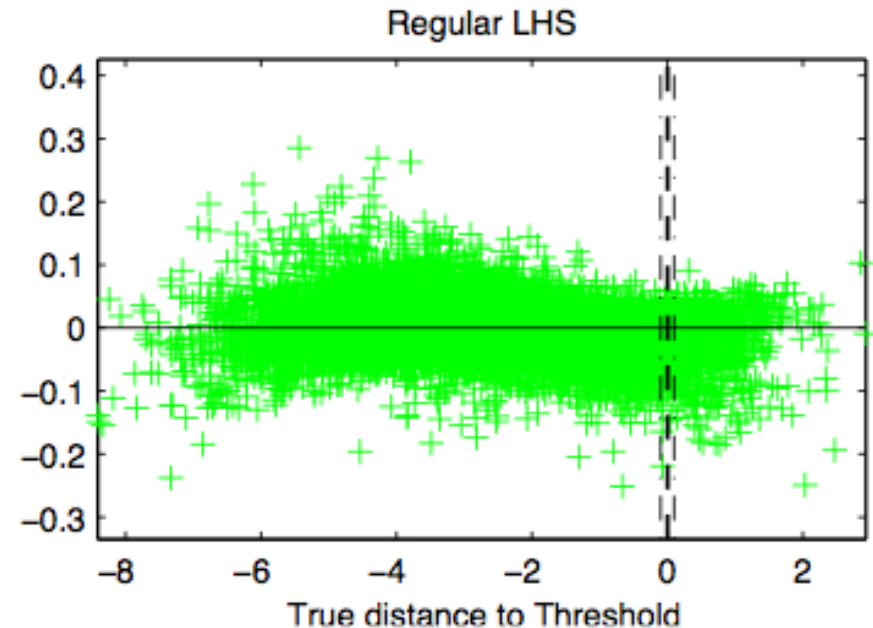
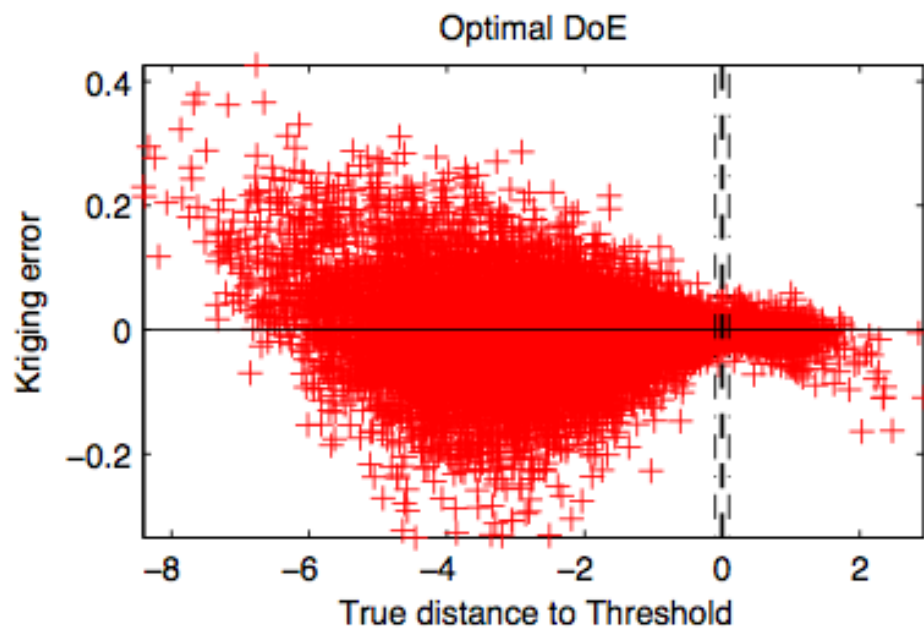


DoE	Full Factorial	Optimal without input distribution	Optimal with input distribution	Probability estimate based on 10^7 MCS
Probability of failure (%)	0.17	0.70	0.77	0.75
Relative error	77 %	7 %	3 %	



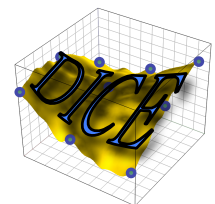
Approximation of a target region – 6D-example

- A 6-dimensional example
 - Function = 1 sample function of a Gaussian Process with linear trend and isotropic Gaussian covariance (known parameters)



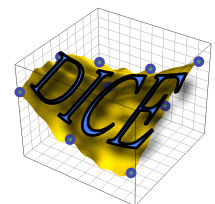
Approximation of a target region – Comparison

- Good results in a numerical study comparing 4 methods → see the poster of Ling Li in UCM 2010
 - Targeted IMSE performs as well as Stepwise Uncertainty Reduction, when W corresponds to the limit case ($\varepsilon \rightarrow 0$)
 - Both tIMSE and SUR seem to outperform the two other ones
 - Future research: theoretical link between tIMSE & SUR ?



Approximation of a target region – Conclusion

- An adaptive strategy
 - Trade-off between exploration of target regions and global uncertainty reduction
 - Model-believer
- Applications to the assessment of probability of failure
- Future research:
 - Influence of parameter estimation in Kriging
 - Adaptation for dimensions ≥ 10
 - A R-package is in preparation



Thank you for your attention !

