Prairie View A&M University
Digital Commons @PVAMU

All Theses

8-1969

A Fundamental Theorem in Linear Programming

George E. Higgs

Follow this and additional works at: https://digitalcommons.pvamu.edu/pvamu-theses

A FUNDAMENTAL THEOREM IN LINEAR PROGRAMMING

2032

A FUNDAMENTAL THEOREM IN LINEAR PROGRAMMING

A Thesis

Submitted to the Graduate School of Prairie View Agricultural and Mechanical College

9A402.5 H5

in Partial Fulfillment of the

Degree of

Master of Science

by

George E. Higgs August, 1969

PRAIRIE VIEW AGRICULTURAL AND MECHANICAL COLLEGE GRADUATE SCHOOL

WORKSHOP SHEET III & IV THESIS (OR ESSAY) REPORT *TURN IN THIS FORM WITH YOUR COMPLETED THESIS OR ESSAY

NAME George Higgs	DEGREE <u>Masters</u> of Science
Prairie View, Texas (Permanent Home Address)	DEPARTMENT: Mathematicsd
	DATE SUBMITTEDAugust 9, 1969
TITLE OF THESIS OR ESSAY:	PREVIOUS DEGREES:
A Fundamental Theorem In Linear	B. S. Prairie View
	(DEGREES) (COLLEGE)
Programming	January 1956
	(DATE)
	Masters Prairie View
	(DEGREE) (COLLEGE)
	August 1969
	(DATE)
RECORD: NUMBER OF PAGES: 23	UNDERGRADUATE MAJORBusiness Adm.
NUMBER OF TABLES OR CHARTS	UNDERGRADUATE MINOR Mathematics
NAME OF TYPIST:	GRADUATE MAJOR Mathematics
010	GRADUATE MINOR Business Adm.
APPROVAL:	of Supervising Professor)
BRIEF SUMMARY OF (Not to exce	THESIS (OR ESSAY) ed 100 words)
(This summary is a permanent b should be written carefully).	bibliographical record. It

A FUNDAMENTAL THEOREM IN LINEAR PROGRAMMING

A Thesis

by

George E. Higgs

Approved as to style and content by

(Advisor)

(Head of Department)

(Member)

(Member)

(Member)

(Member)

(Member)

August, 1969

ACKNOWLEDGMENTS

The writer wishes to express his appreciation and esteemed gratitude to Mrs. E. E. Thornton for her professional guidance, assistance and untiring patience during the writing of this paper.

The writer also wishes to express his sincere thanks to Dr. A. D. Stewart, Mr. Willie Taylor and my other instructors in mathematics for giving me enlightment, and for making the many long hours of study worthwhile.

DEDICATION

This paper is dedicated to my wife Olivette, and my two children, Cherie and Marcus who so willingly and untiringly have made my entire pursuits for an education possible.

TABLE OF CONTENTS

CHAPTER

PAGE

	INTRODUCTIONS	1
I	DEFINITIONS AND TERMINOLOGY	4
II	PROPERTIES OF LINEAR INEQUALITIES	8
III	MAIN THEOREM	15
IV	APPLICATIONS	19
BIBL	IOGRAPHY	24

INTRODUCTION

Linear Programming is a recent empiral tool made available to the market world. It has already found many important applications and offers exciting opportunities in the future. It can serve as an important management aid to marketing firms.

Linear Programming originated during World War II as a method for specifying routes that would minimize travel distance for the limited shipping facilities available to the Allies; for determining the best method of allocating scarce labor, machine tools, and plant facilities to produce war goods; and for similar purposes. Since the end of the war, the method has become highly refined and is being used by a large number of private firms and research organizations.

Linear Programming techniques involve the maximization or minimization of linear function, subject to linear inequalities. The linear function ordinarily is a profit or cost function.

Linear Programming can be applied as to procedure for selecting a beginning plan which is consistent with sets of two or more inequalities defining the upper and lower limit to real activities or unused resources.

Since linear programming is a fairly new concept in the solution of certain types of problems, a thorough understanding about these properties must be comprehended by the teacher of high school algebra.

In the teaching of high school algebra the method that is used to find the maximum or minimum of a function f(X)=AX+b over a polygonal convex set is as follows: Find the corner points of the set, there will be a finite number of them; substitute the coordinates of each into the function; the largest of the value so obtained will be a maximum of the function and the smallest value will be the minimum of the function. Knowing that this method always brings about a practical solution in all cases, the question brought to the writer's mind is why does the maximum or minimum always occur at a corner point?

The primary objective of this paper is to show that given a linear function f defined over a polygonal convex set, its maximum and minimum will occur at the corner points.

In Chapter I we have basic definitions and theorems that will be used throughout this paper.

In Chapter II we show conditions under which a system of inequalities in R² has a solution and in fact

2

we show that if a solution exists it is a convex set. Furthermore we assume that a system of inequalities in \mathbb{R}^n has a solution and show this solution is convex.

In Chapter III we prove two lemmas that are to be used in the proof to the main theorem. We also show in the main theorem that if given a linear function f define over a polygonal set, its maximum or minimum will occur at a corner point.

In Chapter IV we show two examples that are applicable to the main theorem. Although these applications will give the reader some idea of the adaptability of linear-programming methods, it is not the writer's purpose to describe the complete range of linear-programming applications. These applications were selected mainly for their ability to illustrate the techniques of formulating a linear-programming model.

3

CHAPTER I

DEFINITIONS AND TERMINOLOGY

- Definition: Any ordered pair of real numbers
 (x,y) is called a <u>vector</u>.
- 1.1 Definition: $\mathbb{R}^{n} = \{x \mid (x^{1}, x^{2}, x^{n}) \text{ where } x^{i} \in \mathbb{R}$ for i=1, 2, \cdots , \overline{n}
- 1.2 Definition: If V = (x, y), then the <u>norm of V</u> is designated by ||V|| and is defined by $||V|| = \sqrt{x^2 + y^2}$.
- 1.3 Definition: The intersection of closed half planes is a polygonal convex set.
- 1.4 Definition: Let K denote a polygonal convex set then P is a <u>corner point</u> of K if P is on the boundaries of K and is the intersection of two lines.
- 1.5 Definition: If each of x and y is an element of Rⁿ, then
 - 1) the sum of x and y is an element of Rⁿ, denoted by x+y=(x¹+y¹, x²+y², ···xⁿ+yⁿ)
 - 2) the dot product of x and y is an element of R denoted by

$$xy = \begin{bmatrix} x^{1}, x^{2}, \cdots x^{n} \end{bmatrix} \begin{bmatrix} y^{1} \\ y^{2} \\ \vdots \\ y^{n} \end{bmatrix} = x^{1}y^{1} + x^{2}y^{2} + \dots + x^{n}y^{n}$$

Definition: An (m,n) matrix A is a rectangular array of real numbers denoted symbolically by

$$A = \begin{bmatrix} a_{11} & a_{12---}a_{1n} \\ a_{21} & a_{22---}a_{2n} \\ \vdots & \vdots \\ \vdots & \vdots \\ a_{m1} & a_{m2---}a_{mn} \end{bmatrix}$$

1.6

having n rows and m columns. If n=1, A is a column vector and m=1, A is a row vector.

- 1.7 Definition: <u>Greater Than</u> (\geq) ; For every pair x,y of real numbers, x > y if, and only if, x - y is a positive number.
- 1.8 Definition: Less Than (∠); For every pair x,y of real numbers x ∠ y if, and only if x - y is a negative number.
- 1.9 Definition: Let $f: \mathbb{R}^n \longrightarrow \mathbb{R}$ and $x_o \in \mathbb{R}^n$, then $f(x_o)$ is a maximum of f if for each $y \in \mathbb{R}^n$, $f(y) \leq f(x_o)$.
- 2.0 Definition: Let $f: \mathbb{R}^n \longrightarrow \mathbb{R}$ and $x_o \in \mathbb{R}^n$, then $f(x_o)$ is a minimum of f if for each $y \in \mathbb{R}^n$, $f(y) \ge f(x_o)$.
- 2.1 Definition: The statement that A; B is a linear path from the point A to the point B in the Rⁿ means; there is a continuous function

f from $\langle \overline{0}, \underline{17} \rangle$ into \mathbb{R}^n such that if t is an element of $\langle \overline{0}, \underline{17} \rangle$, then $f(t)=(1 - t)\mathbb{A}+t\mathbb{B}$. $\langle \overline{A}; \underline{B7}' = \{f(t) \mid 0 \leq t \leq 1\}$ is called the carrier of the linear path from A to B. Let C denote a subset of \mathbb{R}^n , then the set C is said to be convex provided that if A and B are points in C, the $\langle \overline{A}; \underline{B7}' \rangle$ is a subset of C.

Example:

2.2

H₁: C is a closed circular disc with point P as its center. H₂: C= $\{x \mid || X - P || \leq r$ C: C is a convex set.

Proof:

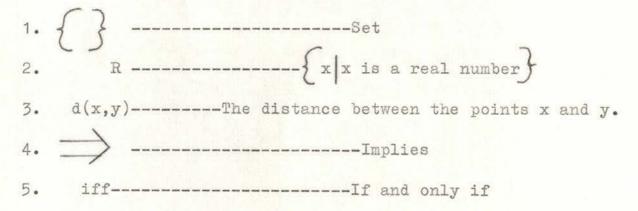
Let A and B be points in C and $\langle \overline{A}; \overline{B} \overline{7} \rangle$ be the linear path from A to B and X a point in $\langle \overline{A}; \overline{B} \overline{7}, \cdot \rangle$ then there exist t $\in \langle \overline{0}, 1 \overline{7} \rangle$ such that X=(1 - t) A+tB.

$$\begin{aligned} d(P,X) &= \| X - P \|, \ X = (1 - t)A + tB \ and \ P = (1 - t)P + tP \\ &= \| (1 - t)A + tB - (1 - t)P + tP \\ &= \| (1 - t)(A - P) + t(B - P) \| \\ &\leq \| (1 - t)(A - P) + t(B - P) \| \\ &\leq \| (1 - t)(A - P) \| + \| t(B - P) \| \\ &= \| (1 - t) \| \| A - P \| + \| t \| \| B - P \| \\ &= \| (1 - t) \| \| A - P \| + \| t \| \| B - P \| \\ &\text{Since } A - P \leq r \text{ and } B - P \leq r \text{ implies that} \end{aligned}$$

Therefore C is a convex set.

6

SYMBOLS USED



CHAPTER II

PROPERTIES OF LINEAR INEQUALITIES

We shall not prove that under certain conditions a system of inequalities has a solution, but we will observe the following:

Consider the system of inequalities: $a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \ge c_1$ $a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n \ge c_2$ $\dots + \dots + a_{m1}x_1 + a_{m2}x_2 \dots + a_{mn}x_n \ge c_n$ If the associated system of equalities, $a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = c_1$ $a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = c_2$ $\dots + a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = c_n$

has a solution, then so does the system of inequalities.

It is interesting to note that given the system

 $a_{11}x_1 + a_{12}x_2 \ge c_1$ $a_{21}x_1 + a_{22}x_2 \ge c_2$

in case $\frac{a_{11}}{a_{21}} = \frac{a_{12}}{a_{22}}$

the associated system

$$\begin{cases} a_{11}x_1 + a_{12}x_2 = c_1 \\ a_{21}x_1 + a_{22}x_2 = c_2 \end{cases}$$

has no solution, but the system of inequalities may have a solution.

We shall state in the following theorem the necessary and sufficient conditions for such a system to have a solution.

Theorem I

^H_{1:} $\begin{cases} a_1 x_1 + b_1 x_2 \ge c_2 \\ a_1 x_1 + b_1 x_2 \ge c_1 \end{cases} c_1 \neq c_2$

C: The system in H₁ has a solution.

Proof:

Since $c_1 \neq c_2$, then either $c_2 > c_1$ or $c_1 > c_2$ Suppose $c_2 > c_1$ Let $K = \{(x_1, x_2) \mid a_1 x_1 + b_1 x_2 = c_2 + d\}$ where $d \ge 0$ We will show that K is a solution set in H_1 : $a_1 x_1 + b_1 x_2 = c_2 + d \ge c_2 \implies a_1 x_1 + b_1 x_2 \ge c_2$ $a_1 x_1 + b_1 x_2 = c_2 + d \ge c_1 + d \ge c_1$ Therefore K is a solution set to H_1

$$\frac{\text{Theorem II}}{\text{H}_{1}:} \begin{cases} a_{1}x_{1} + b_{1}x_{1} \ge c_{1} \\ a_{1}x_{1} + b_{1}x_{1} \le c_{2} \end{cases}$$

C: There exist a solution set to H_1 iff $c_2 \ge c_1$. Assume a solution set exists

Prove: c1≤ c2

Proc	f:				
	$\int a_1 x_1$	+	^b 1 ^x 1	-	c ₁ ≥0
1.	a_1x_1	+	^b 1 ^x 1	-	°2≦0
-	$\left(a_1x_1\right)$				
2.	$\left\{-a_1x_1\right\}$				

Divide second inequality by -1.

3. $c_2 - c_1 \ge 0$ Therefore $c_2 \ge c_1$

Assume $c_1 \leq c_2$, show there exist a solution. 1. Since $c_1 \leq c_2$, $c_1 \leq \frac{c_1 + c_2}{2} \leq c_2$ 2. Let $H = \left(x_1, x_2 \right) |a_1 x_1 + b_1 x_2 = \frac{c_1 + c_2}{2} \right)$ 3. Claim H is a solution set to H_1 . 4. Let $K = \frac{c_1 + c_2}{2}$, Then $a_1 x_1 + b_1 x_2 = K$

5. $x_1 = \frac{K - b_1 x_2}{a_1}$ $a_1 \neq 0 \text{ and } x_2 = \frac{K - a_1 x_1}{b_1}$ $b_1 \neq 0$

6.
$$\frac{1}{2} \left(\frac{\mathbb{K} - b_{1} x_{2}}{2} \right) + \frac{1}{2} \left(\frac{\mathbb{K} - a_{1} x_{1}}{2} \right) \ge c_{1} \\ \frac{1}{2} \left(\frac{\mathbb{K} - b_{1} x_{1}}{2} \right) + \frac{1}{2} \left(\frac{\mathbb{K} - a_{1} x_{2}}{2} \right) \le c_{2} \\ 7. \left(\frac{\mathbb{K} - b_{1} x_{2} + \mathbb{K} - a_{1} x_{1} \ge c_{1} \\ \mathbb{K} - b_{1} x_{2} + \mathbb{K} - a_{1} x_{1} \le c_{2} \\ 8. \left(\frac{2\mathbb{K} - b_{1} x_{2}}{2} - a_{1} x_{1} \le c_{2} \\ 2\mathbb{K} - b_{1} x_{2} - a_{1} x_{1} \le c_{2} \\ 9. \left(\frac{2\left(\frac{c_{1} + c_{2}}{2}\right) - b_{1} x_{2} - a_{1} x_{1} \ge c_{1} \\ \frac{2\left(\frac{c_{1} + c_{2}}{2}\right) - b_{1} x_{2} - a_{1} x_{1} \ge c_{1} \\ \frac{2\left(\frac{c_{1} - c_{2}}{2}\right) - b_{1} x_{2} - a_{1} x_{1} \ge c_{2} \\ 10. \left(\frac{c_{2} - b_{1} x_{1} - a_{1} x_{1} \ge 0 \\ c_{1} - b_{1} x_{2} - a_{1} x_{1} \le 0 \right)$$

Therefore

$$c_2 \geq b_1 x_2 + a_1 x_1$$

$$^{\circ}1 \leq ^{b}1^{x}2^{+a}1^{x}1$$

$\frac{\text{Theorem III}}{\text{H}_{1}:} \begin{cases} a_{11}x_{1} & a_{12}x_{2} & \cdots & a_{1n}x_{n} \geq c_{1} \\ a_{21}x_{1} & a_{22}x_{2} & a_{2n}x_{n} \geq c_{2} \\ \cdots & \cdots & \cdots \\ a_{m1}x_{1} & a_{n2}x_{2} & a_{mn}x_{n} \geq c_{n} \end{cases}$

 $H_2: AX \ge C$

H₃: K is solution set for the inequality H₂. C: K is a convex set Proof:

Let R and S be points in K and $\overline{R}; \underline{S7}$ be the linear path R to S and let X be a point in $\overline{R}:\underline{S7}$, then there exist a t $\overline{\epsilon}/\overline{0}; \underline{17}$ such that X=(1-t)R+tS. Since the dimensions in H₁ are known it can be written in the following form:

A	X	C
a ₁₁ a ₁₂ a _{1n}	$\begin{bmatrix} x_1 \end{bmatrix}$	[c1]
a ₂₁ a ₂₂ a _{2n}	x ₂	°2
• • • • • • • • • • • • • • • • • • • •		
••••••		
a _{m1} a _{m2} a _{mn}	x _n	c _n

- A is called the coefficient matrix of the system of inequality.
- 2. C is called the constant vector of the system.

1. A/(1 - t)R+tS/=2. $AR(1 - t)+ASt \le$ 3. C(1 - t)+Ct = C

Therefore K is a convex set.

Theorem IV

 $\begin{array}{r} a_1 x_1 + b_1 x_2 \ge c_1 \\ a_2 x_1 + b_2 x_2 \ge c_2 \\ x_1 \ge 0 \\ x_2 \ge 0 \end{array}$

H₂: S is a positive Solution to H₁.

C: S is a convex set.

Proof:

Let L and M be points in S and $\angle L; \underline{S7}$ is a linear path from L to M and if K is a point in $\angle L; \underline{M7}'$ there exist a t $\underline{C0, 17}$ such that $\underline{K=(1 - t)L+Mt}$ is a positive number.

Let
$$K = (x_1, x_2)$$

1.

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = (1 - t) \begin{pmatrix} 1_1 \\ 1_2 \end{pmatrix} + t \begin{pmatrix} m_1 \\ m_2 \end{pmatrix}$$

2.
$$\binom{x_1}{x_2} = \binom{(1 - t)1_1}{(1 - t)1_2} + \binom{tm_1}{tm_2}$$

 $x_1 = (1 - t)1_1 + tm_1$
3. $x_2 = (1 - t)1_2 + tm_2$
4. Substituting in inequality #1 in H₁, we have
 $a_1 \angle (1 - t)1_1 + tm_1 \angle 2 = a_1 1_1 (1 - t) + a_1 m_1 t \ge c(1 - t) + ct = c_1$.
5. Substituting in inequality #2 in H₁, we have
 $a_2 \angle (1 - t)1_2 + tm_2 \angle 2 = a_2 1_2 (1 - t) + a_2 m_2 t \ge c(1 - t) + ct = c_2$.
6. Substituting in inequality #3, in H₁ we have
 $(1 - t)1_1 + tm_1 \ge 0(1 - t) + t0 = 0$
7. Substituting in inequality #4, in H₁, we have
 $(1 - t)1_2 + tm_2 \ge 0(1 - t) + t0 = 0$
Therefore S is a convex set.

CHAPTER III MAIN THEOREM

Lemma I:

H₁: $(\overline{A}, \overline{B7})$ is an interval in R

H₂: f(x)=ax+b is defined on $(\overline{A}, \underline{B})$, where A and B are in R H₃: $f(A) \leq f(B)$

C: If $Z \in [A, B]$, then $f(A) \leq f(Z) \leq f(B)$ Proof:

Let A and B be an interval and Z is a point in $\overline{(A, B)}$ such that Z=(1 - t)A+tB, and $t \in \overline{(0, 1)}$, there exist a $f(Z) \in \overline{(f(A); f(B))}$ such that f(Z)=aZ+b.

1. f(A)=aA+b and f(B)=aB+b2. Z=(1 - t)A+tB, $0 \le t \le 1$ 3. f(Z)=a/(1 - t)A+tB/tb4. $= aA(1 - t)+aBt+b \le aB+b=f(B)$ 5. f(Z)=a/(1 - t)A+tB/tb =6. $=aA(1 - t)+tB+b \ge$ 7. aA+b = f(A)

Therefore $f(A) \leq f(A) \leq f(B)$

Lemma II

- H₁: [A; B] is a linear path in \mathbb{R}^n H₂: $f: [A; B] \rightarrow \mathbb{R}$ defined by f(X)=CX+b, where $X=(x_1x_2\cdots x_n)$ and $C=(c_1c_2\cdots c_n)$ $b \in \mathbb{R}$, then $f(X)=c_1x_1+c_2x_2\cdots c_nx_n+b$ H₃: $f(A) \leq f(B)$ C: If $Z \in [A; B]$, then $f(A) \leq f(Z) \leq f(B)$ Proof: 1. Let A and B be points in \mathbb{R}^n and Z is a point in [A; B] such Z=(1-t)A+tB and $t \in [0, 1]$, then f(Z)=CZ+b. We must show that $f(Z) \in [f(A); (B)]$. 2. $A = (a_1, a_2, \cdots a_n)$ $B = (b_1, b_2, \cdots b_n)$ $Z = (z_1, z_2, \cdots b_n)$
- 3. $f(A)=CA+b=c_1a_1+c_2a_2+\cdots+c_na_n+b$ $f(B)=CB+b=c_1b_1+c_2b_2+\cdots+c_nb_n+b$ $f(Z)=CZ+b=c_1z_1+c_2z_2+\cdots+c_nz_n+b$

4.
$$f(Z) = c_1 (1-t)a_1 + tb_1 7 + b + c_2 (1-t)a_2 + tb7 + b + \cdots$$

+ $c_n (1-t)a_n + tb_n 7 + b$
= $c_1a_1(1-t) + c_1b_1 t + b + c_2a_2(1-t) + c_2b_2 t + b + c_na_n$
(1-t) + $c_nb_n t + b$
 $\ge c_1a_1 + c_2a_2 + \cdots + c_na_n + b = f(A)$

5.
$$f(Z) = c_1 \angle (1-t)a_1 + tb_1 \angle 7 + b + c_2 \angle (1-t)a_2 + tb_2 \angle 7 + b + \cdots$$

+ $c_n \angle (1-t)a_n + tb_n \angle 7 + b$
= $c_1a_1(1-t) + c_1b_1t + b + c_2a_2(1-t) + c_2b_2t + b + c_na_n(1-t)$
+ $c_nb_nt + b$
 $\leq c_1b_1 + c_2b_2 + \cdots + c_nb_n + b = f(B)$

Therefore $f(A) \leq f(Z) \leq f(B)$

Theorem

- H1: K is a convex set
- Ho: X is a point in K
- H₃: f is non-constant linear function defined on K. f(X)=AX+b for X in K. A=(a₁, a₂ a_n) X=(x₁, x₂, ... x_n) and b∈ R

 $H_A: f(X_O)$ is a minimum for some $X_O \in K$

X is a corner point of K

Proof:

 Suppose X₀ is not a corner point in K, since K is a convex set, there exist a point X₀ in K such that X₀ € /X₀;X'₀/7'. Extend /X₀;X'₀/7 so that it intersects the boundaries of K at points P and Q either f(P)≥ f(Q) or f(Q)≥ f(P). Assume f(P)≤ f(Q), then f(P)≤ f(X₀)≤ f(Q)⇒ f(X₀)=f(P) since f(X₀) is a minimum.

- 2. If P is a corner point we know $P \neq X_0$, but $f(P)=f(X_0)$ Therefore since f is linear it must be constant, but this leads to a contradiction of H_1 . Hence the theorem holds.
- 3. If P is not a corner point, then $p \in \overline{R}; S7'$ where R and S are corner points in K.
- 4. Assume f(R)≤f(S), then f(R)≤f(P)≤f(S). According to statement 1 f(X₀)=f(P), then we have f(R)≤f(X₀)≤f(S)
- 5. $f(R) \leq f(X_0) \Rightarrow f(X_0)$ is not a minimum which leads to a contradiction.

Therefore X is a corner point.

CHAPTER IV

APPLICATIONS

Example #1

To fill his vitamin needs, a man is to buy 100 pills which must contain at least 750 units of B_1 , 600 units of B_2 , and 280 units of B_6 . At 5 cents per pill, he can buy pill I, which contains 10 units of B_1 , 5 of B_2 and 3 of B_6 . At 6 cents per pill, he can buy pill II which has 12 units of B_1 , 2 of B_2 and 11 of B_6 . Also, pill III, which contains 6 units of B_1 , 7 of B_2 , and 2 of B_6 , is available at 4 cents per pill. How many of each kind of pill should he use in order to fulfill his needs at the lowest cost. Solution

Let x = number of pills at 5¢ y = number of pills at 6¢ 100-x-y = number of pills at 4¢ Total cost to be minimized is 5x+6y+400 - 4x - 4y or x 2y 400.

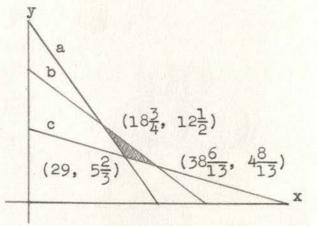
	pill I (5¢)	pill II (6¢)	pill III (4¢)	Amount Needed
^B 1	10	12	6	750
B ₂	5	2	7	600
B ₆	3	11	2	280

a. $10x+12y+600 - 6x-6y \ge 750$; $4x+6y \ge 150$; $2x+3y \ge 75$

- b. $5x+2y+700 7x-7y \ge 600; -2x-5y \ge -100; 2x+5y \le 100$
- c. 3x+11y+200 2x-2y≥ 280; x+9y≥ 80
- d. x≥0
- e. y≥0
- f. x and y must be integers

Solving the system of inequalities, we find that the vertices as listed on the chart below.

Vertex	x+2y+400	Cost
$(18\frac{3}{4}, 12\frac{1}{2})$	183+25+400	$443\frac{3}{4}$ or \$4.44
$(38\frac{6}{13}, 4\frac{8}{13})$	38 <u>6</u> 13+9 <u>13</u> +400	447 <u>9</u> or \$4.48
(29, 5 <u>3</u>)	$29+11\frac{1}{3}+400$	$440\frac{1}{3}$ or \$4.40

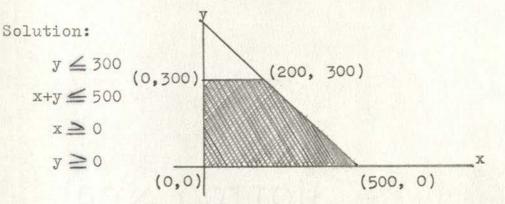


(29, $5\frac{2}{3}$) is vertex of minimum value Therefore x = 29 and y = 6 29 pills can be purchased at 5¢ 6 pills can be purchased at 6¢ 65 pills can be purchased at 4¢ The 100 pills can be purchased for \$4.40.

Example #2

A poultry farmer raises chickens, ducks, and turkeys and has room for 500 birds on his farm. While he is willing to have a total of 500 birds, he does not want more than 300 ducks on his farm at any one time. Suppose that a chicken costs \$1.50, a duck \$1.00, and a turkey \$4.00 to raise to maturity. Assume that the farmer can sell chickens for \$3.00, ducks for \$2.00, and turkeys for T dollars each. He wants to decide which kind of poultry to raise in order to maximize his profit.

> a. Let x be the number of chickens and y be the number of ducks he will raise, then 500 -x - y is the number of turkeys to be raised. What is the convex of possible values of x and y which satisfy the restrictions.



b. Find the expression for the cost of raising x chickens, y ducks, and (500 - x - y) turkeys. Find the total amount he gets for these birds. Compute the profit which he would make under the circumstances.

Solution:

S(x,y)=3.00x+2.00y+T(500 - x - y) C(x,y)=1.50x+1.00y+4(500 - x - y)P(x,y)=1.50x+1.00y+(T - 4)(500 - x - y)

c. If T=\$6.00, show that to obtain the maximum profit the farmer should raise only turkeys.

Solution:

P(0,0)=1.50(0)+1.00(0)+(6 - 4)(500 - 0 - 0)=\$1000.00

d. If T=\$5.00, show that he should raise only chickens and find a maximum profit.

Solution:

P(500,0)=1.50(500)+1.00(0)+(5 - 4)(500-500-0)= 750.00

 e. If T=\$5.50, show that he can raise any combination of chickens and turkeys and find a maximum profit.

Solution:

P(500,0)=1.50(500)+1.00(0)+(5.5 - 4)(500-500-0)=\$750.00 P(0,0)=1.50(0)+1.00(0)+(5.5 - 4)(500-0-0)=\$750.00

Show if the price of turkeys drops below
 \$5.50, the farmer should raise only chickens.

P(0,300)=1.50(0)+1.00(300)+(5.49-4.00)(500-0-300)=\$598.00 P(200,300)=1.50(200)+1.00(300)+(5.49-4.00)(500-200-300) =\$650.00 P(0,0)=1.50(0)+1.00(0)+(5.49-4.00)(500-0-0)=\$745.00 P(500,0)=1.50(500)+1.00(0)+(5.49-4.00)(500-500-0)=\$750.00 g. Show that if the price is above \$5.50 he should raise only turkeys.

P(0,0)=1.50(0)+1.00(0)+(5.51-4.00)(500-0-0)=\$755.00 P(500,0)=1.50(500)+1.00(0)+(5.51-4.00)(500-500-0)=\$750.00 P(200,300)=1.50(200)+1.00(300)+(5.51-4.00)(500-200-300)=\$650.00

P(0,300)=1.50(0)+1.00(300)+(5.51-4.00)(500-0-300)=\$602.00

BIBLIOGRAPHY

- Dolciani, Mary P. <u>Modern Introductory Analysis</u>. New York: Houghton Mifflin Company, 1964.
- Gass, Saul I. Linear Programming. New York: McGraw-Hill Book Company, 1964.
- Heady, Earl O. Linear Programming Methods. Ames, Iowa: The Iowa State University Press, 1964.
- Johnson, Richard E. Modern Algebra. Reading Massachusetts: Addison-Wesley Inc., 1962.
- Kemeny, John G. <u>Finite Mathematics</u>. Englewood Cliffs, New Jersey: Prentice-Hall Inc., 1957.