

Increasing the role of the D -basis in applications

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Based on papers:

"Ordered direct basis of a finite closure system"

joint work with J.B.Nation and R.Rand, Disc. Appl. Math. 2013

"Discovery of the D-basis in binary tables based on hypergraph dualization", 2012

joint work with J.B.Nation, submitted to Theoretical Computer Science, in arxiv

"Measuring the implications of the D-basis in analysis of data in biomedical studies", 2015

joint work with J.B.Nation, G. Okimoto, K. Alibek and others, Proceedings of ICFCA-2015, Spain

Last paper's support:

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“ Algebraic methods of data retrieval”
Nazarbayev University, 2013-2015
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Ministry of Healthcare and Social Development of RK

History of events

- Novi Sad Algebraic Conference, 2005, Kira's talk on "Relatively convex sets and Jamison problem"
- meeting Gyuri Turan, AMS conference in Urbana-Champaign in 2009
- visiting Turan and Bob Sloan in Chicago in 2010, Bertet-Monjardet's paper in TCS, 2010, just out
- first draft of D -basis paper, summer 2010 in Chicago
- Robert Rand and his honor's project, 2010-2011
- talk on the D -basis at RUTCOR seminar, with Endre Boros and Vladimir Gurvich attending, October 2011
- visit of Karell Bertet to New York, May 2012
- first version of paper on the D -basis retrieval, November 2012
- Kira's arrival in Astana, on-line course with Yeshiva University students, grant of Nazarbayev University, Spring 2013

- 1 Closure systems, lattices and implications
- 2 Famous implicational bases
- 3 D -basis
- 4 Ordered direct bases
- 5 Binary tables and Galois connection
- 6 D -basis retrieval from the binary table

Closure systems

$\langle X, \phi \rangle$ is a *closure system*, if

- X is non-empty set (finite in this talk);
- ϕ is a closure operator on X , i.e. $\phi : 2^X \rightarrow 2^X$ with
 - (1) $Y \subseteq \phi(Y)$;
 - (2) $Y \subseteq Z$ implies $\phi(Y) \subseteq \phi(Z)$;
 - (3) $\phi(\phi(Y)) = \phi(Y)$, for all $Y, Z \subseteq X$.
- Closed set: $A = \phi(A)$;
- Lattice of closed sets: $Cl(X, \phi)$.

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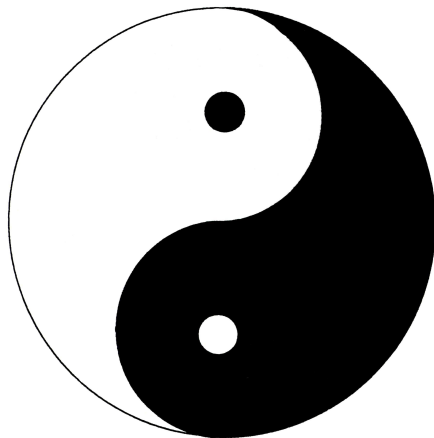
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Yin Yang of a closure system

Algebraic part of a closure system: lattice of closed sets



Logic part of a closure system: set of implications.

Lattices and closure systems

Proposition

Every finite lattice L is the lattice of closed sets of some closure system $\langle X, \phi \rangle$.

- Take $X = \text{Ji}(L)$, the set of join-irreducible elements: $j \in \text{Ji}(L)$, if $j \neq 0$, and $j = a \vee b$ implies $j = a$ or $j = b$;
- Define $\phi(Y) = \{j \in \text{Ji}(L) : j \leq \bigvee Y\}$, $Y \subseteq X$.
- Proof of $L \cong \text{Cl}(X, \phi)$: every element $x \in L$ corresponds to ϕ -closed set of all join irreducibles below x .
- So defined closure system is always *standard*.

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Standard closure systems

- Closure system $\langle X, \phi \rangle$ is **standard**, when for no $x \in X$ there exists $Y \subseteq X \setminus \{x\}$ such that $\phi(x) = \phi(Y)$.
- For every closure system $\langle Y, \phi \rangle$ one can find $X \subseteq Y$ such that, with restriction ϕ_X of ϕ on X , one obtains the *standard* closure system $\langle X, \phi_X \rangle$, with the lattice of closed sets isomorphic to $Cl(Y, \phi)$.
- Moreover, for every $y \in Y \setminus X$ we have $\phi(y) = \phi(X')$, for some $X' \subseteq X$.

Example: Building a closure system associated with lattice A_{12} .

$X = \text{Ji}(A_{12}) = \{1, 2, 3, 4, 5, 6\}$. $\phi(\{4, 6\}) = \{1, 3, 4, 6\}$, $\phi(\{2, 4\}) = X$ etc.

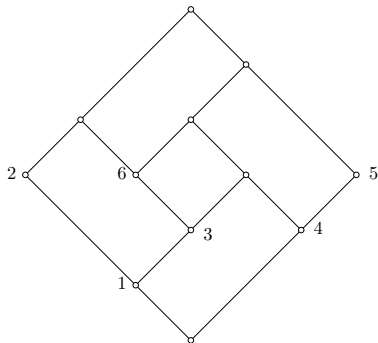


Figure: A_{12}

Closure systems and implications

- An implication σ on X : $Y \rightarrow Z$, for $Y, Z \subseteq X$, $Z \neq \emptyset$.
- σ -closed subset A of X : if $Y \subseteq A$, then $Z \subseteq A$.
- Closure system $\langle X, \phi_{\mathcal{S}} \rangle$ defined by set \mathcal{S} of implications on X : A is closed, if it is σ -closed, for each $\sigma \in \mathcal{S}$
- Every closure system $\langle X, \psi \rangle$ can be presented as $\langle X, \phi_{\mathcal{S}} \rangle$, for some set \mathcal{S} of implications on X .
- Example: $\mathcal{S} = \{A \rightarrow \phi(A) : A \subseteq X, A \neq \phi(A)\}$.

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Operator and sets of implications

Note:

- Every set of implications \mathcal{S} on X defines *unique* closure operator on X .
- There exist *numerous* sets of implications that define the same operator on X .

Example: Let $X = \{a, b, c\}$. Consider $\mathcal{S}_1 = \{a \rightarrow bc\}$ and $\mathcal{S}_2 = \{a \rightarrow bc, ab \rightarrow c, ac \rightarrow b, a \rightarrow b, bc \rightarrow c\}$.

The closure systems defined by \mathcal{S}_1 and \mathcal{S}_2 are the same.

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The bases of a closure system

Term *a base* or *a basis* is used when the set of implications \mathcal{S}' that defines the same closure system satisfies some condition of minimality.

We mention two famous bases: **canonical** and **canonical unit direct (CUD)**.

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D. Maier, *Minimum covers in the relational database model*, JACM **27** (1980), 664–674.

J.L. Guiques, V. Duquenne, *Familles minimales d'implications informatives résultant d'une tables de données binaires*, Math. Sci. Hum. **95** (1986), 5–18.

- Define *critical subsets of X* for a given closure system $\langle X, \phi \rangle$.
- Canonical basis \mathcal{S}_C is $\{C \rightarrow B : C \text{ is critical, } B = \phi(C) \setminus C\}$.
- If \mathcal{S} is any other set of implications generating $\langle X, \phi \rangle$, then for every critical set C one can find $(C' \rightarrow D) \in \mathcal{S}$ such that $C' \subseteq C$, and no other critical or closed set Y with $C' \subseteq Y \subset C$.
- \mathcal{S}_C is the *minimum* basis among all the bases generating $\langle X, \phi \rangle$.

Definition

Set of implications \mathcal{S} defining ϕ on A is called *minimum basis* if $|\mathcal{S}|$ is minimal among all sets of implications defining ϕ .

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Canonical bases from the other

A. Day, *The lattice theory of functional dependencies and normal decompositions*, Int.J.Alg. Comp. **2**(1992), 409–431.

For every set of implications \mathcal{S} , one can find the canonical basis \mathcal{S}_C defining the same operator in time $O(|s(\mathcal{S})|^2)$.

Here the size $s(\mathcal{S})$ of the set of implications $\mathcal{S} = \{X_i \rightarrow Y_i : i \leq n\}$, is the number $s(\mathcal{S}) = |X_1| + |Y_1| + \dots + |X_n| + |Y_n|$.

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Canonical direct unit basis

K.Bertet, B.Monjardet, *The multiple facets of the canonical direct unit implicational basis*, Theoretical Computer Science 411 (2010), 2155-2166.

Basis \mathcal{S} is *unit*, if it comprises implications $Y \rightarrow b$, with the singleton $b \in X$ on the right.

Given unit basis \mathcal{S} and $Y \subseteq X$, define

$$\pi_{\mathcal{S}}(Y) = Y \cup \bigcup \{b : (A \rightarrow b) \in \mathcal{S}, A \subseteq Y\}.$$

$$\text{Then } \phi_{\mathcal{S}}(Y) = \pi_{\mathcal{S}}(Y) \cup \pi_{\mathcal{S}}^2(Y) \cup \pi_{\mathcal{S}}^3(Y) \cup \dots$$

A unit implicational basis is called *direct*, if

$$\phi_{\mathcal{S}}(Y) = \pi_{\mathcal{S}}(Y), \text{ for all } Y \subseteq X.$$

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Canonical direct unit basis

K.Bertet, B.Monjardet, *The multiple facets of the canonical direct unit implicational basis*, Theoretical Computer Science 411 (2010), 2155-2166.

Basis \mathcal{S} is *unit*, if it comprises implications $Y \rightarrow b$, with the singleton $b \in X$ on the right.

Given unit basis \mathcal{S} and $Y \subset X$, define

$$\pi_{\mathcal{S}}(Y) = Y \cup \bigcup \{b : (A \rightarrow b) \in \mathcal{S}, A \subseteq Y\}.$$

$$\text{Then } \phi_{\mathcal{S}}(Y) = \pi_{\mathcal{S}}(Y) \cup \pi_{\mathcal{S}}^2(Y) \cup \pi_{\mathcal{S}}^3(Y) \cup \dots$$

A unit implicational basis is called *direct*, if

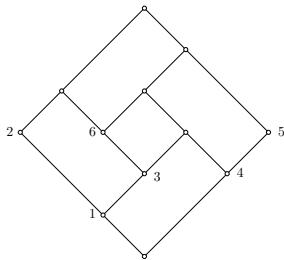
$$\phi_{\mathcal{S}}(Y) = \pi_{\mathcal{S}}(Y), \text{ for all } Y \subseteq X.$$

Example

Canonical basis \mathcal{S}_C of $\langle \text{Ji}(A_{12}), \phi \rangle$ has 8 implications:

$2 \rightarrow 1, 6 \rightarrow 13, 3 \rightarrow 1, 5 \rightarrow 4, 14 \rightarrow 3, 123 \rightarrow 6, 1345 \rightarrow 6, 12346 \rightarrow 5.$

Consider $Y = \{2, 4\}$. Then $\pi(Y) = \{2, 4, 1\}$, $\pi^2(Y) = \{2, 4, 1, 3\}$,
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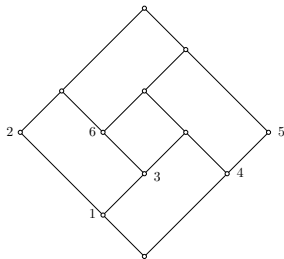


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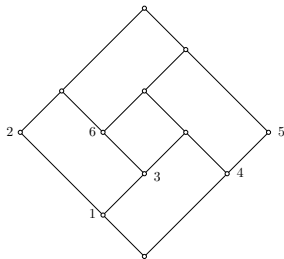


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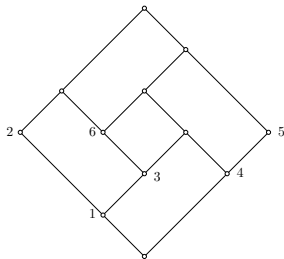


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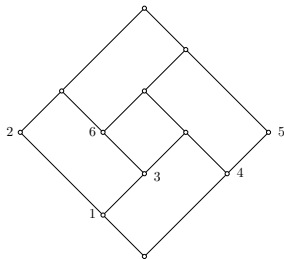
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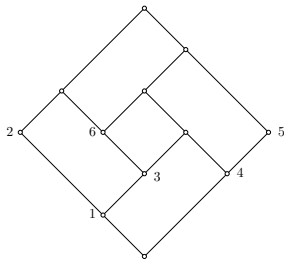


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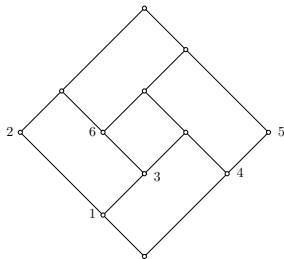
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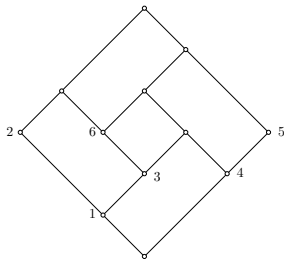
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Canonical unit basis \mathcal{S}_U for $\langle \text{Ji}(A_{12}), \phi \rangle$ has 13 implications:
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 $23 \rightarrow 6, 15 \rightarrow 6, 25 \rightarrow 6, 24 \rightarrow 5, 24 \rightarrow 6.$

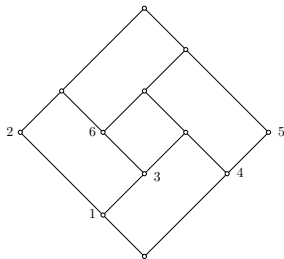
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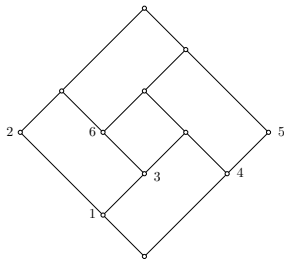
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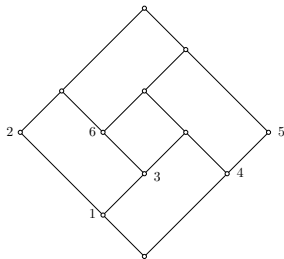
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Various unit direct bases surveyed in B-M:

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The full information about finite lattice L can be compactly recorded in

- partially ordered set of join-irreducible elements $\langle \text{Ji}(L), \leq \rangle$;
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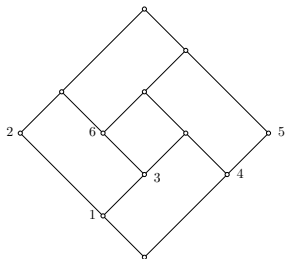


Figure: A_{12}

For lattice A_{12} , the poset of join-irreducible elements is:
 $\langle \text{Ji}(A_{12}), \leq \rangle = \langle \{1, 2, 3, 4, 5, 6, \}, 1 \leq 2, 1 \leq 3 \leq 6, 4 \leq 5 \rangle$.

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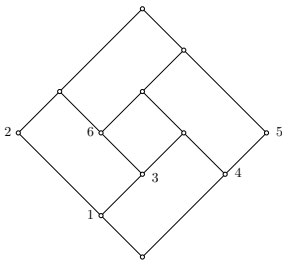
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Examples: $3 \leq 1 \vee 4$, or $6 \leq 2 \vee 5$.

A join-cover $j \leq j_1 \vee \dots \vee j_k$ is called *minimal*, if none of j_1, \dots, j_k can be replaced by smaller join-irreducibles or dropped so that one gets another join-cover.

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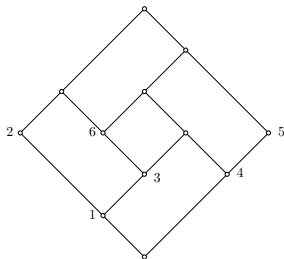
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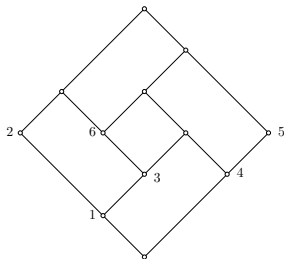
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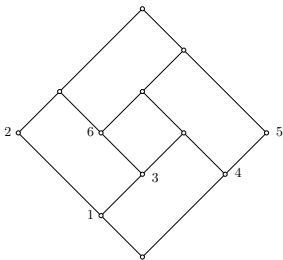
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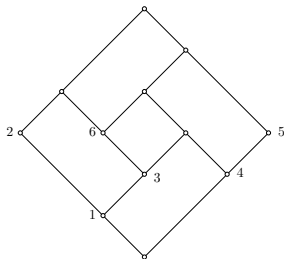
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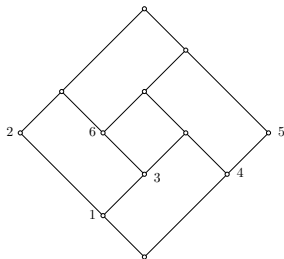
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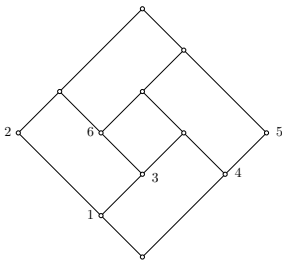
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Definition

Let $\langle X, \phi \rangle$ be a standard closure system with $L = Cl(X, \phi)$.

The set of implications S_D is called the D -basis of $\langle X, \phi \rangle$, if it is made of two parts:

- $\{a \rightarrow b : b \in \phi(a)\}$; equivalently, $b \leq a$ in $\langle Ji(L), \leq \rangle$.
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The set of implications S_D is called the D -basis of $\langle X, \phi \rangle$, if it is made of two parts:

- $\{a \rightarrow b : b \in \phi(a)\}$; equivalently, $b \leq a$ in $\langle Ji(L), \leq \rangle$.
This part is called a binary part of the basis.
- $\{j_1 \dots j_k \rightarrow j : j \leq j_1 \vee \dots \vee j_k$ is a minimal cover in $L\}$.

The D -relation and the D -basis

Why D in the name of the basis?

D -relation is an important concept in the study of free lattices, see R. Freese, J. Jezek, J.B. Nation "Free Lattices", 1995.

Definition

Given $b, c \in \text{Ji}(L)$, one defines bDc , when there is a minimal cover $b \leq c \vee j_1 \vee \dots \vee j_k$, for some $j_1, \dots, j_k \in \text{Ji}(L)$.

Equivalently: bDc iff there exists $Y \rightarrow b$ in the D -basis such that $c \in Y$.

Important: for every $Y \rightarrow b$ in the D -basis, $Y \subseteq bD = \{c \in \text{Ji}(L) : bDc\}$.

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The D -basis and the canonical unit basis

Theorem (ANR-2013)

- S_D generates $\langle X, \phi \rangle$, i.e., D -basis is, indeed, a basis of this closure system.
- S_D is a subset of the canonical unit basis S_U .

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Comparison

Canonical direct unit basis \mathcal{S}_U for $\langle \text{Ji}(A_{12}), \phi \rangle$ has 13 implications.

$2 \rightarrow 1, 6 \rightarrow 1, 6 \rightarrow 3, 3 \rightarrow 1, 5 \rightarrow 4, 14 \rightarrow 3, 24 \rightarrow 3, 15 \rightarrow 3,$
 $23 \rightarrow 6, 15 \rightarrow 6, 25 \rightarrow 6, 24 \rightarrow 5, 24 \rightarrow 6.$

D-basis has 9 implications.

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Ordered iteration

Suppose the set of implications S are put into some linear order:

$$S = \langle s_1, s_2, \dots, s_n \rangle.$$

A mapping $\rho_S : 2^X \rightarrow 2^X$ associated with this ordering is called an *ordered iteration* of S :

- For any $Y \subseteq X$, let $Y_0 = Y$.
- If Y_k is computed and implication s_{k+1} is $A \rightarrow b$, then

$$Y_{k+1} = \begin{cases} Y_k \cup \{b\}, & \text{if } A \subseteq Y_k, \\ Y_k, & \text{otherwise.} \end{cases}$$

- Finally, $\rho_S(Y) = Y_n$.

Definition

An implicational basis of $\langle X, \phi \rangle$, together with its order: $S = \langle s_1, \dots, s_n \rangle$ is called *ordered direct*, if $\rho(Y) = \phi(Y)$, for every $Y \subseteq X$.

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Example

Take \mathcal{S}_C , the set of implications for $\langle \text{Ji}(A_{12}), \phi \rangle$, in its original order:
 $2 \rightarrow 1, 6 \rightarrow 13, 3 \rightarrow 1, 5 \rightarrow 4, 14 \rightarrow 3, 123 \rightarrow 6, 1345 \rightarrow 6, 12346 \rightarrow 5$.

Consider $Y = \{2, 4\}$.

Then $\pi(Y) = \{2, 4, 1\}$, while
 $\rho(Y) = \{2, 4, 1, 3, 6, 5\} = \phi(Y)$.

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Ordered direct basis

Theorem (ANR-2013)

- S_D is an ordered direct basis, associated with any order, where the binary part precedes the rest of implications.
- There exist closure systems, for which the canonical basis cannot be ordered.

Algorithmic aspects

If \mathcal{S} is a any unit direct basis of $\langle X, \phi \rangle$ of size $s = s(\mathcal{S})$ with m implications, then

- it takes time $O(s^2)$ to extract D -basis from \mathcal{S} ;
- it takes time $O(m)$ to put extracted D -basis into a proper order.

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Mid-talk conclusions

- For all practical purposes canonical direct unit basis can be replaced by the considerably shorter D -basis.
- The D -basis preserves the property of direct processing, assuming negligible pre-processing time for its ordering.

Binary tables and the Galois connection

	C_1	C_2	DE	PDE	MP
1	1	0	0	0	0
2	1	1	1	0	0
3	1	1	1	1	0
4	1	1	0	1	0
5	0	0	1	1	1
6	0	0	0	1	1

$U = \{1, 2, 3, 4, 5, 6\}$ is the set of *objects*.

$A = \{C_1, C_2, DE, PDE, MP\}$ is the set of *attributes*.

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Closure systems associated with a binary table

Table $\mathcal{T} = \langle U, A, R \rangle$, where $R \subseteq A \times U$ is a *relation* between U and A .

$S_A : 2^A \rightarrow 2^U$ is a *support function* on A

$S_A(Z) = \{y \in U : (z, y) \in R, \text{ for all } z \in Z\}$, for $Z \in 2^A$.

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Lemma

Let $\mathcal{T} = \langle U, A, R \rangle$ be a table with support functions S_A and S_U .

- S_A and S_U yield Galois connection between the power sets 2^A and 2^U .
- Mapping $\phi_A : Z \mapsto S_U(S_A(Z))$, with $Z \in 2^A$, is a closure operator on A .
- Similarly, mapping $\phi_U : Y \mapsto S_A(S_U(Y))$, with $Y \in 2^U$, is a closure operator on U .

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Lattice and implicational sets of a binary table

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1	1	0	0	0	0
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- The lattice of closed sets: *Galois lattice* or *concept lattice*.
- Implications: usually on the set of attributes.
Examples: $(C_2 \rightarrow C_1)$, $(C_1, DE \rightarrow C_2)$.

Retrieval of a basis from a binary table

- As-of 2012 talk of K. Bertet at Combinatorics Seminar of CUNY, both problems of canonical and canonical unit direct bases generation from a binary table were reported open.
- All existing algorithms required generation of a closure system or a concept lattice, before attempting the basis retrieval.
- The size of the closure system or concept lattice is (worst case) exponential in the size of the table.

Complexity of retrieval of the canonical basis

*Courtesy of Vincent Duquenne and Sergei Kuznetsov

Nails in the Coffin

On the Names of Implication

Sergei O. Kuznetsov

Introduction

Aliases of Implication

Algorithmic Complexity and Scalability Problems

Implications and Big Data Challenge

The number of pseudo-intents may be exponential [S.Kuznetsov, 2004]

Enumerating pseudo-intents in arbitrary order is NP-hard?

Counting pseudo-intents is #P-hard [S.Kuznetsov, 2004]

Enumerating pseudo-intents in the lectional order is impossible with polynomial delay unless P=NP [F.Distel, 2010]

Enumerating pseudo-intents in the reverse lectional order is impossible with polynomial delay unless P=NP [M.Babin, S.Kuznetsov, 2010]

Recognizing whether a subset of attributes is a pseudo-intent is coNP-complete [M.Babin, S.Kuznetsov, S.Obedkov, 2006-2010]

Enumerating pseudo-intents in arbitrary order is TRANSHP-hard [B.Sertkaya 2009]

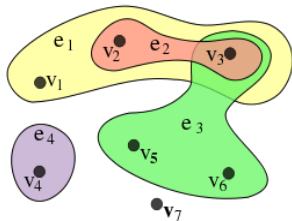
Hopes for scalability of stem base

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Retrieval of the CUD basis and the D -basis

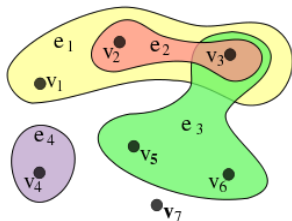
- U. Ryssel, F. Distel and D. Borchmann, *Fast algorithms for implication bases and attribute exploration using proper premises*, Ann. Math. Art. Intell. **70** (2014), 25–53.
- K. Adaricheva, J.B. Nation, *Discovery of the D -basis in binary tables based on hypergraph dualization*, arxiv, subm. TCS, 2015.

Hypergraph Dualization problem



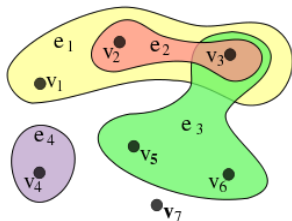
- $V = \{v_1, \dots, v_7\}$ is the set of vertices, $E = \{e_1, \dots, e_4\} \subseteq 2^V$ is the set of hyper-edges.
- $H = \langle V, E \rangle$ is a hypergraph.
- $T \subseteq V$ is a *transversal*, if $T \cap e_i \neq \emptyset$, for all $e_i \in E$.
- Problem: find all *minimal* transversals of given hypergraph H .
- Solution: $H^d = \langle V, E^d = \{v_4 v_3, v_4 v_2 v_5, v_4 v_2 v_6\} \rangle$ is a dual hypergraph.

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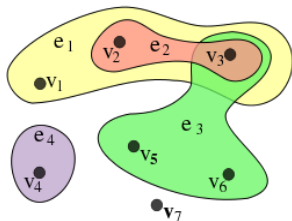
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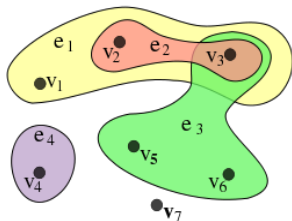
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- Solution: $H^d = \langle V, E^d = \{v_4 v_3, v_4 v_2 v_5, v_4 v_2 v_6\} \rangle$ is a dual hypergraph.

Hypergraph Dualization problem



- $V = \{v_1, \dots, v_7\}$ is the set of vertices, $E = \{e_1, \dots, e_4\} \subseteq 2^V$ is the set of hyper-edges.
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Algorithmic solutions to Hypergraph Dualization

- M. Fredman and L. Khachiyan, *On the complexity of dualization of monotone disjunctive forms*, J. Algorithms **21** (1996), 618–628.
Problem of generating all minimal transversals can be solved in time $O(N^{O(\log N)})$ time, where N is the size of input and output.
- Test results of code implementation of algorithm are presented in L. Khachiyan, E. Boros, K. Elbassioni and V. Gurvich, Disc. Appl. Math. **154** (2006), 2350–2372.
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Instance of HD problem for the D -basis retrieval

- Fix $b \in A$, one particular attribute. The goal: obtain all $Y \rightarrow b$ from the D -basis.
- Due to the definition of the D -basis, all such Y are subsets of $bD = \{c \in A : bDc\}$.
- Use Lemma 11.10 from *Free Lattices* book: bDc , for $b, c \in \text{Ji}(L)$ iff there exists $p \in \text{Mi}(L)$ such that $b \uparrow p$ and $p \downarrow c$.
- Attributes of the table play the role of join-irreducibles and the objects the role of meet-irreducibles of the concept lattice.
- \uparrow and \downarrow relations between the attributes and objects of the table can be found in time polynomial in the size of the table.
- Hypergraph associated with the fixed $b \in A$: set of vertices $V = bD$; hyperedges are $H_p = \{c \in bD : cRp\}$, for each $p \in U$, for which $b \uparrow p$.

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*Pictures: courtesy of J.B Nation



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Then we relocate to the Almaty region, for September 11-13, Friday to Sunday, for the second, less formal half of our program, consisting of additional lectures, mutual research collaboration, and opportunities for hiking in the mountains.

Contact: [Kira Adaricheva](#) or [David Stanovsky](#)



Regards from JB Nation



Figure: JB during hiking in NY State

Acknowledgments

The following people assisted in the project:

- Joshua Blumenkopf (Yeshiva College, New York, 3d year Physics major in 2013)
- Toviah Moldwin (Yeshiva College, New York, 3d year CS major in 2013)
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- Gordon Okimoto (University of Hawaii Cancer Center)
- Nazar Seidalin (hospital of Medical Holding, Astana)
- Kenneth Alibek (Graduate School of Medicine, NU)
- Vyacheslav Adarichev (Biology Department, NU)
- Adina Amanbekyzy (Math Department TA, NU)
- Shuchismita Sarkar (Math Department TA, NU)
- Alibek Sailanbayev (2d year CS student, NU)
- Ulrich Norbistrath (CS Department, NU)
- Mark Sterling (CS Department, NU)