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## LR-PARSING DERIVED

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# LR-parsing derived 

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#### Abstract

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## 0. Introduction

The purpose of this note is to derive and prove the LR-parsing algorithm of Knuth (cf. [7]). The reader is advised to forget momentarily most of what he or she might know of this algorithm. We do not start from scratch completely. The reader is supposed to know context-free grammars and languages, and rightmost derivations. The major prerequisite for reading this note is an acquaintance with predicate calculus and a tendency towards formal verification.

The main argument can be summarised as follows. For any context-free grammar we derive a nondeterministic algorithm that may accept any sentence of the language and cannot accept other strings. If the grammar satisfies the $\operatorname{LR}(k)$ condition, the algorithm is deterministic and accepts all sentences of the language.

The structure of the paper is as follows. In Section 1 we compare the angelic nondeterminacy of language theory with the demonic nondeterminacy usually associated with program correctness. In Section 2 we fix some notations. A first approximation of the parsing algorithm is developed in Section 3.

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Section 4 forms the heart of the paper. We introduce a "heuristic" predicate to guide the nondeterminacy by means of $k$ look-ahead symbols. This predicate is used to derive an algorithm in which certain sets of strings are needed. Subsequently, we derive a recurrence equation for these sets. The sets are used in algorithm $P 2$, which is proved here to be conditionally correct in the sense that it can only terminate for sentences of the language.

In Section 5 we investigate the relationship between the heuristic predicate and rightmost derivations. The results are used in Section 6 to prove that under angelic nondeterminacy any sentence of the language can be accepted by program $P 2$. Section 7 contains the traditional LR $(k)$-parsing algorithm, called $P 4$, that uses a finite automaton and a stack of item sets. It is obtained as an optimisation of program $P 2$.

In Section 8 we reach the conclusion: if the grammar satisfies the $\operatorname{LR}(k)$ condition, algorithm $P 4$ accepts the language. It is also shown that an easy modification of the algorithm generates an error message if the input string does not belong to the language.

Section 9 is devoted to the determination of a set-valued function $R k s$ that is introduced in Section 4. Here the complications appear that are due to the possibility of $\varepsilon$-productions. Finally, in Section 10 we summarise some distinctive features of our approach in comparison with Knuth's paper [7].

Our presentation of LR-parsing is an interplay between parsing theory and program development. The theory could have been separated completely from the program development. We prefer, however, to develop the theory according to the needs of the program. For the ease of the reader, we use the symbol "Theory" to indicate the fragments of the parsing theory, and the symbol "Program" for the parts of the program development.

## 1. Nondeterminacy and language acceptors

Program. In language theory and complexity theory, nondeterminacy of some mechanism usually leads to the question of whether the mechanism admits at least one computation with a certain property (cf. [6, p. 19, p. 163]). This point of view is called the angelic appreciation of nondeterminacy. In programming methodology one usually asks whether all (or all terminating) computations satisfy a certain property (cf. [1, 7.3; 2; 3, Chapter 7]). This point of view is called the demonic appreciation. Here we investigate a possibly nondeterministic algorithm for the parsing of languages. Therefore, we must be careful about the appreciation of nondeterminacy.

If $X$ is a boolean function on the state space, we let $[X]$ denote the proposition that $X$ holds everywhere on the state space. In particular, $[X \Rightarrow Y]$ is the proposition that $\neg X \vee Y$ holds everywhere, i.e. that $X$ is stronger than $Y$. For a command $P$ we write wp.P.X to denote the weakest precondition such that every computation
of $P$ terminates in a state where $X$ holds. We write wIp.P. $X$ to denote the weakest precondition such that every terminating computation of $P$ terminates in a state where $X$ holds (cf. [3, Chapter 7]). The predicate transformers $w p$ and wlp represent the demonic appreciation of nondeterminacy (and wlp corresponds to conditional correctness).

Let us introduce the weakest angelic precondition wap, by specifying that wap.P.X is the weakest precondition such that $P$ has at least one computation that terminates in a state where $X$ holds. Clearly, $P$ has a computation that terminates in a state where $X$ holds if and only if it is not the case that every terminating computation terminates in a state where $\neg X$ holds. Therefore, we have

$$
\begin{equation*}
[\text { wap.P. } X \equiv \neg \text { wlp.P. }(\neg X)] . \tag{0}
\end{equation*}
$$

If $P$ has at least one computation and if every computation of $P$ terminates in a state where $X$ holds, then $P$ has some computation that terminates in a state where $X$ holds. This means

$$
\begin{equation*}
[\neg w p . P . f a l s e \wedge \text { wp.P.X } \Rightarrow \text { wap. P.X]. } \tag{1}
\end{equation*}
$$

In this note we only consider total commands, i.e. commands $P$ that satisfy
(2) [नwp.P.false].

Therefore, formula (1) simplifies to
(3) $\quad[w p . P . X \Rightarrow$ wap.P.X].

We now come to the parsing problem. Recall that a language is a set of strings. A program $P$ is called an acceptor of language $L$ if and only if $m \in L$ is a necessary and sufficient precondition for termination of $P$. Sufficiency means that $m \in L$ implies termination, i.e.

$$
\begin{equation*}
[m \in L \Rightarrow \text { wp.P.true }] . \tag{4}
\end{equation*}
$$

Necessity means that $m \notin L$ implies nontermination, i.e.

$$
\begin{equation*}
[m \notin L \Rightarrow \text { wlp.P.false }] . \tag{5}
\end{equation*}
$$

With contraposition we get from (0) that (5) is equivalent to

$$
\begin{equation*}
[\text { wap.P.true } \Rightarrow m \in L] . \tag{6}
\end{equation*}
$$

In general we do not completely know the language. So, the acceptance problem of context-free languages must be posed in terms of grammars. We only consider context-free grammars. For such a grammar $G$, we write $L . G$ to denote the language that is generated. The problem is to construct a program P.G dependent of a parameter $G$ such that for every grammar $G$ program $P . G$ is an acceptor of the language $L . G$.

It is not difficult to construct a program $P . G$ such that $m \in L . G$ if and only if $P . G$ has some terminating computation, i.e.

$$
\begin{equation*}
[m \in L . G \equiv \text { wap. }(P . G) . t r u e] . \tag{7}
\end{equation*}
$$

Usually, such a program P.G has a nondeterminacy that reflects the freedom any user of the grammar has to generate arbitrary sentences of the language. Clearly, formula (7) implies (6), but it does not imply (4). Nevertheless, it follows that P.G is an acceptor of $L . G$ if $P . G$ satisfies the additional condition

$$
\begin{equation*}
[\text { wap. }(P, G) . t r u e \equiv w p .(P . G) . t r u e], \tag{8}
\end{equation*}
$$

i.e. that termination of $P . G$ is deterministic. Anyhow, since angelic nondeterminacy is not well implementable, it seems reasonable to impose condition (8). There are two possibilities to get (8) for a parametrised program P.G that satisfies (7). In both cases we restrict the class of grammars. The first possibility is to make the program deterministic by strengthening the guards of the nondeterminate choices. In this way, condition (8) is forced, but (7) may have been invalidated. The modified program is correct for the grammars for which (7) remains valid. These grammars, however, may be difficult to characterise.

The other possibility is to preserve program P.G and to characterise the grammars $G$ for which P.G happens to be deterministic. In this way no new proof obligations appear. This approach has the drawback that in the design of program $P . G$ we have the implicit consideration that the class of grammars for which (8) holds should be as large as possible. Nevertheless, this is the way to derive LR-acceptors (and presumably LL-acceptors as well).

It may be mentioned here that the construction of an acceptor is only one step in the construction of a parser, which has the additional tasks of building a derivation tree and of error detection or error recovery. Usually, the construction of a derivation tree can be implemented as a side-effect of the control flow of the acceptor. Error handling requires that the nontermination be replaced by the generation of adequate error messages. In the remainder of this paper we concentrate on the acceptance problem. Error detection is mentioned briefly in Section 8.

## 2. Notational conventions

In each section the formulae are numbered consecutively. For reference to formulae from other sections we use the convention that $i(j)$ refers to formula ( $j$ ) of Section i.

## Functions

The application of a function on an argument is denoted by the infix-operator ".". The operator "." binds stronger than all other operators. It binds from left to right, so as to allow currying.

## Quantifications and sets

We write ( $\forall x \in X: b . x: f . x$ ) to denote the predicate that $f . x$ holds for all $x$, where the dummy $x$ ranges through the elements of $X$ that satisfy predicate $b$. If $b . x$ is
omitted, the default value true is meant. The indication " $\in X$ " can be omitted if the type of $x$ is clear from the context. Similar quantifications are

$$
\begin{array}{ll}
(\exists x \in X: b . x: f . x): & " f x \text { holds for at least one } x \text { with } b . x ", \\
(\cup x \in X: b . x: f . x): & \text { "the union of the } f . x \text { with } b . x ", \\
(\text { SET } x \in X: b \cdot x: f . x): & \text { "the set of the } f . x \text { with } b x " \text { ". }
\end{array}
$$

The empty set is denoted $\emptyset$. The braces " $\{$ " and " $\}$ " are only used to enclose comments within formal proofs.

## Strings

Let $A$ be a set of symbols. We use $A^{*}$ to denote the set of the finite strings of elements of $A$. The elements of $A$ are regarded as strings of length 1 . So $\boldsymbol{A}$ is a subset of $A^{*}$. We write $\varepsilon$ to denote the empty string. Catenation of strings is denoted by means of the infix operator ";" (by convention ";" and $\varepsilon$ are not elements of A). The string functions head and tail are defined as usual: if $x=b ; y$ with $b \in A$ then head. $x=b$ and tail. $x=y$. We also need the string function last which is given by
(0) last. $(y ; b)=b, \quad$ if $b \in A$.

For a string $x$ the set of suffixes Suff. $x$ is given by

$$
\begin{equation*}
y \in \operatorname{Suff} . x \equiv\left(\exists z \in A^{*}:: x=z ; y\right) \tag{1}
\end{equation*}
$$

For any $y \in S u f f . x$ we define string $x-y$ by

$$
\begin{equation*}
x-y=z \equiv x=z ; y . \tag{2}
\end{equation*}
$$

The length of a string $x$ is denoted by $|x|$. If $i$ is an integer with $0 \leqslant i \leqslant|x|$, we write $x \mid i$ to denote the prefix of $x$ of length $i$. If $X$ and $Y$ are sets of strings, we write

$$
\begin{equation*}
X ; Y=(\text { SET } x \in X, y \in Y:: x ; y) . \tag{3}
\end{equation*}
$$

## 3. Two blind algorithms

We let $G=\langle V, T, P, S\rangle$ be a context-free grammar. Here, $T$ is the finite set of the terminal symbols, $V$ is the finite set of the nonterminal symbols, $V$ and $T$ are disjoint, $S \in V$ is the start symbol, and $P$ is the set of productions. Formally speaking, $P$ is a finite subset of the cartesian product $V \times A^{*}$ where $A$ is the disjoint union of $V$ and $T$.

We use the convention that the letters $b, c$, and $d$ represent symbols in $A$ and that the letters from $m$ to $z$ represent strings over $A$. In the programs we use strings $s$ and $z$ over $A$ and strings $m, p, q, r$, and $t$ over $T$; the letter $m$ represents the constant input string, the other letters are program variables subject to the invariants $J 0$ of (3) and $J 1$ of (10) below.

Theory. In LR-parsing, we only consider rightmost derivations. These are formalised as follows. One step of a rightmost derivation is characterised by relation rm: for strings $x, y \in A^{*}$ we define

$$
\begin{align*}
& r m \cdot x \cdot y \equiv  \tag{0}\\
& \quad\left(\exists v \in A^{*}, w \in T^{*},\langle c, z\rangle \in P:: x=v ; c ; w \wedge y=v ; z ; w\right) .
\end{align*}
$$

The reflexive transitive closure of relation $r m$ is denoted by $r m^{*}$. So, formally, we have

$$
\begin{align*}
& r m^{*} \cdot x \cdot y \equiv\left(\exists i: i \geqslant 0: r m^{i} \cdot x \cdot y\right), \text { wherc }  \tag{1}\\
& r m^{0} \cdot x \cdot y \equiv x=y, \quad \text { and } \\
& r m^{i+1} \cdot x \cdot y \equiv\left(\exists z \in A^{*}:: r m^{i} \cdot x \cdot z \wedge r m \cdot z \cdot y\right)
\end{align*}
$$

It is well known (cf. [6, Section 4.3]) that the language generated by grammar $G$ is the set of the strings $m \in T^{*}$ with $r m^{*} . S . m$, that is

$$
\begin{equation*}
\left[m \in L . G \equiv m \in T^{*} \wedge r m^{*} . S . m\right] \tag{2}
\end{equation*}
$$

Program. The task of the algorithm is to read a given string $m \in T^{*}$ and to decide whether $\mathrm{rm}{ }^{*} . S . m$ holds. We assume that the string is read from left to right. So we have the invariant relation $m=p ; t$, where $p$ has been read and $t$ is the remainder of the input string $m$. Let string $s \in A^{*}$ represent the syntactic structure that has been recognised. Accordingly, we extend the invariant to

$$
\begin{equation*}
J 0: \quad m=p ; t \wedge r m^{*}, s . p \tag{3}
\end{equation*}
$$

This is known as the valid prefix property. Now the purpose of the algorithm is to establish (if possible) the validity of rm .. S.m. We observe that

$$
\begin{equation*}
\left[J 0 \wedge s=S \wedge t=\varepsilon \Rightarrow r m^{*} . S . m\right] \tag{4}
\end{equation*}
$$

So we need two kinds of actions: to read string $t$ and to process string $s$. The obvious candidate for a reading command is

$$
\begin{align*}
C 0=\mid[ & s:=(s ; \text { head. } t)  \tag{5}\\
& ; p:=(p ; \text { head. } t) \\
& ; t:=\text { tail. } t] \mid .
\end{align*}
$$

We calculate the weakest precondition of $C 0$ with postcondition $J 0$ in

$$
\begin{aligned}
& w p . C 0 . J 0 \\
\Leftarrow & \{(5) ;(3) ; \text { substitutions }\} \\
& t \neq \varepsilon \wedge m=p ; \text { head. } ; \text { tail. } t \wedge \mathrm{rm}^{*} .(s ; \text { head. } t) .(p ; \text { head. } t) \\
\equiv & \{(0),(1) \text { and head. } t \in T\} \\
& t \neq \varepsilon \wedge m=p ; t \wedge r m^{*} . s . p \\
\equiv & \{(3)\} \\
& J 0 \wedge t \neq \varepsilon .
\end{aligned}
$$

This proves
(6)

$$
[J 0 \wedge t \neq \varepsilon \Rightarrow w p . C 0 . J 0]
$$

In processing string $s$ we have more freedom. The second conjunct of (3) admits replacement of a segment $z$ of $s$ by a nonterminal $c$ if $\langle c, z\rangle \in P$ and if $z$ is followed in $s$ only by terminal symbols. Given a derivation of $m$, we assume that such a reduction is performed as soon as is possible in the repetition. Therefore, we consider only reductions of suffixes $z$ of $s$. So, we propose a command

$$
\begin{equation*}
D 0=|[s:=((s-z) ; c)]| . \tag{7}
\end{equation*}
$$

An adequate precondition is found in

> wp.D0.J0

$$
\begin{aligned}
\equiv & \{(3),(7) \text { and substitutions }\} \\
& m=p ; t \wedge z \in \text { Suff. } s \wedge r m^{*} .((s-z) ; c) \cdot p
\end{aligned}
$$

$$
\leftarrow\left\{(0) \text { and transitivity of } r m^{*}\right\}
$$

$$
m=p ; t \wedge z \in \text { Suff. } s \wedge\langle c, z\rangle \in P \wedge r m^{*} . s . p
$$

$$
\equiv\{(3)\}
$$

$$
J 0 \wedge\langle c, z\rangle \in P \wedge z \in \text { Suff. } s .
$$

This proves that

$$
\begin{equation*}
[J 0 \wedge\langle c, z\rangle \in P \wedge z \in \text { Suff.s } \Rightarrow \text { wp.D0.J0]. } \tag{8}
\end{equation*}
$$

Adding the obvious initialisation we get the program

One can easily verify the correctness of the initialisation. The body of the repetition is an alternative statement which terminates if and only if at least one of the guards holds. If the body terminates, it preserves the invariant $J 0$ by (6) and (8). Even if the body always terminates, the loop need not terminate. When the loop terminates, $J 0$ holds and $t=\varepsilon$ and $s=S$, so that $r m^{*} . S$. $m$ follows from (4). In that case, string $m$ has been recognised (notice that $r m^{*} . S . m$ is constant). This shows that program $P 0$ of ( 9 ) is conditionally correct, in the sense that formula $1(6)$ holds in the form

$$
\left[\text { wap.P0.true } \Rightarrow r m^{*} . S . m\right]
$$

Actually, 1(7) holds as well, but the fact is not useful for the rest of the development (it follows from the result of Section 6 below).

$$
\begin{align*}
& P 0=\mid[p:=\varepsilon ; t:=m ; s:=\varepsilon  \tag{9}\\
& \text {; do }\{J 0\} t \neq \varepsilon \vee s \neq S \rightarrow \\
& \text { if } t \neq \varepsilon \rightarrow C 0 \\
& \text { [ let }\langle c, z\rangle \in P \text { with } z \in \text { Suff } s \rightarrow D 0 \\
& \text { fi } \\
& \mathbf{o d}\left\{J 0 \wedge t=\varepsilon \wedge s=S \text {, and hence } r m^{*} . S . m\right\} \\
& \text { ] }] \text {. }
\end{align*}
$$

The parsing program $P 0$ of (9) may easily turn into a blind alley. In order to avoid this we shall allow more information concerning string $t$ to appear in the guards of the alternative statement. More precisely, we fix a number $k \geqslant 0$ and we let the choice between a shift $C 0$ or an adequate reduction $D 0$ be guided by ( $s ; q$ ) where $q$ is the prefix of $t$ of length $k$. To guarantee that $t$ has a prefix of length $k$, we extend string $m$ with a fixed string of length $k$, say $\perp^{k}$ where $\perp$ is a terminal symbol.

Remark. The decision to use a window of fixed size is rather arbitrary. The particular choice of the additional suffix $L_{-}{ }^{k}$ is irrelevant for the derivation and correctness of our version of LR-parsing. For immediate error detection, however, it is useful to postulate that the first symbol of the suffix (here $\perp$ if $k>0$ ) does not occur in the righthand side of any production.

We now replace program variable $t$ of $P 0$ by the catenation of two program variables $q \in T^{k}$ and $r \in T^{*}$ with the invariant

$$
\begin{equation*}
J 1: \quad m ; \perp^{k}=p ; q ; r \wedge r m^{*} . s . p . \tag{10}
\end{equation*}
$$

This invariant is established by the initialisation

$$
\begin{align*}
\text { In } 1= & \mid[~  \tag{11}\\
& ;=\varepsilon ; s:=\varepsilon \\
& ;=\left(m ; \perp^{k}\right) \mid k \quad\left\{\text { the first } k \text { symbols of } m ; \perp^{k}\right\} \\
& \left.; r:=\operatorname{tail}^{k} .\left(m ; \perp^{k}\right) \quad\{\text { the remainder }\}\right] \mid .
\end{align*}
$$

To preserve $J 1$, command $C 0$ is replaced by

$$
\begin{align*}
C 1= & \mid[~  \tag{12}\\
q & :=(q ; \text { head. } r) ; r:=\text { tail. } r \\
& ; s:=(s ; \text { head. }) ; p:=(p ; \text { head. } q) \\
& ; q:=\text { tail. } q] \mid .
\end{align*}
$$

A straightforward calculation (similar to the one that preceded (6)) yields

$$
\begin{equation*}
[J 1 \wedge r \neq \varepsilon \Rightarrow w p . C 1 . J 1] . \tag{13}
\end{equation*}
$$

Command $D 0$ remains useful and we get

$$
\begin{equation*}
[J 1 \wedge\langle c, z\rangle \in P \wedge z \in \text { Suff.s } \Rightarrow \text { wp.D0.J1]. } \tag{14}
\end{equation*}
$$

Now program $P 0$ is replaced by

$$
\begin{align*}
& P 1=\mid[\text { In } 1  \tag{15}\\
& \quad ; \quad \operatorname{do}\{J 1\} r \neq \varepsilon \vee s \neq S \rightarrow \\
& \quad \text { if } r \neq \varepsilon \rightarrow C 1 \\
& \quad \begin{array}{l}
\text { let }\langle c, z\rangle \in P \text { with } z \in \text { Suff.s } \rightarrow D 0 \\
\quad \text { i } \\
\text { od }\left\{J 1 \wedge r=\varepsilon \wedge s=S \text {, and hence } r m^{*} . S . m\right\}
\end{array} \\
& \\
& \text { ]|. }
\end{align*}
$$

Now all remarks made after program $P 0$ can be repeated. In fact, program $P 1$ may have string $q$ at its disposal, but it does not use this information.

## 4. A heuristic predicate

We now turn to the question of how to use the information contained in string $(s ; q)$ for the guidance of the nondeterminacy of program $P 1$ of $3(15)$. We strengthen the invariant so that choices that cannot be successful are recognised earlier. To this end, we introduce a condition that expresses that $(s ; q)$ is a prefix of a rightmost derivation of $\left(S ; 1^{k}\right)$, and that string $s$-last.s is fully interpreted, in the sense that none of its substrings will be replaced by a nonterminal (compare D0 in $3(7)$ ).

In other words, the condition is that $(s ; q)$ can be obtained from $\left(S ; 1^{k}\right)$ by zero or more steps of the following type. If last.s is a terminal symbol, the last symbol of $(s ; q)$ is removed. If last.s is a nonterminal, it is rewritten. Nonterminals in $s$-last.s are not rewritten since that would yield a string $s^{\prime}$ in which $s^{\prime}$-last. $s^{\prime}$ is not fully interpreted.

Theory. The set of strings that end in at least $k$ terminal symbols is denoted $\left(A^{*} ; T^{k}\right)$ (cf. 2(3)). Now the steps suggested above are formalised in relation $r k$ on ( $A^{*} ; T^{k}$ ), defined by

$$
\begin{align*}
& r k \cdot x . y \equiv  \tag{0}\\
& \quad(\exists b \in T:: x=y ; b) \\
& \quad \vee\left(\exists v \in A^{*}, w \in T^{k},\langle c, z\rangle \in P:: x=v ; c ; w \wedge y=v ; z ; w\right)
\end{align*}
$$

Notice that, since $y \in\left(A^{*} ; T^{k}\right)$, the first disjunct implics that the last $k+1$ symbols of string $x$ are terminals. We define relation $r k^{*}$ on $\left(A^{*} ; T^{k}\right)$ to be the reflexive transitive closure of $r k$. Its formal definition is analogous to 3(1). Predicate $r k^{*} . x . y$ holds if and only if there is a sequence of strings from $x$ to $y$ in which consecutive pairs satisfy $r k$. Such a sequence is called an $r k$-derivation.

The name $r k$ stands for rightmost prefix with respect to number $k$. The condition is a variation of definition $3(0)$, but the trailing string of terminal symbols is forced onto a bed of Procrustes of length $k$.

Program. We extend invariant $J 1$ of $3(10)$ with the "heuristic" predicate

$$
\begin{equation*}
H: \quad r k^{*} \cdot\left(S ; \perp^{k}\right) \cdot(s ; q) \tag{1}
\end{equation*}
$$

Predicate $H$ is only introduced to guide the nondeterminacy. It follows from formula $5(1)$ below that predicate $H$ implies the existence of a string $u \in T^{*}$ with $r m^{*} \cdot\left(S ; 1^{k}\right) \cdot(s ; q ; u)$, so that the execution is not yet in a blind alley.

Remark. Instead of the choices (0) and (1), one can propose to use the relation $r p$ given by

$$
r p \cdot x \cdot y=\left(\exists u \subset T^{*}:: r m^{*} \cdot x \cdot(y ; u)\right)
$$

and the heuristic predicate $r p .\left(S ; \perp^{k}\right) .(s ; q)$. The formulae (2), (3), and (4) below can be adapted immediately. Lemma (8) below, however, has an analogue for strings $w \in\left(V ; T^{k}\right)$ but not for strings $w \in T^{k+1}$ and we need both cases.

We start with an investigation of the preservation of $J 1 \wedge H$ under the commands $C 1$ and $D 0$. It is clear from (1), 3(12), and $3(7)$ that

$$
\begin{align*}
& {\left[w p \cdot C 1 .(J 1 \wedge H) \equiv w p \cdot C 1 . J 1 \wedge r k^{*} \cdot\left(S ; \perp^{k}\right) \cdot(s ; q ; \text { head.r })\right]}  \tag{2}\\
& {\left[w p \cdot D 0 .(J 1 \wedge H)=w p \cdot D 0 . J 1 \wedge r k^{*} \cdot\left(S ; \perp^{k}\right) \cdot((s-z) ; c ; q)\right]} \tag{3}
\end{align*}
$$

The suffixes ( $q ;$ head. $r$ ) and $(c ; q)$ are both elements of $\left(A ; T^{k}\right)$, i.e. they have length $k+1$ and have a suffix of $k$ terminals. This observation suggests to make an analysis of $r k^{*} .\left(S ; \perp^{k}\right) .(x ; w)$ with $x \in A^{*}$ and $w \in\left(A ; T^{k}\right)$.

Theory. For a string $x \in A^{*}$, we define the subset $N . x$ of $\left(A ; T^{k}\right)$ by

$$
\begin{equation*}
w \in N \cdot x \equiv r k^{*} \cdot\left(S ; \perp^{k}\right) \cdot(x ; w) \tag{4}
\end{equation*}
$$

In view of (2) and (3), we shall need $N . x$ for $x=s$ and for prefixes $x$ of $s$. Now the aim is to derive a recurrence equation for function $N$. For $x \in A^{*}$ and $w \in\left(A ; T^{k}\right)$ we observe

$$
\begin{aligned}
& w \in N \cdot x \wedge x \neq \varepsilon \\
\equiv & \{(4)\} \\
& r k^{*} \cdot\left(S ; \perp^{k}\right) \cdot(x ; w) \wedge x \neq \varepsilon \\
\equiv & \left\{\text { use }(8) \text { below with } n:=\left(S ; \perp^{k}\right)\right\} \\
& \left(\exists v, y, z \in A^{*}, c \in V, t \in T^{k}: x=v ; y \wedge y \neq \varepsilon \wedge\langle c, y ; z\rangle \in P:\right. \\
& \left.r k^{*} \cdot\left(S ; \perp^{k}\right) \cdot(v ; c ; t) \wedge r k^{*} \cdot(z ; t) \cdot w\right) \\
\equiv & \{(4) ; 2(1), \text { and } 2(2)\}
\end{aligned}
$$

$$
\left(\exists y \in \text { Suff. } x, z \in A^{*}, c \in V, t \in T^{k}: y \neq \varepsilon \wedge\langle c, y ; z\rangle \in P\right.
$$

$$
\left.(c ; t) \in N \cdot(x-y) \wedge r k^{*} \cdot(z ; t) \cdot w\right)
$$

For any string $x \in\left(A^{*} ; T^{k}\right)$, we now define $R k s . x$ as the subset of $\left(A ; T^{k}\right)$ given by

$$
\begin{equation*}
w \in R k s . x \equiv r k^{*} . x . w . \tag{5}
\end{equation*}
$$

Now the above calculation implies that, for string $x \neq \varepsilon$,

$$
\begin{align*}
& N . x=  \tag{6}\\
& \quad\left(\bigcup y \in \text { Suff. } x, z \in A^{*}, c \in V, t \in T^{k}:\right. \\
& y \neq \varepsilon \wedge\langle c, y ; z\rangle \in P \wedge(c ; t) \in N .(x-y): R k s .(z ; t))
\end{align*}
$$

On the other hand, it follows from (4) and (5) that

$$
\begin{equation*}
N . \varepsilon=R k s .\left(S ; \perp^{k}\right) \tag{7}
\end{equation*}
$$

The sets Rks. $(z ; t)$ need only be computed for finitely many strings: in fact, $z$ ranges over the finite set of suffixes of productions and $t$ ranges over the finite set $T^{k}$. Function $R k s$ can be effectively computed. Since it only depends on the grammar
(not on the input string), we may assume that it is known after inspection of the grammar. This issue is postponed to Section 9. There it turns out that the usual delicacies of nullable nonterminals are encapsulated in $R k s$. Now the equations (6) and (7) can effectively be used to compute $N . x$ for any string $x$.

It remains to prove the technical result used above.

Lemma. For $x \in A^{*}$ and $n, w \in\left(A^{*} ; T^{k}\right)$ with $|n| \leqslant k+1 \leqslant|w|$ we have

$$
\begin{align*}
& r k^{*} \cdot n \cdot(x ; w) \wedge x \neq \varepsilon \equiv  \tag{8}\\
& \quad\left(\exists v, y, z \in A^{*}, c \in V, t \in T^{k}: x=v ; y \wedge y \neq \varepsilon \wedge\langle c, y ; z\rangle \in P:\right. \\
& \left.\quad r k^{*} \cdot n \cdot(v ; c ; t) \wedge r k^{*} \cdot(z ; t) \cdot w\right) .
\end{align*}
$$

Proof. Let the lefthand side of (8) be given. Choose an $r k$-derivation from $n$ to $(x ; w)$. In this derivation, choose the first derivative of $n$ of the form ( $x ; p$ ) with $p \in\left(A^{*} ; T^{k}\right)$ and $r k^{*} . p . w$. Since $|w| \geqslant k+1$, we have $|p| \geqslant k+1$. Since $x \neq \varepsilon$, it follows that $|x ; p|>k+1$ and hence $n \neq(x ; p)$. Let $u$ be the predecessor of $(x ; p)$ in the derivation. Since $(x ; p)$ is the first occurrence, we have $u \neq(x ; p ; b)$ for all $b \in T$. Therefore, from ( 0 ), we have $u=(v ; c ; t)$ with $v \in A^{*}, c \in V$, and $t \in T^{k}$ and there is an $s \in A^{*}$ with $\langle c, s\rangle \in P$ and $v ; s ; t=x ; p$. Again using that $(x ; p)$ is the first occurrence, we see that $x$ is not a prefix of $v$. It follows that

$$
|s ; t|>|p|>k=|t|
$$

so that we can split $s$ into parts $y$ and $z$ with

$$
s=y ; z \wedge y \neq \varepsilon \wedge v ; y=x \wedge z ; t=p .
$$

Thus we obtain the righthand side of (8).
Conversely, let the righthand side of (8) be given. Since $x=v ; y$ and $y \neq \varepsilon$, we have $x \neq \varepsilon$. On the other hand, by (0), the data imply $r k .(v ; c ; t) .(x ; z ; t)$. Since $r k^{*} \cdot(z ; r), w$, we have $r k^{*} \cdot(x ; z ; t) .(x ; w)$. By transitivity it follows that $r k^{*} \cdot n \cdot(x ; w)$. This proves the lefthand side of (8).

Program. After these preparations we come back to the algorithm. With respect to command C1 we observe

$$
\begin{align*}
& w p . C 1 .(J 1 \wedge H)  \tag{9}\\
\equiv & \{(2) \text { and }(4)\} \\
& w p . C 1 . J 1 \wedge q ; \text { head. } r \in N . s \\
\Leftarrow & \{3(13)\} \\
& J 1 \wedge r \neq \varepsilon \wedge q ; \text { head. } r \in N . s .
\end{align*}
$$

With respect to command $D 0$ we observe

$$
\begin{align*}
& w p . D 0 .(J 1 \wedge H)  \tag{10}\\
\equiv & \{(3) \text { and }(4)\} \\
& w p . D 0 . J 1 \wedge c ; q \in N .(s-z) \\
\Leftarrow & \{3(14)\} \\
& J 1 \wedge\langle c, z\rangle \in P \wedge z \in S u f f . s \wedge c ; q \in N .(s-z) .
\end{align*}
$$

In the preconditions given by (9) and (10), predicate $J 1$ occurs instead of $J 1 \wedge H$. Since the initialisation $s=\varepsilon$ and the postcondition $s=S$ are incompatible, the body of the repetition is called at least once. Therefore, we may use the body to establish $J 1 \wedge H$ (if possible). This proves conditional correctness of the annotated program

$$
\begin{align*}
& P 2=\mid[\text { In } 1  \tag{11}\\
& \text {; do }\{J 1\} r \neq \varepsilon \vee s \neq S \rightarrow \\
& \text { if } r \neq \varepsilon \wedge q \text {;head. } r \in N . s \rightarrow C 1 \\
& \text { [ let }\langle c, z\rangle \in P \\
& \text { with } z \in \text { Suff. } s \wedge c ; q \in N .(s-z) \rightarrow D 0 \\
& \text { fi }\{J 1 \wedge H\} \\
& \operatorname{od}\left\{J 1 \wedge r=\varepsilon \wedge s=S \text {, and hence } r m^{*} . S . m\right\} \\
& \text { ]|. }
\end{align*}
$$

That is, program $P 2$ satisfies condition 1(6) in the form

$$
\begin{equation*}
\left\lfloor\text { wap. } P 2 . t r u e ~ \Rightarrow r m^{*} . S . m\right\rfloor . \tag{12}
\end{equation*}
$$

In Section 6 below, we prove that the implication can be replaced by an equivalence. This means that program $P 2$ is an angelic acceptor of the language L.G, see 1(7). It follows from the result of Section 8 that, if grammar $G$ is $\operatorname{LR}(k)$, program $P 2$ is deterministic and, hence, a genuine acceptor. Therefore, program $P 2$ can be our final result.

In program $P 2$, we need the values of $N . x$ for some prefixes $x$ of $s$. The sets $N . x$ can be computed by means of (6) and (7). Since string $s$ is only modified at its tail, it is more efficient to introduce a stack Nst of subsets of ( $A ; T^{k}$ ), say with stack pointer $h$ and invariant

$$
J n: \quad h=|s| \wedge(\forall i: 0 \leqslant i \leqslant h: N s t . i=N .(s \mid i)) .
$$

In order to make $J n$ an invariant of the repetition of $P 2$, it suffices to extend each of the commands $\operatorname{In} 1, C 1$ and $D 0$ with the restoration command

$$
\begin{aligned}
& \mid[h:=|s| \quad\{(\forall i: 0 \leqslant i<h: \text { Nst. } i=N .(s \mid i))\} \\
& ; \quad \text { Nst.h:=N.s } \quad \text { use (6) and (7)\} }] \mid .
\end{aligned}
$$

Here, Nst.h can be computed in constant time from its predecessors (for a fixed grammar). The details are left to the reader. In Section 7 below, we present the usual LR $(k)$ algorithm with its finite automaton and its stack of item sets as another optimisation of program P2.

## 5. The relevance of $\boldsymbol{r k}$-derivations

Up to this point we did not use any relationship between relation rm* of Section 3 and relation $r k^{*}$ of Section 4. The fact that every string of the language can be accepted by program P2, however, depends on the connections between the two relations. There are two kinds of connections: $r k^{*}$ implies some form of $r m^{*}$ and $r m^{*}$ implies some form of $r k^{*}$.

Theory. The first connection is that for $x, y \in\left(A^{*} ; T^{k}\right)$ we have
(0)

$$
r k^{*} \cdot x . y \Rightarrow\left(\exists u \in T^{*}:: r m^{*} \cdot x \cdot(y ; u)\right) .
$$

So, $r k^{*} . x . y$ implies that $y$ is a prefix of a rightmost derivative of $x$.
Formula ( 0 ) is proved by induction on the length of the $r k$-derivation. The base case is $x=y$, in which case the consequent of ( 0 ) holds with $u=\varepsilon$. The induction step is

$$
\begin{aligned}
& r k^{*} \cdot x \cdot y \wedge x \neq y \\
\Rightarrow & \{\text { one step and the induction hypothesis }(0) \text { with } x:=z\} \\
& \left(\exists z \in\left(A^{*} ; T^{k}\right), u \in T^{*}:: r k . x . z \wedge r m^{*} \cdot z \cdot(y ; u)\right) \\
\equiv & \{4(0)\} \\
& \left(\exists z \in\left(A^{*} ; T^{k}\right), u \in T^{*}::\right. \\
& ((\exists b \in T:: x=z ; b) \\
& \left.\vee\left(\exists v \in A^{*}, t \in T^{k},\langle c, w\rangle \in P:: x=v ; c ; t \wedge z=v ; w ; t\right)\right) \\
& \left.\wedge r m^{*} . z \cdot(y ; u)\right) \\
\Rightarrow & \{3(0)\} \\
& \left(\exists z \in\left(A^{*} ; T^{k}\right), u \in T^{*}::((\exists b \in T:: x=z ; b) \vee r m \cdot x . z) \wedge r m^{*} . z .(y ; u)\right) \\
\Rightarrow & \{\text { calculus, } 3(0) \text { and } 3(1)\} \\
& \left(\exists u \in T^{*}::\left(\exists b \in T:: r m^{*} \cdot x .(y ; u ; b)\right) \vee r m^{*} \cdot x \cdot(y ; u)\right) \\
\equiv & \{\text { calculus }\} \\
& \left(\exists u \in T^{*}:: r m^{*} \cdot x .(y ; u)\right) .
\end{aligned}
$$

The converse connection is more complicated. It is expressed in
(1) Theorem. Let $x \in\left(A^{*} ; T^{*}\right), y \in A^{*}$, and $t \in T^{*}$ be such that

$$
\begin{equation*}
r m^{*} \cdot x .(y ; t) \wedge(y=\varepsilon \vee \text { last } . y \in V) \tag{2}
\end{equation*}
$$

Then $|t| \geqslant k$ and $r k^{*} \cdot x .(y ;(t \mid k))$.

Proof. The proof uses induction on the length of the rm-derivation from $x$ to $(y ; t)$. If the derivation has length 0 , then $x=(y ; t)$ and hence $y ; t \in\left(A^{*} ; T^{k}\right)$, so that $|t| \geqslant k$ by the second conjunct of (2), and that $r k^{*} \cdot x .(y ;(t \mid k))$ follows from repeated application of the first disjunct of $4(0)$.

In the case that the derivation is nontrivial, we may split off the last step of the rm-derivation. By $3(0)$, there are $u \in A^{*}, c \in V, v \in T^{*}$, and $\langle c, z\rangle \in P$ with

$$
\begin{equation*}
r m^{*} \cdot x \cdot(u ; c ; v) \wedge u ; z ; v=y ; t . \tag{3}
\end{equation*}
$$

By the induction hypothesis with $y:=(u ; c)$ and $t:=v$, it follows that $|v| \geqslant k$ and

$$
r k^{*} \cdot x .(u ; c ;(v \mid k))
$$

Since $\langle c, z\rangle \in P$, it follows with $4(0)$ that

$$
\begin{equation*}
r k^{*} \cdot x(u ; z ;(v \mid k)) . \tag{4}
\end{equation*}
$$

Since $v \in T^{*}$, the second conjuncts of (2) and (3) imply that $y$ is a prefix of $(u ; z)$, and hence that $v$ is a suffix of $t$. This implies that $|t| \geqslant k$ and that

$$
u ; z ;(v \mid k)=y ;(t \mid k) ; w \text { for some } w \in T^{*}
$$

Repeated application of the first disjunct of $4(0)$ now implies

$$
\begin{equation*}
r k^{*} \cdot(u ; z ;(v \mid k)) .(y ;(t \mid k)) . \tag{5}
\end{equation*}
$$

By transitivity, $r k^{*} . x .(y ;(t \mid k))$ follows from (4) and (5).
We need the following two applications of Theorem (1).
(6) Corollary. Let $b \in A$ and $t \in T^{*}$ with $r m^{*}$.b.t. Then

$$
\left(\forall u \in T^{k}:: r k^{*} .(b ; u) \cdot((t ; u) \mid k)\right) .
$$

Proof. We have $r m^{*} .(b ; u),(t ; u)$. So the assertion follows from Theorem (1) with $x:=b ; u$ and $y:=\varepsilon$ and $t:=t ; u$.
(7) Corollary. Let $v \in A^{*}, t \in T^{k}$, and $c \in V$ with

$$
r m^{*} \cdot\left(S ; \perp^{k}\right) \cdot(v ; c ; t)
$$

(a) Then $|t| \geqslant k$ and $(c ;(t \mid k)) \in N . v$.
(b) For all $s \in A^{*}, u \in T^{*}$, and $\langle c, z\rangle \in P$ we have

$$
s ; u=v ; z ; t \wedge|s|<|v ; z| \Rightarrow|u|>k \wedge(u \mid k+1) \in N . s .
$$

Proof. (a) It follows from Theorem (1) with $x:=\left(S ; \perp^{k}\right)$ and $y:=v ; c$ that $|t| \geqslant k$ and

$$
\begin{equation*}
r k^{*} \cdot\left(S ; \perp^{k}\right) \cdot(v ; c ;(t \mid k)), \tag{8}
\end{equation*}
$$

so that $(c ;(t \mid k)) \in N . v$ by definition 4(4).
(b) Since $|s|<|v ; z|$, we have $|u|>|t| \geqslant k$. The second assertion is proved in

$$
\begin{aligned}
& (u \mid k+1) \in N . s \\
\equiv & \{\text { definition } 4(4)\} \\
& r k^{*} \cdot\left(S ; \perp^{k}\right) \cdot(s ;(u \mid k+1)) \\
\Leftarrow & \left\{s ;(u \mid k+1) \text { is a prefix of }(v ; z ;(t \mid k)), u \in T^{*}, \text { and } 4(0)\right\} \\
& r k^{*} \cdot\left(S ; \perp^{k}\right) \cdot(v ; z ;(t \mid k)) \\
\equiv & \{4(0) \text { and }\langle c, z\rangle \in P \text { and }(8)\}
\end{aligned}
$$

true.

## 6. Angelic guidance suffices

Program. We claim that under angelic nondeterminacy any string $m$ in the language of the given grammar can be recognised by program $P 2$ of $4(11)$. Since recognition is equivalent to termination of $P 2$, this means that program $P 2$ may terminate for the given string $m$. Formally speaking, the claim is

$$
\begin{equation*}
\left[r m^{*} . S . m \Rightarrow \text { wap.P2.true }\right] \tag{0}
\end{equation*}
$$

which is the converse of implication 4(12). This section is devoted to the proof of formula (0).

In order to prove ( 0 ), we assume rm.* S.m. Then we can choose a rightmost derivation of string $m$. Let $x, i$ with $0 \leqslant i \leqslant g$ be the consecutive sentential forms of the derivation, so that

$$
\begin{equation*}
x .0=S \wedge x . g=m \wedge(\forall i: 0<i \leqslant g: r m \cdot(x .(i-1)) \cdot(x . i)) \tag{1}
\end{equation*}
$$

Notice that this implies $r m^{*} .\left(S ; \perp^{k}\right) \cdot\left(x . i ; \perp^{k}\right)$ for $0 \leqslant i \leqslant g$.
It is clear that we may assume

$$
\begin{equation*}
(\forall i: 0<i \leqslant g: x . i \neq S) \tag{2}
\end{equation*}
$$

By $3(0)$, it follows from (1) that, for $0<i \leqslant g$, there exist productions $\langle c . i, z . i\rangle \in P$ and decompositions

$$
\begin{align*}
& x .(i-1)=v . i ; c . i ; w . i  \tag{3}\\
& x . i=v . i ; z . i ; w . i
\end{align*}
$$

with $v . i \in A^{*}$ and $w . i \in T^{*}$.
We force program $4(11)$ to accept string $m=x . g$ by strengthening the guards of the alternative statement in the body of the repetition. For this purpose we introduce a ghost variable $i$ of type integer with the additional invariant

$$
\begin{equation*}
K: \quad 0 \leqslant i \leqslant g \wedge s ; q ; r=x . i ; \perp^{k} \wedge(i=0 \vee|s| \leqslant|v . i ; z . i|) . \tag{4}
\end{equation*}
$$

The third conjunct is motivated by Corollary 5 (7). It was announced in the first paragraph of Section 4 by saying that no substring of $s$-last.s needs to be replaced by a nonterminal. The conventional expression is that $s$ is a viable prefix (cf. [6, p. 249]).

It is easy to see that predicate $K$ is initialised by the extended initialisation

$$
\begin{gather*}
\operatorname{In} 3-\mid[\ln 1 \quad\{\mathrm{cf} .3(11)\}  \tag{5}\\
; \quad i:=g] \mid
\end{gather*}
$$

Since $x .0=S \in V$ and $q \in T^{k}$ and $r \in T^{*}$, it follows from (1) and (2) that

$$
\begin{equation*}
[K \Rightarrow(i=0 \equiv r=\varepsilon \wedge s=S)] . \tag{6}
\end{equation*}
$$

This proves that the guard of the repetition of $4(11)$ may be replaced by $i \neq 0$.
We extend commands $C 1$ and $D 0$ in order to keep predicate $K$ invariant. Actually, $C 1$ need not be changed. Since we want to strengthen the guard of $C 1$ in $4(11)$, we observe

$$
\begin{align*}
& r \neq \varepsilon \wedge q ; h e a d . r \in N . s \wedge w p . C 1 .(J 1 \wedge H \wedge K)  \tag{7}\\
\Leftarrow & \{4(9)\} \\
& J 1 \wedge r \neq \varepsilon \wedge q ; h e a d . r \in N . s \wedge w p . C 1 . K \\
\equiv & \{(4) \text { and definition } C 1 \text { in } 3(12) ; \text { calculus }\} \\
& J 1 \wedge r \neq \varepsilon \wedge q ; h e a d . r \in N . s \wedge 0 \leqslant i \leqslant g \\
& \wedge s ; q ; r=x . i ; \perp^{k} \wedge(i=0 \vee|s|<|v . i ; z . i|) \\
\equiv & \{(4) ;(6) \text { gives } i \neq 0 ; \\
& |s|<|v . i ; z . i| \text { implies }|q ; r|>k \text { so that } r \neq \varepsilon\} \\
& J 1 \wedge K \wedge i \neq 0 \wedge q ; h e a d . r \in N . s \wedge|s|<|v i ; z . i| \\
\equiv & \{\text { Corollary } 5(7)(\mathrm{b}) \text { with } u:=q ; r\} \\
& J 1 \wedge K \wedge i \neq 0 \wedge|s|<|v . i ; z . i| .
\end{align*}
$$

This suggests to replace the first alternative in 4 (11) by

$$
|s|<|v . i ; z . i| \rightarrow C 1 .
$$

In view of the postulated invariance of $K$, it remains to produce an alternative with guard $s=v . i ; z . i$. We now expect an application of $D 0$ of $3(7)$. Production $\langle c . i, z . i\rangle$ is an obvious candidate for usage in $D 0$. Since the usage of a production is a step in the derivation, we also need $i:=i-1$. So, since $s-z . i=v . i$, we propose the refinement $D 3$ of $D 0$ given by

$$
\begin{align*}
D 3=\mid[ & s:=v . i ; c . i  \tag{8}\\
& ; \quad i:=i-1] \mid .
\end{align*}
$$

Since we want to strengthen the guard of $D 0$ in $4(11)$ we observe that, under assumption of $0<i \leqslant g$ and $s=v . i ; z . i$,

$$
\begin{align*}
& c . i ; q \in N .(v . i) \wedge w p . D 3 .(J 1 \wedge H \wedge K)  \tag{9}\\
\Leftarrow & \{4(10)\} \\
& J 1 \wedge c . i ; q \in N .(v . i) \wedge w p . D 3 . K \\
\Leftarrow & \{(3),(4), \text { and Corollary } 5(7)(a)\} \\
& J 1 \wedge K \wedge \text { wp.D3.K } \\
\equiv & \{\text { definition of } K \text { in }(4) \text { and of } D 3 \text { in }(8) ; \text { calculus }\} \\
& J 1 \wedge K \wedge v . i ; c . i ; q ; r=x .(i-1) ; \perp^{k} \\
& \wedge(i-1=0 \vee|v . i ; c . i| \leqslant|v .(i-1) ; z .(i-1)|) \\
\equiv & \{\text { remaining proof obligation, see }(10) \text { below }\} \\
& J 1 \wedge K .
\end{align*}
$$

It remains to observe that, for $0<i \leqslant \mathrm{~g}$,

$$
\begin{align*}
& v . i ; c . i ; q ; r=x .(i-1) ; \perp^{k}  \tag{10}\\
& \wedge \\
= & (i-1=0 \vee|v . i ; c i| \leqslant|v .(i-1) ; z .(i-1)|) \\
\equiv & \left\{(3) \text { and } c . i \in V \text { and } w .(i-1) \in T^{*}\right\} \\
& v . i ; z . i ; q ; r=x . i ; \perp^{k} \\
\Leftarrow & \{(4)\} \\
& K \wedge s=v . i ; z . i .
\end{align*}
$$

Putting (7) and (9) together we have proved conditional correctness of the annotated program $P 3$ given by

$$
\begin{align*}
& P 3=\mid[\operatorname{In} 3\{\text { cf. (5) }\}  \tag{11}\\
& \text {; do }\{J 1 \wedge K\} i \neq 0 \\
& \text { if }|s|<|v, i ; z, i| \rightarrow \\
& \{r \neq \varepsilon \wedge q ; \text { head. } r \in N . s\} C 1 \\
& \text { [ } s=v . i ; z . i \rightarrow \\
& \{c . i ; q \in N .(v . i)\} D 3 \\
& \text { fi } \\
& \operatorname{od}\left\{J 1 \wedge K \wedge i=0 \text {, and hence } r m^{*} . S . m\right\} \\
& \text { ]. }
\end{align*}
$$

Since $K$ implies the disjunction of the guards of the alternative statement, the body of the loop terminates. The loop itself also terminates, as is easily seen, since the variant function $i+|r|$ decreases with 1 in each of the commands $C 1$ and D3. Therefore, program P3 terminates. The assertions in $P 3$ show that $P 3$ is a refinement of program $P 2$ of $4(11)$. This proves that $P 2$ can be guided towards termination, i.e. that wap. P2.true holds for the given string $m$. This concludes the proof of ( 0 ).

## 7. The birth of the automaton

The recurrence equations for $N . x$ given in $4(6)$ and 4(7) may admit (for a fixed grammar) computation in constant time, but are yet inefficient, and inadequate for preprocessing. The same holds for the pattern matching required in the second alternative of program 4(11). In this section we describe the standard LR $(k)$-parsing algorithm as an optimisation of program $P 2$ in which these inefficiencies are avoided.

The idea is that both computations mentioned above require knowledge of the strings $c ; t \in N .(x-y)$ where $y$ is a suffix of $x$ that allows a production $\langle c, y ; z\rangle$. This suggests the three definitions of the next paragraph.

Theory. An item is defined to be a quadruple $\langle c, y, z, t\rangle$ with $c \in V, y, z \in A^{*}, t \in T^{k}$, and $\langle c, y ; z\rangle \in P$. We write Item to denote the set of all items. Notice that Item is a finite set because of the finiteness of $T^{k}$ and $P$. For a string $x \in A^{*}$ we define M. $x$ as the subset of Item given by

$$
\begin{equation*}
\langle c, y, z, t\rangle \in M \cdot x \equiv y \in S u f f . x \wedge c ; t \in N .(x-y) . \tag{0}
\end{equation*}
$$

Now formula 4(6) implies that, for $x \neq \varepsilon$,

$$
\begin{equation*}
N . x=(\bigcup\langle c, y, z, t\rangle \in M . x: y \neq \varepsilon: R k s .(z ; t)) . \tag{1}
\end{equation*}
$$

We want to eliminate function $N$ from the program. Recall from 4(4) that $N . x$ is a subset of $\left(A ; T^{k}\right)$. For every $x \in A^{*}$ we define

$$
\begin{equation*}
E . x=T^{k+1} \cap N . x . \tag{2}
\end{equation*}
$$

Program. Because of definitions (0) and (2), and the fact that $q \in T^{k}$, program $P 2$ of $4(11)$ is equivalent to

$$
\begin{align*}
& \text { |[ In }  \tag{3}\\
& \begin{array}{l}
\text {; do }\{J 1\} r \neq \varepsilon \vee s \neq S \rightarrow \\
\quad \text { if } r \neq \varepsilon \wedge q ; \text { head. } r \in E . s \rightarrow C 1 \\
\quad \square \text { let } c, z \text { with }\langle c, z, \varepsilon, q\rangle \in \text { M.s } \rightarrow D 0 \\
\quad \text { fi }\{J 1 \wedge H\} \\
\text { od }\left\{J 1 \wedge r=\varepsilon \wedge s=S \text {, and hence } r m^{*} . S . p\right\}
\end{array} \\
& \text { ]l. }
\end{align*}
$$

It remains to compute the sets E.s and M.s.
Theory. The set M. $\varepsilon$ is determined by observing that, for every item $\langle c, y, z, t\rangle$,

$$
\begin{aligned}
& \langle c, y, z, t\rangle \in M . \varepsilon \\
\equiv & \{(0)\} \\
& y=\varepsilon \wedge c ; t \in N . \varepsilon \\
\equiv & \{4(7)\} \\
& y=\varepsilon \wedge c ; t \in R k s .\left(S ; \perp^{k}\right) .
\end{aligned}
$$

This implies that

$$
\begin{equation*}
M . \varepsilon=\left(\operatorname{SET} c, z, t:\langle c, z\rangle \in P \wedge c ; t \in R k s .\left(S ; \perp^{k}\right):\langle c, \varepsilon, z, t\rangle\right) \tag{4}
\end{equation*}
$$

We determine a recurrence equation for M.x, in which $M .(x ; b)$ is expressed in terms of M.x. For every item $\langle c, y, z, t\rangle$ with $y \neq \varepsilon$ we observe that

$$
\begin{align*}
& (c, y, z, t\rangle \in M .(x ; b)  \tag{5}\\
\equiv & \{(0) ; \text { we give ";" higher priority than "-""\}} \\
& y \in \text { Suff. }(x ; b) \wedge c ; t \in N .(x ; b-y) \\
\equiv & \{y \neq \varepsilon \text { and calculus }\} \\
& b \in \text { Suff. } y \wedge y-b \in \text { Suff } x \wedge c ; t \in N .(x-(y-b)) \\
\equiv & \{(0)\} \\
& b \in \text { Suff. } y \wedge\langle c, y-b,(b ; z), t\rangle \in M . x .
\end{align*}
$$

For items of the form $\langle c, \varepsilon, z, t\rangle$ we have

$$
\begin{align*}
& \langle c, \varepsilon, z, t\rangle \in M .(x ; b)  \tag{6}\\
\equiv & \{(0)\} \\
& c ; t \in N .(x ; b) \\
\equiv & \{(1) \text { and } x ; b \neq \varepsilon\} \\
& (\exists\langle d, w, v, q\rangle \in M .(x ; b): w \neq \varepsilon: c ; t \in R k s .(v ; q)) \\
\equiv & \{(5) \text { with } w \neq \varepsilon ; \text { introduce } u=w-b\} \\
& (\exists d, u, v, q:\langle d, u,(b ; v), q\rangle \in M . x: c ; t \in R k s .(v ; q)) .
\end{align*}
$$

Traditionally, the items of (5) are called kernel items and the items of (6) are called closure items.

Combining (5) and (6), we obtain for every item $\langle c, y, z, t\rangle$

$$
\begin{align*}
& \langle c, y, z, t\rangle \in M .(x ; b) \equiv  \tag{7}\\
& \quad(\exists d, u, v, q:\langle d, u,(b ; v), q\rangle \in M . x: \\
& \quad\langle c, y, z, t\rangle=\langle d,(u ; b), v, q\rangle \vee(y=\varepsilon \wedge c ; t \in R k s .(v ; q))) .
\end{align*}
$$

Since Item is a finite set, formula (7) suggests the following form of preprocessing. For any subset $U$ of Item and any symbol $b \subset \Lambda$, we define step.b. $U$ as the subset of Item given by

$$
\begin{align*}
& \langle c, y, z, t\rangle \in \operatorname{step} . b . U \equiv  \tag{8}\\
& (\exists d, u, v, q:\langle d, u,(b ; v), q\rangle \in U: \\
& \langle c, y, z, t\rangle=\langle d,(u ; b), v, q\rangle \vee(y=\varepsilon \wedge c ; t \in R k s .(v ; q))) .
\end{align*}
$$

Then formula (7) reduces to

$$
\begin{equation*}
M .(x ; b)=\operatorname{step} . b .(M . x) \tag{9}
\end{equation*}
$$

Let $Q$ be the power set of the finite set Item. Now step is a function $A \rightarrow(Q \rightarrow Q)$. The triple $\langle Q$, step, M. $\varepsilon\rangle$ is a version of the finite automaton that usually occurs in LR-parsing. Function step can be computed in the preprocessing phase, for it clearly does not depend on the input string.

We now want to eliminate function $E$ of formula (2) from the program. It follows from (2) and 4(7) that

$$
\begin{equation*}
E . \varepsilon=T^{k+1} \cap R k s .\left(S ; \perp^{k}\right) \tag{10}
\end{equation*}
$$

It follows from (1) and (2) that, for $x \neq \varepsilon$,

$$
\begin{equation*}
E . x=e .(M . x) \tag{11}
\end{equation*}
$$

where, for every subset $U$ of Item, the set $e . U$ is defined by

$$
\begin{equation*}
e . U=\left(\bigcup\langle c, y, z, t\rangle \in U: y \neq \varepsilon: T^{k+1} \cap R k s .(z ; t)\right) . \tag{12}
\end{equation*}
$$

Clearly, function $e$ is a function from $Q$ to the power set of $T^{k+1}$ that can be computed in the preprocessing phase.

Program. We now come back to the algorithm. In the program of (3) we need the values of E.s and M.s for the application of the two commands. Therefore, after the application we need the values of E.s' and M.s' where $s^{\prime}$ is the new value of $s$. Since $s^{\prime}$ is always nonempty, we can use formula (11) to compute E.s' from M. $s^{\prime}$.

In the case of $C 1$, we have $s^{\prime}=(s ; b)$ with $b \in T$, so that $M . s^{\prime}$ can be obtained from M.s with formula (9). In the case of $D 0$ we have $s^{\prime}=((s-z) ; c)$ with $\langle c, z\rangle \in P$, so that $M . s^{t}$ can be obtained from $M .(s-z)$. Therefore, we introduce a stack Mst for the values M. $x$ where $x$ is a prefix of $s$. Let $h$ be the stack pointer (the identifiers $s$ and $p$ being in use for strings). We introduce a variable $F$ to keep the value of $E . s$. The invariant $J 1$ is extended accordingly with

$$
\begin{equation*}
J m: \quad F=E . s \wedge h=|s| \wedge(\forall i: 0 \leqslant i \leqslant h: M s t . i=M .(s \mid i)) . \tag{13}
\end{equation*}
$$

It is clear that $J m$ is initialised by

$$
\begin{align*}
\operatorname{In} 4= & \mid[\operatorname{In} 1 \quad\{\text { cf. } 3(11)\}  \tag{14}\\
& ; h:=0 \\
& ; F:=E . \varepsilon \quad\{c f .(10)\} \\
& ; \text { Mst.0:=M. } \varepsilon \quad\{c f .(4)\}] \mid .
\end{align*}
$$

To preserve $J m$, command $C 1$ is extended to

$$
\begin{align*}
& C 4=\mid[M s t .(h+1):=\operatorname{step} .(\text { head } .(q ; r)) .(\text { Mst.h })  \tag{15}\\
& \text {; } h:=h+1 \\
& \text {; } F:=e .(M s t . h) \\
& \text {; C1 ]. }
\end{align*}
$$

Instead of head. $(q ; r)$ we may write head. $q$ if $k>0$ and head. $r$ if $k=0$.

Command $D 0$ is extended to

$$
\begin{align*}
D 4= & \mid[\text { Mst. }(h-|z|+1):=\operatorname{step} . c .(\text { Mst. }(h-|z|))  \tag{16}\\
& ; h:=h-|z|+1 \\
& ; F:=e .(\text { Mst. } h) \\
& ; s:=((s-z) ; c)] \mid .
\end{align*}
$$

Now the program of (3) is equivalent to our final result

$$
\begin{align*}
& P 4=\mid[\text { In } 4  \tag{17}\\
& \text {; do }\left\{J 1 \wedge J_{I m}\right\} r \neq \varepsilon \vee s \neq S \rightarrow \\
& \text { if } r \neq \varepsilon \wedge q ; \text { head } r \in F \rightarrow C 4 \\
& \square \text { let } c, z \text { with }\langle c, z, \varepsilon, q\rangle \in \text { Mst. } h \rightarrow D 4 \\
& \text { fi }\{J 1 \wedge J m \wedge H\} \\
& \operatorname{od}\left\{J 1 \wedge r=\varepsilon \wedge s=S \text {, and hence } r m^{*} . S . m\right\} \\
& \text { ]. }
\end{align*}
$$

Since program $P 4$ is equivalent to $P 2$, it follows from $4(12)$ and $6(0)$ that

$$
\begin{equation*}
\left[r m^{*} . S . m \equiv \text { wap.P4.true }\right] \tag{18}
\end{equation*}
$$

which is the analogue of formula $1(7)$.

## 8. The determinstic acceptor

Program. As argued in Section 1, formula $7(18)$ implies that program $P 4$ is an acceptor of the language if it is deterministic (cf. 1(8)). The nondeterminacy of $P 4$ consists of the occurrence of two points of choice. One point is the choice between the first and the second alternative. If this choice occurs, it is called a shift-reduce conflict. The other point is the choice of a production $\langle c, z\rangle$ in the second alternative. If this choice occurs, it is called a reduce-reduce conflict.

More formally, let us consider triples ( $q, F, U$ ) with $q \in T^{k}, F \subset T^{k+1}$, and $U \subset$ Item. We define a triple $(q, F, U)$ or the pair $(q, F)$ to allow a shift if and only if $q ; b \in F$ for some $b \in T$. We define the triple $(q, F, U)$ or the pair $(q, U)$ to allow a reduction $\langle c, z\rangle \in P$ if and only if $\langle c, z, \varepsilon, q\rangle \in U$. A triple is defined to allow conflicts if and only if it allows a shift and a reduction or at least two different reductions. If all reachable triples do not allow conflicts, grammar $G$ is said to be $\operatorname{LR}(k)$ (cf. [7]).

Let grammar $G$ be $\operatorname{LR}(k)$. This implies that a string $m$ belongs to $L . G$ if and only if $P 4$ terminates. So, if $m \notin L . G$, the program does not terminate. One possibility is that the alternative statement aborts since ( $q, M s t . h$ ) does not allow a reduction and either $r=\varepsilon$ or $(q ;$ head. $r) \notin F$. In this case, abortion can be replaced by an error message. In principle, another possibility would be that the repetition of $P 4$ does not terminate, but we now show that this is not possible.
(0) Theorem. Let $G$ be $\operatorname{LR}(k)$ and $m \notin L$.G. Then the alternative statement in the body of the repetition of $P 4$ aborts in a state where $(q, M s t . h)$ does not allow a reduction and either $r=\varepsilon$ or $(q ; h e a d . r) \notin F$.

Proof. Since $P 4$ is equivalent to $P 2$, we may use $P 2$ to argue about. The body of the repetition of $P 2$ establishes $J 1 \wedge H$. Now we observe

$$
\begin{aligned}
& J 1 \wedge H \\
= & \{4(1)\} \\
& J 1 \wedge r k^{*} \cdot\left(S ; \perp^{k}\right) \cdot(s ; q) \\
\Rightarrow & \{\text { formula } 5(0)\} \\
& J 1 \wedge\left(\exists u \in T^{*}:: r m^{*} \cdot\left(S ; \perp^{k}\right) \cdot(s ; q ; u)\right) \\
\Rightarrow & \{3(10), 3(0), \text { and calculus }\} \\
& m ; \perp^{k}=p ; q ; r \wedge\left(\exists u \in T^{*}:: r m^{*} \cdot\left(S ; \perp^{k}\right) \cdot(p ; q ; u)\right) .
\end{aligned}
$$

Since $m \notin L . G$, we have $\neg r m^{*} .\left(S ; \perp^{k}\right) .\left(m ; \perp^{k}\right)$. If string $r$ would be equal to string $u$ of the existential quantification, then program $P 2$ can terminate. Since grammar $G$ is $\operatorname{LR}(k)$, program $P 2$ is deterministic. So, if $r=u$, program $P 2$ necessarily terminates. Therefore, the number of steps performed without inspection of $r$ is finite. This implies that the number of reductions performed in states with fixed $p$ and $q$ is finite. Since input string $m$ is finite the number of shifts is finite. This implies that the only source of nontermination is the alternative statement.

## 9. The determination of function Rks

Theory. In this section we finally obtain an effective characterisation of the crucial function Rks introduced in 4(5), and used in $7(6)$ and $7(8)$. It is here that the possibility of $\varepsilon$-productions complicates the algorithm and the proof. It turns out that our definition of Rks has served to isolate this complication, which in Knuth's paper led to the introduction of the function $H_{k}^{\prime}(\sigma)$ (cf. [7], p. 615]).

Recall from 4(5) that, for $x \in\left(A^{*} ; T^{k}\right)$, the set Rks. $x$ is the subset of ( $A ; T^{k}$ ) given by

$$
\begin{equation*}
w \in R k s \cdot x \equiv r k^{*} \cdot x . w . \tag{0}
\end{equation*}
$$

So, the determination of $R k s$ depends on the determination of $r k^{*} . x . w$ for $w \in$ ( $A ; T^{k}$ ).

Since an $r k$-derivation from $x$ to $w$ may pass through strings of arbitrary length, it is not obvious that $r k^{*} . x . w^{w}$ can effectively be determined. We shall enforce finiteness of computation by transforming the derivations in such a way that the intermediate strings have bounded length. We first extend the freedom of relation $r k$ drastically
by introducing a relation frk (for free $r k$ ). In the second step, the freedom of frk is reduced again by introducing a relation brk (for bounded $r k$ ) in which productive rewritings are only allowed in small strings.

The transformation requires special treatment of the nullable nonterminals, i.e. the elements of the set $V 0$ defined by

$$
\begin{equation*}
c \in V 0 \equiv c \in V \wedge r m^{*} . c . \varepsilon \tag{1}
\end{equation*}
$$

and of the productive symbols: the elements of the set $A 1$ defined by

$$
\begin{equation*}
b \in A 1 \equiv\left(\exists u \in T^{*}:: r m^{*} . b . u\right) \tag{2}
\end{equation*}
$$

Notice that $T \cup V 0 \subset A 1$. There are well-known algorithms to determine the nullable nonterminals and the productive ones (cf. [6], Lemma 4.1 and Theorem 4.3]).

Both frk and brk are relations on the set $A^{*}$, whereas $r k$ of definition $4(0)$ is a relation on ( $A^{*} ; T^{k}$ ). The relations frk and brk also differ from relation rk in two other aspects. They allow more symbol deletions: both allow deletion of productive symbols at the end of the string and of nullable symbols not in the beginning. On the other hand, each has its own condition under which productive rewritings are allowed. Relation frk on $A^{*}$ is defined by

$$
\begin{align*}
& f r k . x . y \equiv  \tag{3}\\
& \qquad(\exists b \subset A 1:: x=y ; b) \\
& \vee\left(\exists r, t \in A^{*}, c \in V 0:: r \neq \varepsilon \wedge x=r ; c ; t \wedge y=r ; t\right) \\
& \vee\left(\exists r \in A^{*}, t \in T^{*},\langle c, w\rangle \in P::\right. \\
& \quad|t| \leqslant k \wedge x=r ; c ; t \wedge y=r ; w ; t) .
\end{align*}
$$

Relation brk on $A^{*}$ is defined by
(4) brk.x.y $\equiv$

$$
(\exists b \in A 1:: x=y ; b)
$$

$\vee\left(\exists r, t \in A^{*}, c \in V 0:: r \neq \varepsilon \wedge x=r ; c ; t \wedge y=r ; t\right)$
$\vee\left(\exists r \in A^{*}, t \in T^{*},\langle c, w\rangle \in P::\right.$

$$
|x| \leqslant k+1 \wedge x=r ; c ; t \wedge y=r ; w ; t) .
$$

We use $f r k^{*}$ and $b r k^{*}$ to denote the reflexive transitive closures of frk and brk, respectively. We use $f r k$-derivations and $b r k$-derivations completely analogous to the $r k$-derivations introduced after definition $4(0)$.

For a given string $x$, the set of strings $y$ with $b r k^{*} . x . y$ can effectively be computed. In fact, the lengths of the intermediate strings is bounded by the maximum of $|x|$
and $k+j$ where $j$ is the maximal length of a production. Therefore, the goal of the present section is to prove
(5) Theorem. For $x \in\left(\Lambda^{*} ; T^{k}\right)$ and $y \in\left(\Lambda ; T^{k}\right)$ we have

$$
r k^{*} . x . y \equiv b r k^{*}, x . y .
$$

Remark. Since it is only an auxiliary concept, we do not mention relation frk* in this theorem. Relation $f r k^{*}$ has been introduced above, since it plays a role in the concept formation and in the proof of the theorem.

Proof. It follows from the definitions (3) and $4(0)$ that relation $f r k^{*}$ is a weakening of $r k^{*}$ in the sense that

$$
\left(\forall x, y \in\left(A^{*} ; T^{k}\right):: r k^{*} \cdot x \cdot y \Rightarrow f r k^{*} \cdot x \cdot y\right)
$$

It follows from (3) and (4) that $f r k^{*}$ is also a weakening of $b r k^{*}$ in the sense that

$$
\left(\forall x, y \in A^{*}:: b r k^{*} \cdot x . y \Rightarrow f r k^{*} . x . y\right)
$$

Therefore, using $\left(A ; T^{k}\right) \subset\left(A^{*} ; T^{k}\right) \subset A^{*}$, we see that it suffices to prove the following reverse implications:

$$
\begin{align*}
& \left(\forall x \in\left(A^{*} ; T^{k}\right), y \in\left(A ; T^{k}\right):: f r k^{*} \cdot x \cdot y \Rightarrow r k^{*} \cdot x \cdot y\right)  \tag{6}\\
& \left(\forall x \in A^{*}, y \in\left(A ; T^{k}\right):: f r k^{*} \cdot x \cdot y \Rightarrow b r k^{*} \cdot x \cdot y\right) . \tag{7}
\end{align*}
$$

Since formula (6) cannot serve as an induction hypothesis, it is generalised in Lemma (8) below. In fact, formula (6) follows from (8) by taking $u:=\varepsilon$. Formula (7) is proved in Lemma (10) below.
(8) Lemma. Let $x \in A^{*}$ and $y \in\left(A ; T^{k}\right)$ with frk*.x.y. Then

$$
\left(\forall u \in T^{*}::(x ; u) \in\left(A^{*} ; T^{k}\right) \Rightarrow r k^{*} \cdot(x ; u) \cdot y\right) .
$$

Proof. We use induction on the length of the frk-dcrivation from $x$ to $y$. In the base case $x=y$ it suffices to observe that relation $r k^{*}$ allows the deletion of all symbols of $u$, since $y \in\left(A ; T^{k}\right)$ and $u \in T^{*}$.

Now, let $x \neq y$. In the $f r k$-derivation from $x$ to $y$, we may assume that the deletion of nullable nonterminals is performed as late as possible and then from right to left. Let $z \in A^{*}$ is the first intermediate string of this frk-derivation from $x$ to $y$. We then have $f r k . x . z$ and $f r k^{*} . z . y$ and, by induction,

$$
\begin{equation*}
\left(\forall v \in T^{*}::(z ; v) \in\left(A^{*} ; T^{k}\right) \Rightarrow r k^{*} \cdot(z ; v) \cdot y\right) . \tag{9}
\end{equation*}
$$

Now let $u \in T^{*}$ be such that $(x ; u) \in\left(A^{*} ; T^{k}\right)$. In view of frk.x. $z$ and definition (3) we distinguish three cases.

We first consider the deletion of a productive symbol at the end of $x$. More precisely, we assume that $x=z ; b$ with $b \in A 1$. If $b \in T$ then $b ; u \in T^{*}$ and we have $(z ; b ; u)=(x ; u) \in\left(A^{*} ; T^{k}\right)$; formula (9) yields $r k^{*} .(z ; b ; u) . y$ and hence $r k^{*} .(x ; u) . y$, as required. If $b \in V \cap A 1$ then $u \in T^{k}$. It then follows from (2) and Corollary 5(6) that $r k^{*} .(b ; u) . v$ for some string $v \in T^{k}$. This implies that $r k^{*} .(x ; u) .(z ; v)$. Using (9) and transitivity of $r k^{*}$, we get $r k^{*} .(x ; u) \cdot y$.

We next consider a productive rewriting of $x$. So, assume that $x-r ; c ; t$ and $z=r ; w ; t$ with $r \in A^{*}, t \in T^{*},\langle c, w\rangle \in P$, and $|t| \leqslant k$. We have $|t ; u| \geqslant k$, so we can choose a prefix $v$ of $u$ with $|t ; v|=k$. We then have $r k^{*} .(x ; u) .(x ; v)$ and $r k .(x ; v) .(z ; v)$, and $r k^{*} .(z ; v) . y$ from (9). This implies $r k^{*} .(x ; u) . y$.

The third possibility is the deletion of a nullable symbol. So we have $x=r ; c ; t$ and $z=r ; t$ with $r \in A^{*}, r \neq \varepsilon, t \in A^{*}$, and $c \in V 0$. Recall that, in the frk-derivation from $x$ to $y$, the deletion of nullable nonterminals is performed as late as possible and then from right to left. This implies that the derivation from $z$ to $y$ does not contain deletions of productive or nullable symbols from substring $t$ of $x=r ; c ; t$, and also no rewritings of nonterminals from $t$. Therefore, $t$ survives as a suffix of $y$. Since $r \neq \varepsilon$ and there is an $f r k$-derivation from $r ; t$ to $y$ in which $t$ survives, and since $y \in\left(A ; T^{k}\right)$, it follows from (3) that $|t| \leqslant k$. Since $t$ is a suffix of $y$, it follows that $t \in T^{*}$. Again, we can choose a prefix $v$ of $u$ such that $(t ; v) \in T^{k}$. Since $c \in V 0$, we have $r k^{*} .(c ; t ; v) .(t ; v)$ by Corollary $5(6)$, and hence $r k^{*} .(x ; v) .(z ; v)$. We also have $r k^{*} .(x ; u) .(x ; v)$ and $r k^{*} .(z ; v) . y$ from (9). This implies $r k^{*} .(x ; u) . y$.
(10) Lemma. Let $x \in A^{*}$ and $y \in\left(A ; T^{k}\right)$ with frk ${ }^{*}$.x.y. Then brk*.x.y.

Proof. Again, we use induction on the length of the frk-derivation from $x$ to $y$. The base case $x=y$ is trivial. So, let $x \neq y$. In the frk-derivation from $x$ to $y$ we may assume that the productive rewritings occur as late as possible. Let $z \in A^{*}$ be the first intermediate string. We have frk.x.z and, by induction, brk*.z.y. If the frk-step from $x$ to $z$ is a $b r k$-step then $b r k^{*} . x . y$ and we are done.

It remains to consider an $f r k$-step that is not a brk-step. So it is a rewriting and there exist $r \in A^{*}, t \in T^{*}$, and $\langle c, w\rangle \in P$ with

$$
x=r ; c ; t \wedge z=r ; w ; t \wedge|t| \leqslant k .
$$

Since $\neg b r k . x . z$, we have $|x| \geqslant k+2$ and, hence $|r ; c| \geqslant 2$ and $r \neq \varepsilon$. Again using $\neg b r k . x . z$, we get $w \neq \varepsilon$, for otherwise the productive rewriting can be regarded as the deletion of a nullable symbol. It follows that $|z| \geqslant k+2$.

It follows from (4) that the brk-derivation from $z$ to $y$ begins with $|z|-(k+1)$ symbol deletions. Since, in the frk-derivation from $x$ to $y$, the productive rewritings occur as late as possible, the brk-derivation from $z$ to $y$ does not contain symbol deletions from $r$ and $t$. It follows that the brk-derivations from $z$ to $y$ begins with $|z|-(k+1)$ symbol deletions from the substring $w$ of $z=r ; w ; t$. Now we observe that

$$
|w|=|z|-|r ; t|=|z|-(|x|-1) \leqslant|z|-(k+1) .
$$

Therefore, $|w|=|z|-(k+1)$ and the $f r k$-derivation from $z$ to $y$ begins with the stepwise deletion of string $w$, followed by a brk-derivation from ( $r ; t$ ) to $y$. Recall that $w \neq \varepsilon$. If $t \neq \varepsilon$ then the stepwise deletion of $w$ implies that $\mathrm{rm}^{*} . w . \varepsilon$ and hence that $c \in V 0$; this implies $b r k . x$. ( $r ; t$ ). If $t=\varepsilon$, the stepwise deletion of $w$ implies that $c \in A 1$ and again brk. $x$. $(r ; t)$. In either case, it follows that $b r k^{*} \cdot x . y$.

Remark. The global structure of the proofs of Theorem (5) and Lemmas (8) and (10) is quite satisfactory. The details are somewhat messy, but that may be due to the accumulated complexity of the definitions (1), (2) and (4).

## 10. Concluding remarks

We regard our presentation of LR-parsing as a derivation, since, after the initial choices $4(0)$ and $4(1)$, there is essentially only one path forward and this path leads to the programs of $4(11)$ and $7(17)$. The algorithm of $7(17)$ is a direct descendant of Knuth's second method for testing the LR( $k$ ) condition (cf. [7, pp. 615-618]).

Distinctive features are that we have isolated the finite automaton and the stack of item sets in the optimisation treated in Section 7, and that we have isolated the delicacies of nullable nonterminals in function $R k s$ which is determined in Section 9.

Another distinctive feature is that our proofs are virtually complete whereas Knuth only gives a recipe. We hope that these features form a sufficient justification for writing a heavy paper about a well-known algorithm that was treated in four pages, 26 years ago. A related analysis of Earley's algorithm (cf. [5]), is given in [4].

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