# Adaptive random quantum eigensolver 

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#### Abstract

We propose an adaptive random quantum algorithm to obtain an optimized eigensolver. Specifically, we introduce a general method to parametrize and optimize the probability density function of a random number generator, which is the core of stochastic algorithms. We follow a bioinspired evolutionary mutation method to introduce changes in the involved matrices. Our optimization is based on two figures of merit: learning speed and learning accuracy. This method provides high fidelities for the searched eigenvectors and faster convergence on the way to quantum advantage with current noisy intermediate-scaled quantum computers.


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## I. INTRODUCTION

The emulation of biological systems has always led to disruptive bioinspired technologies. During the last decades, machine learning (ML) has emerged as an innovative technique that imitates the learning abilities of humans [1-4], where reinforcement learning (RL) occupies an important role. In simple terms, these protocols optimize their performance by the use of trial and error methods [5,6]. This class of algorithms has achieved impressive results as master players for board and video games [7-9]. On the other hand, the development of quantum computing provides a theoretical framework to break fundamental limits of classical computing [10-13]. With the experimental advances in quantum computing in platforms like trapped ions [14-16], superconducting circuits [17-20], and photonics [21], quantum supremacy was recently reached [22-24]. Nevertheless, full-fledged faulttolerant quantum computers are still far from reach. The development of another class of algorithms is needed.

In this manner, quantum computers were able to surpass the performance of current supercomputers for a specific task, be it quantum speckle or boson sampling. Along these lines, quantum machine learning (QML) [25-28] is considered a natural application to surpass current classical protocols to create intelligent machines. In the last years, QML has been a fruitful area, producing faster algorithms for several tasks such as linear and nonlinear algebraic problems, data classification, and variational algorithms [29-33]. As in classical ML methods, also in QML the RL paradigm has received great attention, especially for quantum control [34-37], quantum

[^0]tomography [38,39], state preparation [40,41], as well as optimization of quantum compilers [42], among others [43,44]. This quantum computing revolution of intelligent algorithms has opened the door to develop bioinspired quantum technologies and quantum artificial life protocols [45-48]. In this context, random changes as mutations seem a good starting point for quantum evolutionary algorithms.

A semiautonomous quantum eigensolver has been recently developed theoretically and experimentally $[49,50]$ for the calculation of eigenvectors. This algorithmic method is based on random changes on quantum states handled by single-shot measurements and feedback loops. This can be seen as a mimicking of a natural selection process, where a system evolves due to mutations (random changes) plus an abiotic environment (single-shot measurements). Since this class of algorithms employs only single-shot measurements in each feedback loop, they save a large amount of resources. To reduce the number of copies of the quantum system to be measured is indeed important, in particular when comparing to algorithms relying on expectation values such as the variational quantum eigensolver (VQE) [51-53]. In Ref. [50], it was shown that, for a single-qubit operator, the semiautonomous quantum eigensolver needs only 200 single-shot measurements, while the VQE needs more than 50 times more measures for similar fidelity. Random algorithms, in general, look more robust to noise if we compare with other hybrid algorithms [38,49]. On the other hand, random methods are designed to approach but not to match exact solution, at variance with other hybrid classical-quantum algorithms which might do that if fault-tolerant quantum computers were available. Consequently, the simplicity of semiautonomous quantum algorithms makes them more suitable for current noisy intermediate-scale quantum (NISQ) processors, where noise is just part of the computations.

In this paper, we propose a bioinspired adaptive random quantum eigensolver (ARQE), which is strong under stochastic noise present in the gates in a quantum device. This characteristic makes our proposal suitable for NISQ devices, where the circuit depth is limited by the error of the gates among others sources. We use adaptive random mutations in the eigensolver matrices for getting high fidelities in the eigenvectors of given operators. To this end, we parametrize an arbitrary probability distribution function (PDF), where mutations are selected from. Then, we optimize with two criteria: (i) maximizing the fidelity of the learning accuracy and (ii) maximizing the learning speed via minimization of the number of iterations. The introduced ARQE algorithm is able to deliver high fidelities with faster approximations than variational methods, making it useful for approaching quantum advantage in the NISQ era.

## II. SEMIAUTONOMOUS QUANTUM EIGENSOLVER

An arbitrary quantum observable is mathematically described by a Hermitian operator $\mathcal{O}$, defined by

$$
\begin{equation*}
\mathcal{O}=\sum_{j} \lambda_{j}\left|\psi_{j}\right\rangle\left\langle\psi_{j}\right| \tag{1}
\end{equation*}
$$

where $\lambda_{j}$ and $\left|\psi_{j}\right\rangle$ are the $j$ th eigenvalue and eigenvector, respectively. A $d$-dimensional quantum system, which we will call quantum individual (QI), is characterized by its quantum state $\left|I\left(\vec{\theta}_{t}\right)\right\rangle$, which depends on a set of parameters $\vec{\theta}_{t}=\left(\theta_{0, t}, \theta_{1, t}, \ldots, \theta_{n, t}\right)$ at time $t$, with $n=2(d-1)$. The set of parameters $\left(\vec{\theta}_{t}\right)$ can be considered as the QI's genotype. The role of the abiotic environment is given by a quantum evolution $U_{E}=e^{-i \mathcal{O}}$, which reads

$$
\begin{equation*}
U_{E}=\sum_{j} e^{-i \lambda}\left|\psi_{j}\right\rangle\left\langle\psi_{j}\right| \tag{2}
\end{equation*}
$$

At time $t$, we generate the QI described by $\left|I_{j}\left(\vec{\theta}_{t}\right)\right\rangle=$ $G\left(\vec{\theta}_{t}\right)|j\rangle$, where $G\left(\vec{\theta}_{t}\right)$ is the codification gate and $|j\rangle$ is the initial state provided by the quantum processor in the computational basis, which define our $j$ th solution for the eigenvectors. This codification gate plays the role of a variational ansatz, as in hybrid classical-quantum algorithms like the VQE. This gate can also be decomposed in two level unitary gates as shown in Ref. [38]. After the codification, the QI interacts with the abiotic environment, changing its state as

$$
\begin{align*}
\left|F_{j}\left(\vec{\theta}_{t}\right)\right\rangle & =U_{E}\left|I_{j}\left(\vec{\theta}_{t}\right)\right\rangle=\alpha_{j, t}\left|I_{j}\left(\vec{\theta}_{t}\right)\right\rangle+\beta_{j, t}\left|I_{j}^{\perp}\left(\vec{\theta}_{t}\right)\right\rangle \\
& =\alpha_{j, t}\left|I_{j}\left(\vec{\theta}_{t}\right)\right\rangle+\beta_{j, t} \sum_{k \neq j} c_{k, j, t}\left|I_{k}\left(\vec{\theta}_{t}\right)\right\rangle, \tag{3}
\end{align*}
$$

while satisfying the expressions $\quad \sum_{k \neq j} c_{k, j, t}^{2}=1$, $\left\langle I_{j}^{\perp}\left(\vec{\theta}_{t}\right) \mid I_{j}^{\perp}\left(\vec{\theta}_{t}\right)\right\rangle=1$, and $\left\langle I_{j}\left(\vec{\theta}_{t}\right) \mid I_{j}^{\perp}\left(\vec{\theta}_{t}\right)\right\rangle=0$. Now, we collapse the wave function in the basis $\left\{\left|I_{j}\left(\vec{\theta}_{t}\right)\right\rangle\right\}$ (measurement process) or, equivalently, we perform first the gate $G\left(\vec{\theta}_{t}\right)^{\dagger}$ and then a measurement in the computational basis $\{|j\rangle\}$. This measurement process takes the role of a dead or alive (DOA) event. As the goal is to adapt the QI state to one of the eigenvectors of $\mathcal{O}$ (therefore eigenvectors of $U_{E}$ ),


FIG. 1. Scheme of a bioinspired adaptive random quantum algorithm. The individual is mapped on the encoding gate $G\left(\vec{\theta}_{t}\right)$, the abiotic environment is represented by gate $E$, and the dead-alive probability is given by the decoding gate $G^{\dagger}\left(\vec{\theta}_{t}\right)$ and a measurement in the computational basis $\{|j\rangle\}$. We introduce changes in the encoding and decoding matrix (mutations) using a classical feedback loop (green lines) which depends on the classical communication of the measurement outcome (purple line).
we consider that the QI dies if we obtain, in the measurement process, the state $|m\rangle$ with $m \neq j$. This means that if $\beta_{j, t} \neq 0$, therefore $\left|I_{j}\left(\vec{\theta}_{t}\right)\right\rangle$ cannot be an eigenvector of $\mathcal{O}$. In the other case, if we measure the state $|j\rangle$, then the QI survives to the DOA event, and it is a candidate for eigenvector. In the following iteration, $t+1$, we create the QI described by $\left|I_{j}\left(\vec{\theta}_{t+1}\right)\right\rangle=G\left(\vec{\theta}_{t+1}\right)|j\rangle$, where we define

$$
\begin{align*}
\vec{\theta}_{t+1} & =\left(\theta_{0, t+1}, \theta_{1, t+1}, \ldots, \theta_{n, t+1}\right), \\
\theta_{k, t+1} & =\theta_{k, t}+\pi \epsilon_{k, t}\left(1-\delta_{m, j}\right) \tag{4}
\end{align*}
$$

Here, $m$ is the measurement outcome of the previous iteration $t, \delta_{m, j}=1 \Longleftrightarrow m=j$, and $\delta_{m, j}=0$ for $m \neq j$, while $\epsilon_{k, t}$ is a random number in the range $[-1,1]$ with a $\operatorname{PDF} \mathcal{D}_{t+1}$.

Equation (4) introduces mutations in the genotype only if the QI dies $(m \neq j)$, which means that we create a new QI for time $t+1$. Moreover, if the QI survives, we replicate the same QI for time $t+1$. Additionally, we change the PDF in each step according to a suitable reward or punishment (ROP) criterion $[49,50]$. In general, the latter will increase the probability to obtain stronger mutations (major changes) each time that the local goal is not reached (dead), and decrease the probability to obtain stronger mutations (minor changes) each time that we reach the local goal (alive). We have several ROP criteria to modify the PDF in time to ensure compliance of the previous requirement, which will be specified later. In the next section, we will describe a general parametrization of a symmetric PDF suitable to be optimized and obtain a correct ROP criterion to find the eigenvectors of $\mathcal{O}$. Figure 1 shows a scheme of the adaptive algorithm.

We can summarize our protocol as follows for the $t$ th iteration.
(1) Initialize our quantum device in the state $|j\rangle$. In general, for quantum computers it is usually the state $|0\rangle$.
(2) Apply the codification gate $G\left(\vec{\theta}_{t}\right)$ with parameters $\vec{\theta}_{t}$. As mentioned above, it can be decomposed in two-level unitary operations.
(3) Apply the unitary evolution $U_{E}$ given by the environment.
(4) Apply the gate $G^{\dagger}\left(\vec{\theta}_{t}\right)$ to decode the state.
(5) Measure the resulting state which is given by

$$
\begin{equation*}
\left|\Psi_{j, t}\right\rangle=G^{\dagger}\left(\vec{\theta}_{t}\right) U_{E} G\left(\vec{\theta}_{t}\right)|j\rangle \tag{5}
\end{equation*}
$$

in the computational basis.
(6) Update the parameters $\vec{\theta}_{t}$ for the iteration $t+1$ according to the measurement output as is given in Eq. (4).
(7) Repeat the process.

We point out that random algorithms provide a fast approximation for the eigenspectrum of quantum observables. The total or partial knowledge of the eigenspectrum of an unknown operator is a crucial task for efficient classification of quantum states or to boost quantum optimizers such as the recent proposed algorithms based on digitized-counterdiabatic quantum computing (DCQC) [54]. Also, for semiautonomous quantum devices the capability to adapt a quantum state into an eigenstate could help to develop more sophisticated machines (see Ref. [49]). Therefore, the enhancement of such algorithms is worth studying.

## III. OPTIMIZATION ALGORITHM

From Eq. (4), we can observe that the core of the algorithm is the random change given by the random variable $\epsilon_{k, t}$. Then, to optimize the method described in the previous section, we need to optimize the PDF that defines $\epsilon_{k, t}$. To do this, we parametrize the probability cumulative function (PCF) of a random number generator by means of the inverse transform sampling technique (ITST). According to the ITST we can generate a random variable $X$ in the range $[-\infty, \infty]$ with PCF $F_{X}(x)$, by the use of another random variable $Y$ in the range $[0,1]$ with uniform $\operatorname{PDF}\left(D_{Y}(y)=1\right)$. We know that the probability for the values of $X$ to be in the range $[a, b]$ is

$$
\begin{equation*}
P(a<X<b)=\int_{a}^{b} D_{X}(x) d x \tag{6}
\end{equation*}
$$

and the relation between the $\operatorname{PDF}\left(D_{X}\right)$ and the $\operatorname{PCF}\left(F_{X}\right)$ is

$$
\begin{equation*}
F_{X}(x)=\int_{-\infty}^{x} D_{X}(\bar{x}) d \bar{x}=P(-\infty<X<x) \tag{7}
\end{equation*}
$$

Finally, using the ITST, we have that the random variable $X$ with PDF $D_{X}(x)$ is given by $X=F_{X}^{-1}(Y)$. Therefore, by the parametrization of the PCF $F_{X}$, we are parametrizing the random number generator.

## A. Parametrization of $\boldsymbol{F}_{X}$

As $F_{X}(x)$ is a PCF of a random variable $X$, it is a monotonically increasing function, with $F_{X}(-\infty)=0$, and $F_{X}(\infty)=1$. Moreover, as the random variable represents a mutation in our algorithm, the PDF needs to be symmetric. Therefore, we impose the extra condition over the PCF,

$$
\begin{equation*}
F_{X}(x)=1-F_{X}(-x) \tag{8}
\end{equation*}
$$

which implies $F_{X}(0)=\frac{1}{2}$. Finally, as we consider mutations, we will focus on the generation of a random variable in the range $[-1,1]$, which means $F_{X}(-1)=0$, and $F_{X}(1)=1$.


FIG. 2. Points $\left(x_{j}, y_{j}\right)$ (orange circles), and the monotonic and symmetric interpolation defined by Eq. (9). The green squares represent the points $p_{0}=(-1,0), p_{n+1}=(0,0.5)$, and $(1,1)$, which are fixed to ensure that the interpolation corresponds to a valid symmetric CDF. $f_{j}$ represents the function by parts that interpolates the points $p_{j}$ and $p_{j+1}$.

To parametrize the PCF, we consider the vectors $\vec{x}=\left\{x_{0}=-1, x_{1}, \ldots, x_{n}, x_{n+1}=0\right\} \quad$ and $\quad \vec{y}=\left\{y_{0}=\right.$ $\left.0, y_{1}, \ldots, y_{n}, y_{n+1}=0.5\right\}$ in ascending order. These two vectors define the points $\mathcal{P}=\left\{p_{j}=\left(x_{j}, y_{j}\right)\right\}$. Now, by considering a monotonic interpolation method through the points in the set $\mathcal{P}$, we can obtain a parametrized function $\mathfrak{F}(x, \vec{x}, \vec{y})$, depending on $2 n$ parameters (the end points are fixed). Using this, we can construct a parametrized PCF $F_{X}(x, \vec{x}, \vec{y})$ as (see Fig. 2)

$$
\begin{align*}
& F_{X}(x, \vec{x}, \vec{y})=\mathfrak{F}(x, \vec{x}, \vec{y}), \quad x<0, \\
& F_{X}(x, \vec{x}, \vec{y})=1-\mathfrak{F}(x, \vec{x}, \vec{y}), \quad x>0 . \tag{9}
\end{align*}
$$

Here (see Ref. [55]),

$$
\begin{align*}
\mathfrak{F}(x, \vec{x}, \vec{y}) & =f_{j}(x), \quad x \in\left[x_{j}, x_{j+1}\right] \\
f_{j}(x) & =a_{j}\left(x_{j}-x\right)^{3}+b_{j}\left(x_{j}-x\right)^{2}+c_{j}\left(x_{j}-x\right)+d_{j} \tag{10}
\end{align*}
$$

and

$$
\begin{align*}
& a_{j}=\frac{y_{j}^{\prime}+y_{j+1}^{\prime}-2 s_{j}}{h_{j}^{2}}, \quad b_{j}=\frac{3 s_{j}-2 y_{j}^{\prime}-y_{j+1}^{\prime}}{h_{j}} \\
& c_{j}=y_{j}^{\prime}, \quad d_{j}=y_{j} \tag{11}
\end{align*}
$$

where

$$
\begin{equation*}
s_{j}=\frac{y_{j+1}+y_{j}}{x_{j+1}+x_{j}}, \quad h_{j}=x_{j+1}+x_{j} \tag{12}
\end{equation*}
$$

and

$$
\begin{equation*}
y_{j}^{\prime}=\left.\frac{d}{d x} f_{j}\right|_{x=x_{j}}=\left.\frac{d}{d x} f_{j-1}\right|_{x=x_{j}} \tag{13}
\end{equation*}
$$

Now, we approximate the derivative of the function $f_{j}$ by

$$
\begin{align*}
& y_{j}^{\prime}=0 \quad \text { if }\left(s_{j_{1}} s_{j}\right) \leqslant 0 \\
& y_{j}^{\prime}=2 \operatorname{sign}\left(s_{j}\right)|s|_{j-1, j}^{\min } \\
& \quad \text { if }\left|p_{j}\right|>2|s|_{j-1, j}^{\min } y_{j}^{\prime}=p_{j} \quad \text { otherwise }, \tag{14}
\end{align*}
$$

where

$$
\begin{align*}
p_{j} & =\frac{s_{j-1} h_{j}+s_{j} h_{j-1}}{h_{j-1}+h_{j}} \\
|s|_{j-1, j}^{\min } & =\min \left(\left|s_{j-1},\left|\left|s_{j}\right|\right)\right.\right. \tag{15}
\end{align*}
$$

We note that, according to Eq. (14), we can estimate $y_{j}^{\prime}$ only for $j \in\{1, \ldots, n\}$. We impose the border condition $y_{0}^{\prime}=0$, and the symmetry condition $y_{n+1}^{\prime}=s_{j-1}$.

Finally, we introduce the ROP criteria that we will use in the rest of the paper for the ARQE protocol. As we need to change the PDF of the random number generator, we will define the PCF as in Eq. (9) but with parameters that will change in each iteration, namely,

$$
\begin{equation*}
F_{X}=F_{X}\left(x, \vec{x}_{k}, \vec{y}_{k}\right) \tag{16}
\end{equation*}
$$

Here, $\vec{x}_{k}, \vec{y}_{k}$ are defined for the $k$ th iteration of our algorithm as

$$
\begin{equation*}
\vec{x}_{k}=w_{k} \cdot \vec{x}_{k-1} \quad \vec{y}_{k}=w_{k} \cdot \vec{y}_{k-1} \tag{17}
\end{equation*}
$$

with

$$
\begin{equation*}
w_{k}=\left[p+(r-p) \delta_{m, j}\right] w_{k-1} \tag{18}
\end{equation*}
$$

where $r<1$ is the reward constant, $p>1$ is the punishment constant, $m$ is the measured outcome, and $j$ is the desired outcome defined in the previous section. Also, we require for convergence purposes that $1 \leqslant r p$. We define that the algorithm converges after $N$ iterations if $w_{N}<\Delta$, where $\Delta$ is the tolerance of our algorithm.

## B. Optimization of $\boldsymbol{F}_{X}$

As the proposed ARQE method achieves the result in a stochastic way, we optimize the random number generator using two criteria. In the first one, we define the cost function as the mean number of iterations needed for convergence $(\bar{N})$, obtaining the values of $\vec{x}_{0}$ and $\vec{y}_{0}$ which minimize $\bar{N}$. For the second one, we define the fidelity after $\ell$ iterations as

$$
\begin{equation*}
\left.\mathcal{F}_{\ell}=\left|\left\langle\psi_{j}\right| G\left(\vec{\theta}_{\ell}\right)\right| j\right\rangle\left.\right|^{2} \tag{19}
\end{equation*}
$$

In this case, we define the mean fidelity after $\ell$ iterations $\left(\overline{\mathcal{F}}_{\ell}\right)$ as the cost function, obtaining the values of $\vec{x}_{\text {opt }}$ and $\vec{y}_{\text {opt }}$ which maximize $\overline{\mathcal{F}}_{\ell}$. For the calculation of the mean values we consider $1000 n_{q}$ independent repetitions of the algorithm, where $n_{q}$ is the number of qubits involved in the algorithm. We remark that this optimization process depends on the quantum operator to be diagonalized. In order to carry out a general optimization, we consider the optimization of different operators ( 100 cases), which means finding $\vec{x}_{\text {opt }}$ and $\vec{y}_{\text {opt }}$ for a set of different cases, which could be used for the prediction of $\vec{x}_{\text {opt }}$ and $\vec{y}_{\text {opt }}$ for new operators.

We note that for the learning accuracy, the estimation of the fidelity $\mathcal{F}_{\ell}$ requires a tomography process and also the previous knowledge of the eigenstates $\left|\psi_{j}\right\rangle$, which means that it is impractical from an experimental point of view. Nevertheless, this is interesting to analyze from a pedagogical point of view. Also, the learning accuracy strategy can be enhanced by the numerical simulations and extrapolated for complex systems to avoid experimental limitations.


FIG. 3. Histogram for mean number of interactions to converge without (left panel) and with optimization (right panel) for 100 different $U(\theta, \phi, \lambda)$. Both panels are for optimization of learning speed.

## IV. RESULTS

We consider single-qubit operators of the form

$$
\begin{equation*}
\mathcal{O}\left(a_{I}, a_{x}, a_{y}, a_{z}\right)=a_{I} \mathbb{I}+a_{x} \sigma_{x}+a_{y} \sigma_{y}+a_{z} \sigma_{z} \tag{20}
\end{equation*}
$$

In this case, the codification matrix is a general single-qubit unitary matrix given by

$$
U(\theta, \phi, \lambda)=\left(\begin{array}{cc}
\cos (\theta / 2) & -e^{i \phi} \sin (\theta / 2)  \tag{21}\\
e^{i \lambda} \sin (\theta / 2) & e^{i(\phi+\lambda)} \cos (\theta / 2)
\end{array}\right)
$$

which depends on three parameters (genes). We use 100 different sets of genes chosen randomly in the range $[0,2 \pi]$ to cover different situations. We consider $\vec{x}=\left[-1, x_{1}, x_{2}, 0\right]$ and $\vec{y}=\left[0, y_{1}, y_{2}, 0.5\right]$, where we define $X_{i n}=\left[x_{1}, x_{2}\right]$ and $Y_{\text {in }}=\left[y_{1}, y_{2}\right]$ for the PCF parametrization and optimization. Here, we optimize the iteration number needed until the convergence parameter, $w_{N}$, surpasses a threshold $\Delta=0.9$ (learning speed). The 100 results of the different optimizations are summarized in Fig. 3. From this figure, we can see that the mean-iteration number decreases; from the data set of this case (see Table I in Appendix A), we have that the mean value of the mean-iteration number for the optimized case is $\bar{N} \approx 61$, while for the case without optimization it is $\bar{N} \approx 82$, which means a reduction of $25.4 \%$. The case without optimization refers to a uniform PDF for the mutation process. We also need to mention that in this case the fidelity of the obtained solution remains almost constant (see Fig. 9 in Appendix A), obtaining less iterations to almost converge to the same solution.

In addition, we also perform the optimization fixing the number of iterations $N=80$ and minimizing the convergence parameter, which implies maximization of the fidelity (learning accuracy). We choose again 100 random unitary operators $U(\theta, \phi, \lambda)$ for the environment. Figure 4 summarizes the data for the mean fidelity with and without optimization for this case, which shows a clear increase of the fidelity. From the data set of this case (see Table II in Appendix B), we have that the mean value of the fidelity increases from $\bar{F} \approx 0.95$ without optimization to $\bar{F} \approx 0.97$ with optimization, increasing the learning accuracy of our protocol.

Figure 5 shows an example for the optimal CDF and its corresponding PDF for the optimization of the learning speed. Specifically, the genes are $\theta=2, \phi=$ $\frac{\pi}{2}$, and $\lambda=\pi$, which correspond to $\tau \mathcal{O}=\sigma_{x}$. The opti-


FIG. 4. Histogram for mean fidelity after convergence without (left panel) and with optimization (right panel) for 100 different $U(\theta, \phi, \lambda)$, for optimization of learning accuracy.
mal parameters are $x_{1}=-0.69513535, x_{2}=-0.3989989$, $y_{1}=0.00706757$, and $y_{2}=0.04842301$. We can see that the optimal PDF has two symmetric peaks, which means that the optimal adaptation appears when the most probable mutation is different from zero and approaches zero when the quantum individual becomes adapted. On the other hand, Fig. 6 shows the optimal CDF and PDF using the same genes but for the optimization of the learning accuracy. Here, the optimal parameters are $x_{1}=-0.34315537, x_{2}=$ $-0.24266087, y_{1}=0$, and $y_{2}=0.23737731$.

Finally, we present two two-qubit examples. For the first one, we consider a nondegenerate operator given by

$$
\tau \mathcal{O}=\left(\begin{array}{cccc}
\pi & -\frac{\pi}{2} & -\frac{\pi}{4} & -\frac{\pi}{4}  \tag{22}\\
-\frac{\pi}{2} & \pi & -\frac{\pi}{4} & -\frac{\pi}{4} \\
-\frac{\pi}{4} & -\frac{\pi}{4} & \frac{\pi}{2} & 0 \\
-\frac{\pi}{4} & -\frac{\pi}{4} & 0 & \frac{\pi}{2}
\end{array}\right)
$$

with the following eigenvectors and eigenvalues:

$$
\begin{aligned}
\left|\mathcal{E}^{(0)}\right\rangle & =\frac{1}{2}(|00\rangle+|01\rangle+|10\rangle+|11\rangle), \quad \alpha^{(0)}=0 \\
\left|\mathcal{E}^{(1)}\right\rangle & =\frac{1}{\sqrt{2}}(|10\rangle-|11\rangle), \quad \alpha^{(1)}=\frac{\pi}{2}
\end{aligned}
$$



FIG. 5. Optimal PDF (solid blue line) and PCF (dashed orange line) for learning speed for $\tau \mathcal{O}=\sigma_{x}$. Red dots are the points related to the parametrization; green dots are the fixed points of our PCF.


FIG. 6. Optimal PDF (blue) and PCF (orange) for learning accuracy for $\tau \hat{\mathcal{O}}=\sigma_{x}$. Red dots are the points related to the parametrization; green dots are the fixed points of our PCF.

$$
\begin{align*}
\left|\mathcal{E}^{(2)}\right\rangle & =\frac{1}{2}(|00\rangle+|01\rangle-|10\rangle-|11\rangle), \quad \alpha^{(2)}=\pi, \\
\left|\mathcal{E}^{(3)}\right\rangle & =\frac{1}{\sqrt{2}}(|00\rangle-|01\rangle), \quad \alpha^{(3)}=\frac{3 \pi}{2} . \tag{23}
\end{align*}
$$

As the eigenvalues of this operator are equidistant, then the $A R Q E$ needs a large number of iterations to converge. It is due to the fact that the unitary evolution in Eq. (2) is sensitive to the gap between the eigenvalues, reaching the eigenvectors with large gap easier than the closer one, accelerating our algorithm as is shown in Ref. [50] via numerical inspection. In this case, we use a four points parametrization, which means that $X_{i n}=\left[x_{1}, x_{2}, x_{3}, x_{4}\right]$ and $Y_{i n}=\left[y_{1}, y_{2}, y_{3}, y_{4}\right]$. The corresponding PDF and CDF for optimal learning speed are shown in Fig. 7, while the optimal parameters are $x_{1}=-0.29285222, x_{2}=-0.2132477, x_{3}=$ $-0.19124688, x_{4}=-0.15079198, y_{1}=2.85749338 e-$ $06, y_{2}=0.101155582, y_{3}=0.268075636$, and $y_{4}=$ 0.367572 655. The mean value of the mean-iteration number for the optimized case is $\bar{N} \approx 355$ while for the case without optimization it is $\bar{N} \approx 654$, which means a reduction of $45.7 \%$. The data are summarized in the histogram of


FIG. 7. Optimal PDF (blue) and PCF (orange) for learning speed for $\tau \mathcal{O}$ given by Eq (22). Red dots are the points related to the parametrization; green dots are the fixed points of our PCF.


FIG. 8. The histogram comparison of the mean number of iterations to converge without (left panel) and with optimization (right panel) for Eq (22).

Fig. 8. The mean fidelities for four eigenstates without optimization are $F_{0}=0.952, F_{1}=0.947, F_{2}=0.941$, and $F_{3}=0.938$. The mean fidelities with optimization are $F_{0}=0.946, F_{1}=0.941, F_{2}=0.933, \quad$ and $\quad F_{3}=0.930$. Therefore, we do not obtain appreciable changes in the fidelity but a considerable reduction of the iterations.

An interesting result is that we can see from Figs. 5-7 that the optimal PDF shows peaks in the mutation probability far from zero, which approaches zero when the QI starts to be adapted. It means that in the optimal mutations process the changes close to zero have almost null probability, favoring the mutations in discrete regions of values for the random variable.

The second example is the molecular hydrogen Hamiltonian with a bond length of $0.2[\AA]$. In this case, the environment is given by
$\tau \mathcal{O}=g_{0} \mathbb{I}+g_{1} Z_{0}+g_{2} Z_{1}+g_{3} Z_{0} Z_{1}+g_{4} Y_{0} Y_{1}+g_{5} X_{0} X_{1}$,
with $g_{0}=2.8489, g_{1}=0.5678, g_{2}=-1.4508, g_{3}=0.6799$, $g_{4}=0.0791$, and $g_{5}=0.0791$. The eigenvectors for this case are

$$
\begin{align*}
\left|\mathcal{E}^{(0)}\right\rangle & =-0.03909568|01\rangle+0.99923547|10\rangle \\
\left|\mathcal{E}^{(1)}\right\rangle & =|00\rangle \\
\left|\mathcal{E}^{(2)}\right\rangle & =0.99923547|01\rangle+0.03909568|10\rangle \\
\left|\mathcal{E}^{(3)}\right\rangle & =|11\rangle \tag{25}
\end{align*}
$$

and the eigenvalues

$$
\begin{array}{ll}
\alpha^{(0)}=0.14421033, & \alpha^{(1)}=2.6458 \\
\alpha^{(2)}=4.19378967, & \alpha^{(3)}=4.4118 \tag{26}
\end{array}
$$



FIG. 9. Histogram for mean fidelity without (left panel) and with optimization (right panel) for 100 different $U(\theta, \phi, \lambda)$, for the optimization of learning speed.
respectively. If we choose $r=0.9$ and the convergence condition is $w<0.1$, we need at least 21 single-shot measurements, while for three eigenvectors (the fourth one if orthogonal to the others) we need at least 63 single-shot measurements. However, in this case, the mean iteration is 65 without optimization, which means that the uniform distribution is the optimal one.

We need to mention that our ARQE algorithm is sensitive to the number of different eigenvalues, therefore for a degenerate case the algorithm will be faster, but, as the degenerate space defines an eigensubspace instead of a set of eigenvectors, the result is not unique.

Finally, we highlight that in this paper we do not focus on the implementation of the evolution $U_{E}$, which in many platforms can be nontrivial. Our ARQE algorithm mainly focuses on the efficient extraction, with respect to the number of single-shot measurements, of relevant information (eigenvectors) from a quantum evolution. Moreover, our proposal is not limited to digital NISQ computers, it can be used in analog or digital-analog quantum paradigms in order to implement the evolution $U_{E}$ in a more natural way.

## v. CONCLUSIONS

We have developed a random optimization protocol for proposing bioinspired ARQE algorithms, based on a CDF parametrization defining a random number generator. The latter is responsible for the mutation process, allowing the quantum individual to adapt, and is at the core of this class of algorithms. We develop these ARQE methods according to two different criteria, learning speed and learning accuracy. In this sense, this paper contributes to the search for efficient strategies for random algorithms, providing good approximate solutions with fewer resources, with respect to other random algorithms [ $38,39,49,50$ ]. These have shown, in turn, improvements in the number of single-shot measurements when compared to hybrid classical-quantum algorithms [50].

Moreover, our algorithm focuses on the eigenvector of an operator the eigendecomposition of which is unknown. This can be useful in the characterization of physical interactions, as well as for fast approximations in optimization algorithms reducing the searching space and therefore speeding up the minimization of Hamiltonians. In addition, the ARQE algorithm finds the eigenvectors independently of their eigenenergy, being suitable for the estimation of high-energy orbitals in quantum chemistry. On the other hand, as we consider stochastic algorithms, the scalability of our proposal requires a deep study in statistical mechanics which is out of the scope of the present paper. Finally, we need to highlight that the goal of this paper is to provide an easy formulation to parametrize a random number generator, which is the core of random algorithms like in Refs. [38,39,49,50]. This parametrization allows one to optimize the PDF of the random variable, enhancing the performance of the mentioned protocols as is shown by the numerical results.

We expect that this kind of effort contributes to approaching quantum advantage in available or improved NISQ devices. It is noteworthy to mention that ARQE protocols may also be used as preprocessing for sophisticated
algorithms, including VQEs, quantum phase estimation methods, and DCQC.

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for the optimal CDF. Also the table shows the number of iterations needed for convergence using a uniform PDF ( $N$ ) and the optimal one $\left(N_{\text {opt }}\right)$, as well as the fidelity for the optimal ( $F_{\text {opt }}$ ) and nonoptimal PDF $(F)$. In this case we are optimizing the learning speed.

We note that in this case the fidelity obtained with the optimal PDF is almost the same as without optimization because we are not optimizing the accuracy of the result, but the number of iterations is reduced by more than $20 \%$ on average.

## APPENDIX A: LEARNING SPEED DATA

The next table collects all the data for the 100 different instances for the choice of $\{\theta, \phi, \lambda\}$ and their $X_{i} n$ and $Y_{i} n$

## Learning speed histogram

In Fig. 9, we summarize the data obtained in Table I. The left panel shows the data without the optimal PDF, and the

TABLE I. The data for learning speed optimization.

|  | $\theta$ | $\phi$ | $\lambda$ | $X_{i} n$ | $Y_{i} n$ | N | $N_{\text {opt }}$ | $F$ | $F_{\text {opt }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 2.83651 | 2.51483 | 5.79311 | -0.352607301, -9.4996[-05] | 1.65031947 [-21], 0.499956565 | 84 | 61 | 0.98860 | 0.98812 |
| 2 | 2.60239 | 2.91385 | 1.94757 | -0.36580222, -0.25487967 | $0.01084567,0.18360378$ | 83 | 61 | 0.98875 | 0.98615 |
| 3 | 1.62294 | 2.66070 | 0.16163 | -0.64338053, -0.46788155 | $0.18541396,0.19697403$ | 75 | 63 | 0.98722 | 0.98714 |
| 4 | 2.29195 | 1.76471 | 1.33492 | -0.40441636, -0.01719112 | $0.00343645,0.49993767$ | 79 | 61 | 0.98787 | 0.98714 |
| 5 | 2.42279 | 3.18159 | 5.57723 | -0.50313864, -0.03521012 | $0.04263622,0.33996168$ | 85 | 68 | 0.98565 | 0.98659 |
| 6 | 2.07221 | 2.36239 | 5.79011 | -0.419110756, -0.261993043 | 2.76648[-06], 0.256172562 | 71 | 59 | 0.98885 | 0.98613 |
| 7 | 2.06019 | 1.67036 | 2.73084 | -0.302222205, -0.278906844 | -1.01643954[-20], 0.234360342 | 65 | 57 | 0.98565 | 0.98714 |
| 8 | 2.96621 | 2.51154 | 2.51168 | -0.473367622, -0.413235912 | -5.55111512[-21], 0.487328526 | 88 | 35 | 0.98883 | 0.99666 |
| 9 | 2.26002 | 1.81584 | 4.45387 | $-0.55791953,-0.0460368707$ | $2.85695[-05], 0.475565246$ | 71 | 61 | 0.98673 | 0.98455 |
| 10 | 1.35691 | 0.61534 | 5.02339 | -0.282913602, -0.0557603837 | 0.000208365485, 0.5 | 87 | 59 | 0.98860 | 0.98595 |
| 11 | 2.52209 | 1.73075 | 0.40260 | -0.23743752, -0.16350079 | $0.00959416,0.32915802$ | 83 | 61 | 0.98896 | 0.98652 |
| 12 | 2.74583 | 2.56126 | 3.80340 | -0.51353766, -0.0883247645 | $1.03362794[-21], 0.411686847$ | 82 | 64 | 0.98887 | 0.98725 |
| 13 | 3.10688 | 2.83284 | 5.32182 | -0.46327894, -0.151392808 | 8.9073[-05], 0.333453602 | 90 | 65 | 0.98894 | 0.98815 |
| 14 | 1.95288 | 4.53352 | 3.46380 | -0.433075568, -0.135160185 | $0.000326574362,0.473647838$ | 71 | 56 | 0.98534 | 0.98521 |
| 15 | 2.87028 | 1.87002 | 3.94885 | -0.21353527, -0.0947253 | 0.11645518, 0.49489148 | 88 | 66 | 0.98923 | 0.98786 |
| 16 | 2.15739 | 3.07773 | 5.71602 | -0.25089681, -0.08538334 | $0.00192315,0.46304837$ | 78 | 61 | 0.98881 | 0.98542 |
| 17 | 2.79398 | 5.42806 | 6.24226 | -0.307971979, -0.00695713502 | $0.000188672339,0.499968525$ | 86 | 60 | 0.98941 | 0.98679 |
| 18 | 1.78857 | 0.76770 | 2.56039 | -0.520485426, -0.146095907 | 2.08166817[-20], 0.374574699 | 71 | 61 | 0.98826 | 0.98721 |
| 19 | 2.68895 | 0.81678 | 2.57334 | -0.468694228, $-1[-10]$ | 8.30025[-05], 0.5 | 89 | 63 | 0.98873 | 0.98800 |
| 20 | 2.50068 | 1.42982 | 5.42760 | -0.564136098, -0.175077687 | -2.70483796[-21], 0.3742466 | 82 | 66 | 0.98733 | 0.98744 |
| 21 | 2.38126 | 1.40436 | 5.64973 | -0.406232817, -9.85128[-05] | -5.55111512[-21], 0.5 | 79 | 59 | 0.98672 | 0.98627 |
| 22 | 2.14670 | 1.98890 | 5.87210 | -0.364938465, -0.120608727 | $0.000128319093,0.435746907$ | 75 | 58 | 0.98755 | 0.98407 |
| 23 | 2.76371 | 5.67223 | 5.18676 | -0.41536678, -0.0460577 | 0.00844998, 0.49991171 | 87 | 62 | 0.98898 | 0.98857 |
| 24 | 2.35484 | 2.12405 | 5.77071 | -0.2572922, -0.224169 | $0.01555949,0.43364061$ | 83 | 61 | 0.98793 | 0.98660 |
| 25 | 2.14131 | 3.88017 | 4.43203 | -0.929939457, -0.369182991 | -9.7584383[-17], 0.0000850766777 | 76 | 60 | 0.98763 | 0.98572 |
| 26 | 2.70824 | 1.78139 | 4.29155 | -0.32973799, -0.13942659 | $0.13863571,0.41938758$ | 84 | 62 | 0.98851 | 0.98509 |
| 27 | 1.97566 | 2.68021 | 0.50074 | -0.383118824, -2[-10] | -8.14579432[-20], 0.499902518 | 76 | 61 | 0.98894 | 0.98525 |
| 28 | 1.73206 | 0.07675 | 2.44859 | -0.388221058, -0.0573922577 | -5.93648842[-21], 0.477696285 | 70 | 54 | 0.98636 | 0.98677 |
| 29 | 3.11359 | 2.04632 | 4.96774 | -0.29776454, -0.22670669 | $0.00052851,0.31971397$ | 90 | 59 | 0.98862 | 0.98815 |
| 30 | 2.20927 | 3.00257 | 3.56097 | -0.424833383, -0.284910373 | -2.74925531[-21], 0.18220541 | 74 | 57 | 0.98420 | 0.98325 |
| 31 | 2.12776 | 6.08943 | 4.49468 | $-0.845467863,-1[-10]$ | $6.77626358[-20], 0.496124243$ | 78 | 68 | 0.98737 | 0.98766 |
| 32 | 2.85530 | 4.67939 | 4.28628 | -0.337961514, -0.0986680445 | 0.000138723458, 0.5 | 86 | 61 | 0.98848 | 0.98806 |
| 33 | 2.41524 | 3.79065 | 3.00641 | -0.432054855, -0.403254422 | $4.536599[-05], 0.242284549$ | 77 | 64 | 0.98751 | 0.98602 |
| 34 | 2.93550 | 5.17916 | 4.46644 | -0.34218794, -0.1422061 | 0.0039324, 0.24517162 | 84 | 62 | 0.98941 | 0.98724 |
| 35 | 2.69760 | 4.06237 | 2.82939 | -0.618683055, -0.390404886 | -6.19274316[-21], 6936589[-05] | 87 | 61 | 0.98868 | 0.98717 |
| 36 | 2.26660 | 4.60415 | 4.39647 | -0.45970215, -0.13173758 | 0.00082242, 0.42017257 | 80 | 63 | 0.98841 | 0.98717 |
| 37 | 2.23500 | 1.56288 | 2.13387 | -0.45002646, -0.00158542 | $0.00091409,0.49977423$ | 79 | 60 | 0.98897 | 0.98729 |
| 38 | 2.77113 | 4.38132 | 1.28333 | -0.613252871, -0.317785931 | $6.20192605[-21], 0.0110331927$ | 81 | 61 | 0.98847 | 0.98718 |
| 39 | 2.88243 | 5.35496 | 0.00254 | -0.428712027, -9.99999034[-11] | $2.42861287[-21], 0.5$ | 85 | 61 | 0.98904 | 0.98841 |
| 40 | 2.37142 | 3.14858 | 1.06018 | -0.499436305, -0.000161631827 | 3.432516[-05], 0.393702916 | 80 | 65 | 0.98779 | 0.98525 |
| 41 | 2.21118 | 4.30358 | 5.56859 | -0.39081709, -0.24157334 | 0.0050181, 0.19390617 | 77 | 59 | 0.98820 | 0.98798 |
| 42 | 2.76569 | 4.78934 | 3.68815 | -0.27655431, -0.09309335 | $0.05960735,0.41938602$ | 88 | 66 | 0.98993 | 0.98751 |
| 43 | 2.44340 | 5.86060 | 0.66880 | -0.78475823, -0.49585084 | 0, 0.05258665 | 81 | 65 | 0.98731 | 0.98699 |

TABLE I. (Continued.)

|  | $\theta$ | $\phi$ | $\lambda$ | $X_{i} n$ | $Y_{i} n$ | $N$ | $N_{\text {opt }}$ | $F$ | $F_{\text {opt }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 44 | 2.34349 | 5.17034 | 3.42800 | -0.99856133, -0.50502313 | $0.00258655,0.00518738$ | 80 | 62 | 0.98899 | 0.98745 |
| 45 | 2.89725 | 3.25978 | 2.46404 | -0.387278318, -3.44764[-06] | -5.58731656[-19], 0.5 | 88 | 59 | 0.98871 | 0.98685 |
| 46 | 2.22109 | 3.17582 | 4.57342 | -0.500541647, -0.244572891 | -7.09658898[-21], 0.097607618 | 76 | 60 | 0.98709 | 0.98540 |
| 47 | 2.12925 | 5.74234 | 4.16431 | -0.771209557, -0.511318543 | $6.77593[-05], 0.011359187$ | 78 | 61 | 0.98965 | 0.98821 |
| 48 | 2.04236 | 4.02405 | 4.75088 | $-0.36012526,-0.08207992$ | 0.00086559, 0.5 | 77 | 59 | 0.98810 | 0.98672 |
| 49 | 2.84364 | 3.51744 | 2.31714 | -0.491466218, -0.210036697 | $1.15012[-05] 0.15350186$ | 87 | 62 | 0.98917 | 0.98769 |
| 50 | 2.82916 | 1.62803 | 2.14790 | -0.64864277, -0.24673651 | 0.00116572, 0.2122708 | 87 | 66 | 0.98852 | 0.98784 |
| 51 | 2.89071 | 3.02084 | 4.21549 | -0.546182131, -0.253262929 | 8.822617[-05], 0.132792954 | 88 | 61 | 0.98970 | 0.98744 |
| 52 | 2.46587 | 2.72146 | 4.64330 | -0.297280218, -2[-10] | $9.43813[-05], 0.5$ | 84 | 61 | 0.98733 | 0.98507 |
| 53 | 2.08611 | 1.21178 | 0.73849 | -0.4268411, -0.19888518 | 0, 0.5 | 76 | 59 | 0.98655 | 0.98704 |
| 54 | 2.32228 | 2.97413 | 0.49990 | -0.40492888, -0.02533541 | 0.03269568, 0.49191016 | 80 | 63 | 0.98892 | 0.98833 |
| 55 | 2.58994 | 5.10622 | 0.32334 | $-0.39498385,-0.00474822$ | 0.00495389, 0.49998633 | 85 | 61 | 0.98805 | 0.98648 |
| 56 | 3.12728 | 2.66350 | 0.39019 | -0.326699117, -0.0739915233 | -9.20043811[-22], 0.33948113 | 87 | 65 | 0.98958 | 0.98674 |
| 57 | 2.47000 | 5.43223 | 0.54154 | -0.482205587, -7.549212[-05] | -5.0491846[-18], 0.5 | 80 | 60 | 0.98714 | 0.98682 |
| 58 | 2.72399 | 3.71018 | 6.01040 | -0.303331314, -0.150786279 | $1.92493278[-20], 0.499955936$ | 84 | 60 | 0.98957 | 0.98678 |
| 59 | 2.90324 | 4.67714 | 1.73488 | -0.625136304, -0.281968253 | $5.55111512[-21], 0.00316742482$ | 90 | 65 | 0.98831 | 0.98649 |
| 60 | 2.99424 | 4.13582 | 4.91289 | -0.560501634, -0.119668925 | $3.575767[-05], 0.360405124$ | 88 | 65 | 0.98958 | 0.98844 |
| 61 | 2.04922 | 5.46014 | 5.29590 | -0.639314505, -0.411878255 | $2.87362[-05], 0.0798711858$ | 74 | 61 | 0.98676 | 0.98593 |
| 62 | 2.41078 | 2.27029 | 2.80876 | -0.385793183, -0.0907787454 | $2.74816[-05], 0.499943768$ | 81 | 60 | 0.98786 | 0.98726 |
| 63 | 2.21419 | 3.89046 | 5.83689 | -0.317419452, -0.224085882 | $3.83378[-06], 0.0831143443$ | 75 | 63 | 0.98874 | 0.98588 |
| 64 | 2.94148 | 1.41033 | 4.49399 | -0.270611167, -0.212768941 | $1.12237808[-20], 0.478865876$ | 84 | 52 | 0.98873 | 0.98986 |
| 65 | 2.15569 | 3.79110 | 0.80333 | -0.658249637, -0.0313312003 | $1.27054942[-21], 0.367934754$ | 76 | 62 | 0.98641 | 0.98578 |
| 66 | 2.12855 | 6.09186 | 5.37105 | -0.344879199, -0.273737253 | 3.83749 [-05], 0.431750646 | 75 | 56 | 0.98511 | 0.98549 |
| 67 | 2.46317 | 5.92169 | 0.92723 | -0.9999999999, -0.350759059 | -5.20901191[-20], 0.000227563952 | 82 | 60 | 0.98751 | 0.98583 |
| 68 | 2.57193 | 3.08012 | 2.47826 | -0.30641164, -0.23576931 | $0.00577656,0.29877037$ | 82 | 58 | 0.98741 | 0.98741 |
| 69 | 2.96948 | 0.51671 | 4.13995 | -0.969678914, -0.318876434 | $5.55111512[-21], 0.00696480632$ | 87 | 62 | 0.98854 | 0.98628 |
| 70 | 2.70184 | 0.12106 | 2.01037 | -0.409739807, -0.0117086249 | $2.22044605[-20], 0.498682579$ | 83 | 59 | 0.98916 | 0.98827 |
| 71 | 2.66267 | 0.41965 | 3.55148 | -0.33466489, -0.01850706 | 0.04845566, 0.49860204 | 84 | 63 | 0.98930 | 0.98762 |
| 72 | 2.98978 | 1.38898 | 1.96907 | $-0.40022605,-1[-10]$ | -6.16297582[-33], 0.499910998 | 86 | 66 | 0.98937 | 0.98676 |
| 73 | 2.75605 | 3.05189 | 4.90998 | -0.75059603, -1[-10] | $2.02187991[-21], 0.442531917$ | 87 | 66 | 0.98894 | 0.98796 |
| 74 | 2.91441 | 4.72570 | 0.86171 | -0.45636805, -0.07078021 | $0.0083545,0.43573367$ | 86 | 63 | 0.98928 | 0.98744 |
| 75 | 2.27941 | 5.09299 | 3.50890 | -0.31793731, -0.13291007 | $0.00156619,0.46931166$ | 76 | 57 | 0.98831 | 0.98695 |
| 76 | 2.72950 | 3.56458 | 0.87768 | -0.234274471, -0.221418761 | $6.227788[-05], 0.499907965$ | 87 | 53 | 0.98819 | 0.98787 |
| 77 | 2.76295 | 5.11002 | 0.06402 | -0.282738656, -0.1626622 | 5.0062[-05], 0.32528278 | 85 | 61 | 0.98875 | 0.98703 |
| 78 | 2.72094 | 1.39060 | 3.53269 | -0.423759495, -0.310603864 | $9.50142[-05], 0.113009692$ | 87 | 62 | 0.98924 | 0.98794 |
| 79 | 2.99682 | 3.00681 | 2.64991 | -0.231924605, -0.177429066 | -2.63787115[-20], 0.5 | 87 | 53 | 0.98861 | 0.98860 |
| 80 | 2.86026 | 4.39329 | 3.54436 | $-0.582593075,-0.362445833$ | $4.50945[-06], 0.00342749573$ | 83 | 61 | 0.98938 | 0.98795 |
| 81 | 2.39940 | 0.21368 | 1.29938 | $-0.32610197,-0.268081307$ | 1.29557[-05], 0.5 | 82 | 64 | 0.98822 | 0.98711 |
| 82 | 1.89477 | 2.81396 | 0.23890 | -0.34113826, -0.04654715 | 0.02214931, 0.49999074 | 75 | 57 | 0.98761 | 0.98719 |
| 83 | 2.18455 | 3.97272 | 1.39291 | $-0.283828395,-0.201691582$ | $0.00021136743,0.362781599$ | 80 | 59 | 0.98474 | 0.98371 |
| 84 | 2.49180 | 2.58583 | 5.14075 | -0.653333749, -0.383343467 | $1.56079[-05], 0.0658074559$ | 81 | 63 | 0.98895 | 0.98740 |
| 85 | 2.59845 | 2.37573 | 3.12417 | $-0.621529941,-0.56172392$ | $0.000137961341,0.00064905387$ | 84 | 66 | 0.98824 | 0.98825 |
| 86 | 2.60883 | 6.17957 | 2.03449 | -0.33353985, -0.00353956 | 0.00062256, 0.49998387 | 85 | 59 | 0.98831 | 0.98776 |
| 87 | 2.85977 | 3.13459 | 4.87675 | $-0.735734897,-0.521398633$ | -2.84750996[-20], 0.0000855691489 | 83 | 63 | 0.98925 | 0.98889 |
| 88 | 3.05267 | 2.09009 | 0.15869 | -0.439726034, -0.276376103 | 8.36074[-05], 0.323169545 | 88 | 66 | 0.98953 | 0.98892 |
| 89 | 2.65536 | 1.53336 | 2.01915 | -0.5956152, -0.1775187 | $0.00273495,0.26232643$ | 83 | 64 | 0.98950 | 0.98805 |
| 90 | 2.42194 | 5.35202 | 1.63601 | -0.713680279, -0.32358958 | -2.11556797[-20], 0.0460521672 | 82 | 61 | 0.98628 | 0.98475 |
| 91 | 2.16767 | 1.66413 | 1.52262 | -0.38479997, -0.174828392 | $1.11022302[-20], 0.428639597$ | 80 | 60 | 0.98895 | 0.98738 |
| 92 | 2.98966 | 3.05187 | 1.47806 | -0.42503145, -0.1299089 | 0.0034686, 0.33280943 | 86 | 63 | 0.98810 | 0.98760 |
| 93 | 2.80563 | 4.43216 | 0.93327 | $-0.467989285,-9.99999736[-11]$ | $1.77245422[-21], 0.499900008$ | 88 | 64 | 0.98872 | 0.98726 |
| 94 | 2.76116 | 3.67330 | 3.58557 | -0.483856094, -6.68692[-05] | -5.18797705[-18], 0.49997342 | 88 | 62 | 0.98863 | 0.98729 |
| 95 | 2.86817 | 4.82626 | 0.79992 | -0.45313733, -2[-10] | $3.69508592[-19], 0.499900763$ | 86 | 65 | 0.98895 | 0.98641 |
| 96 | 3.10749 | 6.05200 | 0.55580 | $-0.33922282,-0.0857602356$ | $8.77796[-05], 0.456862679$ | 89 | 59 | 0.98866 | 0.98790 |
| 97 | 2.52530 | 1.56729 | 5.60700 | -0.32663141, -0.02261459 | $0.00403472,0.5$ | 81 | 63 | 0.98761 | 0.98575 |
| 98 | 2.61797 | 5.00611 | 4.61394 | $-0.32243556,-0.12939632$ | $0.00912948,0.43418299$ | 84 | 62 | 0.98958 | 0.98806 |
| 99 | 2.53796 | 3.96390 | 1.80047 | $-0.26281421,-0.16513112$ | $0.0335583,0.49467932$ | 78 | 61 | 0.98766 | 0.98604 |
| 100 | 2.31079 | 5.94527 | 1.46166 | -0.50568839, -0.1482959 | $0.00892103,0.45501687$ | 78 | 63 | 0.98772 | 0.98645 |

TABLE II. Data for learning accuracy.

|  | $\theta$ | $\phi$ | $\lambda$ | $X_{i} n$ | $Y_{i} n$ | $N$ | $F$ | $F_{\text {opt }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 2.83651 | 2.51483 | 5.79311 | $-0.22658129,-0.02628605$ | $6.46642309[-22], 0.499681951$ | 80 | 0.95489 | 0.96506 |
| 2 | 2.60239 | 2.91385 | 1.94757 | -0.38593267, -0.06560765 | $4.99435[-05], 0.498704474$ | 80 | 0.95075 | 0.97406 |
| 3 | 1.62294 | 2.66070 | 0.16163 | -0.602975987, -1[-10] | $0.01540395,0.49991607$ | 80 | 0.97004 | 0.97565 |
| 4 | 2.29195 | 1.76471 | 1.33492 | -0.52017218, -0.33360453 | 3.87541[-05], 0.211416718 | 80 | 0.95621 | 0.97061 |
| 5 | 2.42279 | 3.18159 | 5.57723 | $-0.35962401,-0.07388651$ | 0.02790605, 0.5 | 80 | 0.95731 | 0.97164 |
| 6 | 2.07221 | 2.36239 | 5.79011 | -0.78203655, -0.29764012 | -1.28986258[-20], 0.0923301799 | 80 | 0.95675 | 0.96929 |
| 7 | 2.06019 | 1.67036 | 2.73084 | -0.37643844, -0.01952776 | 4.5851 [-06], 0.499960074 | 80 | 0.96556 | 0.97080 |
| 8 | 2.96621 | 2.51154 | 2.51168 | -0.98231875, -0.50135792 | $0.00018449,0.00037358$ | 80 | 0.94750 | 0.97031 |
| 9 | 2.26002 | 1.81584 | 4.45387 | -0.98949422, -0.5671099 | 0.01415337, 0.03809302 | 80 | 0.95098 | 0.96492 |
| 10 | 1.35691 | 0.61534 | 5.02339 | -0.29599157, -0.57327287 | $0.31984894,0.4923946$ | 80 | 0.93653 | 0.94413 |
| 11 | 2.87028 | 1.87002 | 3.94885 | -0.45664744, -0.29318509 | $0.0095358,0.05159221$ | 80 | 0.94830 | 0.96723 |
| 12 | 2.15739 | 3.07773 | 5.71602 | $-0.42998516,-0.24883537$ | $0.13140672,0.29338095$ | 80 | 0.95490 | 0.97120 |
| 13 | 2.52209 | 1.73075 | 0.40260 | $-0.31623152,-0.14464535$ | 0.01684554, 0.33745235 | 80 | 0.95596 | 0.97104 |
| 14 | 2.74583 | 2.56126 | 3.80340 | -0.50005984, -0.12676685 | $0.00346618,0.21540484$ | 80 | 0.95053 | 0.96758 |
| 15 | 3.10688 | 2.83284 | 5.32182 | $-0.264065269,-9.999[-11]$ | 0, 0.5 | 80 | 0.95043 | 0.96972 |
| 16 | 1.95288 | 4.53352 | 3.46380 | -0.388548, -0.17632076 | 0.01503028, 0.38622965 | 80 | 0.96176 | 0.97168 |
| 17 | 1.73206 | 0.07675 | 2.44859 | -0.28327408, -0.26619532 | $0.09564394,0.35047785$ | 80 | 0.96741 | 0.97520 |
| 18 | 2.20927 | 3.00257 | 3.56097 | -0.32950066, -0.26883062 | $0.02256158,0.28228575$ | 80 | 0.95314 | 0.96663 |
| 19 | 2.79398 | 5.42806 | 6.24226 | -0.95830604, -0.38431026 | $0.00661281,0.00880922$ | 80 | 0.95065 | 0.97053 |
| 20 | 2.38126 | 1.40436 | 5.64973 | $-0.9554078,-0.43829696$ | $0.00012443,0.02216138$ | 80 | 0.95351 | 0.96658 |
| 21 | 2.50068 | 1.42982 | 5.42760 | -0.50448542, -0.10994467 | -6.77626358[-21], 0.49995152 | 80 | 0.95049 | 0.96533 |
| 22 | 1.78857 | 0.76770 | 2.56039 | -0.0624920122, -3.6113[-05] | $0.37509291,0.5$ | 80 | 0.96327 | 0.97092 |
| 23 | 2.68895 | 0.81678 | 2.57334 | -0.251802237, $-1[-10]$ | 0.07207826, 0.5 | 80 | 0.95488 | 0.96392 |
| 24 | 2.76371 | 5.67223 | 5.18676 | -0.20446587, -0.19910618 | -5.55111512[-21], 0.499977945 | 80 | 0.95454 | 0.97839 |
| 25 | 2.35484 | 2.12405 | 5.77071 | -0.79739122, -0.43221379 | $0.00517663,0.06708963$ | 80 | 0.95573 | 0.96874 |
| 26 | 2.14670 | 1.98890 | 5.87210 | -0.22988712, -0.16913267 | 0.000041023229, 0.5 | 80 | 0.95506 | 0.97596 |
| 27 | 2.14131 | 3.88017 | 4.43203 | $-0.99994708,-0.50247325$ | -5.36055763[-20], 0.00700035073 | 80 | 0.96013 | 0.97200 |
| 28 | 2.70824 | 1.78139 | 4.29155 | -0.26922985, -0.07666227 | 0.0000662211987, 0.5 | 80 | 0.94925 | 0.97055 |
| 29 | 3.11359 | 2.04632 | 4.96774 | -0.49732798, -0.01685642 | $0.0000174612887,0.287787822$ | 80 | 0.95234 | 0.96586 |
| 30 | 1.97566 | 2.68021 | 0.50074 | -0.698348786, -8.94312[-05] | $1.96800135[-20], 0.347860102$ | 80 | 0.96010 | 0.97122 |
| 31 | 2.12776 | 6.08943 | 4.49468 | -0.6823936, -0.43406705 | -1.49253285[-20], 8.2134[-05] | 80 | 0.96315 | 0.97325 |
| 32 | 2.85530 | 4.67939 | 4.28628 | -0.91867228, -0.30253779 | $1.552483[-05], 6.98294[-05]$ | 80 | 0.95623 | 0.97096 |
| 33 | 2.41524 | 3.79065 | 3.00641 | $-0.37244503,-0.34949234$ | 0.00355155, 0.04073554 | 80 | 0.95088 | 0.96893 |
| 34 | 2.93550 | 5.17916 | 4.46644 | -0.65012892, -0.00071334 | $9.920904[-05], 0.499348973$ | 80 | 0.95534 | 0.96503 |
| 35 | 2.69760 | 4.06237 | 2.82939 | $-0.63380379,-0.49980422$ | 2.02733247 [-21], 0.0145546481 | 80 | 0.95429 | 0.96918 |
| 36 | 2.26660 | 4.60415 | 4.39647 | -0.113053973, -2[-10] | $0.36858133,0.4999619$ | 80 | 0.95881 | 0.96739 |
| 37 | 2.23500 | 1.56288 | 2.13387 | -0.45531637, -0.00497668 | $0.00062212,0.49991192$ | 80 | 0.95726 | 0.97510 |
| 38 | 2.77113 | 4.38132 | 1.28333 | $-0.24967158,-0.15935152$ | -1.11022302[-20], 0.328961357 | 80 | 0.95507 | 0.97155 |
| 39 | 2.88243 | 5.35496 | 0.00254 | -0.427704684, -2[-10] | 0, 0.49990047 | 80 | 0.94829 | 0.96905 |
| 40 | 2.37142 | 3.14858 | 1.06018 | -0.4651497, -0.126999 | $0.000245935043,0.454376543$ | 80 | 0.95579 | 0.97436 |
| 41 | 2.21118 | 4.30358 | 5.56859 | -0.46724996, -0.14351635 | $9.56351687[-21], 0.387786874$ | 80 | 0.96100 | 0.97322 |
| 42 | 2.76569 | 4.78934 | 3.68815 | -0.716947108, -9.9999[-11] | $0.0000781179353,0.38177391$ | 80 | 0.94966 | 0.96441 |
| 43 | 2.44340 | 5.86060 | 0.66880 | -0.04856462, -0.01146986 | 0.39178085, 0.5 | 80 | 0.95449 | 0.96311 |
| 44 | 2.34349 | 5.17034 | 3.42800 | $-0.50962221,-0.10198462$ | -2.44669142[-21], 0.321459154 | 80 | 0.95993 | 0.97187 |
| 45 | 2.89725 | 3.25978 | 2.46404 | -0.24073117, -0.14868635 | $0.23972925,0.48865284$ | 80 | 0.95361 | 0.96456 |
| 46 | 2.22109 | 3.17582 | 4.57342 | $-0.62021665,-0.40811444$ | -4.32608973[-22], 0.13008986 | 80 | 0.96011 | 0.96776 |
| 47 | 2.12925 | 5.74234 | 4.16431 | -0.9871146, -0.67280069 | $2.0287[-05], 7.73143[-05]$ | 80 | 0.95991 | 0.96988 |
| 48 | 2.04236 | 4.02405 | 4.75088 | -0.68862154, -0.01168985 | 6.60527[-05], 0.499981325 | 80 | 0.96238 | 0.96944 |
| 49 | 2.84364 | 3.51744 | 2.31714 | -0.32325424, -0.14378023 | 3.83964[-05], 0.499543956 | 80 | 0.94615 | 0.96817 |
| 50 | 2.82916 | 1.62803 | 2.14790 | -0.37096935, -0.00577171 | -1.47512731[-21], 0.5 | 80 | 0.95368 | 0.97311 |
| 51 | 2.89071 | 3.02084 | 4.21549 | -0.29921219, -0.00906005 | $-1.35525272[-20], 0.499257551$ | 80 | 0.95582 | 0.97193 |
| 52 | 2.46587 | 2.72146 | 4.64330 | -0.36316915, -0.17747838 | $0.04782131,0.32694109$ | 80 | 0.95432 | 0.96942 |
| 53 | 2.08611 | 1.21178 | 0.73849 | $-0.499964682,-9.99999451[-11]$ | -1.79986232[-22], 0.499906444 | 80 | 0.96474 | 0.96976 |
| 54 | 2.32228 | 2.97413 | 0.49990 | -0.22795569, -0.28454808 | $0.43776391,0.06221192$ | 80 | 0.96224 | 0.97109 |
| 55 | 2.58994 | 5.10622 | 0.32334 | -0.31939401, -0.0295772 | 0.00628181, 0.5 | 80 | 0.95194 | 0.97293 |
| 56 | 3.12728 | 2.66350 | 0.39019 | -0.632374964, -6.1994[-05] | $-1.18584613[-20], 0.49994338$ | 80 | 0.95171 | 0.96751 |
| 57 | 2.47000 | 5.43223 | 0.54154 | -0.50496711, -0.48283996 | $1.25185446[-32], 9.86319[-05]$ | 80 | 0.95510 | 0.96737 |
| 58 | 2.72399 | 3.71018 | 6.01040 | -0.16010373, -0.1469441 | 0.06064396, 0.5 | 80 | 0.95385 | 0.96758 |

TABLE II. (Continued.)

|  | $\theta$ | $\phi$ | $\lambda$ | $X_{i} n$ | $Y_{i} n$ | $N$ | $F$ | $F_{\text {opt }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 59 | 2.90324 | 4.67714 | 1.73488 | -0.28429079, -0.20231022 | 0.00179217, 0.47709926 | 80 | 0.95081 | 0.97573 |
| 60 | 2.99424 | 4.13582 | 4.91289 | -0.02108512, -0.01182204 | 0.4291328, 0.49965538 | 80 | 0.95090 | 0.96142 |
| 61 | 2.41078 | 2.27029 | 2.80876 | $-0.52971722,-2[-10]$ | 0, 0.4999877 | 80 | 0.95496 | 0.96923 |
| 62 | 2.04922 | 5.46014 | 5.29590 | -0.629668181, -1[-10] | 0.00678738, 0.49976816 | 80 | 0.95974 | 0.97135 |
| 63 | 2.21419 | 3.89046 | 5.83689 | -0.47849604, -0.23786693 | $0.01470454,0.1980091$ | 80 | 0.96645 | 0.97392 |
| 64 | 2.94148 | 1.41033 | 4.49399 | -0.91405141, -0.37960688 | $1.23144[-05], 0.015310517$ | 80 | 0.95117 | 0.97334 |
| 65 | 2.15569 | 3.79110 | 0.80333 | -0.4722672, -0.0008256 | $2.7606[-05], 0.490354894$ | 80 | 0.95660 | 0.96973 |
| 66 | 2.12855 | 6.09186 | 5.37105 | -0.68386331, -0.02070827 | $6.78906[-05], 0.445970143$ | 80 | 0.95647 | 0.96928 |
| 67 | 2.46317 | 5.92169 | 0.92723 | -0.40536361, -0.06195646 | -9.71500658[-17], 0.5 | 80 | 0.95483 | 0.97081 |
| 68 | 2.57193 | 3.08012 | 2.47826 | $-0.20387137,-0.15862918$ | 3.9381[-05], 0.498799416 | 81 | 0.95168 | 0.97153 |
| 69 | 2.96948 | 0.51671 | 4.13995 | $-0.3304364,-0.25845847$ | 0.16309126, 0.41210785 | 80 | 0.95115 | 0.96170 |
| 70 | 2.70184 | 0.12106 | 2.01037 | $-0.38296615,-0.06624632$ | 9.13122[-05], 0.499907461 | 80 | 0.95470 | 0.97134 |
| 71 | 2.66267 | 0.41965 | 3.55148 | -0.586690017, -0.000372t | 0.0002436, 0.499949076 | 80 | 0.95525 | 0.96859 |
| 72 | 2.98978 | 1.38898 | 1.96907 | -0.23519674, -0.21290984 | 0.12852131, 0.30134054 | 80 | 0.94986 | 0.96740 |
| 73 | 2.27941 | 5.09299 | 3.50890 | -0.23220527, -0.19757706 | 0.02101817, 0.44517371 | 80 | 0.95617 | 0.97342 |
| 74 | 2.91441 | 4.72570 | 0.86171 | -0.48678714, -0.00094883 | -3.74034123[-22], 0.5 | 80 | 0.95442 | 0.96971 |
| 75 | 2.75605 | 3.05189 | 4.90998 | -0.81900705, -0.33719561 | 0.00041039, 0.01351214 | 80 | 0.94987 | 0.97077 |
| 76 | 2.72950 | 3.56458 | 0.87768 | -0.40243751, -0.00236464 | $4.45289[-05], 0.499937424$ | 80 | 0.95567 | 0.97289 |
| 77 | 2.76295 | 5.11002 | 0.06402 | -0.29332909, -0.1951465 | 0.0212047, 0.39766611 | 80 | 0.95471 | 0.97428 |
| 78 | 2.72094 | 1.39060 | 3.53269 | -0.82801909, -0.26676811 | 1.5504[-05], 0.201188085 | 80 | 0.95052 | 0.96384 |
| 79 | 2.99682 | 3.00681 | 2.64991 | $-0.70675606,-0.01714809$ | 3.9807[-05], 0.368567782 | 80 | 0.95371 | 0.96678 |
| 80 | 2.86026 | 4.39329 | 3.54436 | $-0.372577823,-1[-10]$ | 6.98153[-08], 0.5 | 80 | 0.94878 | 0.97406 |
| 81 | 2.39940 | 0.21368 | 1.29938 | -0.45744, -0.1669 | -2.8281[-20], 0.38364 | 80 | 0.95497 | 0.97135 |
| 82 | 1.89477 | 2.81396 | 0.23890 | -0.510694, -0.092163 | -1.09101[-19], 0.5 | 80 | 0.96706 | 0.97563 |
| 83 | 2.18455 | 3.97272 | 1.39291 | -0.508156, -1[-10] | 0.00456, 0.49991 | 80 | 0.95857 | 0.96752 |
| 84 | 2.49180 | 2.58583 | 5.14075 | -0.99610258, -0.34906797 | $7.73614[-06], 6.6692[-05]$ | 80 | 0.95209 | 0.97350 |
| 85 | 2.59845 | 2.37573 | 3.12417 | -0.441353237, -6.2831[-05] | 0.01563258, 0.5 | 80 | 0.95124 | 0.97010 |
| 86 | 2.60883 | 6.17957 | 2.03449 | -0.21592729, -0.17875946 | $4.21849[-05], 0.312400669$ | 80 | 0.95445 | 0.97418 |
| 87 | 2.85977 | 3.13459 | 4.87675 | -0.950751522, -1[-10] | $1.22478392[-18], 0.499001011$ | 80 | 0.95092 | 0.96456 |
| 88 | 3.05267 | 2.09009 | 0.15869 | -0.553028459, -1[-10] | $1.41296829[-19], 0.409878614$ | 80 | 0.94655 | 0.96793 |
| 89 | 2.65536 | 1.53336 | 2.01915 | -0.3610569, -0.10599245 | 0.00771934, 0.49831975 | 80 | 0.95151 | 0.97561 |
| 90 | 2.42194 | 5.35202 | 1.63601 | -0.35453141, -0.32129783 | 0.12163206, 0.13424023 | 80 | 0.95596 | 0.96609 |
| 91 | 2.16767 | 1.66413 | 1.52262 | -0.98601261, -0.50422059 | -9.48289521[-21], 6.12274[-05] | 80 | 0.96180 | 0.97663 |
| 92 | 2.98966 | 3.05187 | 1.47806 | $-0.529954412,-1.06161[-05]$ | 0.00924164, 0.49999361 | 80 | 0.95481 | 0.96844 |
| 93 | 2.80563 | 4.43216 | 0.93327 | -0.63947564, -0.01072315 | 4.78721 [-05], 0.461841234 | 80 | 0.95126 | 0.96677 |
| 94 | 2.76116 | 3.67330 | 3.58557 | $-0.28274626,-0.0566703$ | -3.38813179[-20], 0.499436234 | 80 | 0.95401 | 0.97358 |
| 95 | 2.86817 | 4.82626 | 0.79992 | -0.3661714, -0.32752026 | 0.11331283, 0.12163038 | 80 | 0.95044 | 0.96680 |
| 96 | 3.10749 | 6.05200 | 0.55580 | $-0.30965446,-0.24969456$ | $0.00307031,0.15108169$ | 80 | 0.95483 | 0.97068 |
| 97 | 2.52530 | 1.56729 | 5.60700 | -0.625100171, -2[-10] | 5.55111511[-21], 0.4999 | 80 | 0.95207 | 0.96550 |
| 98 | 2.61797 | 5.00611 | 4.61394 | $-0.334751199,-1[-10]$ | $0.03123503,0.5$ | 80 | 0.95578 | 0.97218 |
| 99 | 2.53796 | 3.96390 | 1.80047 | -0.998360446, -2[-10] | $1.21919[-05], 0.48416587$ | 80 | 0.95285 | 0.96310 |
| 100 | 2.31079 | 5.94527 | 1.46166 | -0.44647969, -0.27303986 | -3.88578059[-20], 0.150260118 | 80 | 0.95846 | 0.97214 |

right panel shows the data with the optimal PDF. We note that both histograms are basically the same, which means that the learning speed optimization will not affect the fidelity or accuracy of the final result.

## APPENDIX B: LEARNING ACCURACY DATA

The next table collects all the data for the 100 different instances for the choice of $\{\theta, \phi, \lambda\}$ and their $X_{i} n$ and $Y_{i} n$
for the optimal CDF. Also the table shows the fidelity for the optimal $\left(F_{\text {opt }}\right)$ and nonoptimal PDF $(F)$ as well as the number of iterations used $(N)$. In this case we are optimizing the learning accuracy.

We can see in this case that the fidelity obtained with optimization increases with respect to the fidelity obtained by the use of a uniform PDF, which means that the optimization of the learning accuracy works fine.

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