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Maximum Principles for Finite Element Solutions on a Riemann Surface, II

Dedicated to Professor Fumi-Yuki Maeda on the occasion of his 60th birthday

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Abstract

In the previous paper [3] we established the maximum principles for the finite element solutions of the partial differential equation: surface $\bar{\Omega}$. In the present paper we shall improve and extend the results in the paper [3]. First we construct a triangulation K of $\bar{\Omega}$ with width h and introduce a class $S = S(K)$ of element functions on K . For a partition to two parts C_1 and C_2 of the boundary $\partial\Omega$, we define the finite element approximation $\omega_h \in S$ of the boundary value problem: $\Delta u - qu = f$ on Ω , $u = \chi$ on C_1 and $*du = 0$ along C_2 , where by $*du$ we denote the conjugate differential of du . We assume that all angles of 2-simplices of K are $\leq \pi/2$. Under the assumption weaker than one in the paper [3], we shall exhibit that the inequality

$$|\omega_h| \leq \exp\left(\frac{4\pi M}{\sin \theta} \cdot \max_{\bar{\Omega}} q\right) \left(\max_{C_1} |\chi| + \frac{2}{\sin \theta} \iint_{\Omega} |f| \, dx dy\right)$$

holds for sufficiently small h , where θ is the smallest value of all angles of 2-simplices of K and M is a constant. The last inequality will be very useful to obtain error estimates of the finite element solutions.

Introduction

In the previous paper [3] we established the maximum principles for the finite element approximate solutions of the partial differential equation

$$\Delta u - qu \equiv \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} - qu = f \quad (z = x + iy)$$

on a compact bordered Riemann surface $\bar{\Omega}$ under the assumption that there exists $\epsilon > 0$ being independent of individual triangulation K such that all angles of 2-simplices of K are $\leq \pi/2 - \epsilon$. This assumption for angles of

the 2-simplices is not convenient for the various applications of finite element method not only on a Riemann surface but also in the euclidean space. In the present paper we present the maximum principles under the assumption that all angles of 2-simplices of K are $\leq \pi/2$, which is reasonable restriction in actual applications.

The present paper consists of the three sections:

§ 1 is devoted to construction of the triangulations K and K' of two kinds. K is a triangulation of $\bar{\Omega}$ and K' is a modification of K .

In § 2, first we define the original solution u as a solution of the boundary value problem:

$$\begin{aligned} \Delta u - qu &= f && \text{on } \Omega, \\ u &= \chi && \text{on } C_1, \\ *du &= 0 && \text{along } C_2, \end{aligned}$$

where $\{C_1, C_2\}$ is a partition to two parts of the boundary $\partial\Omega$, and by $*du$ we denote the conjugate differential of du . Next we state that u is the solution of the variational problem minimizing the functional

$$J[v] \equiv \iint_{\Omega} \left(\left(\frac{\partial v}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + qv^2 + 2fv \right) dx dy$$

in a class \mathfrak{F}_χ of functions v satisfying $v = \chi$ on C_1 . Further we introduce two classes of element functions on K and K' : the *comparable class* $S = S(K)$ (with u) and the *computable class* $S' = S'(K')$. S' is a collection of modifications $v'_h = F(v_h)$ of $v_h \in S$, where F defines a one-to-one mapping of S onto S' .

In § 3, first we introduce the finite element approximations ω_h and u'_h of u in S and S' respectively which are defined as the functions $\omega_h \in S_\chi$ and $u'_h \in S'_\chi$ satisfying the minimalities

$$J[\omega_h] = \min_{v_h \in S_\chi} J[v_h]$$

and

$$J[u'_h] = \min_{v'_h \in S'_\chi} J[v'_h] \quad \text{resp.,}$$

where S_χ is the subclass of S whose functions v_h satisfy the boundary condition $v_h = \tilde{\chi}$ ($\tilde{\chi}$ is the finite element interpolation of χ (see § 2.5 for the definition)) and $S'_\chi = \{v'_h \mid v'_h = F(v_h), v_h \in S_\chi\}$. The main results in the present paper are stated as follows: For sufficiently small $h > 0$, the inequalities

$$|\omega_h| \leq \exp \left(\frac{4\pi M}{\sin \theta} \cdot \max_{\bar{\Omega}} q \right) \cdot \left(\max_{C_1} |\chi| + \frac{2}{\sin \theta} \iint_{\Omega} |f| dx dy \right) \quad \text{and}$$

$$|u_h| \leq \exp \left(\frac{2\pi M}{\sin \theta} \cdot \max_{\bar{\Omega}} q \right) \cdot \left(\max_{C_1} |\chi| + \frac{1}{\sin \theta} \sum_{s \in K'} \iint_{|s|} |f| dx dy \right)$$

hold, where θ is the smallest value of all angles of the triangles $\varphi_j(s)$ ($\varphi_j(\mathfrak{h}(s))$ in place of $\varphi_j(s)$ for a minor or major simplex s) ($s \in K_j$; $j = 1, \dots, m$) (see § 1 for the definition), M is a constant defined in (i') of § 1.2.

The results in the present paper will be applied to error estimation for the finite element approximations in the forthcoming paper [4].

§ 1. Triangulation.

1. Collection Φ of local parameters. Let Ω be a subdomain of a Riemann surface W whose closure $\bar{\Omega}$ is a compact bordered subregion of W and whose boundary $\partial\Omega$ consists of a finite number of piecewise analytic closed curves. Let $\{p'_k\}_{k=1}^l$ be the collection of the vertices on $\partial\Omega$ at which the curves $\partial\Omega$ is not analytic. Then we assume that there exist parametric disks V_k ($k = 1, \dots, l$) with the centers p'_k and the local parameters $z = \psi_k(p)$ by which $V_k \cap \bar{\Omega}$ are mapped onto sectors $\{|z| \leq r_k\} \cap \{0 \leq \arg z \leq \beta_k\}$ ($0 < \beta_k \leq 2\pi$, $\beta_k \neq \pi$).

Let $\{C', C''\}$ be a partition to two parts of the boundary $\partial\Omega$ such that C' and C'' are sums of boundary components of $\partial\Omega$.

We assign 2σ points $p_1, \dots, p_{2\sigma}$ ($\sigma \geq 0$) on C'' in such a manner that an even number of $p_1, \dots, p_{2\sigma}$ are assigned on each boundary component of C'' in the positive orientation with respect to Ω and in their order.

By $\Phi = \{ z = \varphi_j(p), U_j; j=1, \dots, m \}$ we denote a finite collection of local parameters $z = \varphi_j(p)$ ($j=1, \dots, m$) and parametric disks U_j ($j=1, \dots, m$) on W which satisfies the following conditions (i) ~ (v):

(i) Each U_j ($j=1, \dots, m$) is mapped onto a disk $|z| < \rho_j$ by the mapping $z = \varphi_j(p)$.

(ii) $\bar{\Omega}$ is covered by $\{U_j\}_{j=1}^m$.

(iii) If $U_j \cap U_k \neq \emptyset$, then there exists a constant $L (> 1)$ such that for the mapping $\zeta = \varphi(z) \equiv \varphi_k \circ \varphi_j^{-1}(z)$, $1/L < |\varphi'(z)| < L$ on $\varphi_j(U_j \cap U_k)$.

Let p_k ($k=2\sigma+1, \dots, \nu$) be all the vertices of $\partial\Omega$ which are defined as the points of $\{p'_k\}_{k=1}^{\nu} - \{p_k\}_{k=1}^{2\sigma}$.

(iv) each U_j ($j=1, \dots, m$) contains at most one p_k ($k=1, \dots, \nu$) and if $p_k \in U_j$ then $\varphi_j(p_k) = 0$.

(v) If $U_j \cap \partial\Omega \neq \emptyset$ and U_j does not contain any p_k ($k=1, \dots, \nu$), then $\varphi_j(U_j \cap \Omega)$ is a half disk $\{|z| < \rho_j\} \cap \{\text{Im } z > 0\}$. If U_j contains some p_k ($k=1, \dots, \nu$), then $\varphi_j(U_j \cap \Omega)$ is a sector $\{|z| < \rho_j\} \cap \{0 < \arg z < \alpha_j\}$ ($0 < \alpha_j \leq 2\pi$).

In the latter case of (v), if $p_k \neq p_1, \dots, p_{2\sigma}$, then by the mapping $\zeta = \{\varphi_j(p)\}^{\pi/\alpha_j}$, $U_j \cap \Omega$ is mapped onto a half disk $\{|\zeta| < \rho_j^{\pi/\alpha_j}\} \cap \{\text{Im } \zeta > 0\}$. In this case we define anew $z = \varphi_j(p)$ and ρ_j by $\zeta = \{\varphi_j(p)\}^{\pi/\alpha_j}$ and ρ_j^{π/α_j} respectively. Further, in the latter case of (v), if U_j contains some p_k ($k=1, \dots, 2\sigma$), then by the mapping $\zeta = (\varphi_j(p))^{\pi/2\alpha_j}$, $U_j \cap \Omega$ is mapped onto a quadrant $\{|\zeta| < \rho_j^{\pi/2\alpha_j}\} \cap \{0 < \arg \zeta < \pi/2\}$. In this case we define anew $z = \varphi_j(p)$ and ρ_j by $\zeta = (\varphi_j(p))^{\pi/2\alpha_j}$ and $\rho_j^{\pi/2\alpha_j}$ respectively.

Then, in the case that U_j contains some p_k ($k=1, \dots, \nu$) the local parameter $z = \varphi_j(p)$ is no longer conformal at the center of U_j except for the case when U_j contains some p_k ($k=1,$

$\dots, 2\sigma$) and $\alpha_j = \pi/2$.

2. Triangulation K associated to Φ . For the collection Φ of local parameters and parametric disks defined in § 1.1, and for a sufficiently small $h > 0$, we construct a triangulation $K = K^h$ of $\bar{\Omega}$ which satisfies the following conditions (i) ~ (v). This is called a *triangulation of $\bar{\Omega}$ with width h associated to Φ* .

(i) The points p_1, \dots, p_ν are carriers of some 0-simplices of K .

(ii) K is the sum of subtriangulations K_1, \dots, K_m of K such that each 2-simplex of K belongs to one and only one K_j ($j=1, \dots, m$), and the carrier $|s|$ of each 2-simplex s of K_j is contained in U_j .

If a 1-simplex $e \in K_j$ does not belong to another K_k ($k \neq j$), or a 1-simplex e belongs to $K_j \cap K_k$ ($j \neq k$) and the mapping $\varphi_k \circ \varphi_j^{-1}$ is an affine transformation, then e is said to be *linear*. If each edge of a 2-simplex $s \in K_j$ is linear and $\varphi_j(s)$ is an ordinary triangle, then s is called a *natural simplex*.

(iii) Each 2-simplex $s \in K_j$ which has not a common edge with any 2-simplex of another K_k ($k \neq j$), is a natural simplex.

A 2-simplex of K_k which has a common edge with a 2-simplex $s \in K_j$ ($j \neq k$), is said to be an *adjoint* (simplex) of s and is denoted by s' .

(iv) For each pair of a 2-simplex $s \in K_j$ and its adjoint $s' \in K_k$ with a common edge e , either one of the following three cases (a), (b) and (c) occurs.

(a) Both s and s' are natural simplices.

(b) $\varphi_j(s)$ is a curvilinear triangle such that $\varphi_j(e)$ is a strictly concave arc w.r.t. $\varphi_j(s)$, $\varphi_k(s')$ is an ordinary triangle, and all edges of s and s' except for e are linear (cf. Fig. 1). Then s is called a *minor simplex*. The case where s' is a minor simplex and s is its adjoint may also occur.

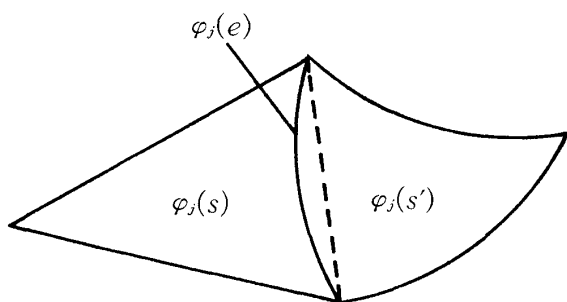


Fig. 1. Minor simplex s and its adjoint s'

(c) $\varphi_j(s)$ is a curvilinear triangle such that $\varphi_j(e)$ is a strictly convex arc w.r.t. $\varphi_j(s)$, $\varphi_k(s')$ is an ordinary triangle, and all edges of s and s' except for e are linear (cf. Fig. 2). Then s is called a *major simplex*. The case where s' is a major simplex and s is its adjoint may also occur.

If s is a minor or major simplex of K_j , then it is assumed that $|s'| \subset U_j$ for its adjoint s' .

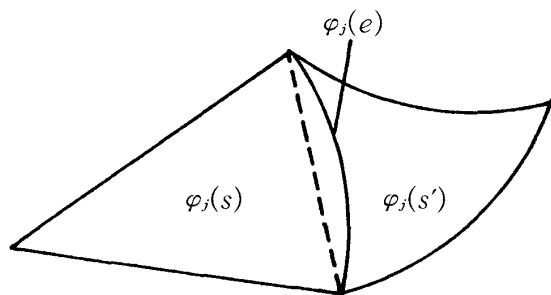


Fig. 2. Major simplex s and its adjoint s'

(v) For each 2-simplex $s \in K_j$ ($j=1, \dots, m$), $d(\varphi_j(s)) \leq h$, where throughout the present paper we denote the diameter of a region G by $d(G)$.

Next, we assume that for the fixed \mathcal{O} the class of the triangulations $K = K^h$ satisfies the following conditions (i') ~ (iv'):

(i') The number N of 2-simplices of K satisfies the inequality:

$$N \leq M \cdot \frac{1}{h^2},$$

where M is a constant which is independent of the individual triangulation K .

For each minor (or major) simplex $s \in K_j$

we define the *naturalized simplex* $\mathfrak{h}s$ of s as the 2-simplex such that $|s| \subset |\mathfrak{h}s|$ ($|\mathfrak{h}s| \subset |s|$ resp.) and $\varphi_j(\mathfrak{h}s)$ is the ordinary triangle which has two common sides with $\varphi_j(s)$.

(ii') All angles of the triangles $\varphi_j(s)$ ($\varphi_j(\mathfrak{h}s)$ in place of $\varphi_j(s)$ for a minor or major simplex s) ($s \in K_j; j=1, \dots, m$) are $\leq \pi/2$.

(iii') For each $j=1, \dots, m$ the union of carriers of all minor and major simplices of K_j , and all their adjoints is contained in a closed subset R_j of $U_j \cap \bar{\mathcal{O}}$ which is independent of the individual triangulation K .

(iv') The number N' of minor and major simplices of K satisfies the inequality:

$$(1.1) \quad N' \leq M' \cdot \frac{1}{h},$$

where M' is a constant which is independent of the individual triangulation K .

3. Lune. For each minor (or major) simplex $s \in K_j$ we define a 2-simplex $\mathfrak{b}\ell = \mathfrak{b}\ell(s)$ ($\#\ell = \#\ell(s)$ resp.) with two edges whose carrier is the closed region $|\mathfrak{h}s| - |s|$ ($|s| - |\mathfrak{h}s|$ resp.). $\mathfrak{b}\ell(s)$ ($\#\ell(s)$ resp.) is called the *deficient* (*excessive* resp.) *lune* of s .

Each triple of a minor (or major) simplex $s \in K_j$, its adjoint $s' \in K_k$ and its deficient lune $\mathfrak{b}\ell$ (*excessive lune* $\#\ell$ resp.) is denoted by $(s, s', \mathfrak{b}\ell)$ ($(s, s', \#\ell)$ resp.), and is called a *triple for a minor* (*major* resp.) *simplex* s or for a *deficient* (*excessive* resp.) *lune* $\mathfrak{b}\ell$ ($\#\ell$ resp.) (cf. Figs. 3 and 4), where it is always assumed that $|\mathfrak{b}\ell| \subset |s'|$ for each $(s, s', \mathfrak{b}\ell)$.

For simplicity of notation, we also denote $\mathfrak{b}\ell = \mathfrak{b}\ell(s)$ or $\#\ell = \#\ell(s)$ by $\ell = \ell(s)$. If a minor or major simplex s is in K_j , then we say that $\ell = \ell(s)$ is a *lune of* K_j and write $\ell \in K_j$.

Now we shall define the *naturalized triangulation* K' associated to K .

First, K'_j ($j=1, \dots, m$) are defined as triangulations such that the collection of all 2-simplices of K'_j consists of all 2-simplices of K_j which are not minor or major, and of all

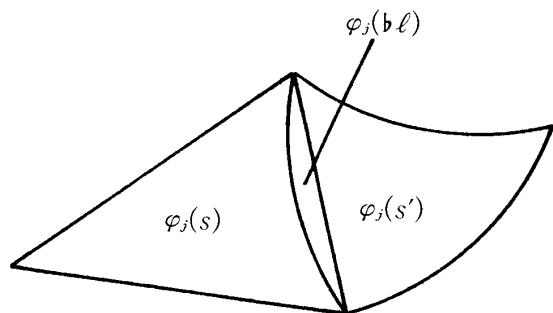


Fig. 3. Triple (s, s', bℓ) for a minor simplex.

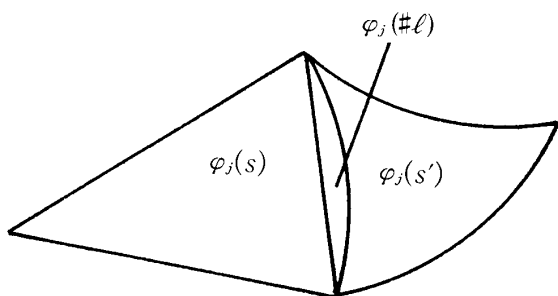


Fig. 4. Triple (s, s', #ℓ) for a major simplex.

naturalized simplices of minor and major ones of K_j . Then the triangulation K' is defined as the sum of K'_j ($j=1, \dots, m$). We should note that K' is no longer a triangulation of $\bar{\Omega}$, and also is not an ordinary triangulation.

4. Area of lune.

LEMMA 1.1. *Let (s, s', ℓ) be a triple for an arbitrary deficient or excessive lune ℓ. Then, the estimate*

$$(1.2) \quad A(\varphi_j(\ell)) \leq \frac{h_1^3}{8} \left(\left| \frac{\psi''(\xi_1)}{\psi'(\xi_1)^2} \right| + xh_1 \right)$$

holds, where throughout the present paper we denote the area of a region G by $A(G)$, $z = \psi(\zeta) \equiv \varphi_j \circ \varphi_k^{-1}(\zeta)$, $h_1 = d(\varphi_j(\ell))$, ξ_1 is one of the vertices of the lunar domain $\varphi_k(\ell)$ and x is a constant depending only on ψ .

See Lemma 1.1 of [1] for the proof.

§ 2. Classes of functions.

1. Class \mathfrak{F} . We consider the partial differen-

tial equation

$$(2.1) \quad L_z[u] \equiv \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} - qu = f$$

on Ω , where $z = x + iy$ is a local parameter, u is an unknown function, q and f are the Hölder continuous (with exponent α ($0 < \alpha \leq 1$)) covariant tensors which are defined by satisfying

$$(2.2) \quad q(z) = \left| \frac{d\zeta}{dz} \right|^2 q(\varphi(z)) \text{ and } f(z) = \left| \frac{d\zeta}{dz} \right|^2 f(\varphi(z))$$

by a change of local parameters $\zeta = \varphi(z)$, and we assume that $q \geq 0$.

By \mathfrak{F} we denote the class of all continuous functions v on $\bar{\Omega} = \Omega \cup \partial\Omega$, for which the partial derivatives $\partial v / \partial x$ and $\partial v / \partial y$ with respect to the local parameter $z = x + iy$ exist and are continuous on Ω at most except for a finite number of rectifiable curves on Ω , and for which the integral

$$\iint_{\Omega} \left(\left(\frac{\partial v}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + qv^2 + 2|fv| \right) dx dy$$

is finite. Let v and w be functions in \mathfrak{F} , let \mathfrak{f} be a covariant tensor on $\bar{\Omega}$, and let G be a subregion of $\bar{\Omega}$. We introduce the notations

$$(\mathfrak{f}, v)_{0,G} \equiv \iint_G \mathfrak{f} v \, dx dy,$$

$$(v, w)_G \equiv \iint_G \left(\frac{\partial v}{\partial x} \frac{\partial w}{\partial x} + \frac{\partial v}{\partial y} \frac{\partial w}{\partial y} + qvw \right) dx dy$$

and

$$\|v\|_G \equiv (v, v)_G^{1/2}.$$

We define an *inner product* (v, w) of v and w , a *norm* $\|v\|$ of v and a functional $J[v]$ of v by

$$\begin{aligned} (v, w) &= (v, w)_{\Omega}, \\ \|v\| &= \|v\|_{\Omega} \quad \text{and} \\ J[v] &= \|v\|^2 + 2(\mathfrak{f}, v)_{0,\Omega} \\ &= \iint_{\Omega} \left(\left(\frac{\partial v}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial y} \right)^2 + qv^2 + 2fv \right) dx dy \end{aligned}$$

respectively. For simplicity, we set

$$(\mathfrak{f}, v)_0 = (\mathfrak{f}, v)_{0,\Omega}.$$

2. Original solution. Let γ_k ($k=1, \dots, \sigma$) be the arcs (closed sets) on C'' from p_{2k-1} to p_{2k} , and let $C'_1 = \sum_{k=1}^{\sigma} \gamma_k$, $C_1 = C' + C'_1$ and $C_2 = C'' - C'_1$, where $\{p_k\}_{k=1}^{2\sigma}$ are the 2σ points on C'' defined in § 1.1. Let χ be a function in \mathfrak{F} which satisfies the conditions:

(i) The 2nd ordered partial derivatives of χ are Hölder continuous (with exponent α ($0 < \alpha \leq 1$)) on a neighborhood of C' .

(ii) χ is constant on each γ_k ($k=1, \dots, \sigma$). By \mathfrak{F}_χ we denote the subclass of \mathfrak{F} consisting of all functions v of \mathfrak{F} satisfying the boundary condition:

$$v = \chi \quad \text{on } C_1.$$

The solution u of the equation (2.1) on Ω satisfying the boundary conditions:

$$(2.3) \quad u = \chi \quad \text{on } C_1, \quad \text{and}$$

$$(2.4) \quad *du = 0 \quad \text{along } C_2$$

is called the *original solution* in \mathfrak{F}_χ , where by $*du$ we denote the conjugate differential of du . It is shown that the original solution u is uniquely determined and the 2nd ordered partial derivatives of u are Hölder continuous (with exponent α ($0 < \alpha \leq 1$)) (cf. Gilbarg and Trudinger [5]).

The following lemma is easily verified by standard argument.

LEMMA 2.1 *The original solution u satisfies the minimality*

$$(2.5) \quad J[u] = \min_{v \in \mathfrak{F}_\chi} J[v].$$

In the equality (2.5), the minimum of the right hand side is attained if and only if $v = u$.

3. Subclass S of \mathfrak{F} . We define a subclass $S = S(K)$ of \mathfrak{F} , called the *comparable class* (with u), as the class of functions v_h which satisfy the following conditions (i)~(iv):

(i) $v_h \in \mathfrak{F}$.

(ii) If $s \in K_j$ ($j=1, \dots, m$) is a natural simplex, then v_h is a linear expression $ax + by + c$

(a, b, c : constants) of local variables x and y ($z = \varphi_j(p) = x + iy$) on $\varphi_j(s)$.

(iii) Let $(s, s', \mathfrak{b}\ell)$ be a triple for a minor simplex s . Then v_h is a linear expression of local variables on $\varphi_j(s)$ and $\varphi_k(s') - \varphi_k(\mathfrak{b}\ell)$ respectively, and a harmonic function in $|\mathfrak{b}\ell|$.

(iv) Let $(s, s', \#\ell)$ be a triple for a major simplex s . Then v_h is a linear expression of local variables on $\varphi_j(\mathfrak{h}s)$ and $\varphi_k(s')$ respectively, and a harmonic function in $|\#\ell|$.

4. Class S' of functions. Let K' be the naturalized triangulation associated to K . For each function $v_h \in S$, we define the *function v'_h on K' associated to v_h* as the function v'_h which satisfies the following conditions (i), (ii):

(i) For each 2-simplex $s \in K'_j$ ($j=1, \dots, m$), v'_h is a linear expression of local variables on $\varphi_j(s)$.

(ii) $v'_h = v_h$ on the carrier of K minus all lunes.

We should note that the function v'_h is defined just twice on each deficient lune $\mathfrak{b}\ell$, while it is never defined on any excessive lune $\#\ell$. In the former case, for each triple $(s, s', \mathfrak{b}\ell)$ we shall denote the function v'_h on $\mathfrak{h}s \in K'_j$ and $s' \in K'_k$ by v'_{hs} and $v'_{hs'}$ respectively.

The class of all functions v'_h associated to $v_h \in S$ is denoted by $S' = S'(K')$ and called the *computable class*. Let v'_h and w'_h be functions in S' , and \mathfrak{f} be a covariant tensor on $\overline{\Omega}$. We define an *inner product* (v'_h, w'_h) of v'_h and w'_h , a *norm* $\|v'_h\|$ of v'_h and a *functional* $J[v'_h]$ of v'_h by

$$\begin{aligned} (v'_h, w'_h) &\equiv \sum_{s \in K'} (v'_h, w'_h)_s \\ &= \sum_{s \in K'} \iint_{|s|} \left(\frac{\partial v'_h}{\partial x} \frac{\partial w'_h}{\partial x} + \frac{\partial v'_h}{\partial y} \frac{\partial w'_h}{\partial y} \right. \\ &\quad \left. + q v'_h w'_h \right) dx dy, \end{aligned}$$

$$\|v'_h\| \equiv (v'_h, v'_h)^{1/2} \quad \text{and}$$

$$\begin{aligned}
 J[v_h] &\equiv \sum_{s \in K'} (\|v_h\|_s^2 + 2(f, v_h)_{0,s}) \\
 &= \sum_{s \in K'} \iint_{|s|} \left(\left(\frac{\partial v_h}{\partial x} \right)^2 + \left(\frac{\partial v_h}{\partial y} \right)^2 \right. \\
 &\quad \left. + qv_h'^2 + 2fv_h' \right) dx dy
 \end{aligned}$$

respectively. Further, we introduce the notation

$$\begin{aligned}
 (f, v_h)_0 &\equiv \sum_{s \in K'} (f, v_h)_{0,s} \\
 &= \sum_{s \in K'} \iint_{|s|} f v_h' dx dy
 \end{aligned}$$

We see that $v_h = F(v_h)$ defines a one-to-one mapping of S onto S' .

5. Finite element interpolations. Let v be a function of \mathfrak{F} . We define the *finite element interpolation* \hat{v} of v in the class S as the function uniquely determined by the following conditions (i) and (ii):

- (i) $\hat{v} \in S$;
- (ii) $\hat{v}(p) = v(p)$ at the carrier p of each 0-simplex of K .

§ 3. Finite element approximations.

1. Finite element approximation ω_h in S .

Let $\hat{\chi}$ be the finite element interpolation of χ in the class S . By S_x we denote the subclass of S consisting of all functions v_h satisfying the boundary condition:

$$v_h = \hat{\chi} \quad \text{on } C_1.$$

By ω_h we denote the function satisfying the minimality

$$(3.1) \quad J[\omega_h] = \min_{v_h \in S_x} J[v_h].$$

We call ω_h the *finite element approximation* of the original solution u in the class S .

2. Basis of S . Let $\{q_j\}_{j=1}^n$ be the collection of all 0-simplices of the triangulation K . We define the *basis* ϕ_1, \dots, ϕ_n of the class S as the functions of S which are uniquely determined by the condition

$$(3.2) \quad \phi_j(p) = \begin{cases} 1 & (p = |q_j|), \\ 0 & (p = |q_k|; k \neq j), \end{cases} \quad (j, k = 1, \dots, n).$$

Then an arbitrary function v_h of S can be represented as a linear combination

$$v_h = \sum_{j=1}^n v_j \phi_j$$

of ϕ_j ($j=1, \dots, n$), where $v_j = v_h(|q_j|)$ ($j=1, \dots, n$).

LEMMA 3.1. *The coefficients u_j ($j=1, \dots, n$) of the function $\omega_h = \sum_{j=1}^n u_j \phi_j$ which minimizes the functional $J[v_h]$ in S_x , are the solutions of the system of linear equations:*

$$(3.3) \quad \sum_{k=1}^n K_{jk} u_k = F_j \quad (j=1, \dots, n'),$$

$$(3.4) \quad u_j = \chi(|q_j|) \quad (j = n'+1, \dots, n),$$

where

$$\begin{aligned}
 K_{jk} &= (\phi_j, \phi_k) \\
 &\quad (j=1, \dots, n'; k=1, \dots, n), \\
 F_j &= -(f, \phi_j)_0 \quad (j=1, \dots, n')
 \end{aligned}$$

and by $\{q_k\}_{k=n'+1}^n$ we denote the collection of all 0-simplices on C_1 .

See lemma 3.1 of [3] and also Chapter 3 of [6] for the proof.

3. Maximum principle for ω_h .

THEOREM 3.1. *If $h > 0$ is sufficiently small, then for the finite element approximation ω_h of the original solution u , the inequality*

$$(3.5) \quad |\omega_h| \leq \exp\left(\frac{4\pi M}{\sin \theta} \cdot \max_{\bar{\Omega}} q\right) \cdot \left(\max_{c_1} |\chi| + \frac{2}{\sin \theta} \iint_{\bar{\Omega}} |f| dx dy\right)$$

holds, where θ is the smallest value of all angles of the triangles $\varphi_j(s)$ ($\varphi_j(\mathfrak{h}s)$ in place of $\varphi_j(s)$ for a minor or major simplex s) ($s \in K_j$; $j=1, \dots, m$), M is a constant defined in (i') of § 1.2 and $\max_{\bar{\Omega}} q$ means

$$\max_{\bar{\Omega}} q \equiv \max_{1 \leq j \leq m} \max_{\varphi_j(\bar{U}_j \cap \bar{\Omega})} q.$$

PROOF. By $\text{supp } v$ we denote the support of a function v on $\bar{\Omega}$. Let q_0 be an arbitrarily fixed 0-simplex of K whose carrier belongs to $\bar{\Omega} - C_1$, let ϕ_0 be the base of S satisfying $\phi_0(|q_0|)=1$, and let ϕ_j ($j=1, \dots, \nu$) be the collection of basis of S which satisfy the condition

$$D_j \equiv \text{supp } \phi_0 \cap \text{supp } \phi_j \neq \emptyset.$$

We note that

$$(3.6) \quad \sum_{j=0}^{\nu} \phi_j = 1 \quad \text{on } \text{supp } \phi_0.$$

The equations (3.3) can be written in the form

$$(3.7) \quad \sum_{j=0}^{\nu} (P_j + Q_j)u_j = F \quad (|q_0| \in \bar{\Omega} - C_1),$$

where

$$P_j = \iint_{\Omega} \left(\frac{\partial \phi_0}{\partial x} \frac{\partial \phi_j}{\partial x} + \frac{\partial \phi_0}{\partial y} \frac{\partial \phi_j}{\partial y} \right) dx dy,$$

$$Q_j = \iint_{\Omega} q \phi_0 \phi_j dx dy \quad (j=0, \dots, \nu)$$

and

$$F = - \iint_{\Omega} f \phi_0 dx dy.$$

Let s_k ($k=1, \dots, \nu'$; $\nu' \leq \nu$) be the collection of all 2-simplices of K , having q_0 as one of their vertices. Then, D_j ($j=\nu'+1, \dots, \nu$) are carriers of some lunes. By the condition (ii') of § 1.2 and Lemma 1.1 we can verify that for sufficiently small $h > 0$ there hold the inequalities

$$(3.8) \quad -P_j \geq 0, \quad Q_j \geq 0 \quad (j=1, \dots, \nu).$$

Furthermore, by (3.6) we have that

$$(3.9) \quad P_0 + \dots + P_{\nu} = 0.$$

By (3.7)~(3.9) the inequalities

$$(P_0 + Q_0) |u_0| \leq (-(P_1 + \dots + P_{\nu}) - (Q_1 + \dots + Q_{\nu})) \cdot \max(|u_1|, \dots, |u_{\nu}|) + |F|$$

$$\leq \left(P_0 + \sum_{j=1}^{\nu} Q_j \right) \cdot \max(|u_1|, \dots, |u_{\nu}|)$$

$$+ \iint_{\Omega} |f| \phi_0 dx dy$$

hold and thus the inequality

$$(3.10) \quad |u_0| \leq \left(1 + \frac{1}{P_0} \sum_{j=1}^{\nu} Q_j \right) \cdot$$

$$\cdot \max(|u_1|, \dots, |u_{\nu}|) + \frac{1}{P_0} \iint_{\Omega} |f| \phi_0 dx dy$$

holds for sufficiently small $h > 0$.

Let s be a 2-simplex of K , having q_0 as one of its vertices and let θ_1 be the angle of the triangle $\varphi_j(s)$ ($\varphi_j(\mathbf{s})$ in place of $\varphi_j(s)$ for a minor or major simplex s) at the vertex $\varphi_j(|q_0|)$. Then we can easily verify that if s is a natural simplex, a major one or its adjoint, then from the property of ϕ_0 it follows that

$$(3.11) \quad \iint_{|s|} \left(\left(\frac{\partial \phi_0}{\partial x} \right)^2 + \left(\frac{\partial \phi_0}{\partial y} \right)^2 \right) dx dy > \frac{1}{2} \sin \theta_1,$$

and if s is a minor simplex or its adjoint, then by Lemma 1.1 in addition to it, it follows that

$$(3.12) \quad \iint_{|s|} \left(\left(\frac{\partial \phi_0}{\partial x} \right)^2 + \left(\frac{\partial \phi_0}{\partial y} \right)^2 \right) dx dy$$

$$> \frac{1}{2} (1 - \chi h) \sin \theta_1,$$

where χ is a constant depending only on $z = \psi(\zeta) \equiv \varphi_j \circ \varphi_k^{-1}(\zeta)$. Since $\nu' \geq 2$, by (3.11) and (3.12) the inequalities

$$(3.13) \quad P_0 \geq \iint_{|s_1| + \dots + |s_{\nu'}|} \left(\left(\frac{\partial \phi_0}{\partial x} \right)^2 + \left(\frac{\partial \phi_0}{\partial y} \right)^2 \right) dx dy$$

$$> \frac{\sin \theta}{2}$$

hold for sufficiently small $h > 0$. Furthermore we can immediately see that

$$(3.14) \quad \sum_{j=1}^{\nu} Q_j \leq 2\pi h^2 \cdot \max_{\bar{\Omega}} q.$$

(3.10), (3.13) and (3.14) imply that

$$|u_0| \leq \left(1 + \frac{4\pi h^2}{\sin \theta} \cdot \max_{\bar{\Omega}} q \right) \cdot \max(|u_1|, \dots, |u_{\nu}|)$$

$$+ \frac{2}{\sin \theta} \iint_{\Omega} |f| \phi_0 dx dy.$$

By (i') of § 1.2 and making use of the formula $(1 + r/N)^N \leq e^r$ ($r > 0$), the repeating of a finite number of the above argument implies the inequality (3.5).

4. Finite element approximation u'_h in S' .

Let $S'_x = \{v'_h \mid v'_h = F(v_h), v_h \in S_x\}$. By u'_h we

denote the function of S'_x such that

$$(3.15) \quad J[u'_h] = \min_{v'_h \in S'_x} J[v'_h].$$

We call u'_h the *finite element approximation of u in the class S'* .

5. Basis of S' . Let $\{q_j\}_{j=1}^n$ be the collection of all 0-simplices of the triangulation K' . We define the *basis ϕ'_1, \dots, ϕ'_n of the class S'* as the functions of S' which are uniquely determined by the condition

$$(3.16) \quad \phi'_j(p) = \begin{cases} 1 & (p=|q_j|), \\ 0 & (p=|q_k|; k \neq j). \end{cases} \quad (j, k=1, \dots, n)$$

Then an arbitrary function v'_h of S' can be represented as a linear combination

$$v'_h = \sum_{j=1}^n v'_j \phi'_j$$

of ϕ'_j ($j=1, \dots, n$), where $v'_j = v'_h(|q_j|)$ ($j=1, \dots, n$).

LEMMA 3.2. *The coefficients u'_j ($j=1, \dots, n$) of the function $u'_h = \sum_{j=1}^n u'_j \phi'_j$ which minimizes the functional $J[v'_h]$ in S'_x , are the solutions of the system of linear equations:*

$$(3.17) \quad \sum_{k=1}^n K'_{jk} u'_k = F'_j \quad (j=1, \dots, n'),$$

$$(3.18) \quad u'_j = \chi(|q_j|) \quad (j=n'+1, \dots, n),$$

where

$$\begin{aligned} K'_{jk} &= (\phi'_j, \phi'_k) \\ & \quad (j=1, \dots, n'; k=1, \dots, n), \\ F'_j &= -(f, \phi'_j)_0 \quad (j=1, \dots, n') \end{aligned}$$

and by $\{q_k\}_{k=n'+1}^n$ we denote the collection of all 0-simplices on C_1 .

The proof is similar to that of Lemma 3.1.

THEOREM 3.2. *If $h > 0$ is sufficiently small, then for the finite element approximation u'_h of the original solution u , the inequality*

$$(3.19) \quad |u_h| \leq \exp\left(\frac{2\pi M}{\sin \theta} \cdot \max_{\bar{\Omega}} q\right).$$

$$\cdot \left(\max_{C_1} |x| + \frac{1}{\sin \theta} \sum_{s \in K'} \iint_{|s|} |f| dx dy \right)$$

holds, where $u_h = F^{-1}(u'_h)$ and other notations are the same as in Theorem 3.1.

PROOF. Let q_0 be an arbitrarily fixed 0-simplex of K' whose carrier belongs to Ω . Let s_j ($j=1, \dots, \nu$) be the collection of 2-simplices of K' satisfying the conditions $|q_0| \in |s_j|$ ($j=1, \dots, \nu$) and $|s_j| \cap |s_{j+1}| \neq \emptyset$ ($j=1, \dots, \nu; s_{\nu+1} = s_1$), and let q_j ($j=1, \dots, \nu$) be the collection of 0-simplices such that q_0, q_j, q_{j+1} ($j=1, \dots, \nu; q_{\nu+1} = q_1$) are the vertices of s_j . Let ϕ'_j ($j=0, \dots, \nu$) be the basis of S' satisfying $\phi'_j(|q_j|) = 1$.

We note that

$$(3.20) \quad \phi'_0 + \phi'_j + \phi'_{j+1} \equiv 1 \quad \text{on } |s_j| \quad (j=1, \dots, \nu; \phi'_{\nu+1} \equiv \phi'_1).$$

The equations (3.17) can be written in the form

$$(3.21) \quad \sum_{j=0}^{\nu} (P'_j + Q'_j) u'_j = F' \quad (|q_0| \in \Omega),$$

where

$$P'_0 = \sum_{j=1}^{\nu} \iint_{|s_j|} \left(\left(\frac{\partial \phi'_0}{\partial x} \right)^2 + \left(\frac{\partial \phi'_0}{\partial y} \right)^2 \right) dx dy,$$

$$Q'_0 = \sum_{j=1}^{\nu} \iint_{|s_j|} q \phi_0'^2 dx dy,$$

$$P'_j = \iint_{|s_{j-1}| + |s_j|} \left(\frac{\partial \phi'_0}{\partial x} \frac{\partial \phi'_j}{\partial x} + \frac{\partial \phi'_0}{\partial y} \frac{\partial \phi'_j}{\partial y} \right) dx dy$$

and

$$Q'_j = \iint_{|s_{j-1}| + |s_j|} q \phi_0' \phi'_j dx dy \quad (j=1, \dots, \nu; s_0 \equiv s_{\nu}).$$

By the condition (ii') of § 1.2 we can verify that there hold the inequalities

$$(3.22) \quad -P'_j \geq 0, \quad Q'_j \geq 0 \quad (j=1, \dots, \nu).$$

Furthermore, by (3.20) it follows that

$$(3.23) \quad P'_0 + \dots + P'_\nu = 0.$$

By (3.21)~(3.23) the inequalities

$$\begin{aligned} (P'_0 + Q'_0) |u'_0| & \leq (- (P'_1 + \dots + P'_\nu) - (Q'_1 + \dots + Q'_\nu)) \cdot \\ & \quad \cdot \max(|u'_1|, \dots, |u'_\nu|) + |F'| \\ & \leq \left(P'_0 + \sum_{j=1}^{\nu} Q'_j \right) \cdot \max(|u'_1|, \dots, |u'_\nu|) \end{aligned}$$

$$+ \sum_{s \in K'} \iint_{|s|} |f| \phi'_0 \, dx dy$$

hold and thus the inequality

$$(3.24) \quad |u'_0| \leq \left(1 + \frac{1}{P'_0} \sum_{j=1}^{\nu} Q'_j\right) \cdot$$

$$\cdot \max(|u'_1|, \dots, |u'_\nu|) + \frac{1}{P'_0} \sum_{s \in K'} \iint_{|s|} |f| \phi'_0 \, dx dy$$

holds.

Let s be a 2-simplex of K' , having q_0 as one of its vertices and let θ_1 be the angle of the triangle $\varphi_j(s)$ at the vertex $\varphi_j(q_0)$. Then we can easily verify that from the property of ϕ'_0 it follows that

$$(3.25) \quad \iint_{|s|} \left(\left(\frac{\partial \phi'_0}{\partial x} \right)^2 + \left(\frac{\partial \phi'_0}{\partial y} \right)^2 \right) dx dy > \frac{1}{2} \sin \theta_1.$$

Since $\nu \geq 4$, by (3.25) the inequalities

$$P'_0 = \iint_{|s_{11}| + \dots + |s_{\nu 1}|} \left(\left(\frac{\partial \phi'_0}{\partial x} \right)^2 + \left(\frac{\partial \phi'_0}{\partial y} \right)^2 \right) dx dy$$

$$> \sin \theta$$

hold. Hence we have that

$$(3.26) \quad |u'_0| \leq \left(1 + \frac{1}{\sin \theta} \sum_{j=1}^{\nu} Q'_j\right) \cdot$$

$$\cdot \max(|u'_1|, \dots, |u'_\nu|) + \frac{1}{\sin \theta} \sum_{s \in K'} \iint_{|s|} |f| \phi'_0 \, dx dy.$$

In the case where q_0 is a 0-simplex of K' whose carrier belongs to C_2 , by the similar argument except some minor change we also obtain the inequality (3.26).

The remained parts of the proof are similar to ones of Theorem 3.1.

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リーマン面上の有限要素解 に対する最大値の原理, II

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要 約

前の論文 [3] では, 縁をもつコンパクトなリーマン面 $\bar{\Omega}$ 上で定義された偏微分方程式: $\Delta u - qu = f$ の有限要素解に対する最大最小値の原理を確立したが, 本論文では, 論文 [3] の結果を改良し, 拡張する. まず, $\bar{\Omega}$ の幅 h の三角形分割 K を作成し, K 上の要素関数のクラス $S = S(K)$ を導入する. 境界 $\partial\Omega$ の二つの部分 C_1, C_2 への分割に対して, 境界値問題: Ω 上で $\Delta u - qu = f$, C_1 上で $u = \chi$, C_2 に沿って $*du = 0$ の有限要素近似 $\omega_h \in S$ を定義する, ここで, $*du$ は, du の共役微分を表す. K の 2-単体のすべての内角は $\leq \pi/2$ であると仮定する. 論文 [3] の仮定より弱い, この仮定のもとで, 十分小さい $h > 0$ に対して, 不等式

$$|\omega_h| \leq \exp\left(\frac{4\pi M}{\sin \theta} \cdot \max_{\bar{\Omega}} q\right) \left(\max_{C_1} |\chi| + \frac{2}{\sin \theta} \iint_{\Omega} |f| \, dx dy\right)$$

が成り立つことが示される, ここで, θ は K のすべての 2-単体の内角の最小値, M は定数である. この不等式は, 有限要素解の理論解に対する誤差評価をするときに, 非常に有用となるものである.