

# Existence of a positive solution for a singular system

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ABSTRACT. We show the existence and nonexistence of positive solutions to a system of singular elliptic equations with Dirichlet boundary condition. This system arises in studies of pattern formation in biology and in the activator-inhibitor model proposed by Gierer-Meinhardt.

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## 1 Introduction

In this paper we study the system

$$\begin{cases} -\Delta u = \lambda u^{q_1} - \frac{u^{p_1}}{v^{\beta_1}} & \text{in } \Omega, \\ -\Delta v = \mu v^{q_2} - \frac{v^{p_2}}{u^{\beta_2}} & \text{in } \Omega, \\ u = v = 0 & \text{on } \partial\Omega, \end{cases} \quad (1.1)$$

where  $\Omega \subset \mathbb{R}^N$ ,  $N \geq 1$ , is a bounded domain with smooth boundary  $\partial\Omega$ ,

$$\lambda, \mu \in \mathbb{R}, \quad 0 < q_1, q_2, \beta_1, \beta_2 < 1 \quad \text{and} \quad p_1, p_2 > 0. \quad (1.2)$$

Our main goal in this paper is to show results about existence and nonexistence of positive solutions of (1.1) in terms of the parameters  $\lambda$  and  $\mu$ . It is clear that, thanks to the maximum principle, if  $\lambda \leq 0$  or  $\mu \leq 0$  then (1.1) does not possess positive solutions. With respect to the existence, our main result is

**Theorem 1.1.** (A) Assume that  $q_1 < p_1$ . There is a constant  $\lambda^*(\Omega) > 0$  depending on  $\Omega$  such that for

$$\mu \geq \lambda^*(\Omega)\lambda^\sigma \quad \text{and} \quad \lambda > 0$$

where

$$\sigma = \frac{p_2(1 - q_2)}{(1 + \beta_2)(1 - q_1)},$$

there exists a positive  $C^{1,\Upsilon}(\bar{\Omega})$ ,  $0 < \Upsilon < 1$  solution of (1.1).

(B) Assume that  $q_1 \geq p_1$ . There is a constant  $\lambda_*(\Omega) > 0$  depending on  $\Omega$  such that for

$$\lambda < \lambda_*(\Omega)\mu^{-r} \quad \text{and} \quad \mu > 0,$$

where

$$r = \frac{\beta_1(1 - q_1)}{(1 - p_1)(1 - q_2)},$$

then (1.1) does not possess a positive solution.

Systems of singular equations like (1.1) are the stationary counterpart of general evolutionary problems of the form

$$\begin{cases} u_t = \eta\Delta u + \lambda u^{q_1} - \gamma \frac{u^{p_1}}{v^{\beta_1}} & \text{in } \Omega, \\ v_t = \delta\Delta v + \mu v^{q_2} - \theta \frac{u^{p_2}}{v^{\beta_2}} & \text{in } \Omega, \\ u = v = 0 & \text{on } \partial\Omega. \end{cases} \quad (1.3)$$

In the original model proposed by Gierer-Meinhardt [10],

$$\eta, \delta > 0, \quad \lambda, \mu, \gamma, \theta < 0, \quad q_1 = q_2 = 1, \quad p_1, p_2, \beta_1, \beta_2 > 0, \quad 0 < (p_1 - 1)/\beta_1 < p_2/(\beta_2 + 1)$$

and the boundary conditions are of Neumann type. This system was motivated by biological experiments on hydra in morphogenesis, where  $u$  represents the density of an activator chemical substance and  $v$  is an inhibitor. The slow diffusion of  $u$  and the fast diffusion of  $v$  is translated into the fact that  $\eta$  is small and  $\delta$  is large, see also [11, 16, 18] for an account on biological applications of such systems. There are a few papers dealing with scalar equations [1, 4, 5, 8, 19] and references therein.

According to an observation made in [3], it is natural to study (1.3) with Dirichlet boundary conditions, since numerical experiments from [10] exhibit solutions approaching zero near the boundary of  $\Omega$ . Moreover, Neumann condition is not explicitly mentioned in the original paper [10]. Although, the majority of early papers deal with a system on a bounded domain with Neumann boundary conditions.

The stationary system with

$$\eta = \delta = 1, \quad \lambda = \mu = \gamma = \theta = -1 \quad \text{and} \quad p_1 = p_2 = q_1 = q_2 = \beta_1 = \beta_2 = 1.$$

was studied in [2]. Thus for the system

$$\begin{cases} -\Delta u = -u + \frac{u^{p_1}}{v^{\beta_1}} & \text{in } \Omega, \\ -\Delta v = -v + \frac{u^{p_2}}{v^{\beta_2}} & \text{in } \Omega, \\ u = v = 0 & \text{on } \partial\Omega, \end{cases} \quad (1.4)$$

they have shown existence and nonexistence of solutions and uniqueness of solution in one dimension. Another uniqueness result for (1.4) was proved in [3], in the situation

$$\eta = \delta = 1, \quad \lambda = \mu = \gamma = \theta = -1 \quad \text{and} \quad p_1 = p_2 > 1, \quad \beta_2 = 0, \quad \beta_1 = q_1 = q_2 = 1.$$

A study allowing more general singular nonlinearities was performed in [9, 13, 14].

We are interested in studying stationary states of (1.3) for a different range of parameters and constants (1.2). Notice that our results depend strongly on the size of  $q_1$  and  $p_1$ . Indeed, in the existence part (A) of Theorem 1.1 we require  $q_1 < p_1$ , and the conclusion holds for  $\lambda > 0$  and  $\mu \geq C\lambda^\sigma$  for some positive constants  $C$  and  $\sigma$ . Part (B) demands  $q_1 \geq p_1$ , thus the nonexistence of solution is inferred for  $\lambda > 0$  and  $\mu < C\lambda^{-r}$  for some positive constants  $C$  and  $r$ . In order to obtain our main results we use an adequate sub-supersolution method, which will be detailed later.

The paper is organized as follows. In section 2 we show that the sub-supersolution method holds for our system, which has singular nonlinearities, generalizing classical results, see for instance [17]. In section 3 we study some auxiliary problems related to sublinear equations, singular equations and porous medium logistic equation. Section 4 is devoted to the proof of Theorem 1.1.

## 2 The sub-super method for singular systems

First of all we show that the sub-supersolution method works well for singular systems. We consider the general system

$$\begin{cases} -\Delta u = f(x, u, v) & \text{in } \Omega, \\ -\Delta v = g(x, u, v) & \text{in } \Omega, \\ u = v = 0 & \text{on } \partial\Omega, \end{cases} \quad (2.1)$$

where  $f, g : \Omega \times \mathbb{R} \times \mathbb{R} \mapsto \mathbb{R}$  are Caratheodory functions. On the other hand, we denote by

$$\rho_0(x) = \text{dist}(x, \partial\Omega),$$

and given  $w \leq z$  a.e. in  $\Omega$

$$[w, z] := \{u : w(x) \leq u(x) \leq z(x) \quad \text{a.e. } x \in \Omega\}.$$

The notions of solutions and sub-supersolutions of (2.1) are:

**Definition 2.1.** *We say that  $(u, v) \in (L^1(\Omega))^2$  is a solution of (2.1) if*

1.  $f(\cdot, u, v)\rho_0, g(\cdot, u, v)\rho_0 \in L^1(\Omega)$ ;

2.

$$-\int_{\Omega} u \Delta \xi = \int_{\Omega} f(x, u, v) \xi, \quad -\int_{\Omega} v \Delta \xi = \int_{\Omega} g(x, u, v) \xi, \quad \forall \xi \in C_0^2(\bar{\Omega}).$$

**Definition 2.2.** We say that  $(\underline{u}, \underline{v}), (\bar{u}, \bar{v}) \in (L^1(\Omega))^2$  is a pair of sub-supersolutions of (2.1) if

1.  $\underline{u} \leq \bar{u}$  and  $\underline{v} \leq \bar{v}$  in  $\Omega$ ;

2.

$$\begin{aligned} f(\cdot, u, v) \rho_0, f(\cdot, u, v) \rho_0 &\in L^1(\Omega) \quad \text{for all } u \in [\underline{u}, \bar{u}] \text{ and } v \in [\underline{v}, \bar{v}], \\ g(\cdot, u, v) \rho_0, g(\cdot, u, v) \rho_0 &\in L^1(\Omega) \quad \text{for all } u \in [\underline{u}, \bar{u}] \text{ and } v \in [\underline{v}, \bar{v}]; \end{aligned} \quad (2.2)$$

3. for all  $\xi \in C_0^2(\bar{\Omega}), \xi \geq 0$ ,

$$-\int_{\Omega} \underline{u} \Delta \xi - \int_{\Omega} f(x, \underline{u}, v) \xi \leq 0 \leq -\int_{\Omega} \bar{u} \Delta \xi - \int_{\Omega} f(x, \bar{u}, v) \xi, \quad \forall v \in [\underline{v}, \bar{v}];$$

and

$$-\int_{\Omega} \underline{v} \Delta \xi - \int_{\Omega} g(x, u, \underline{v}) \xi \leq 0 \leq -\int_{\Omega} \bar{v} \Delta \xi - \int_{\Omega} g(x, u, \bar{v}) \xi, \quad \forall u \in [\underline{u}, \bar{u}].$$

Next we prove that the existence of a pair of sub-supersolutions implies the existence of a solution of the system.

**Theorem 2.3.** Assume that there exists a pair of sub-supersolution  $(\underline{u}, \underline{v}), (\bar{u}, \bar{v})$  of (2.1). Then, there exists a solution  $(u, v)$  of (2.1) such that  $\underline{u} \leq u \leq \bar{u}$  and  $\underline{v} \leq v \leq \bar{v}$  in  $\Omega$ .

*Proof.* First, we define the truncations

$$Tu(x) := \begin{cases} \bar{u}(x) & \text{if } u(x) \geq \bar{u}(x), \\ u(x) & \text{if } \underline{u}(x) \leq u(x) \leq \bar{u}(x), \\ \underline{u}(x) & \text{if } u(x) \leq \underline{u}(x), \end{cases} \quad (2.3)$$

and

$$Sv(x) := \begin{cases} \bar{v}(x) & \text{if } v(x) \geq \bar{v}(x), \\ v(x) & \text{if } \underline{v}(x) \leq v(x) \leq \bar{v}(x), \\ \underline{v}(x) & \text{if } v(x) \leq \underline{v}(x). \end{cases} \quad (2.4)$$

We denote by

$$L^1(\rho_0, \Omega) := \{u : u \rho_0 \in L^1(\Omega)\}.$$

We define the Nemytskii operators (well defined by (2.2))

$$\begin{aligned} F : L^1(\Omega) \times L^1(\Omega) &\mapsto L^1(\rho_0, \Omega) \\ (u, v) &\mapsto F(u, v) := f(x, Tu, Sv) \end{aligned}$$

and similarly

$$\begin{aligned} G : L^1(\Omega) \times L^1(\Omega) &\mapsto L^1(\rho_0, \Omega) \\ (u, v) &\mapsto G(u, v) := g(x, Tu, Sv). \end{aligned}$$

We define the operator  $K : L^1(\rho_0, \Omega) \mapsto L^1(\Omega)$  by  $h \mapsto w := K(h)$ , being  $w$  the unique solution of

$$\begin{cases} -\Delta w = h & \text{in } \Omega, \\ w = 0 & \text{on } \partial\Omega. \end{cases}$$

It can be proved:

1.  $F$  and  $G$  are continuous (Theorem 2.1 in [15], the notion of equi-integrability is not needed here).
2.  $[F, G](L^1(\Omega))^2$  is bounded in  $L^1(\rho_0, \Omega)$ , since  $T$  and  $S$  defined by (2.3) and (2.4) are bounded.
3.  $K \circ F$  and  $K \circ G$  are continuous and compact operators from  $(L^1(\Omega))^2$  to  $L^1(\Omega)$  (Theorem 3.1 in [15]).

Then, by the Schauder's fixed point theorem, we can conclude the existence of a solution  $(u, v) \in (L^1(\Omega))^2$  of

$$\begin{cases} -\Delta u = f(x, Tu, Sv) & \text{in } \Omega, \\ -\Delta v = g(x, Tu, Sv) & \text{in } \Omega, \\ u = v = 0 & \text{on } \partial\Omega. \end{cases}$$

We claim that  $(u, v) \in [\underline{u}, \bar{u}] \times [\underline{v}, \bar{v}]$  and so  $(u, v)$  is solution of (2.1). Indeed, let

$$w := u - \bar{u}.$$

Then, for all  $V \in [\underline{v}, \bar{v}]$  and all  $\xi \in C_0^2(\bar{\Omega}), \xi \geq 0$ , we get

$$-\int_{\Omega} w \Delta \xi \leq \int_{\Omega} (f(x, Tu, Sv) - f(x, \bar{u}, V)) \xi$$

and then taking  $V = Sv$

$$-\int_{\Omega} w \Delta \xi \leq \int_{\Omega} (f(x, Tu, Sv) - f(x, \bar{u}, Sv)) \xi.$$

Then, applying the Kato's inequality (see Proposition 3.1 in [15]) we obtain

$$-\int_{\Omega} w^+ \Delta \xi \leq \int_{[u \geq \bar{u}]} (f(x, Tu, Sv) - f(x, \bar{u}, Sv)) \xi = 0 \quad \forall \xi \in C_0^2(\bar{\Omega}), \xi \geq 0.$$

We deduce that  $w^+ = 0$  a.e.; and conclude the proof.  $\square$

**Remark 2.4.** Assuming more regularity to  $f, g$  and the pair of sub-supersolution, we can obtain that the solution lies in a better space, see Section 5 in [15]. See also Remark 3.6.

### 3 Some auxiliary problems

In order to find a pair of sub-supersolutions of (1.1) we need to study some scalar equations. First of all, given  $\lambda \in \mathbb{R}$  and  $0 < q < 1$ , consider

$$\begin{cases} -\Delta u = \lambda u^q & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases} \quad (3.1)$$

It is well-known that there exists a unique positive solution of (3.1) if, and only if,  $\lambda > 0$ . We denote this solution by  $\omega_{[\lambda,q]}$ ; moreover

$$\omega_{[\lambda,q]} = \lambda^{1/(1-q)} \omega_{[1,q]}.$$

It is known that there exist constants  $k$  and  $K$  with  $0 < k < K < +\infty$  such that

$$k\rho_0(x) \leq \omega_{[\lambda,q]}(x) \leq K\rho_0(x) \quad x \in \Omega. \quad (3.2)$$

We need to study the following problem

$$\begin{cases} -\Delta u = \lambda f(x, u) - \frac{a(x)}{u^\beta} & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (3.3)$$

where  $\beta \in (0, 1)$  and

$$a : \Omega \rightarrow \mathbb{R} \quad \text{is a continuous positive function,} \quad (3.4)$$

$$\text{there is } 1 < \gamma < 2 \quad \text{such that} \quad \limsup_{x \rightarrow \partial\Omega} \frac{a(x)}{\rho_0(x)^{\gamma(1+\beta)-2}} < +\infty, \quad (3.5)$$

$$f : \Omega \times \mathbb{R} \rightarrow \mathbb{R} \quad \text{is a continuous function,} \quad (3.6)$$

$$f(x, s) > 0 \quad \text{for } s \neq 0, \quad (3.7)$$

$$\lim_{s \rightarrow +\infty} \frac{f(x, s)}{s} = 0 \quad \text{uniformly in } x. \quad (3.8)$$

In the following result we characterize the existence of positive solution of (3.3).

**Proposition 3.1.** *There exists  $\lambda^* \in (0, +\infty)$  such that for all  $\lambda \geq \lambda^*$ , problem (3.3) has a positive a.e. weak solution and no positive solution for  $\lambda < \lambda^*$ .*

*Proof.* We are going to apply the sub-supersolution method from [15]. Take

$$\underline{u} := c\varphi_1^\gamma, \quad \bar{u} := Ke,$$

for  $c, K > 0$  such that  $\underline{u} \leq \bar{u}$  in  $\Omega$ , where  $e$  is the unique positive solution of

$$\begin{cases} -\Delta e = 1 & \text{in } \Omega, \\ e = 0 & \text{on } \partial\Omega, \end{cases}$$

and  $\varphi_1 > 0$  is the first eigenfunction of the Laplacian in  $H_0^1(\Omega)$  such that  $\|\varphi_1\|_\infty = 1$ . Recall that there exist positive constants  $0 < c < C < \infty$  such that

$$0 < c\rho_0(x) \leq e(x), \varphi_1(x) \leq C\rho_0(x), \quad \forall x \in \Omega.$$

First, observe that

$$\left| \lambda f(x, u) - \frac{a(x)}{u^\beta} \right| \rho_0 \in L^1(\Omega), \quad \forall u \in [\underline{u}, \bar{u}].$$

Indeed, for  $u \in [\underline{u}, \bar{u}]$  we have

$$|a(x)u^{-\beta}| \rho_0 \leq Ca(x)\rho_0^{-\gamma\beta+1} \leq C\rho_0^{\gamma-1} \in L^1(\Omega)$$

if  $\gamma - 1 > -1$ .

To show that  $\underline{u}$  is subsolution, we need to verify

$$-\Delta \underline{u} + \frac{a(x)}{\underline{u}^\beta} = -c\gamma(\gamma-1)\varphi_1^{\gamma-2}|\nabla\varphi_1|^2 + c\gamma\lambda_1\varphi_1^\gamma + a(x)c^{-\beta}\varphi_1^{-\beta\gamma} \leq \lambda f(x, c\varphi_1^\gamma) \quad \text{in } \Omega.$$

We distinguish two cases:

(i) Near the boundary  $\partial\Omega$ :

For every  $M > 0$  there is a  $\delta > 0$  such that for every

$$x \in \Omega_\delta := \{x \in \Omega : \rho_0(x) < \delta\}$$

one has by (3.5)

$$\begin{aligned} -c\gamma(\gamma-1)\varphi_1^{\gamma-2}|\nabla\varphi_1|^2 + a(x)c^{-\beta}\varphi_1^{-\beta\gamma} &= c^{-\beta}\varphi_1^{\gamma-2}[-c^{1+\beta}\gamma(\gamma-1)|\nabla\varphi_1|^2 + \frac{a(x)}{\varphi_1^{\gamma-2+\beta\gamma}}] \\ &\leq c^{-\beta}\varphi_1^{\gamma-2}[-c^{1+\beta}\gamma(\gamma-1)|\nabla\varphi_1|^2 + M] \leq \frac{-c}{2}\gamma(\gamma-1)\varphi_1^{\gamma-2}|\nabla\varphi_1|^2 \end{aligned}$$

for a sufficiently large  $c > 0$ .

In this way, taking  $\delta$  smaller if necessary, we get

$$-\Delta \underline{u} + \frac{a(x)}{\underline{u}^\beta} \leq c\gamma\varphi_1^{\gamma-2}\left[-\frac{(\gamma-1)}{2}|\nabla\varphi_1|^2 + \lambda_1\varphi_1^2\right] \leq 0.$$

Notice that if  $M = 0$ , we can take  $c > 0$  arbitrary.

(ii) Inner points  $x \in \Omega \setminus \bar{\Omega}_\delta$ .

Once  $c$  has been fixed above, take  $\lambda$  large enough in such a way that

$$c^{1+\beta}\gamma\lambda_1\varphi_1^\gamma + a(x)\varphi_1^{-\beta\gamma} \leq \lambda c^\beta f(x, c\varphi_1^\gamma).$$

On the other hand, with respect to the supersolution we need that

$$-\Delta \bar{u} \geq \lambda f(x, \bar{u}) - \frac{a(x)}{\bar{u}^\beta},$$

for which it suffices that

$$K \geq \lambda f(x, Ke).$$

This is promptly verified for  $K$  large enough thanks to (3.8).

We claim that there is no positive solution of (3.3) if  $\lambda > 0$  is small. Indeed, if  $u > 0$  is an existing solution, multiply the equation by  $\varphi_1$  and integrate. Hence,

$$\int_{\Omega} \left( \lambda_1 \varphi_1 u + \frac{a(x)}{u^\beta} \varphi_1 \right) = \lambda \int_{\Omega} f(x, u) \varphi_1 \quad (3.9)$$

Let  $\delta > 0$  and  $\Omega^\delta := \{x \in \Omega : \rho_0(x) > \delta\}$ . Thus

$$c \int_{\Omega^\delta} \left( u + \frac{1}{u^\beta} \right) \varphi_1 \leq \int_{\Omega^\delta} \left( \lambda_1 u + \frac{a(x)}{u^\beta} \right) \varphi_1 < \lambda \int_{\Omega} f(x, u) \varphi_1 \quad (3.10)$$

where  $c$  is a constant depending on  $\delta$ ,  $\Omega$  and  $\|a\|_{L^\infty(\Omega^\delta)}$ . Since

$$\lambda \int_{\Omega} f(x, u) \varphi_1 \rightarrow 0 \quad \text{as } \lambda \rightarrow 0$$

we get a contradiction since  $u + 1/u^\beta$  is bounded from below and  $\int_{\Omega} f(x, u) \varphi_1$  is bounded. This last assertion follows from the fact that  $u$  is a priori bounded independently from  $\lambda$  by a bootstrap argument, since there is a constant  $C > 0$  such that  $-\Delta u \leq C\lambda(1+u)$  for every  $u$ .

Setting

$$\lambda^* = \inf \{ \lambda > 0 \mid \text{such that (3.3) has a positive a.e. solution} \}.$$

Then  $\lambda^* < +\infty$  and for all  $\lambda \geq \lambda^*$ , problem (3.3) has a positive a.e. weak solution.  $\square$

**Remark 3.2.** *If  $\gamma - 2 + \beta\gamma > 0$ , then in view of (3.5),  $a(x) \rightarrow 0$  as  $x \rightarrow \partial\Omega$ . This is true if  $\beta \geq 1$  for example.*

*If  $\gamma - 2 + \beta\gamma < 0$ , then eventually  $0 < \beta < 1$  and  $a(x) \rightarrow 0$  as  $x \rightarrow \partial\Omega$  or  $a(x) \rightarrow +\infty$  as  $x \rightarrow \partial\Omega$ . But with (3.5) satisfied.*

We now consider a particular case of (3.3),

$$\begin{cases} -\Delta u = \lambda u^q - a(x) \frac{1}{u^\beta} & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (3.11)$$

where  $0 < q, \beta < 1$  and  $a$  verifies (3.4) and (3.5).

**Proposition 3.3.** *There exists  $\lambda^*(a) > 0$  such that a positive maximal solution of (3.11) exists if, and only if,*

$$\lambda \geq \lambda^*(a).$$

*We denote this maximal solution by  $\Theta_{[\lambda, q, \beta, a]}$ . Moreover, the map  $a \mapsto \lambda^*(a)$  is increasing. Furthermore, if  $a \in C(\overline{\Omega})$ , there exist constants  $c$  and  $C$  such that*

$$c\rho_0(x) \leq \Theta_{[\lambda, q, \beta, a]}(x) \leq C\rho_0(x). \quad (3.12)$$

*Proof.* The existence of a positive solution as well as  $\lambda^*(a)$  follow by Proposition 3.1. The maximality of the solution is due to the fact that any positive solution of (3.3) is a subsolution of (3.1).

The fact that  $a \mapsto \lambda^*(a)$  is increasing is immediate.

The existence of the constant  $c$  verifying (3.12) is due to the Hopf maximum principle and  $C$  is due to the  $C^1(\overline{\Omega})$  regularity of the solution, see also Remark 3.6.  $\square$



We need some properties of the porous medium logistic equation with a possibly singular weight

$$\begin{cases} -\Delta u = \lambda u^q - N(x)u^p & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (3.13)$$

where  $0 < q < 1$ ,  $p > 0$  with

$$0 < N \leq k\rho_0(x)^\beta, \quad k > 0, \quad (3.14)$$

$N \in C(\Omega)$  and  $\beta \in \mathbb{R}$  (possibly negative).

**Proposition 3.4.** *Assume that  $\beta + p > -1$ .*

1. *If  $q < p$ , then there exists a unique  $C^1(\overline{\Omega})$  positive solution if, and only if,  $\lambda > 0$ .*
2. *If  $q \geq p$ , then there exists  $\lambda_*(N) \geq 0$  such that there exists a positive  $C^1(\overline{\Omega})$  solution if, and only if,  $\lambda \geq \lambda_*(N)$ .*

*Moreover, if  $N \geq N_0 > 0$  for some  $N_0 \in \mathbb{R}$  then  $\lambda_*(N) > 0$ .*

*Proof.* Take  $\bar{u} := Ke$  and  $\underline{u} := \varepsilon\varphi_1^r$ ,  $r \geq 1$  and  $K, \varepsilon > 0$  positive constants to be chosen later. In order to apply the sub-supersolution method we need that

$$|N(x)u^p|_{\rho_0} \in L^1(\Omega), \quad \forall u \in [\underline{u}, \bar{u}].$$

Observe that (3.14) implies

$$|N(x)u^p|_{\rho_0} \leq K\rho_0^{\beta+p+1}$$

and so  $|N(x)u^p|_{\rho_0} \in L^1(\Omega)$  if

$$\beta + p > -2.$$

First observe that  $\underline{u}$  is subsolution of (3.13) provided that

$$r(1-r)\varepsilon^{1-q}\varphi_1^{r(1-q)-2}|\nabla\varphi_1|^2 + r\varepsilon^{1-q}\lambda_1\varphi_1^{r(1-q)} + C\varepsilon^{p-q}\varphi_1^{r(p-q)+\beta} \leq \lambda. \quad (3.15)$$

On the other hand,  $\bar{u}$  is supersolution if  $K$  is taken large. Take also  $K$  large such that  $\underline{u} \leq \bar{u}$  in  $\Omega$ . So, it suffices to verify (3.15). For that, we consider two cases:

1. Assume that  $p > q$ . Take  $r > 1$  such that  $r(p-q) + \beta > 0$ . Then, recalling that  $\|\varphi_1\|_\infty = 1$ , (3.15) is satisfied if

$$r\varepsilon^{1-q}\lambda_1 + C\varepsilon^{p-q} \leq \lambda$$

for which it suffices to take  $\varepsilon$  sufficiently small.

With respect to the uniqueness, the result follows applying Theorem 2.1 in [6], specifically taking  $g(t) = t^q$ .

2. Assume now that  $p \leq q$ . Take now  $\varepsilon = 1$ . Again we distinguish two cases:

(i) Near the boundary  $\partial\Omega$ :

Take in this case  $r \geq 1$  and  $r(1-q) - 2 < r(p-q) + \beta$ , or equivalently,  $r(1-p) < \beta + 2$ . Then we need that  $1 < (2 + \beta)/(1 - p)$  or equivalently  $-1 < \beta + p$ . In this case, (3.15) is equivalent to

$$\varphi_1^{r(1-q)-2} \left[ r(1-r)|\nabla\varphi_1|^2 + r\lambda_1\varphi_1^2 + C\varphi_1^{r(p-1)+\beta+2} \right] \leq \lambda.$$

Take  $\delta > 0$  small enough such that

$$r(1-r)|\nabla\varphi_1|^2 + r\lambda_1\varphi_1^2 + C\varphi_1^{r(p-1)+\beta+2} < 0$$

in  $\Omega_\delta = \{x \in \Omega : \rho_0(x) < \delta\}$ .

(ii) Inner points:

In the region  $\Omega \setminus \overline{\Omega}_\delta$  we have that  $\varphi_1 \geq c(\delta)$  for some  $c(\delta) > 0$ . Hence, for (3.15) it is sufficient that

$$r\lambda_1 + C(\delta) \leq \lambda,$$

for some  $C(\delta)$ . Fixed  $\delta$ , we can take  $\lambda$  large.

Hence, we can define

$$\lambda_*(N) = \inf \{ \lambda > 0 \mid \text{such that (3.13) has a positive a.e. solution} \}.$$

Then  $\lambda_*(N) < +\infty$  and for all  $\lambda \geq \lambda_*(N)$ , problem (3.13) has a positive a.e. weak solution.

Finally, assume that  $N \geq N_0 > 0$  and  $q \geq p$ . Then, multiplying the equation by  $\varphi_1$  and integrating we have

$$0 = \int_{\Omega} \varphi_1 u^p (\lambda u^{q-p} - N - \lambda_1 u^{1-p}) \leq \int_{\Omega} \varphi_1 u^p (\lambda u^{q-p} - N_0 - \lambda_1 u^{1-p}).$$

Assuming  $q > p$ , the maximum of the function  $f(x) := \lambda x^{q-p} - \lambda_1 x^{1-p}$  is attained at

$$x_M = \left( \frac{\lambda(q-p)}{\lambda_1(1-p)} \right)^{1/(1-q)}$$

and

$$f(x_M) = \lambda^{(1-p)/(1-q)} \left( \frac{q-p}{\lambda_1(1-p)} \right)^{(q-p)/(1-q)} \frac{1-q}{1-p}$$

and so if  $\lambda$  is small we have that

$$\int_{\Omega} \varphi_1 u^p (\lambda u^{q-p} - N_0 - \lambda_1 u^{1-p}) < 0,$$

a contradiction. A similar argument can be used in the case  $q = p$ . This completes the proof.  $\square$

**Remark 3.5.** Equations (3.3) and (3.11) have been studied in [5] and [19], but with different behavior of  $a(x)$  or without  $a(x)$ . Also, equation (3.13) has been previously studied when  $N$  is bounded, see [7] and references therein.

**Remark 3.6.** The solutions of Propositions 3.3, 3.4 and Theorem 1.1 (A) belong to  $C^{1,\Upsilon}(\overline{\Omega})$ ,  $0 < \Upsilon < 1$ . This follows from the results in [12] which says that if  $-\Delta u = h$  in  $\Omega$  with  $u = 0$  on  $\partial\Omega$  and  $\sup_{\overline{\Omega}} |h(x)| \rho_0^\Upsilon(x) < \infty$  for some  $0 < \Upsilon < 1$ , then  $u \in C^{1,1-\Upsilon}(\overline{\Omega})$ .

## 4 Proof of Theorem 1.1

We are going to apply the sub-supersolution method to system (1.1). If we denote

$$f(u, v) := \lambda u^{q_1} - \frac{u^{p_1}}{v^{\beta_1}} \quad g(u, v) := \mu v^{q_2} - \frac{v^{p_2}}{u^{\beta_2}},$$

the third paragraph of the definition of sub-supersolution (Definition 2.2) is equivalent to

$$-\Delta \underline{u} \leq f(\underline{u}, \underline{v}), \quad -\Delta \bar{u} \geq f(\bar{u}, \bar{v}),$$

and

$$-\Delta \underline{v} \leq g(\bar{u}, \underline{v}), \quad -\Delta \bar{v} \geq g(\underline{u}, \bar{v}).$$

We start the proof of Theorem 1.1:

*Proof.* (A) Take

$$\bar{u} := \omega_{[\lambda, q_1]}, \quad \text{and} \quad \bar{v} := \omega_{[\mu, q_2]}. \quad (4.1)$$

A subsolution is

$$\underline{v} := \Theta_{[\mu, q_2, \beta_2, \omega_{[\lambda, q_1]}^{p_2}]}. \quad (4.2)$$

Observe that  $\omega_{[\lambda, q_1]} = \lambda^{1/(1-q_1)} \omega_{[1, q_1]}$  and so  $\underline{v}$  verifies

$$-\Delta v = \mu v^{q_2} - \lambda^{p_2/(1-q_1)} \frac{\omega_{[1, q_1]}^{p_2}}{v^{\beta_2}} \quad \text{in } \Omega. \quad (4.3)$$

Under the change of variable

$$V = Rv,$$

where

$$R = \frac{1}{\lambda^{p_2/((1-q_1)(1+\beta_2))}},$$

(4.3) transforms into

$$\begin{cases} -\Delta V = \Lambda V^{q_2} - \frac{\omega_{[1, q_1]}^{p_2}}{V^{\beta_2}} & \text{in } \Omega, \\ V = 0 & \text{on } \partial\Omega, \end{cases} \quad (4.4)$$

where

$$\Lambda = \mu \lambda^{-\sigma},$$

with

$$\sigma = \frac{p_2(1-q_2)}{(1-q_1)(1+\beta_2)}$$

Observe that (4.4) is in the setting of (3.11) by taking  $a = \omega_{[1, q_1]}^{p_2}$ . Indeed, (3.4) and (3.5) are verified for all  $\gamma$  such that

$$\gamma \leq \frac{p_2 + 2}{1 + \beta_2},$$

which can be chosen  $1 < \gamma$ . Hence, applying Proposition 3.3, we conclude the existence of a positive solution of (4.4) if

$$\Lambda \geq \lambda^*(\Omega)$$

or equivalently,

$$\mu \geq \lambda^*(\Omega)\lambda^\sigma.$$

It is clear that  $\underline{v} \leq \bar{v}$  and  $\underline{v} > 0$  if  $\mu \geq \lambda^*(\Omega)\lambda^\sigma$ . It remains to check that there exists  $\underline{u} > 0$  and satisfies

$$-\Delta \underline{u} \leq \lambda \underline{u}^{q_1} - \underline{v}^{-\beta_1} \underline{u}^{p_1} \quad \text{in } \Omega.$$

Let  $u$  be the solution of

$$\begin{cases} -\Delta u = \lambda u^{q_1} - \underline{v}^{-\beta_1} u^{p_1} & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases} \quad (4.5)$$

Observe that in this case  $N(x) = \underline{v}^{-\beta_1}$ , being  $\underline{v}$  defined in (4.2). Hence, taking into account (3.12) we obtain that  $0 < N \leq C\rho_0^{-\beta_1}$  and so it is clear that

$$-\beta_1 + p_1 > -1.$$

Thus we can apply Proposition 3.4 to conclude that, if  $q_1 < p_1$ , there exists a positive solution of (4.5) provided  $\lambda > 0$ . Moreover, it is clear that  $\underline{u} \leq \bar{u}$ .

Finally, the second paragraph of Definition 2.2 is easy to verify.

In conclusion, if  $q_1 < p_1$  there is a positive solution of (1.1) if  $\lambda > 0$  and  $\mu \geq \lambda^*(\Omega)\lambda^\sigma$ . (B) Finally, we assume that  $q_1 \geq p_1$ . Observe that if  $(u, v)$  is a solution of (1.1), then

$$v \leq \omega_{[\mu, q_2]} = \mu^{1/(1-q_2)} \omega_{[1, q_2]}$$

and then,

$$-\Delta u \leq \lambda u^{q_1} - \mu^{-\beta_1/(1-q_2)} \omega_{[1, q_2]}^{-\beta_1} u^{p_1}.$$

Under the change of variable

$$U = Ru, \quad R = \mu^{\beta_1/((1-q_2)(1-p_1))}$$

the above inequality is transformed into

$$\begin{cases} -\Delta U \leq \lambda \mu^r U^{q_1} - \omega_{[1, q_2]}^{-\beta_1} U^{p_1} & \text{in } \Omega, \\ U = 0 & \text{on } \partial\Omega. \end{cases}$$

Hence, multiplying by  $\varphi_1$ , integrating and with a similar argument to the proof of Proposition 3.4, we can conclude that if

$$\lambda \mu^r < \lambda_*(\Omega),$$

there is no positive solution of (1.1).  $\square$

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