© World Scientific Publishing Company

DOI: 10.1142/S0219199710003920



OPTIMIZATION PROBLEM FOR EXTREMALS OF THE TRACE INEQUALITY IN DOMAINS WITH HOLES

LEANDRO M. DEL PEZZO

Departamento de Matemática, FCEyN Universidad de Buenos Aires, Pabellón I Ciudad Universitaria (1428), Buenos Aires, Argentina ldpezzo@dm.uba.ar

> Received 4 September 2008 Revised 19 November 2009

We study the Sobolev trace constant for functions defined in a bounded domain Ω that vanish in the subset A. We find a formula for the first variation of the Sobolev trace with respect to the hole. As a consequence of this formula, we prove that when Ω is a centered ball, the symmetric hole is critical when we consider deformation that preserve volume but is not optimal for some case.

Keywords: Steklov eigenvalues; Sobolev trace embedding; shape derivative.

Mathematics Subject Classification 2010: 35P15, 49K20, 49Q10

1. Introduction and Main Results

Let Ω be a bounded smooth domain in \mathbb{R}^N with $N \geq 2$ and $1 . We denote by <math>p^*$ the critical exponent for the Sobolev trace immersion given by $p^* = p(N-1)/(N-p)$ if p < N and $p^* = \infty$ if $p \geq N$.

For any $A \subset \overline{\Omega}$, which is a smooth open subset, we define the space

$$W_A^{1,p}(\Omega) = \overline{C_0^{\infty}(\overline{\Omega} \backslash A)},$$

where the closure is taken in $W^{1,p}$ -norm. By the Sobolev Trace Theorem, there is a compact embedding

$$W_A^{1,p}(\Omega) \hookrightarrow L^q(\partial\Omega), \tag{1.1}$$

for all $1 \le q < p^*$. Thus, given $1 \le q < p^*$, there exists a constant C = C(q, p) such that

$$C\left\{ \int_{\partial\Omega} |u|^q \, \mathrm{d}S \right\}^{\frac{p}{q}} \le \int_{\Omega} |\nabla u|^p + |u|^p \, \mathrm{d}x.$$

The best (largest) constant in the above inequality is given by

$$S_q(A) := \inf_{u \in W_A^{1,p}(\Omega) \setminus W_0^{1,p}(\Omega)} \frac{\int_{\Omega} |\nabla u|^p + |u|^p \, \mathrm{d}x}{\left\{ \int_{\partial \Omega} |u|^q \, \mathrm{d}S \right\}^{\frac{p}{q}}}.$$
 (1.2)

By (1.1), there exist an extremal for $S_q(A)$. Moreover, an extremal for $S_q(A)$ is a weak solution to

$$\begin{cases}
-\Delta_p u + |u|^{p-2} u = 0 & \text{in } \Omega \backslash \overline{A}, \\
|\nabla u|^{p-2} \frac{\partial u}{\partial \nu} = \lambda |u|^{q-2} u & \text{on } \partial \Omega \backslash \overline{A}, \\
u = 0 & \text{on } \partial A,
\end{cases}$$
(1.3)

where $\Delta_p u = \operatorname{div}(|\nabla u|^{p-2}\nabla u)$ is the usual p-Laplacian, $\frac{\partial}{\partial \nu}$ is the outer unit normal derivative and λ depends on the normalization of u. When $||u||_{L^q(\partial\Omega)} = 1$ we have that $\lambda = S_q(A)$. Moreover, when p = q, the problem (1.3) becomes homogeneous and therefore is a nonlinear eigenvalue problem. In this case, the first eigenvalue of (1.3) coincides with the best Sobolev trace constant $S_q(A) = \lambda_1(A)$ and it is shown in [9] that it is simple (see also [3]). Therefore, if p = q, the extremal for $S_p(A)$ is unique up to constant factor. In the linear setting, i.e., when p = q = 2, this eigenvalue problem is known as the Steklov eigenvalue problem, see [11].

The aim of this paper is to analyze the dependence of the Sobolev trace constant $S_q(A)$ with respect to variations on the set A. To this end, we compute the so-called shape derivative of $S_q(A)$ with respect to regular perturbations of the hole A.

Let $V: \mathbb{R}^N \to \mathbb{R}^N$ be a regular (smooth) vector filed, globally Lipschitz, with support in Ω and let $\psi_t: \mathbb{R}^N \to \mathbb{R}^N$ be defined as the unique solution to

$$\begin{cases} \frac{d}{dt}\psi_t(x) = V(\psi_t(x)) & t > 0\\ \psi_0(x) = x & x \in \mathbb{R}^N. \end{cases}$$
 (1.4)

We have

$$\psi_t(x) = x + tV(x) + o(t) \quad \forall x \in \mathbb{R}^N.$$

Now, we define $A_t := \psi_t(A) \subset \Omega$ for all t > 0 and

$$S_q(t) = \inf_{u \in W_{A_t}^{1,p}(\Omega) \setminus W_0^{1,p}(\Omega)} \frac{\int_{\Omega} |\nabla u|^p + |u|^p \,\mathrm{d}x}{\left\{ \int_{\partial \Omega} |u|^q \,\mathrm{d}S \right\}^{\frac{p}{q}}}.$$
 (1.5)

Observe that $A_0 = A$ and therefore $S_q(0) = S_q(A)$.

In the linear case p = q = 2, Rossi studies the best constant of the Sobolev trace embedding in a domain without holes, see [10]. He finds a formula for the first variation of the best constant with respect to the domain. As a consequence

he proves that the ball is a critical domain when we consider deformations that preserve volume.

In [2], Fernández Bonder, Groisman and Rossi analyze this problem in domain with holes and prove that $S_2(t)$ is differentiable with respect to t at t = 0 and it holds

$$\frac{d}{dt}S_2(t)|_{t=0} = -\int_{\partial A} \left(\frac{\partial u}{\partial \nu}\right)^2 \langle V, \nu \rangle \, \mathrm{d}S,$$

where u is a normalized eigenfunction for $S_2(A)$ and ν is the exterior normal vector to $\Omega \setminus \overline{A}$. Furthermore, in the case that Ω is the ball B_R with center 0 and radius R > 0 the authors show that a centered ball $A = B_r, r < R$, is critical in the sense that $S'_2(A) = 0$ when considering deformations that preserves volume and that this configuration is not optimal.

We say that a hole A^* is optimal for the parameter $\alpha, 0 < \alpha < |\Omega|$, if $|A^*| = \alpha$ and

$$S_q(A^*) = \inf_{\substack{A \subset \overline{\Omega} \\ |A| = \alpha}} S_q(A).$$

Therefore, in the case p=q=2, there is a lack of symmetry in the optimal configuration.

Here we extend these results to the more general case $1 \le p < \infty$ and $1 \le q < p^*$. Our method differs from the one in [2] in order to deal with the nonlinear character of the problem.

Our first result states

Theorem 1.1. Suppose $A \subset \overline{\Omega}$ is a smooth open subset and let $1 \leq q < p^*$. Then, with the previous notation, we have that $S_q(t)$ is differentiable at t = 0 and

$$S_q'(0) = \frac{d}{dt} S_q(t) \Big|_{t=0} = (1-p) \int_{\partial A} \left| \frac{\partial u}{\partial \nu} \right|^p \langle V, \nu \rangle \, \mathrm{d}S,$$

where u is a normalized extremal (according to $||u||_{L^q(\partial\Omega)} = 1$) for $S_q(A)$ and ν is the exterior normal vector to $\Omega \setminus \overline{A}$.

Remark 1.2. If u is an extremal for $S_q(A)$ we have that |u| is also an extremal associated to $S_q(A)$. Then in the previous theorem we can suppose that $u \geq 0$ in Ω . Moreover, by [8], we have that for all $U \subset\subset \Omega$ open subset such that $U \cap \partial A \neq \emptyset$ is a smooth open set there exists $\delta \in (0,1)$ such that $u \in C^{1,\delta}(\overline{U \setminus A})$ and u > 0 on $\partial \Omega \setminus \partial A$ if $\Omega \setminus \overline{A}$ satisfies the interior ball condition for all $x \in \partial \Omega \setminus \partial A$, see [12].

In the case that $\Omega = B_R$, we have the next result

Theorem 1.3. Let $\Omega = B_R$ and let the hole be a centered ball $A = B_r$. Then, if $1 \leq q \leq p$, this configuration is critical in the sense that $S'_q(B_r) = 0$ for all deformations V that preserve the volume of B_r .

But, if q is sufficiently large, the symmetric hole with a radial extremal is not an optimal configuration. In fact, we prove

Theorem 1.4. Let r > 0 and 1 be fixed. Let <math>R > r and

$$Q(R) = \frac{1}{S_p(B_r)^{\frac{p}{p-1}}} \left(1 - \frac{N-1}{R} S_p(B_r) \right) + 1.$$
 (1.6)

If q > Q(R) then the centered hole B_r is not optimal.

Finally, to study the asymptotic behavior of Q(R)

Proposition 1.5. The function Q(R) has the following asymptotic behavior

$$\lim_{R\to r}Q(R)=1^-\quad and\quad \lim_{R\to +\infty}Q(R)=p.$$

Observe that Q(R) < 1 for R close to r and therefore the symmetric hole with a radial extremal is not an optimal configuration for R close to r.

2. Proof of Theorem 1.1

2.1. Preliminary results

The proof of Theorem 1.1 require some technical results. In this subsection we use some ideas from [4].

Given $u \in W_{A_t}^{1,p}(\Omega) \setminus W_0^{1,p}(\Omega)$ we consider $v = u \circ \psi_t$, so $v \in W_A^{1,p}(\Omega) \setminus W_0^{1,p}(\Omega)$ and $\nabla v^T = {}^T \psi_t' \nabla (u \circ \psi_t)^T$, where ψ_t' denotes the differential matrix of ψ_t and ${}^T A$ is the transpose of matrix A. Thus, by the change of variables formula, we have that

$$\int_{\Omega} |\nabla u|^p + |u|^p \, dx = \int_{\Omega} \{ |T[\psi_t']^{-1} \nabla v^T|^p + |v|^p \} J(\psi_t) \, dx,$$

here $J(\psi_t)$ is the usual Jacobian of ψ_t . Moreover, since $\mathrm{supp}(V) \subset \Omega$, we have that

$$\int_{\partial\Omega} |u|^q \, \mathrm{d}S = \int_{\partial\Omega} |v|^q \, \mathrm{d}S.$$

In [5], are proved the following asymptotic formulas

$$[\psi_t']^{-1}(x) = Id - tV'(x) + o(t), \tag{2.1}$$

$$J(\psi_t)(x) = 1 + t \operatorname{div} V(x) + o(t).$$
 (2.2)

Then, by (2.1) and (2.2), we have

$$\int_{\Omega} |v|^p J(\psi_t) \, \mathrm{d}x = \int_{\Omega} |v|^p \{1 + t \, \mathrm{div} \, V + o(t)\} \, \mathrm{d}x$$
$$= \int_{\Omega} |v|^p \, \mathrm{d}x + t \int_{\Omega} |v|^p \, \mathrm{div} \, V \, \mathrm{d}x + o(t)$$

and

$$\int_{\Omega} |^{T} [\psi'_{t}]^{-1} \nabla v^{T}|^{p} J(\psi_{t}) dx = \int_{\Omega} |[Id - t^{T}V' + o(t)] \nabla v^{T}|^{p} \{1 + t \operatorname{div} V + o(t)\} dx$$

$$= \int_{\Omega} |\nabla v - t^{T}V' \nabla v^{T} + o(t)|^{p} \{1 + t \operatorname{div} V + o(t)\} dx,$$

since

$$|\nabla v - t^T V' \nabla v^T + o(t)|^p = |\nabla v|^p - pt |\nabla v|^{p-2} \langle \nabla v, T V' \nabla v^T \rangle + o(t)$$

we obtain that

$$\int_{\Omega} |T[\psi_t']^{-1} \nabla v^T|^p J(\psi_t) \, \mathrm{d}x = \int_{\Omega} |\nabla v|^p \, \mathrm{d}x + t \int_{\Omega} |\nabla v|^p \, \mathrm{div} \, V \, \mathrm{d}x$$
$$-pt \int_{\Omega} |\nabla v|^{p-2} \langle \nabla v, T V' \nabla v^T \rangle \, \mathrm{d}x + o(t).$$

Thus, we conclude

$$\int_{\Omega} |\nabla u|^p + |u|^p \, \mathrm{d}x = \int_{\Omega} \{|T[\psi_t']^{-1} \nabla v^T|^p + |v|^p\} J(\psi_t) \, \mathrm{d}x$$

$$= \int_{\Omega} |v|^p \, \mathrm{d}x + \int_{\Omega} |\nabla v|^p \, \mathrm{d}x + t \int_{\Omega} \{|\nabla v|^p + |v|^p\} \mathrm{div} \, V \, \mathrm{d}x$$

$$- pt \int_{\Omega} |\nabla v|^{p-2} \langle \nabla v, V' \nabla v' \rangle \, \mathrm{d}x + o(t).$$

Therefore, we can rewrite (1.5) as

$$S_q(t) = \inf_{v \in W_1^{1,p}(\Omega) \setminus W_0^{1,p}(\Omega)} \{ \rho(v) + t\gamma(v) \},$$
 (2.3)

where

$$\rho(v) = \frac{\int_{\Omega} |\nabla v|^p + |v|^p \, \mathrm{d}x}{\left\{ \int_{\partial \Omega} |v|^q \, \mathrm{d}S \right\}^{p/q}},$$

and

$$\gamma(v) = \frac{\int_{\Omega} \{ |\nabla v|^p + |v|^p \} \operatorname{div} V \, \mathrm{d}x - p \int_{\Omega} |\nabla v|^{p-2} \langle \nabla v, ^T V' \nabla v^T \rangle \, \mathrm{d}x}{\left\{ \int_{\partial \Omega} |v|^q \, \mathrm{d}S \right\}^{p/q}} + o(1).$$

Given $t \geq 0$, let $v_t \in W_A^{1,p}(\Omega) \setminus W_0^{1,p}(\Omega)$ such that $||v_t||_{L^q(\partial\Omega)} = 1$ and $S_q(t) = \varphi(t) + t\phi(t)$.

where

$$\varphi(t) = \rho(v_t)$$
 and $\phi(t) = \gamma(v_t) \quad \forall t \ge 0.$

We observe that $\varphi, \phi : \mathbb{R}_{\geq 0} \to \mathbb{R}$ and

Lemma 2.1. The function ϕ is nonincreasing.

Proof. Let $0 \le t_1 \le t_2$. By (2.3), we have that

$$\varphi(t_2) + t_1 \phi(t_2) \ge S_q(t_1) = \varphi(t_1) + t_1 \phi(t_1) \tag{2.4}$$

$$\varphi(t_1) + t_2 \phi(t_1) \ge S_q(t_2) = \varphi(t_2) + t_2 \phi(t_2). \tag{2.5}$$

Subtracting (2.4) from (2.5), we get

$$(t_2 - t_1)\phi(t_1) \ge (t_2 - t_1)\phi(t_2).$$

Since $t_2 - t_1 \ge 0$, we obtain

$$\phi(t_1) \ge \phi(t_2).$$

This ends the proof.

Remark 2.2. Since ϕ is nonincreasing, we have

$$\phi(t) \le \phi(0) \quad \forall \, t \ge 0,$$

and there exists

$$\phi(0^+) = \lim_{t \to 0^+} \phi(t).$$

Corollary 2.3. The function φ is nondecreasing.

Proof. Let $0 \le t_1 \le t_2$. Again, by (2.3), we have that

$$\varphi(t_2) + t_1 \phi(t_2) \ge S_q(t_1) = \varphi(t_1) + t_1 \phi(t_1) \tag{2.6}$$

SO

$$\varphi(t_2) - \varphi(t_1) \ge t_1(\phi(t_1) - \phi(t_2)).$$

Since $0 \le t_1 \le t_2$, by Lemma 2.1, we have that $\phi(t_1) - \phi(t_2) \ge 0$. Then

$$\varphi(t_2) - \varphi(t_1) \ge 0$$

that is what we wished to prove.

Now we can prove that $S_q(t)$ is continuous at t=0.

Theorem 2.4. The function $S_q(t)$ is continuous at t = 0, i.e.

$$\lim_{t \to 0^+} S_q(t) = S_q(0).$$

Proof. Given $t \ge 0$ so, by Corollary 2.3,

$$S_q(t) - Sq(0) = \varphi(t) + t\phi(t) - \varphi(0) \ge t\phi(t).$$

On the other hand, by (2.3), we have that

$$S_q(t) \le \varphi(0) + t\phi(0) = S_q(0) + t\phi(0).$$

Then

$$t\phi(t) \le S_q(t) - Sq(0) \le t\phi(0).$$

Thus, by Remark 2.2,

$$\lim_{t \to 0^+} S_q(t) - S_q(0) = 0.$$

This finishes the proof.

Thus, from Remark 2.2 and Theorem 2.4, we obtain the following corollary:

Corollary 2.5. The function φ is continuous at t=0, i.e.

$$\lim_{t \to 0^+} \varphi(t) = \varphi(0).$$

Proof. We observe that

$$\varphi(t) - \varphi(0) = S_q(t) - S_q(0) - t\phi(t).$$

Then, by Remark 2.2 and Theorem 2.4,

$$\lim_{t \to 0^+} \varphi(t) - \varphi(0) = 0.$$

That proves the result.

Finally, we prove the following:

Theorem 2.6. The function φ is differentiable at t=0 and

$$\frac{\mathrm{d}\varphi}{\mathrm{d}t}(0) = 0.$$

Proof. Let 0 < r < t. By (2.3), we get

$$S_q(r) = \varphi(r) + r\phi(r) \le \varphi(t) + r\phi(t),$$

and

$$S_q(t) = \varphi(t) + t\phi(t) \le \varphi(r) + t\phi(r).$$

So

$$\frac{r}{t}(\phi(r) - \phi(t)) \le \frac{\varphi(t) - \varphi(r)}{t} \le \phi(r) - \phi(t).$$

Hence, taking limits when $r \to 0^+$, by Remark 2.2 and Corollary 2.1, we have that

$$0 \le \frac{\varphi(t) - \varphi(0)}{t} \le \phi(0^+) - \phi(t).$$

Now, taking limits when $t \to 0^+$, and again by Remark 2.2, we get

$$\lim_{t \to 0^+} \frac{\varphi(t) - \varphi(0)}{t} = 0,$$

as we wanted to show.

2.2. Proof of Theorem 1.1

We proceed in three steps.

Step 1. We show that $S_q(t)$ is differentiable at t=0 and

$$S_q'(0) = \phi(0^+).$$

We have that

$$\frac{S_q(t) - S_q(0)}{t} = \frac{\varphi(t) - \varphi(0)}{t} + \phi(t).$$

Then, by Remark 2.2 and Theorem 2.6,

$$S'_q(0) = \lim_{t \to 0^+} \frac{S_q(t) - S_q(0)}{t} = \phi(0^+).$$

Step 2. We show that there exists u extremal for $S_q(A)$ such that $||u||_{L^q(\partial\Omega)} = 1$ and

$$\phi(0^+) = \int_{\Omega} (|\nabla u|^p + |u|^p) \operatorname{div} V \, dx - p \int_{\Omega} |\nabla u|^{p-2} \langle \nabla u, T V' \nabla u \rangle \, dx.$$

By Theorem 2.1,

$$||v_t||_{W^{1,p}(\Omega)}^p = \varphi(t) \to \varphi(0) = S_q(0) \text{ when } t \to 0^+.$$
 (2.7)

Then there exists $u \in W^{1,p}(\Omega)$ and $t_n \to 0^+$ when $n \to \infty$ such that

$$v_{t_n} \rightharpoonup u \quad \text{weakly in } W^{1,p}(\Omega),$$
 (2.8)

$$v_{t_n} \to u$$
 strongly in $L^q(\partial\Omega)$, (2.9)

$$v_{t_n} \to u$$
 a.e. in Ω . (2.10)

By (2.9) and (2.10), $u \in W_A^{1,p}(\Omega)$ and $||u||_{L^q(\partial\Omega)} = 1$ and by (2.8)

$$S_q(0) = \lim_{n \to \infty} \|v_{t_n}\|_{W^{1,p}(\Omega)}^p \ge \|u\|_{W^{1,p}(\Omega)}^p \ge S_q(0),$$

then

$$S_q(0) = ||u||_{W^{1,p}(\Omega)}^p. (2.11)$$

Moreover, by (2.7), (2.8) and (2.11), we have that

$$v_{t_n} \to u$$
 strongly in $W^{1,p}(\Omega)$.

Therefore

$$\phi(0^+) = \lim_{n \to \infty} \phi(v_{t_n})$$

$$= \int_{\Omega} (|\nabla u|^p + |u|^p) \operatorname{div} V \, \mathrm{d}x - p \int_{\Omega} |\nabla u|^{p-2} \langle \nabla u, \, ^T V' \nabla u^T \rangle \, \mathrm{d}x.$$

Step 3. Finally, we show that

$$\begin{split} S_q'(0) &= \int_{\Omega} (|\nabla u|^p + |u|^p) \mathrm{div} \ V \, \mathrm{d}x - p \int_{\Omega} |\nabla u|^{p-2} \langle \nabla u, \ ^T V' \nabla u^T \rangle \, \mathrm{d}x \\ &= (1-p) \int_{\partial A} \left| \frac{\partial u}{\partial \nu} \right|^p \langle V, \nu \rangle \, \mathrm{d}S. \end{split}$$

To show this we require that $u \in \mathbb{C}^2$. However, this is not true in general. Since u is an extremal for $S_q(A)$ and $||u||_{L^q(\partial\Omega)}=1$, we know that u is weak solution to

$$\begin{cases} -\Delta_p u + |u|^{p-2} u = 0 & \text{in } \Omega \backslash \overline{A}, \\ |\nabla u|^{p-2} \frac{\partial u}{\partial \nu} = S_q(A) |u|^{q-2} u & \text{on } \partial \Omega \backslash \overline{A}, \\ u = 0 & \text{on } \partial A, \end{cases}$$

and by [8] we get that u belongs to the class $C^{1,\delta}$ for some $0 < \delta < 1$.

Now, in order to overcome our difficulty, we proceed as follows. We consider the following problem, let $\varepsilon > 0$

$$S_{\varepsilon} := \inf_{v \in W_A^{1,p}(\Omega) \setminus W_0^{1,p}(\Omega)} \frac{\int_{\Omega} (|\nabla v|^2 + \varepsilon^2)^{\frac{p-2}{2}} |\nabla v|^2 + |v|^p \,\mathrm{d}x}{\left\{ \int_{\partial \Omega} |v|^q \,\mathrm{d}S \right\}^{\frac{p}{q}}}.$$
 (2.12)

Let u_{ε} be the normalized positive eigenvalue associated to S_{ε} . Observe that the eigenfunction is weak solution to

$$\begin{cases}
-\operatorname{div}(|\nabla u_{\varepsilon}|^{2} + \varepsilon^{2})^{(p-2)/2} \nabla u_{\varepsilon}) + |u_{\varepsilon}|^{p-2} u_{\varepsilon} = 0 & \text{in } \Omega \backslash \overline{A}, \\
(|\nabla u_{\varepsilon}|^{2} + \varepsilon^{2})^{(p-2)/2} \frac{\partial u_{\varepsilon}}{\partial \nu} = S_{\varepsilon} |u_{\varepsilon}|^{q-2} u_{\varepsilon} & \text{on } \partial \Omega, \\
u_{\varepsilon} = 0 & \text{on } \partial A.
\end{cases}$$
(2.13)

It is well known that the solution u_{ε} to (2.13) is of class $C^{2,\rho}(\Omega \setminus \overline{A})$ for some $0 < \rho < 1$ (see [6]).

Thus, since $u_{\varepsilon} \in W_A^{1,p}(\Omega) \setminus W_0^{1,p}(\Omega)$ and $||u_{\varepsilon}||_{L^q(\partial\Omega)} = 1$ for all $\varepsilon > 0$, we have that

$$S_{q}(A) \leq S_{\varepsilon}$$

$$\leq \int_{\Omega} (|\nabla u_{\varepsilon}|^{2} + \varepsilon^{2})^{\frac{p-2}{2}} |\nabla u_{\varepsilon}|^{2} + |u_{\varepsilon}|^{p} dx$$

$$\leq \int_{\Omega} (|\nabla u|^{2} + \varepsilon^{2})^{\frac{p-2}{2}} |\nabla u|^{2} + |u|^{p} dx.$$

Then $\lambda_{\varepsilon} \to S_q(0)$ as $\varepsilon \to 0^+$ and the normalized eigenfunction u_{ε} associated to λ_{ε} are bounded in $W^{1,p}(\Omega)$ uniformly in $\varepsilon > 0$. Therefore, there exists a sequence, that we still call $\{u_{\varepsilon}\}$, and a function $w \in W^{1,p}(\Omega)$ such that

$$u_{\varepsilon} \rightharpoonup w$$
 weakly in $W^{1,p}(\Omega)$,
 $u_{\varepsilon} \to w$ strongly in $L^{q}(\partial \Omega)$,
 $u_{\varepsilon} \to w$ a.e. in Ω .

Hence, $w \in W_A^{1,p}(\Omega)$, $||w||_{L^q(\partial\Omega)} = 1$ and

$$S_{q}(A) = \lim_{\varepsilon \to 0^{+}} S_{\varepsilon}$$

$$= \lim_{\varepsilon \to 0^{+}} \int_{\Omega} (|\nabla u_{\varepsilon}|^{2} + \varepsilon^{2})^{\frac{p-2}{2}} |\nabla u_{\varepsilon}|^{2} + |u_{\varepsilon}|^{p} dx$$

$$\geq \int_{\Omega} |\nabla w|^{p} + |w|^{p} dx$$

$$\geq S_{q}(A).$$

These imply that w is a normalized positive extremal for $S_q(A)$ and $||u_{\varepsilon}||_{W^{1,p}(\Omega)} \to ||w||_{W^{1,p}(\Omega)}$ as $\varepsilon \to 0^+$, and therefore

$$u_{\varepsilon} \to w$$
 strongly in $W^{1,p}(\Omega)$.

Let $U \subset\subset \Omega$ be a smooth open subset such that $U\setminus \overline{A}$ is a smooth open set and the support of V is contained in U. By [8], there exists $\delta \in (0,1)$ such that $w, u_{\varepsilon} \in C^{1,\delta}(\overline{U\setminus \overline{A}})$. Moreover, there exists a constant C independent of $\varepsilon > 0$ such that

$$||u_{\varepsilon}||_{C^{1,\delta}(\overline{U\setminus\overline{A}})} \le C.$$

Then, we have that $u_{\varepsilon} \to w$ and $\nabla u_{\varepsilon} \to \nabla w$ uniformly in $\overline{U \setminus \overline{A}}$ as $\varepsilon \to 0^+$. Hence,

$$\begin{split} S_q'(0) &= \int_{\Omega} (|\nabla w|^p + |w|^p) \mathrm{div} \ V \, \mathrm{d}x - p \int_{\Omega} |\nabla w|^{p-2} \langle \nabla w, \ ^T V' \nabla w^T \rangle \, \mathrm{d}x \\ &= \lim_{\varepsilon \to 0^+} \int_{\Omega} [(|\nabla u_{\varepsilon}|^2 + \varepsilon^2)^{\frac{p}{2}} | + |u_{\varepsilon}|^p] \mathrm{div} \ V \, \mathrm{d}x \\ &- p \int_{\Omega} |\nabla w|^{p-2} \langle \nabla w, ^T V' \nabla w^T \rangle \, \mathrm{d}x, \end{split}$$

and since

$$\operatorname{div}(|u_{\varepsilon}|^{p}V) = |u_{\varepsilon}|^{p}\operatorname{div} V + p|u_{\varepsilon}|^{p-2}u_{\varepsilon}\langle\nabla u_{\varepsilon}, V\rangle,$$

$$\operatorname{div}((|\nabla u_{\varepsilon}|^{2} + \varepsilon^{2})^{\frac{p}{2}}V) = (|\nabla u_{\varepsilon}|^{2} + \varepsilon^{2})^{\frac{p}{2}}\operatorname{div} V + p(|\nabla u_{\varepsilon}|^{2} + \varepsilon^{2})^{\frac{p-2}{2}}\langle\nabla u_{\varepsilon}D^{2}u_{\varepsilon}, V\rangle$$

$$= (|\nabla u_{\varepsilon}|^{2} + \varepsilon^{2})^{\frac{p}{2}}\operatorname{div} V + p(|\nabla u_{\varepsilon}|^{2} + \varepsilon^{2})^{\frac{p-2}{2}}\langle\nabla u_{\varepsilon}, \nabla\langle\nabla u_{\varepsilon}, V\rangle\rangle$$

$$- p(|\nabla u_{\varepsilon}|^{2} + \varepsilon^{2})^{\frac{p-2}{2}}\langle\nabla u_{\varepsilon}, T V' \nabla u_{\varepsilon}^{T}\rangle,$$

we have that

$$S_q'(0) = \lim_{\varepsilon \to 0^+} a_\varepsilon - pb_\varepsilon$$

where

$$a_{\varepsilon} = \int_{\Omega} \operatorname{div}((|\nabla u_{\varepsilon}|^{2} + \varepsilon^{2})^{\frac{p}{2}} V + |u_{\varepsilon}|^{p} V) \, \mathrm{d}x,$$

$$b_{\varepsilon} = \int_{\Omega} \{(|\nabla u_{\varepsilon}|^{2} + \varepsilon^{2})^{\frac{p-2}{2}} \langle \nabla u_{\varepsilon}, \nabla \langle \nabla u_{\varepsilon}, V \rangle \rangle + |u_{\varepsilon}|^{p-2} u_{\varepsilon} \langle \nabla u_{\varepsilon}, V \rangle \} \, \mathrm{d}x.$$

Now, integrating by parts and using that $\operatorname{supp}(V) \subset \Omega$ and $u_{\varepsilon} = 0$ on $\partial \Omega$, we obtain that

$$a_{\varepsilon} = \int_{\partial A} (|\nabla u_{\varepsilon}|^2 + \varepsilon^2)^{\frac{p}{2}} \langle V, \nu \rangle \, \mathrm{d}S,$$

and since u_{ε} is solution of (2.13), we have

$$b_{\varepsilon} = \int_{\partial A} (|\nabla u_{\varepsilon}|^2 + \varepsilon^2)^{\frac{p-2}{2}} \langle \nabla u_{\varepsilon}, V \rangle \langle \nabla u_{\varepsilon}, \nu \rangle \, \mathrm{d}S,$$

where ν is the exterior normal vector to $\Omega \setminus \overline{A}$. Then using that $\nabla w_{\varepsilon} \to \nabla w$ uniformly in $\overline{U \setminus \overline{A}}$ as $\varepsilon \to 0^+$, we get that

$$S_q'(0) = \int_{\partial A} |\nabla w|^p \langle V, \nu \rangle \, \mathrm{d}S - p \int_{\partial A} |\nabla w|^{p-2} \langle \nabla w, \nu \rangle \langle \nabla w, V \rangle \, \mathrm{d}S.$$

Hence, since $\nabla w = \frac{\partial w}{\partial \nu} \nu$ on ∂A ,

$$S'_{q}(0) = (1 - p) \int_{\partial A} \left| \frac{\partial w}{\partial \nu} \right|^{p} \langle V, \nu \rangle \, \mathrm{d}S,$$

as we wanted to show.

3. Lack of Symmetry in the Ball

In this section, we consider the case where $\Omega = B_R$ and $A = B_r$ with r < R and show Theorems 1.3 and 1.4 and Proposition 1.5. The proofs are based on the arguments of [2, 7] adapted to our problem. In order to simplify notations, we write $S_q(r)$ instead $S_q(B_r)$.

First, we proof Theorem 1.3, for this we need the following proposition

Proposition 3.1. Let 1 < q < p. The non-negative solution of (1.3) is unique.

Proof. Suppose that there exist two non-negative solutions u and v of (1.3). By Remark 1.2 it follows that u, v > 0 on $\partial \Omega$. Let $v_n = v + \frac{1}{n}$ with $n \in \mathbb{N}$, using first Picone's identity (see [1]) and the weak formulation of (1.3) we have

$$0 \leq \int_{B_R} |\nabla u|^p \, \mathrm{d}x - \int_{B_R} |\nabla v_n|^{p-2} \nabla v_n \nabla \left(\frac{u^p}{v_n^{p-1}}\right) \, \mathrm{d}x$$

$$= \int_{B_R} |\nabla u|^p \, \mathrm{d}x - \int_{B_R} |\nabla v|^{p-2} \nabla v \nabla \left(\frac{u^p}{v_n^{p-1}}\right) \, \mathrm{d}x$$

$$= -\int_{B_R} u^p \, \mathrm{d}x + \lambda \int_{\partial B_R} u^q \, \mathrm{d}S + \int_{B_R} v^{p-1} \frac{u^p}{v_n^{p-1}} \, \mathrm{d}x - \lambda \int_{\partial B_R} v^{q-1} \frac{u^p}{v_n^{p-1}} \, \mathrm{d}S$$

$$\leq \lambda \int_{\partial B_R} u^q \, \mathrm{d}S - \lambda \int_{\partial B_R} v^{q-1} \frac{u^p}{v_n^{p-1}} \, \mathrm{d}S.$$

Thus, by the Monotone Convergence Theorem,

$$0 \le \int_{\partial B_R} u^q \, dS - \int_{\partial B_R} v^{q-1} \frac{u^p}{v^{p-1}} \, dS$$
$$= \int_{\partial B_R} u^p (u^{q-p} - v^{q-p}) \, dS.$$

Note that the role of u and v in the above equation are exchangeable. Therefore, adding we get

$$0 \le \int_{\partial B_R} (u^p - v^p)(u^{q-p} - v^{q-p}) \,\mathrm{d}S.$$

Since q < p we have that $u \equiv v$ on ∂B_R . Then, by uniqueness of solution to the Dirichlet problem, we get $u \equiv v$ in B_R .

Remark 3.2. As the problem (1.3) is rotationally invariant, by uniqueness we obtain that the non-negative solution of (1.3) must be radial. Therefore, if $\Omega = B_R$, $A = B_r$ and $1 \le q \le p$ we can suppose that the extremal for $S_q(r)$ found in the Theorem 1.1 is non-negative and radial.

Now we can prove the Theorem 1.3,

Proof of Theorem 1.3. We consider $\Omega = B_R, A = B_r$ and $1 \le q \le p$. By Theorem 1.3 and Remark 3.2 there exist a non-negative and radial normalized extremal for $S_q(r)$ such that

$$S'_q(0) = (1-p) \int_{\partial B_r} \left| \frac{\partial u}{\partial \nu} \right|^p \langle V, \nu \rangle \, \mathrm{d}S.$$

Since u is radial

$$\frac{\partial u}{\partial \nu} \equiv c \quad \text{on } \partial B_r,$$

where c is a constant.

Thus, using that we are dealing with deformations V that preserves the volume of the B_r , we have that

$$S'_{q}(0) = (1-p)c^{p} \int_{\partial B_{r}} \langle V, \nu \rangle dS = (p-1)c^{p} \int_{B_{r}} \operatorname{div}(V) dx = 0.$$

To prove Theorem 1.4, we need two previous results.

Proposition 3.3. Let r > 0 fixed. Then, there exists a positive radial function u_0 such that

$$\begin{cases}
-\Delta_p u + |u|^{p-2}u = 0 & \text{in } \mathbb{R}^N \backslash B_r, \\
u = 0 & \text{on } \partial B_r.
\end{cases}$$
(3.1)

This u_0 is unique up to a constant factor and for any R > r the restriction of u_0 to B_R is the first eigenfunction of (1.3) with q = p.

Proof. For R > r, let u_R be the unique solution of the Dirichlet problem

$$\begin{cases} \Delta_p u_R = |u_R|^{p-2} u_R & \text{in } B_R \backslash \overline{B_r}, \\ u(R) = 1, \\ u(r) = 0. \end{cases}$$

Then, by uniqueness, u_R is a non-negative and radial function. Moreover, by the regularity theory and maximum principle we have $\frac{\partial u_R}{\partial \nu}(r) \neq 0$ (see [8, 12]). Thus, for any R > r, we define the restriction of u_0 by

$$u_0 = \frac{u_R}{\frac{\partial u_R}{\partial \nu}(r)}.$$

By uniqueness of the Dirichlet problem, it is easy to check that u_0 is well defined and is a non-negative radial solution of (3.1). Furthermore, by the simplicity of $S_p(r)$, u_0 is the eigenfunction associated to $S_p(r)$ for every R > r.

Proposition 3.4. Let v be a radial solution of (1.3). Then v is a multiple of u_0 . In particular any radial minimizer of (1.2) is a multiple of u_0 .

Proof. Let a > 0 be such that $v = au_0$ on $\partial B(0, R)$. Then v and au_0 are two solutions to the Dirichlet problem $\Delta_p w = w^{p-1}$ and w = v on $\partial (B_R \setminus \overline{B_r})$. Hence, by uniqueness, we have that $v = au_0$ in B_R .

Remark 3.5. If 1 < q < p then the solution of (1.3), by Remark 3.2 and Proposition 3.4, is a multiple of u_0 .

Now we can deal with the proof of Theorem 1.4.

Proof of Theorem 1.4. Let R > r be fixed and consider u_0 to be the non-negative radial function given by Proposition 3.3 such that that $u_0 = 1$ on ∂B_R . Then, by Proposition 3.4, it is enough to prove that u_0 is not a minimizer for $S_q(r)$ when q > Q(R).

First let us move this symmetric configuration in the x_1 direction. For any $t \in \mathbb{R}$ and $x \in \mathbb{R}^N$ we denote $x_t = (x_1 - t, x_2, \dots, x_N)$ and define

$$U(t)(x) = u_0(x_t).$$

Observe that U vanishes in $A_t := B_r(te_1)$ (the ball with center te_1 and radius r) a subset of B_R of the same measure of B_r for all t small.

Consider the function

$$h(t) = \frac{f(t)}{g(t)}$$

where

$$f(t) = \int_{B_R} |\nabla U|^p + U^p \, \mathrm{d}x \quad \text{and} \quad g(t) = \left(\int_{\partial B_R} U^q \, \mathrm{d}S\right)^{\frac{p}{q}}.$$

We observe that h(0) = 0 and since h is an even function, we have h'(0) = 0. Now,

$$h''(0) = \frac{f''g^2 - fgg'' - 2f'gg' - 2fgg'}{g^3} \bigg|_{t=0}.$$

Next we compute these terms. First, since u_0 is the first eigenfunction of (1.3) with q = p and $u_0 = 1$ on ∂B_R , we get

$$f(0) = S_p(r)|\partial B_R|$$
 and $g(0) = |\partial B_R|^{\frac{p}{q}}$.

Thus, by Gauss-Green's theorem and using the fact that u_0 is radial, we get

$$f'(0) = -\int_{B_R} \frac{\partial}{\partial x_1} (|\nabla u_0|^p + u_0^p) \, dx = \int_{\partial B_R} (|\nabla u_0|^p + u_0^p) \nu_1 \, dS = 0.$$

Again, since u_0 is radial,

$$g'(0) = \frac{p}{q} \left(\int_{\partial B_R} u^q \, dS \right)^{\frac{p}{q} - 1} \left(\int_{\partial B_R} \frac{\partial u^q}{\partial x_1} \, dS \right) = 0.$$

Finally, using that $u_0 = 1$ on ∂B_R , we obtain

$$g''(0) = p|\partial B_R|^{\frac{p}{q}-1} \int_{\partial B_R} (q-1) \left(\frac{\partial u_0}{\partial x_1}\right)^2 + \frac{\partial^2 u_0}{\partial x_1^2} dS$$

and, by the Gauss-Green's theorem

$$f''(0) = p \int_{B_R} \frac{\partial}{\partial x_1} \left(\frac{1}{2} |\nabla u_0|^{p-2} \frac{\partial |\nabla u_0|^2}{\partial x_1} + \frac{1}{p} \frac{\partial u_0^p}{\partial x_1} \right) dx$$
$$= p \int_{\partial B_R} \left(\frac{1}{2} |\nabla u_0|^{p-2} \frac{\partial |\nabla u_0|^2}{\partial x_1} + \frac{1}{p} \frac{\partial u_0^p}{\partial x_1} \right) \nu_1 dS.$$

Then

$$h''(0) = \frac{p}{|\partial B_R(0)|^{p/q}} \left[\int_{\partial B_R} \left(\frac{1}{2} |\nabla u_0|^{p-2} \frac{\partial |\nabla u_0|^2}{\partial x_1} + \frac{1}{p} \frac{\partial u_0^p}{\partial x_1} \right) \nu_1 \, dS - S_p(r) \int_{\partial B_R} (q-1) \left(\frac{\partial u_0}{\partial x_1} \right)^2 + \frac{\partial^2 u_0}{\partial x_1^2} \, dS \right].$$

Thus, since u_0 is radial, we get

$$h''(0) = \frac{p}{N|\partial B_R(0)|^{p/q}} \left[\int_{\partial B_R} \left(\frac{1}{2} |\nabla u_0|^{p-2} \frac{\partial |\nabla u_0|^2}{\partial \nu} + \frac{1}{p} \frac{\partial u_0^p}{\partial \nu} \right) dS - S_p(r) \int_{\partial B_R} (q-1) |\nabla u_0|^2 + \Delta u_0 dS \right].$$

Now, by definition, $u_0(x) = u_0(|x|)$ and α satisfies

$$(s^{N-1}|u_0'|^{p-1}u_0')' = s^{N-1}u_0^{p-1} \quad \forall \, s > r$$

with $u_0(R) = 0$ and $u_0(r) = 0$, moreover, by Proposition 3.3, we have

$$u_0'(s)^{p-1} = S_p(r)u_0(s)^{p-1} \quad \forall s > r.$$

Then

$$\frac{1}{2} |\nabla u_0|^{p-2} \frac{\partial |\nabla u_0|^2}{\partial \nu} + \frac{1}{p} \frac{\partial u_0^p}{\partial \nu} = \frac{S_p(r)^{\frac{1}{p-1}}}{p-1} \left(1 - \frac{N-1}{R} S_p(r) \right) + S_p(r)^{\frac{1}{p-1}}$$

and

$$S_p(r)[(q-1)|\nabla u_0|^2 + \Delta u_0] = (q-1)S_p(r)^{\frac{p+1}{p-1}} + \frac{S_p(r)^{\frac{1}{p-1}}}{p-1} \left(1 - \frac{N-1}{R}S_p(r)\right) + \frac{N-1}{R}S_p(r)^{\frac{p}{p-1}}.$$

Therefore

$$h''(0) = \frac{pS_p^{\frac{1}{p-1}}}{N|\partial B_R|^{\frac{p}{q}-1}} \left[1 - (q-1)S_p(r)^{\frac{p}{p-1}} - \frac{N-1}{R}S_p(r) \right].$$

Thus, if q > Q(R) we get that h''(0) < 0 and so 0 is a strict local maxima of ψ . So we have proved that

$$S_q(r) = h(0) > h(t) \ge S_q(B_r(te_1))$$

for all t small. Therefore a symmetric configuration is not optimal. \Box

To finish the paper we prove Proposition 1.5.

Proof of Proposition 1.5. We proceed in two steps.

Step 1. First we show that, for R > r, $S_p(R,r) = S_p(r)$ verifies the differential equation

$$\frac{\partial S_p}{\partial R} = -\frac{N-1}{R} S_p + 1 - (p-1) S_p^{\frac{p}{p-1}}$$
 (3.2)

with the condition

$$S_p|_{R=r} = +\infty.$$

Again we consider $u_0(x) = u_0(|x|)$ the non-negative radial function given by Proposition 3.3. Thus, for all R > r, we get

$$\begin{cases} (p-1)(u_0')^{p-2}u_0'' + \frac{N-1}{R}(u_0')^{p-1} = u_0^{p-1}, \\ u_0'(R)^{p-1} = S_p u_0(R)^{p-1}, \\ u_0(r) = 0. \end{cases}$$

Then

$$S_p = \left(\frac{u_0'(R)}{u_0(R)}\right)^{p-1}.$$

Thus

$$\begin{split} \frac{\partial S_p}{\partial R} &= (p-1) \left(\frac{u_0'(R)}{u_0(R)} \right)^{p-2} \frac{u_0''(R)u_0(R) - u_0'(R)^2}{u_0(R)^2} \\ &= (p-1) \left(\frac{u_0'(R)}{u_0(R)} \right)^{p-2} \frac{u_0''(R)}{u_0(R)} - (p-1)S_p^{\frac{p}{p-1}} \\ &= (p-1) \frac{u_0'(R)^{p-2}u_0''(R)}{u_0(R)^{p-1}} - (p-1)S_p^{\frac{p}{p-1}} \\ &= 1 - \frac{N-1}{R} S_p - (p-1)S_p^{\frac{p}{p-1}}. \end{split}$$

On the other hand, since (by definition) $\frac{\partial u_0}{\partial \nu} \equiv 1$ on ∂B_r , we get that u'(r) = 1. Then

$$\lim_{R \to r} S_p = \lim_{R \to r} \left(\frac{u_0'(R)}{u_0(R)} \right)^{p-1} = +\infty.$$

Now, it is easy to check that $\lim_{R\to r} Q(R) = 1^-$.

Step 2. Finally, we prove that

$$\lim_{R \to +\infty} Q(R) = p.$$

We begin differentiating (3.2) to obtain

$$\frac{\partial^2 S_p}{\partial R^2} = \frac{N-1}{R^2} S_p - \frac{N-1}{R} \frac{\partial S_p}{\partial R} - p S_p^{\frac{1}{p-1}} \frac{\partial S_p}{\partial R}.$$

Then, since $S_p > 0$, at any critical point $(S'_p = 0)$ we have that $S''_p > 0$. Thus, S_p has at most one critical point, which is a minimum. If S_p has a minimum, then there exist $R_0 > r$ such that $S'_p(R_0) = 0$. Moreover, since $S'_p(R) \neq 0$ for any $R \neq R_0$ and $S_p \to +\infty$ as $R \to r$ and by (3.2), we get that $S'_p < 0$ for all $r < R < R_0$ and $S'_p > 0$ for all $R > R_0$. Thus, using again (3.2) we have that $S_p^{\frac{p}{p-1}} < \frac{1}{p-1}$ for all $R > R_0$. Then S_p is strictly increasing as a function of R and bonded for all $R > R_0$. Consequently $S'_p \to 0$ as $R \to +\infty$. It follows, by (3.2), that $S_p^{\frac{p}{p-1}} \to \frac{1}{p-1}$ as $R \to +\infty$. On the other hand using (1.6) and (3.2) we see that

$$S_p = (Q(R) - p)S_p^{\frac{p}{p-1}}. (3.3)$$

So, if S_p has a minimum, we get that Q(R) > p for all $R > R_0$ and $Q(R) \to p^+$ as $R \to +\infty$. Now, If S_p has not critical points so $S'_p \neq 0$ for all R > r and using that $S_p \to +\infty$ as $R \to r$ and (3.2) we get that $S'_p < 0$ for all R > r. Consequently, in this case, S_p is strictly decreasing and therefore $S'_p \to 0$ as $R \to +\infty$ and by (3.2) we have that $S_p \to \frac{1}{p-1}$ as $R \to +\infty$. Then, if S_p has not critical points, we get Q(R) < p and $Q(R) \to p^-$ as $R \to +\infty$.

Acknowledgments

I would like to thank J. Fernández Bender for his throughout reading of the manuscript that helped me to improve the presentation of the paper and also to the reviewer for his remarks and suggestions. The author was supported by Universidad de Buenos Aires under grant X078, by ANPCyT PICT No. 2006-290 and CONICET (Argentina) PIP 5478/1438. Leandro M. Del Pezzo fellow of CONICET.

References

- W. Allegretto and Y. X. Huang, A Picone's identity for the p-Laplacian and applications, Nonlinear Anal. 32(7) (1998) 819–830.
- [2] J. Fernández Bonder, P. Groisman and J. D. Rossi, Optimization of the first Steklov eigenvalue in domains with holes: A shape derivative approach, Ann. Mat. Pura Appl. (4) 186(2) (2007) 341–358.
- [3] J. Fernández Bonder and J. D. Rossi, A nonlinear eigenvalue problem with indefinite weights related to the Sobolev trace embedding, *Publ. Mat.* **46**(1) (2002) 221–235.
- [4] J. García Melián and J. Sabina de Lis, On the perturbation of eigenvalues for the p-Laplacian, C. R. Acad. Sci. Paris Sér. I Math. 332(10) (2001) 893–898.
- [5] A. Henrot and M. Pierre, Optimization de Forme: Un Analyse Géométric, Mathematics and Applications, Vol. 48 (Springer-Verlag, 2005).
- [6] O. A. Ladyženskaja, V. A. Solonnikov and N. N. Ural'ceva, Linear and Quasilinear Equations of Parabolic Type, Translated from the Russian by S. Smith, Translations of Mathematical Monographs, Vol. 23 (American Mathematical Society, Providence, R.I., 1967).
- [7] E. J. Lami Dozo and O. Torné, Symmetry and symmetry breaking for minimizers in the trace inequality, Commun. Contemp. Math. 7(6) (2005) 727–746.
- [8] G. M. Lieberman, Boundary regularity for solutions of degenerate elliptic equations, Nonlinear Anal. 12(11) (1988) 1203–1219.
- [9] S. Martínez and J. D. Rossi, Isolation and simplicity for the first eigenvalue of the p-Laplacian with a nonlinear boundary condition, Abstr. Appl. Anal. 7(5) (2002) 287–293.
- [10] J. D. Roossi, First variations of the best Sobolev trace constant with respect to the domain, Math. Bull. Canad. 51(1) (2008) 140–145.
- [11] M. W. Steklov, Sur les problèmes fondamentaux en physique mathématique, Ann. Sci. Ecole Norm. Sup. 19 (1902) 445–490.
- [12] J. L. Vázquez, A strong maximum principle for some quasilinear elliptic equations, Appl. Math. Optim. 12(3) (1984) 191–202.