

## Research Article

# Time Coordination of Periodic Passenger Train Connections in Conditions of Single-Track Lines

Filip Lorenz,<sup>1</sup> Vit Janos,<sup>2</sup> Dusan Teichmann,<sup>2,3</sup> and Michal Dorda <sup>3</sup>

<sup>1</sup>Department of Control Systems and Instrumentation, Faculty of Mechanical Engineering, VSB–Technical University of Ostrava, 17. listopadu 2172/15, 708 00 Ostrava-Poruba, Czech Republic

<sup>2</sup>Department of Logistics and Management of Transport, Faculty of Transportation Sciences, CTU in Prague, Konviktska 20, 110 00 Prague, Czech Republic

<sup>3</sup>Institute of Transport, Faculty of Mechanical Engineering, VSB–Technical University of Ostrava, 17. listopadu 2172/15, 708 00 Ostrava-Poruba, Czech Republic

Correspondence should be addressed to Michal Dorda; [michal.dorda@vsb.cz](mailto:michal.dorda@vsb.cz)

Received 30 June 2020; Revised 12 January 2021; Accepted 6 February 2021; Published 9 March 2021

Academic Editor: Luca D'Acerno

Copyright © 2021 Filip Lorenz et al. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

The article addresses creation of a mathematical model for a real problem regarding time coordination of periodic train connections operated on single-track lines. The individual train connections are dispatched with a predefined tact, and their arrivals at and departures to predefined railway stations (transfer nodes) need to be coordinated one another. In addition, because the train connections are operated on single-track lines, trains that pass each other in a predefined railway stations must be also coordinated. To optimize the process, mathematical programming methods are used. The presented article includes a mathematical model of the given task, and the proposed model is tested with real data. The calculation experiments were implemented using optimization software Xpress-IVE.

## 1. Introduction: Motivation to Solve the Given Problem

The main objective of the transport processes in passenger transportation is to make them as short as possible. We need to start with an assumption than the moving time, for example, [1], is usually unproductive time. That is why we insist on making it as short as possible. This formulation is expressed by the following formula:

$$T = t_1 + t_w + t_t + t_{tr} + t_2, \quad (1)$$

where  $T$  is the total transport time (min),  $t_1$  is the walking time from the moving source to the given train stop (min),  $t_w$  is the waiting time for the train (min),  $t_t$  is the time spent on the train (transport time) (min),  $t_{tr}$  is the transfer time (including waiting time at the transfer nodes) (min), and  $t_2$  is the walking time from the train stop to the given moving destination (min).

As it is clear from the above-stated formula, one of the possibilities of how to shorten the total transport time is to minimize the waiting time for connections at the transfer nodes.

The motivation for solving the problem is to find an approach that would allow for a maximal transportation fluency by shortening the waiting times at the transfer nodes.

Time coordination of the transport processes is then based on the principle of proposing such time positions of the given connections that will allow for minimizing time losses of the passengers from the moment they board the first train on their transport route until the moment they get off the last connection on their way.

## 2. Analysis of the Current State of the Art

A thorough summary of coordination optimization models is provided in [2]. This relatively extensive work deals with multimodal transport networks, individual connections

(lines) of which meet in transfer terminals, which means that passengers transfer there from one line to another. The author claims that the main motivation for solving the issue is the necessity to make public transport more attractive for passengers by making the transfers among individual connections more efficient. The author approaches the topic in two ways:

- (i) Connection coordination by timetable modifications (Schedule Coordination)
- (ii) Connection coordination in real time (Connection Protection)

The work includes an optimization model for generating timetables and minimizing transfer times among individual connections. The objective of the model is to find an optimal timetable by shifting existing connections to a new time position and/or by delaying a given connection, i.e., waiting for a subsequent connection, thus minimizing the overall delay of both connections. The model considers waiting time of the transferring passengers as well as delay times of the people who use one of the two connections, but who do not transfer. The model has been validated by case studies and the positive results are demonstrated by concrete time savings. Furthermore, the author concludes that even if a timetable is modified based on the corresponding mathematical model output, it is still necessary to pay attention to the stochastic character of the transport, i.e., occurrence of extraordinary situations and delays, which disrupt the transfer relations. That is why the work also included development of a CP model (Connection Protection). The objective function of the model considers probability of the implementation of the transfer relations and optimizes expenses. This model is evaluated and compared with previous models with the objective to demonstrate it as a tool for improving the efficiency of the transfer relations and for reducing waiting times of the passengers.

Ciaffi et al. [3] focus on transfer relations between a secondary public transport network in the cities (primarily bus transport) and the main transport network (metro and railway). The objective is to develop a procedure that simultaneously generates routes and frequencies (time intervals) in the bus transport network, making sure it is applicable for solving problems of a size that corresponds to the extent of real cities.

Sun et al. [4] address classification of bus routes and their relations to the main transit (railway) transport. The objective of the proposed solution is to maximize the use of the transit (railway) routes by passengers and to optimize the existing bus lines from the perspective of their contribution to the given transit (railway) route. The article also presents an algorithm that is used for defining the relation between bus lines and main transit routes.

Authors of study [5] address coordination of the transfer relations among individual transit routes in real time. They realize the advantages of coordinated transfers, i.e., shortening of the passengers' waiting time, while also considering the risks of delays of the passengers who are on the given line, passengers who intend to travel on that line, and

accumulation of the transport means at the coordination nodes. In the first part of their study, the authors developed a dynamic management strategy, which is based on the given management theory and thanks to an optimal management strategy which was determined (delays of individual connections at the coordinated nodes). A maximal delay is thus determined by the estimates of arrivals of individual connections and passengers in real time and by uncertainty of these estimates.

Gkiotsalitis et al. [6] explore a robust coordination of connection times, including public transport, for the purpose of the given network coordination. The authors focus on analyzing the robustness of the synchronization results in two limit situations. The first limit situation occurs under standard operation conditions and the second limit situation under extreme operation conditions (extreme operation conditions are represented by significant disruptions of the planned timetable). The optimization approach proposed in their article is based on evolution algorithms. The authors execute the corresponding calculation experiments using real data obtained from the bus transport system in the city of Hague, Netherlands.

The objective of [7] was to identify individual bus connections and their mutual relations from the perspective of their competitiveness, complementarity, or independence. Next, the authors decided about time changes of individual bus connections, which were servicing a given unified area based on a calculation of the travel cost of the passengers, walking time, and waiting time related to each individual bus route. Furthermore, the authors explored passenger behavior when they choose suitable bus connections, and they incorporate the given survey results in their solution.

Omar and Yasmin [8] focus on the creation of timetables of the bus lines operated by several private bus companies in the city of Monterrey, Mexico. The following are the objectives of the study:

- (1) Preventing cumulation of bus connections of various bus lines in individual transfer nodes
- (2) Increasing potential transfer links

Based on the above-stated objectives, the authors developed a suitable model, which is able to fulfil the defined objectives.

The study carried out by Almasi et al. [9] looks into the timetable proposal of individual bus connections and their intensity, with the objective to conveniently interlink them with the railway transit system. The authors created an improved metaheuristic approach based on the Imperialist Competitive Algorithm and Water Cycle Algorithm. The optimization criterion here is the cost function, which includes expenses of the networks users, expenses related to the operation of technical equipment, and also social expenses, such as the cost of the network operation and cost related to the pollution caused by individual vehicles. The developed metaheuristic approach was tested on an actual network of the city of Petaling Jaya in Kuala Lumpur, Malaysia.

Wong et al. [10] present a proposal of a coordination of public transport timetables, which allow for smooth transfers with minimal delays for all passengers based on mixed-integer programming. The approach focuses on nonperiodic timetables. The authors tested the proposed approach in the conditions of the city railway transport in Hong Kong on a network that consisted of six railway lines and a significant number of transfer stations. The authors also explore the options of searching for compromises between waiting times and the operation parameters of a given public transport system.

Liu et al. [11] explore time coordination of metro train connections in southern China. The authors developed a heuristic approach based on the simulated annealing method. Only riding times among individual metro stops and the current timetable of the train connections were used for the needs of the developed heuristic approach. Using an experimental case, the authors found a solution with time savings for passengers and without an impact on the number of the operated trains and infrastructure changes.

The study carried out by Xiaopeng and Huimin [12] looks into a proposal of a timetable of train connections at a single transfer node using nonlinear integer programming. The optimization criterion was an exponential utility function. The developed mathematical model was tested on real input data.

Xueping et al. [13] explore the creation of transfer links between bus and train connections. In the first part of the research, the authors developed a mixed-integer nonlinear model, which ensures minimization of the number of unexecuted transfers between bus and train connections. In the second part of the research, the authors use integer linear programming for the creation of a timetable of bus connections.

Authors of article [14] focus on minimizing time losses of the passengers, caused by timetable reserves. Moreover, they also emphasize behavior of the passengers. Based on the above, the authors developed an integer, bi-objective, and bi-level mathematical model, functionality and effectiveness of which were tested on a small model network.

In [15], a mathematical programming method for the time coordination of public transport connections is used. The main contribution of the article is a proposal of optimization approaches that work with the dynamically changing demand for transfers. The authors of the article propose a nonlinear mixed-integer mathematical model amended by the heuristic method and a linear mixed-integer model for the coordination. The authors test both proposed approaches on a real metro line in Teheran, Iran.

To coordinate the given timetables, the classic heuristic method is used in [16]. The authors of the study particularly focus on the coordination of public transport connections in the networks with lines operated in a parallel way, which join in certain transfer hubs. A characteristic feature of the lines serviced in a parallel way is the fact that the travel times between two identical transfer hubs are different. The proposed heuristic method is tested not only on model networks but also in the conditions of a real bus transport network, which consists of 7 bus lines and 3 transfer hubs.

Authors of [17] explore maximization of the number of the current connection arrivals to a transfer hub, with the objective to minimize transfer waiting times and thus also the expenses related to the waiting of the transferring passengers. The intention is to propose the so-called robust timetables of individual connections, which allow for considering extraordinary situations along the given connection routes (traffic congestions, etc.). The instrument for increasing the robustness of the timetables is represented by the so-called slack times, which allow for incorporating sufficient times into the given transport times for eliminating the consequences of the corresponding extraordinary situations. The work includes a proposal of a stochastic optimization model. Its solution is implemented using the method of branches and limits and amended by a strategy that leads to an improved efficiency of the calculation procedure. The presented calculation experiments with the given proposed approach are implemented on model situations.

Authors of [18] propose a nonlinear optimization model that shortens the transfer waiting times by the means of timetable modifications. The study also includes a proposal of a heuristic approach based on the Tabu Search method. The proposed approach was tested on real data in the conditions of the city of Copenhagen, Denmark.

Authors of [19] explore the issue of synchronization of train day timetables, when significant changes in the demand of passengers occur. A nonlinear programming model is proposed for the optimization. The actual solution utilizes metaheuristics based on the particle swarm, combined with the simulated annealing method. The case study from the real world explores the situation in the conditions of the metro system in Beijing, China.

Technical literature often uses optimization approaches based on genetic algorithms for time coordination of individual connections in transfer hubs.

Jiaqing et al. [20] analyze coordination of the time schedule between fast transit bus connections (buses and frequency of stops of which is lower than of the city public transportation buses, which have a dedicated traffic lane available to them) and other related bus connections of the city public transportation in Beijing. The authors analyze coordination of these systems from the perspective of being increasingly used by passengers and their negative impacts on the integrated public transportation when the degree of coordination is low. The first part of the article focuses on the study of operation characteristics and determines an optimization criterion, which is represented by the total cost of the operation of the given systems. When doing so, the authors also consider the overall transportation time of the passengers.

In the next part of the study, the authors create a coordinated operation model. The last part of the work is devoted to the creation of a genetic algorithm and its application on the analyzed coordinated operation, with the objective to optimize the values of the specified criteria.

Two results were obtained by the application of the abovementioned algorithm:

- (1) The total cost related to the operation of the coordinated systems was reduced based on the coordination of individual timetables
- (2) The total waiting time of the passengers was reduced based on the coordination of fast transit buses and city public transportation buses

Dissertation [21] explores time coordination of bus connections using genetic algorithms in combination with the Monte Carlo method. The proposed genetic algorithm must be tested on real input data, thus demonstrating its functionality. A disadvantage of the genetic algorithm is a long calculation time for solving the task.

Authors of [22] explore the creation of a train transportation timetable based on a genetic algorithm. While developing the given mathematical model, they also took into account the corresponding infrastructure elements and used railway cars. The final genetic algorithm was tested on model data. The achieved results seemed very satisfactory considering the problem complexity. Almost optimal results were achieved in a very short time.

Authors of [23] combine genetic algorithms with another heuristic method. The authors focus on minimizing the waiting times in periodically serviced public transport networks. They use a two-stage approach for their solution. The optimization criterion is the waiting time. The first stage of the solution is based on the principles on a manual construction of timetables, using the greedy algorithm. The result of the first stage is an initial solution. As a part of the second stage, possibilities of its improvement are tested using genetic algorithms. The calculation experiments were applied to a real railway network of German railway lines serviced by long-distance and important regional trains.

In [24], genetic algorithms for optimizing the transfer relations in metropolitan networks of individual lines are also used. As a part of the optimization approach, the authors of the article use the summation of the transfer waiting time for all pairs of lines and all stations as a criterion. The authors applied the proposed approach on a network of bus lines in the city of Mashhad, Iran. The network is serviced by 139 two-way bus lines and 278 one-way lines. The network incorporates 3,618 bus stops, 841 of which are transfer stops.

Moreover, genetic algorithms in the conditions of public transport are also used by authors of [25], who explore solutions of the coordination problem of individual lines, for which irregular travel times among individual stops are expected. The objective is to minimize the total waiting time cost for three types of passengers (i.e., transferring passengers, boarding passengers, and through passengers). The authors publish a stochastic integer linear model, amended by an approach based on genetic algorithms, utilizing classic operators and the local search strategy. The authors implement the calculation experiments for verifying the effectivity of the proposed optimization model on ten types of randomly selected, generated instances of practical environments.

The topic of the abovementioned study is further explored in [26]. The authors present a two-criterial mathematical model that can be used for modifying timetables,

implemented with the objective to improve transfer fluency. As a part of the first criterion, the number of passengers who experience fluent transfers is maximized. As a part of the second criterion, the maximal deviations of the new connection times from the existing connection times are minimized. Genetic algorithms are used again for the actual practical solutions. Functionality and effectiveness of the approach are validated on a real network serviced by seven lines, which included three transfer hubs.

The potential of genetic algorithms is also utilized in publication [27]. The article explores a proposal of an optimization approach for the public transport system with variable demand during the planned period. The optimization approach allows for considering symmetric timetables. The optimization criterion is the total waiting time of the passengers, transferring in all directions. The optimization approach is verified in the conditions of a transfer hub in the city of Beijing, China.

Yin et al. [28] explore the issue of a synchronization of timetables in the conditions of the metro transport system in Beijing, utilizing genetic algorithms. The optimization process focuses on the synchronization of the time positions of the last night train connections. Corresponding weights are assigned to individual connections. The connections running from the city center are assigned higher weights than the connections running to the city center. The presented solution also takes into account the amount of the operation expenses related to the last night trains and the subsidies provided to the metro operator. The actual synchronization of the timetables is implemented simultaneously in 17 transfer hubs.

The available analyzed results obviously address the topic from various points of view and from the perspective of individual transport types (passenger transport and cargo transport), as well as the interaction between individual transport modes (railway transport-road transport, bus transport-tram transport, bus transport-bus transport, city bus transport-long-distance bus transport, etc.). Time coordination is conducted in a sectional, point, or multipoint manner at the network locations.

From the perspective of individual approaches, the authors use exact as well as heuristic (and especially metaheuristic) methods.

The below proposed procedure will thus be particularly linked to works [2, 8, 12]. It will develop the issue of a network coordination (i.e., time coordination at multiple locations simultaneously) based on exact tools among the connections of several transportation companies. Furthermore, the specifics of a single-track operation, which is particularly common for regional networks around the entire world, will be also taken into account.

### 3. Mathematical Model Proposal

In this section, we will propose a linear mathematical model for optimizing the timetable implemented for the single-track railway route in question. It will represent a coordination task with a compact part of a railway network, in which time changes of the trains that service the network will be possible to make (hereinafter referred to as the “network

in question”). The network in question will be connected to other parts of the railway network via a defined set of nodes. At the connection locations (nodes), passengers will transfer between the train connections that service the network in question and other train connections, which will be marked by the names of the train connections of the given external transportation providers. Apart from that, there will also be transfer nodes inside of the network in question. The objective will be to propose such time positions of individual train connections that service the network in question, which will ensure that the overall time losses of the transfer passengers are minimal.

**3.1. Problem Formulation.** The  $K$  set of nodes is defined in the transport network in question. Passenger transfers are planned at these nodes. Moreover, the  $D$  set of nodes, at which passing of trains can occur, is also defined. The  $K$  node set consists of two subsets marked as  $K^G$  and  $K^C$ , for which it holds that  $K = K^G \cup K^C$  and, at the same time,  $K^G \cap K^C = \emptyset$ . Subset  $K^C$  is a subset of transfer nodes, in which passengers transfer between train connections of the transportation provider that services the railway network in question and train connections of other railway transportation providers (transfer nodes, by the means of which the network in question is connected to other railway networks of the given country). Subset  $K^G$  is a subset of transfer nodes inside of the network in question, in which passengers transfer between train connections of the railway transportation provider that services the network in question.

Apart from that, the  $K^V$  set of initial nodes of train connections, which are operated by the railway carrier on the railway network, is defined. It applies that an initial node can belong to set  $K^G$  or  $K^C$ , or it does not have to belong to any of these sets.

The minimal necessary transfer time  $t_k^{tr}$  that includes exit of the passenger from the given train, his/her transfer to the platform of the connecting train, and his/her boarding of this connecting train is defined for each transfer node  $k \in K$ . For each transfer node  $k \in K$ , the  $S_k$  set of train directions passengers transfer to is given. The  $J_{sk}$  set of departing connections is defined for each direction  $s \in S_k$ .

For each node  $k \in K^C$ , the  $I_k^{CA}$  set of train connections of external transport providers is defined. In addition, for each node  $k \in K^C$ , the set  $I_k^P$  of train connections entering the node from the network being optimized is given. It holds for the set of transfer nodes  $k \in K^C$  that if  $i \in I_k^{CA}$  and  $j \in J_{sk}$ , where  $s \in S_k$ , then  $|S_k| = 1$ . If it holds that  $i \in I_k^P$  and  $j \in J_{sk}$ , then  $|S_k| \geq 1$ .

For each node  $k \in K^G$ , set of train connections  $I_k^P$ , which arrive to this node, is defined. There is a set of train connections  $I^{GW}$  operated, within the given network, and a set of connections, with which these connections, are coordinated at the outer nodes of the railway network in question  $I^{CA}$ .

For each train connection  $i \in I^{GW}$ , the  $K_i$  set of nodes is defined. These nodes will be used by passengers for transfer from the given train connection. Moreover, another set of nodes  $D_i$  is also defined. In these nodes, the

given train connection can pass a train connection from the opposite direction. The earliest possible departure time of a train connection from initial node  $T_i^{\text{dep}}$ , trip time from the initial node to transfer node  $k \in K_i$  marked as  $t_{ik}$ , and trip time from the initial node to node  $d \in D_i$  ( $\cup_{i \in I^{GW}} D_i = D$ ) with possible passing, marked as  $\tau_{id}$ , are also defined.

For each train connection  $i \in I^{GW}$ , maximal permitted change  $N$  is defined in relation to the earliest possible time position of the given train connection (it is constant for all train connections). Train connections within set  $I^{GW}$  in individual directions run in regular intervals, which we mark by the symbol  $INT$ .

For each train connection of an external transportation provider  $i \in I_k^{CA}$ , we know the time of its arrival to node  $k \in K^C$  and the time of its departure from node  $k \in K^C$  (for simplification purposes, we consider the arrival time to node  $k \in K^C$  and the departure time from node  $k \in K^C$  to be identical). The values of the maximal permitted time changes for all connections from set  $I^{CA}$  are equal to zero.

The objective is to determine departure and arrival time changes at the coordination nodes, making sure the time loss of the transferring passengers is as minimal as possible.

**3.2. Mathematical Model Proposal.** First, we specify the earliest possible departure times of the train connections from the initial nodes. It is required that train connections  $I^{GW}$  run in a predefined cycle. In order to make the modelling easier, connections departing in the same directions from individual initial nodes will be grouped together.

If we mark the number of connections leaving from initial node  $k \in K^V$  as  $n_k$ , then the earliest possible departure times of connections  $j = 1, 2, \dots, n_k$  from the initial node (marked with index 1) can be calculated pursuant to the following formula:

$$T_j^{\text{dep}} = T_1^{\text{dep}} + (j - 1) \cdot \text{INT}, \quad (2)$$

and the earliest possible departure times of connections  $j = 1, 2, \dots, n_k$  from node  $k \in K^V \setminus \{1\}$  will be calculated pursuant to the following formula:

$$T_{(n_0 + \dots + n_{k-1} + j)}^{\text{dep}} = T_{(n_0 + \dots + n_{k-1} + 1)}^{\text{dep}} + (j - 1) \cdot \text{INT}, \quad (3)$$

where  $T_{(n_0 + \dots + n_{k-1} + j)}^{\text{dep}}$  is the earliest possible departure time of train connection  $j = 1, 2, \dots, n_k$  from initial node  $k \in K^V$ ,  $T_{(n_0 + \dots + n_{k-1} + 1)}^{\text{dep}}$  is the earliest possible departure time of the 1st train connection from initial node  $k \in K^V$ , and  $\text{INT}$  is the defined value of the interval between departing train connections.

For initial nodes of train connections heading in multiple directions, individual train connections can be grouped pursuant to individual directions.

In order to define the set of train connections that can pass one another in the opposite directions, incidence matrix  $A$  was established. When passing of trains  $i \in I^{GW}$  and  $j \in I^{GW}$  is possible, then  $a_{ij} = 1$ , if not, then  $a_{ij} = 0$ .

Table 1 presents a summary of notation used in the mathematical model.

The mathematical model will then have the following :

$$\begin{aligned}
\min f(x, z, h, m, q) = & \sum_{i \in I_k^P} \sum_{j \in J_{sk}} \sum_{s \in S_k} \sum_{k \in K^C} h_{ijsk} f_{ijsk} \\
& + \sum_{i \in I_k^{CA}} \sum_{j \in J_{sk}} \sum_{s \in S_k} \sum_{k \in K^C} h_{ijsk} f_{ijsk} + \\
& + \sum_{i \in I_k^P} \sum_{j \in J_{sk}} \sum_{s \in S_k} \sum_{k \in K^G} h_{ijsk} f_{ijsk} \\
& + \sum_{i \in I^{GW}} \sum_{j \in J_{sk}} \sum_{d \in D} a_{ij} q_{ijd}
\end{aligned} \tag{4}$$

subject to

$$\begin{aligned}
(T_j^{\text{dep}} + x_j) - (T_i^{\text{dep}} + t_k^{\text{tr}}) \\
\geq M(z_{ijsk} - 1), \quad \text{for } i \in I_k^{CA}, j \in J_{sk}, k \in K^C, s \in S_k,
\end{aligned} \tag{5}$$

$$\begin{aligned}
(T_j^{\text{dep}} + x_j) - (T_i^{\text{dep}} + t_k^{\text{tr}}) \leq h_{ijsk} \\
+ M(1 - z_{ijsk}), \quad \text{for } i \in I_k^{CA}, j \in J_{sk}, k \in K^C, s \in S_k,
\end{aligned} \tag{6}$$

$$\sum_{j \in J_{sk}} z_{ijsk} = 1, \quad \text{for } i \in I_k^{CA}, k \in K^C, s \in S_k^G, \tag{7}$$

$$\begin{aligned}
T_j^{\text{dep}} - (T_i^{\text{dep}} + t_{ik} + x_i + t_k^{\text{tr}}) \\
\geq M(z_{ijsk} - 1), \quad \text{for } i \in I_k^P, j \in J_{sk}, k \in K^C, s \in S_k,
\end{aligned} \tag{8}$$

$$\begin{aligned}
T_j^{\text{dep}} - (T_i^{\text{dep}} + t_{ik} + x_i + t_k^{\text{tr}}) \leq h_{ijsk} \\
+ M(1 - z_{ijsk}), \quad \text{for } i \in I_k^P, j \in J_{sk}, k \in K^C, s \in S_k,
\end{aligned} \tag{9}$$

$$\sum_{j \in J_{sk}} z_{ijsk} = 1, \quad \text{for } i \in I_k^P, k \in K^C, s \in S_k^{CA}, \tag{10}$$

$$\begin{aligned}
(T_j^{\text{dep}} + t_{jk} + x_j) - (T_i^{\text{dep}} + t_{ik} + x_i + t_k^{\text{tr}}) \\
\geq M(z_{ijsk} - 1), \quad \text{for } i \in I_k^P, j \in J_{sk}, k \in K^G, s \in S_k,
\end{aligned} \tag{11}$$

$$\begin{aligned}
(T_j^{\text{dep}} + t_{jk} + x_j) - (T_i^{\text{dep}} + t_{ik} + x_i + t_k^{\text{tr}}) \leq h_{ijsk} \\
+ M(1 - z_{ijsk}), \quad \text{for } i \in I_k^P, j \in J_{sk}, k \in K^G, s \in S_k,
\end{aligned} \tag{12}$$

$$\sum_{j \in J_{sk}} z_{ijsk} = 1, \quad \text{for } i \in I_k^P, k \in K^G, s \in S_k, \tag{13}$$

$$\begin{aligned}
(T_j^{\text{dep}} + \tau_{jd} + x_j) - (T_i^{\text{dep}} + \tau_{id} + x_i) \\
\geq M(m_{ijd} - 1), \quad \text{for } i \in I^{GW}, j \in I^{GW}, a_{ij} = 1, d \in D,
\end{aligned} \tag{14}$$

$$\begin{aligned}
(T_j^{\text{dep}} + \tau_{jd} + x_j) - (T_i^{\text{dep}} + \tau_{id} + x_i) \leq q_{ijd} \\
+ M(1 - m_{ijd}), \quad \text{for } i \in I^{GW}, j \in I^{GW}, a_{ij} = 1, d \in D,
\end{aligned} \tag{15}$$

$$\sum_{d \in D} m_{ijd} = 1, \quad \text{for } i \in I^{GW}, j \in I^{GW}, a_{ij} = 1, \tag{16}$$

$$x_i \leq N, \quad \text{for } i \in I^{GW}, \tag{17}$$

$$x_i \in R_0^+, \quad \text{for } i \in I^{GW}, \tag{18}$$

$$\begin{aligned}
h_{ijsk} \in R_0^+, \quad \text{for } i \in I_k^{CA}, j \in J_{sk}, k \in K^C, s \in S_k \\
\text{and, } i \in I_k^P, j \in J_{sk}, k \in K^C, s \in S_k \text{ and,} \\
i \in I_k^P, j \in J_{sk}, k \in K^G, s \in S_k,
\end{aligned} \tag{19}$$

$$q_{ijd} \in R_0^+, \quad \text{for } i \in I^{GW}, j \in I^{GW}, a_{ij} = 1, d \in D, \tag{20}$$

$$\begin{aligned}
z_{ijsk} \in \{0, 1\}, \quad \text{for } i \in I_k^{CA}, j \in J_{sk}, k \in K^C, s \in S_k \text{ and,} \\
i \in I_k^P, j \in J_{sk}, k \in K^C, s \in S_k \text{ and,} \\
i \in I_k^P, j \in J_{sk}, k \in K^G, s \in S_k,
\end{aligned} \tag{21}$$

$$m_{ijd} \in \{0, 1\}, \quad \text{for } i \in I^{GW}, j \in I^{GW}, a_{ij} = 1, d \in D. \tag{22}$$

Function (4) represents an optimization criterion of the overall time loss arising from the creation of the transfer relations between individual train connections and the overall time loss arising from passing of train connections running in the opposite directions. Constraints (5), (8), and (11) ensure that if it is not possible to link an arriving train connection to a departing train connection at the given node, no transfer relation is formed between these train connections. Constraints (6), (9), and (12) ensure that when a transfer relation between two train connections is formed, the corresponding time loss is incorporated in the given function. Constraints in pairs (5) and (6), (8) and (9), and (11) and (12) represent the so-called constraints of the "either-or" type, which means that only one of the stated constraints is always active. Constraints (7), (10), and (13) ensure that each arriving train connection is assigned precisely to one connecting connection for each direction of transfer. Constraints (14) and (16) ensure that if passing can be implemented at a suitable node for the given train connections running in opposite directions, this passing is implemented and the time loss arising from waiting for the train connection running in the opposite direction will be

TABLE 1: Summary of mathematical model notation.

Symbol	Meaning	Unit
$A$	The incidence matrix representing whether train connections from the set $I^{GW}$ can pass one another in the opposite directions or not	
$a_{ij}$	The element of the incidence matrix $A$ ; when passing of trains $i \in I^{GW}$ and $j \in I^{GW}$ is possible, then $a_{ij} = 1$ , if not, then $a_{ij} = 0$	
$D$	The set of nodes where passing train connections from the set $I^{GW}$ one another is possible	
$D_i$	The set of nodes where passing the train connection $i \in I^{GW}$ with the train connection in the opposite direction is possible	
$f_{ijsk}$	Volume of the transfer passengers who arrived to coordination node $k \in K$ by train connection $i \in I_k^P \cup I_k^{CA}$ and who are transferring to train connection $j \in J_{sk}$ that is departing in direction $s \in S_k$	
$h_{ijsk}$	Nonnegative variable that models the time loss of passengers who are transferring in transfer node $k \in K^G$ from train connection $i \in I_k^P \cup I_k^{CA}$ to train connection $j \in J_{sk}$ that is departing in direction $s \in S_k$	(min)
$I_k^P$	Set of train connections arriving to node $k \in K$	
$I^{GW}$	Set of train connections operated within the network in question	
$I^{CA}$	Set of train connections, with which connection included in $I^{GW}$ are coordinated in the set of nodes $K^C$	
$I_k^{CA}$	Set of train connections of external transportation providers that service node $k \in K$	
$J_{sk}$	Set of train connections departing from node $k \in K$ in direction $s \in S_k$	
$K$	Set of nodes, in which transfer of passengers among train connections are planned	
$K^C$	Subset of transfer nodes of set $K$ , in which transfers of passengers between train connections of the transportation provider in question and train connections of external transportation providers are planned	
$K^G$	Subset of transfer nodes of set $K$ , in which transfers of passengers among train connections of the transportation provider in question are planned	
$K^V$	Set of the initial nodes of individual train connections	
$K_i$	Set of nodes, in which passengers will transfer from train connection $i \in I^{GW}$	
$m_{ijd}$	Binary variable that models the passing plan of the train connections coming from opposite directions $i \in I^{GW}$ and $j \in I^{GW}$ ; $a_{ij} = 1$ in node $d \in D$	
$N$	Maximal permitted change of individual train connections	(min)
$n_k$	Number of train connections leaving from initial node $k \in I^{GW}$	
$q_{ijd}$	Nonnegative variable that models the time loss incurred due to two train connections passing each other in the opposite direction $i \in I^{GW}$ and $j \in I^{GW}$ ; $a_{ij} = 1$ in node $d \in D$	
$R_0^+$	Set of nonnegative numbers	
$S_k$	Set of the directions, in which individual train connections leave from transfer node $k \in K$	
INT	Regular time interval among connections that service the routes within the network in question	(min)
$T_i^{dep}$	Earliest possible departure time of train connection $i \in I^{GW}$ from its initial node	(min)
$t_k^{tr}$	Transfer time for node $k \in K$	(min)
$t_{ik}$	Trip time of train connection $i \in I^{GW}$ from its initial node to transfer node $k \in K_i$	(min)
$x_i$	Nonnegative variable that models the time change of the departure of train connection $i \in I$ from the initial node	(min)
$z_{ijsk}$	Binary variable that models the origin of a transfer relation between train connection $i \in I_k^P \cup I_k^{CA}$ and train connection $j \in J_{sk}$ that departs in direction $s \in S_k$ in node $k \in K$	
$\tau_{id}$	Trip time of train connection $i \in I^{GW}$ from the initial node to node $d \in D_i$	(min)

included into the value of the optimization criterion. Constraint (16) ensures that one node suitable for passing will be determined for each pair of the train connections running in opposite directions, provided passing is required for this pair of the train connections (this fact is given by the incidence matrix). Constraint (17) defines the maximal possible time change of the corresponding train connections. Constraints (18)–(22) specify domains of definition of the variables used in the model.

#### 4. Calculation Experiments with Proposed Model: Case Study

The given coordination problem is solved within the frame of a real railway network in the South Bohemian Region in the Czech Republic, see Figures 1 and 2.

The actual railway network is formed by three railway routes, numbered 194 (Ceske Budejovice-Nove Udoli), 197 (Cicenice-Nove Udoli), and 198 (Strakonice-Volary).

Route number 194 starts at the Ceske Budejovice train station, passes through Cesky Krumlov, and ends in Cerny Kriz. Some trains that run along this line continue all the way to Nove Udoli.

Route number 197 starts at the Cicenice train station, passes through Prachatice, Volary, and Cerny Kriz, and ends in Nove Udoli.

The last route, number 198, starts at the Strakonice train station, passes through Vimperk, and ends in Volary.

The explored railway network is shown on Figure 3.

It is a single-track railway network. All its routes are serviced by GWTR, a railway transportation provider. Time changes of the connections of this transportation provider can be adopted. The network is connected to other railway routes and serviced by other (external) transportation providers, at the Ceske Budejovice, Cicenice, and Strakonice train stations. Time changes of the connections of external transportation providers are not possible (due to, for example, establishing transfer connections in other transfer nodes, which do not form a subject of the coordination process).



FIGURE 1: Position of the Czech Republic in Europe [29].

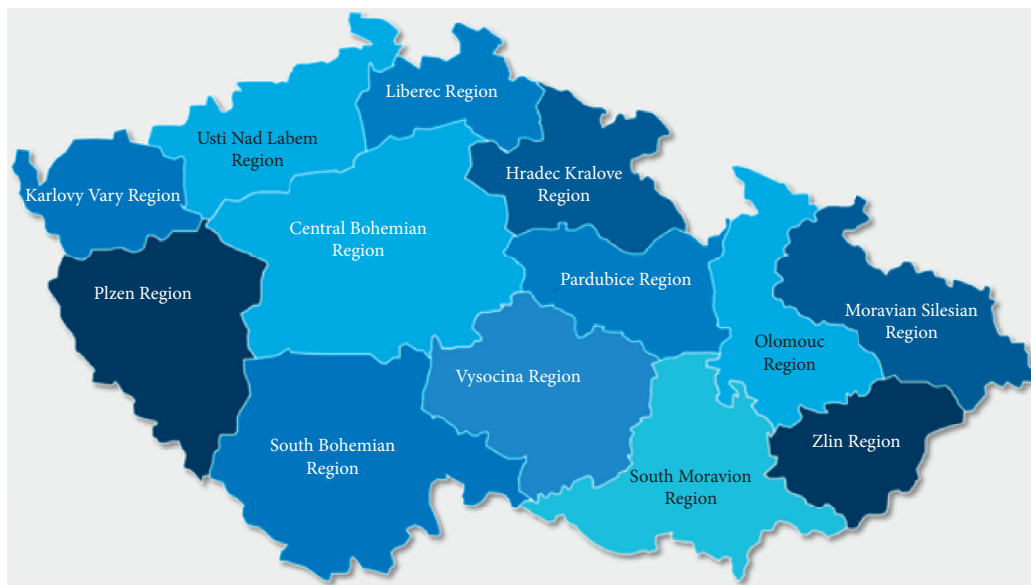


FIGURE 2: Position of the South Bohemian region in the Czech Republic [30].

Because all railway lines of the network in question are single-track, passing of trains going in opposite directions thus have to be ensured at intermediate railway stations.

Figure 3 shows directions, to which train connection time changes can be implemented. These connections are marked purple, yellow, and green. Directions, to which such time changes cannot be implemented, are the orange and blue directions. The orange and blue directions in Figure 3 represent transfers among connections of railway carrier GETR and connections of external transport providers. The purple directions in Figure 3 represent transfers among train lines on route number 198 (Strakonice-Volary). The yellow directions represent transfers among train lines on route number 197 (Cicenice-Nove Udoli) and the green directions represent transfers among train lines on routes 194 and 197 (Ceske Budejovice-Nove Udoli and Cicenice-Nove Udoli).

From the perspective of functions, there are two types of nodes (train stations) in the network. The first type is

represented by nodes where train connections are coordinated (passengers can transfer there). The other type is represented by nodes, in which passing of individual train connections occurs (trains that run in opposite directions meet at these nodes). Some nodes have both functions, i.e., passengers transfer there and passing of train running in opposite directions occurs there as well. A list of all nodes pursuant to individual types is attached below.

Nodes, at which train connections are coordinated:

Strakonice, Cicenice, Ceske Budejovice, Volary, and Cerny Kriz.

Nodes, at which passing of train connections occur:

Strunkovice n. Vol., Ckyne, Bohumilice v C., Vimperk, Lenora, Vodnany, Bavorov, Strunkovice nad Blanici, Prachatice, Chroboly, Zbytiny, Volary, Cerny Kriz, Borsov nad Vltavou, Kremze, Zlata Koruna,



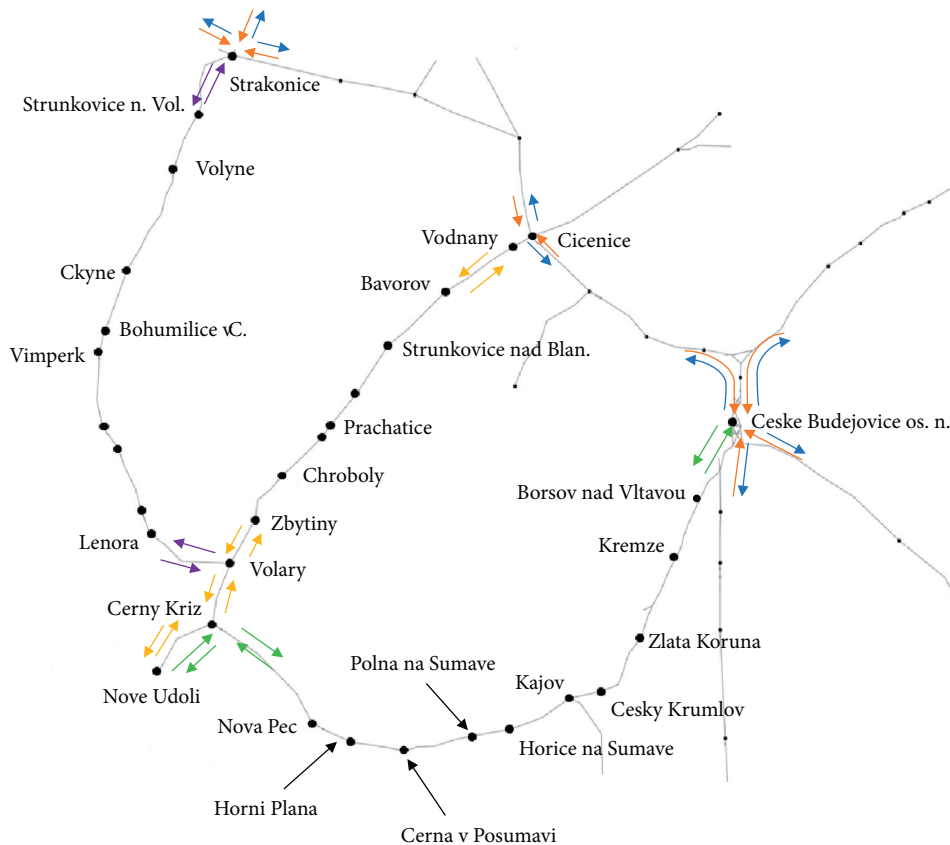


FIGURE 3: The railway network in question with transfer links.

Cesky Krumlov, Kajov, Horice na Sumave, Polna na Sumave, Cerna v Posumavi, Horni Plana, and Nova Pec.

Operation at the characterized railway network is periodical. Train connections along all routes in question are operated in both directions in the same interval. It is required for the planned schedule that individual train connections depart the corresponding initial train station in a 2-hour cycle.

In case of the presented case study, the model considers a total of 38 periodic train connections, time positions of which can be changed. Furthermore, the model also considers a total of 299 train connections for which it holds that their time positions cannot be changed.

The number of the train connections arriving to the Ceske Budejovice train station amounts to 70, while for the Cicenice train station the number is 43 and for the Strakonice train station 30. In this case, the directions, from which these train connections arrive, are not considered since the model ensures that exactly one transfer relation to a departing connection is created for each of the above-mentioned train connection.

However, such a simplification cannot be applied to departing connections since the departing direction, in which the given connection is departing, must be also considered for every departing connection. The total number of the train connections departing from the Ceske

Budejovice train station amounts to 70. Their directional structure is as follows: 10 connections depart in the direction of Horni Dvoriste, 8 connections depart in the direction of Ceske Velenice, 27 connections depart in the direction of Veseli nad Luznici, and 25 connections depart in the direction of Cicenice. The total number of the train connections departing from the Strakonice train station is 35. Their directional structure is as follows: 19 connections depart in the direction of Razice, 8 connections depart in the direction of Horazdovice, and 8 connections depart in the direction of Blatna. The total number of the train connections departing from the Cicenice train station is 51. Their directional structure is as follows: 26 connections depart in the direction of Protivin and 25 connections depart in the direction of Divcice.

Train connections for which it holds that their time positions can be changed are divided in the following manner. The route Ceske Budejovice-Nove Udoli has a total of 12 starting train connections (the Ceske Budejovice train station is the initial node for 6 of them, while the Nove Udoli train station is the initial node for the remaining 6 train connections).

The route Cicenice-Nove Udoli has a total of 14 starting train connections (the Cicenice train station is the initial node for 7 of them, while the Nove Udoli train station is the initial node for the remaining 7 train connections).

TABLE 2: Travel time for the Ceske Budejovice-Nove Udoli route.

Coordination node suitable for passing- $D$	Travel time from Ceske Budejovice in the direction of Nove Udoli (hh:mm)- $\tau_{id}$	Travel time from Ceske Budejovice in the direction of Nove Udoli (mm)- $\tau_{id}$	Travel time from Nove Udoli in the direction of Ceske Budejovice (hh:mm)- $\tau_{id}$	Travel time from Nove Udoli in the direction of Ceske Budejovice (mm)- $\tau_{id}$
Ceske Budejovice	0:00	0	2:21	141
Borsov nad Vltavou	0:09	9	2:09	129
Kremze	0:23	23	1:55	115
Zlata Koruna	0:36	36	1:42	102
Ceský Krumlov	0:52	52	1:31	91
Kajov	1:00	60	1:20	80
Horice na Sumave	1:14	74	1:06	66
Polna na Sumave	1:24	84	0:56	56
Cerna v Posumavi	1:38	98	0:42	42
Horni Plana	1:50	110	0:35	35
Nová Pec	1:59	119	0:23	23
Cerny Kriz	2:17	137	0:05	5
Nove Udoli	2:28	148	0:00	0

TABLE 3: Travel time for the Cicenice-Nove Udoli route.

Coordination node suitable for passing- $D$	Travel time from Cicenice in the direction of Nove Udoli (hh:mm)- $\tau_{id}$	Travel time from Cicenice in the direction of Nove Udoli (mm)- $\tau_{id}$	Travel time from Nove Udoli in the direction of Cicenice (hh:mm)- $\tau_{id}$	Travel time from Nove Udoli in the direction of Cicenice (mm)- $\tau_{id}$
Cicenice	0:00	0	2:04	124
Vodnany	0:07	7	1:58	118
Bavorov	0:22	22	1:45	105
Strunkovice nad Blanici	0:32	32	1:33	93
Prachatice	0:55	55	1:20	80
Chroboly	1:08	68	1:01	61
Zbytiny	1:23	83	0:47	47
Volary	1:47	107	0:30	30
Cerny Kriz	1:56	116	0:12	12
Nove Udoli	2:07	127	0:00	0

TABLE 4: Strakonice-Volary travel times.

Coordination node suitable for passing- $D$	Travel time from Strakonice in the direction of Volary (hh:mm)- $\tau_{id}$	Travel time from Strakonice in the direction of Volary (mm)- $\tau_{id}$	Travel time from Volary in the direction of Strakonice (hh:mm)- $\tau_{id}$	Travel time from Volary in the direction of Strakonice (mm)- $\tau_{id}$
Strakonice	0:00	0	1:53	113
Strunkovice nad Volynkou	0:11	11	1:41	101
Ckyne	0:37	37	1:15	75
Bohumilice v Cechach	0:43	43	1:08	68
Vimperk	0:53	53	1:00	60
Lenora	1:37	97	0:15	15
Volary	1:42	102	0:00	0

The route Strakonice-Volary has a total of 12 starting train connections (Strakonice train station is the initial node for 6 of them, while the Volary train station is the initial node for the remaining 6 train connections).

The initial time positions of the train connections related to individual coordination nodes and to individual nodes, at which trains running in the opposite directions can pass one another (see Tables 2–4), represent necessary input data. Yet other input data are formed by the earliest possible time

positions of the departures of individual train connections (see Tables 5–8). Other input data include the volumes of the transfer passengers for individual coordination nodes (see Table 9). The transfer time defined for individual nodes amounts to 3 minutes.

For the train connections running in opposite directions that serve routes 194, 197, and 198, passing must be implemented at the given intermediate stations. The necessity to solve passing of trains running in opposite

TABLE 5: Earliest possible arrival times of the train connections to the Ceske Budejovice, Cicenice, and Strakonice coordination nodes, train connections for which no time changes are possible, belonging to set  $I_k^{CA}$ .

Arrival time at Ceske Budejovice (hh : mm)	Arrival time at Ceske Budejovice (mm)	Arrival time at Strakonice (hh : mm)	Arrival time at Strakonice (mm)	Arrival time at Cicenice (hh : mm)	Arrival time at Cicenice (mm)
7 : 50	470	8 : 51	531	8 : 18	498
7 : 51	471	9 : 05	545	8 : 25	505
7 : 54	474	9 : 50	590	8 : 42	522
7 : 56	476	10 : 32	632	9 : 10	550
8 : 02	482	10 : 45	645	9 : 32	572
8 : 05	485	10 : 51	651	9 : 39	579
8 : 30	510	11 : 05	665	10 : 18	618
8 : 41	521	11 : 50	710	10 : 25	625
8 : 45	525	12 : 32	752	10 : 39	639
8 : 51	531	12 : 45	765	10 : 41	641
8 : 52	532	12 : 51	771	11 : 00	660
8 : 58	538	13 : 05	785	11 : 10	670
9 : 11	551	13 : 21	801	11 : 32	692
9 : 49	589	13 : 50	830	11 : 39	699
9 : 54	594	14 : 32	872	12 : 18	738
9 : 56	596	14 : 45	885	12 : 25	745
9 : 58	598	14 : 51	891	12 : 39	759
10 : 02	602	15 : 05	905	12 : 41	761
10 : 41	641	15 : 45	945	13 : 00	780
10 : 48	648	15 : 47	947	13 : 10	790
10 : 51	651	16 : 18	978	13 : 32	812
11 : 02	662	16 : 32	992	13 : 35	815
11 : 09	669	16 : 50	1010	14 : 18	858
11 : 29	689	16 : 51	1011	14 : 25	865
11 : 49	709	17 : 04	1024	14 : 39	879
11 : 51	711	17 : 05	1025	14 : 41	881
11 : 54	714	17 : 48	1068	15 : 00	900
11 : 56	716	18 : 32	1112	15 : 09	909
11 : 57	717	18 : 45	1125	15 : 32	932
12 : 02	722	18 : 51	1131	15 : 35	935
12 : 41	761			16 : 18	978
12 : 45	765			16 : 25	985
12 : 51	771			16 : 40	1000
12 : 57	777			16 : 41	1001
13 : 09	789			17 : 15	1035
13 : 27	807			17 : 17	1037
13 : 49	829			17 : 32	1052
13 : 52	832			17 : 35	1055
13 : 54	834			18 : 18	1098
13 : 56	836			18 : 25	1105
14 : 02	842			18 : 40	1120
14 : 41	881			18 : 41	1121
14 : 44	884			19 : 10	1150
14 : 48	888				
14 : 51	891				
14 : 58	898				
15 : 07	907				
15 : 21	921				
15 : 27	927				
15 : 49	949				
15 : 51	951				
15 : 54	954				
15 : 56	956				
15 : 58	958				
16 : 02	962				
16 : 30	990				
16 : 41	1001				
16 : 48	1008				

TABLE 5: Continued.

16:49	1009
16:51	1011
16:57	1017
16:58	1018
17:02	1022
17:06	1026
17:27	1047
17:48	1068
17:49	1069
17:52	1072
17:54	1074
17:56	1076

TABLE 6: Earliest possible departure times of the train connections from the Ceske Budejovice coordination node, train connections for which no time changes are possible, belonging to set  $I_{sk}^O$ .

Departure time from Ceske Budejovice in the direction of Horni Dvoriste (hh:mm)	Departure time from Ceske Budejovice in the direction of Horni Dvoriste (mm)	Departure time from Ceske Budejovice in the direction of Ceske Velenice (hh:mm)	Departure time from Ceske Budejovice in the direction of Ceske Velenice (mm)	Departure time from Ceske Budejovice in the direction of Veseli n. Luznici (hh:mm)	Departure time from Ceske Budejovice in the direction of Veseli n. Luznici (mm)	Departure time from Ceske Budejovice in the direction of Cicenice (hh:mm)	Departure time from Ceske Budejovice in the direction of Cicenice (mm)
12:06	726	12:10	730	11:57	717	12:04	724
13:02	782	14:10	850	12:02	722	12:13	733
14:03	843	15:10	910	13:02	782	12:42	762
15:01	901	16:10	970	13:08	788	13:12	792
16:06	966	17:10	1030	13:12	792	14:04	844
17:02	1022	18:10	1090	13:57	837	14:13	853
18:03	1083	20:10	1210	14:02	842	14:27	867
20:06	1206	23:02	1382	14:08	848	14:42	882
21:10	1270			14:57	897	15:12	912
22:59	1379			15:02	902	15:29	929
				15:08	908	16:04	964
				15:12	912	16:13	973
				15:57	957	16:33	993
				16:02	962	16:52	1012
				16:08	968	17:12	1032
				17:02	1022	17:38	1058
				17:08	1028	18:04	1084
				17:14	1034	18:13	1093
				17:57	1077	18:42	1122
				18:02	1082	19:12	1152
				19:08	1148	20:04	1204
				19:12	1152	20:13	1213
				20:08	1208	21:07	1267
				20:57	1257	22:08	1328
				21:10	1270	22:57	1377
				22:02	1322		
				23:02	1382		

directions is defined in the incidence matrix, a fragment of which is presented in Table 10. When it is necessary to solve passing between train connections  $i$  and  $j$ , the incidence matrix shows value  $a_{ij} = 1$ ; in the opposite case, the value is

0. Passing of the train connections in their initial nodes (train stations) is not considered since in these situations train units could accumulate in the given initial train stations.

TABLE 7: Earliest possible departure times of the train connections from the Strakonice coordination node-, train connections for which no time changes are possible, belonging to set  $I_{sk}^O$ .

Departure time from Strakonice in the direction of Razice (hh:mm)	Departure time from Strakonice in the direction of Razice (mm)	Departure time from Strakonice in the direction of Horazdovice (hh:mm)	Departure time from Strakonice in the direction of Horazdovice (mm)	Departure time from Strakonice in the direction of Blatna (hh:mm)	Departure time from Strakonice in the direction of Blatna (mm)
11:06	666	10:53	653	11:10	670
11:19	679	12:53	773	13:10	790
12:07	727	13:55	835	15:15	915
13:06	786	14:53	893	16:21	981
13:22	802	16:53	1013	17:10	1030
14:02	842	17:51	1071	19:10	1150
14:36	876	18:53	1133	21:10	1270
15:06	906	20:53	1253	22:40	1360
15:19	919				
16:02	962				
17:06	1026				
17:19	1039				
17:32	1052				
18:07	1087				
19:06	1146				
19:19	1159				
21:06	1266				
21:20	1280				
22:30	1350				

TABLE 8: Earliest possible departure times of the train connections from the Cicence coordination node, train connections for which no time changes are possible, belonging to set  $I_{sk}^O$ .

Departure time from Cicence in the direction of Protivin (hh:mm)	Departure time from Cicence in the direction of Protivin (mm)	Departure time from Cicence in the direction of Divcice (hh:mm)	Departure time from Cicence in the direction of Divcice (mm)
8:26	506	8:19	499
9:11	551	8:42	522
9:40	580	9:33	573
10:26	626	10:19	619
10:41	641	10:41	641
11:11	671	11:00	660
11:40	700	11:33	693
12:26	746	12:19	739
12:41	761	12:41	761
13:11	791	13:00	780
13:36	816	13:33	813
14:26	866	14:19	859
14:41	881	14:41	881
15:10	910	15:00	900
15:36	936	15:33	933
16:26	986	16:19	979
16:41	1001	16:41	1001
17:18	1038	17:21	1041
17:36	1056	17:33	1053
18:26	1106	18:19	1099
18:41	1121	18:41	1121
19:11	1151	19:33	1173
19:36	1176	19:59	1199
20:26	1226	20:19	1219
21:36	1296	21:33	1293
23:26	1406		

TABLE 9: Volumes of transfer passengers.

Number of transfer passengers in the direction Cesky Krumlov > CB > Horni Dvoriste	4	10	21	20	17	15	9	19	1	23								
Number of transfer passengers in the direction Cesky Krumlov > CB > Ceske Velenice	6	19	0	17	0	20	18	20										
Number of transfer passengers in the direction Cesky Krumlov > CB > Veseli nad L.	20	20	9	6	12	12	3	3	3	11	3	24	10	2	20	6	1	8
Number of transfer passengers in the direction Cesky Krumlov > CB > Cicence	21	13	4	7	10	17	12	1	7	20	16	18	23	20	0	24	8	9
Number of transfer passengers in the direction CB > Cesky Krumlov	18	1	9	2	13	14	21											
	15	9	19	1	23	6	19	0	17	0	20	18	20	20	20	9	6	12
	12	3	3	3	11	3	24	10	2	20	6	1	8	18	21	18	21	11
	21	10	12	5	21	13	4	7	10	17	12	1	7	20	16	18	23	20
	0	24	8	9	18	1	9	2	13	14	21	3	3	24	23	25		
Number of transfer passengers in the direction Vimperk > Strakonice > Razice	6	15	13	5	1	12	20	6	19	7	20	3	4	7	0	10	23	16
Number of transfer passengers in the direction Vimperk > Strakonice > Horazdovice	22																	
Number of transfer passengers in the direction Vimperk > Strakonice > Blatna	5	12	17	3	13	11	24	2										
Number of transfer passengers in the direction Strakonice > Vimperk	24	9	9	2	19	7	7	7										
Number of transfer passengers in the direction Prachatice > Cicence > Protivin	15	1	25	0	20	15	9	15	4	16	22	8	13	18	21	25	1	13
Number of transfer passengers in the direction Prachatice > Cicence > Divcice	19	10	7	8	0	19	4	8	12	7	6	17						
Number of transfer passengers in the direction Vimperk > Volary > Cerny Kriz	7	12	24	13	19	22	21	12	12	19	9	8	23	14	22	17	1	3
Number of transfer passengers in the direction Cerny Kriz > Volary > Vimperk	22	16	1	3	13	3	17	4										
Number of transfer passengers in the direction Cesky Krumlov > Cerny Kriz > Volary	12	25	14	2	11	18	4	12	25	3	20	17	4	21	11	5	21	19
	7	6	3	22	2	17	14											
	19	21	5	15	3	12	9	1	6	18	19	6	13	19	18	12	18	10
	2	22	11	17	24	16	8	9	9	0	4	6	6	24	13	5	2	3
	6	4	10	22	2	12	23											
	2	5	3	7	6	4												
	7	8	3	4	9	4	6											
	8	2	3	2	5	2	8											
	5	2	8	7	5	7												

TABLE 10: Fragment of the incidence matrix, which demonstrates the necessity of passing of train connections running in opposite directions.

A	Departure time (hh:mm)	Sequence	194-departure from Ceske Budejovice						194-departure from Nove Udoli					
			8:00	10:00	12:00	14:00	16:00	18:00	9:00	11:00	13:00	15:00	17:00	19:00
			1	2	3	4	5	6	7	8	9	10	11	12
194-departure from ceske Budejovice	8:00	1	x	0	0	0	0	0	1	0	0	0	0	0
	10:00	2	0	x	0	0	0	0	1	1	0	0	0	0
	12:00	3	0	0	x	0	0	0	0	1	1	0	0	0
	14:00	4	0	0	0	x	0	0	0	0	1	1	0	0
	16:00	5	0	0	0	0	x	0	0	0	0	1	1	0
	18:00	6	0	0	0	0	0	x	0	0	0	0	1	1
194-departure from nove udoli	9:00	7	1	1	0	0	0	0	x	0	0	0	0	0
	11:00	8	0	1	1	0	0	0	0	x	0	0	0	0
	13:00	9	0	0	1	1	0	0	0	0	x	0	0	0
	15:00	10	0	0	0	1	1	0	0	0	0	x	0	0
	17:00	11	0	0	0	0	1	1	0	0	0	0	x	0
	19:00	12	0	0	0	0	0	1	0	0	0	0	0	x

TABLE 11: Results achieved by optimization.

Direction	Departure time prior to optimization (mm), (hh : mm)	Earliest possible departure time prior to optimization (mm), (hh : mm)- $T_i^{odj}$	Change (mm)- $x$	Departure time after optimization (mm), (hh : mm)	Passing train stations	
Ceske Budejovice > Nove Udoli	8:13	8:00	480	5	8:05	485
	10:07	10:00	600	5	10:05	605
	12:13	12:00	720	5	12:05	725
	14:26	14:00	840	5	14:05	845
	16:13	16:00	960	5	16:05	965
	18:13	18:00	1080	5	18:05	1085
Nove Udoli > Ceske Budejovice	9:15	9:00	540	30	9:30	570
	11:22	11:00	660	30	11:30	690
	13:19	13:00	780	30	13:30	810
	15:23	15:00	900	30	15:30	930
	17:21	17:00	1020	30	17:30	1050
	19:18	19:00	1140	30	19:30	1170
Cicenice > Nove Udoli	7:39	7:30	450	5	7:35	455
	9:42	9:30	570	5	9:35	575
	11:42	11:30	690	5	11:35	695
	13:40	13:30	810	5	13:35	815
	15:40	15:30	930	5	15:35	935
	17:40	17:30	1050	5	17:35	1055
Nove Udoli > Cicenice	19:40	19:30	1170	5	19:35	1175
	6:14	6:00	360	24	6:24	384
	8:00	8:00	480	24	8:24	504
	10:15	10:00	600	24	10:24	624
	12:15	12:00	720	24	12:24	744
	14:15	14:00	840	24	14:24	864
Strakonice > Volary	16:19	16:00	960	24	16:24	984
	18:16	18:00	1080	24	18:24	1104
	9:25	9:00	540	8	9:08	548
	11:25	11:00	660	8	11:08	668
	13:25	13:00	780	8	13:08	788
	15:25	15:00	900	8	15:08	908
Volary > Strakonice	17:25	17:00	1020	8	17:08	1028
	19:25	19:00	1140	8	19:08	1148
	8:47	8:30	510	27	8:57	537
	10:47	10:30	630	27	10:57	657
	12:47	12:30	750	27	12:57	777
	14:47	14:30	870	27	14:57	897
	16:47	16:30	990	27	16:57	1017
	18:47	18:30	1110	27	18:57	1137

Upon substituting the input values to the proposed mathematical model, the following results were achieved, see Table 11.

It is clear from the achieved results that individual train connection times changed and, moreover, nodes suitable for passing of individual train connections were also determined.

Based on the results of the mathematical model and on subsequent conversion of the achieved values to a projected timetable, we can compare the operation characteristics along individual routes with the current situation.

Periodical operation was introduced along route Ceske Budejovice-Nove Udoli. As a part of it, passing occurs at the Horni Plana and Cesky Krumlov train stations, while the departures of individual train connections are of a periodical character. The train connections currently depart only in approximately similar time positions and the passing nodes of individual train units are not unified.

Periodical operation along route Cicenice-Nove Udoli was preserved, so were the passing nodes, i.e., the Bavorov and Zbytiny train stations. Only the time positions of the train connections were changed.

Periodical operation along route Strakonice-Volary was also preserved. Along this route, one passing node was changed, specifically from the Ckyne train station to the Bohumilice v Cechach train station. Furthermore, time positions of the train connections were also changed.

Yet another output of the mathematical model is represented by the creation of transfer relations. A total of 222 relations were created at the Strakonice, Cicenice, Ceske Budejovice, Cerny Kriz, and Volary nodes. The time loss arising from the transfers among individual train connections amounts to 83 357 minutes. The time loss arising from the transfers among individual train connections in the current situation amounts to 112 262 minutes, based on

which we can see that the optimization process resulted in a reduction of the time loss by 28 905 minutes.

## 5. Conclusions

The objective of the presented work was to develop an optimization tool, which will be used for reducing the time losses arising from transfers among individual passenger train connections. In the introduction of the article, we discuss the importance of the issue in question and we talk about the analysis of the state of the art and individual solutions related to the time coordination of the connections in various transportation systems.

The main part of the article deals with the proposal and detailed description of the general mathematical model which enables to coordinate train connections operated on single-track railway networks. The proposed mathematical model was tested in conditions of the selected railway network of the Czech Republic. The railway network used in the case study is in the South Bohemian Region and is operated by the railway carrier GWTR.

In the conclusion of the article, we assess the results of the time coordination of the given train connections at the Ceske Budejovice, Cicenice, Strakonice, Volary, and Cerny Kriz coordination nodes. The outputs of the mathematical model are presented in the table form, and they show time changes of the train connections based on the result of the optimization calculation and the passing locations of the given train connections.

The model proposed in this article is very general and can be easily modified based on particular conditions at other railway networks (the number of the transfer nodes or the number of train stations suitable for passing train connections running in opposite directions can be increased or reduced). The model can also be used for coordinating transfers among train connections in transfer nodes as well as multitrack and two-track railway routes, which are characterized by the fact that individual tracks are used only by train connections running in one direction (in that case, the input values, groups of conditions, and components of the purposeful function related to passing at en route stations are removed). The model can also be used for optimizing transfer relations during railway network operation or modernization outages, when the number of tracks between two train stations, etc., is temporarily reduced.

## Data Availability

All data used in the study are presented in the manuscript.

## Conflicts of Interest

The authors declare that they have no conflicts of interest.

## References

- [1] I. Olivkova, "Provoz a ekonomika dopravy," 2020.
- [2] E. Chung, *Transfer Coordination Model and Real-Time Strategy for Inter-modal Transit Services*, Department of Civil Engineering University of Toronto, Toronto, MA, USA, 2009.
- [3] F. Ciaffi, E. Cipriani, and M. Petrelli, "Feeder bus network design problem: a new metaheuristic procedure and real size applications," *Procedia-Social and Behavioral Sciences*, vol. 54, pp. 798–807, 2012.
- [4] Y. Sun, X. Sun, B. Li, and D. Gao, "Joint optimization of a rail transit route and bus routes in a transit corridor," *Procedia-Social and Behavioral Sciences*, vol. 96, pp. 1218–1226, 2013.
- [5] C. Daganzo and P. Anderson, *Coordinating Transit Transfers in Real Time*, University of California at Berkeley, California, CA, USA, 2016.
- [6] K. Gkiotsalitis, O. A. L. Eikenbroek, and O. Cats, "Robust network-wide bus scheduling with transfer synchronizations," *IEEE Transactions on Intelligent Transportation Systems*, vol. 21, no. 11, pp. 4582–4592, 2020.
- [7] N. Vijayakumar and A. El-Geneidy, *Coordinating Schedules of Bus Routes in a Shared Service Area*, McGill University, London, UK, 2011.
- [8] J. Omar and A. Yasmin, *Synchronization of Bus Timetabling*, Universidad Autónoma de Nuevo León (UANL), Mexico, MA, USA, 2012.
- [9] M. Almasi, A. Sadollah, S. Kang, and M. Karim, "Optimization of an improved intermodal transit model equipped with feeder bus and railway systems using metaheuristics approaches," *Sustainability*, vol. 8, no. 6, p. 537, 2016.
- [10] R. C. W. Wong, T. W. Y. Yuen, K. W. Fung, and J. M. Y. Leung, "Optimizing timetable synchronization for rail mass transit," *Transportation Science*, vol. 42, no. 1, pp. 57–69, 2008.
- [11] X. Liu, H. Qu, S. Chien, L. Spasovic, B. Ran, and M. Huang, *Optimizing Passenger Transfer Coordination in a Large Scale Rapid Rail Network*, The 94th Annual Meeting, Washington, DC, USA, 2014.
- [12] T. Xiaopeng and N. Huimin, "A dynamic programming approach to synchronize train timetables," *Advances in Mechanical Engineering*, vol. 9, no. 6, 2017.
- [13] D. Xueping, M. Qiang, and G. Xiucheng, "Bus schedule coordination for the last train service in an intermodal bus-and-train transport network," *Transportation Research Part C: Emerging Technologies*, vol. 60, pp. 360–376, 2015.
- [14] L. Tao and C. Avishai, "Integrated public transport timetable synchronization and vehicle scheduling with demand assignment: a bi-objective bi-level model using deficit function approach," 2017.
- [15] E. Hassannayebi, S. H. Zegordi, M. Yaghini, and M. R. Amin-Naseri, "Timetable optimization models and methods for minimizing passenger waiting time at public transit terminals," *Transportation Planning and Technology*, vol. 40, no. 3, pp. 278–304, 2017.
- [16] A. Ceder, B. Golany, and O. Tal, "Creating bus timetables with maximal synchronization," *Transportation Research Part A: Policy and Practice*, vol. 35, no. 10, pp. 913–928, 2001.
- [17] W. Wu, R. Liu, and W. Jin, "Designing robust schedule coordination scheme for transit networks with safety control margins," *Transportation Research Part B: Methodological*, vol. 93, no. A, pp. 495–519, 2016.
- [18] L. N. Jansen, M. B. Pedersen, and O. A. Nielsen, "Minimizing passenger transfer times in public transport timetables," 2002.
- [19] X. Guo, H. Sun, J. Wu, J. Jin, J. Zhou, and Z. Gao, "Multi-period-based timetable optimization for metro transit networks," *Transportation Research Part B: Methodological*, vol. 96, pp. 46–67, 2017.
- [20] W. Jiaqing, R. Song, Y. Wang, F. Chen, and L. Shubin, "Modeling the coordinated operation between bus rapid



- transit and bus,” *Mathematical Problems in Engineering*, vol. 2015, 2015.
- [21] F. Cevallos, *Optimization of Transit Transfer Times: A System-wide Approach*, Florida International University, London, UK, 2006.
- [22] D. Arenas, R. Chevrier, S. Hanafi, and J. Rodriguez, “Solving the train timetabling problem, a mathematical model and a genetic algorithm solution approach,” 2015.
- [23] K. Nachtigall and S. Voget, “A genetic algorithm approach to periodic railway synchronization,” *Computers & Operations Research*, vol. 23, no. 5, pp. 453–463, 1996.
- [24] Y. Shafahi and A. Khani, “A practical model for transfer optimization in a transit network: model formulations and solutions,” *Transportation Research Part A: Policy and Practice*, vol. 44, no. 6, pp. 377–389, 2010.
- [25] Y. Wu, J. Tang, Y. Yu, and Z. Pan, “A stochastic optimization model for transit network timetable design to mitigate the randomness of traveling time by adding slack time,” *Transportation Research Part C: Emerging Technologies*, vol. 52, pp. 15–31, 2015.
- [26] Y. Wu, H. Yang, J. Tang, and Y. Yu, “Multi-objective re-synchronizing of bus timetable: model, complexity and solution,” *Transportation Research Part C: Emerging Technologies*, vol. 67, pp. 149–168, 2016.
- [27] N. Cao, T. Tang, and C. Gao, “Multiperiod transfer synchronization for cross-platform transfer in an urban rail transit system,” *Symmetry*, vol. 12, no. 10, p. 1665, 2020.
- [28] H. Yin, J. Wu, H. Sun, L. Kang, and R. Liu, “Optimizing last trains timetable in the urban rail network: social welfare and synchronization,” *Transportmetrica B: Transport Dynamics*, vol. 7, no. 1, pp. 473–497, 2019.
- [29] [https://www.mzv.cz/london/en/about\\_the\\_czech\\_republic/basic\\_information\\_on\\_the\\_czech\\_republic/index.html](https://www.mzv.cz/london/en/about_the_czech_republic/basic_information_on_the_czech_republic/index.html).
- [30] <https://www.sketchbubble.com/en/powerpoint-czech-republic-map.html#mz-expanded-view-1490896153680>.