

# Temporal Form in Interaction Design

Interaction design is distinguished from most other design disciplines through its temporal form. It is the computational structures, which enables and demands a temporal expression in the resulting design. The temporal form is what enables poetry. In music it is the composition of tones, pauses, and timbre that enable the harmonies and rhythms, which makes up a musical piece. In interaction design it is, for instance, the behaviors of pixels on a screen or the movements in the shape-changing interfaces.

In this paper we show the power of working explicitly with the temporal form in designing computational things. We give a nuanced account of what temporal form is in interaction design and we look at related work synthesizing what we already know of the temporal concerns in interaction design and HCI. In the second part we present a design experiment through which we explore the experiential qualities of a set of 11 simple temporal forms by letting a series of expert designers reflect upon them. We borrow a framework from Boorstin's film theory where he distinguishes between the voyeuristic, the vicarious, and the visceral experience. We finalize the paper by arguing how the temporal form in computational things enables richer experiences than static objects do based on the outcomes of the study. And summarize how the temporal form enables different kinds of complexities which each seems to evoke different kinds of experiences (e.g. how small rhythmic anomalies evoke the sense of the technology being alive, or how the forceful behavior can evoke strong vicarious responses).

The goal of this paper is to point out the significance of the temporal form in interaction design and to do so through providing a better understanding of some of the qualities at play. We know practitioners are familiar with some of these temporal considerations simply because we cannot design computational things without them. However, the aim here is also to provide some insights from both a theoretical and empirical perspective, which can help qualify our temporal design considerations.

**Keywords** – Computational things, design research, form-giving, shape change, temporal form

**Relevance to Design Practice** – Developing an understanding for temporal form in interaction design can be compared to developing musicology or knowledge of physical forms. It gives us a better understanding of what we can do with interaction design as well as a language to articulate choices and preferences.

## Introduction

Interaction design<sup>1</sup> is distinguished from most other design disciplines through its temporal form. It is the computational structures, which enables and demands a temporal expression in the resulting design. When programming computers we create a temporal form, which then comes to expression through an output of actuators and other materials. Indeed, it is these material manifestations of the temporal forms, which enable our interactions with computational things as digital computations in them selves are inaccessible. As such, the temporal form causes interaction design to bear a kinship with temporal arts like music, dance, and film. While several interaction design researchers have already articulated this aspect we are still to grasp the details of what it entails (cf., Hallnäs and Redström, 2001; Hallnäs and Redström, 2006; Mazé and Redström, 2005; Vallgård, 2014). How do we experience temporal form in computational things? What significance does the temporal form hold for the overall experience? What is the relation between the temporal form and the other form-elements in interaction design? What relations can we find between the expressions of computational things and our experience of them when it comes to temporal forms?

The temporal form is what enables poetry. In music it is the composition of tones, pauses, and timbre that enable the harmonies and rhythms, which makes up a musical piece. In movies it is the composition of actions and backgrounds moving stories forward. In poetry it is the composition of meanings and rhythms. The temporal form holds functional as well as aesthetic power in the composition of the overall design – just as the physical form does. The traditional view on temporal form in relation to computational things has been that of speed. It has been a matter of removing delays from hardware and software to enable instantaneous representation on the graphical displays; it has been about speeding up the computations to achieve faster results, etc. Certainly, the execution speed in a computational thing is important and will affect what we do with it but there are more aspects to be explored of the temporal form than speed. Material and tangible computing has changed what forms of interaction we design for and the materials we use. It has meant that the contexts in which we use computational things have multiplied and that not all of those are suited for speed as the only temporal expression. Indeed, it has become crucial to pay attention to the underexplored notions of timbre and pauses as well as the relations between materials and state-changes. From what can we design our rhythms and harmonies?

Vallgård (2014) has proposed to see the temporal form as part of a trinity of forms that would constitute the form-giving concerns in the practice of interaction design. With the other forms being the physical form and the interaction gestalt. We have since long understood the physical form and its relation to materials. In industrial design schools, for instance, students are taught how any physical form can be broken down to cubes and cylinders, and that every other form comes out of

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<sup>1</sup> Interaction design is in the paper understood as related to product design and thus concerned with designing entire computational things and environments – meaning any thing or environment in which computers play a role in their expression and/or function.

the transitions between them (cf. Itten, 1975; Ching, 2010). We know about materials and their influence in form and expression (cf. Manzini, 1989) and we know about style of physical objects (cf. Semper, 2004). We also have an understanding of the interaction gestalt where concepts like affordances (Gibson, 1986) or signifiers (Norman, 2011) help us understand how the physical form is linked to the interaction gestalt. Additionally, Dourish (2001) has succeeded in establishing all interaction as social as well as embodied. Indeed, what we lack most is an understanding of the temporal form's role in all this.

In this paper we underline the importance of working explicitly with the temporal form in the design of computational things. We give a nuanced account of what temporal form is in interaction design. We then look at related work synthesizing what we already know of the temporal concerns in interaction design and HCI. In the second part we present a design experiment through which we explore the experiential qualities of a set of 11 simple temporal forms by letting a series of expert designers reflect upon them. We borrow from film theory Boorstin's distinction between the voyeuristic, the vicarious, and the visceral experience as it gives us a framework to qualify our analysis of the relation between the expressions of the temporal forms and how they are experienced. We finalize the paper by arguing how the temporal form in computational things enables richer experiences than static objects do based on the outcomes of the study. And summarize how the temporal form enables different kinds of complexities which each seems to evoke different kinds of experiences (e.g. how small rhythmic anomalies evoke the sense of the technology being alive, or how the forceful behavior can evoke strong vicarious responses).

## **Temporal form in interaction design**

Simplified, we can talk of four temporalities at play in any interaction design: the temporality of the human, the temporality of the society, the temporality of the computer, and the temporality of the input/output compositions (the physical form). The latter two determines the temporal expression of any computational thing, while the first two plays into how we experience the temporal unfolding of a design. The temporality of the human is characterized by our ability to perceive the passing of time not just consciously but also in our embodied actions. We always experience the now in a simultaneous combination of what just happened (retention), what is happening (impression), and what we anticipate is going to happen (protention) (Gallagher and Zahavi, 2012). The temporality of the society is created through our mutual participation and interactions (Ingold, 1993). Yet these interactions happen resonance with our environment – with the rhythms of nature, the day and night, the seasons in a year, the tides etc. (Ingold, 1993). The temporality of the computer is determined by a combination of the hardware and software. It is a combination of the internal clock conducting the execution of instructions in the processor and the designs of the algorithms being executed. Finally, the temporality of the input/output compositions are determined by the by the actuators and sensors transductive abilities as well as the responsiveness of the materials they are connected to (Vallgård and Sokoler, 2010). Designing a computational thing or environment must inevitably take all these temporalities into account.

Basically, the temporal form in a computational thing is created from a combination of the temporality of the computer and the temporality of the input and output compositions (cf., Redström, 2001). Yet, to help us explain what temporal form is we can look at music. Music is a temporal form. As Stambaugh notes in her paper: “In musical ‘form’ what ‘flows’ are tones, tone complexes, and patterns, and these are genuinely temporal in themselves” (Stambaugh, 1964, p. 268). In computational form (the program) what flows are the changes of states, and patterns of state changes manifested as different voltage levels. The absolute majority of these state changes is not intended for output and will thus remain only as part of the computational structure. The output, however, is adapted in the physical form through various transducers and results in a spatial gestalt of the computational form (e.g. as pixels on a screen, as movements in a physical form, as audio, as temperature changes). Thus, unlike the pure computational form, this spatial gestalt is available to the human perception. The temporal form is then the overall behavioral expression of a computational thing.

A musical score is comparable with the computer program before execution. The score and the program constitute the plan for what should happen. A key difference is that while it is possible to create music without notes (improvised) it is not possible to create any temporal form in a computational thing without a computational form (a program). Albeit, the lines get blurred when working with genetic algorithms and adaptive AI but even they need a programmed starting point. Thus designing computational things can be equated to composing music. Indeed, designing the temporal form is always in the shape of a plan or a structure and not the actual execution of events. This becomes most apparent when the computational thing takes input from either interaction or other sort of background information. This input will likely influence the expression and quality of the execution and can thus be precipitated but not actually known in advance. Thus, the computational form is the structure that interprets the input and which determine how and to what extent the input is reflected in the output. For instance, there may be a close relation between the input and the output both temporally and spatially but they may as easily be separated by time and space.

Continuing with the musical analogy, composing tonal music, for instance, is more than just devising sequences of tones. It is as much about the temporal structure (i.e. the tempo and the pauses), about the timbre, the relation between the instruments in mind etc. We can see the states and state changes of computation as equivalent to devising sequences of tones in music. As soon as we take the physical form into account, however, composing the temporal form of computational things becomes equally as loaded with potential variations and is equally as complex as composing music. Indeed, in design of computational things we too need to consider aspects such as tempo and timbre as they afford certain interactive and communicative qualities. Indeed, it is in the composition of the temporal form that feedback and feed-forward cues are likely to be devised (cf., Wensveen *et al.*, 2004).

The choice of instrument in music can be equated to the choice of composition for the physical form – the composition of transducers and other materials. While the computational form in theory may be possible to execute in many different compositions it will most certainly look and feel different and thus have different communicative and interactive qualities. In practice, however, the transferability of the computational structure will be limited because the transducers and the materials will enable and afford different temporal expressions. For example, the states and how the states changes are composed must differ dramatically to suit the qualities of LED light and Peltier element controlled temperature changes respectively simply because of the speed with which their effect comes to expression. Also, while we still work with states as the basic component the transitions between them will in certain material compositions be the most expressive. For instance, in shape-change compositions the transitions may be the primary expression and the states only perimeters that may never be reached (e.g. two endpoints in a rotation).

As described above, what is designed is a plan for an execution and not the execution itself, as that will happen in the future and typically repeatedly. It is a plan for how events should unfold and how input should be interpreted. Only the future user can really determine whether these interpretations and responses are meaningful. Thus, the designer must always accept open-endedness. In a similar vein, some composers deliberately leave aspects indeterminate for future orchestrations to fill out (Cage, 2009). Such freedom demands a heightened attention and participation of the musicians, which can strengthen the nerve, and presence of the performance (Cage, 2009). This open-endedness can be compared to what we leave open to the users in interaction design (cf. Gaver *et al.*, 2003).

This is an early account of temporal forms in computational things, which we assume will become more nuanced and expanded as we come to better understand its ramifications. With the study presented below we aim to begin to grasp what it qualitatively entails to design a temporal form and more importantly how people perceive some of these temporal expressional qualities.

## **Related work**

Temporal matters have been treated within HCI and interaction design in a number of different ways. Some work has been focused on users' perception in interaction, other on the efficiency of the technology, and other again on the use of temporal elements to communicate functionality or to achieve specific aesthetic experiences. Below we have attempted to outline this varied landscape.

### **Temporal concerns in interaction**

The primary focus in previous studies of the temporal aspects of interaction has been on the perceived fluency in the interaction. In his work with experiential qualities Löwgren (2007) is, for instance, concerned with “the degree of gracefulness with which the users deals with multiple demands for their attention and action” (Löwgren, 2009, p. 3). In a similar vein several researchers have been concerned with interruptions (cf., Bailey *et al.*, 2001; Hudson *et al.*, 2003). For example,

when an email program running in the background calls for the user's attention by making a sound and showing a message in the corner of the screen. The concerns have primarily been to understand how such interruptions affect the users' workflow when they become stressful and when they relieve stress (cf., Bailey *et al.*, 2001; Hudson *et al.*, 2003). Related, Huang and Stolterman (2011) study the users' duration of attention in their interaction with an email client, which they propose to represent as graphs. Lundgren (2013) later proposes to nuance the concept of fluency as she introduces seven temporal themes (live time, real time, unbroken flow, sequential events, disordered events, juxtaposed events and branched versions) to assist analysis of temporal concerns in interaction. As is, however, the concepts of this list are not mutually exclusive and thus difficult to use in a context different than that from which they were derived.

### **Temporal concerns in graphical user interfaces**

The temporal concerns have typically been a little more difficult to handle when it comes to the usability of computational things and environments. With the introduction of the graphical interface in the mid 80's and the diminished latency to the I/O units rose the promise of dynamically adaptable user interfaces under the slogan "Why should people have to adapt to systems, systems should adapt to people instead?" (Höök, 2000p., 409). This, however, proved to be somewhat more complex than anticipated because the dynamics turned out to compromise the predictability and transparency of how the system worked (cf., Shneiderman, 1997; Höök, 2000). Thus, the adaptive graphical user interface has been largely abandoned and currently exists primarily as platform-dependent adaptation and not as a temporal concern within a work session.

The dynamic or animated aspect of the GUI has, however, stayed on as aid to communicate interaction possibilities either as feed-forward or feedback (cf., Wensveen *et al.*, 2004; Harrison *et al.*, 2011). Apple's iOS has a number of such examples, for instance, the jumping icons indicate that they can be switched around – they are now in that mode of interaction. In their analysis of Kineticons Harrison et al. (2011) lay out the communicative aspects of six types of motion metaphors: biological motion (human locomotion), gestures (deliberate human motion), organic motion (motion recognizable from nature), mechanical motion (toggles, sliders etc.), physics & natural effects (glass shatter, paper folds), and finally the cartoon conventions which include exaggerations and other manipulations of motions recognizable from nature. While the stringency of this taxonomy can be debated it is an attempt to articulate the qualities of different temporal metaphors of different use of transitions between states.

### **Temporal concerns in ambient displays**

When Weiser and Brown (1995) introduced the concept of Calm technology they were, albeit implicitly, working with the temporal expression of computational things, for instance, the Dangling String (Weiser and Brown, 1995). Ishii et al. (1998) later continued the exploration of the theme with their AmbientROOM. Here a host of information services was delegated to different objects and location within an office. The information was displayed through different temporal

forms of, for instance, changing light or airflow. In both cases, however, the temporal form of the ambient and calm displays is not discussed explicitly, even if it seems obvious that to create something that is ambient and peripheral the patterns of changes must play a significant role. Indeed, most commonly, temporal concerns in information visualization are paid little attention beyond basic observations of the designers' own experiences (cf., Holmquist and Skog, 2003; Jafarinaimi *et al.*, 2005; Mankoff *et al.*, 2003; Stasko *et al.*, 2004). For example:

Also, the display will change quite slowly, so that changes will usually not be noticeable unless one looks at the display for an extended period of time, or if there are long intervals between each time it is viewed. These are conscious design decisions that have been made to make the applications function more like a visually pleasing art-work, and less like animated computer graphics. (Mankoff *et al.*, 2003, p. 170)

This is not meant as specific critique of Mankoff *et al.* (2003) it only serves as an example to demonstrate the extent and quality of reflections on the temporal form thus far.

### **Temporal concerns in computational things**

When shifting focus from seeing the computer as a thing to instead seeing the thing first and the computer only as a structural or material part, the view on the design concerns also changes (Vallgård, 2014). This means, for instance, that the temporal concerns for computational things are not a matter of seeing interfaces or internal time constrains separately. Rather, they become integral concerns. When endeavoring into designing with new materials and new modes of input and output the accumulated knowledge regarding reaction times and the conventional modes of interactions need reevaluation. Fluency and easy of use may not be the primal objectives for the interaction gestalt rather the new modes of expression may lead to entirely new areas of application.

As Maeda (2000) and later Mazé & Redström (2005) argue designing the temporal forms of machines is new to the computational age. In the age of macroscopic mechanics the temporal form was given by the speed of the mechanical devices but the computations happens at a speed and in a form language that is impossible for humans to perceive. Thus, not only do we need to design the computations, but also how they come to expression.

Hallnäs & Redström's (2001) work on slow technology was probably the first deliberate attempt to bring the temporality of computational things to the foreground through critical reflection. By working with delays they challenged the expectations of their audience. They played on our general experience with computational things like laptops, smartphones, etc. as something that work more or less instantaneously and where a delay indicate something is wrong (i.e., the internet in down or the execution of the program stalls for some reason). Indeed, simply by seeking the opposite of the predominant focus on speed in computational things they opened up a design space in which we could experiment with the temporal form. With their slow technology they introduced a design for reflection (Hallnäs and Redström, 2001).

While we may readily want to explore the potential of this design space we also quickly realize the complexity involved in composing forms for things we have had little possibility to become familiar with because it is often not built yet. As a means to address this Frens *et al.* (2003) propose a combination of paper prototyping and “a timer to be able to time and scale the actions and reactions of the model” (Frens *et al.*, 2003, p. 7). The purpose is to find a way where a “desired feel for a movement can be composed by combining different materials and can be assessed at the handles of the haptic composer” (Frens *et al.*, 2003, p. 7). Nilsson *et al.* (2011) develop a combination of a graphical interface and a ‘musical sheet’ as tools to experiment with the patterns of color change in the textile upholstery on an interactive piece of furniture. Here, the computations have here been left as the last part of the design and the authors experiment with the piece of furniture as one would get to know a new musical instrument.

From a similar practice perspective Parkes and Ishii (2009) focus on the need for a vocabulary to express behavioral transformability. They deconstruct kinetic behavior into material (amorphous, layered, skeletal, rigid), mechanical (rotational, linear, radial) and behavioral (speed, acceleration, direction, twitter, delay, pattern) elements (Parkes and Ishii, 2009). They further state the importance of isolating “the perceptual response a motion can trigger, simplifying the mental leap and engineering knowledge necessary to arrive at a potentially new and innovative design solution.” (Parkes and Ishii, 2009, p. 370) but have not yet proceeded to do this. Rasmussen *et al.* (2012) take this a step further and look at both kinetic parameters and expressive parameters. With the expressive parameters they begin to address some of the qualities for temporal form in a shape-change context. Based on analysis of a series of shape-changing interfaces/installations they divide the expressive parameters into ‘adjectives,’ which refers to qualities (e.g. soft, peaceful, turbulent) and personality traits (e.g. happy, sad, angry), and ‘association,’ which covers organic (e.g. anthropomorphic, nature) and mechanical behavior (Rasmussen *et al.*, 2012). Building on this Kwak *et al.* (2014) devise a series of six shape-change behaviors, which they then subject to evaluation by 18 students in a repertory grid study. They let the test subjects describe their experience by giving them a series of construct/contrast pairs and a number between 1-7 (Kwak *et al.*, 2014). The results suggest that 1. a segmented surface is perceived as playful, 2. a surface which approach the test subject is more energetic, 3. the speed of shape change relates directly to the perceived assertiveness, where 4. slow and retracting shape changes are perceived as calm and introvert, and finally 5. rotating shape change is perceived as mechanical (Kwak *et al.*, 2014).

As we can see from this body of work dealing with the four temporalities in design of computational things is by no means trivial. Using the concept of temporal form, we believe, will enable us to get a handle on the design space – what levers and knobs we can work with. We still have little sense of the relation between the temporal form of the computational thing and the temporalities of the interaction gestalt. While Kwak *et al.* (2014) begin to study this empirically it is difficult to discern whether their results are relevant beyond the scope of their specific study since no attempts were made to understand the underlying explanation for the correlations. Thus, in the following part of the paper we begin to study the relation between temporal form and interaction.



Through an experimental setup we specifically aim to understand the underlying relations between expression and experience.

## Method

In this paper we have set out to explore the expressional qualities of the temporal form for the practice of interaction design. While it is not possible to establish a formal link between an expression and how it is experienced there is a degree to which we do have shared experiences simply because we do have similar bodies, with similar perception abilities, and sometimes we even share culture and previous experiences (Goldman, 2005; Merleau-Ponty, 2002). For example, there is a reason why it is a common trait among western pop songs to increase the pitch by half a note in the B section of the song or why there are car chases in action movies.

In this study we have chosen an experimental setup that is kept simple on all matters concerning the physical form and the interaction gestalt as means to maintain a focus on the temporal forms (cf. Vallgård, 2014). The physical setup is inspired by the shape-changing study by Kwak *et al.* (2014) as well as our own previous work on shape-changing textile (Dumitrescu *et al.*, 2012) (see Figure 1). Here, however, we are not attempting to introduce new forms of shape-change, on the contrary, we have chosen super simple motors and spiraled shaped shape-memory-alloys (SMA) and their direct effect on a cotton textile surface. We have designed three boxes, each with two servomotors, two stepper motors, or two SMAs. The two motor boxes were given four different temporal forms – meaning programs that define a pattern of movements – and the SMA box were given three. Further, the study-participants could to control aspects of the temporal form through parameters like speed, rotation degree, delay, or ampere by turning a couple of knobs on the side of the boxes. As study participants we invited experts, primarily interaction design experts, but we also included some with expertise in other temporal arts like music and dance. The argument for choosing experts is that they will be better equipped to reflect upon and articulate what they see. Each was subjected to an hour and a half think-aloud study. In the following subsections we describe in detail the physical setup of the study including aesthetic descriptions of the temporal forms. We also account for the backgrounds of the seven expert participants, and describe the study scenarios as well as our subsequent analysis method.



Figure 1 The three boxes, the left powered by two stepper motors, the middle by two spiral strings of shape memory alloys, the right by two servomotors. All three boxes are 20 inches in length and width and four inches high. See also the temporal forms in action at <https://vimeo.com/album/3639572>.

## Experimental setup

In order to set up the experiments we had to first span out the design space they should explore. We did this by early on deciding on a physical form and an interaction gestalt. On top of this we then designed a series of temporal forms, which would explore temporal aspects such as synchronicity and distortion. The forms further included different potentials to change elements such as speed, acceleration, velocity, delay, or intensity.

As the physical form, we chose to do an abstract setup in which we could focus on the aesthetics of the expressions rather than their ability to convey or perform a specific function. The choice of the white/light boxes was inspired by the “white cube” tradition of art galleries used to present the artworks without having to compete with other colors or patterns (cf., O’Doherty, 1999). While we know that no physical form could ever be neutral, we still believe that the box poses as little a spectacle as possible for the study. Thus, we wanted the patterns of movements in the textile to stand out and the rest withdraw to the background. The choice of textile and actuators were partly inspired by Dumitrescu et al. (2012) and partly by Kwak et al. (2014). We chose two types of rotating motors, one servo and one stepper. For the third one we used spiraled shape-memory-alloy (SMA). We simply attached them to the textile so the motors would rotate the textile, and the spiral SMA would contract it. Technically, it was a simple platform to set up. The reason for choosing

two similar actuators (the two types of rotating motors) was because, even if they technically perform a similar rotation, the possible patterns of those movements would be different. This would allow us to explore whether the experienced temporal form would also be different. Furthermore, we chose movements in a physical material over, more traditional forms of expression in a computational thing, such as graphics on an LCD, light patterns in LEDs, or audio. The reason was a desire to explore the part of the design space where the instantaneous state changes, which we have come to expect from traditional computational things, would be suspended. Through removing this expectation we would be allowed to explore a larger range of expressions in which, for instance, transitions between the states could play an important role. Finally, we chose two actuators per box. One actuator per box would have been a more simple choice but we quickly realized that the temporal forms would soon be too monotonous. Two actuators, on the other hand, would allow us the interplay between them and the use of the temporal form elements of synchronicity and asynchronicity.

As for the interaction gestalt, we also chose simplicity. A pilot study had shown that the study participants found it difficult to engage with the temporal forms if they had no means of interacting with them. Thus we introduced two turning knobs per box. Turning knobs are so simple and familiar that they would not require further instructions. As such, we hoped they would not distract from the temporal forms we wanted to study.

Only after completing the physical setups did we start to program their behavior and to explore our own perception of different temporal forms. We chose to restrict the parameters to two: synchronicity and level of control (see Figure 2). We had some initial notions that an asynchronous behavior of the two actuators would result in a more organic expression while a synchronous behavior would appear more mechanistic. We further contemplated that with less direct (more distorted control) the user would have (through the knobs) the more organic and less mechanistic the expression would seem. These were however only initial notions meant to aid us in designing a variety of the temporal forms. The four temporal forms these notions resulted in were only fully implemented on the two motor setups as the reaction time and nature of the shape-memory-alloy forced us to do some variations.

## **Description of the temporal forms**

The four temporal forms for the two motor boxes were derived from different combinations synchronicity and level of control (see Figure 2). In the first temporal form in the motor boxes would be synchronous in the two motors and their rotation would be a continuous oscillation from one extreme to another. One of the knobs would here control how far the motor should turn – where its extreme point should be. The other knob would for the servomotor control the speed and for the stepper control the acceleration. In the second temporal form, the two motors would still be synchronous, however, we had inserted a randomness factor in calculating the end position in the oscillation. This resulted in an abrupt movement pattern where it sometimes would move from one extreme to the other but most often it would change direction mid-way. The speed or acceleration

would still be directly controlled by the position of the second knob. In the third form, the motors would be asynchronous, as we had inserted a random length delay between them but the knobs fully controlled the degree of rotation, pace or acceleration respectively. And finally, the fourth temporal form would also be asynchronous and the control of the end positions would include a randomness factor resulting. (see Figure 2). See also the temporal forms in action at <https://vimeo.com/album/3639572>.

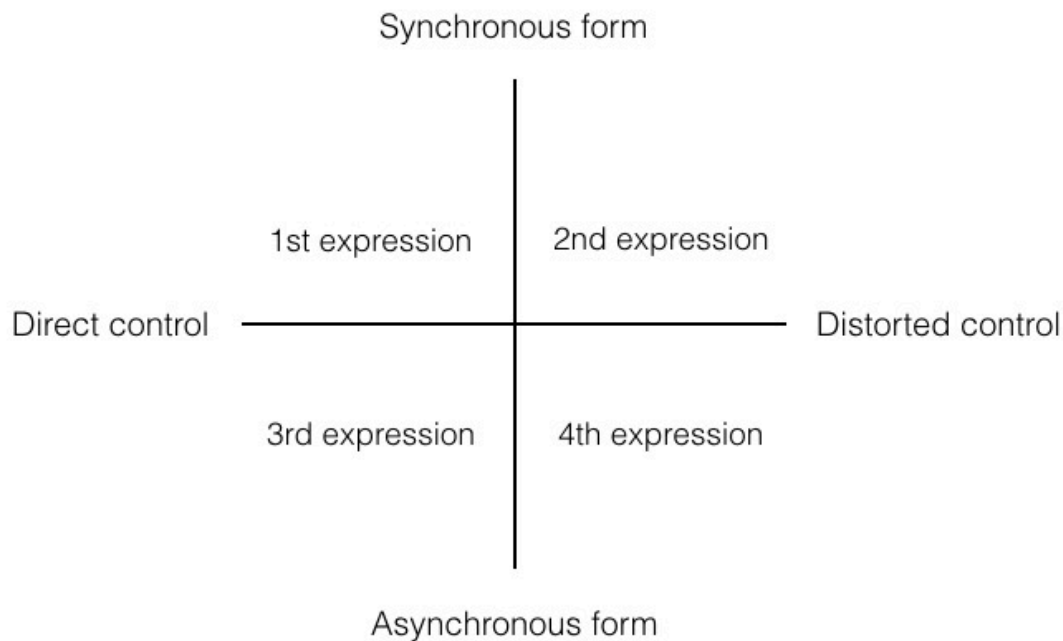


Figure 2 Illustration of the four different temporal form expressions in the two motor driven boxes. For instance, the 1<sup>st</sup> expression is a synchronized temporal form where the participant is in full control over speed and degree of oscillation. And in the 4<sup>th</sup> expression the temporal form is asynchronous and the participant's control of speed and oscillation has been distorted by a randomization factor.

Since the SMA works in a different temporal range than the motors – they react more slowly – it did not make sense to have the exact same setup for them. While, we still explored the synchronous/asynchronous axis, the knobs would instead control the length of time the power was on or the number of ampere sent through the wires.

Thus, in the first temporal form, the two wires would synchronously contract and relax. One knob would control the length of the contracted state and the other the length of the relaxed state. (Later referred to as synchronous). In the second form each knob control the corresponding SMA wire and the number of ampere flowing through it. (Later referred to as ampere). And finally, in the third temporal form, one SMA would be turned on when the other was turned off and vice versa. The knobs would here determine the length of the states respectively. (Later referred to as

asynchronous). The temporal form-factors at play in the temporal forms of the study are thus, synchronicity, degree of distortion, speed, acceleration, and degree of movement. Where acceleration only is present in the stepper motor and to some degree in the SMA in the ampere set-up. In the analysis we look at which experiences the overall expression foster and only then break down the different experiences into the different form-factors.

In total we explored 11 different temporal forms expressed in three physical forms (See <https://vimeo.com/album/3639572>).

## **Study Participants**

As mentioned, the argument for choosing experts is that their phenomenal field is broader than a layperson's (cf., Svanæs, 2013; Merleau-Ponty, 2002). So, while they may not have a vocabulary to describe the experiential qualities of a temporal form they still have a frame of reference in related matters, for instance, for describing physical forms or interaction gestalts. Their expertise will enable us to ask them, not just for their immediate experience, but also for how this experience is related to what they see. Thus, if they express frustration they are also likely capable of explaining what it is that makes it frustrating. This would provide us with reflections on the connection between expression and experience and thus ultimately give us a more nuanced picture from which we can begin to understand the temporal form.

We invited a total of seven experts from different fields. Four of the experts held a PhD in interaction design, design, or HCI, and had subsequently worked at least three years with research and teaching within the field. None of these were from our own research institution. They are referred to IxD-1-4 in the analysis below. We further invited a ceramicist, who had done a PhD on the topic of developing computer-based graphical forms and behaviors as means to create new ceramic shapes and had since continued this research for several years. He is referred to as the Ceramicist in the analysis below. We also invited a musician who did a bachelor in musical theory and now is finishing a master in modern culture. The musician started out as a classic violinist as a child but now plays drums in a band with professional engagements two to three times a month. She is referred to as the Musician in the analysis below. Lastly, we invited a professional ballet dancer who has been dancing for 30 years and professionally for 20. He is referred to as the Dancer in the analysis below. Among the seven experts three were female and four male and among the interaction designers specifically, two were male and two female.

The interaction designers were chosen for the obvious reason of having a heightened sensibility for and reflection on interactive artifacts. They have all been forced to articulate critiques of interactive artifacts in their professional career in teaching and peer-review contexts and thus could be expected to be able to possess both the critical eye and a vocabulary to express their thoughts on the intentionally abstract installations they were presented with. The ballet dancer and the musician were invited because of their experience with other types of temporal aesthetics and we thus expected them to be able to provide a critical reflection based on their respective profession. Finally,

the ceramicist was invited as someone who had an ingrained experience with the relation between the temporal and the physical albeit for him the temporal would always end in a solid state.

### **Study scenario**

Each participant would be presented to one box at the time with one or two researchers present (see Figure 3). Each session was audio recorded and video filmed. We would typically spend half an hour per box, however the first would usually get a little extra time for the participant to get used to the setup. The participant was asked to think aloud and only once in a while would the researcher would ask questions like “What are you experiencing here?” “Can you describe the behavior you see?” or “Why does this make you laugh?”

We would alternate between starting with the servomotor and the stepper motor but would always have the SMA in the middle as means to clear the palate and ensure it would not become too monotonous. We would also keep the order of the temporal forms for each box as they are described in the section above. The argument here was that there is a learning curve in how the boxes works and the first temporal form was the easiest to understand. While confounding of the experimental set-ups is likely inevitable it does not really matter since we were not interested in particular temporal forms but rather experts’ expressed experiences and their own explanations.

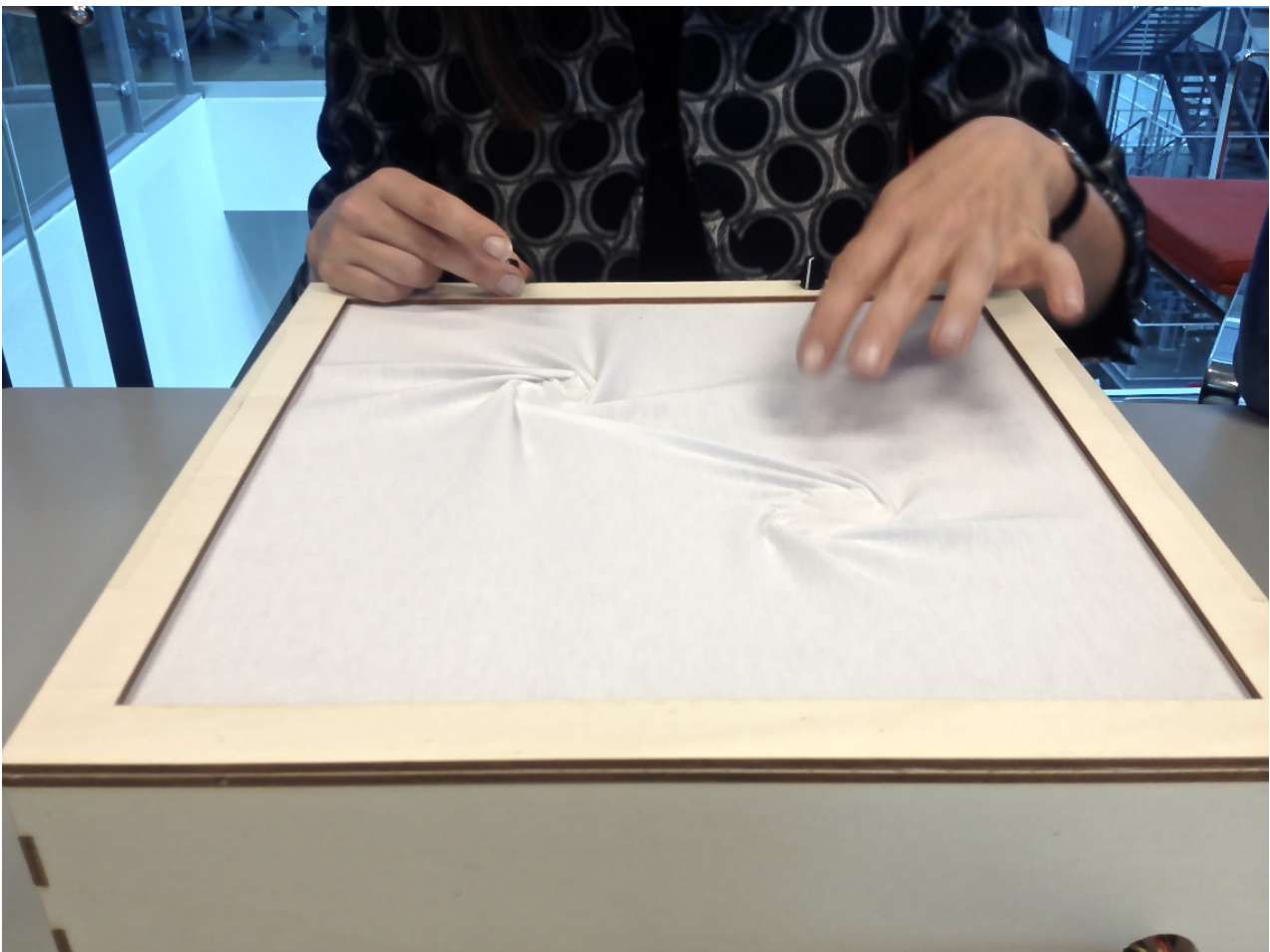


Figure 3 Picture of one of the study participants explaining her experience of a form developing through the servomotor setup.

## **Data analysis**

All seven interviews were transcribed by the researchers and afterwards sensitized and coded by one of the researchers. We used open coding with the purpose of identifying key themes among their description of their experiences. In coding the transcripts we were looking for recurring themes, but particularly for any description of experiences that would enable us to link them to expressions. Obviously, however, the more participants who corroborated on such a link the more detailed we have been able to describe it.

## **Reflection on using experts**

As expected, the interaction design experts demonstrated little experience with seeing and talking about temporal form in a design context. Thus, their frame of reference for temporal behaviors arises from everyday encounters in nature and society. They did, however, rely on their expertise when analyzing the qualities of the relation between the temporal and the physical form and what this entails for an interaction experience. The musician, on the other hand, had ample experience in analyzing temporal form in music and thus her frame of references has much to do with rhythms and repetition while she refrained from analyzing the physical form or the interaction. The ballet dancer read whole stories into the movement patterns in the boxes. Towards the end he would revisit the three boxes and tell a story of how one represented teenagers, another adults having a divorce and the third serenity of growing old. He did not discriminate between the individual movements but looked at their capability as a whole. The ceramicists, especially in the beginning, looked less for the movements and more for points where the movements created shapes he deemed worth preserving in ceramics. Later, he would shift focus towards the movements and their inherent qualities rather than what they could lead to.

## **Explaining the experiences of temporal forms**

What we are looking for here is to better understand the relationship between the experiences and expressions of the temporal forms. We are taking an outset in the experts' experiences or their analysis of the temporal expressions and through that we try to understand what qualities of the expressions elicited these experiences. As means to unpack this relationship we use Boorstin's three ways to experience a movie: the voyeuristic, the vicarious, and the visceral (Boorstin, 1995). His point is that any experience will encompass some element of all three but with different emphasis. We have found that the experts' experiences are well explained through Boorstin's voyeuristic, vicarious, and visceral experiences even if the unfolding expressions of the boxes are not movies with intricate plots.

The voyeuristic experience is that of the 'prying observer' the one who critically examines the world as it unfolds before her. The voyeur is captured if the world is believable, the flow is intact and she is entertained as long as there is an aspect of novelty. "The voyeur's pleasure is the simple joy of seeing the new and the wonderful" (Boorstin, 1995, p. 12).

The vicarious experience draws on our empathic abilities and tendency to project and test what we see with our own reaction pattern. “If we see a face we have a natural, automatic impulse to divine what the person behind the face is feeling, to test that emotion inwardly to see if it is suitable, and if it is, to taste it as our own. If it is not there [...] we will even try to fill in what’s missing ” (Boorstin, 1995, p. 65). Indeed, the “viewer performs a dual role, empathy, yes, but something more, he projects his own feelings into the characters. [...] The vicarious eye sees with the heart” (Boorstin, 1995, p. 66).

Finally, the visceral experience is the immediately sensed experience of the unfolding events (Boorstin, 1995). The visceral include experiences like harmony, anticipation, surprise, and even suspense, which in a movie can be how the current unfolding of events are colored by previous knowledge like a bomb on the bus, or a killer in the room (Boorstin, 1995).

Boorstin’s three views were not used in the moment of coding but are introduced now as means to unpack the findings further. The concepts allow us to better articulate the coupling of expressional qualities with the experts’ expressed experiences.

### **Voyeuristic experiences**

The boxes and their behaviors are not movies. They do not already depict worlds we have to believe. Instead, these abstract unfolding forms elicit our inherent need to make sense of what we see. The participants are forced to draw on their own experiences in order to explain what they see. We have chosen to divide these associations into two levels, those that serve merely as a frame to set the scene (a crawling worm or a contracting muscle) and those that are more vicariously experiences (a sense of being hugged or people fighting in the midst of a divorce). Here we will look at the ones that merely set the scene – the ones that arise from the being the prying observer.

#### *Is it alive or a machine?*

The expressions associated with perceptions of the mechanical versus the biological are not easy to determine. The study indicates that discernable rhythms can elicit both associations and that it comes down to the quality of the rhythm. Sometimes only miniscule differences determine whether a rhythm is associated with mechanical behavior or a biological behavior. Breathing or heartbeat associations are not surprisingly strongest in rhythms where the cadence matches our experience of both – meaning relatively slow and steady. That alone, however, does not seem to do it. Rather apparently a hint of irregularity is necessary in order to rule out the machine from the association. Indeed, this was the case whether the set-up were synchronous or asynchronous as long as a repetitive rhythm with a slight anomaly were discernable. Also, the speed seemed primarily to influence the kind of biological association at play.

I find that there is a certain breathing quality about them. Meaning, they hold a rhythm that is possible to discern. I don’t know if it is completely precise but at least they hold a rhythm which I find expresses something calm.  
(IxID-1, SMA, synchronous)



There is still a rhythm over here but it is not machine-like anymore. It is a bit like there is a longer cycle of movements. It is no longer the same little movement it repeats it has more like that weave-like... (IxD-1, Stepper, asynchronous w/ direct control)

Well, it pulls in this sort of contraction again and then it relaxes. But it is more alive in a way because it isn't a totally steady rhythm like the one we had before. (IxD-3, Servo, synchronous w/ distorted control)

Yes it is rhythmical. Of course it is rhythmical, but it is more unpredictable. There are some shifts happening which means that I cannot... I lack the right words regarding the rhythm – a shift that makes it less mechanical and more organic in a way. (IxD-3, Stepper asynchronous w/ direct control)

And then the breathing, sky, and water. Again, the rhythm. Weaves. I was more fascinated by the first two – no the second because it had that rhythm where it sort of moved back and forth within the lines as if it was lapping. As a fetus lying in the abdomen lapping in the amniotic fluid. Where this is sort of mechanic. Before it made that lapping back and forth and it wasn't... It was sort of in an irregular way. (Ceramicists, SMA, synchronous)

There is something extremely calming about such a regular rhythm – this is a very slow one. It makes me think of something pulse or heartbeats or something. (Musician, Servo, synchronous w/ direct control)

Now it feels like it is doing it all synchronous but sometimes it gets sort of out of beat with itself, which is rather - it's a pretty great feeling. It sort of softens what it is doing. (Musician, Stepper, asynchronous, w/ direct control)

### *Personality*

The participants willingly ascribed the boxes personality and lives when the interaction with them was distorted but never when the participants remained in control through the interactions. Whether they were synchronous or asynchronous, fast or slow, dramatic or calm seemed less important.

The machine appears more in this jerky way. Yes it gets a personality. And this is because I don't control it as much. (IxD-2, servo, synchronous w/ distorted control)

Now it is a little unpredictable as if they get their own life. It is pretty cute in a way. Confused. As if they don't really know what to do – a little indecisive. (Musician, Servo, synchronous w/ distorted control)

It is funny how they are out of sync because then I think it becomes more difficult to see some sort of regularity and it becomes more alive that way. (IxD-3, stepper, asynchronous w/ distorted control)

It is unpredictable. In a way a little crazy or insane because it appears a little as a compulsion I mean a weird distortion. Maybe it is because the fabric gets distorted and tense and it isn't really possible to follow the idea. I mean there is no repetition or rhythm that makes sense in relation to one another. (Musician, Stepper, asynchronous w/ distorted control)

### *Entertainment*

On several occasions the participants gave up interacting and merely stared at the behaviors. The expressions were sufficiently pleasurable and entertaining to engage the participants in a voyeuristic experience. The common denominator for the expressions was their complexity and unpredictability.

Indeed, the participants only indicated this level of entertainment when the actuators were asynchronous or the behavior was distorted or both. Again, levels of speed, acceleration, and degree of movement seemed less important.

I feel less of a need to adjust it here. But just sort of look at it and see what they are up to by wringing that fabric. [...] It is crazy difficult to figure out what they are doing here but somehow still fascinating. Or, you get dragged into it. (Musician, Servo, asynchronous w/ distorted control)

This gets exciting because you really get to see how the material gets stretched to its limits. This is consistent with these two centers – it is fascinating that there are two. If there had been only one it had it been less complex and the complexity is what fascinates. You get a narration. You become curious. There is something temporal in it right. It is exciting how it develops as we go along. It is a story getting narrated. Something is changing. There is something cinematic in the physical form. (Ceramicist, stepper, Synchronous w/ distorted)

Well, what happens here? I don't see a rhythm the same way. It is more unpredictable but still of course within the same frame of movements. The same folds in the fabric but much more unpredictable. Oy! Some completely unpredictable things appear. And now I'm less busy turning the knobs. There is sufficient activity without. Yes completely unpredictable. [...] There is a sort of aggression in this in a way. A wringing a forceful wringing some in a way is pretty satisfying to look at now when the material gets destroyed. The surface gets interrupted in a way. But I do not need to turn the knobs to have something interesting or meaningful to look at. At least this is interesting. There was a fun reaction at some point when it got really violent and I thought that it might tear but I also thought that it is as if something sort or fills my senses. (IxD-3, stepper, Asynchronous w/ distorted)

Obviously our choice of two centers instead of one was to enable us to create more complex forms but it seemed that this aspect was best achieved when they behaved asynchronous.

The asynchronous movements become more interesting. I have the sense that there is something more organic about this shape-change here. It is as if the some shape transferred from one to the other. There is something at play between the two now. This centerline appears – there is a pull, which I can't recall from the synchronous behavior. (IxD-1, servomotor, asynchronous w/ direct control)

This works pretty good now. When this pulls in and then afterwards the other pulls in. This makes it a kind of collaboration between them that fits. (IxD-2, stepper motor, asynchronous w/ direct control)

What I find most interesting are the transitions. There was a nice one. Nice transition also between the two lines. How many steps can you see right. At one point it is unperceivable. I lost it. I had a super nice transition before. The waves between the two are interesting. (IxD-4, SMA, asynchronous)

These are some pointers on what to consider when setting the scene – when designing the expression. In designs where a function is made explicit these associations are likely to be diminished, yet, independent movements have a strong hold on our imagination as the findings below further corroborate. While efficiency traditionally is more important than entertainment in interaction design when considering long-term use and perhaps even passive use like with ambient displays etc. entertainment may warrant an extra degree of aesthetic complexity. Indeed, breaking

rhythms slightly or providing complex and unpredictable temporal forms seems to go a long way when designing for a vicarious experience.

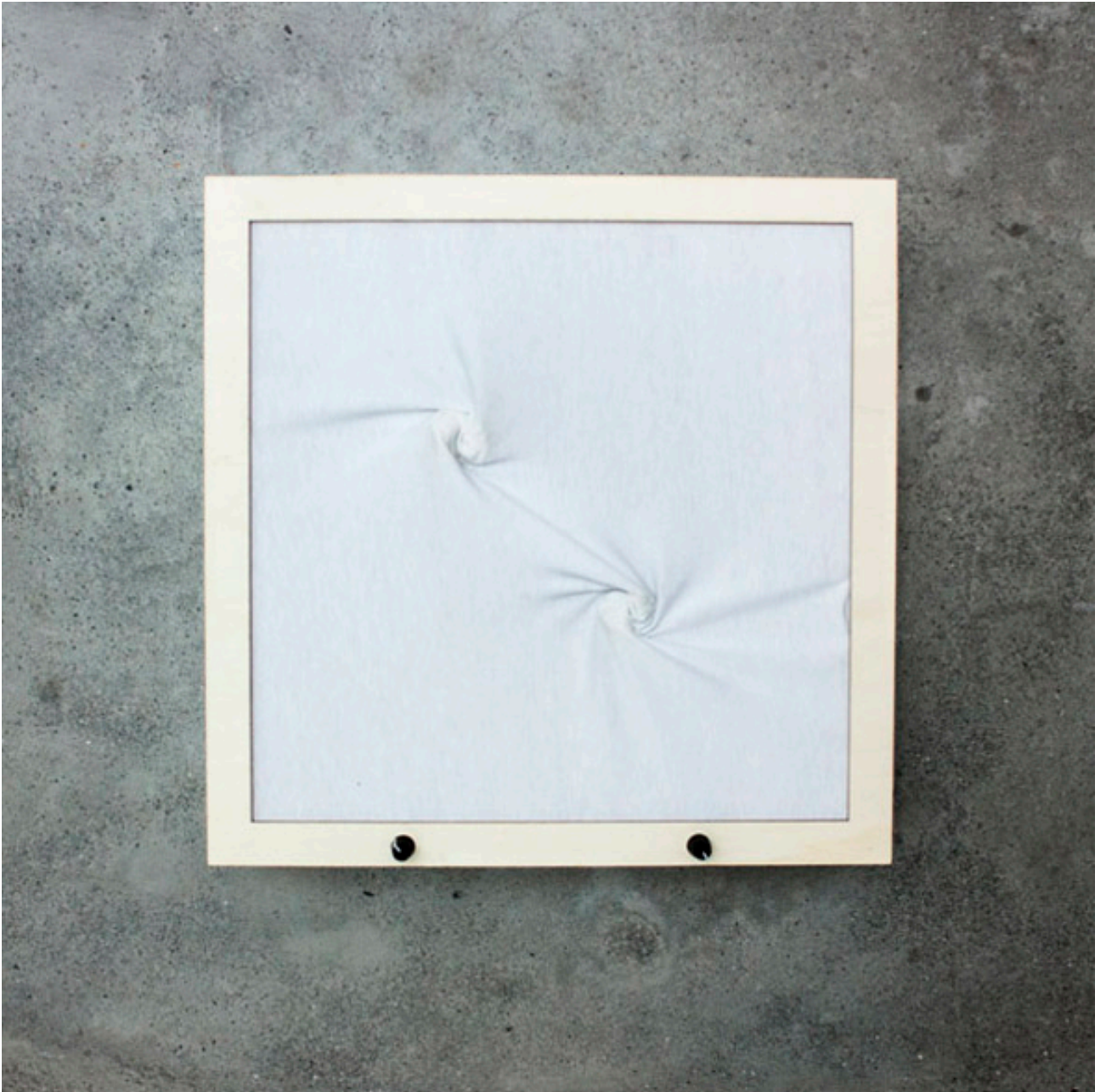


Figure 4 Still of the rotation created by the stepper motor. The temporal forms in this set-up seemed to elicit strong embodied experiences. See also: <https://vimeo.com/144300679>

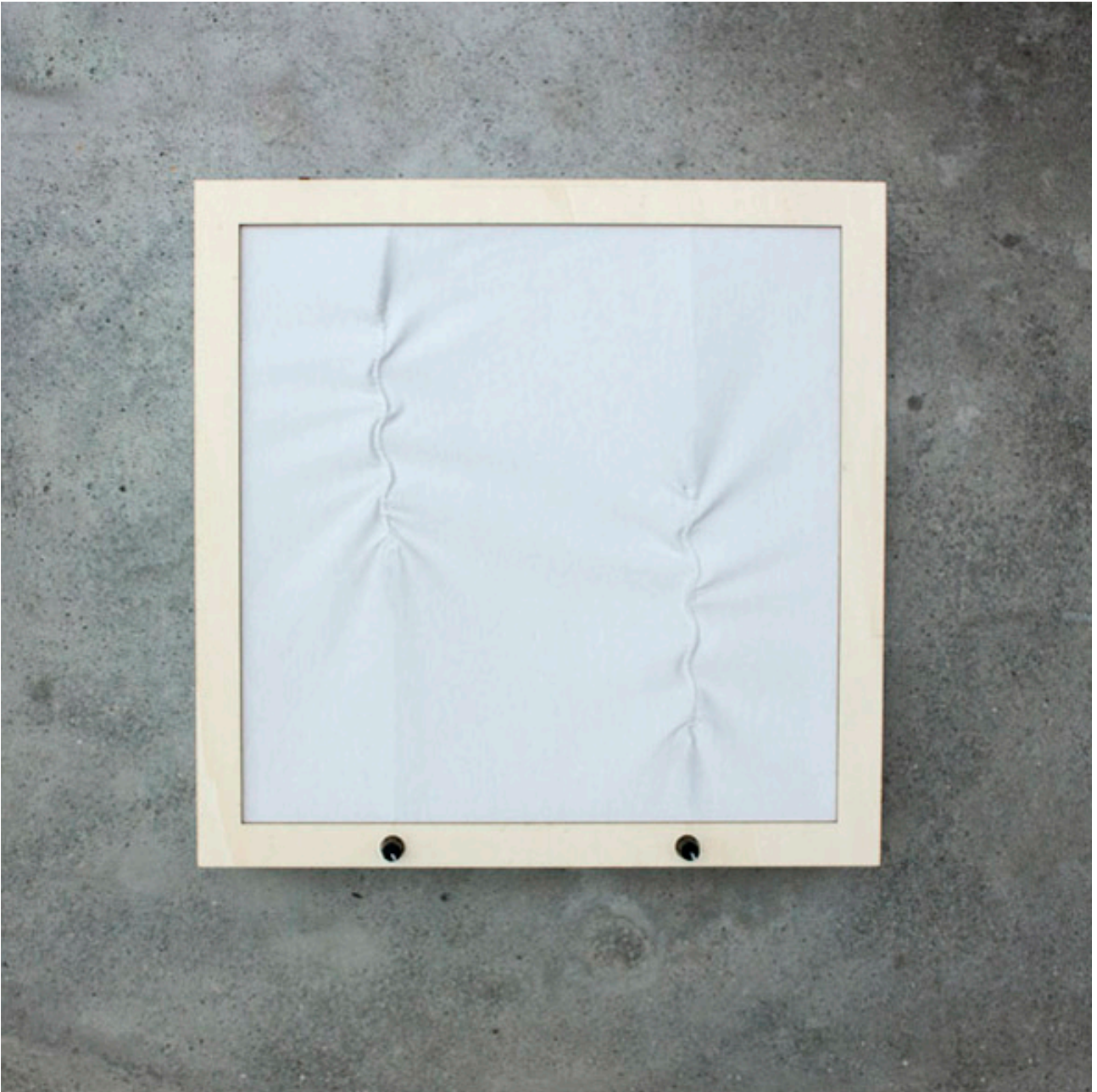


Figure 5 Still of a contracted form created by the shape-memory-alloy (SMA). The stitching in the fabric fostered associations to scars while the temporal behavior was experienced as meditative and relaxing. See also: <https://vimeo.com/144300673>

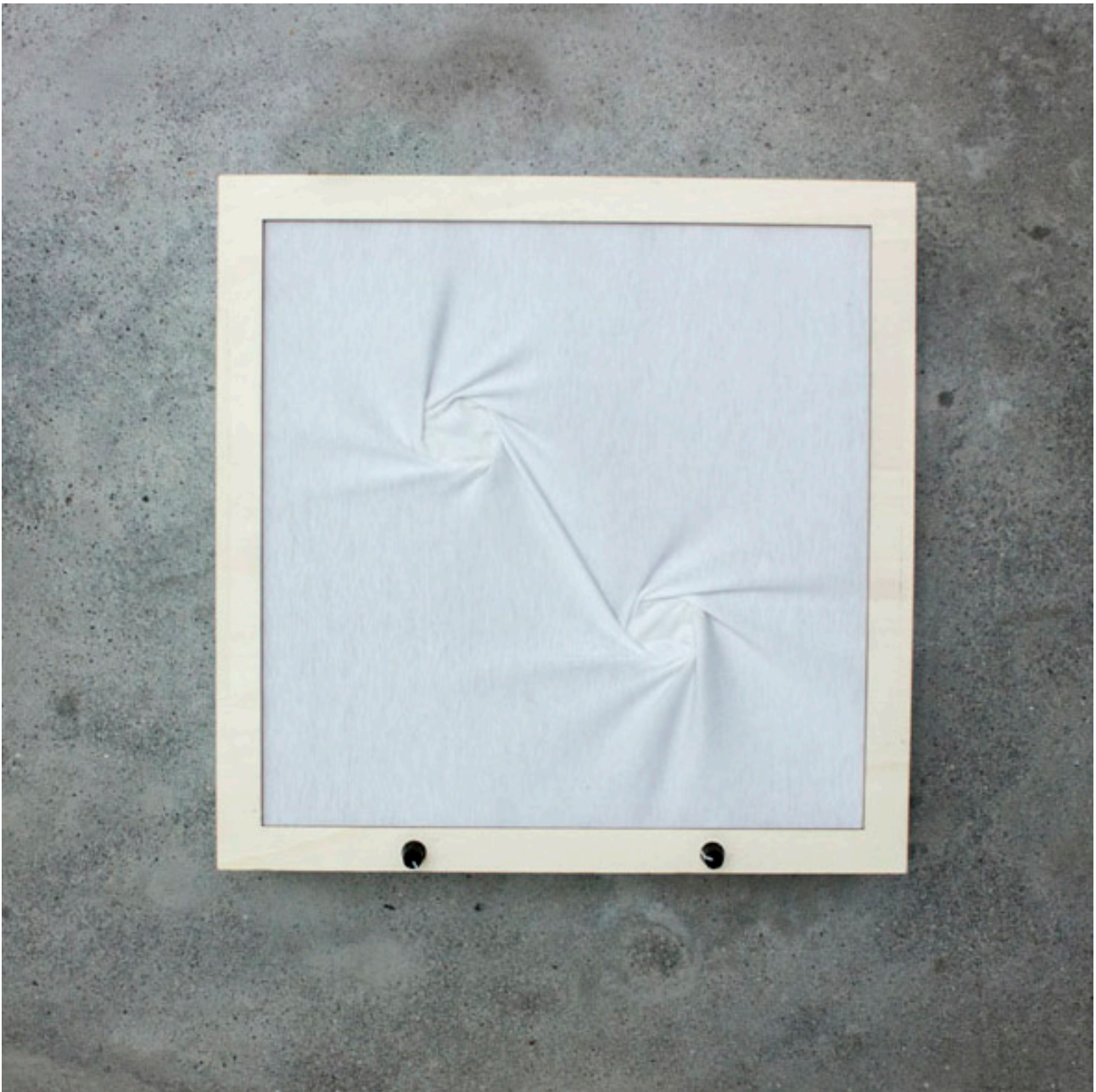


Figure 6 Still of the rotations created by the two servomotors. The temporality of this input output compositions was apparently able to excite sexual associations. See also: <https://vimeo.com/144300672>

### **Vicarious experiences**

While the associations described above were the result of consciously relying on experience we saw a whole range of reactions that seemed to be more vicarious. They were immediate and strong empathic reactions some of which even left the participants a bit embarrassed. They were typically visible in their faces or in their bodily movements (clenched fists, blushing, intense concentration, expression of horror or surprise) and the quotes below are their explanations of what had happened. While, Boorstin (1995) talked of the vicarious experience in relation to stories acted by characters in movies, the vicarious experiences is here based alone on the abstract behavior of the textile in the boxes. Thus, these vicarious experiences is predominantly concerned with simple embodied

projections. However, once in a while more complex emotional experiences appear, like when participants describe feeling caressed and hugged or even blush over imagined erotic behavior. Generally, it seems as if the force and acceleration of the stepper motor (Figure 4) elicited particular strong embodied reactions and only in an asynchronous setting does the more orderly and even paced servomotor (Figure 6) evoke vicarious sentiments. Of a different kind but non-less strong reactions were also elicited from the slow and gentle movements in the SMA, which were stitched into the fabric (Figure 5).

When I sit here and see this I get an urge to clench some clothing. I'm imagining that I was down there sort of grasping the clothes. That is actually a nice experience. It is a very physical sensation in the hand because I have done that with fabric before. It is very easy to relate to in a way. (IxD-1, stepper motor, asynchronous w/ distorted control)

This has probably to do with how it wrings the textile and that it isn't mechanical like the other was. This one changes pace. It grabs and slowly let go. It grabs slowly. Let go slowly. It is very... It becomes more like hands. It is physical. There is a being underneath. It becomes like a being right. Now I have to touch it! This one is more present. (Ceramicists, stepper motor, synchronous w/ distorted control)

This is like a sort of erotic experience because it is a sort of caress or a surprise right. When you touch one another there are some things that will sort of [audibly draw in air] give you a thrill. So you can turn away from it or you can take it in somehow. You have to – how to put it – it is something, which suddenly fill your senses. There is something very relaxing about it you could say. It is as if it is filled in a way and then you relax afterwards. It is like a muscle – it is relaxing in a way. It is as if you give a hug and this is the same. You can also talk about in in other ways but yes this is the same. (IxD-3, Stepper, asynchronous w/ distorted control)

Wow. What is this? I don't know. It feels very bodily in a way. It has something to do with... I don't know, but the way they intertwine and sort of cramps. (IxD-2, servo, asynchronous w/ direct control)

You get an urge to put your fingers down in those. (IxD-2, stepper, synchronous w/ direct control)

Go back! Go back! You are hurting yourself! [...] Phew! That was stressful! (IxD-4, stepper, synchronous w/ direct control)

Here one participant is almost hurting because his association to the SMA is a stitched scar. Less dramatic but also affected is the dancer who describe a sense of constriction (see also Figure 5).

This is so pronounced I think that when you look at this healing laceration you can almost feel that sort of sensitive and delicate expression which expands around the stretch and contraction. You can almost feel that form as if it picks in a scab or a scar or something that is sewn together. Not just when you draw in it but also when you squeeze it together of course. It is because the surface is punctuated with the stiches and the irregularity around the seam wriggles back and forth in those curves. It creates a sort of fracture or crack, which is very, very skin like. (IxD-3, SMA, synchronous)

It's because it's straight and can't really curve properly because it has to be attached to something that is vertical to work that... It feels constricted in a way. That it cannot... The movement is dictated by the mechanics so it doesn't feel as free as this one [stepper], where you can get bigger variety of shapes. And maybe that's why its... Its not ugly or anything, its just not, you don't feel as comfortable looking at it. You get a bit like "ah hi" uneasy. (Dancer, SMA, synchronous)

After sitting and staring at the movements for several minutes in silence the participants noted about the SMA setup (see also Figure 5).

There is something almost meditative about sitting here and watching the same rhythm over again because it is so complex and dynamic. (Ceramicist, stepper, synchronous w/ direct control)

Maybe it is because you get the urge to breathe with it. It is sort of the same rhythm. (Musician, SMA, synchronous)

It is like the box is breathing. Its like a calm way, when you sleep and you just go [inhales, exhales] without snoring. It is not snoring. It is more peaceful now than it was the first time. (Dancer, SMA, ampere)

This is very lovely concentration exercise. It is very relaxing. (IxD-3, SMA, asynchronous)

This one is so calming! You slow down. My interactions are slower compared to the other one. You feel it inside (IxD-4, SMA, synchronous)

Finally, several participants experienced a slight embarrassment in the form of blushing or being slightly flustered as they explained their sexual associations to the movements. Not all of them were confident enough in the situation to explain beyond the fact that is was a sexual association but here are a few examples (see also Figure 6).

Oy! This is almost sexual in a way [...] The thing is it has nothing to do with the resemblance of genitals. It is more about the movement. Which is more female masturbation than male masturbation. Yes there is something... Yes exactly more about masturbation. Am I anonymous here? (IxD-2, servo, asynchronous w/ direct control)

That pace it is... yeah orgasm! Haha. (IxD-2, stepper, synchronous w/ direct control)

It's a naughty box. I am not going into a porn description now. (Dancer, servo, asynchronous w/ direct control)

This gives me the impression of a kind of sexy behavior. It is because it is so relatively slow. It makes the effort of moving all the way into these shapes. (IxD-1, servomotor, asynchronous w/ direct control)

While the white cotton fabric may have alluded to bed linen or cotton briefs we doubt boxes without movements would elicit similar sexual associations. Indeed, we were a bit surprised by the elaborate vicarious experiences these rather sterile white boxes elicited

Generally, what explicitly evoked these different experiences is a little harder to pin down. None of them seems to have any correlation with the amount of control the participants had over the movements. The responses seem to be to the based on the behavior of the textile, of the combination of the physical and temporal form. And while the more complex projections inevitably must be situated and subjective (depending on the state of mind etc.) the fact that all of the

participants regardless of expertise expressed these vicarious experiences does indicate something about the power of the temporal form.

## **Visceral experiences**

The participants' visceral experiences of the temporal forms as they unfolded in the boxes were especially concerned with the harmony between the temporalities of the actuators behavior and the temporality of the material connected to it. The experiences were immediate reactions to the sensory input and thus less emotional than the vicarious experiences. Here, especially the IxD experts engaged in a critique of the behaviors and the design of the boxes as part of their reflection over their visceral experiences.

### *(Dis)harmony between the temporal form and the material*

The visceral experiences are concerned with the temporal form of the actuators movements in relation to the quality of the textile it is connected to. When the material is challenged to the edge of its anticipated strength or even when justice is not done to the apparent potential of the material it creates a tension. The participants all expressed aspects of this tension but IxD-1 explained it most fully.

I would rather want it slow. Not necessarily all the way down but when we have it about here I can better follow the shape changes in these stretches. I think it becomes difficult [turns up the speed] – my eyes simply can't perceive the changes. There are too many beautiful shapes I'm missing here. It's more about... cool that it moves but there are many qualities in the shape changes I don't manage to catch. This is really annoying! Maybe it is just a bad use of motors and textile – this could be done through 2D images and sound. But at this pace I can hardly perceive the shape change. Maybe if the material were thick leather it would appear calmer. This looks really nervous – it does not suit this material. Maybe it is because this material is easily agitated in the sense that it reacts instantly to the slightest movement. (IxD-1, servomotor, synchronous direct control)

It is a little bit like if you are dancing in a big ball gown then you shouldn't dance jitterbug because that is somehow not the best way to get something out of that gown. (IxD-1, servomotor, asynchronous distorted control)

The fabric is stretched – the movement exploits some of the qualities in the fabric. It can be stretched and it gives in the interspace down here but without tearing anything. You don't tear the fabric apart. There is a good interplay between the movement and the fabric here. (IxD-1, SMA, synchronous)

This works with the slow pace and the fabric. This fits. The movement and the material fit much better. You experience it more natural in a way. It is not because so much is happening here but in a way you think the rhythm in the material fits now. (IxD-2, SMA, synchronous)

The harmony as well as the disharmony was also expressed as the root of some of the vicarious experiences described above. For instance, when the participants made associations to orgasms there must have been an underlying harmony or satisfactory correlation between the temporal form and the material. Or when one participant is afraid that the box will hurt itself because the textile is stressed to what appears to be the limit.



### *Anticipating movement*

When we experience things in motion we quickly form an anticipation of where it is going – what likely paths it can take. When a movement deviates from these expectations it creates a friction resulting in a visceral experience of surprise or even frustration.

Now I want to see ‘go stop’ ‘go stop’. But it is not. It is overlapping. (IxD-4, stepper motor, asynchronous w/ direct control)

It is as if it embarks on a movement but then regrets it and instead stutters – it doesn’t follow through. Of course, this is because I have a sense there is a right way of for this to behave. When it has embarked on this curly-movement, and I recognize that this is possible, I want it to go all the way into this snail shape. This is frustrating. Now that I know that it could make such beautiful transition between these shapes... It does not achieve the optimal where the optimal would be a perfect circle or a particularly beautiful snail. (IxD-1, servomotor, synchronous w/ distorted control)

Here is actually a feeling that it completely takes on this form right. Yes! This form that I have been talking about the one that I think must be the purpose of them. They reach the perfect form and then slowly turn back. They actually turn all the way over. Ok this has to be the most optimal setting if you talk about going from one right form into the other right form. The other right form being when they are flat and uncurled. (IxD-1, stepper motor, asynchronous w/ direct control)

I liked it better when they were both twisting the same way, because the shape there was more attracting to the eye because it gave sort of half of an eight. Whereas here it looks like the movement is cut. There is something missing, there is a connection missing. It looks like there is more tension, whereas before the movement looked, even though they were twisting the same way, the movement looked more connected. They looked more connected to each other. If you know what I mean (Dancer, stepper, asynchronous w/ direct control)

Working with the anticipation can be used to create a smooth impression and in a successful combination of physical and temporal form possibly also to a satisfactory experience. On the other hand, working against the anticipation can be used to gain attention in the interaction gestalt. For instance, the element of surprise can be used as an opportunity for action.

Generally, finding a good balance between the physical form and the temporal form is clearly not entirely straightforward. Our experience with materials, their endurance and flexibility obviously play a role in whether we are ‘convinced’ by the combination or not. At the extremes, as with the anticipated movements, this can be used consciously to capture the attention of a user at the possible cost of frustration or it can be used to create a more complete sensation.

## **Discussion**

Based on this study we argue that the temporal form in computational things enables richer experiences than static objects do. Obviously, more is happening when things move and change state but we also argue that the temporal form evokes qualitatively stronger responses in those who

interact and observe. The voyeuristic experience is about being entertained about experiencing something new; evidently this is easier to do when the possibility of change is included in the toolbox. Our participants expressed that they were entertained by looking at a white cloth exactly because it was stretched, crinkled, and twisted. While we did not study their reactions to static white cloth we feel fairly certain that it would not have proven equally entertaining. Thus, the voyeuristic experience would have been shorter and possibly less memorable unless, of course, is we had been Robert Rauschenberg. The vicarious experience is about getting emotionally invested; it is about living through someone or something else for a while. This experience can occur with inanimate objects but the temporal form undoubtedly creates a larger repertoire of means to evoke. Further, the, for us, surprisingly strong and elaborate experiences we encountered with the relatively simple temporal forms seems to suggest that the potential of evoking vicarious experiences through temporal forms is larger in quality and not just in quantity. However, further studies would be necessary to corroborate this. Finally, the potential visceral experiences are increased with the introduction of temporal forms as they are increased by the once from the temporal realm: surprise, suspense, anticipation, apprehension etc. And while we only evoked a few of these with our temporal forms we did evoke them and we believe others are more easily created in less abstract settings where contexts can aid expectations. In other words, temporal forms hold a qualitative power to create experiences. The temporal arts rely on it, but we are only beginning to comprehend the extent of this power it in the context of interaction design.

This study has shown, how little anomalies in a rhythm can create the perception of biological or animalistic beings. It has shown how un-initiated and erratic behavior will likely be interpreted as a sign of personality, and it has shown how increasing the complexity of a temporal form can capture the attention of the observer for a longer period of time. But it has also shown the quality of the behavior matters, indicating that forceful and potentially uncontrollable powers evoke strong vicarious responses the same does the delicate timid behaviors, albeit of a different kind. Where the orderly and predictably behaviors received less attention and fewer strong responses. Finally, the study has shown that in composing the temporal within the physical we play into a large repertoire of previous experiences and capacity for empathy, which will color the overall experience. Indeed, behavior cannot just be designed by itself but must be developed in relation the materials it is expressed in regardless whether the aim is to create a tension or the opposite.

We only see this study as a first attempt of analyzing and articulating the potential of temporal form in interaction design. The study was deliberately kept abstract as means to get a first handle on the temporal form in it self, however, the temporal form will never appear in and by itself. We have used theories from both music and films as means to help us unpack the temporal form. None of them are sufficient on their own but where musical theory fits well with the stringency of computation film theory fits well with the complexity of temporal form expressed through actuators in different materials. We can even say that the temporality of the computer fist the temporality of music while the temporality of a film fits the temporality of shape-changing expressions. We believe further studies may more meaningfully begin to look at temporal forms in the context of

functional interaction design. Not just ambient displays, but comprehensive and intricate designs where the material and physical forms extends beyond the two-dimensional glass and plastic surfaces, and the interaction gestalt comprise more than look and point actions.

## Acknowledgments

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