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Performance bound for Approximate Optimistic Policy Iteration

Christophe Thiery, Bruno Scherrer

We provide here a proof of the performance bound theorem published in Thiery and Scherrer (2010). This theorem applies to Least-Squares λ Policy Iteration and more generally approximate, optimistic Policy Iteration algorithms.

Theorem 1 (Performance bound for Approximate Optimistic Policy Iteration)

Let $(\lambda_n)_{n\geq 1}$ be a sequence of positive weights such that $\sum_{n\geq 1} \lambda_n = 1$. Let Q_0 be an arbitrary initialization. We consider an iterative algorithm that generates the sequence $(\pi_k, Q_k)_{k\geq 1}$ with

$$\pi_{k+1} \leftarrow \operatorname{greedy}(Q_k),$$

$$Q_{k+1} \leftarrow \sum_{n>1} \lambda_n (B_{\pi_{k+1}})^n Q_k + \epsilon_{k+1}.$$

 ϵ_{k+1} is the approximation error made when estimating the next value function. Let ϵ be a uniform majoration of that error, i.e. for all k, $\|\epsilon_k\|_{\infty} \leq \epsilon$. Then

$$\limsup_{k \to \infty} \|Q^* - Q^{\pi_k}\|_{\infty} \le \frac{2\gamma}{(1 - \gamma)^2} \epsilon.$$

Proof

Notations and main idea of the proof We will use the following notations:

- $b_k = Q_k B_{\pi_{k+1}} Q_k$ is the Bellman error,
- $d_k = Q^* (Q_k \epsilon_k)$ is the difference between the optimal value function and the Q_k iterate (before error),
- $s_k = Q_k \epsilon_k Q^{\pi_k}$ is the difference between the Q_k iterate (before error) and the (true) value of the policy π_k ,
- $\beta = \sum_{n>1} \lambda_n \gamma^n$ (note that $0 \le \beta \le \gamma$).

The distance between the value of the optimal policy and the value of the current policy can be formulated as

$$||Q^* - Q^{\pi_k}||_{\infty} = \max(Q^* - Q^{\pi_k})$$

$$= \max(Q^* - Q_k + \epsilon_k + Q_k - \epsilon_k - Q^{\pi_k})$$

$$= \max(d_k + s_k)$$

$$\leq \max d_k + \max s_k$$
(1)

The idea of the proof is to compute upper bounds on d_k and s_k . As we will see, the bounds we will obtain will both depend on an upper on the Bellman error b_k , that we derive first.

An upper bound on the Bellman error b_k : As π_{k+1} is the greedy policy with respect to Q_k , we have $B_{\pi_k}Q_k \leq B_{\pi_{k+1}}Q_k$, which allows us to write

$$\begin{split} b_k &= Q_k - B_{\pi_{k+1}} Q_k \\ &= Q_k - B_{\pi_k} Q_k + B_{\pi_k} Q_k - B_{\pi_{k+1}} Q_k \\ &\leq Q_k - B_{\pi_k} Q_k \\ &= (Q_k - \epsilon_k + \epsilon_k) - B_{\pi_k} (Q_k - \epsilon_k + \epsilon_k) \\ &= (Q_k - \epsilon_k) - B_{\pi_k} (Q_k - \epsilon_k) + \epsilon_k - \gamma P_{\pi_k} \epsilon_k \\ &= \sum_{n \geq 1} \lambda_n \left[(B_{\pi_k})^n Q_{k-1} \right] - \sum_{n \geq 1} \lambda_n \left[(B_{\pi_k})^{n+1} Q_{k-1} \right] + (I - \gamma P_{\pi_k}) \epsilon_k \\ &= \sum_{n \geq 1} \lambda_n \left[(B_{\pi_k})^n Q_{k-1} \right] - (B_{\pi_k})^{n+1} Q_{k-1} \right] + (I - \gamma P_{\pi_k}) \epsilon_k \\ &= \sum_{n \geq 1} \lambda_n (\gamma P_{\pi_k})^n (Q_{k-1} - B_{\pi_k} Q_{k-1}) + (I - \gamma P_{\pi_k}) \epsilon_k \\ &= \sum_{n \geq 1} \lambda_n (\gamma P_{\pi_k})^n b_{k-1} + (I - \gamma P_{\pi_k}) \epsilon_k. \end{split}$$

By using the fact that P_{π_k} is a stochastic matrix, we have

$$\max b_k \le \sum_{n \ge 1} \lambda_n \gamma^n \max b_{k-1} + (1+\gamma)\epsilon = \beta \max b_{k-1} + (1+\gamma)\epsilon.$$

We then deduce by induction that

$$\max b_k \le \sum_{j=0}^{k-1} \beta^j (1+\gamma)\epsilon + \beta^k \max b_0 = \frac{1+\gamma}{1-\beta}\epsilon + O(\gamma^k).$$
 (2)

An upper bound on d_k : Let us now consider the d_k term and its evolution.

$$d_{k+1} = Q^* - (Q_{k+1} - \epsilon_{k+1})$$

$$= Q^* - \sum_{n \ge 1} \lambda_n (B_{\pi_{k+1}})^n Q_k$$

$$= \sum_{n \ge 1} \lambda_n \left[Q^* - (B_{\pi_{k+1}})^n Q_k \right]. \tag{3}$$

Since π_{k+1} is the greedy policy with respect to Q_k , we have $B_{\pi^*}Q_k \leq B_{\pi_{k+1}}Q_k$. Therefore

$$\begin{split} &Q^* - (B_{\pi_{k+1}})^n Q_k \\ &= B_{\pi^*} Q^* - B_{\pi^*} Q_k + B_{\pi^*} Q_k - B_{\pi^{k+1}} Q_k + B_{\pi_{k+1}} Q_k - \\ &- (B_{\pi_{k+1}})^2 Q_k + (B_{\pi_{k+1}})^2 Q_k - \ldots + (B_{\pi_{k+1}})^{n-1} Q_k - (B_{\pi_{k+1}})^n Q_k \\ &\leq B_{\pi^*} Q^* - B_{\pi^*} Q_k + \gamma P_{\pi_{k+1}} (Q_k - B_{\pi_{k+1}} Q_k) + \\ &+ (\gamma P_{\pi_{k+1}})^2 (Q_k - B_{\pi_{k+1}} Q_k) + \ldots + (\gamma P_{\pi_{k+1}})^{n-1} (Q_k - B_{\pi_{k+1}} Q_k) \\ &= \gamma P_{\pi^*} (Q^* - Q_k) + \\ &+ \left[\gamma P_{\pi_{k+1}} + (\gamma P_{\pi_{k+1}})^2 + \ldots + (\gamma P_{\pi_{k+1}})^{n-1} \right] (Q_k - B_{\pi_{k+1}} Q_k) \\ &= \gamma P_{\pi^*} (Q^* - (Q_k - \epsilon_k)) - \gamma P_{\pi^*} \epsilon_k + \\ &+ \left[\gamma P_{\pi_{k+1}} + (\gamma P_{\pi_{k+1}})^2 + \ldots + (\gamma P_{\pi_{k+1}})^{n-1} \right] (Q_k - B_{\pi_{k+1}} Q_k) \\ &= \gamma P_{\pi^*} d_k - \gamma P_{\pi^*} \epsilon_k + \left[\gamma P_{\pi_{k+1}} + (\gamma P_{\pi_{k+1}})^2 + \ldots + (\gamma P_{\pi_{k+1}})^{n-1} \right] b_k. \end{split}$$

As P_{π^*} and $P_{\pi_{k+1}}$ are stochastic matrices, we deduce

$$\max[Q^* - (B_{\pi_{k+1}})^n Q_k] \le \gamma \max d_k + \gamma \epsilon + (\gamma + \gamma^2 + \dots + \gamma^{n-1}) \max b_k$$
$$= \gamma \max d_k + \gamma \epsilon + \frac{\gamma - \gamma^n}{1 - \gamma} \max b_k.$$

By using Equation 3, we obtain the following induction on $\max d_k$:

$$\max d_{k+1} \le \gamma \max d_k + \gamma \epsilon + \sum_{n>1} \lambda_n \left[\frac{\gamma - \gamma^n}{1 - \gamma} \max b_k \right].$$

With the help of the Bellman error upper bound obtained earlier (Equation 2) we obtain

$$\max d_{k+1} \le \gamma \max d_k + \gamma \epsilon + \sum_{n \ge 1} \lambda_n \left[\frac{\gamma - \gamma^n}{(1 - \gamma)(1 - \beta)} \right] (1 + \gamma) \epsilon + O(\gamma^k)$$
$$= \gamma \max d_k + \gamma \epsilon + \frac{\gamma - \beta}{(1 - \gamma)(1 - \beta)} (1 + \gamma) \epsilon + O(\gamma^k)$$

which gives, by taking the limit superior,

$$\limsup_{k \to \infty} \max d_k \le \frac{\gamma}{1 - \gamma} \epsilon + \left[\frac{\gamma - \beta}{(1 - \gamma)^2 (1 - \beta)} \right] (1 + \gamma) \epsilon. \tag{4}$$

An upper bound on s_k : Let us now consider the s_k term from Equation 1:

$$s_{k+1} = Q_{k+1} - \epsilon_{k+1} - Q^{\pi_{k+1}}$$

$$= \sum_{n \ge 1} \lambda_n \left[(B_{\pi_{k+1}})^n Q_k \right] - (B_{\pi_{k+1}})^\infty Q_k$$

$$= \sum_{n \ge 1} \lambda_n \left[(B_{\pi_{k+1}})^n Q_k - (B_{\pi_{k+1}})^\infty Q_k \right]. \tag{5}$$

It can be seen that

$$(B_{\pi_{k+1}})^n Q_k - (B_{\pi_{k+1}})^\infty Q_k$$

$$= (B_{\pi_{k+1}})^n Q_k - (B_{\pi_{k+1}})^{n+1} Q_k + (B_{\pi_{k+1}})^{n+1} Q_k - (B_{\pi_{k+1}})^{n+2} Q_k + \dots$$

$$= (\gamma P_{\pi_{k+1}})^n (Q_k - B_{\pi_{k+1}} Q_k) + (\gamma P_{\pi_{k+1}})^{n+1} (Q_k - B_{\pi_{k+1}} Q_k) + \dots$$

$$= (\gamma P_{\pi_{k+1}})^n [I + \gamma P_{\pi_{k+1}} + (\gamma P_{\pi_{k+1}})^2 + \dots] b_k.$$

As above, by using the stochasticity of $P_{\pi_{k+1}}$, we obtain

$$\max[(B_{\pi_{k+1}})^n Q_k - (B_{\pi_{k+1}})^{\infty} Q_k] \le \gamma^n (1 + \gamma + \gamma^2 + \dots) \max b_k = \frac{\gamma^n}{1 - \gamma} \max b_k.$$

By using Equation 5, we obtain an upper bound on $\max s_{k+1}$:

$$\max s_{k+1} \leq \frac{1}{1-\gamma} \left[\sum_{n \geq 1} \lambda_n \gamma^n \max b_k \right].$$

With the help of the Bellman error upper bound (Equation 2) and by taking the limit superior, we have

$$\limsup_{k \to \infty} \max s_k \le \frac{1}{1 - \gamma} \left(\sum_{m \ge 1} \lambda_n \gamma^n \frac{1 + \gamma}{1 - \beta} \epsilon \right) = \frac{\beta}{(1 - \gamma)(1 - \beta)} (1 + \gamma) \epsilon. \tag{6}$$

Conclusion of the proof Finally, let us get back to Equation 1 and use the upper bounds we just derived for d_k (Equation 4) and s_k (Equation 6):

$$\begin{split} \lim\sup_{k\to\infty}\|Q^*-Q^{\pi_k}\|_{\infty} &\leq \limsup\max_{k\to\infty} d_k + \limsup\max_{k\to\infty} s_k \\ &= \frac{\gamma}{1-\gamma}\epsilon + \left[\frac{\gamma-\beta}{(1-\gamma)^2(1-\beta)} + \frac{\beta}{(1-\gamma)(1-\beta)}\right](1+\gamma)\epsilon. \\ &= \frac{\gamma}{1-\gamma}\epsilon + \left[\frac{\gamma-\beta+(1-\gamma)\beta}{(1-\gamma)^2(1-\beta)}\right](1+\gamma)\epsilon. \\ &= \frac{\gamma}{1-\gamma}\epsilon + \left[\frac{\gamma}{(1-\gamma)^2}\right](1+\gamma)\epsilon. \\ &= \frac{\gamma(1-\gamma)+\gamma(1+\gamma)}{(1-\gamma)^2}\epsilon \\ &= \frac{2\gamma}{(1-\gamma)^2}\epsilon. \quad \blacksquare \end{split}$$

References

Thiery, C. and B. Scherrer (2010). Least-squares λ policy iteration: Biasvariance trade-off in control problems. In *ICML'10: Proceedings of the 27th Annual International Conference on Machine Learning.*