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Numerical simulation of unsteady MHD flows and applications

R. Abgrall^{1,2}, R. Huart¹, P. Ramet^{1,3}

¹ *INRIA Bordeaux Sud-Ouest*

² *Mathématiques Appliquées de Bordeaux, Université Bordeaux 1*

³ *LABRI, Université Bordeaux 1*

We present a robust numerical method for solving the compressible Ideal Magneto-Hydrodynamic equations. It is based on the Residual Distribution (RD) algorithms already successfully tested in many problems [1]. We adapted the scheme to the multi-dimensional unsteady MHD model. The constraint $\nabla \cdot \mathbf{B} = 0$ is enforced by the use a Generalized Lagrange Multiplier (GLM) technique [2]. First, we present this complete system and the keys to get its eigensystem, as we may need it in the algorithm. Next, we introduce the numerical scheme built in order to get a compressible, unsteady and implicit solver which has good shock-capturing properties and is second-order accurate at the converged state. To show the efficiency of our method, we will then comment some 2D results. We will end by pointing out some issues and the extensions we plan for this solver.

1. Introduction The interest in the simulation of plasma models, and so in the resolution of the Magneto-Hydrodynamic equations, has been much increasing in the last decade due to the rise of new techniques and fields of research like thermonuclear fusion or in astrophysics. Our present work here is situated in the ITER context, as we aim to be soon able to simulate plasma instabilities, but it is expected to be of the same interest for all applications of the MHD model. We won't talk about the recent addition of the resistive MHD in the solver, because it has not been tested yet. Up to now, lots of numerical methods have been tested for solving the compressible MHD equations. However, most of them rely on approximate Riemann solvers used in standard Godunov schemes. Here we want to improve the ability of Residual Distribution schemes to solve this hyperbolic system, as started earlier in [3]. In this last reference, the authors mainly tested the LDA and N schemes which are two genuinely multidimensional upwind RD schemes. The most promising results were obtained by making a modified N scheme, another upwind RD scheme. Here we focus on the limited and stabilized Rusanov scheme [4], which captures shocks very well, as well as other discontinuities as slip lines or very strong gradient zones, and is much easier to implement than the previous N, LDA and blended RD schemes. We add a correction technique to ensure the solenoidal character of the magnetic field. Multidimensional upwinding techniques are made possible by the derivation of the full eigensystem of the corrected symmetrizable system. We indicate here the way we made that, through the symmetrization of the equations. Following the idea of [3], we use the system with Powell's source terms [5] while doing that, i.e. each time we use the eigensystem, whereas we solve the equations without them.

Let us now review first the whole corrected model and its symmetrization, and after the numerical method we employed. Then we will comment the 2D results we have got until now. While concluding, we'll also point out the improvements still to be done and what we plan to add to our model.

2. Description of the method Let us recall the physical context of our work and then we present the numerical method used to deal with it.

2.1. The Ideal MHD equations Naturally, we started with studying and discretizing these advection PDEs. It describes the behavior of a **totally** ionized gas, called a *plasma*. The approximation of a perfect fluid, underlying the Ideal MHD model, here partly means that the plasma has no viscosity nor resistivity: it's a perfectly conducting gas. As in traditional fluid mechanics, this comes from neglecting some collision effects. We also add an equation of state of perfect gases $p = (\gamma - 1)\rho e$, which is here a sufficiently good approximation, with p the hydrodynamic pressure, $\rho e = E - \frac{1}{2}\rho\mathbf{u}^2 - \frac{\mathbf{B}^2}{2\mu_0}$ and E the total energy.

We may note from now on that we won't make any use of the total pressure, usually called $P = p + \frac{\mathbf{B}^2}{2\mu_0}$, in order to avoid confusions. In the rest of this paper, we will drop the magnetic permeability μ_0 by assuming that the magnetic field \mathbf{B} has been normalized in this way : $\mathbf{B} := \frac{\mathbf{B}}{\sqrt{\mu_0}}$.

We start with the conservative form of the Ideal MHD equations, adding another equation which is not explicitly included in this system : the Maxwell-flux equation $\text{div } \mathbf{B} = 0$. Many ideas were found to ensure this constraint during the simulations. Mainly two techniques among them revealed to give good results

1. Building divergence-free elements by a collocation method, consisting in storing the magnetic field values on the faces/edges of each element (for a vertex-centered approach),
2. Introducing some correction terms by modifying the system of equations and adding a scalar variable representing the divergence of the magnetic field.

The first approach has shown to ensure a very accurate zero divergence. However, this technique is not suitable in a Residual Distribution framework. The use of a correcting variable coupled to the equations was then the best choice. Following the works of Dedner, Munz et al. [2], we modified the system

$$\begin{aligned} \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) &= 0 \\ \frac{\partial (\rho \mathbf{u})}{\partial t} + \nabla \cdot \left(\rho \mathbf{u} \mathbf{u}^t + \left(p + \frac{\mathbf{B}^2}{2} \right) Id - \mathbf{B} \mathbf{B}^t \right) &= \mathbf{0} \\ \frac{\partial E}{\partial t} + \nabla \cdot \left(\left(E + p + \frac{\mathbf{B}^2}{2} \right) \mathbf{u} - (\mathbf{u} \cdot \mathbf{B}) \mathbf{B} \right) &= 0 \end{aligned}$$

$$\frac{\partial \mathbf{B}}{\partial t} + \nabla \cdot (\mathbf{u} \mathbf{B}^t - \mathbf{B} \mathbf{u}^t + \psi Id) = \mathbf{0} \quad (1a)$$

$$\frac{\partial \psi}{\partial t} + c_h^2 \nabla \cdot \mathbf{B} = -\frac{c_h^2}{c_p^2} \psi \quad (1b)$$

Both classical and new systems can be reformulated in a quasi-linear form involving diagonalizable Jacobean matrices. This means they are hyperbolic systems of PDEs, as we only need to work with real quantities.

$$\frac{\partial U}{\partial t} + \mathbf{K} \cdot \nabla U = 0$$

where $\mathbf{K} = (A \ B \ C)^t$ is a vector of Jacobian matrices, U being the vector of the conservative variables.

Considering an arbitrary direction \mathbf{n} , we are interested in studying K_n , the projection of the Jacobian matrices. The eigenvalues of K_n for the corrected system consist of the classical transport, slow and fast magneto-sonic and Alfvén

waves, and of new divergence waves. Respectively $\lambda_1 = u_n$, $\lambda_{\pm s} = u_n \pm c_s$, $\lambda_{\pm f} = u_n \pm c_f$, $\lambda_{\pm a} = u_n \pm c_a$, $\lambda_{\pm h} = \pm c_h$ where u_n is the dot product of the velocity and the vector \vec{n} .

Noting $a = \sqrt{\frac{\gamma p}{\rho}}$, $b = \sqrt{\frac{B^2}{\rho}}$ and $b_n = \frac{\mathbf{B} \cdot \mathbf{n}}{\sqrt{\rho}}$, the wave speeds are given by $c_s = \sqrt{\frac{1}{2} \left(a^2 + b^2 - \sqrt{(a^2 + b^2)^2 - 4a^2 b_n^2} \right)}$, $c_f = \sqrt{\frac{1}{2} \left(a^2 + b^2 + \sqrt{(a^2 + b^2)^2 - 4a^2 b_n^2} \right)}$ and $c_a = b_n$.

Remark 2.1 *Alfvén waves only appear in the three-dimensional case.*

As we may need some characteristic decompositions in the numerical methods, we are also looking for the full eigensystem of K_n , that is to say the left and right eigenvectors. Unfortunately, the direct formal calculation of these vectors is really complex. It was early found [6] that the Ideal MHD system could be symmetrized by adding some source terms proportional to $\nabla \cdot \mathbf{B}$, hence not modifying the physical solutions of the equations.

For the corrected system, adding the same source terms doesn't make it symmetrizable. In fact, if we look at the last two eigenvalues, we note that the system does not even achieve Galilean invariance. Then, in [2], the authors proposed to add some symmetrizing terms so that this last property be recovered, depending on the gradient of ψ .

Moreover, as we make unsteady computations, the time t truly denotes the physical time and we aim to get a divergence-free solution at each physical time step. Then we drop the time derivative from the last equation (1b), which actually corresponds to the converged form of the equation : $\nabla \cdot \mathbf{B} = -\frac{\psi}{c_p^2}$. This will provide a definition of our numerical divergence.

The Jacobian K_n^* of the symmetrizable system is

$$K_n^* = \begin{pmatrix} 0 & \mathbf{n}^t & 0 & \mathbf{0}^t & 0 \\ (\gamma - 1) \frac{\mathbf{u}^2}{2} \mathbf{n} - u_n \mathbf{u} & (1 - \gamma) \mathbf{n} \mathbf{u}^t + \mathbf{u} \mathbf{n}^t + u_n Id & (\gamma - 1) \mathbf{n} & (2 - \gamma) \mathbf{n} \mathbf{B}^t - B_n Id & \mathbf{0} \\ (K_n^*)_{5,1} & \frac{H}{\rho} \mathbf{n}^t + (1 - \gamma) u_n \mathbf{u}^t - \frac{B_n}{\rho} \mathbf{B}^t & \gamma u_n & (2 - \gamma) u_n \mathbf{B}^t - B_n \mathbf{u}^t & B_n \\ \frac{B_n \mathbf{u} - u_n \mathbf{B}}{\rho} & \frac{B \mathbf{n}^t - B_n Id}{\rho} & \mathbf{0} & u_n Id & \mathbf{n} \\ 0 & \mathbf{0}^t & 0 & c_h^2 \mathbf{n}^t & u_n \end{pmatrix}$$

where $H = E + p + \frac{B^2}{2}$ is the enthalpy, $c = \sqrt{\frac{\gamma p}{\rho}}$ the classical sound speed for the Euler equations, and $(K_n^*)_{5,1} = u_n \left((\gamma - 1) \frac{\mathbf{u}^2}{2} - \frac{H}{\rho} \right) + \frac{B_n}{\rho} \mathbf{u} \cdot \mathbf{B}$.

As we said the system was verifying Galilean invariance (we'll see it after the symmetrization), the last eigenvalue has become $\lambda_{\pm h} = u_n \pm c_h$.

2.2. A note on the role of ψ . Like in [2], we prefer using the generalized Lagrange Multiplier (**GLM**) approach with a mixed hyperbolic-parabolic correction. It offers both transport and dissipative (smoothing) properties, which can be seen by rewriting the last equation in terms of ψ . First, one has to note that the divergence of equation (1a) gives

$$\partial_t (\nabla \cdot \mathbf{B}) + \Delta \psi = 0.$$

Then, taking the time derivative of equation (1b), we get the Telegraph equation

$$\frac{\partial^2 \psi}{\partial t^2} + \frac{c_h^2}{c_p^2} \frac{\partial \psi}{\partial t} - c_h^2 \Delta \psi = 0. \quad (2)$$

Consequently, the ratio $\frac{c_h}{c_p}$ gives a control on the balance between parabolic and hyperbolic behaviors.

2.3. Symmetrization Starting from the symmetrizable system, we followed Jameson's work [7] to get a set of symmetrizing variables W satisfying

$$dW = \left(\frac{dp}{c^2}, \frac{\rho}{c} du, \frac{\rho}{c} dv, \frac{\rho}{c} dw, \frac{dp}{c^2} - d\rho, \frac{\sqrt{\rho}}{c} dB_x, \frac{\sqrt{\rho}}{c} dB_y, \frac{\sqrt{\rho}}{c} dB_z, \frac{\sqrt{\rho}}{c} \frac{d\psi}{c_h} \right)^t.$$

Denoting $h = \frac{c^2}{\gamma-1} + \frac{\mathbf{u}^2}{2}$ and $\beta = \frac{\gamma-1}{c^2}$, the transformation matrices $\frac{\partial U}{\partial W}$ and $\frac{\partial W}{\partial U}$ are easily found. The symmetrized Jacobian is given by $K_s = \frac{\partial W}{\partial U} K_n^* \frac{\partial U}{\partial W}$

$$K_s = \begin{pmatrix} u_n & c\mathbf{n}^t & 0 & \mathbf{0}^t & 0 \\ c\mathbf{n} & u_n Id & \mathbf{0} & \frac{\mathbf{n}\mathbf{B}^t - B_n Id}{\sqrt{\rho}} & 0 \\ 0 & \mathbf{0}^t & u_n & \mathbf{0}^t & 0 \\ \mathbf{0} & \frac{\mathbf{B}\mathbf{n}^t - B_n Id}{\sqrt{\rho}} & \mathbf{0} & u_n Id & c_h \mathbf{n} \\ 0 & \mathbf{0}^t & 0 & c_h \mathbf{n}^t & u_n \end{pmatrix}$$

Here we see clearly that Galilean invariance is achieved, as $K_s = u_n Id + K_s|_{u_n=0}$. We are then able to calculate the full eigensystem of this matrix, and so of K_n^* .

2.4. The numerical scheme. Our framework is the RD approach, which principles are known as

1. Integrating the unsteady equations over the contour of an element T to get the so-called "residual" Φ^T ,
2. Distributing it to each node of the element $\rightarrow \Phi_i^T$,
3. For each node of the mesh, adding all partial residuals and solving

$$\sum_{T, i \in T} \Phi_i^T = 0.$$

Details can be found in [4], we only recall here the more important points and how they adapt to the MHD equations.

While the first step basically relies on a quadrature formula conditioning the formal accuracy of the whole scheme, all RD schemes differ from each other by their second step. For our purpose, we only deal with the Rusanov scheme. The pure one consists in distributing the residuals in the following way

$$\Phi_i^T = \frac{1}{N_s} \left(\Phi^T + \alpha \sum_{j \in T} (U_i - U_j) \right)$$

where N_s is the number of nodes in the element and α is the maximum of all the eigenvalues of K_n (not K_n^* !). Since α strongly conditions the behavior of the scheme, we have to take care about the value we impose for c_h : it shouldn't not be greater than the fastest physical wave. Here, it means we have to choose $c_h < c_f$.

We prefer another definition for the unsteady Rusanov scheme

$$\Phi_i^T = \frac{1}{N_s} \left(\left(\frac{\partial u^h}{\partial t} \right)_i + \int_T \operatorname{div} \mathbf{F}(U) + \alpha \sum_{j \in T} (U_i - U_j) \right) \quad (3)$$

This distribution has very interesting properties [4]. Of course, it is necessarily conservative as $\sum_{i \in T} \Phi_i^T = \Phi^T$. But its main advantage remains in its strong positivity, ensured by the choice of α , making it capturing shocks very well and in a monotonic manner.

For the time discretization, we choose the Gear implicit scheme so that we get, in the case of a constant time step Δt

$$\left(\frac{\partial u^h}{\partial t}\right)_i^{Gear} = \frac{3}{2} \frac{U_i^{n+1} - U_i^n}{\Delta t} - \frac{1}{2} \frac{U_i^n - U_i^{n-1}}{\Delta t}$$

$$\Phi_i^T = \frac{1}{N_s} \left(\left(\frac{\partial u^h}{\partial t}\right)_i^{Gear} + \int_T \operatorname{div} \mathbf{F}(U)^{n+1} + \alpha \sum_{j \in T} (U_i^{n+1} - U_j^{n+1}) \right)$$

However, it results in a first order scheme. In order to get, formally, the second order of accuracy, we have to turn it into a modified nonlinear scheme [4].

First, let us recall that all RD schemes can be rewritten like it : $\Phi_i^T = \beta_i^T \Phi^T$. The idea is to modify β_i^T so that we ensure it is bounded, and then we know that Φ_i^T and Φ^T are of the same order of accuracy, e.g. second order if the quadrature formula is so. This nonlinear process is called the ‘‘Limitation’’. The bounding of these coefficients also improves the monotonicity of the solution. In fact, we can still improve this by projecting the residuals Φ_i^T in the basis of the eigenvectors of K_n^* , which provides better conditioned β_i^T . However, the limitation application does not preserve the solenoidal character of the magnetic field, and that is why the correction technique is **absolutely necessary** even in simple test cases : with its use, the method effectively converges to a divergence-free behavior.

Second, we have to ensure that the convergence of the algorithm chosen for the third step will be good enough. In other words, we want a good conditioning for the system to solve. A way to do that, is to add a SUPG-like term S_i^T providing an upwind bias to our discretization [4]. Indeed, the basic distribution of the Rusanov scheme doesn’t respect upwinding and we have no control on it. That’s why it may be even possible that a node doesn’t receive information **at all** from the surrounding elements. Nevertheless, as the effect of this term is also to smooth out the regular solutions, we don’t apply this near discontinuities. In fact we use a shock sensor θ^T . This addition is called the ‘‘Stabilization’’. One possible expression is $S_i^T = -\frac{\theta^T}{d} K_i N \Phi^T$, where d is the number of space dimensions and N is the matrix of the Narrow scheme (see e.g. [1]), for which the knowledge of the eigensystem is required. The limited and stabilized Rusanov scheme, $\Phi_i^T = (\beta_i^{Rus})^* \Phi^T + S_i^T$, achieves second order of accuracy when converged.

We recall that we expect, like in [3], that the use of the symmetrizable (non-conservative) system in the limitation and the stabilization, instead of the eigen-system of the conservative equations (actually solved), should not affect the quality of the solution.

The third step, gathering all the signals and finding the zero for each node-associated problem, is performed by mean of an iterative Newton method, which solves a linear problem in each iteration.

3. Results

3.1. The Rotor problem This test, taken from [8], involves strong oblique Alfvén waves rising from a rotating high density region in the center of the domain. At the beginning, the ambient fluid is light and static. The whole domain is under

the effect of an initially uniform magnetic field in the x -direction. The problem takes place in a two dimensional unit square containing 200×200 cells. The two parts of the plasma have the same pressure $p = 1$, magnetic field $B_x = 5$ and $B_y = 0$. The central region, inside a radius $r = 0.1$, has a 10 units density and spins at a constant rotating speed $\omega = 2$. From $r = 0.1$ to 0.115 , the density decreases linearly from 10 to 1, so that we have no real discontinuity (to avoid a strong shock). The ratio of specific heats is $\gamma = 1.4$, and we set $c_h = 1$ and $c_p = 10$. On Figure 1, we show the solution at time 0.18, when the waves reach the boundary (arbitrarily considered as opened).

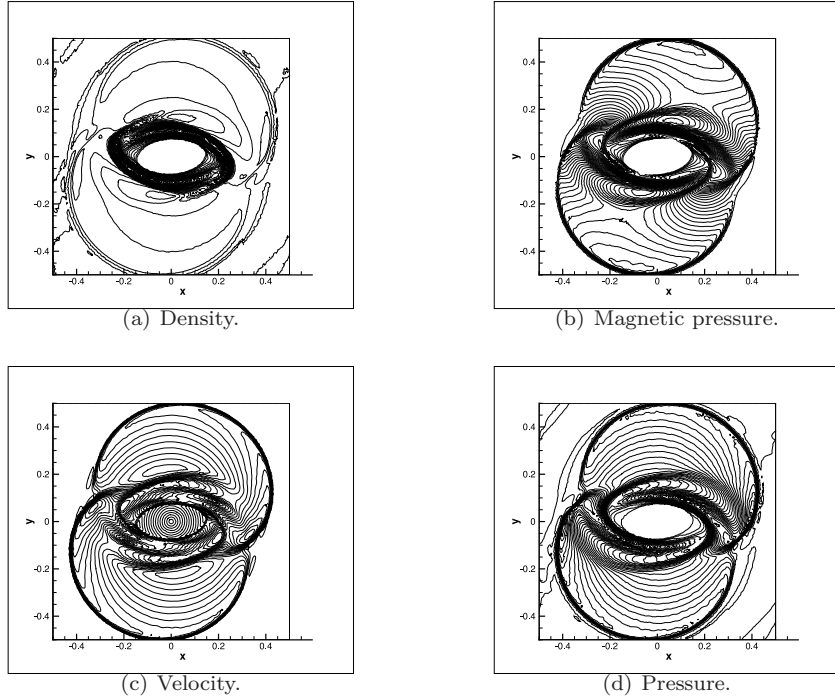


Figure 1: A rotor involving torsional waves.

3.2. The Blast problem Also inspired from [8], this simulation introduces a very strong shock wave coming from a central high pressure zone. We use the same mesh as before. The plasma is entirely exposed to a strong magnetic field along the x -direction so that the particles, for most of them, are constrained to move parallel to it. Hence we expect to get two fronts moving along x until they reach the opened boundaries. Initially, the uniform magnetic field is $B_x = 100$ and $B_y = 0$, the density is 1 and the velocity vector $\mathbf{0}$ everywhere. Inside the central zone, inside a radius $r = 0.1$, we set the hydrodynamic pressure $p = 1000$, which falls immediately to 0.1 outside this region. We keep the same γ and we set $c_h = 10$ and $c_p = 100$. In Figure 2, we show the solution at time 0.1. This problem has been run without stabilization, causing the solution to wiggle a little.

4. Conclusion and perspectives We have got an efficient solver for 2D Ideal MHD problems. However, more tests will be necessary, and we will look for

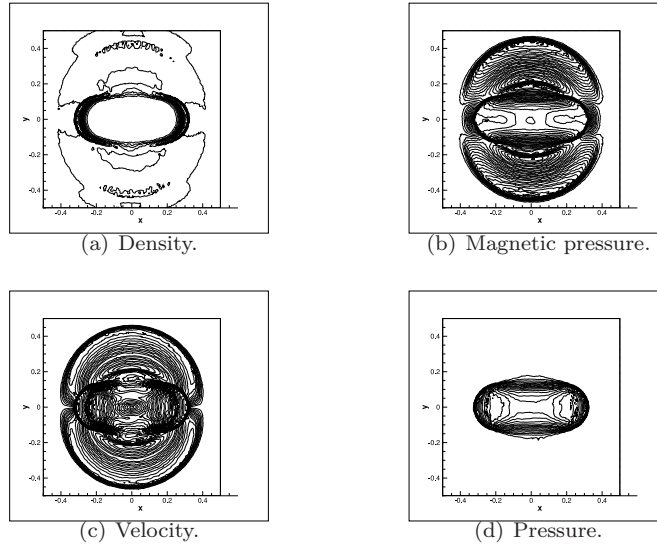


Figure 2: A blast explosion with fast shock waves.

possible improvements of the stabilization procedure. The code is also expected to work in three dimensional cases. We started to implement the resistive MHD equations by using a Continuous Galerkin method, which has not been tested yet. We aim at simulating plasma instabilities for ITER configurations.

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