

Controlled Term Rewriting

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Analysis of term rewriting under strategies with tree automata techniques

Innermost is analogous of *call by value*, [Rety Vuotto JSC 05], [Gascon, Godoy, Jacquemard WRS 08]

Outermost is analogous of *call by name*, [Rety Vuotto JSC 05]

Context-sensitive is used for *if...then...else* [Kojima Sakai RTA 08]

Bottom-up [Durand Senizergues Sylvestre RTA 07,10,11]

Node selection explicit definition of rewrite positions

e.g. with XPath in XML transformation languages

[Jacquemard Rusinowitch PPDP 10]

- XQuery Update Facility, W3C recommendation.
- Analysis of Access Control Policies.

- Formalization of controlled term rewriting systems (CntTRSs)
- Showing decidable or undecidable properties about reachability or model checking problem for CntTRSs.
 - Monotonic CntTRSs,
 - Prefix CntTRSs,
 - Non-monotonic CntTRSs, and
 - Recursive prefix CntTRSs.

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Tree automaton (TA)

The automaton that accepts trees (terms).

Example (TA accepting $f(a, b)$)

TA $\mathcal{A} = \langle Q, F, \Delta \rangle$, $\mathcal{L}(\mathcal{A}) = \{f(a, b)\}$

- F (final states): $\{q_f\}$
- Δ (transition rules): $\{a \rightarrow q_1, b \rightarrow q_2, f(q_1, q_2) \rightarrow q_f\}$

$$f(a, b) \xrightarrow{\Delta} f(q_1, b) \xrightarrow{\Delta} f(q_1, q_2) \xrightarrow{\Delta} q_f \in F$$

Controlled term rewriting systems (CntTRSs)

A controlled rewrite rule $\mathcal{A} : l \rightarrow r$ is made of

- a Selection Automaton (SA) \mathcal{A} and
- a rewrite rule $l \rightarrow r$

Was introduced for string rewriting, see survey [Senizergues 93] and [Dassow, Paun, Sallomaa 97].

Definition (Selection automaton (Gottlob, Koch 04))

Quadruple $\langle Q, F, S, \Delta \rangle$ where $\langle Q, F, \Delta \rangle$ is TA and $S \subseteq Q$.

Example

$$R = \begin{cases} \mathcal{A}_1 & : a \rightarrow c \\ \mathcal{A}_2 & : b \rightarrow c \\ \mathcal{A}_3 & : f(x, y) \rightarrow g(x, y) \end{cases}$$

where

	Q	F	S		Δ
\mathcal{A}_1	$\langle \{q_1, q_2, q_f\}, \{q_f\}, \{q_1\}, \{a \rightarrow q_1, b \rightarrow q_2, f(q_1, q_2) \rightarrow q_f\} \rangle$				
\mathcal{A}_2	$\langle \{q_1, q_2, q_f\}, \{q_f\}, \{q_2\}, \{a \rightarrow q_1, b \rightarrow q_2, g(q_1, q_2) \rightarrow q_f\} \rangle$				
\mathcal{A}_3	$\langle \{q_1, q_2, q_f\}, \{q_f\}, \{q_f\}, \{c \rightarrow q_1, b \rightarrow q_2, f(q_1, q_2) \rightarrow q_f\} \rangle$				

$$f(a, b) \xrightarrow{R} f(c, b) \xrightarrow{R} g(c, b) \xrightarrow{R} g(c, c).$$

$$f(a, b) \xrightarrow{\mathcal{A}_1} f(q_1, b) \xrightarrow{\mathcal{A}_1} f(q_1, 2) \xrightarrow{\mathcal{A}_1} q_f$$

Example

$$R = \begin{cases} \mathcal{A}_1 & : a \rightarrow c \\ \mathcal{A}_2 & : b \rightarrow c \\ \mathcal{A}_3 & : f(x, y) \rightarrow g(x, y) \end{cases}$$

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\mathcal{A}_2	$\langle \{q_1, q_2, q_f\}, \{q_f\}, \{q_2\}, \{a \rightarrow q_1, b \rightarrow q_2, g(q_1, q_2) \rightarrow q_f\} \rangle$				
\mathcal{A}_3	$\langle \{q_1, q_2, q_f\}, \{q_f\}, \{q_f\}, \{c \rightarrow q_1, b \rightarrow q_2, f(q_1, q_2) \rightarrow q_f\} \rangle$				

$$f(a, b) \xrightarrow{R} f(c, b) \xrightarrow{R} g(c, b) \xrightarrow{R} g(c, c).$$

$$f(a, b) \xrightarrow{\mathcal{A}_1} f(q_1, b) \xrightarrow{\mathcal{A}_1} f(q_1, q_2) \xrightarrow{\mathcal{A}_1} q_f.$$

Example

$$R = \begin{cases} \mathcal{A}_1 & : a \rightarrow c \\ \mathcal{A}_2 & : b \rightarrow c \\ \mathcal{A}_3 & : f(x, y) \rightarrow g(x, y) \end{cases}$$

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\mathcal{A}_2	$\langle \{q_1, q_2, q_f\}, \{q_f\}, \{q_2\}, \{a \rightarrow q_1, b \rightarrow q_2, g(q_1, q_2) \rightarrow q_f\} \rangle$				
\mathcal{A}_3	$\langle \{q_1, q_2, q_f\}, \{q_f\}, \{q_f\}, \{c \rightarrow q_1, b \rightarrow q_2, f(q_1, q_2) \rightarrow q_f\} \rangle$				
	$f(a, b) \xrightarrow{R} f(c, b) \xrightarrow{R} g(c, b) \xrightarrow{R} g(c, c).$				

$$f(c, b) \xrightarrow{\mathcal{A}_3} f(q_1, b) \xrightarrow{\mathcal{A}_3} f(q_1, q_2) \xrightarrow{\mathcal{A}_3} q_f.$$

Example

$$R = \begin{cases} \mathcal{A}_1 & : a \rightarrow c \\ \mathcal{A}_2 & : b \rightarrow c \\ \mathcal{A}_3 & : f(x, y) \rightarrow g(x, y) \end{cases}$$

where

	Q	F	S	Δ
$\mathcal{A}_1 =$	$\langle \{q_1, q_2, q_f\}, \{q_f\}, \{q_1\}, \{a \rightarrow q_1, b \rightarrow q_2, f(q_1, q_2) \rightarrow q_f\} \rangle$			
$\mathcal{A}_2 =$	$\langle \{q_1, q_2, q_f\}, \{q_f\}, \{q_2\}, \{a \rightarrow q_1, b \rightarrow q_2, g(q_1, q_2) \rightarrow q_f\} \rangle$			
$\mathcal{A}_3 =$	$\langle \{q_1, q_2, q_f\}, \{q_f\}, \{q_f\}, \{c \rightarrow q_1, b \rightarrow q_2, f(q_1, q_2) \rightarrow q_f\} \rangle$			

$$f(a, b) \xrightarrow{R} f(c, b) \xrightarrow{R} g(c, b) \xrightarrow{R} g(c, c).$$

$$g(c, b) \xrightarrow{\mathcal{A}_2} g(q_1, b) \xrightarrow{\mathcal{A}_2} g(q_1, q_2) \xrightarrow{\mathcal{A}_2} q_f.$$

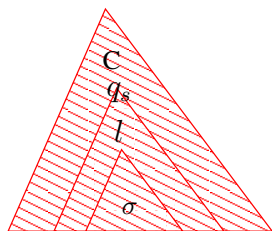
Definition (Rewriting by CntTRS)

$s \xrightarrow{R} t$ by the rewrite rule $\mathcal{A} : l \rightarrow r$ for a CntTRS R if

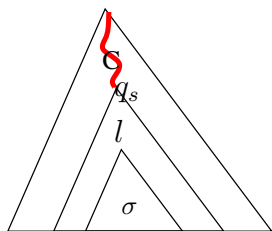
$$s = C[l\sigma]_p, t = C[r\sigma]_p \text{ and } C[l\sigma]_p \xrightarrow{\mathcal{A}}^* C[q]_p \xrightarrow{\mathcal{A}}^* q^f.$$

where $q \in S$ and $q^f \in F$.

Prefix CntTRSs (pCntTRSs)



CntTRS



Prefix CntTRS

Red part in the above figures represent controlled part.

- CntTRS can control whole term.
- Prefix CntTRS can only control prefix.

Generality

(Context-sensitive TRS \leq) Prefix CntTRS \leq CntTRS.

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Reachability problem

- **Input** : Terms s, t and CntTRSs R .
- **Output** : Yes if $s \xrightarrow{*}_R t$, No otherwise.

Regular model-checking problem

- $R^*(L) = \{t \mid \exists s \in L. s \xrightarrow{*}_R t\}$
- **Input** : Regular tree language $L_{\text{in}}, L_{\text{err}}$ and CntTRSs R .
- **Output** : Yes $R^*(L_{\text{in}}) \cap L_{\text{err}} \neq \emptyset$, No otherwise.
Note that $R^*(L_{\text{in}})$ is the rewrite closure of L_{in} by R .

Classes of CntTRSs

Definition (Context-free (CF))

A rule $\mathcal{A} : l \rightarrow r$ is *context-free* if

- l is of the form $f(x_1, \dots, x_n)$ where x_1, \dots, x_n are distinct.

A CntTRS R is *context-free* if each rule of R is context-free.

Definition (Monotonic)

A rule $\mathcal{A} : l \rightarrow r$ is *monotonic* if

- $l \rightarrow r$ is of the form $C[x_1, \dots, x_n] \rightarrow D[x_1, \dots, x_n]$ where x_1, \dots, x_n are distinct variables and $|C| \leq |D|$.

A CntTRS R is *monotonic* if each rule of R is monotonic.

Definition (flat)

A rule $\mathcal{A} : l \rightarrow r$ is *flat* if

- the depth of l and r are zero or one.

A CntTRS R is *flat* if each rule of R is flat.

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Context-sensitive tree grammar (CSTG)

Definition (Tree grammar)

A *tree grammar* is a quadruple $\langle N, \Sigma, S, P \rangle$ that generates a tree language.

- Production rules are term rewriting rules over $N \cup \Sigma$.

Definition (Context-sensitive tree grammar)

Context-sensitive tree grammar (CSTG) is a tree grammar where

- each production rule is monotonic term rewriting rule,
- membership is PSPACE-complete, and
- emptiness is undecidable.

Theorem

Given a context-sensitive tree grammar (CSTG) G and a monotonic CntTRS R , we can construct a CSTG generating $R^(L(G))$.*

Corollary

Reachability is PSPACE-complete for monotonic CntTRSs.

Unary signature : Symbols of arity 1 and one constant \perp .

Proposition

Reachability is NLINSPACE-complete and regular model checking is undecidable for monotonic flat CntTRSs over unary signatures

Theorem

Given a context-sensitive tree grammar (CSTG) G and a monotonic CntTRS R , we can construct a CSTG generating $R^(L)$.*

Proof (sketch).

(a) Simulate rewrite rules (without control)

- to add a symbol $\langle a \rangle$ to N for each $a \in \Sigma$, and
- if $\mathcal{A} : l \rightarrow r \in R$ then add $\langle l \rangle \rightarrow \langle r \rangle$ to P where $\langle l \rangle$ can be obtained by replacing each symbol f in l by $\langle f \rangle$.

Since $l \rightarrow r$ is monotonic, $\langle l \rangle \rightarrow \langle r \rangle$ is also monotonic.

Proof (sketch).

(b) Simulate control of SA

- to add symbols of the form $\langle f, q \rangle$ to N where $f \in \Sigma$ and $q \in Q$, and
- to add the production rule $\langle f \rangle(\langle f_1, q_1 \rangle(\overline{x_1}), \dots, \langle f_n, q_n \rangle(\overline{x_n})) \rightarrow \langle f, q \rangle(\langle f_1, q_1 \rangle(\overline{x_1}), \dots, \langle f_n, q_n \rangle(\overline{x_n}))$ for $f(q_1, \dots, q_n) \rightarrow q \in \Delta$.

where Q and Δ are the set of states and transition rules of SA \mathcal{A} , respectively.



Proposition

Reachability is NLINSPACE-complete and regular model checking is undecidable for monotonic flat CntTRS over unary signatures.

Proof (Undecidability).

By reducing emptiness of a linear bounded automaton (LBA) to regular model checking of monotonic flat CntTRSs.

Proof (Undecidability).

Every configuration of LBA \mathcal{M} is represented by

$\|:a_1 \dots a_{j-1} \underline{a_j^p} a_{j+1} \dots a_n:\|$.

For the transition $\theta = ((a, p) \rightarrow (b, p', left))$ we associate the following rules:

$$\begin{aligned} \|\Gamma^* \underline{ca^p} \Gamma^*\| &: a^p(x) \rightarrow \langle a^p, \theta \rangle(x) \\ \|\Gamma^* \underline{c} \langle a^p, \theta \rangle \Gamma^*\| &: c(x) \rightarrow \langle c, \theta \rangle(x) \\ \|\Gamma^* \langle c, \theta \rangle \underline{\langle a^p, \theta \rangle} \Gamma^*\| &: \langle a^p, \theta \rangle(x) \rightarrow b(x) \\ \|\Gamma^* \underline{\langle c, \theta \rangle} b \Gamma^*\| &: \langle c, \theta \rangle(x) \rightarrow c^{p'}(x) \end{aligned}$$

where Γ is the input alphabet of \mathcal{M} .

$R^*(\|:S\Gamma^*\|) \cap (\|:F\Gamma^*\|) = \text{iff } L(\mathcal{M}) = \text{where } S \text{ and } F \text{ are start and final symbol of } \mathcal{M}, \text{ respectively.}$ □

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Proposition

For all CS tree language L over an unary signature Σ , there exists a CF non-collapsing pCntTRS R s.t. $L = R^*(\{c\}) \cap \mathcal{T}(\Sigma)$

Proof.

Every CS language can be generated by a CS grammar with rules of the forms $A \rightarrow BC, AB \rightarrow AC, A \rightarrow a$ ([Penttonen 74]).

CS grammar $G = \langle N, \Sigma, S, P \rangle$ is simulated by the following pCntTRS R :

$$R = \left\{ \begin{array}{l} \underline{c} : c \rightarrow S(\perp) \\ (N \cup \Sigma)^* \underline{A} : A(x) \rightarrow B(C(x)) \\ (N \cup \Sigma)^* \underline{AB} : B(x) \rightarrow C(x) \\ (N \cup \Sigma)^* \underline{A} : A(x) \rightarrow a(x) \end{array} \right.$$



Corollary

Reachability is PSPACE-complete and regular model checking is undecidable for CF-non-collapsing pCntTRS over unary signatures.

- Formalization of controlled term rewriting systems (CntTRSs)
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Proposition

Reachability is undecidable for flat CntTRS over unary signatures.

Proposition

Reachability is undecidable for ground CntTRSs.

Theorem

Reachability is decidable in PSPACE for flat non-collapsing pCntTRSs over unary signatures.

Proposition

Reachability is undecidable for flat CntTRS over unary signatures.

Proof.

Monotonic flat CntTRS simulate LBA.

Non-monotonic flat CntTRSs simulate LBA + tape end = TM.

Reducing halting problem of TM.

Tape end is simulated by the following rules:

- $:|| \rightarrow b:||$ and $b:|| \rightarrow :||$ where b is the blank symbol of TM.



Proposition

Reachability is undecidable for ground CntTRSs.

Proof.

- Simulating Turing Machine.
- By representing a word $a_1 \cdots a_n$ as right combs $f(a_1, f(\cdots f(a_n, \perp)))$.
- Simulate TM transitions by controlled rewrite rules of the form $\mathcal{A} : a \rightarrow a'$ where \mathcal{A} controls the neighborhood of a .



Flat non-collapsing pCntTRSs

Theorem

Reachability is decidable in PSPACE for flat non-collapsing pCntTRS over unary signatures.

Proof.

We show the claim: $u \xrightarrow{*}_R v$ iff $u = u_0 \xrightarrow{R} u_1 \xrightarrow{R} \cdots \xrightarrow{R} u_k = v$ with $|u_0|, \dots, |u_k| \leq \max(|u|, |v|)$.

(If part) Trivial.

(Only if part) Let $\max(|u|, |v|) = M$. Since R is prefix CntTRS,

$$\begin{array}{ccc} u_i = b_1 \cdots b_M & & u_i = b_1 \cdots b_M \\ \downarrow & & \downarrow \\ \text{if } \vdots & \text{then } \vdots & \\ \downarrow & & \downarrow \\ u_j = b'_1 \cdots b'_M \cdots b'_{n_j} & & u_j[\perp]_M = b'_1 \cdots b'_M \end{array}$$

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Example

$$\begin{cases} \mathcal{A}_1 : aa \rightarrow b \\ \mathcal{A}_2 : c \rightarrow d \end{cases} \quad \text{where} \quad \begin{cases} L(\mathcal{A}_1) = aa\Sigma^* \\ L(\mathcal{A}_2) = aaaa\Sigma^* \end{cases}$$

Then, with recursive control: $aaaac \xrightarrow{R} abc \xrightarrow{R} abd$.

- Since $aa \in L(\mathcal{A}_1)$, we have $aaaac \xrightarrow{R} abc$, and
- Since $aaaa \xrightarrow{R} abc$ and $aaaa \in L(\mathcal{A}_2)$, we have $abc \xrightarrow{R} abd$.

Definition (Rewriting by recursive pCntTRS)

$s \xrightarrow{R} t$ by the rewrite rule $\mathcal{A} : l \rightarrow r$ for a recursive pCntTRS R if

$$s = C[l\sigma]_p, t = C[r\sigma]_p, \exists D. D[x]_p \xrightarrow{*}_R C[x]_p \wedge D[l\sigma]_p \xrightarrow{*}_{\mathcal{A}} D[q_s]_p \xrightarrow{*}_{\mathcal{A}} q^f$$

where $q_s \in S$ and $q^f \in F$.

Controlled prefix must belong to the rewrite closure of a given regular language.

A result for recursive pCntTRSs

Theorem

Regular model-checking is decidable in EXPTIME for linear right-shallow recursive pCntTRS.

Proof.

By constructing an alternating tree automaton recognizing $R^*(L)$ for a given recursive pCntTRS R and a tree language L . □

Example

TA for initial term : $q_5 \xleftarrow{a} q_4 \xleftarrow{a} q_3 \xleftarrow{a} q_2 \xleftarrow{a} q_1 \xleftarrow{c} q_0 \xleftarrow{\perp}$

SA \mathcal{A}_1 : $u_2 \xleftarrow{a} u_1 \xleftarrow{a} u_s \xleftarrow{\perp, \Sigma} u_0 \xleftarrow{\Sigma} u_0$

SA \mathcal{A}_2 : $v_4 \xleftarrow{a} v_3 \xleftarrow{a} v_2 \xleftarrow{a} v_1 \xleftarrow{a} v_s \xleftarrow{\perp, \Sigma} v_0 \xleftarrow{\Sigma} u_0$

$$\frac{q_3 \xleftarrow{a} q_2 \xleftarrow{a} q_1 \text{ and } \mathcal{A}_1 : aa \rightarrow b \in R}{q_3 \wedge u_s \xleftarrow{b} q_1}$$

Example

TA for initial term : $q_5 \xleftarrow{a} q_4 \xleftarrow{a} q_3 \xleftarrow{a} q_2 \xleftarrow{a} q_1 \xleftarrow{c} q_0 \xleftarrow{\perp}$

SA \mathcal{A}_1 : $u_2 \xleftarrow{a} u_1 \xleftarrow{a} u_s \xleftarrow{\perp, \Sigma} u_0 \xleftarrow{\Sigma} u_0$

SA \mathcal{A}_2 : $v_4 \xleftarrow{a} v_3 \xleftarrow{a} v_2 \xleftarrow{a} v_1 \xleftarrow{a} v_s \xleftarrow{\perp, \Sigma} v_0 \xleftarrow{\Sigma} u_0$

$$\frac{v_2 \xleftarrow{a} v_1 \xleftarrow{a} v_s \text{ and } \mathcal{A}_1 : aa \rightarrow b \in R}{v_2 \wedge u_s \xleftarrow{b} v_s}$$

Example

TA for initial term : $q_5 \xleftarrow{a} q_4 \xleftarrow{a} q_3 \xleftarrow{a} q_2 \xleftarrow{a} q_1 \xleftarrow{c} q_0 \xleftarrow{\perp}$

SA \mathcal{A}_1 : $u_2 \xleftarrow{a} u_1 \xleftarrow{a} u_s \xleftarrow{\perp, \Sigma} u_0 \xleftarrow{\Sigma} u_0$

SA \mathcal{A}_2 : $v_4 \xleftarrow{a} v_3 \xleftarrow{a} v_2 \xleftarrow{a} v_1 \xleftarrow{a} v_s \xleftarrow{\perp, \Sigma} v_0 \xleftarrow{\Sigma} u_0$

$$\frac{q_1 \xleftarrow{c} q_0 \text{ and } \mathcal{A}_2 : c \rightarrow d \in R}{q_1 \wedge v_s \xleftarrow{d} q_0}$$

An example of construction of ATA

Example

with these transitions, we have the following runs for 2 descendants of $aaaac$

$$\begin{array}{ccccc} a & a & b & c & \perp \\ \left\{ \begin{array}{c} q_5 \\ u_2 \end{array} \right\} & \left\{ \begin{array}{c} q_4 \\ u_1 \end{array} \right\} & \left\{ \begin{array}{c} q_3 \\ u_s \end{array} \right\} & \left\{ \begin{array}{c} q_1 \\ u_0 \end{array} \right\} & \left\{ \begin{array}{c} q_0 \\ u_0 \end{array} \right\} \end{array}$$

$$\begin{array}{ccccc} a & a & b & d & \perp \\ \left\{ \begin{array}{c} q_5 \\ v_4 \\ u_2 \end{array} \right\} & \left\{ \begin{array}{c} q_4 \\ v_3 \\ u_1 \end{array} \right\} & \left\{ \begin{array}{c} q_3 \\ v_2 \\ u_s \end{array} \right\} & \left\{ \begin{array}{c} q_1 \\ v_s \\ u_0 \end{array} \right\} & \left\{ \begin{array}{c} q_0 \\ v_0 \\ u_0 \end{array} \right\} \end{array}$$

- Controlled TRS (CntTRS):
 - TRS with selection of rewrite positions using SA.
- Proved decidability or undecidability of reachability and regular model checking for classes CntTRSs.
 - Monotonic CntTRSs,
 - Prefix CntTRSs,
 - Non-monotonic CntTRSs, and
 - Recursive prefix CntTRSs.

- Reachability is decidable for ground pCntTRS and flat non-collapsing pCntTRS (not unary)?
 - Undecidable for ground CntTRSs.
 - Decidable for flat non-collapsing pCntTRSs over unary signatures
- Generalization of conditional grammars [Dassow et.al. 1997] to trees.
conditional grammar CF grammars s.t. production sequences can be restricted to a regular language.
- Generalization of CntTRS to unranked trees.
 - XML are represented by unranked trees.