



Modelling of seismic waves propagation in harmonic domain by hybridizable discontinuous Galerkin method (HDG)

M. Bonnasse-Gahot^{1,2}, H. Calandra³, J. Diaz¹ and S. Lanteri²

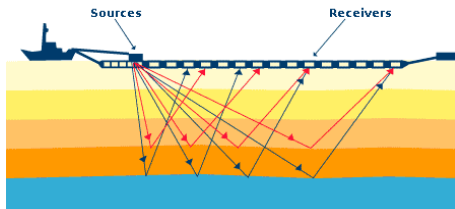
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³ TOTAL Exploration-Production

Motivation

Examples of seismic applications



Motivation

Imaging method : the full wave inversion

- ▶ Iterative procedure
- ▶ Inverse problem requiring to solve a **lot of forward problems**

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Seismic imaging : time-domain or harmonic-domain ?

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- ▶ Harmonic-domain : **imaging condition simple** but **huge computational cost**

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Forward problem of the inversion process

- ▶ Elastic wave propagation in harmonic domain : **Helmholtz equation**
- ▶ Reduction of the size of the linear system

Motivation

Seismic imaging in heterogeneous complex media

- ▶ Complex topography
- ▶ High heterogeneities

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DG method

- ▶ Flexible choice of interpolation orders (p – adaptativity)
- ▶ Highly parallelizable method
- ▶ Increased computational cost as compared to classical FEM

Motivation

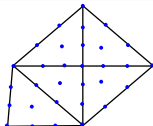
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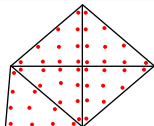
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DOF of classical FEM



DOF of DGM

Motivation

Objective of this work

- ▶ Development of an hybridizable DG (HDG) method
- ▶ Comparison with a reference method : a standard nodal DG method

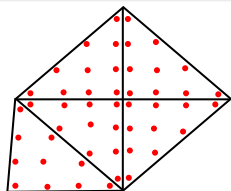


FIGURE : Degrees of freedom of DGM

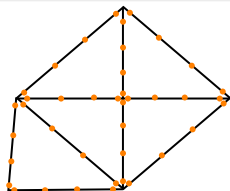


FIGURE : Degrees of freedom of HDGM

HDG methods

HDG methods

- ▶ **B. Cockburn, J. Gopalakrishnan, R. Lazarov** *Unified hybridization of discontinuous Galerkin, mixed and continuous Galerkin methods for second order elliptic problems*, SIAM Journal on Numerical Analysis, Vol. 47 (2009)
- ▶ **S. Lanteri, L. Li, R. Perrussel**, *Numerical investigation of a high order hybridizable discontinuous Galerkin method for 2d time-harmonic Maxwell's equations*, COMPEL, Vol. 32 (2013) (time-harmonic domain)
- ▶ **N.C. Nguyen, J. Peraire, B. Cockburn**, *High-order implicit hybridizable discontinuous Galerkin methods for acoustics and elastodynamics*, J. of Comput. Physics, Vol. 230 (2011) (time domain for seismic applications)

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Notations and definitions

Hybridizable Discontinuous Galerkin method

2D Numerical results

3D preliminary numerical results

Conclusions-Perspectives

3D Helmholtz elastic equations

First order formulation of Helmholtz wave equations

$$\mathbf{x} = (x, y, z) \in \Omega \subset \mathbb{R}^3,$$

$$\begin{cases} i\omega\rho(\mathbf{x})\mathbf{v}(\mathbf{x}) = \nabla \cdot \underline{\underline{\sigma}}(\mathbf{x}) + \mathbf{f}_s(\mathbf{x}) \\ i\omega\underline{\underline{\sigma}}(\mathbf{x}) = \underline{\underline{C}}(\mathbf{x}) \underline{\underline{\varepsilon}}(\mathbf{v}(\mathbf{x})) \end{cases}$$

- ▶ Free surface condition : $\underline{\underline{\sigma}}\mathbf{n} = 0$ on Γ_f
- ▶ Absorbing boundary condition : $\underline{\underline{\sigma}}\mathbf{n} = \mathbf{PAP}^T\mathbf{v}$ on Γ_a

- ▶ \mathbf{v} : velocity vector
- ▶ $\underline{\underline{\sigma}}$: stress tensor
- ▶ $\underline{\underline{\varepsilon}}$: strain tensor

3D Helmholtz elastic equations

First order formulation of Helmholtz wave equations

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-
- ▶ ρ : mass density
 - ▶ $\underline{\underline{C}}$: tensor of elasticity coefficients
 - ▶ v_p : P-wave velocity
 - ▶ v_s : S-wave velocity
 - ▶ f_s : source term, $f_s \in L^2(\Omega)$

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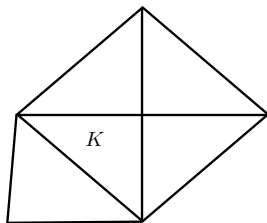
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Notations and definitions

Notations

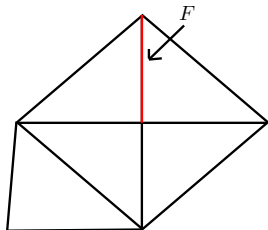
- ▶ \mathcal{T}_h mesh of Ω composed of tetrahedrons K



Notations and definitions

Notations

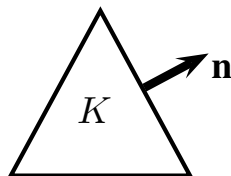
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- ▶ \mathcal{F}_h set of all faces F of \mathcal{T}_h



Notations and definitions

Notations

- ▶ \mathcal{T}_h mesh of Ω composed of tetrahedrons K
- ▶ \mathcal{F}_h set of all faces F of \mathcal{T}_h
- ▶ \mathbf{n} the normal outward vector of an element K



Notations and definitions

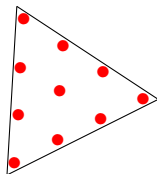
Approximations spaces

- ▶ $P_p(K)$ set of polynomials of degree at most p on K

Notations and definitions

Approximations spaces

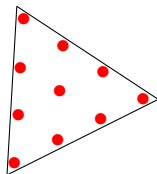
- ▶ $P_p(K)$ set of polynomials of degree at most p on K
- ▶ $\mathbf{V}_h^p = \{\mathbf{v} \in (L^2(\Omega))^3 : \mathbf{v}|_K \in \mathbf{V}^p(K) = (P_p(K))^3, \forall K \in \mathcal{T}_h\}$



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Approximations spaces

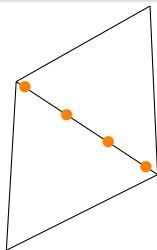
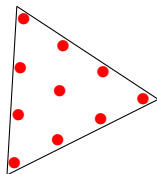
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- ▶ $\underline{\underline{\Sigma}}_h^p = \{\underline{\underline{\sigma}} \in (L^2(\Omega))^6 : \underline{\underline{\sigma}}|_K \in \underline{\underline{\Sigma}}^p(K) = (P_p(K))^6, \forall K \in \mathcal{T}_h\}$



Notations and definitions

Approximations spaces

- ▶ $P_p(K)$ set of polynomials of degree at most p on K
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- ▶ $\mathbf{M}_h = \{\eta \in (L^2(\mathcal{F}_h))^3 : \eta|_F \in (P_p(F))^3, \forall F \in \mathcal{F}_h\}$



Notations and definitions

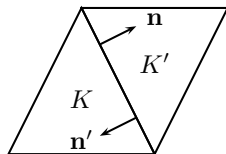
Definitions

- ▶ Jump $[[\cdot]]$ of a vector \mathbf{v} through F :

$$[[\mathbf{v}]] = \mathbf{v}^+ \cdot \mathbf{n}^+ + \mathbf{v}^- \cdot \mathbf{n}^- = \mathbf{v}^+ \cdot \mathbf{n}^+ - \mathbf{v}^- \cdot \mathbf{n}^+$$

- ▶ Jump of a tensor $\underline{\underline{\sigma}}$ through F :

$$[[\underline{\underline{\sigma}}]] = \underline{\underline{\sigma}}^+ \mathbf{n}^+ + \underline{\underline{\sigma}}^- \mathbf{n}^- = \underline{\underline{\sigma}}^+ \mathbf{n}^+ - \underline{\underline{\sigma}}^- \mathbf{n}^+$$



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HDG formulation of the equations

Local HDG formulation

$$\begin{cases} i\omega\rho\mathbf{v} - \nabla \cdot \underline{\underline{\sigma}} = 0 \\ i\omega\underline{\underline{\sigma}} - \underline{\underline{C}}\varepsilon(\mathbf{v}) = 0 \end{cases}$$

HDG formulation of the equations

Local HDG formulation

$$\left\{ \begin{array}{l} \int_K i\omega \rho^K \mathbf{v}^K \cdot \mathbf{w} + \int_K \underline{\underline{\sigma}}^K : \nabla \mathbf{w} - \int_{\partial K} \widehat{\underline{\underline{\sigma}}}^{\partial K} \cdot \mathbf{n} \cdot \mathbf{w} = 0 \\ \int_K i\omega \underline{\underline{\sigma}}^K : \underline{\underline{\xi}} + \int_K \mathbf{v}^K \cdot \nabla \cdot (\underline{\underline{C}}^K \underline{\underline{\xi}}) - \int_{\partial K} \widehat{\mathbf{v}}^{\partial K} \cdot \underline{\underline{C}}^K \underline{\underline{\xi}} \cdot \mathbf{n} = 0 \end{array} \right.$$

$\widehat{\underline{\underline{\sigma}}}^K$ and $\widehat{\mathbf{v}}^K$ are numerical traces of $\underline{\underline{\sigma}}^K$ and \mathbf{v}^K respectively on ∂K

HDG formulation of the equations

Local HDG formulation

$$\begin{cases} \int_K i\omega \rho^K \mathbf{v}^K \cdot \mathbf{w} + \int_K \underline{\underline{\sigma}}^K : \nabla \mathbf{w} - \int_{\partial K} \underline{\underline{\hat{\sigma}}}^{\partial K} \cdot \mathbf{n} \cdot \mathbf{w} = 0 \\ \int_K i\omega \underline{\underline{\sigma}}^K : \underline{\underline{\xi}} + \int_K \mathbf{v}^K \cdot \nabla \cdot (\underline{\underline{C}}^K \underline{\underline{\xi}}) - \int_{\partial K} \underline{\underline{\hat{v}}}^{\partial K} \cdot \underline{\underline{C}}^K \underline{\underline{\xi}} \cdot \mathbf{n} = 0 \end{cases}$$

We define :

$$\begin{aligned} \underline{\underline{\hat{v}}}^F &= \lambda^F, & \forall F \in \mathcal{F}_h, \\ \underline{\underline{\hat{\sigma}}}^{\partial K} \cdot \mathbf{n} &= \underline{\underline{\sigma}}^K \cdot \mathbf{n} - \tau \mathbf{l}(\mathbf{v}^K - \lambda^{\partial K}), & \text{on } \partial K \end{aligned}$$

where τ is the stabilization parameter ($\tau > 0$)

HDG formulation of the equations

Local HDG formulation

We replace $\hat{\mathbf{v}}^K$ and $(\hat{\underline{\underline{\sigma}}}^K \cdot \mathbf{n})$ by their definitions into the local equations

$$\left\{ \begin{array}{l} \int_K i\omega \rho^K \mathbf{v}^K \cdot \mathbf{w} + \int_K \underline{\underline{\sigma}}^K : \nabla \mathbf{w} - \int_{\partial K} \underline{\underline{\sigma}}^K \cdot \mathbf{n} \cdot \mathbf{w} \\ \quad + \int_{\partial K} \tau \mathbf{l} (\mathbf{v}^K - \lambda^{\partial K}) \cdot \mathbf{w} = 0 \\ \int_K i\omega \underline{\underline{\sigma}}^K : \underline{\underline{\xi}} + \int_K \mathbf{v}^K \cdot \nabla \cdot (\underline{\underline{C}}^K \underline{\underline{\xi}}) - \int_{\partial K} \lambda^{\partial K} \cdot \underline{\underline{C}}^K \underline{\underline{\xi}} \cdot \mathbf{n} = 0 \end{array} \right.$$

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Local HDG formulation

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We define :

$$\underline{\underline{W}}^K = \left(\underline{v}_x^K, \underline{v}_y^K, \underline{v}_z^K, \underline{\sigma}_{xx}^K, \underline{\sigma}_{yy}^K, \underline{\sigma}_{zz}^K, \underline{\sigma}_{xy}^K, \underline{\sigma}_{xz}^K, \underline{\sigma}_{yz}^K \right)^T$$

$$\underline{\underline{\Lambda}} = \left(\underline{\Lambda}^{F_1}, \underline{\Lambda}^{F_2}, \dots, \underline{\Lambda}^{F_{n_f}} \right)^T, \text{ where } n_f = \text{card}(\mathcal{F}_h)$$

Discretization of the local HDG formulation

$$\underline{\underline{A}}^K \underline{\underline{W}}^K + \underline{\underline{C}}^K \underline{\underline{\Lambda}} = 0$$

HDG formulation of the equations

Transmission condition

In order to determine λ^K , the continuity of the normal component of $\underline{\hat{\sigma}}^K$ is weakly enforced, rendering this numerical trace conservative :

$$\int_F \llbracket \underline{\hat{\sigma}}^K \cdot \mathbf{n} \rrbracket \cdot \eta = 0$$

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Replacing $(\underline{\hat{\sigma}}^K \cdot \mathbf{n})$ and summing over all faces, the transmission condition becomes :

$$\sum_{K \in \mathcal{T}_h} \int_{\partial K} (\underline{\hat{\sigma}}^K \cdot \mathbf{n}) \cdot \eta - \sum_{K \in \mathcal{T}_h} \int_{\partial K} \tau \mathbf{l} (\mathbf{v}^K - \lambda^{\partial K}) \cdot \eta = 0$$

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In order to determine λ^K , the continuity of the normal component of $\underline{\hat{\sigma}}^K$ is weakly enforced, rendering this numerical trace conservative :

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Discretization of the transmission condition

$$\sum_{K \in \mathcal{T}_h} [\mathbb{B}^K \underline{W}^K + \mathbb{L}^K \underline{\Lambda}] = 0$$

HDG formulation of the equations

Global HDG formulation

$$\left\{ \begin{array}{l} \int_K i\omega \rho^K \mathbf{v}^K \cdot \mathbf{w} - \int_K (\nabla \cdot \underline{\underline{\sigma}}^K) \cdot \mathbf{w} + \int_{\partial K} \tau \mathbf{l} (\mathbf{v}^K - \lambda^{\partial K}) \cdot \mathbf{w} = 0 \\ \int_K i\omega \underline{\underline{\sigma}}^K : \underline{\underline{\xi}} + \int_K \mathbf{v}^K \cdot \nabla \cdot (\underline{\underline{c}}^K \underline{\underline{\xi}}) - \int_{\partial K} \lambda^{\partial K} \cdot \underline{\underline{c}}_{K\xi} \cdot \mathbf{n} = 0 \\ \sum_{K \in \mathcal{T}_h} \int_{\partial K} (\underline{\underline{\sigma}}^K \cdot \mathbf{n}) \cdot \eta - \sum_{K \in \mathcal{T}_h} \int_{\partial K} \tau \mathbf{l} (\mathbf{v}^K - \lambda^{\partial K}) \cdot \eta = 0 \end{array} \right.$$

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Global HDG discretization

$$\left\{ \begin{array}{l} \mathbf{A}^K \underline{\underline{W}}^K + \mathbf{C}^K \underline{\underline{\Lambda}} = 0 \\ \sum_{K \in \mathcal{T}_h} [\mathbf{B}^K \underline{\underline{W}}^K + \mathbf{L}^K \underline{\underline{\Lambda}}] = 0 \end{array} \right.$$

HDG formulation of the equations

Global HDG formulation

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Global HDG discretization

$$\left\{ \begin{array}{l} \underline{\underline{W}}^K = -(\underline{\underline{A}}^K)^{-1} \underline{\underline{C}}^K \underline{\underline{\Lambda}} \\ \sum_{K \in \mathcal{T}_h} [\underline{\underline{B}}^K \underline{\underline{W}}^K + \underline{\underline{L}}^K \underline{\underline{\Lambda}}] = 0 \end{array} \right.$$

HDG formulation of the equations

Global HDG formulation

$$\left\{ \begin{array}{l} \int_K i\omega \rho^K \mathbf{v}^K \cdot \mathbf{w} - \int_K (\nabla \cdot \underline{\underline{\sigma}}^K) \cdot \mathbf{w} + \int_{\partial K} \tau \mathbf{l} (\mathbf{v}^K - \lambda^{\partial K}) \cdot \mathbf{w} = 0 \\ \int_K i\omega \underline{\underline{\sigma}}^K : \underline{\underline{\xi}} + \int_K \mathbf{v}^K \cdot \nabla \cdot (\underline{\underline{c}}^K \underline{\underline{\xi}}) - \int_{\partial K} \lambda^{\partial K} \cdot \underline{\underline{c}}_{K\xi} \cdot \mathbf{n} = 0 \\ \sum_{K \in \mathcal{T}_h} \int_{\partial K} (\underline{\underline{\sigma}}^K \cdot \mathbf{n}) \cdot \eta - \sum_{K \in \mathcal{T}_h} \int_{\partial K} \tau \mathbf{l} (\mathbf{v}^K - \lambda^{\partial K}) \cdot \eta = 0 \end{array} \right.$$

Global HDG discretization

$$\sum_{K \in \mathcal{T}_h} [-\mathbf{B}^K (\mathbf{A}^K)^{-1} \mathbf{C}^K + \mathbf{L}^K] \underline{\underline{\Lambda}} = 0$$

Main idea of the algorithm using the HDG formulation

1. Construction of the linear system $\mathbf{M}\underline{\Lambda}$

with $\mathbf{M} = \sum_{K \in \mathcal{T}_h} \left[-\mathbf{B}^K (\mathbf{A}^K)^{-1} \mathbf{C}^K + \mathbf{L}^K \right]$

for $K = 1$ to Nb_{tri} **do**

 Compute matrices \mathbf{B}^K , $(\mathbf{A}^K)^{-1}$, \mathbf{C}^K and \mathbf{L}^K

 Construction of the corresponding section of \mathbf{M}

end for

Main idea of the algorithm using the HDG formulation

-
1. Construction of the linear system $\mathbf{M}\underline{\Lambda}$
 2. Construction of the right hand side \mathbf{S}
-

Main idea of the algorithm using the HDG formulation

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1. Construction of the linear system $\underline{M}\underline{\Lambda}$
 2. Construction of the right hand side \underline{S}
 3. Resolution $\underline{M}\underline{\Lambda} = \underline{S}$
-

Main idea of the algorithm using the HDG formulation

-
1. Construction of the linear system $\underline{M}\underline{\Lambda}$
 2. Construction of the right hand side \underline{S}
 3. Resolution $\underline{M}\underline{\Lambda} = \underline{S}$
 4. Computation of the solutions of the initial problem

for $K = 1$ to Nb_{tri} **do**
 Compute $\underline{W}^K = -(\underline{A}^K)^{-1}\underline{C}^K\underline{\Lambda}$
end for

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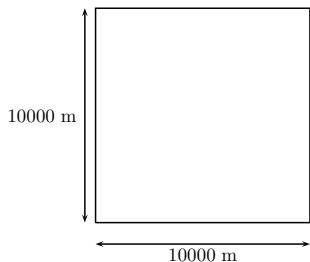
Plane wave in an homogeneous medium

Marmousi test-case

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Conclusions-Perspectives

Plane wave



Computational domain Ω
setting

► Physical parameters :

- $\rho = 2000 \text{ kg.m}^{-3}$
- $\lambda = 16 \text{ GPa}$
- $\mu = 8 \text{ GPa}$

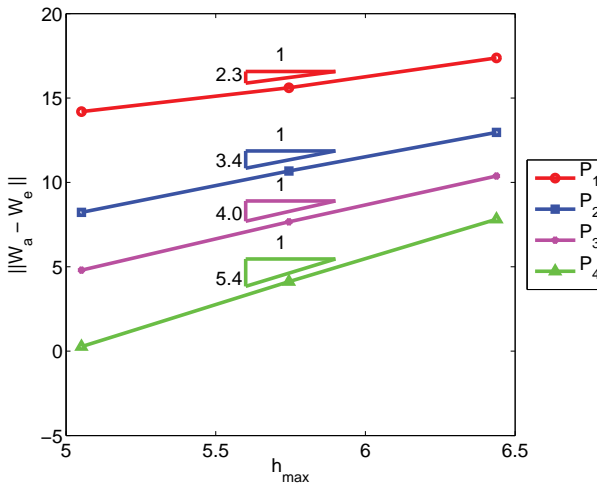
► Plane wave :

$$u = \nabla e^{i(k \cos \theta x + k \sin \theta y)}$$

where $k = \frac{\omega}{v_p}$

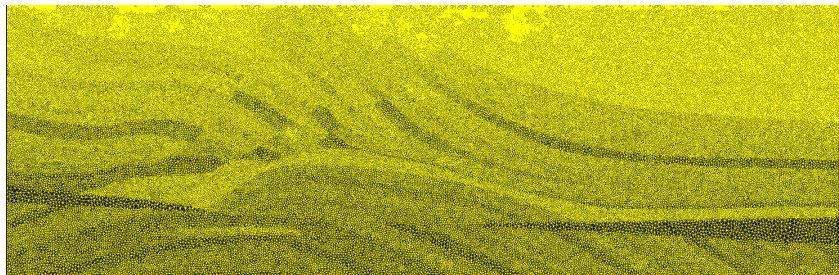
- $\theta = 0$
- Three meshes :
 - 3000 elements
 - 10000 elements
 - 45000 elements

Plane wave



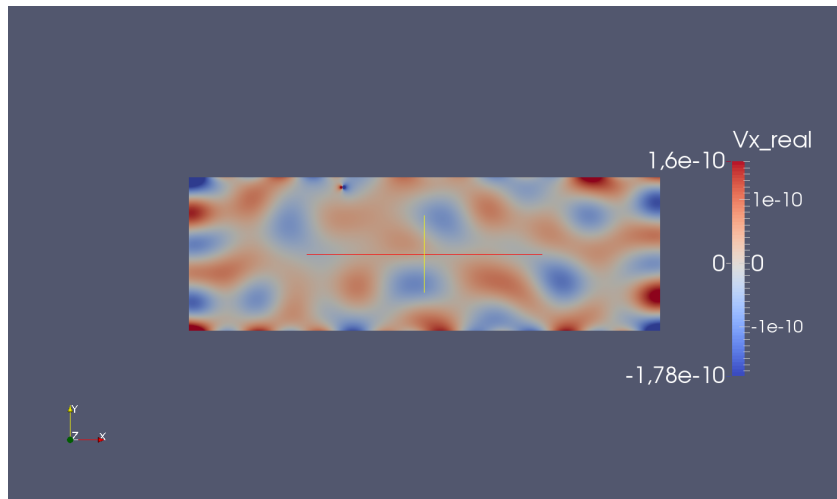
Convergence order of the HDG scheme

Marmousi test-case



Computational domain Ω composed of 235000 triangles

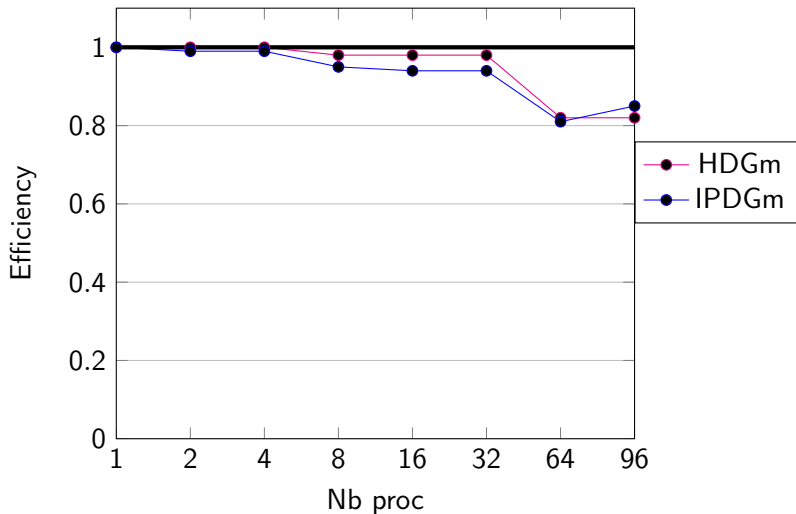
Parallel results for the Marmousi test-case with the HDG-P3 scheme, $f = 2\text{Hz}$



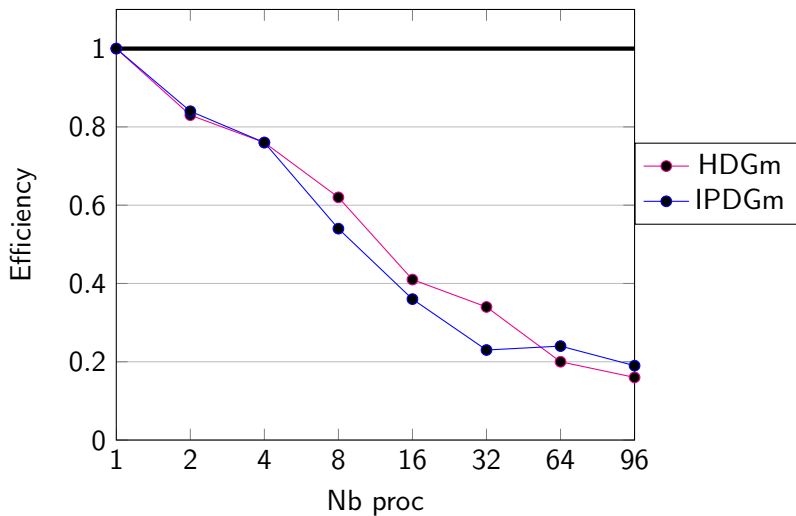
Characteristics of the computing processors used

- **Plafrim** platform
- Hardware specification : 16 nodes, 12 cores by nodes
- Characteristics of computing nodes :
 - ▶ 2 Hexa-core Westmere Intel[®] Xeon[®] X5670
 - ▶ Frequency : 2,93 GHz
 - ▶ Cache L3 : 12 Mo
 - ▶ RAM : 96 Go
 - ▶ Infiniband DDR : 20Gb/s
 - ▶ Ethernet : 1Gb/s

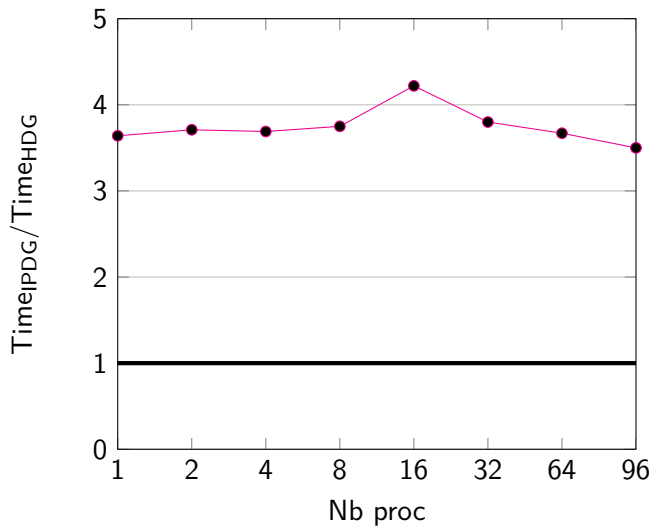
Efficiency of the parallelism of the global matrix construction



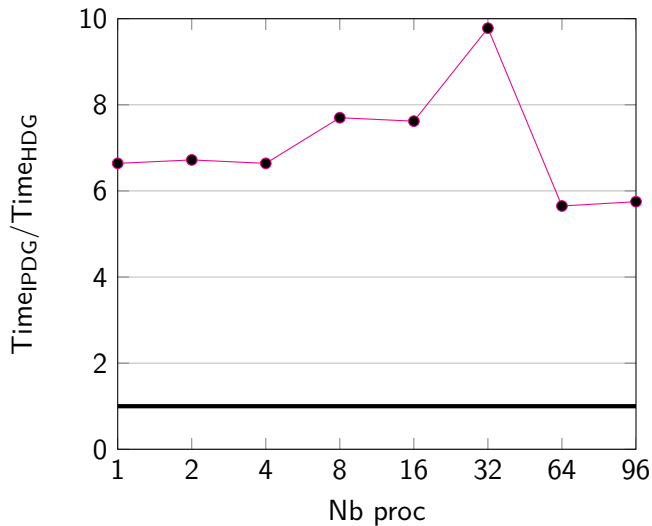
Efficiency of the parallelism of the whole algorithm



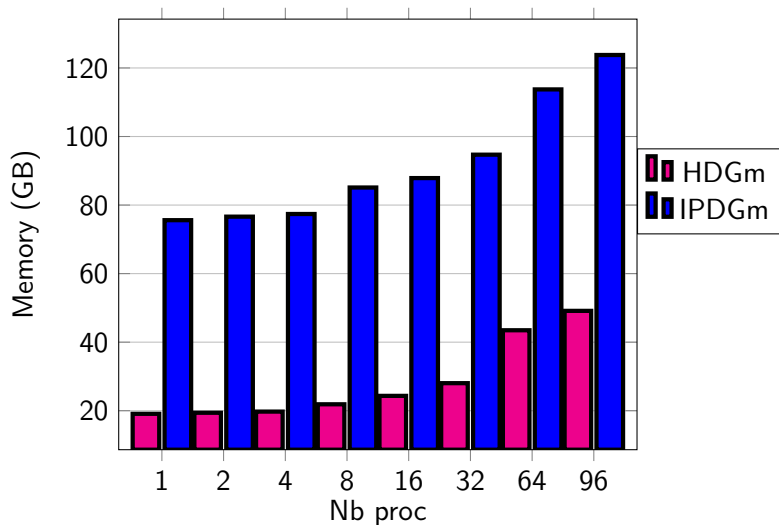
Speed up for the global matrix construction



Speed up (Total simulation time)



Memory required (GB) for the simulation



Contents

3D Helmholtz elastic equations

Notations and definitions

Hybridizable Discontinuous Galerkin method

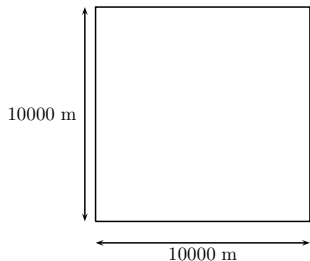
2D Numerical results

3D preliminary numerical results

Plane wave in an homogeneous medium

Conclusions-Perspectives

Plane wave



Computational domain Ω
setting

▶ Physical parameters :

- ▶ $\rho = 2000 \text{ kg} \cdot \text{m}^{-3}$
- ▶ $\lambda = 16 \text{ GPa}$
- ▶ $\mu = 8 \text{ GPa}$

▶ Plane wave :

$$u = \nabla e^{i(k \cos \theta x + k \sin \theta y)}$$

where $k = \frac{\omega}{v_p}$

- ▶ $\theta = 0$
- ▶ Two meshes :
 - ▶ 2600 elements
 - ▶ 6400 elements

3D preliminary numerical results

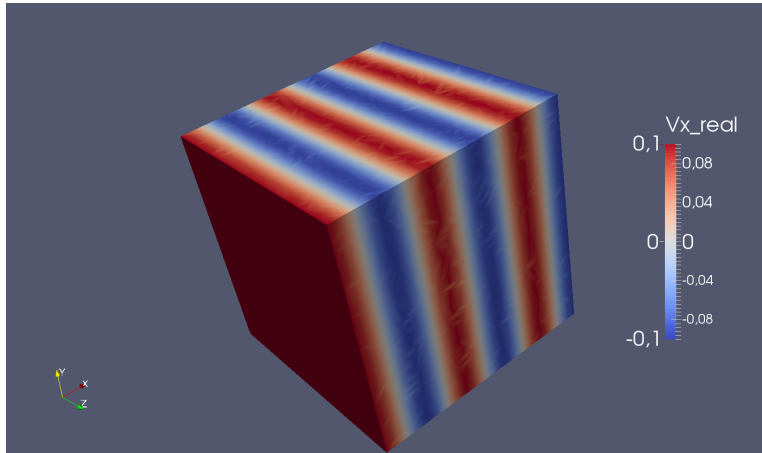


FIGURE : Exact solution

3D preliminary numerical results

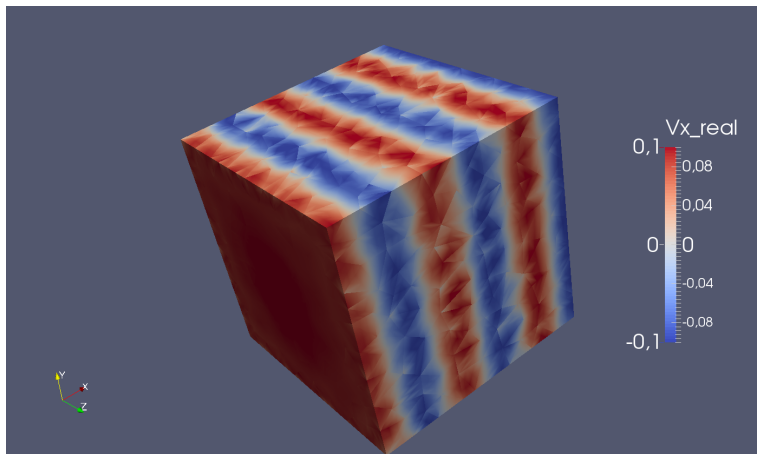


FIGURE : Numerical solution computed with P_3 -HDG scheme on mesh composed of 6400 tetrahedrons

Elements	Order	CPU Time (s)		Memory (MB)	
		HDG	IPDG	HDG	IPDG
2600	1	11		572	
6400	1	59		1981	
2600	2	91		2254	
6400	2	498		7894	
2600	3	508		6242	
6400	3	2386		21899	

Elements	Order	CPU Time (s)		Memory (MB)	
		HDG	IPDG	HDG	IPDG
2600	1	1	1.09	1	0.8
6400	1	1	0.9	1	0.8
2600	2	1	1.35	1	1.19
6400	2	1	1.83	1	1.35
2600	3	1	2.77	1	2.14
6400	3	1	4.35	1	2.19

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Conclusions

On a same mesh, with the 2D HDG method :

- ▶ Memory gain
- ▶ Computational time gain

Conclusions-Perspectives

Conclusions

On a same mesh, with the 2D HDG method :

- ▶ Memory gain
- ▶ Computational time gain

Perspectives

- ▶ Study of the 3D HDG algorithm for Helmholtz equations
- ▶ Solution strategy for the HDG linear system

Thank you !

The logo for Inria, featuring the word "inria" in a stylized, cursive font with a color gradient from red to orange. Above the "ria" part, the words "informatiques" and "mathématiques" are written in a smaller, sans-serif font, separated by a small star-like symbol.

inria
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