1	Model development and numerical analysis of a vertical falling
2	film absorption heat pump
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11	ABSTRACT: Traditional gas fired boilers and air-source heat pumps are not
12	efficient for heating when the outdoor temperature is low, while the air-source heat
13	pump is still one of the most promoting measures for building energy-efficient
14	heating. In this study, a novel air-source gas-fired absorption heat pump with vertical
15	falling film exchangers has been proposed for district heating. Compared with
16	conventional gas fired boilers, the proposed system has higher efficiency, since it can
17	absorb heat from the ambient air. A lumped and distributed parameter coupled
18	numerical model is established to analyze its thermodynamic performance, together
19	with a test rig established to validate the numerical model. Experimental results
20	indicated that when the evaporator temperature increased from -10 °C to -5 °C, the
21	coefficient of performance rose from 1.53 to 1.62, and heating capacity improved
22	from 36.88 kW to 45.32 kW. Additionally, the coupled model showed high
23	prediction accuracy, with the maximum error less than 8%. Due to the opposite
24	contributions of the supply water temperature and water flow rate to the coefficient
25	of performance, the genetic algorithm was adopted to identify the optimal solution of

a multi-objective optimization procedure. Results displayed that the proposed system
was feasible and efficient for heating in cold region under different operating
conditions.

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30 KEYWORDS: numerical analysis; coupled model; falling film heat transfer;
31 absorption heat pump

Nomenclature		Subsc	Subscript		
Cp	constant pressure specific heat $(J/kg \cdot K)$	abs	absorber		
COP	coefficient of performance	cond	condenser		
Cl_i	proximity index	evap	evaporator		
EEV	electronic expansion valve	env	environment		
ΔH_m	the heat of mixing of the R22-DEGDME (J/mol)	gen	generator		
h	specific enthalpy (J/kg)	he	heat exchanger		
Н	molar enthalpy (J/kg)	in	inlet		
J	heat equivalent of work $(g \cdot m/J)$	intf	interface		
М	molecular weight (g/mol)	ng	natural gas		
т	mass flow rate (g/s)	out	outlet		
Р	pressure (MPa)	r	refrigerant		
Q	heat transfer rate (kW)	S	strong		
Т	temperature (K)	W	weak/water		
t	temperature (°C)	Greek	symbols		
u	velocity in the x direction (m/s)	$\eta_{_b}$	boiler efficiency (%)		

v	velocity in the y direction (m/s)	μ	Dynamic viscosity (kg/m·s)
W_P	power input (kW)	ξ	mass concentration (%)
Y	molar concentration (%)	λ	Thermal conductivity $(W/m \cdot K)$
x,y	coordinate directions (m)	δ	film thickness (m)

1. Introduction

With the growth of the thermal comfort requirements and improvements of 34 human living standard, there has been a significant increase in building energy 35 consumption, accounting for 20.6% of China's total energy consumption (Liu et al., 36 2020). While in northern China, the proportion of energy consumed by the district 37 heating system in energy consumption of building sector is approximately 40%, 38 mainly relying on fossil fuel (Zhang et al., 2020). Burning these fuels, however, will 39 cause serious environmental issues, such as global warming and air pollution (Wu et 40 al., 2019). Decreasing the energy demand of buildings is one of the greatest 41 challenges for our society. However, according to the International Energy Agency 42 (IEA), building energy consumption rose by 39% from 2000 to 2018, and it is 43 expected to increase by more than 25% by 2040 (IEA., 2018). Therefore, the 44 development of clean energy technologies and efficient heating solutions becomes 45 necessary (Khalid R., 2019). As air is rich, clean and easy to access, many 46 researchers have been investigating in developing air-source solutions for district 47 heating (Wei et al., 2020). 48

In practice, the most efficient way of using the energy within the ambient air for

space heating is the heat pump technique, which can be categorized into two main 50 types: the air-source absorption heat pump (ASAHP) and the air-source compression 51 52 heat pump (ASCHP). The ASCHP systems have been widely studied by researchers. The coefficient of performance (COP) of the ASCHP systems can be higher than 3, 53 54 although it highly relies on the ambient air temperature. Since the ASCHP is driven by electricity, the power generation efficiency should also be considered, when 55 calculating the total COP from the primary energy (Lu et al., 2019). The ASAHP is 56 superior over the conventional ASCHP in energy saving, environmental protection 57 and low cost, since the total COP of the ASAHP from the primary energy is higher 58 than that of the ASCHP (Wu et al., 2016). Anna et al. (2014) found that the 59 absorption heat pump (AHP) has a lower impact on the environment than that of the 60 61 compression heat pump (CHP). Zhang et al. (2014) compared an AHP system and a CHP system under the uniform heating quantity condition. They indicated that the 62 district heating systems driven by AHP have lower energy consumption. With the 63 same heating capacity and heating conditions, the primary energy efficiency (PEE) 64 of the district heating systems driven by AHP can be higher for approximately 42% 65 than those driven by CHP. 66

Although AHP systems are efficient methods for district heating, there are still limitations when using it at low ambient temperature in cold regions. Garimella et al. (1996) indicated that the COP of the generator-absorber heat exchange systems will rise from 1.05 to 1.4, when the ambient temperature increases from -30 °C to 5.6 °C. Additionally, there are also some problems in choosing the working fluid. As the water-lithium bromide working fluid will freeze at evaporation temperature below
0 °C, while the ammonia-water working fluid is toxic and flammable. The two main
approaches for tackling these problems are designing novel systems and seeking for
new working fluids.

76 For designing novel systems, there have been numerous researches focused on absorption-compression hybrid heat pump systems, which are superior in working at 77 low evaporation pressure and high absorption pressure (Wu et al., 2016). Wu et al. 78 (2018) investigated a compression-assisted AHP to extend the applicable conditions 79 80 and improve the heating performance. Results showed that the primary energy efficiency of the compression-assisted AHP can be improved by 0.2-54% compared 81 with the conventional AHP. They also compared the thermodynamic performance of 82 83 AHP and compression-assisted AHP with different low-GWP working fluids. They indicated that the compression-assisted AHP can improve the absorption pressure 84 and strengthen absorption process, leading to higher concentration difference (Wu et 85 al., 2017). This form of system improves the system performance by adding a 86 compressor, which in turn increases its complexity and initial cost. Another 87 improvement measure is to recover the excess heat of the flue gas (Lu et al., 2020). 88 There is considerable amount of waste heat contained within the high temperature 89 flue gas (Shang et al., 2017). Hence, recovering the flue gas waste heat is an efficient 90 way to improve the system energy efficiency (Khalid R., 2019). But in many cases, 91 the recovered waste heat is utilized by heating the return water of the district heating 92 system, and sometimes the return temperature is higher than the dew point of the 93

flue gas, which will lead to inefficient utilization of the excess heat from the flue gas 94 (Yang et al., 2018). Qu et al. (2014) designed a gas-liquid heat exchanger for the 95 96 AHP system. Both latent heat and sensible heat of the flue gas are recovered by this system. They concluded that the heat recovery efficiency can be increased by 10%. 97 In addition, falling film heat exchangers applied in the AHP system has high heat 98 transfer coefficient under low heat flux compared with the conventional heat 99 exchangers in the refrigeration and air conditioning application (Hu et al., 2019). 100 Falling film heat exchangers with less working fluid and smaller size have been 101 102 widely used in AHP systems to achieve higher efficiency and lower cost (Robabeh et al., 2020). However, most existing literature mainly involves the numerical and 103 experimental investigation on the single heat exchange tube flow and heat transfer. 104 105 Bundles falling film heat exchange process is more dependent on heat exchange tubes steam direction and arrangement which have more complex mechanism of heat 106 transfer compared with single tube falling film. Saeed et al. (2021) investigated the 107 phase change mass transfer of the falling thin film on the surface of a vertical tube 108 and a series of remarkable evaporative heat transfer correlations are collected. Hu et 109 al. (2019) conducted a falling film heat exchanger simulation model applied to a 110 water vapor heat pump system. The temperature distributions of both the heat 111 exchanger and working tubes were obtained by finite element method. Liu et al. 112 (2017) proposed a system with four main vertical falling film heat exchangers and 113

the pressure increases from 190 kPa to 260 kPa, the bilateral falling film renders the

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set up a testing rig to examine the system's performance. They concluded that when

absorbers generate steam more easily. Cheng et al. (2020) studied the falling film heat transfer characteristics of vertical tubes based on a series of experiments, and developed a model to accurately predict the performance of falling film. Liu et al. (2021) established a falling film heat exchanger experiment rig to measure the outer circumferential distribution of local heat transfer coefficient. According to their experimental data, the local heat flux distribution on tube surfaces was obtained by numerical calculation.

The existing gaps of improving the performance of air-source AHP systems are 123 summarized as follows: 1) studies on new working fluid are needed, which can 124 operate with high efficiency under cold ambient conditions; 2) hybrid 125 absorption-compression heat pump systems is a good solution but with high cost 126 127 compared with single AHP systems; 3) studies on flue gas heat recovery utilization below dew point is rare; 4) studies on the heat exchanger process of falling films in 128 tube bundles are not sufficient. Therefore, this study has presented a novel gas-fired 129 absorption heat pump using air-source for district heating. The proposed system is 130 driven by natural gas and the working fluid is chosen as the R22-DEGDME. The 131 ASAHP system can operate at the evaporation temperature below -10 °C with higher 132 COP. To reduce the flow rate and pump power, both the absorber and generator are 133 considered as falling film heat exchangers, which have high heat transfer coefficients. 134 A coupled lumped parameter and distributed parameter numerical model is 135 developed to analyze the system performance, together with an experimental rig 136 designed for model validation. In addition, a multi-objective optimization approach 137

is applied to optimize the system performance using the NSGA-II approach and
TOPSIS decision-making method. This system provides a feasible and efficient
method to collect more energy from ambient air for district heating, and it is
technologically available in different heating capacities with the following
contributions:

143 1) The system can sufficiently recover the flue gas waste heat and operate at low144 outdoor temperature with high efficiency.

145 2) A coupled model with satisfied prediction accuracy including distributed146 parameter numerical and lumped parameter model has been established.

147 3) The two-dimensional distributed parameter models of the generator and absorber148 in the ASAHP system are proposed and validated.

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150 **2. System description**

151 **2.1. Fundamental**

A schematic diagram of the ASAHP systems is displayed in Fig. 1. The ASAHP 152 consists of three circuits, the black line for working fluid circuit, the blue line for the 153 hot water circuit, the green and purple lines for solution circuits. In the refrigerant 154 loop, the refrigerant vapor generates from the generator enters the condenser to heat 155 the supply water. The refrigerant vapor condenses into liquid and goes to the 156 reservoir. In the exchanger-II, the refrigerant vapor from the evaporator is heated by 157 the liquid refrigerant from the reservoir. Then the refrigerant condensing pressure 158 decreases to the evaporation pressure in the EEV. The low pressure and temperature 159

refrigerant is heated by the ambient environment in the evaporator. Finally, therefrigerant vapor from the evaporator turns to the absorber.



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Fig. 1 Schematic view of a typical ASAHP system

There are three working fluids which are refrigerant, strong solution and weak 164 solution. The strong solution contains more refrigerant with the refrigerant mass 165 fraction of 30%; while the weak solution contains less refrigerant with the refrigerant 166 mass fraction of about 18%. The whole circulation starts from the absorber. The 167 refrigerant vapor from the evaporator is absorbed by the weak solution in the 168 absorber, and becomes strong solution. The supply water is heated by the mixture of 169 the refrigerant vapor and weak solution. In the solution heat exchanger, the strong 170 solution extracted from the absorber exchange heat with the weak solution from the 171 generator. Then the strong solution pumped by the solution pump enters the 172

generator. The strong solution absorbs heat from the combustion of natural gas and 173 produces refrigerant vapor when the solution temperature reaches the refrigerant 174 175 boiling temperature. Then the refrigerant concentration of the solution decreases and the strong solution becomes weak solution. The weak solution goes to the solution 176 heat exchanger while the refrigerant vapor enters the condenser. The generator 177 pressure reduces to the absorber pressure by the EEV throttling process and the weak 178 solution is returned to the absorber. In the condenser and absorber, the return water 179 from the user is heated to the set supply water temperature. 180

181 According to the existing theoretical analysis, a test rig has been developed for the ASAHP system, as shown in Fig. 2. All the valves and two EEVs controlled by 182 independent controllers are opened before the startup of the system. Due to the 183 184 limitation of experimental conditions, the flue gas waste heat was not recovered, but left for future investigations. The experimental system runs based on the following 185 steps: 1) the combustion chamber is opened by the controller; 2) it turns on the fixed 186 volume solution pump and started the circulation of the solution, and 3) it starts fan 187 coils and water pumps to for water circulation. 188



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(a) Photo of the test bench



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(b) 3-D geometric model of the test bench

194 1-Evaporation, 2-Absorber, 3-EEV, 4-Combustor, 5-Condenser, 6-Fan coil, 7-Data acquisition

- 195 machine, 8-Generator, 9-Solution heat exchanger, 10-Solution pump, 11-Pressure meter,
- 196 12-Valve, 13-Chimney, 14-Reservoir, 15-Volume flowmeter, 16-Glass speculum, 17- Controller,

18-Water flowmeter





198

(c) Design drawings of absorber and generator

200

Fig.2 Test rig and design drawings of absorber and generator

201 Suitable selection of working fluids is significant which has the following advantages: 1) improving energy conversion efficiency; 2) reducing irreversible 202 destruction. AHP systems with ammonia-water and water-lithium bromide pairs have 203 204 been studied by many researchers. However, both working pairs have disadvantages. For example, a system with water-lithium bromide as the working fluid will not 205 work at an evaporation temperature below 0 °C because water freezes, which cannot 206 be used in cold regions (Nico et al., 2020). Ammonia, however, is flammable and 207 toxic (Yuan et al., 2018). In the air-source gas-fired AHP, the system with 208 ammonia-water as the working fluid has obvious hazards. Solution of 209 R22-DEGDME is non-toxic and non-flammable, which can work below the outdoor 210 temperature of 0 °C (Wu et al., 2020). This solution with high GWP and ODP, 211

however, cannot be extensively applied in the future (Ando et al., 1984). As system
with R22-DEGDME working pair has better operating performance, this, however,
indicates some different direction and operating guidance for system design and
working pair selection. According to the Kigali Amendment, R22 with high GWP
and ODP cannot be applied. In the Table A1, some properties of the solution are
displayed.

218 2.2. Experimental components and operating conditions

Table 1 presents the main equipment of the proposed system, and Table 2 displays the detailed experimental design conditions.

221 Table 1 Equipment of the proposed system

Equipment Types		Specifications
Heat exchanger-II	PL26-20	Heat load: 3 kW; heat exchanger area: 1.5 m ² .
Condenser	Double-pipe exchangers TH-SCE25	Heat load: 25 kW ; heat exchanger area: 12 m^2 .
Water pump	LRS-9	Flow rate: 0 -7.8 m ³ /h
Generator	Vertical falling film	Heat load: 24 kW; heat exchanger area: 0.36 m ² .
Absorber	Vertical falling film	Heat load: 15 kW; heat exchanger area: 1.2 m^2 .
Fan coil	BFP-70WD	Cooling capacity: 50 kW; air volume: 7000 m3/h
Evaporator	Finned tube exchanger DYGT-15	Heat load: 15 kW; heat exchanger area: 28 m ² .
Flowmeter	YH-LWGYJD	Flow rate: 0-6.62 m ³ /h
Solution heat exchanger	PL95-86	Heat load: 130 kW; heat exchanger area: 10 m ² .
EEV	PCH-SD1N-002	-
Pressure meter	RL-2088	-
Thermometer	PT-100	Pressure: -0.1 to 60 MPa
Solution pump	Metering pump TL-D1800	Flow rate: 1.74 m ³ /h
Data acquisition machine	GRAPHTEC-GL840	-

222

223 Table 2 System working conditions

Range

Condensing temperature

Variables

Evaporating temperature	-10 °C - 0 °C
Generator temperature	150 °C - 190 °C
Water flow rate	1.5 m³/h - 2.4 m³/h
Volume of the solution pump	70% - 100%

225 **2.3. Uncertainty analysis**

In the system shown in Figs. 1 and 2, temperature, flow rate and pressure are obtained by the data acquisition instrument in the experiment for further analysis. Therefore, uncertainty analysis becomes necessary to evaluate the experimental data. The total uncertainty is divided into random uncertainty and system uncertainty, as defined by Equation 1 (Lu et al., 2020),

$$\sigma_T = \sigma_R + \sigma_s \tag{1}$$

According to the uncertainty analysis theory, if there are *n* measured variables,

the related directly-measured parameters are applied to calculate the total uncertainty

233 (Lu et al., 2020). If y is a function of $x_1, x_2, ..., x_n$, as defined by Equation 2,

$$y = f(x_1, x_2, ..., x_n)$$
(2)

The function y total uncertainty can be calculated by Equation 3 (Lu et al., 2020),

$$\sigma_T = \sqrt{\left(\frac{\partial f}{\partial x_1}\sigma_{T,x_1}\right)^2 + \left(\frac{\partial f}{\partial x_2}\sigma_{T,x_2}\right)^2 + \dots + \left(\frac{\partial f}{\partial x_n}\sigma_{T,x_n}\right)^2} \tag{3}$$

Taking the heat load as an example, the total uncertainty could be written as follows(Lu et al., 2020),

$$Q = c_{p,w} \rho V(T_1 - T_2) \tag{4}$$

$$\sigma_{T} = \sqrt{\left(\frac{\partial f}{\partial V}\sigma_{T,V}\right)^{2} + \left(\frac{\partial f}{\partial T_{1}}\sigma_{T,T_{1}}\right)^{2} + \left(\frac{\partial f}{\partial T_{2}}\sigma_{T,T_{2}}\right)^{2}}$$

$$= c_{p,w}\rho\sqrt{\left(T_{1} - T_{2}\right)^{2}\sigma_{T,V} + V^{2}\left(\sigma_{T,T_{1}}^{2} + \sigma_{T,T_{2}}^{2}\right)}$$
(5)

3. Numerical model

238	Fig.3 displays the P-T and T-S figure of different processes. To analyze the
239	system performance, a coupled model including a lumped parameter model and a
240	distributed parameter model have been established, with the following assumptions
241	for simplification:
242	1) Both system components and thermodynamic processes are stable.
243	2) Constant pressure in the absorber and generator.
244	3) At the condenser and evaporator outlets, refrigerants are considered as
245	saturated.
246	4) Ignoring the pressure drop and heat loss (Lu et al., 2019).
247	5) The two-dimensional model for the heat and mass transfer process is
248	employed for the falling film absorber and generator.
249	6) The liquid and vapor flows are considered to be steady, laminar, and

250 Newtonian (Robabeh et al., 2018).



Fig. 3 P-T diagram of the ASAHP system

3.1. The coupled model

Solution equilibrium equations and absorption cycle model have been listed in 255 Appendix B. Figs. 4(a) and 4(b) show the diagram of the two-dimensional 256 distributed parameter model for both the absorber and the generator. A fully 257 developed two-phase of R22-DEGDME solution flows downward and the pure R22 258 gas flows upwards in a copper pipe. The solution film with even inlet temperature 259 and mass fraction goes to the pipe with an initial thickness of δ_{lin} . In the absorber, 260 the liquid film thickness increases due to the continuous absorption of R22 vapor 261 during the falling film process; while in the generator, the liquid film thickness 262 decreases because of the constant release of R22 vapor during the process. The 263 two-dimensional distributed parameter model is defined in Cartesian coordinates, 264 and x represents the pipe length direction and y represents the pipe diameter 265 direction, respectively. 266

267



(a) absorber



281
$$\frac{\partial(\rho_l v_l)}{\partial \tau} + \frac{\partial(\rho_l u_l v_l)}{\partial x} + \frac{\partial(\rho_l v_l v_l)}{\partial y} = -\frac{\partial P_l}{\partial y} + \mu_l (\frac{\partial^2 v_l}{\partial x^2} + \frac{\partial^2 v_l}{\partial y^2}) + \rho_l g_y \qquad (8)$$

In the solution energy conservation equations, the energy transfer due to

inter-diffusion should be considered in the energy balance equation. The energyconservation equation of the liquid solution is written as Equation 9,

285
$$\frac{\partial(\rho_l c_{p,l} T_l)}{\partial \tau} + \frac{\partial(\rho_l c_{p,l} u_l T_l)}{\partial x} = \lambda_l (\frac{\partial^2 T_l}{\partial x^2} + \frac{\partial^2 T_l}{\partial y^2}) + \rho_l D_l \frac{\partial^2 \xi_{R22}}{\partial y^2} (\bar{h}_{R22} - \bar{h}_{DEG}) \quad (9)$$

As there is no concentration equation for pure vapor, the R22 component equilibrium equation in the liquid phase can be defined by Equation 10,

288
$$\frac{\partial(\rho_l \xi_{R22})}{\partial \tau} + \frac{\partial(\rho_l u_l \xi_{R22})}{\partial x} + \frac{\partial(\rho_l v_l \xi_{R22})}{\partial y} = \rho_l D_l (\frac{\partial^2 \xi_{R22}}{\partial x^2} + \frac{\partial^2 \xi_{R22}}{\partial y^2}) \quad (10)$$

In the gas phase, mass, momentum, and energy conversation equations aredescribed by Equations 11-14,

291
$$\frac{\partial \rho_g}{\partial \tau} + \frac{\partial (\rho_g u_g)}{\partial x} + \frac{\partial (\rho_g v_g)}{\partial y} = 0$$
(11)

292
$$\frac{\partial(\rho_g u_g)}{\partial \tau} + \frac{\partial(\rho_g u_g u_g)}{\partial x} + \frac{\partial(\rho_g v_g u_g)}{\partial y} = -\frac{\partial P_g}{\partial x} + \mu_g (\frac{\partial^2 u_g}{\partial x^2} + \frac{\partial^2 u_g}{\partial y^2}) + \rho_g g_x \quad (12)$$

293
$$\frac{\partial(\rho_g v_g)}{\partial \tau} + \frac{\partial(\rho_g u_g v_g)}{\partial x} + \frac{\partial(\rho_g v_g v_g)}{\partial y} = -\frac{\partial P_g}{\partial y} + \mu_g (\frac{\partial^2 v_g}{\partial x^2} + \frac{\partial^2 v_g}{\partial y^2}) + \rho_g g_y \quad (13)$$

294
$$\frac{\partial(\rho_g c_{p,g} T_g)}{\partial \tau} + \frac{\partial(\rho_g c_{p,g} u_g T_g)}{\partial x} + \frac{\partial(\rho_g c_{p,g} v_g T_g)}{\partial y} = \lambda_g \left(\frac{\partial^2 T_g}{\partial x^2} + \frac{\partial^2 T_g}{\partial y^2}\right)$$
(14)

295 **3.2. Boundary conditions**

To solve the distributed parameter model mentioned above, the boundary conditions for the model are necessary. Firstly, some assumptions were made:

- 1) The velocity in the y direction is ignored (M.Mittermaier et al. 2015).
- 299 2) The velocity of solution and vapor in the x direction is constant
 300 (M.Mittermaier et al. 2015).
- 301 3) The solution is an in-compressible and the film thickness is constant

302 (Mittermaier et al. 2014).

- 303 4) The convection term in the y direction and the diffused term in the x
 304 direction is neglected (E.García-Rivera et al. 2019).
- 305 5) The wall temperature of the absorber and the heat flux density in the
 306 generator is constant (Robabeh et al. 2018).

According to Figs. 4(a) and 4(b), the boundary conditions were defined. At the inlet of the absorber and the generator (x=0), the inlet temperature, velocity and mass fraction of R22 are given by Equations 15 and 16,

310
$$u_{l.in} = u, \ T_{l.in} = T_{S3}, \ \xi_{R22.in} = \xi_{R22.S3}, \ \frac{\partial T_g}{\partial x} = 0 \qquad \text{Absorber} \qquad (15)$$

311
$$u_{l.in} = u, \ T_{l.in} = T_{S6}, \ \xi_{R22.in} = \xi_{R22.S6}, \ \frac{\partial T_g}{\partial x} = 0 \qquad \text{Generator} \qquad (16)$$

At the wall beside the liquid phase (y=0), the conditions for wall temperature, velocity and mass fraction of R22 are given. The wall liquid temperature equals to the pipe wall temperature in the absorber; while the pipe wall is defined by the second type of boundary conditions in the generator. The mass fraction gradient at the wall is 0 as there is no mass transfer.

317
$$u_l = 0, v_l = 0, T_l = T_{wall}, \frac{\partial \xi_{R22}}{\partial y} = 0$$
 Absorber (17)

318
$$u_l = 0, v_l = 0, q_w = -\lambda_l \frac{\partial T_l}{\partial y}\Big|_{y=0}, \frac{\partial \xi_{R22}}{\partial y} = 0$$
 Generator (18)

At the wall beside the R22 gas phase ($y=H_a$, H_g), the wall with a temperature gradient of 0 is an adiabatic wall.

$$\frac{\partial T_g}{\partial y} = 0 \tag{19}$$

At the outlet of the pipe ($x=L_a, L_g$), the boundary conditions are defined as:

323
$$\frac{\partial T_l}{\partial x} = 0, \quad \frac{\partial \xi_{R22}}{\partial x} = 0, \quad u_{g.in} = u_2, \quad T_{g.in} = T_{R7} \quad \text{Absorber} \quad (20)$$

324
$$\frac{\partial T_l}{\partial x} = 0, \quad \frac{\partial \xi_{R22}}{\partial x} = 0, \quad u_{g.in} = u_2, \quad T_{g.in} = T_{l.out}$$
 Generator (21)

At the interface, the temperature is continuous and the solution temperature equals to the vapor temperature. Both absorption heat and generator heat are transferred into the film by the heat conduction.

$$T_{l.intf} = T_{g.intf}$$
(22)

$$-\lambda_{l} \frac{\partial T_{l}}{\partial y}\Big|_{y=\delta} = m_{\text{int}\,f} \cdot \Delta h \tag{23}$$

where m_{intf} is the mass flux at the interface and Δh is the absorption heat and generator heat which has been defined as a function of the enthalpy of refrigerant vapor and the partial enthalpy of R22 in the solution.

$$m_{\text{int}f} = -\rho_l D_l \frac{\partial \xi_{R22}}{\partial y}\Big|_{y=\delta}$$
(24)

334

$$\Delta h = (h_{R22,g} - h_{R22,l})_{int f}$$
(25)

335 **3.3. Solution method**

For the solution of the coupled model, the specific code was developed through Python. In the distributed parameter model, central difference scheme is applied to discretize the diffusion terms, and first-order upwind difference scheme is applied to discretize convection terms. The flowchart of the distributed parameter model algorithm is shown in Fig. 5.

341 **3.4.** System multi-objective optimization

342 According to both experimental and simulation results, with increasing water 343 flow rate, the COP increased while the supply water temperature decreased. 344 Therefore, a system multi-objective optimization method should be conducted as it 345 can help to identify the optimal solution at the same time for the two objectives (Wu 346 et al., 2020). There are two objective functions, which are COP and supply water 347 temperature calculated by the lumped parameter model. The decision variables 348 include water flow rate, generator temperature and condensing temperature which 349 have significant effect on the supply water temperature and COP (Jain et al., 2017).



351

Fig. 5 Flow chart of the distributed parameter model.

The safety operating conditions are applied to formulate the inequality constraints while the lumped parameter model are used to determine the equality constraints. Jain et al., (2017) stated that the NSGA-II approach, a valid evolutive optimization method to find the optimal solutions with the details pseudo codes, can be applied to optimize the decision variables. In addition, Pareto frontier and TOPSIS decision-making method should also be discussed and adopted (Wang et al.,
2017). The non-dimensionalization of both supply water temperature and COP
should be conducted by the Fuzzy method (Wu et al., 2019):

$$COP_i^n = \frac{\max(COP_i) - COP_i}{\max(COP_i) - \min(COP_i)}$$
(26)

$$T_{w.i}^{n} = \frac{\max(T_{w.i}) - T_{w.i}}{\max(T_{w.i}) - \min(T_{w.i})}$$
(27)

360

To find the optimized result on the Pareto frontier, the TOPSIS decision-making method has been applied in this study. In this process, there are non-ideal and ideal points, with ideal points maximizing objective functions and non-ideal points minimizing them. On the Pareto frontier, the distance of any points to the ideal and non-ideal points was calculated by Equations 28 and 29 (Wu et al., 2020),

$$d_{i+} = \sqrt{(COP_i - COP^{ideal})^2 + (T_{w,i} - T_w^{ideal})^2}$$
(28)

$$d_{i-} = \sqrt{(COP_i - COP^{non-ideal})^2 + (T_{w.i} - T_w^{non-ideal})^2}$$
(29)



The proximity index can be calculated by Equation 30 (Wu et al., 2020). The maximum Cl_i is chosen as the final solution and Fig. 6 provides the optimization flow chart.

$$Cl_{i} = \frac{d_{i-}}{d_{i-} + d_{i+}}$$
(30)

4. Results and discussions

The generator is heated separately to achieve set conditions as soon as possible, before the system starts. Fig. 7 shows the start-up performance consisting of both pressure and temperature in the generator. As shown in Fig. 7, it took 40 minutes for the solution temperature to increase from 100 °C to 190 °C and the pressure to rise from 12.75 bar to 17.49 bar. The solution temperature and pressure increased approximately in a linear nature with time. After 15 minutes, fan coils and water pumps started to result in decreased solution temperature and pressure. After 40 minutes, the system achieved the set operating condition.



384

383

Fig. 7 Starting performance of the system

385 4.1. Thermal performance analysis

At a typical operating condition calculated by the lumped parameters model, Table 3 indicates uncertainty within the system and the experimental parameters. The pressure meter, PT-100, and volume flowmeter have been applied to collect

389	experimental values which are recorded data acquisition machine. The average
390	values are the average of five measurements and the system uncertainty is the error
391	of the device. Table 4 displays the thermodynamic analysis of the heat load and COP
392	under a typical condition. The absorber load, condenser load, evaporator load and
393	generator load calculated by the Equations (B-6)-(B-9) are 11.42 kW, 24.98 kW,
394	14.79 kW and 23.02 kW, respectively. Heating capacity calculated by Equation
395	(B-10) is the sum of the condenser load and absorber load while the COP defined by
396	the Equation (B-13) is 1.58.

398 Table 3 Experimental values and the uncertainty of different parameters

Variables	State points	Average values	System uncertainty
Working fluid temperature in generator outlet	R1	191.5 °C	±0.1 °C
Working fluid temperature in condenser outlet	R2	46.3 °C	±0.1 °C
Working fluid temperature in reservoir outlet	R3	46.1 °C	±0.1 °C
Working fluid temperature in heat exchanger-II outlet	R4	25.8 °C	±0.1 °C
Working fluid temperature in evaporator inlet	R5	-9.2 °C	±0.1 °C
Working fluid temperature in evaporator outlet	R6	-8.9 °C	±0.1 °C
Working fluid temperature in absorber inlet	R7	28.4 °C	±0.1 °C
Water temperature in absorber inlet	W1	24.5 °C	±0.1 °C
Water temperature in condenser inlet	W2	31.3 °C	±0.1 °C
Supply water temperature	W3	38.4 °C	±0.1 °C
Weak solution temperature in generator outlet	S1	190.9 °C	±0.1 °C
Weak solution temperature in heat exchanger outlet	S2	50.8 °C	±0.1 °C

Weak solution temperature	52	49.2.90	1019C	
in absorber inlet	55	48.2 °C	±0.1 °C	
Strong solution temperature	S.4	12 5 °C	101°C	
in absorber outlet	54	43.3 C	±0.1 C	
Strong solution temperature	85	11 5 °C	101°C	
in solution pump outlet	35	44.5 C	±0.1 C	
Strong solution temperature	56	121.9 %	10.1 °C	
in generator inlet	30	131.0 C	±0.1 C	
Water flow rate	Flowmeter-IV	2.3 m ³ /h	$\pm 0.1 \text{ m}^{3}/\text{h}$	
Working fluid flow rate	Flowmeter-III	0.25 m³/h	$\pm 0.02 \text{ m}^{3}/\text{h}$	
Strong solution flow rate	Flowmeter-II	1.71 m³/h	$\pm 0.02 \text{ m}^{3}/\text{h}$	
Weak solution flow rate	Flowmeter-I	1.38 m³/h	$\pm 0.02 \text{ m}^{3}/\text{h}$	
Natural gas flow rate	Controller	2.42 m ³ /h	$\pm 0.02 \text{ m}^{3}/\text{h}$	
Generator pressure	-	1.85 MPa	±0.01 MPa	
Evaporation pressure	-	0.35 MPa	±0.01 MPa	

400 Table 4 Performance analysis of the heat load under a typical condition

Variables	Values	Accuracy
Absorber load	11.42 kW	±0.42 kW
Condenser load	24.98 kW	±0.38 kW
Evaporator load	14.79 kW	±0.42 kW
Generator load	23.02 kW	±0.43 kW
COP	1.58	± 0.05
Heating capacity	36.41 kW	±0.52 kW

401

Fig. 8 depicts the variations of the COP and heating capacity in both experiment and simulation, with rising generator temperature at different evaporation temperatures. In Fig. 8, there are three sets of data which are experimental value, simulation value and simulation value after model correction. The simulation values were calculated according to the lumped parameter model, while simulation values after model correction were calculated based on the coupled model shown in Section 3.1. From Figs. 8(a) and 8(b), all experimental values, simulation values and

409	simulation values after model correction of the heating capacity rose with the
410	increasing generator temperature at the evaporation temperatures of -10 °C and -5 °C.
411	When the generator temperature was 190 °C, the simulation heating capacity,
412	simulation heating capacity after model correction and the experimental heating
413	capacity were 37.77 kW, 36.75 kW and 36.41 kW, respectively, at the evaporation
414	temperature of -10 °C; while they were 46.51 kW, 44.65 kW and 44.98 kW, when the
415	evaporation temperature was -5 °C. Relative errors of experimental heating capacity
416	to simulation heating capacity and simulation heating capacity after model correction
417	were 3.61% and 2.69% at the evaporation temperatures of -10 °C, and they were
418	3.99% and 3.27% at the evaporation temperatures of -5 °C. It could be observed in
419	Figs. 8(c) and 8(d) that with the increase of generator temperature, the COP
420	increased at both evaporation temperatures of -10 °C and -5 °C. At the generator
421	temperature of 190 °C, the simulated COP was 1.66, simulated COP after model
422	correction was 1.61 and the experimental COP was 1.58, at the evaporation
423	temperature of -10 °C, and they were 1.64, 1.66 and 1.71, when the evaporation
424	temperature was -5 °C. Under this condition, the relative errors of experimental COP
425	to simulated COP and simulated COP after model correction were 4.47% and 2.73%
426	at the evaporation temperatures of -10 °C, and they were 4.03% and 3.11% at the
427	evaporation temperature of -5 °C. These trends can be interpreted that increasing
428	generator temperature causes decreasing weak solution concentration. If the strong
429	solution concentration determined by the evaporation temperature keeps unchanged,
430	the deflation ratio will rise leading to the increasing absorption ability. Furthermore,

the working fluid mass flow rate increased which caused the increase of both heating capacity and COP. In addition, the increase of evaporation temperature caused the increase of absorber pressure, leading to an increase of strong solution concentration. If the weak solution concentration determined by the generator temperature was unchanged, the deflation ratio would rise, leading to the increase of absorption ability. The experimental value was lower than the simulated value, and this is because there were pressure and heat loss under the experimental conditions.

438



(a)

439

















Fig. 8 Variation of COP and heating capacity under different generator and evaporation temperature

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447 448

Fig. 9 illustrates the variation of heating capacity and COP at different 450 451 condensing and evaporation temperature. It can be seen from the Figs. 9(a) and 9(c), the heating capacity decreased with the rising condensing temperature at the 452 different evaporation temperature. When the condensing temperature was 46.5 °C, 453 the simulation and experiment heating capacity were minimized; the simulation 454 heating capacity, simulation heating capacity after model correction and experiment 455 heating capacity were 39.13 kW, 35.65 kW and 36.41 kW with the relative error of 456 3.69% and 2.74% at the evaporation temperature of -10 °C; these heating capacity 457 were 48.55 kW, 44.65 kW and 44.85 kW with the relative error of 3.41% and 2.86% 458 at the evaporation temperature of -5 °C. Figs. 9(b) and 9(d) indicate the COP 459 decreased with the increasing condensing temperature. The COP reached minimum 460 value at the condensing temperature of 46.5 °C; the simulation COP, simulation COP 461

after model correction and experiment COP were 1.58, 1.48 and 1.44 with the 462 relative error of 4.46% and 2.74%, respectively, when the evaporation temperature 463 was -10 °C; the simulation COP, simulation COP after model correction and 464 experiment COP were 1.62, 1.52 and 1.48 with the relative error of 4.03% and 465 2.64%, respectively, at the evaporation temperature of -5 °C. This could be explained 466 by that the increase of condensing temperature resulted in a growing working fluid 467 enthalpy in the condenser outlet which would lead to the decrease of COP and 468 heating capacity. 469

470



471















479 Fig. 9 Variation of COP and heating capacity under different condensing and evaporation
480 temperature

477 478

Fig. 10 presents the change of COP and supply water temperature with different 482 483 flow rate of water. It can be seen that with the rising flow rate of water, the COP rose but the supply water temperature decreased. Fig. 10 illustrates that while the flow 484 rate of water was 2.25 m³/h, the COP was 1.58 and the supply water temperature was 485 38.8 °C; while the flow rate of water increased from 2.25 m³/h to 6.98 m³/h, the COP 486 increased from 1.58 to 1.66 while the supply water temperature decreased from 487 38.8 °C to 30.6 °C. This could be explained by that the increase of water flow rate 488 caused the reducing condensing temperature which leading to the increase of 489 refrigerant enthalpy difference in the condenser inlet and outlet. This would lead to 490 the increase of heating capacity and COP, when the working fluid mass flow rate 491 492 kept unchanged.





Fig. 10 Variation of supply water temperature and COP with the increase of water flow rate

495 **4.2. Coupled model validation**

The coupled model should be validated to ensure its accuracy and correctness. 496 Table 5 shows the comparison between experimental values and simulated values 497 after model correction in the generator. It is shown that the maximum relative error 498 of T_{R1-Ex} and T_{R1-Sim} was 3.12%, while the maximum relative error of T_{S1-Ex} and 499 T_{S1-Sim} was 4.75%. Table 6 displays the comparison between experimental values and 500 simulated values in the absorber. It shows the maximum relative error of T_{S4-Ex} and 501 Ts4-sim of 5.03%. The simulated solutions were in good agreement with the 502 experimental results under the condition of the necessary assumptions and 503 instrument errors. In addition, the distributed parameter model can be used to predict 504 the thermal performance of both generators and absorbers. 505

506 Table 5 Experimental values and simulation values in generator under different conditions

т	C	T_{W1}	T_{W3}	T_{S6}	T_{R1-Sim}	T _{R1-Ex}	RE	T _{S1-Sim}	T _{S1-Ex}	RE
I evap	Case	(°C)	(°C)	(°C)	(°C)	(°C)	(%)	(°C)	(°C)	(%)

	1	24.5	38.4	131.1	193.1	190.3	1.47	195.7	190.6	2.71
	2	24.5	37.9	129.4	187.8	184.8	1.58	190.8	185.1	3.06
	3	24.5	37.5	127.7	183.3	180.2	1.73	186.4	180.2	3.41
т –	4	24.6	37.1	126.1	178.8	175.1	2.16	181.1	175.1	3.48
$I_{evap} =$	5	24.6	36.6	124.5	174.1	169.8	2.50	176.9	170.1	3.96
-10 C	6	24.6	36.3	123.1	169.4	164.8	2.75	172.3	165.2	4.33
	7	24.6	35.9	121.6	164.4	159.7	2.93	167.1	159.9	4.39
	8	24.6	35.6	120.2	159.5	154.9	3.05	162.3	155.1	4.60
	9	24.6	34.9	119.1	154.4	149.7	3.12	157.2	150.1	4.75
	10	24.4	39.7	122.1	193.2	190.2	1.59	192.5	190.2	1.23
	11	24.5	39.3	120.4	189.3	184.7	2.52	187.3	184.7	1.42
	12	24.5	38.9	118.9	184.1	180.1	2.24	182.7	180.1	1.46
т	13	24.5	38.5	117.4	178.2	174.9	1.88	177.5	174.9	1.49
$I_{evap} = 5$	14	24.5	38.1	115.9	172.4	169.7	1.62	172.5	169.7	1.68
-5 °C	15	24.5	37.7	114.6	166.9	164.7	1.36	167.9	164.8	1.94
	16	24.5	37.3	113.3	163.8	159.5	2.67	162.7	159.5	1.99
	17	24.5	37.0	112.1	158.5	154.7	2.45	158.1	154.7	2.17
	18	24.5	36.3	110.9	153.1	149.6	2.32	153.4	149.6	2.53

508 Table 6 Experimental values and simulation values in absorber under different conditions

T _{evap}	Case	$T_{W1} \\$	T_{W3}	T_{S3}	T_{R7}	T_{S4-Sim}	$T_{\text{S4-Ex}}$	RE
	Cuse	(°C)	(°C)	(°C)	(°C)	(°C)	(°C)	(%)
	1	24.5	38.4	48.5	24.8	43.5	41.9	3.73
	2	24.5	38.1	47.5	27.6	41.3	39.7	3.92
	3	24.5	37.9	46.5	26.9	40.5	38.9	3.96
т	4	24.5	37.8	45.5	26.2	39.8	38.3	3.99
$I_{evap} =$	5	24.5	37.7	44.5	25.5	38.7	37.2	4.18
-10 C	6	24.5	37.6	43.5	24.8	37.2	35.6	4.44
	7	24.5	37.6	42.5	24.1	36.2	34.6	4.49
	8	24.5	37.5	41.5	23.4	35.3	33.7	4.67
	9	24.5	37.4	40.4	22.7	34.6	33.1	5.03

509

510 4.3. Performance analysis in both absorbers and generators

511 Fig. 11 shows the interface temperature and mass concentration in both 512 generators and absorbers, according to the distributed parameter model described in

Section 3.2. It is shown in Fig. 11(a) that the interface temperature decreased slowly 513 in the initial part of the pipe and dropped rapidly after 300 mm. This is because that 514 515 in the initial stage, the solution concentration is low and the ability to absorb steam is strong; more absorbed heat is released when the R22 vapor is absorbed, leading to 516 517 little change in interface temperature. Then, the rising mass fraction of the solution leads to the gradual decrease of absorptive capacity and the conductive heat transfer 518 rate through the wall becomes greater than the absorption heat. Therefore, the 519 interface temperature gradually decreases and basically reaches the same 520 521 temperature as the wall temperature at the pipe exit. The variation trend of interface mass concentration is opposite to that of interface temperature. Fig. 11(a) indicates 522 that the interface temperature increased rapidly in the initial part of the pipe and 523 524 reached 190 °C at 200 mm. After 200 mm, the interface temperature remained almost constant. This is because at the inlet, the solution temperature is low and the 525 R22 mass concentration is high; the heat released by the combustor is partly given to 526 the solution, and partly to generating heat of the refrigerant. And the interface 527 temperature is lower, releasing less refrigerant vapor. When the solution temperature 528 reached 190 °C, the heat released by the combustor provided the generating heat for 529 the refrigerant leading to the constant interface temperature. According to a reference 530 (Robabeh et al., 2020), a two-dimensional numerical model of a vertical falling film 531 absorber was proposed, and their results showed that the interface temperature 532 decreased while the interface mass concentration increased with the increasing tube 533 length, which is similar to the results from the proposed model. 534







Fig. 11 Interface temperature and mass concentration in the generator and absorber

4.4. System optimization

It can be seen from Fig. 10 that the COP increased but the water supply 542 temperature reduced, with the growing flow rate of water. Under the same 543 evaporation and generation temperature, the higher the COP, the lower the water 544

545 supply temperature, and vice versa. According to the NSGA-II approach and 546 TOPSIS decision-making method, the multi-objective optimization elaborated in 547 Section 3.6 is carried out in this study. Table A3 displays the optimization process 548 tuning parameters, and these parameters have been used in a similar study as well 549 (Jain et al., 2017).

550 According to Equations 26 and 27, the normalized COP and the normalized 551 supply water temperature on the Pareto frontiers optimized by the NSGA-II 552 approach are both displayed in Fig. 12. The supply water temperature and the COP 553 will be maximum at normalized supply water temperature and COP of 1. However, 554 the non-ideal points can be determined at the normalized supply water temperature 555 and COP are 0. In fact, there is no i non-ideal and deal points. While the normalized 556 supply water temperature is 1 and the normalized COP is 0, the system will be 557 optimally designed based on supply water temperature. When the normalized supply 558 water temperature is 0 and the normalized COP is 1, however, the system can be 559 optimally designed based on COP. To find the optimal result on the Pareto frontier, 560 therefore, the TOPSIS decision-making method was applied.



563

Fig. 12 Pareto frontier in optimization

564 According to Equations 28-30, d_{i+} , d_{i-} and Cl_i was calculated and the 565 maximum Cl_i was chosen as the final result of the proposed system. The variations 566 of d_{i+} , d_{i-} and Cl_i with normalized supply water temperature are presented in 567 Fig. 13. From Fig. 13, when the maximum Cl_i was 0.761, the normalized supply 568 water temperature was 0.678. Under this optimal result, the COP was 1.63 with the 569 supply water temperature of 36.3 °C. It can be seen from Fig. 13 that the system had 570 better COP performance on the left hand side of the orange line while it had better 571 supply water temperature on the right hand side.





Fig. 13 The distance values and proximity index calculated by the TOPSIS method

574 Table 7 presents the normalized supply water temperature, the supply water 575 temperature, the normalized COP and the COP in different optimization cases. The 576 results showed that if the system design only considered the COP, the design scheme 577 cannot fully meet the water supply temperature design, and vice versa. If the 578 optimized COP system was chosen, the supply water temperature was 20.98% lower 579 than the maximum possible solution. If the optimized supply water temperature 580 system was determined, the COP was 4.24% lower than its maximum possible 581 solution. However, the COP and supply water temperature were 1.21% and 5.95% 582 lower than their maximized values as the multi-objective optimization design was 583 chosen. Therefore, the multi-objective optimization result can be considered as the 584 optimized working condition.

⁵⁸⁵ Under the optimal operating conditions, the multi-objective optimization COP ⁵⁸⁶ is 1.63 and the supply water temperature is 36.3 °C at the evaporation temperature ⁵⁸⁷ -10 °C. Lu et al. (2020) have proposed an air-source AHP for heating. They indicated

588	that the system had 30kW heating capacity and the water could be heated from
589	34.2 °C to 55.1 °C with the COP of 1.66 at the evaporation temperature of 0 °C.
590	When evaporation temperatures increased from to -10 °C to -5 °C, the COP
591	increased from 1.40 to 1.51, respectively. It can be seen that the COP in this study is
592	higher than the COP in reference (Lu et al., 2020) under the evaporation temperature
593	-10 °C. This can be explained by that the system in this study has a low condensation
594	temperature (46.3 °C) and the heat recovery of flue gas.

595	Table 7	Values	under	different	opti	mizatio	n process
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Doromotors	COD	Supply water temperature	Normalized COP	Normalized supply water	
	COP	(°C)	Normalized COP	temperature	
COP optimal design	1.65	30.5	1	0	
Supply water temperature	1 58	38.6	0	1	
optimal design	1.00	2010	v	-	
Multi-objective optimization	1.63	36 3	0.621	0.678	
design	1.05	50.5	0.021	0.078	

5. Conclusions

597	In this study, a novel air-source gas-fired absorption heat pump system with
598	vertical falling film exchangers has been proposed for heating buildings. A coupled
599	model was established and a testing rig was built up. The effects of different
600	operating parameters were studied and analyzed. Multi-objective optimization was
601	carried out to find the optimized working conditions. The following main
602	conclusions could be drawn from this study:
603	1. The proposed system had good stability and feasibility. With the evaporator
604	temperature increasing from -10 °C to -5 °C, the experimental coefficient of
605	performance increased from 1.58 to 1.64, and experimental heating capacity rose
606	from 36.41 kW to 44.98 kW.
607	2. The proposed coupled model with a maximum error less than 8% is more accurate
608	than the lumped parameter model with a maximum error less than 10%.
609	3. The variation trend of interface temperature was opposite to that of interface mass
610	concentration in the absorber and generator. The absorber required longer pipes
611	while the generator required more tubes.
612	4. Under the multi-objective optimization condition, the supply water temperature
613	was 5.95% lower than the maximum values and COP was 1.21% lower than the
614	maximum values which were better than that of single-objective optimization.
615	This study has fulfilled the gap of improving the use of outdoor heat for heating
616	buildings in cold region, through a novel air-source gas-fired absorption heat pump

617 system. The proposed system can greatly extend the applications of absorption heat 618 pumps in the district heating and the vertical falling film exchangers can promote the 619 development of this technology. In the future, the stability and compatibility of the 620 ASAHP system with the optimal operating condition should be tested by engineering 621 in cold region. Further research should include the heat exchanger optimization and 622 the new environmental working fluid pair.

623

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Appendix A

The tables for this article are shown below.

Table A1 R22-DEGDME solution	on properties	(Wu	et al., 2020))
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Parameters	DEGDME	R22
Corrosivity	No	No
Toxicity	No	No
Density (kg/m ³) (t=20 °C)	944	1210
Critical temperature (°C)	328.85	96.15
Boiling point (°C) (P=101325 Pa)	162	-40.8
Molecular weight (g/mol)	134.17	86.46

n	A_n	B_n	C_n	$A_n^{c_p}$	$B_n^{c_p}$	$C_n^{c_p}$	G_n
0	5.21E+01	-5.58E+03	-6.34E+00	2.79E+02	-4.2E-02	2.31E-03	-1.90E+04
1	1.27E+01	3.39E+03	-1.43E+00	-1.51E+02	5.98E-01	-5.97E-03	8.72E+03
2	-1.39E+02	-8.60E+03	2.23E+01	1.01E+02	-1.37E+00	3.43E-03	-1.39E+03
3	7.32E+02	-3.16E+03	-1.14E+02	-1.28E+02	1.02E+00	1.05E-03	-6.42E+02
4	-1.19E+03	3.04E+04	1.81E+02	-	-	-	-
5	5.47E+02	-1.90E+04	-8.19E+01	-	-	-	-

Table A2 Coefficients in Equations.(B-1)-(B-4) (Wu et al., 2020)

Tuning parameters	Value
Probability of mutation	0.9
Maximum number of generations	400
Population size	100
Tournament size	2
Selection process	Tournament
Probability of crossover	0.75

Table A3 Multi-objective optimization tuning parameters (Jain et al., 2017)

Appendix B

Solution equilibrium equations and absorption cycle model in this study.

According to literature (Takcshito et al., 1984), the solution equilibrium equation consists of three aspects which are solution pressure P, molar concentration Y of R22 and solution temperature T. It can be defined by Equation B-1,

$$\ln P = \sum_{n=0}^{5} A_n Y^n + \frac{1}{T} \sum_{n=0}^{5} B_n Y^n + \ln T \cdot \sum_{n=0}^{5} C_n Y^n$$
(B-1)

The R22-DEGDME solution specific heat composes of R22 molar the solution temperature T and concentration Y, defined by Equation B-2 (Takeshito et al., 1984),

$$c_{p} = \sum_{n=0}^{3} A_{n}^{c_{p}} Y^{n} + t \sum_{n=0}^{3} B_{n}^{c_{p}} Y^{n} + t^{2} \cdot \sum_{n=0}^{3} C_{n}^{c_{p}} Y^{n}$$
(B-2)

The mixed heat is written as a function of R22 molar concentration Y (Takeshito et al., 1984). A_n , B_n , C_n , $A_n^{c_p}$, $B_n^{c_p}$, $C_n^{c_p}$ and G_n are the constant coefficients

which have been shown in Table A2.

$$\Delta H_m = Y(1-Y) \cdot \sum_{n=1}^{4} G_n (1-2Y)^{n-1}$$
(B-3)

Molar enthalpy of solution is defined as a function of specific heat c_p , mixed heat ΔH_m , molar concentration of R22, Y, molecular weights of DEGDME M_D and R22 M_{R22} , thermal equivalent of work J, and solution temperature t. Molar enthalpy is expressed by Equation B-4 (Takcshito et al., 1984),

$$H = \frac{\Delta H_m + \int_{10}^{t} c_p dt + \int_{0}^{10} c_p (Y=0) dt + Y(\int_{0}^{10} c_p (Y=1) dt - \int_{0}^{10} c_p (Y=0) dt)}{J(M_D(1-Y) + M_{R22}Y)} + 100$$
(B-4)

Based on the first law of thermodynamics, each components heat load was defined. In the generator, the thermal load consists of solution enthalpy and mass flow rate, and working medium mass flow rate and enthalpy, which can be defined by Equation B-5 (Wu et al., 2020),

$$Q_{gen} = m_{wf} \cdot h_{R1} + m_{w} \cdot h_{S1} - m_{s} \cdot h_{S6}$$
(B-5)

Since the combustion of natural gas is to driven the generator, the thermal load Q_{gen} is defined by Equation B-6,

$$Q_{gen} = q \cdot V_{ng} \tag{B-6}$$

where V_{ng} is the natural gas flow rate of the and q is the calorific value.

Heat is transferred from ambient air to refrigerant in the evaporator, with heat determined by Equation B-7 (Wu et al., 2020),

$$Q_{eavp} = m_{wf} (h_{R6} - h_{R5})$$
(B-7)

Refrigerant vapor condenses and releases heat to the supply to the target temperature water in the condenser. A mixed heat of solution and refrigerant heats the supply water in the absorber. The heating capacity is consisted of absorber heat load and condenser heat load, which is shown as:

$$Q_{cond} = m_r (h_{R2} - h_{R2}) = c_{p.w} \rho_w V_w (T_{W3} - T_{W2})$$
(B-8)

$$Q_{abs} = m_r \cdot h_{R7} + m_w \cdot h_{S3} - m_s \cdot h_{S4} = c_{p.w} \rho_w V_w (T_{W2} - T_{W1})$$
(B-9)

$$Q_{hc} = Q_{cond} + Q_{abs} = c_{p.w} \rho_w V_w (T_{W3} - T_{W1})$$
(B-10)

The heat load in the heat exchanger-II and solution heat exchanger are calculated by Equations B-11 and B-12, respectively,

$$Q_{she} = m_s(h_{S6} - h_{S5}) = m_w(h_{S1} - h_{S2})$$
(B-11)

$$Q_{he-II} = m_r (h_{R4} - h_{R3}) = m_r (h_{R7} - h_{R6})$$
(B-12)

The COP of the system is written by Equation B-13 (Wu et al., 2020),

$$COP = \frac{Q_{cond} + Q_{abs}}{Q_{gen} / \eta_b + W_p}$$
(B-13)

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