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Differential astrometric framework for the Jupiter relativistic experiment with *Gaia*

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ABSTRACT

We employ differential astrometric methods to establish a small field reference frame stable at the microarcsecond (μas) level on short time-scales using high-cadence simulated observations taken by *Gaia* in 2017 February of a bright star close to the limb of Jupiter, as part of the relativistic experiment on Jupiter’s quadrupole. We achieve sub μas -level precision along scan through a suitable transformation of the field angles into a small-field tangent plane and a least-squares fit over several overlapping frames for estimating the plate and geometric calibration parameters with tens of reference stars that lie within ~ 0.5 deg from the target star, assuming perfect knowledge of stellar proper motions and parallaxes. Furthermore, we study the effects of unmodelled astrometric parameters on the residuals and find that proper motions have a stronger effect than unmodelled parallaxes, e.g. unmodelled *Gaia* DR2 proper motions introduce extra residuals of ~ 23 μas (AL) and 69 μas (AC) versus the ~ 5 μas (AL) and 17 μas (AC) due to unmodelled parallaxes. On the other hand, assuming catalogue errors in the proper motions and parallaxes such as those from *Gaia* DR2 has a minimal impact on the stability introducing sub μas and μas level residuals in the along and across scanning direction, respectively. Finally, the effect of a coarse knowledge in the satellite velocity components (with time-dependent errors of 10 $\mu\text{as s}^{-1}$) is capable of enlarging the size of the residuals to roughly 0.2 mas.

Key words: methods: data analysis – methods: statistical – astrometry – reference systems.

1 INTRODUCTION

The on-going *Gaia* space mission (Gaia Collaboration 2016a) has provided high-precision global astrometric catalogues in two successive data releases over the past few years (Gaia Collaboration 2016b, 2018). This has heralded the beginning of an era of high-precision astrometry in which the models and methodologies are required to demonstrate at least microarcsecond (μas) level, if not higher, precision (Lattanzi 2012). Indeed, as part of the *Gaia* Data Processing and Analysis Consortium (DPAC) activities, the description of stellar positions in *Gaia* measurements, using the baseline Gaia RELativistic Model (GREM) model in the Astrometric Global Iterative Solution (AGIS; Klioner 2003) or its Relativistic Astrometric MODel (RAMOD; Crosta et al. 2008c; Crosta & Vecchiato 2010) counterpart in the Global Sphere Reconstruction (GSR) module for the astrometric verification of the AGIS solution, is accurate at the sub μas level.

The astrometric parameters (position, proper motion, and parallaxes) as provided in past *Gaia* data releases are absolute parameters obtained by the AGIS solution (e.g. Lindegren et al. 2016; Lindegren et al. 2018). The scanning motion of the satellite is specifically

designed to provide measurements over the whole celestial sphere in 6 months’ time through a combination of three motion: (a) rotation of *Gaia* around its spin axis every 6 h, (b) the precession of the spin axis every 63 d, and (c) the orbital motion of the satellite around the Sun (Lindegren et al. 2016). It is possible to perform differential astrometry starting with *Gaia*’s global astrometric measurements, constructing a high-precision inertial astrometric reference frame over small fields with a size essentially defined by the dimensions of *Gaia*’s field of view (FOV). This approach requires a sophisticated methodology that uses the set of coordinates (field angles) in the focal plane of the satellite as input and depends mainly on the geometric calibrations of the CCDs and the satellite attitude. The main challenge to face concerns the ability to robustly define such a local reference frames over the very different time-scales associated to diverse scientific applications of this approach, such as relativistic deflection of light tests (duration of a few days), astrometric microlensing events (duration up to months), and orbital reconstruction of binary and substellar companions, including exoplanets (duration of years). The developed methodology must be able to account for highly different distributions and number of comparison stars at different epochs of *Gaia* observations (transits), depending on the satellite’s scanning direction, as well as highly changing geometric calibrations, particularly when the timespan of the observations exceeds a few weeks (Lindegren et al. 2018).

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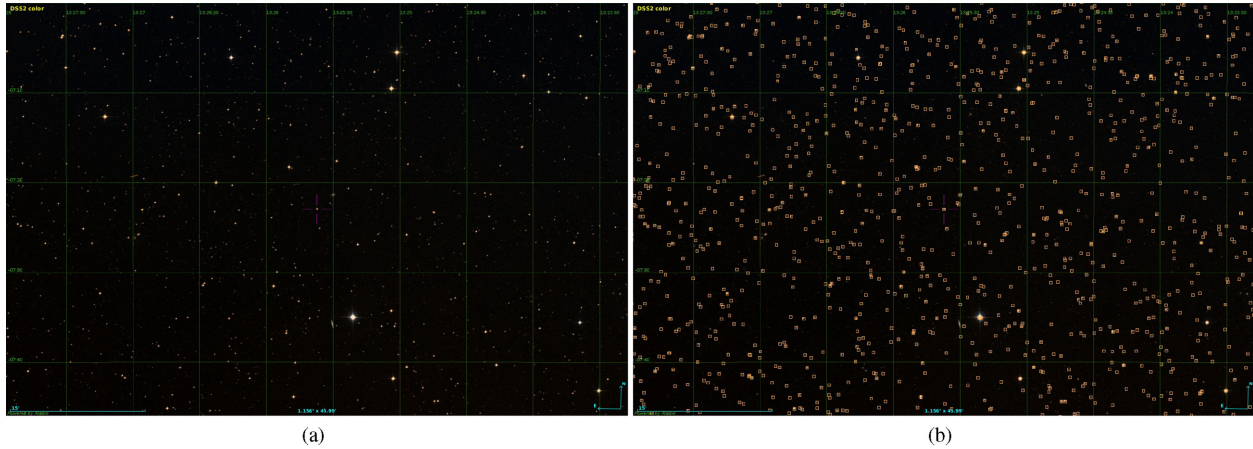


Figure 2. The star field surrounding the target star located at $\alpha = 201^{\circ}.4053$, $\delta = -7^{\circ}.3830$. Left-hand panel (a) shows the DSS image of the field of size $69'.36 \times 45'.99$ and the right-hand panel (b) shows the *Gaia* DR2 stars overlaid (courtesy: Aladin).

last column with 6 CCD rows (see fig. 4 in Gaia Collaboration 2016b).

2.2 The simulated field angles and reference stars

The adopted set-up is based on the *Gaia* satellite equipped with two FOVs that are separated by the basic angle of 106.5 deg and rotating at a fixed rate of 59.9605 arcsec s^{-1} around its spin axis (Gaia Collaboration 2016b). The simulator is run using nominal CCD size, focal plane geometry and FOV size and orbital parameters. The observed source direction or its proper direction is computed using a suitable relativistic model necessary for highly accurate astrometric observations in the parametrized post-Newtonian (PPN) framework and specifically adopted by *Gaia* (Klioner 2003). This formulation takes into account the relativistic modelling of the motion of the observer and modelling of relativistic aberration and gravitational light deflection, as well as a relativistic treatment of the parallaxes and proper motions.

The first 15 transits around the target star ($G = 12.68$ mag) in 2017 February were used which also coincide with when Jupiter is seen within the same frame. In order to maximize the number of observations, close bright stars ($10 < G < 13$ mag) having 2d windows, and, hence the η and ζ coordinates are chosen to lie within ± 30 s of the observing time of the target star for the same CCD column. This ensures that the target star always lies at the centre of the frame surrounded by the set of reference stars that are not necessarily seen by *Gaia* on each and every one of the 15 transits during which the target star is present, mainly depending on the scanning direction during those instants of time causing different orientations of the astrometric field. This leads to different ‘subsets’ of reference stars observed on different transits as some areas of the field are ‘cut off’ depending on the scanning angle, for e.g. the target star that is ideally seen in the central row 4 leading to the whole surrounding star field being visible, could be seen on row 1 or 7 in the following transit caused by the shift in the focal plane leading to the whole lower or upper part, respectively, of the star field to remain hidden from *Gaia* and unobserved (see Fig. 3). Under these conditions, we have chosen the reference frame to contain the maximum number of reference stars, in this case 31 stars, surrounding the target star. This high number of stars is given by the observing times as seen by AF1 during *Gaia*’s fifth

transit over the star field and converted into spatial coordinates as described in Section 2.3. The AF1–AF8 observations were used, AF9 observations were rejected due to the presence of the WFS. Table 1 shows the total number of times each of the reference stars is seen. All the reference stars are seen eight times during a whole transit except for star no. 21 that is seen a few times less on the second transit as it falls at the very edge of the FOV as mentioned earlier. Table 2 gives the total number of reference stars seen on each transit that consists of eight frames.

2.3 Effect due to the AL–AC motion of a star

We need to define a set of frames (our ‘plates’), each one identified by a unique observing time. For convenience, we can choose it to be the t_{ot} of the target star – to which the measurements of all the stars observed some $\pm \Delta t$ from t_{ot} are referred to. For each t_{ot} we will have a different local frame, with coordinate axes identified by the along and across scan direction at time t_{ot} , and we must model accordingly all measurements that we assign to that frame. Then, we use the principles of differential astrometry to adjust all the frames to a common frame by means of translations, rotations, scale terms, and possible distortion terms if necessary.

It is important that for each star observed at time t_{os} , such that

$$|(t_{ot} - t_{os})| < \Delta t \quad (1)$$

we refer its measured coordinates to the same local frame. To do so, we first compute the star’s field angles (η , ζ) using the best current calibration parameters; then, we use the time derivatives of the field angles ($d\eta/dt$, $d\zeta/dt$) to take into account the variation of the direction of the (η , ζ) axes that occurred in the elapsed time Δt . To first-order approximation, the local coordinates of a star observed in the frame defined by t_{ot} are

$$\begin{aligned} \eta(t_{ot}) &= \eta(t_{os}) + \dot{\eta} \times (t_{ot} - t_{os}) \\ \zeta(t_{ot}) &= \zeta(t_{os}) + \dot{\zeta} \times (t_{ot} - t_{os}). \end{aligned} \quad (2)$$

For the field-angle rates, we can use the following formulae:

$$\begin{aligned} \dot{\eta} &= -\omega_z + [\omega_x \cos \varphi + \omega_y \sin \varphi] \tan \zeta \\ \dot{\zeta} &= -\omega_x \sin \varphi + \omega_y \cos \varphi, \end{aligned} \quad (3)$$

where ω_x , ω_y , and ω_z are the components of the instantaneous inertial angular velocity of *Gaia*, and $\varphi = \eta \pm \gamma/2$, where the plus

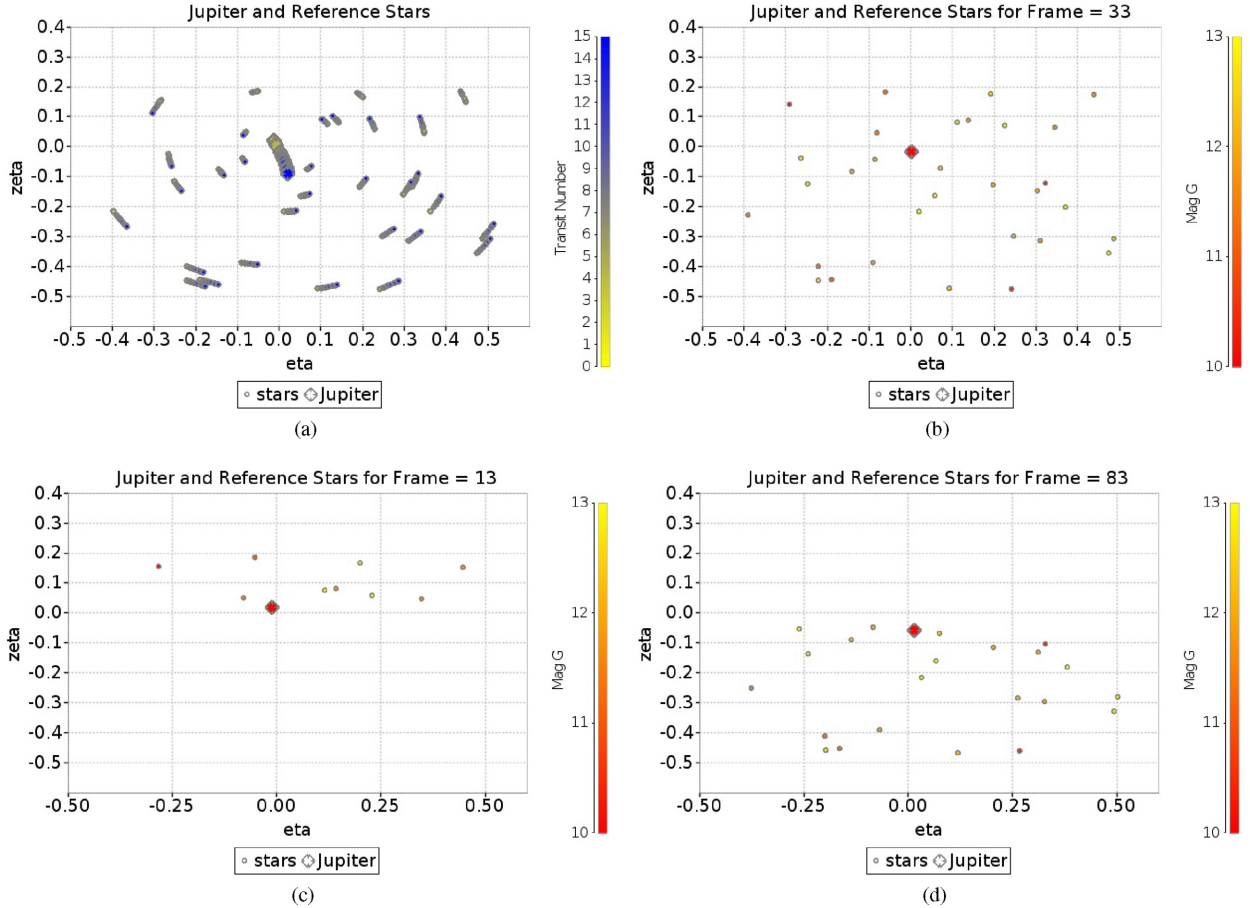


Figure 3. The simulated star field surrounding the target star (not shown here) and Jupiter’s position on various transits as seen by *Gaia* (scale shown in degrees). In reality, Jupiter will not be observed in the AF due to its extreme brightness ($V = -2.7$ mag). The top left panel shows the reference stars and Jupiter as seen on all transits, colour coded by the transit number. The top right panel (b) shows the reference frame with the maximum number of reference stars seen over the 15 transits. The symbols are colour coded according to their magnitude as shown in the colour bar at the right. The small circles show the reference stars whereas the larger diamond denotes Jupiter. Lower left panel (c) shows the reference stars as seen in frame 13, and (d) shows the stars as seen in frame 83.

or minus sign is used for preceding or following FOV, respectively, and γ being the basic angle between the two fields of view of *Gaia*.

2.4 Calibration effects

Amongst the possible distortion effects, we take into account the large-scale AL and AC calibrations where the former could potentially vary over time-scales of a day. As we are considering observations over a couple of days, we assume these large-scale calibrations to be constant to first approximation. The AL large-scale calibration is modelled as a low-order polynomial in the across-scan pixel coordinate μ (that varies from 13.5 to 1979.5 across the CCD columns; Lindegren et al. 2012) and can be written as

$$\eta_{fn}(\mu, t) = \eta_n^0 + \sum_{r=0}^2 \Delta\eta_{rfn} L_r^* \left(\frac{\mu - 13.5}{1966} \right), \quad (4)$$

where f is the FOV index, n is the CCD index, and r is the degree of the shifted Legendre polynomial $L_r^*(\tilde{\mu})$ as a function of the normalized AC pixel coordinate ($\tilde{\mu}$) and η_n^0 is the nominal calibration.

A similar equation holds for the AC large-scale calibrations which can be written as

$$\zeta_{fn}(\mu, t) = \zeta_{fn}^0 + \sum_{r=0}^2 \Delta\zeta_{rfn} L_r^* \left(\frac{\mu - 13.5}{1966} \right). \quad (5)$$

We will assume non-gated observations, which is technically only valid for faint sources; brighter star observations involve as many as a dozen gates that would need to be calibrated. Image saturation by stars brighter than about $G = 12$ is mitigated through the use of TDI gates, activated to inhibit charge transfer and hence to effectively reduce the integration time for bright sources (Gaia Collaboration 2016b). The adopted TDI gate scheme impacts the bright-star errors and it can be seen that predicted end-of-mission parallax errors averaged over the sky vary in the range of 5–16 μas (see fig. 10 in de Bruijne 2012). However, the advantage of using sources brighter than $G \sim 13$ mag is that they will always be observed as two-dimensional images, and therefore have high-precision measurements in both coordinates, though the precision of the AC coordinate is a factor of 5 worse than the AL one due to the rectangular shape of the CCD pixels (de Bruijne 2005, also see table 1 in Abbas et al. 2017).

Table 1. List of observing time occurrences (nObs) of the reference stars around Jupiter used in this experiment, plus their DR2 astrometric parameters (i.e. parallaxes and proper motions) and errors.

starId	nObs	π (mas)	σ_π (mas)	$\mu_{\alpha*}$ (mas yr ⁻¹)	$\sigma_{\mu_{\alpha*}}$ (mas yr ⁻¹)	μ_δ (mas yr ⁻¹)	σ_{μ_δ} (mas yr ⁻¹)
1	104	0.580	0.047	-43.699	0.079	-15.470	0.057
2	88	0.271	0.037	-5.453	0.067	-0.527	0.052
3	80	2.325	0.051	-26.436	0.079	6.346	0.070
4	80	3.059	0.051	-43.430	0.090	-3.309	0.067
5	88	1.008	0.050	-2.197	0.066	2.964	0.053
6	104	0.689	0.066	0.590	0.081	-9.552	0.077
7	88	2.810	0.058	20.508	0.098	-49.644	0.117
8	96	1.866	0.039	-19.363	0.077	-10.430	0.056
9	56	0.876	0.065	4.522	0.236	-8.638	0.096
10	112	0.417	0.037	-5.592	0.080	0.653	0.055
11	112	6.977	0.040	-76.545	0.074	-7.742	0.060
12	112	1.179	0.043	-8.800	0.077	12.454	0.059
13	104	2.350	0.036	-16.248	0.076	15.734	0.048
14	80	3.980	0.045	22.883	0.083	-17.226	0.058
15	80	3.443	0.050	-22.019	0.080	-18.794	0.069
16	88	5.450	0.045	-23.764	0.081	-16.905	0.063
17	88	5.609	0.049	-112.627	0.081	-30.181	0.083
18	88	2.569	0.038	-29.627	0.082	0.251	0.057
19	88	8.986	0.078	104.889	0.104	-48.145	0.102
20	88	1.297	0.046	-10.022	0.075	4.051	0.055
21	85	0.556	0.045	-25.758	0.086	-7.016	0.064
22	112	1.314	0.040	-5.323	0.070	-0.234	0.053
23	96	0.603	0.046	-10.050	0.086	-24.174	0.077
24	104	1.401	0.038	-16.193	0.072	-4.848	0.056
25	80	1.534	0.049	-0.476	0.075	-3.760	0.059
26	80	0.671	0.094	-3.727	0.209	2.446	0.272
27	80	2.643	0.101	4.523	0.166	-7.290	0.130
28	104	1.316	0.066	4.191	0.094	0.802	0.071
29	56	0.351	0.040	5.266	0.079	-15.818	0.065
30	88	2.628	0.072	-31.088	0.117	-5.173	0.109
31	56	3.439	0.053	-57.511	0.116	-22.168	0.110

Table 2. Total number of reference stars seen on each transit.

Transit no.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
No. of ref stars	13	8	20	18	31	25	27	31	23	28	22	22	28	21	28

3 TRANSFORMATION AND FITTING PROCEDURE

The field angles are transformed by first rotating them onto the (1,0,0) vector and then projecting them on to the tangent plane through a gnomonic transformation. The least-squares fitting procedure then involves the Taylor series expansion of the transformed field coordinates.

3.1 A priori removal of parallaxes and proper motions

With the aim of keeping the number of unknowns to be estimated to a minimum, we show the procedure of removing a priori the parallaxes and proper motions from *Gaia* DR2. As can be seen in Table 1, the *Gaia* DR2 proper motions for this set of stars varies up to 116 mas yr⁻¹ and with parallaxes up to 9 mas. In the simulation, we account for these errors as Gaussian distributions with standard deviations from *Gaia* DR2. These quantities are given in equatorial coordinates that then need to be converted to the Satellite Reference System (SRS) giving the projected along and across scan values. This transformation is completely determined by the position angle

of the scan given by

$$\begin{aligned}\mu_\eta &= \mu_\alpha \sin \theta + \mu_\delta \cos \theta \\ \mu_\zeta &= -\mu_\alpha \cos \theta + \mu_\delta \sin \theta.\end{aligned}\quad (6)$$

When treating the parallaxes, μ_α and μ_δ can be replaced with the parallax factors f_α and f_δ , respectively, to obtain the transformed parallax factors along and across the scanning direction. These transformed quantities are then subtracted from the η and ζ positions of the stars after multiplying the proper motions by the time passed since a chosen reference epoch and the parallaxes by the parallax factors.

The ‘corrected’ field angles are then given as

$$\begin{aligned}\eta &= \eta_{\text{calc}} - \mu_\eta(t - T) - f_\eta \pi \\ \zeta &= \zeta_{\text{calc}} - \mu_\zeta(t - T) - f_\zeta \pi\end{aligned}\quad (7)$$

where η_{calc} and ζ_{calc} are calculated from the CCD and FOV information such as the CCD row and column numbers and FOV index combined with the geometrical calibrations. The proper direction to the star at a given time is then obtained through the field angles by including the attitude at that instant.

3.2 Pre-rotation and gnomonic transformation

The fundamental ingredients to the model are the SRS field angles (η , ζ) for these stars including their geometric calibrations (Section 2.4) and AL–AC motion (Section 2.3). Furthermore, the operations mentioned in Section 3.1 are performed which involve the estimation and a priori removal of the *Gaia* DR2 proper motions and parallaxes. We denote the target star as measured in the i th frame by η'_{i0} and ζ'_{i0} , whereas η'_{ij} and ζ'_{ij} are the observed calibrated field angles of the j th star in the i th frame.

Before trying a global adjustment of all the frames using the principles of tangent-plane astrometry, field angle measurements must be rectified via a gnomonic transformation. In order to minimize the differential effect of the so-called *tilt* terms, which are second-order quantities arising from a misalignment of the nominal versus true position of the telescope’s optical axis, all the reference stars, including the target, are rotated in such a way that the position of the target star becomes aligned with the (1,0,0) vector defining the optical axis of *Gaia*.

Then these field angles are converted to coordinates in the tangent plane with tangent point (0,0) using gnomonic transformations as follows:

$$X'_{ij} = \tan(\eta'_{ij}), \quad Y'_{ij} = \frac{\tan(\zeta'_{ij})}{\cos(\eta'_{ij})} \quad (8)$$

for the i th frame and the j th star.

3.3 Taylor series expansion

We linearize the expressions from equation (8) and perform a Taylor series expansion of the reference star coordinates in the tangent plane from above around the nominal position of the star, i.e. the fiducial position free from any calibrations. This operation has the added advantage of reducing the number of calibration unknowns by a factor of 3 with respect to the astrometric model used in Abbas et al. (2017) as will be shown below.

The nominal positions will be denoted by the unprimed quantities η_{ij} and ζ_{ij} . The expansion to first order can be written as

$$\begin{aligned} X'_{ij} &= X_{ij} \Big|_{\eta_{ij}\zeta_{ij}} + (\eta'_{ij} - \eta_{ij}) \frac{\partial X'_{ij}}{\partial \eta} + (\zeta'_{ij} - \zeta_{ij}) \frac{\partial X'_{ij}}{\partial \zeta} \\ Y'_{ij} &= Y_{ij} \Big|_{\eta_{ij}\zeta_{ij}} + (\eta'_{ij} - \eta_{ij}) \frac{\partial Y'_{ij}}{\partial \eta} + (\zeta'_{ij} - \zeta_{ij}) \frac{\partial Y'_{ij}}{\partial \zeta}, \end{aligned} \quad (9)$$

where the partial derivatives are evaluated at the nominal position and are treated as known quantities. They are given as

$$\begin{aligned} \frac{\partial X'_{ij}}{\partial \eta} \Big|_{\eta_{ij}\zeta_{ij}} &= \frac{\cos(\zeta_{ij}) \cos(\eta_{ij})}{f(\eta_{ij}, \zeta_{ij})} - \frac{\cos(\zeta_{ij}) \sin(\eta_{ij})}{f^2(\eta_{ij}, \zeta_{ij})} \\ &\quad \times (-\cos(\zeta_{ij}) \sin(\eta_{ij})) \\ \frac{\partial X'_{ij}}{\partial \zeta} \Big|_{\eta_{ij}\zeta_{ij}} &= -\frac{\sin(\zeta_{ij}) \sin(\eta_{ij})}{f(\eta_{ij}, \zeta_{ij})} - \frac{\cos(\zeta_{ij}) \sin(\eta_{ij})}{f^2(\eta_{ij}, \zeta_{ij})} \\ &\quad \times (-\sin(\zeta_{ij}) \cos(\eta_{ij})) \end{aligned} \quad (10)$$

$$\begin{aligned} \frac{\partial Y'_{ij}}{\partial \eta} \Big|_{\eta_{ij}\zeta_{ij}} &= -\frac{\sin(\zeta_{ij})}{f^2(\eta_{ij}, \zeta_{ij})} \times (-\cos(\zeta_{ij}) \sin(\eta_{ij})) \\ \frac{\partial Y'_{ij}}{\partial \zeta} \Big|_{\eta_{ij}\zeta_{ij}} &= -\frac{\cos(\zeta_{ij})}{f(\eta_{ij}, \zeta_{ij})} - \frac{\sin(\zeta_{ij})}{f^2(\eta_{ij}, \zeta_{ij})} \times (-\sin(\zeta_{ij}) \cos(\eta_{ij})), \end{aligned} \quad (11)$$

where $f(\eta_{ij}, \zeta_{ij}) = \cos(\zeta'_{ij}) \cos(\eta'_{ij})$.

The differences multiplying the partial derivatives are the calibration terms given in equations (4) and (5) that are to be estimated through the least-squares technique mentioned later on.

3.4 Astrometric model

The positions of the stars in each frame are adjusted to its reference frame value through a simple linear plate transformation given as

$$\begin{aligned} X'_{0j}(t_{0r}) &= a_i X'_{ij}(t_{it}) + b_i Y'_{ij}(t_{it}) + c_i \\ Y'_{0j}(t_{0r}) &= d_i X'_{ij}(t_{it}) + e_i Y'_{ij}(t_{it}) + f_i, \end{aligned} \quad (12)$$

where X' and Y' are the star coordinates in the tangent plane, with X'_{0j} and Y'_{0j} being the coordinates of the j th star on the reference frame. The plate constants are given by a_i , b_i , c_i , d_i , e_i , and f_i .

The software package GAUSSFIT (Jefferys, Fitzpatrick & McArthur 1988) is used to solve this set of equations through a least-squares procedure that minimizes the sum of squares of the residuals weighted according to the input errors. The estimated plate/frame parameters (a_i through f_i) allow to transport the calibrated observations (X'_{ij} , Y'_{ij}) to a common reference frame. The distribution of residuals then informs us as to how well the model accounts for various effects. As can be expected, it is found that a_i and e_i are almost unity, whereas $b_i = -d_i$ and together they give the rotation and orientation. The offsets c_i and f_i give the zero-point of the common system (see Abbas et al. 2017, for more details).

4 RESULTS

We summarize here the most relevant findings of our numerical experiments aimed at determining the ultimate systematic floor of our methodology for differential astrometry. We study in particular its behaviour (a) as a function of unmodelled parallaxes and proper motions that are not removed a priori, (b) when taking into account catalogue errors in the astrometric parameters, and (c) in the case of lower precision knowledge of the satellite velocity.

4.1 Systematic floor of the methodology

Fig. 4 shows the sub μ as-level stability achievable in the AL direction (1 μ as in AC) when no physical effects are included in the simulation (i.e. aberration and gravitational light deflection are turned off) and after an a priori removal of the star’s parallax and proper motion (following the procedure mentioned in Section 3.1). The figure shows the differences between the fitted η and ζ per star (equation 12) using the best-fitting plate and calibrations parameters obtained through the least-squares procedure of GAUSSFIT and the corresponding values on the reference frame as a function of the transit number. Each transit is the average over eight frames from the first eight columns in the astrometric field (reason for this is described at the end of Section 2.2), and the green points depict the average differences with respect to the reference frame values for each star seen on that transit. The black points are the averages over all the reference stars for that transit and the error bars show the standard deviation of the green points. The AL/AC input error and output residual distributions are shown in Fig. 5 demonstrating the full recovery of the input standard errors in the methodology.

4.2 Residuals due to unmodelled effects

Here, we will look at the effect of not accounting for the stars’ parallaxes nor their proper motions by neither removing their

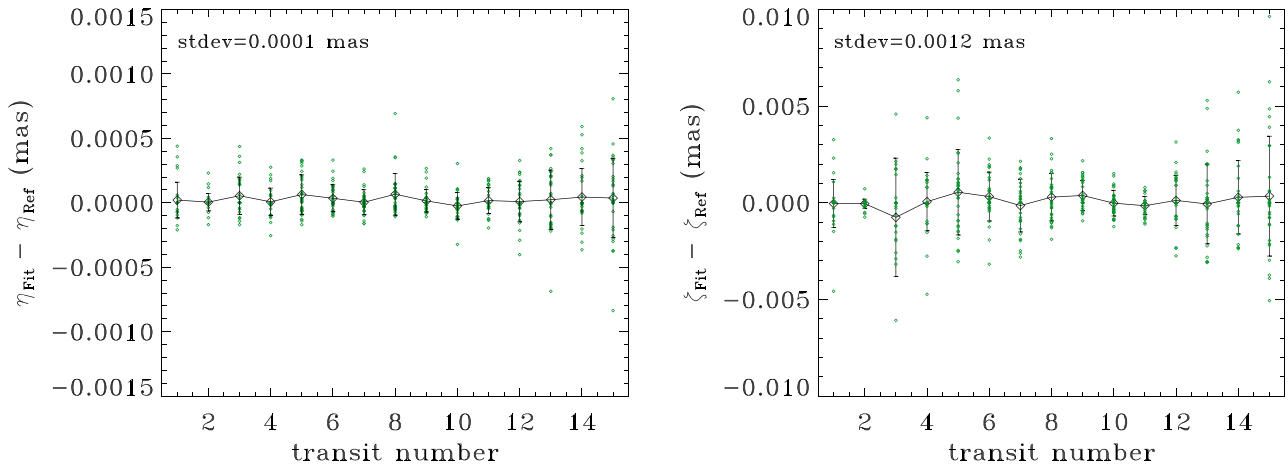


Figure 4. The residuals after removing a priori the proper motions and parallaxes of the stars as a function of the transit number with no added physical effects demonstrating the accuracies at the sub μ as level in AL (left-hand panel) and μ as level in AC (right-hand panel). The points show the average differences of the best-fitting positions for a reference star and its position on the reference frame on any given transit, where the green points are the mean differences for the star on that transit and the black points and error bars depict the average over all the stars for that transit and their standard deviation, respectively.

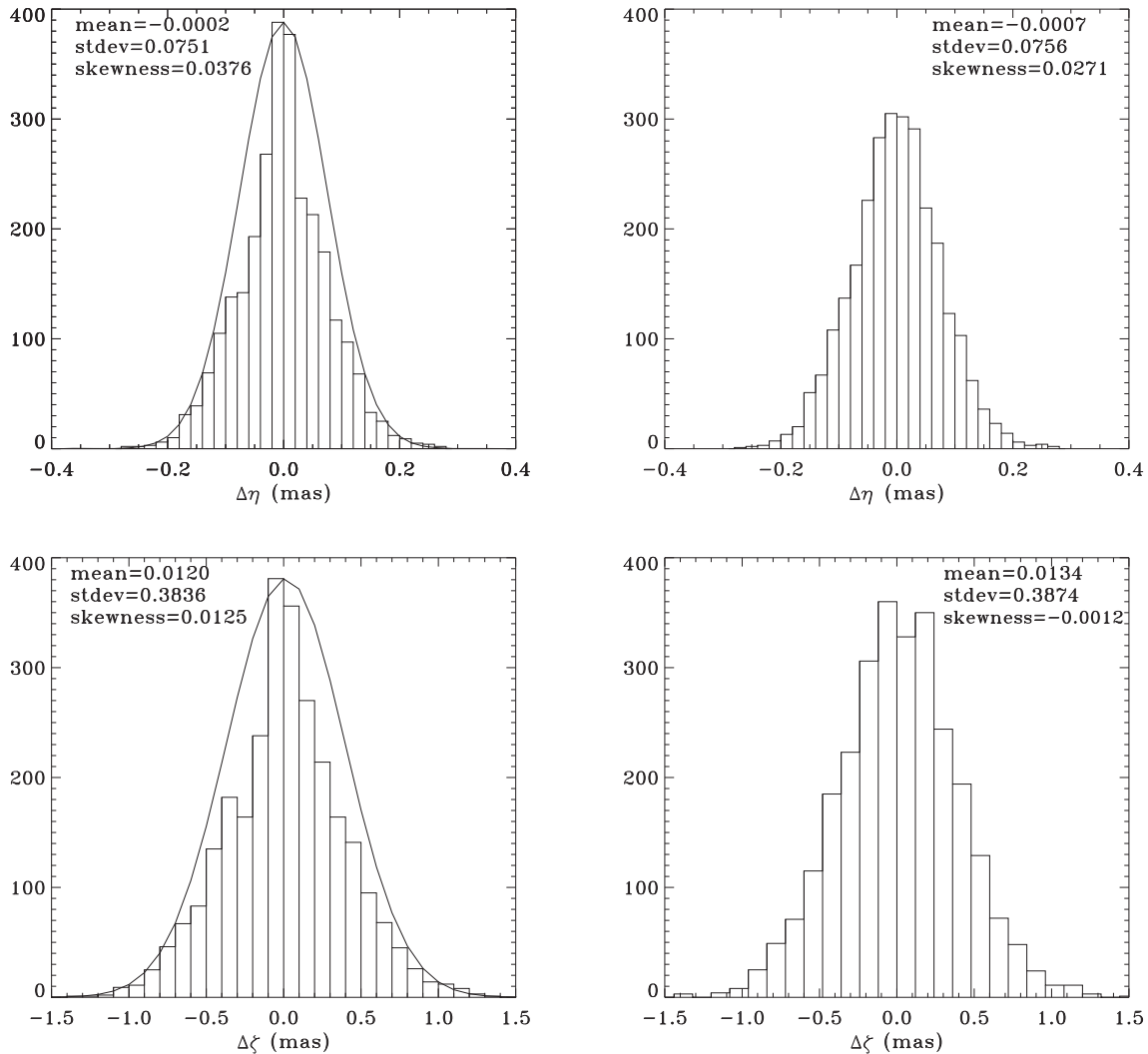


Figure 5. The residuals after removing a priori the proper motions and parallaxes of the stars (left-hand panels) with input Gaussian errors (right-hand panels) that follow the standard magnitude-dependent errors (Abbas et al. 2017).

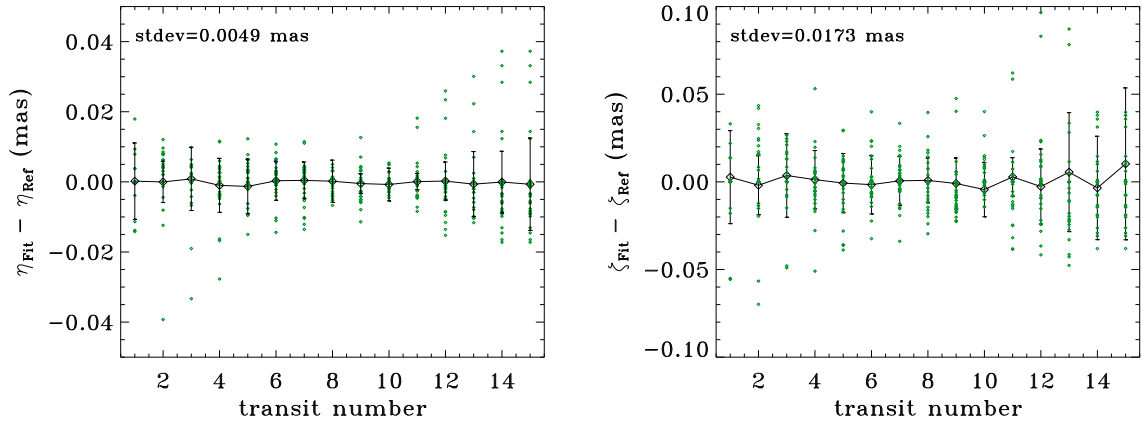


Figure 6. The stability of reference stars with unmodelled parallaxes that do not have their parallax estimates removed a priori (only proper motion estimates are removed). The left-hand panel shows the AL differences in the standard deviations and the right-hand panel shows the AC differences.

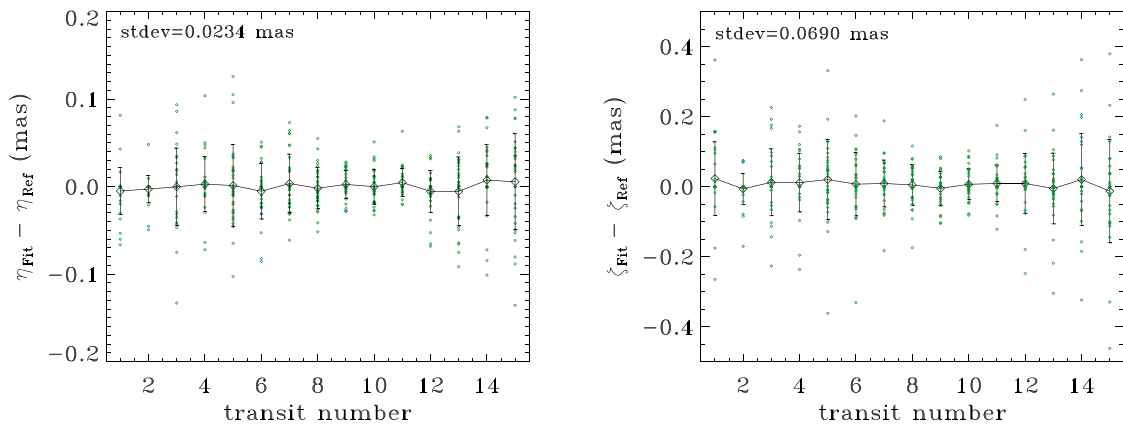


Figure 7. Same as Fig. 6 but now for unmodelled proper motions and parallaxes estimates removed a priori.

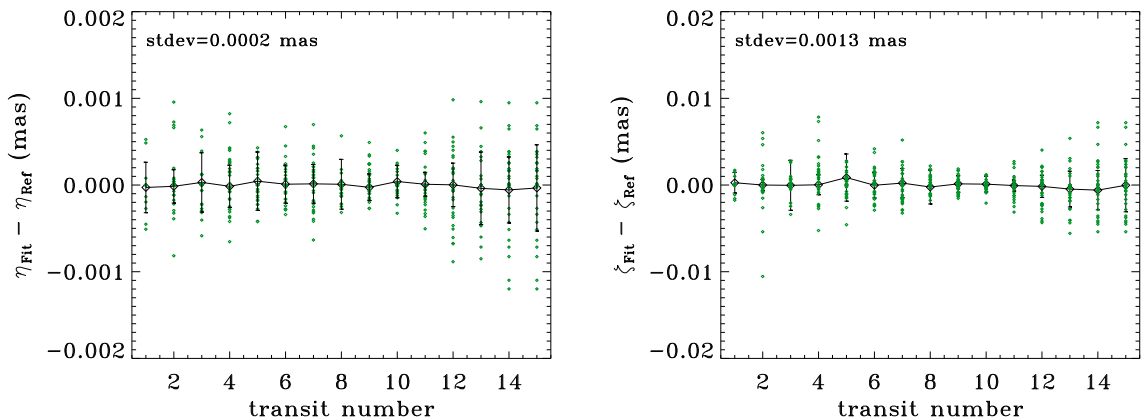


Figure 8. The stability of reference stars that have *Gaia* DR2 errors in their parallaxes. The left-hand panel shows the AL differences in the standard deviations and the right-hand panel shows the AC differences.

estimated values a priori nor attempting to model their contribution with appropriate unknown parameters that are subsequently estimated through a least-squares fitting procedure. These astrometric parameters would then augment the systematic floor and Figs 6 and 7 show the contributions from unmodelled parallaxes and proper motions, respectively, to the differences between the best-fitted star parameters for that transit and its reference frame value (see the

previous Section 4.1 for a more detailed description of the plot and points).

We can see that unmodelled proper motions have a four to five times larger effect on the stability than unmodelled parallaxes, where unmodelled *Gaia* DR2 proper motions introduce extra residuals of $\sim 23 \mu\text{s}$ (AL) and $69 \mu\text{s}$ (AC) versus the $\sim 5 \mu\text{s}$ (AL) and $17 \mu\text{s}$ (AC) due to unmodelled parallaxes. This result

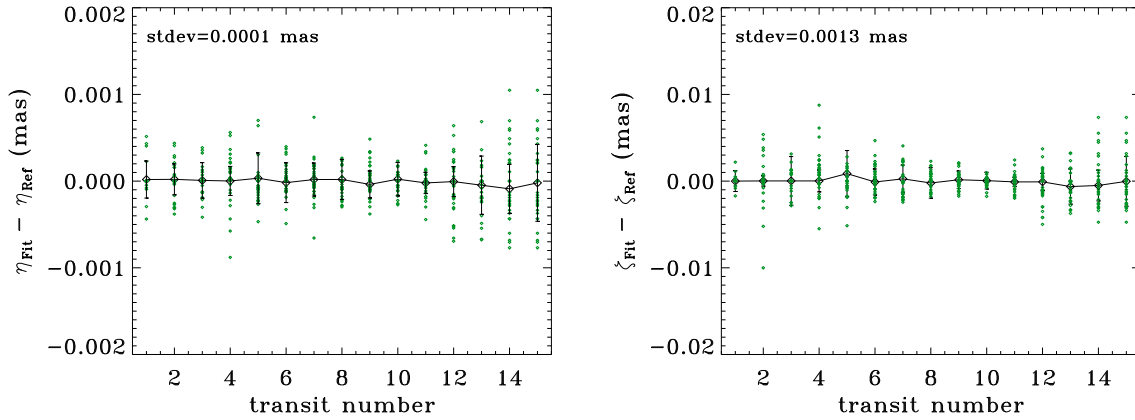


Figure 9. The stability of reference stars with errors in their proper motions as given by the *Gaia* DR2 catalogue.

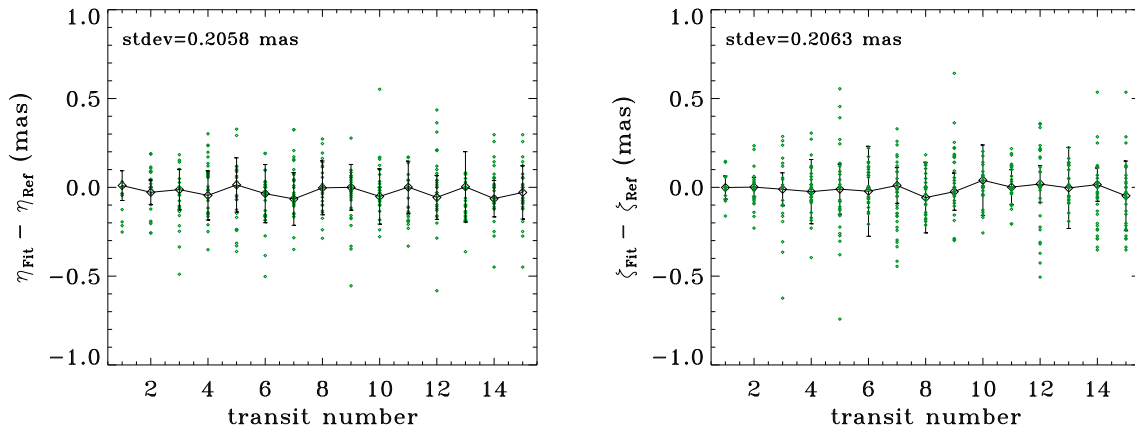


Figure 10. The stability of reference stars with $10 \mu\text{as s}^{-1}$ errors in each of the components of the satellite velocity.

can be explained by the smaller magnitudes of the parallaxes versus the much larger proper motions in combination with the time of year (contributing to the size of the parallax factor) and the short time span of observations.

4.3 Effect of parameter errors

In order to see the effect that catalogue errors in the astrometric parameters have on the stability, we add them as Gaussian deviates to the parameter values and remove projected estimates of the original error-free astrometric parameters a priori. Figs 8 and 9 show the effects of the catalogue errors in the parallaxes and proper motions. We can see that the stability remains at the sub μas level in AL and μas level in AC for both the parallaxes and proper motions demonstrating the minimal effect of such errors.

To see the effect, an imprecise satellite velocity has on the residuals, we artificially perturb its value by adding a time-dependent error of $10 \mu\text{as s}^{-1}$ in each of the components of the satellite velocity. The effect is shown in Fig. 10 giving AL and AC scan residuals of roughly 0.2 mas each. We noticed that by introducing even a small time dependence on the uncertainty quickly translates into a much larger error on the stability of the reference system over the time span of the observations. This is a highly conservative estimate in light of a variety of attitude errors such as microclanks and micrometeoroid hits (Lindegren et al. 2016). Interestingly enough, this type of error contributes large residuals eventually giving AL and AC stability values that are almost equal.

5 SUMMARY AND DISCUSSION

In this paper, we have further developed a differential astrometric framework for the analysis of *Gaia* observations, initially introduced in Abbas et al. (2017). We have specifically targeted high-cadence, short time-scale observations in one of the fields of the GAREQ experiment, which is set to provide an unprecedented measurement of the relativistic deflection of light due to Jupiter’s quadrupole and a first-time measurement in the optical of the light deflection due to Jupiter’s monopole (expected to be $\sim 16 \text{ mas}$ for a grazing light; Crosta & Mignard 2006).

We have demonstrated the sub μas -level stability of a local reference frame composed of a few tens of comparison stars surrounding the bright target star that is expected to show a large value for the relativistic light deflection due to its proximity to Jupiter’s limb. Our differential astrometric methodology relies upon pre-rotations that minimize second-order differential effects by transporting the various frames containing the field angles at different times to be overlapping around the target star, aligned with the unit vector defining the optical axis of *Gaia*. Subsequent gnomonic transformations convert the field angles into tangent plane coordinates centred on the target star. Furthermore, a Taylor series expansion of each reference star’s position around its fiducial point allows us to keep the number of calibration parameters to be estimated at a minimum, i.e. only two per CCD for each direction.

We show that a procedure for removing a priori error-free parallaxes and proper motions of reference stars brings the advantage of

reducing the number of unknown parameters to be estimated to only the calibration and plate parameters. Indeed if such a procedure is not adopted and the parallaxes and proper motions are left unmodelled, the residuals are enlarged with the most dominant effect (by a factor of 4–5) being that due to the proper motion. The inclusion of catalogue errors in the parallaxes and proper motions has a minimal impact, i.e. at the sub μas level in AL, mainly due to the smaller magnitudes in the errors. We also show that a lower precision knowledge of the satellite velocity with $10\ \mu\text{as s}^{-1}$ errors in its velocity components has a relatively important effect on the residuals giving conservative estimates of ~ 0.2 mas in both AL and AC.

We plan next to apply the methodology presented here to the analysis of the actual observations of events in the GAREQ experiment, and carry out detailed modelling of the various effects discussed in this paper. Additional, future applications of the differential astrometric approach to the analysis of *Gaia* observations naturally include configurations in which *Gaia* data are gathered on significantly longer time-scales than those (around 24 h) encompassed by the GAREQ experiment. Possible science cases include studies of future microlensing events (e.g. Bramich 2018; Mustill, Davies & Lindegren 2018), the astrometric detection of orbital motion induced by planetary-mass companions (e.g. Perryman et al. 2014; Sozzetti et al. 2014, 2016), and investigations of the brown dwarf binary fraction (e.g. Marocco et al. 2015, and references therein). All the above analyses will require further improvements in the modelling of calibration and instrument attitude effects, which become important for *Gaia* astrometric time series with years-long baselines. A robust modelling framework for differential astrometry is also mandatory in view of future developments in the field aimed at pushing the ultimate precision in position measurements in the μ as regime (e.g. Malbet et al. 2016) significantly beyond that achievable by *Gaia*.

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