



THE UNIVERSITY *of* EDINBURGH

Edinburgh Research Explorer

Limpet: an Autonomous Bioinspired Robot for Environmental Monitoring

Citation for published version:

Aracri, S, Sayed, M, Roberts, J, Mcconnell, A & Stokes, A 2018, 'Limpet: an Autonomous Bioinspired Robot for Environmental Monitoring'.

Link:

[Link to publication record in Edinburgh Research Explorer](#)

Document Version:

Other version

General rights

Copyright for the publications made accessible via the Edinburgh Research Explorer is retained by the author(s) and / or other copyright owners and it is a condition of accessing these publications that users recognise and abide by the legal requirements associated with these rights.

Take down policy

The University of Edinburgh has made every reasonable effort to ensure that Edinburgh Research Explorer content complies with UK legislation. If you believe that the public display of this file breaches copyright please contact openaccess@ed.ac.uk providing details, and we will remove access to the work immediately and investigate your claim.





THE UNIVERSITY *of* EDINBURGH



LIMPET: AN AUTONOMOUS BIOINSPIRED ROBOT FOR ENVIRONMENTAL MONITORING

Simona Aracri, Mohammed E. Sayed, Jamie O. Roberts, Alistair C. McConnell, Adam A. Stokes

The University of Edinburgh

STOKES RESEARCH GROUP

19TH BIENNIAL SEMINAR ON WATER RESOURCES AND ENVIRONMENTAL
MANAGEMENT
SEPTEMBER 2018





- The Limpet

The Limpet was born as the answer to the industry urge to monitor remotely harsh off shore environments, as such it is capable of several exteroceptive sensing modalities, robust in communication, portable, long leaving, low cost and low energy.

- Water Applications

Focus: LED turbidity measurements

Application: turbidity measurements for clean water and offshore hazardous substances detection

- Experiments & Results

Calibration using standard off-the-shelf turbidimeter

Light setting assessment

- Future work

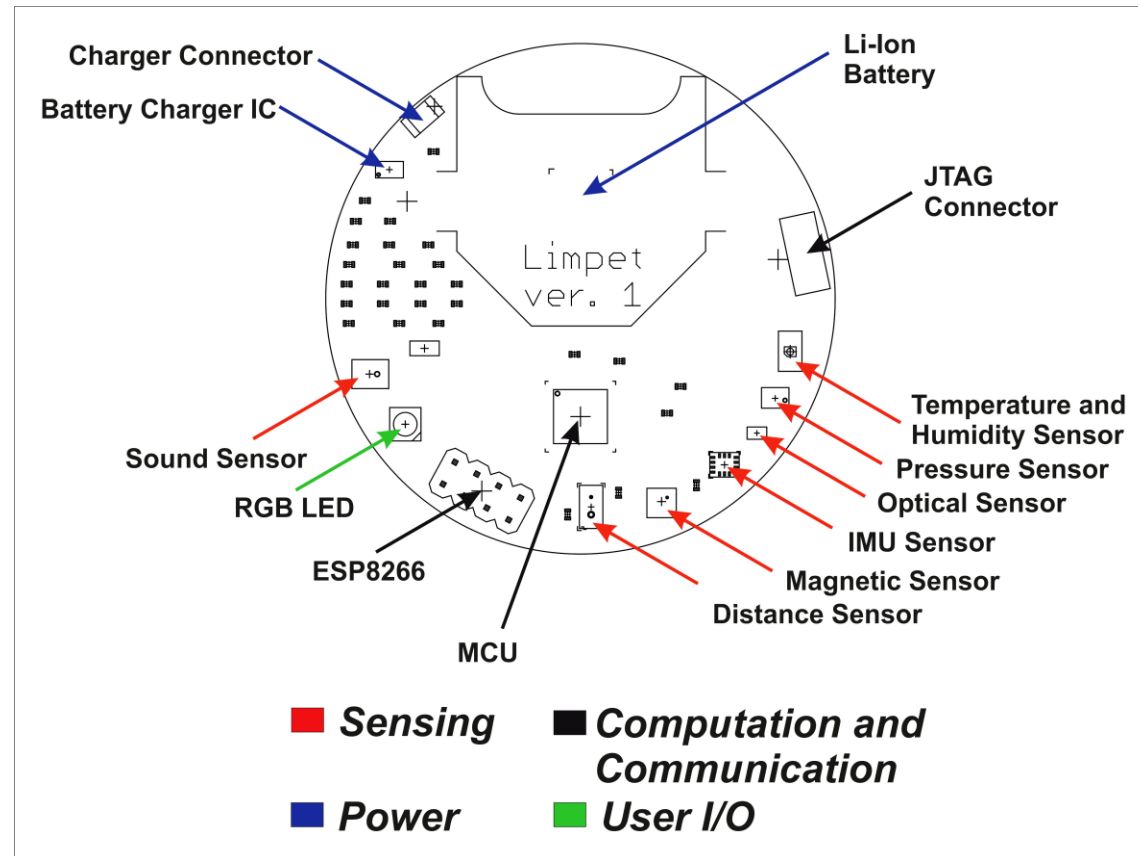
The potential of the Limpet is huge: energy harvesting, underwater applications, etc...





The Limpet

- 9 sensors
- Low cost: 20 £
- Low power: 182.9/0.1 mA
- Life time: 67 days/52 mins
- Portable: 50 mm



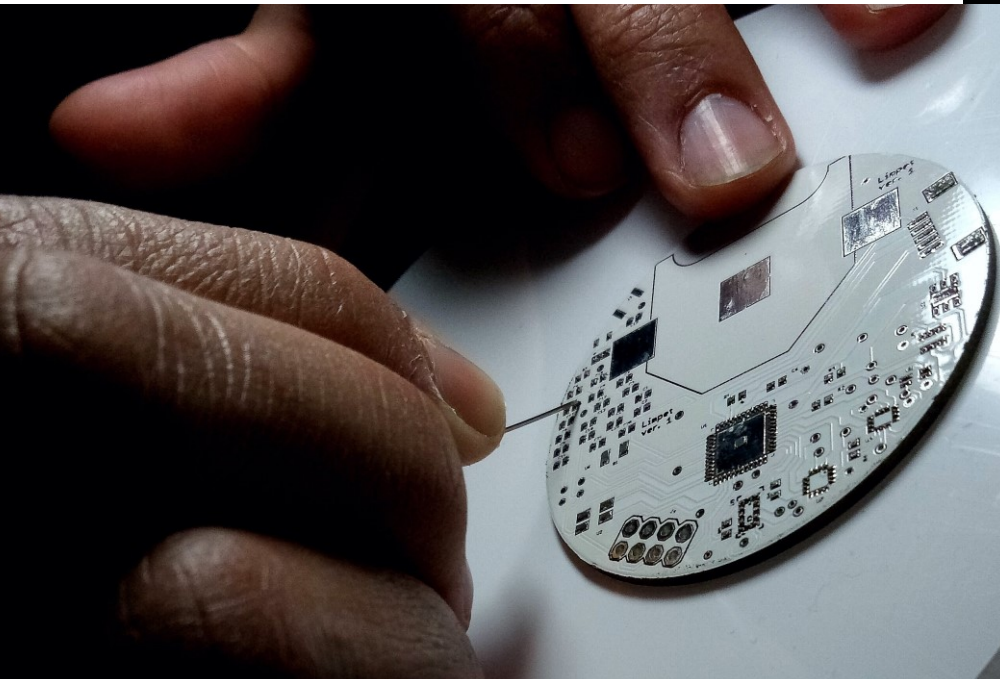
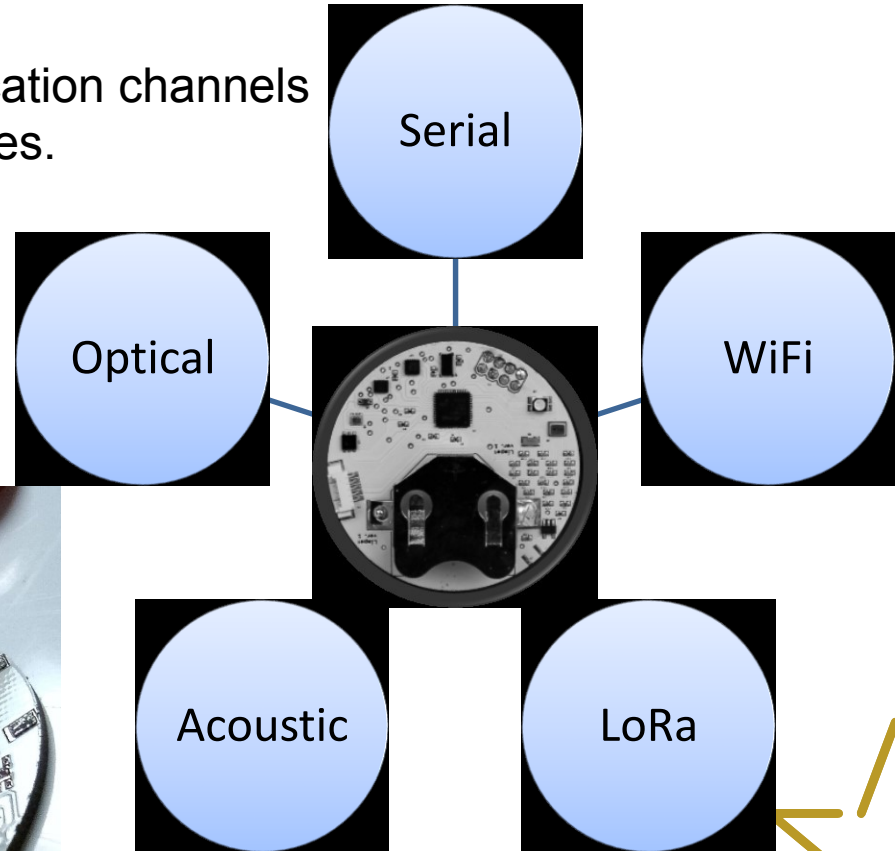


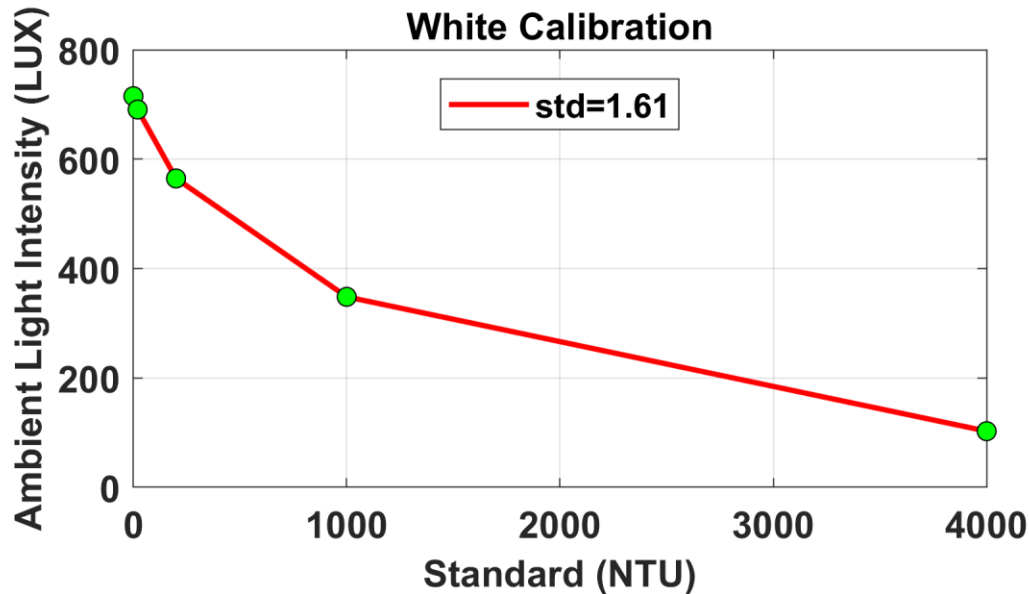
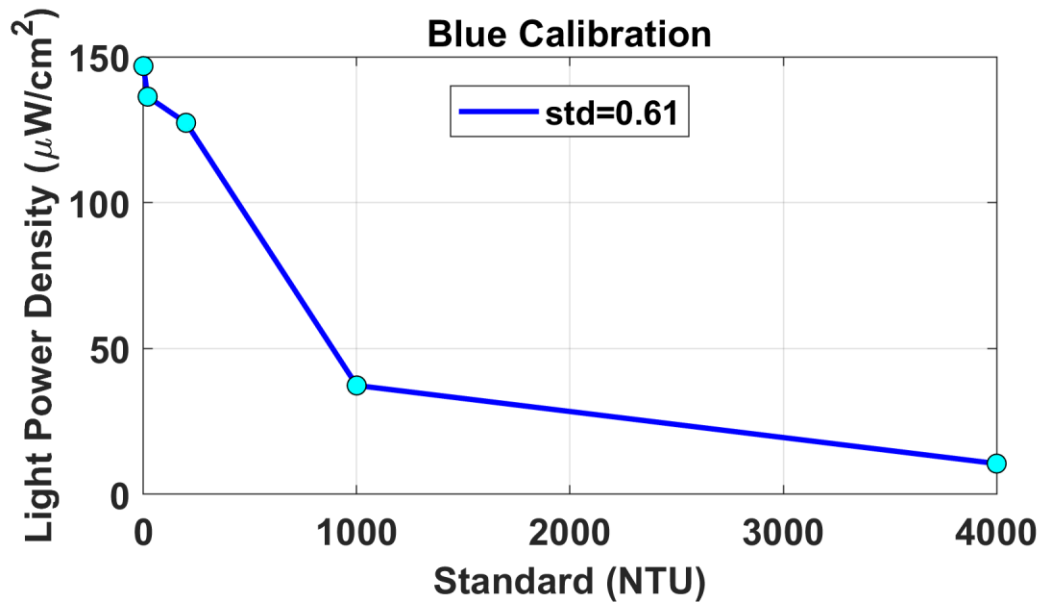
Sensor	Sensor Modality	Measurements
Accelerometer	Acceleration	<ul style="list-style-type: none">• Acceleration (x, y, z)• Temperature
Gyroscope	Angular Velocity	<ul style="list-style-type: none">• Angular Velocity (x, y, z)• Temperature
Temperature Sensor	Temperature	<ul style="list-style-type: none">• Temperature
Humidity Sensor	Humidity	<ul style="list-style-type: none">• Relative Humidity
Microphone	Sound	<ul style="list-style-type: none">• Sound Frequency
Pressure Sensor	Pressure	<ul style="list-style-type: none">• Temperature• Pressure• Altitude
Hall-Effect Sensor	Magnetic Field Strength	<ul style="list-style-type: none">• Magnetic Field Strength (x, y, z)• Temperature
Optical Sensor	Light Frequency	<ul style="list-style-type: none">• Correlated Color Temperature• Red/Green/Blue Light Power Density• Ambient Light Intensity
Distance (Time-of-Flight) Sensor	Laser	<ul style="list-style-type: none">• Distance (Range)



Robust Communication:
the Limpet blends traditional communication channels with the latest communication techniques.

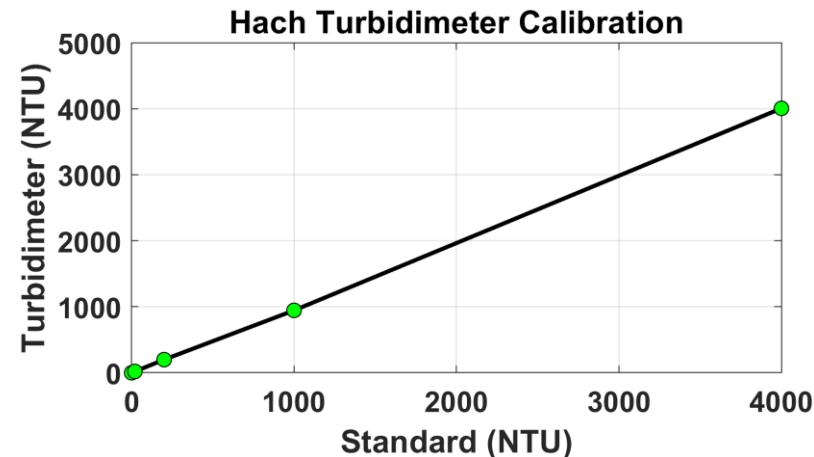
Communication Fail-over
the Limpet is able to switch between different communication channels if it is needed, e.g. in case of failure





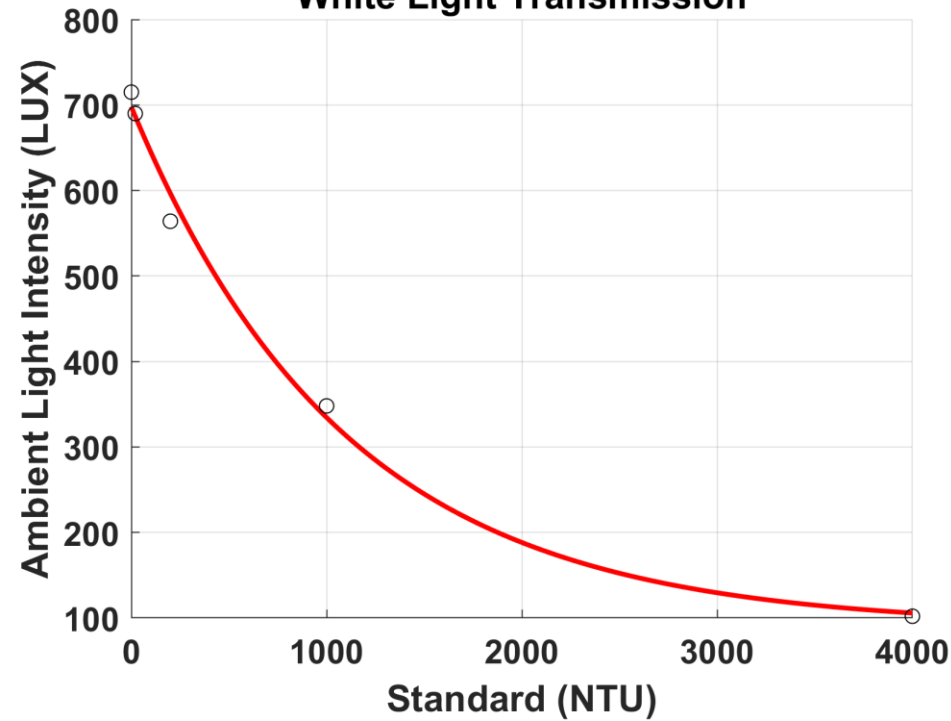
We ran measurements using solutions with a known turbidity level, i.e. Stabilized Formazin Turbidity Standards. The results displayed refer to:

- Hatch Turbidimeter
- Limpet Blue Light transmission
- Limpet White Light transmission

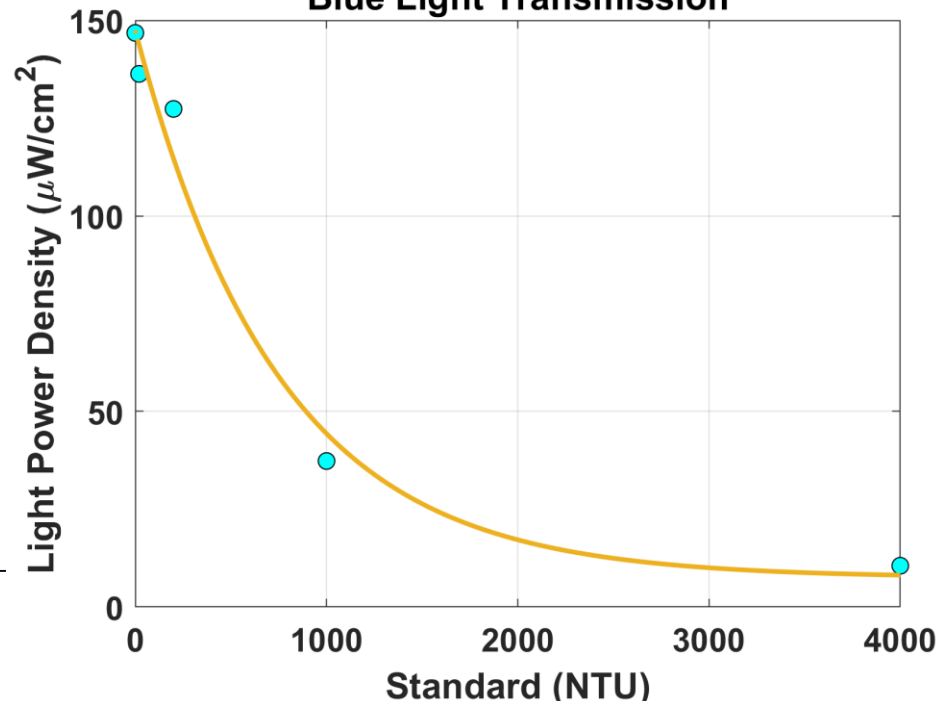




White Light Transmission



Blue Light Transmission





SOLUTION TESTING

Solutions measured by the Hatch Turbidimeter	
	MEAN±STD
Lemon Juice	577.7±48.6 (NTU)

Solutions measured by the Limpet with blue LED	
	MEAN±STD
Lemon Juice	72.2 ±0.70 (uW/cm2) 572 (NTU)

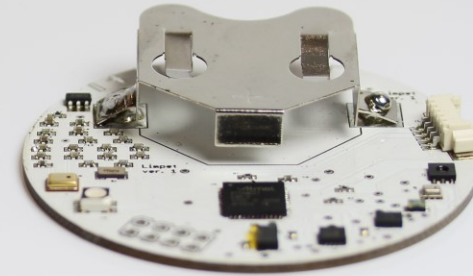
Solutions measured by the Limpet with white LED	
	MEAN±STD
Lemon Juice	374.5 ±5.2 (LUX) 852 (NTU)





Future Work

- Improve the fitting curve with more calibration points
- Investigate the back scatter parameter
- Develop an underwater set up for environmental monitoring





THE UNIVERSITY *of* EDINBURGH



THANK YOU

