

On a non-linear hyperbolic equation

By

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§ 1. Introduction

Let Ω be a bounded domain in \mathbb{R}^n with smooth boundary $\partial\Omega$. In this note we consider the initial-boundary value problem of the form

$$(1.1) \quad \partial^2 u / \partial t^2 - \Delta u + G(u) = 0, \quad x \in \Omega, \quad t > 0,$$

$$(1.2) \quad u(x, t) = 0, \quad x \in \partial\Omega, \quad t \geq 0,$$

$$(1.3) \quad \begin{cases} u(x, 0) = u_0(x), & x \in \Omega, \\ \partial u / \partial t(x, 0) = u_1(x), & x \in \Omega. \end{cases}$$

When the non-linear term G is Hölder continuous, J. C. Saut gave existence of global solutions of the above problem in [3].

The purpose of the present note is to extend a part of the Saut's results. We make on a continuous function G the following condition

$$(1.4) \quad |G(u)| \leq k_0 |u|^\alpha + k_1, \quad 0 < \alpha \leq 1,$$

Where k_0, k_1 are positive constants.

Remark 1.1. If G is Hölder continuous, then G satisfies (1.4).

We shall deal with real valued functions and use the notation in the book of J. L. Lions [2] and prove the following

Theorem. *Suppose that $u_0 \in H_0^1(\Omega)$, $u_1 \in L^2(\Omega)$. Then there exists a function u such that*

$$(1.5) \quad u \in L^\infty(0, T; H_0^1(\Omega)), \quad T > 0,$$

$$(1.6) \quad \partial u / \partial t \in L^2(0, T; L^2(\Omega)), \quad T > 0,$$

and which satisfies (1.1) in a generalized sense and (1.3).

Remark 1.2. The boundary condition (1.2) is implied by (1.5).

Remark 1.3. It follows from (1.5) and (1.6) that u is continuous from $[0, T]$ to $L^2(\Omega)$, possibly after a modification on a set of measure zero and from (1.5), (1.6) and (1.1) that $\partial u / \partial t$ is continuous from $[0, T]$ to $H^{-1}(\Omega)$.

§ 2. Existence of an approximate solution

Suppose that $0 < \alpha < 1$. We shall use the Galerkin's method. Let $\{w_i\}_{i=1,2,\dots}$ be a complete system in $H_0^1(\Omega)$. We look for an approximate solution $u_m(x, t)$ of the form

$$(2.1) \quad u_m(t) = \sum_{i=1}^m g_{im}(t) w_i, \quad g_{im} \in C^2([0, T]).$$

The unknown functions g_{im} are determined by the system of ordinary differential equations

$$(2.2) \quad \begin{cases} (u_m''(t), w_j) + a(u_m(t), w_j) + (G(u_m(t)), w_j) = 0, \\ 1 \leq j \leq m, \end{cases}$$

with initial conditions

$$(2.3) \quad u_m(0) = u_{0m}, \quad u_{0m} = \sum_{i=1}^m \alpha_{im} w_i \rightarrow u \quad \text{in } H_0^1(\Omega) \quad \text{as } m \rightarrow \infty,$$

$$(2.4) \quad u_m'(0) = u_{1m}, \quad u_{1m} = \sum_{i=1}^m \beta_{im} w_i \rightarrow u_1 \quad \text{in } L^2(\Omega) \quad \text{as } m \rightarrow \infty.$$

Here $u' = \partial u / \partial t$, $u'' = \partial^2 u / \partial t^2$, $(u, v) = \int_{\Omega} uv dx$,

$$(2.5) \quad a(u, v) = \sum_{i=1}^n \int_{\Omega} (\partial u / \partial x_i) (\partial v / \partial x_i) dx.$$

By general theory on the system of ordinary differential equations, there exists a solution of (2.2), (2.3) and (2.4) in an interval $[0, t_m]$, $t_m > 0$.

A priori estimate in §3 assure that $t_m = T$.

§ 3. A priori estimate

Multiplying (2.2) by $g_{im}'(t)$ and summing over j from 1 to m , we get

$$(3.1) \quad (1/2) (d/dt) (|u_m'(t)|^2 + \|u_m(t)\|^2) + (G(u_m(t)), u_m'(t)) = 0,$$

Where $|u|^2 = (u, u)$, $\|u\|^2 = a(u, u)$.

Using (1.4), Hölder's inequality and Sobolev's inequality, we have

$$(3.2) \quad \left\{ \begin{aligned} (1/2) (d/dt) (|u'_m(t)|^2 + \|u_m(t)\|^2) &\leq k_2 |u'_m| \|u_m\|^{\alpha} + k_3 |u'_m| \\ &\leq k_4 (|u'_m|^{1+\alpha} + \|u_m\|^{1+\alpha}) + k_5 \quad (\text{by Young's inequality}) \\ &\leq k_6 \{ (1/2) (|u'_m|^2 + \|u_m\|^2) \}^{\frac{1+\alpha}{2}} + k_7 \end{aligned} \right.$$

Where k_2, \dots, k_7 are positive constants.

We define $e_m(t)$ by

$$(3.3) \quad e_m(t) = (1/2) (|u'_m(t)|^2 + \|u_m(t)\|^2),$$

then by integrating with respect to t and using (2.3) and (2.4), we have an integral inequality

$$(3.4) \quad e_m(t) \leq c_0 + c_1 t + c_2 \int_0^t e_m^{\frac{1+\alpha}{2}}(s) ds,$$

Where c_0, c_1, c_2 are positive constants independent of m .

From the results of integral inequalities (see [1]), we obtain

$$(3.5) \quad e_m(t) \leq c_0 + c_1 t + M(t).$$

Here $M(t)$ is the maximal solution of ordinary differential equation of the form

$$(3.6) \quad y'(t) = c_2 (c_0 + c_1 t + y)^{\frac{1+\alpha}{2}},$$

with initial condition

$$(3.7) \quad y(0) = 0.$$

Since $0 < \frac{1+\alpha}{2} < 1$, the above maximal solution $M(t)$ exists in the large. Hence

$$(3.8) \quad (1/2) (|u'_m(t)|^2 + \|u_m(t)\|^2) \leq c(T),$$

and $c(T)$ is a constant independent of m .

This a priori estimate shows $t_m = T$.

§4. Existence of global solutions

From a priori estimate (3.8) and Rellich's theorem, we can find a function u and a subsequence $\{u_\mu\}$ of $\{u_m\}$ such that

$$(4.1) \quad u_\mu \rightarrow u \quad \text{in } L^\infty(0, T; H_0^1(\Omega)) \text{ weakly star,}$$

$$(4.2) \quad u'_\mu \rightarrow u' \quad \text{in } L^\infty(0, T; L^2(\Omega)) \text{ weakly star,}$$

$$(4.3) \quad u_\mu \rightarrow u \text{ in } L^2(0, T; L^2(\Omega)) \text{ strongly and a. e. in } \Omega \times [0, T].$$

By (4.3), (1.4) and a well-known lemma (see Lemma 1.3 [2]), we have

$$(4.4) \quad G(u_\mu) \rightarrow G(u) \text{ in } L^{\frac{2}{\alpha}}(0, T; L^{\frac{2}{\alpha}}(\Omega)) \text{ weakly,}$$

Which implies the function u satisfies (1.1) in a generalized sense.

We next prove that u satisfies (1.3). From (4.1), (4.2) and Lemma 1.2 [2], in particular

$$(4.5) \quad u_\mu(0) \rightarrow u(0) \text{ in } L^2(\Omega) \text{ weakly}$$

and since $u_\mu(0) = u_{0\mu} \rightarrow u_0$ in $H_0^1(\Omega)$, we have

$$(4.6) \quad u(0) = u_0.$$

Using (2.2), (4.1), (4.2) and (4.4), we get

$$(4.7) \quad (u_\mu'', w_j) \rightarrow (u'', w_j) \text{ in } L^{\frac{2}{\alpha}}(0, T) \text{ weakly.}$$

It follows from (4.2) (4.7) that

$$(4.8) \quad (u_\mu'(0), w_j) \rightarrow (u', w_j)|_{t=0} = (u'(0), w_j) \quad \forall j.$$

Since $(u_\mu'(0), w_j) = (u_{1\mu}, w_j) \rightarrow (u_1, w_j) \quad \forall j$ we have

$$(4.9) \quad u'(0) = u_1.$$

This completes the proof of theorem when $0 < \alpha < 1$.

Remark 4.1. When $\alpha = 1$, we can more easily prove the existence of global solutions.

References

- [1] V. Lakshmikantham and S. Leela, Differential and Integral Inequalities Vol. 1, Academic Press, New York and London, 1969.
- [2] J. L. Lions, Quelques Méthodes de Résolution des Problèmes aux Limites non Linéaire, Dunod, Paris, 1969.
- [3] J. C. Saut, Sur un problème hyperbolique non linéaire, C. R. Acad. Sc. Paris, t. **273** (1971), 671-673.