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Detection and Prediction of Absence Seizures Based on Nonlinear Analysis of the EEG in Wag/Rij Animal Model

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Abstract

Background: Epilepsy is a common neurological disorder with a prevalence of 1% of the world population. Absence epilepsy is a form of generalized seizures with Spike wave discharge in EEG. Epileptic patients have frequent absence seizures that cause immediate loss of consciousness.

Methods: In this study, it has been tried to explore whether EEG changes can effectively detect epilepsy in animal model applying non-linear features. To predict the occurrence of absence epilepsy, a long-term EEG signal has been recorded from frontal cortex in seven Wag/Rij rats. After preprocessing, the data was transferred to the phase space to extract the brain system dynamic and geometric properties of this space. Finally, the ability of each features to predict and detect absence epilepsy with two criteria of predictive time and the accuracy of detection and its results were compared with previous studies.

Results: The results indicate that the brain system dynamic changes during the transition from freeseizure to pre-seizure and then seizure. Proposed approach diagnostic characteristics yielded 97% accuracy of absence epilepsy diagnosis indicating that due to the nonlinear and complex nature of the system and the brain signal, the use of methods consistent with this nature is important in understanding the dynamic transfer between different epileptic seizures.

Conclusion: By changing the state of the absence Seizures, the dynamics are changing, and the results of this research can be useful in real-time applications such as predicting epileptic seizures. **Keywords:** Component; Absence epilepsy, Electroencephalogram, Phase space, Nonlinear attractor, Geometric properties

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Introduction

Epilepsy is one of the most common neurological disorders with a prevalence of 1% of the world's population. About 80% of people with epilepsy live in developing countries.¹ Today, people with epilepsy and their families suffer from social discrimination and social stigma in many parts of the world. Epileptic seizures can be associated with impairment or loss of consciousness.^{1,2}

Absence seizures are a form of generalized seizures with Spike wave discharge (SWD) in EEG.² These rapid and sudden seizures are transient symptoms and/or signs of abnormal, excessive or synchronous neuronal activity in the brain.³ People with absence epilepsy have repeated seizures that cause momentary lapses of consciousness.⁴ The period of short-lived absence seizures usually lasts from several seconds to about a minute, and may be repeated more than 100 times a day.5

Since these sudden and rapid seizures often occur in childhood or adolescence, and may have significant impact on the educational development of patients.^{6,7} Therefore, understanding the transition of brain activity to the absence seizure, called the pre-seizure, is a very difficult goal and is still under discussion.^{8,9}

The EEG, which records spontaneous electrical activity in the brain, was first measured in humans by Hans Berger in 1929. Since then, EEG is one of the most useful tools for studying cognitive processes and brain physiopathology,^{9,10} especially the processes involved in epileptic seizures.^{11,12}

In the recent decade, dynamics from free-seizure to seizure status has been investigated with different linear or nonlinear methods.¹⁰⁻¹² To some extent, these results

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showed that the change in EEG features during the seizure could be detected several minutes before the onset of a seizure in focal epilepsy.¹³⁻¹⁵ However, the prediction of sudden and rapid seizures with dynamic EEG changes in people with absence epilepsy is still open problem.^{16,17} Additionally, understanding the transition of brain activity to epileptic seizures and the identification of some pioneering tasks is challenging.^{8,9,18}

Sitnikova and van Luijtelaar et al showed that SWD activity in albino rats was associated with the precursor delta and theta short activities in cortex and thalamus.¹⁸⁻²⁰ These EEG precursors in rat models provide clues for the prediction of human absence epilepsy. Signal analysis and its trajectory in the phase space can lead to a better understanding of the system's dynamics and provide valuable information about attractors and system behavior. In particular, nonlinear time series analysis methods are presented to identify epileptic seizure states.^{16,21-26} To a certain extent, these methods mainly include the Lyapunov exponent and the correlation dimension, which is able to extract the properties of the useful EEG data to provide evidence to confirm the existence of a previous state of seizure in temporal lobe epilepsy.²¹⁻²⁴

Ouyang et al used recurrent quantification analysis to distinguish between states in GEARS genetic model of absence epilepsy and show that certainty in seizure periods is higher than in two other states.²⁷ Multiscale permutation entropy (MPE) was used to describe the dynamic properties of EEG on various human absence epilepsy and the ability to classify MPE by linear discrimination analysis (LDA) was evaluated. Comparison with the conventional entropy methods with a classification accuracy of 86.1%, the classification rate was 90% with a MPE index.²⁸ Similarly, in Li et al study using permutation entropy, an examination was implemented to determine whether EEG data changes can detect various states of human absence epilepsy.1 The average PE values have been shown to gradually decrease from no seizure to seizure state and provide evidence that three different phases of seizure in absence epilepsy can be detectable.

Despite numerous studies conducted on human EEG and animal models, it has been largely attributed to the extraction of global features. The evolutionary characteristics of the EEG signal based on the dynamics of turbulence is still an open issue.²⁷ Using geometric features, regardless of any assumptions about the type of dynamics of the basis, provides studies independent of the hypothesis of chaos and therefore independent of the analysis of alternative data.²⁹ This study attempts to apply features based on phase space geometry to discover whether EEG changes can effectively identify absence seizures.

Materials and Methods

Surgery and Recording System

EEG epochs were obtained from 7 of genetic absence



epilepsy Wag/Rij rats (Male, weight 300 ± 5 g) with a minimum age of 5 months. Animals were anesthetized with ketamine 100 mg/kg and xylazine 10 mg/kg. In all animals, dipole EEG stainless steel electrodes were placed in the frontal cortex area (1 mm above Bregma and 3 mm from Lambda) and the reference electrode was also placed in the temporal region. Each animal was kept in a separate box for recovery in the animal house. The EEG electrode signal was directly connected to the BioAmp ML 136 amplifier and stored using LabChart software. The EEG data was recorded for a long term of 48 to 72 hours at a sampling rate of 1 kHz using a 16-bit ADC and a filter with frequency band of 0.5-100 Hz (Figure 1).

Feature Extraction

Based on the well-known theory of phase space and embedding, Takens states that system behavior in state space can be estimated by a vector of observation, such as EEG. A variety of new concepts and time series analysis techniques have been developed to allow the description of the behavioral dynamics of the system for an indefinite system. Proposed geometric properties can be calculated in accordance with equation (1) to the trajectory x (t) in dimension d. In practice, all d states are not accessible in the phase space, and only the vector of observations x (t) is available.³⁰

$$\vec{x}(t) = [x_1(t), x_2(t), \dots, x_d(t)]$$
 (1)

The Takens method,¹⁹ is used frequently to embedded the time series x(t) into the d-dimensional phase space:

$$\vec{x}(t) = [x(t), x(t-\tau) \dots x(t-(d-1)\tau)]$$
 (2)

Where *d* is the embedding dimension and τ is the lag estimated by the false nearest neighbor algorithm³¹ and the mean of mutual information.³² Table 1 lists the features list, some of which are presented below.

Center of Gravity

The center (g_x, g_y) is equal to:

$$\begin{cases} g_x = \frac{1}{N} \sum_{i=1}^{N} x_i \\ g_y = \frac{1}{N} \sum_{i=1}^{N} y_i \end{cases}$$
(3)

Where *N* is the number of points in the 2-D phase space.

Table 1. Geometric Features of Phase Space³³

Feature	Symbol	Description
1	A	Area
2	G _x	Horizontal center of gravity
3	G _v	Vertical center of gravity
4	T Í	Axis of Least Inertia
5	E	Eccentricity
6	C _{va}	Circularity ratio
7	C _{va}	Ellipse variance
8	В	Average bending energy
9	Р	Perimeter
10	R	Rectangularity
11	TAR	Triangle area representation
12	CD	Centroid distance
13	CC	Complex coordinate



Figure 2. Least Inertia. The yellow point shows the center of gravity.³³

Axis of Least Inertia

The least inertia axis, the *ALI*, is used as a unique reference line to maintain the shape orientation, and is defined in such a way that the square integral of the distances from the boundary points is minimal (Figure 2).

Average Bending Energy

The average bending energy, BE, is defined as:

$$BE = \frac{1}{N} \sum_{s=0}^{N-1} K(s)^2$$
(4)

K(s) is the Curvature function, *s* is the parameter of the arc length and *N* is the number of contour points.³⁴





Eccentricity

This criterion measures the aspect ratio, and in fact the ratio of the axis to the small one (Figure 3). It can be calculated using the principal axis method or the minimum bounding rectangle method.³³

Circularity Ratio

The circularity ratio explains how the shape is similar to a circle³⁵:

$$C_{va} = \frac{\sigma_R}{\mu_R}$$
(5)

 μ and σ are the mean and standard deviation of the radial distance from the center of gravity of the basin of attraction relative to the boundary points.

Ellipse Variance

This criterion is equivalent to mapping error to fit to the ellipse with a similar covariance matrix.³³

Rectangularity

The rectangularity states how and to what extent the minimum rectangle fills the boundary:

Rectangularity =
$$\frac{A_S}{A_R}$$
 (6)

Where A_S is the area of the shape and A_R , the area of the minimum rectangle is the range.³³

Convexity

The ratio of the perimeter of the convex cortex to the contour environment³⁶:

$$Convexity = \frac{O_{Convexhull}}{O}$$
(7)

Complex Coordinate

The complex coordinate function is the simplification of complex numbers generated from the coordinates of the boundary points³³:

$$\begin{cases} P_{n}(x(n),y(n)), & n \in [1,N] \\ z(n) = [x(n) - g_{x}] + i[y(n) - g_{y}] \end{cases}$$
(8)



Figure 4. Area function, S(n) is the area between the boundary points $P_{o'}P_{o+1}$ and the center of gravity, G.³³

Area Function

By changing the boundary points along the boundary, the area of the triangle formed with two border points and the center of gravity also changes (Figure 4).³³

Triangle Area Representation

The triangle area representation, *TAR*, is calculated by the area of the triangle formed by points on the boundary of the shape.³³ For sequential points $P_n(x_n, y_n)$, $P_n(x_{n-t_s}, y_{n-t_s})$ and $P_n(x_{n+t_s}, y_{n+t_s})$, *N* is even.

$$TAR(n,t_{s}) = \frac{1}{2} \begin{vmatrix} x_{n-t_{s}} & y_{n-t_{s}} & 1 \\ x_{n} & y_{n} & 1 \\ x_{n+t_{s}} & y_{n+t_{s}} & 1 \end{vmatrix}$$
(9)

Feature Evaluation

Chaotic a n d nonlinear dynamics features have two important characteristics:

- is sensitive to the dynamic changes of the system.
- is invariant to the initial conditions change.

So, firstly, the proposed features were evaluated with the Lorenz system trajectory, Equation 10.

Lorenz system:
$$\begin{cases} \frac{dX}{dt} = \sigma(Y - Z) \\ \frac{dY}{dt} = rX - Y - XZ \\ \frac{dZ}{dt} = XY - \beta Z \end{cases}$$
 (10)

To evaluate the features, each was calculated for different parameters of Lorenz system and 10 iterations. If the distribution is different from each other for different values of the parameter, the feature will be invariant. This significant separability is tested by two-sample t test method (Figure 5).

Results

Table 2 represents the *P* values of the Jarque-Bera test for feature values for each of the parameters. The values of P > 0.05 show that the values of features follow the normal distribution. As it can be seen in most cases the p-value is greater than 0.05, so that the *t* test can be applied to the values of the features.

Figure 6 present results of two-sample t test at the 5% significance level. Each black pixel shows feature values that causes pixels are independent. This means that the two sets of parameter values are meaningfully separated. It is observed that the properties of the Lorenz system are highly sensitive to parameter variations and are invariant due to initial conditions variations. After evaluating the features, phase space analysis and their calculation on the EEG signal of the animal model were made. As it can be seen, the geometry of the phase space of the EEG in the transition from seizure-free to seizure state is changing (Figure 7). The phase space symmetry is lost in transit from seizure free to seizure state, in such a way that the phase space has become asymmetrical from the ellipse shape. Additionally, the contraction and expansion in the phase space of the seizure state is the signs of the stretching



Figure 5. The Trajectory of the Lorenz System for σ = 16, r = 50 and β = 4.

Table 2. The P Values of Features Values for Normality Test

Feature	Lorenz System					
А	0.50	0.50	0.01	0.30	0.13	
G _x	0.27	0.50	0.50	0.18	0.20	
G	0.42	0.21	0.07	0.005	0.50	
T I	0.23	0.50	0.27	0.41	0.50	
E	0.50	0.07	0.35	0.05	0.50	
C _{va}	0.002	0.50	0.01	0.33	0.50	
E	0.50	0.07	0.35	0.05	0.50	
E _{va}	0.2	0.50	0.28	0.3	0.1	
R	0.50	0.004	0.50	0.14	0.37	
TAR	0.50	0.50	0.34	0.11	0.1	
CD	0.004	0.50	0.37	0.17	0.001	
CC	0.40	0.21	0.002	0.50	0.50	

The bold values are greater than 0.05 that means feature values come from normal distribution.



Figure 6. The result of *t* test between all pair of parameters for each of the features which are extracted from Lorenz trajectories. The black color shows that the feature values for pair parameter are independent.

and folding of the EEG in this state, which confirms the existence of chaotic degrees even in seizure mode.

Figure 8A-E shows values of some of the features for 5 seconds before the seizure and 10 seconds after for 1500 EEG segments.



Figure 7. The Mean Phase-Space Contour of the 1500 EEG Segments in an Animal Model for Free-Seizure, Pre-seizure, and Seizure States.

According to the results of the counter area, the phase space in the transition from free-seizure state to a seizure state is increasing (Figure 8A).

In addition to changing the geometry of the phase space, changing the position of the phase space on the phase space can reveal the dynamic changes of the EEG signal, which in this transition the position of the center of gravity of the phase space is being displaced (Figure 8B). With regard to the significant changes in the Axis of Least Inertia (Figure 8C), it is proved that the orientation of the phase space in the transition to the seizure varies considerably. Other features also showed significant changes (Figures 8C-E).

In order to achieve the optimal threshold, the detection accuracy curve was calculated in terms of threshold for each of the features and the optimal threshold was determined. Figure 9 shows this curve for the Axis of

 $\ensuremath{\text{Table 3.}}$ Average Accuracy of Geometric Features for 1500 EEG Segments

Feature	Mean ACC %
А	97
G _x	91
G _v	82.5
1 Í	97
E	25
C _{va}	66
E _{va}	64
В	81
Р	95.5
R	47
TAR	10.5
CD	97
CC	94

Least Inertia feature.

Discussion

In this Research, it was attempted to determine whether EEG changes could effectively identify the free-seizure, pre-seizure and seizure states in the animal model of absence epilepsy by applying features based on phasespace geometry (Table 3). Unlike traditional time series analysis, nonlinear dynamics describes the nonlinear relation of system variables by examining variables only in phase space. The main strength of this method is to provide information in accordance with the basic dynamics of the system without having information of all the evolution parameters in the system. Hence, in this approach, the dynamics of the system in the reconstruction phase space



Figure 8. (A) Representation of Area feature, A. (B) Horizontal Center of Gravity, G_x. (C) Axis of Least Inertia, *I*. (D) Perimeter, *P*. (E) Centroid Distance, *CD*.



Figure 9. Determination of the Optimal Threshold by Calculating the Seizure Detection Accuracy for Different Thresholds.

 Table 4. Performance comparison with some existing methods that use the same data sets

ACC%	Seizures	Year	Reference
21 & 54	314	2007	16
94	Not reported	2008	37
Accuracy higher than 90	202	2009	38
85	Not reported	2009	39
94.8	73	2014	40
91.8 94.9 89.9 For three absence genes	205	2015	41

and then the reconstructed attractors were quantified.

Table 4 compares the results of the proposed approach and previous studies in the detection of absence seizures. As the results suggest, the performance of the proposed method has improved in comparison with other previous studies. One of the highlights of this study is generalization, so that 1500 segments were used for evaluation, however, with a 97% accuracy.

In addition, in previous studies, it has often used linear approaches to quantification of the EEG signal, while the nature of the EEG signal is particularly nonlinear and it is necessary to provide an approach to detect the dynamics of this signal. The shape clearly confirms the appropriateness of the dynamic variation of the phase space with the transition of the EEG signal from freeseizure to the seizure phase.

In this study, it was shown that simple, yet meaningful features such as the area and the environment can be found to provide best detection. Certainly, the application of more complex pattern identification systems will improve the detection results. Dynamic changes during multiple seizures and the prognosis of the disease are among the issues discussed in examining absence epilepsy with the use of the EEG signal.

Conflict of Interest Disclosures

The authors declare that they have no conflict of interests.

Ethical Statement

All animal experiments were conducted in compliance with the international ethical and animal-laboratory regulations and the Code of Ethics for Laboratory and also according to Human and

animal research ethics committee rules of Ferdowsi University of Mashhad.

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