

Drivers of Jet-flap interaction noise: The thrust vs. shear layer difference velocity experiment

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Knowledge for Tomorrow

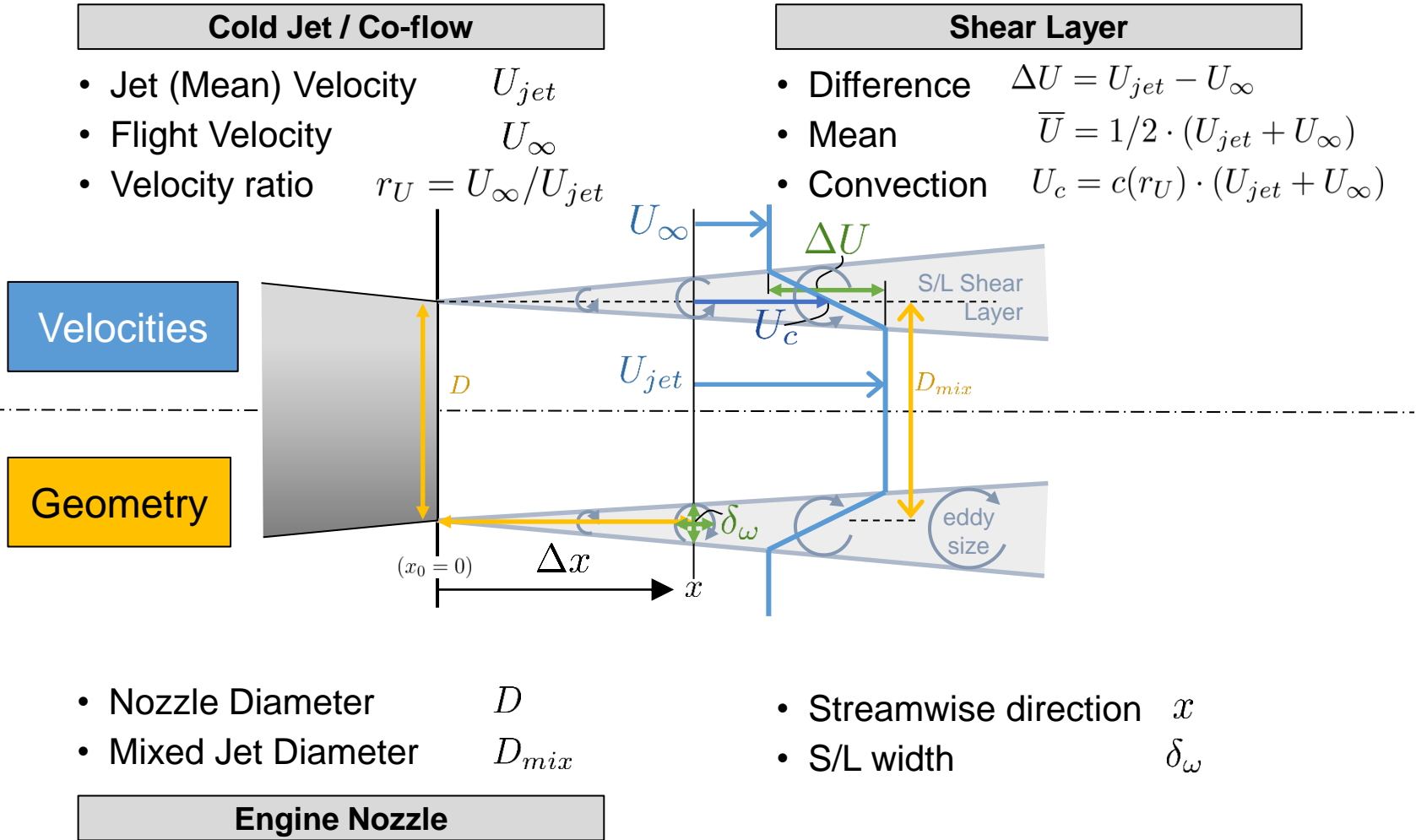
Motivation

- not fully known: velocity scaling parameter for two-phase / flight ops JFI problems
- Can we predict JFI noise using a simple engine velocity parameter?
(maybe with focus on high frequencies, radical engine integrations)
 - exponent known
 - more than one suitable flow parameter candidate available



Definition of jet shear layer properties

Christian Jente and Jan Delfs. Velocity scaling of shear layer noise induced by cold jet flow with co-flowing flight stream. In 25th AIAA/CEAS Aeroacoustics Conference, Aeroacoustics Conferences. American Institute of Aeronautics and Astronautics, 2019. 2019-2496



Definition of velocity parameters

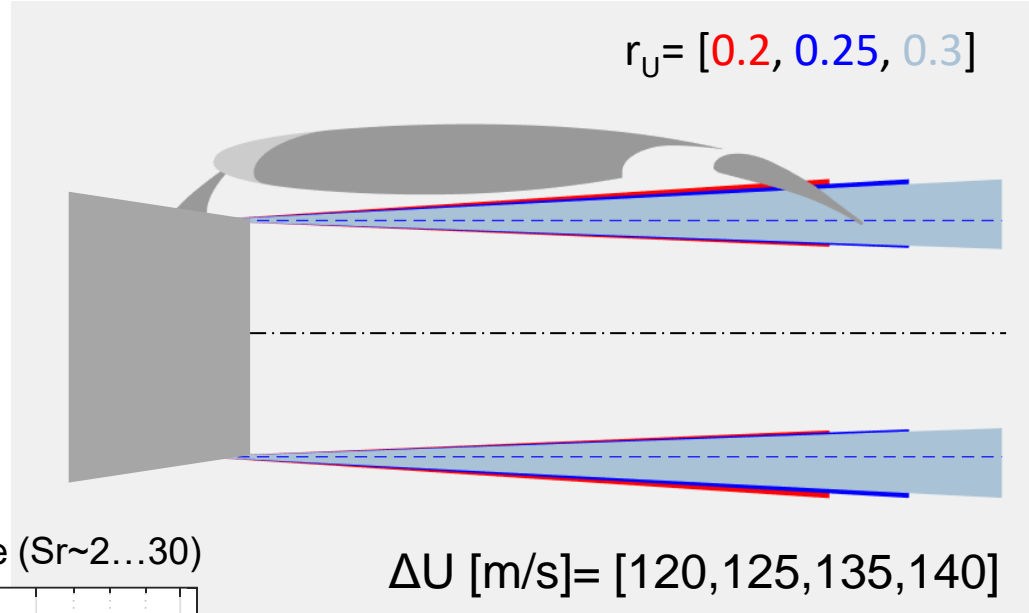
- Velocity ratio $r_U = \frac{U_\infty}{U_{jet}}$
- Thrust $F := \rho_j A_j \cdot U_j (U_j - U_\infty)$
- Thrust „velocity“ $U_{th} := \sqrt{\frac{F}{\rho_j A_j}} = \sqrt{U_j (U_j - U_\infty)} = U_j \sqrt{1 - r_U}$
- S/L Difference velocity $\Delta U := U_j - U_\infty = U_j (1 - r_U)$
- Thrust- ΔU - relationship $U_j = \frac{U_{th}}{\sqrt{1 - r_U}} = \frac{\Delta U}{(1 - r_U)}$

Assumptions inlet-to-outlet
 no mass flow loss
 no static pressure difference

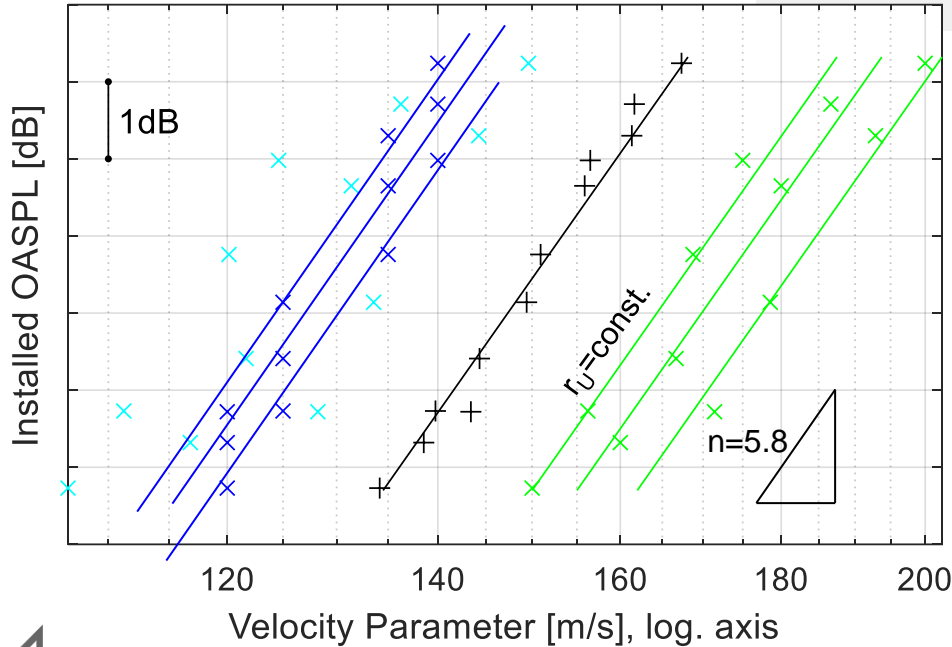


Motivation

- Self-similar velocity profiles $r_U := U_f / U_j$



Velocity Scaling of high-frequent JFI-noise (Sr~2...30)



Velocity Parameter	
+	U_{thrust}
x	ΔU
x	U_{jet}
x	U_{mean}

account this as preliminary



Hypothesis 1: Assume thrust is scaling parameter

- thrust scales with $n=5\dots 6$, same-thrust spectra collapse (no matter which ΔU) (or higher, $n=6..7$? Mahdi Azarpeyvand: “An overview of jet noise research at the University of Bristol”, DJINN Conference)
- What is the expected scaling difference for thrust (while keeping ΔU const!)?

$$U_{th}(\Delta U) = \sqrt{1 - r_U} \Delta U$$

$$\Delta SPL_{Uth} = n \cdot 10 \cdot \lg \left(\frac{\sqrt{1 - r_{U1}}}{\sqrt{1 - r_{U2}}} \right) = 55 \lg \left(\frac{\sqrt{1 - r_{U1}}}{\sqrt{1 - r_{U2}}} \right)$$

- AWB minimum $r_{U1}=0.04\dots 0.05$ (quasi-static jet, closed-circuit wind tunnel)
- for max use $r_{U2}=0.2$ (good limit, high jet speed possible) $\Delta SPL=2\text{dB}$
- or maybe $r_{U2}=0.3$ (wind tunnel limit 60 m/s) $\Delta SPL=3.6\text{dB}$



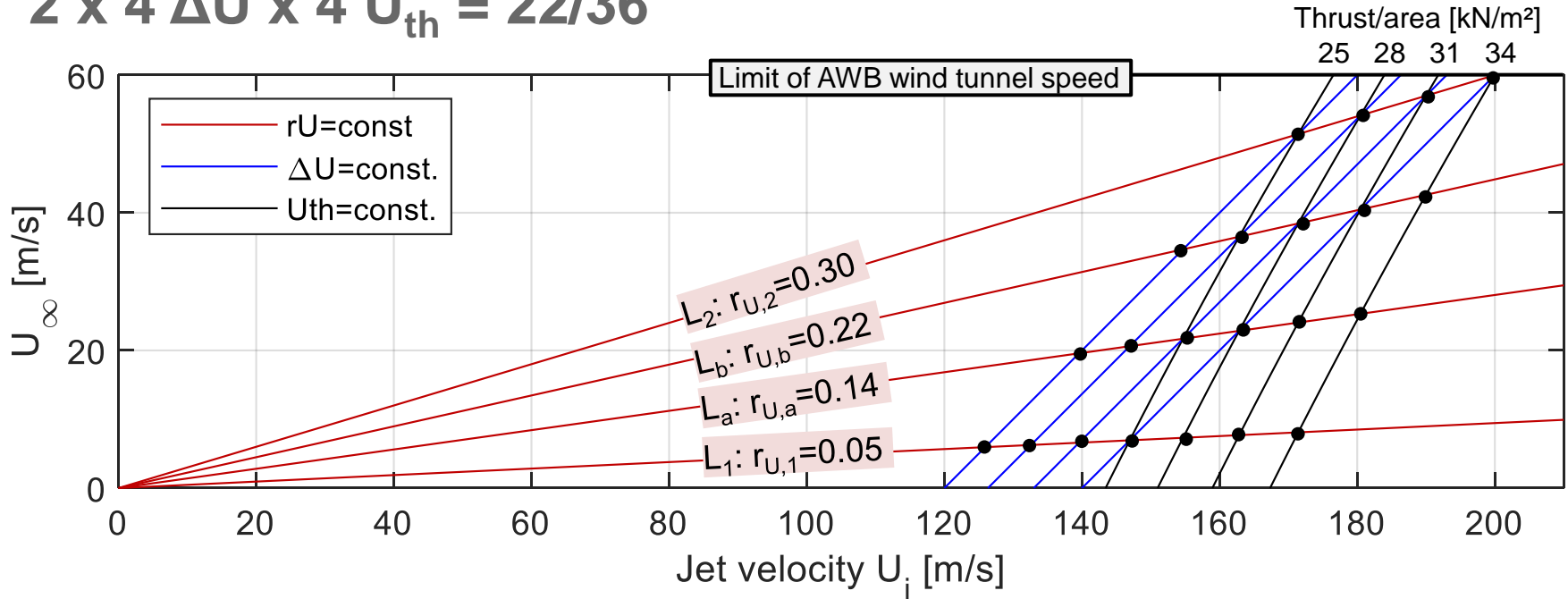
Hypothesis 2: Assume ΔU is scaling parameter

- ΔU scales with $n=5\dots 6$, same difference velocities collapse (no matter which thrust is used)
- Same scaling difference



Definition of test operations

$2 \times 4 \Delta U \times 4 U_{th} = 22/36$

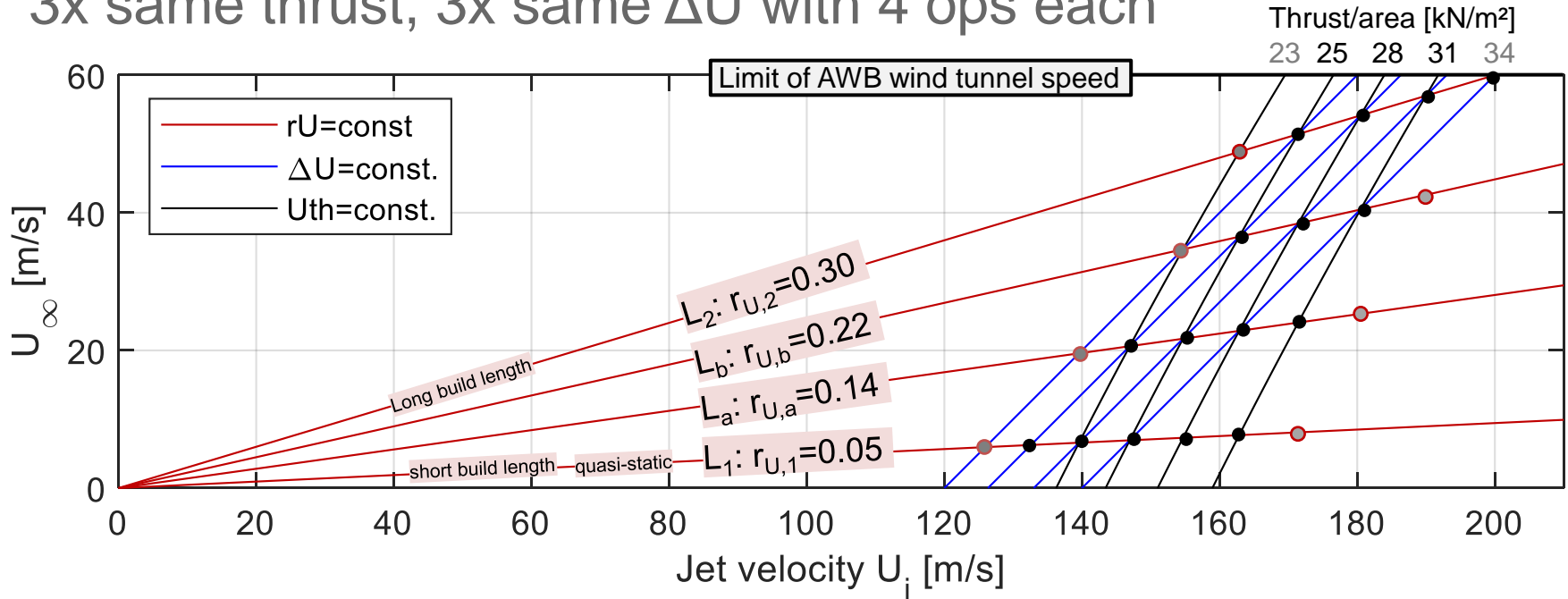


- For generation of general grid, can be optimized

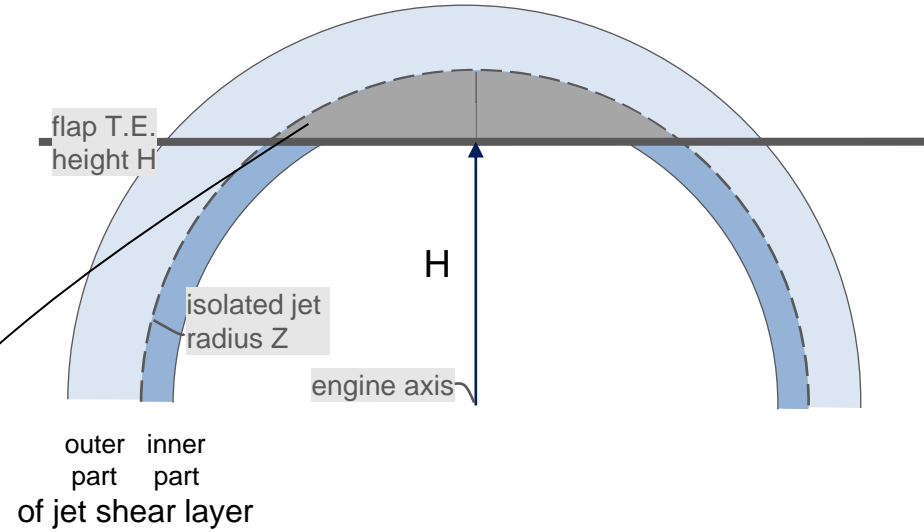
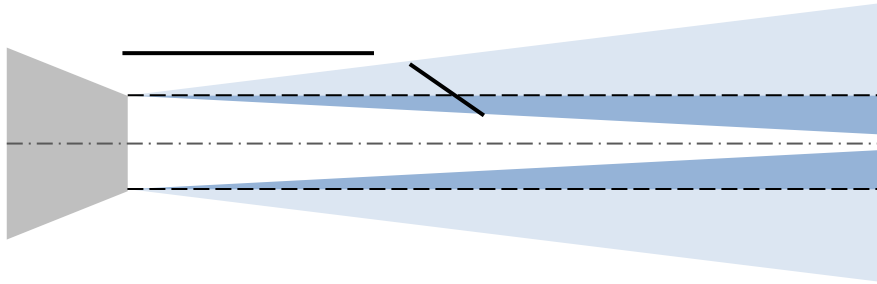


Definition of test operations, optimized

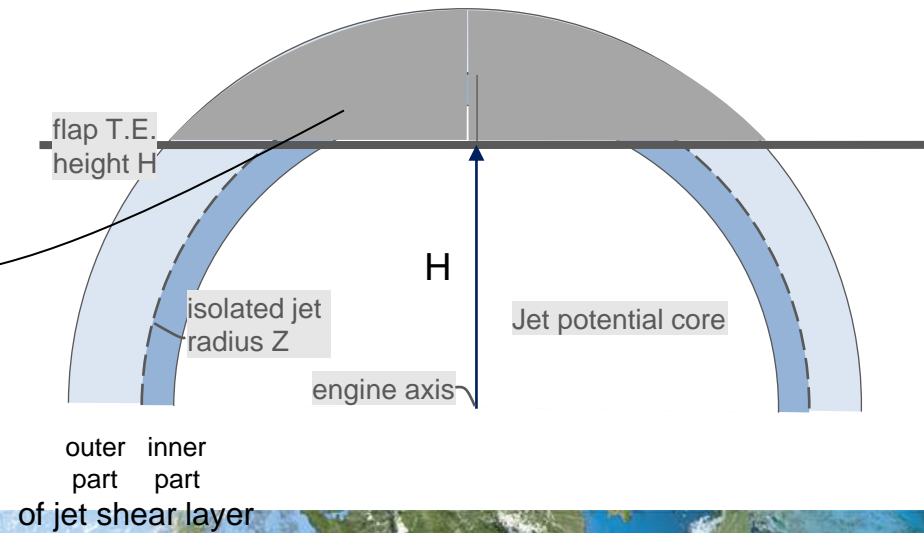
3x same thrust, 3x same ΔU with 4 ops each



Dependence on (theoretical) jet impingement areas



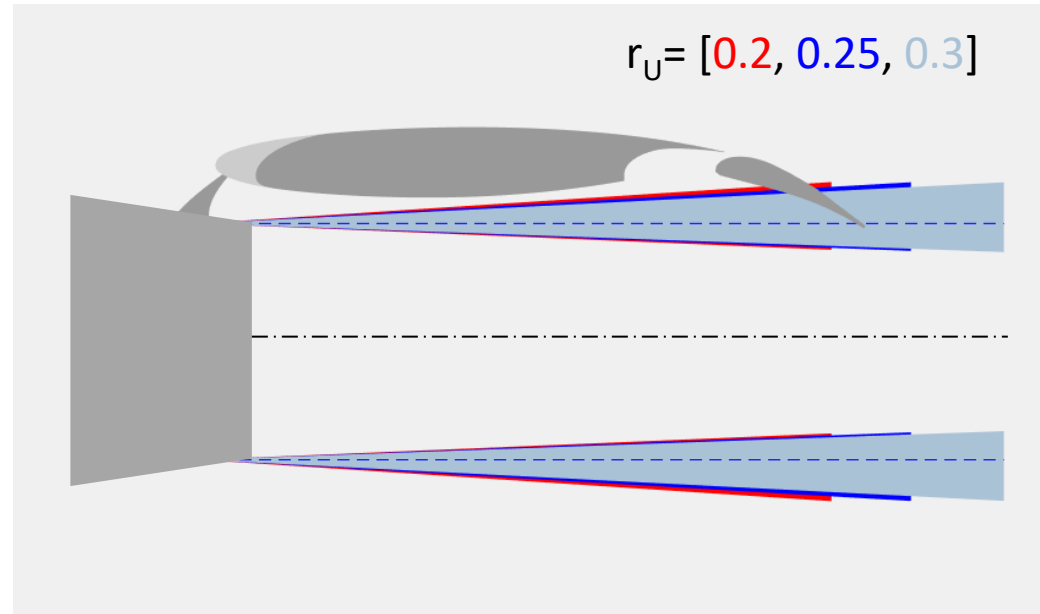
(A) Only mixed jet



(B) Full theoretical jet width



Calculation of length adjustment



$$\delta_\omega \propto (L - x_0) \cdot \frac{1 - r_U}{1 + r_U}$$

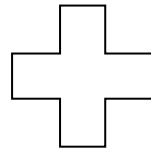
$$\frac{(L_2 - x_0)}{(L_1 - x_0)} = \frac{1 - r_{U1}}{1 + r_{U1}} \cdot \frac{1 + r_{U2}}{1 - r_{U2}} = 1.68$$



Results

Typical campaign

1 build/
16 Ops isolated



12 builds / $29 \times 3 = 87$ press. Ops installed + 87 BGN

	L1	La	Lb	L2
H1	5	4	16	4
H2	5	4	16	4
H3	5	4	16	4

- The derived experiment is tailored to force a definite result wrt. thrust or S/L velocity.
- Maybe there is no simple explanation, idea: downwash-velocities

Questions?



Acknowledgements



The EU DJINN (Decrease Jet Installation Noise) project receives funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 861438. DJINN is a collaborative effort between CFD-Berlin (coordinator), Airbus SAS, Dassault Aviation, Safran Aircraft Engines, Rolls-Royce Deutschland, ONERA, DLR, University of Southampton, CERFACS, Imperial College London, von Karman Institute, CNRS, and Queen Mary University of London.

