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Explicit phase diagram for a one-dimensional blister model

G. CHMAYCEM^{b,*}, M. JAZAR^{*} AND R. MONNEAU^b

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Abstract

We consider a thin film bonded to a substrate. The film acquires a residual stress upon cooling because of the mismatch of thermal expansion coefficient between the film and the substrate. The film tends to lift off the substrate when this residual stress is compressive and large enough. In this work, this phenomenon is described by a simplified one-dimensional variational model. We minimize an energy and study its global minimizers. Our problem depends on three parameters: the length of the film, its elasticity and a thermal parameter. Our main result consists in describing a phase diagram depending on those parameters in order to identify three types of global minimizers: a blister, a fully delaminated blister and a trivial solution (without any delamination). Moreover, we prove various qualitative results on the shape of the blisters and identify the smallest blister which may appear.

Keywords: blister, thin film, fracture, delamination, buckling, Föppel-von Kármán, variational model, classification of global minimizers, phase diagram, nonlinear elasticity, obstacle problem, non interpenetration condition.

1 Introduction

1.1 Physical motivation

The thin films are often obtained by evaporation on a substrate. When the coefficient of thermal expansion of the substrate is higher than that of the film, cooling to ambient temperature leads to a compressive residual stress in the film. If compression is sufficient, the film tends to buckle, separating from the substrate. It is said that the film delaminates (see Figure 1).

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An oversimplified one dimensional model which describes this phenomena is given by the minimization of the following energy (of Föppel-von Kármán type)

$$E(\zeta_1, \zeta_2) := \int_{\Omega} \gamma \mathbf{1}_{\{\zeta_2 > 0\}} + 4\alpha \left(\zeta_1' + \frac{1}{2}(\zeta_2')^2 \right)^2 + \frac{4\alpha}{3} \zeta_2''^2 - 2\bar{\theta} \zeta_2''^2 \quad \text{with} \quad \gamma = 1, \quad (1.1)$$

with

$$\Omega = \mathbb{R}/\bar{L}\mathbb{Z} = [-\bar{L}/2, \bar{L}/2]_{per},$$

and where \bar{L} is the length of the film, $\alpha > 0$ represents its elasticity coefficient and $\bar{\theta} > 0$ is the thermal parameter. Here the parameter γ measures the cost of delamination and is similar to the formulation of fracture with Griffith criterion (see for instance Francfort, Marigo [6], Griffith [7], Larsen [9]). For $\gamma = 0$, this model was formally derived from 3D elasticity in the asymptotics of thin films in [5] by El Doussouki and the last author, see also [10]. For simplicity, we normalize this parameter γ to be equal to 1 in the whole paper (this normalization can always be absorbed in a redefinition of E , α and $\bar{\theta}$ by rescaling). The quantity $\zeta_2(x)$ denotes the vertical displacement and is assumed to be nonnegative (the film is above the substrate) and $\zeta_1(x)$ is the horizontal one with $x \in \Omega$, where the periodicity is assumed to simplify the analysis (see also Remark 1.4 for other boundary conditions describing a clamped film). We introduce the following space

$$Y := H^1(\Omega) \times \{\zeta_2 \in H^2(\Omega), \zeta_2 \geq 0\}. \quad (1.2)$$

The solution of our model is given by solving the following problem

$$\min_{(\zeta_1, \zeta_2) \in Y} E(\zeta_1, \zeta_2). \quad (1.3)$$

Definition 1.1 (*Blister*)

We call a "blister" any global minimizer of the energy E defined in (1.1) which is non trivial i.e. $(\zeta_1, \zeta_2) \neq (0, 0)$.

This paper elaborates the delamination of compressed thin films. Under appropriate conditions, blisters may appear. We give a complete description of global minimizers in terms of the parameters of the problem.

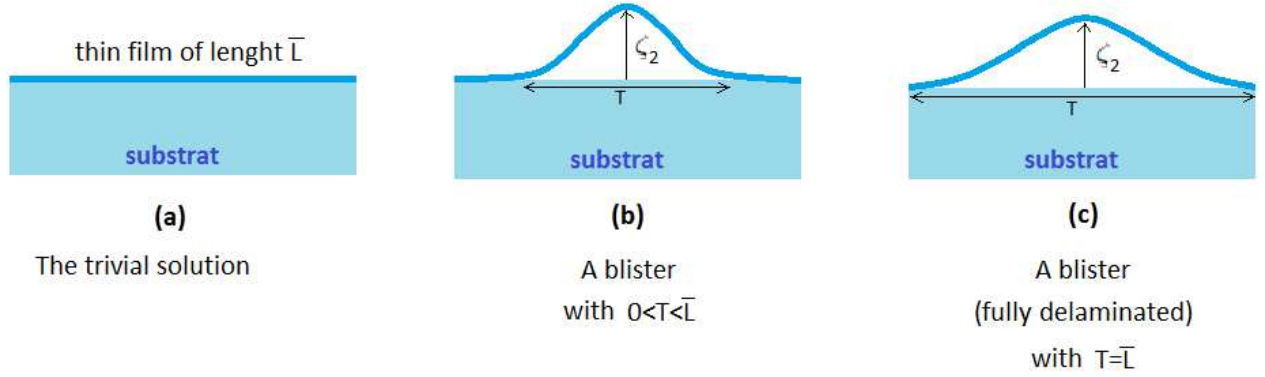


Figure 1: Different types of solutions of problem (1.3)

1.2 Main results

Theorem 1.2 (*Existence of global minimizers*)

There exists a (global) minimizer $\zeta = (\zeta_1, \zeta_2) \in Y$ of the energy E introduced in (1.1).

In order to study minimizers of E , it is useful to consider the following auxiliary minimizing problem

$$\min_{X \in \mathcal{D}} f(X), \quad (1.4)$$

where

$$f(X) := \begin{cases} (\theta - X)^{-1/2} - LX^2 & \text{if } 0 < X < \theta; \\ 0 & \text{if } X = 0; \end{cases} \quad (1.5)$$

with rescaled versions of the thermal parameter $\bar{\theta}$ and of the length \bar{L}

$$\theta := \frac{\bar{\theta}}{\alpha}, \quad \text{and} \quad L := \frac{1}{2\pi} \sqrt{\frac{3}{2}} \alpha \bar{L}, \quad (1.6)$$

where $\alpha > 0$ is from now on fixed in the model and \mathcal{D} is the interval given by

$$\mathcal{D} := \left[0, \tilde{\theta}^+\right], \quad \text{with} \quad \tilde{\theta}^+ = \max \left\{ \tilde{\theta}, 0 \right\} \quad \text{and} \quad \tilde{\theta} := \theta - \frac{\alpha^2}{L^2}. \quad (1.7)$$

Indeed the following theorem shows that the minimizing problem (1.3) is equivalent to the study of the auxiliary problem (1.4).

Theorem 1.3 (*Description of global minimizers of E*)

i) (*Implication*)

For any global minimizer $\zeta = (\zeta_1, \zeta_2)$ of the energy E , there exists at least a minimizer $K \in \mathcal{D}$ of problem (1.4) such that the following holds: there exists $T \in [0, \bar{L}]$ such that (up to

addition of constants and translation of (ζ_1, ζ_2) , this minimizer ζ can be written as follows

$$\left\{ \begin{array}{l} \zeta_1(x) = \begin{cases} \frac{K}{2} \left(x + \frac{\bar{L}}{2} \right) & \text{in } [-\bar{L}/2, -T/2]; \\ \frac{K\bar{L}}{8\pi} \sin(2\beta x) + \frac{K}{2} \left(1 - \frac{\bar{L}}{T} \right) x & \text{in } (-T/2, T/2); \\ \frac{K}{2} \left(x - \frac{\bar{L}}{2} \right) & \text{in } [T/2, \bar{L}/2], \end{cases} \\ \zeta_2(x) = \begin{cases} A(\cos(\beta x) + 1) & \text{in } [-T/2, T/2]; \\ 0 & \text{elsewhere,} \end{cases} \end{array} \right. \quad (1.8)$$

where β , A and T are given by

$$\beta := \sqrt{\frac{3(\bar{\theta} - \alpha K)}{2\alpha}}; \quad A := \sqrt{\frac{K\bar{L}}{\pi\beta}}; \quad T := \begin{cases} \frac{2\pi}{\beta} & \text{if } K > 0; \\ 0 & \text{if } K = 0. \end{cases} \quad (1.9)$$

More generally, for any $K \in \mathcal{D}$ and any functions (ζ_1, ζ_2) given in (1.8)-(1.9), we have

$$E(\zeta_1, \zeta_2) = 2\pi\sqrt{\frac{2}{3}}f(K), \quad (1.10)$$

and for $K \in \mathcal{D}$

$$\left\{ \begin{array}{l} T = \bar{L} \Leftrightarrow K = \tilde{\theta}; \\ \text{and} \\ T < \bar{L} \Leftrightarrow K < \tilde{\theta}. \end{array} \right. \quad (1.11)$$

ii) (Reciprocal)

If $K \in \mathcal{D}$ is a minimizer of problem (1.4), then the function $\zeta = (\zeta_1, \zeta_2)$ given in (1.8)-(1.9) is a global minimizer of E on Y .

Notice that $\bar{\theta} - \alpha K > 0$ because $K \in \mathcal{D}$. Moreover, when $K = 0$ then $A = T = 0$ which implies that $\zeta_1 = \zeta_2 = 0$. Thus with our definition, T can be interpreted as the length of the support of ζ_2 . Theorem 1.3 identifies three types of global minimizers. For $K = 0$, we get the trivial solution (Figure 1, (a)). For $K \in (0, \tilde{\theta})$, then $0 < T < \bar{L}$ and we get the blister solution (Figure 1, (b)). Finally, for $K = \tilde{\theta}$, then $T = \bar{L}$ and we get the fully delaminated blister (Figure 1, (c)). We still use the name "blister" for the mathematical solution even if physically the film is completely delaminated. Note that our blister solution (Figure 1, (b)) can be roughly speaking seen as the cross section of blisters with the shape of fingers (see for instance experiments in Figure 8.1 in [12]).

Remark 1.4 (*Clamped boundary conditions*)

Recall that the periodic boundary conditions are included in the set Y defined in (1.2). We now introduce another set of functions satisfying clamped boundary conditions

$$\tilde{Y} := H_0^1(-\bar{L}/2, \bar{L}/2) \times \{\zeta_2 \in H_0^2(-\bar{L}/2, \bar{L}/2), \zeta_2 \geq 0\}.$$

Then

$$\inf_{\tilde{Y}} E \geq \inf_Y E,$$

because any $y \in \tilde{Y}$ can be seen as an element of Y when it is extended by periodicity. Moreover, any global minimizer of E on Y is given (up to addition of constants and translation of (ζ_1, ζ_2)) by the solution written in (1.8) which satisfies $(\zeta_1, \zeta_2) \in \tilde{Y}$. Therefore,

$$\inf_{\tilde{Y}} E = \inf_Y E,$$

and then in this paper we also solved the minimization problem of E on \tilde{Y} .

To classify the solutions obtained in Theorem 1.3, we have to define the following functions in order to introduce some domains D_0 , D_1 and D_2 of parameters (θ, L) . Figure 2 describes those domains (still for arbitrary fixed value α). We will show that trivial solutions correspond to D_0 , blister solutions to D_1 and fully delaminated blister to D_2 . For this purpose, we introduce

$$\left\{ \begin{array}{l} \theta^* := \frac{5}{4}\alpha^{-1/2}; \end{array} \right. \quad (1.12)$$

$$\left\{ \begin{array}{l} L_{01}(\theta) := \frac{5^{5/2}}{16}\theta^{-5/2} \end{array} \right. \quad \text{for } 0 < \theta \leq \theta^*; \quad (1.13)$$

$$\left\{ \begin{array}{l} L_{02}(\theta) := \frac{\alpha^{5/4}}{(\sqrt{\alpha}\theta - 1)^{1/2}} \end{array} \right. \quad \text{for } \theta \geq \theta^* > \alpha^{-1/2}; \quad (1.14)$$

$$\left\{ \begin{array}{l} L_{12}(\theta) := \left(2\alpha^3\theta + 2\alpha^2\sqrt{\alpha(\alpha\theta^2 - 1)}\right)^{1/2} \end{array} \right. \quad \text{for } \theta \geq \theta^* > \alpha^{-1/2}. \quad (1.15)$$

Definition 1.5 (*Domains D_0, D_1 and D_2*)

Let us now introduce the following sets of $(\theta, L) \in (0, +\infty)^2$:

$$\left\{ \begin{array}{l} D_0 := \left\{ \begin{array}{l} (\theta, L), \quad L < L_{01}(\theta) \quad \text{if } 0 < \theta \leq \theta^* \\ \quad \quad \quad L < L_{02}(\theta) \quad \text{if } \theta > \theta^* \end{array} \right\}; \end{array} \right. \quad (1.16)$$

$$\left\{ \begin{array}{l} D_1 := \left\{ \begin{array}{l} (\theta, L), \quad L > L_{01}(\theta) \quad \text{if } 0 < \theta \leq \theta^* \\ \quad \quad \quad L > L_{12}(\theta) \quad \text{if } \theta > \theta^* \end{array} \right\}; \end{array} \right. \quad (1.17)$$

$$\left\{ \begin{array}{l} D_2 := \{(\theta, L), \theta > \theta^* \text{ and } L_{02}(\theta) < L < L_{12}(\theta)\}. \end{array} \right. \quad (1.18)$$

We denote by

$$\left\{ \begin{array}{l} \Gamma_{01} := \{(\theta, L), 0 < \theta < \theta^* \text{ and } L = L_{01}(\theta)\}; \\ \Gamma_{02} := \{(\theta, L), \theta > \theta^* \text{ and } L = L_{02}(\theta)\}; \\ \Gamma_{12} := \{(\theta, L), \theta > \theta^* \text{ and } L = L_{12}(\theta)\}; \\ P = (\theta^*, L_{01}(\theta^*)). \end{array} \right. \quad (1.19)$$

$$\Gamma_{02} := \{(\theta, L), \theta > \theta^* \text{ and } L = L_{02}(\theta)\}; \quad (1.20)$$

$$\Gamma_{12} := \{(\theta, L), \theta > \theta^* \text{ and } L = L_{12}(\theta)\}; \quad (1.21)$$

$$P = (\theta^*, L_{01}(\theta^*)). \quad (1.22)$$

Remark 1.6 (*A partition of the domains*)

We have the following disjoint decomposition

$$(0, +\infty)^2 = D_0 \cup D_1 \cup D_2 \cup \Gamma_{21} \cup \Gamma_{01} \cup \Gamma_{02} \cup \{P\}.$$

Moreover, the following properties hold true

$$\left\{ \begin{array}{ll} L'_{12}(\theta) > 0 \text{ and } L'_{02}(\theta) < 0, & \text{for } \theta > \theta^*; \\ L'_{01}(\theta) < 0, & \text{for } 0 < \theta < \theta^*; \\ L^* := L_{12}(\theta^*) = L_{01}(\theta^*) = L_{02}(\theta^*); \end{array} \right. \quad (1.23)$$

where θ^* is defined in (1.12).

The proof of Remark 1.6 is done by a simple computation.

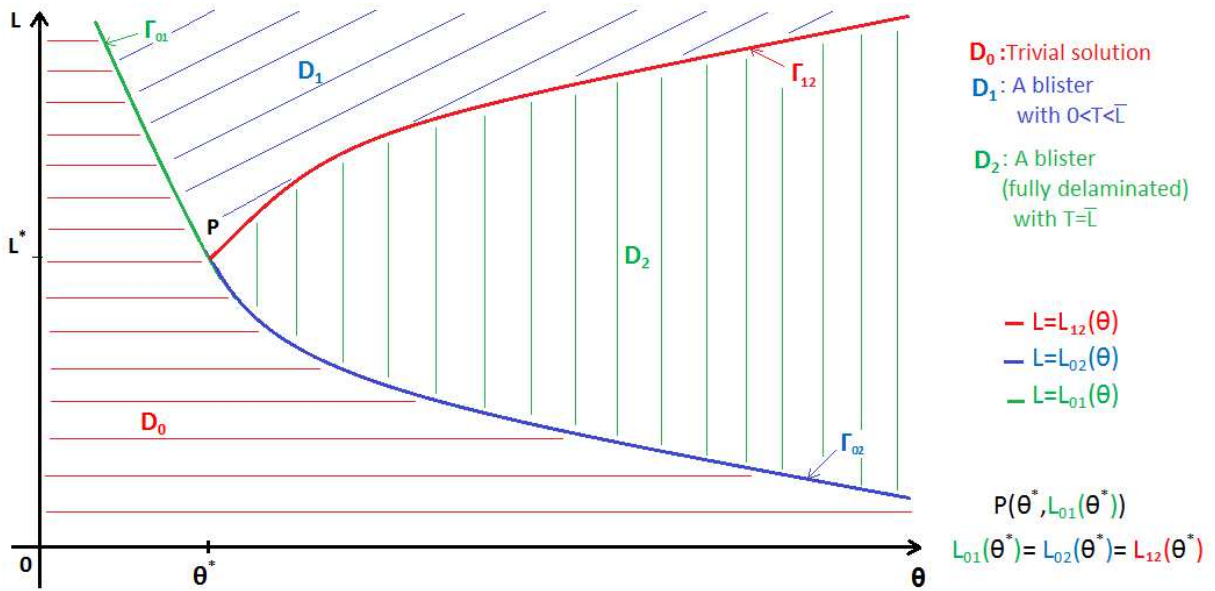


Figure 2: Schematic phase diagram for parameters (θ, L)

Theorem 1.7 (Classification of global minimizers of E)

i) For $(\theta, L) \in D_0$, the unique global minimizer of the energy E introduced in (1.1) is the trivial solution $(\zeta_1, \zeta_2) = (0, 0)$.

ii) For $(\theta, L) \in D_1 \cup D_2 \cup \Gamma_{12}$, there is a unique blister $\zeta = (\zeta_1, \zeta_2) \in Y$ (see Definition 1.1) minimizing the energy E . Moreover, the component ζ_2 has a support of length T which is defined in (1.9) and

$$\begin{cases} T < \bar{L} & \text{if } (\theta, L) \in D_1; \\ T = \bar{L} & \text{if } (\theta, L) \in D_2 \cup \Gamma_{12}. \end{cases} \quad (1.24)$$

iii) For $(\theta, L) \in \Gamma_{01} \cup \Gamma_{02} \cup \{P\}$, the energy E has exactly two global minimizers: the trivial solution $\zeta = (\zeta_1, \zeta_2) = (0, 0)$ and a blister $\zeta = (\zeta_1, \zeta_2) \in Y$ given in (1.8) with

$$\begin{cases} T < \bar{L} & \text{if } (\theta, L) \in \Gamma_{01}; \\ T = \bar{L} & \text{if } (\theta, L) \in \Gamma_{02} \cup \{P\}. \end{cases} \quad (1.25)$$

Proposition 1.8 (Blister's properties in $D_1 \cup D_2 \cup \Gamma_{12}$)

For $(\theta, L) \in D_1 \cup D_2 \cup \Gamma_{12}$, there exists a unique $K \in \mathcal{D}$ (depending on (θ, L)) minimizing problem (1.4). Recalling (1.6), we consider T and A given in (1.9).

i) Monotonicity

First, T and A are continuous in (θ, L) on $D_1 \cup D_2 \cup \Gamma_{12}$ and satisfy the following properties

$$\frac{\partial T}{\partial \theta}, \frac{\partial T}{\partial L} \geq 0 \quad \text{and} \quad \frac{\partial A}{\partial \theta}, \frac{\partial A}{\partial L} \geq 0.$$

In particular,

$$T = \bar{L} \quad \text{on} \quad D_2 \cup \Gamma_{12}.$$

ii) "Smallest" blister solutions

We have

$$\inf_{(\theta, L) \in D_1} T = T^* := 4\pi \sqrt{\frac{2}{3}} \alpha^{1/4}, \quad (1.26)$$

and

$$\inf_{(\theta, L) \in D_1} A = A^* := \frac{4}{\sqrt{3}}. \quad (1.27)$$

Remark 1.9 (Prediction for the smallest blisters; not fully delaminated case)

For any $(\theta, L) \in D_1$, we have a unique blister $(\zeta_1, \zeta_2) \in Y$ minimizing the energy E . According to Proposition 1.8, the second component ζ_2 has a support of length $T > T^*$ with $T < \bar{L}$. This shows that T^* can be interpreted as the infimum of the width of blisters whose length support is strictly less than the length of the film. Similarly, we can also interpret the amplitude A^* as the minimal amplitude of the blisters.

Remark 1.10 (Relatively small blisters for large L)

For $(\theta, L) \in D_1$, it is possible to check, as L tends to infinity, that T and A have a behavior like $L^{1/3}$ and $L^{2/3}$ respectively. In particular, for θ fixed and for large enough films, the size of the blisters is much smaller than the size of the film.

Remark 1.11 (*Phase diagram for local minimizers*)

For local minimizers (with small perturbation of the support with $T < \bar{L}$), we expect to have similar phase diagram for p blisters (only local minimizers) of the same width T with now \bar{L} replaced by \bar{L}/p , L replaced by L/p and $T \leq \bar{L}/p$ (see Remark 2.2).

1.3 Brief review of the literature

Buckling delamination blisters have commonly been studied for a long time. In [8], Gioia and Ortiz give an overview of experiments, propose and study mathematically variational models of blisters, among other things motivated by the description of telephone-cord morphology. See also [1] where such a telephone-cord instability is studied.

Experimentally and theoretically in [11], the authors study blisters which have the one dimensional symmetry. Their results seem coherent with ours, even if the problem and the modeling are not exactly the same. We also refer the reader to [3] and the references therein for recent developments on the analysis and modeling of blisters. In this nice work, the authors consider a Föppel-von Kármán model for the film with a special bonding energy with the substrate. For this variational model, they study several regimes for the energy. This is also interesting to mention the work [2] where the authors derive rigorously a variational similar model of thin films bonded to a substrate when the thickness of the film goes to zero. Their limit energy contains in particular a bonding term which is similar to our term with γ in the energy (1.1).

1.4 Organization of the paper

The organization of the paper is as follows. In Section 2, we prove Theorems 1.2 and 1.3 i) on the existence and the description of global minimizers. Section 3 is dedicated to the detailed classification of global minimizers and their qualitative properties. There we prove Theorem 1.7, Theorem 1.3 ii) and Proposition 1.8. To this end, we divided this section into three parts. In the first one, we present some results which will be useful to prove Theorem 1.7. The second subsection is devoted to prove Theorem 1.7. We end up Section 3 by the proofs of Theorem 1.3 ii) and Proposition 1.8.

2 Proofs of Theorems 1.2 and 1.3 i)

This section is divided into two parts: the first one is devoted to prove Theorem 1.2 and the second is dedicated to the proof of Theorem 1.3 i).

2.1 Existence of global minimizers**Proof of Theorem 1.2**

The proof of Theorem 1.2 is very classical. By considering a minimizing sequence $\zeta^k = (\zeta_1^k, \zeta_2^k) \in Y$ such that $E(\zeta^k) \xrightarrow{k \rightarrow \infty} I = \inf_{\zeta \in Y} E(\zeta)$, and using Young's inequality, we get

$$2\bar{\theta} \int_{\Omega} (\zeta_2^{k'})^2 = 4\bar{\theta} \int_{\Omega} \left(\zeta_1^{k'} + \frac{1}{2}(\zeta_2^{k'})^2 \right) \leq \frac{2\bar{\theta}^2 \bar{L}}{\alpha} + 2\alpha \int_{\Omega} \left(\zeta_1^{k'} + \frac{1}{2}(\zeta_2^{k'})^2 \right)^2. \quad (2.1)$$

Thus we can bound the energy $E(\zeta^k)$. We will skip the steps of the proof since the result can be obtained in a classical way (see also [10] and [4]). □

2.2 Description of global minimizers of E

We first start this subsection by the following lemma which will be used to prove Theorem 1.3 i).

Lemma 2.1 (*Classification of solutions ζ_2*)

Let $\zeta_2 \in \{f \in H^2(\Omega), f \geq 0\}$. Consider the following ordinary differential equation

$$\begin{cases} \zeta_2^{(4)} + \frac{3(\bar{\theta} - \alpha K)}{2\alpha} \zeta_2'' = 0 & \text{on } \omega_0 = (x_0, y_0); \\ \zeta_2 > 0 & \text{on } \omega_0; \\ \zeta_2 = 0 & \text{on } \partial\omega_0; \end{cases} \quad (2.2)$$

where $x_0 < y_0$.

If $\bar{\theta} - \alpha K \leq 0$, then there is no solution of (2.2).

If $\bar{\theta} - \alpha K > 0$, then up to translate ζ_2 , we have

$$\begin{cases} x_0 = -\frac{T}{2} \quad \text{and} \quad y_0 = \frac{T}{2}; \\ \zeta_2(x) = A_0(\cos(\beta x) + 1) & \text{on } \omega_0 = (x_0, y_0); \\ \beta = \sqrt{\frac{3(\bar{\theta} - \alpha K)}{2\alpha}} = \frac{2\pi}{T}; \end{cases} \quad (2.3)$$

where $A_0 > 0$ is a constant.

Proof of Lemma 2.1

Since $\zeta_2 \in H^2(\mathbb{R}/\bar{L}\mathbb{Z})$, then $\zeta_2 \in C^1(\mathbb{R}/\bar{L}\mathbb{Z})$. Moreover $\zeta_2 \geq 0$, which implies that

$$\zeta_2(x_0) = \zeta_2'(x_0) = 0 = \zeta_2(y_0) = \zeta_2'(y_0). \quad (2.4)$$

We can write ζ_2 as $\zeta_2(x) = \zeta_2^S(x) + \zeta_2^A(x)$ on $\omega_0 = (x_0, y_0)$, where ζ_2^S is the symmetric part of ζ_2 and ζ_2^A is its anti-symmetric part. In particular ζ_2^S verifies the following conditions

$$\zeta_2^S > 0 \quad \text{on } \omega_0 \quad \text{and} \quad \zeta_2^S = (\zeta_2^S)' = 0 \quad \text{on } \partial\omega_0. \quad (2.5)$$

We skip the details of the proof which is a routine exercise. □

Proof of Theorem 1.3 i)

Let $(\zeta_1, \zeta_2) \in Y$ be a minimizer of E .

Step 1: Differentiating E with respect to ζ_1

Differentiating E with respect to ζ_1 leads to the following Euler-Lagrange equation:

$$\left(\zeta_1' + \frac{1}{2}(\zeta_2')^2 \right)' = 0 \quad \text{on } \Omega,$$

i.e.

$$\zeta_1' + \frac{1}{2}(\zeta_2')^2 = \frac{K}{2} \quad \text{where} \quad K = \frac{1}{L} \int_{\Omega} (\zeta_2')^2 \geq 0. \quad (2.6)$$

Therefore the total energy becomes

$$E(\zeta_1, \zeta_2) = \bar{E}(\zeta_2) := \int_{\Omega} \mathbf{1}_{\{\zeta_2 > 0\}} + \frac{\alpha}{L} \left(\int_{\Omega} (\zeta_2')^2 \right)^2 + \frac{4\alpha}{3} \int_{\Omega} (\zeta_2'')^2 - 2\bar{\theta} \int_{\Omega} (\zeta_2')^2.$$

If $K = 0$, then $\zeta_2 \equiv 0$ and thus $\zeta_1 \equiv \text{const}$ on Ω , and up to subtract a constant to ζ_1 , we can assume that $\zeta_1 \equiv 0$.

If $K > 0$, then $\zeta_2 \not\equiv 0$ and we proceed as follows.

Step 2: Differentiating \bar{E} with respect to ζ_2

Differentiating \bar{E} with respect to ζ_2 , yields the following Euler-Lagrange equation

$$\zeta_2^{(4)} + \frac{3(\bar{\theta} - \alpha K)}{2\alpha} \zeta_2'' = 0 \quad \text{on } \{\zeta_2 > 0\}.$$

Up to add a constant to ζ_2 , we can assume that $\inf_{\Omega} \zeta_2 = 0$. Therefore there exists $x_0 \in \Omega$ such that $\zeta_2(x_0) = 0$. Up to translation, we choose $x_0 = -\bar{L}/2$. Then, we deduce that

$$\{\zeta_2 > 0\} = \bigcup_{i \in J} \omega_i, \quad \text{for } \omega_i = (x_i, y_i),$$

where J is a set at most countable and such that $\omega_i \cap \omega_j = \emptyset$ for $i \neq j$. Applying Lemma 2.1 to each ω_i , we conclude that $\bar{\theta} - \alpha K > 0$,

$$y_i - x_i = T = 2\pi \sqrt{\frac{2\alpha}{3(\bar{\theta} - \alpha K)}}$$

and up to translation, the solution ζ_2 is given by (2.3) on each ω_i with the amplitude A_0 replaced by A_i . Now, we deduce that $\text{card}(J) = p < +\infty$ with $p \geq 1$ satisfying $pT \leq \bar{L}$. Since the ω_i are disjoint, we get

$$K\bar{L} = \int_{\Omega} (\zeta_2')^2 = \frac{\beta^2 T}{2} \sum_{i=1}^p A_i^2. \quad (2.7)$$

Hence using (2.3), we get

$$\bar{E}(\zeta_2) = \bar{\bar{E}}(K, p) := 2p\pi \sqrt{\frac{2\alpha}{3(\bar{\theta} - \alpha K)}} - \alpha K^2 \bar{L} \quad (2.8)$$

with the conditions

$$1 \leq p \leq \frac{\bar{L}}{T} \quad \text{and} \quad T = \frac{2\pi}{\beta}. \quad (2.9)$$

Then we minimize the energy with respect to p and we get the results. □

Remark 2.2 (Local minimizers)

For local minimizers of E , we may have p blisters (all separated by any positive distance) with the same width T and with amplitude A_i satisfying (2.7). For $p \geq 1$ given, we can also optimize K in $\overline{E}(K, p)$ which should correspond to local minimizers of E (restricted to small perturbations of the support with $T < \overline{L}$) with \overline{L} replaced by \overline{L}/p , L replaced by L/p and $T \leq \overline{L}/p$.

3 Proofs of Theorem 1.7, Theorem 1.3 ii) and Proposition 1.8

Our aim is to prove Theorem 1.7, Theorem 1.3 ii) and Proposition 1.8. For this purpose, this section is divided into several parts. In the first one, we give some tools which will be useful to prove Theorem 1.7. The second subsection is dedicated to the proof of Theorem 1.7. Finally, we prove Theorem 1.3 ii) and Proposition 1.8 in the last subsection.

3.1 Preliminaries

First, we are interested in the following auxiliary minimization problem

$$\min_{X \in \mathcal{D}} f(X) = f(K), \quad (3.1)$$

where f and \mathcal{D} are defined respectively in (1.5) and (1.7). Recall that for $(\theta, L) \in (0, \infty)^2$, we have that $\mathcal{D} \subsetneq [0, \theta)$. In order to determine the minimum of the function f on $[0, \theta)$, we have to introduce the quantity

$$L_d = L_d(\theta) := \frac{25}{24} \sqrt{\frac{5}{3}} \theta^{-5/2}, \quad \text{for } \theta > 0. \quad (3.2)$$

Proposition 3.1 (Minimizing f on $[0, \theta)$ and its consequences)

We consider f defined in (1.5) and L_d introduced in (3.2).

i) If $L \leq L_d$, then f is increasing on $(0, \theta)$ and

$$\operatorname{argmin}_{\mathcal{D}} f = \{0\}.$$

In this case, we set artificially $X_m := 2\theta/5$.

ii) If $L > L_d$, then there exist X_M and X_m such that $0 < X_M < 2\theta/5 < X_m < \theta$ and

$$\begin{cases} f' \geq 0 & \text{on } (0, X_M] \cup [X_m, \theta); \\ f' < 0 & \text{on } (X_M, X_m); \end{cases}$$

and

$$\operatorname{argmin}_{\mathcal{D}} f \subset \{0, X_m\}. \quad (3.3)$$

iii) Moreover for $L > L_d$, the function $X_m = X_m(\theta, L)$ is smooth and satisfies

$$\partial_\theta X_m = \frac{3/4(\theta - X_m)^{-5/2}}{3/4(\theta - X_m)^{-5/2} - 2L} > 1, \quad (3.4)$$

and

$$\partial_L X_m = \frac{2X_m}{3/4(\theta - X_m)^{-5/2} - 2L} > 0. \quad (3.5)$$

Proof of Proposition 3.1

Step 1: Proof of i) and ii)

For $0 < X < \theta$, we have

$$f'(X) = g(X) - h(X) \quad \text{with} \quad g(X) := \frac{1}{2}(\theta - X)^{-3/2} \quad \text{and} \quad h(X) := 2LX.$$

We notice that g is strictly convex on $[0, \theta)$, with $g(0) > 0$ and $g'(0) > 0$. Therefore there exists a unique $L = L_d > 0$ such that the straight line $y = h(X)$ is tangent from below to the graph $y = g(X)$, at a point $X_d > 0$. In particular, we have

$$\begin{cases} g(X_d) = h(X_d); \\ g'(X_d) = h'(X_d). \end{cases}$$

The unique solution of this system is $X_d = 2\theta/5$ and the value of L_d given in (3.2). Using the strict convexity of g (and the fact that $g(\theta^-) = +\infty$), we deduce the variations of f in cases i) and ii). With the notations of case ii) in Proposition 3.1, X_m is in particular uniquely characterized by

$$f'(X_m) = 0 \quad \text{with} \quad X_m \in \left(\frac{2\theta}{5}, \theta\right), \quad (3.6)$$

and then we get (3.3).

Step 2: Proof of iii)

In order to compute the derivative with respect to (θ, L) , we write the dependance of f on (θ, L) as: $f(X) = f(X, \theta, L)$. Using (3.6) we have

$$\partial_{XX}^2 f(X_m, \theta, L) = \frac{3}{4}(\theta - X_m)^{-5/2} - 2L = \frac{L(5X_m - 2\theta)}{\theta - X_m} > 0. \quad (3.7)$$

Using (3.7), we have $\partial_{XX} f(X_m, \theta, L) \neq 0$. Then using the Implicit Function Theorem, we deduce that $X_m = X_m(\theta, L)$ is a smooth function. Now using the definition of $X_m = X_m(\theta, L)$, we get

$$\frac{d}{d\theta}(\partial_X f(X_m, \theta, L)) = \partial_{XX}^2 f(X_m, \theta, L)\partial_\theta X_m + \partial_{X\theta}^2 f(X_m, \theta, L) = 0. \quad (3.8)$$

Using (3.8) and (3.7), we get (3.4). In a similar way, we get (3.5). □

In what follows, we consider the minimizer of f on the subinterval \mathcal{D} of $[0, \theta]$ where we recall that $\mathcal{D} := [0, \tilde{\theta}^+]$ and $\tilde{\theta}^+$ is defined in (1.7). For this purpose, we introduce

$$\bar{X} := \min \left\{ \tilde{\theta}^+, X_m \right\}, \quad (3.9)$$

where X_m is the quantity introduced in Proposition 3.1. Then we have

$$\operatorname{argmin}_{\mathcal{D}} f \subset \{0, \bar{X}\}. \quad (3.10)$$

For this reason, we have to study in particular the equalities

$$\begin{cases} X_m &= \tilde{\theta}; \\ f(0) &= f(X_m); \\ f(0) &= f(\tilde{\theta}). \end{cases}$$

And then we need to consider the following functions

$$\begin{cases} L_d(\theta) := \frac{25}{24} \sqrt{\frac{5}{3}} \theta^{-5/2} & \text{for } \theta > 0; \end{cases} \quad (3.11)$$

$$\begin{cases} L_{01}(\theta) := \frac{5^{5/2}}{16} \theta^{-5/2} & \text{for } \theta > 0; \end{cases} \quad (3.12)$$

where L_d and L_{01} have already been introduced in (3.2) and (1.13).

First of all, we have to give some geometrical results concerning the position of such curves describing our domains. For an illustration of the following lemma, we refer the reader to Figure 3.

Lemma 3.2 (*Positions of some curves*)

We recall θ^* given in (1.12). The following results hold true:

- i) $L_{01}(\theta^*) = L_{02}(\theta^*) = L_{12}(\theta^*)$.
- ii) For all $\theta > \theta^*$, we have $L_{01}(\theta) < L_{02}(\theta) < L_{12}(\theta)$.
- iii) For all $\theta > 0$, we have $L_{01}(\theta) > L_d(\theta)$.

We skip the proof of Lemma 3.2 since it is easy to check the result by simple computations.

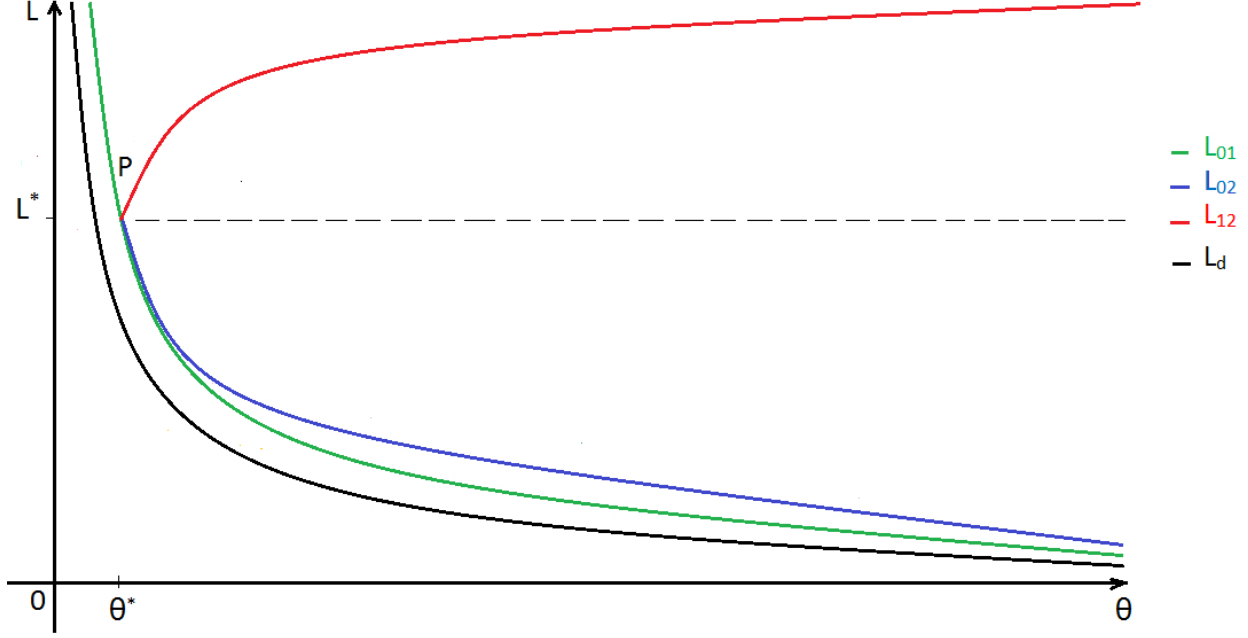


Figure 3: Schematic phase diagram for parameters (θ, L)

Lemma 3.3 (*Properties of the function $X_m - \tilde{\theta}$*)

i) For $\theta > 0$ and $L > L_d(\theta)$, we have $\partial_\theta(X_m - \tilde{\theta}) > 0$, where $X_m = X_m(\theta, L)$ and $\tilde{\theta} = \tilde{\theta}(\theta, L)$ are respectively introduced in Proposition 3.1 and (1.7).

ii) For $\theta > 0$ and $L = L_{01}(\theta)$, we have $L > L_d(\theta)$ and

$$\begin{cases} X_m < \tilde{\theta} & \text{for } 0 < \theta < \theta^*; \\ X_m = \tilde{\theta} & \text{for } \theta = \theta^*; \\ X_m > \tilde{\theta} & \text{for } \theta > \theta^*. \end{cases}$$

iii) For $\theta \geq \theta^*$ and $L = L_{12}(\theta)$, we have $L > L_d(\theta)$ and $X_m = \tilde{\theta}$.

Proof of Lemma 3.3

Proof of i) Let $\theta > 0$ and $L > L_d(\theta)$. According to Proposition 3.1 ii), f admits a non zero minimizer $X_m \in (2\theta/5, \theta)$. Using (3.4) and the definition of $\tilde{\theta}$ in (1.7), we get

$$\partial_\theta(X_m - \tilde{\theta}) = \frac{3/4(\theta - X_m)^{-5/2}}{3/4(\theta - X_m)^{-5/2} - 2L} - 1 = \frac{2L}{3/4(\theta - X_m)^{-5/2} - 2L} > 0.$$

Proof of ii) Let $\theta > 0$ and $L = L_{01}(\theta)$. Using Lemma 3.2, we deduce that $L = L_{01}(\theta) > L_d(\theta)$ for all $\theta > 0$. Then according to Proposition 3.1 ii), f admits a non zero minimizer $X_m \in (2\theta/5, \theta)$. Using (3.6) we have

$$\frac{1}{2}(\theta - X_m)^{-3/2} = 2L_{01}(\theta)X_m \quad \text{with} \quad \frac{2}{5}\theta < X_m < \theta.$$

Let $Y_m := X_m/\theta$, then we have

$$\frac{1}{2}(1 - Y_m)^{-3/2} = \frac{5^{5/2}}{8}Y_m \quad \text{with} \quad \frac{2}{5} < Y_m < 1. \quad (3.13)$$

The uniqueness of Y_m shows that Y_m is a constant independent of θ . It is easy to check that $Y_m = 4/5$ is the solution of (3.13). Then

$$X_m = \frac{4}{5}\theta \quad \text{for all } \theta > 0 \text{ and } L = L_{01}(\theta). \quad (3.14)$$

Using (3.14), we get that for $\theta > 0$ and $L = L_{01}(\theta)$

$$X_m - \tilde{\theta} = \frac{4\theta}{5} - \tilde{\theta}(\theta, L_{01}(\theta)) = \frac{\theta}{5} \left(\frac{4^4\alpha^2}{5^4}\theta^4 - 1 \right),$$

which vanishes for $\theta = \theta^*$ and then we get the result.

Proof of iii) Let $\theta \geq \theta^*$ and $L = L_{12}(\theta)$. Using Lemma 3.2, we conclude that $L = L_{12}(\theta) \geq L_{01}(\theta) > L_d(\theta)$ for all $\theta \geq \theta^*$. Then using Proposition 3.1 ii), f admits a non zero minimizer $X_m \in (2\theta/5, \theta)$. A direct computation of $f'(\tilde{\theta})$ shows that

$$f'(\tilde{\theta}) = \frac{Q(\theta, L)}{2\alpha^3 L} \quad \text{with} \quad Q(\theta, L) := L^4 - 4\alpha^3\theta L^2 + 4\alpha^5.$$

It is easy to check that in particular for $\theta \geq \theta^*$ and $L = L_{12}(\theta)$, we have $Q(\theta, L_{12}(\theta)) = 0$ and then $f'(\tilde{\theta}) = 0$. Using Lemma 3.3 ii), we know that

$$\tilde{\theta} = X_m > \frac{2}{5}\theta \quad \text{at the point} \quad (\theta, L) = (\theta^*, L^*) = P. \quad (3.15)$$

Moreover for $\theta > \theta^*$ and $L = L_{12}(\theta)$, we have

$$\frac{d}{d\theta} \left(\tilde{\theta}(\theta, L_{12}(\theta)) - \frac{2}{5}\theta \right) = \frac{3}{5} + 2\frac{\alpha^2}{L_{12}^3(\theta)}L'_{12}(\theta) > 0.$$

Therefore we deduce that $\tilde{\theta} > 2\theta/5$ for $\theta \geq \theta^*$ and $L = L_{12}(\theta)$. Then we conclude that $X_m = \tilde{\theta}$ for $\theta \geq \theta^*$ and $L = L_{12}(\theta)$. □

Lemma 3.4 (Properties of $f(X_m)$ and $f(\tilde{\theta})$)

Let $f(X) = f(X, \theta, L)$ be given in (1.5).

A) Properties of $f(X_m)$

For $\theta > 0$ with $L > L_d(\theta)$ and $X_m = X_m(\theta, L)$ introduced in Proposition 3.1, we have

A.i) $\frac{d}{dL}f(X_m(\theta, L), \theta, L) < 0,$

A.ii) $\frac{d}{d\theta}f(X_m(\theta, L), \theta, L) < 0.$

B) Properties of $f(\tilde{\theta})$

B.i) Let $(\theta, L) \in (0, +\infty)^2$ such that $\tilde{\theta} = \tilde{\theta}(\theta, L) > 0$. Then we have $\frac{d}{d\theta}f(\tilde{\theta}(\theta, L), \theta, L) < 0.$

B.ii) For $\theta > \theta^*$ and $L > L_{02}(\theta)$, we have $\tilde{\theta} > 0$ and $\frac{d}{dL}f(\tilde{\theta}(\theta, L), \theta, L) < 0.$

Proof of Lemma 3.4

A) Let $\theta > 0$ and $L > L_d(\theta)$. Using Proposition 3.1 ii), f admits a non zero minimizer $X_m \in (2\theta/5, \theta)$.

Proof of A.i) We have

$$\frac{d}{dL}f(X_m(\theta, L), \theta, L) = \partial_L f(X_m, \theta, L) + \partial_X f(X_m, \theta, L) \partial_L X_m = -X_m^2 < 0,$$

where we have used (1.5) and (3.6) to get the last equality.

Proof of A.ii) We have

$$\frac{d}{d\theta}f(X_m(\theta, L), \theta, L) = \partial_\theta f(X_m, \theta, L) + \partial_X f(X_m, \theta, L) \partial_\theta X_m = -\frac{1}{2}(\theta - X_m)^{-3/2} < 0,$$

where again we have used (1.5) and (3.6) to get the last equality.

B) We recall that $\tilde{\theta} = \tilde{\theta}(\theta, L)$ is given in (1.7).

Proof of B.i) Let $(\theta, L) \in (0, +\infty)^2$ such that $\tilde{\theta} = \tilde{\theta}(\theta, L) > 0$. We have

$$\frac{d}{d\theta}f(\tilde{\theta}(\theta, L), \theta, L) = \frac{d}{d\theta} \left[L \left(\frac{1}{\alpha} - \tilde{\theta}^2 \right) \right] = -2L\tilde{\theta} < 0.$$

Proof of B.ii) It is easy to check that $\tilde{\theta}(\theta, L_{02}(\theta)) = \alpha^{-1/2} > 0$ for $\theta \geq \theta^*$. Since $\partial_L \tilde{\theta} > 0$, we deduce that

$$\tilde{\theta} > \alpha^{-1/2} > 0 \quad \text{for } \theta > \theta^* \text{ and } L > L_{02}(\theta). \quad (3.16)$$

Now because $\tilde{\theta} > 0$, a direct computation shows that for $\theta > \theta^*$ and $L > L_{02}(\theta)$ we have

$$\frac{d}{dL}f(\tilde{\theta}(\theta, L), \theta, L) = \frac{d}{dL} \left[L \left(\frac{1}{\alpha} - \tilde{\theta}^2 \right) \right] = \frac{1}{\alpha} - \tilde{\theta}^2 - 4\alpha^2 \frac{\tilde{\theta}}{L^2}.$$

Using (3.16) we get the result. □

3.2 Classification of global minimizers of E

In this subsection, we prove Theorem 1.7.

Proof of Theorem 1.7

Using Theorem 1.3, a minimizer $\zeta = (\zeta_1, \zeta_2)$ of the energy E is always defined as in (1.8) and (1.9). So we have to identify the value of $K \in \mathcal{D}$ solving Problem (3.1) in each case.

Case A: $(\theta, L) \in D_0$

Case A.i): $\theta > 0$ and $L \leq L_d(\theta)$

Using Proposition 3.1 i) we deduce that

$$\operatorname{argmin}_{\mathcal{D}} f = \{0\}.$$

Case A.ii): $\theta > 0$ and $L_d(\theta) < L < L_{01}(\theta)$

Using Proposition 3.1 ii) we deduce that f admits a non zero minimizer $X_m \in (2\theta/5, \theta)$.

Using (3.14), a simple computation leads us to the following

$$f(X_m) = 0 = f(0) \quad \text{for } \theta > 0 \text{ and } L = L_{01}(\theta). \quad (3.17)$$

Using Lemma 3.4 A.i), we deduce that $f(X_m) > 0 = f(0)$ for $\theta > 0$ and $L_d(\theta) < L < L_{01}(\theta)$. Then

$$\underset{\mathcal{D}}{\operatorname{argmin}} f = \{0\}.$$

Case A.iii): $\theta > \theta^*$ and $L_{01}(\theta) \leq L < L_{02}(\theta)$

Using Lemma 3.2, we have $L \geq L_{01}(\theta) > L_d(\theta)$. Now using Proposition 3.1 ii), we deduce that f admits a non zero minimizer $X_m \in (2\theta/5, \theta)$. Using Lemma 3.3 ii), we conclude that

$$X_m > \tilde{\theta} \quad \text{for } \theta > \theta^* \text{ and } L = L_{01}(\theta). \quad (3.18)$$

Using Lemma 3.3 i), we deduce that $X_m > \tilde{\theta}$ for $\theta > \theta^*$ and $L_{01}(\theta) \leq L < L_{02}(\theta)$. Therefore $\underset{\mathcal{D}}{\operatorname{argmin}} f \in \{0, \tilde{\theta}\}$. Now, we distinguish two cases:

If $\tilde{\theta} \leq 0$, then $\mathcal{D} = \{0\}$ and $\underset{\mathcal{D}}{\operatorname{argmin}} f = \{0\}$.

If $\tilde{\theta} > 0$, we proceed as follows: A direct computation shows that

$$f(\tilde{\theta}) = 0 = f(0) \quad \text{for } \theta > \theta^* \text{ and } L = L_{02}(\theta). \quad (3.19)$$

According to Lemma 3.4 B.i), we deduce that $f(\tilde{\theta}) > 0 = f(0)$ for $\theta > \theta^*$ and $L_{01}(\theta) \leq L < L_{02}(\theta)$. Therefore $\underset{\mathcal{D}}{\operatorname{argmin}} f = \{0\}$.

This shows that in case A.iii), we have

$$\underset{\mathcal{D}}{\operatorname{argmin}} f = \{0\}.$$

Case B: $(\theta, L) \in D_1$

According to Lemma 3.2, we have $L > L_{01}(\theta) > L_d(\theta)$ for $0 < \theta \leq \theta^*$. Using again Lemma 3.2, we also have $L > L_{12}(\theta) > L_{01}(\theta) > L_d(\theta)$ for $\theta > \theta^*$. Therefore, we have $L > L_d(\theta)$ for all $(\theta, L) \in D_1$. Then using Proposition 3.1 ii), we deduce that f admits a non zero minimizer $X_m \in (2\theta/5, \theta)$. Using Lemma 3.3 ii), we conclude that

$$X_m < \tilde{\theta} \quad \text{for } 0 < \theta < \theta^* \text{ and } L = L_{01}(\theta). \quad (3.20)$$

Moreover using Lemma 3.3 iii), we have

$$X_m = \tilde{\theta} \quad \text{for } \theta \geq \theta^* \text{ and } L = L_{12}(\theta). \quad (3.21)$$

Using Lemma 3.3 i), we deduce that $X_m < \tilde{\theta}$ for $(\theta, L) \in D_1$. Therefore $\underset{\mathcal{D}}{\operatorname{argmin}} f \in \{0, X_m\}$.

Using (3.17) and Lemma 3.4 A.ii), we get that $f(X_m) < 0 = f(0)$ for $(\theta, L) \in D_1$. Therefore

$$\underset{\mathcal{D}}{\operatorname{argmin}} f = \{X_m\}.$$

Case C: $(\theta, L) \in D_2$

According to Lemma 3.2, we have $L > L_{02}(\theta) > L_{01}(\theta) > L_d(\theta)$ for $\theta > \theta^*$. Then using Proposition 3.1 ii), we deduce that f admits a non zero minimizer $X_m \in (2\theta/5, \theta)$.

i) For $\theta > \theta^*$ and $L^* < L < L_{12}(\theta)$, using (3.21) and Lemma 3.3 i), we deduce that $X_m > \tilde{\theta}$.

ii) For $\theta > \theta^*$ and $L_{02}(\theta) < L \leq L^*$, using (3.18) and Lemma 3.3 i), we deduce that $X_m > \tilde{\theta}$. Therefore for $(\theta, L) \in D_2$, we have $\operatorname{argmin}_{\mathcal{D}} f \in \{0, \tilde{\theta}\}$.

On the other hand, using Lemma 3.4 B.ii) for $\theta > \theta^*$ and $L > L_{02}(\theta)$, we have $\tilde{\theta} > 0$. Using (3.19) and Lemma 3.4 B.ii), we deduce that $f(\tilde{\theta}) < 0 = f(0)$ for $(\theta, L) \in D_2$. Therefore

$$\operatorname{argmin}_{\mathcal{D}} f = \{\tilde{\theta}\}.$$

Case D: $(\theta, L) \in \Gamma_{01}$

It is easy to check that

$$\operatorname{argmin}_{\mathcal{D}} f = \{0, \bar{X}\} \quad \text{with} \quad 0 < \bar{X} = X_m < \tilde{\theta}.$$

Case E: $(\theta, L) \in \Gamma_{02}$

It is easy to verify that

$$\operatorname{argmin}_{\mathcal{D}} f = \{0, \bar{X}\} \quad \text{with} \quad 0 < \bar{X} = \tilde{\theta} < X_m.$$

Case F: $(\theta, L) \in \Gamma_{12}$

Similarly, we can show that

$$\operatorname{argmin}_{\mathcal{D}} f = \{\bar{X}\} \quad \text{with} \quad \bar{X} = X_m = \tilde{\theta} > 0.$$

Case G: $(\theta, L) = P = (\theta^*, L^*)$

Finally, we can check that

$$\operatorname{argmin}_{\mathcal{D}} f = \{0, \bar{X}\} \quad \text{with} \quad 0 < \bar{X} = X_m = \tilde{\theta}.$$

Conclusion: So we have proved that

$$\operatorname{argmin}_{\mathcal{D}} f = \begin{cases} \{0\} & \text{if } (\theta, L) \in D_0; \\ \{X_m\} & \text{if } (\theta, L) \in D_1; \\ \{\tilde{\theta}\} & \text{if } (\theta, L) \in D_2 \cup \Gamma_{12}; \end{cases} \quad (3.22)$$

and

$$\operatorname{argmin}_{\mathcal{D}} f \in \begin{cases} \{0, X_m\} & \text{if } (\theta, L) \in \Gamma_{01}; \\ \{0, \tilde{\theta}\} & \text{if } (\theta, L) \in \Gamma_{02} \cup \{P\}. \end{cases} \quad (3.23)$$

Now using Theorem 1.3, a minimizer $\zeta = (\zeta_1, \zeta_2)$ of the energy E is defined as in (1.8) and (1.9). Moreover, using (1.11) we get $T < \bar{L}$ if $(\theta, L) \in D_1$, and $T = \bar{L}$ if $(\theta, L) \in D_2 \cup \Gamma_{12}$ which shows (1.24). Similarly, we get (1.25) for $(\theta, L) \in \Gamma_{01}$ or $(\theta, L) \in \Gamma_{02} \cup \{P\}$. \square

3.3 Global minimizers of E and blister's properties

In this subsection, we prove Theorem 1.3 ii) and Proposition 1.8.

Proof of Theorem 1.3 ii)

a) Case $(\theta, L) \in D_0 \cup D_1 \cup D_2 \cup \Gamma_{12}$

Using (3.22), there exists a unique minimizer $K \in \mathcal{D}$ of the function f . Now using Theorems 1.2 and 1.3 i), there exists a global minimizer $\zeta \in Y$ of the energy E and there exists $T \in [0, \bar{L}]$ such that (up to addition of constants and translation of (ζ_1, ζ_2)) this minimizer is given by (1.8) and (1.9).

b) Case $(\theta, L) \in \Gamma_{01} \cup \Gamma_{02} \cup \{P\}$

Using (3.23), there exist exactly two minimizers of the function f on \mathcal{D} . Similarly using (1.10), Theorems 1.2 and 1.3 i), we see that the energy E has exactly two global minimizers in Y : the trivial solution $(\zeta_1, \zeta_2) = (0, 0)$ and a blister $\zeta \in Y$ given by (1.8)-(1.9). □

Proof of Proposition 1.8

Proof of i)

Let $(\theta, L) \in D_1 \cup D_2 \cup \Gamma_{12}$. Using (3.22), we conclude that there exists a unique $K = K(\theta, L) \in \mathcal{D}$ (see (3.22)) such that

$$\min_{X \in \mathcal{D}} f(X) = f(K),$$

with f and \mathcal{D} , respectively introduced in (1.5) and (1.7). According to (1.9), the length of the support of ζ_2 and its amplitude A can be written (using (1.6) to express $(\bar{\theta}, \bar{L})$ in terms of (θ, L)) as

$$T = 2\pi \sqrt{\frac{2\alpha}{3(\bar{\theta} - \alpha K)}} = 2\pi \sqrt{\frac{2}{3}} (\theta - K)^{-1/2}, \quad (3.24)$$

and

$$A = \sqrt{\frac{K\bar{L}}{\pi\beta}} = \left(\frac{2}{3}\right)^{1/4} (\pi\alpha)^{-1/2} (KLT)^{1/2}. \quad (3.25)$$

Using (3.22), we have

$$K = K(\theta, L) = \begin{cases} X_m(\theta, L) & \text{if } (\theta, L) \in D_1; \\ \tilde{\theta}(\theta, L) & \text{if } (\theta, L) \in D_2 \cup \Gamma_{12}. \end{cases}$$

The function $\tilde{\theta}$ is smooth. Moreover, X_m is smooth on D_1 according to Proposition 3.1 iii). Therefore $K = K(\theta, L)$ is a smooth function of (θ, L) on each domain D_1 and D_2 .

Straightforward calculations show that for $(\theta, L) \in D_1 \cup D_2$

$$\left\{ \begin{array}{l} \partial_\theta T = \pi \sqrt{\frac{2}{3}} (\theta - K)^{-3/2} (\partial_\theta K - 1), \\ \partial_L T = \pi \sqrt{\frac{2}{3}} (\theta - K)^{-3/2} \partial_L K, \\ \partial_\theta A = \left(\frac{1}{24}\right)^{1/4} \left(\frac{L}{\alpha \pi K T}\right)^{1/2} (T \partial_\theta K + K \partial_\theta T), \\ \partial_L A = \left(\frac{1}{24}\right)^{1/4} \left(\frac{1}{\alpha \pi K T L}\right)^{1/2} (K T + T L \partial_L K + K L \partial_L T). \end{array} \right. \quad (3.26)$$

Case 1: $(\theta, L) \in D_1$

Using (3.4), (3.5) and (3.26), we conclude that $\partial_\theta T, \partial_L T, \partial_\theta A, \partial_L A \geq 0$.

Case 2: $(\theta, L) \in D_2 \cup \Gamma_{12}$

Using (3.22), we have $K = \tilde{\theta}(L) = \theta - \alpha^2/L^2$ and $T = \bar{L}$. So we have

$$\partial_\theta K = 1 \quad \text{and} \quad \partial_L K = \frac{2\alpha^2}{L^3} > 0.$$

Using (3.26), we conclude that $\partial_\theta T, \partial_L T, \partial_\theta A, \partial_L A \geq 0$.

Proof of ii)

Step 1: Proof of (1.26)

Our goal is to compute the derivative of T with respect to θ along the curve Γ_{01} . Using (3.26), (3.4) and (3.5), we get with obvious notation for $(\theta, L) \in \Gamma_{01}$ (using the fact that $L = L_{01}(\theta)$ given in (1.13))

$$\begin{aligned} \frac{d}{d\theta} T(\theta, L_{01}(\theta)) &= \pi \sqrt{\frac{2}{3}} (\theta - K)^{-3/2} [(\partial_\theta K - 1) + (\partial_L K) L'_{01}(\theta)] \\ &= \pi \sqrt{\frac{2}{3}} (\theta - K)^{-3/2} \left[\frac{5^{5/2} \theta^{-5/2} (2 - 5\theta^{-1} K)}{16 (3/4 (\theta - K)^{-5/2} - 2L)} \right]. \end{aligned}$$

Using (3.6) and (3.7), we conclude that $T = T(\theta, L_{01}(\theta))$ is decreasing in θ along the curve Γ_{01} . Then we deduce that $\inf_{(\theta, L) \in \Gamma_{01}} T = T(P) = T(\theta^*, L_{01}(\theta^*))$. Using (1.25), we have

$T(P) = \bar{L}^*$, where \bar{L}^* is the value of \bar{L} at the point P . Therefore

$$\inf_{(\theta, L) \in \Gamma_{01}} T = \bar{L}^* = 2\pi \sqrt{\frac{2}{3}} \frac{L_{01}(\theta^*)}{\alpha} = 4\pi \sqrt{\frac{2}{3}} \alpha^{1/4} =: T^*. \quad (3.27)$$

Using the monotonicity of T in θ and L on D_1 , we get (1.26).

Step 2: Proof of (1.27)

Let $\bar{K} := K/\theta$. Similarly using (3.25) and (3.24), we explicit A in term of \bar{K} for $(\theta, L) \in \Gamma_{01}$ (in particular $L = L_{01}(\theta)$). A straightforward computation gives

$$A(\theta, L_{01}(\theta)) = \left(\frac{1}{12}\right)^{1/2} 5^{5/4} (\bar{K}(1 - \bar{K})^{-1/2})^{1/2} \alpha^{-1/2} \theta^{-1}.$$

For $(\theta, L) \in \Gamma_{01}$, with $K = X_m$ we have by (3.14) that $\bar{K} = 4/5$. Then $A = A(\theta, L_{01}(\theta))$ is decreasing in θ along the curve Γ_{01} . So

$$\inf_{(\theta, L) \in \Gamma_{01}} A = A(\theta^*, L_{01}(\theta^*)) = 2 \left(\frac{5}{9} \right)^{1/4} (\bar{K}(1 - \bar{K})^{-1/2})^{1/2} = 4/\sqrt{3} =: A^*.$$

Finally using the monotonicity of A in θ and L on D_1 , we get (1.27). □

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