

Causal Mediation Analysis for Difference-in-Difference Design and Panel Data

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Appendix A

$$Y_{gt}(a) \perp A_{gt} | Y_{g0} \forall a \leftrightarrow Y_{gt}(a) - Y_{g0}(a) \perp A_{gt} \forall a$$

Lemma 1. Random variables X, Y, Z satisfies $X \perp Y | Z \leftrightarrow E[X|Y, Z] = E[X|Z]$.

Proof:

$$\begin{aligned} P\{X \leq x, Y = y, Z = z\} &= P\{X \leq x, Y = y | Z = z\} P\{Z = z\} \\ &= P\{X \leq x | Z = z\} \times P\{Y = y | Z = z\} \times P\{Z = z\} \\ &= P\{X \leq x | Z = z\} \times P\{Y = y, Z = z\} \end{aligned}$$

Then we have

$$\begin{aligned} P\{X \leq x | Y = y, Z = z\} &= \frac{P\{X \leq x, Y = y, Z = z\}}{P\{Y = y, Z = z\}} \\ &= \frac{P\{X \leq x | Z = z\} \times P\{Y = y, Z = z\}}{P\{Y = y, Z = z\}} \\ &= P\{X \leq x | Z = z\} \end{aligned}$$

This proves lemma 1.

By iterated expectation and Lemma 1.

$$\begin{aligned} & E[Y_{gt}(a) - Y_{g0}(a) | A_{gt} = a] \\ &= E[E[Y_{gt}(a) - Y_{g0}(a) | A_{gt} = a, Y_{g0}]] \\ &= E[E[Y_{gt}(a) - Y_{g0}(a) | A_{gt} = a]] \\ &= E[Y_{gt}(a) - Y_{g0}(a)] \\ &\leftrightarrow Y_{gt}(a) - Y_{g0}(a) \perp A_{gt} \forall a \end{aligned}$$

Appendix B

Assumptions

NEPT

$$(A1) \ Y_{g_0} = Y_{g_0}(a), \text{ for all } a$$

Exchangeability

$$(E1) \ Y_{gt}(a) - Y_{g_0}(a) \perp A_{gt} \ \forall a$$

Detailed Process

$$\begin{aligned} TE &= E[Y_{gt}(1)] - E[Y_{gt}(0)] \\ &= \{E[Y_{gt}(1)] - E[Y_{g_0}]\} - \{E[Y_{gt}(0)] - E[Y_{g_0}]\} \quad (\text{by (A1)}) \end{aligned}$$

With assumptions (A1) and (E1), it could be identified as follows.

Let $\phi_{TE}(a)$ be a causal parameter for TE.

$$\begin{aligned} \phi_{TE}(a) &:= E[Y_{gt}(a)] - E[Y_{g_0}] \\ &= E[Y_{gt}(a)] - E[Y_{g_0}(a)] \quad (\text{by (A1)}) \\ &= E[Y_{gt}(a) - Y_{g_0}(a)] \\ &= E[Y_{gt}(a) - Y_{g_0}(a) | A_{gt} = a] \quad (\text{by (E1)}) \\ &= E[Y_{gt} - Y_{g_0} | A_{gt} = a] \quad (\text{by consistency}) \\ &= E[Y_{gt} | A_{gt} = a] - E[Y_{g_0} | A_{gt} = a] \end{aligned}$$

$$\begin{aligned} TE &= \phi_{TE}(a_1) - \phi_{TE}(a_0) \\ &= E[Y_{gt} - Y_{g_0} | A_{gt} = a_1] - E[Y_{gt} - Y_{g_0} | A_{gt} = a_0] \\ &= \{E[Y_{gt} | A_{gt} = a_1] - E[Y_{g_0} | A_{gt} = a_1]\} - \{E[Y_{gt} | A_{gt} = a_0] - E[Y_{g_0} | A_{gt} = a_0]\} \end{aligned}$$

Appendix C

Assumptions

NEPT

$$(A2) \ Y_{g_0} = Y_{g_0}(a, m), \text{ for all } a \text{ and } m$$

Exchangeability

$$(E1) \ Y_{gt}(a) - Y_{g_0}(a) \perp A_{gt} \ \forall a$$

$$(E2) \ Y_{gt}(a, m) - Y_{g_0}(a, m) \perp M_{gt} \mid A_{gt} \ \forall a, m$$

Detailed Process

$$\begin{aligned} CDE(m) &= E[Y_{gt}(a_1, m)] - E[Y_{gt}(a_0, m)] \\ &= \{E[Y_{gt}(a_1, m)] - E[Y_{g_0}]\} - \{E[Y_{gt}(a_0, m)] - E[Y_{g_0}]\} \quad (\text{by (A2)}) \end{aligned}$$

With assumptions (A2), (E1) and (E2), it could be identified as follows.

Let $\phi_{CDE}(a)$ be a causal parameter for CDE.

$$\begin{aligned} \phi_{CDE}(a) &:= E[Y_{gt}(a, m)] - E[Y_{g_0}] \\ &= E[Y_{gt}(a, m)] - E[Y_{g_0}(a, m)] \quad (\text{by (A2)}) \\ &= E[Y_{gt}(a, m) - Y_{g_0}(a, m)] \\ &= E[Y_{gt}(a, m) - Y_{g_0}(a, m) \mid A_{gt} = a] \quad (\text{by (E1)}) \\ &= E[Y_{gt}(a, m) - Y_{g_0}(a, m) \mid A_{gt} = a, M_{gt} = m] \quad (\text{by (E2)}) \\ &= E[Y_{gt} - Y_{g_0} \mid A_{gt} = a, M_{gt} = m] \quad (\text{by consistency}) \end{aligned}$$

$$\begin{aligned} CDE(m) &= \phi_{CDE}(a_1) - \phi_{CDE}(a_0) \\ &= E[Y_{gt} - Y_{g_0} \mid A_{gt} = a_1, M_{gt} = m] - E[Y_{gt} - Y_{g_0} \mid A_{gt} = a_0, M_{gt} = m] \\ &= \{E[Y_{gt} \mid A_{gt} = a_1, M_{gt} = m] - E[Y_{g_0} \mid A_{gt} = a_1, M_{gt} = m]\} - \\ &\quad \{E[Y_{gt} \mid A_{gt} = a_0, M_{gt} = m] - E[Y_{g_0} \mid A_{gt} = a_0, M_{gt} = m]\} \end{aligned}$$

Appendix D

Assumptions

NEPT

- (A1) $Y_{g0} = Y_{g0}(a)$, for all a
- (A2) $Y_{g0} = Y_{g0}(a, m)$, for all a and m
- (A3) $Y_{g0} = Y_{g0}(a, M_{gt}(a^*))$, for all a and a^*
- (A4) $M_{g0} = M_{g0}(a)$, for all a

Exchangeability

- (E1) $Y_{gt}(a) - Y_{g0}(a) \perp A_{gt} \forall a$
- (E2) $Y_{gt}(a, m) - Y_{g0}(a, m) \perp M_{gt} | A_{gt} \forall a, m$
- (E3) $M_{gt}(a) - M_{g0}(a) \perp A_{gt} \forall a$
- (E4) $Y_{gt}(a, m) - Y_{g0}(a, m) \perp M_{gt}(a^*) | A_{gt} \forall a, a^*, m$

Detailed Process

With assumptions (A1)-(A4) and (E1)-(E4).

Let $\phi_{NE,Y}(a, a^*)$ be a causal parameter for the effect of M_{gt} on Y_{gt} .

$$\begin{aligned}
 \phi_{NE,Y}(a, a^*) &:= E \left[Y_{gt} \left(a, M_{gt}(a^*) \right) \right] - E[Y_{g0}] \\
 &= E \left[Y_{gt} \left(a, M_{gt}(a^*) \right) \right] - E \left[Y_{g0} \left(a, M_{gt}(a^*) \right) \right] \quad (\text{by (A3)}) \\
 &= \int_m E \left[Y_{gt}(a, m) - Y_{g0}(a, m) | M_{gt}(a^*) = m \right] f_{M_{gt}(a^*)}(m) dm \\
 &= \int_m E \left[Y_{gt}(a, m) - Y_{g0}(a, m) \right] f_{M_{gt}(a^*)}(m) dm \quad (\text{by (E4)}) \\
 &= \int_m E \left[Y_{gt}(a, m) - Y_{g0}(a, m) | A_{gt} = a \right] f_{M_{gt}(a^*)}(m) dm \quad (\text{by (E1)}) \\
 &= \int_m E \left[Y_{gt}(a, m) - Y_{g0}(a, m) | A_{gt} = a, M_{gt} = m \right] f_{M_{gt}(a^*)}(m) dm \quad (\text{by (E2)}) \\
 &= \int_m E \left[Y_{gt} - Y_{g0} | A_{gt} = a, M_{gt} = m_{gt} \right] f_{M_{gt}(a^*)}(m) dm \quad (\text{by consistency})
 \end{aligned}$$

And with (A4), (E3) and (C3), let $\phi_{NE,M}(a_{gt})$ be a causal parameter for the effect of A_{gt} on M_{gt} , we can also identify $\phi_{NE,M}(a_{gt})$:

$$\begin{aligned}
 \phi_{NE,M}(a_{gt}) &:= E \left[M_{gt}(a) \right] - E \left[M_{g0} \right] \\
 &= E \left[M_{gt}(a) \right] - E \left[M_{g0}(a) \right] \quad (\text{by (A4)}) \\
 &= E \left[M_{gt}(a) - M_{g0}(a) \right]
 \end{aligned}$$

$$= E[M_{gt}(a) - M_{g0}(a)|A_{gt} = a] \quad (\text{by (E3)})$$

$$= E[M_{gt} - M_{g0}|A_{gt} = a] \quad (\text{by consistency})$$

The rest of the identification is related to the variable type of M_{gt} , so it will be discussed in the section of estimation.

Since M_{gt} is binary, the integration of m could be reduced to a summation of $M_{gt} = 1$ and $M_{gt} = 0$.

$$\Phi_{NE,Y}(a, a^*)$$

$$= \sum_{m=0}^1 E[Y_{gt} - Y_{g0}|A_{gt} = a, M_{gt} = m] Pr(M_{gt} = m|A_{gt} = a^*)$$

$$= Pr(M_{gt} = 1|A_{gt} = a^*) \{E[Y_{gt} - Y_{g0}|A_{gt} = a, M_{gt} = 1] -$$

$$E[Y_{gt} - Y_{g0}|A_{gt} = a, M_{gt} = 0]\} + E[Y_{gt} - Y_{g0}|A_{gt} = a, M_{gt} = 0]$$

Then the process of identification is finished, it contains no more counterfactual terms. The

original definition of NDE is $E[Y_{gt}(a_1, M_{gt}(a_0)) - Y_{gt}(a_0, M_{gt}(a_0))]$ and NIE is

$E[Y_{gt}(a_1, M_{gt}(a_1)) - Y_{gt}(a_1, M_{gt}(a_0))]$, but by assumption (A3), it can be extended to

$\Phi_{NE,Y}(a_1, a_0) - \Phi_{NE,Y}(a_0, a_0)$ and $\Phi_{NE,Y}(a_1, a_1) - \Phi_{NE,Y}(a_1, a_0)$. Then we can use the

result of identified $\Phi_{NE,Y}(a, a^*)$, and also estimate NDE and NIE by an DID estimator of Y .

$$NIE = E[Y_{gt}(a_1, M_{gt}(a_1)) - Y_{gt}(a_1, M_{gt}(a_0))]$$

$$= \Phi_{NE,Y}(a_1, a_1) - \Phi_{NE,Y}(a_1, a_0)$$

$$= \left\{ \left[E[M_{gt}|A_{gt} = a_1] - E[M_{g0}|A_{gt} = a_1] \right] - \left[E[M_{gt}|A_{gt} = 0] - \right.$$

$$\left. E[M_{g0}|A_{gt} = 0] \right\} \left\{ \left[E[Y_{gt}|A_{gt} = a_1, M_{gt} = 1] - E[Y_{g0}|A_{gt} = a_1, M_{gt} = 1] \right] - \right.$$

$$\left. \left[E[Y_{gt}|A_{gt} = a_1, M_{gt} = 0] - E[Y_{g0}|A_{gt} = a_1, M_{gt} = 0] \right] \right\}$$

Appendix E

$$E[Y_{gt}|A_{gt} = a_{gt}] = \gamma_A a_{gt} + \gamma_t + \gamma_g \quad (\text{Model 1})$$

$$E[Y_{gt}|A_{gt} = a_{gt}, M_{gt} = m_{gt}] = \theta_A a_{gt} + \theta_M m_{gt} + \theta_t + \theta_g \quad (\text{Model 2})$$

$$E[M_{gt}|A_{gt} = a_{gt}] = \beta_A a_{gt} + \beta_t + \beta_g \quad (\text{Model 3})$$

The equivalence of $\widehat{\gamma}_A - \widehat{\theta}_A$ and $\widehat{\theta}_M \widehat{\beta}_A$:

$$E[Y_{gt}|A_{gt} = a_{gt}] = \sum_m E[Y_{gt}|A_{gt} = a_{gt}, M_{gt} = m_{gt}] \times Pr(M_{gt}|A_{gt} = a_{gt})$$

$$= \sum_m (\theta_A a_{gt} + \theta_M m_{gt} + \theta_t + \theta_g) \times Pr(M_{gt}|A_{gt} = a_{gt})$$

$$= \theta_A a_{gt} + \theta_t + \theta_g + \theta_M \sum_m m_{gt} \times Pr(M_{gt}|A_{gt} = a_{gt})$$

$$\begin{aligned}
&= \theta_A a_{gt} + \theta_t + \theta_g + \theta_M E[M_{gt} | A_{gt} = a_{gt}] \\
&= \theta_A a_{gt} + \theta_t + \theta_g + \theta_M (\beta_A a_{gt} + \beta_t + \beta_g) \\
&= \theta_A a_{gt} + \theta_M \beta_A a_{gt} + (\theta_t + \theta_M \beta_t) + (\theta_g + \theta_M \beta_g) \\
\gamma_A a_{gt} + \gamma_t + \gamma_g &= \theta_A a_{gt} + \theta_M \beta_A a_{gt} + (\theta_t + \theta_M \beta_t) + (\theta_g + \theta_M \beta_g) \\
\Rightarrow (\gamma_A - \theta_A) a_{gt} &= \theta_M \beta_A a_{gt}
\end{aligned}$$

Appendix F

40 countries: Argentina, Australia, Austria, Bolivia, Brazil, Canada, Chile, Colombia, Croatia, Denmark, Egypt, Finland, France, Germany, Indonesia, Iraq, Ireland, Israel, Italy, Japan, Malaysia, Mexico, Netherlands, New Zealand, Peru, Philippines, Poland, Portugal, Saudi Arabia, Singapore, South Korea, Spain, Sweden, Taiwan, Thailand, Turkey, United Arab Emirates, United Kingdom, United States, and Venezuela.

Appendix G

Table S1. The summary statistics for all variables across 40 countries and 12 months.

	Mean	Minimum	Maximum	SD
covid-19 outbreak	128	0	3137	311.5
Extent of mobility restriction	10.83	39.57	-2.133	7.363
Search volume	45.85	0	91	21.1

Appendix H

The built models for the search volumes of ‘insomnia’ and the extent of mobility restriction.

$E[(\text{search volume of keyword})_{gt} | (\text{the extent of national covid-19 outbreak})_{gt}] = \gamma_A \times (\text{the extent of national covid-19 outbreak})_{gt} + \gamma_t + \gamma_g$ (**Model 4**)

$E[(\text{search volume of keyword})_{gt} | (\text{extent of mobility restriction})_{gt}, (\text{the extent of national covid-19 outbreak})_{gt}] = \theta_M \times (\text{extent of mobility restriction})_{gt} + \theta_A \times (\text{the extent of national covid-19 outbreak})_{gt} + \theta_t + \theta_g$ (**Model 5**)

$E[(\text{extent of mobility restriction})_{gt} | (\text{the extent of national covid-19 outbreak})_{gt}] = \beta_A \times (\text{the extent of national covid-19 outbreak})_{gt} + \beta_t + \beta_g$ (**Model 6**)

Appendix I

Table S2. Coefficient estimations in Model 2-4.

	Estimation	SD	95%CI	P value
γ_A	1.41	0.72	(-0.004, 2.82)	0.051
β_A	0.75	0.28	(0.19, 1.31)	0.008
θ_A	1	0.71	(-0.40, 2.39)	0.16
θ_M	0.55	0.12	(0.32, 0.77)	<0.001