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Distal Fuzzy Dynamical Systems

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Abstract

In this paper the t -distal notion is extended for fuzzy dynamical systems on fuzzy metric spaces. A method for constructing fuzzy metric spaces is studied. The product of t -distal fuzzy dynamical systems is considered. It is proved that: a product of fuzzy dynamical systems is t -distal if and only if its components are t -distal. The persistence of the t -distal property up to a fuzzy factor map is proved.

Keywords: Fuzzy t -distal; Fuzzy dynamical system; Fuzzy factor map; Cartesian product of fuzzy metric spaces.

MSC 2010: 37C70, 54A40

1. Introduction:

In the theory of fuzzy dynamical systems, the fuzzy continuity [Chang (1968), George et al. (1997), George et al. (1994), Grabiec (1998)] and its extensions [Molaei (2004), Rahmat et al. (2008)] are essential means to describe the system behavior. Distal property is the other mathematical property which can describe the behavior of a system without paying attention to the continuity of a system.

In this paper we are going to consider the dynamics on a fuzzy metric space without paying attention to its fuzzy continuity. We are going to define a property which can be a suitable

replacement for fuzzy continuity. By this property we can consider the behavior of fuzzy dynamical systems which may not be fuzzy continuous. In section 2 we recall the definition of fuzzy metric spaces and we present a method for constructing new fuzzy metric spaces. By a fuzzy dynamical system, we mean a bijection on a fuzzy metric space. We introduce the notion of \mathfrak{t} -distal property [Host et al. (2010)] for fuzzy dynamical systems in addition. Intuitively a \mathfrak{t} -distal fuzzy dynamical system as a kind of dynamics that does not let the points of a fuzzy metric space converge to each other up to a fuzzy metric in the level \mathfrak{t} . We prove that two fuzzy dynamical systems on two fuzzy metric spaces are \mathfrak{t} -distal if and only if their product up to a special \mathfrak{t} -norm is \mathfrak{t} -distal. In addition we also introduce the notion of a fuzzy factor map as a kind of conjugate relation and show that the \mathfrak{t} -distal property preserves under a fuzzy factor map.

2. Preliminaries

A binary operation $*:[0,1] \times [0,1] \rightarrow [0,1]$ is a continuous \mathfrak{t} -norm if it satisfies the following conditions:

- 1) $*$ is an associative and commutative operation;
- 2) $a * 1 = a$, for all $a \in [0,1]$;
- 3) $a * b \leq c * d$, whenever $a \leq b, c \leq d$ where $a, b, c, d \in [0,1]$.

A fuzzy metric space $(X, M, *)$ is a triple $(X, M, *)$ where X , is a nonempty set, $*:[0,1] \times [0,1] \rightarrow [0,1]$ is a continuous \mathfrak{t} -norm and $M : X \times X \times (0, \infty) \rightarrow [0,1]$ is a mapping which has the following properties:

For every $x, y, z \in X$ and $t, s > 0$,

- 1) $M(x, y, t) > 0$;
- 2) $M(x, y, t) = 1$ if and only if $x = y$;
- 3) $M(x, y, t) = M(y, x, t)$;
- 4) $M(x, z, t + s) \geq M(x, y, t) * M(y, z, s)$;
- 5) $M(x, y, \cdot) : (0, \infty) \rightarrow [0,1]$ is a continuous map.

Theorem 2.1. If $(X, M, *)$ is a fuzzy metric space then:

- i) For given $a, b \in [0,1]$ $a * b = 1$ implies $a = b = 1$;
- ii) The inequality $t \leq s$ implies $M(x, y, t) \leq M(x, y, s)$, where $x, y \in X$.

Proof:

One can deduce the first property immediately. To prove (ii) put $s = t + r$, then

$$M(x, y, s) = M(x, y, t + r) \geq M(x, y, t) * M(y, y, r) = M(x, y, t) * 1 = M(x, y, t).$$

One can prove the following theorem by direct calculations.

Theorem 2.2. If $*_1, *_2$ are two t -norms, then

$$*_m : [0,1] \times [0,1] \rightarrow [0,1]$$

$$(a, b) \mapsto \min \{a *_1 b, a *_2 b\}$$

is a t -norm.

Theorem 2.3. Let $(X_1, M_1, *_1)$ and $(X_2, M_2, *_2)$ be two fuzzy metric spaces. Assume that the t -norm $*$ has the following additional property:

$$A: a * a \geq 0 \text{ for all } 0 < a,$$

then $X_1 \times X_2$ with the mapping

$$M : (X_1 \times X_2) \times (X_1 \times X_2) \times (0, \infty) \rightarrow [0,1]$$

$$((x_1, x_2), (y_1, y_2), t) \mapsto M_1(x_1, y_1, t) *_m M_2(x_2, y_2, t)$$

is a fuzzy metric space.

Proof:

The property A of the t -norm implies M is a positive function. More precisely let $M((x_1, x_2), (y_1, y_2), t) = 0$ for some $x_1, y_1 \in X_1$, $x_2, y_2 \in X_2$ and $t \in (0, \infty)$. Without loss of generality, we assume that $M_1(x_1, y_1, t) *_1 M_2(x_2, y_2, t) = 0$ and $M_1(x_1, y_1, t) \leq M_2(x_2, y_2, t)$. So

$$M_1(x_1, y_1, t) *_1 M_1(x_1, y_1, t) = 0.$$

Thus, $M_1(x_1, y_1, t) = 0$, which is a contradiction.

$M((x_1, x_2), (y_1, y_2), t) = 1$ if and only if $M_1(x_1, y_1, t) = 1$ and $M_2(x_2, y_2, t) = 1$, which is equivalent to $x_1 = y_1, x_2 = y_2$.

Now we want to prove the triangle inequality.

$$\begin{aligned} M((x_1, x_2), (z_1, z_2), t+s) \\ = \min \{M_1(x_1, z_1, t+s) *_1 M_2(x_2, z_2, t+s), M_1(x_1, z_1, t+s) *_1 M_2(x_2, z_2, t+s)\}. \end{aligned}$$

Since

$$M_i(x_i, z_i, t+s) \geq M_i(x_i, z_i, t) \text{ and } M_i(x_i, z_i, t+s) \geq M_i(x_i, z_i, s), \text{ for } i = 1, 2,$$

there

$$\begin{aligned} M((x_1, x_2), (z_1, z_2), t+s) \\ = \min\{M_1(x_1, z_1, t+s) *_1 M_2(x_2, z_2, t+s), M_1(x_1, z_1, t+s) *_1 M_2(x_2, z_2, t+s)\} \\ \geq \min\{\min\{M_1(x_1, y_1, t) *_1 M_2(x_2, y_2, t), M_1(x_1, y_1, t) *_2 M_2(x_2, y_2, t)\}, \end{aligned}$$

$$\begin{aligned} \min\{M_1(x_1, y_1, s) *_1 M_2(x_2, y_2, s), M_1(x_1, y_1, s) *_2 M_2(x_2, y_2, s)\} \\ \geq (M_1(x_1, y_1, t) *_m M_2(x_2, y_2, t)) *_m (M_1(x_1, y_1, s) *_m M_2(x_2, y_2, s)) \\ = M((x_1, x_2), (y_1, y_2), t) *_m M((x_1, x_2), (y_1, y_2), s). \end{aligned}$$

$(X_1 \times X_2, M, *_m)$, presented in Theorem 2.3 is called the Cartesian product of fuzzy metric spaces X_1, X_2 .

3. The Distal Property for Fuzzy Dynamics

Now let us to introduce the notion of distality for fuzzy dynamical systems. For this purpose we assume that: $(X, T, M, *)$ is a fuzzy dynamical system, i.e., $(X, M, *)$ is a fuzzy metric space and $T: X \rightarrow X$ is a bijection.

Remark: If $(X_1, T_1, M_1, *_1)$, and $(X_2, T_2, M_2, *_2)$ are two fuzzy dynamical systems, then $(X_1 \times X_2, M, *_m)$ is a fuzzy dynamical system.

Definition 3.1. Let $(X, T, M, *)$ be a fuzzy dynamical system. Then a pair $(x, y) \in X \times X$ is called a fuzzy \mathbf{t} -distal pair if

$$\sup_{n \in \mathbb{Z}} \{M(T^n(x), T^n(y), t)\} < 1.$$

$(X, T, M, *)$ is called \mathbf{t} -distal if for a given pair of distinct points $x, y \in X$, and $t \in (0, \infty)$, (x, y) is a fuzzy \mathbf{t} -distal pair.

Theorem 3.1. If $(X_1, M_1, T_1, *_1)$ and $(X_2, M_2, T_2, *_2)$ are two fuzzy dynamical systems, then $(X_1, M_1, T_1, *_1)$ and $(X_2, M_2, T_2, *_2)$ are \mathbf{t} -distal fuzzy dynamical systems if and only if $(X_1 \times X_2, T, M, *_m)$ is a \mathbf{t} -distal fuzzy dynamical system, where $T = T_1 \times T_2$.

Proof:

Let $(X_1, M_1, T_1, *_1)$ and $(X_2, M_2, T_2, *_2)$ are \mathfrak{t} -distal fuzzy dynamical systems and $(x_1, x_2) \neq (y_1, y_2)$, $(x_1, x_2) \in X_1 \times X_2$, $(y_1, y_2) \in X_1 \times X_2$. Without loss of generality let $x_1 \neq x_2$. Then,

$$\begin{aligned} \sup_n \{M(T^n(x_1, x_2), T^n(y_1, y_2), t)\} &= \sup_n \{M((T_1^n(x_1), T_2^n(x_2)), (T_1^n(y_1), T_2^n(y_2)), t)\} \\ &= \sup_n \{M_1((T_1^n(x_1), T_1^n(y_1), t) *_m M_2(T_2^n(x_2), T_2^n(y_2), t))\} \\ &= \sup_n \{\min\{M_1((T_1^n(x_1), T_1^n(y_1), t) *_1 M_2(T_2^n(x_2), T_2^n(y_2), t), \end{aligned}$$

$$\begin{aligned} &M_1((T_1^n(x_1), T_1^n(y_1), t) *_2 M_2(T_2^n(x_2), T_2^n(y_2), t))\} \\ &\leq \min\{\sup_n \{M_1((T_1^n(x_1), T_1^n(y_1), t) *_1 M_2(T_2^n(x_2), T_2^n(y_2), t))\}, \end{aligned}$$

$$\sup_n \{M_1((T_1^n(x_1), T_1^n(y_1), t) *_2 M_2(T_2^n(x_2), T_2^n(y_2), t))\} < 1.$$

The last inequality holds because

$$M_1((T_1^n(x_1), T_1^n(y_1), t) \leq \sup_{n \in \mathbb{Z}} \{M_1((T_1^n(x_1), T_1^n(y_1), t)\}$$

and

$$M_2((T_2^n(x_2), T_2^n(y_2), t) \leq \sup_{n \in \mathbb{Z}} \{M_2((T_2^n(x_2), T_2^n(y_2), t)\}.$$

Thus,

$$\begin{aligned} &M_1((T_1^n(x_1), T_1^n(y_1), t) *_1 M_2(T_2^n(x_2), T_2^n(y_2), t) \\ &\leq \sup_n \{M_1((T_1^n(x_1), T_1^n(y_1), t)\} *_1 \sup_n \{M_2(T_2^n(x_2), T_2^n(y_2), t)\}. \end{aligned}$$

So

$$\begin{aligned} &\sup_n \{M_1((T_1^n(x_1), T_1^n(y_1), t)\} *_1 M_2(T_2^n(x_2), T_2^n(y_2), t)\} \\ &\leq \sup_n \{M_1((T_1^n(x_1), T_1^n(y_1), t)\} *_1 \sup_n \{M_2(T_2^n(x_2), T_2^n(y_2), t)\} < 1 \end{aligned}$$

Thus, $(X_1 \times X_2, T, M, *_m)$ is \mathfrak{t} -distal.

Conversely, let $(X_1 \times X_2, T, M, *_m)$ be a \mathfrak{t} -distal fuzzy dynamical system, $x_1, y_1 \in X_1$, and $x_1 \neq y_1$. Let x_2 be a point in X_2 . Then $(x_1, x_2) \neq (y_1, x_2)$, where $(x_1, x_2), (y_1, x_2) \in X_1 \times X_2$. So $\sup_n \{M((T_1^n(x_1), T_2^n(x_2)), (T_1^n(y_1), T_2^n(x_2)), t)\} < 1$.

Because

$$\begin{aligned} M((T_1^n(x_1), T_2^n(x_2)), (T_1^n(y_1), T_2^n(x_2)), t) &= M_1((T_1^n(x_1), T_1^n(y_1), t) *_m M_2(T_2^n(x_2), T_2^n(x_2), t) \\ &= M_1((T_1^n(x_1), T_1^n(y_1), t) *_m 1 = M_1((T_1^n(x_1), T_1^n(y_1), t). \end{aligned}$$

Hence,

$$\sup\{M_1((T_1^n(x_1), T_1^n(y_1), t))\} < 1.$$

So $(X_1, M_1, T_1, *_1)$ is a t -distal fuzzy dynamical system.

Similarly $(X_2, M_2, T_2, *_2)$ is a t -distal fuzzy dynamical system.

Corollary 3.1. If $\{X_i, i = 1, \dots, k\}$ is a family of fuzzy dynamical systems, then

$$(X_1 \times X_2 \times \dots \times X_k, T_1 \times T_2 \times \dots \times T_k, M, *_m)$$

is t -distal if and only if $(X_i, T_i, M_i, *_i)$ is t -distal for each $1 \leq i \leq k$.

In the above corollary $X_1 \times X_2 \times \dots \times X_k$ means $(X_1 \times X_2 \times \dots \times X_{k-1}) \times X_k$.

Corollary 3.2. If $(X, T, M, *)$ is a fuzzy dynamical system, then the following properties are equivalent:

- i) $(X, T, M, *)$ is a t -distal fuzzy dynamical system,
- ii) $(X^m, T^m, M, *)$ is a t -distal fuzzy dynamical system for all integer m .
- iii) $(X^m, T^m, M, *)$ is a t -distal fuzzy dynamical system for some integer m .

Definition 3.2. Let $(X_1, T_1, M_1, *_1)$ and $(X_2, T_2, M_2, *_2)$ be two fuzzy dynamical systems, an isometry between $(X_1, T_1, M_1, *_1)$ and $(X_2, T_2, M_2, *_2)$ is a mapping $P: X_1 \rightarrow X_2$ such that $M_1(x, y, t) = M_2(P(x), P(y), t)$ for all $x, y \in X_1$ and $t \in (0, \infty)$.

Definition 3.3. A fuzzy factor of a fuzzy dynamical system $(X_1, T_1, M_1, *_1)$ is another fuzzy dynamical system $(X_2, T_2, M_2, *_2)$ such that: there is an onto isometry P from X_1 onto X_2 , so that the following diagram commutes.

$$\begin{array}{ccc} X_1 & \xrightarrow{T_1} & X_1 \\ P \downarrow & & \downarrow P \\ X_2 & \xrightarrow{T_2} & X_2 \end{array}$$

In this case, P is called a fuzzy factor map.

Lemma 3.1. If $P: X_1 \rightarrow X_2$ is a fuzzy factor map, then $P: X_1 \rightarrow X_2$ is a one to one map.

Proof:

If $P(x) = P(y)$, then $M_2(P(x), P(y), t) = 1$. So $M_1(x, y, t) = 1$. Thus, $x = y$.

Now let us to present the main theorem of this section, which prepare a method of congruence for distal fuzzy dynamical systems.

Theorem 3.2. If a fuzzy dynamical system $(X_1, T_1, M_1, *_1)$ has a fuzzy factor $(X_2, T_2, M_2, *_2)$, then $(X_1, T_1, M_1, *_1)$ is a t -distal fuzzy dynamical system if and only if $(X_2, T_2, M_2, *_2)$ is a t -distal fuzzy dynamical system.

Proof:

Let X_1 be a t -distal fuzzy dynamical system and $P: X_1 \rightarrow X_2$ be a factor map. Then for given $y_1, y_2 \in X_2$, if $\sup_n \{M_2(T_2^n(y_1), T_2^n(y_2), t)\} = 1$, then there exists $x_1, x_2 \in X_1$ such that $y_1 = P(x_1), y_2 = P(x_2)$, and $\sup_n \{M_2(T_2^n(P(x_1)), T_2^n(P(x_2)), t)\} = 1$. Hence, $\sup_n \{M_2(P(T_1^n(x_1)), P(T_1^n(x_2)), t)\} = 1$. Thus, $\sup_n \{M_1(T_1^n(x_1), T_1^n(x_2), t)\} = 1$. So, $x_1 = x_2$. Thus, $y_1 = y_2$. Hence $(X_2, T_2, M_2, *_2)$ is a t -distal fuzzy dynamical system.

If $(X_2, T_2, M_2, *_2)$ is a t -distal fuzzy dynamical system, then by replacing P with P^{-1} we can show that $(X_1, T_1, M_1, *_1)$ is a t -distal fuzzy dynamical system.

4. Conclusion

In this paper we have successfully deduced a method for constructing fuzzy metric spaces. We considered the product of t -distal fuzzy dynamical systems. We have also studied the distal property for the product of fuzzy dynamical systems. We proved the persistence of t -distal property up to a fuzzy factor map. The fuzzy factor map is a kind of conjugate relation which leads us to the notion of stability for fuzzy dynamical system. The consideration of fuzzy stability using fuzzy factor map can be a topic for further research.

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