Stroke

Predicting Infarct Core From Computed Tomography Perfusion in Acute Ischemia With Machine Learning
Lessons From the ISLES Challenge

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BACKGROUND AND PURPOSE: The ISLES challenge (Ischemic Stroke Lesion Segmentation) enables globally diverse teams to compete to develop advanced tools for stroke lesion analysis with machine learning. Detection of irreversibly damaged tissue on computed tomography perfusion (CTP) is often necessary to determine eligibility for late-time-window thrombectomy. Therefore, the aim of ISLES-2018 was to segment infarcted tissue on CTP based on diffusion-weighted imaging as a reference standard.

METHODS: The data, from 4 centers, consisted of 103 cases of acute anterior circulation large artery occlusion stroke who underwent diffusion-weighted imaging rapidly after CTP. Diffusion-weighted imaging lesion segmentation was performed manually and acted as a reference standard. The data were separated into 63 cases for training and 40 for testing, upon which quality metrics (dice score coefficient, Hausdorff distance, absolute lesion volume difference, etc) were computed to rank methods based on their overall performance.

RESULTS: Twenty-four different teams participated in the challenge. Median time to CTP was 185 minutes (interquartile range, 180–238), the time between CTP and magnetic resonance imaging was 36 minutes (interquartile range, 25–79), and the median infarct lesion size was 15.2 mL (interquartile range, 5.7–45). The best performance for Dice score coefficient and absolute volume difference were 0.51 and 10.1 mL, respectively, from different teams. Based on the ranking criteria, the top team's algorithm demonstrated for average Dice score coefficient and average absolute volume difference 0.51 and 10.2 mL, respectively, outperforming the conventional threshold-based method (dice score coefficient, 0.3; volume difference, 15.3). Diverse algorithms were used, almost all based on deep learning, with top-ranked approaches making use of the raw perfusion data as well as methods to synthetically generate complementary information to boost prediction performance.

CONCLUSIONS: Machine learning methods may predict infarcted tissue from CTP with improved accuracy compared with threshold-based methods used in clinical routine. This dataset will remain public and can be used to test improvement in algorithms over time.

Key Words: decision-making ■ machine learning ■ reperfusion ■ stroke ■ tissue survival ■ triage

Nonstandard Abbreviations and Acronyms

CBF	cerebral blood flow
CT	computed tomography
CTP	computed tomography perfusion
DSC	dice score coefficient
DWI	diffusion-weighted imaging
HD	Hausdorff distance
IQR	interquartile range
ISLES	Ischemic Stroke Lesion Segmentation
MRI	magnetic resonance imaging
VD	volume difference

The DEFUSE 3 (Endovascular Therapy Following Imaging Evaluation for Ischemic Stroke 3) and DAWN (Clinical Mismatch in the Triage of Wake Up and Late Presenting Strokes Undergoing Neurointervention With Trevo) trials demonstrated that endovascular treatment is highly efficacious in patients seen 6 to 24 hours after onset.[1,2] Both trials selected patients predominantly using computed tomography (CT) perfusion (CTP), and as a consequence, CTP-based selection of patients in the late time window is now in the American Heart Association guidelines.[3] These events have spawned a surge in the adoption of CTP in centers worldwide. The dynamic CTP images acquired by the scanner need postprocessing to obtain estimates of the volumes of the infarct core and hypoperfused regions. These volumes are then used to determine suitability for treatment. Although current threshold-based CTP algorithms[4–6] are capable of identifying patients with a high response to treatment,[7] correspondence of the CTP-derived measurements to reference standard diffusion-weighted imaging (DWI) lesions is still suboptimal.[4] Given the inherent complexity of acute ischemic stroke lesion development, data-driven machine learning methods could be used to improve the estimate of core infarcted tissue.

The ISLES challenge (Ischemic Stroke Lesion Segmentation) was created in 2015 to encourage researchers around the world to develop advanced tools for stroke lesion analysis.[8] ISLES publicly provides standardized, high-quality datasets to overcome the limitations of varying dataset sizes and heterogeneity in postprocessing, making it possible to compare novel approaches in a fair way.[9,10] An increasing number of teams have participated in this challenge, which is annually organized in conjunction with the international conference on Medical Image Computing and Computer Assisted Intervention (MICCAI). Over time, there has been intense development in the algorithms used, starting from classical machine learning tools and now focusing almost exclusively on deep learning techniques.[9]

Based on the development of clinical trials and community feedback, the aim of the ISLES 2018 was to predict the infarction core based on CTP imaging from acute ischemic stroke patients, using DWI-based manual segmentation from magnetic resonance imaging (MRI) acquired shortly after. This cohort was initially reported on by Cereda et al[4] using threshold-based method. This report summarizes the logistics of the challenge, its results in comparison with a commercially available threshold-based software for CTP postprocessing, and the methods used by teams along with the results of the top-performing teams.

METHODS

We point readers toward the publicly available data set, which since the challenge in 2018 has already been used in other studies,[11,12] to encourage more rapid innovation. The data can be requested at https://www.smir.ch/ISLES/Start2018.

Patients and Image Acquisition

The patients were part of 2 prospective ischemic stroke trials[13,14] diagnosed with acute large artery occlusive ischemic stroke without signs of hemorrhage ≤8 hours after last seen normal. Ethics approval was obtained from the local institutional review board at each center. MRI was acquired within 3 hours of CTP. DWI was coregistered to the CTP acquisition by aligning both to the Montreal Neurological Institute atlas. The cases were previously reported on by Cereda et al[4] but exclusively using a threshold-based method and without the use of training/validation splitting. Unlike the Cereda study, tissue regions were not excluded if there was evidence of partial reperfusion (normally perfused DWI lesions with time to maximum ≤4 s on the CTP study), with the goal of making the challenge generalizable to real-world conditions.

The goal of the challenge was to accurately segment infarct core from CTP, which was defined by manual segmentation of DWI on subsequent MRI. No treatment occurred between the CTP and DWI. The segmentations, which acted as the reference standard for the challenge, were manually delineated by a single investigator, a stroke neurologist with >10 years of experience, and then subjected to group review until acceptance of the delineated lesion by the other group members. All investigators were blinded to baseline perfusion and all other imaging.

In total, datasets from 103 patients presenting with acute large artery occlusion anterior circulation ischemic stroke from 3 US centers and 1 Australian center were used in the challenge (Table 1). The CTP images were acquired from all 4 major manufacturers (GE, Philips, Siemens, and Toshiba). More details are available in the study by Cereda et al.[4]

Training and Testing Data Provided

The data were split into 2 groups—training group and testing group—randomized by vendor strata to ensure a balance between vendors in the two sets. To test the robustness of the algorithms, cases with no lesions were included in the testing set. To include a wide range of possible lesions, 40 patients were included in the test set for the challenge. In this group, the reference standard lesion segmentations were withheld from the teams, and the performance of the algorithm was determined by the organizing committee using predetermined criteria (see below). The remaining 63 cases comprised the training

Table 1. Demographics of the Patient Population

Patient criteria	
Mean age, y	68 (SD, 14)
Median baseline NIHSS	16 (IQR, 11–19)
Median time from onset to CT, min	185 (IQR, 180–238)
Median time between completion of CT and start of MRI, min	36 (IQR, 25–79; range, 15–181)
Scanners and number of patients in training group	GE: 16
	Philips: 32
	Siemens: 2
	Toshiba: 13
Scanners and number of patients in testing group	GE: 13
	Philips: 20
	Siemens: 1
	Toshiba: 6

CT indicates computed tomography; IQR, interquartile range; MRI, magnetic resonance imaging; and NIHSS, National Institutes of Health Stroke Scale.

set, for which the competitors received the CTP images, DWI images, and DWI-based segmentations, which allowed them to train their models.

Teams were given the following types of training data: (1) motion-corrected dynamic CTP source data, which had been resampled to a standardized 1-s temporal resolution; (2) postprocessed perfusion maps, that is, cerebral blood flow (CBF), cerebral blood volume, mean transit time, and time to maximum, calculated by conventional thresholding method (RAPID; iSchemaview, Menlo Park, CA). No threshold-based lesion segmentations were provided; (3) DWI lesion segmentation in binary form and (4) the DWI images themselves. Of note, noncontrast enhanced CT scans were not provided to the teams. For the test set, only the CTP raw data and the postprocessed maps were provided (ie, no segmentations or DWI images). All images were provided at 256×256 in-plane resolution and native slice thickness with one exception: Toshiba Aquilion One 320 slice data (0.5-mm native resolution) was downsampled to 10-mm thickness by volume averaging sets of 20 slices. CTP covered from 2.4 to 16 cm in the axial direction depending on hardware and prediction of the lesion for each case was performed only within this image volume.

Challenge

Organization of the data and assessment of the algorithms were the responsibility of an international team of experts in artificial intelligence, neurology, and neuroradiology from Belgium, Germany, Switzerland, the United Kingdom, and the United States, who did not participate in the challenge.

Information about the challenge, its background, and aims were published online on the official website of the challenge (http://www.isles-challenge.org) that included a link to the training set, which was used to validate and optimize the method used by each participant. Shortly before the 2018 Medical Image Computing and Computer Assisted Intervention conference, the raw CTP data from the test sets were released. The teams were asked to run their algorithms and upload their segmentation results along with the submission of a short abstract describing their algorithmic approach. Finally, the

results from each participant were compared with the reference standard manual infarct segmentations, and the teams were ranked using predetermined evaluation metrics.

Evaluation Metrics

The following metrics were used for evaluation: the Dice score coefficient (DSC), Hausdorff distance (HD), average and absolute lesion volume difference (VD), precision, recall, and average symmetrical surface distance. DSC is a measure of overlap between the reference standard on DWI and the predicted lesion from CTP, hence it tests the resemblance between the two lesions, while HD calculates the largest distance between the two contours representing the prediction lesion and the reference standard on DWI. For more details, the reader is pointed to Winzeck et al[9] and Maier et al.[8] The same metrics were assessed using the suggested parameter (relative CBF, <0.38)[4] from the threshold-based method, using the relative CBF core as the predicted infarct core segmentation.

A case-wise approach was used to calculate ranks for each team, following the rationale of Maier et al[8] as patient cases can have different degrees of complexity in predicting stroke outcome. DSC was the most important as it combines precision and sensitivity. First, DSC, HD, and average symmetrical surface distance were calculated for each case, for each team, with high DSC and low HD resulting in a high rank for an individual case. The mean of these ranks per case provided a case-specific rank. Calculating the average of all case-specific ranks through all cases for each team resulted in the team's final overall rank.

Statistical Analysis

For each team and for the threshold-based method, the mean and SD of DSC, mean absolute VD, precision, and recall were calculated. Furthermore, the HD and average symmetrical surface distance from each case were compared to define the best case from each team. Wilcoxon signed-rank test (for nonuniformly distributed data) was used to compare results among teams. Furthermore, based on DSC and absolute VD, the best- and worst-performing test cases from the top 5 teams were defined and analyzed according to lesion volume and lesion location.

RESULTS

Challenge Characteristics

Demographics of the patients and scanners included in the study can be found in Table 1. Median time from last seen normal to CTP was 185 minutes (interquartile range [IQR], 180–238). Time between completion of CT and the start of MRI ranged from 15 to 181 minutes (median, 36 minutes). Lesion volume ranged from 0 to 309 mL (average, 32 mL). In 6 patients, there was no diffusion lesion present (ie, zero core volume).

Teams from 15 different countries, as well as multinational collaboration teams, were registered. In total, 24 teams affiliated to research institutes, university hospitals, and industry participated and submitted results on all 40 test cases (Table 2).

Table 2. Investigator, Title of the Submitted Abstracts, and Affiliation of the Participating Teams According to the Overall Ranking

Team	Entrant	Title	Institution
1	Song	3D Multi-Scale U-Net With Atrous Convolution for Ischemic Stroke Lesion Segmentation	Sensetime Research, China
2	Pengbo et al	Stroke Lesion Segmentation With 2D Convolutional Neutral Network and Novel Loss Function	Beijing University of Technology, China
3	Chen et al	Ensembles of Modalities Fused Model for Ischemic Stroke Lesion Segmentation	Tencent Jarvis Lab, Shenzhen, China
4	Huang et al	StrokeNet: 3D Local Refinement Network for Ischemic Stroke Lesion Segmentation	Malong Technologies, China
5	Clerigues et al	Ensemble of Convolutional Neural Networks for Acute Stroke Anatomy Differentiation	VICOROB Institute, University of Girona, Spain
6	Pinheiro et al	V-Net and U-Net for Ischemic Stroke Lesion Segmentation in a Small Dataset of Perfusion Data	School of Electrical and Computer Engineering, University of Campinas, Brazil
7	Liang et al	A Mix-Weight Modality Densely UNet for Ischemic Stroke Lesion Segmentation	School of Computer Science and Engineering, Central South University, China
8	Pisov et al	Fine-Tuning U-Net for Ischemic Stroke Lesion Segmentation	Skolkovo Institute of Science and Technology, Russia
9	Khened et al	Fully Automatic Segmentation for Ischemic Stroke Using CT Perfusion Maps	Department of Engineering Design, Indian Institute of Technology Madras, India
10	Hashemi et al	Automatic Segmentation of Ischemic Stroke Lesion Core Based on CT Perfusion Using a Deep Fully Convolutional Densely Connected Network	Department of Radiology, Boston Children's Hospital, Harvard Medical School, United States
11	Werner et al	Defining a Baseline for ISLES 2018: Applying Good Old Random Forest and/or Common Encoder-Decoder-Style CNNs	Department of Computational Neuroscience, University Medical Center Hamburg-Eppendorf, DAISYlab Forschungszentrum Medizintechnik, Hamburg, Germany
12	Zhuo et al	Multi-Modal Fusion Network on Ischemic Stroke Lesion Segmentation	Tencent Jarvis Lab, Shenzhen, China
13	Su et al	Multi-Scale Voxresnet Network	Sun Yat-sen University, Guangzhou, China
14	Dolz et al	Dense Multi-Path U-Net for Ischemic Stroke Lesion Segmentation in Multiple Image Modalities	ETS Montreal, Canada
15	Islam et al	Ischemic Stroke Lesion Segmentation Using Adversarial Network	Imperial College London, BioMedIA, United Kingdom
			Department of Biomedical Engineering, National University of Singapore
16	Xu et al	Ischemic Stroke Lesion Segmentation in a Few Seconds Using Fully Convolutional Network and Transfer Learning	Huazhong University of Science and Technology, China
17	Miyamoto et al	Ensemble Learning With Generative Adversarial Data Augmentation for Ischemic Stroke Lesion Segmentation	Research and Development Department, LPixel, Inc, Tokyo, Japan
18	Bertels et al	Contra-Lateral Information CNN for Core Lesion Segmentation in Acute Stroke	KU Leuven, Belgium
19	Tureckova et al	ISLES Challenge: U-Shaped Convolutional Neural Network for 3D Stroke Lesion Segmentation	Faculty of Applied Informatics, Tomas Bata University, Czech Republic
			University of Innsbruck, Austria
20	Abulnaga et al	Stroke Lesion Segmentation in Perfusion Images Using a Fully Convolutional Neural Network	Massachusetts Institute of Technology, the United States
			Philips Research North America, MA, the United States
21	Stimpel et al	Multi-Encoding U-Net for Stroke Lesion Segmentation in CT Perfusion Data	Pattern Recognition Lab, Friedrich-Alexander University Erlangen-Nuremberg, Germany
22	Monteiro et al	Modified 2D VNet for Prediction of Stroke Lesion Outcome Segmentation	University of Lisbon, Portugal
23	Wang et al	Intracranial Ischemic Lesion Segmentation via 3D Deconvolutional Network Based on the U-Net Architecture	Department of Brain and Cognitive Engineering, Korea University, Seoul, South Korea
24	Yang et al	Volumetric Adversarial Training for Ischemic Stroke Lesion Segmentation	CuraCloud Corporation, Seattle, the United States

More details in the Data Supplement (Abstracts Submitted to the Challenge).

Best-Performing Teams for Overall Performance

Based on the mean ranking of their performance on DSC, HD, and average symmetrical surface distance, the winner was Song from East China Normal University (team No. 1). He used a deep learning generative adversarial network algorithm in which the CTP data (raw and postprocessed maps) were used to create a pseudo-DWI image based on a U-net architecture. This pseudo-DWI image was compared with the true DWI image using a discriminator that attempted to determine whether the

image presented was the real or pseudo-DWI. The features that were useful for making the distinction were fed back into the generator to improve its ability to predict the pseudo-DWI lesion. Once trained, the pseudo-DWI image was segmented using a separate deep learning algorithm that had been trained on a large number of self-segmented DWI scans.

Team No. 2 (Pengbo et al; Beijing University of Technology) used a convolutional neural network utilizing a 2-dimensional U-net with residual connection as the model backbone. To balance the gradients of the positive and negative areas in the training phase and highlight the stroke lesions, they proposed a novel loss function that contains a weight cross-entropy loss and generalized Dice score loss. Based on experiments during the training phase, this hybrid loss was found to be more stable.

Team No. 3 (Chen et al; Youtu Laboratory, Tencent) used a 2.5-dimensional framework, based on an ensemble of networks, including U-nets, to extract and fuse information from different modalities.

For more details about methods used by each team, please see the Data Supplement or refer to the proceeding of the challenge.[15]

Best-Performing Teams for Specific Metrics

The top-ranking team (team No. 1; Song) achieved an average DSC of 0.51±0.31 (mean±SD). Several teams achieved similar performance (Table 3). This result is superior to the DSC achieved with a traditional threshold-based CBF method (0.34±0.29; *P*<0.001). The top-ranking team for average absolute lesion VD was team No. 2, Pengbo et al (10.0±10.5 mL). Their results on the absolute volume metric compared favorably to the threshold-based CBF method (15.3±16.4 mL; *P*=0.002). Figure 1 is a case example showing predictions for infarct core for each of the top 3 teams along with the conventional threshold-based method. The results of all teams compared with the results obtained with a threshold-based CBF method are shown in Table 3 and Figures 2 and 3.

Best- and Worst-Performing Cases

From the top 5 teams, 8 cases were identified as the best-performing cases, and 9 cases as the worst-performing cases, based on DSC. Twenty cases were identified as the best cases and 13 cases were identified as the worst cases based on absolute VD. Due to the overlap between teams, the number of best and worst cases was varying in each category.

Dice Score Coefficient

The median DWI volume for the best-performing cases was 72.8 mL (IQR, 42.45–103.1), and the median dice

was 0.86 (IQR, 0.81–0.91); all cases were M1 lesions. The median DWI volume for the worst-performing cases was 6.7 mL (IQR, 2.8–9), and the median dice was 0.28 (IQR, 0.2–0.37; Figure I in the Data Supplement). In these cases, 66.7% were M1 lesions and 33.3% were M2.

Absolute VD

The median DWI volume from the best-performing cases was 7.2 mL (IQR, 3–20.7), and the median absolute VD was 2.6 mL (IQR, 0.64–5.06). In these cases, 70% were M1 lesions, 15% were M2, and 15% showed no occlusion. The median DWI volume from the worst-performing cases was 41.3 mL (IQR, 6.7–76.4), and the median absolute VD was 26.41 mL (IQR, 9.36–36.87; Figure II in the Data Supplement). In these cases, 92.3% were M1 lesions, 7.7% were M2, and 15.4% were P1.

DISCUSSION

In this article, we describe the structure and rationale of the concluded ISLES 2018 stroke segmentation challenge. Many diverse teams throughout the world, in industry and academia, participated. The top teams demonstrated significantly better performance than a CBF-based threshold method (relative CBF, <0.38) that has previously been shown to best match DWI volume.[4] The top teams almost exclusively incorporated deep learning methods using convolution neural networks, with a wide variety of network architectures, input data, and training methods.

Using machine learning algorithms to detect and segment abnormal imaging findings, including ischemic lesions, is an active research field that has been growing in recent years.[16–18] However, building a satisfactory algorithm is an active process, requiring continuous improvement and testing. For this reason, having a well-characterized data set upon which to test algorithms is critical, since it enables the identification of improved performance. Furthermore, having a standardized data set enables researchers to directly test their algorithms and compare them to the results of other researchers, thus accelerating progress on the most promising methods.

For this reason, the ISLES challenge was initiated in 2015 to provide a platform with processed data that allows a continuous validation of different algorithms in a fair manner.[10] The images provided are already preprocessed and annotated by experts in the field, so researchers can apply their method directly to the given data, generating results that are not affected by preprocessing steps or processing software. The datasets from the 2018 challenge and the previous years are available on the challenge website (http://www.isles-challenge.org) to allow further evaluation and testing of new algorithms. During the last several years of the challenge, there has been obvious progress in the algorithms used, starting from classical machine learning

Table 3. Results of Each Team Obtained at the Time of Challenge Submission and the Results Obtained From a Threshold-Based Method, Using Relative Cerebral Blood Flow <0.38

Rank	Team	Mean DSC (±SD)	Mean absolute VD (mL±SD)	Mean precision (±SD)	Mean recall (±SD)	Best HD obtained from a single case, mm	Best ASSD obtained from a single case, mm
1	Song	0.51±0.31	10.24±9.94	0.55±0.36	0.55±0.34	5.68	0.19
2	Pengbo et al	0.49±0.31	10.08±10.58	0.56±0.37	0.53±0.33	7.02	0.15
3	Chen et al	0.48±0.32	10.59±13.16	0.59±0.38	0.46±0.33	5.39	0.17
4	Huang et al	0.47±0.31	11.14±12.74	0.56±0.37	0.49±0.33	7.24	0.15
5	Clerigues et al	0.44±0.31	14.17±14.08	0.45±0.34	0.56±0.34	9.98	0.29
6	Pinheiro et al	0.43±0.32	14.69±16.83	0.50±0.38	0.49±0.34	5.75	0.24
7	Liang et al	0.43±0.3	12.49±15.92	0.54±0.37	0.41±0.3	7.34	0.43
8	Pisov et al	0.43±0.31	13.01±17.01	0.62±0.39	0.40±0.31	7.34	0.18
9	Khened et al	0.43±0.31	17.04±22.29	0.52±0.38	0.44±0.33	5.46	0.29
10	Hashemi et al	0.42±0.31	14.30±15.41	0.48±0.38	0.51±0.35	9.92	0.25
11	Werner et al	0.42±0.3	14.70±14.59	0.52±0.39	0.45±0.32	10.51	0.29
12	Zhuo et al	0.42±0.3	16.68±16.70	0.41±0.33	0.52±0.33	12.00	0.33
13	Su et al	0.40±0.29	23.20±19.72	0.38±0.32	0.58±0.32	12.30	0.45
14	Dolz et al	0.40±0.31	11.86±13.42	0.52±0.36	0.37±0.31	6.35	0.35
15	Islam et al	0.39±0.33	10.90±15.72	0.55±0.4	0.36±0.33	7.78	0.18
16	Xu et al	0.39±0.3	13.23±13.27	0.46±0.36	0.42±0.32	6.35	0.28
17	Miyamoto et al	0.39±0.28	17.02±23.82	0.57±0.41	0.35±0.28	7.02	0.53
18	Bertels et al	0.38±0.3	17.22±16.88	0.47±0.35	0.44±0.34	7.87	0.55
19	Tureckova et al	0.38±0.27	20.66±27.08	0.48±0.38	0.41±0.3	10.69	0.32
20	Abulnaga et al	0.37±0.31	15.41±20.48	0.53±0.4	0.37±0.32	10.43	0.47
21	Stimpel et al	0.36±0.28	16.71±25.17	0.53±0.4	0.34±0.29	7.19	0.50
22	Monteiro et al	0.34±0.3	14.79±16.75	0.53±0.4	0.30±0.29	9.38	0.55
23	Wang et al	0.23±0.25	24.50±44.18	0.44±0.41	0.19±0.23	9.50	0.72
24	Yang et al	0.01±0.01	200.95±211.75	0.00±0.01	0.03±0.12	135.97	35.46
	Threshold-based method	0.34±0.29	15.29±16.39	0.46±0.41	0.32±0.26	11.51	0.43

ASSD indicates average symmetrical surface distance; DSC, dice score coefficient; HD, Hausdorff distance; and VD, volume difference.

tools to advanced deep learning techniques. Lessons learned from previous ISLES challenges were summarized in the previously published articles (Maier et al[8] and Winzeck et al[9]).

CT is increasingly being used for acute stroke triage, given its lower cost, widespread availability, and only few exclusion criteria. Core infarct size is an important predictor of outcome in acute stroke and represents the minimal lesion that can be expected after thrombectomy. Its relationship to at-risk or penumbral tissue has been used as entry criteria for recent thrombectomy trials in the late time window (6–24 hours).[1] However, one of the disadvantages of CT, in contrast to MRI, is the challenge of accurately defining infarction core.[19] Different criteria have been proposed over the years to estimate core from CTP data, with a threshold of relative CBF <0.38 of normal tissue being the suggested metric in the software used in this study.[4] In contrast, DWI is generally recognized as a better estimate of irreversibly damaged tissue and serves as a marker of infarct core for MRI studies. DWI-based signal hyperintensity was used

in this study as a reference standard for infarct core, which was to be predicted from CTP data acquired at a median time difference of 36 minutes. Recent reports of trained artificial intelligence algorithms show that they can perform well on narrow sets of input data but fail when exposed to real-world conditions.[20] For this reason, the cases included in this challenge were chosen to be widely representative, from multiple institutions and scanned on all 4 major CT manufacturers. We additionally included cases in which there was potential reperfusion of infarcted tissue—a known challenge for CTP prediction. Of note, these regions were excluded from the earlier study of this cohort using threshold-based method. Thus, the structure of the challenge will reward algorithms that can generalize well to different case characteristics, which is critical for the clinical use of artificial intelligence methods.

Some of the teams showed innovation in their algorithm designs. The top team combined the provided raw perfusion data to the processed perfusion maps in an integrated network to boost their model and
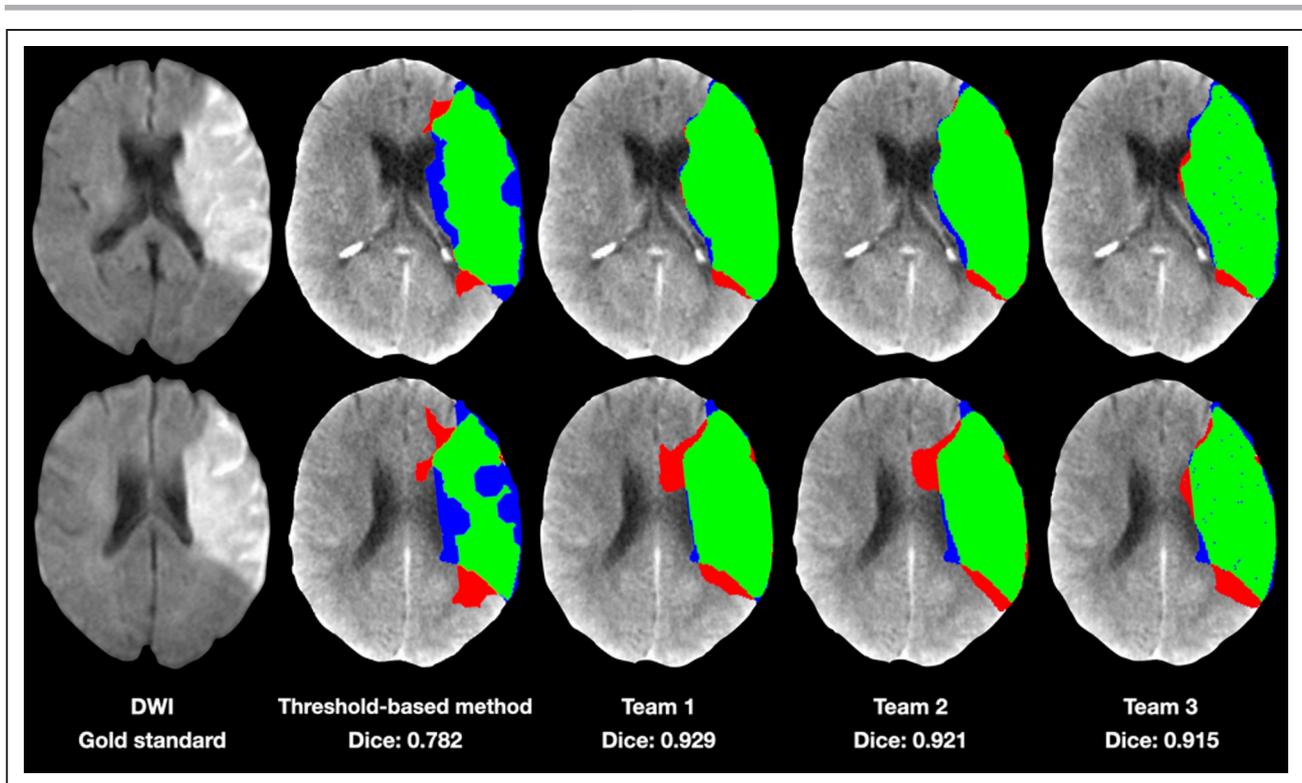
Figure 1. Case example illustrating a patient with a large left middle cerebral artery infarction as seen on the dice score coefficient (DWI; far left).
The estimated infarction core by threshold-based method and by the three top teams is highlighted. Green, true positive; blue, false negative; and red, false positive. The results of team 3 show multiple little blue dots (low probability), possibly due to artifacts resulting from a lack of regularization of the network or postprocessing.

improve the prediction of the DWI lesion, as it has also been shown in the study by Pinto et al for the stroke prediction from MRI data.[21] Despite the majority of approaches using neural networks of similar architectures, the performance variations indicate the difficulty of designing a successful machine learning algorithm for stroke lesion segmentation.

Performance differences among teams were observed (Table 3), alluding to potential overfitting and lack of regularization, stemming from the low sample size of the training dataset. Second, we observed that solutions having strong heuristics for postprocessing routines (eg, hard-coded elimination of a number of isolated objects) were also outperformed by solutions where regularization was performed implicitly via standard deep learning solutions, such as data augmentation and dropout.

Possible causes for poor algorithm performance include reperfusion of dead tissue, imperfect registration between the DWI and CTP which can have a large impact on the overlap between very small lesions and make it impossible to achieve a high DSC for such cases.

Teams varied in performance in each metric, for example, DSC was higher in team 1, but team 2 showed better VD, as DSC measures the relative overlap between the predicted lesion and the reference standard, whereas the VD is not influenced by the amount of overlap. Hence these metrics do not measure the same feature, so they do not correlate perfectly. In fact, there is a trade-off between these two metrics, that is, to obtain an optimal DSC, it is often better to allow for oversegmentation.[22]

The case-based analysis of the best- and worst-performing cases from the top 5 teams shows that the bigger the lesion, the better the DSC but the larger the absolute VD. There was no apparent correlation between performance and the anatomic or territorial location of the lesion.

Previous works aimed to use machine learning for stroke lesion segmentation, mostly focusing on MRI studies, giving the advantage of higher tissue contrast and DWI as a sensitive parameter for infarction core. In this study, we show the performance of deep learning techniques on CTP with MRI as a reference standard. We also show the shift toward more advanced deep learning techniques such as generative adversarial network. Also, the value of using raw perfusion data (not only the postprocessed perfusion maps) to reach a more accurate prediction is demonstrated.

The results of this challenge show the advantages of applying deep learning in stroke patients. The algorithms from top teams compared favorably with the state-of-the-art CTP postprocessing tool used in clinical practice, showing more accurate prediction of infarction core, which allows for better decisions regarding use of invasive therapy. Therefore, our results support the necessity
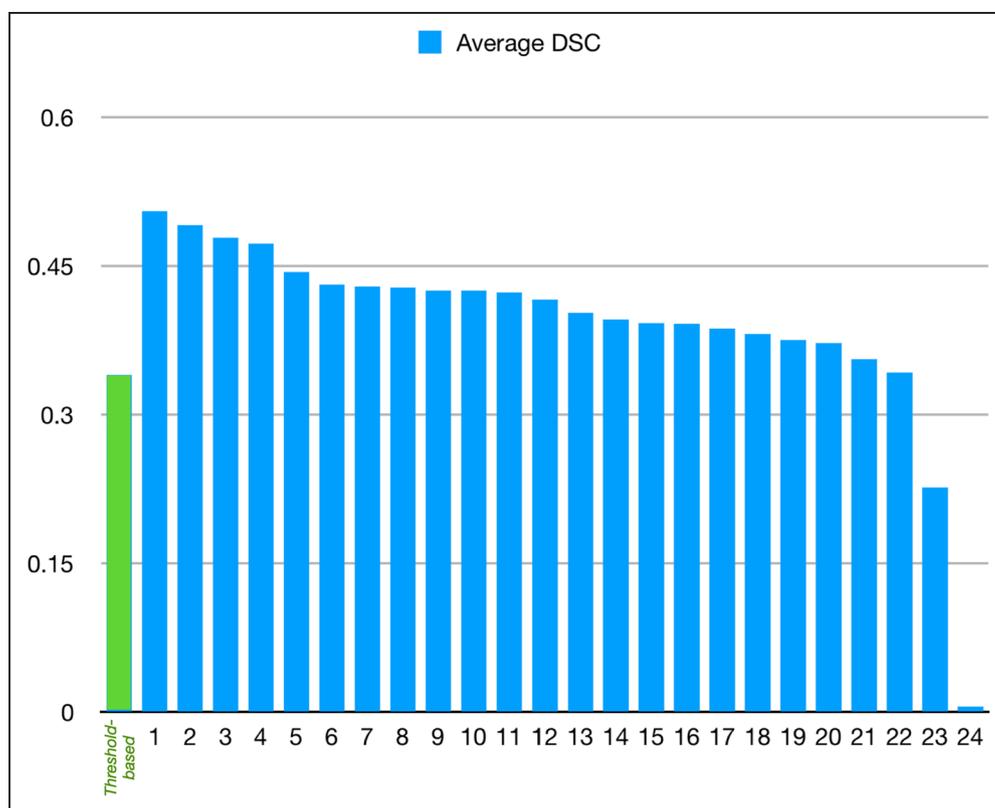
Figure 2. **Chart showing the average of dice score coefficient (DSC) for each team compared with the results obtained from the threshold-based method.**

of shifting the conventional stroke workflow toward the integration of modern computational algorithms in decision-making, which will improve stroke care and patient management.

There were several limitations to our study. Due to the strict criteria of including patients with CTP and DWI within 3 hours of each other, the dataset is relatively small. This points out the need for different centers to collaborate and share data to improve the ability of researchers to improve their algorithms. Also, the reference standard was defined as diffusion restriction on MRI, which was always performed after CTP. This may mean that the predictions do not exactly match the infarct core at the time of the CTP but rather may reflect some degree of lesion growth. Of course, it was not technically possible to acquire both modalities at the exact same time, and the retrospective nature of the dataset precluded randomization of CTP and MRI. Another potential limitation is that of spontaneous partial reperfusion, which would alter the CTP lesion severity and possibly introduce some degree of DWI lesion reversal that would render the CTP-to-DWI relationship much less predictable.[23,24] Another limitation is the coverage on the z axis. The ISLES 2018 datasets were acquired in the period 2004 to 2012, and some scans were, therefore, acquired on older systems. While there have not been any major breakthroughs in improved contrast-to-noise of CTP,

scanners generally have increased in terms of brain coverage along the patient z axis of CTP over the last 20 years. Seventy-six of 103 datasets were under 8-cm coverage along the patient z axis, whereas with modern scanners with wider detector arrays, at least 8 cm is usually imaged. One could speculate that larger spatial coverage could provide more context for the infarct prediction and potentially improve it. The limited spatial coverage will also result in lower absolute volumetric error than what would have been seen in whole-brain studies due to the smaller image volume acquired. So absolute volumetric error is biased by low coverage in some cases and not likely to indicate performance in a dataset with larger spatial coverage, but it still serves to compare between participating groups. Finally, the noncontrast CT data were not provided to the teams despite being typically available in the acute stroke setting. The presence of noncontrast CT hypodensity contains useful information about infarct core and might have helped the teams with their predictions. However, some of this information is present in the baseline (ie, prebolus arrival) CTP raw images, and some of the top-performing teams took advantage of this. Also, we did not include CT angiography data, given the wide variety of CT angiography methods in the cases. Consideration will be given to including coregistered noncontrast CT and CT angiography in future challenges.
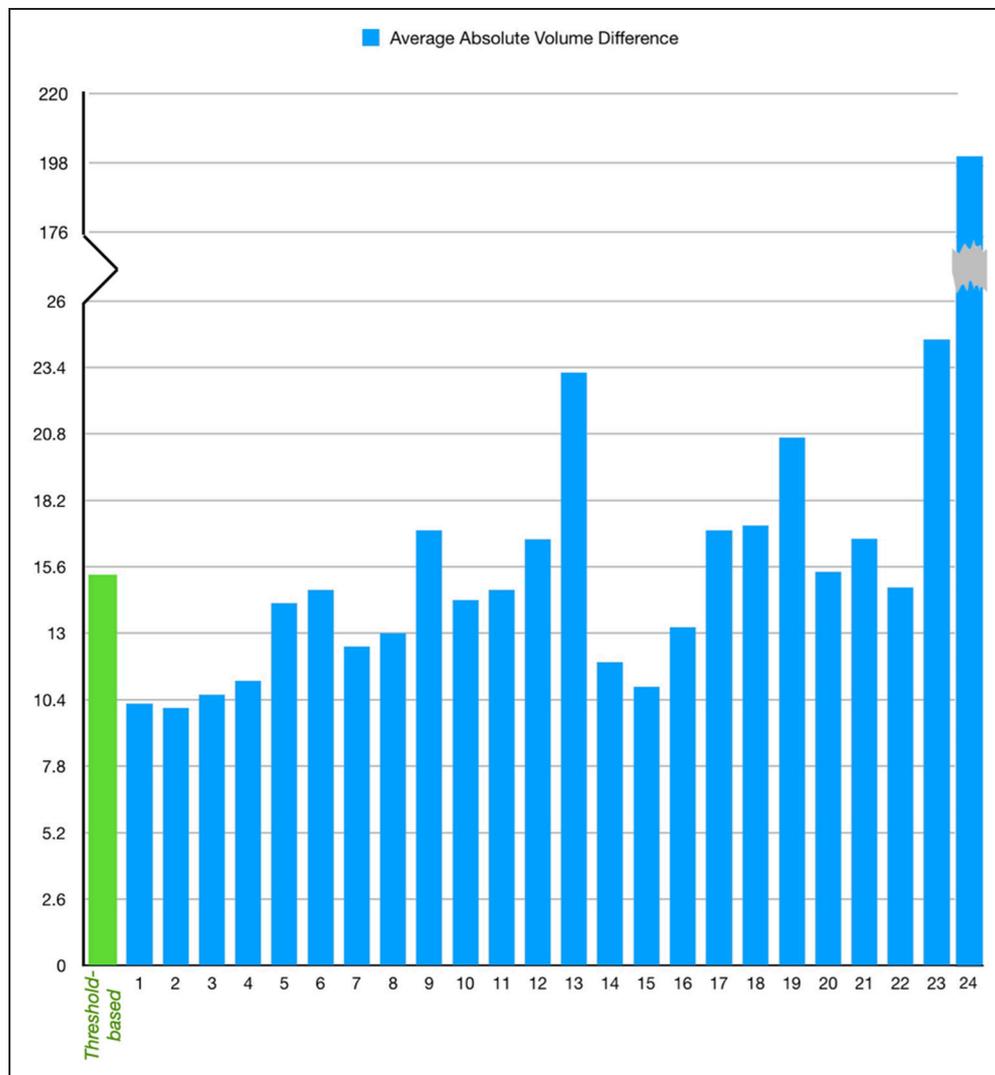
Figure 3. The average absolute volume difference between reference standard and automatically predicted infarction volume from the 24 teams compared with the threshold-based method.

CONCLUSIONS

This report summarizes the results of the ISLES 2018 challenge to predict core infarct lesions using CTP in acute large artery occlusive stroke. The top-ranked teams used various deep learning convolutional neural network approaches, including some state-of-the-art methods such as generative adversarial networks. The performance of the top groups was significantly better than threshold-dependent, rules-based models. The ISLES 2018 challenge data remain publicly available for researchers to improve methods for automatically segmenting infarct core on CTP.

ARTICLE INFORMATION

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Supplemental Materials

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Abstracts Submitted to the Challenge
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