

The influence of partial occlusion on shape recognition

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Background



“...information is concentrated along contours at those points on a contour at which its direction changes most rapidly...”

“Common objects may be represented with great economy, and fairly striking fidelity, by copying the points at which their contours change direction maximally, and then connecting these points appropriately with a straightedge.”



Previous work

SCIENTIFIC REPORTS



OPEN

Shape recognition: convexities, concavities and things in between

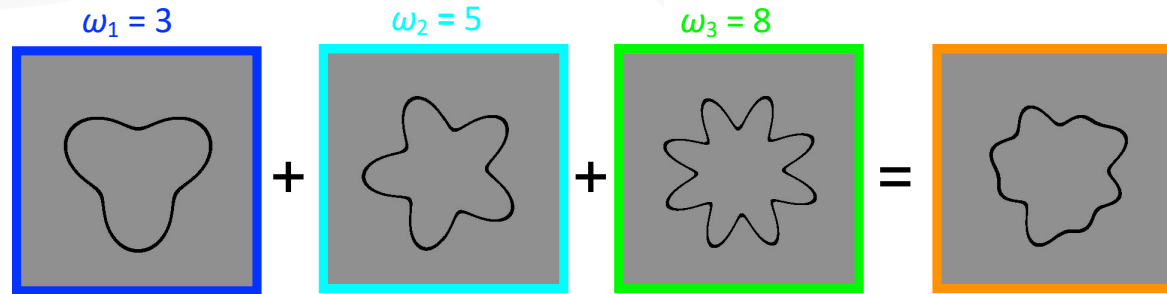
Gunnar Schmidtman, Ben J. Jennings & Frederick A. A. Kingdom



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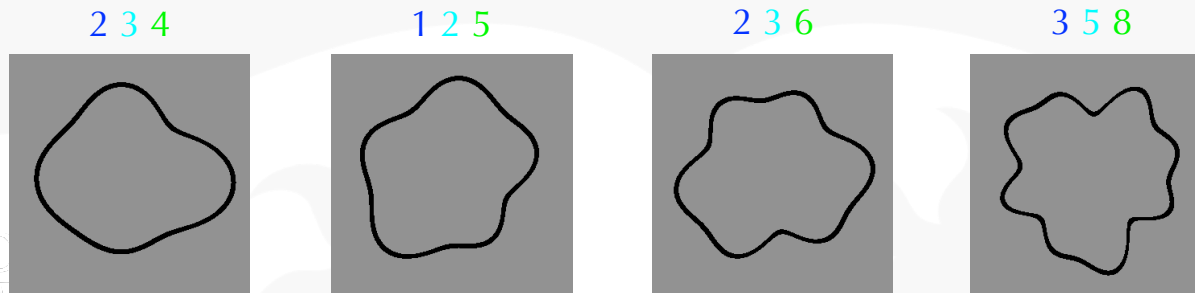
Stimuli

compound radial frequency patterns

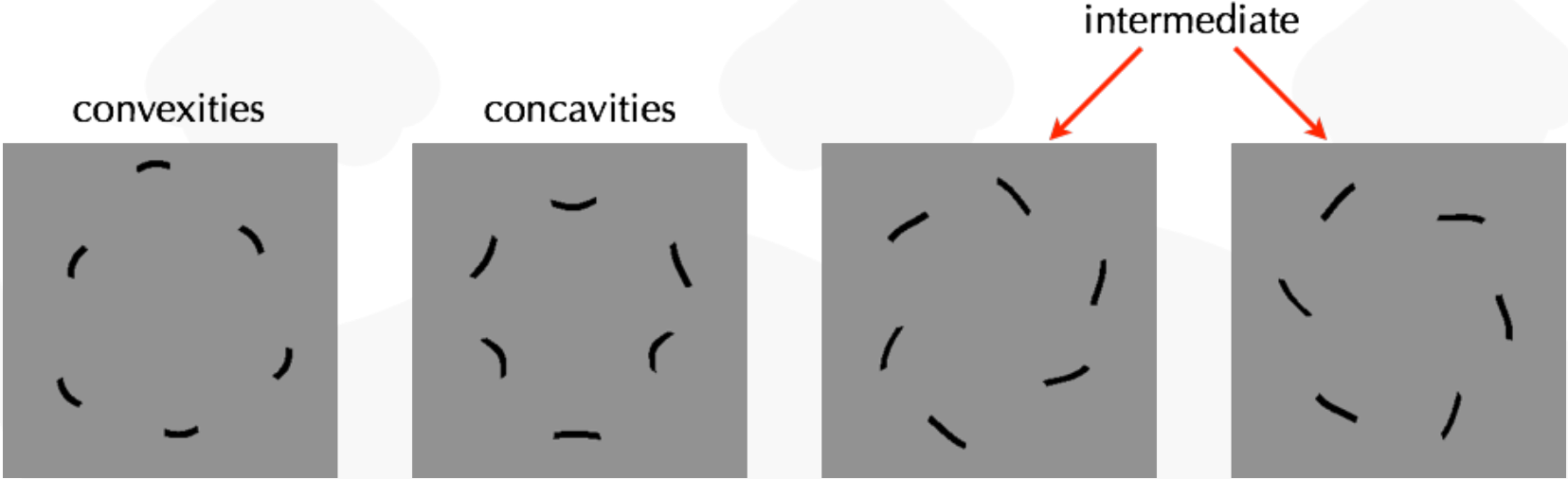


$$RF_{compound} = r_{mean}(1 + A_1 \sin(\omega_1 \theta + \varphi_1) + A_2 \sin(\omega_2 \theta + \varphi_2) + A_3 \sin(\omega_3 \theta + \varphi_3))$$

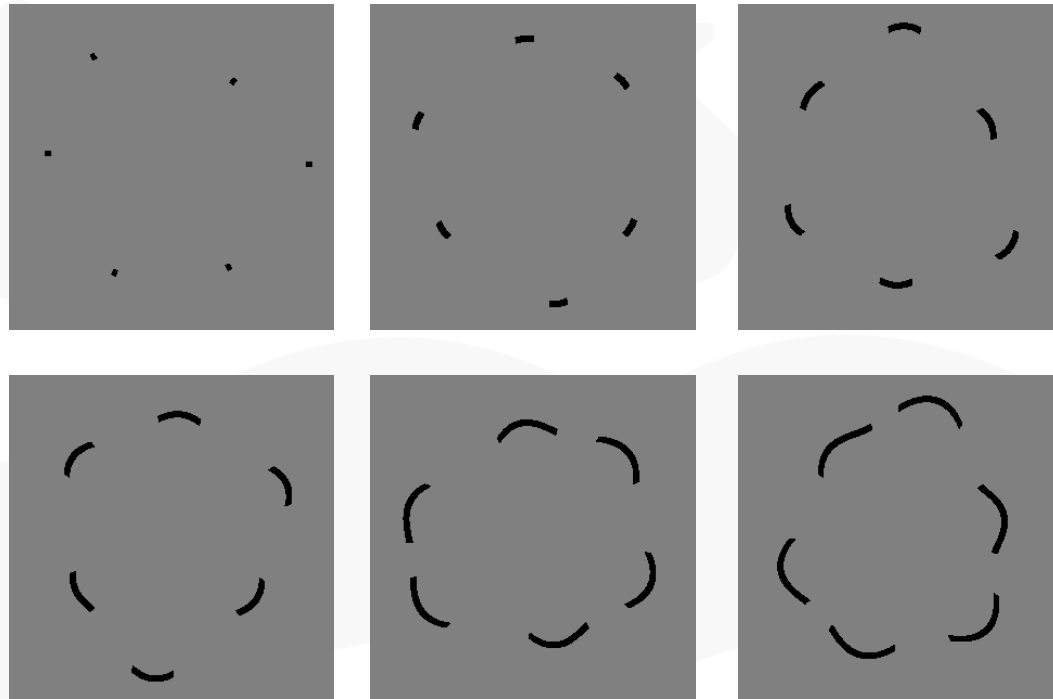
- r_{mean} : mean radius of underlying circle (=100 Pixel)
- A : modulation amplitude (=0.1)
- ω_1 : radial frequency
- θ : polar angle
- φ_1 : phase / orientation (random)



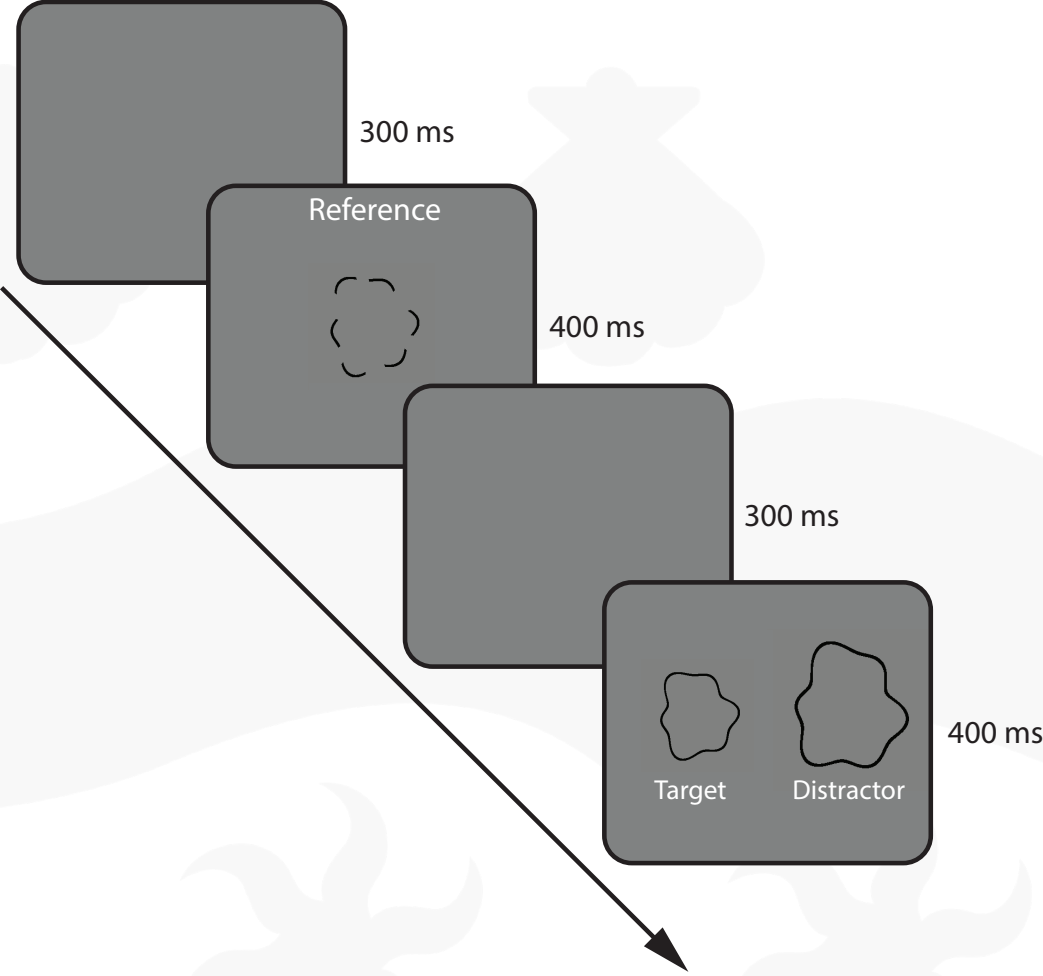
Stimuli



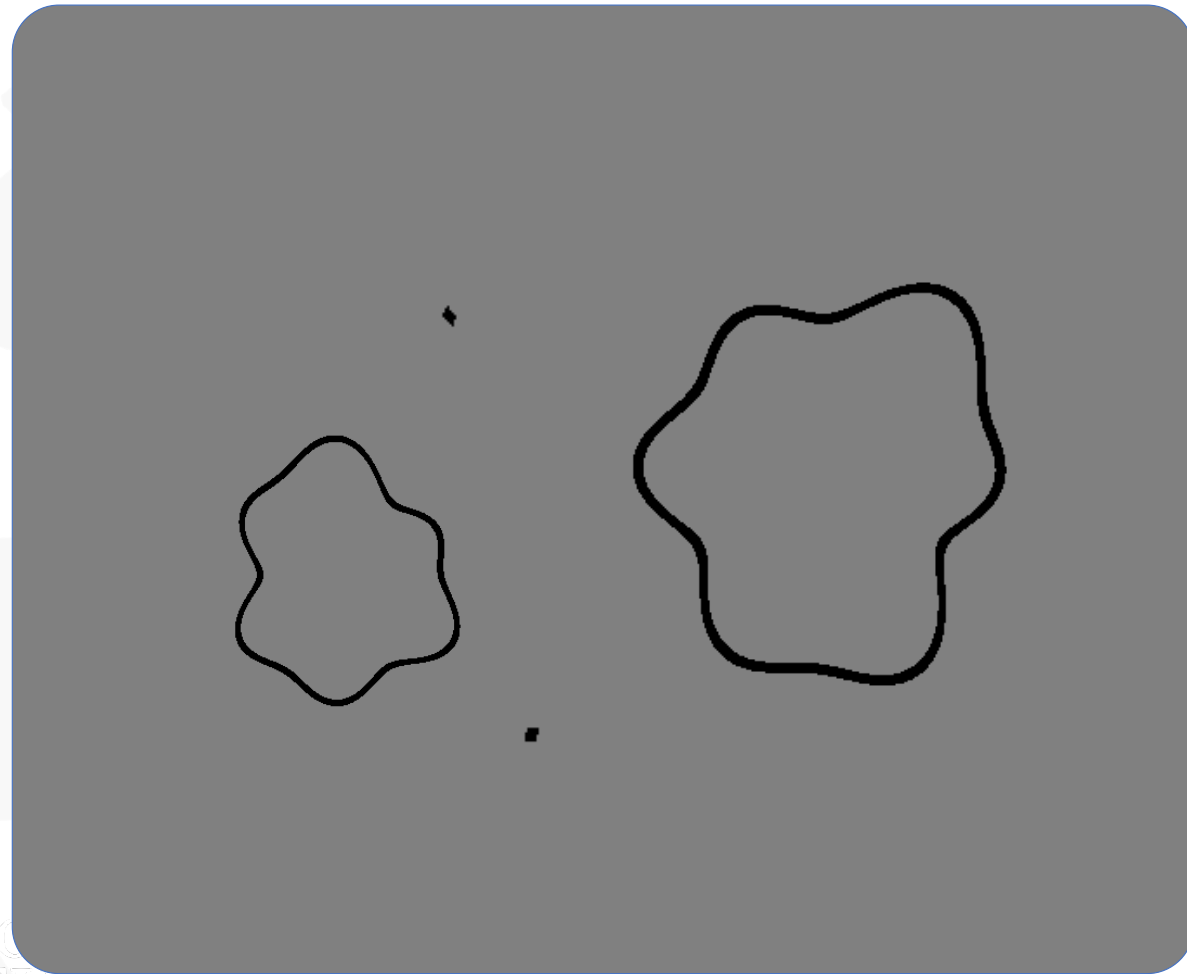
Stimuli



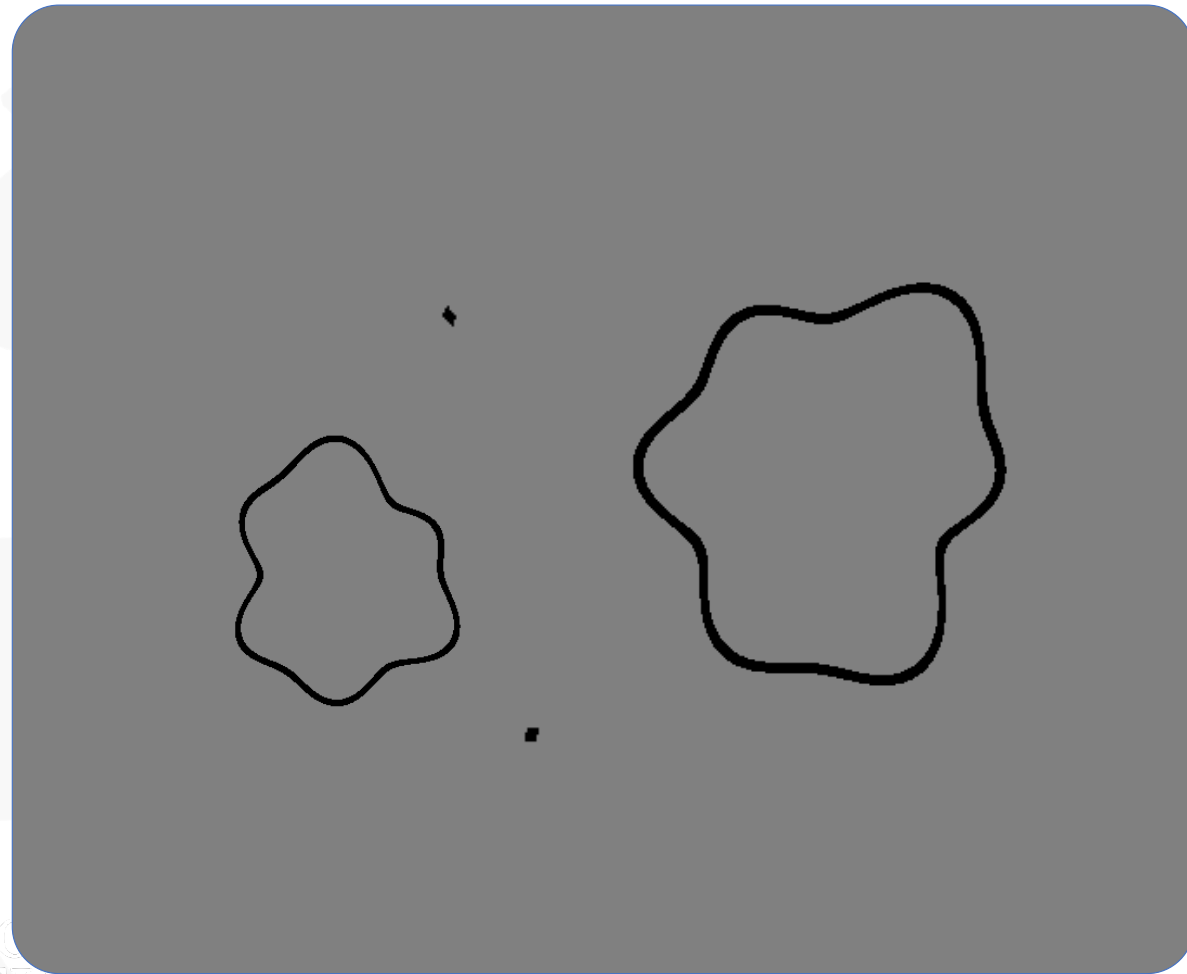
Paradigm



Demo

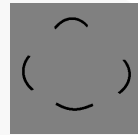
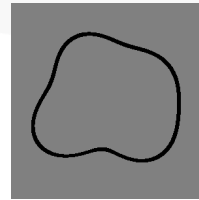


Demo



Results

2-3-4



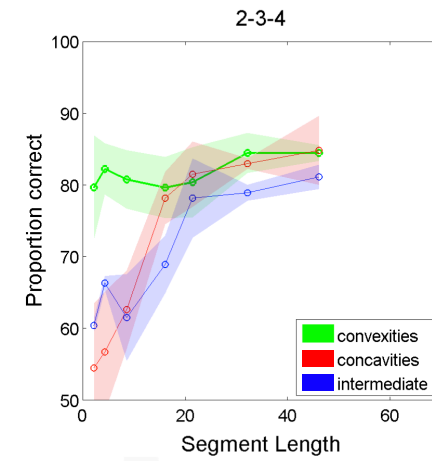
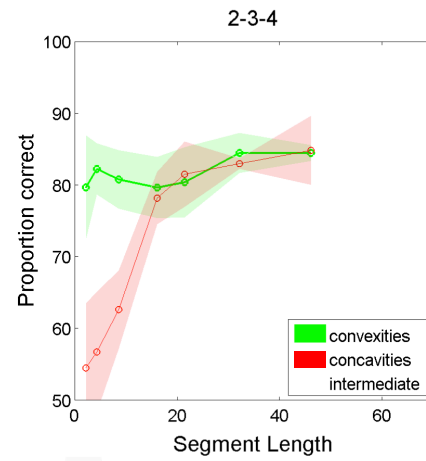
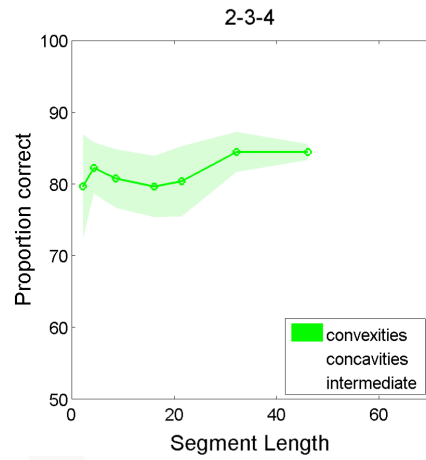
convexities



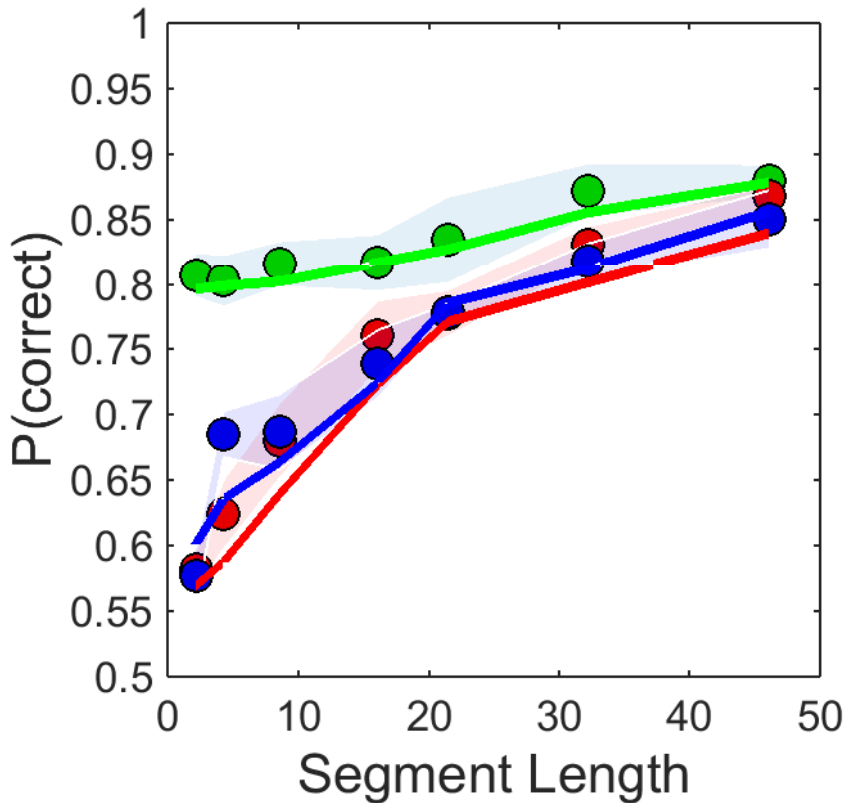
concavities



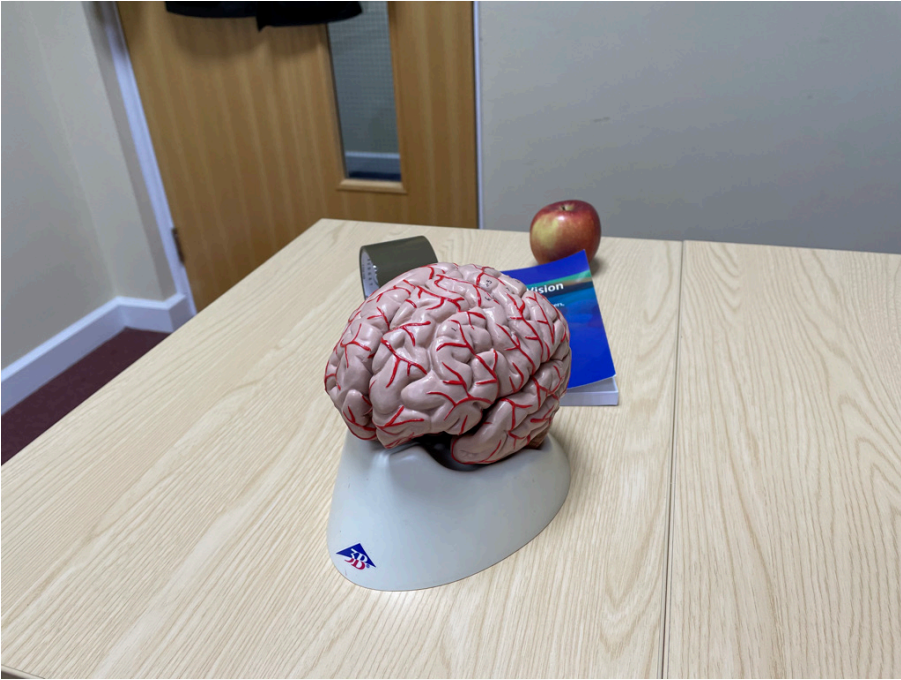
intermediate



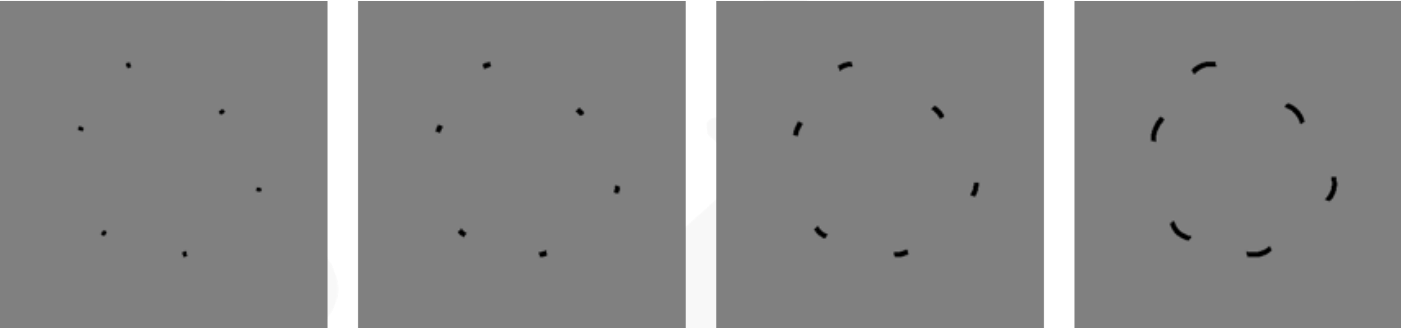
Model Results



New Experiment - Partial Occlusion



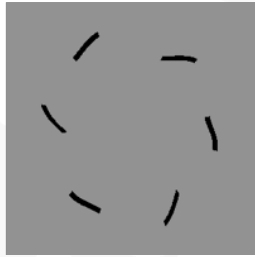
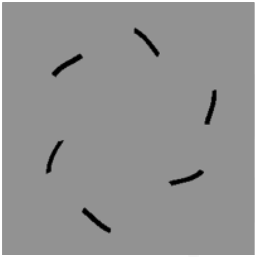
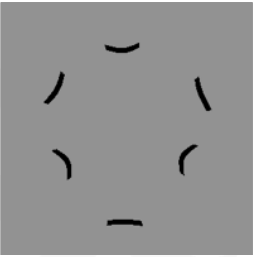
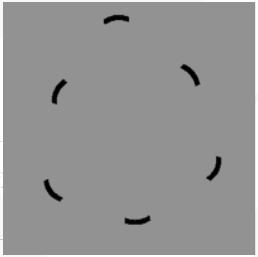
Stimuli



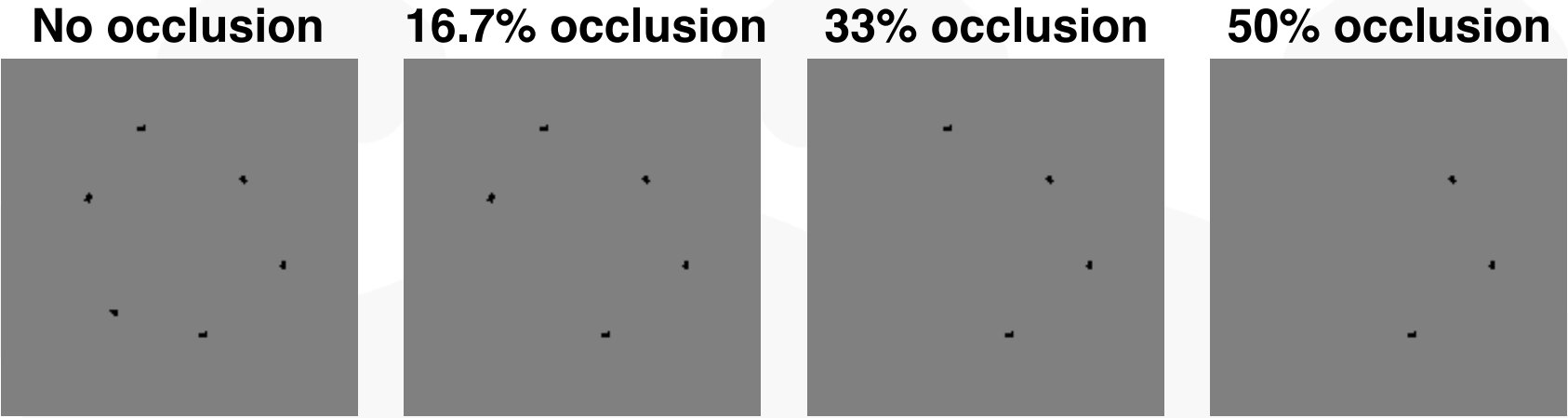
intermediate

convexities

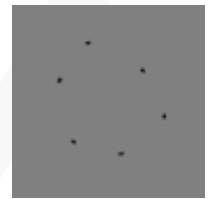
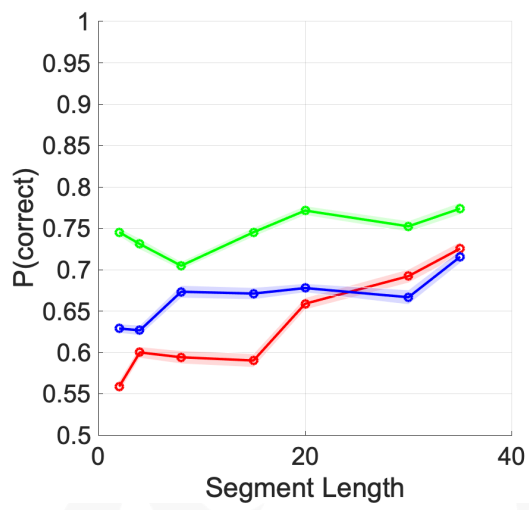
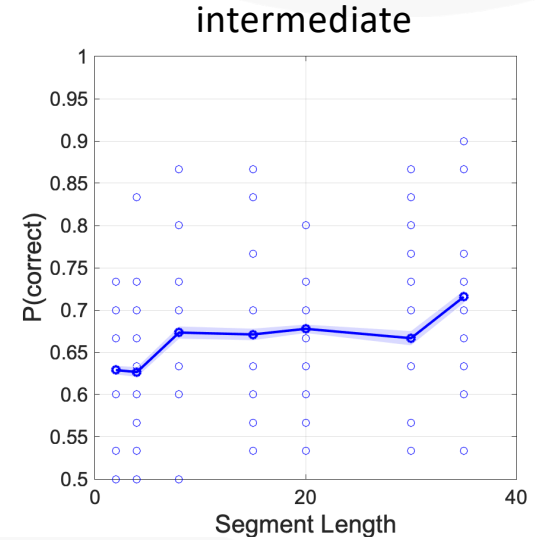
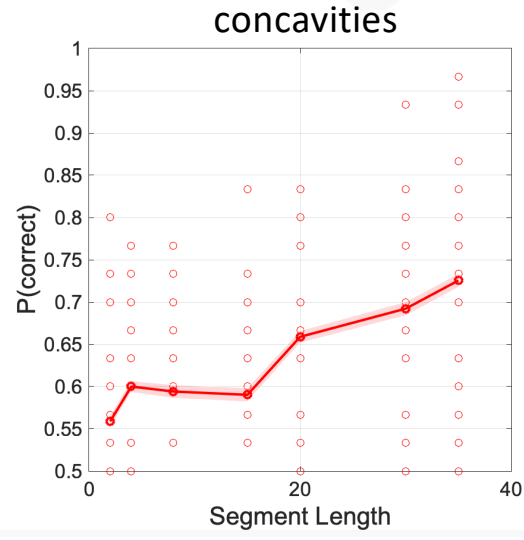
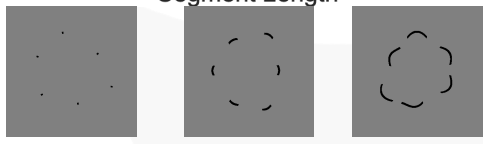
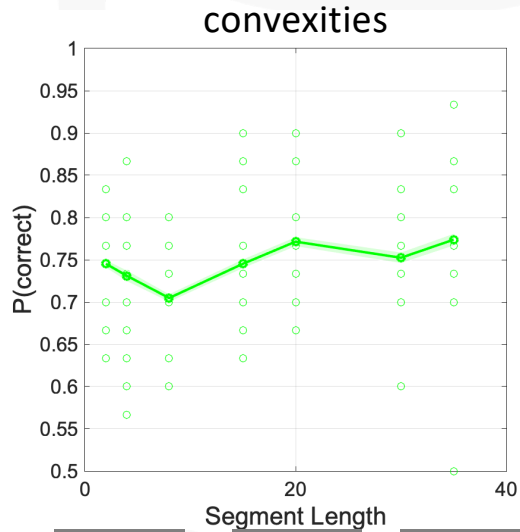
concavities



Partial Occlusion

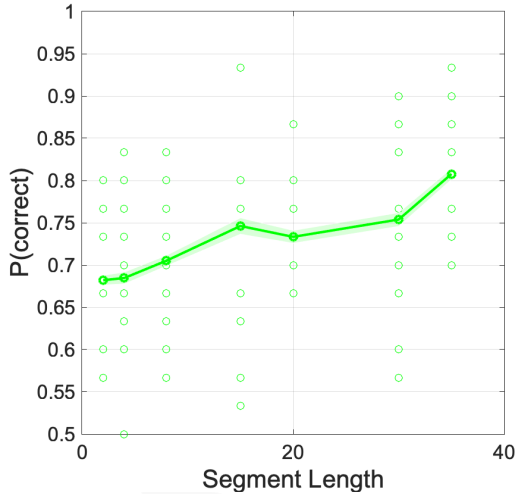


Results – no occlusion

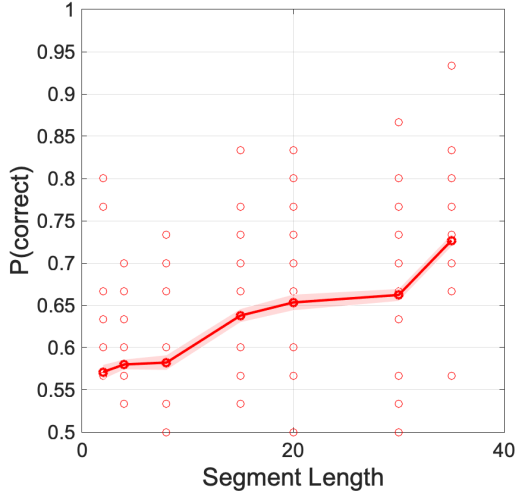


Results – 16.7% occlusion

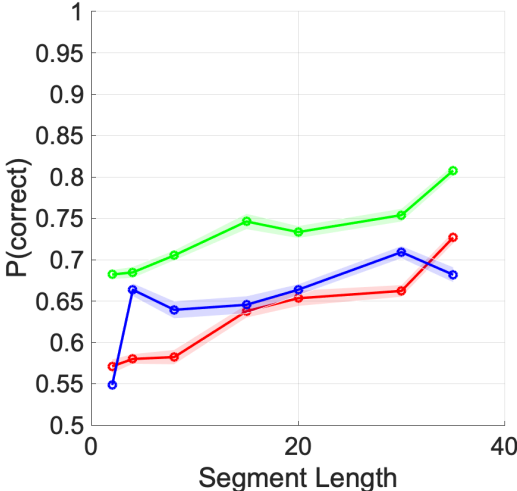
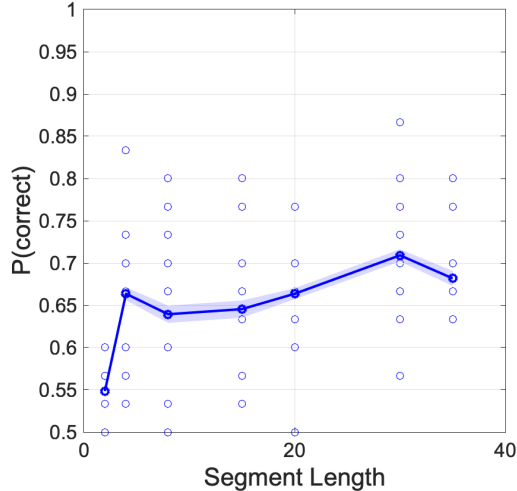
convexities



concavities



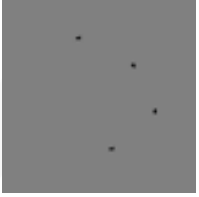
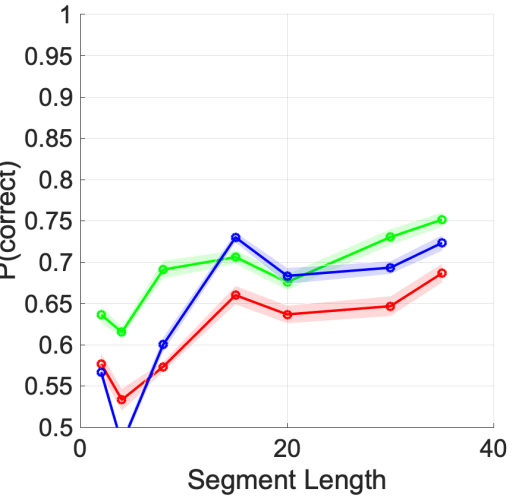
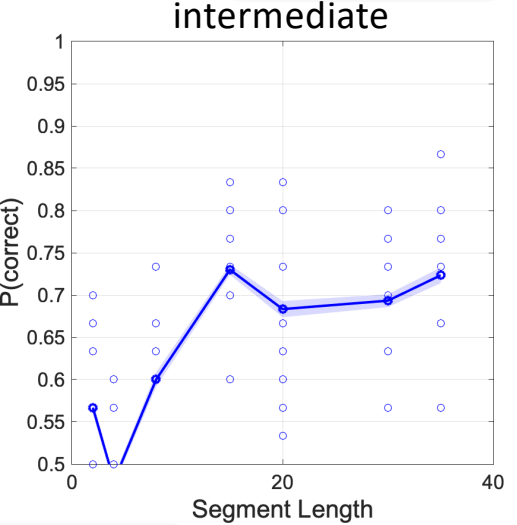
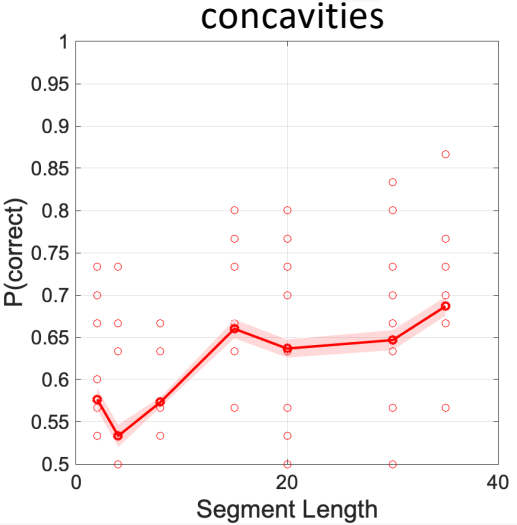
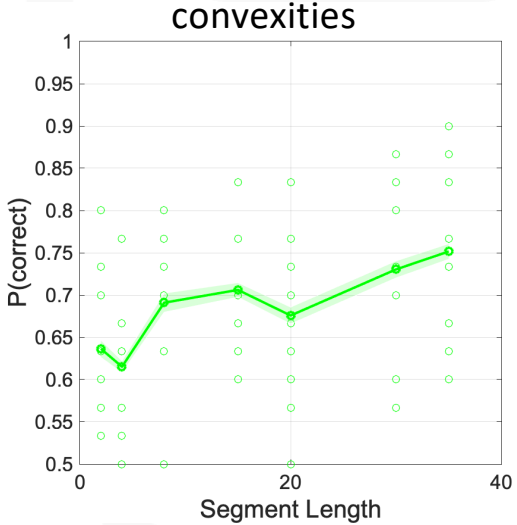
intermediate



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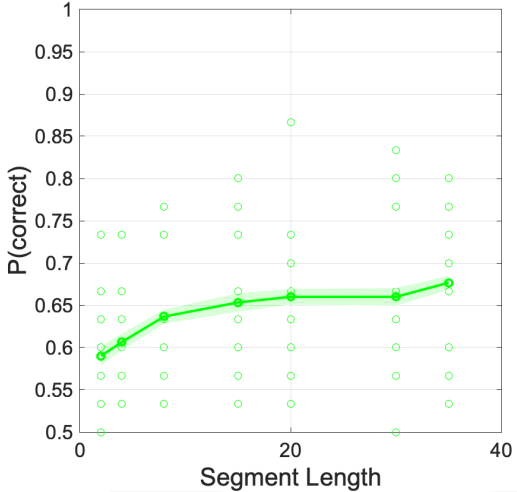


Results – 33% occlusion

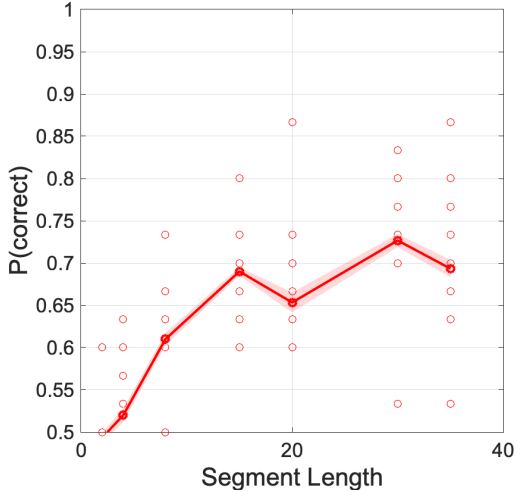


Results – 50% occlusion

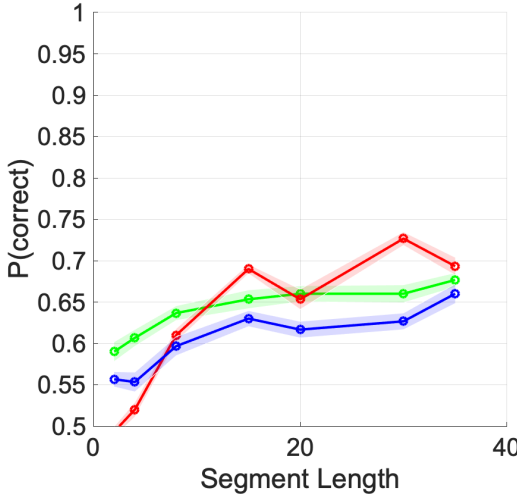
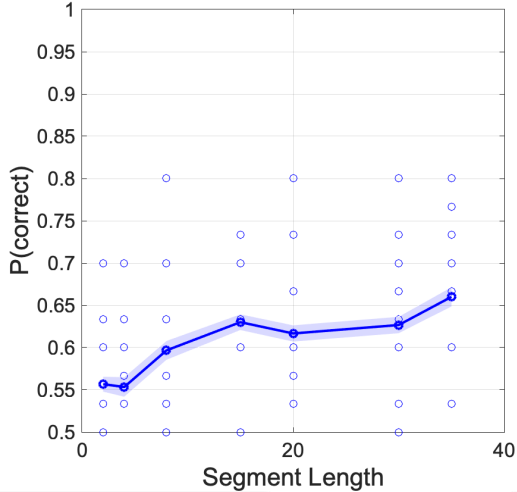
convexities



concavities



intermediate

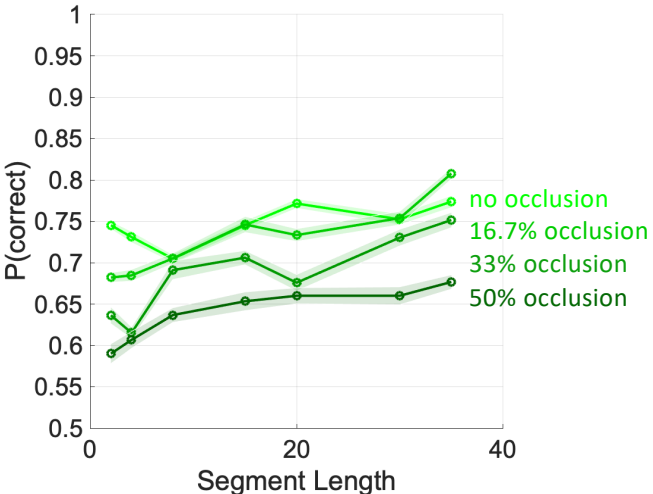


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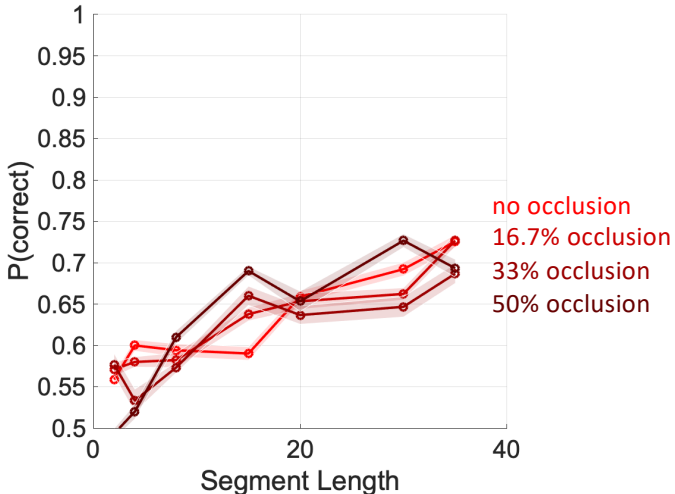


Results – combined

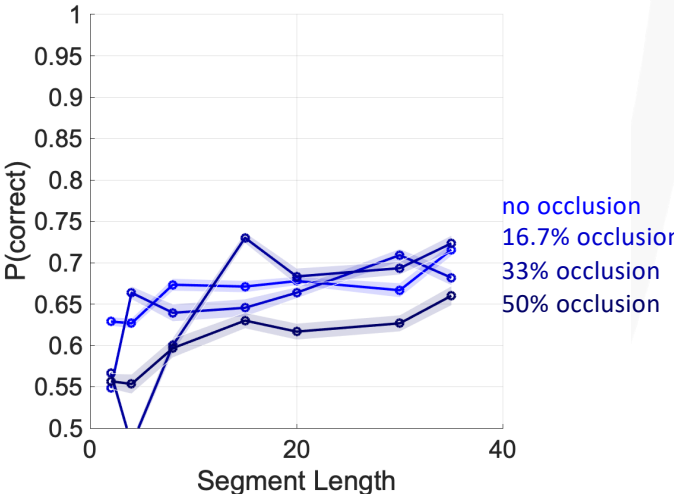
convexities



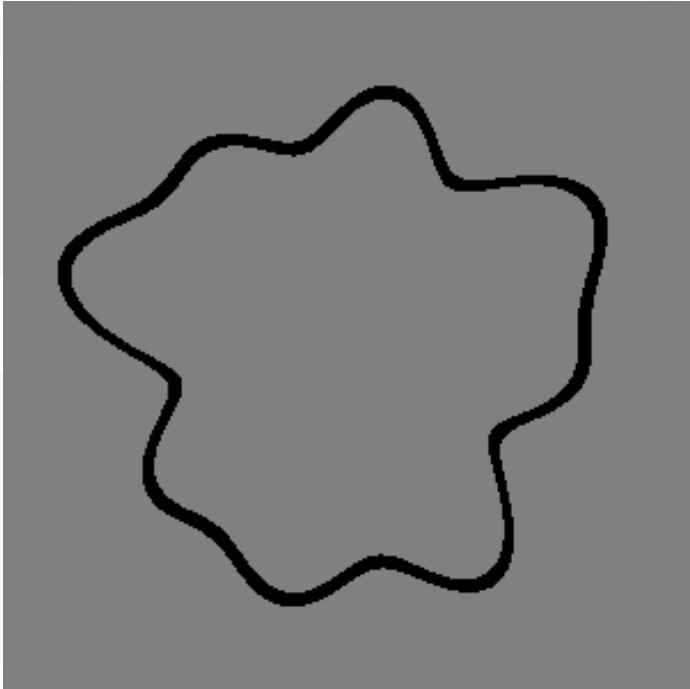
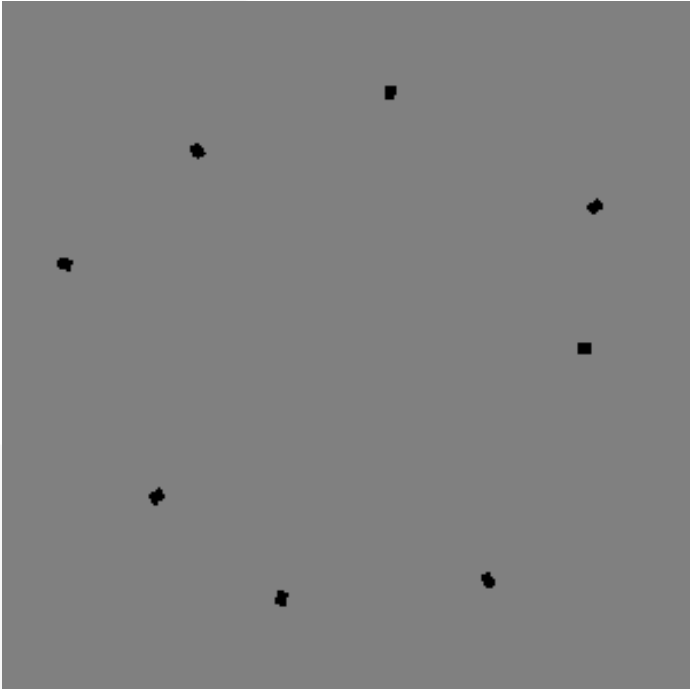
concavities



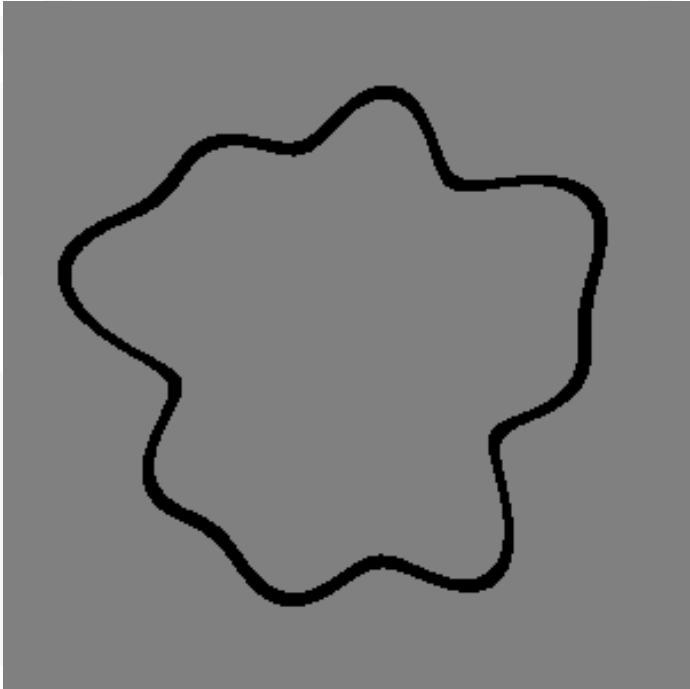
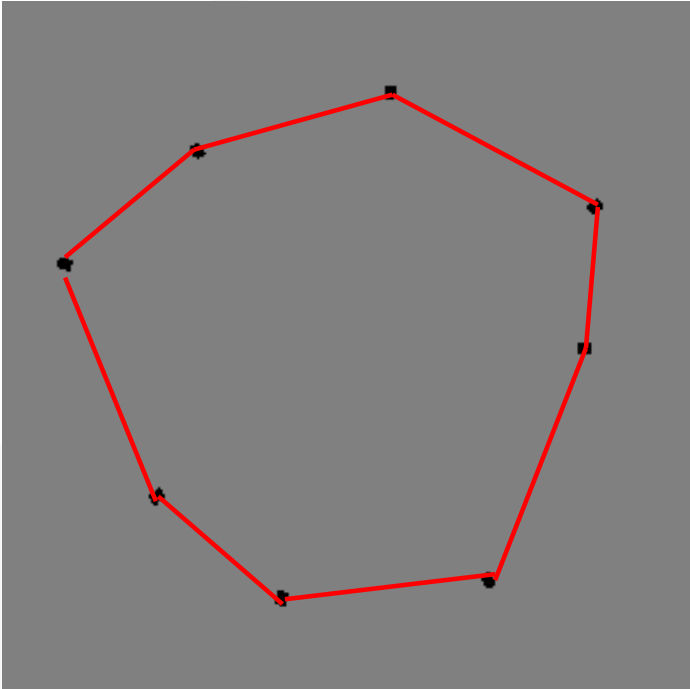
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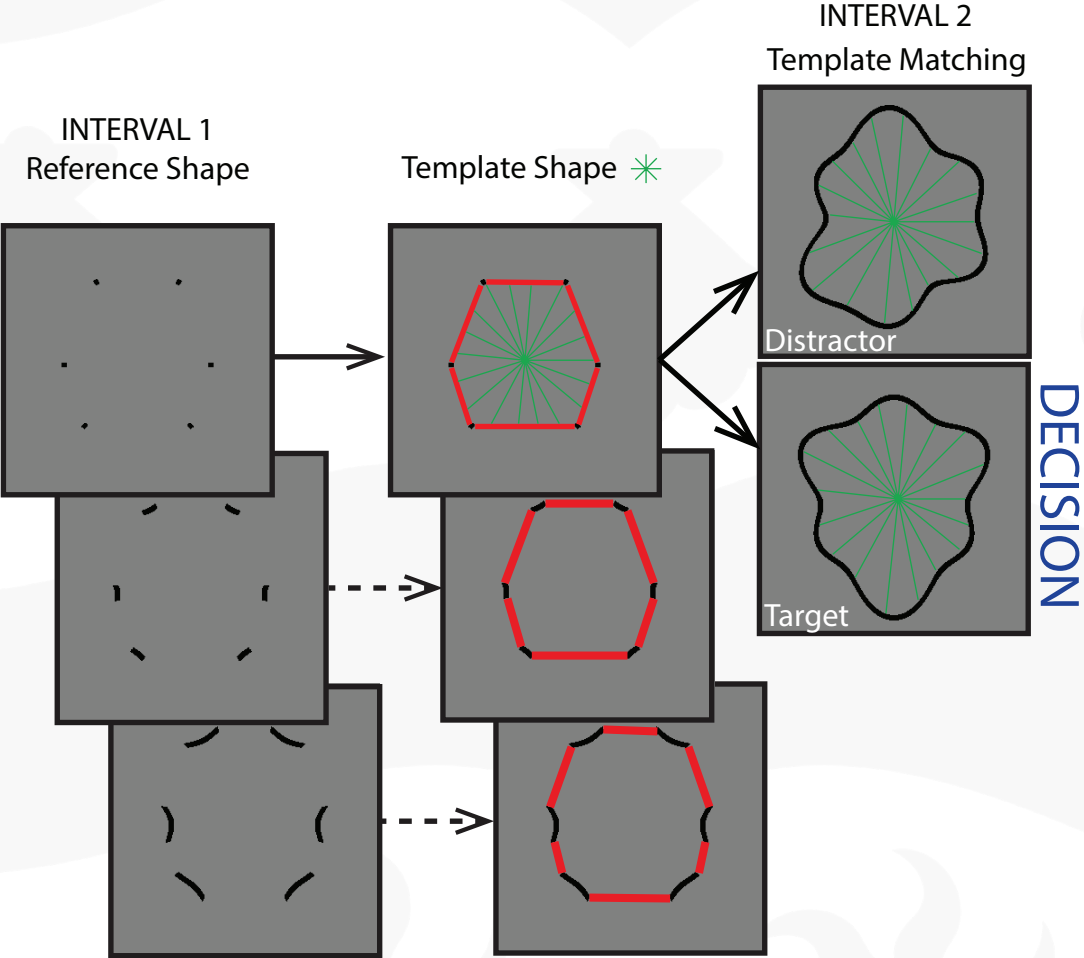
Model – Schmidtman et al. (2015)



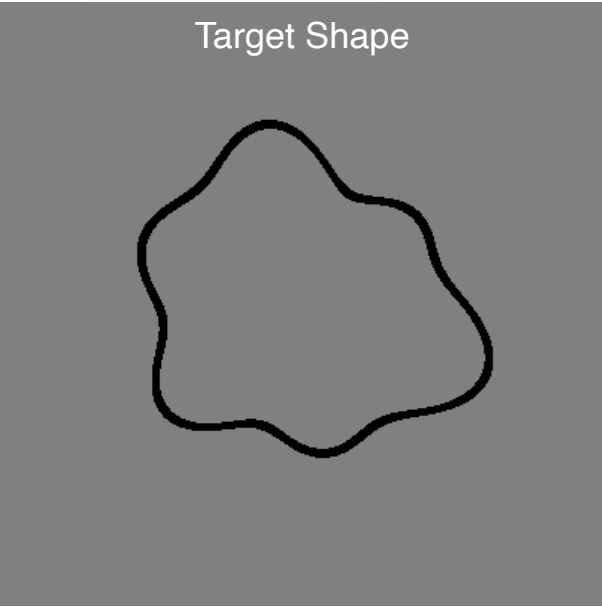
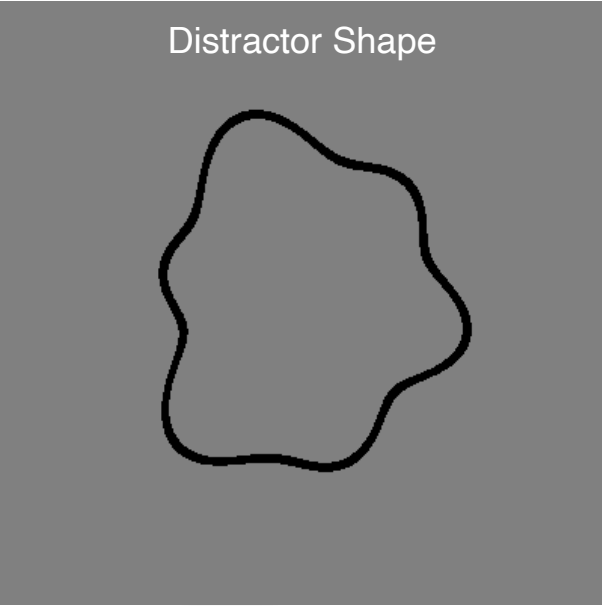
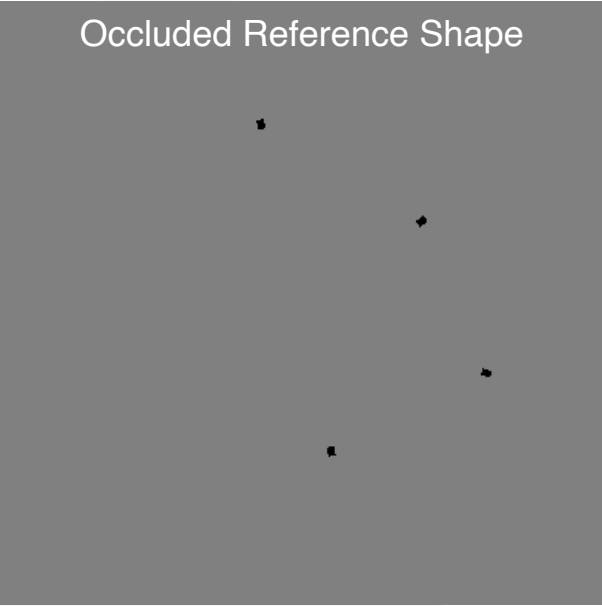
Model – Schmidtman et al. (2015)



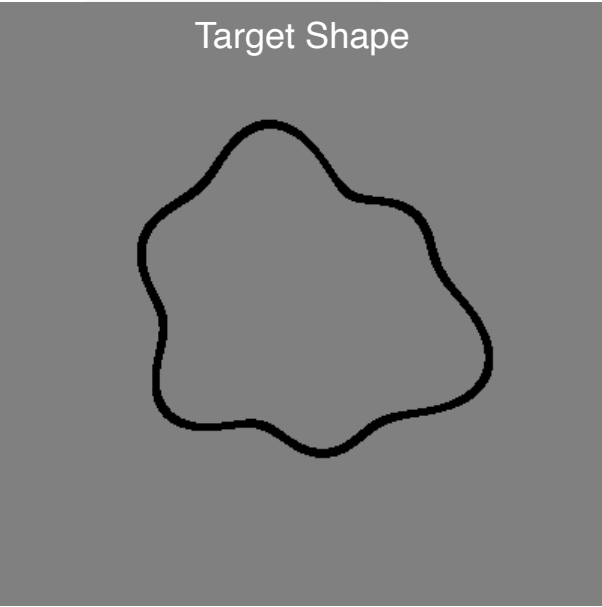
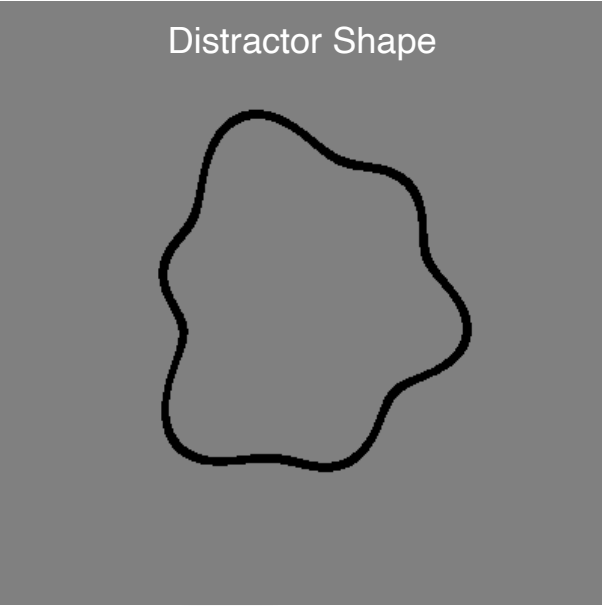
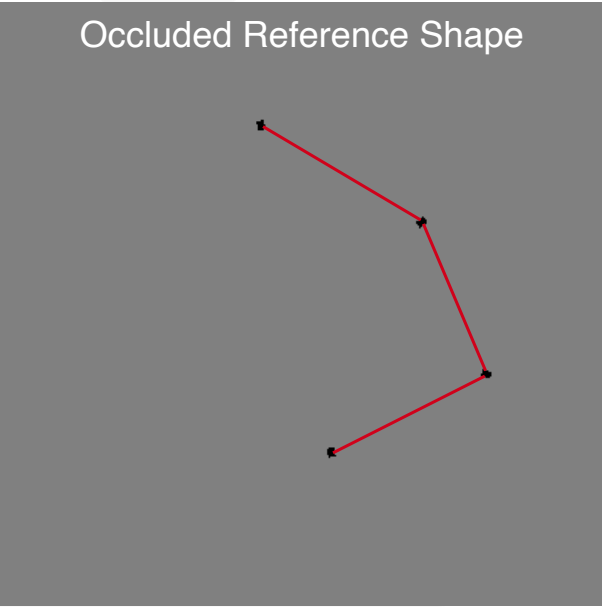
Model – Schmidtman et al. (2015)



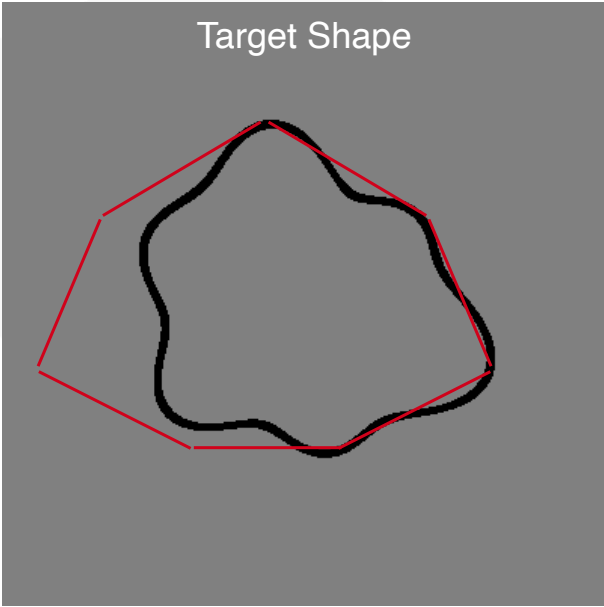
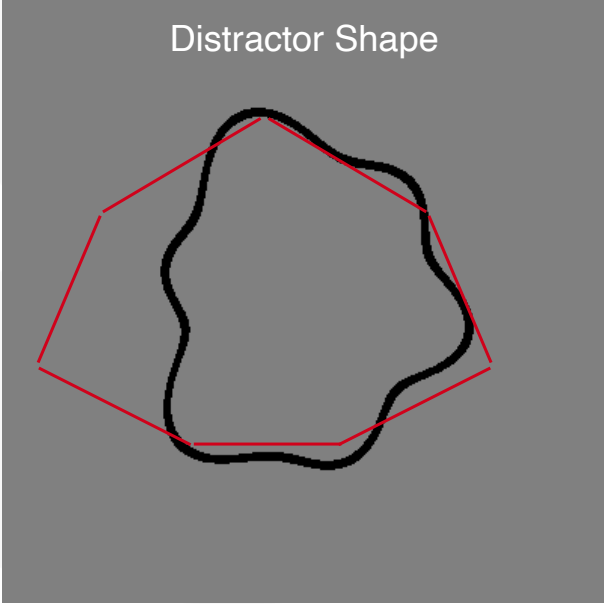
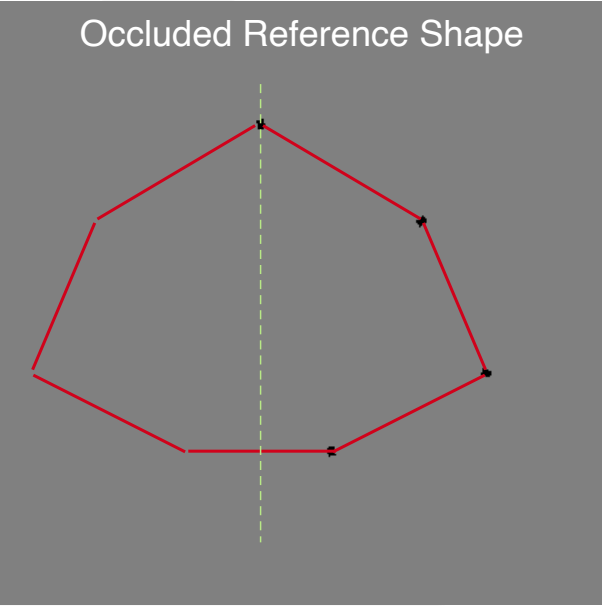
Proposed Model Idea



Proposed Model Idea



Proposed Model Idea



Summary

- Performance for convex features is superior to the other shape features and independent of segment length, replicating Schmidtman et al. (2015)
- Points at the location of convex curvature maxima are sufficient to extract shape information
- Performance is only significantly impaired when 50% of the shape is occluded
- Results demonstrate the importance of convexities maxima for shape encoding, and the flexibility of the visual system to deal with partially occluded shapes



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Optometry students (University of Plymouth)

- Abdulfatai Shonuga
- Abigail Medland
- Lucy Cooper
- Sarah Beachus
- Sohaib Naseem



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