



+ SkySat Block 3 Launch Campaign

Monte Fitz Roy, Patagonia – March 19, 2018



Our Speakers



Lisa McGill
SkySat Mission Ops



Addison Faler
Guidance, Navigation and
Control

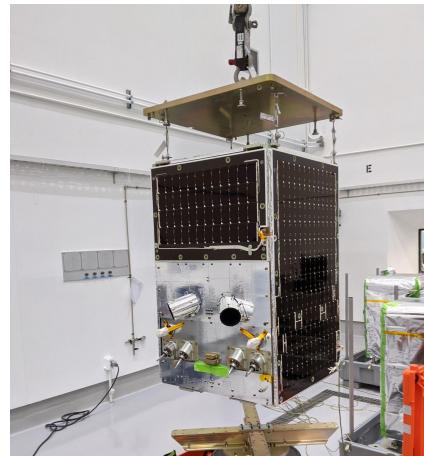




PLANET'S MISSION

To image the whole world every day,
making change **visible, accessible,
and actionable.**







Ground Station Network

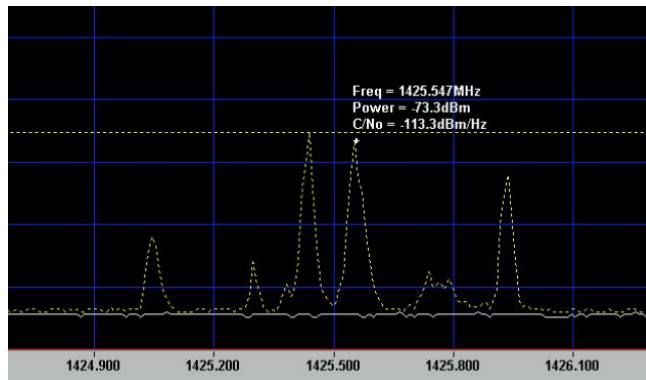
- Awarua, New Zealand
- Goonhilly, United Kingdom
- Maddock, North Dakota, USA
- Punta Arenas, Chile
- Jeju Island, South Korea





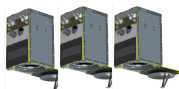
Launch Day

- 10 minutes to space
- 12 minutes to launch vehicle separation
- 18 minutes to first ground station contact



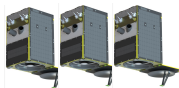
Falcon 9 (Cape Canaveral, FL)

Launch: 6/13/2020



Falcon 9 (Cape Canaveral, FL)

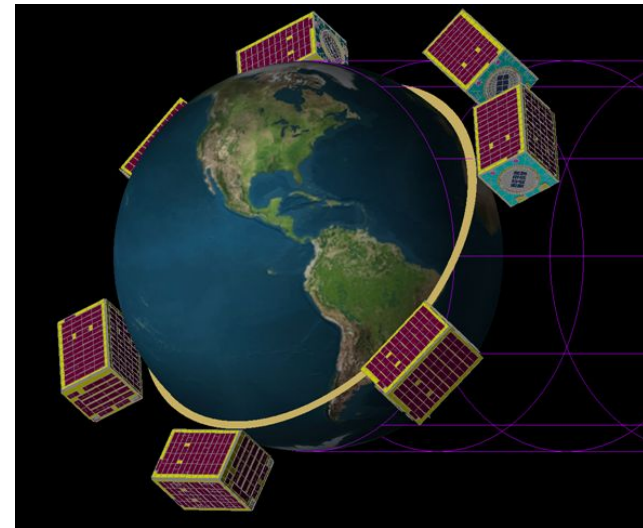
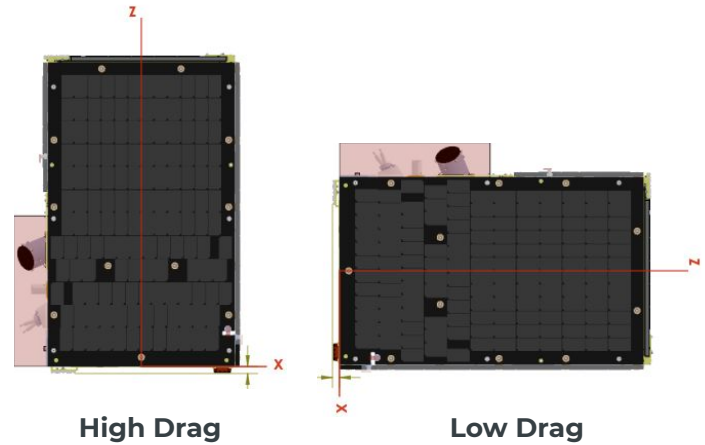
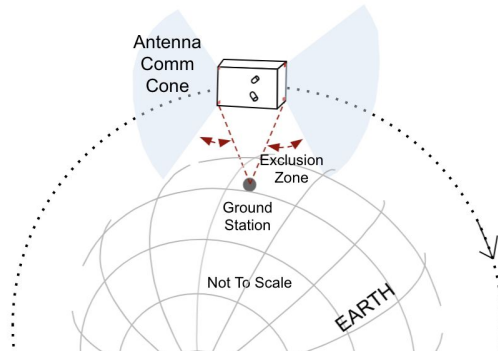
Launch: 8/18/2020





Low Drag

- Pitch 90 degrees to expose its smallest cross-section to be parallel to velocity direction
- Payload door remained closed
- Reduce atmospheric drag
- Updates to ops scripts to support telemetry and commanding



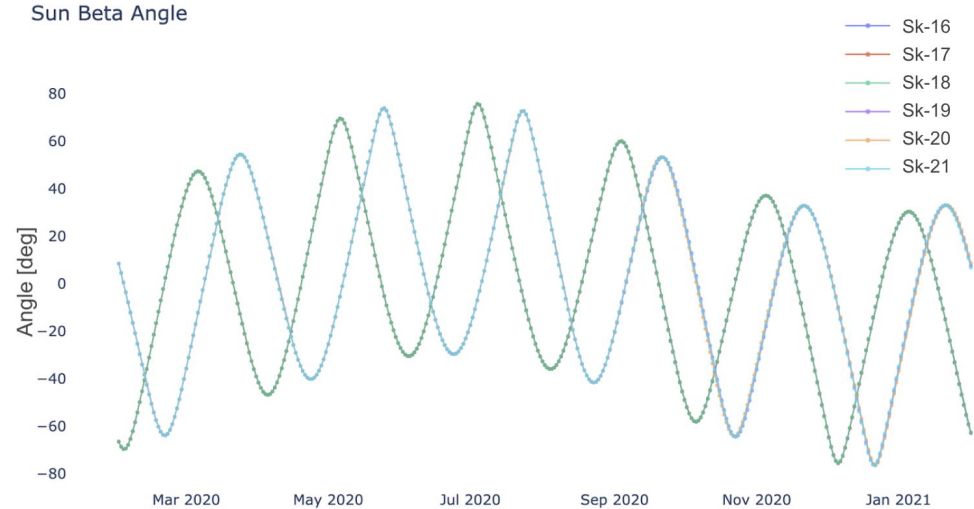


Attitude Management

What is a beta angle?

- A measurement that describes the angle between a satellite's orbital plane and a vector from the center of the Earth pointing toward the sun

Develop a new attitude management scheduling system!



Beta Angle Magnitude	Classification	Issues
$0 \leq \beta \leq 15$ deg	Low Beta	Poor star tracker performance
$15 < \beta < 45$ deg	Mid Beta	No issues
$45 \leq \beta < 68$ deg	High Beta	High temps; thermal buildup
$\beta \geq 68+$ deg	Extreme Beta	No eclipses; severe thermal buildup



On-Orbit Operations

Singapore Strait, Singapore – July 29, 2016





On Orbit Issues

Two Primary Issues

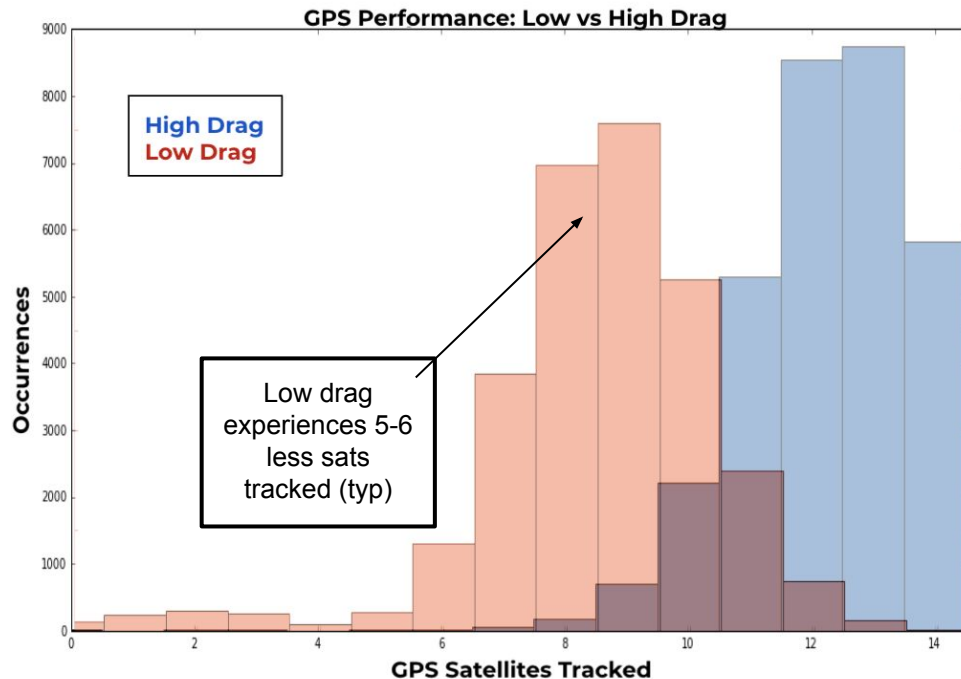
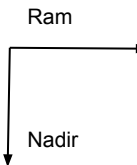
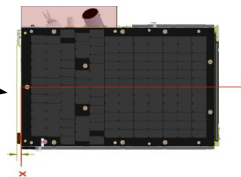
Unexpected GPS Loss:

- During commissioning (in low-drag) experienced higher occurrence of GPS lock/solution dropouts
- Sustained dropouts can cause ACS faults, due to degradation in position knowledge
- Compared performance to high drag SkySats - it was confirmed this was product of GPS antenna orientation whilst in low-drag, towards horizon (ram/anti-ram) vs anti-nadir
- Mitigation: When needed, used GPS override mode (uses onboard propagator and TLE to approximate position temporarily)

Non-Operational Thruster:

- Sensor anomaly monitoring thruster on SkySat-20
- Out of precaution deemed thruster non-operational
- Shifted to “reduced thruster operations” i.e 3-thruster Ops
- Following slides detail...

GPS on -Z face
(anti-ram/ram in
low-drag orientation)





Maneuver ADCS

Nominal vs 3-Thruster

	Nominal	3-Thruster
Thruster Control	Closed-Loop PID 1Hz - Variable DC Optimization ²	Open-Loop Fixed DC
Attitude Control		Nominal 16 Hz PD
Actuators	4x Thrusters	4x Reaction Wheels
Sensors¹	Gyros	Gyros
Duration	~300-360sec	70-100sec

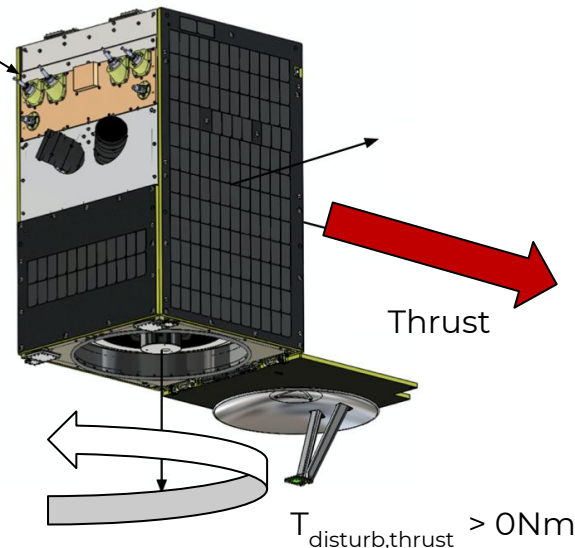
¹Star Trackers occluded by Plume

²Convex Optimization -- to max DC and satisfy nullspace (Thrust won't impart torque on vehicle)

PID: Proportional-Integral-Derivative

4x Thrusters

Open Loop Thruster Control



Maintain pointing ?
Nominal ACS controller using
RWs (to counter $T_{\text{disturb,thrust}}$)

**How to calculate open loop
DC's ?**





Reduced Thruster Maneuvers

Selecting Duty Cycles

Objective: Maximize Impulse

$$\text{Imp} = F_{\text{th}} * t_{\text{dur}} = \text{Thrust} * \text{duration} [\text{N-s}]$$

Variables:

Duty cycles of 3-functioning thrusters¹

Where:

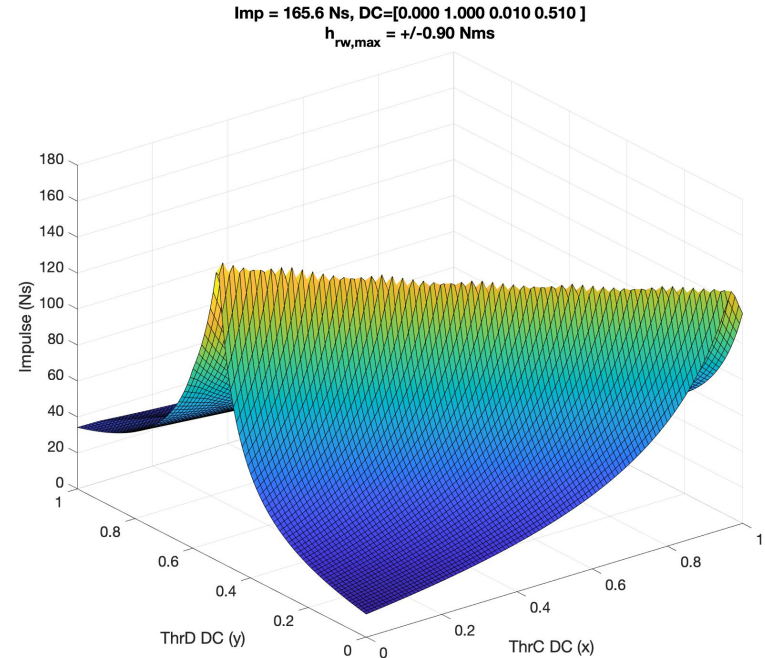
$$F_{\text{th}}, \text{Thrust} = f(\text{DC})$$

$$T_{\text{dist}}, \text{Disturbance Torque} = f(\text{DC})$$

$$t_{\text{dur}}, \text{Burn Duration} = h_{\text{rw,max}} / T_{\text{dist}}$$

$h_{\text{rw,max}}$, Total Available RW Momentum

¹technically 2-thrusters, we hold one constant to zero for simplicity



Example of Thruster duty cycle optimization: Holding one thruster fixed (B) and solving for Thruster C & D duty cycles





Nominal 3-thruster Maneuver

RW Momenta

No-RW Prebias

Burn Time: 70 seconds

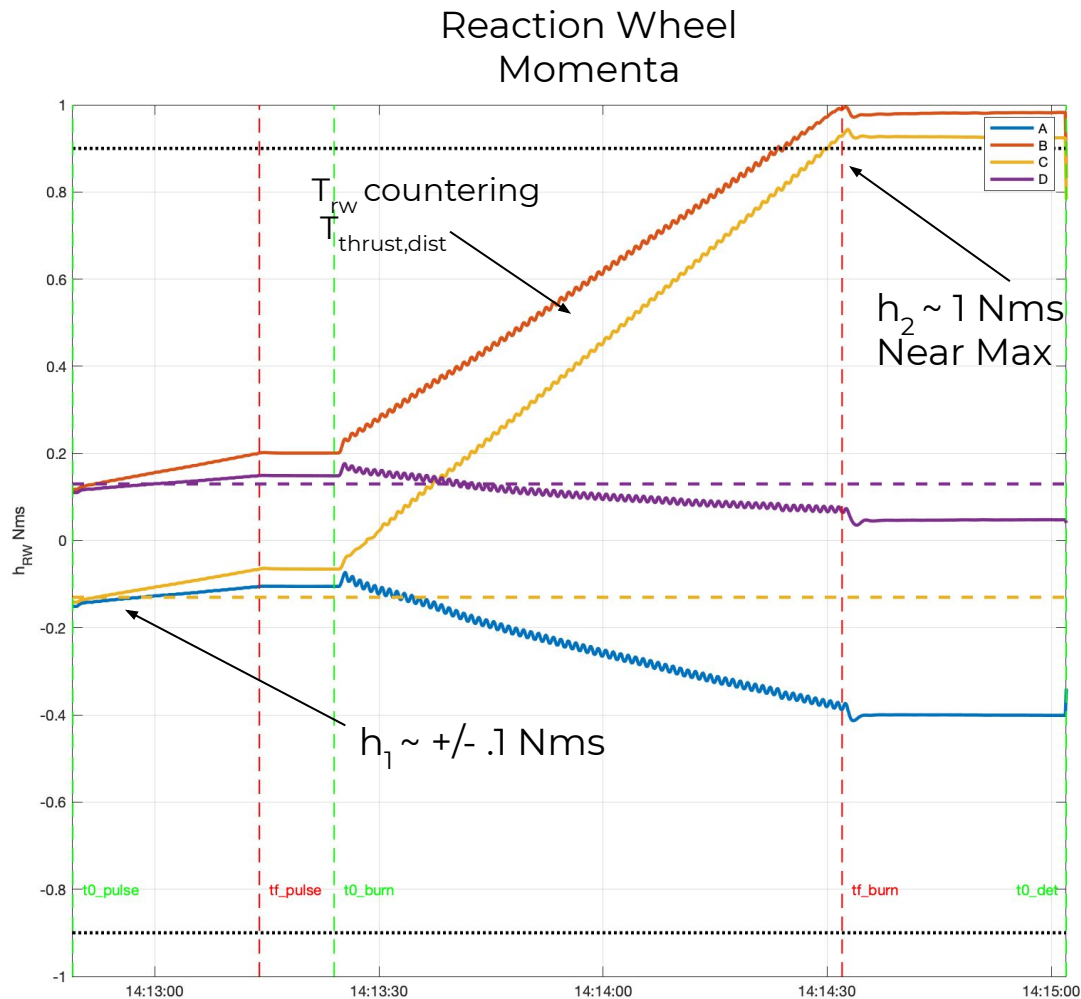
Total Activity Time: 1hr 20 min

Pros:

Activity/planning complexity is comparable to nominal 4-thruster maneuver

Cons:

Duration is minimal





Nominal Pre-bias Maneuver RW Momenta

RW Prebias

Burn Time: 100 seconds

Total Activity Time: 2hr 20 min

Pros:

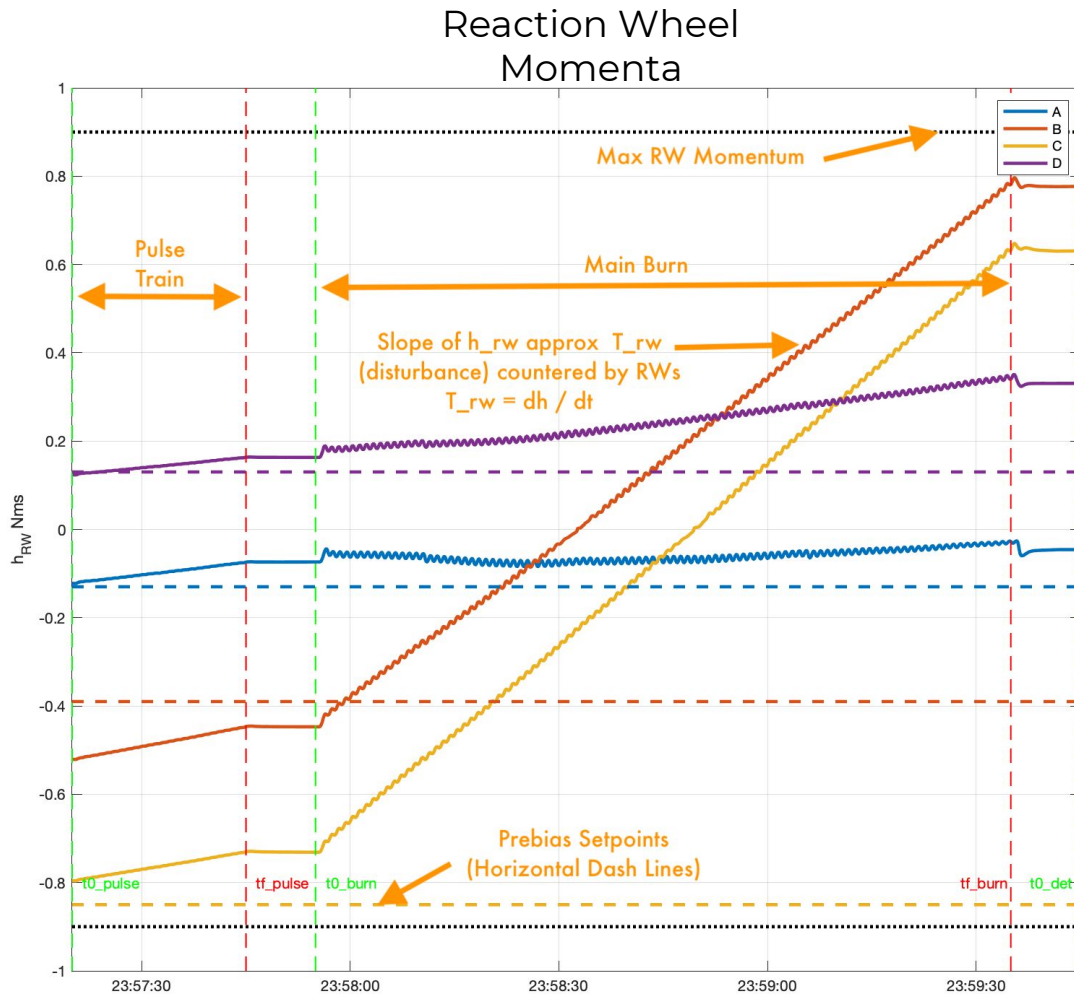
Duration improved vs non-prebiased

~50% improvement in impulse

Cons:

Longer activity +1hr

Much more complex, planning and execution





Orbits Strategy

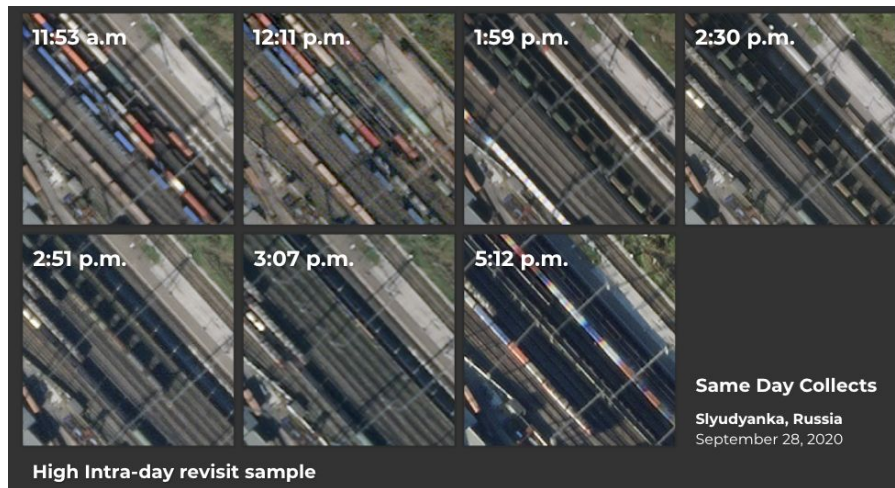
Singapore Strait, Singapore – July 29, 2016





Constellation Goals

- 50 cm Resolution
- 6+ year lifetime
- phased to provide repeat-revisit
- **Repeat-Revisit:** multiple revisits over any single area are possible, with up to 12 times per day, and at a global average of 7 times per day





Orbit Raising Campaign

Initial orbit: 375 x 208 km ellipse

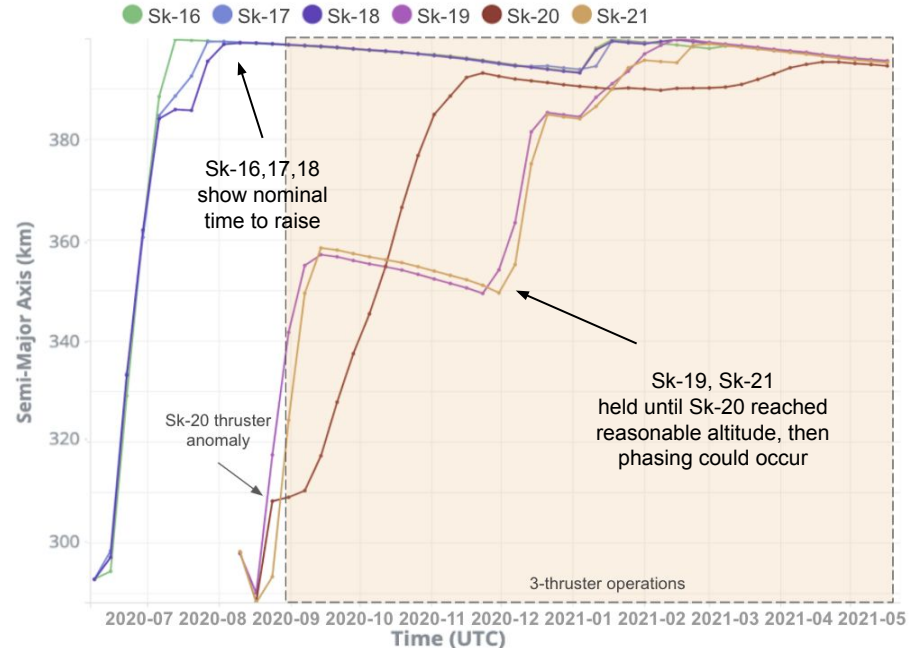
Target orbit: 400 km circular

Goal: raise perigee immediately, then phase appropriately

Impacts of 3-thruster Ops:

- Shorter maneuvers: 70-100 secs
 - vs 360 sec nominally (3.6-5x reduction)
- More maneuvers (3x days vs 1 per 2 days)
- Less ΔV , longer time to raise

Skysat-20 3-thruster operations delayed raising campaign for Skysat 19,20,21



Thank you!

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