# HACK Modular On-Board Computer for Edge Computing in Micro-Satellites

### Introduction

Argotec HACK OBC offers unprecedent **flexibility** thanks to its design developed from scratch to be **modular** and easily **reconfigurable**. Different standard modules, based on both state-of-the-art SoCs and FPGAs, can be assembled without the need of external harness to face a wide variety of applications, from spacecraft management to hardware acceleration. The design leverages a mix of rad-hard, defense-grade and automotive components carefully selected to enable the execution of demanding edge-computing tasks while ensuring a reliability level significantly higher than standard CubeSat avionics. Each HACK module is designed to be powered by a single +5V DC rail and has standardized thermal and mechanical interfaces, allowing the

The HACK module general block diagram is shown in Figure - 1. It shows one of the OBC possible configurations since the subsystem has been designed to be modular and reconfigurable according to mission-specific needs. The OBC design includes two principal hardware units:

installation both as single unit or as part of a complex OBC subsystem. A third module, labelled as Router Board (RB), has been planned as well. The standard configuration, which includes one Core Board and one The RB can be used for configurations requiring more than one CB and



## **System Description**

• The Core Board (CB), which hosts the main SoC that runs the OSW The aXelerator Module (aXM), which act as both mass memory controller and chipset in order to supply additional interfaces to the CB; optionally, the aXM FPGA could be used to implement mission-specific hardware accelerators



DDR3 SDRAM

DDR2 SDRAM

Flash NOR

Flash Memory	
Bitstream Memory	s
	RS644 GPIC
	R: Tran

erator Module (aXM)				
		CAN	12C	
		CAN	I2C	
		CAN	I2C	
		CAN	I2C	
	-			
		CAN	I2C	
		CAN	I2C	
		CAN	I2C	
		CAN	I2C	
Figure 2				
HACK Module – 1 CB and 1 aXM stacked together		CAN	I2C	
The form factor is reported in the Figure 2, selecting a configuration with one CB and one aXM.		CAN	I2C	



### aXelerator Module





 CAN – to manage board-to-board TM and TC I2C – restricted to TM collection or CAN bus backup • SpaceWire – point-to-point link between boards Redundant Configuration СΒ

RB