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# Precise determination of the $B_s^0 - \overline{B}_s^0$ oscillation frequency

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#### Abstract

Mesons comprising a beauty quark and a strange quark can oscillate between particle  $(B_s^0)$  and antiparticle  $(\overline{B}_s^0)$  flavour eigenstates, with a frequency given by the mass difference between heavy and light mass eigenstates,  $\Delta m_s$ . Here we present a measurement of  $\Delta m_s$  using  $B_s^0 \rightarrow D_s^- \pi^+$  decays produced in proton-proton collisions collected with the LHCb detector at the Large Hadron Collider. This measurement improves upon the current  $\Delta m_s$  precision by a factor of two. The oscillation frequency is found to be  $\Delta m_s = 17.7683 \pm 0.0051 \pm 0.0032 \,\mathrm{ps}^{-1}$ , where the first uncertainty is statistical and the second systematic. We combine this result with previous LHCb measurements to determine  $\Delta m_s = 17.7656 \pm 0.0057 \,\mathrm{ps}^{-1}$ .

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Neutral mesons with strange, charm or beauty quantum numbers can mix with their antiparticles, as these quantum numbers are not conserved by the weak interaction. The neutral meson comprising an antibeauty quark and a strange quark, the  $B_s^0$  meson, and its antiparticle, the  $\overline{B}_s^0$  meson, are one such example. In the  $B_s^0 - \overline{B}_s^0$  system, the observed particle and antiparticle states are linear combinations of the heavy (H) and light (L) mass eigenstates. The mass eigenstates have masses  $m_{\rm H}$  and  $m_{\rm L}$  and decay widths  $\Gamma_{\rm H}$ and  $\Gamma_{\rm L}$  [1]. As a consequence, the  $B_s^0 - \overline{B}_s^0$  system oscillates with a frequency given by the mass difference,  $\Delta m_s = m_{\rm H} - m_{\rm L}$ . This oscillation frequency is an important parameter of the Standard Model of particle physics. In combination with the  $B^0 - \overline{B}^0$  oscillation frequency,  $\Delta m_d$ , it provides a powerful constraint on the Cabibbo–Kobayashi–Maskawa quark-mixing matrix [2–5]. A precise measurement of  $\Delta m_s$  is also required to reduce the systematic uncertainty associated with measurements of matter-antimatter differences in the  $B_s^0 - \overline{B}_s^0$  system [6].

In this paper, we present a measurement of  $\Delta m_s$  using  $B_s^0$  mesons that decay to a charmed-strange  $D_s^-$  meson and a pion,  $B_s^0 \to D_s^- \pi^+$ , and the decays with opposite charge,  $\overline{B}_s^0 \to D_s^+ \pi^-$ . We refer to both charge combinations as  $B_s^0 \to D_s^- \pi^+$  throughout the paper, and similarly for decays of the  $D_s^-$  meson. The measurement is performed using data collected between 2015 and 2018, denoted Run 2 of the Large Hadron Collider (LHC), corresponding to an integrated luminosity of 6 fb<sup>-1</sup> of proton-proton (*pp*) collisions at a centre-of-mass energy of 13 TeV.

The first measurement of  $\Delta m_s$  was obtained by the CDF collaboration [7]. More recently, the LHCb collaboration has performed several measurements of  $\Delta m_s$  using data collected at the LHC: a measurement using  $B_s^0 \rightarrow D_s^- \pi^+$  decays [8]; two measurements using  $B_s^0 \rightarrow J/\psi K^+ K^-$  decays [9, 10]; and a measurement using  $B_s^0 \rightarrow D_s^\mp \pi^\pm \pi^\pm \pi^\mp$ decays [11]. Theoretical predictions for  $\Delta m_s$  are available [5, 12–16], with the most precise prediction in Ref. [17]. The prediction is consistent with but significantly less precise than existing experimental results.

The  $B_s^0 \to D_s^- \pi^+$  decay-time distribution, in the absence of detector effects, can be written as

$$P(t) \sim e^{-\Gamma_s t} \left[ \cosh\left(\frac{\Delta\Gamma_s t}{2}\right) + C \cdot \cos(\Delta m_s t) \right] ,$$
 (1)

where  $\Gamma_s = (\Gamma_{\rm H} + \Gamma_{\rm L})/2$  is the inverse of the  $B_s^0$  lifetime, known as the decay width in the literature, and  $\Delta \Gamma_s = \Gamma_{\rm H} - \Gamma_{\rm L}$  is the decay-width difference between the heavy and light mass eigenstates. The parameter C takes the value C = -1 for decays in which the initially produced meson mixed into its antiparticle before decaying, *i.e.*  $\overline{B}_s^0 \to B_s^0 \to D_s^- \pi^+$ , and C = 1 for unmixed decays, *i.e.*  $B_s^0 \to D_s^- \pi^+$ . The mixed decay is referred to as  $\overline{B}_s^0 \to D_s^- \pi^+$ throughout the paper. The mass difference  $\Delta m_s$  corresponds to a frequency in natural units, and is measured in inverse picoseconds.

The LHCb detector [18, 19] is designed to study the decays of beauty and charm hadrons produced in pp collisions at the LHC. It instruments a region around the proton beam axis, covering the polar angles between 10 and 250 mrad, in which approximately a quarter of the *b*-hadron decay products are fully contained. The detector includes a high-precision tracking system with a dipole magnet, providing measurements of the momentum and decay-vertex position of particles. Different types of charged particles are distinguished using information from two ring-imaging Cherenkov detectors, a calorimeter and a muon system.

Simulated samples of  $B_s^0 \to D_s^- \pi^+$  decays and data control samples are used to verify

the analysis procedure and to study systematic effects. The simulation provides a detailed model of the experimental conditions, including the pp collision, the decays of the particles produced, their final-state radiation and the response of the detector. Simulated samples are corrected for residual differences in relevant kinematic distributions to improve the agreement with data. The software used is described in Refs. [20–25].

The  $B_s^0$  mesons travel a macroscopic distance at LHC energies (on average 1 cm) before decaying and are significantly heavier than most other particles produced directly in pp collisions. Thus their decay products have significant displacement relative to the pp collision point, and a larger momentum transverse to the beam axis, compared to other particles. The candidate selection exploits these fundamental properties. Two fast real-time selections use partial detector information to reject LHC bunch crossings likely to be incompatible with the presence of the signal, before a third selection uses fully aligned and calibrated data in real time to reconstruct and select topologies consistent with the signal [26]. Selected collisions are recorded to permanent storage. Two subsequent selections fully reconstruct the decays with the  $D_s^-$  meson reconstructed in both  $K^-K^+\pi^$ and  $\pi^-\pi^+\pi^-$  final states. These selections sequentially improve the signal purity of the sample to the final value of 84%, which is optimised using simulation to maximize the product of signal significance and signal efficiency. This criterion gives the optimal sensitivity to the oscillation frequency. All but the first real-time selection are based on multivariate classifiers.

The remaining sources of background after selection consist of: random track combinations (combinatorial background);  $B_s^0 \to D_s^{*-}\pi^+$  decays, where the photon from the  $D_s^{*-} \to D_s^-\gamma$  decay is not reconstructed; and contributions from *b*-hadron decays with similar topologies to the signal, namely  $B^0 \to D^-\pi^+$ ,  $\bar{A}_b^0 \to \bar{A}_c^-\pi^+$  and  $B_s^0 \to D_s^{\mp}K^{\pm}$ decays. The decays with similar topology are suppressed by applying kinematic vetoes and additional particle identification requirements.

In order to measure  $\Delta m_s$ , a  $B_s^0 \to D_s^- \pi^+$  decay time distribution is first constructed in the absence of background. This is achieved by performing an unbinned two-dimensional likelihood fit to the observed  $D_s^- \pi^+$  and  $K^- K^+ \pi^-$  or  $\pi^- \pi^+ \pi^-$  invariant-mass distributions. This fit is used to determine the signal yield and a set of weights [27] used to statistically subtract the background in the subsequent fit to the decay-time distribution. The invariantmass distributions of the selected decays are shown in Fig. 1.

The probability density functions describing the signal and background invariant mass distributions are obtained using a mixture of control samples in data and simulation. The  $D_s^-\pi^+$  and  $K^-K^+\pi^-$  or  $\pi^-\pi^+\pi^-$  invariant-mass signal shapes are described by the sum of a Hypatia [28] and Johnson  $S_U$  [29] functions. The combinatorial background contribution for both invariant-mass distributions is described by an exponential function in each with parameters determined in the fit. The  $B^0 \to D^-\pi^+$ ,  $\overline{A}_b^0 \to \overline{A}_c^-\pi^+$  or  $B_s^0 \to D_s^{\mp}K^{\pm}$ background components constitute less than 2% of the signal yield and are accounted for in the fit to the invariant mass distributions using yields obtained from known branching fractions and relative efficiencies, as determined from simulated samples, which are weighted to account for differences between data and simulation. The  $B^0 \to D_s^-\pi^+$  and  $B_s^0 \to D_s^{*-}\pi^+$  background components are also obtained from simulated samples and included in the mass fit. The combined  $B^0 \to D_s^-\pi^+$  and  $B_s^0 \to D_s^{*-}\pi^+$  yield is a free parameter of the fit. The signal yield obtained from the invariant mass fit is 378 700  $\pm$  700.

The decay-time parametrisation in Eq. 1 is modified to account for the following detector effects: a time-dependent reconstruction efficiency; a time-dependent decay-time



Figure 1: **Invariant-mass distributions.** Distributions of the (left)  $D_s^-\pi^+$ , and (right)  $K^+K^-\pi^{\pm}$  or  $\pi^+\pi^-\pi^{\pm}$  invariant mass for the selected candidates,  $m(D_s^-\pi^+)$  and  $m(K^+K^-\pi^{\pm},\pi^+\pi^-\pi^{\pm})$ , respectively. The mass fit described in the text is overlaid. The different contributions are shown as coloured areas (for background) or by dashed lines (for signal).

resolution; the imperfect knowledge of the initial flavour of the reconstructed  $B_s^0$  or  $\overline{B}_s^0$  meson; the asymmetry in  $B_s^0$  or  $\overline{B}_s^0$  production in pp collisions; and an asymmetry in reconstruction of final state particles due to interactions in the detector material [30].

Due to the lifetime biasing effect of the selections, the reconstruction efficiency is low at small decay times and increases to a plateau after 2 ps. The time-dependent reconstruction efficiency is modelled with cubic b-splines curves as described in Ref. [31]. The spline coefficients are allowed to vary in the fit to the observed decay-time distribution.

The decay-time resolution is measured using a data sample of  $D_s^-$  mesons originating from pp interactions without being required to come from an intermediate  $B_s^0$  meson decay. These 'prompt' candidates pass the same selection procedure as for the signal sample except for requirements that reject signals with short decay times. The reconstructed decay time in this sample is proportional to the distance between the  $D_s^-$  production vertex and an artificial  $B_s^0$  decay vertex, formed by combining the prompt  $D_s^-$  meson with a  $\pi^+$  track from the same pp collision. It is therefore compatible with zero decay time up to bias and resolution effects. A linear relationship is observed between the decay-time resolution measured at zero decay time and the decay-time uncertainty estimated in the vertex fit. This relationship is used to calibrate the  $B_s^0 \rightarrow D_s^- \pi^+$  decay-time uncertainty. Simulated prompt  $D_s^-$  and  $B_s^0 \rightarrow D_s^- \pi^+$  decays, for which the generated decay time is known, are used to check the suitability of this method, which determines a 0.005 ps bias in the reconstructed decay time due to residual detector misalignments. This bias is corrected for in the analysis.

To determine if a neutral meson oscillated into its antiparticle, knowledge of the  $B_s^0$  or  $\overline{B}_s^0$  flavour at production and decay is required. In  $B_s^0 \to D_s^- \pi^+$  decays, the  $B_s^0$  flavour at decay is identified by the charge of the pion as the  $D_s^+ \pi^-$  decay cannot be produced directly. To determine whether the  $B_s^0$  oscillated before decay, the flavour at production is inferred from the hadronisation of the  $B_s^0$  meson or the decay of other beauty hadrons produced in the collision using a combination of several flavour-tagging algorithms [32–35].

Each algorithm estimates the probability that a candidate has been assigned the wrong flavour tag. The algorithms that use information independent of signal fragmentation are calibrated using  $B^+$  meson decays and a combined wrong-tag estimate is used in the fit. The tagging efficiency is measured to be  $\varepsilon = (80.30 \pm 0.07)\%$  with a probability to tag a candidate as the wrong flavour of  $\omega = (36.21 \pm 0.17)\%$ , where the uncertainties account for the calibration.

In the fit to extract  $\Delta m_s$ , the calibration parameters for the combined wrong tag estimate are allowed to vary. Additional free parameters are the values of the spline coefficients used to describe the time-dependent reconstruction efficiency and the  $B_s^0 - \overline{B}_s^0$ production and detection asymmetries.

The parameters  $\Gamma_s$  and  $\Delta\Gamma_s$ , are fixed in the fit to their known values [36]. Other fixed parameters are: the estimate of the wrong-tag fraction and efficiency of the tagging algorithms, the decay-time bias correction and the decay-time resolution calibration parameters. The decay-time distribution of the tagged-mixed,  $\overline{B}_s^0 \rightarrow D_s^- \pi^+$ , taggedunmixed,  $B_s^0 \rightarrow D_s^- \pi^+$ , and untagged, where the initial flavour is unknown, samples are shown in Fig. 2 (left). The corresponding fit projection is overlaid. In order to highlight the oscillation phenomenon, the asymmetry distribution between the tagged-unmixed and tagged-mixed samples is defined as

$$A(t) = \frac{N(B_s^0 \to D_s^- \pi^+, t) - N(\overline{B}_s^0 \to D_s^- \pi^+, t)}{N(B_s^0 \to D_s^- \pi^+, t) + N(\overline{B}_s^0 \to D_s^- \pi^+, t)},$$
(2)

with t modulo  $2\pi/\Delta m_s$ , and is shown in Fig. 2 (right). Here,  $N(\overline{B}_s^0 \to D_s^- \pi^+, t)$  and  $N(B_s^0 \to D_s^- \pi^+, t)$  indicate respectively the tagged-mixed and tagged-unmixed decays observed at a time t. For this distribution each event, in addition to the weight used to statistically subtract the background, is also weighted by the product of two factors. The first is a flavour-tagging dilution factor, related to the probability that the flavour tag is indeed correct. The second is an effective decay-time uncertainty dilution factor, depending on the reconstructed decay time per-event resolution and on  $\Delta m_s$ , for which the central value of the decay time fit is being used. The continuous line overlaid corresponds to the fit result. The result of the fit for  $\Delta m_s$  is 17.7683  $\pm 0.0051 \,\mathrm{ps}^{-1}$ , where this uncertainty is related to the sample size.

Several sources of systematic uncertainty have been investigated and those with a non-negligible contribution are listed in Table 1. These include the uncertainty on the momentum scale of the detector, obtained by comparing the reconstructed masses of known particles with the most accurate available values [36]; residual detector misalignment and length scale uncertainties; and uncertainties due to the choice of mass and decay-time fit models, determined using alternate parametrisations and pseudoexperiments. To verify the robustness of the measurement to variations in  $\Delta m_s$  as a function of the decay kinematics, the data sample is split into mutually disjoint subsamples, each having the same statistical significance, in relevant kinematic quantities, such as the  $B_s^0$  momentum, and the  $\Delta m_s$  values obtained from each subsample are compared. The largest observed variation is included as a systematic uncertainty. The total systematic uncertainty is  $0.0032 \,\mathrm{ps}^{-1}$ , with the leading contribution due to residual detector misalignment and detector length scale uncertainties.

The value of the  $B_s^0 - \overline{B}_s^0$  oscillation frequency determined in this article:

$$\Delta m_s = 17.7683 \pm 0.0051 \,(\text{stat}) \pm 0.0032 \,(\text{syst}) \,\text{ps}^{-1}$$



Figure 2: Decay-time distribution of the signal decays. Distribution of the (left) decay time of the  $B_s^0 \rightarrow D_s^- \pi^+$  signal decays and (right) decay-time asymmetry between mixed and unmixed signal decays. The fit described in the text is overlaid.

Table 1: Systematic uncertainties affecting the measurement of  $\Delta m_s$ . Sources of systematic uncertainties. The total systematic uncertainty is obtained by adding the contributions in quadrature.

Description	Systematic uncertainty $[ps^{-1}]$
Reconstruction effects:	
momentum scale uncertainty	0.0007
detector length scale	0.0018
detector misalignment	0.0020
Invariant mass fit model:	
background parametrisation	0.0002
$B_s^0 \to D_s^{*-} \pi^+$ and $B^0 \to D_s^- \pi^+$ contributions	0.0005
Decay-time fit model:	
decay-time resolution model	0.0011
neglecting correlation among observables	0.0011
Cross-checks:	
kinematic correlations	0.0003
Total systematic uncertainty	0.0032

is the most precise measurement to date. The precision is further enhanced by combining this result with the values determined in Refs. [8, 11]. Reference [8] uses  $B_s^0 \to D_s^- \pi^+$ decays collected in 2011. Reference [11] uses a sample of  $B_s^0 \to D_s^- \pi^+ \pi^+ \pi^-$  decays selected from the combined 2011–2018 data set, corresponding to 9 fb<sup>-1</sup>. The measurements are statistically independent. The systematic uncertainties related to the momentum scale, length scale and residual detector misalignment are assumed to be fully correlated. The correlation between  $\Delta m_s$  and the fixed parameters  $\Delta \Gamma_s$  and  $\Gamma_s$  is negligible and ignored in the combination procedure. A covariance matrix is constructed by adding statistical and systematic uncertainties in quadrature for each input, including correlations between systematic uncertainties. The results are averaged by minimizing the  $\chi^2$  from the full covariance matrix. The value of  $\Delta m_s$  obtained is 17.7666  $\pm$  0.0057 ps<sup>-1</sup>. Additionally, these results are combined with those from Refs. [9, 10] where  $\Delta m_s$  is determined using



Figure 3: Summary of LHCb measurements. Comparison of LHCb  $\Delta m_s$  measurements from Refs. [8–11], the result presented in this article and their average. The measurement described in this paper is labeled as  $D_s^- \pi^+ 6 \text{ fb}^{-1}$ . The band indicates the size of the uncertainty on the average for comparison purposes. The combination procedure and inputs are described in the text.

 $B_s^0 \to J/\psi K^+ K^-$  decays in the 2011–2012 (3 fb<sup>-1</sup>) and 2015–2016 (2 fb<sup>-1</sup>) data sets, respectively. The result for  $\Delta m_s$  is 17.7656 ± 0.0057 ps<sup>-1</sup>. The different measurements, and the resulting combination, are shown in Fig. 3.

In summary, this paper presents the most precise measurement of the  $\Delta m_s$  oscillation frequency, 17.7683  $\pm$  0.0051 (stat)  $\pm$  0.0032 (syst) ps<sup>-1</sup>, where the first uncertainty is statistical and the second systematic. The result is obtained using a sample of  $B_s^0 \rightarrow D_s^- \pi^+$ decays collected with the LHCb detector during Run 2 of the LHC. Combining the result of this paper with previous measurements by the LHCb collaboration yields a  $\Delta m_s$  value of 17.7656  $\pm$  0.0057 ps<sup>-1</sup>. This value is compatible with, and considerably more precise than, the predicted value from lattice QCD [12–14] and sum rule calculations [15,16] of  $18.4^{+0.7}_{-1.2}$  ps<sup>-1</sup> [17]. The combined result represents a significant improvement over previous measurements, and is a legacy measurement of the original LHCb detector. The experiment is currently undergoing a major upgrade to operate at five times the instantaneous luminosity from 2022 onwards [37]. The largest sources of systematic uncertainty for this measurement, namely those related to the detector length scale and misalignment, will be a focal point to further improve upon this result for future data taking periods.

### Methods

The LHCb detector. The LHCb detector [18, 19] is a single-arm forward spectrometer covering the pseudorapidity range  $2 < \eta < 5$ , designed for the study of particles containing b or c quarks. The detector includes a high-precision tracking system consisting of a silicon-strip vertex detector surrounding the pp interaction region [38], a large-area siliconstrip detector located upstream of a dipole magnet with a bending power of about 4 Tm, and three stations of silicon-strip detectors and straw drift tubes [39] placed downstream of the magnet. The tracking system provides a measurement of the momentum, p, of charged particles with a relative uncertainty that varies from 0.5% at low momentum to 1.0% at 200 GeV/c. The minimum distance of a track to a primary vertex (PV), the impact parameter (IP), is measured with a resolution of  $(15 + 29/p_T) \mu m$ , where  $p_T$  is the component of the momentum transverse to the beam, in GeV/c. Different types of charged hadrons are distinguished using information from two ring-imaging Cherenkov detectors [40]. Photons, electrons and hadrons are identified by a calorimeter system consisting of scintillating-pad and preshower detectors, an electromagnetic and a hadronic calorimeter. Muons are identified by a system composed of alternating layers of iron and multiwire proportional chambers [41].

Simulation of the LHCb detector response is required to model the effects of the detector acceptance and the imposed selection requirements. In the simulation, *pp* collisions are generated using PYTHIA [20] with a specific LHCb configuration [21]. Decays of unstable particles are described by EVTGEN [22], in which final-state radiation is generated using PHOTOS [25]. The interaction of the generated particles with the detector, and its response, are implemented using the GEANT4 toolkit [23] as described in Ref. [24].

**Selection.** A fast decision about which pp collisions are of interest is made by a trigger system [42]. It consists of a hardware stage, based on information from the calorimeter and muon systems, followed by a software stage, which reconstructs the pp collision based on all available detector information. The software trigger selects candidates consistent with a *b*-hadron decay topology, with tracks originating from a vertex detached from the primary pp collision point, known as the primary vertex (PV). The mean  $B_s^0$  lifetime is 1.5 ps [36], which corresponds to an average flight distance of 1 cm in the LHCb detector.

After being accepted by the trigger, a further selection is applied which forms  $D_s^- \to K^- K^+ \pi^-$  and  $D_s^- \to \pi^- \pi^+ \pi^-$  candidates from reconstructed charged tracks and subsequently combines them with a fourth track to form  $B_s^0 \to D_s^- \pi^+$  candidates. Particle identification information is used to assign mass hypotheses to each of the final-state tracks.

The  $B_s^0$  invariant-mass resolution is improved by constraining the  $D_s^-$  invariant mass to its known value [36]. The  $K^+K^-\pi^{\pm}$  or  $\pi^+\pi^-\pi^{\pm}$  and  $D_s^-\pi^+$  invariant-mass ranges considered in this analysis are [1930,2015] and [5300,5800] MeV/ $c^2$ , respectively.

To suppress  $B_s^0$  candidates formed from random track combinations, a gradient boosted decision tree (BDT) is used, implemented in the XGBoost library [43]. The training uses data for both the signal and the background samples in order to avoid mismatches between data and simulation. This classifier uses information on: the fit quality of the  $D_s^-$  and  $B_s^0$  decay vertices; the  $D_s^-$  and  $B_s^0 \chi_{\rm IP}^2$  defined as the difference in the  $\chi^2$  of the vertex fit for a given PV reconstructed with and without the considered particle; the angles between their momentum vector and the vector connecting their production and decay vertices; and the  $p_{\rm T}$  and impact parameter  $\chi_{\rm IP}^2$  of the final-state tracks. The BDT classifier threshold is chosen to maximize the product of the signal significance and the signal efficiency. This choice optimises sensitivity to the oscillation frequency.

**Flavour tagging.** The initial flavour of the  $B_s^0$  meson must be known in order to determine if it has oscillated prior to decay. Flavour tagging algorithms are used to determine the initial flavour from properties of the *b*-hadron production in the *pp* collision.

Beauty quarks are predominantly produced in pairs. Opposite side (OS) tagging algorithms [33] determine the initial flavour of the  $B_s^0$  meson based on information from the other beauty-quark decay. These include the OS muon and OS electron taggers, which identify the flavour from the charge of leptons produced in the other *b*-hadron decay. The OS kaon tagger identifies  $b \to c \to s$  transitions, the OS charm quark tagger identifies  $b \to c$  transitions, and the OS vertex charge tagger calculates the effective charge of an OS displaced vertex [34]. In addition, a same side (SS) kaon tagger exploits the charge information of the kaon originating from the  $\bar{s}$  or s quark leftover from the  $B_s^0$  or  $\bar{B}_s^0$  meson fragmentation [35]. Each algorithm determines the initial flavour of the  $B_s^0$  meson from the charge of the reconstructed tagging particle or the reconstructed vertex in the case of the OS vertex tagger.

The tagging information is incorporated in the decay-time description. The amplitude of the oscillation is reduced by a dilution factor  $D = (1 - 2\omega)$ , with  $\omega$  the average fraction of incorrect tags known as the mistag rate in the literature. Different machine learning algorithms provide an estimate of the mistag rate which is calibrated with data to match the true mistag distribution. A linear calibration of the average mistag as a function of the predicted mistag for the combined OS tag and SS kaon tag information is then implemented in the decay-time fit with freely varying calibration parameters. The combined tagging efficiency of the sample is  $\varepsilon = (80.30 \pm 0.07)\%$  with a mistag fraction of  $\omega = (36.21 \pm 0.02 \pm 0.17)\%$  where the first uncertainty is due to the finite size of the calibration sample and the second is due to the calibration procedure. This results in a combined effective performance of  $(6.10 \pm 0.02 \pm 0.15)\%$  with respect to a perfect tagging algorithm which would have a 100% tagging efficiency and zero mistag rate.

Systematic uncertainties. The following sources of systematic uncertainty have been found to give a non negligible contribution to the  $\Delta m_s$  measurement. These are summarised in Table 1 of the article.

The measured decay-time is inversely proportional to the  $B_s^0$  momentum, and therefore depends upon an accurate determination of the momentum scale uncertainty of the tracking system. The uncertainty is determined by varying the  $B_s^0$  meson momentum by  $\pm 0.03\%$  (coming from a comparison of masses of different particles with their known values) in simulated signal samples. The corresponding uncertainty on  $\Delta m_s$  is  $0.0007 \,\mathrm{ps}^{-1}$ .

The measured decay time is also proportional to the distance the  $B_s^0$  meson travels between production and decay, which is affected by precise knowledge of the position of the vertex detector elements along the proton beam axis. The measured uncertainty is 100 µm over a length of 1 m [38]. The corresponding uncertainty on  $\Delta m_s$  is 0.0018 ps<sup>-1</sup>.

The relative alignment of the tracking detector elements can also lead to uncertainties in the decay time. The uncertainty due to imprecise knowledge of this alignment has been obtained from the analysis of simulated signal samples in which the detector elements have been deliberately misaligned by random values in the range between 0 and 9  $\mu$ m as determined from survey results. Each misaligned simulated sample is then corrected for decay time bias in the same manner as for data, and the extracted  $\Delta m_s$  value is compared with the value obtained in simulation without any misalignment. This comparison produces a corresponding uncertainty on the bias correction procedure of 0.0020 ps<sup>-1</sup>.

Alternative parametrisations of the background contributions to the invariant mass fit have been obtained by using different weighting methods; the difference between these parametrisations corresponds to an uncertainty of  $0.0002 \,\mathrm{ps}^{-1}$ .

For the specific  $B_s^0 \to D_s^{*-}\pi^+$  and  $B^0 \to D_s^{-}\pi^+$  background contributions, the relative fraction of these components cannot be reliably determined from the data. Their relative contributions are nominally set to an equal mixture and varied between 0 (pure  $B^0 \to D_s^-\pi^+$ ) and 1 (pure  $B_s^0 \to D_s^{*-}\pi^+$ ) to determine the maximum deviation in  $\Delta m_s$ corresponding to an uncertainty of 0.0005 ps<sup>-1</sup>. The decay-time resolution is obtained from data using a sample of  $D_s^-$  mesons that are produced directly in pp collision. These are combined with a  $\pi^+$  meson coming from the same collision to produce a fake  $B_s^0$  candidate with a decay time equal to zero, ignoring resolution effects. Different parametrisations of the measured decay-time distribution are applied to a simulated signal sample. The largest deviation of the extracted  $\Delta m_s$  value with respect to the nominal parametrisation is found to be 0.0011 ps<sup>-1</sup>.

The procedure used to subtract background contributions in the fit to the decay-time distribution assumes no large correlations between the decay-time and the reconstructed  $B_s^0$  and  $D_s^-$  invariant masses. This is studied by analysing simulated signal and background samples where any residual correlations between these observables are removed. The difference in measured value of  $\Delta m_s$  between the decorrelated and nominal samples is found to be  $0.0003 \,\mathrm{ps}^{-1}$ .

The data sample was split into mutually disjoint subsamples in order to study the effect of potential correlations between kinematic ranges, data taking periods, flavour-tagging categories, the BDT-based selection and the measured value of  $\Delta m_s$ . The measured values obtained from each subsample are compared and the largest observed variation is found to be  $0.0003 \text{ ps}^{-1}$ .

The largest sources of systematic uncertainty are found to be due to imprecise knowledge of the position and alignment of the tracking detector closest to the nominal pp collision region.

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